Drag and Bulk Transfer Coefficients Over Water Surfaces in Light Winds

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Abstract The drag coefficient (C_D) , experimentally determined from observed wind speed 13and surface stress, has been reported to increase in the low wind-speed range (< 3 m s⁻¹) as 14wind speed becomes smaller. However, until now, the exact causes for its occurrence have 15not been determined. Here, possible causes for increased C_D values in near-calm conditions 16are examined using high quality datasets selected from three-year continuous measurements 17obtained from the centre of Lake Kasumigaura, the second largest lake in Japan. Based on 18 our analysis, suggested causes including (i) measurement errors, (ii) lake currents, (iii) 19capillary waves, (iv) the possibility of a measurement height within the interfacial/transition 20sublayer, and (v) a possible mismatch in the representative time scale used for mean and 21covariance averaging, are not considered major factors. The use of vector-averaged, instead 22of scalar-averaged, wind speeds and the presence of waves only partially explain the increase 23in C_D under light winds. A small increase in turbulence kinetic energy due to buoyant 24production at low wind speeds is identified as the likely major cause for this increase in C_D in 25the unstable atmosphere dominant over inland water surfaces. 26

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Keywords Drag coefficient • Eddy correlation • Lake Kasumigaura • Turbulence kinetic
 energy • Weak wind speed

30 1 Introduction

31 Drag coefficients are commonly used in various fields of study. For example, in 32 meteorology and hydrology, the surface shear stress τ is often estimated from the mean wind 33 speed, \overline{U} , by applying the following bulk relation

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$$\tau = \rho u_*^2 = \rho C_D \overline{U}^2 = -\rho \overline{u'w'}$$
(1)

provided that a value of the drag coefficient, C_D , is known a priori. In Eq. 1 ρ is the air 35density, u_* is the friction velocity, and $\overline{u'w'}$ is the covariance of the horizontal and the 36 vertical wind speed fluctuations. The overbar denotes a time average-see below for a 37discussion on the method of time averaging. The calculation is particularly useful over a 38water surface because τ and other relevant surface fluxes, e.g. the sensible heat flux, H, and 3940the latent heat flux, $L_e E$ (where L_e is the latent heat of vaporization and E is evaporation), can be formulated in the same manner as τ using variables that can be clearly defined and 41 42measured at the surface. For surface types such as vegetated fields these calculations may not be possible (e.g., Sugita and Brutsaert 1996). Generally, L_eE and H can be calculated 43from 44

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$$L_e E = \rho L_e C_E \overline{U} \left(\overline{q_s} - \overline{q} \right) = \rho L_e \overline{w'q'}, \qquad (2)$$

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$$H = \rho c_p C_H \overline{U} \left(\overline{\theta_s} - \overline{\theta} \right) = \rho c_p \overline{w' \theta'}, \qquad (3)$$

where C_E and C_H are the bulk transfer coefficients for water vapour and for heat respectively, 47 c_p is the specific heat of air at constant pressure, q and θ are the specific humidity and 48potential temperature at a reference height in the surface layer, and those with subscript s (i.e., 49 q_s and θ_s) denote corresponding values at the water surface. $\overline{w'\theta'}$ and $\overline{w'q'}$ are the 50covariance of w and θ , and that of w and q, respectively. Note that C_D , C_E , and C_H are a 51mild function of atmospheric stability; thus, it is common to define drag and bulk coefficients 52for neutral atmospheric stability (e.g. Stull 1988; Garratt 1992; Fairall et al. 1996; Brut et al. 53542005), denoted here as C_{DN} , C_{EN} , and C_{HN} .

55 Drag and bulk coefficients over water surfaces have been extensively studied (e.g., 56 Garratt 1992). Earlier datasets were mostly based on observations obtained under moderate 57 to strong wind conditions over the ocean (e.g., Fairall et al., 1996). As a result, the

wind-speed range over which published values are specified is heavily represented by 58stronger wind speeds. Amongst earlier studies that dealt with drag coefficients at low wind 59speeds, Mitsuta et al. (1970) derived C_D values over lake surfaces (see Table 1 for a summary 60of previous studies that reported drag and bulk transfer coefficients as a function of wind 6162speeds under low wind speeds over water surfaces). These early results indicated an increase in drag coefficients as wind speed decreased toward zero, but in excess of that 63 expected for C_D values for aerodynamically smooth surfaces. Kondo and Fujinawa (1972) 64suggested possible reasons for this, including: (i) the neglect of atmospheric stability during 6566the derivation of drag coefficients, and (ii) the neglect of the presence of surface water currents by giving the magnitude of the error for C_D values resulting from the neglect of (i) or 67(ii) under typical, but hypothetical conditions. Mitsuta and Tsuamoto (1978) provided an 68 analysis of observations obtained over Lake Biwa (the largest lake in Japan) under neutral 69 conditions and found similar results. Using an analysis of σ_{θ} , σ_u/\overline{U} , and σ_w/\overline{U} (where 70 σ is the standard deviation of temperature, and the horizontal and vertical wind components, 7172respectively) as a function of the mean wind speed, these authors argued that an increase in turbulence intensity of thermal origin was responsible for the increase in C_D . Showing a 73similar increase in coefficients for smaller wind speeds, Ikebuchi et al. (1988) presented C_E 74as a function of wind speed (as small as 1.5 m s⁻¹) over Lake Biwa based on results using an 75advanced sonic anemometer. Heikinheimo et al. (1999) investigated the aerodynamic 7677roughness length over a lake surface as a function of the friction velocity, and a larger roughness length than predicted by considering both a smooth surface and gravity waves (see 78below in sect. 3.2.2), was found for $u_* < 0.2 \text{ m s}^{-1}$ although no explanation was provided 79for the discrepancy. Xiao et al. (2013) also reported similar results for C_D , C_E , and C_H over 80 three lake surfaces in China and suggested possible causes for large coefficients under low 81 wind speeds, including the influence of capillary waves (Wu 1994) and an omission of 82 gustiness (e.g., Godfrey and Beljaars 1991; Stull 1994) in wind-speed determinations. 83 However, neither hypothesis was verified in the data analyses. 84

Much of the global ocean surface is influenced by weak winds. For example, a light wind regime ($< 2 \text{ m s}^{-1}$) occurs approximately 20% of the time within the equatorial west Pacific Ocean (Grachev et al. 1997), and in observations made over the northern Indian Ocean, approximately 40% of wind-speed values were $< 4 \text{ m s}^{-1}$ (Parekh et al. 2011). Thus studies in light winds are essential to expand our ability to predict surface fluxes, and as such, 90 observational analyses in weak winds over the ocean have also been reported. Among such studies, Greenhut and Khalsa (1995), Yelland and Tylor (1996), and Dupuis et al. (1997) 91reported an increase in C_D , C_E , and C_H for smaller wind speeds. On the other hand, a widely 92used parametrization of the drag coefficient (the Coupled Ocean-Atmosphere Response 93Experiment (COARE) algorithm that now spans a wind-speed range from zero to 25 m s⁻¹) 94does not include an increase in C_D for smaller wind speeds, with the exception of that 95expected for a smooth surface (see, for example, Fairall et al. 2003; Edson et al. 2013). The 96 mechanism or the cause(s) for this discrepancy has not been clearly outlined. Mahrt et al. 97(2001) explored possible problems with estimations of C_D under weak wind conditions, 98particularly in regards to the method of averaging and the influence of mesoscale motions. 99

To summarize, experimental evidence shows larger C_D values under weak wind 100conditions than those expected from predictions for smooth surfaces. The exact cause has not 101been determined. One reason for the lack of understanding is that, in past studies, not all 102possibilities were tested using the same datasets, so the influence of factors other than those 103104investigated could not be discarded. The purpose of our study is to revisit this phenomenon, mainly for C_D , and partially for C_E and C_H , over the low wind-speed range and to provide 105106 physical explanations for past results. To achieve our goal, factors that could possibly influence C_D are tested using datasets based on the same experiment. 107

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109 **2 Methods**

110 2.1 Study Area

111Observations were obtained from the Koshin Observatory of the Kasumigaura River Office (Kanto Regional Development Bureau, Ministry of Land, Infrastructure, Transport and 112Tourism of Japan) located at the centre (36°02'35"N, 140°24'42"E) of Lake Kasumigaura, the 113second largest lake in Japan and close to sea level. Lake Kasumigaura has a surface area of 114220 km² and an average depth of 4 m. However, at the observatory the water depth is 7.1 m 115(Sugita et al. 2014). The minimum fetch of the observatory is 3 km in the north-east 116 direction, while in other directions it is 4-17 km. The area surrounding the lake is relatively 117flat and has an altitude of approximately 30 m (see Fig. A1 in Appendix 1). 118

Recently, Sahlée et al. (2014) reported (based on turbulence measurements made 119 over a lake with a similar undisturbed fetch) different behaviour for the variance of the 120horizontal velocity and scalars than those found over land. Based on their results, the 121authors concluded that large eddies originating from surrounding land surfaces remain in 122123effect over longer distances over the lake to have influenced their turbulence measurements, while smaller eddies quickly became adjusted to the lake surface and did not influence the 124125measurements. Thus it is possible that the upwind land surfaces may also have influenced our measurements. However, the possible impact of this recent finding on the present study 126127should be limited since Sahlée et al. (2014) did not find any discrepancies for fluxes and for drag and bulk transfer coefficients, with the exception of minor influences on the integral 128turbulence characteristic (ITC) test required for screening turbulence data (see below). 129Dörenkämper et al. (2015) provided a case for decreased wind speed over an ocean 130influenced by advected air from the land (unstable condition) to the ocean (stable condition). 131Since unstable conditions were dominant (95%) during the three-year observational period 132over Lake Kasumigaura (see Fig. A2), the finding of Dörenkämper et al. (2015) likely does 133not apply to our case. Indeed, Araya (2008) estimated the wind field at 10 m on and around 134Lake Kasumigaura by applying a regional meteorological model of the Advance Research 135136Weather Research and Forecasting (WRF) model (Skamarock et al., 2005) using GFS-FNL reanalysis data (NCEP, 2000) with the Global 30 Arc-Second Elevation (GTOPO30) digital 137138elevation model (USGS, 2015) as the boundary condition for surface topography. In the study, the author determined that wind speeds over the lake become greater than those over 139140the surrounding land surface under weak winds, implying a rapid response of the flow moving from land to the lake. When strong mesoscale flow dominated the area, no clear 141142difference was obtained between wind speeds over the lake and those over the surrounding land surface. This was probably because increase in wind speed over the lake was too small 143144relative to the prevailing high wind speeds. Thus the influences of land on the measurements over water surfaces suggested by these studies can probably be neglected for 145our analysis. 146

147 The daily change in energy balance can be characterized by the relatively large 148 contribution from the heat stored in the lake through the absorption and release of energy. 149 By comparison, the sensible and latent heat fluxes were often smaller (see Fig. A3). About 150 50% of measured wind speeds at 9.8-m height were $< 4 \text{ m s}^{-1}$, and 30% were $< 3 \text{ m s}^{-1}$.

151 2.2 Observation System

152Since June 2006, a measurement system has been in place at the Koshin Observatory (Sugita et al. 2014), and data obtained from 2008-2010 have been used for our analysis. 153Table 2 provides details regarding the measurements (also see the schematic figure showing 154instrumentation on and around the observatory, Fig. A4 in Appendix 2). 155Briefly, observations consisted of turbulence measurements, radiation balance components, 156temperature and humidity, and water surface conditions. Data obtained at the Koshin 157Observatory, both routinely and for special observations, were also used whenever necessary. 158

159 2.3 Datasets

160 2.3.1 30-min Dataset

To select data records of high quality, continuous data averaged over 30 min were culled 161based on the following data screening criteria: (i) rainy days, (ii) unfavourable wind 162directions, (iii) the presence of spikes in the data time series, and (iv) weak turbulence. 163More specifically, data that were obtained 3 h prior to and following a rainfall event, recorded 164using a 0.5-mm rain gauge of the Koshin observatory, were rejected to avoid possible 165contamination due to raindrops on the sensors. To avoid the possible influence of the 166 observatory (Fig. A4), data obtained within a wind direction of 060° to 160° were rejected. 167Data with spikes caused by system/sensor breakdown and interference from periodic 168maintenance operations during site visits were excluded. To avoid cases of very weak 169turbulence, data with $u_* < 0.05 \text{ m s}^{-1}$, $\overline{w'\theta'} < 0.015 \text{ K m s}^{-1}$ or $\overline{w'q'} < 0.015 \text{ g m}^{-2} \text{ s}^{-1}$ were 170also excluded. Turbulence data were further examined for quality assurance. Quality 171assurance tests that we applied included a stationary test (Foken and Wichura 1996) and an 172ITC test on the development of the turbulence which compares the measured and the 173modeled flux-variance similarity characteristics (Foken and Wichura 1996, Foken et al. 2004). 174In the stationary test, the covariance determined for the averaging period T = 30 min were 175176compared with that determined as a mean of the six covariances, each of which were determined for T=5 min. However, as cautioned by Vesala et al. (2012), the casual and 177178automatic application of these tests to turbulence measurements over a lake surface is a questionable practice, particularly in cases where the cause(s) of a C_D increase under low 179180wind speeds could be related to mesoscale atmospheric circulations. Thus, all data were 181 retained for the analysis regardless of the test results, and the test results were regarded as a

guideline for providing information on the characteristics of the datasets. A total of 7,343 30-min data records (hereafter to be referred to as the 30-min dataset) were used for our analysis. The common correction procedures for turbulence data, including a correction for the water vapour flux (Webb et al. 1980) and coordinate rotation for vector wind components (Kaimal and Finnigan 1994), were applied.

187 2.3.2 Two-hour Dataset

For the detailed analysis, 10-Hz wind-speed data collected over a period of 2 h were selected 188by applying the same procedure as for the 30-min dataset with the exception of the criteria 189190 that were not applicable for wind-speed data. However, the following additional criteria were applied in order to select the appropriate 2-h data: (i) During the 2-h period, no obvious 191trend in wind speed, wind direction, and temperature should be evident in the time series. 192(ii) The results of the stationary and the ITC tests should fall within classes one through five 193(see, e.g., Foken et al. 2004 for the flagging scheme). The latter criterion is somewhat 194195arbitrary but provides a compromise between the traditional good quality indication and data that could include the influence of mesoscale atmospheric phenomena. Based on these 196criteria, eight 2-h data records (hereafter to be referred to as the 2-h dataset) were chosen. 197 Four of the data records (S1 – S4) contained strong wind cases ($\overline{U} \ge 5 \text{ m s}^{-1}$) and four (W1 – 198W4) contained weak wind cases. 199

Selected data records were used with and without coordinate rotation. Rotation ensured that the vertical wind velocities were not contaminated by horizontal wind components. However, as stated by Metzger and Holmes (2008), the time-averaging operation and the introduction of high-pass filtering to data can result in the underestimation of fluxes. Therefore, to resolve differences, both types of data were subjected to the same analysis.

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207 2.4 Analysis

208 2.4.1 Neutral Drag and Bulk Coefficients

The neutral drag and bulk coefficients C_{DN} , C_{HN} , and C_{EN} were derived from Eqs. 1-3 in order to remove the effects of atmospheric stability, with measured fluxes and corresponding mean values at 10 m converted for the neutral atmospheric condition. The 10-m neutral wind speed was computed from the wind speed measured at a height z = 9.80 m using

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$$\overline{U}_{10N} = \overline{U}(z) + \frac{u_*}{k} \left[\ln(\frac{10}{z}) + \Psi_m(z/L) \right].$$
(4)

Similarly, for the specific humidity and temperature difference, the corresponding equationsare, as follows

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$$\overline{q}_{10N} = \overline{q}(z) - \frac{E}{ku_*\rho} \left[\ln(\frac{10}{z}) + \Psi_v(z/L) \right],$$
(5)

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$$\overline{\theta}_{10N} = \overline{\theta}(z) - \frac{H}{\rho c_p k u_*} \left[\ln(\frac{10}{z}) + \Psi_h(z/L) \right], \tag{6}$$

where k is the von Kármán constant (= 0.4) and Ψ_x represents the stability function for x (m for momentum, v for water vapor and h for heat). With humidity and temperature measurements at z = 3.72 m, Ψ_x functions proposed by Brutsaert (2005) were used for the present study. Note that $L = -T_a u_*^3 / \left[kg \left(\overline{w'\theta'} + 0.61T_a \overline{w'q'} \right) \right]$ is the Obukhov length, T_a is the air temperature in K, and g is the acceleration due to gravity. In the 30-min dataset, 63% of the data records were in the range of $-1 < z/L \le 0$, 17% for $-2 < z/L \le -1$, and the remainder for $-10 < z/L \le -2$.

225 2.4.2 Water State (Wave) Parameters

As shown in Table 2, the wave parameters, wave height and period, determined from 226measurements at the Koshin Observatory, were used for the analysis. Raw data included 227water-surface levels measured at 20 Hz subjected to both high-pass (10 sec) and low-pass 228filtering (1 sec). The mean water level, the significant wave period, and the wave height for 229every 10-min period were then determined from the filtered data. The filtering operation 230should eliminate swell as well as capillary wave components from the data. However, this 231should not be a problem since capillary wave information can be estimated using water 232temperature (see below) and swells are not likely to exist in Lake Kasumigaura due to its 233limited fetch. To verify this, the raw data were recorded continuously at 20 Hz for one 234month from 20 November 2009 during a preliminary analysis. A power spectrum was 235

calculated and wave periods were derived from the peak frequency. The results were compared with those from Koshin observatory and both were found essentially to be the same (Miyano, 2010). Thus, for the present study, the wave phase speed, C_p , was estimated from the measured significant wave period, T_p , through an iteration of the dispersion relationship (e.g. Smedman et al. 2003), as follows,

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$$C_{p} = \frac{g}{\omega_{0}} \tanh\left(\frac{\omega_{0}h}{C_{p}}\right)$$
(7)

242 where h (= 4 m) is the mean water depth, and $\omega_0 = 2\pi/T_p$ is the wave frequency.

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244 **3 Results and Discussion**

245 3.1 Neutral Drag and Bulk Coefficients

Figure 1 (black open circles) provides the relationship between neutral C_{DN} , C_{HN} , and C_{EN} 246values for a reference height of z = 10 m determined from Eqs. 1-6 and the corresponding 247mean neutral wind speed, \overline{U}_{10N} , converted from the vector-averaged \overline{U} (see below) based 248on the 30-min dataset. Results derived from previous studies (light blue, green and red 249colours) for weak wind cases over water surfaces (also see Table 1 for those that gave 250functional forms) are also provided for comparison. Overall, the derived values agree with 251those reported in the past for the general range $\overline{U}_{10N} > 4 \text{ m s}^{-1}$, approximately In this 252range, C_{DN} , C_{HN} , and C_{EN} are close to a constant, while for $\overline{U}_{10N} < 3 \text{ m s}^{-1}$, increases in C_{DN} , 253 C_{HN} , and C_{EN} for \overline{U}_{10N} decreasing are clearly observed. The results are in agreement with 254some but not all studies (see the discussion in sect. 3.3 for additional information regarding 255this issue). The fitted equations can be expressed for the range of 14 m s⁻¹ > $\overline{U}_{10N} \ge 0.5$ 256m s^{-1} , as follows, 257

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$$C_{DN} = \left(b_{D1} / \overline{U}_{10N}\right) \exp\left[-\left(\ln \overline{U}_{10N} - b_{D2}\right)^3\right] + \left(b_{D3} + b_{D4}\overline{U}_{10N}\right), \tag{8}$$

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$$C_{EN} = \left(b_{E1} / \overline{U}_{10N}\right) \exp\left[-\left(\ln \overline{U}_{10N} - b_{E2}\right)^3\right] + \left(b_{E3} + b_{E4} \overline{U}_{10N}\right), \tag{9}$$

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$$C_{HN} = \left(b_{H1} / \overline{U}_{10N}\right) \exp\left[-\left(\ln \overline{U}_{10N} - b_{H2}\right)^3\right] + \left(b_{H3} + b_{H4}\overline{U}_{10N}\right).$$
(10)

261 which are modified versions of Zhu and Furst (2013). The coefficients have values

262 $b_{D1} = 2.3 \times 10^{-2}, b_{D2} = -5.5 \times 10^{-1}, b_{D3} = 1.2 \times 10^{-3}, \text{ and } b_{D4} = 4.9 \times 10^{-6}$ for Eq. 8, 263 $b_{E1} = 9.1 \times 10^{-4}, b_{E2} = 2.2 \times 10^{-1}, b_{E3} = 1.1 \times 10^{-3}, \text{ and } b_{E4} = -1.5 \times 10^{-5}$ for Eq. 9, and 264 $b_{H1} = 2.1 \times 10^{-3}, b_{H2} = 2.8 \times 10^{-1}, b_{H3} = 9.1 \times 10^{-4}, \text{ and } b_{H4} = 1.6 \times 10^{-5}$ for Eq. 10. Those 265 coefficients are given to produce C_{DN}, C_{HN} , and C_{EN} values with two significant digits. 266

267 3.2 Possible Causes for Large Drag Coefficients for Low Wind Speeds

As mentioned previously, the behaviour of C_{DN} , C_{HN} , and C_{EN} under weak winds was originally attributed to measurement error and the neglect of atmospheric stability. However, with the advent of improved measurement technology and careful data screening procedures, it is not likely (or possible) that measurement errors are solely responsible for the discrepancies that exist. Similarly, the small stability effect on C_D , C_H , and C_E is mitigated, at least partially, by employing neutral coefficients C_{DN} , C_{HN} , and C_{EN} . In the following discussion, remaining possibilities are examined for C_{DN} .

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276 *3.2.1 Lake Current*

When the magnitude of the surface current is not negligible as compared to that of \overline{U} in Eq. 2771, \overline{U} should be replaced by $\overline{U} - \overline{u_s}$, where $\overline{u_s}$ represents the mean surface current speed 278in the mean wind direction. For this purpose, a 30-min dataset for $\overline{u_s}$ at z = -0.75 m, 279measured at the Koshin Observatory from 22 February to 17 March 2008 using an acoustic 280Doppler current profiler (ADCP) (INA Corporation 2008; Table 2), was selected for an 281analysis from all available profiles based on the following consideration. INA Corporation 282(2008) reported that ADCP measurements generally agreed with those obtained using an 283electromagnetic current meter for the same location and for the same general depth, with the 284exception that occasional disagreements were observed for a depth of 0.25 m for $\overline{U} > 10$ m 285s⁻¹. The presence of large waves was speculated by INA Corporation (2008) to make ADCP 286measurements near the surface less reliable. To avoid this type of uncertainty, $\overline{u_s}$ 287measured at -0.75 m was adopted for our analysis. Also, to consider the possible 288underestimation of $\overline{u_s}$ by choosing measurements at greater depths, $\overline{u_s}$ values at -0.75 m 289and -0.25 m were compared when surface measurements appeared reliable. A *t*-test was 290

performed in order to compare the averages of both measurements. For the datasets $\overline{U} < 1$ m s⁻¹, $\overline{U} < 2$ m s⁻¹, $\overline{U} < 3$ m s⁻¹, and $\overline{U} < 4$ m s⁻¹, no statistically significant differences at a level of 0.01 were found. Thus, those $\overline{u_s}$ values measured at z = -0.75 can probably be used as for the weak wind-speed range. Note that for $\overline{U} > 6$ m s⁻¹, $\overline{u_{s,-0.75m}} = 0.67\overline{u_{s,-0.25m}}$ was obtained from a regression analysis and thus the use of measurements at z = -0.75should result in underestimation of $\overline{u_s}$.

297Based on the measurements, we found that the surface current speed increased with increasing wind speed for most cases, that the magnitude of the surface current speed was at 298most 0.25 m s⁻¹ during measurements, and that $\overline{u_s}$ was two orders of magnitude smaller 299than that of the wind speed (Fig. 2). For a small value of \overline{U} , these findings could be relevant 300 for the determination of C_{DN} . The mean and standard deviation of C_{DN} values were derived 301for small bins of both $\overline{U} - \overline{u_s}$ or \overline{U} . In general, the determined differences were very 302small, with a t-test indicating that the means were not significantly different at the 0.01 303 significance level. Even when data were only selected for $\overline{U} < 2 \text{ m s}^{-1}$, the difference of 304the means was not found to be significant. Therefore, it is likely safe to conclude that the 305lake's current has a negligible effect on C_{DN} at the centre of Lake Kasumigaura. 306

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308 3.2.2 Waves

Wu (1994) and Bourassa et al. (1999) suggested that the bulk coefficient may not be a simple function for wind speed over water surfaces and that the influence of waves should be considered. To include the influence of waves, it is customary and more convenient to use the roughness length, z_{0m} , instead of C_D since z_{0m} directly expresses the nature of the surface. Based on the wind profile,

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$$\overline{U} = \frac{u_*}{k} \ln\left(\frac{z}{z_{0m}} - \Psi_m\left(\frac{z}{L}\right)\right)$$
(11)

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316 re-arranging gives

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$$C_{D} = \frac{k^{2}}{\left\{\ln\left(z/z_{0m}\right) - \Psi_{m}\left(z/L\right)\right\}^{2}}.$$
 (12)

Wind waves can have different forms depending on the nature of the airflow and fetch. In the natural environment, capillary waves and gravity waves (wind sea and swell) are considered relevant in the range of $0 < \overline{U} < 20$ m s⁻¹. As mentioned, however, swells probably do not exist in the case of Lake Kasumigaura. Aerodynamically smooth surfaces, on the other hand, may also play a role for weak winds. Traditionally, the roughness length that corresponds to each has been parameterized separately as,

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$$z_{0s} = \frac{0.11v}{u_*}$$
(13)

for a smooth surface (e.g., Brutsaert 1982), where v is the kinematic viscosity,

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$$z_{0g} = a \frac{{u_*}^2}{g}$$
 (14)

for gravity waves (Charnock 1955), where a is the Charnock parameter to be determined experimentally; and

$$z_{0c} = \frac{b\sigma_w}{u_*^2 \rho_w} \tag{15}$$

for capillary waves, where b is an experimental parameter. σ_w and ρ_w are the surface 330 tension and the water density, respectively, and were estimated as a function of water 331temperature. Based on a tank experiment, a value of b = 0.18 was originally proposed by 332 Wu (1994). Based on a re-examination of data, Bourassa et al. (1999) concluded that b =3330.06 was more appropriate for neutral atmospheric stability. A value of b = 0.18 was found to 334be optimum for our datasets, and, as discussed below, this value was adopted. Wu (1968, 3351994) proposed Eq. 15 for explaining larger drag coefficients than those predicted by Eq. 13 336 for weak winds observed by Geernaert et al. (1988) and Bradley et al. (1991). 337

From Eq. 14 and by assuming $z_{0g} = z_{0m}$, as determined from Eq. 11 using the measured u_{*} and \overline{U}_{10} , as well as the stability parameter z/L estimated from the measured surface

340 fluxes of u_* , $L_e E$, and H, the value of the Charnock parameter was determined to be a =0.032. The 30-min dataset was employed, but the data were further scrutinized by applying 341the stationary and ITC test criteria (classes 1-2) and the roughness Reynolds number, 342 $Re_{+} = u_{*}z_{0} / v > 2.5$ (Nikuradse, 1933, Sugita et al., 1995), so that only rough surface 343observations were chosen. The value of a = 0.032 clearly falls within the range of previous 344proposals of a = 0.012 - 0.035 (e.g., Garratt 1992) and was used for our analysis, and for the 345discussion provided below, although the value is higher than the commonly assumed value of 346a = 0.011 used for the ocean (e.g., Fairall et al. 1996, 2003). Proposals have been suggested 347that relate the Charnock parameter, a, to the wave age, C_p/u_* (e.g. Smith et al. 1992; Oost 348et al. 2002; Drennan et al. 2003). However, this procedure did not produce improved 349 estimates for z_{0m} or u_* for the present dataset, likely because the dataset contained a 350narrower range of $5 < C_p / u_* < 18$ than that encountered above the ocean (typically in the 351range of $10 < C_p / u_* < 50$). Thus, the procedure was not further considered. 352

The roughness lengths obtained using Eqs. 13 and 14 are often linearly added in order to obtain the total roughness length, z_{0m} , (e.g., Smith 1988). The contribution of capillary waves is not considered in

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$$z_{0m} = z_{0g} + z_{0s} \,. \tag{16}$$

However, a proposal by Bourassa et al. (1999, 2001) exists in which the contribution of capillary waves is considered and where Eqs. 13-15 are added as the root-mean-square (r.m.s) sum using separate weighting factors of β_s , β_c , and β_g (where $\beta_s + \beta_c + \beta_g = 1$), as follows,

$$z_{0m} = \left[\left(\beta_s z_{0s} \right)^2 + \left(\beta_c z_{0c} \right)^2 + \left(\beta_g z_{0g} \right)^2 \right]^{1/2}.$$
(17)

Bourassa et al. (2001) considered this procedure for a three-dimensional wave field. However, since wave direction was not available, the analysis was performed by assuming that wind and waves move in the same direction. Possible errors due to this assumption can be assessed to some extent by referring to Bourassa et al. (1999) who estimated for the case of $\overline{U}_{10} = 3 \text{ m s}^{-1}$ that the stress when wind and wave directions were the same was 82% of the stress when these directions were opposite. Bourassa et al. (2001) also included wave age in the third term as a parameter for estimating roughness due to gravity waves. As mentioned above, no improvement was determined for our dataset by including the wave age,
so it was not included in Eq. 17.

371Whether or not capillary waves should be considered is still not clear. Brunke et al. (2003) provided a comprehensive comparison of flux estimates using different bulk 372aerodynamic relations derived from measurements and concluded that algorithms that 373consider capillary waves tend to overestimate fluxes under low wind regimes. With regards 374375to the choice of summation methods, a simple sum or an r.m.s sum of the components has been adopted. However, neither method contains sound reasoning. In fact, a method based 376on a different point of view could be employed (i.e. obtain a total roughness length, z_{0m} , that 377 could produce the total drag, τ , acting at the water's surface), noting that forces of various 378origin can be linearly added. Thus, the linear sum of $\left[\ln \frac{z}{z_{0m}} \right]^{-2}$ could be used as an 379alternative 380 method

as indicated by: $\tau \propto \left[\ln \frac{z}{z_{0m}} - \Psi\left(\frac{z}{L}\right) \right]^{-2}$ from Eqs. 1 and 11. The roughness length z_{0m} that reflects such total force can be obtained using

$$\left[\ln\left(\frac{z}{z_{0m}}\right)\right]^{-2} = \beta_g \left[\ln\left(\frac{z}{z_{0g}}\right)\right]^{-2} + \beta_c \left[\ln\left(\frac{z}{z_{0c}}\right)\right]^{-2} + \beta_s \left[\ln\left(\frac{z}{z_{0s}}\right)\right]^{-2} \quad . \tag{18}$$

The second term can be omitted and $\beta_s = \beta_g = 1$ if capillary waves are not considered, while $\beta_s + \beta_c + \beta_g = 1$ if they are considered. A standard reference height of z = 10 m can also be used.

For our analysis, we compared z_{0m} , obtained using Eq. 11 with the measured u_* and \overline{U} , and z_{0s} , z_{0c} and $z_{0s} + z_{0g}$ estimated using Eqs. 13, 15, and 16 as a function of \overline{U}_{10N} (Fig. 3). Also shown in Fig.3 are z_{0m} values estimated from Eqs. 17-18. The weighting factors employed in Eq. 17 were $\beta_c = 1$ and $\beta_s = \beta_g = 0$ for $0 \le \overline{U}_{10N} < 2.5 \text{ m s}^{-1}$, $\beta_g = 1.5 \times 10^{-1} \overline{U}_{10N} - 3.6 \times 10^{-1}$, $\beta_c = 1 - \beta_g$, and $\beta_s = 0$ for $2.5 \le \overline{U}_{10N} < 8 \text{ m s}^{-1}$, and $\beta_s = \beta_c = 0$ and $\beta_g = 1$ for 8 m s⁻¹ $\le \overline{U}_{10N}$, and were determined by minimizing the r.m.s difference between z_{0m} based on Eq. 17 and z_{0m} derived from Eq. 11. If the weighting

factors were based on Eq. 18, then $\beta_c = 1$ and $\beta_s = \beta_g = 0$ for $0 \le \overline{U}_{10N} \le 2.5$ m s⁻¹, 394 $\beta_{g} = 1.3 \times 10^{-1} \overline{U}_{10N} - 2.1 \times 10^{-1}, \ \beta_{c} = 1 - \beta_{g}, \ \text{and} \ \beta_{s} = 0 \quad \text{for} \quad 2.5 \leq \overline{U}_{10N} < 8 \quad \text{m} \quad \text{s}^{-1}, \ \text{and} \quad \beta_{s} = 0 \quad \text{for} \quad 2.5 \leq \overline{U}_{10N} < 8 \quad \text{m} \quad \text{s}^{-1}, \ \text{and} \quad \beta_{s} = 0 \quad \text{for} \quad 2.5 \leq \overline{U}_{10N} < 8 \quad \text{m} \quad \text{s}^{-1}, \ \text{and} \quad \beta_{s} = 0 \quad \text{for} \quad 2.5 \leq \overline{U}_{10N} < 8 \quad \text{m} \quad \text{s}^{-1}, \ \text{and} \quad \beta_{s} = 0 \quad \text{for} \quad 2.5 \leq \overline{U}_{10N} < 8 \quad \text{m} \quad \text{s}^{-1}, \ \text{and} \quad \beta_{s} = 0 \quad \text{for} \quad 2.5 \leq \overline{U}_{10N} < 8 \quad \text{m} \quad \text{s}^{-1}, \ \text{for} \quad \beta_{s} = 0 \quad \quad$ 395 $\beta_s = \beta_c = 0$ and $\beta_g = 1$ for 8 m s⁻¹ $\leq \overline{U}_{10N}$. As can be determined from Fig. 3, the z_{0m} 396 values estimated using Eqs. 16-18 all agreed well with those from measurements obtained 397 using Eq. 11 for $\overline{U}_{10N} > 7$ m s⁻¹. For light winds, on the other hand, those from Eqs. 16-18 398tended to be much smaller than those from Eq. 11. Therefore, it appears that the effect of 399waves has a limited contribution to large C_D values under light wind conditions at Lake 400Kasumigaura (also see Fig. 1 (triangles) in which C_{DN} values converted from z_{0m} , derived 401 using Eq. 17, are shown). It is interesting to note that a C_{DN} increase as wind speed 402decreasing in the low wind-speed range was also reported under unstable conditions with 403measurements made over land surfaces where waves do not exist (e.g., Rao et al. 1996; Rao 404 2004; Zhu and Frust 2013). Nevertheless, to generalize our result, it is likely necessary that 405additional studies are undertaken under different conditions other than those for Lake 406407 Kasumigaura and that a dataset that includes measurements of wave direction is obtained. This is particularly needed for weak winds, since wind direction is likely more variable and 408409 waves may not be in equilibrium with winds. This will result in different wind and wave directions. 410

411

412 3.2.3 Methods of Averaging and Gustiness

Thus far, the analysis and results presented have been based on the vector-averaged wind speed,

415
$$\overline{U_{\nu}} \equiv \left(\overline{u}^2 + \overline{v}^2\right)^{1/2}$$
 (19),

416 and the flux

417
$$\tau / \rho = \tau_{v} / \rho = u_{*v}^{2} \equiv \left(\overline{w'u'}^{2} + \overline{w'v'}^{2}\right)^{1/2}$$
(20)

418 where u and v are the instantaneous horizontal wind components, and the subscript v419 indicates vector averaging. Defining averages for instantaneous scalar values is also 420 possible. Such operations would yield scalar averages, indicated by the subscript *s* and421 defined by

422
$$\overline{U_s} = \overline{\left(u^2 + v^2\right)^{1/2}}, \qquad (21)$$

423 and:

424
$$\tau / \rho = \tau_s / \rho = u_{*s}^2 \equiv \overline{\left(-w'u'^2 + w'v'^2\right)^{1/2}}.$$
 (22)

With the vector-averaging of wind speed, random perturbations in opposite directions tend to 425cancel out, while scalar-averaging preserves such components. Convection within the 426atmospheric boundary layer creates such random perturbations and gustiness near the surface 427(e.g., Schumannm 1988; Godfrey and Beljaars 1991; Mahrt and Sun 1995). Therefore, in 428general, $\overline{U_v} \leq \overline{U_s}$, and convection may need to be considered when Eq. 1 is applied using 429the vector-averaged wind speed. Since it was not considered in the analysis presented so far, 430it is possible that the underestimation of \overline{U} due to the omission of the perturbation 431component in $\overline{U_{\nu}}$ could have contributed to the increase of C_{DN} for small \overline{U} values. 432

In the derivation of C_D , averages obtained from both Eqs. 19 and 21 have been used 433previously for \overline{U} , while for fluxes, on the other hand, only Eq. 20 is commonly used. This 434is because in Eq. 22 dominant downward momentum fluxes and periodic upward momentum 435436fluxes are added as part of the total flux regardless of the flux direction. This type of total flux is generally not required and is therefore not used. Thus, C_D values have been 437determined either as the combination of Eqs. 19 and 20, or 21 and 20. Note, however, that 438for the Eq. 21 and 20 combination, relationships such as Eq. 12 may not hold because 439similarity theory requires vector averages for both wind speeds and fluxes. 440

In the present study, both averaging methods are available such that the magnitudes of $\overline{U_s}$ and $\overline{U_v}$ can be computed and compared with the 30-min dataset, to investigate whether the use of $\overline{U_v}$ could have influenced the large C_{DN} values for small \overline{U} values. We determined that the difference was negligible with the exception $\overline{U_s} < 3 \text{ m s}^{-1}$. For light wind conditions, the difference became significant and, in general, $\overline{U_s} \ge \overline{U_v}$. The r.m.s 446 difference between $\overline{U_s}$ and $\overline{U_v}$ for $0.5 \le \overline{U_v} < 3 \text{ m s}^{-1}$ was determined to be 0.05 m s⁻¹ 447 and was significant at the 0.05 level. To investigate the impact on the determination of C_{DN} , 448 C_{EN} and C_{HN} , both were used in Eqs. 1-3 in order to compare the resulting values. The 449 outcome is provided in Fig. 1 as open circles and asterisks. As expected, smaller drag 450 coefficients were derived from $\overline{U_s}$. However, the r.m.s difference of C_{DN} for the 451 $0.5 \le \overline{U_v} < 3 \text{ m s}^{-1}$ wind-speed range was as small as 1.8×10^{-3} and did not change the 452 general trend for an increase of C_{DN} for small \overline{U} values.

Note that it is also possible to investigate the impact of adopting $\overline{U_{\nu}}$ to the C_{DN} value by following the suggestion of Godfrey and Beljaar (1991) to add the gustiness component, $\overline{u_g}$, using

456
$$\overline{u_{\sigma}} = \beta w_* = \beta (F_b z_i)^{1/3}$$
(23)

to vector-averaged wind speeds in order for them to be compatible with scalar averages sothat

459
$$\overline{U_s} = \overline{U_v} + \overline{u_g}.$$
 (24)

In the above formulations, $w_* \equiv (\overline{gw'\theta'_v} z_i/\overline{\theta})^{1/3}$ is the convective velocity scale (Deardoff 1970), and $F_b = \frac{g}{\overline{\theta}}(\overline{w'\theta'_v})$ is the buoyancy flux, where θ_v is the virtual potential temperature, z_i is the convective boundary layer height, and β is the ratio between the horizontal and vertical scales of the convection circulation. A value of $\beta = 0.8$ was suggested by Schumann (1988). Wei (2013) examined this approach by estimating z_i using measurements of surface sensible fluxes in and around Lake Kasumigaura and verified the relationship in Eq. 24. Thus this approach was not tested any further.

467 3.2.4 Interfacial/Transition Layers

468 Until now, the discussion provided has been based on an assumption that U was measured at 469 z within the surface layer where flux-profile relationships such as Eq. 11 are valid. However, 470 this may not necessarily be true and z may have been located below the surface layer inside

of interfacial/transition sublayers (e.g., Smedman et al. 2003) where atmospheric stability and 471the roughness of the underlying surface may influence flow. For water surfaces, wave 472parameter(s) may need to be included within the profile-flux relationship. An attempt to 473estimate the interfacial/transition sublayer height, z_c , was undertaken by Cheng and 474475Brustsaert (1972) who concluded, based on dimensional arguments, that z_c was a function of C_p/u_* and the roughness length. For the wave-age range of $5 < C_p/u_* < 18$, as 476encountered at the Koshin observatory during the observation period, the largest z_c value 477can be estimated from Fig. 1 and Eq. 16 from Cheng and Brustsaert (1972) to be 0.5 m (for 478 $z_{0m} = 10^{-5}$ m) and 5 m (for $z_{0m} = 10^{-4}$ m), both for $C_p/u_* = 18$. Thus, the measurement 479height of z = 9.8 m at the Koshin Observatory was likely within the surface layer. 480

To ensure that the measurement height was above the interfacial sublayer, a simple analysis was also performed to test if wave age has any influence to the flux-profile relationship. Thus the stability effect was removed first in Eq. 11 by replacing \overline{U} with \overline{U}_{10N} , determined by Eq. 4 and $\Psi_{\rm m}$ with Ψ given by,

485
$$\Psi = \Psi(C_p / u_*).$$
 (25)

486 Ψ should be around zero if z = 9.8 m was within the surface layer. If a relationship exists, 487 on the other hand, it tends to indicate that the measurement height was located within the 488 interfacial sublayer. The results (not shown) indicated that no clear relationship existed and 489 on average $\overline{\Psi} = 0$. Thus, it is indeed probable that measurements were made inside the 490 surface sublayer.

Since the interfacial sublayer tends to develop for cases of strong swell that, as stated 491above, are quite rare at Lake Kasumigaura, the result obtained above is likely reasonable. 492Observations by Smedman et al. (2003) provide support for this interpretation. They 493determined non-logarithmic wind profiles using 5-level measurements from a 30-m tower 494located at the ocean's surface when swell was important. For wind sea conditions, on the 495other hand, the wind profiles were determined to be logarithmic. The difference in the 496497results was interpreted to be the consequence of the development of the interfacial layer to a height of 10 m or more during a developing swell. 498

The averaging time T to be required in order to determine a meaningful first moment (i.e., the 500mean) and the second moment (such as the variance or covariance) is understood different 501and, in general, the higher the order of the turbulence moments the longer the requirement for 502T results (e.g., Wyngaard 1973). Thus, \overline{U} and u_* values for the same averaging time T 503may not fully represent turbulence on the same time scale. \overline{U} can potentially represent 504eddies of all relevant sizes while u_* only represents those of smaller sizes related to shorter 505time scales. When this circumstance occurs, a mismatch arises between the time scales of 506 \overline{U} and u_* and can lead to an unreliable value for C_D . Mahrt et al. (2001) examined this 507idea by comparing \overline{U} , τ , and C_D averaged over different T values (for T < 300 s) and 508determined that \overline{U} is almost always constant while τ and C_D increase for longer T values. 509We performed the same analysis using the 2-h dataset at T = 1 min intervals but for an 510averaging time of up to T = 60 min. 511

Two types of 2-h dataset, one that was produced following coordinate rotation in order to force $\overline{w} = 0$ and one without rotation, were analyzed. The overall result was not very different. Therefore, in the discussion that follows the result obtained without rotation is presented. For the analysis, the following equations were applied to each of the 2-h data records,

517
$$\bar{u}_T = \frac{1}{T} \int_{t-T/2}^{t+T/2} u dt , \qquad (26)$$

518
$$\overline{u'w'}_T = \frac{1}{T} \int_{t-T/2}^{t+T/2} (u - \overline{u_T})(w - \overline{w_T}) dt , \qquad (27)$$

where overbars indicate time averaging over the period $(t - T/2) \le t < (t + T/2)$. The application of Eqs. 26-27 was possible for the 2/*T* number of segments within the 2-h period (if the unit of time for *T* was hours and fractions are ignored), using moving windows without overlaps of the data. For example, for T = 1/6 h, N = 12 segments existed within the 2-h data. The resulting 2/*T* sets of results for the same averaging period, *T*, were averaged using

524
$$\overline{U}_T = \frac{1}{N} \sum \left(\overline{u}_T \right)_i, \qquad (28)$$

$$\overline{U'W'}_T = \frac{1}{N} \sum \left(\overline{u'w'}_T \right)_i, \qquad (29)$$

526 and, they were used to determine the average C_{D} ,

527

$$\overline{C_D}_T = \frac{\left(-U'W'_T\right)}{\overline{U}_T^2}.$$
(30)

As the averaging time, *T*, becomes longer, the smaller the number of samples. Therefore, the magnitude of the error for \overline{U}_T and $\overline{U'W'}_T$ tends to be larger for a larger value of *T*.

Figure 4 provides $\overline{U'W'}_{T}/\overline{U'W'}_{60 \min}$, $\overline{U}_{T}/\overline{U}_{60\min}$, and $\overline{C}_{D_{T}}/\overline{C}_{D_{60\min}}$ as a function of the averaging time, *T*. As is clear from Fig. 4, \overline{U}_{T} quickly comes to a constant value for *T* <20-30 min while it takes longer (approximately T > 30-60 min) for $\overline{U'W'}_{T}$ and $\overline{C}_{D_{T}}$ to reach similar constant values. Based on these results, a mismatch of the time scale is indeed

possible for a shorter averaging time of approximately T < 30 min. However, when T =30-60 min is adopted, as is often the case, such an outcome is generally not a concern and the averaging time is not likely to be the cause of large C_D values for a small \overline{U} , at least for Lake Kasumigaura. The time scales that have physical relevance to the unstable surface layer proposed in the past (see e.g., Metzger and Holms, 2008) are also listed in Table 3. Clearly, those time scales are equal to or smaller than T = 30 min, supporting our finding given above.

541 3.2.6 Turbulence Intensity and Atmospheric Stability

542As mentioned in the Introduction, Mitsuta and Tsukamoto (1978) suggested that an increase in turbulence intensity due to thermal origin was the cause of the increase in C_D for small \overline{U} 543The same analysis together with some additional investigation was performed using 544values. the 2-h dataset, to see if the same conclusion can be obtained. Each of 2-h data records was 545further divided into 30-min segments in order to increase the number of data points and they 546were again screened using the same data selection procedure described above. Based on the 547procedure, 25 high quality segments were retained for our analysis. Results are provided in 548Fig. 5, where σ_u / \overline{U} , σ_w / \overline{U} , C_{uw} (the correlation coefficient for $\overline{u'w'}$, defined as 549 $\overline{u'w'}/(\sigma_u\sigma_w)$), σ_u , σ_w , σ_{θ} , C_D , and e (the turbulence kinetic energy, TKE) are plotted 550against \overline{U} . As in Mitsuta and Tsukamoto (1978), σ_u/\overline{U} and σ_w/\overline{U} were observed to 551increase as \overline{U} became smaller. The result was largely caused by a decrease in \overline{U} but 552

was also due to an increase in σ_w , indicating that turbulence was enhanced for smaller \overline{U} ranges. This turbulence enhancement was likely caused by intensified buoyant energy as suggested by Mitsuta and Tsukamoto (1978) since an increase in σ_{θ} was observed at the same time. Although there are other possible reasons, including vertical transport and pressure correlations, for increased turbulence, they were likely negligible because measurements were obtained within the surface sublayer.

This enhancement of turbulence was not very large and was on the order of e = 0.05m² s⁻² at the most. However, an introduction of a linear relationship of $u_*^2 = c_1 e$, with c_1 being the mean slope, as assumed by Bradshow et al. (1967) and Peterson (1969) and also experimentally verified by Zhu and Furst (2013) among others, should lead to:

563
$$C_D = c_1 e / \overline{U}^2. \tag{31}$$

Therefore, for a small range of \overline{U} , even a small increase in *e* should result in a large increase 564in C_{D} . From the data examined here, $c_1 = 0.21$ was obtained for $\overline{U} < 2.0$ m s⁻². So, an 565increase in e by 0.05 m² s⁻² should result in an increase in C_D of 0.017 for a typical small 566wind speed of $\overline{U} = 0.7 \text{ m s}^{-1}$. Figure 6 compares C_D values derived using Eq. 31 and those 567derived from Eq. 1 for the same 25 selected data segments, including those with \overline{U} < 2 m 568 s^{-1} . Clearly, a small increase in TKE for small wind speeds successfully reproduced the 569observed C_D increase when Eq. 31 was employed. However, good agreement was the result 570of calibration. In fact, a different value of $c_1 = 0.14$ was obtained if all of the data points 571were used. The use of this value would lead to a decrease in the estimated C_D values 572presented in Fig. 6. Nevertheless, unlike the other mechanisms tested above, an increase in 573TKE due to buoyant energy production successfully explained the order of magnitude C_D 574increase for the low wind-speed range. For complete understanding, TKE budget studies 575under weak wind conditions are required. 576

The above discussion can also be interpreted using a slightly different approach. When $\overline{U} \rightarrow 0$ and mechanical turbulence becomes weaker while buoyant turbulence increases, the correlation between u_* and \overline{U} should become weaker. For such a case, C_{DN} increase tends to be proportional to $(\overline{U}_{10N})^{-1/2}$ for $\overline{U}_{10N} \rightarrow 0$ as Eq. 1 implies.

Note that the above finding that buoyancy effect is the major cause of the increased 581 C_{DN} is in a way contradictory to the fact that our results such as Fig. 1 have been presented 582for neutral stability. Under neutral stability, buoyancy effects cannot play a major role. 583This apparent inconsistency was likely caused by the fact that C_{DN} , C_{HN} and C_{EN} were not 584measured variables but were derived from \overline{U}_{10N} from Eq. 4 and measured u_* under the 585assumptions that the profile equations, Eqs. 4-6, based on the traditional Monin-Obukhov 586similarity theory are valid and the stability Ψ_x functions are well established. They may 587not be true under strongly unstable condition. Grachev et al. (1998) also addressed a 588possible problem in the assumption to derive \overline{U}_{10N} that z_{0m} does not change with stability 589over water surfaces. Additionally, in the derivation process of \overline{U}_{10N} and C_{DN} , u_* values 590observed under non-neutral stratification are assumed unchanged and valid under neutral 591condition. This may not be true, either. For example, under neutral condition we may not 592be able to observe a very small u_* value that can easily be found under unstable condition. 593These assumptions are probably the causes of the inconsistency outlined above. In fact, 594even if C_D and \overline{U}_{10} were used in Fig. 1, the same features such as the increase in C_D at low 595wind speeds resulted. 596

597 3.3 Comparison with Previous Studies

We compared our finding, that the increased turbulence due to intensified buoyant energy is 598the main cause of the increase in C_D for the weak wind-speed range, to previous drag 599coefficient studies to assess the consistency with each other. As mentioned above, and as 600 shown in Fig. 1 and Table 1, an increase in C_{DN} for small \overline{U}_{10N} has been reported for many 601602 but not all cases. Those without increase are not in line with our result. A possible explanation is that only when unstable conditions dominate is an increase in C_{DN} the result 603 because of the role of buoyancy. Figure 1 and Table 1 indicate that larger increases in C_{DN} 604than expected for smooth flows were observed for the majority of datasets dominated by the 605606unstable case (light blue colour). The exceptions referenced above are those of Oost et al. (2002) and Fairall et al. (2003) whose datasets both represent largely unstable conditions. 607 608Also, the COARE3.0 algorithm (Fairall et al. 2003) was applied to our data, which resulted in almost constant C_{DN} values at small wind speeds (Fig.1, black dotted line). 609

610

Large increases of C_{DN} at low wind speeds were not reported for the datasets

obtained under stable condition (red). Under near neutral condition (green), such increases 611were obtained by Mitsuta et al. (1978) but not by Subrahamanyam and Ramachandran (2002). 612 As mentioned above, however, Mitsuta et al. (1978) did show increased turbulence due to 613 buoyancy at low wind speeds. Thus it is likely that these increased C_{DN} values were 614obtained in the unstable side of near neutral condition. Thus the hypothesis that a C_{DN} 615increase for small \overline{U}_{10N} occurs only in unstable condition is mostly supported by the 616 previous studies, and this is consistent with the idea that the intensified turbulence due to 617 buoyancy is the major cause of the increase in C_{DN} . However, a few cases are not in 618agreement with this, and more studies are desirable to reconcile this discrepancy. 619

Note that we have adopted the definition of C_{DN} , C_{HN} and C_{EN} and shown them as a function of \overline{U}_{10N} so a comparison to previous studies that represent traditional and widely accepted formulations could be undertaken. However, in view of the results obtained above, it can be argued that expressing C_{DN} as a function of other parameters such as $\theta_s - \theta$, in addition to \overline{U}_{10N} , is a more reasonable approach (for example, see Kara et al., 2005), although it is often not practical or convenient for end users of C_{DN} and bulk approaches to predict u_* .

627

628 4 Conclusions

We investigated the exchange of water vapour, heat, and momentum over Lake Kasumigaura, 629 630 Japan, dominated by mostly unstable conditions by focusing on the characteristics of the bulk transfer coefficients for momentum, heat, and water vapour. Derived neutral coefficients 631agreed with those previously reported over water surfaces for the larger wind-speed of \overline{U}_{10N} 632 > 4 m s⁻¹. In the low wind-speed region \overline{U}_{10N} < 3 m s⁻¹, approximately, an increase in 633 C_{DN} was determined when the mean neutral wind speed, \overline{U}_{10N} , at 10 m became smaller, in 634agreement with some, but not all, previously obtained results under unstable conditions. All 635known possible mechanisms for the increase were investigated using 30-min, as well as 2-h, 636 datasets. Among the possible mechanisms, the use of vector mean wind speed and the 637inclusion of the wave influence (particularly the use of capillary waves for estimation of 638aerodynamic roughness) were determined to have a minor role in the increase of C_{DN} for 639

640 $\overline{U}_{10N} \rightarrow 0$. An increase in turbulence kinetic energy, *e*, caused mainly by an increase in σ_w 641 for the weak wind range, and due to enhanced buoyant energy, appeared to be the major 642 cause of the increase under unstable atmospheric conditions. This idea is in accordance 643 with the majority of the results reported in previous studies. However, the discrepancy with 644 a few studies that did not show an increase of C_{DN} in weak wind speeds under unstable 645 condition remains unsolved.

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652

653 Appendix 1 Lake Kasumigaura: Its topographical and climatological characteristics

Figure A1 provides a map of Lake Kasumigaura and the surrounding area. Lake Kasumigaura mainly consists of Nishiura (172 km²), smaller water bodies (Kitaura (36 km²) and Sotonasakaura (6 km²)), and connecting rivers. The outlet of the lake is located approximately 15 km from the Pacific Ocean and is connected to the ocean through the Tone River. Approximately 30 km to the north-west of the lake is Mt. Tsukuba (877 m), the headwater region of the Kasumigaura watershed.

Figure A2 provides a histogram of the temperature difference between the water 660 surface and the atmosphere during the three-year observation period. Unstable conditions 661 clearly dominate in the region. Figure A3 provides two examples of diurnal meteorological 662 variables, and the radiation and energy balance observed on two typical sunny days during 663 summer and winter. Monthly changes for general climatic data as well as radiation and 664 energy balance were reported in Sugita et al. (2014). In general, sunny weather dominates 665during the winter and summer periods, while spring and autumn are characterized by 666 alternate sunny and cloudy conditions. 667

669 Appendix 2 Koshin observatory

Figure A4 provides a schematic view of the instruments at the Koshin Observatory that provided the data used in our study. Figure A5 provides a panoramic view from the turbulence sensors located 9.8 m above the water surface.

673

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Proposed Equations for C_{DN} , C_{HN} and C_{EN} (×10 ⁻³)	Height of measurement (z, m) , range of wind speeds $(m s^{-1})$, and stability (z/L)	Study area	Reference
$C_{DN} = 11.7 \overline{U}_{10N}^{-2} + 0.668$ $C_{HN} = C_{EN} = 2.79 \overline{U}_{10N}^{-1} + 0.66$	$z = 16$ $0 < \overline{U}_{10N} < 5.5$ $-8 < z/L < 0 \text{ (Unstable condition dominated)}$	North Atlantic	Dupuis et al. (1997)
$C_{DN} = C_{DN} = 0.138 \overline{U}_{10N} + 0.18$ $C_{HN} = 0.0814 \overline{U}_{10N} - 0.509$ $C_{EN} = 1.10 \pm 0.22$	$z = 23$ $2 < \overline{U}_{10N} < 15 (C_{DN}) \text{ and } 2 < \overline{U}_{10N} < 18 (C_{HN} \text{ and } C_{EN})$ $z/L: \text{ N/A} (\text{Unstable condition dominated}) (C_{DN})$ $-0.5 < z/L < 0.1 (\text{Unstable condition dominated}) (C_{HN})$ $-0.5 < z/L < 0 (C_{EN})$	Dutch coast	Oost et al. (2000, 2002)
$C_{DN} = 0.8366 + 0.0436 \overline{U}$ $C_{HN} = C_{EN} = 1.11 \pm 0.06.$	$z = 10$ $1 < \overline{U} < 14$ $-6 < z/L < 0 $ (Neutral condition dominated)	Western Tropical Indian Ocean	Subrahamanyam and Ramachandran (2002, 2003)
$C_D = 1.1 \overline{U}_{10N}^{-0.1475}$	z = 3 or 3.5 $0 < \overline{U}_{10N} < 3.75$ z/L: N/A	Indian Ocean	Parekh et al. (2011)

N/A: not available

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Table 1 Proposed functions for the drag and bulk coefficients based on measurements over water surfaces that include the wind-speed range of $< 3 \text{ m s}^{-1}$.

8	6	5
\sim	\sim	<u> </u>

Category	Item	Instrument	Sensor height	Sampling	Averaging
			(above/below	interval, type,	time (min)
			mean water	observation	
			surface) (m)	$period^1$	
Turbulence	3-component wind velocity and	Sonic anemometer (Gill	9.80	0.1 sec,	30
	temperature	Instruments Ltd., R3A)		continuous	
	H_2O and CO_2 concentration	Open path gas analyzer (LI-COR,	9.80	0.1 sec,	30
		Inc., LI-7500)		continuous	
Radiation	4-component radiation	4-component radiometer (Kipp &	4.29	5 sec,	30
		Zonen B.V., CNR-1)		continuous	
Temperature and	Air temperature and relative	Ventilated psychrometer within a	2.00, 3.72	5 sec,	30
humidity	humidity	radiation shied (REBS, Inc.)		continuous	
	Water surface temperature	Infrared radiation thermometer	4.27	5 sec,	30
		(Everest Interscience Inc.,		continuous	
		4000.4ZL)			
	Water temperature	Platinum resistance thermometer	-0.1, -1.0,	30 min,	Instantaneous
			-2.5	continuous	
Water surface	Wave height and period	Capacitance-type wave height	about –1	0.05 sec,	10
condition		meter (Denshi Kogyo Co. Ltd)		continuous	
	Lake water level	Water level meter (Yokogawa	-4	measured at 1	30
		Electric Corp., W-446-Z2)		sec interval	
				with running	
				averages of 20	
				data for	
				outputs.	

Lake current speed and	Electromagnetic current meter	-0.5	$2 \sec$	10
direction	(JFE Advantech Co., Ltd.,		2008/2/23-	
	COMPACT-EM)		2008/3/4	
	Acoustic Doppler current profiler	-5.7	0.125 sec	
	(Teledyne RD Instruments,	(data: from	2007/11/9-	
	Workhourse Sentinel ADCP	-0.25 to -4.75	2008/3/4	
	1200kHz	as the mean of		
		0.5-m layer)		

866 ¹ Entries without observation period: all from June of 2006 to present (2015/9)

Table 2 A summary of measurements.

	data	t (min)	\tilde{t} (min)	\tilde{t} (min)	<i>t</i> * (min)	t (min)	$t_{-}(\min)$		
	record	ι_c (IIIII)		<i>t</i> (IIIII)	i (iiiii)	$\iota_{\overline{U'W}}$ (mm)	$\iota_{\overline{U}}(\ldots)$		
	S1	19	20	24	4	57	8		
	S2	31	15	15	6	8	8		
	S3	27	20	6	4	44	3		
	S4	19	25	2	17	6	6		
	W1	17	1	12	3	20	17		
	W2	6	20	10	6	29	19		
	W3	8	15	11	8	18	21		
	W4	4	20	12	9	31	9		
871	t_c : the cospectral time scale	for $\overline{u'w'}$ define	ned as the time who	en the ogive cu	rve reaches its	asymptote (Oncley	v et al. 1996).		
872 873	\tilde{t}_{MR} : the multiresolution deco \tilde{t} : the convergence time scal	e of the vertica	e scale defined as t l velocity variance	the zero-crossing determined as	ng in the multir the minimum	resolution decompo time required to rea	sition of the flux ach $\sigma_{_{wT}} / \sigma_{_{w60mi}}$	ces (Howell and Mahrt 1997). nin = 0.99 (Sakai et al. 2001, Metzge	er
874	and Holmes 2008).								
875 876	t^* : the convective time scale z_i was estimated from the pea	defined as the k frequency of	ratio of the mixed	-layer depth ov ocity spectra b	er the convecti y the method o	ive velocity scale w f Liu and Ohtaki (1	* (Lilly 1968). 997).	The convective boundary layer heig	;ht
877	$t_{\overline{UW}}$: the characteristic time	for $\overline{U'W'}$ det	termined as the min	nimum time re	quired to reach	$\overline{U'W'}_T / \overline{U'W'}_{60 \min}$	= 0.99.		
878	$t_{\overline{U}}$: the characteristic time fo	r \overline{U} determin	ned as the minimur	n time required	to reach \overline{U}_T	$\overline{U}_{60 \min} = 0.99.$			
879	Table 3 The characteristic tir	ne scales of flu	xes and the mean	wind speed.					
880									

881 Figure caption

882 Fig 1 The neutral 10-m bulk coefficient, C_{DN} , and the equivalent bulk transfer coefficients C_{HN} and C_{EN} 883 obtained in this study (black colour) and those reported in previous studies (unstable condition: light blue, 884 neutral condition: green, and stable condition: red colours). Those from our observations are: 1) open 885 circles: from Eqs. 1-3 using vector averaged wind speeds from Eq. 19 and Eqs. 4-6; 2) asterisks: C_{DN}, C_{HN}, 886 and CEN values calculated from Eqs. 1-3 based on scalar averaged wind speeds obtained from Eq. 21 and 887 Eqs. 4-6; 3) black solid lines: Eqs. 8-10; 4) open triangles: C_{DN} values calculated using Eq. 12, Eq. 17, 888 and the vector averaged wind speeds calculated using Eq. 19 with Eq. 4; 5) black dotted lines: C_{DN} , C_{HN} , and C_{EN} values estimated by the COARE3.0 algorithm with the 30-min dataset. Each data point 889 represents the bin-average for a 0.5 m s^{-1} interval and its error bar (standard deviation). 890 The stability 891 range of Xiao et al. (2013) was deduced from Wang et al. (2014) and that of Fairall et al. (2003) from 892Weller and Anderson (1996). Data points of Mistuta and Tsukamoto (1978) were from Zhu and Furst 893 (2013). Geernaert et al. (1988), Bradley et al. (1991), Greenhut and Khalsa (1995), Subrahamanyam and Ramachandran (2003) and Xiao et al. (2013) gave their results for \overline{U}_{10} , and $\overline{U}_{10N} = \overline{U}_{10}$ was assumed 894 in the figure. Similarly, Greenhut and Khalsa (1995) gave C_D , and $C_{DN} = C_D$ was assumed in the figure. 895896

Fig 2 A comparison of wind speeds, \overline{U}_{10} , and water surface current speeds, \overline{u}_s , averaged over a 30-min period measured from 22 February 2008 through 18 March 2008.

899

900 **Fig 3** The relationship between momentum roughness length z_{0m} (in m) and \overline{U}_{10N} . The estimated 901 z_{0m} values were obtained by means of Eqs. 11, 13 (Brutsaert 1982), 14 (Charnock 1955), 15 (Wu 1968, 902 1994), 16 (Smith 1988), 17 (Bourassa et al. 2001), and 18 (this study).

903

904 Fig 4
$$\overline{U}_T / \overline{U}_{60 \min}$$
, $\overline{U'W'}_T / \overline{U'W'}_{60 \min}$, and $\overline{C}_{D_T} / \overline{C}_{D_{60 \min}}$ as a function of the averaging time, *T*. In the

905 left and middle panels for $\overline{U}_T / \overline{U}_{60 \text{ min}}$ and $\overline{U'W'}_T / \overline{U'W'}_{60 \text{ min}}$, the required T values $t_{\overline{u'w'}}$ and $t_{\overline{U}}$,

906 provided in Table 3, are shown using vertical lines of the same colour for each data record. In the right

907 panels for $\overline{C_D}_T / \overline{C_D}_{00min}$, estimates of the required time, based on several proposals (Metzger and Holmes,

908 2008) and as provided in Table 3, are shown for the S3 and W3 data records using vertical lines. Dashed

909 lines represent t_c , dotted lines \tilde{t}_{MR} , the dot-dashed line \tilde{t} , and the solid lines t^* .

911	Fig 5 The intensity of turbulence and the wind speeds. For the TKE value, the <i>y</i> -axis is broken at $e = 0.3$
912	and the y-axis scale for $e < 0.3$ is expanded to show changes for e over the small range.
913	
914	Fig 6 A comparison of C_D values derived from Eqs. 1 and 31. Closed circles represent data for $\overline{U} < 2$
915	m s ⁻¹ and open circles those for $\overline{U} > 2 \text{ m s}^{-1}$.
916	
917	Fig A1 A map showing the topography surrounding Lake Kasumigaura.
918	
919	Fig A2 Histograms showing the distribution of the temperature difference between the water surface (T_s)
920	and the atmosphere at $z = 3.72 \text{ m} (T_a)$.
921	
922	Fig A3 Time changes for: (a) Wind speed (U), water temperature (T_w) at $z = -1.0$ m, water surface
923	temperature (T_s), and air temperature (T_a) at $z = 3.72$ m. (b) The radiation balance, where S_u , S_d , L_u , L_d ,
924	and R_n represent upward shortwave radiation, downward shortwave radiation, upward longwave radiation,
925	downward longwave radiation, and net radiation, respectively. (c) Energy balance for the winter (15
926	January 2008) and summer (15 August 2008), where the storage term $Q = R_n - H - L_e E$. JST is Japan
927	Standard Time
928	
929	Fig A4 A schematic figure showing instrumentation on and around the Koshin Observatory.
930	
931	Fig A5 A panoramic view from the turbulence sensors at 9.8 m located above the water surface.
932	

907	Fig 5 The intensity of turbulence and the wind speeds. For the TKE value, the y-axis is broken at $e = 0.3$
908	m ² s ⁻² and the y-axis scale for $e < 0.3 \text{ m}^2 \text{ s}^{-2}$ is expanded to show changes for <i>e</i> over the small range.
909	
910	Fig 6 A comparison of C_D values derived from Eqs. 1 and 31. Closed circles represent data for $\overline{U} < 2$
911	m s ⁻¹ and open circles those for $\overline{U} > 2 \text{ m s}^{-1}$.
912	
913	Fig A1 A map showing the topography surrounding Lake Kasumigaura.
914	
915	Fig A2 Histograms showing the distribution of the temperature difference between the water surface (T_s)
916	and the atmosphere at $z = 3.72$ m (T_a).
917	
918	Fig A3 Time changes for: (a) Wind speed (<i>U</i>), water temperature (T_w) at $z = -1.0$ m, water surface
919	temperature (T_s), and air temperature (T_a) at $z = 3.72$ m. (b) The radiation balance, where S_u , S_d , L_u , L_d ,
920	and R_n represent upward shortwave radiation, downward shortwave radiation, upward longwave radiation,
921	downward longwave radiation, and net radiation, respectively. (c) Energy balance for the winter (15
922	January 2008) and summer (15 August 2008), where the storage term $Q = R_n - H - L_e E$. JST is Japan
923	Standard Time
924	
925	Fig A4 A schematic figure showing instrumentation on and around the Koshin Observatory.
926	
927	Fig A5 A panoramic view from the turbulence sensors at 9.8 m located above the water surface.
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