

Fluid Force Acting on the Hand during Sculling of a World-Class Synchronized Swimmer

一流シンクロナイズドスイマーのスクーリング時の手部流体力

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Introduction

Synchronized swimming is a competitive sport requiring the exposure of a portion of the body above the water surface. When a portion of the body is exposed above the water surface, buoyancy is reduced in proportion to the volume above the water surface; and therefore, to maintain a steady position in the water, a load-bearing capacity comparable to the reduced buoyancy must be generated. In synchronized swimming, a propulsion technique such as sculling (an arm stroke for generating propulsive force) is used to get upward propulsive force, so as to maintain a portion of the body above the water surface and perform the various movements. Earlier studies measuring the load above the water surface for basic performance positions reported that different positions produce different loads. For example, for a swimmer with a weight of 52 kg, the load is approximately 145 N in the vertical position with both legs raised above the water surface and the torso and head underwater, and approximately 83 N in the ballet leg position where one leg is lifted straight up in the back layout position; and synchronized swimmers choose the most suitable and efficient sculling methods for different loads (Homma 2000).

While sculling is the most basic technique in synchronized swimming, it is also an important technique, and considered the most difficult even for elite swimmers. Previous studies (Homma 2006, Homma et al. 2006, Homma et al. 2007) have investigated the movement characteristics of sculling by world-class synchronized swimmers and provided practical

suggestions for efficient sculling. However, the precise fluid forces involved in actual synchronized swimming movements remain unclear.

Currently, several studies are using pressure sensors for direct measuring of the pressure on the swimmer's hand, in order to estimate the fluid forces acting on the hand. Because the fluid force created by the hand will be reflected in the distribution of pressure on the surface of the hand, methods utilizing pressure sensors to collect real-time measurements of the pressure working on the hand are considered to be effective.

In this study, fluid forces acting on the hand will be estimated using a pressure distribution measuring method, with the aim of elucidating the characteristics of the fluid forces acting on the hand when subjected to different levels of load during sculling in synchronized swimming.

Methods

Participant

One female national-level synchronized swimmer participated in this study.

Trial Procedure

The swimmer was asked to perform a flat scull in a stationary back layout position (Figure 1), and a support scull in a stationary vertical position (Figure 2), under the following four conditions, for five seconds each: with no load, and with 1, 2, or 3 kg of weight attached to the waist. The swimmer was instructed to maintain the most elevated position possible, in a stable position.

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Figure 1. Back layout position



Figure 2. Vertical position

Experimental settings

Small pressure sensors (PS-05KC, Kyowa Electronic Instruments Co., Ltd.) were attached to six places on the swimmer's left hand, and pressure distribution was measured during the demonstrations using a sampling frequency of 200 Hz. With reference to Ozaki et al. (2009), the left hand was divided in a longitudinal direction into three areas, from the thumb to the space between the index finger and the middle finger (hereinafter the "thumb"), from the space between the index finger and the middle finger to the space between the middle finger and the ring finger (hereinafter the "middle"), and from the space between the middle finger and the ring finger to the little finger (hereinafter the "little"). The sensors were attached to each of these areas on the palm and the dorsal side of the hand. Figure 3 shows the parts of the hand to which the sensors were

attached. P1, P2, and P3 were attached to the index finger, the middle finger, and the ring finger on the dorsal side of the hand, respectively, and P4, P5, and P6 were attached to the ring finger, the middle finger, and the index finger on the palm side of the hand, respectively, near the metacarpophalangeal joint.

The sculling movement was recorded by a total of four cameras (with a shutter speed of 1/500 sec and a sampling frequency of 60 Hz). Two underwater cameras were installed on the bottom of the pool (CPT-30A-H2A, Fujifilm Co., Ltd.), one video camera (TK-C1381, VC KENWOOD Corporation) was installed at the viewing window on the sidewall of the pool, and one wireless video camera (WUC-265, Nihon Jimukoki Co., Ltd.) capable of recording underwater/above water shots at the same time was installed on the pool wall opposite the viewing window.

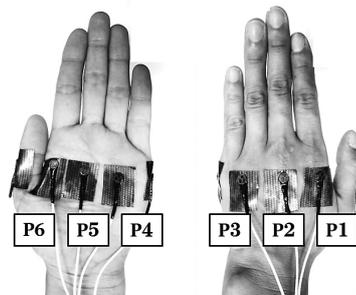


Figure 3. The parts of the hand to which sensors were attached

Data analysis

As sculling is a repetitive movement, one cycle of sculling was extracted from the stable demonstration and analyzed in this study. For the purpose of the study, a sculling cycle was considered to begin at the moment when the hands were closest to each other. The phase in which the hands move away from each other is called the out scull, and that in which the hands move towards each other is called the in scull.

The dynamic pressure acting on the hand was estimated by subtracting the static pressure on the pressure sensors from the pressure value measured during sculling, and by calculating the difference in the pressure value between the sensors on the palm and the dorsal side of the hand for each sensor on the index finger, middle finger, and ring finger. The hydrodynamic force was computed by considering the pressure measured in each area as a representative value, and by multiplying the estimated dynamic pressure by the projection area of the "thumb" for P1 and P6, by the

projection area of the “middle” for P2 and P5, and by the projection area of the “little” for P3 and P4. The projection area of each region was derived by drawing an outline of the hand on 1-mm square graph paper.

The following items were computed from the pressure value measured by the pressure sensors.

- F_{hand} (N): The resultant fluid force acting on the entire hand
- F_{vert} (N): The vertical direction component of F_{hand}
- P_{1-6} (Pa): The pressure value measured by the sensor on each area

Results

Flat scull

The change with time of F_{hand} for the flat scull is shown in Figure 4. The value of F_{hand} produced a double peak curve in which a peak was created in the stroke phase of the out scull and of the in scull. The maximum value of F_{hand} for the respective loads was 41.3 N for no load, 43.0 N for the 1 kg load, 41.2 N for the 2 kg load, and 40.5 N for the 3 kg load; all were observed during the out scull. Additionally, when the load was increased to 2 kg or greater, the maximum value and average value for the in scull increased.

The change with time of P_{1-6} for the flat scull with 3 kg load is shown in Figure 5. The changes in the pressure value show that when the value of F_{hand} was small, the difference in pressure between the palm and the dorsal side of the hand was small, and when the value of F_{hand} was large, the difference in pressure was large. This was not caused by increased pressure on the palm side, but by decreased pressure on the dorsal side of the hand.

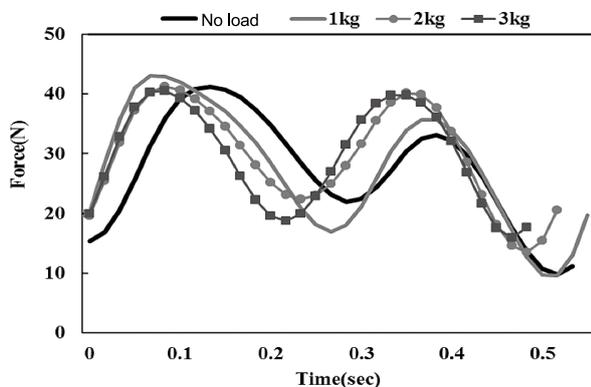


Figure 4. F_{hand} for the flat scull

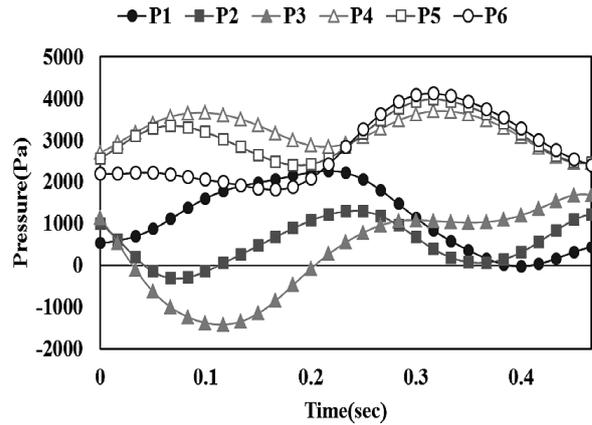


Figure 5. P_{1-6} when the load is 3 kg

Support scull

The change with time of F_{hand} for the support scull is shown in Figure 6. The maximum value of F_{hand} for the respective loads was 67.7 N for no load, 72.3 N for the 1 kg load, 76.7 N for the 2 kg load, and 75.7 N for the 3 kg load; all were observed during the in scull. The average value for the in scull increased as the load increased.

The change with time of P_{1-6} for the support scull with 3 kg load is shown in Figure 7. The changes in the pressure value show that when the value of F_{hand} was small, the difference in pressure between the palm and the dorsal side of the hand was small, and when the value of F_{hand} was large, the difference in pressure was large. This was not caused by increased pressure on the palm side, but by decreased pressure on the dorsal side of the hand.

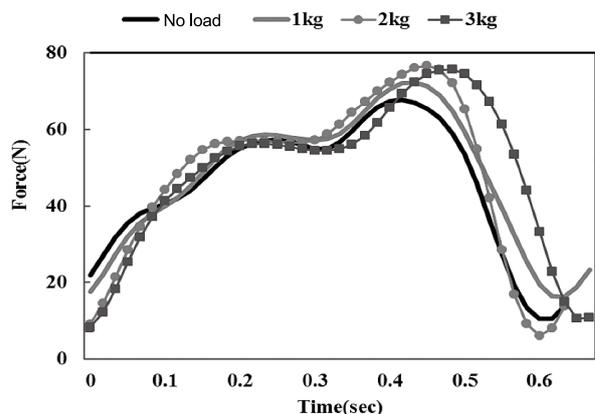


Figure 6. F_{hand} for the support scull

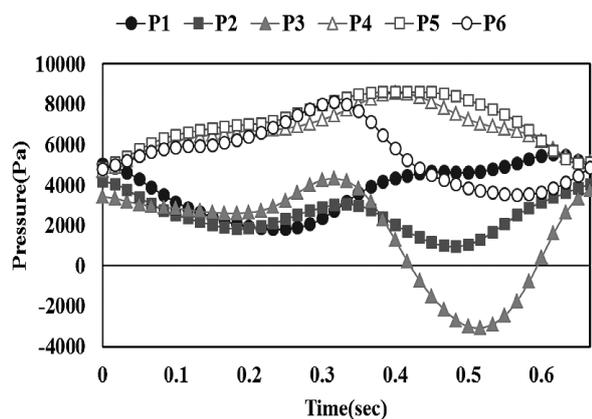


Figure 7. P_{1-6} when the load is 3 kg

Discussion

Flat scull

The value of F_{hand} for the flat scull produced a double peak curve in which a peak was created in the stroke phase of the out scull and of the in scull. All maximum values were observed during the out scull. When the load was increased to 2 kg or greater, the value for the in scull increased and indicated values similar to those of the out scull. Based on these findings, it may be concluded that when the load is small, the out scull by itself can generate a large fluid force, such that the in scull acts merely as a recovery movement of the out scull; but when the load increases, the power generated by the out scull alone becomes insufficient to bear the load, and for this reason, the in scull begins to be used to generate power, so as to cope with the load. As a result, the following description in a representative textbook for synchronized swimming may be said to be confirmed: “the pressure of the in scull and the out scull should be the same when sculling” (Homma 2006).

The changes in the pressure value of P_{1-6} showed that when the value of F_{hand} was small, the difference in pressure between the palm and the dorsal side of the hand was small, and when the value of F_{hand} was large, the difference in pressure was large. This was not caused by increased pressure on the palm side, but by decreased pressure on the dorsal side of the hand. Especially during the out scull, the sensor (P_3) near the little finger indicated a large negative value and during the in scull, the sensor (P_1) near the thumb indicated a low value. A similar trend was also observed under other loads. From these findings, it may be concluded that the pressure on

the dorsal side of the hand near the finger which is the first to move when the hand moves must be decreased to create large fluid force.

Support scull

The maximum value of F_{hand} for the support scull was entirely observed during the in scull. When the load was increased to 2 kg or greater, the maximum value also increased. A large teardrop-shaped sculling pattern, in which the hand moved toward the bottom of the pool and then drew a semicircle as it shifted from the out scull to the in scull, was observed (Homma et al. 2006); and the reason for this would appear to be that the movement of the hand which pushes water downward and then scoops it up generates large fluid force, composed largely of drag force.

The changes in the pressure value of P_{1-6} showed that when the value of F_{hand} was small, the difference in pressure between the palm and the dorsal side of the hand was small, and when the value of F_{hand} was large, the difference in pressure was large. This was not caused by increased pressure on the palm side, but by decreased pressure on the dorsal side of the hand. Especially during the out scull, the sensor (P_1) near the thumb indicated a low value; and during the in scull, the sensor (P_3) near the little finger indicated a large negative value. A similar trend was also observed under other loads. From these findings, it may be concluded that, as was the case for the flat scull, the pressure on the dorsal side of the hand near the finger which is the first to move when the hand moves must be decreased to create large fluid force.

Conclusion

The following summary results were obtained in this study on the fluid forces acting on the hand of a world-class synchronized swimmer when sculling.

- The largest value of the flat scull with no load in the back layout position was 41.3 N, observed during the out scull.
- The largest value of the support scull with no load in the vertical position was 67.7 N, observed during the in scull.
- It was apparent that in the case of both sculls, the fluid force increased as the load increased, and the pressure on the dorsal side of the hand decreased when large fluid force was generated.

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