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# The Integrated Theory of Selling and Buying Problems Based on the Concepts of Symmetry and Analogy (ver.002)

by

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#### Alice's Adventures in Wonderland\*

### The Integrated Theory of Selling and Buying Problems Based on the Concepts of Symmetry and Analogy

— ver.002 —

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#### Keywords

selling problem, buying problem, optimal stopping problem, search, symmetry, analogy, quitting penalty price, market restriction, recognizing time, staring time, initiating time, null time zone, deadline engulfing

#### Abstract

A trading problem can be classified into the following four types: a selling problem and a buying problem, each of which can be categorized as a problem with a reservation price mechanism (where the counter trader proposes the trading price) and a problem with a posted price mechanism (where the leading trader proposes the trading price). Let us refer to this group of four problems as the quadruple-asset-trading-problems. The main objective of this paper is twofold: to construct a general theory that integrates the quadruple-asset-trading-problems and to analyze fundamental models of these problems by using the theory. To achieve this objectives, several novel concepts are introduced: symmetry, analogy, initiating time, quitting penalty price, market restriction, etc. These concepts lead us to a new horizon that has not been previously explored by any researchers, including the authors of this paper. The most notable findings resulting from the analysis of these models are twofold: first, there is a significant breakdown of symmetry between the selling problem and the buying problem; second, the existence of null-time-zone, a time period during which any decision-making activity is entirely senseless. Particularly, the latter discovery challenges us to re-examine the entire discussions that have been conducted regarding conventional trading problems as decision-making processes. Moreover interestingly, when this zone encompasses all points in time on the planning horizon except the deadline, it follows that all decision-making activities scheduled throughout the entire planning horizon are engulfed by the deadline, which is reminiscent of all matter, even light, falling into a black hole. Lastly, we present an extensive range of models for asset trading problems that have not yet been proposed, concluding this study by emphasizing that the treatment of these problems is nearly impossible without the integrated-theory.

 $\heartsuit$ 

It was a spring afternoon in March, 1966, and the distant song of a bird filled the air. I was in the office of my academic supervisor Dr. (Eng.) Shizuo Senju. Sunbeams streamed through leaves, casting a gentle sway on window glasses. The professor silently rose from the chair and drew a picture of one apple on the blackboard. He turned to me and said "Would you take this apple? If you do, you can eat it and that will be the end of it. However, if you choose not to, this apple will disappear, and another one may appear—either greater or smaller than the one that vanished. In considering this situation, how would you decide whether or not to take this apple?". After a few moments of contemplation, the professor softly continued "Many decision problems in corporate management have a similar structure .... This is the subject of your master's thesis!". With that, he left the room. Even now, the sound of the chalk sliding on the blackboard echoes in the depths of my ears. With those words, he exited the room, leaving behind the lingering resonance of chalk sliding on the blackboard, a sound forever etched in the recesses of my memory.

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<sup>\*</sup>Readers will be bewildered by the indication in Alice 1(p.44), 2(p.46), and 3(p.46).

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### Abbreviations

ATP Asset Trading Problem ASP Asset Selling Problem ABP Asset Buying Problem Asset Trading Model ATMAsset Selling Model ASM ABM Asset Buying Model Lemma in Total market (F) Tom Lemma in Positive market  $(\mathscr{F}^+)$ Pom Lemma in Mixed market  $(\hat{\mathscr{F}}^{\pm})$ Mim Nem Lemma in Negative market  $(\mathscr{F}^-)$ Assertion A.A  $\mathcal{A}$ ssertion system  $\mathbb{R}$ Reservation price mechanism P Posted price mechanism M:x[X][X]Model of asset selling problem  $(x = 1, 2, 3, \mathbb{X} = \mathbb{R}, \mathbb{P}, \mathbb{X} = \mathbb{A}, \mathbb{E})$ M:x[X][X]Model of asset buying problem  $(x = 1, 2, 3, \mathbb{X} = \mathbb{R}, \mathbb{P}, \mathbb{X} = \mathbb{A}, \mathbb{E})$ Q(Models)quadruple-asset-trading-models  $\mathcal{S}(\mathsf{Models})$ structured unit of models SOE System of Optimality Equations [soé] OIT Optimal-Initiating-Time [òuít] d0ITs degenerate OIT to the starting time dOITd degenerate OIT to the deadline ndOIT nondegenerate OIT optimal decision rule h odr  ${\tt Conduct}{\leadsto}{\tt Skip}$ switch from search-Conduct to search-Skip  $\rightarrow$  C $\rightarrow$ S / $(C \rightarrow S)$ Skip⊸Conduct switch from search-Skip to search-Conduct  $\rightarrow$  S $\leadsto$ C /S $\leadsto$ C Null-TZ Null-Time-Zone [n\u00e1lti:z\u00e1:] tE-case tackle-Enforced-case tA-case tackle-Allowed-case sE-case search-Enforced-case sA-case search-Allowed-case tE-model tackle-Enforced-model tackle-Allowed-model tA-model sE-model search-Enforced-modelsA-model search-Allowed-model iiE-Case immediate-initiation-Enforced-case immediate-initiation-Allowed-case iiA-Case iiE-model ${\tt immediate-initiation-Enforced-model}$ iiA-model immediate-initiation-Allowed-model switch from "Conduct-search" to "Skip-search" C/S-switch C⊶S abbreviation of C/S-switch

switch from "Skip-search" to "Conduct-search"

abbreviation of S/C-switch

future subject reference of F.S.

# Symbols

F.S.

migration

# Part 1

# Introduction

This part provides all the necessary information required before the construction of the integrated-theory in Part 2 (p.51).

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# Preface

### 1.1 Two Motives

First, let us consider the fact that an economic behaviour is fundamentally constituted by various types of transactions. Different models for trading assets (house, car, a lot of land,  $\cdots$ ), commodities (wheat, copper, gasoline,  $\cdots$ ), and goods (fruit, fish, clothes,  $\cdots$ ) have been proposed and examined thus far. The trading problem can be classified into the following four types: an asset selling problem<sup>†</sup> and an asset buying problem, each of which falls into the two categories. One where a leading-trader (a primary party in a transaction) proposes a trading price, the other where an counter-trader (a counter party in the transaction) proposes a trading price. We refer to these four types of trading problems as the *quadruple-asset-trading-problems*. While considering the four problems, two questions as shown below naturally come to appear. The exploration of these questions has formed the two main motivations that have driven the present paper.

#### Motive 1 Is a buying problem always symmetrical to a selling problem?

Long before the inception of this study, we held a naive perspective on the selling and buying problems: "Could a buying problem always be symmetrical to a selling problem?" In other words, If we understand the nature of a seller's problem, could we immediately grasp the nature of its corresponding buyer's problem by merely altering the signs of variables, parameters, constants, etc. defined in the seller's problem? While this context, most researchers, including the authors of this study, paid little attention to the aforementioned simplistic viewpoint. However, our ultimate response to this viewpoint is a resolute "no!"

### Motive 2 Is it possible for a general theory integrating quadruple-asset-trading-problems to exist?

Before beginning to write this paper, we extensively reviewed numerous papers related to the buying and selling problems and naturally developed a preliminary expectation that there could potentially be a "common denominator" underlying all discussions presented therein. This intuition guided us to the insight (realization) that this common denominator is closely connected to a function known as the T-function (refer to Section 6.1.1(p.25)). Urged by this insight, we soon developed a faint anticipation that a general theory integrating the quadruple-asset-trading-problems could exist. As we delved deeper into our exploration, a ray of hope emerged that constructing such a theory might indeed be possible. This hope was buoyed by introducing the concepts of symmetry (see Chap. 13(p.69)) and analogy (see Chap. 14(p.89)). Fortunately, our work (attempt) over an extended period led to the successful construction of this theory (see Chap. 17(p.115)).

### 1.2 Philosophical Background of This paper

Before proceeding with our discussions, let us outline the philosophical background that underpins the entire writing of this paper.

### 1.2.1 Outset

When I (Ikuta) was a high-school student (1958), during a physics lesson, the teacher placed one cotton ball and one iron ball in a glass tube of one-meter length, setting it upright. Not surprisingly, the iron ball fell with a thud, and the cotton ball fell slowly as if chasing the iron ball. Afterward, the air in the tube was evacuated with a turn of the motor switch, and the tube was again set upright. This time, both balls fell alongside. Why? A surprise passed through my mind. The teacher then drew a picture and explained the rationality of this phenomenon; it was my first introduction to the power of real experiments and thought experiments in physics. After an interval, he mentioned that Galileo conducted an experiment of a free fall in the Tower of Pisa and harked back that it took several thousand years to recognize the shift from the earth-centered theory to the sun-centered

 $<sup>^{\</sup>dagger}[30,1962],\ [32,1963],\ [3,1977],\ [38,1983],\ [37,1983],\ [40,1990],\ [7,1991],\ [33,1993],\ [44,1993],\ [36,1995],\ [27,1995],\ [45,1995],\ [47,1997],\ [9,1997],\ [12,1998],\ [20,1999],\ [11,1999],\ [13,2001],\ [35,2002],\ [11,2002],\ [15,2004],\ [19,2005],\ [16,2005]$ 

<sup>&</sup>lt;sup>‡</sup>[9,1998], [11,2002]

theory (the Copernican revolution). Shortly afterwards, the teacher tossed a sponge ball from the platform toward us (students) and explained that the trajectory of an object tossed over forms a parabola expressed by the quadratic curve. Without air, a speed at which an object thrown horizontally will loop back around the earth, drawing a circular orbit, is approximately 7.9 kilometers per second, and the speed at which it flies out of the orbit is about 11.2 kilometers per second. After graduating from high-school, I enrolled in the engineering department of Keio University, where I learned high-level physics. In the spring afternoon of March, 1966, I visited the laboratory office of my academic supervisor, Dr. Professor Shizuo Senju (see the episode on the title page of this paper). In the process of this personal history, I gradually came to recognize not only natural phenomena but also human behaviors physically. This is the fundamental outset that has influenced the entirety of my investigative life.

### 1.2.2 Decision Theory as Physics

Basically, every human being's behavior is influenced by their underlying philosophical background. Therefore, naturally, the authors (Ikuta & Kang, both holding D.Eng.) consistently approached their research with a deep-rooted focus on the physical perspective. Physics, described as a scientific pursuit unraveling the mysteries of natural phenomena, is seen by the authors as a research discipline that necessitates unfiltered observation of a subject, free from preconceived premises, assumptions, hypotheses, or preconceptions. It requires researchers to actively engage both ears and eyes in observing the research object, calmly listening to every sound from its depths and carefully observing every light emerging within. While the authors are open to integrating concepts, knowledge, and techniques from business administration, economics, and mathematics as necessary, their core viewpoint is that decision processes are inherently connected to human-driven physical phenomena. Therefore, the decision theory discussed in this paper, for the authors, is a decision theory as physics—always the starting point and the ultimate perspective. If we were not researchers in the field of natural science, this paper would not saw the light of day at all in this world.

### 1.3 Structure of Asset Trading Problems

The section provides an overview of asset trading problems.

### 1.3.1 Definitions of Terms

Before proceeding, let us establish definitions for some key terms that will be used in our upcoming discussion.

- For the subject matter of transaction, whether properties, commodities, or goods, we refer to it as the asset in a general term
- For the decision-making problem related to the trading of asset, we refer to it as the asset trading problem, ATP for short, consisting of asset selling problem and asset buying problem, simply ASP and ABP respectively.
- For the parts involved in a trading, we use the terms "leading-trader" and "counter-trader" to distinguish between the part leading the trading and its counterpart. Accordingly, in ASP (ABP), the seller (buyer) is a leading-trader and the buyer (seller) is an counter-trader.

### 1.3.2 Asset Trading Problem (ATP)

Below, let us conceptualize the asset trading problem as a drama involving a leading-trader and an counter-trader on unfolding two scenes below:

- ullet Scene  $\mathbb R$  in which
  - o first a counter-trader appears and posts his trading price,
  - then a leading-trader appears and answers whether or not to accept it based on his reservation price.
- ullet Scene  ${\mathbb P}$  in which
  - o first a leading-trader appears and posts his trading price,
  - o then a counter-trader appears and answers whether or not to accept it based on his reservation price.

Let us refer to the trading in Scene  $\mathbb{R}$  (Scene  $\mathbb{P}$ ) as the asset trading problem with the reservation price mechanism (posted price mechanism), simply ATP with  $\mathbb{R}$ -mechanism (ATP with  $\mathbb{P}$ -mechanism), further abbreviated as

$$\mathsf{ATP}[\mathbb{R}]$$
 ( $\mathsf{ATP}[\mathbb{P}]$ ).

The above asset *trading* problem (ATP) can be translated into the asset *selling* problem (ASP) and the asset *buying* problem (ABP) as below.

 $<sup>^\</sup>dagger A$  threshold based on which it is judged whether or not to accept it.

 $<sup>\</sup>P{[4,1995],[6,2001]}$ 

 $<sup>^{\</sup>parallel}[5,1998],\![6,2001],\![21,1994],\![44,1993],\![45,1995]$ 

### 1.3.3 Asset Selling Problem (ASP)

In the asset selling problem, a leading-trader is a seller and its counter-trader is a buyer, hence the drama of the above asset trading problem (ATP) can be rewritten as below:

### Scene $\mathbb{R}$ in which

- o first a buyer (counter-trader) appears and posts his buying price,
- o then a seller (leading-trader) appears and answers whether or not to accept it based on his reservation price.

#### Scene P in which

- o first a seller (leading-trader) appears and posts his selling price,
- o then a buyer (counter-trader) appears and answers whether or not to accept it based on his reservation price.

Let us refer to the selling problem in Scene  $\mathbb{R}$  (Scene  $\mathbb{P}$ ) as the asset selling problem with reservation price mechanism (posted price mechanism), simply ASP with  $\mathbb{R}$ -mechanism ( $\mathbb{P}$ -mechanism), further abbreviated as

$$\mathtt{ASP}[\mathbb{R}]$$
 ( $\mathtt{ASP}[\mathbb{P}]$ ).

The following two examples convey a flavor of the models of the above asset selling problem, which mirror the "mental conflict" of a seller (leading-trader) in the above drama.

□ Example 1.3.1 (Scene ℝ) Suppose you (seller, leading-trader) have to sell your car by a specified deadline due to a compelling reason, such as being required to suddenly return to your mother country by order of the head office when you are stationed in a foreign country. A potential buyer (counter-trader) has just appeared. In this situation, if the buyer offers a high buying price, you would likely sell the car. However, if the offered price is very low, you might hesitate. In either case, you are faced with a decision that involves the following risks. Selling the car carries the risk of missing out a higher-paying buyer that may appear in the future. On the other hand, not selling the car carries the risk that a higher-paying buyer may not appear before the deadline, or even worse, no buyers may appear at all, leading to the necessity of selling the car at a very low price (a giveaway price) or incurring costs to dispose of it. Considering these risks, you must decide whether or not to sell your car to each successive buyer. This perspective implies that, as the deadline approaches, it is necessary to gradually lower the minimum permissible selling price (referred to as the reservation price). This expectation reflects a mental conflict of you (seller as a decision-maker) that you must more and more become "selling spree" as the deadline approaches. □

The above example is what has been defined and investigated under the name "optimal stopping problem"; To the best of the authors' knowledge, the earliest papers related to the problem can be traced back to 1960's [43,1961][30,1962][10,1971][34,1973].

 $\Box$  Example 1.3.2 (Scene  $\mathbb{P}$ ) In the same example as mentioned above, let us suppose that you set a selling price for your car to buyers who appear successively in front of you. In the situation, if you set your price too low, a buyer will buy the car, conversely, if your price is excessively high, the buyer will leave (walk away). This indicates that selling the car at a low posted price carries the risk of missing an opportunity that a potential buyer willing to pay a higher price appears in the future. On the other hand, setting a high posted price carries the risk of no buyer appearing before the deadline, or even being compelled to sell your car at a significantly reduced price (a rock-bottom price) or dispose of it at a cost. Considering these risks, you must decide whether or not to sell your car to each successive buyer. Similarly to in Example 1.3.1(p.5), this perspective implies that, as the deadline approaches, it is necessary to gradually lower the selling price to propose (referred to as the proposed price). This expectation reflects a mental conflict of you (seller as a decision-maker) that you must more and more become "selling spree" as the deadline approaches.  $\Box$ 

### 1.3.4 Asset Buying Problem (ABP)

In the asset buying problem, a leading-trader is a buyer and its counter-trader is a seller, hence the drama of the asset trading can be rewritten as below:

### Scene $\mathbb{R}$ in which

- o first a seller (counter-trader) appears and posts his selling price,
- o then a buyer (leading-trader) appears and answers whether or not to accept it based on his reservation price.

### Scene $\mathbb{P}$ in which

- o first a buyer (leading-trader) appears and posts his buying price,
- then a seller (counter-trader) appears and answers whether or not to accept it based on his reservation price.

Let us refer to the buying problem in Scene  $\mathbb{R}$  (Scene  $\mathbb{P}$ ) as the asset buying problem with reservation price mechanism (posted price mechanism), simply ABP with  $\mathbb{R}$ -mechanism (ABP with  $\mathbb{P}$ -mechanism), further abbreviated as

$$ABP[\mathbb{R}]$$
 ( $ABP[\mathbb{P}]$ ).

One may say that since the following two examples seem to be *mere inverses* of the asset selling problem, they are redundant and unnecessary. However, it will be known later on that fine differences between the asset selling problem and the asset buying problem produces a significant difference between both.

□ Example 1.3.3 (Scene ℝ) Suppose you (buyer, leading-trader) have to buy a car by a specified date (deadline) due to the need to secure a car hastily for daily life and commuting upon returning from a foreign assignment, and then you find a potential seller. In this situation, if the price offered by the seller is low enough, you will buy the car from the seller. However, if it is very high, you will hesitate to buy. Buying the car carries the risk of missing an opportunity that you can find a potential seller offering a lower price in the future. On the other hand, not buying a car carries the risk that a lower-offering seller may not appears before the deadline. Considering these risks, you must decide whether or not to buy a car from each successive seller. This perspective implies that, as the deadline approaches, it is necessary to gradually raise the maximum permissible buying price (referred to as the reservation price). This expectation reflects a mental conflict of you (buyer as a decision-maker) that you must more and more become "buying spree" as the deadline approaches. □

 $\Box$  Example 1.3.4 (Scene  $\mathbb{P}$ ) In the same example as mentioned above, let us suppose that you propose your buying price to a potential seller. Then, if your proposed price is high enough, the seller will sell the car, conversely, if it is very low, the seller will reject the offer. Buying the car carries the risk that a seller offering a lower price may appear in the future. On the other hand, not buying a car carries the risk that a lower-offering seller may not appear before the deadline. Considering these risks, you must determine your buying price to propose. Similarly to in Example 1.3.3(p.6), this perspective implies that, as the deadline approaches, it is necessary to gradually raise the buying price to propose (referred to as the proposed price). This expectation reflects a mental conflict of you (buyer as a decision-maker) that you must more and more become "buying spree" as the deadline approaches.  $\Box$ 

### 1.3.5 Quadruple-Asset-Trading-Problems

Let us refer to the set of the four asset trading problems  $ASP[\mathbb{R}]$ ,  $ASP[\mathbb{R}]$ ,  $ASP[\mathbb{R}]$ , and  $ABP[\mathbb{R}]$  defined above as the *quadruple-asset-trading-problems*, represented as

$$qATP = \{ASP[\mathbb{R}], ABP[\mathbb{R}], ASP[\mathbb{P}], ABP[\mathbb{P}]\}. \tag{1.3.1}$$

The interconnectedness among these problems are somewhat akin to a drama played across the *looking glass*, depicted as in Figure 1.3.1(p.6) below.

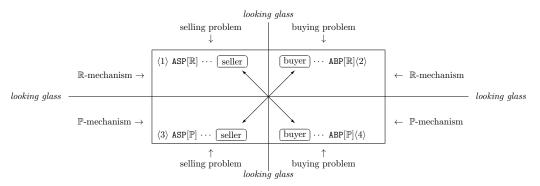


Figure 1.3.1: Interconnectedness among the quadruple-asset trading-problems

The aslant arrows X in the above figure symbolizes a drama which revolves between a leading-trader in ASP and a leading-trader in ASP, i.e.,

- $\circ$  The leading-trader buyer in  $\langle 4 \rangle$  ABP[P] faces the leading-trader seller in  $\langle 1 \rangle$  ASP[R],
- $\circ$   $\checkmark$  The leading-trader buyer in  $\langle 2 \rangle$  ABP[ $\mathbb{R}$ ] faces the leading-trader seller in  $\langle 3 \rangle$  ASP[ $\mathbb{P}$ ],
- o  $\nearrow$  The leading-trader seller in  $\langle 3 \rangle$  ASP[ $\mathbb{P}$ ] faces the leading-trader buyer in  $\langle 2 \rangle$  ABP[ $\mathbb{R}$ ].

### 1.3.6 Symmetry and analogy

The concepts of symmetry and analogy play pivotal role in the construction of the integrated-theory as stated in Motive 1(p3). We delve into these concepts further, illustrating their significance in Figure 1.3.2(p.7) below.

- (i) A symmetry is observed between  $\langle 1 \rangle$  ASP[ $\mathbb{R}$ ] and  $\langle 2 \rangle$  ABP[ $\mathbb{R}$ ],
- (ii) Similarly, symmetry relation between  $\langle 3 \rangle$  ASP[P] and  $\langle 4 \rangle$  ABP[P],
- (iii) An analogy is drawn between  $\langle 1 \rangle$  ASP[ $\mathbb{R}$ ] and  $\langle 3 \rangle$  ASP[ $\mathbb{P}$ ],
- (iv) Likewise, an analogy is evident between  $\langle 2 \rangle$  ABP[ $\mathbb{R}$ ] and  $\langle 4 \rangle$  ABP[ $\mathbb{P}$ ].

<sup>&</sup>lt;sup>†</sup>The leading-trader (buyer) in  $\langle 4 \rangle$  ABP[P] is an counter-trader from the standpoint of the leading-trader (seller) in  $\langle 1 \rangle$  ASP[R].

 $<sup>^{\</sup>ddagger}$ The leading-trader  $\overline{\text{(seller)}}$  in  $\langle 1 \rangle$  ABP[ $\mathbb{R}$ ] is an counter-trader from the standpoint of the leading-trader  $\overline{\text{(buyer)}}$  in  $\langle 4 \rangle$  ASP[ $\mathbb{P}$ ].

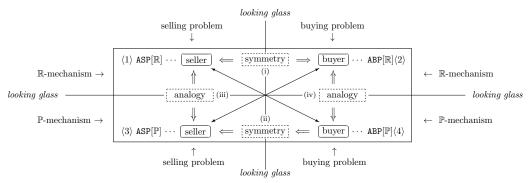


Figure 1.3.2: Symmetry and analogy among the quadruple-asset-trading-problems

Roughly speaking, the two concepts implies the following. The symmetry relation in each of (i) and (ii) means that for each of  $\mathbb{X} = \mathbb{R}, \mathbb{P}$ , a given simple *transformation* of some variables in an assertion on  $ASP[\mathbb{X}]$  yields its corresponding assertion on  $APP[\mathbb{X}]$  and vice versa, and the analogy relation in each of (iii) and (iv) means that a given simple *replacement* of some variables in an assertion on  $APP[\mathbb{R}]$  by others yields its corresponding assertion on  $APP[\mathbb{P}]$  and vice versa. The strict definitions of symmetry and analogy will be given in Chaps. 13(p.69), 14(p.89), 15(p.101), and 16(p.111).

### 1.4 Highlights of This Paper

Before we proceed with our discussions, let us outline the key points of this paper.

### H1. Recognizing time, starting time, initiating time, stopping time, and deadline

The above five points in time (see Section 8.1(p.43)) are essential requisites for "a decision theory as physics" (see Section 1.2(p.3) and  $\overline{\overline{C}}$ ??(p.??)). Below are summaries of implications that they have:

### a. Recognizing time

A decision is, after all, what is made by a human-being; accordingly, it eventually follows that a behaviour of "decision" first materializes only when being recognized in the bottom of heart of a person; let us refer to the time point of this recognition as the *recognizing time*  $t_r$ . Now, when a decision-making problem is recognized, the first question to answer is whether or not it is enforced to tackle with the decision problem.

- i. tE-case: Let us refer to the former case as the *tackle-Enforced-case*. In this case, even if it is known to yield no profit when tackling the problem, a decision-maker must accept the red ink.
- ii. tA-case: Let us call the latter case the *tackle-Allowed* (not enforced) case. In this case, a decision-maker has the option "whether to tackle the problem or not". Therefore, when it is known that no profit yields even if tackling the problem, it suffices not to tackle it.

### b. Starting time

Whether in tE-case or when it is determined to tackle the problem in tA-case, after a period of preparation, it arrives at the time when the decision-maker can *start* to initiate the attack of the decision-making problem. Let us refer to the time point as the *starting time*  $\tau$ .

### c. Initiating time

Before moving further on ahead, let us suppose the following two cases related to "whether or not it is enforced to immediately initiate the attack of the problem at the starting time  $\tau$ ":

- i. iiE-Case: The case in which it is *enforced* to immediately initiate the attack, called the *immediate-initiation-enforced-case*.
- ii. iiA-Case: The case in which it is allowed (not enforced) to immediately initiate the attack, called the immediate-initiation-allowed-case. In this case, it is possible to postpone its initiation; in other words, we have the options "initiation at the starting time  $\tau$ ", "initiation at the time  $\tau 1$ ", ..., "initiation at the deadline (time 0)". Then, if it is determined to initiate the attack of the decision-making problem at time t ( $\tau \ge t \ge 0$ ), then let us refer to this time point as the initiating time  $t_i$ . Here it is naturally questioned what is the optimal initiating time, denoted by  $t_{\tau}^*$  (see Section 8.2.4.1(p.44)).

#### c. Stopping time

When the attack of the decision-making problem initiates at the optimal initiating time  $t_{\tau}^*$  and then the asset's sale (in ASP) or the asset's purchase (in ABP) occurs thereafter, the process stops at that time. We refer to this point in time as the *stopping time*  $t_s$ .

### d. Deadline

In this paper, from a practical viewpoint, we stress that a decision process with an infinite planning horizon is a product of mathematical imagination beyond the real world; in fact, considering a planning horizon spanning over 135 hundred

millions years is nonsensical and futile. Therefore, in this paper, we will focus on only models with *finite* planning horizons. Then, let us refer to the terminal (final) point in time of the decision process as *deadline*. However, we can have the two reasons for which it becomes still meaningful to discuss the model with the *infinite* planning horizon. One is that it can become an approximation for the models with an enough long (finite) planning horizon, the other is that results mathematically derived from it can provide an important information for the analyses of models with the *finite* planning horizon.

#### e. The flow of the five points in time

The flow of the above five points in time can be depicted as below.

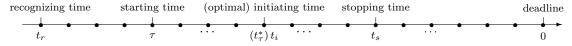


Figure 1.4.1: Five points in time

### H2. Deadline and Decision-Making Behaviour

A decision process with a finite planning horizon is akin to a conveyor-belt machinery which willy-nilly moves on to a deadline with the passage of time, usually leading to undesirable results, say a sale for a giveaway price in *Example* 1.3.1(p.5), a bankruptcy in the business management, and a ruination of state in the political decision. This event which is brought forth by the deadline becomes stronger as it gets nearer to the deadline and conversely weaker as it get away from the deadline. The mental conflict of a seller (decision-maker) stated in *Examples* 1.3.1(p.5) graphically reflects this situation in the sense that the reservation price of a seller becomes smaller as the distance from the deadline get shorter. The above phenomenon also implies that a decision-making behaviour at any point in time is, in varying degrees, touched off by the existence of deadline, conversely, without the existence of deadline, it follows that a decision-making behaviour is difficult to be excited. For this reason, the existence of deadline should be said to be an imperative requirement of decision process in the real world. In other words, the decision process with infinite planning horizon (without deadline) is what can be considered only at an abstract level (see A11(p.13)), implying that the existence of such decision process should be said to be a creature of fantasy from the realistic viewpoint.

### H3. Null-time-zone and Deadline-engulfing

Before delving into the explanation of the two terms in the title, let us recall here the definitions of the starting time  $\tau$  and the initiating time t (see H1(p7)). Additionally, let us denote the *optimal initiating time* by  $t_{\tau}^*$  ( $\tau \geq t_{\tau}^*$ ) (see (8.2.4(p.44))). Then, the case of  $\tau > t_{\tau}^*$  indicates that no action is taken at every point in time  $t \in \{\tau, \tau - 1, \cdots, t_{\tau}^*\}$ . In this case, we will refer to this period of time as the *null-time-zone* (see Section 8.2.4.5(p.46)). Next, consider an interesting case in which the *optimal initiating time*  $t_{\tau}^*$  *coincides with the deadline, i.e.,*  $t_{\tau}^* = 0$ . This situation ultimately implies that, any actions undertaken prior to the deadline are rendered meaningless, suggesting "Don't do anything until the deadline." Using a metaphorical comparison, it is akin to "All actions undertaken before the deadline being engulfed by the deadline itself", much like all forms of matter, including light, being absorbed into a black hole. Taking this into consideration, we refer to this phenomenon as *deadline-engulfing* (see Section 8.2.4.6(p.46)). Then, when we regard a decision process with the infinite planning horizon process, the existence of "deadline-engulfing" implies that the decision process with the finite planning horizon fades away in time toward the infinite future. This could be considered one of the most remarkable discoveries in this paper, compelling us to undertake a comprehensive re-evaluation of the entire theory of decision processes (see Section A 5(p.319)) that have been explored so far without taken into account the phenomenon of "deadline-engulfing".

#### H4. Symmetry

The notion of the adjective "symmetrical" used in Motive 1(p3) was initially sparked by a vague inspiration drawn from the yin-yan principle, an ancient Chinese philosophy, which offers conceptual guidance for harmonizing opposites. This concept is reified in ways that transforming some of terms related to the asset selling problem with  $\mathbb{R}$ -mechanism (ASP[ $\mathbb{R}$ ]) produces the asset buying problem with  $\mathbb{R}$ -mechanism ABP[ $\mathbb{R}$ ] (see Chap. 13(p.69)).

#### H5. Analogy

At the earlier stage of this study we could not absolutely imagine that there will exist a relationship between the asset selling problem with  $\mathbb{R}$ -mechanism (ASP[ $\mathbb{R}$ ]) and the asset selling problem with  $\mathbb{R}$ -mechanism (ASP[ $\mathbb{R}$ ]). However, in the process of delving into discussions, we observed certain similarity between the two problems. This scenario led us to a procedure, referred to as the *analogy replacement operation*; replacing the two parameters a and  $\mu^{\dagger}$  appearing within ASP[ $\mathbb{R}$ ] by  $a^{\star \dagger}$  and a respectively produces ASP[ $\mathbb{P}$ ], yielding the analogouse relation ASP[ $\mathbb{R}$ ]  $\bowtie$  ASP[ $\mathbb{R}$ ] (see Chap. 14(p.89)).

<sup>&</sup>lt;sup>†</sup>The lower bound a and the expectation  $\mu$  of the distribution function of  $\xi$  (see A9(p.12))

 $<sup>^{\</sup>ddagger} \mathrm{See} \ (6.1.26 (p.26))$ 

### H6. Integrated-Theory

As ones corresponding to the relations  $ASP[\mathbb{R}] \sim ABP[\mathbb{R}] \cdots (1^*)$  and  $ASP[\mathbb{R}] \bowtie ASP[\mathbb{P}] \cdots (2^*)$  depicted in Figure 1.4.2(p.9) below, we obtain also the relations  $ASP[\mathbb{P}] \sim ABP[\mathbb{P}] \cdots (3^*)$  and  $ABP[\mathbb{R}] \bowtie ABP[\mathbb{P}] \cdots (4^*)$ .

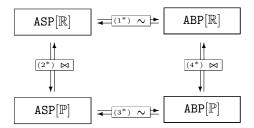


Figure 1.4.2: Integrated-Theory

The above figure schematizes the flow of the formulation of the integrated-theory (refer to Figure 17.1.1(p.115)), which can be explained as follows:

- ·  $(1^*)$  represents the symmetry relation between the selling problem with  $\mathbb{R}$ -mechanism (ASP[ $\mathbb{R}$ ]) and the buying problem with  $\mathbb{R}$ -mechanism (ABP[ $\mathbb{R}$ ]) (see Chap. 13(p.69)).
- ·  $(2^*)$  represents the analogy relation between the selling problem with  $\mathbb{R}$ -mechanism (ASP[ $\mathbb{R}$ ]) and the selling problem with  $\mathbb{P}$ -mechanism (ASP[ $\mathbb{P}$ ]) (see Chap. 14(p.89)).
- ·  $(3^*)$  represents, the symmetry relation between the selling problem with  $\mathbb{P}$ -mechanism (ASP[ $\mathbb{P}$ ]) and the buying problem with  $\mathbb{P}$ -mechanism (ABP[ $\mathbb{P}$ ]) (see Chap. 15(p.101)).
- · (4\*) represents the analogy relation between the buying problem with  $\mathbb{R}$ -mechanism (ABP[ $\mathbb{R}$ ]) and the buying problem with  $\mathbb{P}$ -mechanism (ABP[ $\mathbb{P}$ ]) (see Chap. 16(p.111)).

#### H7. Collapse of symmetry

The symmetry and analogy discussed in H4 and H5 were all derived under the assumption that the price  $\xi$  is defined on the interval  $(-\infty, \infty)$ , which allows for the possibility of negative values. However, in a typical the real-world, prices  $\xi$  are always positive, i.e.,  $\xi \in (0, \infty)$ . Consequently, if we constrain  $\xi \in (-\infty, \infty)$  to  $\xi \in (0, \infty)$ , then a natural question arises: "Are the symmetry and analogy inherited? (see Motive 1(p3)). Contrary to this expectation, it will be observed that "not inherited" frequently occurs in reality (see Chap. 19(p.129)).

### H8. Diagonal symmetry

In H7(p.9) we asserted that the symmetry is not always inherited on  $(0, \infty)$ . However, it can be demonstrated in Chap. 19(p.129) that the symmetry is consistently preserved between the selling problem on  $(-\infty, 0)$  and the buying problem on  $(0, \infty)$ , which is referred to as the "diagonal symmetry".

### H9. Underlying functions

The introduction of the underlying functions T, L, K, and  $\mathcal{L}$  (see Chap. 6(p.25)) stands as a significant highlights in this paper. While T-function has been widely recognized thus far in fields of statistics, operational research, and economics (see [14,Deg1970]), the remaining underlying functions L, K, and  $\mathcal{L}$  are all what were first defined in the present paper. It will be known later on that the properties of these functions (see Chap. 11(p.55)) play a central role in the analyses of all the models presented in the present paper. Without properties of these functions, not only could we challenge systematic analysis of these models, but also the successful construction of the integrated-theory would have been nearly impossible.

### H10. Structured-unit-of models

This paper addresses two types of models, no-recall model and recall model (see Section 3.2(p.16)). For each model we define 24 distinct models. In this paper we refer to the whole of these 24 models as the structured-unit-of-model (see Section 3.3(p.16)). Now, these 24 models are not what were *capriciously* defined but what were *inevitably* established based on the principles of quitting penalty price  $\rho$  (see A7(p.12)) and search enforced/allowed-case (see (A5(p.11))). In this paper, through treating the entirety of these 24 models as a cohesive unit, we endeavored to comprehensively analyze all of them. Although so many models of asset trading problems have been posed so far,<sup>†</sup> all of them have been one-by-one and independently treated thus far without touching upon any relationships each other. Against this, in the present paper, we aim to clarify the interconnectedness among all models included in the *structured-unit-of-model*.

 $<sup>^{\</sup>dagger}[30,1962],\ [32,1963],\ [3,1977],\ [38,1983],\ [37,1983],\ [40,1990],\ [7,1991],\ [33,1993],\ [44,1993],\ [36,1995],\ [27,1995],\ [45,1995],\ [47,1997],\ [9,1997],\ [12,1998],\ [20,1999],\ [1,1999],\ [13,2001],\ [35,2002],\ [11,2002],\ [15,2004],\ [19,2005],\ [16,2005]^{\ddagger}$ 

# Assumptions

# 2.1 Ultimate Simplification of Models

In addressing a given real-world problem, two distinct approaches to study emerge. One is the construction of a model that faithfully represents its research object to the greatest extent possible. The other involves building the simplest model conceivable where further simplification risks the loss of essential elements. Here, we label research based on the former as experimental study and the latter as theoretical study. While there is no inherent superiority between these two approaches, our overall stance in this study aligns with the latter, reflecting our philosophical background (see Section 1.2(p.3)). The methodology classification into these two categories acts as a dividing ridge, causing a study to bifurcate in counter directions. The first drop of water from the former follows the east wall, and the first drop of water from the latter follows the west wall. Eventually, both converge in a lake with a common bottom, and shortly thereafter, a flower blooms. This amalgamation of results from both methodologies leads us to a genuine understanding of the reality in question.

### 2.2 Assumptions

In order to realize the simplification of models that was stated above let us configure the following assumptions:

#### A1 Points in time

The asset trading process occurs intermittently at points in time equally spaced along a finite length of the time axis as depicted in Figure 2.2.1(p.11) below. We shall backward label each point in time from the final point in time, denoted as time 0 (deadline), as 0, 1, and so forth. Accordingly, when the *present* point in time is designated as time t, the two adjacent points in time, t+1 and t-1, are the *previous* and *next* points in time respectively.

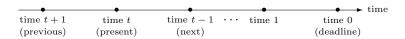


Figure 2.2.1: Points in time

### A2 Absolutely necessary condition

In ASP (ABP), the leading-trader acting as a seller (buyer) must sell (buy), by all means, the trading asset to a buyer (from a seller) by the deadline. To rephrase, the seller (buyer) is not allowed to quit the selling (buying) process without completing the sale (purchase) of the asset.

### A3 Stop of process

The process stop when the leading-trader accepts a price proposed by an counter-trader in  $ATP[\mathbb{R}]$  and when an counter-trader accepts a price proposed by the leading-trader in  $ATP[\mathbb{P}]$ .

### A4 Search cost

A cost  $s \ge 0$ , referred to as the *search cost*, must be paid to search for counter-traders, which includes expenses for advertising, communication, transfer, and so on.

### A5 Search-Enforced-Model and search-Allowed-Model

The two models are related to the question "Whether it is enforced to conduct the search or not?".

a. search-Enforced-model (sE-model): This refers to the case in which, once the process has initiated, conducting the search at every subsequent point in time is mandatory. In this scenario, as illustrated in Figure 2.2.2(p.12) below, a decision-maker must continue to conduct the search until the process stops.

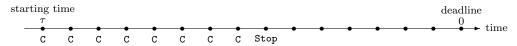


Figure 2.2.2: Flow of Search-Conducts in the search-Enforced-model

b. search-Allowed-model (sA-model): This refers to the case in which, even after the process has initiated, it is *permissible* to skip the search at every subsequent point in time. In other words, a leading-trader has the option to conduct the search or to skip it at every point in time as long as the process does not stop. In this scenario, we can consider different types of flows for search-Conduct and search-Skip, as illustrated in Figure 2.2.3(p.12) below, where "~" represents the transition from search-Skip to search-Conduct or from search-Conduct to search-Skip.

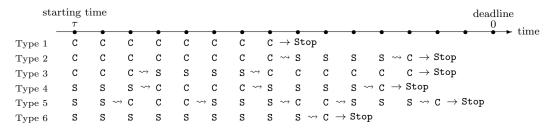


Figure 2.2.3: Different flows of search-Conduct and search-Skip

**Definition 2.2.1** By  $C \rightarrow S$  ( $S \rightarrow C$ ) let us denote the switch from search-Conduct to search-Skip (search-Skip to search-Conduct).  $\Box$ 

### A6 Opposite-trader's appearance probability $\lambda$

In this paper, it is assumed that when the search is conducted at a certain point in time, an counter-trader appears at the next point in time with a known probability  $\lambda$  (0 <  $\lambda \le 1$ ).

### A7 Quitting penalty price

Suppose that the counter-trader appearing probability  $\lambda$  is less than 1, i.e.,  $0 < \lambda < 1$ . Then it is possible that no counter-trader appears in the subsequent points in time even if conducting the search. This situation can lead to the risk that a leading-trader potentially has to quit the process at the final point in time point (deadline) without executing the trade for the asset, which contradicts the requirement of A2. When facing with such a circumstance, the leading-trader will take the following actions at the deadline:

- $\circ$  In ASP, the seller (leading-trader) will attempt to find ways to sell the asset by proposing a giveaway price  $\rho$  to any available buyer (counter-trader).
- $\circ$  In ABP, the buyer (leading-trader) will strive to acquire the asset by presenting a notably high-price  $\rho$  to any available seller (counter-trader).

Let us refer to such a price  $\rho$  as the terminal quitting penalty price  $\rho$ , implying that, at the deadline (terminal point in time 0), the leading-trader can quit the process in exchange for the  $\rho$ . Additionally, we can consider the case that such a  $\rho$  is available also at every point in time including the terminal point in time (deadline). Then let us refer to it as the intervening quitting penalty price. In the explanation above, the  $\rho$  is implicitly assumed to be positive  $\rho \in (0, \infty)$ ; however, to generalize discussions that follows, we define it to be  $\xi \in (-\infty, \infty)$ .

### A8 Range of price

Whether a price  $\xi$  proposed by an appearing counter-trader or the reservation price  $\xi$  of an appearing counter-trader, it should be defined on  $(0,\infty)$  in the normal market of the real-world (see Section 18.2(p.117)). However, in this paper, to construct the integrated-theory in Part 2 (p.51) we dare to define it on  $(-\infty,\infty)$ .

### A9 Distribution function

In ATP[ $\mathbb{R}$ ] (ATP[ $\mathbb{P}$ ]) we assume that the prices proposed by successively appearing counter-trader,  $\boldsymbol{\xi}$ ,  $\boldsymbol{\xi}'$ ,  $\cdots$  (the reservation prices of successively appearing counter-trader,  $\boldsymbol{\xi}$ ,  $\boldsymbol{\xi}'$ ,  $\cdots$ ) are independent identically distributed random variables having a *continuous* distribution function  $F(\boldsymbol{\xi}) = \Pr\{\boldsymbol{\xi} \leq \boldsymbol{\xi}\}$  with a finite expectation  $\mu$  where

$$F(\xi) = 0 \quad \cdots (1) \quad \xi \le a,$$

$$0 < F(\xi) < 1 \quad \cdots (2) \quad a < \xi < b,$$

$$F(\xi) = 1 \quad \cdots (3) \quad b \le \xi,$$
(2.2.1)

for given constants a and b such that

$$-\infty < a < \mu < b < \infty. \tag{2.2.2}$$

Furthermore, for its probability density function  $f(\xi)$  let us assume

$$f(\xi) = 0 \quad \cdots (1) \quad \xi < a,$$
  

$$0 < f(\xi) < 1 \quad \cdots (2) \quad a \le \xi \le b,$$
  

$$f(\xi) = 0 \quad \cdots (3) \quad b < \xi.$$
(2.2.3)

Here assume that there exits f such that

$$\underline{f} = \inf_{a < \xi < b} f(\xi)d\xi > 0. \tag{2.2.4}$$

Let us represent the set consisting of all possible distribution functions with (2.2.2(p.12)) by F, i.e.,

$$\mathscr{F} = \{ F \mid -\infty < a < \mu < b < \infty \}, \tag{2.2.5}$$

called the  $total\ distribution\ function\ space$ , simply the total-DF-space.

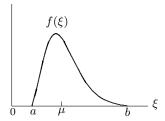


Figure 2.2.4: Probability density function  $f(\xi)$ 

### A10 Recallability of once rejected counter-trader

Whether a model with  $\mathbb{R}$ -mechanism or a model with  $\mathbb{P}$ -mechanism, if a once-rejected counter-trader can be recalled later and accepted at the discretion of the leading-trader, then it is referred to as the recall-model or model-with-recall (see Section 3.2.2(p.16) and Part 4(p.247)). Conversely, if such recallability is not allowed, then it is referred to as the no-recall-model, model-with-no-recall, or model-without-recall.

### A11 Finiteness of planning horizon

In the present paper we consider only models with the *finite* planning horizon (see H1d(p.7)). Our basic standpoint over the whole of this paper lies in a *grim reality* that a process with the *infinite* planning horizon is a *mere product of fantasy* created by mathematics, which does not exist in the real world at all; in fact, it is an inanity to consider a model with the planning horizon of more than 135 hundred millions years. However, we can have the two reasons for which it becomes still meaningful to discuss the model with the *infinite* planning horizon. One is that it can become an approximation for the process with an enough long (finite) planning horizon, the other is that results obtained from it can provide a meaningful information for the analyses of models with the *finite* planning horizon.

### A12 Discount factor $\beta$

First, let us note here that the concept of *value creation process* lies, overtly and covertly, beneath business science and economic science. This fact implies that, without this concept, any managerial and/or economic activity becomes meaningless. Below let us clarify the practical implications of this concept.

- a. Fund: Let us refer to the amount of money on hand as fund, which can be always and freely invested. Let us represent its interest rate per period as  $r \ge 0$  and define  $\beta = (1+r)^{-1}$   $(1 \ge \beta > 0)$ , called the discount factor.
- b. Profit: Let us refer to the *increment* of the fund yielded by a managerial and/or economic activity as a *profit* (P dollar).
- c. Cost: Suppose that an amount of the fund has been paid away for a reason. Then, let us refer to the amount of fund as an expense (E dollar). Now, if the amount of funds were not paid away as an expense, then it would remain (return to life) as savings on hand; let us call it the opportunity savings (S dollar). However, this expense is what had been already paid, hence it is booked as a loss, which is usually called the opportunity loss (L dollar) in standard textbooks of management and/or economics. In this paper, we refer to this opportunity loss a cost (C dollar).
- d. Discount factor for profit: In an asset selling problem (ASP), a seller can invest the profit x obtained by selling his/her asset. Since the profit is a part of fund, it can be invested at a given rate of interest r > 0 by definition; as a result, the profit x obtained today (the present point in time) increases to  $(1+r)^n x$  after n days, i.e.,  $x \to \beta^{-n} x$ . By  $A_0$  and  $A_n$  let us represent actions with the profits  $P_0$  and  $P_n$  obtained today and n days later respectively. Then we have  $P_0 \to \beta^{-n} P_0$ , schematized as in the figure below.

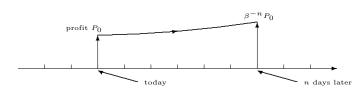


Figure 2.2.5: Discount factor  $\beta$  for profit

The above context implies the following:

The profit  $P_0$  that you take today increases, if not taking today, to  $(1+r)^n P_0$  after n days, which you take on that day.

The evaluation (on n days later) of the relative merits between actions  $A_0$  and  $A_n$  should be made not by  $P_0 \ge (\le) P_n$  but by  $\beta^{-n}P_0 \ge (\le) P_n$ . Multiplying the latter inequality by  $\beta^n$  leads to  $P_0 \ge (\le) \beta^n P_n$ , implying that the evaluation (on today) is made by this inequality. We refer to the  $\beta^n P_n$  as the present (today) value of the profit  $P_n$  gained n days later. Accordingly, it follows that the total present value of profit for the action with profits  $P_0, P_1, P_2, \cdots$  is given by  $P_0 + \beta P_1 + \beta^2 P_2 + \cdots$ .

e. Discount factor for cost To begin with, let us start with a simple question "Since a cost is a fund which has already been paid away, it cannot be invested, so how to evaluate a future's cost as in a profit?" Fortunately we can find out its answer within the concept of the *opportunity saving* which is a part of fund that can be invested. By  $A_0$  and  $A_n$  let us represent actions with the expenses  $E_0$  and  $E_n$  today and  $E_n$  days later respectively. Suppose that the payment of a today's expense  $E_0$  postpones to  $E_n$  days later. Then, during that time, the paid expense transforms into the *opportunity savings*  $E_n$ 0, which increases to  $E_n$ 1 does not materialize, hence  $E_n$ 2 is paid, not only the *opportunity saving*  $E_n$ 3 but also  $E_n$ 4 does not materialize, hence  $E_n$ 5 is lost in fact and becomes a *opportunity loss*  $E_n$ 6 and finally  $E_n$ 6. The above scenario can be depicted as in the figure below.

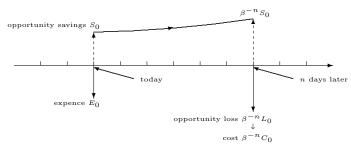


Figure 2.2.6: Discount factor  $\beta$  for cost

The above context implies the following:

The cost  $C_0$  that you incur today increases, if not incurring today, to  $(1+r)^n C_0$  after n days, which you incur on that day.

From the above we see that the evaluation (n days later) of the relative merits between actions  $A_0$  and  $A_n$  should be made not by  $C_0 \ge (\le) C_n$  but by  $\beta^{-n}C_0 \ge (\le) C_n$ . Multiplying the latter inequality by  $\beta^n$  leads to  $C_0 \ge (\le) \beta^n C_n$ , implying that the evaluation (today) is made by this inequality. We refer to the  $\beta^n C_n$  as the present (today) value of the profit  $C_n$  gained n days later. Accordingly, it follows that the total present value of cost for the action with costs  $C_0, C_1, C_2, \cdots$  is given by  $C_0 + \beta C_1 + \beta^2 C_2 + \cdots$ .

# 2.3 Evolutionary Development of Models

For a positivist, theoretical research might seem unrealistic due to the excessive simplification of models. However, the simplicity of a theoretical model, achieved by excluding many elements of real-world problems, makes it relatively easier to understand the essence of the problem it addresses. On the contrary, embarking on a complex model from the outset, incorporating numerous elements, can make it relatively challenging to grasp the essence of the problems, given the complexity involved. Nevertheless, if an interesting and essential characteristic is discovered in a simplified model, there is a possibility that this characteristic is also embedded in an extended model derived from the simplified version. From this perspective, we initiated our analysis with some simplified models. However, our exploration didn't stop at the discovery of characteristics identified through its analyses; we continued defining and researching even more complex (extended) models. Through this approach, our research has progressed towards models providing deeper insights for real-world problems. The models under this study have undergone an evolution over time.

# Classification of Models

### 3.1 Model Classification Factors

The paper categorizes models based on the following four factors:

- (A) The first factor is whether selling model or buying model, represented as:
  - $\circ \ \operatorname{Selling\ model} \to M.$
  - $\circ$  Buying model  $\to \tilde{M}$ .
- (B) The second factor is the quitting penalty price  $\rho$  (see A7(p.12)), classified as:
  - $\circ$  Model 1 in which the quitting penalty price  $\rho$  is not available.
  - $\circ$  Model 2 in which the only terminal quitting penalty price  $\rho$  is available.
  - $\circ$  Model 3 in which both terminal quitting penalty price  $\rho$  and intervening quitting penalty  $\rho$  are available.
- (C) The third factor is whether R-mechanism or P-mechanism (see Section 1.3(p.4)), denoted as:
  - $\circ \mathbb{R}$ -mechanism-model ( $\mathbb{R}$ -model)  $\to [\mathbb{R}]$ .
  - $\circ \mathbb{P}$ -mechanism-model  $(\mathbb{P}$ -model)  $\to [\mathbb{P}]$ .
- (D) Thelast factor is whether search-Enforced-model or search-Allowed-model (see A5(p.11)), symbolized as:
  - $\circ$  search-Enforced-model (sE-model)  $\rightarrow$  [E].
  - $\circ$  search-Allowed-model (sA-model)  $\rightarrow$  [A].

### 3.2 Tables of Models

### 3.2.1 No-Recall-Model

Let us designate sE-model with no recall by

$$M:x[X][E]$$
  $(\tilde{M}:x[X][E])$   $x=1,2,3, X=\mathbb{R},\mathbb{P},^{\ddagger}$ 

and  $\mathsf{s} A\mathsf{-model}$  with no recall by

$$\mathsf{M}:x[\mathbb{X}][\mathsf{A}] \ (\tilde{\mathsf{M}}:x[\mathbb{X}][\mathsf{A}]) \ x=1,2,3, \ \mathbb{X}=\mathbb{R},\mathbb{P}.$$

Then let us define the set

$$\mathcal{Q}\langle\mathsf{M}\!:\!x[\mathtt{X}]\rangle\stackrel{\scriptscriptstyle\mathrm{def}}{=}\{\mathsf{M}\!:\!x[\mathbb{R}][\mathtt{X}],\tilde{\mathsf{M}}\!:\!x[\mathbb{R}][\mathtt{X}],\mathsf{M}\!:\!x[\mathbb{P}][\mathtt{X}],\tilde{\mathsf{M}}\!:\!x[\mathbb{P}][\mathtt{X}]\},\quad x=1,2,3,\ \ \mathtt{X}=\mathtt{E},\mathtt{A},$$

called the quadruple-asset-trading-models-with-no-recall, consisting of the 24 models in the table below:

Table 3.2.1: Twenty Four No-recall-Models

${\tt ASP}[\mathbb{R}]$	$\mathtt{ABP}[\mathbb{R}]$	$\mathtt{ASP}[\mathbb{P}]$	$\mathtt{ABP}[\mathbb{P}]$
$\mathcal{Q}\{M{:}1[\mathtt{E}]\} = \{\ M{:}1[\mathbb{R}][\mathtt{E}],$	$ ilde{M}{:}1[\mathbb{R}][E],$	$M{:}1[\mathbb{P}][E],$	$\tilde{M}{:}1[\mathbb{P}][E]$ }
$\mathcal{Q}\{M{:}1[\mathtt{A}]\} =\{M{:}1[\mathbb{R}][\mathtt{A}],$	$ ilde{M}{:}1[\mathbb{R}][\mathtt{A}],$	$M{:}1[\mathbb{P}][\mathtt{A}],$	$ ilde{M}{:}1[\mathbb{P}][\mathtt{A}]$ }
$\mathcal{Q}\{M{:}2[E]\} = \{ M{:}2[\mathbb{R}][E],$	$\tilde{M}{:}2[\mathbb{R}][E],$	$M{:}2[\mathbb{P}][E],$	$\tilde{M}{:}2[\mathbb{P}][E]$ }
$\mathcal{Q}\{M{:}2[\mathtt{A}]\} =\{M{:}2[\mathbb{R}][\mathtt{A}],$	$ ilde{M}{:}2[\mathbb{R}][\mathtt{A}],$	$M{:}2[\mathbb{P}][\mathtt{A}],$	$ ilde{M}{:}2[\mathbb{P}][\mathtt{A}]$ }
$\mathcal{Q}\{M{:}3[E]\} = \{ M{:}3[\mathbb{R}][E],$	$\tilde{M}{:}3[\mathbb{R}][E],$	$M{:}3[\mathbb{P}][E],$	$\tilde{M}$ :3[ $\mathbb{P}$ ][ $E$ ] }
$\mathcal{Q}\{M{:}3[\mathtt{A}]\} = \{M{:}3[\mathbb{R}][\mathtt{A}],$	$\tilde{M}{:}3[\mathbb{R}][\mathtt{A}],$	$M{:}3[\mathbb{P}][\mathtt{A}],$	$\tilde{M}{:}3[\mathbb{P}][\mathtt{A}]\ \}$

### 3.2.2 Recall-Model

Let us designate sE-model with recall by

$$rM:x[X][E]$$
  $(r\tilde{M}:x[X][E])$   $x = 1, 2, 3, X = \mathbb{R}, \mathbb{P},$ 

and sA-model with recall by

$$rM:x[X][A]$$
  $(r\tilde{M}:x[X][A])$   $x = 1, 2, 3, X = \mathbb{R}, \mathbb{P}.$ 

Then let us define the set

$$\mathcal{Q}\langle \mathbf{r} \mathsf{M} : x[\mathtt{X}] \rangle \stackrel{\text{def}}{=} \{\mathbf{r} \mathsf{M} : x[\mathbb{R}][\mathtt{X}], \mathbf{r} \tilde{\mathsf{M}} : x[\mathbb{R}][\mathtt{X}], \mathbf{r} \mathsf{M} : x[\mathbb{P}][\mathtt{X}], \mathbf{r} \tilde{\mathsf{M}} : x[\mathbb{P}][\mathtt{X}] \}, \quad x = 1, 2, 3, \ \mathtt{X} = \mathtt{E}, \mathtt{A}, \mathtt{A} = \mathtt{E}, \mathtt{A}, \mathtt{A}, \mathtt{A}, \mathtt{A} = \mathtt{E}, \mathtt{A}, \mathtt{A}, \mathtt{A}, \mathtt{A}, \mathtt{A} = \mathtt{E}, \mathtt{A}, \mathtt$$

called the quadruple-asset-trading-models-with-recall, consisting of the 24 models in the table below:

Table 3.2.2: Twenty Four Recall-Models

${\tt ASP}[\mathbb{R}]$	$\mathtt{ABP}[\mathbb{R}]$	$\mathtt{ASP}[\mathbb{P}]$	$\mathtt{ABP}[\mathbb{P}]$
$\mathcal{Q}\{rM{:}1[E]\} = \{ rM{:}1[\mathbb{R}][E],$	$r\tilde{M}{:}1[\mathbb{R}][E],$	$rM{:}1[\mathbb{P}][E],$	$r\tilde{M}{:}1[\mathbb{P}][E]$ }
$\mathcal{Q}\{rM{:}1[\mathtt{A}]\} =\{rM{:}1[\mathbb{R}][\mathtt{A}],$	$r\tilde{M}{:}1[\mathbb{R}][\mathtt{A}],$	$rM{:}1[\mathbb{P}][\mathtt{A}],$	$\tilde{\mathrm{rM}}{:}1[\mathbb{P}][\mathtt{A}]\}$
$\mathcal{Q}\{rM{:}2[E]\} = \{ rM{:}2[\mathbb{R}][E],$	$r\tilde{M}{:}2[\mathbb{R}][E],$	$rM:2[\mathbb{P}][E],$	$\tilde{rM}:2[\mathbb{P}][E]$ }
$\mathcal{Q}\{rM{:}2[\mathtt{A}]\} =\{rM{:}2[\mathbb{R}][\mathtt{A}],$	$r\tilde{M}{:}2[\mathbb{R}][\mathtt{A}],$	$rM{:}2[\mathbb{P}][\mathtt{A}],$	$\tilde{\mathrm{rM}}{:}2[\mathbb{P}][\mathtt{A}]\}$
$\mathcal{Q}\{rM{:}3[E]\} = \{ rM{:}3[\mathbb{R}][E],$	$r\tilde{M}:3[\mathbb{R}][E],$	rM:3[ℙ][E],	$\tilde{rM}:3[\mathbb{P}][E]$ }
$\mathcal{Q}\{rM{:}3[\mathtt{A}]\} \ = \{\ rM{:}3[\mathbb{R}][\mathtt{A}],$	$r\tilde{M}{:}3[\mathbb{R}][\mathtt{A}],$	$rM{:}3[\mathbb{P}][\mathtt{A}],$	$\tilde{rM}{:}3[\mathbb{P}][\mathtt{A}]\}$

### 3.3 Structured-Unit-of-Models

Let us refer to the set of 24 models defined in each of Tables 3.2.1(p.16) and 3.2.2(p.16) as the *structured-unit-of-models*. Here note that all models within each structured-unit-of-model are not ones *blindly* defined but ones *systematically* and *inevitably* defined. The big difference from all other studies that have been made by many researchers, including the authors in the past, lies in clarifying the *overall interconnectedness* among these models.

<sup>&</sup>lt;sup>‡</sup>Throughout the paper, the model of the asset *buying* problem (ABP) is represented by the symbol upon which the tilde "~" is capped like  $\tilde{\mathsf{M}}$ .

### 3.4 Decisions

What a leading-trader should determine in each of models defined in Tables 3.2.1(p.16) and 3.2.2(p.16) are as follows:

- $\langle 1 \rangle$  When to initiate the process (for all models) (see Section 8.2.4(p.44)).
- $\langle 2 \rangle$  Whether or not to accept the price proposed by a counter-trader (only for  $\mathbb{R}$ -model) (see Section 8.2.1(p.43)),
- $\langle 3 \rangle$  What price to post (only for P-model) (see Section 8.2.2(p.44)),
- (4) Whether or not to conduct the search (only for sA-model) (see Section 8.2.3(p.44)),

# 3.5 Trading Problem with Negative Trading Price

In A8(p.12) we defined a price  $\xi$  on  $(-\infty, \infty)$ . However, this seemingly unrealistic assumption can be justified by the following reason. First, let us note here that "sell" means "deliver" and "buy" means "receive"; more precisely speaking:

- o In a selling problem, a seller (leading-trader) delivers the asset to a buyer (counter-trader), who receives it from the seller.
- o In a buying problem, a buyer (leading-trader) receives the asset from a seller (counter-trader), who delivers it to the buyer.

The above two scenarios can be schematized as below.

In other words, "selling problem" and "buying problem" can be said to be "delivering problem" and "receiving problem" respectively. Now let us consider here a transaction in which the asset traded there is a worthless debris such as surplus soil, concrete blocks and so on which are disposed of when a building is broken up. In this case, a receiving-side (buyer), in whether selling problem or buying problem, rightly requires some amount of money as a disposal cost nevertheless being a buyer. Seeing the problem from the standpoint of the seller (delivering-side), the seller gives some amount of money to the buyer (receiving-side) nevertheless being a seller. This interpretation implies that the trading problem stated above can be regarded as "a trading problem with a negative trading price" whether selling problem or buying problem. To discuss the trading problem more generally for the above reason, expanding the range of the trading price to  $(-\infty, \infty)$  can be said to be reasonable from a practical viewpoint. See Section A 7.5(p.326) for a further economic implication.

### 3.6 Symbols of Models

In the paper we will sometimes use the following symbols for the no-recall-model.

```
o By M:x[\mathbb{R}/\mathbb{P}][X] let us denote M:x[\mathbb{R}][X] and M:x[\mathbb{P}][X].
o By \tilde{M}:x[\mathbb{R}/\mathbb{P}][X] let us denote \tilde{M}:x[\mathbb{R}][X] and \tilde{M}:x[\mathbb{P}][X].
o By M/\tilde{M}:x[\mathbb{R}/\mathbb{P}][X] let us denote M:x[\mathbb{R}/\mathbb{P}][X] and \tilde{M}:x[\mathbb{R}/\mathbb{P}][X].
o By M:1/2/3[\mathbb{X}][X] let us denote M:1[\mathbb{X}][X], M:2[\mathbb{X}][X], and M:3[\mathbb{X}][X].
o By \tilde{M}:x[\mathbb{X}][E/A] let us denote M:x[\mathbb{X}][E] and M:x[\mathbb{X}][A].
o By \tilde{M}:x[\mathbb{X}][X] let us denote \tilde{M}:1[\mathbb{X}][X], \tilde{M}:2[\mathbb{X}][X], and \tilde{M}:3[\mathbb{X}][X].
o By \tilde{M}:x[\mathbb{X}][E/A] let us denote \tilde{M}:x[\mathbb{X}][E] and \tilde{M}:x[\mathbb{X}][A].
```

Also for the recall-model we define the same symbols, say  $rM/\tilde{M}:x[\mathbb{R}/\mathbb{P}][X]$ ,  $r\tilde{M}:x[\mathbb{R}/\mathbb{P}][X]$ , ...

# **Definitions of Models**

### 4.1 No-Recall-Model

### 4.1.1 Model 1

 $\textbf{4.1.1.1} \quad \textbf{Search-Enforced-Model:} \ \mathcal{Q}(\texttt{M}:1[\texttt{E}]) = \{\texttt{M}:1[\texttt{R}][\texttt{E}], \ \texttt{M}:1[\texttt{P}][\texttt{E}], \ \tilde{\texttt{M}}:1[\texttt{R}][\texttt{E}], \ \tilde{\texttt{M}}:1[\texttt{R}][\texttt{E}], \ \tilde{\texttt{M}}:1[\texttt{R}][\texttt{E}], \ \tilde{\texttt{M}}:1[\texttt{R}][\texttt{E}], \ \tilde{\texttt{M}}:1[\texttt{R}][\texttt{E}], \ \tilde{\texttt{M}}:1[\texttt{R}][\texttt{E}], \ \tilde{\texttt{M}}:1[\texttt{R}][\texttt{R}], \ \tilde{\texttt{M}}:1[\texttt{R}][\texttt{R}][\texttt{R}], \ \tilde{\texttt{M}}:1[\texttt{R}][\texttt{R}][\texttt{R}], \ \tilde{\texttt{M}}:1[\texttt{R}][\texttt{R$ 

### **4.1.1.1.1** M:1[ $\mathbb{R}$ ][E] and M:1[ $\mathbb{P}$ ][E]

These two are the most basic models of the asset selling problem [8,Ber1995,p.158-162][46,You1998], which are defined by the following assumptions:

- A1. Once the process initiates, at every point in time after that it is enforced to conduct the search for buyers (see (A5a(p.11))), hence the search cost  $s \ge 0$  is paid at every point in time (see A4(p.11)).
- A2. After the search has been conducted at a point in time t > 0, a buyer certainly appears at time t 1 (next point in time), i.e., the buyer appearing probability  $\lambda = 1$  (see A6(p.12)).
- A3. The prices  $\xi$ ,  $\xi'$ ,  $\xi''$ ,  $\cdots$  proposed by successively appearing buyers in M:1[ $\mathbb{R}$ ][E] and the reservation prices  $\xi$ ,  $\xi'$ ,  $\xi''$ ,  $\cdots$  of successively appearing buyers in M:1[ $\mathbb{R}$ ][E] are both assumed to be independent identically distributed random variables having a known *continuous* probability distribution function  $F(\xi) = \Pr{\{\xi \leq \xi\} \text{ (see A9}(p.12)).}^{\dagger}$
- A4. Both terminal quitting penalty price  $\rho$  and intervening quitting penalty price  $\rho$  are not available (see A7(p.12)).
- A5. The selling process stops/terminates at the point in time when the asset is sold to an appearing buyer (see A3(p.11)).

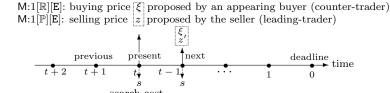


Figure 4.1.1:  $M:1[\mathbb{R}][E]$  and  $M:1[\mathbb{P}][E]$ 

The objective is to maximize the total expected present discounted *profit*, i.e., the expected present discounted value of the price for which the asset is sold, *minus* the total expected present discounted value of the search costs which will be paid until the process stops with selling the asset.

### Remark 4.1.1

- (a) The starting time  $\tau$  must be greater than 0, i.e.,  $\tau > 0$  for the following reason. If  $\tau = 0$ , there exists no buyer at time 0, hence the process must stop without selling the asset, which contradicts A2(p.11).
- (b) Suppose the process has proceeded up to time 1. Then, since the search is conducted at that time due to A1(p.19), a buyer certainly appears at time 0 (deadline) due to A2(p.19).
  - 1. In  $M:1[\mathbb{R}][E]$ , due to A2(p.11) the seller must sell the asset to the buyer however small the price proposed by the buyer may be.
  - 2. In M:1[P][E], the seller must propose the price a to the buyer where a is the lower bound of the distribution function F for the reservation price  $\boldsymbol{\xi}$  of the buyer (see Figure 2.2.4(p.13)). Then, the buyer certainly buys the asset.  $\square$

 $<sup>^{\</sup>dagger}\boldsymbol{\xi}$  and  $\boldsymbol{\xi}$  represent a random variable and a realized value respectively.

### **4.1.1.1.2** $\tilde{M}:1[\mathbb{R}][E]$ and $\tilde{M}:1[\mathbb{P}][E]$

These two are both the models of the asset buyinq problem, defined by the following assumptions:

- A1. Once the process initiates, at every point in time after that it is enforced to conduct the search for sellers, hence the search cost  $s \ge 0$  is paid at every point in time.
- A2. After the search has been conducted at a point in time t > 0, a seller certainly appears at time t 1 (next point in time), i.e., the seller appearing probability  $\lambda = 1$ .
- A3. The prices  $\xi$ ,  $\xi'$ ,  $\xi''$ ,  $\cdots$  proposed by successively appearing sellers in  $\tilde{M}:1[\mathbb{R}][E]$  and the reservation prices  $\xi$ ,  $\xi'$ ,  $\xi''$ ,  $\cdots$  of successively appearing sellers in  $\tilde{M}:1[\mathbb{P}][E]$  are both assumed to be independent identically distributed random variables having a known *continuous* probability distribution function  $F(\xi) = \Pr{\{\xi \leq \xi\}}$ .
- A4. Both terminal quitting penalty price  $\rho$  and intervening quitting penalty price  $\rho$  are not available.
- A5. The buying process stops at the point in time when the asset is bought by an appearing seller.

 $\tilde{M}$ :1[ $\mathbb{R}$ ][ $\mathbb{E}$ ]: selling price  $\mathcal{E}$  proposed by an appearing seller (opposite-trader)  $\tilde{M}$ :1[ $\mathbb{P}$ ][ $\mathbb{E}$ ]: buying price z proposed by the buyer (leading-trader)

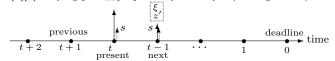


Figure 4.1.2:  $\tilde{M}:1[\mathbb{R}][E]$  and  $\tilde{M}:1[\mathbb{P}][E]$ 

The objective is to minimize the total expected present discounted *cost*, i.e., the expected present discounted value of the price for which the asset is bought, *plus* the total expected present discounted value of the search costs which will be paid until the process stops with buying the asset.

Remark 4.1.2 Here it should be noted that the direction of the vectors representing the trading price  $(\xi, z, \text{ and } z')$  and that of the search cost (s) are converse in 4.1.1(p.19) but identical in 4.1.2(p.20).  $\square$ 

### **4.1.1.2** Search-Allowed-Model 1: $Q(M:1[A]) = \{M:1[R][A], M:1[P][A], \tilde{M}:1[R][A], \tilde{M}:1[P][A]\}$

### **4.1.1.2.1** $M:1[\mathbb{R}][A]$ and $M:1[\mathbb{P}][A]$

These two are the same as  $M:1[\mathbb{R}][E]$  and  $M:1[\mathbb{P}][E]$  in Section 4.1.1.1.1(p.19) only except that A1(p.19) is changed into as follows:

A1. At every point in time t > 0, it is allowed to skip the search (see (A5b(p.12))); in other words, the seller has an option whether to conduct the search or to skip.

#### Remark 4.1.3

- (a) The starting time  $\tau$  must be greater than 0, i.e.,  $\tau > 0$  for the same reason as in Remark 4.1.1(p.19) (a).
- (b) Suppose the process has proceeded up to time t=1. Then, if the search is skipped at that time, no buyer appears at time t=0, hence the seller is faced with the situation of having to quit the process without selling the asset, which contradicts A2(p.11). Accordingly, also in this case the search must be necessarily conducted at time t=1; as a result, a buyer certainly appears at time 0 due to the assumption A2.  $\square$

### **4.1.1.2.2** $\tilde{M}:1[\mathbb{R}][A]$ and $\tilde{M}:1[\mathbb{P}][A]$

These two are the same as  $\tilde{M}:1[\mathbb{R}][E]$  and  $\tilde{M}:1[\mathbb{P}][E]$  in Section 4.1.1.1.2(p.20) only except that after the process has initiated, it is allowed to skip the search.

### 4.1.2 Model 2

### **4.1.2.1** Search-Enforced-Model 2: $Q(M:2[E]) = \{M:2[\mathbb{R}][E], M:2[\mathbb{P}][E], \tilde{M}:2[\mathbb{R}][E], \tilde{M}:2[\mathbb{P}][E]\}$

The quadruple models indicated in the above brace are the same as in Section 4.1.1.1.1(p.19) only except that the assumptions A2(p.19) and A4(p.19) are changed into as follows:

- A2. After the search has been conducted at time t > 0, a buyer appears at the next point in time with a probability  $\lambda \le 1$ .
- A4. The terminal quitting penalty price  $\rho$  is available.

Remark 4.1.4 In these models it is possible to stop the process by accepting the terminal quitting penalty price  $\rho$  at time 0 (deadline), hence the starting time  $\tau=0$  is permitted since the leading-trader can quit the process with accepting the  $\rho$  at time 0 even if no counter-trader exists at time 0. Accordingly, in these models it follows that the starting time  $\tau$  is greater than or equal to 0, i.e.,  $\tau \geq 0$ .

 $<sup>^{\</sup>dagger}\xi$  and  $\xi$  represent a random variable and a realized variable respectively.

### $\textbf{4.1.2.2} \quad \textbf{Search-Allowed-Model 2:} \quad \mathcal{Q}(\mathsf{M}:2[\mathtt{A}]) = \{\mathsf{M}:2[\mathbb{R}][\mathtt{A}], \ \mathsf{M}:2[\mathbb{P}][\mathtt{A}], \ \tilde{\mathsf{M}}:2[\mathbb{R}][\mathtt{A}], \ \tilde{\mathsf{M}}:2[\mathbb{R}][\mathtt{A}]\}$

The quadruple models indicated in the above brace are the same as in Section 4.1.2.1(p.20) only except that A1(p.19) is changed as follows:

A1. After the process has initiated, it is allowed to skip the search at every point in time t > 0.

### 4.1.3 Model 3

### **4.1.3.1** Search-Enforced-Model 3: $\mathcal{Q}(M:3[E]) = \{M:3[R][E], M:3[P][E], \tilde{M}:3[R][E], \tilde{M}:3[P][E]\}$

The quadruple models are the same as in Section 4.1.2.1(p.20) only except that the assumption A4(p.20) is changed as follows:

A4. In addition to the terminal quitting penalty price  $\rho$ , the intervening quitting penalty price  $\rho$  is also available.

### $\textbf{4.1.3.2} \quad \textbf{Search-Allowed-Model 3:} \mathcal{Q}(\texttt{M}:3[\texttt{A}]) = \{\texttt{M}:3[\texttt{R}][\texttt{A}], \ \texttt{M}:3[\texttt{P}][\texttt{A}], \ \tilde{\texttt{M}}:3[\texttt{R}][\texttt{A}], \ \tilde{\texttt{M}}:3[\texttt{P}][\texttt{A}]\}$

The quadruple models indicated in the above brace are the same as those in Section 4.1.3.1(p.21) only except that after the process has initiated, it is allowed to skip the search.

### 4.2 Recall-Model

See Chap. 25(p.249).

### 4.3 Spaces

Let us refer to  $\lambda \in (0,1]$ ,  $\beta \in (0,1]$ ,  $s \in [0,\infty)$ , and  $\rho \in (-\infty,\infty)$  as the parameter of models, all of which are independent of the distribution function F. Then, let  $\mathbf{p} = (\lambda, \beta, s)$  for Model 1 and  $\mathbf{p} = (\lambda, \beta, s, \rho)$  for Models 2 and 3, which are called the parameter vector. We represent the set of all possible  $\mathbf{p}$ 's by

$$\mathscr{P} = \{ \boldsymbol{p} \mid \lambda = 1, \ 0 < \beta \le 1, \ 0 \le s \}$$
 for Model 1, (4.3.1)

$$\mathscr{P} = \{ \boldsymbol{p} \mid 0 < \lambda \le 1, \ 0 < \beta \le 1, \ 0 \le s, \ -\infty < \rho < \infty \} \quad \text{for Models 2,3,}$$

$$(4.3.2)$$

called the total parameter space, simply total-P-space. Then, let us refer to the direct product (Cartesian product) of the total-P-space  $\mathscr{P}$  and total-DF-space  $\mathscr{F}$  (see (2.2.5(p.13))), i.e.,

$$\mathscr{P} \times \mathscr{F} = \{ (\boldsymbol{p}, F) \mid \boldsymbol{p} \in \mathscr{P}, F \in \mathscr{F} \}$$

$$(4.3.3)$$

as the total-P/DF-space.

### Different Variations

In this chapter let us present various variations of models defined in Chap. 4(p.19).

### 5.1 No-Recall-Model

Below are variations of models defined in Section 4.1(p.19).

- (1) Limited search budget [24,Iku1992]<sup>†</sup> This model involves a limited total budget allocated for search activities. The challenge lies in determining how to distribute this limited budget among search activities at each time point throughout the planning horizon.
- (2) Price mechanism switching [17,Eem2006] [15,Eem2004]\* This model allows for the switching of price mechanisms between R-mechanism and P-mechanism at each time point during the planning horizon.
- (3) Several search areas [25,Iku1995]<sup>‡</sup> For instance, consider Tokyo, Kyoto, and Osaka as potential areas where the leading-trader can search for counter-traders. If the leading-trader is in Tokyo today, the decision arises tomorrow whether to remain in Tokyo, move to Kyoto, or relocate to Osaka?
- (4) Uncertain deadline [18,Eem2009] In Example 1.3.1(p.5), the return home date is not yet definite; it could be imminent, one week later, or the directive itself might be rescinded.

### 5.2 Recall-Model

Below are variations of models defined in Section 4.2(p.21).

- (5) Uncertain recall [31,Kar1977] [2,Aki2014] [23,Iku1988]§ This is the model in which the recall of counter-traders once rejected is uncertain.
- (6) Costly recall [28,Kan1999],[29,Kan2005] This is the model in which some cost must be paid to recall counter-traders once rejected.
- (7) Reserved recall [41,Sai1998],[42,Sai1999] This is the model in which the availability of recall can be reserved by paying some deposit

### 5.3 Others

In addition to the above variations, in the future we will have other different variations which are not yet posed by any researchers. For example:

- (8) Multiple assets model This is the model in which multiple assets are traded. In the model, the optimal decision rule depends on the number of assets remaining not yet being traded.
- $\langle 9 \rangle$  Lasting effect of search activity This is the model in which the effect of the search activity that was taken at a certain point in time lasts for a while. The simplest case of the variation is that its effect disappears with a given probability p at the next point in time; hence, it lasts with the probability 1-p.

<sup>&</sup>lt;sup>†</sup>https://www.orsj.or.jp/~archive/pdf/e\_mag/Vol.35\_02\_172.pdf

 $<sup>{\</sup>rm *https://commons.sk.tsukuba.ac.jp/discussion/page/27~No.1098~(2004)}$ 

 $<sup>^{\</sup>ddagger} https://www.orsj.or.jp/~archive/pdf/e\_mag/Vol.38\_01\_089.pdf$ 

 $<sup>\</sup>label{eq:https://www.orsj.or.jp/~archive/pdf/e_mag/Vol.31_02_145.pdf} $$ https://www.orsj.or.jp/~archive/pdf/e_mag/Vol.31_02_145.pdf $$$ 

# 5.4 Future Subjects

ES. 1 We can consider the structured-unit-of-model also for each of the 9 variations presented above. Since each structured-unit-of-model consists of 24 model, it follows that the total number of variations amounts to  $216 = 24 \times 9$ . Analyses of all of them remain as subjects of future study (see Section 32.1(p.297)).

# **Underlying Functions**

This chapter defines some functions called the *underlying function*, which will be used to derive the system of optimality equations of the 24 model in Table 3.2.1(p.16).

### 6.1 Definition

### $extbf{6.1.1}$ $T,\,L\,,\,K,\, ext{and}\,\,\mathcal{L}\,\, ext{of Type}\,\,\mathbb{R}$

For any  $F \in \mathscr{F}$  let us define

$$T(x) = \mathbf{E}[\max\{\boldsymbol{\xi} - x, 0\}] \tag{6.1.1}$$

$$= \int_{-\infty}^{\infty} \max\{\xi - x, 0\} f(\xi) d\xi,^{\dagger \ddagger}$$

$$(6.1.2)$$

and then define

$$L(x) = \lambda \beta T(x) - s, \tag{6.1.3}$$

$$K(x) = \lambda \beta T(x) - (1 - \beta)x - s,$$
 § (6.1.4)

$$\mathcal{L}(s) = L(\lambda \beta \mu - s), \tag{6.1.5}$$

$$\kappa = \lambda \beta T(0) - s \tag{6.1.6}$$

$$= L(0) = K(0) = \lambda \beta T(0) - s \tag{6.1.7}$$

Let us refer to each of T, L, K, and  $\mathcal{L}$  as the *underlying function* of Type  $\mathbb{R}$  and to  $\kappa$  as the  $\kappa$ -value of Type  $\mathbb{R}$ . The formula below will be sometimes used in the rest of the paper.

$$K(x) + (1 - \beta)x = L(x),$$
 (6.1.8)

$$K(x) + x = L(x) + \beta x,$$
 (6.1.9)

$$\lambda \beta \mathbf{E}[\max\{\boldsymbol{\xi}, x\}] + (1 - \lambda)\beta x - s = K(x) + x \tag{6.1.10}$$

### **6.1.2** $\tilde{T}, \tilde{L}, \tilde{K}, \text{ and } \tilde{\mathcal{L}} \text{ of Type } \mathbb{R}$

For any  $F \in \mathscr{F}$  let us define

$$\tilde{T}(x) = \mathbf{E}[\min\{\boldsymbol{\xi} - x, 0\}] \tag{6.1.11}$$

$$= \int_{-\infty}^{\infty} \min\{\xi - x, 0\} f(\xi) d\xi, \tag{6.1.12}$$

and then define

$$\tilde{L}(x) = \lambda \beta \tilde{T}(x) + s, \tag{6.1.13}$$

$$\tilde{K}(x) = \lambda \beta \tilde{T}(x) - (1 - \beta)x + s, \tag{6.1.14}$$

$$\tilde{\mathcal{L}}(s) = \tilde{L}(\lambda \beta \mu + s), \tag{6.1.15}$$

$$\tilde{\kappa} = \lambda \beta \tilde{T}(0) + s \tag{6.1.16}$$

$$= \tilde{L}(0) = \tilde{K}(0). \tag{6.1.17}$$

Let us refer to each of  $\tilde{T}$ ,  $\tilde{L}$ ,  $\tilde{K}$ , and  $\tilde{\mathcal{L}}$  as the underlying function of Type  $\mathbb{R}$  and to  $\tilde{\kappa}$  as the  $\tilde{\kappa}$ -value of Type  $\mathbb{R}$ .

<sup>†</sup>See [14,DeGroot70].

<sup>&</sup>lt;sup>‡</sup>See Figure A 7.3(p.324) (I) ,

 $<sup>\</sup>S$  See Figure A 7.3(p.324) (II) ,

### **6.1.3** $T, L, K, \text{ and } \mathcal{L} \text{ of Type } \mathbb{P}$

For any  $F \in \mathscr{F}$  let us define

$$p(z) = \Pr\{z \le \xi\},$$
 (6.1.18)

$$T(x) = \max_{z} p(z)(z-x)^{\dagger}$$
 (6.1.19)

and then define

$$L(x) = \lambda \beta T(x) - s, \tag{6.1.20}$$

$$K(x) = \lambda \beta T(x) - (1 - \beta)x - s, \tag{6.1.21}$$

$$\mathcal{L}(s) = L(\lambda \beta a - s), \tag{6.1.22}$$

$$\kappa = \lambda \beta T(0) - s \tag{6.1.23}$$

$$= L(0) = K(0) \tag{6.1.24}$$

Let us refer to each of T, L, K, and  $\mathcal{L}$  as the *underlying function* of Type  $\mathbb{P}$  and to  $\kappa$  as the  $\kappa$ -value of Type  $\mathbb{P}$ . Let us denote z maximizing p(z)(z-x) by z(x) if it exists, i.e.,

$$T(x) = p(z(x))(z(x) - x). (6.1.25)$$

**Definition 6.1.1** If there exists multiple z(x), let us define the *smallest* of them as z(x).  $\Box$ 

Furthermore, for convenience of later discussions, let us define

$$a^* = \inf\{x \mid T(x) + x > a\} = \inf\{x \mid T(x) > a - x\},\tag{6.1.26}$$

$$x^* = \inf\{x \mid z(x) > a\}. \tag{6.1.27}$$

Noting that (6.1.18(p.26)) can be rewritten as  $p(z) = 1 - \Pr\{\xi < z\} = 1 - \Pr\{\xi \le z\}$  due to the assumption of F being continuous (see A9(p.12)), we have p(z) = 1 - F(z). Accordingly, it can be immediately seen that

$$p(z) \begin{cases} = 1, & z \le a & \cdots (1) & \text{due to } (2.2.1 (1) (p.12)), \\ < 1, & a < z & \cdots (2) & \text{due to } (2.2.1 (2,3) (p.12)), \end{cases}$$

$$(6.1.28)$$

$$p(z) \begin{cases} > 0, & z < b \quad \cdots (1), & \text{due to } (2.2.1 (1,2) \text{ (p.12)}), \\ = 0, & b \le z \quad \cdots (2), & \text{due to } (2.2.1 \text{ (p.12)})3. \end{cases}$$

$$(6.1.29)$$

In general p(z)(z-x) can be depicted as below.

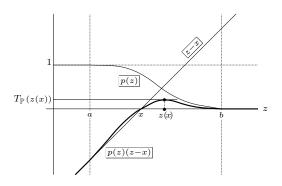


Figure 6.1.1: Graph of p(z)(z-x)

When F is the uniform distribution function on [a, b], we have

$$a^* = 2a - b \quad \text{(see (A 7.6 (1) (p.325)))}.$$
 (6.1.30)

### **6.1.4** $\tilde{T}$ , $\tilde{L}$ , $\tilde{K}$ , and $\tilde{\mathcal{L}}$ of Type $\mathbb{P}$

For any  $F \in \mathscr{F}$  let us define

$$\tilde{p}(z) = \Pr\{\boldsymbol{\xi} \le z\},\tag{6.1.31}$$

$$\tilde{T}(x) = \min \tilde{p}(z)(z - x), \tag{6.1.32}$$

 $<sup>^{\</sup>dagger}$ See Figure A 7.4(p.324) .

and then define

$$\tilde{L}(x) = \lambda \beta \tilde{T}(x) + s, \tag{6.1.33}$$

$$\tilde{K}(x) = \lambda \beta \tilde{T}(x) - (1 - \beta)x + s, \tag{6.1.34}$$

$$\tilde{\mathcal{L}}(s) = \tilde{L}(\lambda \beta b + s), \tag{6.1.35}$$

$$\tilde{\kappa} = \lambda \beta \tilde{T}(0) + s \tag{6.1.36}$$

$$= \tilde{L}(0) = \tilde{K}(0). \tag{6.1.37}$$

Let us refer to each of  $\tilde{T}$ ,  $\tilde{L}$ ,  $\tilde{K}$ , and  $\tilde{\mathcal{L}}$  as the *underlying function* of Type  $\mathbb{P}$  and to  $\tilde{\kappa}$  as the  $\tilde{\kappa}$ -value of Type  $\mathbb{P}$ . Let us denote z minimizing  $\tilde{p}(z)(z-x)$  by z(x) if it exists, i.e.,

$$\tilde{T}(x) = \tilde{p}(z(x))(z(x) - x).$$
 (6.1.38)

**Definition 6.1.2** If there exists multiple z(x), let us define the *largest* of them as z(x).  $\square$ 

Furthermore, for convenience of later discussions, let us define

$$b^* = \sup\{x \mid \tilde{T}(x) + x < b\} = \sup\{x \mid \tilde{T}(x) < b - x\},\tag{6.1.39}$$

$$\tilde{x}^* = \sup\{x \,|\, z(x) < b\}. \tag{6.1.40}$$

Noting that (6.1.31 (p.26)) can be rewritten as  $\tilde{p}(z) = F(z)$ , we can immediately see that

$$\tilde{p}(z) \begin{cases} = 0, & z \le a & \cdots (1) & \text{due to } (2.2.1 \, (1) \, (\text{p.12})), \\ > 0, & a < z & \cdots (2) & \text{due to } (2.2.1 \, (2.3) \, (\text{p.12})), \end{cases}$$

$$(6.1.41)$$

$$\tilde{p}(z) \begin{cases} < 1, & z < b & \cdots (1) & \text{due to } (2.2.1 (1,2) \text{ (p.12)}), \\ = 1, & b \le z & \cdots (2) & \text{due to } (2.2.1 (3) \text{ (p.12)}). \end{cases}$$

$$(6.1.42)$$

### 6.2 Solutions

The solutions defined below are commonly used in the analyses of all models in the whole paper.

(a) Let us define the solutions of the equations L(x) = 0, K(x) = 0, and  $\mathcal{L}(s) = 0$  (whether Type  $\mathbb{R}$  or Type  $\mathbb{P}$ ) by  $x_L$ ,  $x_K$ , and  $s_{\mathcal{L}}$  respectively if they exist, i.e.,

$$L(x_L) = 0 \cdots (1), \qquad K(x_K) = 0 \cdots (2), \qquad \mathcal{L}(s_L) = 0 \cdots (1).$$
 (6.2.1)

If multiple solutions exist for each of the above three equations, we employ the smallest as its solution.

(b) Let us define the solutions of the equations  $\tilde{L}(x) = 0$ ,  $\tilde{K}(x) = 0$ , and  $\tilde{\mathcal{L}}(s) = 0$  (whether Type  $\mathbb{R}$  or Type  $\mathbb{P}$ ) by  $x_{\tilde{L}}$ ,  $x_{\tilde{K}}$ , and  $s_{\tilde{L}}$  respectively if they exist.

$$\tilde{L}(x_{\tilde{L}}) = 0 \cdots (1), \qquad \tilde{K}(x_{\tilde{K}}) = 0 \cdots (2), \qquad \tilde{\mathcal{L}}(s_{\tilde{\mathcal{L}}}) = 0 \cdots (1).$$
 (6.2.2)

If multiple solutions exist for each of the above three equations, we employ the largest as its solution.

### 6.3 Primitive Underlying Functions and Derivative Underlying Functions

Sometimes let us refer to each of T- and  $\tilde{T}$ -functions as the <u>primitive</u> underlying function and to each of L-, K-,  $\tilde{L}$ -,  $\tilde{L}$ -, and  $\tilde{\mathcal{L}}$ -functions as the <u>derivative</u> underlying function, which are defined by use of primitive underlying functions T and  $\tilde{T}$ .

### 6.4 Identical Representation and Explicit Representation

In the rest of the paper, when we need to distinguish

$$T, L, K, \mathcal{L}, \kappa, x_L, x_K, s_{\mathcal{L}}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, \tilde{\kappa}, x_{\tilde{L}}, x_{\tilde{K}}, s_{\tilde{\mathcal{L}}}$$
 (6.4.1)

between Type  $\mathbb{R}$  and Type  $\mathbb{P}$ , let us denote them by

$$T_{\mathbb{R}}, L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}, x_{L_{\mathbb{R}}}, x_{K_{\mathbb{R}}}, s_{\mathcal{L}_{\mathbb{R}}}, \tilde{T}_{\mathbb{R}}, \tilde{L}_{\mathbb{R}}, \tilde{K}_{\mathbb{R}}, \tilde{\mathcal{L}}_{\mathbb{R}}, \tilde{\kappa}_{\mathbb{R}}, x_{\tilde{L}_{\mathbb{D}}}, x_{\tilde{K}_{\mathbb{D}}}, s_{\tilde{\mathcal{L}}_{\mathbb{D}}}, s_{\tilde$$

$$T_{\mathbb{P}}, L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}, x_{L_{\mathbb{P}}}, x_{K_{\mathbb{P}}}, s_{\mathcal{L}_{\mathbb{P}}}, \tilde{T}_{\mathbb{P}}, \tilde{L}_{\mathbb{P}}, \tilde{K}_{\mathbb{P}}, \tilde{\mathcal{L}}_{\mathbb{P}}, \tilde{\kappa}_{\mathbb{P}}, x_{\tilde{L}_{\mathbb{p}}}, x_{\tilde{K}_{\mathbb{p}}}, s_{\tilde{\mathcal{L}}_{\mathbb{p}}}.$$

$$(6.4.3)$$

Let us refer to (6.4.1) as the identical representation and to (6.4.2) and (6.4.3) as the explicit representation.

# 6.5 Characteristic Vector and Characteristic Element

Let us here define the two vectors,  $C_{\mathbb{R}}$  consisting of (6.1.3(p.25))-(6.1.6(p.25)) and  $\tilde{C}_{\mathbb{R}}$  consisting of (6.1.13(p.25))-(6.1.16(p.25)), i.e,

$$oldsymbol{C}_{\mathbb{R}} = (L_{\mathbb{R}}\,, K_{\mathbb{R}}\,, \mathcal{L}_{\mathbb{R}}\,, \kappa_{\mathbb{R}}), \qquad ilde{oldsymbol{C}}_{\mathbb{R}} = ( ilde{L}_{\mathbb{R}}\,, ilde{K}_{\mathbb{R}}\,, ilde{\mathcal{L}}_{\mathbb{R}}\,, ilde{\kappa}_{\mathbb{R}}).$$

Likewise, let us define the two vectors,  $C_{\mathbb{P}}$  consisting of (6.1.20(p.26))-(6.1.23(p.26)) and  $\tilde{C}_{\mathbb{P}}$  consisting of (6.1.33(p.27))-(6.1.36(p.27)), i.e.,

$$oldsymbol{C}_{\mathbb{P}} = (L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}), \qquad ilde{oldsymbol{C}}_{\mathbb{P}} = ( ilde{L}_{\mathbb{P}}, ilde{K}_{\mathbb{P}}, ilde{\mathcal{L}}_{\mathbb{P}}, ilde{\kappa}_{\mathbb{P}}).$$

Furthermore, adding T- and  $\tilde{T}$ -functions to the above vectors, let us define

$$egin{aligned} oldsymbol{C}_{\mathbb{R}}^T &= (T_{\mathbb{R}}, L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}), \quad ilde{oldsymbol{C}}_{\mathbb{R}}^T &= ( ilde{T}_{\mathbb{R}}, ilde{L}_{\mathbb{R}}, ilde{K}_{\mathbb{R}}, ilde{\mathcal{L}}_{\mathbb{R}}, ilde{\kappa}_{\mathbb{R}}), \\ oldsymbol{C}_{\mathbb{P}}^T &= (T_{\mathbb{P}}, L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}), \quad ilde{oldsymbol{C}}_{\mathbb{P}}^T &= ( ilde{T}_{\mathbb{P}}, ilde{L}_{\mathbb{P}}, ilde{K}_{\mathbb{P}}, ilde{\mathcal{L}}_{\mathbb{P}}, ilde{\kappa}_{\mathbb{P}}). \end{aligned}$$

Let us call each of the vectors defined above the *characteristic vector* and its element the *characteristic element*. In the identical representation, the above vectors are all represented by C,  $\tilde{C}$ ,  $C^{T}$ , and  $\tilde{C}^{T}$  respectively.

# Systems of Optimality Equations

In this chapter we derive the system of optimality equations (SOE) for each of the 24 models in Table 3.2.1(p.16) (see Chap. 26(p.251) for models in Table 3.2.2(p.16)).

### 7.1 Preliminary

Definition 7.1.1 Throughout the paper let us represent the action

"Conduct the search at time t" ("Skip the search at time t")

as  $Conduct_t$  ( $Skip_t$ ) for short. Then, when this action is simply optimal, indifferently optimal, or strictly optimal, let us represent it as respectively

$$\mathtt{Conduct}_{t_{\vartriangle}}\left(\mathtt{Skip}_{t^{\vartriangle}}\right), \quad \mathtt{Conduct}_{t_{\parallel}}\left(\mathtt{Skip}_{t^{\parallel}}\right), \quad \mathtt{or} \quad \mathtt{Conduct}_{t_{\blacktriangle}}\left(\mathtt{Skip}_{t^{\blacktriangle}}\right). \quad \Box$$

Remark 7.1.1 (relationship between SOE and assertion) In general, a model M of a decision process, whether in this paper or not, has the system of optimality equations, denoted by SOE{M}, which should be said to be a mirror exhaustively reflecting the entire aspect of the model M. In other words, SOE{M} involves the exhaustive information of the model M as if a gene has the exhaustive information of a life. This implies that any assertion which is characterized by the sequence  $\{V_t\}$  generated from SOE{M} can be regarded as an assertion on the model M; conversely, an assertion which is not characterized by the sequence  $\{V_t\}$  cannot be said to be an assertion on the M.  $\square$ 

Below let us represent "buyer (seller) proposing a price w" by "buyer (seller) w" for short.

### 7.2 No-Recall-Model

### 7.2.1 Search-Allowed-Model

### 7.2.1.1 Model 1

Let us note here that  $\lambda = 1$  is assumed in this model.

### **7.2.1.1.1** M:1[ $\mathbb{R}$ ][A]

By  $v_t(w)$   $(t \ge 0)$  and  $V_t$  (t > 0) let us denote the maximums of the total expected present discounted *profit* from initiating the process at time t with a buyer w and with no buyer respectively. Then, we have

$$v_0(w) = w, (7.2.1)$$

$$v_t(w) = \max\{w, V_t\}, \quad t > 0,$$
 (7.2.2)

where  $V_t$  is the maximum of the total expected present discounted profit from rejecting the proposed price w. Then, we have

$$V_1 = \beta \mathbf{E}[v_0(\xi)] - s = \beta \mathbf{E}[\xi] - s = \beta \mu - s \quad \text{(see Remark 4.1.3(p.20) (b))},$$
 (7.2.3)

$$V_t = \max\{\mathbf{C} : \beta \mathbf{E}[v_{t-1}(\xi)] - s, \ \mathbf{S} : \beta V_{t-1}\}, \quad t > 1,$$
(7.2.4)

where C and S represent the actions of Conducting the search and Skipping the search respectively. Then, since  $v_{t-1}(\boldsymbol{\xi}) = \max\{\boldsymbol{\xi}, V_{t-1}\} = \max\{\boldsymbol{\xi} - V_{t-1}, 0\} + V_{t-1}$ , we have  $\mathbf{E}[v_{t-1}(\boldsymbol{\xi})] = T(V_{t-1}) + V_{t-1}$  for t > 1 (see (6.1.1(p.25))), hence (7.2.4(p.29)) can be written as

$$V_{t} = \max\{\beta T(V_{t-1}) + \beta V_{t-1} - s, \beta V_{t-1}\}$$

$$= \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} \quad (\text{see } (6.1.4(p.25)) \text{ with } \lambda = 1)$$

$$= \max\{K(V_{t-1}) + (1 - \beta)V_{t-1}, 0\} + \beta V_{t-1}$$

$$= \max\{L(V_{t-1}), 0\} + \beta V_{t-1}, \quad t > 1 \quad (\text{see } (6.1.8(p.25))).$$

$$(7.2.6)$$

 $\square$  SOE{M:1[ $\mathbb{R}$ ][A]} is given by the set of (7.2.1(p.29)) - (7.2.4(p.29)). However, since the sequence  $\{V_t\}$  is generated from the two expressions (7.2.3(p.29)) and (7.2.5(p.29)), due to Remark (7.2.1(p.29)) it can be reduced to only the two in Table (7.4.1(p.41)) (I).  $\square$ 

Now, let us here define

$$S_t = \beta(\mathbf{E}[v_{t-1}(\xi)] - V_{t-1}) - s, \quad t > 1.$$
(7.2.7)

Then, (7.2.4(p.29)) can be rewritten as

$$V_{t} = \max\{\beta \mathbf{E}[v_{t-1}(\boldsymbol{\xi})] - \beta V_{t-1} - s, 0\} + \beta V_{t-1}$$
  
= \text{max}\{S\_{t}, 0\} + \beta V\_{t-1}, \quad t > 1, \quad (7.2.8)

implying that

$$\mathbb{S}_t \ge (\le) \ 0 \Rightarrow \mathtt{Conduct}_t \ (\mathtt{Skip}_t), \tag{7.2.9}$$

which can be rewritten as, due to Def. 7.1.1(p.29),

$$\mathbb{S}_t \ge (\le) \ 0 \Rightarrow \mathsf{Conduct}_{t_{\Delta}} \ (\mathsf{Skip}_{t_{\Delta}}). \tag{7.2.10}$$

$$\mathbb{S}_t = (=) \ 0 \Rightarrow \mathsf{Conduct}_{t \parallel} \ (\mathsf{Skip}_{t \parallel}). \tag{7.2.11}$$

$$\mathbb{S}_t > (<) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}} \ (\mathtt{Skip}_{t_{\blacktriangle}}).$$
 (7.2.12)

Then, from (7.2.2(p.29)) we can rewrite (7.2.7(p.30)) as

$$\mathbb{S}_t = \beta(\mathbf{E}[\max\{\xi, V_{t-1}\}] - V_{t-1}) - s = \beta \mathbf{E}[\max\{\xi - V_{t-1}, 0\}] - s.$$

Accordingly, from (6.1.1(p.25)) and (6.1.3(p.25)) with  $\lambda = 1$  we have

$$S_t = \beta T(V_{t-1}) - s \tag{7.2.13}$$

$$= L(V_{t-1}), \quad t > 1. \tag{7.2.14}$$

### **7.2.1.1.2** $M:1[\mathbb{R}][A]$

By  $v_t(w)$   $(t \ge 0)$  and  $V_t$  (t > 0) let us denote the minimums of the total expected present discounted *cost* from initiating the process at time t with a seller w and with no seller respectively. Then, we have

$$v_0(w) = w, (7.2.15)$$

$$v_t(w) = \min\{w, V_t\}, \quad t > 0,$$
 (7.2.16)

where  $V_t$  is the minimum of the total expected present discounted cost from rejecting the proposed price w. Then, we have

$$V_1 = \beta \mathbf{E}[v_0(\xi)] + s = \beta \mathbf{E}[\xi] + s = \beta \mu + s, \tag{7.2.17}$$

$$V_t = \min\{\beta \mathbf{E}[v_{t-1}(\xi)] + s, \, \beta V_{t-1}\}, \quad t > 1.$$
(7.2.18)

Then, since  $v_{t-1}(\boldsymbol{\xi}) = \min\{\boldsymbol{\xi}, V_{t-1}\} = \min\{\boldsymbol{\xi} - V_{t-1}, 0\} + V_{t-1}$ , we have  $\mathbf{E}[v_{t-1}(\boldsymbol{\xi})] = \tilde{T}(V_{t-1}) + V_{t-1}$  for t > 1 (see (6.1.11(p.25))), hence (7.2.18(p.30)) can be written as

$$V_{t} = \min\{\beta \tilde{T}(V_{t-1}) + \beta V_{t-1} + s, \beta V_{t-1}\}$$

$$= \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} \quad (\text{see } (6.1.14(p.25)) \text{ with } \lambda = 1)$$

$$= \min\{\tilde{K}(V_{t-1}) + (1-\beta)V_{t-1}, 0\} + \beta V_{t-1}$$

$$= \min\{\tilde{L}(V_{t-1}), 0\} + \beta V_{t-1}, \quad t > 1 \quad (\text{see } (6.1.14(p.25)) \text{ and } (6.1.13(p.25)) \text{ with } \lambda = 1).$$

$$(7.2.20)$$

 $\square$  SOE $\{\tilde{M}:1[\mathbb{R}][A]\}$  can be reduced to (7.2.17(p.30)) and (7.2.19(p.30)), listed in Table 7.4.1(p.41) (II).  $\square$ 

Remark 7.2.1 Note here that the same notations  $v_t(w)$  and  $V_t$  are used for both  $M:1[\mathbb{R}][A]$  and  $\tilde{M}:1[\mathbb{R}][A]$ . For explanatory convenience, later on we sometimes represent the  $v_t(w)$  and  $V_t$  for  $\tilde{M}:1[\mathbb{R}][A]$  by  $\tilde{v}_t(w)$  and  $\tilde{V}_t$  respectively. Then (7.2.15(p.30))-(7.2.18(p.30)) are written as respectively

$$\begin{split} &\tilde{v}_0(w) = w, \\ &\tilde{v}_t(w) = \min\{w, \tilde{V}_t\}, \\ &\tilde{V}_1 = \beta \mu + s, \\ &\tilde{V}_t = \min\{\beta \operatorname{\mathbf{E}}[\tilde{v}_{t-1}(\boldsymbol{\xi})] + s, \beta \tilde{V}_{t-1}\}. \quad \Box \end{split}$$

Now, let us here define

$$\tilde{\mathbb{S}}_t = \beta(\mathbf{E}[v_{t-1}(\xi)] - V_{t-1}) + s, \quad t > 1.$$
(7.2.21)

Then, (7.2.18(p.30)) can be rewritten as

$$V_{t} = \min\{\beta \mathbf{E}[v_{t-1}(\xi)] - \beta V_{t-1} + s, 0\} + \beta V_{t-1}$$
  
= \text{min}\{\tilde{\S}\_{t}, 0\} + \beta V\_{t-1}, \quad t > 1, \quad (7.2.22)

which can be rewritten as, due to Def. 7.1.1(p.29),

$$\tilde{\mathbb{S}}_t \le (\ge) \ 0 \Rightarrow \mathsf{Conduct}_t \ (\mathsf{Skip}_t),$$
 (7.2.23)

which can be rewritten as, due to Def. 7.1.1(p.29),

$$\tilde{\mathbb{S}}_t \le (\ge) \ 0 \Rightarrow \mathsf{Conduct}_{t_{\Delta}} \ (\mathsf{Skip}_{t_{\Delta}}).$$
 (7.2.24)

$$\tilde{\mathbb{S}}_t = (=) \ 0 \Rightarrow \mathsf{Conduct}_{t \parallel} \ (\mathsf{Skip}_{t \parallel}). \tag{7.2.25}$$

$$\tilde{\mathbb{S}}_t < (>) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}} \ (\mathtt{Skip}_{t_{\blacktriangle}}).$$
 (7.2.26)

Then, from (7.2.16(p.30)) we can rewrite (7.2.21(p.31)) as

$$\tilde{\mathbb{S}}_t = \beta(\mathbf{E}[\min\{\xi, V_{t-1}\}] - V_{t-1}) + s = \beta \mathbf{E}[\min\{\xi - V_{t-1}, 0\}] + s.$$

Accordingly, from (6.1.11(p.25)) and (6.1.13(p.25)) with  $\lambda = 1$  we have

$$\tilde{\mathbb{S}}_t = \beta \tilde{T}(V_{t-1}) + s \tag{7.2.27}$$

$$= \tilde{L}(V_{t-1}), \quad t > 1. \tag{7.2.28}$$

### **7.2.1.1.3** M:1[ $\mathbb{P}$ ][A]

By  $v_t$   $(t \ge 0)$  and  $V_t$  (t > 0) let us denote the maximums of the total expected present discounted *profit* from initiating the process at time t with a buyer and with no buyer respectively. In addition, let us denote the optimal price to propose at time  $t \ge 0$  by  $z_t$ . In this model, since the search must be necessarily conducted at time 1 (see Remark 4.1.3(p.20) (b)), there exists a buyer at time 0. Suppose the process has proceeded up to time 0. Then, since the seller must necessarily sell the asset at that time, he must propose the price  $a^{\dagger}$  to a buyer appearing at that time (see Remark 4.1.1(p.19) (b2)), thus we have

$$z_0 = a. (7.2.29)$$

Hence, the profit that the seller obtains at time 0 becomes a, i.e.,

$$v_0 = a. (7.2.30)$$

Now, since the search is conducted at time 1 (see Remark 4.1.3(p.20) (b)), we have

$$V_1 = \beta v_0 - s = \beta a - s. \tag{7.2.31}$$

In addition, we have

$$V_t = \max\{\beta v_{t-1} - s, \, \beta V_{t-1}\}, \quad t > 1. \tag{7.2.32}$$

If the seller proposes a price z, the probability of a buyer buying the asset is given by  $p(z) = \Pr\{z \leq \xi\}$  (see (6.1.18(p.26))), hence we have

$$v_t = \max_{z} \{ p(z)z + (1 - p(z))V_t \} = \max_{z} p(z)(z - V_t) + V_t = T(V_t) + V_t, \quad t > 0,$$
(7.2.33)

due to (6.1.19(p.26)), implying that the optimal price  $z_t$  which the seller should propose is given by

$$z_t = z(V_t), \quad t > 0, \quad (\text{see } (6.1.25(p.26))).$$
 (7.2.34)

Now, since  $v_{t-1} = T(V_{t-1}) + V_{t-1}$  for t > 1, we can rearrange (7.2.32(p.31)) as follows

$$V_{t} = \max\{\beta T(V_{t-1}) + \beta V_{t-1} - s, \beta V_{t-1}\}$$

$$= \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} \quad (\text{see } (6.1.21(p.26)) \text{ with } \lambda = 1)$$

$$= \max\{K(V_{t-1}) + (1-\beta)V_{t-1}, 0\} + \beta V_{t-1}$$

$$(7.2.35)$$

$$= \max\{L(V_{t-1}), 0\} + \beta V_{t-1}, \quad t > 1, \quad (\text{see } (6.1.21(p.26)) \text{ and } (6.1.20(p.26)) \text{ with } \lambda = 1)$$

$$(7.2.36)$$

 $\square$  SOE{M:1[P][A]} is given by (7.2.31(p.31)) and (7.2.35(p.31)), listed in Table 7.4.1(p.41) (III).  $\square$ 

Now, let us here define

$$S_t = \beta(v_{t-1} - V_{t-1}) - s, \quad t > 1. \tag{7.2.37}$$

Then, (7.2.32(p.31)) can be rewritten as

 $<sup>^{\</sup>dagger}$ The lower bound of the distribution function for the reservation price (maximum permissible buying price) of the buyer.

$$V_{t} = \max\{\beta v_{t-1} - \beta V_{t-1} - s, 0\} + \beta V_{t-1}$$
  
= \text{max}\{\S\_{t}, 0\} + \beta V\_{t-1}, \quad t > 1, \quad (7.2.38)

implying that

$$\mathbb{S}_t \ge (\le) \ 0 \Rightarrow \mathsf{Conduct}_t \ (\mathsf{Skip}_t).$$
 (7.2.39)

which can be rewritten as, due to Def. 7.1.1(p.29),

$$\mathbb{S}_t \ge (\le) \ 0 \Rightarrow \mathsf{Conduct}_{t_{\Delta}} \ (\mathsf{Skip}_{t_{\Delta}}). \tag{7.2.40}$$

$$\mathbb{S}_t = (=) \ 0 \Rightarrow \mathsf{Conduct}_{t \parallel} \ (\mathsf{Skip}_{t \parallel}). \tag{7.2.41}$$

$$\mathbb{S}_t > (<) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}} \ (\mathtt{Skip}_{t_{\blacktriangle}}).$$
 (7.2.42)

Then, from (7.2.33(p.31)) with t-1 we have  $v_{t-1} = T(V_{t-1}) + V_{t-1}$ , hence  $v_{t-1} - V_{t-1} = T(V_{t-1})$ , thus, noting (6.1.20(p.26)), we can rewrite (7.2.37(p.31)) as below

$$S_t = \beta T(V_{t-1}) - s \tag{7.2.43}$$

$$= L(V_{t-1}), \quad t > 1. \tag{7.2.44}$$

### **7.2.1.1.4** $\tilde{M}:1[\mathbb{P}][A]$

By  $v_t$  ( $t \ge 0$ ) and  $V_t$  (t > 0) let us denote the minimums of the total expected present discounted cost from initiating the process at time t with a seller and with no seller respectively. In addition, let us denote the optimal price to propose at time  $t \ge 0$  by  $z_t$ . In this model, since the search must be necessarily conducted at time 1, there exists a seller at time 0. Suppose the process has proceeded up to time 0. Then, since the buyer must necessarily buy the asset at that time, he must propose the price  $b^{\dagger}$  to a seller appearing at that time, thus we have

$$z_0 = b. (7.2.45)$$

Hence, the cost that the buyer pays at time 0 becomes b, i.e.,

$$v_0 = b. (7.2.46)$$

Now, since the search is conducted at time 1, we have

$$V_1 = \beta v_0 + s = \beta b + s. \tag{7.2.47}$$

In addition, we have

$$V_t = \min\{\beta v_{t-1} + s, \, \beta V_{t-1}\}, \quad t > 1. \tag{7.2.48}$$

If the buyer proposes a price z, the probability of a seller selling the asset is given by  $\tilde{p}(z) = \Pr\{\xi \leq z\}$  (see (6.1.31(p.26))), hence we have

$$v_t = \min\{\tilde{p}(z)z + (1 - \tilde{p}(z))V_t\} = \min\tilde{p}(z)(z - V_t) + V_t = \tilde{T}(V_t) + V_t, \quad t > 0,$$
(7.2.49)

due to (6.1.32(p.26)), implying that the optimal price  $z_t$  which the buyer should propose is given by

$$z_t = z(V_t), \quad t > 0, \quad (\text{see } (6.1.38(p.27))).$$
 (7.2.50)

Now, since  $v_{t-1} = \tilde{T}(V_{t-1}) + V_{t-1}$  for t > 1, we can rearrange (7.2.48(p.32)) as

$$V_{t} = \min\{\beta \tilde{T}(V_{t-1}) + \beta V_{t-1} + s, \beta V_{t-1}\}$$

$$= \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} \quad (\text{see } (6.1.34(p.27)) \text{ with } \lambda = 1)$$

$$= \min\{\tilde{K}(V_{t-1}) + (1-\beta)V_{t-1}, 0\} + \beta V_{t-1}$$

$$= \min\{\tilde{L}(V_{t-1}), 0\} + \beta V_{t-1}, \quad t > 1. \quad (\text{see } (6.1.34(p.27)) \text{ and } (6.1.33(p.27)) \text{ with } \lambda = 1)$$

$$(7.2.52)$$

 $\square$  SOE{ $\tilde{M}$ :1[ $\mathbb{P}$ ][A]} is given by (7.2.47(p.32)) and (7.2.51(p.32)), listed in Table 7.4.1(p.41) (IV).  $\square$ 

Now, let us here define

$$\tilde{\mathbb{S}}_t = \beta(v_{t-1} - V_{t-1}) + s, \quad t > 1.$$
 (7.2.53)

Then, (7.2.48(p.32)) can be rewritten as

$$V_{t} = \min\{\beta v_{t-1} - \beta V_{t-1} + s, 0\} + \beta V_{t-1}$$
  
= \text{min}\{\tilde{\Sigma}\_{t}, 0\} + \beta V\_{t-1}, \quad t > 1, \tag{7.2.54}

implying that

 $<sup>^\</sup>dagger$  The upper bound of the distribution function for the reservation price (minimum permissible selling price) of the seller

$$\tilde{\mathbb{S}}_t \le (\ge) \ 0 \Rightarrow \mathtt{Conduct}_t \ (\mathtt{Skip}_t). \tag{7.2.55}$$

which can be rewritten as, due to Def. 7.1.1(p.29),

$$\tilde{\mathbb{S}}_t \le (\ge) \ 0 \Rightarrow \mathsf{Conduct}_{t_{\Delta}} \ (\mathsf{Skip}_{t_{\Delta}}).$$
 (7.2.56)

$$\tilde{\mathbb{S}}_t = (=) \ 0 \Rightarrow \mathtt{Conduct}_{t \parallel} \ (\mathtt{Skip}_{t \parallel}). \tag{7.2.57}$$

$$\tilde{\mathbb{S}}_t < (>) \ 0 \Rightarrow \mathsf{Conduct}_{t_{\mathbf{A}}} \ (\mathsf{Skip}_{t_{\mathbf{A}}}).$$
 (7.2.58)

Then, from (7.2.49(p.32)) with t-1 we have  $v_{t-1} = \tilde{T}(V_{t-1}) + V_{t-1}$ , hence  $v_{t-1} - V_{t-1} = \tilde{T}(V_{t-1})$ , thus, noting (6.1.33(p.27)), we can rewrite (7.2.53(p.32)) as below

$$\mathbb{S}_t = \beta \tilde{T}(V_{t-1}) + s \tag{7.2.59}$$

$$= \tilde{L}(V_{t-1}), \quad t > 1. \tag{7.2.60}$$

#### 7.2.1.2 Model 2

# **7.2.1.2.1** M:2[ $\mathbb{R}$ ][A]

By  $v_t(w)$   $(t \ge 0)$  and  $V_t$  (t > 0) let us denote the maximums of the total expected present discounted *profit* from initiating the process at time t with a buyer w and with no buyer respectively. Then we have

$$v_0(w) = \max\{w, \rho\},\tag{7.2.61}$$

$$v_t(w) = \max\{w, V_t\}, \quad t > 0, \tag{7.2.62}$$

where

$$V_t = \max\{\lambda \beta \mathbf{E}[v_{t-1}(\xi)] + (1-\lambda)\beta V_{t-1} - s, \, \beta V_{t-1}\}, \quad t > 0.$$
 (7.2.63)

Let us here define

$$V_0 = \rho. \tag{7.2.64}$$

Then (7.2.62(p.33)) holds for  $t \ge 0$  instead of t > 0, i.e.,

$$v_t(w) = \max\{w, V_t\}, \quad t \ge 0. \tag{7.2.65}$$

Since  $v_{t-1}(\boldsymbol{\xi}) = \max\{\boldsymbol{\xi}, V_{t-1}\} = \max\{\boldsymbol{\xi} - V_{t-1}, 0\} + V_{t-1} = T(V_{t-1}) + V_{t-1} \text{ for } t > 0 \text{ (see (6.1.1(p.25))), from (7.2.63(p.33)) we have } V_t = \max\{\lambda\beta(T(V_{t-1}) + V_{t-1}) + (1-\lambda)\beta V_{t-1} - s, \beta V_{t-1}\}$ 

$$= \max\{\lambda \beta T(V_{t-1}) + \beta V_{t-1} - s, \beta V_{t-1}\}$$

$$= \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} \quad (\text{see } (6.1.4(p.25)))$$
(7.2.66)

$$= \max\{K(V_{t-1}) + (1-\beta)V_{t-1}, 0\} + \beta V_{t-1}$$
  
= \text{max}\{L(V\_{t-1}), 0\} + \beta V\_{t-1}, \quad t > 0 \quad \text{(see (6.1.8(p.25)))}. (7.2.67)

 $\square$  SOE{M:2[ $\mathbb{R}$ ][A]} is given by (7.2.64(p.33)) and (7.2.66(p.33)), listed in Table 7.4.3(p.41) (I).  $\square$ 

Let us here define

$$S_t = \lambda \beta (\mathbf{E}[v_{t-1}(\xi)] - V_{t-1}) - s, \quad t > 0. \tag{7.2.68}$$

Then, (7.2.63(p.33)) can be rewritten as

$$V_{t} = \max\{\lambda \beta \mathbf{E}[v_{t-1}(\xi)] - \lambda \beta V_{t-1} - s, 0\} + \beta V_{t-1}$$
  
= \text{max}\{S\_{t}, 0\} + \beta V\_{t-1}, \quad t > 0, \tag{7.2.69}

implying that

$$\mathbb{S}_t \ge (\le) \ 0 \Rightarrow \mathsf{Conduct}_t \ (\mathsf{Skip}_t), \quad t > 0. \tag{7.2.70}$$

which can be rewritten as, due to Def. 7.1.1(p.29)

$$\mathbb{S}_t \ge (\le) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\Delta}} \ (\mathtt{Skip}_{t_{\Delta}}). \tag{7.2.71}$$

$$\mathbb{S}_t = (=) \ 0 \Rightarrow \mathsf{Conduct}_{t \parallel} \ (\mathsf{Skip}_{t \parallel}). \tag{7.2.72}$$

$$\mathbb{S}_t > (<) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\mathbf{A}}} \ (\mathtt{Skip}_{t_{\mathbf{A}}}).$$
 (7.2.73)

Then, from (7.2.68(p.33)) we can rewrite (7.2.62(p.33)) as

$$\mathbb{S}_t = \beta(\mathbf{E}[\max\{\xi, V_{t-1}\}] - V_{t-1}) - s = \beta \mathbf{E}[\max\{\xi - V_{t-1}, 0\}] - s.$$

Accordingly, from (6.1.1(p.25)) and (6.1.3(p.25)) we have

$$S_t = \beta T(V_{t-1}) - s \tag{7.2.74}$$

$$= L(V_{t-1}), \quad t > 0. \tag{7.2.75}$$

### **7.2.1.2.2** $\tilde{M}:2[\mathbb{R}][A]$

By  $v_t(w)$   $(t \ge 0)$  and  $V_t$  (t > 0) let us denote the minimums of the total expected present discounted cost from initiating the process at time t with a seller w and with no seller respectively. Then, we have

$$v_0(w) = \min\{w, \rho\},\tag{7.2.76}$$

$$v_t(w) = \min\{w, V_t\}, \quad t > 0, \tag{7.2.77}$$

where

$$V_t = \min\{\lambda \beta \mathbf{E}[v_{t-1}(\xi)] + (1-\lambda)\beta V_{t-1} + s, \, \beta V_{t-1}\}, \quad t > 0.$$
 (7.2.78)

Let us here define

$$V_0 = \rho. \tag{7.2.79}$$

Then (7.2.77(p.34)) holds for  $t \ge 0$  instead of t > 0, i.e.,

$$v_t(w) = \min\{w, V_t\}, \quad t \ge 0. \tag{7.2.80}$$

Since  $v_{t-1}(\boldsymbol{\xi}) = \min\{\boldsymbol{\xi}, V_{t-1}\} = \min\{\boldsymbol{\xi} - V_{t-1}, 0\} + V_{t-1} = \tilde{T}(V_{t-1}) + V_{t-1} \text{ for } t > 0 \text{ (see (6.1.11(p.25))), from (7.2.78(p.34)) we have } \boldsymbol{\xi} = \sum_{t=0}^{n} (1 - t) \left( \sum_{t=0$ 

$$V_{t} = \min\{\lambda\beta(\tilde{T}(V_{t-1}) + V_{t-1}) + (1 - \lambda)\beta V_{t-1} + s, \beta V_{t-1}\}\$$

$$= \min\{\lambda \beta \tilde{T}(V_{t-1}) + \beta V_{t-1} + s, \beta V_{t-1}\}$$

$$= \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} \quad (\text{see } (6.1.14(p.25)))$$
(7.2.81)

$$= \min\{\tilde{K}(V_{t-1}) + (1-\beta)V_{t-1}, 0\} + \beta V_{t-1}$$

$$= \min\{\tilde{L}(V_{t-1}), 0\} + \beta V_{t-1}, \quad t > 0. \quad (\text{see } (6.1.14(\text{p.25})) \text{ and } (6.1.13(\text{p.25})))$$

$$(7.2.82)$$

 $\square$  SOE{ $\tilde{M}$ :2[ $\mathbb{R}$ ][A]} is given by (7.2.79(p.34)) and (7.2.81(p.34)), listed in Table 7.4.3(p.41) (II).  $\square$ 

Let us here define

$$\tilde{\mathbb{S}}_t = \lambda \beta (\mathbf{E}[v_{t-1}(\xi)] - V_{t-1}) + s, \quad t > 0.$$
 (7.2.83)

Then, (7.2.78(p.34)) can be rewritten as

$$V_{t} = \min\{\lambda \beta \mathbf{E}[v_{t-1}(\xi)] - \lambda \beta V_{t-1} + s, 0\} + \beta V_{t-1}$$
  
= \text{min}\{\tilde{\Sigma}\_{t}, 0\} + \beta V\_{t-1}, \quad t > 0, \quad (7.2.84)

implying that

$$\tilde{\mathbb{S}}_t \le (\ge) \ 0 \Rightarrow \mathsf{Conduct}_t \ (\mathsf{Skip}_t), \tag{7.2.85}$$

which can be rewritten as, due to Def. 7.1.1(p.29),

$$\tilde{\mathbb{S}}_t \le (\ge) \ 0 \Rightarrow \mathsf{Conduct}_{t_\Delta} \ (\mathsf{Skip}_{t_\Delta}).$$
 (7.2.86)

$$\tilde{\mathbb{S}}_t = (=) \ 0 \Rightarrow \mathsf{Conduct}_{t \parallel} \ (\mathsf{Skip}_{t \parallel}). \tag{7.2.87}$$

$$\tilde{\mathbb{S}}_t < (>) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}} \ (\mathtt{Skip}_{t_{\blacktriangle}}).$$
 (7.2.88)

Then, from (7.2.77(p.34)) we can rewrite (7.2.83(p.34)) as

$$\tilde{\mathbb{S}}_t = \beta(\mathbf{E}[\min\{\xi, V_{t-1}\}] - V_{t-1}) + s = \beta \mathbf{E}[\min\{\xi - V_{t-1}, 0\}] + s.$$

Accordingly, from (6.1.11(p.25)) and (6.1.13(p.25)) we have

$$\tilde{\mathbb{S}}_t = \beta \tilde{T}(V_{t-1}) + s \tag{7.2.89}$$

$$= \tilde{L}(V_{t-1}), \quad t > 1. \tag{7.2.90}$$

#### **7.2.1.2.3** M:2[ $\mathbb{P}$ ][A]

By  $v_t$   $(t \ge 0)$  and  $V_t$   $(t \ge 0)$  let us denote the maximums of the total expected present discounted *profit* from initiating the process at time t with a buyer and with no buyer respectively. In addition, let us denote the optimal price to propose at time  $t \ge 0$  by  $z_t$ . Suppose there exists a buyer at time t = 0 (deadline). Then, the seller must determine whether to accept the terminal quitting penalty  $\rho$  or to sell the asset to the buyer. Let the  $\rho$  is accepted. Then the profit which the seller can obtain is  $\rho$ . On the other hand, let the asset be sold to the buyer. Then since the seller must necessarily sell the asset to the buyer due to A2( $\rho$ ,11), the price  $a^{\dagger}$  must be proposed to the buyer; in other words, the optimal price to propose at time t = 0 is given by

$$z_0 = a, (7.2.91)$$

hence the profit which the seller can obtain at that time is a. Accordingly, it follows that the profit that the seller can obtain at time 0 is given by

 $<sup>^{\</sup>dagger}$  The lower bound of the distribution function for the reservation price (the maximum permissible buying price) of the buyer.

$$v_0 = \max\{\rho, a\}. \tag{7.2.92}$$

Suppose there exists a buyer at a time t > 0. Then, since the reservation price (maximum permissible buying price) of the buyer is  $\xi$ , if the seller proposes a price z, the probability of the buyer buying the asset is given by  $p(z) = \Pr\{z \leq \xi\}$  (see (6.1.18(p.26))). Hence we have

$$v_t = \max_{z} \{ p(z)z + (1 - p(z))V_t \} = \max_{z} p(z)(z - V_t) + V_t = T(V_t) + V_t, \quad t > 0,$$
(7.2.93)

due to (6.1.19(p.26)), implying that the optimal selling price  $z_t$  which the seller should propose is given by

$$z_t = z(V_t), t > 0,$$
 (7.2.94)

due to (6.1.25(p.26)). Finally  $V_t$  can be expressed as follows.

$$V_0 = \rho, \tag{7.2.95}$$

$$V_t = \max\{\lambda \beta v_{t-1} + (1 - \lambda)\beta V_{t-1} - s, \, \beta V_{t-1}\}, \quad t > 0.$$
(7.2.96)

For t = 1 we have

$$V_{1} = \max\{\lambda \beta v_{0} + (1 - \lambda)\beta V_{0} - s, \beta V_{0}\}$$

$$= \max\{\lambda \beta \max\{\rho, a\} + (1 - \lambda)\beta \rho - s, \beta \rho\}$$

$$= \max\{\lambda \beta \max\{0, a - \rho\} + \beta \rho - s, \beta \rho\}.$$
(7.2.97)

Since  $v_{t-1} = T(V_{t-1}) + V_{t-1}$  for t > 1 from (7.2.93(p.35)), we can rearrange (7.2.96(p.35)) as follows.

$$V_{t} = \max\{\lambda\beta(T(V_{t-1}) + V_{t-1}) + (1 - \lambda)\beta V_{t-1} - s, \beta V_{t-1}\}$$

$$= \max\{\lambda\beta T(V_{t-1}) + \beta V_{t-1} - s, \beta V_{t-1}\}$$

$$= \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} \quad (\text{see } (6.1.21(p.26)))$$

$$= \max\{K(V_{t-1}) + (1 - \beta)V_{t-1}, 0\} + \beta V_{t-1}$$

$$= \max\{L(V_{t-1}), 0\} + \beta V_{t-1}, \quad t > 1 \quad (\text{see } (6.1.21(p.26)) \text{ and } (6.1.20(p.26))).$$

$$(7.2.99)$$

 $\square$  SOE{M:1[P][A]} is given by (7.2.95(p.35)), (7.2.97(p.35)), and (7.2.98(p.35)), listed in Table 7.4.3(p.41) (III).

Now let us here define

$$S_t = \lambda \beta (v_{t-1} - V_{t-1}) - s, \quad t > 0. \tag{7.2.100}$$

Then (7.2.96(p.35)) can be rewritten as

$$V_{t} = \max\{\lambda \beta v_{t-1} - \lambda \beta V_{t-1} - s, 0\} - \beta V_{t-1}$$
  
= \text{max}\{\mathbb{S}\_{t}, 0\} + \beta V\_{t-1}, \quad t > 0, \tag{7.2.101}

implying that

$$\mathbb{S}_t \ge (\le) \ 0 \Rightarrow \mathsf{Conduct}_t \ (\mathsf{Skip}_t), \tag{7.2.102}$$

which can be rewritten as, due to Def. 7.1.1(p.29),

$$\mathbb{S}_t \ge (\le) \ 0 \Rightarrow \mathsf{Conduct}_{t_{\triangle}} \ (\mathsf{Skip}_{t_{\triangle}}). \tag{7.2.103}$$

$$\mathbb{S}_t = (=) \ 0 \Rightarrow \mathsf{Conduct}_{t \parallel} \ (\mathsf{Skip}_{t \parallel}). \tag{7.2.104}$$

$$\mathbb{S}_t > (<) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}} \ (\mathtt{Skip}_{t_{\blacktriangle}}). \tag{7.2.105}$$

Then, from (7.2.93(p.35)) with t-1 we have  $v_{t-1}=T(V_{t-1})+V_{t-1}$ , hence  $v_{t-1}-V_{t-1}=T(V_{t-1})$ , thus, noting (6.1.20(p.26)), we can rewrite (7.2.100(p.35)) as below

$$S_t = \beta T(V_{t-1}) - s \tag{7.2.106}$$

$$= L(V_{t-1}), \quad t > 0. \tag{7.2.107}$$

## **7.2.1.2.4** $\tilde{M}$ :2[ $\mathbb{P}$ ][ $\mathbb{A}$ ]

By  $v_t$   $(t \ge 0)$  and  $V_t$   $(t \ge 0)$  let us denote the minimums of the total expected present discounted cost from initiating the process at time t with a seller and with no seller respectively. In addition, let us denote the optimal price to propose at time  $t \ge 0$  by  $z_t$ . Suppose there exists a seller at time t = 0 (deadline). Then, the buyer must determine whether to accept the terminal quitting penalty  $\rho$  or to buy the asset from the seller. Let the  $\rho$  is accepted. Then the cost which the buyer pays is  $\rho$ . On the other hand, let an asset be bought from the seller. Them since the buyer must necessarily buy the asset from the seller due to A2(p.11), the price  $b^{\dagger}$  must be proposed to the seller; in other words, the optimal price to propose at time t = 0 is given by

<sup>&</sup>lt;sup>†</sup>The upper bound of the distribution function for the reservation price (the minimum permissible selling price) of the seller.

$$z_0 = b, (7.2.108)$$

hence the cost which the buyer pays at that time is b. Accordingly, the cost that the buyer pays at time 0 becomes

$$v_0 = \min\{\rho, b\}. \tag{7.2.109}$$

Suppose there exists a seller at a time t > 0. Then, since the reservation price (minimum permissible selling price) of the seller is  $\xi$ , if the buyer proposes a price z, the probability of the seller selling the asset is given by  $\tilde{p}(z) = \Pr\{\xi \leq z\}$  (see (6.1.31(p.26))). Hence we have

$$v_t = \min_{\tilde{z}} \{ \tilde{p}(z)z + (1 - p(z))V_t \} = \min_{\tilde{z}} \tilde{p}(z)(z - V_t) + V_t = \tilde{T}(V_t) + V_t, \quad t > 0,$$
 (7.2.110)

due to (6.1.32(p.26)), implying that the optimal buying price  $z_t$  which the buyer should propose is given by

$$z_t = z(V_t), t > 0,$$
 (7.2.111)

due to (6.1.38(p.27)). Finally  $V_t$  can be expressed as follows.

$$V_0 = \rho, \tag{7.2.112}$$

$$V_t = \min\{\lambda \beta v_{t-1} + (1 - \lambda)\beta V_{t-1} + s, \, \beta V_{t-1}\}, \quad t > 0.$$
(7.2.113)

For t = 1 we have

$$V_{1} = \min\{\lambda\beta v_{0} + (1-\lambda)\beta V_{0} + s, \beta V_{0}\}$$

$$= \min\{\lambda\beta \min\{\rho, b\} + (1-\lambda)\beta\rho + s, \beta\rho\}$$

$$= \min\{\lambda\beta \min\{0, b-\rho\} + \beta\rho + s, \beta\rho\}.$$
(7.2.114)

Since  $v_{t-1} = \tilde{T}(V_{t-1}) + V_{t-1}$  for t > 1 from (7.2.110(p.36)), we can rearrange (7.2.113(p.36)) as follows.

$$\begin{split} V_{t} &= \min\{\lambda\beta(\tilde{T}(V_{t-1}) + V_{t-1}) + (1-\lambda)\beta V_{t-1} + s, \beta V_{t-1}\} \\ &= \min\{\lambda\beta\tilde{T}(V_{t-1}) + \beta V_{t-1} + s, \beta V_{t-1}\} \\ &= \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} \quad (\text{see } (6.1.34(\text{p.27}))) \\ &= \min\{\tilde{K}(V_{t-1}) + (1-\beta)V_{t-1}, 0\} + \beta V_{t-1} \\ &= \min\{\tilde{L}(V_{t-1}), 0\} + \beta V_{t-1}, \quad t > 1. \quad (\text{see } (6.1.34(\text{p.27})) \text{ and } (6.1.33(\text{p.27}))) \end{split}$$
(7.2.116)

 $\square$  SOE{ $\tilde{M}$ :2[ $\mathbb{P}$ ][A]} can be reduced to (7.2.112(p.36)), (7.2.114(p.36)), and (7.2.115(p.36)), listed in Table 7.4.3(p.41) (IV).  $\square$  Now, let us here define

$$\tilde{\mathbb{S}}_t = \lambda \beta (v_{t-1} - V_{t-1}) + s, \quad t > 0. \tag{7.2.117}$$

Then, (7.2.113(p.36)) can be rewritten as

$$V_{t} = \min\{\lambda \beta v_{t-1} - \lambda \beta V_{t-1} + s, 0\} - \beta V_{t-1}$$
  
= \text{min}\{\tilde{\Sigma}\_{t}, 0\} + \beta V\_{t-1}, \quad t > 0, \tag{7.2.118}

implying that

$$\tilde{\mathbb{S}}_t \le (\ge) \ 0 \Rightarrow \mathsf{Conduct}_t \ (\mathsf{Skip}_t), \tag{7.2.119}$$

which can be rewritten as, due to Def. 7.1.1(p.29),

$$\tilde{\mathbb{S}}_t \le (\ge) \ 0 \Rightarrow \mathsf{Conduct}_{t_\Delta} \ (\mathsf{Skip}_{t_\Delta}).$$
 (7.2.120)

$$\tilde{\mathbb{S}}_t = (=) \ 0 \Rightarrow \mathtt{Conduct}_{t \parallel} \ (\mathtt{Skip}_{t \parallel}). \tag{7.2.121}$$

$$\tilde{\mathbb{S}}_t < (>) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}} \ (\mathtt{Skip}_{t_{\blacktriangle}}).$$
 (7.2.122)

Then, from (7.2.110(p.36)) with t-1 we have  $v_{t-1} = \tilde{T}(V_{t-1}) + V_{t-1}$ , hence  $v_{t-1} - V_{t-1} = \tilde{T}(V_{t-1})$ , thus, noting (6.1.33(p.27)), we can rewrite (7.2.117(p.36)) as below

$$S_t = \beta \tilde{T}(V_{t-1}) + s \quad t > 0. \tag{7.2.123}$$

$$= \tilde{L}(V_{t-1}), \quad t > 0. \tag{7.2.124}$$

#### 7.2.1.3 Model 3

## **7.2.1.3.1** M:3[ $\mathbb{R}$ ][A]

By  $v_t(w)$   $(t \ge 0)$  and  $V_t$   $(t \ge 0)$  let us denote the maximums of the total expected present discounted *profit* from initiating the process at time t with a buyer w and with no buyer respectively, expressed as

$$v_0(w) = \max\{w, \rho\},\tag{7.2.125}$$

$$v_t(w) = \max\{w, \rho, U_t\}, \quad t > 0,$$
 (7.2.126)

$$V_0 = \rho,$$
 (7.2.127)

$$V_t = \max\{\rho, U_t\}, \qquad t > 0,$$
 (7.2.128)

where  $U_t$  is the maximum of the total expected present discounted *profit* from rejecting both the price w and intervening quitting penalty  $\rho$  in (7.2.128(p37)) and from rejecting the intervening quitting penalty  $\rho$  in (7.2.128(p37)). Then,  $U_t$  can be expressed as

$$U_t = \max\{\lambda \beta \,\mathbf{E}[v_{t-1}(\boldsymbol{\xi})] + (1-\lambda)\beta V_{t-1} - s, \,\beta V_{t-1}\}, \quad t > 0.$$
 (7.2.129)

For convenience, let us here define  $U_0=\rho,$  hence from (7.2.127(p.37)) we have

$$V_0 = U_0 = \rho. (7.2.130)$$

Then, it follows that both (7.2.126(p37)) and (7.2.128(p37)) hold true for  $t \ge 0$  instead of t > 0, i.e.,

$$v_t(w) = \max\{w, \rho, U_t\}, \quad t \ge 0, \tag{7.2.131}$$

$$V_t = \max\{\rho, U_t\}, \qquad t \ge 0, \tag{7.2.132}$$

thus (7.2.131(p.37)) can be expressed as

$$v_t(w) = \max\{w, V_t\}, \quad t \ge 0. \tag{7.2.133}$$

Accordingly, since  $\mathbf{E}[v_{t-1}(\boldsymbol{\xi})] = \mathbf{E}[\max\{\boldsymbol{\xi}, V_{t-1}\}] = \mathbf{E}[\max\{\boldsymbol{\xi} - V_{t-1}, 0\}] + V_{t-1} = T(V_{t-1}) + V_{t-1} \text{ for } t > 0 \text{ from } (6.1.1(p.25)),$  we can rewrite (7.2.129(p.37)) as

$$U_{t} = \max\{\lambda\beta(T(V_{t-1}) + V_{t-1}) + (1 - \lambda)\beta V_{t-1} - s, \beta V_{t-1}\}$$

$$= \max\{\lambda\beta T(V_{t-1}) + \beta V_{t-1} - s, \beta V_{t-1}\}$$

$$= \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} \quad (\text{see } (6.1.4(\text{p.25})))$$

$$= \max\{K(V_{t-1}) + (1 - \beta)V_{t-1}, 0\} + \beta V_{t-1}$$

$$= \max\{L(V_{t-1}), 0\} + \beta V_{t-1}, \quad t > 0 \quad (\text{see } (6.1.8(\text{p.25}))). \tag{7.2.135}$$

 $\square$  SOE{M:3[ $\mathbb{R}$ ][A]} can be reduced to (7.2.130(p.37)), (7.2.132(p.37)), and (7.2.134(p.37)), listed in Table 7.4.5(p.41)(I).  $\square$ 

#### **7.2.1.3.2** $\tilde{M}$ :3[ $\mathbb{R}$ ][A]

By  $v_t(w)$   $(t \ge 0)$  and  $V_t$   $(t \ge 0)$  let us denote the minimums of the total expected present discounted cost from initiating the process at time  $t \ge 0$  with a seller w and with no seller respectively, expressed as

$$v_0(w) = \min\{w, \rho\},\tag{7.2.136}$$

$$v_t(w) = \min\{w, \rho, U_t\}, \quad t > 0, \tag{7.2.137}$$

$$V_0 = \rho,$$
 (7.2.138)

$$V_t = \min\{\rho, U_t\}, \qquad t > 0, \tag{7.2.139}$$

where  $U_t$  is the minimum of the total expected present discounted cost from rejecting both the price w and intervening quitting penalty  $\rho$  in (7.2.137(p.37)) and from rejecting the intervening quitting penalty  $\rho$  in (7.2.139(p.37)). Then,  $U_t$  can be expressed as

$$U_t = \min\{\mathbf{C} : \lambda \beta \,\mathbf{E}[v_{t-1}(\boldsymbol{\xi})] + (1-\lambda)\beta V_{t-1} + s, \,\, \mathbf{S} : \beta V_{t-1}\}, \quad t > 0.$$
(7.2.140)

For convenience, let us here define  $U_0 = \rho$ , hence from (7.2.138(p.37)) we have

$$V_0 = U_0 = \rho. (7.2.141)$$

Then, it follows that both (7.2.137(p37)) and (7.2.139(p37)) hold true for  $t \ge 0$  instead of t > 0, i.e.,

$$v_t(w) = \min\{w, \rho, U_t\}, \quad t \ge 0, \tag{7.2.142}$$

$$V_t = \min\{\rho, U_t\}, \qquad t \ge 0, \tag{7.2.143}$$

thus (7.2.137(p.37)) can be expressed as

$$v_t(w) = \min\{w, V_t\}, \quad t \ge 0. \tag{7.2.144}$$

Accordingly, since  $v_{t-1}(\boldsymbol{\xi}) = \min\{\boldsymbol{\xi}, V_{t-1}\} = \mathbf{E}[\min\{\boldsymbol{\xi} - V_{t-1}, 0\}] + V_{t-1} = \tilde{T}(V_{t-1}) + V_{t-1} \text{ for } t > 0 \text{ from (6.1.11(p.25))}, \text{ we can rewrite (7.2.140(p.37)) as follows.}$ 

$$U_{t} = \min\{\lambda\beta(\tilde{T}(V_{t-1}) + V_{t-1}) + (1 - \lambda)\beta V_{t-1} + s, \beta V_{t-1}\}$$

$$= \min\{\lambda\beta\tilde{T}(V_{t-1}) + \beta V_{t-1} + s, \beta V_{t-1}\}$$

$$= \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} \quad (\text{see } (6.1.14(\text{p.25})))$$

$$= \min\{\tilde{K}(V_{t-1}) + (1 - \beta)V_{t-1}, 0\} + \beta V_{t-1}$$

$$= \max\{\tilde{L}(V_{t-1}), 0\} + \beta V_{t-1}, \quad t > 0 \quad (\text{see } (6.1.14(\text{p.25})) \text{ and } (6.1.13(\text{p.25}))).$$

$$(7.2.146)$$

 $\square$  SOE $\{\tilde{M}:3[\mathbb{R}][A]\}$  can be reduced to (7.2.141(p.37)), (7.2.143(p.37)), and (7.2.145(p.38)), listed in Table (7.4.5(p.41)) (II).

#### **7.2.1.3.3** M:3[ $\mathbb{P}$ ][A]

By  $v_t$   $(t \ge 0)$  and  $V_t$   $(t \ge 0)$  let us denote the maximums of the total expected present discounted *profit* from initiating the process at time t with a buyer and with no buyer respectively. In addition, let us denote the optimal price to propose at time  $t \ge 0$  by  $z_t$ . Suppose there exists a buyer at time t = 0 (deadline). Then, the seller must determine whether to accept the terminal quitting penalty  $\rho$  or to sell the asset to the buyer. Let the  $\rho$  be accepted. Then the profit which the seller can obtain is  $\rho$ . On the other hand, let the asset be sold to the buyer. Then, since the seller must sell the asset to the buyer due to A2( $\rho$ .11), the price  $a^{\dagger}$  must be proposed to the buyer, in other words, the optimal price to propose at time t = 0 is given by

$$z_0 = a, (7.2.147)$$

hence the profit which the seller obtains at that time is a. Accordingly, the profit that the seller obtains at time 0 becomes

$$v_0 = \max\{\rho, a\}. \tag{7.2.148}$$

Next we have

$$v_t = \max\{\rho, H_t\}, \quad t > 0, \tag{7.2.149}$$

$$V_0 = \rho, (7.2.150)$$

$$V_t = \max\{\rho, U_t\}, \quad t > 0, \tag{7.2.151}$$

where  $H_t$  and  $U_t$  are defined as follows. Firstly  $H_t$  is the maximum of the total expected present discounted *profit* from rejecting the intervening quitting penalty  $\rho$ . Since a buyer exists due to the above definition of  $v_t$  and since the reservation price (maximum permissible buying price) of the buyer is  $\boldsymbol{\xi}$ , if the seller proposes a price z, the probability of the buyer buying the asset is given by  $p(z) = \Pr\{z \leq \boldsymbol{\xi}\}$  (see (6.1.18(p.26))). Hence we have

$$H_t = \max_{z} \{ p(z)z + (1 - p(z))V_t \} = \max_{z} p(z)(z - V_t) + V_t = T(V_t) + V_t, \quad t > 0$$
 (7.2.152)

due to (6.1.19(p.26)), implying that the optimal selling price  $z_t$  which the seller should propose is given by

$$z_t = z(V_t), t > 0, (7.2.153)$$

due to (6.1.25(p.26)). Finally  $U_t$  is the maximum of the total expected present discounted *profit* from rejecting the intervening quitting penalty  $\rho$ . Since no buyer exists due to the above definition of  $V_t$ , it can be expressed as follows.

$$U_t = \max\{ \mathbf{C} : \lambda \beta v_{t-1} + (1 - \lambda) \beta V_{t-1} - s, \ \mathbf{S} : \beta V_{t-1} \}, \quad t > 0.$$
 (7.2.154)

For t = 1 we have

$$U_{1} = \max\{\lambda\beta v_{0} + (1-\lambda)\beta V_{0} - s, \beta V_{0}\}$$

$$= \max\{\lambda\beta \max\{\rho, a\} + (1-\lambda)\beta\rho - s, \beta\rho\}$$

$$= \max\{\lambda\beta \max\{0, a-\rho\} + \beta\rho - s, \beta\rho\}.$$
(7.2.155)

Now, from (7.2.152(p38)) we have  $H_t - V_t = T(V_t)$  for t > 0, hence from (7.2.149(p38)) we have  $v_t - V_t = \max\{\rho - V_t, H_t - V_t\} = \max\{\rho - V_t, T(V_t)\} \cdots$  (1) for t > 0. Since  $V_t \ge \rho$  for t > 0 from (7.2.151(p38)), we have  $\rho - V_t \le 0$  for t > 0. In addition, since p(b) = 0 due to (6.1.29(2)(p.26)), from (6.1.19(p.26)) we have  $T(V_t) \ge p(b)(b - V_t) = 0$ . Therefore, since  $\rho - V_t \le 0 \le T(V_t)$ , from (1) we have  $v_t - V_t = T(V_t)$  for t > 0, i.e.,  $v_t = T(V_t) + V_t$  for t > 0, hence  $v_{t-1} = T(V_{t-1}) + V_{t-1}$  for t > 1. Accordingly (7.2.154(p.38)) with  $t > 1^{\ddagger}$  can be rearranged as

$$\begin{split} U_{t} &= \max\{\lambda\beta(T(V_{t-1}) + V_{t-1}) + (1 - \lambda)\beta V_{t-1} - s, \beta V_{t-1}\} \\ &= \max\{\lambda\beta T(V_{t-1}) + \beta V_{t-1} - s, \beta V_{t-1}\} \\ &= \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} \quad (\text{see } (6.1.21(\text{p.26}))) \\ &= \max\{K(V_{t-1}) + (1 - \beta)V_{t-1}, 0\} + \beta V_{t-1} \\ &= \max\{L(V_{t-1}), 0\} + \beta V_{t-1}, \quad t > 1 \quad (\text{see } (6.1.21(\text{p.26})) \text{ and } (6.1.20(\text{p.26}))). \end{split}$$
(7.2.157)

<sup>&</sup>lt;sup>†</sup>The lower bound of the distribution function for the reservation price (the maximum permissible buying price) of the buyer

 $<sup>^{\</sup>ddagger}$ Instead of t > 0.

For convenience, let  $U_0 = \rho$ . Then, due to (7.2.150(p.38)) we have

$$V_0 = U_0 = \rho, \tag{7.2.158}$$

hence it follows that (7.2.151(p.38)) holds true for  $t \ge 0$  instead of t > 0, i.e.,

$$V_t = \max\{\rho, U_t\}, \quad t \ge 0. \tag{7.2.159}$$

 $\square$  SOE{M:3[P][A]} is given by (7.2.158(p.39)), (7.2.159(p.39)), (7.2.155(p.38)), and (7.2.156(p.38)), listed in Table 7.4.5(p.41) (III).  $\square$ 

#### **7.2.1.3.4** $\tilde{M}$ :3[ $\mathbb{P}$ ][ $\mathbb{A}$ ]

By  $v_t$  ( $t \ge 0$ ) and  $V_t$  ( $t \ge 0$ ) let us denote the minimums of the total expected present discounted cost from initiating the process at time t with a seller and with no seller respectively. In addition, let us denote the optimal price to propose at time  $t \ge 0$  by  $z_t$ . Suppose there exists a seller at time t = 0 (deadline). Then, the buyer must determine whether to accept the terminal quitting penalty  $\rho$  or to buy the asset from the seller. Let the  $\rho$  be accepted. Then, the cost which the buyer pays at time 0 is  $\rho$ . On the other hand, let the asset be bought for the buyer. Then, since the buyer must buy the asset from the seller due to A2(p.11), the price  $b^{\dagger}$  must be is proposed to the seller; in other words, the optimal price to propose is given by

$$z_0 = b, (7.2.160)$$

hence the cost which the buyer pays at that time is b. Accordingly, the buyer pays at time 0 becomes

$$v_0 = \min\{\rho, b\}. \tag{7.2.161}$$

Next we have

$$v_t = \min\{\rho, H_t\}, \quad t > 0. \tag{7.2.162}$$

$$V_0 = \rho, (7.2.163)$$

$$V_t = \min\{\rho, U_t\}, \quad t > 0, \tag{7.2.164}$$

where  $H_t$  and  $U_t$  are defined as follows. Firstly  $H_t$  is the minimum of the total expected present discounted *cost* from rejecting the intervening quitting penalty  $\rho$ . Since a seller exists due to the above definition of  $v_t$  and since the reservation price (minimum permissible selling price) of the seller is  $\xi$ , if the buyer proposes the price z to an appearing seller, the probability of the seller selling the asset for the price z is  $\tilde{p}(z) = \Pr\{\xi \leq z\}$  (see (6.1.31(p.26))). Hence we have

$$H_t = \min_{z} \{ \tilde{p}(z)z + (1 - \tilde{p}(z))V_t \} = \min_{z} \tilde{p}(z)(z - V_t) + V_t = \tilde{T}(V_t) + V_t, \quad t > 0,$$
 (7.2.165)

due to (6.1.32(p.26)), implying that the optimal buying price which the buyer should pay is given by

$$z_t = z(V_t), t \ge 0,$$
 (7.2.166)

due to (6.1.38(p.27)). Finally  $U_t$  is the minimum of the total expected present discounted cost from rejecting the intervening quitting penalty  $\rho$ . Since no seller exists due to the above definition of  $V_t$ , it can be expressed as follows.

$$U_t = \min\{\mathbf{C}: \lambda \beta v_{t-1} + (1-\lambda)\beta V_{t-1} + s, \ \mathbf{S}: \beta V_{t-1}\}, \quad t > 0.$$
 (7.2.167)

For t = 1 we have

$$U_{1} = \min\{\lambda\beta v_{0} + (1-\lambda)\beta V_{0} + s, \beta V_{0}\}$$

$$= \min\{\lambda\beta \min\{\rho, b\} + (1-\lambda)\beta\rho + s, \beta\rho\}$$

$$= \min\{\lambda\beta \min\{0, b-\rho\} + \beta\rho + s, \beta\rho\}.$$
(7.2.168)

Now, from (7.2.165(p.39)) we have  $H_t - V_t = \tilde{T}(V_t)$  for t > 0, hence from (7.2.162(p.39)) we have  $v_t - V_t = \min\{\rho - V_t, H_t - V_t\} = \min\{\rho - V_t, \tilde{T}(V_t)\} \cdots$  (2) for t > 0. Since  $V_t \le \rho$  for t > 0 from (7.2.164(p.39)), we have  $\rho - V_t \ge 0$  for t > 0. In addition, since  $\tilde{p}(a) = 0$  due to (6.1.41 (1) (p.27)), from (6.1.32(p.26)) we have  $\tilde{T}(V_t) \le \tilde{p}(a)(a - V_t) = 0$ . Therefore, since  $\rho - V_t \ge 0 \ge \tilde{T}(V_t)$ , from (2) we have  $v_t - V_t = \tilde{T}(V_t)$  for t > 0, i.e.,  $v_t = \tilde{T}(V_t) + V_t$  for t > 0, hence  $v_{t-1} = \tilde{T}(V_{t-1}) + V_{t-1}$  for t > 1. Accordingly (7.2.167(p.39)) with t > 1 can be rearranged as

$$\begin{split} U_t &= \min\{\lambda\beta(\tilde{T}(V_{t-1}) + V_{t-1}) + (1-\lambda)\beta V_{t-1} + s, \beta V_{t-1}\} \\ &= \min\{\lambda\beta\tilde{T}(V_{t-1}) + V_{t-1}) + \beta V_{t-1} + s, \beta V_{t-1}\} \\ &= \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} \quad (\text{see } (6.1.34(\text{p.27}))) \\ &= \min\{\tilde{K}(V_{t-1}) + (1-\beta)V_{t-1}, 0\} + \beta V_{t-1}, \quad t > 1 \\ &= \max\{\tilde{L}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} \quad (\text{see } (6.1.34(\text{p.27})) \text{ and } (6.1.33(\text{p.27}))) \end{split}$$
(7.2.170)

 $<sup>^{\</sup>dagger}$ The upper bound of the distribution function for the reservation price (the minimum permissible selling price) of the seller.

For convenience, let  $U_0 = \rho$ . Then, due to (7.2.163(p.39)) we have

$$V_0 = U_0 = \rho, \tag{7.2.171}$$

hence it follows that (7.2.164(p.39)) holds true for  $t \ge 0$  instead of t > 0, i.e.,

$$V_t = \min\{\rho, U_t\}, \quad t \ge 0. \tag{7.2.172}$$

 $\square$  SOE $\{\tilde{M}:3[\mathbb{R}][A]\}$  is given by (7.2.171(p.40)), (7.2.172(p.40)), (7.2.168(p.39)), and (7.2.169(p.39)), listed in Table 7.4.5(p.41) (IV).

## 7.2.2 Search-Enforced-Model

In sE-model (M:x[X][E] and  $\tilde{M}:x[X][E]$  with x=1,2,3 and  $X=\mathbb{R},\mathbb{P}$ ) a leading-trader needs to take no decision activity regarding whether or not to conduct the search. This implies that eliminating the terms related to this decision from the systems of optimality equations in sA-model  $(SOE\{M:x[X][A]\})$  and  $SOE\{\tilde{M}:x[X][A]\}$  produces the systems of optimality equations in sE-model  $(SOE\{M:x[X][E]\})$  and  $SOE\{\tilde{M}:x[X][E]\})$ . Noting this, from Tables 7.4.1(p.41), 7.4.3(p.41), and 7.4.5(p.41) we can immediately obtain the systems of optimality equations for E-model, which are given by Tables 7.4.2(p.41), 7.4.4(p.41), and 7.4.6(p.41).

# 7.2.3 Assertion and Assertion System of Model

In general, let us refer to a description on whether or not a given statement is true as the *assertion*, denoted by A, and as a set consisting of some assertions as the *assertion system*, denoted by  $\mathscr{A}$ . In addition, let us denote an assertion and an assertion system for a given Model by respectively  $A\{\mathsf{Model}\}$  and  $\mathscr{A}\{\mathsf{Model}\}$ .

# 7.3 Recall-Model

See Chap. 26(p.251).

# 7.4 Summary of the System of Optimality Equations (SOE)

# Model 1

# Table 7.4.1: Search-Allowed-Model 1

$ \begin{array}{l} \text{(I) SOE}\{\mathrm{M:1}[\mathbb{R}][\mathbb{A}]\} \\ V_1 = \beta \mu - s, \\ V_t = \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ t > 1. \end{array} $	(7.4.1) (7.4.2)	$\begin{split} \boxed{ & \text{(II) SOE}\{\tilde{\mathbf{M}}:1[\mathbb{R}][\mathbf{A}]\} \\ & V_1 = \beta \mu + s, \\ & V_t = \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ t > 1. \end{split} }$	(7.4.3) (7.4.4)
(III) SOE{M:1[P][A]} $ V_1 = \beta a - s, $ $V_t = \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ t > 1. $	(7.4.5) (7.4.6)		(7.4.7) (7.4.8)

# Table 7.4.2: Search-Enforced-Model 1

(I) SOE $\{M:1[\mathbb{R}][E]\}\$ $V_1 = \beta \mu - s,$ $V_t = K(V_{t-1}) + V_{t-1}, \ t > 1.$	(7.4.9) (7.4.10)	I) SOE $\{\tilde{M}:1[\mathbb{R}][E]\}\$ $V_1=\beta\mu+s,$	(7.4.11)
(III) SOE{M:1[P][E]} $V_{1} = \beta a - s,$ $V_{t} = K(V_{t-1}) + V_{t-1}, t > 1,$		$V_{t} = \tilde{K}(V_{t-1}) + V_{t-1}, \ t > 1.$ $V) \ S0E\{\tilde{M}:1[\mathbb{P}][\mathbf{E}]\}$ $V_{1} = \beta b + s,$ $V_{t} = \tilde{K}(V_{t-1}) + V_{t-1}, \ t > 1,$	(7.4.12) (7.4.15) (7.4.16)

# 

$ \begin{array}{l} \text{(I) SOE}\{M.2[\mathbb{R}][\mathbb{A}]\} \\ V_0 = \rho, \\ V_t = \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ t>0. \end{array} $	(7.4.17) (7.4.18)	$ \begin{array}{ll} \text{(II) SOE}\{\tilde{M} : 2[\mathbb{R}][\mathbb{A}]\} \\ V_0 &= \rho, \\ V_t &= \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ t > 0. \end{array} $	(7.4.19) (7.4.20)
$\begin{split} & \text{(III) SOE}\{M\text{:}2[\mathbb{P}][\mathtt{A}]\} \\ & V_0 = \rho, \\ & V_1 = \max\{\lambda\beta\max\{0, a-\rho\} + \beta\rho - s, \beta\rho\}, \\ & V_t = \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ t > 1. \end{split}$	(7.4.21) (7.4.22) (7.4.23)		(7.4.24) (7.4.25) (7.4.26)

# Table 7.4.4: Search-Enforced-Model 2

(I) $SOE\{M:2[\mathbb{R}][E]\}$ $V_0 = \rho,$ $V_t = K(V_{t-1}) + V_{t-1}, \ t > 0,$	(7.4.27) (7.4.28)	(II) SOE $\{\tilde{\mathbf{M}}: 2[\mathbb{R}][\mathbf{E}]\}\$ $V_0 = \rho,$ $V_t = \tilde{K}(V_{t-1}) + V_{t-1}, \ t > 0,$	(7.4.29) (7.4.30)
(III) SOE{M:2[P][E]} $ V_0 = \rho, \\ V_1 = \lambda \beta \max\{0, a - \rho\} + \beta \rho - s, \\ V_t = K(V_{t-1}) + V_{t-1}, \ t > 1, $	(7.4.31) (7.4.32) (7.4.33)	$ \begin{aligned} & (\text{IV}) \ \text{SOE}\{\tilde{\mathbf{M}}\text{:}2[\mathbb{P}][\mathbf{E}]\} \\ & V_0 = \rho, \\ & V_1 = \lambda\beta \min\{0, b - \rho\} + \beta\rho + s, \\ & V_t = \tilde{K}(V_{t-1}) + V_{t-1}, \ t > 1, \end{aligned} $	(7.4.34) (7.4.35) (7.4.36)

# ${\bf Model~3}$ Table 7.4.5: **Search-Allowed-Model** 3

$(I)$ SOE $\{M:3[\mathbb{R}][A]\}$		$(II) SOE\{M:3[R][A]\}$	
$V_0 = U_0 = \rho,$	(7.4.37)	$V_0 = U_0 = \rho,$	(7.4.40)
$V_t = \max\{\rho, U_t\}, \ t \ge 0,$	(7.4.38)	$V_t = \min\{\rho, U_t\}, \ t \ge 0,$	(7.4.41)
$U_{t} = \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t}\}$	$-1$ }, $t > 0$ . $(7.4.39)$	$U_t = \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ t > 0.$	(7.4.42)
(III) $SOE\{M:3[\mathbb{P}][A]\}$		(IV) $SOE\{\tilde{M}:3[\mathbb{P}][A]\}$	
$V_0 = U_0 = \rho,$	(7.4.43)	$V_0 = U_0 = \rho,$	(7.4.47)
$V_t = \max\{\rho, U_t\}, \ t \ge 0,$	(7.4.44)	$V_t = \min\{\rho, U_t\}, \ t \ge 0,$	(7.4.48)
$U_1 = \max\{\lambda\beta \max\{0, a - \rho\} + \beta$	$\beta \rho - s, \beta \rho \}, \qquad (7.4.45)$	$U_1 = \min\{\lambda\beta\min\{0, b - \rho\} + \beta\rho + s, \beta\rho\},\$	(7.4.49)
$U_{t} = \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t}\}$	$_{-1}$ }, $t > 1$ . $(7.4.46)$	$U_t = \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ t > 1.$	(7.4.50)

# Table 7.4.6: Search-Enforced-Model 3

(I) $SOE\{M:3[\mathbb{R}][E]\}$		(II) $SOE\{\tilde{M}:3[\mathbb{R}][E]\}$	
$V_0 = U_0 = \rho,$	(7.4.51)	$V_0 = U_0 = \rho,$	(7.4.54)
$V_t = \max\{\rho, U_t\}, \ t \ge 0,$	(7.4.52)	$V_t = \min\{\rho, U_t\}, \ t \ge 0,$	(7.4.55)
$U_t = K(V_{t-1}) + V_{t-1}, \ t > 0.$	(7.4.53)	$U_t = \tilde{K}(V_{t-1}) + V_{t-1}, \ t > 0.$	(7.4.56)
(III) $SOE\{M:3[\mathbb{P}][E]\}$		(IV) $SOE\{\tilde{M}:3[\mathbb{P}][E]\}$	
$V_0 = U_0 = \rho,$	(7.4.57)	$V_0 = U_0 = \rho,$	(7.4.61)
$V_t = \max\{\rho, U_t\}, \ t \ge 0,$	(7.4.58)	$V_t = \min\{\rho, U_t\}, \ t \ge 0,$	(7.4.62)
$U_1 = \lambda \beta \max\{0, a - \rho\} + \beta \rho - s,$	(7.4.59)	$U_1 = \lambda \beta \min\{0, b - \rho\} + \beta \rho + s,$	(7.4.63)
$U_t = K(V_{t-1}) + V_{t-1}, \ t > 1.$	(7.4.60)	$U_t = \tilde{K}(V_{t-1}) + V_{t-1}, \ t > 1.$	(7.4.64)

# Chapter 8

# **Optimal Decision Rules**

This chapter clarifies the structure of the optimal decision rules for the 24 no-recall-models in Table 3.2.1(p.16).

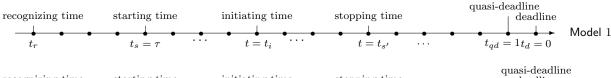
# 8.1 Five Points in Time

To start with, let us note here that the optimal decision rules are closely related to the following six points in time (see H1(p.7)).

- $\circ$  Recognizing time  $t_r \geq 0$ ,
- $\circ$  Starting time  $t_s$  ( $t_{\tau} \geq t_s \geq t_i$ ), represented by  $\tau$ , i.e.,  $\tau = t_s$ ,
- Initiating time  $t_i$   $(t_s \ge t_i \ge t_{s'})$ , sometimes represented by  $t = t_i$ ,
- Stopping time  $t_{s'}$   $(t_i \ge t_{s'} \ge 0)$ , sometimes represented by  $t = t_{s'}$ ,
- Deadline  $t_d = 0$ , the final point in time of the decision process.
- $\circ$  Quasi-deadline  $t_{qd}$ , the smallest of all possible initiating times where

$$t_{qd} = 1 \text{ for Model } 1 \quad \text{(see Remark 4.1.1(p.19) (a))},$$
 (8.1.1)

$$t_{qd} = 0 \text{ for Model } 2/3 \text{ (see Remark } 4.1.4(p.20)).$$
 (8.1.2)



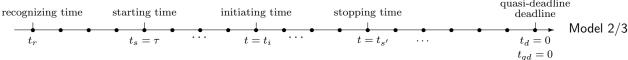


Figure 8.1.1: Six points in time related to the optimal decision rules

## 8.2 Four Kinds of Decisions

Below, let us provide the more strict definitions for the four kinds of decisions prescribed in Section 3.4(p.17).

#### 8.2.1 Whether or Not to Accept the Proposed Price

This is the decision only for  $\mathbb{R}$ -model. Below let us represent

"Accept a price 
$$w$$
 at time  $t$ " and "Reject a price  $w$  at time  $t$ " as  $\mathsf{Accept}_t\langle w \rangle$  and  $\mathsf{Reject}_t\langle w \rangle$  respectively. (8.2.1)

First, in the selling model  $(M:1/2[\mathbb{R}][A])$  suppose that a buyer appearing at a time t has proposed a buying price w. Then, from (7.2.2[p.29]) and (7.2.62[p.33]) we have

$$w \ge (\le) V_t \Rightarrow \mathsf{Accept}_t \langle w \rangle \ (\mathsf{Reject}_t \langle w \rangle).$$
 (8.2.2)

Similarly, in the buying model  $(\tilde{\mathsf{M}}:1/2[\mathbb{R}][\mathtt{A}])$  suppose that a seller appearing at a time t has proposed a selling price w. Then, from (7.2.16[p.30]) and (7.2.77[p.34]) we have

$$w \leq (\geq) V_t \Rightarrow \mathsf{Accept}_t \langle w \rangle \ (\mathsf{Reject}_t \langle w \rangle).$$

We refer to the  $V_t$  given above as the optimal-reservation-price, opt- $\mathbb{R}$ -price for short.

#### 8.2.2 What Price to Propose

This is the decision only for  $\mathbb{P}$ -model. In the selling model the optimal selling price  $(M:1/2[\mathbb{P}][A])$  which a seller (leading-trader) should propose at a time t is given by

$$z_t = z(V_t)$$
 (see (7.2.34(p.31)) and (7.2.94(p.35))).

Similarly, in the buying model  $(\tilde{M}:1/2[\mathbb{P}][A])$  the optimal buying price which a buyer (leading-trader) should propose at a time t is given by

$$z_t = z(V_t)$$
 (see (7.2.50(p.32)) and (7.2.111(p.36))).

We refer to the  $z_t$  given above as the optimal-posted-price, opt-P-price for short.

#### 8.2.3 Whether or not to Conduct the Search

This is the decision only for sA-model (see (A5b(p.12)). Then, its decision rule is given by (7.2.9(p.30)), (7.2.23(p.31)), (7.2.39(p.32)), (7.2.55(p.33)), (7.2.70(p.33)), (7.2.85(p.34)), (7.2.102(p.35)), and (7.2.119(p.36)).

Remark 8.2.1 (Conduct ~Skip (C~S) (see Figure 2.2.3(p.12))) Figure 8.2.1(p.44) (I) below sketches the case that the search-Conduct starts at the optimal initiating time  $t_{\tau}^*$  and continue up to the quasi-deadline  $t_{qd}=1$  (Model 1) so long as the process does not stop; it will be known later on that this case occurs everywhere in the paper. Contrary to this, Figure 8.2.1(p.44) (II) schematizes the case that the search-Conduct starts at the optimal initiating time  $t_{\tau}^*$ , continues for a while, and switches to the search-Skip at a certain point in time  $t' < t_{qd}$ ; this is a very rare case that occurs only in Tom's 22.1.4(p.166) (b3iii), 22.1.7(p.177) (b3iii), and 22.1.10(p.178) (b3iii). Let us represent the case as Conduct ~Skip, simply C~S (Def. 2.2.1(p.12)).  $\Box$ 

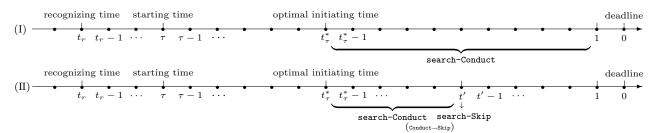


Figure 8.2.1: Conduct~Skip (C~S)

■ Alice 1 (jumble of intuition and theory) Herein, Alice was hit by the following question. For example, suppose that  $\mathbb{S}_t < 0$  at a time t (see (7.2.12[p:0])), meaning that the search-skip becomes <u>strictly optimal</u> at that time. Then, since  $\max\{\mathbb{S}_t,0\} = 0$ , we have  $V_t = \beta V_{t-1}$  from (7.2.8[p:0]), implying that initiating the process at time t becomes <u>indifferent</u> to initiating the process at time t-1; nevertheless, the search skip is <u>strictly optimal!</u> After having mumbled, letting out a strange noise "Is this a little bit funny?", she gave a shout "Such a laughable affair!". Then, Dr. Rabbit again appeared and pedantically told to Alice "The above two results are both ones based on a theory of mathematics, but your confusion is caused by an <u>intuition</u>; there does not exist any logical relationship between the two! Well · · · your confusion is what is caused by a jumble of intuition and theory!!", and he again disappeared down the hole as murmuring "Oh dear! I shall be too late for the faculty meeting!".

# 8.2.4 When to Initiate the Process (Optimal Initiating Time)

This is the decision only for iiA-Case (see (H1(p.7)(d))).

## 8.2.4.1 Definition

The definition below is only for a selling model with  $t_{qd} = 1$  (Model 1 ( $t_{qd} = 0$  for Model 2)).<sup>†</sup> Suppose that the process has started at the starting time  $\tau$  and that the seller (leading-trader) has determined to *initiate* the process at a given time t ( $\tau \ge t \ge t_{qd}$ ) after that, i.e.,  $\tau - t$  periods hence. Then, the total expected present discounted profit at the *starting time*  $\tau$  is given by

$$I_{\tau}^{t} \stackrel{\text{def}}{=} \beta^{\tau - t} V_{t}, \quad \tau \ge t \ge t_{ad}. \tag{8.2.3}$$

See (7.2.3(p.29)) and (7.2.4(p.29)) for the definition of  $V_t$ . Then, by  $t_{\tau}^*$  let us denote t maximizing  $I_{\tau}^t$  on  $\tau \geq t \geq t_{qd}$ , i.e.,

$$I_{\tau}^{t_{\tau}^*} = \max_{\tau \ge t \ge t_{rd}} I_{\tau}^t \quad \text{or equivalently} \quad I_{\tau}^{t_{\tau}^*} \ge I_{\tau}^t, \quad \tau \ge t \ge t_{qd}. \tag{8.2.4}$$

Let us call the  $t_{\tau}^*$  the *optimal initiating time* (see H1(p.7)), denoted by OIT $_{\tau}\langle t_{\tau}^*\rangle_{\vartriangle}$ . If

$$I_{\tau}^{t_{\tau}^*} > I_{\tau}^t \text{ for } t \neq t_{\tau}^*, \tag{8.2.5}$$

then it is called the strictly optimal initiating time, denoted by  $OIT_{\tau}\langle t_{\tau}^*\rangle_{\blacktriangle}$ .

 $<sup>^{\</sup>dagger} \text{The similar things can be said for all other models.}$ 

Remark 8.2.2 (\* strict optimality) Suppose that the initiating time  $t_{\tau}^*$  is strictly optimal in a sense of (8.2.5(p.41)). Then, since  $I_{\tau}^{t_{\tau}^*} > I_{\tau}^{t_{\tau}^*-1}$ , we have  $\beta^{\tau-t_{\tau}^*}V_{t_{\tau}^*} > \beta^{\tau-t_{\tau}^*+1}V_{t_{\tau}^*-1}$ , hence  $V_{t_{\tau}^*} > \beta V_{t_{\tau}^*-1}$ . Accordingly, since  $V_{t_{\tau}^*} = \max\{\mathbb{S}_{t_{\tau}^*}, 0\} + \beta V_{t_{\tau}^*-1}$  from (7.2.8(p.30)) with  $t = t_{\tau}^*$ , hence  $\max\{\mathbb{S}_{t_{\tau}^*}, 0\} > 0$ , we have  $\mathbb{S}_{t_{\tau}^*} > 0$ , implying that it becomes strictly optimal to conduct the search due to (7.2.12(p.30)); in other words, it is not allowed to skip the search.  $\square$ 

Throughout the paper, let us employ the following preference rule.

Preference Rule 8.2.1 Let  $I_{\tau}^t = I_{\tau}^{t-1}$  for a given t. Then, the seller (leading-trader) prefers t-1 to t as the initiating time, implying that "Postpone the initiation of the process so long as it is not unprofitable to do so."

#### 8.2.4.2 $\beta$ -adjusted sequence $V_{\beta[\tau]}$

First, let us denote the sequence consisting of  $V_{\tau}$ ,  $V_{\tau-1}$ ,  $V_{\tau-2}$ , ...,  $V_{t_{ad}}$  by

$$V_{[\tau]} \stackrel{\text{def}}{=} \{V_{\tau}, V_{\tau-1}, V_{\tau-2}, \cdots, V_{t_{nd}}\}, \tag{8.2.6}$$

called the original sequence and let

$$t_{\tau}^{*\prime} = \arg\max V_{[\tau]} = \arg\max\{V_{\tau}, V_{\tau-1}, V_{\tau-2}, \cdots, V_{t_{nd}}\}. \tag{8.2.7}$$

Next, let us denote the sequence

$$V_{\beta[\tau]} \stackrel{\text{def}}{=} \{ V_{\tau}, \beta V_{\tau-1}, \beta^2 V_{\tau-2}, \cdots, \beta^{\tau-t_{qd}} V_{t_{qd}} \} = \{ I_{\tau}^{\tau}, I_{\tau}^{\tau-1}, I_{\tau}^{\tau-2}, \cdots, I_{\tau}^{t_{qd}} \}, \tag{8.2.8}$$

called the  $\beta$ -adjusted sequence of  $V_{[\tau]}$ . By definition, the optimal initiating time  $t_{\tau}^*$  is given by t attaining the maximum of elements within  $\beta$ -adjusted sequence  $V_{\beta[\tau]}$ , i.e.,

$$t_{\tau}^* = \arg\max V_{\beta[\tau]} = \arg\max \{V_{\tau}, \beta V_{\tau-1}, \beta^2 V_{\tau-2}, \cdots, \beta^{\tau - t_{qd}} V_{t_{qd}}\}.$$
 (8.2.9)

Note here that the monotonicity of the original sequence  $V_{[\tau]}$  is not always inherited to the  $\beta$ -adjusted sequence  $V_{\beta[\tau]}$ , i.e.,  $t_{\tau}^* \neq t_{\tau}^{*'}$  (see Section A 5.2.2(p.320)).

#### 8.2.4.3 Three Possibilities

Below let us define the three types of the optimal initiating time (OIT).

### 1. Degeneration to the starting time $\tau$

Let  $t_{\tau}^* = \tau$ , i.e., it is optimal to initiate the process at the starting time  $\tau$ , denoted by s. Then, the optimal initiating time  $t_{\tau}^*$  is said to degenerate to the starting time  $\tau$ , represented by s doints. If the optimal initiating time  $t_{\tau}^*$  is strict (see (8.2.5(p.44))), it is called the strictly degenerate OIT, represented by s doints.

#### 2. Non-degeneration $(\tau > t_{\tau}^* > t_{qd})$

Let  $\tau > t_{\tau}^* > t_{qd}$ , i.e., the optimal initiating time is between the starting time  $\tau$  and the quasi-deadline  $t_{qd}$ , denoted by  $\odot$ . Then, the optimal initiating time  $t_{\tau}^*$  is said to be non-degenerate OIT, represented by  $\boxed{\odot}$  ndOIT $_{\tau}\langle t_{\tau}^* \rangle$   $\boxed{}_{\Delta}$  ( $\bigcirc$   $\Delta$  for short). If

$$I_{\tau}^{\tau} = I_{\tau}^{\tau - 1} = \dots = I_{\tau}^{t_{\tau}^{*}} \ge I_{\tau}^{t_{qd}} \tag{8.2.10}$$

as a special case, then it is said to be indifferent non-degenerate OIT (see Preference Rule 8.2.1), represented by  $\boxed{\textcircled{o} \ \mathtt{ndOIT}_{\tau}\langle t_{\tau}^{*}\rangle}$  ( $\boxed{\textcircled{o}}_{\parallel}$  for short). If  $I_{\tau}^{t_{\tau}^{*}} > I_{\tau}^{t}$  for all  $t \neq t_{\tau}^{*}$ , then it is said to be strictly non-degenerate OIT, represented by  $\boxed{\textcircled{o} \ \mathtt{ndOIT}_{\tau}\langle t_{\tau}^{*}\rangle}_{\blacktriangle}$  ( $\boxed{\textcircled{o}}_{\blacktriangle}$  for short).

#### 3. Degeneration to the deadline $t_{ad}$

Let  $t_{\tau}^* = t_{qd} = 1$  (0) for Model 1 (Model 2/3), i.e., the optimal initiating time is the quasi-deadline, denoted by **3**. Then, the optimal initiating time  $t_{\tau}^*$  is said to degenerate to the quasi-deadline  $t_{qd}$ , represented by  $\bullet dOITd_{\tau}\langle t_{qd}\rangle$  (**3** for short). If its optimality is strict, then it is called the strictly degenerate OIT, represented by  $\bullet dOITd_{\tau}\langle t_{qd}\rangle$  (**3** for short). If

$$I_{ au}^{ au} = I_{ au}^{ au-1} = \dots = I_{ au}^{t_{qd}}, \dots$$
 (1)

then the degeneration is said to be *indifferent*, represented by  $\bullet dOITd_{\tau}\langle t_{qd}\rangle_{\parallel}$  ( $\bullet_{\parallel}$  for short).

Remark 8.2.3 When (8.2.10(p.45)) is possible, as an optimal initiating time we can define  $\textcircled{s}_{\parallel}$  if Preference Rule 8.2.1(p.45) is ignored. However, this definition is not permitted since the preference rule is applied throughout the paper.  $\Box$ 

#### 8.2.4.4 First Search Conducing Time

There might exist a person who thinks that the optimal initiating time can be given also by the first search conducing time. However, for example, consider  $M:2[\mathbb{R}][A]$  ( $t_{qd}=0$ ) with the starting time  $\tau=6$  where

$$\mathtt{Skip}_{6^{\,\Delta}}, \quad \mathtt{Skip}_{5^{\,\Delta}}, \quad \mathtt{Skip}_{4^{\,\Delta}}, \quad \mathtt{Conduct}_{3_{\,\blacktriangle}}, \quad \mathtt{Conduct}_{2^{\,\Delta}}, \quad \mathtt{Conduct}_{1^{\,\Delta}}.$$

This means that the first search conducting time is  $t_{\tau}^{**} \stackrel{\text{def}}{=} 3 \cdots$  (2). Then, since

$$S_6 < 0$$
,  $S_5 < 0$ ,  $S_4 < 0$ ,  $S_3 > 0$ ,  $S_2 > 0$ ,  $S_1 > 0$ 

from (7.2.71(p.33)) and (7.2.73(p.33)), we have

$$\max\{\mathbb{S}_6,0\} = 0, \quad \max\{\mathbb{S}_5,0\} = 0, \quad \max\{\mathbb{S}_4,0\} = 0, \quad \max\{\mathbb{S}_3,0\} > 0, \quad \max\{\mathbb{S}_2,0\} \geq 0, \quad \max\{\mathbb{S}_1,0\} \geq 0.$$

Thus, from (7.2.69(p.33)) we have

$$V_6 = \beta V_5$$
,  $V_5 = \beta V_4$ ,  $V_4 = \beta V_3$ ,  $V_3 > \beta V_2$ ,  $V_2 > \beta V_1$ ,  $V_1 > \beta V_0$ ,

so

$$V_6 = \beta V_5 = \beta^2 V_4 = \beta^3 V_3 > \beta^4 V_2 \ge \beta^5 V_1 \ge \beta^6 V_0 \quad \text{or equivalently} \quad I_6^6 = I_6^5 = I_6^4 = \boxed{I_6^3} > I_6^2 \ge I_6^1 \ge I_6^0 \ge I_6^1 \ge I_6^0 \ge I_6^1 \ge I_6^0 \ge I_6^1 \ge I_6^$$

due to (8.2.3(p.44)), hence we have the optimal initiating time  $t_{\tau}^* = 3 \cdots$  (3) by definition.

■ Alice 2 (first search conducting time) When the story has come up to here, after a moment's reflection, Alice happened to conceive of an idea; "Since  $t_{\tau}^{**} = t_{\tau}^{*} = 3$  from (2) and (3), as an optimal initiating time we can employ the first search conducting time  $t_{\tau}^{**} = 3$  instead of  $t_{\tau}^{*}$ !". Then, Dr. Rabbit suddenly appeared and told to her "Surely you are not incorrect, Miss Alice!. But, but—the profit attained by initiating the process at the first search conducting time  $t_{\tau}^{**}$  is the same as the profit attained by initiating the process at the optimal initiating time  $t_{\tau}^{*}$ ; in other words, since the former profit does not become greater than the latter profit, we have no reason why  $t_{\tau}^{**}$  must be used instead of  $t_{\tau}^{**}$ ; accordingly, it suffices to employ  $t_{\tau}^{**}$ !! Miss Alice!!!". And then, taking a watch out of the waistcoat-pocket and murmuring "Oh dear! Oh dear! I shall be too late for the faculty meeting", he again disappeared down the hole.

#### 8.2.4.5 Null-Time-Zone

In this section let us raise a perplexing situation caused by the optimal initiating time  $t_{\tau}^*$ . Here let  $\tau > t_{\tau}^*$ , i.e., the optimal initiating time  $t_{\tau}^*$  is not the starting time  $\tau$  (see Figure 8.2.2(p.46) below), implying that no decision-making action is taken at every point in time  $t = \tau, \tau - 1, \cdots, t_{\tau}^* + 1$ . Let us refer to each of  $\tau, \tau - 1, \cdots, t_{\tau}^* + 1$  as the null point in time and the whole of these time points as the null-time-zone, denoted as Null-TZ.

Null-TZ 
$$\stackrel{\text{def}}{=} \langle \tau, \tau - 1, \cdots, t_{\tau}^* + 1 \rangle$$
.

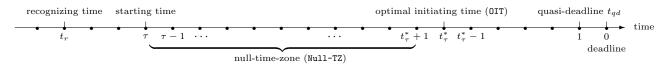


Figure 8.2.2: Null-time-zone in Model 1 with  $t_{qd}=1$  (Null-TZ)

The above event implies that, without noticing the existence of Null-TZ, we unwittingly or unconsciously might have continued to fall into the senselessness of engaging in unnecessary decision-making activities over these points in time.

#### 8.2.4.6 Deadline-Engulfing

■ Alice 3 (black hole) Hereupon, Alice supposed "If the optimal initiating time  $t_{\tau}^*$  degenerates to the deadline (time 0), then what will ever happen?", and screamed out "If so, it follows that don't conduct any decision-making activity up to the deadline!; If that happens, the whole of decision-making activities which are scheduled at the starting time  $\tau$  come to naught as if being falling into the deadline!". Alice was heavily nonplused and cried "It ..., it is the same as that black hole into which all physical matters, even light, are squeezed into! If so, ..., a decision process with an infinite planning horizon vanishes away in time toward an infinite future! Oh dear!! Oh dear!! ... "She hunkered down, and then buried her head in her hands. Then, Dr. Rabbit again appeared and told to her a little bit ungraciously "This is an undeniable conclusion that is theoretically derived!."

In this paper, let us refer to "falling into the deadline" as "deadline-engulfing", represented by **@**-engulfing. This situation can be depicted as the two figures below.

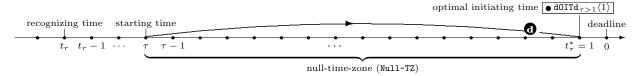


Figure 8.2.3: Deadline-engulfing (**d**) for Model 1

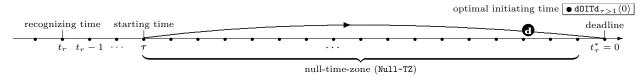


Figure 8.2.4: Deadline-engulfing (**d**) for Model 2

Later on we will see that the **1**-engulfing is not a rare event but a phenomenon which is very often possible even in the simplest case " $\beta = 1$  and s = 0" (see Pom's 22.2.1(p.209), 22.2.5(p.212), 22.2.9(p.222), and 22.2.17(p.231)). Taking this fact into consideration, we will inevitably be led to a serious re-examination of the whole discussion that have been made so far for all decision processes, including Markovian decision processes [22,Howard,1960] (see Section A 5(p.319)).

# 8.3 Five Time Zones

From all discussions which have been made so far, it is seen that we have the following five kinds of time-zones:

 $\circ$  Let us refer to the interval between  $t_r$  and  $t_s$  (=  $\tau$ ) as the preparation-time-zone, denoted by

Preparation-TZ = 
$$\{t_r, t_r - 1, \cdots, t_s\}$$
.

 $\circ$  Let us refer to the interval between  $t_s (= \tau)$  and 0 as the total-time-zone, denoted by

Total-TZ = 
$$\{t_s, t_s - 1, \dots, 0\}$$
.

 $\circ$  Let us refer to the interval between  $t_s (= \tau)$  and  $t_i$  as the Null-time-zone, denoted by

$$Null-TZ = \{t_s, t_s - 1, \dots, t_i\}.$$

 $\circ$  Let us refer to the interval between  $t_i$  and  $t_{s'}$  as the searching-time-zone, denoted by

Searching-TZ = 
$$\{t_i, t_i - 1, \cdots, t_{s'}\}$$
.

 $\circ$  Let us refer to the interval between  $t_{s'}$  and 0 as the remaining-time-zone, denoted by

$$\texttt{Remaining-TZ} = \{t_{s'}, t_{s'}-1, \cdots, 0\}.$$

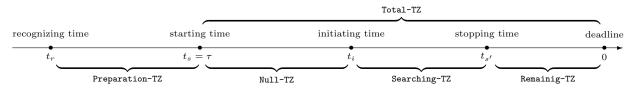


Figure 8.3.1: Five time-zones

# 8.4 Monotonicity of opt- $\mathbb{R}/\mathbb{P}$ -price

Here, let us represent "opt- $\mathbb{R}$ -price  $(V_t)$  and/or opt- $\mathbb{P}$ -price  $(z_t)$ " defined in Chap. 7(p.29) by opt- $\mathbb{R}/\mathbb{P}$ -price  $(V_t/z_t)$  for short. In this paper, one of main concerns on the opt- $\mathbb{R}/\mathbb{P}$ -price is its monotonicity.

#### 8.4.1 Normal Mental Conflict

Suppose that the monotonicity over the entire planning horizon is

- · nondecreasing in t (see Figure 8.4.1(p.48) (I)) or
- · nonincreasing in t (see Figure 8.4.1(p.48) (II)).

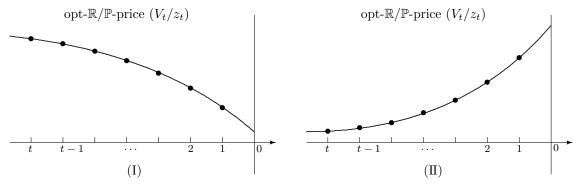


Figure 8.4.1: Normal Conflict

Remark 8.4.1 (normal mental conflict) The monotonicity of the opt- $\mathbb{R}/\mathbb{P}$ -price reflects the mental conflict of decision-maker that was presented within the expectation of  $Examples \ 1.3.1(p.5) - 1.3.4(p.6)$ . This mental conflict can be restated as follows. As the deadline approaches,

- $\cdot$  a seller becomes "selling spree" in the selling problem.
- · a buyer becomes "buying spree" in the buying problem.

Let us refer to this as the *normal mental conflict*..  $\square$ 

# 8.4.2 Abnormal Mental Conflict

Suppose that the monotonicity over the entire planning horizon shifts

- · from "nondecreasing" to "nonincreasing" in t (see Figure 8.4.2(p.48) (I)) or
- · from "nonincreasing" to "nondecreasing" in t (see Figure 8.4.2(p.48) (I)).

Remark 8.4.2 (abnormal mental conflict) The above monotonicity of the opt- $\mathbb{R}/\mathbb{P}$ -price can be stated as follows. As the deadline approaches

- · A seller shift from "selling spree" to "selling restraint" in the selling problem.
- · A buyer shift from "buying spree" to "buying restraint" in the buying problem.

This does not reflect the mental conflict of decision-maker in Examples~1.3.1(p.5) - 1.3.4(p.6). Let us refer to this as the abnormal mental conflict..  $\square$ 

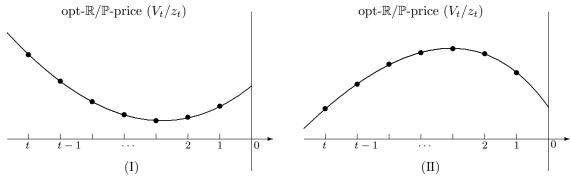


Figure 8.4.2: Abnormal Conflict

# Chapter 9

# Conclusions of Part 1 (Prologue)

The whole discussions over Chaps. 1(p.3) - 8(p.43) are summarized as below.

# $\overline{\overline{\mathsf{C}}}1.$ Two motives of this study (see Section 1.1(p.3)).

Behavior of human-beings, whether a little action or a significant one, often begins with a subtle motive. Now, in an early stage of this study, the authors observed similarities between selling and buying problems, as well as resemblances among methodologies used to analyze them. This led to two initial questions: (1) Is a buying problem symmetrical to a selling problem? and (2) Is it possible for a general theory integrating quadruple-asset-trading-problems to exist? This study, spanning over half a century, was be inspired by the desire to answer these seemingly trivial questions. Our final conclusions of us are "No" for (1) and "Yes" for (2).

# $\overline{\mathsf{C}}2$ . Philosophical background of this paper (see Section 1.2(p.3)).

Refer to Section 1.2(p3) for the philosophical background on how and why we came to perceive a decision theory as physics, which fundamentally informs the entire content of this paper. Generally, a physical viewpoint stems from a mental process involving unfiltered observation of a subject, free from any preconceived premises, assumptions, hypotheses, or biases. It is crucial to recognize the difficulty of this task, even for modern individuals who consider themselves scientifically aware. Prior to Galileo's era (pre-1600s), no one would have questioned the belief that the heaven revolved around the Earth (Ptolemaic system). Similarly, in the absence of modern knowledge, individuals, including the authors, would without question adhere to this theory today. It is essential to acknowledge that the transition to the sun-centered theory (Copernican system) took thousands of years, highlighting the challenge of objectively examining facts without biases or preconceptions. History demonstrates that the natural science, including physics, have successfully undergone this rigorous examination, but it is uncertain whether other fields have done so. Scientists must remain open to the existence of "as-yet-unrecognized knowledge" and embrace the acknowledgment of ignorance. Those familiar with physics will quickly grasp the essence of Albert Einstein "As far as the laws of mathematics refer to reality, they are not certain, and as far as they are certain, they do not refer to reality." However, for those without such experience, understanding may require significant time or may never fully materialize.

## $\overline{\overline{C}}3$ . Time concept in decision theory

Guided by the aforementioned philosophical background, we came to regard human beings themselves as real entities that scientists study as their research objects. Now, since there are no physical existence devoid of the time concept, we inevitably and/or unconsciously began to recognize the concepts of the five points in time: recognizing time, starting time, initiating time, stopping time, and deadline (see H1(p.7) and Section 8.1(p.43)). Readers will recognize that these time concepts dominate the whole description of this paper.

# $\overline{\overline{C}}4$ . Optimal initiating time

Especially noteworthy one among the aforementioned five points in time is the *initiating time*, which leads us to the *optimal initiating time* (OIT) (see Section 8.2.4.1(p.44)). This yields three kinds of points in time: (§) (starting time), (onn-degenerate time), and (deadline) (see Section 8.2.4.3(p.45)).

# $\overline{\text{C5}}$ . Null-time-zone and deadline-engulfing (see Sections 8.2.4.5(p.46) and 8.2.4.6(p.46))

It is striking here that the last two,  $\odot$  and  $\odot$ , necessarily gives rise to the events of *null-time-zone* and *deadline-engulfing* (see H3(p.8)), both of which can be considered novel concepts; they have not been previously recognized by researchers, including the authors. Furthermore, what is remarkable is that the existence of the two time points,  $\odot$  and  $\odot$ , are not rare but rather occurs very frequently (see 22.2% and 33.4% in Table 24.1.1(p.246)). Lastly, it is important to emphasize that  $\odot$  and  $\odot$  (strictly optimal) occur at 2.6% and 3.2% respectively (see Table 24.1.1(p.246)). Presumably, the confirmed existence of these two events could be considered the most significant *discoveries* in this paper, suggesting the need for

a comprehensive re-examination of all results derived from past investigations of decision processes without incorporating the concept of the optimal initiating time.

# $\overline{\overline{\mathsf{C}}}6$ . Structured-unit-of-models (see Section 1.3(p.4))).

Before delving into the core of the study, we endeavored to clarify the general structure of asset trading problems, which gave rise to the concepts of the quadruple-asset-trading-problems (see Figure 1.3.1(p.6)) and the structured-unit-of-models (see Section 3.3(p.16)). It is important to note that this structure will become indispensable for the whole analysis of all models addressed in the present paper (see H10(p.9)). One of the key points in this paper is not to analyze respective models included in the structured-unit-of-models discretely and individualistically but to clarify the interconnectedness among these models systematically and comprehensively by using the integrated-theory in Part 2(p.51).

# $\overline{\overline{\mathsf{C}}}$ 7. Assumptions (see Chap. 2(p.11))).

In Chap. 2(p.11) we presented essential assumptions necessary for providing strict definitions of all models related to asset trading problems discussed in this paper. What should be particularly noted among them are the introductions of the quitting penalty price  $\rho$  (see A7(p.12)) and the discount factor  $\beta$  for cost (see A12(p.13)). The former leads to inevitable definitions of the three types of models (see (B(p.15))) and the latter offers a novel interpretation of the discount factor (see A12(p.13)).

# $\overline{\overline{C}}8$ . Discount factor for cost

Refer to [39, Ross] for a description concerning a managerial and/or economic implications of the discount factor  $\beta$  for profit. However, surprisingly, to the best of the authors' knowledge, we have not encountered references providing a persuasive explanation for the implications of the discount factor  $\beta$  for cost. We provided a clear interpretation for this issue (see A12(p.13)).

# $\overline{\overline{\mathsf{C}}}9$ . Underlying functions (see Chap. 6(p.25)).

Here, it is important to note that the system of optimality equations (see Chap. 7(p.29)) for all models (see Table 3.2.1(p.16)) is expressed by using functions T, L, K, and  $\mathcal{L}$ , referred to as the underlying function (see Chap. 6(p.25)). The function T has been already defined and used in the fields of mathematical statistics, operational research, and economics (see [14,Deg1970]); however, the introduction of other functions L, K, and  $\mathcal{L}$  (see  $(6.1.3(p.25)) \cdot (6.1.5(p.25))$ ) is presumably the first in this paper. Moreover, it is essential to remember that different properties of these functions are consistently utilized in the analysis of these models. All properties of these underlying functions (see Lemmas 11.1.1 $(p.55) \cdot 11.3.1(p.59)$ ) were derived through the repeated arrangement and rearrangement, as if solving a jigsaw puzzle, of many results obtained over more than ten years of various models. In [26,Iku1996] it was demonstrated that various results for wide-ranging types of decision problems posed and examined in many references thus far can be expressed by using these functions. These facts suggest the broader and deeper possibilities of properties inherent within these functions.

## $\overline{\overline{C}}10$ . Jumble of intuition and theory

We reiterate here that a question in Alice 1(p.44) is stemmed from the confusion between intuition and theory. While many researchers may quickly recognize the inaccuracy in her question, is it merely speculative to assume the possibility of individuals who have difficulty acknowledging their tendency to become entangled in this confusion? Indeed, in the past, we had encountered cases where submitted papers were nearly rejected due to referees' misunderstandings caused by such a jumble as described above.

# Part 2

# ${\bf Integrated\text{-}Theory}$

In this part we attempt to construct the integrated-theory.

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# Chapter 10

# Flow of the Construction of Integrated Theory

# 10.1 Bird's-Eye View

Figure 10.1.1(p.53) below provides a bird's-eye view of the flow of discussions which constructs the integrated-theory.

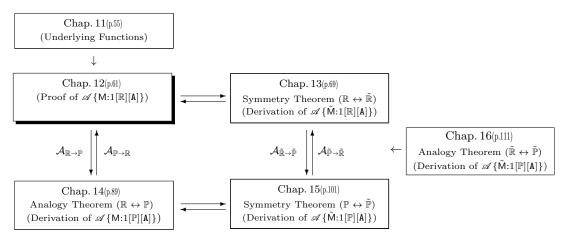


Figure 10.1.1: The flow of the construction of the integrated theory

The above figure states the following:

- o In Chap. 11(p.55), lemmas and corollaries for underlying functions are proven.
- ∘ In Chap. 12(p.61),  $\mathscr{A}\{M:1[\mathbb{R}][A]\}$  is proven by using the results in Chap. 11(p.55).
- In Chap. 13(p.69), the symmetry theorem  $(\mathbb{R} \leftrightarrow \tilde{\mathbb{R}})$  is proven, by which  $\mathscr{A}\{\tilde{M}:1[\mathbb{R}][A]\}$  is derived form  $\mathscr{A}\{M:1[\mathbb{R}][A]\}$ .
- $\circ \ \, \text{In Chap.} \ 14 \text{(p.89)} \,, \, \text{the analogy theorem} \,\, (\mathbb{R} \leftrightarrow \mathbb{P}) \,\, \text{is proven, by which} \,\, \mathscr{A} \{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\} \,\, \text{is derived form} \,\, \mathscr{A} \{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}.$
- $\circ$  In Chap. 15(p.101), the symmetry theorem ( $\mathbb{P} \leftrightarrow \tilde{\mathbb{P}}$ ) is proven, by which  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}$  is derived form  $\mathscr{A}\{M:1[\mathbb{P}][A]\}$ .
- In Chap. 16[p.111], the analogy theorem  $(\mathbb{R} \leftrightarrow \mathbb{P})$  is proven, which gives the relationship between  $\mathscr{A}\{\tilde{M}:1[\mathbb{R}][A]\}$  and  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}$ .

## 10.2 Connection with Both Directions

In the flow of Figure 10.1.1(p.53) above we should note the following:

- It is only  $\overline{\mathscr{A}\{M:1[\mathbb{R}][A]\}}$  that is directly proven.
- The above four boxes are connected with both directions ( $\leftrightarrow \updownarrow$ ). The above interrelationship implies that any given box can be derived from any other box by applying operations  $\mathcal{S}_{\mathbb{R}\to\mathbb{R}}$ ,  $\mathcal{S}_{\mathbb{R}\to\mathbb{R}}$ ,  $\mathcal{S}_{\mathbb{P}\to\mathbb{P}}$ ,  $\mathcal{S}_{\mathbb{P}\to\mathbb{P}}$ ,  $\mathcal{S}_{\mathbb{P}\to\mathbb{P}}$ ,  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$ ,  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$ , and  $\mathcal{A}_{\mathbb{P}\to\mathbb{R}}$ , which are defined in Chaps. 13(p.69)-16(p.111).

# Chapter 11

# **Properties of Underlying Functions**

This chapter examines the properties of underlying functions  $T_{\mathbb{R}}$ ,  $L_{\mathbb{R}}$ ,  $K_{\mathbb{R}}$ , and  $\mathcal{L}_{\mathbb{R}}$  and the  $\kappa_{\mathbb{R}}$ -value (see (6.1.1(p.25))-(6.1.6(p.25))), which are used to clarify the properties of the optimal decision rules for M:1[ $\mathbb{R}$ ][A] (see Chap. 12(p.61)).

**Definition 11.0.1**  $(A\{X_{\mathbb{R}}\}\text{and } \mathscr{A}\{X_{\mathbb{R}}\})$  Let us denote an assertion on  $X_{\mathbb{R}} = T_{\mathbb{R}}, L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}$  by  $A\{X_{\mathbb{R}}\}$  and an assertion system consisting of some assertions  $A\{X_{\mathbb{R}}\}$ 's by  $\mathscr{A}\{X_{\mathbb{R}}\}$ .  $\square$ 

# 11.1 Primitive Underlying Function $T_{\mathbb{R}}$

To begin with, let us prove the following lemma for the assertion system  $\mathscr{A}\{T_{\mathbb{R}}\}.$ 

**Lemma 11.1.1** ( $\mathscr{A}\{T_{\mathbb{R}}\}$ ) For any  $F \in \mathscr{F}$ :

- (a) T(x) is continuous on  $(-\infty, \infty)$ .
- (b) T(x) is nonincreasing on  $(-\infty, \infty)$ .
- (c) T(x) is strictly decreasing on  $(-\infty, b]$ .
- (d) T(x) + x is nondecreasing on  $(-\infty, \infty)$ .
- (e) T(x) + x is strictly increasing on  $[a, \infty)$ .
- (c) T(x) + x is stricing increasing on  $[a, \infty)$ .
- (f)  $T(x) = \mu x \text{ on } (-\infty, a] \text{ and } T(x) > \mu x \text{ on } (a, \infty).$
- (g) T(x) > 0 on  $(-\infty, b)$  and T(x) = 0 on  $[b, \infty)$ .
- (h)  $T(x) \ge \max\{0, \mu x\}$  on  $(-\infty, \infty)$ .
- (i)  $T(0) = \mu \text{ if } a > 0 \text{ and } T(0) = 0 \text{ if } b < 0.$
- (j)  $\beta T(x) + x$  is nondecreasing on  $(-\infty, \infty)$  if  $\beta = 1$ .
- (k)  $\beta T(x) + x$  is strictly increasing on  $(-\infty, \infty)$  if  $\beta < 1$ .
- (1) If x < y and a < y, then T(x) + x < T(y) + y.
- (m)  $\lambda \beta T(\lambda \beta \mu s) s$  is nonincreasing in s and strictly decreasing in s if  $\lambda \beta < 1$ .
- (n)  $a < \mu$ .<sup>†</sup>
- $\bullet$  *Proof* First, for any x and y let us prove the following two inequalities:

$$-(x-y)(1-F(y)) \le T(x) - T(y) \le -(x-y)(1-F(x)) \cdots (1), \tag{11.1.1}$$

$$(x-y)F(y) \le T(x) + x - T(y) - y \le (x-y)F(x) \cdots (2). \tag{11.1.2}$$

Then, let  $T(x,y) \stackrel{\text{def}}{=} \mathbf{E}[(\boldsymbol{\xi}-x)I(\boldsymbol{\xi}>y)]$  for any x and y.  $\stackrel{\ddagger}{=}$  Since  $1 \geq I(\boldsymbol{\xi}>y) \geq 0$  and since  $\max\{\boldsymbol{\xi}-x,0\} \geq 0$  and  $\max\{\boldsymbol{\xi}-x,0\} \geq \boldsymbol{\xi}-x$ , we have

$$\max\{\boldsymbol{\xi}-x,0\} \geq \max\{\boldsymbol{\xi}-x,0\}I(\boldsymbol{\xi}>y) \geq (\boldsymbol{\xi}-x)I(\boldsymbol{\xi}>y),$$

hence from (6.1.1(p.5)) we get  $T(x) \geq \mathbf{E}[(\xi - x)I(\xi > y)] = T(x,y)$ . Accordingly, for any x and y we have

$$T(x) - T(y) \ge T(x, y) - T(y) = \mathbf{E}[(\xi - x)I(\xi > y)] - \mathbf{E}[(\xi - y)I(\xi > y)] = -(x - y)\mathbf{E}[I(\xi > y)].$$

Since  $I(\boldsymbol{\xi} \leq y) + I(\boldsymbol{\xi} > y) = 1$ , we have

$$T(x) - T(y) \ge -(x - y)(\mathbf{E}[1 - I(\boldsymbol{\xi} \le y)]) = -(x - y)(1 - \mathbf{E}[I(\boldsymbol{\xi} \le y)]).$$

Then, since

$$\mathbf{E}[I(\boldsymbol{\xi} \leq y)] = \int_{-\infty}^{\infty} I(\boldsymbol{\xi} \leq y) f(\boldsymbol{\xi}) d\boldsymbol{\xi} = \int_{-\infty}^{y} 1 \times f(\boldsymbol{\xi}) d\boldsymbol{\xi} = \int_{-\infty}^{y} f(\boldsymbol{\xi}) d\boldsymbol{\xi} = \Pr{\{\boldsymbol{\xi} \leq y\} = F(y),\}}$$

we have  $T(x) - T(y) \ge -(x - y)(1 - F(y))$ , hence the far left inequality of (1) holds. Multiplying both sides of the inequality by -1 leads to  $-T(x) + T(y) \le (x - y)(1 - F(y))$  or equivalently  $T(y) - T(x) \le -(y - x)(1 - F(y))$ . Then, interchanging the

<sup>†</sup>The self-evident assertion is intentionally added here in order to keep the consistency with Lemma 14.2.1(p.93) (n).

<sup>&</sup>lt;sup>‡</sup>If a given statement S is true, then I(S) = 1, or else I(S) = 0.

notations x and y yields  $T(x) - T(y) \le -(x - y)(1 - F(x))$ , hence the far right inequality of (1) holds. (2) is immediate from adding x - y to (1). Let us note here that T(x) defined by (6.1.1(p.25)) can be rewritten as

$$T(x) = \mathbf{E}[\max\{\xi - x, 0\}I(a \le \xi)] + \mathbf{E}[\max\{\xi - x, 0\}I(\xi < a) \cdots (3)], \tag{11.1.3}$$

$$= \mathbf{E}[\max\{\xi - x, 0\}I(b < \xi)] + \mathbf{E}[\max\{\xi - x, 0\}I(\xi \le b)] \cdots (4). \tag{11.1.4}$$

- (a,b) Immediate from (6.1.1(p.25)) and from the fact that  $\max\{\boldsymbol{\xi}-x,0\}$  is continuous and nonincreasing in  $x\in(-\infty,\infty)$  for any given  $\boldsymbol{\xi}$ .
- (c) Let y < x < b, hence x y > 0. Then, since F(x) < 1 due to  $(2.2.1(1,2) \cdot (0.12))$ , we have -(x y)(1 F(x)) < 0, hence T(x) T(y) < 0 due to (1), so T(x) < T(y), i.e., T(x) is strictly decreasing on  $x < b \cdots (5)$ . Let us assume T(x) = T(b) on x < b. Then, for any sufficiently small  $\varepsilon > 0$  such that  $b x > 2\varepsilon$  we have  $b > b \varepsilon > x + \varepsilon > x$ , hence  $T(b) = T(x) > T(b \varepsilon) \ge T(b)$  due to the strict decreasingness shown above and the nonincreasingness in (b), which is a contradiction. Thus, it must be that  $T(x) \ne T(b)$  on x < b, so T(x) > T(b) or T(x) < T(b) on x < b; however, the latter is impossible due to (b), hence it follows that T(x) > T(b) on x < b. From this fact and (5) it inevitably follows that T(x) is strictly decreasing on  $x \le b$ , i.e., T(x) is strictly decreasing on  $(-\infty, b]$ .
  - (d) Evident from the fact that  $T(x) + x = \mathbf{E}[\max\{\boldsymbol{\xi},x\}]$  from (6.1.1(p.5)) and  $\max\{\boldsymbol{\xi},x\}$  is nondecreasing in x for any  $\boldsymbol{\xi}$ .
- (e) Let a < y < x, hence F(y) > 0 due to  $(2.2.1\,(2,3)\,(\text{p12}))$ . Then, since (x-y)F(y) > 0, we have 0 < T(x) + x T(y) + y from (2), hence T(y) + y < T(x) + x, i.e., T(x) + x is strictly increasing on  $a < x \cdots$  (6). Let us assume T(a) + a = T(x) + x on a < x. Then, for any sufficiently small  $\varepsilon > 0$  such that  $x a > \varepsilon$  we have  $a < a + \varepsilon < x$ , hence  $T(a) + a = T(x) + x > T(a + \varepsilon) + a + \varepsilon \ge T(a) + a$  due to the strict increasingness shown above and the nondecreasing in (d), which is a contradiction. Thus, it must be that  $T(x) + x \ne T(a) + a$  on a < x, so we have T(x) + x > T(a) + a or T(x) + x < T(a) + a on a < x; however, the latter is impossible due to (d), hence it follows that T(x) + x > T(a) + a on a < x. From this fact and (6) it inevitably follows that T(x) + x > T(x) + x is strictly increasing on  $[a, \infty)$ .
- (f) Let  $x \leq a$ . If  $a \leq \boldsymbol{\xi}$ , then  $x \leq \boldsymbol{\xi}$ , hence  $\max\{\boldsymbol{\xi} x, 0\} = \boldsymbol{\xi} x$  and if  $\boldsymbol{\xi} < a$ , then  $f(\boldsymbol{\xi}) = 0 \cdots (7)$  due to (2.2.3(1) (p.13)). Thus, from (3) we have  $T(x) = \mathbf{E}[(\boldsymbol{\xi} x)I(a \leq \boldsymbol{\xi})] + 0$ . Then, since  $\mathbf{E}[(\boldsymbol{\xi} x)I(\boldsymbol{\xi} < a)] = \int_{\infty}^{a} (\boldsymbol{\xi} x)f(\boldsymbol{\xi})d\boldsymbol{\xi} = 0$  due to (7), we have

$$T(x) = \mathbf{E}[(\boldsymbol{\xi} - x)I(a \leq \boldsymbol{\xi})] + \mathbf{E}[(\boldsymbol{\xi} - x)I(\boldsymbol{\xi} < a)] = \mathbf{E}[(\boldsymbol{\xi} - x)(I(a \leq \boldsymbol{\xi}) + I(\boldsymbol{\xi} < a))] = \mathbf{E}[\boldsymbol{\xi} - x] = \mu - x,$$

hence the former half is true. Then, since  $T(a) = \mu - a$  or equivalently  $T(a) + a = \mu$ , if a < x, from (e) we have  $T(x) + x > T(a) + a = \mu$ , hence  $T(x) > \mu - x$ , thus the latter half is true.

- (g) Let  $b \le x$ . If  $b < \xi$ , then  $f(\xi) = 0$  due to (2.2.3 (3) (p.13)), hence  $\mathbf{E}[\max\{\xi x, 0\}I(b < \xi)] = \int_b^\infty \max\{\xi x, 0\}f(\xi)d\xi = 0$  and if  $\xi \le b$ , then  $\xi \le x$ , hence  $\max\{\xi x, 0\}I(\xi \le b) = 0$ , so  $\mathbf{E}[\max\{\xi x, 0\}I(\xi \le b)] = 0$ . Accordingly, from (4) we have  $T(x) = 0 \cdots (8)$ , so the latter half is true. Let x < b. Then, since T(x) > T(b) from (c) and T(b) = 0 from (8), we have T(x) > 0, hence the former half is true.
- (h) Since  $T(x) \ge \mu x$  on  $(-\infty, \infty)$  from (f) and  $T(x) \ge 0$  on  $(-\infty, \infty)$  from (g), it follows that  $T(x) \ge \max\{0, \mu x\}$  on  $(-\infty, \infty)$ .
- (i) From (6.1.1(p.25)) and (2.2.3(1,3)(p.13)) we have  $T(0) = \mathbf{E}[\max\{\boldsymbol{\xi},0\}] = \mathbf{E}[\max\{\boldsymbol{\xi},0\}I(a \leq \boldsymbol{\xi} \leq b)]$ . Hence, if a > 0, then  $T(0) = \mathbf{E}[\boldsymbol{\xi}I(a \leq \boldsymbol{\xi} \leq b)] = \mathbf{E}[\boldsymbol{\xi}I(a \leq \boldsymbol{\xi} \leq b)] = \mathbf{E}[\boldsymbol{\xi}I(a \leq \boldsymbol{\xi} \leq b)] = 0$ .
  - (j) If  $\beta = 1$ , then  $\beta T(x) + x = T(x) + x$ , hence the assertion is true from (d).
- (k) Since  $\beta T(x) + x = \beta(T(x) + x) + (1 \beta)x$ , if  $\beta < 1$ , then  $(1 \beta)x$  is strictly increasing in x, hence the assertion is true from (d).
- (l) Let x < y and a < y. If  $x \le a$ , then  $T(x) + x \le T(a) + a < T(y) + y$  due to (d,e), and if a < x, then  $a \le x < y$ , hence K(x) + x < K(y) + y due to (e). Thus, whether  $x \le a$  or a < x, we have T(x) + x < T(y) + y
  - (m) From (6.1.1(p.25)) we have

$$\begin{split} \lambda\beta T(\lambda\beta\mu-s)-s &= \lambda\beta \operatorname{\mathbf{E}}[\max\{\boldsymbol{\xi}-\lambda\beta\mu+s,0\}]-s \\ &= \operatorname{\mathbf{E}}[\max\{\lambda\beta\boldsymbol{\xi}-(\lambda\beta)^2\mu+\lambda\beta s,0\}]-s \\ &= \operatorname{\mathbf{E}}[\max\{\lambda\beta\boldsymbol{\xi}-(\lambda\beta)^2\mu-(1-\lambda\beta)s,-s\}], \end{split}$$

which is nonincreasing in s and strictly decreasing in s if  $\lambda \beta < 1$ .

(n) Evident.

# 11.2 Derivative Underlying Functions

First let us define

$$\delta = 1 - (1 - \lambda)\beta. \tag{11.2.1}$$

Then, since  $0 < \beta \le 1$  and  $1 \ge \lambda > 0$ , we have

$$\delta \ge 1 - (1 - \lambda) \times 1 = \lambda > 0 \cdots (1), \qquad \delta \le 1 - (1 - \lambda) \times 0 = 1 \cdots (2). \tag{11.2.2}$$

Now, from (6.1.3(p.25)) and (6.1.4(p.25)) and from Lemma 11.1.1(p.55) (f) we obtain

$$L(x) \begin{cases} = \lambda \beta \mu - s - \lambda \beta x \text{ on } (-\infty, a] & \cdots (1), \\ > \lambda \beta \mu - s - \lambda \beta x \text{ on } (a, \infty) & \cdots (2), \end{cases}$$
(11.2.3)

$$K(x) \begin{cases} = \lambda \beta \mu - s - \delta x & \text{on } (-\infty, a] & \cdots (1), \\ > \lambda \beta \mu - s - \delta x & \text{on } (a, \infty) & \cdots (2). \end{cases}$$
(11.2.4)

In addition, from (6.1.4(p.25)) and Lemma 11.1.1(p.55)(g) we have

$$K(x) \begin{cases} > -(1-\beta)x - s \text{ on } (-\infty, b) & \cdots (1), \\ = -(1-\beta)x - s \text{ on } [b, \infty) & \cdots (2), \end{cases}$$
 (11.2.5)

from which we obtain

$$K(x) + x \ge \beta x - s$$
 on  $(-\infty, \infty)$ . (11.2.6)

Then, from (11.2.4(1)(p.57)) and (11.2.5(2)(p.57)) we get

$$K(x) + x = \begin{cases} \lambda \beta \mu - s + (1 - \lambda) \beta x \text{ on } (-\infty, a] & \cdots (1), \\ \beta x - s & \text{on } [b, \infty) & \cdots (2). \end{cases}$$

$$(11.2.7)$$

From (6.1.8(p.5)) we have  $K(x) = L(x) - (1-\beta)x$  and  $L(x) = K(x) + (1-\beta)x$ . Accordingly, if  $x_L$  and  $x_K$  exist, then we get

$$K(x_L) = -(1 - \beta) x_L \cdots (1), \qquad L(x_K) = (1 - \beta) x_K \cdots (2).$$
 (11.2.8)

#### Lemma 11.2.1 ( $\mathscr{A}\{L_{\mathbb{R}}\}$ )

- (a) L(x) is continuous.
- (b) L(x) is nonincreasing on  $(-\infty, \infty)$ .
- (c) L(x) is strictly decreasing on  $(-\infty, b]$ .
- (d) Let s = 0. Then  $x_L = b$  where  $x_L > (\leq) x \Leftrightarrow L(x) > (=) 0 \Rightarrow L(x) > (\leq) 0$ .
- (e) Let s > 0.
  - 1.  $x_L$  uniquely exists with  $x_L < b$  where  $x_L > (= (<)) x \Leftrightarrow L(x) > (= (<)) 0$ .
  - 2.  $(\lambda \beta \mu s)/\lambda \beta \leq (>) a \Leftrightarrow x_L = (>) (\lambda \beta \mu s)/\lambda \beta$ .  $\square$
- *Proof* (a-c) Immediate from (6.1.3(p.25)) and Lemma 11.1.1(p.55) (a-c).
- (d) Let s=0. Then, since  $L(x)=\lambda\beta T(x)$ , from Lemma 11.1.1(p.55) (g) we have L(x)>0 for b>x and L(x)=0 for  $b\leq x$ , hence  $x_L=b$  by the definition of  $x_L$  (see Section 6.2(p.27) (a)), thus  $x_L>(\leq)x\Rightarrow L(x)>(=)0$ . The inverse is true by contraposition. In addition, since  $L(x)=0\Rightarrow L(x)\leq 0$ , we have  $L(x)>(=)0\Rightarrow L(x)>(\leq)0$ .
  - (e) Let s > 0.
- (e1) From (11.2.3 (1) (p.57)) and from  $\lambda > 0$  and  $\beta > 0$  we have L(x) > 0 for a sufficiently small x < 0 such that  $x \le a$ . In addition, we have  $L(b) = \lambda \beta T(b) s = -s < 0$  due to Lemma 11.1.1(p.55) (g). Hence, from (a,c) it follows that  $x_L$  uniquely exists. The inequality  $x_L < b$  is immediate from L(b) < 0. The latter half is evident.
  - (e2) If  $(\lambda \beta \mu s)/\lambda \beta \le (>) a$ , from (11.2.3(p.57)) we have

$$L((\lambda \beta \mu - s)/\lambda \beta) = (>) \lambda \beta \mu - s - \lambda \beta (\lambda \beta \mu - s)/\lambda \beta = 0,$$

hence  $x_L = (>) (\lambda \beta \mu - s)/\lambda \beta$  from (e1). Thus "\Rightarrow" was proven. Its inverse "\Rightarrow" is immediate by contraposition.

# Corollary 11.2.1 $(\mathscr{A}\{L_{\mathbb{R}}\})$

- (a)  $x_L > (\leq) x \Leftrightarrow L(x) > (\leq) 0$ .
- (b)  $x_L \ge (\le) x \Rightarrow L(x) \ge (\le) 0.$
- Proof (a) "\Rightarrow" is immediate from Lemma 11.2.1(p.57) (d,e1). "\Rightarrow" is evident by contraposition.
- (b) Since  $x_L > (\leq) x \Rightarrow L(x) > (\leq) 0$  due to (a) and since  $L(x) > (\leq) 0 \Rightarrow L(x) \geq (\leq) 0$ , we have  $x_L > (\leq) x \Rightarrow L(x) \geq (\leq) 0$ . In addition, if  $x_L = x$ , then  $L(x) = L(x_L) = 0$  or equivalently  $x_L = x \Rightarrow L(x) = 0$ , hence  $x_L = x \Rightarrow L(x) \geq 0$ . Accordingly, it follows that  $x_L \geq (\leq) x \Rightarrow L(x) \geq (\leq) 0$ .

## Lemma 11.2.2 ( $\mathscr{A}\{K_{\mathbb{R}}\}$ )

- (a) K(x) is continuous on  $(-\infty, \infty)$ .
- (b) K(x) is nonincreasing on  $(-\infty, \infty)$ .
- (c) K(x) is strictly decreasing on  $(-\infty, b]$ .
- (d) K(x) is strictly decreasing on  $(-\infty, \infty)$  if  $\beta < 1$ .
- (e) K(x) + x is nondecreasing on  $(-\infty, \infty)$ .

- (f) K(x) + x is strictly increasing on  $(-\infty, \infty)$  if  $\lambda < 1$ .
- (g) K(x) + x is strictly increasing on  $[a, \infty)$ .
- (h) If x < y and a < y, then K(x) + x < K(y) + y.
- (i) Let  $\beta = 1$  and s = 0. Then  $x_K = b$  where  $x_K > (\leq) x \Leftrightarrow K(x) > (=) 0 \Rightarrow K(x) > (\leq) 0$ .
- (j) Let  $\beta < 1$  or s > 0.
  - 1. There uniquely exists  $x_K$  where  $x_K > (= (<)) x \Leftrightarrow K(x) > (= (<)) 0$ .
  - 2.  $(\lambda \beta \mu s)/\delta \le (>) \ a \Leftrightarrow x_K = (>) \ (\lambda \beta \mu s)/\delta$ .
  - 3. Let  $\kappa > (=(<)) \ 0$ . Then  $x_K > (=(<)) \ 0$ .  $\square$
- *Proof* (a-c) Immediate from (6.1.4(p.25)) and Lemma 11.1.1(p.55) (a-c).
  - (d) Immediate from (6.1.4(p.25)) and Lemma 11.1.1(p.55) (b).
  - (e) From (6.1.4(p.25)) we have

$$K(x) + x = \lambda \beta T(x) + \beta x - s = \lambda \beta (T(x) + x) + (1 - \lambda) \beta x - s \cdots (1),$$

hence the assertion holds from Lemma 11.1.1(p.55) (d).

- (f) Obvious from (1) and Lemma 11.1.1(p.55) (d).
- (g) Clearly from (1) and Lemma 11.1.1(p.55) (e).
- (h) Let x < y and a < y. If  $x \le a$ , then  $K(x) + x \le K(a) + a < K(y) + y$  due to (e,g), and if a < x, then a < x < y, hence K(x) + x < K(y) + y due to (g). Thus, whether  $x \le a$  or a < x, we have K(x) + x < K(y) + y
- (i) Let  $\beta=1$  and s=0. Then, since  $K(x)=\lambda T(x)$  due to (6.1.4 p.25), from Lemma 11.1.1 (p.55) (g) we have K(x)>0 for x< b and K(x)=0 for  $b\leq x$ , hence  $x_K=b$  by the definition of  $x_K$  (see Section 6.2 (p.27) (a)). Thus  $x_K>(\leq) x\Rightarrow K(x)>(=) 0$ . The inverse holds by contraposition. In addition, since  $K(x)=0\Rightarrow K(x)\leq 0$ , we have  $K(x)>(=) 0\Rightarrow K(x)>(\leq) 0$ .
  - (j) Let  $\beta < 1$  or s > 0.
  - (j1) This proof consists of the following six steps:
- First note (11.2.5 (2) (p.57)). If  $\beta < 1$ , then K(x) < 0 for any sufficiently large x > 0 with  $x \ge b$  and if s > 0, then, whether  $\beta < 1$  or  $\beta = 1$ , we have K(x) < 0 for any sufficiently large x > 0 with  $x \ge b$ . Hence, whether  $\beta < 1$  or s > 0, we have K(x) < 0 for any sufficiently large x > 0 with  $x \ge b$ .
- Next note (11.2.4(1)(p.57)). Then, since  $\delta > 0$  from (11.2.2(1)(p.56)), whether  $\beta < 1$  or s > 0 we have K(x) > 0 for any sufficiently small x < 0 with  $x \le a$ .
- Hence, whether  $\beta < 1$  or s > 0, it follows that there exists the solution  $x_K$ .
- $\circ$  Let  $\beta < 1$ . Then, the solution  $x_K$  is unique from (d).
- Let s > 0. If  $\beta < 1$ , the solution  $x_K$  is unique for the reason just above. If  $\beta = 1$ , we have K(b) = -s < 0 from (11.2.5 (2) (p.57)), hence  $x_K < b$  due to (c), so K(x) is strictly decreasing on the neighbourhood of  $x = x_K$  due to (c), hence the solution  $x_K$  is unique. Therefore, whether  $\beta < 1$  or  $\beta = 1$ , it follows that the solution  $x_K$  is unique.
- $\circ$  Accordingly, whether  $\beta < 1$  or s > 0, it follows that the solution  $x_K$  is unique.

From all the above, whether  $\beta < 1$  or s > 0, it follows that the solution  $x_K$  uniquely exists and hence that the latter half becomes true.

(j2) Let  $(\lambda \beta \mu - s)/\delta \le (>) a$ . Then, from (11.2.4(1(2))(p.57)) we have

$$K((\lambda \beta \mu - s)/\delta) = (>) \lambda \beta \mu - s - \delta(\lambda \beta \mu - s)/\delta = 0,$$

hence  $x_K = (>) (\lambda \beta \mu - s)/\delta$  due to (j1). Thus " $\Rightarrow$ " was proven. Its inverse " $\Leftarrow$ " is immediate by contraposition.

(j3) If  $\kappa > (= (<)) 0$ , then K(0) > (= (<)) 0 from (6.1.7(p.25)), hence  $x_K > (= (<)) 0$  from (j1).

# Corollary 11.2.2 $(\mathscr{A}\{K_{\mathbb{R}}\})$

- (a)  $x_K > (\leq) x \Leftrightarrow K(x) > (\leq) 0$ .
- (b)  $x_K \ge (\le) x \Rightarrow K(x) \ge (\le) 0.$
- ullet Proof (a) " $\Rightarrow$ " is immediate from Lemma 11.2.2(p.57) (i,j1). " $\Leftarrow$ " is evident by contraposition.
- (b) Since  $x_K > (\leq) x \Rightarrow K(x) > (\leq) 0$  due to (a) and since  $K(x) > (\leq) 0 \Rightarrow K(x) \geq (\leq) 0$ , we have  $x_K > (\leq) x \Rightarrow K(x) \geq (\leq) 0$ . In addition, if  $x_K = x$ , then  $K(x) = K(x_K) = 0$  or equivalently  $x_K = x \Rightarrow K(x) = 0$ , hence  $x_K = x \Rightarrow K(x) \geq 0$ . Accordingly, it follows that  $x_K \geq (\leq) x \Rightarrow K(x) \geq (\leq) 0$ .

### Lemma 11.2.3 $(\mathscr{A}\{L_{\mathbb{R}}/K_{\mathbb{R}}\})$

- (a) Let  $\beta = 1$  and s = 0. Then  $x_L = x_K = b$ .
- (b) Let  $\beta = 1$  and s > 0. Then  $x_L = x_K$ .
- (c) Let  $\beta < 1$  and s = 0. Then  $b > (= (<)) 0 \Leftrightarrow x_L > (= (<)) x_K \Rightarrow x_K > (= (=)) 0$ .
- (d) Let  $\beta < 1$  and s > 0. Then  $\kappa > (= (<)) \ 0 \Leftrightarrow x_L > (= (<)) \ x_K \Rightarrow x_K > (= (<)) \ 0$ .  $\square$

- *Proof* (a) If  $\beta = 1$  and s = 0, then  $x_L = b$  from Lemma 11.2.1(p.57) (d) and  $x_K = b$  from Lemma 11.2.2(p.57) (i), hence  $x_L = x_K = b$ .
- (b) Let  $\beta = 1$  and s > 0. Then  $K(x_L) = 0$  from (11.2.8(1)(p.57)), hence  $x_K = x_L$  from Lemma 11.2.2(p.57)(j1).
  - (c) Let  $\beta < 1$  and s = 0. Then  $x_L = b \cdots (1)$  from Lemma 11.2.1(p.57) (d).
- o If b > 0, then  $x_L > 0$ , hence  $K(x_L) < 0$  from (11.2.8 (1) (p.57)), so  $x_L > x_K$  from Lemma 11.2.2(p.57) (j1). If b = (<) 0, then  $x_L = (<)$  0, hence  $K(x_L) = (>)$  0 from (11.2.8 (1) (p.57)), so  $x_L = (<)$   $x_K$  from Lemma 11.2.2(p.57) (j1). Accordingly, we have " $\Rightarrow$ " holds and its inverse " $\Leftarrow$ " is immediate by contraposition. Thus the first relation " $\Leftrightarrow$ " holds.
- o If b > 0, from (6.1.7(p.25)) we have  $K(0) = \lambda \beta T(0) > 0$  due to Lemma 11.1.1(p.55) (g), hence  $x_K > 0 \cdots$  (2) from Lemma 11.2.2(p.57) (j1). If b = (<) 0, from (6.1.7(p.25)) we have  $K(0) = \lambda \beta T(0) = 0$  due to Lemma 11.1.1(p.55) (g), hence  $x_K = (<) 0$  from Lemma 11.2.2(p.57) (j1). Accordingly, we have the *second relation* " $\Rightarrow$ ".
- (d) Let  $\beta < 1$  and s > 0. Now, since  $\kappa = K(0)$  from (6.1.7(p25)), if  $\kappa > (=(<)) 0$ , then K(0) > (=(<)) 0, thus  $x_K > (=(<)) 0 \cdots (3)$  from Lemma 11.2.2(p.57) (j1). Accordingly  $L(x_K) > (=(<)) 0$  from (11.2.8 (2) (p.57)), hence  $x_L > (=(<)) x_K$  from Lemma 11.2.1(p.57) (e1). Thus, " $\Rightarrow$ " in the first relation " $\Rightarrow$ " holds and its inverse " $\Leftarrow$ " is immediate by contraposition. Finally, the first relation " $\Rightarrow$ " is immediate from (3).

### Lemma 11.2.4 $(\mathcal{L}_{\mathbb{R}})$

- (a)  $\mathcal{L}(s)$  is nonincreasing in s and strictly decreasing in s if  $\lambda \beta < 1$ .
- (b) Let  $\lambda \beta \mu > b$ .
  - 1.  $x_L \leq \lambda \beta \mu s$ .
  - 2. Let s > 0 and  $\lambda \beta < 1$ . Then  $x_L < \lambda \beta \mu s$ .
- (c) Let  $\lambda \beta \mu < b$ . Then, there exists a  $s_{\mathcal{L}} > 0$  such that if  $s_{\mathcal{L}} > (\leq) s$ , then  $x_{\mathcal{L}} > (\leq) \lambda \beta \mu s$ .  $\square$
- *Proof* (a) From (6.1.5(p.25)) and (6.1.3(p.25)) we have

$$\mathcal{L}(s) = L(\lambda \beta \mu - s) = \lambda \beta T(\lambda \beta \mu - s) - s \cdots (1),$$

hence the assertion holds from Lemma 11.1.1(p.55) (m).

- (b) Let  $\lambda \beta \mu \geq b$ . Then, from (1) we have  $\mathcal{L}(0) = \lambda \beta T(\lambda \beta \mu) = 0 \cdots$  (2) due to Lemma 11.1.1(p.55) (g).
- (b1) Since  $s \ge 0$ , from (a) we have  $\mathcal{L}(s) \le \mathcal{L}(0) = 0$  due to (2) or equivalently  $L(\lambda \beta \mu s) \le 0$  due to (1), hence  $x_L \le \lambda \beta \mu s$  from Corollary 11.2.1(p.57) (a).
- (b2) Let s > 0 and  $\lambda \beta < 1$ . Then, from (a) we have  $\mathcal{L}(s) < \mathcal{L}(0) = 0 \cdots$  (3) due to (2) or equivalently  $\mathcal{L}(\lambda \beta \mu s) < 0$  due to (1), hence  $x_L < \lambda \beta \mu s$  from Lemma 11.2.1(p.57) (e1).
- (c) Let  $\lambda\beta\mu < b$ . From (1) we have  $\mathcal{L}(0) = \lambda\beta T(\lambda\beta\mu) > 0\cdots$  (4) due to Lemma 11.1.1(p.55) (g). Note (11.2.3 (1) (p.57)). Then, for any sufficiently large s > 0 such that  $\lambda\beta\mu s \le a$  and  $\lambda\beta\mu s < 0$  we have

$$\mathcal{L}(s) = L(\lambda \beta \mu - s) = \lambda \beta \mu - s - \lambda \beta (\lambda \beta \mu - s) = (1 - \lambda \beta)(\lambda \beta \mu - s) \le 0.$$

Accordingly, due to (a) it follows that there exists the solution  $s_{\mathcal{L}}$  of  $\mathcal{L}(s) = 0$  where  $s_{\mathcal{L}} > 0$  due to (4). Then, since  $\mathcal{L}(s) > 0$  for  $s < s_{\mathcal{L}}$  and  $\mathcal{L}(s) \le 0$  for  $s \ge s_{\mathcal{L}}$  or equivalently  $L(\lambda \beta \mu - s) > 0$  for  $s < s_{\mathcal{L}}$  and  $L(\lambda \beta \mu - s) \le 0$  for  $s \ge s_{\mathcal{L}}$ , from Corollary 11.2.1(p.57) (a) we get  $x_{\mathcal{L}} > \lambda \beta \mu - s$  for  $s < s_{\mathcal{L}}$  and  $x_{\mathcal{L}} \le \lambda \beta \mu - s$  for  $s \ge s_{\mathcal{L}}$ .

# 11.3 $\kappa_{\mathbb{R}}$ -value

Lemma 11.3.1  $(\mathscr{A}\{\kappa_{\mathbb{R}}\})$ 

- (a)  $\kappa = \lambda \beta \mu s \text{ if } a > 0 \text{ and } \kappa = -s \text{ if } b < 0.$
- (b) Let  $\beta < 1$  or s > 0, Then  $\kappa > (= (<)) 0 \Leftrightarrow x_K > (= (<)) 0$ .
- *Proof* (a) Immediate from (6.1.6(p.25)) and Lemma 11.1.1(p.55) (i).
- (b) Let  $\beta < 1$  or s > 0. Then, if  $\kappa > (=(<))$  0, we have K(0) > (=(<)) 0 from (6.1.7(p.25)), hence  $x_K > (=(<))$  0 from Lemma 11.2.2(p.57) (j1). Thus " $\Rightarrow$ " was proven. Its inverse " $\Leftarrow$ " is immediate by contraposition.

# Chapter 12

# Proof of $\mathscr{A}\{M:1[\mathbb{R}][A]\}$

# 12.1 Preliminary

From (7.2.8(p.30)) and (7.2.14(p.30)) we have

$$V_t - \beta V_{t-1} = \max\{S_t, 0\}$$
  
= \text{max}\{L(V\_{t-1}), 0\}, \ t > 1. \tag{12.1.1}

Accordingly:

1. If  $L(V_{t-1}) \ge 0$ , then  $V_t - \beta V_{t-1} = L(V_{t-1})$ , hence from (6.1.9(p.25)) we have

$$V_t = L(V_{t-1}) + \beta V_{t-1} = K(V_{t-1}) + V_{t-1}, \quad t > 1.$$
(12.1.2)

2. If  $L(V_{t-1}) \leq 0$ , then  $V_t - \beta V_{t-1} = 0$ , hence

$$V_t = \beta V_{t-1}, \quad t > 1.. \tag{12.1.3}$$

Now, from (7.4.2(p.41)) with t=2 we have

$$V_2 - V_1 = \max\{K(V_1), -(1-\beta)V_1\}. \tag{12.1.4}$$

Finally, from (7.2.14(p.30)) and (7.2.12(p.30)) we have

$$\mathbb{S}_t = L(V_{t-1}) > (<) \, 0 \Rightarrow \, \mathtt{Conduct}_{t_{\blacktriangle}}(\mathtt{Skip}_{t_{\blacktriangle}}), \quad t > 1.. \tag{12.1.5}$$

# 12.2 Proof of $\mathscr{A}\{M:1[\mathbb{R}][A]\}$

**Definition 12.2.1** (assertion and assertion system) By  $A\{M:1[\mathbb{R}][A]\}$  let us represent an assertion included in each of Tom's 12.2.1(p.61) and 12.2.2(p.62) below and by  $\mathscr{A}\{M:1[\mathbb{R}][A]\}$  the assertion system consisting of all assertions included in each Tom.  $\square$  Below, note that  $\lambda=1$  is assume in the model (See Def. 13.7.1(p.83) for the meaning of symbol  $\square$  which is used below).

- Tom 12.2.1 ( $\mathscr{A}\{M:1[\mathbb{R}][A]\}$ ) Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nondecreasing in t > 0.
- (b) We have  $\P$  doing  $\text{doins}_{\tau>1}\langle \tau \rangle$  where  $\text{conduct}_{\tau\geq t>1}$ .
- Proof Let  $\beta=1$  and s=0. Then, from (6.1.4(p.25)) we have  $K(x)=T(x)\geq 0\cdots (1)$  for any x due to

Lemma 11.1.1(p.55) (g), hence from (7.4.2(p.41)) and (1) we have

$$V_t = \max\{T(V_{t-1}) + V_{t-1}, V_{t-1}\} = \max\{T(V_{t-1}), 0\} + V_{t-1} = T(V_{t-1}) + V_{t-1} \cdot \cdot \cdot (2), \quad t > 1.$$

- (a) Since  $V_2 = T(V_1) + V_1$ , we have  $V_2 \ge V_1$  due to (1). Suppose  $V_{t-1} \le V_t$ . Then, from Lemma 11.1.1(p.55) (d) we have  $V_t \le T(V_t) + V_t = V_{t+1}$ . Hence, by induction  $V_{t-1} \le V_t$  for t > 1, i.e.,  $V_t$  is nondecreasing in t > 0.
- (b) Since  $V_1 = \mu$  from (7.4.1(p.41)), we have  $V_1 < b$ . Suppose  $V_{t-1} < b$ . Then, from (2) we have  $V_t < T(b) + b = b$  due to Lemma 11.1.1(p.55) (l,g). Accordingly, by induction  $V_{t-1} < b$  for t > 1, hence  $L(V_{t-1}) > 0$  for t > 1 due to Lemma 11.2.1(p.57) (d); accordingly,  $L(V_{t-1}) > 0 \cdots$  (3) for  $\tau \ge t > 1$ . Thus, from (12.1.1(p.61)) we obtain  $V_t \beta V_{t-1} > 0$  for  $\tau \ge t > 1$ , i.e.,  $V_t > \beta V_{t-1}$  for  $\tau \ge t > 1$ . Accordingly, since  $V_\tau > \beta V_{\tau-1} > \cdots > \beta^{\tau-1} V_1$ , we have  $t_\tau^* = \tau$  for  $\tau > 1$ , i.e., subseteq su

Let us define

$$\mathbf{S}_1 \boxed{\$ \blacktriangle \circledcirc \Vdash} = \left\{ \begin{array}{ll} \text{For any } \tau > 1 \text{ there exists } t^\bullet_\tau > 1 \text{ such that} \\ (1) \qquad \boxed{\$ \text{ dOITs}_{t^\bullet_\tau \geq \tau > 1} \langle \tau \rangle}_{\blacktriangle} \text{ where } \mathbf{CONDUCT}_{\tau \geq t > 1 \blacktriangle}, \\ (2) \qquad \boxed{\$ \text{ indOIT}_{\tau > t^\bullet_\tau} \langle t^\bullet_\tau \rangle}_{\Vdash} \text{ where } \mathbf{CONDUCT}_{\tau \geq t > 1 \blacktriangle}. \end{array} \right\}$$

- Tom 12.2.2 ( $\mathscr{A}\{M:1[\mathbb{R}][A]\}$ ) Let  $\beta < 1$  or s > 0.
- (a)  $V_t$  is nondecreasing in t > 0 and converges to a finite  $V \ge x_K$  as  $t \to \infty$ .
- (b) Let  $\beta \mu \geq b$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
- (c) Let  $\beta \mu < b$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $\mu s \leq a$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $\mu s > a$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}$  where  $\text{CONDUCT}_{\tau \geq t > 1}$ .
  - 2. Let  $\beta < 1$  and s = 0 ((s > 0)).
    - i. Let b>0 ( $\kappa>0$ ). Then  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau\rangle}$  where  $\text{CONDUCT}_{\tau\geq t>1}$ .
    - ii. Let  $b = 0 ((\kappa = 0))$ .
      - 1. Let  $\beta \mu s \leq a$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta\mu s > a$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1}\langle \tau \rangle}_{\blacktriangle}$  where  $\text{CONDUCT}_{\tau > t > 1}_{\blacktriangle}$ .
    - iii. Let  $b < 0 (\kappa < 0)$ .
      - $1. \quad \operatorname{Let} \, \beta \mu s \leq a \ \operatorname{or} \ s_{\mathcal{L}} \ \leq s. \ \operatorname{Then} \left[ \bullet \operatorname{dOITd}_{\tau > 1} \langle 1 \rangle \right]_{\parallel}.$
      - 2. Let  $\beta\mu-s>a$  and  $s< s_{\mathcal{L}}$  . Then  $\mathbf{S}_1(\mathbf{p}\mathbf{f}\mathbf{l})$   $\boxed{\$ \blacktriangle \odot \parallel}$  is true.  $\Box$
- Proof Let  $\beta < 1$  or s > 0. In this model, note that the search must be necessarily conducted at time t = 1 (see Remark 4.1.3(p.20) (b)) and that  $\delta = 1 \cdots (1)$  (see (11.2.1(p.56))) due to the assumption  $\lambda = 1 \cdots (2)$ .
- (a) Since  $x_K \geq \beta \mu s = V_1$  due to Lemma 11.2.2(p.57) (j2) and (7.4.1(p.41)), we have  $K(V_1) \geq 0$  due to Lemma 11.2.2(p.57) (j1), hence  $V_2 V_1 \geq 0$  from (12.1.4(p.61)), i.e.,  $V_1 \leq V_2$ . Suppose  $V_{t-1} \leq V_t$ . Then, from (7.4.2(p.41)) and Lemma 11.2.2(p.57) (e) we have  $V_t \leq \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Hence, by induction  $V_{t-1} \leq V_t$  for t > 1, i.e.,  $V_t$  is nondecreasing in t > 0. Consider a sufficiently large M > 0 with  $\beta \mu s \leq M$  and  $b \leq M$ , hence  $V_1 \leq M$  from (7.4.1(p.41)). Suppose  $V_{t-1} \leq M$ . Then, from (7.4.2(p.41)), Lemma 11.2.2(p.57) (e), and (11.2.7 (2) (p.57)) we have  $V_t \leq \max\{K(M) + M, \beta M\} = \max\{\beta M s, \beta M\} \leq \max\{M, M\} = M$  due to  $\beta \leq 1$  and  $s \geq 0$ . Hence, by induction  $V_t \leq M$  for t > 0, i.e.,  $V_t$  is upper bounded in t. Accordingly  $V_t$  converges to a finite V as  $t \to \infty$ . Then, from (7.4.2(p.41)) we have  $V = \max\{K(V) + V, \beta V\}$ , hence  $0 = \max\{K(V), -(1-\beta)\beta V\}$ . Thus, since  $K(V) \leq 0$ , we have  $V \geq x_K$  from Lemma 11.2.2(p.57) (j1).
- (b) Let  $\beta \mu \geq b$ . Then  $x_L \leq \beta \mu s = V_1$  from Lemma 11.2.4(p.59) (b1) with  $\lambda = 1$ , hence  $x_L \leq V_{t-1}$  for t > 1 from (a). Accordingly, since  $L(V_{t-1}) \leq 0$  for t > 1 due to Corollary 11.2.1(p.57) (a), we have  $L(V_{t-1}) \leq 0$  for  $\tau \geq t > 1$ . Hence, from (12.1.3(p.61)) we have  $V_t = \beta V_{t-1}$  for  $\tau \geq t > 1$ . Thus  $V_\tau = \beta V_{\tau-1} = \cdots = \beta^{\tau-1}V_1$ , i.e.,  $I_\tau^\tau = I_\tau^{\tau-1} = \cdots = I_\tau^1$ , hence  $t_\tau^* = 1$  for  $\tau > 1$ , i.e.,  $\bullet$  d0ITd $_{\tau>1}\langle 1 \rangle_{\parallel}$  (see Preference Rule 8.2.1(p.45)).
  - (c) Let  $\beta \mu < b$ .
- (c1) Let  $\beta = 1 \cdots$  (3), hence s > 0 due to the assumption " $\beta < 1$  or s > 0". Then, from (3), (1), (2) we have  $(\lambda \beta \mu s)/\delta = \mu s \cdots$  (4). In addition, since  $x_L = x_K \cdots$  (5) from Lemma 11.2.3(p.58) (b), we have  $K(x_L) = K(x_K) = 0 \cdots$  (6).
- (c1i) Let  $\mu s \le a$ . Then  $x_L = x_K = \mu s = V_1$  from (5), Lemma 11.2.2(p.57) (j2), (4), and (7.4.1(p.41)). Accordingly, since  $x_L \le V_{t-1}$  for t > 1 from (a), we have  $L(V_{t-1}) \le 0$  for t > 1 due to Lemma 11.2.1(p.57) (e1). Hence, for the same reason as in the proof of (b) we obtain  $\bullet dOITd_{\tau>1}\langle 1 \rangle$ .
- (c1ii) Let  $\mu s > a$ . Then  $x_L = x_K > \mu s = V_1 > a$  from (5) and Lemma 11.2.2(p.57) (j2), hence  $a < V_{t-1}$  for t > 1 from (a). Suppose  $V_{t-1} < x_L$ , hence  $L(V_{t-1}) > 0$  from Lemma 11.2.1(p.57) (e1). Then, from (12.1.2(p.61)), Lemma 11.2.2(p.57) (g), and (5) we have  $V_t < K(x_L) + x_L = K(x_K) + x_L = x_L$ . Accordingly, by induction  $V_{t-1} < x_L$  for t > 1, hence  $L(V_{t-1}) > 0$  for t > 1 due to Corollary 11.2.1(p.57) (a). Thus, for the same reason as in the proof of Tom 12.2.1(p.61) (b) we have superior (superior (superior
  - (c2) Let  $\beta < 1$  and s = 0 (s > 0).
- (c2i) Let b > 0 ( $\kappa > 0$ ). Then  $x_L > x_K > 0 \cdots$  (7) from Lemma 11.2.3(p.58) (c (d)). Now, since  $x_K \ge \beta \mu s$  due to Lemma 11.2.2(p.57) (j2), (1), and (2), we have  $x_K \ge V_1$  from (7.4.1(p.41)). Suppose  $x_K \ge V_{t-1}$ . Then, from (7.4.2(p.41)) and Lemma 11.2.2(p.57) (e) we have  $V_t \le \max\{K(x_K) + x_K, \beta x_K\} = \max\{x_K, \beta x_K\} = x_K$  due to (7). Accordingly, by induction  $V_{t-1} \le x_K$  for t > 1, hence  $V_{t-1} < x_L$  for t > 1 from (7), thus  $L(V_{t-1}) > 0$  for t > 1 due to Corollary 11.2.1(p.57) (a). Hence, for the same reason as in the proof of Tom 12.2.1(p.61) (b) we have  $suppose v_K \ge V_{t-1}$ .
  - (c2ii) Let b = 0 ( $\kappa = 0$ ). Then  $x_L = x_K \cdots$  (8) from Lemma 11.2.3(p.58) (c (d)).
- (c2ii1) Let  $\beta\mu s \leq a$ . Then,  $x_K = \beta\mu s = V_1$  from Lemma 11.2.2(p.57) (j2). Suppose  $V_{t-1} = x_K$ , hence  $V_{t-1} = x_L$  from (8), so  $L(V_{t-1}) = L(x_L) = 0$ . Then, from (12.1.2(p.61)) we have  $V_t = K(x_K) + x_K = x_K$ . Accordingly, by induction  $V_{t-1} = x_K$  for t > 1, hence  $V_{t-1} = x_L$  for t > 1 due to (8). Then, since  $L(V_{t-1}) = L(x_L) = 0$  for t > 1, we have  $V_t = \beta V_{t-1}$  for t > 1 from (12.1.3(p.61)), hence, for the same reason as in the proof of (b) we obtain  $\bullet$  d0ITd $_{\tau > 1}(1)$ .
- (c2ii2) Let  $\beta\mu s > a$ . Then, since  $V_1 > a$  from (7.4.1(p.41)), we have  $V_{t-1} > a$  for t > 1 due to (a). In addition, we have  $x_K > \beta\mu s = V_1$  from Lemma 11.2.2(p.57) (j2). Suppose  $x_K > V_{t-1}$ , hence  $x_L > V_{t-1}$  from (8). Then, since  $L(V_{t-1}) > 0$  due to Corollary 11.2.1(p.57) (a), from (12.1.2(p.51)) and Lemma 11.2.2(p.57) (g) we have  $V_t < K(x_K) + x_K = x_K$ . Hence, by induction  $x_K > V_{t-1}$  for t > 1, so  $x_L > V_{t-1}$  for t > 1 due to (8). Accordingly, since  $L(V_{t-1}) > 0$  for t > 1 due to Corollary 11.2.1(p.57) (a), for the same reason as in the proof of (c1ii) we have  $\mathbb{S}$  dolls  $\mathbf{v} = \mathbf{v} = \mathbf{v}$ 
  - (c2iii) Let b < 0 ( $\kappa < 0$ ). Then  $x_L < x_K \cdots$  (9) from Lemma 11.2.3(p.58) (c (d)).

(c2iii1) Let  $\beta\mu - s \leq a$  or  $s_{\mathcal{L}} \leq s$ . First let  $\beta\mu - s \leq a$ . Then, since  $x_K = \beta\mu - s = V_1$  from Lemma 11.2.2(p.57) (j2), we have  $x_L < V_1$  from (9), hence  $x_L \leq V_1$ . Next, let  $s_{\mathcal{L}} \leq s$ . Then, since  $x_L \leq \beta\mu - s$  due to Lemma 11.2.4(p.59) (c), we have  $x_L \leq V_1$ . Accordingly, whether  $\beta\mu - s \leq a$  or  $s_{\mathcal{L}} \leq s$ , we have  $x_L \leq V_1$ , thus  $x_L \leq V_{t-1}$  for t > 1 due to (a). Hence, since  $L(V_{t-1}) \leq 0$  for t > 1 from Corollary 11.2.1(p.57) (a), for the same reason as in the proof of (b) we obtain  $\bullet$  d0ITd $_{\tau}\langle 1 \rangle_{\parallel}$  for  $\tau > 1$ .

(c2iii2) Let  $\beta\mu - s > a \cdots$  (10) and  $s < s_{\mathcal{L}}$ . Then, from (9) and Lemma 11.2.4(p.59) (c) we have  $x_K > x_L > \beta\mu - s = V_1 \cdots$  (11), hence  $K(V_1) > 0 \cdots$  (12) from Lemma 11.2.2(p.57) (j1). In addition, since  $V_1 > a$  due to (10), we have  $V_{t-1} > a$  for t > 0 from (a). Now, from (12.1.4(p.51)) and (12) we have  $V_2 - V_1 > 0$ , i.e.,  $V_2 > V_1$ . Suppose  $V_{t-1} < V_t$ . Then, from Lemma 11.2.2(p.57) (g) we have  $V_t < \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Accordingly, by induction  $V_{t-1} < V_t$  for t > 1, i.e.,  $V_t$  is strictly increasing in t > 0. Note that  $V_1 < x_L$  due to (11). Assume that  $V_{t-1} < x_L$  for all t > 1, hence  $V \le x_L$  due to (a). Then, from (9) and from  $V \ge x_K$  due to (a) we have the contradiction of  $V \ge x_K > x_L \ge V$ . Hence, it is impossible that  $V_{t-1} < x_L$  for all t > 1, implying that there exists  $t_{\tau}^* > 1$  such that

$$V_1 < V_2 < \dots < V_{t_{\tau}^{\bullet} - 1} < x_L \le V_{t_{\tau}^{\bullet}} < V_{t_{\tau}^{\bullet} + 1} < V_{t_{\tau}^{\bullet} + 2} < \dots,$$

from which

$$V_{t-1} < x_L, \quad t_{\tau}^{\bullet} \ge t > 1, \qquad x_L \le V_{t-1}, \quad t > t_{\tau}^{\bullet}.$$
 (12.2.1)

Therefore, from Corollary 11.2.1(p.57) (a) we have

$$L(V_{t-1}) > 0 \cdots (13), \quad t_{\tau}^{\bullet} \ge t > 1, \qquad L(V_{t-1}) \le 0 \cdots (14), \quad t > t_{\tau}^{\bullet}.$$

- 1. Let  $t_{\tau}^{\bullet} \geq \tau > 1$ . Then, since  $L(V_{t-1}) > 0 \cdots (15)$  for  $\tau \geq t > 1$  from (13), for the same reason as in the proof of (c1ii) we have  $\boxed{\$ \text{ dOITs}}_{t_{\tau}^{\bullet} \geq \tau > 1} \langle \tau \rangle_{\blacktriangle}$  and  $\text{CONDUCT}_{\tau \geq t > 1}_{\blacktriangle}$ . Hence  $S_1(1)$  is true.
- 2. Let  $\tau > t^{\bullet}_{\tau}$ . First, let  $\tau \geq t > t^{\bullet}_{\tau}$ . Then, since  $L(V_{t-1}) \leq 0$  for  $\tau \geq t > t^{\bullet}_{\tau}$  from (14), we have  $V_t = \beta V_{t-1}$  for  $\tau \geq t > t^{\bullet}_{\tau}$  from (12.1.3(p.61)), thus

$$V_{\tau} = \beta V_{\tau-1} = \beta^2 V_{\tau-2} = \dots = \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} \cdots$$
 (16).

Next let  $t_{\tau}^{\bullet} \geq t > 1$ . Then, from (13) and (12.1.1(p.61)) we have  $V_t - \beta V_{t-1} > 0$  for  $t_{\tau}^{\bullet} \geq t > 1$ , i.e.,  $V_t > \beta V_{t-1}$  for  $t_{\tau}^{\bullet} \geq t > 1$ , hence

$$V_{t_{\tau}^{\bullet}} > \beta V_{t_{\tau}^{\bullet}-1} > \beta^2 V_{t_{\tau}^{\bullet}-2} > \dots > \beta^{t_{\tau}^{\bullet}-1} V_1 \cdots (17).$$

From (16) and (17) we have

$$V_{\tau} = \beta V_{\tau-1} = \beta^2 V_{\tau-2} = \dots = \beta^{\tau - t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} > \beta^{\tau - t_{\tau}^{\bullet} + 1} V_{t_{\tau}^{\bullet} - 1} > \beta^{\tau - t_{\tau}^{\bullet} + 2} V_{t_{\tau}^{\bullet} - 2} > \dots > \beta^{\tau - 1} V_{1},$$

hence we obtain  $t_{\tau}^* = t_{\tau}^{\bullet}$ , i.e.,  $\boxed{\odot \text{ ndOIT}_{\tau > t_{\tau}^{\bullet}} \langle t_{\tau}^{\bullet} \rangle}_{\parallel}$  due to Preference Rule 8.2.1(p.45). In addition, we have Conduct<sub>t.</sub> for  $t_{\tau}^{\bullet} \geq t > 1$  due to (13) and (12.1.5(p.61)). Hence  $S_1(2)$  is true.

**Definition 12.2.2** (model-migration) If " $\boxed{\text{@dOITs}_{\tau>1}\langle\tau\rangle}$  and  $\texttt{CONDUCT}_{\tau\geq t>1}$  " holds in M:1[ $\mathbb{R}$ ][A], then the search is not skipped over  $\tau\geq t>1$ , implying that the model M:1[ $\mathbb{R}$ ][A] is substantively reduced to the model in which the search is enforced over  $\tau\geq t>1$ , i.e. , M:1[ $\mathbb{R}$ ][E]. We refer to this event as "M:1[ $\mathbb{R}$ ][A] migrates over to M:1[ $\mathbb{R}$ ][E] ", represented as

$$\mathsf{M}:1[\mathbb{R}][\mathsf{A}] \hookrightarrow \mathsf{M}:1[\mathbb{R}][\mathsf{E}].$$

# 12.3 Structure of Assertion System $\mathscr{A}\{M:1[\mathbb{R}][A]\}$

In this section we clarify the structure of the assertion system  $\mathscr{A}\{M:1[\mathbb{R}][A]\}$  (see Def. 12.2.1(p.61)). It will be known later on that its structure will play an essential role in the discussions in Step 6 (p.78).

## 12.3.1 Breakdown and Aggregation

Before proceeding with our discussions, let us define the following two perspectives (see Figure 12.3.1(p.64) below (k=3)).

(I) The breakdown of a given set  $\mathscr{X}$  into k mutually disjoint subsets  $\mathscr{X}_1, \mathscr{X}_2, \cdots$ , and  $\mathscr{X}_k$  (k > 0), i.e.,

$$\mathscr{X} = \mathscr{X}_1 \cup \mathscr{X}_2 \cup \cdots \cup \mathscr{X}_k$$
 where  $\mathscr{X}_i \cap \mathscr{X}_i = \emptyset$  for any  $i \neq j$ .

This is called the *breakdown scenario*, represented as  $\mathscr{X} \Rightarrow \{\mathscr{X}_1, \mathscr{X}_2, \cdots, \mathscr{X}_k\}$ .

(II) The aggregation of k mutually disjoint subsets  $\mathscr{X}'_1, \mathscr{X}'_2, \cdots$ , and  $\mathscr{X}'_k$  (k>0) of a given set  $\mathscr{X}$ , i.e.,

$$\mathscr{X}' \stackrel{\text{def}}{=} \mathscr{X}'_1 \cup \mathscr{X}'_2 \cup \cdots \cup \mathscr{X}'_k \subseteq \mathscr{X} \text{ where } \mathscr{X}'_i \cap \mathscr{X}'_i = \emptyset \text{ for any } i \neq j.$$

This is called the *aggregation scenario*, represented as  $\{\mathscr{X}'_1, \mathscr{X}'_2, \cdots, \mathscr{X}'_k\} \Rightarrow \mathscr{X}'$ .  $\square$ 

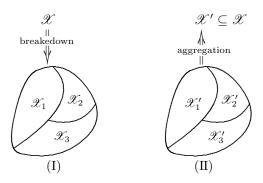


Figure 12.3.1: Breakdown and aggregation

# 12.3.2 Structure of Assertion $A\{M:1[\mathbb{R}][A]\}$

## 12.3.2.1 Condition-Space $\mathscr{C}\langle A \rangle$

In general, any given assertion  $A\{M:1[\mathbb{R}][A]\}$  consists of a statement S and a condition-expression CE, schematized as

$$A\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\} = \{\mathsf{S} \text{ holds if } \mathsf{CE} \text{ is satisfied}\}. \tag{12.3.1}$$

 $\square$  Example 12.3.1 The assertion given by Tom 12.2.2(p.62) (b) can be rewritten as

$$A\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}=\{ \bullet \mathsf{dOITd}_{\tau>1}\langle 1\rangle_{\parallel} \text{ holds if } \beta\mu\geq b \text{ is satisfied} \}$$

where  $S = \{ \boxed{\bullet dOITd_{\tau > 1} \langle 1 \rangle}_{\parallel} \}$  and  $CE = \{ \beta \mu \geq b \}$ .

Then, in general, the condition-expression CE is given as a conditional on a parameter vector p and a distribution function F where

$$oldsymbol{p} \in \mathscr{P}_{A} \subseteq \mathscr{P},$$
 $F \in \mathscr{F}_{A|oldsymbol{p}} \subseteq \mathscr{F}$ 

for a given parameter space  $\mathscr{P}_A \subseteq \mathscr{P}$  (see (4.3.1(p.2l)) and (4.3.2(p.2l))) and a given distribution function space  $\mathscr{F}_{A|p} \subseteq \mathscr{F}$  (see (2.2.5(p.13))) related to a given  $p \in \mathscr{P}_A$ . Then (12.3.1(p.6l)) can be rewritten as

$$A\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\} = \{\mathsf{S} \text{ holds for } \boldsymbol{p} \in \mathscr{P}_{\mathsf{A}} \subseteq \mathscr{P} \text{ and } F \in \mathscr{F}_{\mathsf{A}|\boldsymbol{p}} \subseteq \mathscr{F}\}. \tag{12.3.2}$$

 $\square$  For the assertion A given by Tom 12.2.2(p.62) (c1i) we have

$$\begin{split} \mathscr{P}_{\!A} \; &= \; \{ \boldsymbol{p} \; \big| \; \lambda = 1 \cap \beta = 1 \cap s > 0 \},^{\dagger} \\ \mathscr{F}_{\!A|\boldsymbol{p}} \; &= \; \{ F \; \big| \; \beta \mu < b \cap \mu - s \leq a \}. \end{split}$$

 $\square$  For the assertion A given by Tom 12.2.2(p.62) (c2iii2) we have

$$\begin{split} \mathscr{P}_{\!\!A} \; &= \; \{ \boldsymbol{p} \; \big| \; \lambda = 1 \cap \beta < 1 \cap \; s = 0 \, (\!(s > 0\!)\!) \, \}, \\ \mathscr{F}_{\!\!A|\boldsymbol{p}} \; &= \; \{ F \; \big| \; \beta \mu < b \cap \; b < 0 \, (\!(\kappa < 0\!)\!) \; \cap \beta \mu - s > a \cap s < \; s_{\mathcal{L}} \, \}. \end{split}$$

Here let us define

$$\mathscr{C}\langle A \rangle \stackrel{\text{def}}{=} \{ (\boldsymbol{p}, F) \mid \boldsymbol{p} \in \mathscr{P}_A \subseteq \mathscr{P}, F \in \mathscr{F}_{A|\boldsymbol{p}} \subseteq \mathscr{F} \}, \tag{12.3.3}$$

called the *condition-space* of a given assertion  $A\{M:1[\mathbb{R}][A]\}$ . Then, (12.3.2[p.64]) can be rewritten as

$$A\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\} = \{\mathsf{S} \text{ holds on } \mathscr{C}\langle A\rangle \}. \tag{12.3.4}$$

Throughout the rest of the paper, for explanatory convenience, let us alternatively express the whole of (12.3.4[p.64]) as

$$A\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\} \text{ holds on } \mathscr{C}\langle A\rangle. \tag{12.3.5}$$

<sup>&</sup>lt;sup>†</sup>When  $\beta = 1$ , we have s > 0 due to the assumption " $\beta < 1$  or s > 0".

#### 12.3.2.2 Structure of Tom

#### Definition 12.3.1

- (a) We sometimes represent Tom 12.2.1(p.61) and Tom 12.2.2(p.62) by "Tom" for short, removing "12.2.1" and "12.2.2".
- (b) To discriminate multiple Tom's we sometimes use  $Tom_1$ ,  $Tom_2$ ,  $\cdots$ . For example,  $Tom_1 = Tom 12.2.1(p.61)$  and  $Tom_2 = Tom 12.2.2(p.62)$ .
- (c) In order to stress that an assertion  $A\{M:1[\mathbb{R}][A]\}$  is included in a given Tom, i.e.,  $A\{M:1[\mathbb{R}][A]\} \in Tom$ , let us represent it as  $A_{Tom}\{M:1[\mathbb{R}][A]\}$  and an assertion system consisting of all  $A_{Tom}\{M:1[\mathbb{R}][A]\}$  as  $\mathscr{A}_{Tom}\{M:1[\mathbb{R}][A]\}$ .  $\square$

Then (12.3.2(p.64))-(12.3.5(p.64)) can be rewritten as respectively

$$A_{\mathsf{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\} = \{\mathsf{S} \text{ holds for } \boldsymbol{p} \in \mathscr{P}_{A_{\mathsf{Tom}}} \subseteq \mathscr{P} \text{ and } F \in \mathscr{F}_{A_{\mathsf{Tom}}|\boldsymbol{p}} \subseteq \mathscr{F}\}, \tag{12.3.6}$$

$$\mathscr{C}\langle A_{\mathtt{Tom}}\rangle \ \stackrel{\mathrm{def}}{=} \ \{(\boldsymbol{p},F) \mid \boldsymbol{p} \in \mathscr{P}_{A_{\mathtt{Tom}}} \subseteq \mathscr{P}, F \in \mathscr{F}_{A_{\mathtt{Tom}}|\boldsymbol{p}} \subseteq \mathscr{F}\}, \tag{12.3.7}$$

$$A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbf{A}]\} = \{\mathsf{S} \text{ holds on } \mathscr{C}\langle A_{\text{Tom}}\rangle \}, \tag{12.3.8}$$

$$A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\} \text{ holds on } \mathscr{C}\langle A_{\text{Tom}}\rangle.$$
 (12.3.9)

Closely looking into the structure of Tom 12.2.1(p.61) and Tom 12.2.2(p.62), in general, we see that a given Tom consists of a basic-premise BP and some assertions  $A_{\text{Tom}}^1$ ,  $A_{\text{Tom}}^2$ ,  $\cdots$ , i.e.,

 $\mathtt{Tom} = \{ \mathtt{Let} \ \mathsf{BP} \ \mathsf{be} \ \mathsf{true}. \ \mathsf{Then} \ \mathsf{assertions} \ A^1_{\mathtt{Tom}}, \ A^2_{\mathtt{Tom}}, \cdots \ \mathsf{hold.} \}$ 

or equivalently

$$Tom = \{Assertions \ A_{Tom}^1, \ A_{Tom}^2, \cdots \text{ hold if BP be true.}\}$$
 (12.3.10)

in which the basic-premise BP is given as a conditional on a parameter vector  $\boldsymbol{p}$  and a distribution function F where

$$m{p} \in \mathscr{P}_{\mathsf{Tom}} \subseteq \mathscr{P},$$

$$F \in \mathscr{F}_{\mathsf{Tom}|\mathbf{p}} \subseteq \mathscr{F} \tag{12.3.11}$$

for given subsets  $\mathscr{P}_{\mathtt{Tom}} \subseteq \mathscr{P}$  and  $\mathscr{F}_{\mathtt{Tom}|p} \subseteq \mathscr{F}$ . Then the basic-premise  $\mathsf{BP}$  can be written as

$$\mathsf{BP} \ = \ \{ \mathsf{a} \ \mathsf{condition} \ \mathsf{on} \ \boldsymbol{p} \in \mathscr{P}_{\mathsf{Tom}} \subseteq \mathscr{P} \ \mathsf{and} \ F \in \mathscr{F}_{\mathsf{Tom}|\boldsymbol{p}} \subseteq \mathscr{F} \}. \tag{12.3.12}$$

 $\square$  Example 12.3.2 For M:1[ $\mathbb{R}$ ][A] we have

$$\begin{split} \mathscr{P}_{\mathsf{Tom}} &= \{ \boldsymbol{p} \mid \lambda = 1 \cap \beta = 1 \cap s = 0 \} \\ \mathscr{P}_{\mathsf{Tom}} &= \{ \boldsymbol{p} \mid \lambda = 1 \cap (\beta < 1 \cup s > 0) \} \end{split} \qquad \text{for Tom } 12.2.2 \text{(p.61)} \\ \mathscr{F}_{\mathsf{Tom} \mid \boldsymbol{p}} &= \mathscr{F} \\ \mathscr{F}_{\mathsf{Tom} \mid \boldsymbol{p}} &= \mathscr{F} \end{aligned} \qquad \text{for Tom } 12.2.2 \text{(p.62)} \\ \mathscr{F}_{\mathsf{Tom} \mid \boldsymbol{p}} &= \mathscr{F} \end{aligned} \qquad \text{for Tom } 12.2.2 \text{(p.62)} \\ \mathscr{F}_{\mathsf{Tom} \mid \boldsymbol{p}} &= \mathscr{F} \end{aligned}$$

For  $M:2[\mathbb{R}][A]$  in Section 22.1.4(p.162) we have

$$\begin{split} \mathscr{P}_{\mathsf{Tom}} &= \{ \boldsymbol{p} \mid \lambda \leq 1 \cap \beta = 1 \cap s = 0 \cap -\infty < \rho < \infty \} & \text{for Tom } 22.1.1 \text{(p.163)} \\ \mathscr{P}_{\mathsf{Tom}} &= \{ \boldsymbol{p} \mid \lambda \leq 1 \cap (\beta < 1 \cup s > 0) \cap -\infty < \rho < \infty \} & \text{for Tom } 22.1.2 \text{(p.163)} \\ \mathscr{P}_{\mathsf{Tom}} &= \{ \boldsymbol{p} \mid \lambda \leq 1 \cap (\beta < 1 \cup s > 0) \cap -\infty < \rho < \infty \} & \text{for Tom } 22.1.3 \text{(p.166)} \\ \mathscr{P}_{\mathsf{Tom}} &= \{ \boldsymbol{p} \mid \lambda \leq 1 \cap (\beta < 1 \cup s > 0) \cap -\infty < \rho < \infty \} & \text{for Tom } 22.1.4 \text{(p.166)} \\ \mathscr{F}_{\mathsf{Tom}|\boldsymbol{p}} &= \{ F \mid -\infty < a < \mu < b < \infty \} = \mathscr{F} & \text{for Tom } 22.1.1 \text{(p.163)} \\ \mathscr{F}_{\mathsf{Tom}|\boldsymbol{p}} &= \{ F \mid F \in \mathscr{F} \cap \rho < x_K \} & \text{for Tom } 22.1.2 \text{(p.163)} \\ \mathscr{F}_{\mathsf{Tom}|\boldsymbol{p}} &= \{ F \mid F \in \mathscr{F} \cap \rho = x_K \} & \text{for Tom } 22.1.3 \text{(p.166)} \\ \mathscr{F}_{\mathsf{Tom}|\boldsymbol{p}} &= \{ F \mid F \in \mathscr{F} \cap \rho > x_K \} & \text{for Tom } 22.1.4 \text{(p.166)} \end{split}$$

#### 12.3.2.3 Condition Space $\mathscr{C}\langle \mathsf{Tom}\rangle$

For a given Tom let us define

$$\mathscr{C}\langle \mathsf{Tom} \rangle \stackrel{\text{def}}{=} \{ (\boldsymbol{p}, F) \mid \boldsymbol{p} \in \mathscr{P}_{\mathsf{Tom}} \subseteq \mathscr{P}, F \in \mathscr{F}_{\mathsf{Tom} \mid \boldsymbol{p}} \subseteq \mathscr{F} \}, \tag{12.3.13}$$

called the *condition space* of Tom. Then (12.3.12(p.65)) can be rewritten as

$$\mathsf{BP} = \{ \text{a condition on } \mathscr{C} \langle \mathsf{Tom} \rangle \}, \tag{12.3.14}$$

hence (12.3.10(p.65)) can be rewritten as

$$Tom = \{Assertions A_{Tom}^1, A_{Tom}^2, \cdots \text{ hold on BP}\},$$
 (12.3.15)

alternatively as

$$Tom = \{Assertions A_{Tom}^1, A_{Tom}^2, \cdots \text{ hold on } \mathscr{C}(Tom)\}.$$
 (12.3.16)

Moreover, for explanatory convenience, we will sometimes express the event " $A_{\text{Tom}}$  and  $A_{\text{Tom}}^j$  are included in Tom" as " $A_{\text{Tom}} \in \text{Tom}$ " and  $A_{\text{Tom}}^j \in \text{Tom}$ ".

# 12.3.3 Construction of Assertion System $\mathscr{A}\{M:1[\mathbb{R}][A]\}$

#### 12.3.3.1 Completeness of Tom on $\mathscr{C}\langle \mathsf{Tom}\rangle$

(12.3.16(p.65)) means that assertions  $A_{\text{Tom}}^1$ ,  $A_{\text{Tom}}^2$ ,  $\cdots$  included in Tom are all over all possible parameters  $(p, F) \in \mathcal{C}(\text{Tom})$ . In this paper we refer to this fact as the *completeness* of Tom on  $\mathcal{C}(\text{Tom})$ .

#### 12.3.3.2 Breakdown of $\mathscr{C}\langle Tom \rangle$

Let us note here that the completeness of Tom is not what should be proven but what is given as a requirement; in other words, the breakdown of the condition space  $\mathscr{C}\langle \mathsf{Tom}\rangle$  to the condition spaces  $\mathscr{C}\langle A^1_{\mathsf{Tom}}\rangle$ ,  $\mathscr{C}\langle A^2_{\mathsf{Tom}}\rangle$ ,  $\cdots$  is given as a priori requirement. This scenario can be described as the expression below.

$$\mathscr{C}\langle \mathsf{Tom}\rangle = \cup_{j=1,2,\cdots} \mathscr{C}\langle A^j_{\mathsf{Tom}}\rangle = \cup_{A_{\mathsf{Tom}}\in \mathsf{Tom}} \mathscr{C}\langle A_{\mathsf{Tom}}\rangle, \tag{12.3.17}$$

depicted as in Figure 12.3.2(p.66) below.

$$\begin{array}{c} \mathscr{C}\langle\mathsf{Tom}\rangle \\ & \text{ } \\ \mathsf{breakedown} \\ & \bigvee \\ \\ \left(\mathscr{C}\langle A^1_\mathsf{Tom}\rangle, \ \mathscr{C}\langle A^2_\mathsf{Tom}\rangle \ \mathscr{C}\langle A^3_\mathsf{Tom}\rangle \right) \end{array}$$

Figure 12.3.2: Breakedown of  $\mathscr{C}\langle \mathsf{Tom}\rangle$  to  $\mathscr{C}\langle A^1_{\mathsf{Tom}}\rangle$ ,  $\mathscr{C}\langle A^2_{\mathsf{Tom}}\rangle$ ,  $\mathscr{C}\langle A^3_{\mathsf{Tom}}\rangle$ 

### 12.3.3.3 Construction of $\mathscr{A}_{Tom} \{M:1[\mathbb{R}][A]\}$

Consider the list of (12.3.9(p.65)) over Tom, i.e.,  $A_{\text{Tom}}^1, A_{\text{Tom}}^2, \dots \in \text{Tom}$ , or equivalently

$$\begin{tabular}{ll} ``A^1_{\tt Tom}\{{\sf M}{:}1[\mathbb{R}][\mathbb{A}]\} \ \mbox{holds on} \ \mathscr{C}\langle A^1_{\tt Tom}\rangle \ ", \\ ``A^2_{\tt Tom}\{{\sf M}{:}1[\mathbb{R}][\mathbb{A}]\} \ \mbox{holds on} \ \mathscr{C}\langle A^2_{\tt Tom}\rangle \ ", \\ \vdots \ \end{tabular}$$

Then, gathering the above list with noting (12.3.17(p.66)), we get

$$\mathscr{A}_{\mathsf{Tom}}\left\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\right\} \text{ holds on } \mathscr{C}\langle\mathsf{Tom}\rangle$$
 (12.3.18)

where

$$\mathscr{A}_{\mathsf{Tom}}\left\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\right\} \stackrel{\mathsf{def}}{=} \left\{A^1_{\mathsf{Tom}}\left\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\right\}, A^2_{\mathsf{Tom}}\left\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\right\}, \cdots\right\}. \tag{12.3.19}$$

#### 12.3.3.4 Condition-Space $\mathscr{C}\langle \mathcal{T}om \rangle$

For explanatory convenience, let us represent  $Tom\ 12.2.1(p.61)$  and  $Tom\ 12.2.2(p.62)$  by  $Tom_1$  and  $Tom_2$  respectively; in general, let  $Tom_1, Tom_2, \cdots$ . Then, let us define

$$\mathcal{T}$$
om  $\stackrel{\text{def}}{=} \{ \texttt{Tom}_1, \texttt{Tom}_2, , \cdots \} = \{ \texttt{Tom} \}.$ 

 $\square$  Example 12.3.3 For example we have

$$\begin{split} \mathcal{T}\text{om} \;\; &= \; \big\{ \text{Tom}_1 = \text{Tom} \;\; 12.2.1 \text{(p.61)} \;, \\ \text{Tom} \;\; &= \; \big\{ \text{Tom}_1 = \text{Tom} \;\; 22.1.1 \text{(p.163)} \;, \\ \text{Tom} \;\; &= \; \big\{ \text{Tom}_1 = \text{Tom} \;\; 22.1.1 \text{(p.163)} \;, \\ \text{Tom}_2 = \text{Tom} \;\; 22.1.2 \text{(p.163)} \;, \\ \text{Tom}_3 = \text{Tom} \;\; 22.1.3 \text{(p.166)} \;, \\ \text{Tom}_4 = \text{Tom} \;\; 22.1.4 \text{(p.166)} \; \big\}. \end{split}$$

Here let us define

$$\mathscr{C}\langle \mathsf{Tom}\rangle \stackrel{\text{def}}{=} \cup_{i=1,2,\dots} \mathscr{C}\langle \mathsf{Tom}_i\rangle = \cup_{\mathsf{Tom}\in\mathcal{T}_{\mathsf{om}}} \mathscr{C}\langle \mathsf{Tom}\rangle, \tag{12.3.20}$$

called the condition space of Tom, schematized as in Figure 12.3.3(p.67) below.

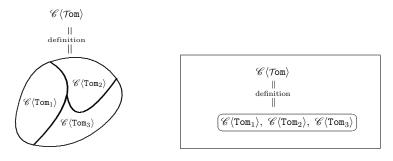


Figure 12.3.3: Condition space  $\mathscr{C}\langle \mathcal{T}om \rangle$ 

For convenience of discussions that follows, as one corresponding to (12.3.10(p.65)), let us define, for  $i=1,2,\cdots$ ,

$$Tom_{i} = \{Assertions A^{1}_{Tom_{i}}, A^{2}_{Tom_{i}}, \cdots \text{ hold on } \mathscr{C}\langle Tom \rangle_{i} \}.$$

$$(12.3.21)$$

#### 12.3.3.5 Construction of $\mathscr{A}\{M:1[\mathbb{R}][A]\}$

Using (12.3.17(p.66)), we can express (12.3.20(p.66)) as below

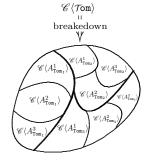
$$\mathscr{C}\langle \mathcal{T}om \rangle = \bigcup_{i=1,2,\cdots} \bigcup_{j=1,2,\cdots} \mathscr{C}\langle A^j_{\mathsf{Tom}_i} \rangle \tag{12.3.22}$$

$$= \cup_{\mathsf{Tom} \in \mathcal{T}_{\mathsf{om}}} \cup_{j=1,2,\cdots} \mathscr{C} \langle A^{j}_{\mathsf{Tom}} \rangle \tag{12.3.23}$$

$$= \cup_{\mathsf{Tom} \in \mathcal{T}_{\mathsf{Om}}} \cup_{A_{\mathsf{Tom}} \in \mathsf{Tom}} \mathscr{C} \langle A_{\mathsf{Tom}} \rangle \tag{12.3.24}$$

This relation implies the *breakdown* of  $\mathscr{C}\langle \mathsf{Tom}\rangle$  into  $\mathscr{C}\langle A^j_{\mathsf{Tom}_i}\rangle \, / \, \mathscr{C}\langle A^j_{\mathsf{Tom}}\rangle \, / \, \mathscr{C}\langle A_{\mathsf{Tom}}\rangle$ .

Then, fetching Figure 12.3.2(p.66) in Figure 12.3.3(p.67) with noting (12.3.22(p.67)) produces Figure 12.3.4(p.67) below, which is the breakdown of  $\mathscr{C}\langle \mathcal{T}om \rangle$  into  $\mathscr{C}\langle A^j_{\mathsf{Tom}_i} \rangle$ .



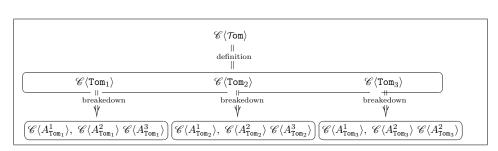


Figure 12.3.4: Breakdown of  $\mathscr{C}\langle \mathsf{Tom}\rangle$  into  $\mathscr{C}\langle A^j_{\mathsf{Tom}_i}\rangle$ , i,j=1,2,3

Figure 12.3.4(p.67) above implies that first

" 
$$[\mathscr{C}(Tom)]$$
 is broken down to  $[\mathscr{C}(Tom_i)]$ ,  $i = 1, 2, 3$ ", by definition

and then

" each 
$$\boxed{\mathscr{C}\langle \mathtt{Tom}_i\rangle}\!,\,i=1,2,3$$
 is broken down to  $\boxed{\mathscr{C}\langle A^j_{\mathtt{Tom}_i}\rangle}\!,\,i,j=1,2,3.$  "

The above two successive breakdown procedures eventually yields

" 
$$\boxed{\mathscr{C}\langle \mathcal{T}\mathtt{om}\rangle}$$
 is broken down to  $\boxed{\mathscr{C}\langle A^j_{\mathtt{Tom}_i}\rangle}$  for  $i,j=1,2,3$  ",

more generally

" 
$$[\mathscr{C}\langle \mathcal{T}om \rangle]$$
 is broken down to  $[\mathscr{C}\langle A_{\mathsf{Tom}} \rangle]$ "

Here, consider the list of (12.3.18(p.66)) over  $\mathtt{Tom}_1,\mathtt{Tom}_2,,\dots\in\mathcal{T}\mathtt{om}=\{\mathtt{Tom}_1,\mathtt{Tom}_2,\dots\},$  i.e.,

$$\text{``$\mathcal{A}_{\mathtt{Tom}_1}$ } \{\mathsf{M}{:}1[\mathbb{R}][\mathtt{A}]\} \text{ holds on $\mathscr{C}$} \langle \mathtt{Tom}_1 \rangle \text{ ''}.$$

$$\text{``$\mathcal{A}_{\mathtt{Tom}_2}$ $\{M$:$1[\mathbb{R}][\mathbb{A}]$} \text{ holds on $\mathscr{C}$$$\langle$\mathtt{Tom}_2$$\rangle ".}$$

:

Then, gathering the above list with noting (12.3.22(p.67)), we obtain

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\} \text{ holds on } \mathscr{C}\langle \mathcal{T}\mathtt{om}\rangle \tag{12.3.25}$$

where

$$\mathscr{A}\{\mathsf{M}{:}1[\mathbb{R}][\mathtt{A}]\} \stackrel{\mathtt{\tiny def}}{=} \{\mathscr{A}_{\mathtt{Tom}_1}\{\mathsf{M}{:}1[\mathbb{R}][\mathtt{A}]\}, \mathscr{A}_{\mathtt{Tom}_2}\{\mathsf{M}{:}1[\mathbb{R}][\mathtt{A}]\}, \cdots\}.$$

# 12.3.3.6 Completeness of $\mathcal{T}om$ on $\mathscr{C}\langle \mathcal{T}om \rangle = \mathscr{P} \times \mathscr{F}$

Throughout this paper, the condition space  $\mathscr{C}\langle \mathsf{Tom} \rangle$  is constructed so as to equal the total-P/DF-space  $\mathscr{P} \times \mathscr{F}$  (see (4.3.3(p2l))), i.e.,

$$\mathscr{C}\langle \mathsf{Tom}\rangle = \mathscr{P} \times \mathscr{F}. \tag{12.3.26}$$

The equality (12.3.26(p.68)) implies that assertions  $A^j_{\mathtt{Tom}_i}$ ,  $i, j = 1, 2, \cdots$ , raised and discussed there are all over all possible points  $(\boldsymbol{p}, F) \in \mathscr{C}\langle \mathtt{Tom} \rangle = \mathscr{P} \times \mathscr{F}$  (see (12.3.3.1(p.66))).

Remark 12.3.1 (a priori requirement) What should be especially noted here is that this is not what should be proven but what should be satisfied as a priori requirement.  $\Box$ 

The above perspective can be depicted as in Figure 12.3.4(p.67) as below.

$$\begin{split} \mathscr{C}\langle \mathsf{Tom} \rangle &= \mathscr{P} \times \mathscr{F} \\ \text{complete breakedown} \\ & \bigvee \\ \mathscr{C}\langle A_{\mathsf{Tom}_1}^1 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^1 \rangle \\ \mathscr{C}\langle A_{\mathsf{Tom}_1}^2 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^2 \rangle \\ \mathscr{C}\langle A_{\mathsf{Tom}_1}^2 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^2 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^2 \rangle \\ \mathscr{C}\langle A_{\mathsf{Tom}_1}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^2 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle \\ \mathscr{C}\langle A_{\mathsf{Tom}_1}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle \\ & \mathscr{C}\langle A_{\mathsf{Tom}_1}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle \\ & \mathscr{C}\langle A_{\mathsf{Tom}_1}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle \\ & \mathscr{C}\langle A_{\mathsf{Tom}_1}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle \\ & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle \\ & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle \\ & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle \\ & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle \\ & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle \\ & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle \\ & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle \\ & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle \\ & \mathscr{C}\langle A_{\mathsf{Tom}_2}^3 \rangle & \mathscr{C}\langle$$

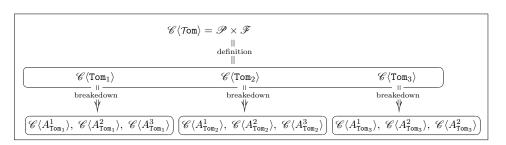


Figure 12.3.5: The complete breakedown of  $\mathscr{C}\langle \mathsf{Tom}\rangle$  to  $\mathscr{C}\langle A^j_{\mathsf{Tom}_i}\rangle$ , i,j=1,2,3

treakdown scenario

# Chapter 13

# Symmetry Theorem $(\mathbb{R} \leftrightarrow \tilde{\mathbb{R}})$

### 13.1 Two Kinds of Equality

### 13.1.1 Correspondence Equality

For  $\boldsymbol{\xi}$ , a,  $\mu$ , b, T(x),  $\cdots$ , which are all dependent on a given distribution function  $F \in \mathscr{F}$  (see (2.2.5(p.13))), let us define  $\hat{\boldsymbol{\xi}} = -\boldsymbol{\xi}$ ,  $\hat{a} = -a$ ,  $\hat{\mu} = -\mu$ ,  $\hat{b} = -b$ ,  $\hat{T}(x) = -T(x)$ ,  $\cdots$  respectively, called the *reflection operation*  $\mathcal{R}$ . Then, for any given distribution function  $F \in \mathscr{F}$ , i.e.,

$$F(\xi) = \Pr\{\xi \le \xi\} \subseteq \mathscr{F},\tag{13.1.1}$$

let us define the distribution function of  $\hat{\boldsymbol{\xi}}$  by  $\check{F}$ , i.e.,

$$\check{F}(\xi) \stackrel{\text{def}}{=} \Pr{\{\hat{\boldsymbol{\xi}} \le \xi\}},\tag{13.1.2}$$

where its probability density function is represented by  $\check{f}$  and the set of all possible  $\check{F}$  is denoted by  $\check{\mathscr{F}}$ , i.e.,

$$\check{\mathscr{F}} \stackrel{\text{def}}{=} \{ \check{F} \mid F \in \mathscr{F} \}. \tag{13.1.3}$$

Now, since  $\check{\check{F}}(\xi) = \Pr\{\hat{\check{\xi}} \leq \xi\}$  for any  $\xi$  due to the definition (13.1.2(p.69)) and since

$$\widehat{\hat{\boldsymbol{\xi}}} = \widehat{-\boldsymbol{\xi}} = -(-\boldsymbol{\xi}) = \boldsymbol{\xi},\tag{13.1.4}$$

we have  $\check{\check{F}}(\xi)=\Pr\{\pmb{\xi}\leq\xi\}=F(\xi) \text{ for any } \xi \text{ due to } (13.1.1 \text{(p.69)}), \text{ i.e.,}$ 

$$\overset{\circ}{F} \equiv F. \tag{13.1.5}$$

For any subset  $\mathscr{F}' \subseteq \mathscr{F}$  let us define

$$\check{\mathscr{F}}' \stackrel{\text{def}}{=} \{ \check{F} \mid F \in \mathscr{F}' \}. \tag{13.1.6}$$

Then we have

$$\check{\tilde{\mathcal{F}}}' = \{\check{F} \mid \check{F} \in \check{\mathcal{F}}'\} = \{F \mid \check{F} \in \check{\mathcal{F}}'\}$$
(13.1.7)

due to (13.1.5(p.69)). If  $F \in \mathscr{F}'$ , then  $\check{F} \in \check{\mathscr{F}}'$  from (13.1.6(p.69)), hence  $F \in \check{\mathscr{F}}'$  due to (13.1.7(p.69)); accordingly, we have  $\mathscr{F}' \subseteq \check{\mathscr{F}}' \cdots (*)$ . If  $F \in \check{\mathscr{F}}'$ , then  $\check{F} \in \check{\mathscr{F}}'$  due to (13.1.7(p.69)), hence  $F \in \mathscr{F}'$  from (13.1.6(p.69)), therefore, we have  $\check{\mathscr{F}}' \subseteq \mathscr{F}'$ . From this and (\*) it follows that

$$\check{\mathscr{F}}'=\mathscr{F}'.$$

By  $\check{a}$ ,  $\check{\mu}$ , and  $\check{b}$  let us denote the lower bound, the expectation, and the upper bound of  $\check{F} \in \mathscr{F}$  corresponding to any given  $F \in \mathscr{F}$  with the lower bound a, the expectation  $\mu$ , and the upper bound b. Then, from Figure 13.1.1(p.70) just below we clearly have, for any  $\xi$ ,

$$f(\xi) = \check{f}(\hat{\xi}),\tag{13.1.8}$$

called the correspondence equality, where

$$\hat{a} = \check{b}, \quad \hat{\mu} = \check{\mu}, \quad \hat{b} = \check{a}.$$
 (13.1.9)

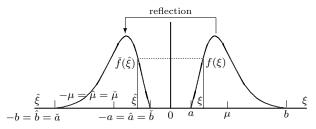


Figure 13.1.1: Relationship between probability density functions f and  $\check{f}$ 

#### 13.1.2 Identity Equality

#### Lemma 13.1.1

- (a)  $\mathscr{F}$  and  $\check{\mathscr{F}}$  are one-to-one correspondent where  $\mathscr{F} = \check{\mathscr{F}}$ .
- (b) For any  $\check{F} \in \check{\mathscr{F}}$  there exists a  $F \in \mathscr{F}$  which is identical to the  $\check{F}$ , i.e.,  $F \equiv \check{F}$ .
- (c) For any  $F \in \mathscr{F}$  there exists a  $\check{F} \in \check{\mathscr{F}}$  which is identical to the F, i.e.,  $\check{F} \equiv F$ .
- Proof If  $F \in \mathscr{F}$ , then  $\check{F} \in \check{\mathscr{F}}$  from (13.1.3(p.69)), hence  $F \in \mathscr{F} \Rightarrow \check{F} \in \check{\mathscr{F}} \cdots$  (1). Conversely, if  $\check{F} \in \check{\mathscr{F}}$ , then F from which  $\check{F} \in \check{\mathscr{F}}$  is defined is clearly an element of  $\mathscr{F}$  due to (13.1.3(p.69)), i.e.,  $F \in \mathscr{F}$ , hence  $\check{F} \in \check{\mathscr{F}} \Rightarrow F \in \mathscr{F} \cdots$  (2).
  - (a) First, for any  $F \in \mathscr{F}$  and for the  $\check{F} \in \check{\mathscr{F}}$  corresponding to the F we have

$$\check{F}(\xi) = \Pr\{\hat{\xi} \le \xi\} = \Pr\{-\hat{\hat{\xi}} \le -\hat{\xi}\} = \Pr\{\hat{\xi} \ge \hat{\xi}\} = \Pr\{\xi \ge \hat{\xi}\} \quad \text{(due to (13.1.4(p.69)))}$$

$$= 1 - \Pr\{\xi < \hat{\xi}\} = 1 - \Pr\{\xi \le \hat{\xi}\}^{\ddagger} = 1 - F(\hat{\xi}) \cdots \textbf{(3)}.$$

Suppose any  $F \in \mathscr{F}$  yields the two different  $\check{F}_1 \in \check{\mathscr{F}}$  and  $\check{F}_2 \in \check{\mathscr{F}}$ , meaning that there exists at least one  $\xi'$  such that  $\check{F}_1(\xi') \neq \check{F}_2(\xi')$ . Then, since  $\check{F}_1(\xi') = 1 - F(\hat{\xi}')$  and  $\check{F}_2(\xi') = 1 - F(\hat{\xi}')$  due to (3), we have the contradiction of  $\check{F}_1(\xi') = \check{F}_2(\xi')$ , hence the  $F \in \mathscr{F}$  must correspond to a *unique*  $\check{F} \in \check{\mathscr{F}}$ .

Next, for any  $\check{F} \in \check{\mathscr{F}}$  and for  $F \in \mathscr{F}$  from which  $\check{F} \in \check{\mathscr{F}}$  is defined we have

$$F(\xi) = \Pr\{\xi \le \xi\} = \Pr\{-\hat{\xi} \le -\hat{\xi}\} = \Pr\{\hat{\xi} \ge \hat{\xi}\} = 1 - \Pr\{\hat{\xi} < \hat{\xi}\} = 1 - \Pr\{\hat{\xi} \le \hat{\xi}\}^{\ddagger} = 1 - \check{F}(\hat{\xi}) \cdots (4).$$

Suppose any  $\check{F} \in \check{\mathscr{F}}$  is yielded from the two different  $F_1 \in \mathscr{F}$  and  $F_2 \in \mathscr{F}$ , meaning that there exists at least one  $\xi'$  such that  $F_1(\xi') \neq F_2(\xi')$ . Then, since  $F_1(\xi') = 1 - \check{F}(\hat{\xi}')$  and  $F_2(\xi') = 1 - \check{F}(\hat{\xi}')$  due to (4), we have the contradiction of  $F_1(\xi') = F_2(\xi')$ , hence the  $\check{F} \in \check{\mathscr{F}}$  must correspond to a unique  $F \in \mathscr{F}$ . Thus, the former half of the assertion is true.

The latter half can be proven as follows. First, consider any  $F \in \tilde{\mathscr{F}}$ . Then, since  $F \in \mathscr{F}$  by definition, we have  $\tilde{\mathscr{F}} \subseteq \mathscr{F} \cdots$  (5). Next, consider any  $F \in \mathscr{F}$ . Then, since  $\check{F} \in \check{\mathscr{F}}$  due to (1), we have  $\check{F} \in \mathscr{F}$  due to (5). Hence  $\check{F} \in \check{\mathscr{F}}$  due to (1(p.70)), so  $F \in \check{\mathscr{F}}$  due to (13.1.5(p.69)), thus we have  $\mathscr{F} \subseteq \mathscr{F}$ . From this and (5) we have  $\check{\mathscr{F}} = \mathscr{F} \cdots$  (6).

- (b) Consider any  $\check{F} \in \mathscr{F}$ , hence  $\check{F} \in \mathscr{F} \cdots (7)$  due to (6). Suppose every  $F \in \mathscr{F}$  is not identical to the  $\check{F}$ , i.e.,  $F \not\equiv \check{F}$ , implying that the  $\check{F}$  lies outside  $\mathscr{F}$ , hence cannot become an element of  $\mathscr{F}$ , i.e.,  $\check{F} \not\in \mathscr{F}$ , which contradicts (7). Hence, it follows that there must exist at least one F such that  $F \equiv \check{F}$ , thus the assertion holds.
- (c) Consider any  $F \in \mathscr{F}$ , hence  $F \in \mathscr{\tilde{F}} \cdots$  (8) due to (6). Suppose every  $\check{F} \in \mathscr{\tilde{F}}$  is not identical to the F, i.e.,  $\check{F} \not\equiv F$ , implying that the F lies outside  $\mathscr{\tilde{F}}^{\parallel}$ , hence cannot become an element of  $\mathscr{\tilde{F}}$ , i.e.,  $F \not\in \mathscr{\tilde{F}}$ , which contradicts (8). Hence, it follows that there must exist at least one  $\check{F}$  such that  $\check{F} \equiv F$ , thus the assertion holds.

Lemma 13.1.1(p.70) (b,c) implies that there always exist F and  $\check{F}$  such that  $F \equiv \check{F}$  holds; in other words, there always exist f and  $\check{f}$  such that  $f \equiv \check{f}$  or equivalently

$$f(\xi) \equiv \check{f}(\xi),\tag{13.1.10}$$

called the identity equality.

### 13.2 Definitions of Underlying Functions

The functions defined in the successive two sections are all the variations of ones that were defined in Sections 6.1.1(p.25) and 6.1.2(p.25).

<sup>&</sup>lt;sup>†</sup>This means  $F(x) = \check{F}(x)$  for all  $x \in (-\infty, \infty)$ .

<sup>&</sup>lt;sup>‡</sup>Due to the assumption of F being continuous (see A9(p.12))

<sup>§</sup>Note that  $\mathscr{F}$  is a set consisting of all possible F's by definition.

Note that  $\check{\mathscr{F}}$  is a set consisting of all possible  $\check{F}$ 's by definition.

### 13.2.1 $\check{T}$ , $\check{L}$ , $\check{K}$ , $\check{\mathcal{L}}$ , and $\check{\kappa}$ of Type $\mathbb{R}$

Let us define the underlying functions of Type  $\mathbb{R}$  (see Section 6.1.1(p.25)) for  $\check{F} \in \check{\mathscr{F}}$  corresponding to any  $F \in \mathscr{F}$  as follows.

$$\check{T}(x) = \check{\mathbf{E}}[\max\{\xi - x, 0\}] = \int_{-\infty}^{\infty} \max\{\xi - x, 0\}\check{f}(\xi)d\xi, \tag{13.2.1}$$

$$\check{L}(x) = \lambda \beta \check{T}(x) - s, \tag{13.2.2}$$

$$\check{K}(x) = \lambda \beta \check{T}(x) - (1 - \beta)x - s, \tag{13.2.3}$$

$$\check{\mathcal{L}}(s) = \check{L}(\lambda \beta \check{\mu} - s). \tag{13.2.4}$$

Let the solutions of  $\check{L}(x) = 0$ ,  $\check{K}(x) = 0$ , and  $\check{\mathcal{L}}(s) = 0$  be denoted by  $x_{\check{L}}$ ,  $x_{\check{K}}$ , and  $s_{\check{\mathcal{L}}}$  respectively if they exist. If each of the equations has the multiple solutions, let us employ the *smallest* one (see (a) of Section 6.2(p.27)). Let us define

$$\check{\kappa} = \lambda \beta \check{T}(0) - s. \tag{13.2.5}$$

By  $\check{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]$  let us define  $\mathsf{M}:1[\mathbb{R}][\mathtt{A}]$  for  $\check{F}\in\check{\mathscr{F}}$  corresponding to any  $F\in\mathscr{F}$ . Then, for the same reason as for  $\mathsf{M}:1[\mathbb{R}][\mathtt{A}]$  we can express  $\mathsf{SOE}\{\check{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}$  as (see Table 7.4.1(p.41) (I))

$$SOE\{\check{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\} = \{V_1 = \beta\check{\mu} - s, \ V_t = \max\{\check{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ t > 1\}.$$

## 13.2.2 $\check{T}$ , $\check{L}$ , $\check{K}$ , $\check{\mathcal{L}}$ , and $\check{\kappa}$ of Type $\mathbb{R}$

Let us define the underlying functions of Type  $\mathbb{R}$  for  $\check{F} \in \check{\mathscr{F}}$  corresponding to any  $F \in \mathscr{F}$  as follows.

$$\check{T}(x) = \check{\mathbf{E}}[\min\{\xi - x, 0\}] = \int_{-\infty}^{\infty} \min\{\xi - x, 0\} \check{f}(\xi) d\xi, \tag{13.2.6}$$

$$\overset{\circ}{L}(x) = \lambda \beta \overset{\circ}{T}(x) + s, \tag{13.2.7}$$

$$\tilde{K}(x) = \lambda \beta \tilde{T}(x) - (1 - \beta)x + s, \qquad (13.2.8)$$

$$\check{\mathcal{L}}(s) = \check{L}(\lambda \beta \check{\mu} + s). \tag{13.2.9}$$

Let the solutions of  $\check{L}(x)=0$ ,  $\check{K}(x)=0$ , and  $\check{\mathcal{L}}(s)=0$  be denoted by  $x_{\check{L}}$ ,  $x_{\check{K}}$ , and  $s_{\check{\mathcal{L}}}$  respectively if they exist. If each of the equations has the multiple solutions, let us employ the *largest* one (see (b) of Section 6.2(p.27)). Let us define

$$\dot{\tilde{\kappa}} = \lambda \beta \dot{\tilde{T}}(0) + s. \tag{13.2.10}$$

By  $\check{M}:1[\mathbb{R}][A]$  let us define  $\check{M}:1[\mathbb{R}][A]$  for  $\check{F}\in \check{\mathscr{F}}$  corresponding to any  $F\in \mathscr{F}$ . Then, for the same reason as for  $\check{M}:1[\mathbb{R}][A]$  we can express  $SOE\{\check{M}:1[\mathbb{R}][A]\}$  as (see Table 7.4.1(p.41) (II))

$$\mathtt{SOE}\{\check{\tilde{\mathsf{M}}}:1[\mathbb{R}][\mathtt{A}]\} = \{V_1 = \beta\check{\mu} + s, \ V_t = \min\{\check{\check{K}}\left(V_{t-1}\right) + V_{t-1}, \beta V_{t-1}\}, \ \ t > 1\}.$$

#### 13.2.3 List of the Underline Functions of Type $\mathbb R$ and Type $\mathbb R$

So far we have defined the four kinds of underlying functions, which may cause confusions. To give a clearer picture of these functions, we shall coordinate them as in Table 13.2.1(p.71).

Table 13.2.1: List of the underlying functions of Type  $\mathbb{R}$  and Type  $\mathbb{R}$ 

Type ℝ	$ ilde{ t Type} \ \mathbb{R}$
For any $F \in \mathscr{F}$	For $\check{F} \in \check{\mathscr{F}}$ corresponding to any $F \in \mathscr{F}$
$T(x) = \int_a^b \max\{\xi - x, 0\} f(\xi) d\xi$	$\check{T}(x) = \int_a^b \max\{\xi - x, 0\} \check{f}(\xi) d\xi$
$L\left(x\right) = \beta T(x) - s$	$\check{L}(x) = \beta \check{T}(x) - s$
$K(x) = \beta T(x) - (1 - \beta)x - s$	$\check{K}(x) = \beta \check{T}(x) - (1 - \beta)x - s$
$\mathcal{L}(x) = L(\beta \mu - s)$	$\check{\mathcal{L}}(x) = \check{\mathcal{L}}(\beta\check{\mu} - s)$
See Section 6.1.1(p.25)	See Section 13.2.1(p.71)
$\tilde{T}(x) = \int_a^b \min\{\xi - x, 0\} f(\xi) d\xi$	$\check{T}(x) = \int_a^b \min\{\xi - x, 0\} \check{f}(\xi) d\xi$
$\tilde{L}(x) = \beta \tilde{T}(x) + s$	$\check{L}(x) = \beta \check{T}(x) + s$
$\tilde{K}(x) = \beta \tilde{T}(x) - (1 - \beta)x + s$	$\check{K}(x) = \beta \check{T}(x) - (1 - \beta)x + s$
$\tilde{\mathcal{L}}(x) = \tilde{\mathcal{L}}(\beta \mu + s)$	$\check{\mathcal{L}}\left(x ight)=\check{\check{L}}\left(eta\check{\mu}+s ight)$
See Section 6.1.2(p.25)	See Section 13.2.2(p.71)

### 13.3 Two Kinds of Replacements

### 13.3.1 Correspondence Replacement

**Lemma 13.3.1**  $(\mathcal{C}_{\mathbb{R}})$  The left-hand side of each equality below is for any  $F \in \mathscr{F}$  and its right-hand side is for  $\check{F} \in \check{\mathscr{F}}$  corresponding to the F.

- (a)  $f(\xi) = \check{f}(\hat{\xi}).$
- (b)  $\hat{a} = \check{b}, \quad \hat{\mu} = \check{\mu}, \quad \hat{b} = \check{a}.$
- (c)  $\hat{T}(x) = \check{T}(\hat{x}).$
- (d)  $\hat{L}(x) = \hat{L}(\hat{x}).$
- (e)  $\hat{K}(x) = \check{K}(\hat{x}).$
- (f)  $\hat{\mathcal{L}}(s) = \hat{\mathcal{L}}(s)$ .
- (g)  $\hat{x}_L = x_{\tilde{L}}$ .
- $\hat{x}_K = x_{\tilde{K}}^{-}.$
- (i)  $s_{\mathcal{L}} = s_{\tilde{\mathcal{L}}}$ .
- (j)  $\hat{\kappa} = \check{\tilde{\kappa}}$ .  $\square$
- *Proof* (a) The same as (13.1.8(p.69)).
  - (b) The same as (13.1.9(p.69)).
  - (c) The function T(x) for any F (see (6.1.2(p.25))) can be rewritten as

$$T(x) = \int_{-\infty}^{\infty} \max\{-\hat{\xi} + \hat{x}, 0\} f(\xi) d\xi$$
$$= -\int_{-\infty}^{\infty} \min\{\hat{\xi} - \hat{x}, 0\} f(\xi) d\xi$$
$$= -\int_{-\infty}^{\infty} \min\{\hat{\xi} - \hat{x}, 0\} \check{f}(\hat{\xi}) d\xi \quad \text{due to (a)}.$$

Let  $\eta \stackrel{\text{def}}{=} \hat{\xi} = -\xi$ , hence  $d\eta = -d\xi$ . Then, we have

$$\begin{split} T(x) &= \int_{\infty}^{-\infty} \min\{\eta - \hat{x}, 0\} \check{f}(\eta) d\eta \\ &= -\int_{-\infty}^{\infty} \min\{\eta - \hat{x}, 0\} \check{f}(\eta) d\eta \\ &= -\int_{-\infty}^{\infty} \min\{\xi - \hat{x}, 0\} \check{f}(\xi) d\xi \quad \text{(without loss of generality}^{\dagger}\text{)} \\ &= -\check{T}(\hat{x}) \quad \text{(see (13.2.6(p.7l)))}, \end{split}$$

hence  $\hat{T}(x) = \check{T}(\hat{x})$ .

- (d) From (6.1.3(p.25)) and (c) we have  $L(x) = -\lambda \beta \hat{T}(x) s = -\lambda \beta \check{T}(\hat{x}) s = -\check{L}(\hat{x})$  from (13.2.7(p.71)), hence  $\hat{L}(x) = \check{L}(\hat{x})$ .
- (e) From (6.1.4(p.25)) and (c) we have  $K(x) = -\lambda \beta \hat{T}(x) + (1-\beta)\hat{x} s = -\lambda \beta \check{T}(\hat{x}) + (1-\beta)\hat{x} s = -\check{K}(\hat{x})$  from (13.2.8(p.71)), hence  $\hat{K}(x) = \check{K}(\hat{x})$ .
- (f) From (6.1.5(p.25)) we have  $\mathcal{L}(s) = -\hat{L}(\lambda\beta\mu s)$ , hence from (d) we obtain  $\mathcal{L}(s) = -\check{L}(\lambda\widehat{\beta}\mu s) = -\check{L}(-\lambda\beta\mu + s) = -\check{L}(\lambda\beta\hat{\mu} + s)$  due to (b). Accordingly, from (13.2.9(p.71)) we obtain  $\mathcal{L}(s) = -\check{L}(s)$ , hence  $\hat{\mathcal{L}}(s) = \check{L}(s)$ .
- (g) Since  $L(x_L) = 0$  by definition, we have  $\hat{L}(x_L) = 0$ , which can be rewritten as  $\check{L}(\hat{x}_L) = 0$  from (d), implying that  $\check{L}(x) = 0$  has the solution  $x_{\check{r}} = \hat{x}_L$  by definition.
- (h) Since  $K(x_K) = 0$  by definition, we have  $\hat{K}(x_K) = 0$ , which can be rewritten as  $\check{K}(\hat{x}_K) = 0$  from (e), implying that  $\check{K}(x) = 0$  has the solution  $x_{\check{K}} = \hat{x}_K$  by definition.
- (i) Since  $\mathcal{L}(s_{\mathcal{L}}) = 0$  by definition, we have  $\hat{\mathcal{L}}(s_{\mathcal{L}}) = 0$ , which can be rewritten as  $\check{\mathcal{L}}(s_{\mathcal{L}}) = 0$  from (f), implying that  $\check{\mathcal{L}}(s) = 0$  has the solution  $s_{\check{z}} = s_{\mathcal{L}}$  by definition.
- (j) From (6.1.6(p.25)) we have  $\kappa = -\lambda \beta \hat{T}(0) s$ , which can be rewritten as  $\kappa = -\lambda \beta \hat{T}(\hat{0}) s$  from (c), hence  $\kappa = -\lambda \beta \hat{T}(0) s = -\tilde{\kappa}$  from (13.2.10(p.71)), thus  $\hat{\kappa} = \tilde{\kappa}$ .

**Definition 13.3.1** (correspondence replacement operation  $\mathcal{C}_{\mathbb{R}}$ ) Let us call the operation of replacing the left-hand of each equality in Lemma 13.3.1(p.72) by its right-hand the *correspondence replacement operation*  $\mathcal{C}_{\mathbb{R}}$ .

**Lemma 13.3.2**  $(\tilde{\mathcal{C}}_{\mathbb{R}})$  The left-hand side of each equality below is for any  $F \in \mathscr{F}$  and its right-hand side is for  $\check{F} \in \check{\mathscr{F}}$  corresponding to the F.

- (a)  $f(\xi) = \check{f}(\hat{\xi}).$
- (b)  $\hat{b} = \check{a}, \quad \hat{\mu} = \check{\mu}, \quad \hat{a} = \check{b}.$
- (c)  $\hat{T}(x) = \check{T}(\hat{x})$ .

<sup>&</sup>lt;sup>†</sup>The mere replacement of the symbol  $\eta$  by  $\xi$ .

- (d)  $\hat{L}(x) = L(\hat{x}).$
- (e)  $\hat{K}(x) = K(\hat{x}).$
- (f)  $\hat{\mathcal{L}}(s) = \check{\mathcal{L}}(s)$ .
- (g)  $\hat{x}_{\tilde{L}} = x_{\tilde{L}}$ .
- $(h) \quad \hat{x}_{\tilde{K}} = x_{\check{K}}.$
- (i)  $s_{\tilde{\mathcal{L}}} = s_{\tilde{\mathcal{L}}}$ .
- (j)  $\hat{\tilde{\kappa}} = \check{\kappa}$ .
- *Proof* (a) The same as (13.1.8(p.69)).
  - (b) The same as (13.1.9(p.69)).
  - (c) The function  $\tilde{T}(x)$  for any F (see (6.1.12(p.25))) can be rewritten as

$$\begin{split} \tilde{T}(x) &= \int_{-\infty}^{\infty} \min\{-\hat{\xi} + \hat{x}, 0\} f(\xi) d\xi \\ &= -\int_{-\infty}^{\infty} \max\{\hat{\xi} - \hat{x}, 0\} f(\xi) d\xi \\ &= -\int_{-\infty}^{\infty} \max\{\hat{\xi} - \hat{x}, 0\} \check{f}(\hat{\xi}) d\xi \quad \text{(due to (a(p.72)))}. \end{split}$$

Let  $\eta = \hat{\xi} = -\xi$ . Then, since  $d\eta = -d\xi$ , we have

$$\begin{split} \tilde{T}(x) &= \int_{-\infty}^{-\infty} \max\{\eta - \hat{x}, 0\} \check{f}(\eta) d\eta \\ &= -\int_{-\infty}^{\infty} \max\{\eta - \hat{x}, 0\} \check{f}(\eta) d\eta \\ &= -\int_{-\infty}^{\infty} \max\{\xi - \hat{x}, 0\} \check{f}(\xi) d\xi \quad \text{(without loss of generality}^{\dagger}\text{)} \\ &= -\check{T}(\hat{x}) \quad \text{(see (13.2.1(p.7l)))}, \end{split}$$

hence  $\hat{T}(x) = \check{T}(\hat{x})$ .

- (d) From (6.1.13(p.25)) and (c) we have  $\tilde{L}(x) = -\lambda \beta \hat{T}(x) + s = -\lambda \beta \check{T}(\hat{x}) + s = -\check{L}(\hat{x})$  from (13.2.2(p.71)), hence  $\hat{L}(x) = \check{L}(\hat{x})$ .
- (e) From (6.1.14(p.25)) and (c) we have  $\tilde{K}(x) = -\lambda \beta \hat{T}(x) + (1-\beta)\hat{x} + s = -\lambda \beta \tilde{T}(\hat{x}) + (1-\beta)\hat{x} + s = -\check{K}(\hat{x})$  from (13.2.3(p.71)), hence  $\hat{K}(x) = \check{K}(\hat{x})$ .
- (f) From (6.1.15(p.25)) and (d) we have  $\tilde{\mathcal{L}}(s) = -\hat{\tilde{L}}(\lambda\beta\mu + s) = -\check{L}(\lambda\widehat{\beta}\mu + s) = -\check{L}(\lambda\beta\mu s) = -\check{L}(\lambda\beta\hat{\mu} s) = -\check{L}(\lambda\beta\hat{\mu} s) = -\check{L}(\lambda\beta\hat{\mu} s)$  due to (b), hence from (13.2.4(p.71)) we obtain  $\tilde{\mathcal{L}}(s) = -\check{\mathcal{L}}(s)$ , hence  $\hat{\tilde{\mathcal{L}}}(s) = \check{\mathcal{L}}(s)$ .
- (g) Since  $\tilde{L}(x_{\tilde{L}}) = 0$  by definition, we have  $\hat{L}(x_{\tilde{L}}) = 0$ , which can be rewritten as  $L(\hat{x}_{\tilde{L}}) = 0$  from (d), implying that L(x) = 0 has the solution  $x_{\tilde{L}} = \hat{x}_{\tilde{L}}$  by definition.
- (h) Since  $\tilde{K}(x_{\tilde{K}}) = 0$  by definition, we have  $\hat{K}(x_{\tilde{K}}) = 0$ , which can be rewritten as  $K(\hat{x}_{\tilde{K}}) = 0$  from (e), implying that K(x) = 0 has the solution  $x_{\tilde{K}} = \hat{x}_{\tilde{K}}$  by definition.
- (i) Since  $\tilde{\mathcal{L}}(s_{\tilde{\mathcal{L}}}) = 0$  by definition, we have  $\hat{\tilde{\mathcal{L}}}(s_{\tilde{\mathcal{L}}}) = 0$ , which can be rewritten as  $\check{\mathcal{L}}(s_{\tilde{\mathcal{L}}}) = 0$  from (f), implying that  $\check{\mathcal{L}}(s) = 0$  has the solution  $s_{\check{\mathcal{L}}} = s_{\check{\mathcal{L}}}$  by definition.
- (j) From (6.1.16 (p.25)) we have  $\tilde{\kappa} = -\lambda \beta \hat{T}(0) + s$ , which can be rewritten as  $\tilde{\kappa} = -\lambda \beta \check{T}(\hat{0}) + s$  from (c), hence  $\tilde{\kappa} = -\lambda \beta \check{T}(0) + s = -\check{\kappa}$  from (13.2.5 (p.71)), thus  $\hat{\tilde{\kappa}} = \check{\kappa}$ .

**Definition 13.3.2** (correspondence replacement operation  $\tilde{\mathcal{C}}_{\mathbb{R}}$ ) Let us call the operation of replacing the left-hand of each equality in Lemma 13.3.2(p.72) by its right-hand the *correspondence replacement operation*  $\tilde{\mathcal{C}}_{\mathbb{R}}$ .  $\square$ 

**Definition 13.3.3** (reflective element and non-reflective element) It should be noted that the left-hand of each of the equalities in Lemmas 13.3.1(p.72) (i) and 13.3.2(p.72) (i) have not the hat symbol "  $^{\circ}$ ". In other words,  $s_{\mathcal{L}}$  and  $s_{\tilde{\mathcal{L}}}$  are not subjected to the reflection. For the reason, let us refer to each of  $s_{\mathcal{L}}$  and  $s_{\tilde{\mathcal{L}}}$  as the non-reflective element and to each of all the other elements as the reflective element.  $\square$ 

### 13.3.2 Identity Replacement

**Lemma 13.3.3**  $(\mathcal{I}_{\mathbb{R}})$  The left-hand side of each equality below is for  $\check{F} \in \check{\mathscr{F}}$  corresponding to any  $F \in \mathscr{F}$  and the right-hand side is for  $F \in \mathscr{F}$  such that  $F \equiv \check{F} \cdots [1^*]^{\dagger}$ 

- (a)  $\check{F}(\xi) = F(\xi) \cdots [2^*] \text{ and } \check{f}(\xi) = f(\xi) \cdots [3^*] \text{ for any } \xi.$
- (b)  $\check{a} = a, \ \check{\mu} = \mu, \ \check{b} = b.$
- (c)  $\check{T}(x) = \tilde{T}(x)$ .
- (d)  $\check{L}(x) = \tilde{L}(x)$ .
- (e)  $\tilde{K}(x) = \tilde{K}(x)$ .

<sup>&</sup>lt;sup>†</sup>The mere replacement of the symbol  $\eta$  by  $\xi$ .

<sup>†</sup>See Lemma 13.1.1(p.70) (b,c).

- $\mathcal{\tilde{L}}(s) = \mathcal{\tilde{L}}(s).$
- $x_{\tilde{L}} = x_{\tilde{L}}$ .
- $x_{\tilde{K}}^- = x_{\tilde{K}}$ . (h)
- $s_{\tilde{\mathcal{L}}}^{\kappa} = s_{\tilde{\mathcal{L}}}.$  $\tilde{\kappa} = \tilde{\kappa}.$
- (j)
- *Proof* (a) Clear from  $[1^*]$ .
  - (b) Obvious from (a).
  - (c) Evident from (13.2.6(p.71)), (6.1.12(p.25)), and  $[3^*]$ .
  - (d) From (13.2.7(p.71)) and (c) we have  $\tilde{L}(x) = \lambda \beta \tilde{T}(x) + s$ , hence  $\tilde{L}(x) = \tilde{L}(x)$  from (6.1.13(p.25)).
  - (e) From (13.2.8(p.71)) and (c) we have  $\tilde{K}(x) = \lambda \beta \tilde{T}(x) (1-\beta)x + s$ , hence  $\tilde{K}(x) = \tilde{K}(x)$  from (6.1.14(p.25)).
  - (f) From (13.2.9(p.71)) and (d) we have  $\check{\mathcal{L}}(s) = \tilde{L}(\lambda\beta\check{\mu} + s)$ , hence  $\check{\mathcal{L}}(s) = \tilde{L}(\lambda\beta\mu + s)$  from (b), so  $\check{\mathcal{L}}(s) = \tilde{\mathcal{L}}(s)$  (6.1.15(p.25)).
  - (g) Since  $\tilde{L}(x_{\tilde{L}}) = 0$  by definition, we have  $\tilde{L}(x_{\tilde{L}}) = 0$  from (d), hence  $\tilde{L}(x) = 0$  has the solution  $x_{\tilde{L}} = x_{\tilde{L}}$ .
  - Since  $\tilde{K}(x_{\tilde{K}}) = 0$  by definition, we have  $\tilde{K}(x_{\tilde{K}}) = 0$  from (e), hence  $\tilde{K}(x) = 0$  has the solution  $x_{\tilde{K}} = x_{\tilde{K}}$ .
  - Since  $\tilde{\mathcal{L}}(s_{\tilde{\mathcal{L}}}) = 0$  by definition, we have  $\tilde{\mathcal{L}}(s_{\tilde{\mathcal{L}}}) = 0$  from (f), hence  $\tilde{\mathcal{L}}(x) = 0$  has the solution  $s_{\tilde{\mathcal{L}}} = s_{\tilde{\mathcal{L}}}$  by definition.
  - From (13.2.10(p.71)) and (c) with x = 0 we have (6.1.16(p.25)).

**Definition 13.3.4** (identity replacement operation  $\mathcal{I}_{\mathbb{R}}$ ) Let us call the operation of replacing the left-hand side of each equality in Lemma 13.3.3(p.73) by its right-hand side the identity replacement operation  $\mathcal{I}_{\mathbb{R}}$ .

**Lemma 13.3.4**  $(\tilde{\mathcal{I}}_{\mathbb{R}})$  The left-hand side of each equality below is for  $\check{F} \in \check{\mathscr{F}}$  corresponding to any  $F \in \mathscr{F}$  and the right-hand  $side\ is\ for\ F\in\mathscr{F}\ such\ that\ F\equiv \check{F}\cdots [1^*].^\dagger$ 

- $\check{F}(\xi) = F(\xi) \cdots [2^*]$  and  $\check{f}(\xi) = f(\xi) \cdots [3^*]$  for any  $\xi$ .
- $\check{a} = a, \ \check{\mu} = \mu, \ \check{b} = b.$ (b)
- $\check{T}(x) = T(x).$ (c)
- $\check{L}(x) = L(x).$ (d)
- (e)  $\check{K}(x) = K(x).$
- $\check{\mathcal{L}}(s) = \mathcal{L}(s).$ (f)
- (g)  $x_{\check{L}} = x_L$ .
- (h)  $x_{\check{K}} = x_K$ .
- (i)  $s_{\check{\mathcal{L}}} = s_{\mathcal{L}}$ .
- $\check{\kappa} = \kappa$ .  $\square$ (i)
- Proof (a) Clear from [1\*].
  - (b) Obvious from (a).
  - (c) Evident from (13.2.1(p.71)), (6.1.2(p.25)), and  $[3^*]$ .
  - (d) From (13.2.2(p.71)) and (c) we have  $\check{L}(x) = \lambda \beta T(x) s$ , hence  $\check{L}(x) = L(x)$  from (6.1.3(p.25)).
  - (e) From (13.2.3(p.71)) and (c) we have  $\check{K}(x) = \lambda \beta T(x) (1-\beta)x s$ , hence  $\check{K}(x) = K(x)$  from (6.1.4(p.25)).
- (f) From (13.2.4(p.71)) and (d) we have  $\check{\mathcal{L}}(s) = \check{L}(\lambda\beta\mu s)$ , hence  $\check{\mathcal{L}}(s) = \check{L}(\lambda\beta\mu + s)$  from (b), so  $\mathcal{L}(s) = \check{L}(\lambda\beta\mu + s)$ , hence  $\check{\mathcal{L}}(s) = \mathcal{L}(s) \text{ from } (6.1.5(p.25)).$ 
  - (g) Since  $L(x_L) = 0$  by definition, we have  $\check{L}(x_L) = 0$  from (d), hence  $\check{L}(x) = 0$  has the solution  $x_{\check{L}} = x_L$  by definition.
  - (h) Since  $K(x_K) = 0$  by definition, we have  $\check{K}(x_K) = 0$  from (e), hence  $\check{K}(x) = 0$  has the solution  $x_{\check{K}} = x_K$  by definition.
  - Since  $\mathcal{L}(s_{\mathcal{L}}) = 0$  by definition, we have  $\check{\mathcal{L}}(s_{\mathcal{L}}) = 0$  from (f), hence  $\check{\mathcal{L}}(x) = 0$  has the solution  $s_{\check{\mathcal{L}}} = s_{\mathcal{L}}$  by definition.
  - (j) From (13.2.5(p.71)) and (c) with x = 0 we have (6.1.6(p.25)).

**Definition 13.3.5** (identity replacement operation  $\tilde{\mathcal{I}}_{\mathbb{R}}$ ) Let us call the operation of replacing the left-hand of each equality in Lemma 13.3.4(p.74) by its right-hand the identity replacement operation  $\tilde{\mathcal{I}}_{\mathbb{R}}$ .

#### 13.4 Attribute Vector

Closely looking into the contents of all assertions  $A\{M:1[\mathbb{R}][A]\}\in \mathscr{A}\{M:1[\mathbb{R}][A]\}$  (see Tom's 12.2.1(p.61) and 12.2.2(p.62)), we can immediately see that each assertion is described by using a part or all of the following twelve kinds of elements;

$$a,\,\mu,\,b,\,\,x_{\rm L}\,,\,\,x_{\rm K},\,\,s_{\rm L}\,,\,\kappa,\,T,\,L\,,\,K,\,{\rm L}\,,\,V_t$$

where  $V_t$  represents the sequence  $\{V_t, t = 1, 2, \cdots\}$  generated from  $SOE\{M:1[\mathbb{R}][A]\}$  (see Table 7.4.1(p.41) (I)). Let us call each element the attribute element and the vector of them the attribute vector, denoted by

<sup>†</sup>See Lemma 13.1.1(p.70) (b,c).

$$\theta(A\{M:1[\mathbb{R}][A]\}) = (a, \mu, b, x_L, x_K, s_L, \kappa, T, L, K, L, V_t). \tag{13.4.1}$$

In addition, also for the assertion system  $\mathscr{A}\{M:1[\mathbb{R}][A]\}$  we can employ the similar definition, denoted by

$$\boldsymbol{\theta}(\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}) = (a, \mu, b, x_L, x_K, s_{\mathcal{L}}, \kappa, T, L, K, \mathcal{L}, V_t). \tag{13.4.2}$$

### 13.5 Scenario $[\mathbb{R}]$

In this section we write up a scenario deriving an assertion on  $\tilde{M}:1[\mathbb{R}][A]$  (buying model with  $\mathbb{R}$ -mechanism) from a given assertion on  $M:1[\mathbb{R}][A]$  (selling model with  $\mathbb{R}$ -mechanism). Let us refer to this as the scenario of Type  $\mathbb{R}$ , denoted by Scenario  $[\mathbb{R}]$ .

#### ■ Step 1 (opening)

• The system of optimality equations for M:1[R][A] is given by Table 7.4.1(p.41) (I), i.e.,

$$SOE\{M:1[\mathbb{R}][\mathbb{A}]\} = \{V_1 = \beta \mu - s, \ V_t = \max\{K(V_{t-1}) + V_{t-1}, \ \beta V_{t-1}\}, \quad t > 1\}. \tag{13.5.1}$$

 $\circ$  Let us consider an assertion  $A_{\texttt{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}^{\dagger}$  included in  $\texttt{Tom}\ 12.2.2(\texttt{p.61})$  or  $\texttt{Tom}\ 12.2.2(\texttt{p.62})$ , which can be written in general as

$$A_{\mathsf{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\} \ = \ \{\mathsf{S} \text{ is true for } \boldsymbol{p} \in \mathscr{P}_{A_{\mathsf{Tom}}} \subseteq \mathscr{P} \text{ and } F \in \mathscr{F}_{A_{\mathsf{Tom}}|\boldsymbol{p}} \subseteq \mathscr{F}\} \quad (\mathrm{see} \ (12.3.6(\text{p.65}))) \tag{13.5.2}$$

= 
$$\{S \text{ is true on } \mathscr{C}\langle A_{Tom}\rangle\}\ (\text{see } (12.3.8(p.65))).$$
 (13.5.3)

To facilitate the understanding of the discussion that follows, let us use the following example. ‡

$$S = \langle V_t + s_{\mathcal{L}} + x_L + \kappa + a + \mu + b \ge 0, \ t > 0 \rangle. \tag{13.5.4}$$

• The attribute vector of the assertion  $A_{Tom}\{M:1[\mathbb{R}][\mathbb{A}]\}$  is given by (13.4.1(p.75)), i.e.,

$$\boldsymbol{\theta}(A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\}) = (a, \mu, b, x_L, x_K, s_{\mathcal{L}}, \kappa, T, L, K, \mathcal{L}, V_t). \tag{13.5.5}$$

#### ■ Step 2 (reflection operation $\mathcal{R}$ )

o Applying the reflection operation  $\mathcal{R}$  (see Section 13.1.1(p.69)) to (13.5.1(p.75)) produces

$$\mathcal{R}[SOE\{M:1[\mathbb{R}][\mathbb{A}]\}] = \{-\hat{V}_1 = -\beta\hat{\mu} - s, -\hat{V}_t = \max\{-\hat{K}(V_{t-1}) - \hat{V}_{t-1}, -\beta\hat{V}_{t-1}\}, \ t > 1\}$$

$$= \{-\hat{V}_1 = -\beta\hat{\mu} - s, -\hat{V}_t = -\min\{\hat{K}(V_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \ t > 1\}$$

$$= \{\hat{V}_1 = \beta\hat{\mu} + s, \ \hat{V}_t = \min\{\hat{K}(V_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \ t > 1\}.$$
(13.5.6)

 $\circ$  Applying  ${\cal R}$  to (13.5.2(p.75)) and (13.5.3(p.75)) yields to

$$\mathcal{R}[A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}] = \{\mathcal{R}[\mathsf{S}] \text{ is true for } \boldsymbol{p} \in \mathscr{P}_{A_{\text{Tom}}} \subseteq \mathscr{P} \text{ and } F \in \mathscr{F}_{A_{\text{Tom}}|\boldsymbol{p}} \subseteq \mathscr{F}\}$$

$$(13.5.7)$$

$$= \{ \mathcal{R}[S] \text{ is true on } \mathscr{C}\langle A_{\mathsf{Tom}} \rangle \}. \tag{13.5.8}$$

For our example we have:

$$\mathcal{R}[S] = \langle -\hat{V}_t + s_{\mathcal{L}} - \hat{x}_L - \hat{\kappa} - \hat{a} - \hat{\mu} - \hat{b} \ge 0, \ t > 0 \rangle^{\S}$$

$$= \langle \hat{V}_t - s_{\mathcal{L}} + \hat{x}_L + \hat{\kappa} + \hat{a} + \hat{\mu} + \hat{b} \le 0, \ t > 0 \rangle.$$
(13.5.9)

 $\circ \ \, \text{The attribute vector of the assertion} \, \, \mathcal{R}[A_{\texttt{Tom}}\{M:1[\mathbb{R}][A]\}] \, \, \text{is given by applying} \, \, \mathcal{R} \, \, \text{to} \, \, (13.5.5(\texttt{p.75})), \, \text{i.e.},$ 

$$\boldsymbol{\theta}(\mathcal{R}[A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbf{A}]\}]) \stackrel{\text{def}}{=} \mathcal{R}[\boldsymbol{\theta}(A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbf{A}]\})] \tag{13.5.10}$$

$$= (\hat{a}, \hat{\mu}, \hat{b}, \hat{x}_L, \hat{x}_K, s_L, \hat{\kappa}, \hat{T}, \hat{L}, \hat{K}, \hat{\mathcal{L}}, \hat{V}_t). \tag{13.5.11}$$

#### ■ Step 3 (correspondence replacement operation $\mathcal{C}_{\mathbb{R}}$ )

• Here let us consider the application of the correspondence replacement operation  $\mathcal{C}_{\mathbb{R}}$ , i.e., the replacement of the left-hand side of each equality in Lemma 13.3.1(p.72),

$$f(\xi), \hat{a}, \hat{\mu}, \hat{b}, \hat{x}_L, \hat{x}_K, s_L, \hat{\kappa}, \hat{T}(x), \hat{L}(x), \hat{K}(x), \hat{L}(s) \cdots (1^*),$$

by its right-hand,

$$\check{f}(\hat{\xi}), \check{b}, \, \check{\mu}, \, \check{a}, \, \, x_{\check{\tilde{L}}}, \, \, x_{\check{\tilde{K}}}, \, \, s_{\check{\tilde{C}}}, \, \, \check{\tilde{\kappa}}, \, \, \check{\check{T}}(\hat{x}), \, \check{\check{L}}(\hat{x}), \, \check{\check{K}}(\hat{x}), \, \check{\check{L}}(s) \cdots (2^*),$$

where  $(1^*)$  is for any  $F \in \mathscr{F}$  and  $(2^*)$  is for  $\check{F} \in \check{\mathscr{F}}$  corresponding to the  $F \in \mathscr{F}$ .

<sup>†</sup>See Def. 12.3.1(p.65) (c) for the symbol "Tom" in  $A_{\text{Tom}}\{M:1[\mathbb{R}][A]\}$ .

<sup>&</sup>lt;sup>‡</sup>The example is a hypothetical assertion which is not contained in ∠<sub>Tom</sub> {M:1[ℝ][A]}; It is used merely for explanatory convenience.

 $<sup>\</sup>S$  Note Def. 13.3.3(p.73).

 $\circ$  Applying  $\mathcal{C}_{\mathbb{R}}$  to (13.5.6(p.75)) leads to

$$\mathcal{C}_{\mathbb{R}}\mathcal{R}[SOE\{M:1[\mathbb{R}][A]\}] = \{\hat{V}_1 = \beta\check{\mu} + s, \ \hat{V}_t = \min\{\check{K}(\hat{V}_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \ t > 1\}.$$
(13.5.12)

• Applying  $\mathcal{C}_{\mathbb{R}}$  to  $\mathcal{R}[S]$  in (13.5.9(p.75)), we have

$$\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathsf{S}] = \langle \hat{V}_t - s_{\tilde{c}} + x_{\tilde{c}} + \check{k} + \check{b} + \check{\mu} + \check{a} \le 0, \ t > 0 \rangle. \tag{13.5.13}$$

Now, let us note here that the application of  $\mathcal{C}_{\mathbb{R}}$  inevitably transforms

"
$$F \in \mathscr{F}_{A_{\mathsf{Tom}}|p} \subseteq \mathscr{F}$$
" in  $(13.5.2(p.75))$ 

into

"
$$\check{F} \in \check{\mathscr{F}}_{A_{\mathsf{Tom}}|p} \subseteq \check{\mathscr{F}} \text{ corresponding to } F \in \mathscr{F}_{A_{\mathsf{Tom}}|p} \subseteq \mathscr{F}$$
" (13.5.14)

where

$$\check{\mathscr{F}}_{A_{\mathsf{Tom}}\mid\boldsymbol{p}}\stackrel{\text{\tiny def}}{=} \{\check{F}\mid F\in\mathscr{F}_{A_{\mathsf{Tom}}\mid\boldsymbol{p}}\}\subseteq \{\check{F}\mid F\in\mathscr{F}\}=\check{\mathscr{F}} \quad (\text{see }(13.1.3(\text{p.69}))). \tag{13.5.15}$$

Hence, applying  $\mathcal{C}_{\mathbb{R}}$  to (13.5.7(p.75)) produces

$$\mathcal{C}_{\mathbb{R}}\mathcal{R}[A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\}] = \{\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathsf{S}] \text{ is true for } \boldsymbol{p} \in \mathscr{P}_{A_{\text{Tom}}} \text{ and } \check{F} \in \check{\mathscr{F}}_{A_{\text{Tom}}|\boldsymbol{p}} \subseteq \check{\mathscr{F}}$$

$$\text{corresponding to } F \in \mathscr{F}_{A_{\text{Tom}}|\boldsymbol{p}} \subseteq \mathscr{F}\}.$$

$$(13.5.16)$$

Now, since the phrase " $\check{F} \in \check{\mathscr{F}}_{A_{\mathsf{Tom}}|p} \subseteq \check{\mathscr{F}}$ " is implicitly accompanied with the phrase " $corresponding to <math>F \in \mathscr{F}_{A_{\mathsf{Tom}}|p} \subseteq \mathscr{F}$ ", the latter phrase becomes redundant. Accordingly, (13.5.16(p.%)) can be rewritten as

$$\mathcal{C}_{\mathbb{R}}\mathcal{R}[A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\}] = \{\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathsf{S}] \text{ is true for } \boldsymbol{p} \in \mathscr{P}_{A_{\text{Tom}}} \subseteq \mathscr{P} \text{ and } \check{F} \in \check{\mathscr{F}}_{A_{\text{Tom}}|\boldsymbol{p}} \subseteq \check{\mathscr{F}}\}$$

$$= \{\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathsf{S}] \text{ is true on } \check{\mathscr{C}}\langle A_{\text{Tom}}\rangle\}$$

$$(13.5.17)$$

where

$$\check{\mathscr{E}}\langle A_{\texttt{Tom}}\rangle = \{(\boldsymbol{p}, \check{F}) \mid \boldsymbol{p} \in \mathscr{P}_{A_{\texttt{Tom}}} \subseteq \mathscr{P}, \check{F} \in \check{\mathscr{F}}_{A_{\texttt{Tom}}|\boldsymbol{p}} \subseteq \check{\mathscr{F}}\} \quad \text{(compare } (12.3.3(p.64))). \tag{13.5.18}$$

• The attribute vector of  $\mathcal{C}_{\mathbb{R}}\mathcal{R}[A_{\text{Tom}}\{M:1[\mathbb{R}][A]\}]$  is given by applying  $\mathcal{C}_{\mathbb{R}}$  to (13.5.10(p.75)), i.e.,

$$\theta(\mathcal{C}_{\mathbb{R}}\mathcal{R}[A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\}]) = \mathcal{C}_{\mathbb{R}}\mathcal{R}[\theta(A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\})] 
= (\check{b},\check{\mu},\check{a}, x_{\check{\kappa}}, x_{\check{\kappa}}, x_{\check{\kappa}}, \check{\kappa}, \check{T}, \check{L}, \check{K}, \check{\mathcal{L}}, V_{t}).$$
(13.5.19)

- Step 4 (identity replacement operation  $\mathcal{I}_{\mathbb{R}}$ )
- Here let us consider the application of the identity replacement operation  $\mathcal{I}_{\mathbb{R}}$ , i.e., the replacement of the left-hand side of each equality in Lemma 13.3.3(p.73),

$$\check{f}(\xi), \check{a}, \check{\mu}, \check{b}, \ x_{\check{L}}, \ x_{\check{K}}, \ s_{\check{\mathcal{L}}}, \ \check{\kappa}, \ \check{\tilde{T}}(x), \ \check{\tilde{L}}(x), \ \check{\tilde{K}}(x), \ \check{\tilde{L}}(s) \cdots (1^*),$$

by its right-hand side,

$$f(\xi)$$
,  $a$ ,  $\mu$ ,  $b$ ,  $x_{\tilde{L}}$ ,  $x_{\tilde{K}}$ ,  $s_{\tilde{L}}$ ,  $\tilde{\kappa}$   $\tilde{T}(x)$ ,  $\tilde{L}(x)$ ,  $\tilde{K}(x)$ ,  $\tilde{\mathcal{L}}(s) \cdots (2^*)$ ,

where  $(1^*)$  is for any  $F \in \mathscr{F}$  and  $(2^*)$  is for  $\check{F} \in \check{\mathscr{F}}$  which is identical to the  $\check{F} \in \mathscr{F}$ , i.e.,  $\check{F} \equiv F \cdots (1)$  (see Lemma 13.1.1(p.70) (c)).

• Applying  $\mathcal{I}_{\mathbb{R}}$  to (13.5.12(p.76)) yields

$$\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathsf{SOE}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\}] = \{\hat{V}_1 = \beta\mu + s, \ \hat{V}_t = \min\{\tilde{K}(\hat{V}_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \ t > 1\}. \tag{13.5.20}$$

Now, we have  $\hat{V}_1 = \beta \mu + s = V_1$  from (7.4.3(p.41)). Suppose  $\hat{V}_{t-1} = V_{t-1}$ . Then, since  $\hat{V}_t = \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} = V_t$  from (7.4.4(p.41)), by induction  $\hat{V}_t = V_t$  for t > 0. Thus (13.5.20(p.76)) can be rewritten as

$$\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[SOE\{M:1[\mathbb{R}][\mathbb{A}]\}] = \{V_1 = \beta\mu + s, V_t = \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, t > 1\},$$

which is the same as  $SOE{\tilde{M}:1[\mathbb{R}][A]}$  (see Table 7.4.1(p.41) (II)). Thus we have

$$SOE\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\} = \mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[SOE\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\}]$$

$$= \{V_1 = \beta\mu + s, V_t = \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ t > 1\}.$$
(13.5.21)

• Applying  $\mathcal{I}_{\mathbb{R}}$  to (13.5.17(p.76)) yields (note  $\check{F} \equiv F$  in (1))

$$\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}] = \{\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathsf{S}] \text{ is true on } \check{\mathscr{C}}\langle A_{\text{Tom}}\rangle \}. \tag{13.5.23}$$

Applying  $\mathcal{I}_{\mathbb{R}}$  to (13.5.13(p.76)) yields

$$\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathsf{S}] = \langle V_t - s_{\tilde{\mathcal{L}}} + x_{\tilde{\mathcal{L}}} + \tilde{\kappa} + b + \mu + a \leq 0, \ t > 0 \rangle. \tag{13.5.24}$$

Now  $V_t$  within  $\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[S]$  is generated from  $SOE\{\tilde{M}:1[\mathbb{R}][A]\}$ , hence (13.5.23(p.77)) can be regarded as the assertion on  $\tilde{M}:1[\mathbb{R}][A]$  (see Remark 7.1.1(p.29)). Thus, we have

$$A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\} = \mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}]$$

$$(13.5.25)$$

$$= \{ \mathcal{I}_{\mathbb{R}} \mathcal{C}_{\mathbb{R}} \mathcal{R}[S] \text{ is true on } \check{\mathscr{C}} \langle A_{\text{Tom}} \rangle \}.$$
 (13.5.26)

• The attribute vector of  $A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}$  is given by applying  $\mathcal{I}_{\mathbb{R}}$  to (13.5.19(p.76)), i.e.,

$$\boldsymbol{\theta}(A_{\mathtt{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}) \ = \ \mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[\boldsymbol{\theta}(A_{\mathtt{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\})]$$

■ Step 5 (symmetry transformation operation  $S_{\mathbb{R}\to\tilde{\mathbb{R}}}$ ) =  $(b, \mu, a, x_{\tilde{L}}, x_{\tilde{K}}, s_{\tilde{\mathcal{L}}}, \tilde{\kappa}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_t)$ , (13.5.27) Lining up the four attribute vectors in Steps 1-4, we have the following:

The above flow can be eventually reduced to

$$\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} \stackrel{\text{def}}{=} \left\{ \begin{array}{ccccc} a, \mu, b, & x_{L}, x_{K}, s_{\mathcal{L}}, \kappa, T, L, K, \mathcal{L}, V_{t} \\ \downarrow & \downarrow \\ b, \mu, a, & x_{\tilde{L}}, x_{\tilde{K}}, s_{\tilde{\mathcal{L}}}, \tilde{\kappa}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_{t} \end{array} \right\},$$

$$(13.5.29)$$

called the symmetry transformation operation, which can be regarded as the successive application of the three operations, i.e., " $\mathcal{R} \to \mathcal{C}_{\mathbb{R}} \to \mathcal{I}_{\mathbb{R}}$ ". Hence, defining

$$S_{\mathbb{R} \to \tilde{\mathbb{R}}} = \mathcal{I}_{\mathbb{R}} C_{\mathbb{R}} \mathcal{R}, \tag{13.5.30}$$

we can rewrite (13.5.25(p.77)) as

$$A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbf{A}]\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbf{A}]\}]$$
$$= \{\tilde{\mathsf{S}} \text{ holds on } \check{\mathscr{E}}\langle A_{\text{Tom}}\rangle \}$$
(13.5.31)

where

$$\tilde{\mathsf{S}} \stackrel{\text{def}}{=} \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathsf{S}]. \tag{13.5.32}$$

Then, from (13.5.24(p.77)) we have

$$\tilde{\mathsf{S}} = \langle V_t - s_{\tilde{c}} + x_{\tilde{t}} + \tilde{\kappa} + b + \mu + a < 0, \ t > 0 \rangle. \tag{13.5.33}$$

Furthermore, (13.5.21(p.76)) can be rewritten as

$$SOE\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[SOE\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}]. \tag{13.5.34}$$

In addition, (13.5.27(p.77)) can be rewritten as

$$\theta(A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}) = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\theta(A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\})]$$
(13.5.35)

$$= (b, \mu, a, x_{\tilde{L}}, x_{\tilde{K}}, s_{\tilde{C}}, \tilde{\kappa}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_t). \tag{13.5.36}$$

From all the above we see that Scenario [ $\mathbb{R}$ ] starting with (13.5.3(p.75)) finally ends up with (13.5.31(p.77)), which can be alternatively rewritten as respectively (see (12.3.5(p.64)))

$$A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\} \text{ holds on } \mathscr{C}\langle A_{\text{Tom}}\rangle \quad \text{(see (12.3.8(p.65)))}, \tag{13.5.37}$$

$$A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\} \text{ holds on } \mathscr{E}\langle A_{\text{Tom}}\rangle.$$

From the above two results and (13.5.34(p.77)) we eventually obtain the following lemma.

**Lemma 13.5.1** Let  $A_{\text{Tom}}\{M:1[\mathbb{R}][A]\}\ holds\ on\ \mathscr{C}\langle A_{\text{Tom}}\rangle$ . Then  $A_{\text{Tom}}\{\tilde{M}:1[\mathbb{R}][A]\}\ holds\ on\ \check{\mathscr{C}}\langle A_{\text{Tom}}\rangle$  where

$$A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}]. \quad \Box$$
 (13.5.38)

#### ■ Step 6 (Completeness of $\tilde{T}$ om)

### $\bigstar$ Condition Space $\check{\mathscr{C}}\langle A_{\mathtt{Tom}}\rangle$

Applying Lemma 13.5.1(p.78) to any assertion  $A\{M:1[\mathbb{R}][A]\}$  included in Tom's 12.2.1(p.61) and 12.2.2(p.62), we have  $A\{\tilde{M}:1[\mathbb{R}][A]\}$  corresponding to each  $A\{M:1[\mathbb{R}][A]\}$ , which are given by Tom's 13.7.1(p.83) and 13.7.2(p.84). Below let us replace the two symbols Tom's as Tom<sub>1</sub> and Tom<sub>2</sub> respectively, i.e.,

 $\mathtt{Tom}_1 = \mathtt{Tom} \ 13.7.1 (p.83) \quad \text{and} \quad \mathtt{Tom}_2 = \mathtt{Tom} \ 13.7.2 (p.84) \,.$ 

Furthermore, let

$$\mathsf{Tom} \stackrel{\mathsf{def}}{=} \mathsf{Tom}_1, \mathsf{Tom}_2, \cdots. \tag{13.5.39}$$

Here, as one corresponding to (13.5.18(p.76)), let us define

$$\check{\mathscr{E}}\langle A_{\mathsf{Tom}_i}\rangle = \{(\boldsymbol{p},\check{F}) \mid \boldsymbol{p} \in \mathscr{P}_{A_{\mathsf{Tom}_i}} \subseteq \mathscr{P}, \check{F} \in \check{\mathscr{F}}_{A \cdot \mathsf{Tom}_i} | \boldsymbol{p} \subseteq \check{\mathscr{F}}\}, \quad i = 1, 2, \cdots.$$

$$(13.5.40)$$

In general, let

$$\check{\mathscr{C}}\langle A_{\text{Tom}}\rangle = \{(\boldsymbol{p}, \check{F}) \mid \boldsymbol{p} \in \mathscr{P}_{A_{\text{Tom}}} \subseteq \mathscr{P}, \check{F} \in \check{\mathscr{F}}_{A_{\text{Tom}}|\boldsymbol{p}} \subseteq \check{\mathscr{F}}\}.$$
(13.5.41)

In addition, let us define

$$\begin{split} & \operatorname{Tom}_i \ \stackrel{\text{\tiny def}}{=} \ \{A^1_{\operatorname{Tom}_i}, A^2_{\operatorname{Tom}_i}, \cdots\} = \{A_{\operatorname{Tom}_i}\}, \\ & \tilde{\mathcal{T}} \text{om} \ \stackrel{\text{\tiny def}}{=} \ \{\operatorname{Tom}_1, \operatorname{Tom}_2, \cdots\} = \{\operatorname{Tom}\}. \end{split}$$

Then, as one corresponding to (12.3.17(p.66)), let us define

$$\check{\mathscr{C}}\langle \mathsf{Tom}_i \rangle \stackrel{\text{def}}{=} \cup_{j=1,2,\dots} \check{\mathscr{C}}\langle A^j_{\mathsf{Tom}_i} \rangle = \cup_{A_{\mathsf{Tom}_i} \in \mathsf{Tom}_i} \check{\mathscr{C}}\langle A_{\mathsf{Tom}_i} \rangle, \quad i=1,2,\dots, \tag{13.5.42}$$

which is the aggregation of  $\check{\mathscr{C}}\langle A^j_{\mathtt{Tom}_i}\rangle$ ,  $j=1,2,\cdots$ , into  $\check{\mathscr{C}}\langle \mathtt{Tom}_i\rangle$ . This can be rewritten as

$$\check{\mathscr{E}}\langle \mathsf{Tom}_i \rangle \stackrel{\text{def}}{=} \{ \check{\mathscr{E}}\langle A^1_{\mathsf{Tom}_i} \rangle, \check{\mathscr{E}}\langle A^2_{\mathsf{Tom}_i} \rangle, \cdots \}, \quad i = 1, 2, \cdots.$$
 (13.5.43)

 $\square \ Example \ \mathbf{13.5.1} \quad \text{Let } \tilde{\mathcal{T}} \text{om} = \{ \mathsf{Tom}_1, \mathsf{Tom}_2, \mathsf{Tom}_3 \} \ \text{and} \ \check{\mathscr{C}} \langle \mathsf{Tom}_i \rangle = \{ \check{\mathscr{C}} \langle A^1_{\mathsf{Tom}_i} \rangle, \check{\mathscr{C}} \langle A^2_{\mathsf{Tom}_i} \rangle, \check{\mathscr{C}} \langle A^3_{\mathsf{Tom}_i} \rangle \}, \ i = 1, 2, 3. \quad \square$ 

Then, the flow of aggregating  $\check{\mathcal{E}}\langle A_{\mathtt{Tom}_{j}}^{j}\rangle$ , j=1,2,3, into  $\check{\mathcal{E}}\langle\mathtt{Tom}_{i}\rangle$  can be depicted as in Figure 13.5.1(p.78) below:

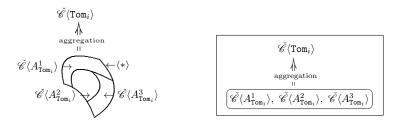


Figure 13.5.1: Aggregation of  $\check{\mathscr{C}}\langle A^1_{\mathtt{Tom}_i} \rangle$ ,  $\check{\mathscr{C}}\langle A^2_{\mathtt{Tom}_i} \rangle$ ,  $\check{\mathscr{C}}\langle A^3_{\mathtt{Tom}_i} \rangle$  into  $\check{\mathscr{C}}\langle \mathtt{Tom}_i \rangle$ 

#### $\bigstar$ Condition-Space $\mathscr{E}\langle \tilde{\mathcal{T}} \text{om} \rangle$

As one corresponding to (12.3.20(p.66)), let us define

$$\check{\mathscr{E}}\langle \tilde{\mathcal{T}} \mathsf{om} \rangle \stackrel{\text{def}}{=} \bigcup_{i=1,2,\cdots} \check{\mathscr{E}}\langle \mathsf{Tom}_i \rangle = \bigcup_{\tilde{\mathsf{Tom}} \in \tilde{\mathcal{T}} \mathsf{om}} \check{\mathscr{E}}\langle \mathsf{Tom} \rangle, \tag{13.5.44}$$

called the *condition space* of  $\tilde{\mathcal{T}}$ om, which is the aggregation of  $\mathscr{E}\langle \tilde{\mathcal{T}}$ om<sub>i</sub> into  $\mathscr{E}\langle \tilde{\mathcal{T}}$ om<sub>j</sub>, depicted as in Figure 13.5.2(p.79) below (compare Figure 12.3.3(p.67)).

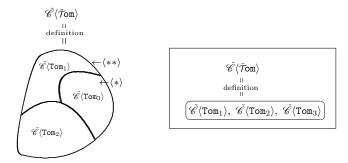


Figure 13.5.2: Condition space  $\check{\mathscr{C}}(\tilde{\mathcal{T}}om)$ 

In the above figure, the *small* deformed circle  $\langle * \rangle$  is the same as the deformed circle  $\langle * \rangle$  in Figure 13.5.1(p.78) and the *big* deformed circle  $\langle ** \rangle$  consists of the three *small* deformed circles including  $\langle * \rangle$ .

### $\bigstar$ Construction of $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}$

Using (13.5.42(p.78)), as ones corresponding to (12.3.22(p.67))-(12.3.24(p.67)), from (13.5.44(p.78)) we have

$$\check{\mathscr{E}}\langle \tilde{\mathcal{T}} \mathsf{om} \rangle = \bigcup_{i=1,2,\cdots} \bigcup_{j=1,2,\cdots} \check{\mathscr{E}}\langle A^j_{\mathsf{Tom}_i} \rangle \tag{13.5.45}$$

$$= \cup_{\mathsf{Tom} \in \tilde{\mathcal{T}}_{\mathsf{om}}} \cup_{j=1,2,\cdots} \check{\mathscr{C}} \langle A^{j}_{\mathsf{Tom}} \rangle \tag{13.5.46}$$

$$= \cup_{\mathsf{Tom} \in \tilde{\mathcal{T}}_{\mathsf{Om}}} \cup_{A_{\mathsf{Tom}} \in \mathsf{Tom}} \check{\mathcal{C}} \langle A_{\mathsf{Tom}} \rangle \tag{13.5.47}$$

Then, noting Figures 13.5.1(p.78) and 13.5.2(p.79), we see from (13.5.45(p.79))-(13.5.47(p.79)) that mingling the three figures for  $\mathcal{E}(\tilde{\mathsf{Tom}}_1)$ ,  $\mathcal{E}(\tilde{\mathsf{Tom}}_2)$ , and  $\mathcal{E}(\tilde{\mathsf{Tom}}_3)$  together yields Figure 13.5.3(p.79) below.

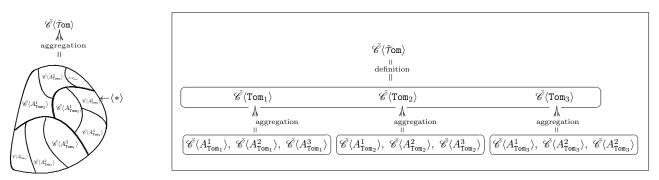


Figure 13.5.3: The aggregation of  $\check{\mathscr{C}}\langle A_{\mathtt{Tom}_{j}}^{j}\rangle$  into  $\check{\mathscr{C}}\langle \tilde{\mathcal{T}} \mathtt{om} \rangle$ 

Figure 13.5.3(p.79) above implies that first

"aggregating 
$$|\widetilde{\mathscr{C}}\langle A_{\mathtt{Tom}_{i}}^{j}\rangle|$$
,  $j=1,2,3,$  for  $i=1,2,3$  produces  $|\widetilde{\mathscr{C}}\langle \mathtt{Tom}_{i}\rangle|$ "

and then

$$\text{``aggregating } \boxed{\check{\mathscr{C}}\langle \mathtt{Tom}_i\rangle}, \ i=1,2,3, \ \mathtt{produces} \ \boxed{\check{\mathscr{C}}\langle \check{\mathcal{T}}\mathtt{om}\rangle} \text{''}.$$

The above two aggregating successive procedures eventually yields

" aggregating 
$$\boxed{\mathscr{C}\langle A^j_{\mathtt{Tom}_i}\rangle}$$
 for  $i,j=1,2,3$  produces  $\boxed{\check{\mathscr{C}}\langle\check{\mathcal{T}}\mathtt{om}\rangle}$ ", (13.5.48)

Moreover, noting  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}$  is associated with  $[\check{\mathscr{C}}(\tilde{\mathsf{Tom}})]$ , we see that Figure 13.5.3(p.79) eventually implies

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\} \text{ holds over } \boxed{\mathring{\mathscr{E}}\langle \tilde{\mathcal{T}} \mathtt{om} \rangle}. \tag{13.5.49}$$

#### $\bigstar$ Completeness of $\tilde{\mathcal{T}}$ om on $\check{\mathscr{E}}\langle \tilde{\mathcal{T}}$ om $\rangle = \mathscr{P} \times \mathscr{F}$

From (12.3.25(p.68)) and (13.5.49(p.79)), we see that aggregating Lemma 13.5.1(p.78) produces Lemma 13.5.2(p.79) below.

**Lemma 13.5.2** Let  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\}\ holds\ on\ \mathscr{C}\langle\mathcal{T}om\rangle$ . Then  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}\ holds\ on\ \mathscr{E}\langle\mathcal{T}om\rangle$  where

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\} = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}]. \quad \Box$$

Here note again (12.3.26(p.68)), i.e.

$$\mathscr{C}\langle \mathsf{Tom}\rangle = \mathscr{P} \times \mathscr{F}. \tag{13.5.50}$$

Whereas we have the following lemma.

#### Lemma 13.5.3 We have

$$\check{\mathscr{E}}\langle \tilde{\mathcal{T}} \mathsf{om} \rangle = \mathscr{P} \times \mathscr{F}. \quad \Box$$
 (13.5.51)

- Proof When  $\mathscr{F}$  in (13.5.14(p.76)) transforms into  $\check{\mathscr{F}}$  in (13.5.15(p.76)), it is clear that the completeness of  $\mathcal{T}$ om on  $\mathscr{C}\langle\mathcal{T}$ om $\rangle = \mathscr{P} \times \mathscr{F}$  is inherited also to the completeness of  $\check{\mathcal{T}}$ om on  $\check{\mathscr{C}}\langle\check{\mathcal{T}}$ om $\rangle = \mathscr{P} \times \check{\mathscr{F}}$ . In addition, since  $\check{\mathscr{F}} = \mathscr{F}$  due to Lemma 13.1.1(p.70) (a), we have  $\check{\mathscr{C}}\langle\check{\mathcal{T}}$ om $\rangle = \mathscr{P} \times \mathscr{F}$ . Below is a more strict proof. First note here that for any given  $\check{F} \in \check{\mathscr{F}}$  there exists a  $F \in \mathscr{F}$  such that  $F \equiv \check{F} \cdots (1)$  (see Lemma 13.1.1(p.70) (b)) and that for any given  $F \in \mathscr{F}$  there exists a  $\check{F} \in \check{\mathscr{F}}$  such that  $\check{F} \equiv F \cdots (2)$  (see Lemma 13.1.1(p.70) (c)).
- o From (13.5.18(p.76)) we have  $\check{\mathcal{C}}\langle A_{\text{Tom}}\rangle \subseteq \{(\boldsymbol{p},\check{F}) \mid \boldsymbol{p} \subseteq \mathscr{P},\check{F} \subseteq \check{\mathscr{F}}\}$  for any  $A_{\text{Tom}}$ , hence due to (1) we get  $\check{\mathcal{C}}\langle A_{\text{Tom}}\rangle \subseteq \{(\boldsymbol{p},F) \mid \boldsymbol{p} \in \mathscr{P}, F \in \check{\mathscr{F}}\} = \mathscr{P} \times \check{\mathscr{F}} = \mathscr{P} \times \mathscr{F}$  due to  $\check{\mathscr{F}} = \mathscr{F}$  from Lemma 13.1.1(p.70) (a). Accordingly, from (13.5.47(p.79)) we obtain  $\check{\mathcal{C}}\langle \tilde{\mathcal{T}} \text{om}\rangle \subseteq \bigcup_{\tilde{\mathsf{Tom}}\in\tilde{\mathsf{Tom}}} \bigcup_{A_{\text{Tom}}\in\tilde{\mathsf{Tom}}} \mathscr{P} \times \mathscr{F} = \mathscr{P} \times \mathscr{F} \cdots$  (3).
- Consider any  $(\boldsymbol{p},F) \in \mathscr{P} \times \mathscr{F} \cdots$  (4). Then, since  $(\boldsymbol{p},F) \in \mathscr{C}\langle \mathsf{Tom} \rangle$  due to (12.3.26(p.68)), we have  $(\boldsymbol{p},F) \in \mathscr{C}\langle A_{\mathsf{Tom}} \rangle$  for at least one  $\mathscr{C}\langle A_{\mathsf{Tom}} \rangle$  due to (12.3.24(p.67)). Hence, since  $F \in \mathscr{F}_{A_{\mathsf{Tom}}|\boldsymbol{p}}$  due to (12.3.7(p.65)), we have  $\check{F} \in \check{\mathscr{F}}_{A_{\mathsf{Tom}}|\boldsymbol{p}}$  due to (13.1.3(p.69)), hence  $(\boldsymbol{p},\check{F}) \in \mathscr{E}\langle A_{\mathsf{Tom}} \rangle$  due to (13.5.18(p.79)), thus  $(\boldsymbol{p},F) \in \mathscr{E}\langle A_{\mathsf{Tom}} \rangle$  due to (2), hence  $(\boldsymbol{p},F) \in \mathscr{E}\langle \tilde{\mathcal{T}}$  due to (3.5.47(p.79)). Accordingly, from (4) we have  $\mathscr{P} \times \mathscr{F} \subseteq \mathscr{C}\langle \tilde{\mathcal{T}}$  om $\rangle \cdots$  (5).

From (3) and (5) we obtain  $\mathcal{E}(\tilde{\mathcal{T}}om) = \mathcal{P} \times \mathcal{F}$ .

Let us refer to the equality (13.5.51(p.80)) as the <u>completeness</u> of  $\tilde{\mathcal{T}}$ om on  $\mathscr{C}\langle \tilde{\mathcal{T}}$ om $\rangle = \mathscr{P} \times \mathscr{F}$ . Then (13.5.48(p.79)) can be rewritten as

"aggregating 
$$\check{\mathcal{E}}\langle A_{\text{Tom.}}^{j}\rangle$$
 for  $i, j = 1, 2, 3$ , produces  $\check{\mathcal{E}}\langle \tilde{\mathcal{T}} \text{om} \rangle = \mathscr{P} \times \mathscr{F}$ ", (13.5.52)

hence Figure 13.5.3(p.79) can be rewritten as Figure 13.5.4(p.80) below.

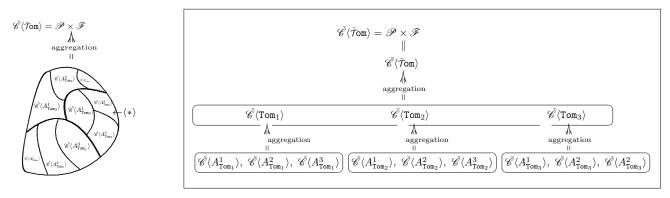


Figure 13.5.4: The complete aggregation of  $\check{\mathscr{E}}\langle A^j_{\mathtt{Tom}_i}\rangle$  into  $\check{\mathscr{E}}\langle \tilde{\mathscr{T}}\mathtt{om}\rangle=\mathscr{P}\times\mathscr{F}$ 

#### ■ Step 7 (symmetry theorem $(\mathbb{R} \to \tilde{\mathbb{R}})$ )

From (13.5.50(p.79)) and (13.5.51(p.80)), it follows that Lemma 13.5.2(p.79) can be rewritten as Theorem 13.5.1(p.80) below.

Theorem 13.5.1 (symmetry theorem  $(\mathbb{R} \to \tilde{\mathbb{R}})$ ) Let  $\mathscr{A}\{M:1[\mathbb{R}][A]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$ . Then  $\mathscr{A}\{\tilde{M}:1[\mathbb{R}][A]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$  where

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}]. \quad \Box$$
 (13.5.53)

Then, clearly the attribute vector of  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}$  becomes as follows (see (13.5.35(p.77)))

$$\boldsymbol{\theta}(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}) = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\boldsymbol{\theta}(\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\})]$$
(13.5.54)  
$$= (b,\mu,a,\ x_{\tilde{L}},\ x_{\tilde{K}},\ s_{\tilde{\mathcal{L}}},\tilde{\kappa},\tilde{T},\tilde{L},\tilde{K},\tilde{\mathcal{L}},V_t)$$
(13.5.55)  
$$\uparrow$$
 aggregation scenario

#### ■ Step 8 (summary of Scenario $[\mathbb{R}]$ )

At a glance, the symmetry transformation operation  $S_{\mathbb{R}\to\tilde{\mathbb{R}}}$  seems to be rather complicated, however it can be simply prescribed as follows.

- Firstly, apply the reflection operation  $\mathcal{R}$  to all *reflective* elements (see Defs 13.3.3(p.73)) appearing within the description of  $\mathscr{A}\{M:1[\mathbb{R}][A]\}$  (see Tom's 12.2.1(p.61) and 12.2.2(p.62)).
- $\circ$  Next, replace each of all elements, whether resultant ones (reflective) or non-reflective ones, with the right side of its corresponding equality in Lemma 13.3.1(p.72) (correspondence replacement operation  $\mathcal{C}_{\mathbb{R}}$ ).
- $\circ$  Finally, remove the check sign " $\circ$ " from all the replaced symbols (identity replacement operation  $\mathcal{I}_{\mathbb{R}}$ ).  $\square$

## 13.6 Derivation of $\tilde{T}_{\mathbb{R}}$ , $\tilde{L}_{\mathbb{R}}$ , $\tilde{K}_{\mathbb{R}}$ , $\tilde{\mathcal{L}}_{\mathbb{R}}$ , and $\tilde{\kappa}_{\mathbb{R}}$

To begin with, let us note here the fact that Scenario [ $\mathbb{R}$ ] is a scenario which is applicable for an assertion  $A\{M:1[\mathbb{R}][A]\}$  related to the attribute vector (see Section 13.4(p.74))

$$\boldsymbol{\theta} = (a, \mu, b, x_L, x_K, s_{\mathcal{L}}, \kappa, T, L, K, \mathcal{L}, V_t).$$

Then it can be immediately seen that the scenario can be always applied also to any assertions involved with the attribute vector  $\boldsymbol{\theta}$ . Accordingly, applying it to any assertion on  $T_{\mathbb{R}}$ ,  $L_{\mathbb{R}}$ ,  $K_{\mathbb{R}}$ ,  $L_{\mathbb{R}}$ , and  $K_{\mathbb{R}}$  yields its corresponding assertion on  $\tilde{T}_{\mathbb{R}}$ ,  $\tilde{L}_{\mathbb{R}}$ ,  $\tilde{K}_{\mathbb{R}}$ ,  $\tilde{L}_{\mathbb{R}}$ , and  $\tilde{K}_{\mathbb{R}}$ , i.e.,

$$\mathscr{A}\{\tilde{T}_{\mathbb{R}},\tilde{L}_{\mathbb{R}},\tilde{K}_{\mathbb{R}},\tilde{\mathcal{L}}_{\mathbb{R}},\tilde{\kappa}_{\mathbb{R}}\}=\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{T_{\mathbb{R}},L_{\mathbb{R}},K_{\mathbb{R}},\mathcal{L}_{\mathbb{R}},\kappa_{\mathbb{R}}\}].$$

Accordingly, we have the following lemma:

#### **Lemma 13.6.1** $(\mathscr{A}\{\tilde{T}_{\mathbb{R}}\})$ For any $F \in \mathscr{F}$ :

- (a)  $\tilde{T}(x)$  is continuous on  $(-\infty, \infty)$ .
- (b)  $\tilde{T}(x)$  is nonincreasing on  $(-\infty, \infty)$ .
- (c)  $\tilde{T}(x)$  is strictly decreasing on  $[a, \infty)$ .
- (d)  $\tilde{T}(x) + x$  is nondecreasing on  $(-\infty, \infty)$ .
- (e)  $\tilde{T}(x) + x$  strictly increasing on  $(-\infty, b]$ .
- (f)  $\tilde{T}(x) = \mu x$  on  $[b, \infty)$  and  $\tilde{T}(x) < \mu x$  on  $(-\infty, b)$ .
- (g)  $\tilde{T}(x) < 0$  on  $(a, \infty)$  and  $\tilde{T}(x) = 0$  on  $(-\infty, a]$ .
- (h)  $\tilde{T}(x) \le \min\{0, \mu x\}$  on  $x \in (-\infty, \infty)$ .
- (i)  $\tilde{T}(0) = 0 \text{ if } a > 0 \text{ and } \tilde{T}(0) = \mu \text{ if } b < 0.$
- (j)  $\beta \tilde{T}(x) + x$  is nondecreasing on  $(-\infty, \infty)$  if  $\beta = 1$ .
- (k)  $\beta \tilde{T}(x) + x$  is strictly increasing on  $(-\infty, \infty)$  if  $\beta < 1$ .
- (1) If x > y and b > y, then  $\tilde{T}(x) + x > \tilde{T}(y) + y$ .
- (m)  $\lambda \beta \tilde{T}(\lambda \beta \mu + s) + s$  is nondecreasing in s and strictly increasing in s if  $\lambda \beta < 1$ .
- (n)  $b > \mu$ .
- Proof by symmetry The lemma, excluding (a,n), can be easily obtained by applying  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Lemmas 11.1.1(p.55) as shown below.
  - (a) Evident from the fact that  $\min\{\xi x, 0\}$  in (6.1.11(p.25)) is continuous on  $(-\infty, \infty)$ .
- (b) Lemma 11.1.1(p.55) (b) can be rewritten as  $A = \{T(x) \geq \tilde{T}(x') \text{ for } x < x'\}$ . Applying  $\mathcal{R}$  to this yields  $\mathcal{R}[A] = \{-\hat{T}(x) \geq -\hat{T}(x') \text{ for } -\hat{x} < -\hat{x}'\} = \{\hat{T}(\hat{x}) \leq \hat{T}(\hat{x}') \text{ for } \hat{x} > \hat{x}'\}$ , and then applying  $\mathcal{C}_{\mathbb{R}}$  to this produces  $\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\check{T}(\hat{x}) \leq \check{T}(\hat{x}') \text{ for } \hat{x} > \hat{x}'\}$ . Finally, applying  $\mathcal{I}_{\mathbb{R}}$  to this leads to  $\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\check{T}(\hat{x}) \leq \check{T}(\hat{x}') \text{ for } \hat{x} > \hat{x}'\}$ . Without loss of generality, this can be rewritten as  $\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A = \{\check{T}(x) \leq \check{T}(x') \text{ for } x > x'\}$ , meaning that  $\check{T}(x)$  is nonincreasing on  $(-\infty, \infty)$ .
  - (c-e) Almost the same as the proof of (b)
- (f) Let the former half of Lemma 11.1.1(p.55) (f) can by rewritten as  $A = \{T(x) = \mu x \text{ for } x \leq a\}$ . Applying  $\mathcal{R}$  to this yields  $\mathcal{R}[A] = \{-\hat{T}(x) = -\hat{\mu} + \hat{x} \text{ for } -\hat{x} \leq -\hat{a}\} = \{\hat{T}(x) = \hat{\mu} \hat{x} \text{ for } \hat{x} \geq \hat{a}\}$ , and then applying  $\mathcal{C}_{\mathbb{R}}$  to this produces  $\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\check{T}(\hat{x}) = \check{\mu} \hat{x} \text{ for } \hat{x} \geq \check{b}\}$ . Finally, applying  $\mathcal{I}_{\mathbb{R}}$  to this lead to  $\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\check{T}(\hat{x}) = \mu \hat{x} \text{ for } \hat{x} \geq b\}$ . Without loss of generality, this can be rewritten as  $\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\check{T}(x) = \mu x \text{ for } x \geq b\} = \{\check{T}(x) = \mu x \text{ on } [b, \infty)\}$ . The proof of the latter half is almost the same as the above.
- (g) The former half of Lemma 11.1.1(p.55) (g) can be rewritten by  $A = \{T(x) > 0 \text{ for } x < b\}$ . Applying  $\mathcal{R}$  to this yields  $\mathcal{R}[A] = \{-\hat{T}(x) > 0 \text{ for } -\hat{x} < -\hat{b}\} = \{\hat{T}(x) < 0 \text{ for } \hat{x} > \hat{b}\}$ , and then applying  $\mathcal{C}_{\mathbb{R}}$  to this produces  $\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\check{T}(\hat{x}) < 0 \text{ for } \hat{x} > \check{a}\}$ . Finally, applying  $\mathcal{I}_{\mathbb{R}}$  to this leads to  $\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\check{T}(\hat{x}) < 0 \text{ for } \hat{x} > a\}$ . Without loss of generality, this can be rewritten as  $\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\check{T}(x) < 0 \text{ for } x > a\} = \{\check{T}(x) < 0 \text{ on } (a, \infty)\}$ . The proof of the latter half is almost the same as the above.
- (h) Applying  $\mathcal{R}$  to Lemma 11.1.1(p.55) (h) yields  $\mathcal{R}[A] = \{-\hat{T}(x) \geq \max\{0, -\hat{\mu} + \hat{x}\} \text{ for } -\infty < -\hat{x} < \infty\} = \{\hat{T}(x) \leq \min\{0, \hat{\mu} \hat{x}\} \text{ for } \infty > \hat{x} > -\infty\}$ , and then applying  $\mathcal{C}_{\mathbb{R}}$  to this produces  $\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\check{T}(\hat{x}) \leq \min\{0, \check{\mu} \hat{x}\} \text{ for } \infty > \hat{x} > -\infty\}$ . Finally, applying  $\mathcal{L}_{\mathbb{R}}$  to this leads to  $\mathcal{L}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\check{T}(\hat{x}) \leq \min\{0, \mu \hat{x}\} \text{ for } \infty > \hat{x} > -\infty\}$ . Without loss of generality, this can be rewritten as  $\mathcal{L}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\check{T}(x) \leq \min\{0, \mu x\} \text{ for } \infty > x > -\infty\} = \{\check{T}(x) \leq \min\{0, \mu x\} \text{ on } (-\infty, \infty)\}$ .
- (i) Immediate from  $\tilde{T}(0) = \mathbf{E}[\min\{\xi, 0\}] = \mathbf{E}[\min\{\xi, 0\}I(a \le \xi \le b)]$  from (6.1.11(p.25)) and (2.2.3(p.13)).
  - (j,k) Almost the same as the proof of (b and c)
- (l) Lemma 11.1.1(p.55) (l) can be rewritten as  $A = \{\text{If } x < y \text{ and } a < y, \text{ then } T(x) + x < T(y) + y\}$ . Applying  $\mathcal{R}$  to this yields  $\mathcal{R}[A] = \{\text{If } -\hat{x} < -\hat{y} \text{ and } -\hat{a} < -\hat{y}, \text{ then } -\hat{T}(x) \hat{x} < -\hat{T}(y) \hat{y}\} = \{\text{If } \hat{x} > \hat{y} \text{ and } \hat{a} > \hat{y}, \text{ then } \hat{T}(x)\hat{x} > T(y) + \hat{y}\}$ , and then applying  $\mathcal{C}_{\mathbb{R}}$  to this produces  $\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\text{If } \hat{x} > \hat{y} \text{ and } \hat{b} > \hat{y}, \text{ then } \hat{T}(\hat{x}) + \hat{x} > \hat{T}(\hat{y}) + \hat{y}\} = \{\text{If } x > y \text{ and } \hat{b} > y, \text{ then } \hat{T}(x) + x > \hat{T}(y) + y\}$ . Finally, applying  $\mathcal{I}_{\mathbb{R}}$  to this leads to  $\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\text{If } x > y \text{ and } b > y, \text{ then } \hat{T}(x) + x > \hat{T}(y) + y\}$ .
- (m) The former half of Lemma 11.1.1(p.55) (m) can be rewritten as Let  $A = \{\lambda \beta T(\lambda \beta \mu s) s \text{ is nonincreasing in } s\}$ , which can be rewritten as  $A = \{\lambda \beta T(\lambda \beta \mu s) s \ge \lambda \beta T(\lambda \beta \mu s') s' \text{ for } s < s'\}$ . Applying  $\mathcal{R}$  to this yields  $\mathcal{R}[A] = \{-\lambda \beta \hat{T}(-\lambda \beta \hat{\mu} s) s \ge \lambda \beta T(\lambda \beta \mu s') s' \text{ for } s < s'\}$ .

 $-\lambda\beta\hat{T}(-\lambda\beta\hat{\mu}-s')-s' \text{ for } s < s'\} = \{\lambda\beta\hat{T}(-\lambda\beta\hat{\mu}-s)+s \leq \lambda\beta\hat{T}(-\lambda\beta\hat{\mu}-s')+s' \text{ for } s < s'\},^{\dagger} \text{ and then applying } \mathcal{C}_{\mathbb{R}} \text{ to this produces } s' \in \mathcal{C}_{\mathbb{R}} \text{ for } s < s' \in \mathcal{C}_{\mathbb{R}} \text{ and then applying } \mathcal{C}_{\mathbb{R}} \text{ for } s < s' \in \mathcal{C}_{\mathbb{$  $C_{\mathbb{R}}\mathcal{R}[A] = \{\lambda\beta\hat{T}(-\lambda\beta\check{\mu} - s) + s \le \lambda\beta\hat{T}(-\lambda\beta\check{\mu} - s') + s' \text{ for } s < s'\} = \{\lambda\beta\hat{T}(\lambda\beta\check{\mu} + s) + s \le \lambda\beta\hat{T}(\lambda\beta\check{\mu} + s') + s' \text{ for } s < s'\}.$  Finally, applying  $\mathcal{I}_{\mathbb{R}}$  to this leads to  $\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\lambda\beta\tilde{T}(\lambda\beta\mu + s) + s \leq \lambda\beta\tilde{T}(\lambda\beta\mu + s') + s' \text{ for } s < s'\}$ , meaning that  $\lambda\beta\tilde{T}(\lambda\beta\mu + s) + s$ is nondecreasing in s. Similarly, the latter half of Lemma 11.1.1(p.55) (m) can be rewritten as  $\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\lambda\beta\tilde{T}(\lambda\beta\mu + s) + s < 1\}$  $\lambda \beta \tilde{T}(\lambda \beta \mu + s') + s'$  for s < s', meaning that  $\lambda \beta \tilde{T}(\lambda \beta \mu + s) + s$  is nonincreasingness in s.

- (n) Clear from (2.2.2(p.12)). ■
- Direct proof See Section A 1.1(p.298) . ■

We have:

$$\tilde{L}(x) \begin{cases} = \lambda \beta \mu + s - \lambda \beta x \text{ on } [b, -\infty) & \cdots (1), \\ < \lambda \beta \mu + s - \lambda \beta x \text{ on } (-\infty, b) & \cdots (2), \end{cases}$$
(13.6.1)

$$\tilde{K}(x) \begin{cases}
= \lambda \beta \mu + s - \delta x & \text{on} \quad [b, \infty) & \cdots (1), \\
< \lambda \beta \mu + s - \delta x & \text{on} \quad (-\infty, b) & \cdots (2).
\end{cases}$$
(13.6.2)

$$\tilde{K}(x) \begin{cases}
= \lambda \beta \mu + s - \delta x & \text{on} \quad [b, \infty) & \cdots (1), \\
< \lambda \beta \mu + s - \delta x & \text{on} \quad (-\infty, b) & \cdots (2).
\end{cases}$$

$$\tilde{K}(x) \begin{cases}
< -(1 - \beta)x + s & \text{on} \quad (a, \infty) & \cdots (1), \\
= -(1 - \beta)x + s & \text{on} \quad (-\infty, a] & \cdots (2),
\end{cases}$$
(13.6.2)

$$\tilde{K}(x) + x \le \beta x + s$$
 on  $(-\infty, \infty)$ . (13.6.4)

$$\tilde{K}(x) + x = \begin{cases}
\lambda \beta \mu + s + (1 - \lambda) \beta x \text{ on } [b, \infty) & \cdots (1), \\
\beta x + s & \text{on } (-\infty, a] & \cdots (2).
\end{cases}$$
(13.6.5)

$$\tilde{K}(x_{\tilde{L}}) = -(1-\beta) x_{\tilde{L}} \cdots (1), \quad \tilde{L}(x_{\tilde{K}}) = (1-\beta) x_{\tilde{K}} \cdots (2). \tag{13.6.6}$$

- Proof by symmetry Obtained by applying  $S_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to (11.2.3(p.57)) (11.2.8(p.57)).
- Direct proof See (A 1.1(p.299))-(A 1.6(p.300)). ■

#### Lemma 13.6.2 $(\mathscr{A}\{\tilde{L}_{\mathbb{R}}\})$

- (a)  $\tilde{L}(x)$  is continuous on  $(-\infty, \infty)$ .
- $\tilde{L}(x)$  is nonincreasing on  $(-\infty, \infty)$ .
- (c)  $\tilde{L}(x)$  is strictly decreasing on  $[a, \infty)$ .
- (d) Let s=0. Then  $x_{\tilde{L}}=a$  where  $x_{\tilde{L}}<(\geq)$   $x\Leftrightarrow \tilde{L}(x)<(=)$   $0\Rightarrow \tilde{L}(x)<(\geq)$  0.
- (e) Let s > 0.
  - 1.  $x_{\tilde{L}}$  uniquely exists with  $x_{\tilde{L}} > a$  where  $x_{\tilde{L}} < (=(>))$   $x \Leftrightarrow \tilde{L}(x) < (=(>))$  0.
  - $(\lambda \beta \mu + s)/\lambda \beta \ge (<) b \Leftrightarrow x_{\tilde{L}} = (<) (\lambda \beta \mu + s)/\lambda \beta \ge (<) b. \square$
- Proof by symmetry Obtained by applying  $S_{\mathbb{R} \to \tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Lemmas 11.2.1(p.57)
- Direct proof See Lemma A 1.2(p.300) . ■

### Corollary 13.6.1 $(\mathscr{A}\{\tilde{L}_{\mathbb{R}}\})$

- $x_{\tilde{L}} < (\geq) x \Leftrightarrow \tilde{L}(x) < (\geq) 0.$
- $x_{\tilde{L}} \leq (\geq) x \Rightarrow \tilde{L}(x) \leq (\geq) 0.$
- Proof by symmetry Obtained by applying  $S_{\mathbb{R} \to \tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Corollaries 11.2.1(p.57)
- ullet Direct proof See Corollary A 1.1(p.300) .  $\blacksquare$

#### Lemma 13.6.3 $(\mathscr{A}\{\tilde{K}_{\mathbb{R}}\})$

- $\tilde{K}(x)$  is continuous on  $(-\infty, \infty)$ .
- $\tilde{K}(x)$  is nonincreasing on  $(-\infty, \infty)$ . (b)
- $\tilde{K}(x)$  is strictly decreasing on  $[a, \infty)$ . (c)
- $\tilde{K}(x)$  is strictly decreasing on  $(-\infty, \infty)$  if  $\beta < 1$ . (d)
- $\tilde{K}(x) + x$  is nondecreasing on  $(-\infty, \infty)$ . (e)
- K(x) + x is strictly increasing on  $(-\infty, b]$ .
- $\tilde{K}(x) + x$  is strictly increasing on  $(-\infty, \infty)$  if  $\lambda < 1$ .
- If x > y and b > y, then  $\tilde{K}(x) + x > \tilde{K}(y) + y$ .
- $\text{(i)} \quad \text{Let } \beta = 1 \text{ and } s = 0. \text{ Then } x_{\tilde{K}} = a \text{ where } x_{\tilde{K}} < (\geq) \ x \Leftrightarrow \tilde{K}(x) < (=) \ 0 \Rightarrow \tilde{K}(x) < (\geq) \ 0.$
- - 1. There uniquely exists  $x_{\tilde{K}}$  where  $x_{\tilde{K}} < (=(>)) x \Leftrightarrow \tilde{K}(x) < (=(>)) 0$ .

<sup>&</sup>lt;sup>†</sup>Note Def. 13.3.3(p.73)).

- 2.  $(\lambda \beta \mu + s)/\delta \ge (<) b \Leftrightarrow x_{\tilde{K}} = (<) (\lambda \beta \mu + s)/\delta$ .
- 3. Let  $\tilde{\kappa} < (=(>))$  0. Then  $x_{\tilde{\kappa}} < (=(>))$  0.  $\square$
- Proof by symmetry Obtained by applying  $S_{\mathbb{R} \to \tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Lemmas 11.2.2(p.57).
- ullet Direct proof See Lemma A 1.3(p.300) .  $\blacksquare$

#### Corollary 13.6.2 $(\mathscr{A}\{\tilde{K}_{\mathbb{R}}\})$

- (a)  $x_{\tilde{K}} < (\geq) x \Leftrightarrow \tilde{K}(x) < (\geq) 0.$
- (b)  $x_{\tilde{K}} \leq (\geq) x \Rightarrow \tilde{K}(x) \leq (\geq) 0.$
- Proof by symmetry Obtained by applying  $S_{\mathbb{R} \to \tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Corollaries 11.2.2(p.58).
- Direct proof See Corollary A 1.2(p.301) .

#### Lemma 13.6.4 $(\mathscr{A}\{\tilde{L}_{\mathbb{R}}/\tilde{K}_{\mathbb{R}}\})$

- (a) Let  $\beta = 1$  and s = 0. Then  $x_{\tilde{L}} = x_{\tilde{K}} = a$ .
- (b) Let  $\beta = 1$  and s > 0. Then  $x_{\tilde{L}} = x_{\tilde{K}}$ .
- (c) Let  $\beta < 1$  and s = 0. Then a < (= (>))  $0 \Leftrightarrow x_{\tilde{L}} < (= (>))$   $x_{\tilde{K}} \Rightarrow x_{\tilde{K}} < (= (=))$  0.
- (d) Let  $\beta < 1$  and s > 0. Then  $\tilde{\kappa} < (=(>))$   $0 \Leftrightarrow x_{\tilde{L}} < (=(>))$   $x_{\tilde{K}} \Rightarrow x_{\tilde{K}} < (=(>))$  0.  $\square$
- Proof by symmetry Obtained by applying  $S_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Lemmas 11.2.3(p.58).

#### Lemma 13.6.5 $(\mathscr{A}\{\tilde{\mathcal{L}}_{\mathbb{R}}\})$

- (a)  $\tilde{\mathcal{L}}(s)$  is nondecreasing in s and is strictly increasing in s if  $\lambda \beta < 1$ .
- (b) Let  $\lambda \beta \mu \leq a$ .
  - 1.  $x_{\tilde{L}} \geq \lambda \beta \mu + s$ .
  - 2. Let s > 0 and  $\lambda \beta < 1$ . Then  $x_{\tilde{L}} > \lambda \beta \mu + s$ .
- (c) Let  $\lambda \beta \mu > a$ . Then, there exists a  $s_{\tilde{L}} > 0$  such that if  $s_{\tilde{L}} > (\leq) s$ , then  $x_{\tilde{L}} < (\geq) \lambda \beta \mu + s$ .  $\square$
- Proof by symmetry Obtained by applying  $S_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Lemmas 11.2.4(p.59).
- Direct proof See Lemma A 1.5(p.302) .

#### Lemma 13.6.6 $(\tilde{\kappa}_{\mathbb{R}})$ We have:

- (a)  $\tilde{\kappa} = \lambda \beta \mu + s \text{ if } b < 0 \text{ and } \tilde{\kappa} = s \text{ if } a > 0.$
- (b) Let  $\beta < 1$  or s > 0. Then  $\tilde{\kappa} < (=(>)) 0 \Leftrightarrow x_{\tilde{\kappa}} < (=(>)) 0$ .
- Proof Obtained by applying  $S_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Lemmas 11.3.1(p.59).
- Direct proof See Lemma A 1.6(p.302) . ■

# 13.7 Derivation of $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}$

**Lemma 13.7.1** ( $\tilde{\mathbb{M}}:1[\mathbb{R}][A]$ ) The optimal initiating time  $t_{\tau}^*$  (OIT) is not subject to the influence of the symmetry transformation operation  $\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}$  (see (13.5.29(p.77))).  $\square$ 

• Proof First, let us represent (8.2.4(p.44)) as  $D \stackrel{\text{def}}{=} \{I_{\tau}^{t_{\tau}^{*}} \geq I_{\tau}^{t} \text{ for } \tau \geq t \geq t_{qd}\} \cdots$  (1), which can be rewritten as  $D = \{\beta^{\tau - t_{\tau}^{*}} V_{t_{\tau}^{*}} \geq \beta^{\tau - t} V_{t} \text{ for } \tau \geq t \geq t_{qd}\}$ . Next, applying  $\mathcal{R}$  to this yields  $\mathcal{R}[D] = \{-\beta^{\tau - t_{\tau}^{*}} \hat{V}_{t_{\tau}^{*}} \geq -\beta^{\tau - t} \hat{V}_{t} \text{ for } \tau \geq t \geq t_{qd}\} = \{\beta^{\tau - t_{\tau}^{*}} \hat{V}_{t_{\tau}^{*}} \leq \beta^{\tau - t} \hat{V}_{t} \text{ for } \tau \geq t \geq t_{qd}\}$ . Then, even if applying  $\mathcal{C}_{\mathbb{R}}$  (Lemma 13.3.1(p.72)) to this, no change occurs, i.e.,  $\mathcal{C}_{\mathbb{R}}\mathcal{R}[D] = \{\beta^{\tau - t_{\tau}^{*}} \hat{V}_{t_{\tau}^{*}} \leq \beta^{\tau - t} \hat{V}_{t} \text{ for } \tau \geq t \geq t_{qd}\}$ . Finally, applying  $\mathcal{I}_{\mathbb{R}}$  (Lemma 13.3.3(p.73)) to this, we have  $\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\beta^{\tau - t_{\tau}^{*}} \hat{V}_{t_{\tau}^{*}} \leq \beta^{\tau - t} \hat{V}_{t} \text{ for } \tau \geq t \geq t_{qd}\}$ . Then, since  $\hat{V}_{t}$  changes into  $V_{t}$  for the same reason as been stated just below (13.5.20(p.76)), so we have  $\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[A] = \{\beta^{\tau - t_{\tau}^{*}} V_{t_{\tau}^{*}} \leq \beta^{\tau - t} V_{t} \text{ for } \tau \geq t \geq t_{qd}\}$ . (2). The above result means that the optimal initiating time is  $t_{\tau}^{*}$  even if  $\mathcal{S}_{\mathbb{R}} \to \mathbb{R}$ , i.e.,  $\{I_{\tau}^{t_{\tau}^{*}} \leq I_{\tau}^{t} \text{ for } \tau \geq t \geq t_{qd}\} \cdots$  (2). ■

**Definition 13.7.1** ( $\blacksquare$  Tom and  $\boxdot$  Tom) The assertion system  $\mathscr{A}\{M:1[\mathbb{R}][A]\}$  is directly proven in  $\blacksquare$  Tom 12.2.1(p.61) and  $\blacksquare$  Tom 12.2.2(p.62); however, the assertion system  $\mathscr{A}\{\tilde{M}:1[\mathbb{R}][A]\}$  is indirectly derived in  $\blacksquare$  Tom 13.7.1(p.83) and  $\blacksquare$  Tom 13.7.2(p.84) just below through the application of the symmetry transformation operation  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}$  to the above two  $\blacksquare$  Tom's. In this sense, let us refer to each of the above two  $\blacksquare$  Tom's as the primitive-Tom and to each of the latter two  $\blacksquare$  Tom's as the derivative-Tom.  $\blacksquare$ 

- $\square$  Tom 13.7.1 ( $\mathscr{A}_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}$ ) Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in t > 0.
- (b) We have  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}$  where  $CONDUCT_{\tau>t>1}$ .

- Proof by symmetry Immediately obtained by applying  $\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Tom 12.2.1(p.61).
- Direct proof See Tom A 4.1(p.312) .
- $\square$  Tom 13.7.2 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}$ ) Let  $\beta<1$  or s>0.
- (a)  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $\beta \mu \leq a$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
- (c) Let  $\beta \mu > a$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $\mu + s \geq b$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $\mu + s < b$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}$  where  $\text{CONDUCT}_{\tau \geq t > 1}$ .
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let a < 0 ( $\tilde{\kappa} < 0$ ). Then subseteq subseteq subseteq where subseteq where subseteq subseteq
    - ii. Let a=0 ( $\tilde{\kappa}=0$ ).
      - 1. Let  $\beta \mu + s \geq b$ . Then  $\boxed{\bullet dOITd_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
      - $2. \quad Let \ \beta \mu + s < b. \ \ Then \ \boxed{\$ \ \text{dOITs}_{\tau > 1} \langle \tau \rangle} \ _{\blacktriangle} \ \ where \ \ \text{CONDUCT}_{\tau \geq t > 1} \ _{\blacktriangle}.$
    - iii. Let a > 0 ( $\tilde{\kappa} > 0$ ).
      - 1. Let  $\beta \mu + s \geq \tilde{b}$  or  $s_{\tilde{\mathcal{L}}} \leq s$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
      - 2. Let  $\beta \mu + s < b$  and  $s_{\tilde{\mathcal{L}}} > s$ . Then  $S_1(p.61)$   $s \neq 0$  is true.  $\Box$
- Proof by symmetry Immediately obtained by applying  $S_{\mathbb{R}\to \widetilde{\mathbb{R}}}$  (see (20.0.1 (p.136))) to Tom 12.2.2 (p.62).
- Direct proof See Tom A 4.2(p.313) .

### 13.8 $\tilde{\mathbf{S}}$ cenario $[\mathbb{R}]$

In this section we write up the inverse of Scenario[ $\mathbb{R}$ ](p.75) which derives  $\mathscr{A}$ {M:1[ $\mathbb{R}$ ][A]} (see Tom's 12.2.1(p.61) and 12.2.2(p.62)) from  $\mathscr{A}$ { $\tilde{\mathsf{M}}$ :1[ $\mathbb{R}$ ][A]} (see Tom's 13.7.1(p.83) and 13.7.2(p.84)). Let us represent this scenario as  $\tilde{\mathsf{S}}$ cenario[ $\mathbb{R}$ ].

#### ■ Štep 1 (opening)

• The system of optimality equation of  $\tilde{M}:1[\mathbb{R}][A]$  is given by Table 7.4.1(p.41) (II), i.e.,

$$SOE\{\tilde{M}:1[\mathbb{R}][A]\} = \{V_1 = \beta \mu + s, V_t = \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \quad t > 1\}.$$
(13.8.1)

 $\circ$  Let us consider an assertion  $A_{\text{Tom}}\{\tilde{\mathbf{M}}:1[\mathbb{R}][\mathbf{A}]\}$  in each of Tom's 13.7.1(p.83) and 13.7.2(p.84), which can be rewritten as

$$A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\} = \{\tilde{\mathsf{S}} \text{ is true for } \boldsymbol{p} \in \mathscr{P}_{A_{\text{Tom}}} \subseteq \mathscr{P} \text{ and } F \in \mathscr{F}_{A_{\text{Tom}}|\boldsymbol{p}} \text{ with } \boldsymbol{p} \in \mathscr{P}_{A_{\tilde{\mathsf{Tom}}}} \subseteq \mathscr{F}\}$$

$$= \{\tilde{\mathsf{S}} \text{ is true on } \check{\mathscr{C}}\langle A_{\text{Tom}}\rangle\} \quad (\text{see } (13.5.31(p.77)))$$

$$(13.8.2)$$

where

$$\check{\mathscr{E}}\langle A_{\mathsf{Tom}}\rangle \ \stackrel{\scriptscriptstyle\mathsf{def}}{=} \ \{(\boldsymbol{p},F) \ \big| \ \boldsymbol{p} \in \mathscr{P}_{A_{\mathsf{Tom}}} \subseteq \mathscr{P}, \, F \in \mathscr{F}_{A_{\mathsf{Tom}}|\boldsymbol{p}} \subseteq \mathscr{F}\}.$$

To facilitate the understanding of the discussion that follows let us use the following example.

$$\tilde{\mathsf{S}} = \langle V_t - s_{\tilde{\mathcal{L}}} + x_{\tilde{\mathcal{L}}} + \tilde{\kappa} + b + \mu + a \leq 0, \ t > 0 \rangle \quad (\text{see } (13.5.33(\text{p.77}))).$$

• The attribute vector of the assertion  $A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}$  is given by (13.5.36(p.77)), i.e.,

$$\boldsymbol{\theta}(A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbf{A}]\}) = (b,\mu,a, x_{\tilde{L}}, x_{\tilde{K}}, s_{\tilde{\mathcal{L}}}, \tilde{\kappa}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_t). \tag{13.8.3}$$

- $\tilde{S}$ tep **2** (reflection operation  $\mathcal{R}$ )
- o Applying the reflection operation  $\mathcal{R}$  to (13.8.1(p.84)) produces

$$\mathcal{R}[\mathsf{SOE}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}] = \{-\hat{V}_1 = -\beta\hat{\mu} + s, -\hat{V}_t = \min\{-\hat{K}(V_{t-1}) - \hat{V}_{t-1}, -\beta\hat{V}_{t-1}\}, \ t > 1\}$$

$$= \{-\hat{V}_1 = -\beta\hat{\mu} + s, -\hat{V}_t = -\max\{\hat{K}(V_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}\}$$

$$= \{\hat{V}_1 = \beta\hat{\mu} - s, \hat{V}_t = \max\{\hat{K}(V_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \ t > 1\}.$$

$$(13.8.4)$$

 $\circ$  Applying  $\mathcal{R}$  to (13.8.2(p.84)) yields to

$$\mathcal{R}[A_{\mathsf{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}] = \{\mathcal{R}[\tilde{\mathsf{S}}] \text{ is true on } \check{\mathcal{E}}\langle A_{\mathsf{Tom}}\rangle \}. \tag{13.8.5}$$

For our example we have:

$$\mathcal{R}[\tilde{S}] = \langle -\hat{V}_t - s_{\tilde{\mathcal{L}}} - \hat{x}_{\tilde{L}} - \hat{\kappa} - \hat{b} - \hat{\mu} - \hat{a} \leq 0, \ t > 0 \rangle$$

$$= \langle \hat{V}_t + s_{\tilde{\mathcal{L}}} + \hat{x}_{\tilde{L}} + \hat{\kappa} + \hat{b} + \hat{\mu} + \hat{a} \geq 0, \ t > 0 \rangle.$$
(13.8.6)

• The attribute vector of the assertion  $\mathcal{R}[A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}]$  is given by applying  $\mathcal{R}$  to (13.5.36(p.77)), i.e.,

$$\theta(\mathcal{R}[A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}]) \stackrel{\text{def}}{=} \mathcal{R}[\theta(A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\})] 
= (\hat{b},\hat{\mu},\hat{a},\,\hat{x}_{\tilde{L}},\,\hat{x}_{\tilde{K}},\,s_{\tilde{\mathcal{E}}},\hat{\kappa},\hat{T},\,\hat{L},\,\hat{K},\,\hat{\mathcal{E}},\,\hat{V}_{t}).$$
(13.8.7)

#### ■ $\tilde{\mathsf{S}}\mathsf{tep}\ \mathbf{3}$ (correspondence replacement operation $\tilde{\mathcal{C}}_{\mathbb{R}}$ )

 $\circ$  Here let us consider the application of the correspondence replacement operation  $\tilde{\mathcal{C}}_{\mathbb{R}}$ , i.e., the replacement of the left-hand side of each equality in Lemma 13.3.2(p.72).

$$\hat{b}, \hat{\mu}, \hat{a}, \hat{x}_{\tilde{L}}, \hat{x}_{\tilde{K}}, s_{\tilde{\mathcal{L}}}, \hat{\hat{\kappa}}, \hat{\tilde{T}}(x), \hat{\tilde{L}}(x), \hat{\tilde{K}}(x), \hat{\tilde{\mathcal{L}}}(s) \cdots (1^*)$$

by its right-hand side

$$\check{a}, \check{\mu}, \check{b}, \check{x}_L, \check{x}_K, s_{\check{L}}, \check{\kappa}, \check{T}(\hat{x}), \check{L}(\hat{x}), \check{K}(\hat{x}), \check{\mathcal{L}}(s) \cdots (2^*)$$

where  $(1^*)$  is for any  $F \in \mathscr{F}$  and  $(2^*)$  is for  $\check{F} \in \check{\mathscr{F}}$  corresponding to the  $F \in \mathscr{F}$ .

• Applying  $\tilde{\mathcal{C}}_{\mathbb{R}}$  to (13.8.4(p.84)) leads to

$$\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[\mathtt{SOE}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}] = \mathtt{SOE}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\} = \{\hat{V}_1 = \beta\check{\mu} - s, \ \hat{V}_t = \max\{\check{K}(\hat{V}_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \ t > 1\}. \quad (13.8.8)$$

• Applying  $\tilde{\mathcal{C}}_{\mathbb{R}}$  to  $\mathcal{R}[\tilde{S}]$  in (13.8.6(p.84)), we have

$$\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[\tilde{\mathsf{S}}] = \langle \hat{V}_t + s_{\check{\kappa}} + \check{x}_L + \check{\kappa} + \check{a} + \check{\mu} + \check{b} \le 0, \ t > 0 \rangle. \tag{13.8.9}$$

Now, let us note here that the application of  $\tilde{\mathcal{C}}_{\mathbb{R}}$  (see Lemma 13.3.2(p.72)) inevitably changes

"for 
$$F \in \mathscr{F}_{A_{\text{Tom}}|p} \subseteq \mathscr{F}$$
" in (13.8.5(p.84))

into

 $\text{``for }\check{F}\in\check{\mathscr{F}}_{A_{\mathsf{Tom}}\mid\boldsymbol{p}}\subseteq\mathscr{F}\ \ corresponding\ to\ any\ F\in\mathscr{F}_{A_{\mathsf{Tom}}\mid\boldsymbol{p}}\ \ with\ \boldsymbol{p}\in\mathscr{P}_{A_{\mathsf{Tom}}}\subseteq\mathscr{P}\text{''}$ 

where

$$\check{\mathscr{F}}_{A_{\mathsf{Tom}}|p} = \{\check{F} \mid F \in \mathscr{F}_{A_{\mathsf{Tom}}|p}\} \quad \text{(see (13.1.3(p.69)))}.$$

Hence, applying (13.8.5(p.84)), we have

$$\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\}] = \{\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathsf{S}] \text{ is true for } \boldsymbol{p} \in \mathscr{P}_{A_{\text{Tom}}} \subseteq \mathscr{P} \text{ and } \check{F} \in \check{\mathscr{F}}_{A_{\text{Tom}}|\boldsymbol{p}} \subseteq \mathscr{F} \text{ with } \boldsymbol{p} \in \mathscr{P}_{A_{\text{Tom}}} \subseteq \mathscr{P}\}. (13.8.11)$$

Now, since the phrase " $F \in \mathscr{F}_{A_{\mathsf{Tom}}|p} \subseteq \mathscr{F}$ " is implicitly accompanied with the phrase " $\check{F} \in \check{\mathscr{F}}_{A_{\mathsf{Tom}}|p} \subseteq \mathscr{F}$ ". Accordingly (13.8.11(p.85)) can be rewritten as

$$\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[A_{\mathsf{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}] = \{\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[\tilde{\mathsf{S}}] \text{ is true for } \boldsymbol{p} \in \mathscr{P}_{A_{\mathsf{Tom}}} \subseteq \mathscr{P} \text{ and } \check{F} \in \check{\mathscr{F}}_{A_{\mathsf{Tom}}|\boldsymbol{p}} \subseteq \mathscr{F}\}, \tag{13.8.12}$$

$$= \{\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathsf{S}] \text{ is true on } \check{\mathscr{E}}\langle A_{\mathsf{Tom}} \rangle \}$$

where

$$\check{\mathscr{E}}\langle A_{\mathsf{Tom}}\rangle \stackrel{\text{def}}{=} \{(\boldsymbol{p},F) \mid \boldsymbol{p} \in \mathscr{P}_{A_{\mathsf{Tom}}} \subseteq \mathscr{P}, \check{F} \in \check{\mathscr{F}}_{A_{\mathsf{Tom}}|\boldsymbol{p}} \subseteq \mathscr{F}\}. \tag{13.8.13}$$

• The attribute vector of  $\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}]$  is given by applying  $\tilde{\mathcal{C}}_{\mathbb{R}}$  to (13.8.7(p.85)), i.e.,

$$\theta(\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}]) = \tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[\theta(A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\})] 
= (\check{a},\check{\mu},\check{b},\check{x}_{L},\check{x}_{K},s_{\check{L}},\check{\kappa},\check{T},\check{L},\check{K},\check{\mathcal{L}},\hat{V}_{t}).$$
(13.8.14)

#### lacksquare $\tilde{\mathsf{S}}\mathsf{tep}\ 4$ (identity replacement operation $\tilde{\mathcal{I}}_{\mathbb{R}}$ )

• Here let us consider the application of the identity replacement operation  $\tilde{\mathcal{I}}_{\mathbb{R}}$ , i.e., the replacement of the left-hand of each equality in Lemma 13.3.4(p.74)

$$\check{F}$$
,  $\check{a}$ ,  $\check{\mu}$ ,  $\check{b}$ ,  $\check{x}_L$ ,  $\check{x}_K$ ,  $s_{\check{c}}$ ,  $\check{\kappa}$ ,  $\check{T}(x)$ ,  $\check{L}(x)$ ,  $\check{K}(x)$ ,  $\check{\mathcal{L}}(s) \cdots (1^*)$ 

by its right-hand side

$$F, a, \mu, b, x_L, x_K, s_L, \kappa, T(x), L(x), K(x), \mathcal{L}(s) \cdots (2^*)$$

where  $(1^*)$  is for any  $F \in \mathscr{F}$  and  $(2^*)$  is for  $\check{F} \in \check{\mathscr{F}}$  which is identical to the  $F \in \mathscr{F}$ , i.e.,  $\check{F} \equiv F \cdots (1)$ .

 $\circ$  Applying  $\tilde{\mathcal{I}}_{\mathbb{R}}$  to (13.8.8(p.85)) yields

$$\tilde{\mathcal{I}}_{\mathbb{R}}\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[\text{SOE}\{\tilde{\mathbf{M}}:1[\mathbb{R}][\mathbb{A}]\}] = \{\hat{V}_1 = \beta\mu - s, \ \hat{V}_t = \max\{K(\hat{V}_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \ t > 1\}.$$

Now, we have  $\hat{V}_1 = \beta \mu - s = V_1$  from (7.4.5(p.41)). Suppose  $\hat{V}_{t-1} = V_{t-1}$ . Then, since  $\hat{V}_t = \max\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} = V_t$  from (7.4.6(p.41)), by induction  $\hat{V}_t = V_t$  for t > 0. Thus we have

$$\tilde{\mathcal{I}}_{\mathbb{R}}\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[\text{SOE}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}] = \{V_1 = \beta\mu - s, \ V_t = \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ t > 1\},$$

which is the same as  $SOE\{M:1[\mathbb{R}][A]\}$  (see Table 7.4.1(p.41) (I)). Thus we have

$$\begin{aligned} & \mathtt{SOE}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\} = \tilde{\mathcal{I}}_{\mathbb{R}}\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[\mathtt{SOE}\{\check{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}] \\ & = \{V_1 = \beta\mu - s, \ V_t = \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ t > 1\}. \end{aligned} \tag{13.8.15}$$

 $\circ$  Applying  $\tilde{\mathcal{I}}_{\mathbb{R}}$  to (13.8.12(p.85)) yields

$$\tilde{\mathcal{I}}_{\mathbb{R}}\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}] = \{\tilde{\mathcal{I}}_{\mathbb{R}}\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[\tilde{\mathsf{S}}] \text{ is true on } \tilde{\mathscr{C}}\langle A_{\text{Tom}}\rangle \}. \tag{13.8.16}$$

Applying  $\tilde{\mathcal{I}}_{\mathbb{R}}$  to (13.8.9(p.85)) yields

$$\tilde{\mathcal{I}}_{\mathbb{R}}\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[\tilde{\mathsf{S}}] = \langle V_t + s_{\mathcal{L}} + x_L + \kappa + a + \mu + b \le 0, \ t > 0 \rangle. \tag{13.8.17}$$

Now  $V_t$  within  $\tilde{\mathcal{I}}_{\mathbb{R}}\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[\tilde{S}]$  is generated from  $SOE\{M:1[\mathbb{R}][A]\}$ , hence (13.8.16(p.86)) can be regarded as an assertion as to  $M:1[\mathbb{R}][A]$ . Thus, we have

$$A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\} = \tilde{\mathcal{I}}_{\mathbb{R}}\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}]$$

$$= \{\tilde{\mathcal{I}}_{\mathbb{R}}\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[\tilde{\mathsf{S}}] \text{ is true on } \mathscr{E}\langle A_{\text{Tom}}\rangle \}.$$

$$(13.8.18)$$

• The attribute vector of  $A_{\tilde{1}om}\{M:1[\mathbb{R}][A]\}$  is given by applying  $\tilde{\mathcal{I}}_{\mathbb{R}}$  to (13.8.14(p.85)), i.e.,

$$\theta(A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\}) = \tilde{\mathcal{I}}_{\mathbb{R}}\tilde{\mathcal{C}}_{\mathbb{R}}\mathcal{R}[\theta(A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\})] 
= (a, \mu, b, x_L, x_K, s_{\mathcal{L}}, \kappa, T, L, K, \mathcal{L}, V_t),$$
(13.8.19)

#### ■ $\tilde{\mathsf{S}}\mathsf{tep}\ \mathbf{5}$ (symmetry transformation operation $\mathcal{S}_{\tilde{\mathbb{R}}\to\mathbb{R}}$ )

Below, letting us line up the attribute vectors given in Step 1 to Step 4, we have the following:

The above flow can be eventually reduced to

$$\mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}} \stackrel{\text{def}}{=} \left\{ \begin{bmatrix} b, \mu, a, & x_{\tilde{L}}, x_{\tilde{K}}, s_{\tilde{\mathcal{L}}}, \tilde{\kappa}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_t \\ \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \downarrow \\ a, \mu, b, & x_L, x_K, s_{\mathcal{L}}, \kappa, T, L, K, \mathcal{L}, V_t \end{bmatrix},$$

$$(13.8.21)$$

called the symmetry transformation operation, which can be regarded as the successive application of the three operations, i.e., " $\mathcal{R} \to \tilde{\mathcal{L}}_{\mathbb{R}} \to \tilde{\mathcal{L}}_{\mathbb{R}}$ ". Here let us define

$$\mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}} \stackrel{\text{def}}{=} \tilde{\mathcal{I}}_{\mathbb{R}} \tilde{\mathcal{C}}_{\mathbb{R}} \mathcal{R}. \tag{13.8.22}$$

Then (13.8.18(p.86)) can be rewritten as

$$A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\} = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}[A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}]$$

$$= \{\mathsf{S} \text{ is true on } \tilde{\mathscr{E}}\langle A_{\text{Tom}}\rangle \}$$
(13.8.23)

where

$$S = S_{\tilde{\mathbb{D}}_{\sim}\mathbb{D}}[\tilde{S}]. \tag{13.8.24}$$

Then, from (13.8.17(p.86)) we have

$$S = \langle V_t + s_{\mathcal{L}} + x_L + \kappa + a + \mu + b \le 0, \ t > 0 \rangle.$$

Then, (13.8.15(p.86)) can be rewritten as

$$SOE\{M:1[\mathbb{R}][A]\} = S_{\tilde{\mathbb{R}} \to \mathbb{R}}[SOE\{\tilde{M}:1[\mathbb{R}][A]\}]. \tag{13.8.25}$$

In addition, (13.5.27(p.77)) can be rewritten as

$$\theta(A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}) = \mathcal{S}_{\tilde{\mathbb{R}}\to\mathbb{R}}[\theta(A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\})]$$
(13.8.26)

$$= (b, \mu, a, x_{\tilde{L}}, x_{\tilde{K}}, s_{\tilde{\mathcal{L}}}, \tilde{\kappa}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_t)$$

$$(13.8.27)$$

From all the above we see that  $\tilde{S}$ cenario[ $\mathbb{R}$ ] starting with (13.8.2(p.84)) finally ends up with (13.8.23(p.86)), which can be rewritten as respectively

$$A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\} \text{ holds on } \mathscr{C}\langle A_{\text{Tom}}\rangle,$$
 (13.8.28)

$$A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\} \text{ holds on } \check{\mathscr{C}}\langle A_{\text{Tom}}\rangle.$$
 (13.8.29)

From the above two results and (13.8.25(p.87)) we eventually obtain the following lemma.

**Lemma 13.8.1** Let  $A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}\ holds\ on\ \check{\mathscr{E}}\langle A_{\text{Tom}}\rangle$ . Then  $A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\}\ holds\ on\ \mathscr{E}\langle A_{\text{Tom}}\rangle$  where

$$A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\} = \mathcal{S}_{\tilde{\mathbb{R}}\to\mathbb{R}}[A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}]. \quad \Box$$
 (13.8.30)

#### ■ Štep 6 (aggregation)

We can construct quite the same procedure as in Step 6 (p.78).

■  $\tilde{\mathsf{S}}\mathsf{tep}\ 7$  (symmetry theorem  $\mathbb{R}\leftarrow\tilde{\mathbb{R}}$ )

Through the procedure in Step 6 (p.87) we have the following theorem

**Theorem 13.8.1** Let  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}.\ Then\ \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}\ where$ 

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\} = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}]. \quad \Box$$

$$(13.8.31)$$

• *Proof* Immediate for the same reason as in Theorem 13.5.1(p.80).  $\blacksquare$ 

The attribute vector of  $\mathscr{A}\{M:1[\mathbb{R}][A]\}$  is given by

$$\theta(\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}) = \mathcal{S}_{\tilde{\mathbb{R}}\to\mathbb{R}}[\theta(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\})]$$
(13.8.32)

$$= (a, \mu, b, x_L, x_K, s_L, \kappa, T, L, K, L, V_t)$$
(13.8.33)

### 13.9 Definition of Symmetry

Thus far, the term of *symmetry* has been used in the rather intuitive nuance. In order to make our discussions more clear, below let us provide its strict definition.

#### Definition 13.9.1

- (a) Let  $A\{M_1\}$  and  $A\{M_2\}$  be assertions on models  $M_1$  and  $M_2$  respectively. Then, if  $A\{M_2\} = \mathcal{S}_{\mathbb{R} \to \mathbb{R}}[A\{M_1\}]$  and  $A\{M_1\} = \mathcal{S}_{\mathbb{R} \to \mathbb{R}}[A\{M_2\}]$ , let  $A\{M_1\}$  and  $A\{M_2\}$  be said to be *symmetrical*, denoted by  $A\{M_1\} \sim A\{M_2\}$ . Then let us employ the expression of " $M_1$  and  $M_2$  are symmetrical with respect to A".
- (b) For given two assertion systems  $\mathscr{A}\{M_1\}$  and  $\mathscr{A}\{M_2\}$  which are one-to-one correspondent, if  $A\{M_1\} \sim A\{M_2\}$  for any pair  $(A\{M_1\}, A\{M_2\})$  where  $A\{M_1\} \in \mathscr{A}\{M_1\}$  and  $A\{M_2\} \in \mathscr{A}\{M_2\}$ , then  $\mathscr{A}\{M_1\}$  and  $\mathscr{A}\{M_2\}$  are said to be *symmetrical*, denoted by  $\mathscr{A}\{M_1\} \sim \mathscr{A}\{M_2\}$ . Then, let us employ the expression of " $M_1$  and  $M_2$  are symmetrical with respect to  $\mathscr{A}$ ".
- (c) Without confusion, let us remove the phrases "with respect to A" and "with respect to A".  $\square$

**Lemma 13.9.1**  $\mathscr{A}\{M:1[\mathbb{R}][A]\}\ and\ \mathscr{A}\{\tilde{M}:1[\mathbb{R}][A]\}\ are\ symmetrical,\ i.e.,$ 

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\} \sim \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}. \quad \Box \tag{13.9.1}$$

• *Proof* Immediate from (13.5.53(p.80)) and (13.8.31(p.87)). ■

### 13.10 Symmetry-Operation-Free

When no change occurs even if the symmetry operation is applied to a given assertion A, the assertion is said to be *free from* the symmetry operation, called the *symmetry-operation-free assertion*.

**Lemma 13.10.1** Even if the symmetry operation is applied to the symmetry-operation-free assertion, no change occurs. □
• Proof Evident. ■

# Chapter 14

# Analogy Theorem $(\mathbb{R} \leftrightarrow \mathbb{P})$

In this chapter we present a methodology which derives  $\mathscr{A}\{M:1[\mathbb{P}][A]\}$  (selling model with  $\mathbb{P}$ -mechanism) from  $\mathscr{A}\{M:1[\mathbb{R}][A]\}$ (selling model with  $\mathbb{P}$ -mechanism).

#### 14.1 **Preliminary**

Lemma 14.1.1 ([46,You])

- (a) Let  $x \ge b$ . Then z(x) = b. (b) Let x < b. Then x < z(x) < b. (c)  $z(x) \ge a$  for any x.  $\square$
- Proof (a) Let  $x \ge b$ . If  $z < b \cdots$  (I), then z < x, hence p(z)(z-x) < 0 due to (6.1.29 (1) (p.26)), and if  $b \le z \cdots$  (III), then p(z)(z-x)=0 due to (6.1.29(2) (p.26)). Hence z(x) can be given by any  $z \geq b$ , thus z(x)=b due to Def. 6.1.1 (p.26).

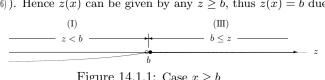


Figure 14.1.1: Case x > b

(b) Let x < b. If  $z \le x \cdots (I)$ , then  $p(z)(z-x) \le 0$ , if  $x < z < b \cdots (II)$ , then p(z)(z-x) > 0 due to (6.1.29(1) (p.26)), and if  $b \le z \cdots (\text{III})$ , then p(z)(z-x) = 0 from (6.1.29(2)(p.26)). Hence, z(x) is given by z such that x < z < b or equivalently x < z(x) < b.



Figure 14.1.2: Case x < b

(c) Assume that z(x) < a for a certain x. Then, since p(z(x)) = 1 = p(a) due to (6.1.28(1)(p.26)), from (6.1.25(p.26)) we have  $T(x) = p(z(x))(z(x) - x) = z(x) - x < a - x = p(a)(a - x) \le T(x)$ , which is a contradiction. Hence, it must be that  $z(x) \ge a$ for any x.

Corollary 14.1.1 ([46,You])  $a \le z(x) \le b$  for any x.  $\square$ 

• *Proof* Immediate from Lemma 14.1.1(p.89). ■

**Lemma 14.1.2** ([46, You]) p(z) is nonincreasing on  $(-\infty, \infty)$  and strictly decreasing in  $z \in [a, b]$ .  $\square$ 

• Proof The former half is immediate from (6.1.18(p.26)). Let  $a \le z' < z \le b$ . Then  $p(z') - p(z) = \Pr\{z' \le \xi\} - \Pr\{z \le \xi\} = p(z')$  $\Pr\{z' \leq \xi < z\} = \int_{z'}^{z} f(\xi) d\xi > 0 \text{ (See } (2.2.3 (2) (p.13))), \text{ hence } p(z') > p(z), \text{ i.e., } p(z) \text{ is strictly decreasing on } [a, b].$ 

**Lemma 14.1.3** ([46, You]) z(x) is nondecreasing on  $(-\infty, \infty)$ .  $\square$ 

• Proof From (6.1.25(p.26)), for any x and y we have

$$\begin{split} T(x) &= p(z(x))(z(x) - x) \\ &= p(z(x))(z(x) - y) - (x - y)p(z(x)) \\ &\leq T(y) - (x - y)p(z(x)) \\ &= p(z(y))(z(y) - y) - (x - y)p(z(x)) \\ &= p(z(y))\big(z(y) - x + (x - y)\big) - (x - y)p(z(x)) \\ &= p(z(y))(z(y) - x) + (x - y)(p(z(y)) - p(z(x))) \\ &\leq T(x) + (x - y)(p(z(y)) - p(z(x))). \end{split}$$

<sup>&</sup>lt;sup>‡</sup>This is the most important property of the function T, which was proven in [?, 0298].

Hence  $0 \le (x-y)(p(z(y))-p(z(x)))$ . Let x>y. Then  $0 \le p(z(y))-p(z(x))$ , so  $p(z(x)) \le p(z(y))\cdots(1)$ . Since  $a \le z(x) \le b$  and  $a \le z(y) \le b$  from Corollary 14.1.1(p.89), if z(x) < z(y), then p(z(x)) > p(z(y)) from Lemma 14.1.2(p.89), which contradicts (1). Hence, it must be that z(x) > z(y), i.e., z(x) is nondecreasing in  $x \in (-\infty, \infty)$ .

#### Lemma 14.1.4

- (a) T(x) is continuous on  $(-\infty, \infty)$ .
- (b) T(x) is nonincreasing on  $(-\infty, \infty)$ .
- (c) T(x) is strictly decreasing on  $(-\infty, b]$ .
- (d) T(x) > 0 on  $(-\infty, b)$  and T(x) = 0 on  $[b, \infty)$ .
- (e)  $T(x) \ge a x$  on  $(-\infty, \infty)$ .
- (f) T(x) + x is nondecreasing on  $(-\infty, \infty)$ .
- (g)  $\beta T(x) + x$  is nondecreasing on  $(-\infty, \infty)$  if  $\beta = 1$ .
- (h)  $\beta T(x) + x$  is strictly increasing on  $(-\infty, \infty)$  if  $\beta < 1$ .
- (i)  $T(x) \ge \max\{0, a x\}$  on  $(-\infty, \infty)$ .
- (j)  $\lambda \beta T(\lambda \beta a s) s$  is nonincreasing in s and is strictly decreasing in s if  $\lambda \beta < 1$ .  $\square$
- Proof (a,b) Immediate from the fact that p(z)(z-x) in (6.1.19(p.26)) is continuous and nonincreasing in  $x \in (-\infty, \infty)$  for any z.
- (c) Let x' < x < b. Then z(x) < b from Lemma 14.1.1(p.89) (b). Accordingly, since p(z(x)) > 0 due to  $(6.1.29\,(1)\,(p.26)\,)$  and since z(x) x < z(x) x', from  $(6.1.25\,(p.26)\,)$  we have  $T(x) = p(z(x))(z(x) x) < p(z(x))(z(x) x') \le T(x')$ , implying that T(x) is strictly decreasing on  $(-\infty,b)\cdots$  (1). Assume T(b) = T(x) for a given x < b, so b x > 0. Then, for any sufficiently small  $\varepsilon > 0$  such that  $b x > 2\varepsilon > 0$  we have  $b > b \varepsilon > x + \varepsilon > x$ , hence  $T(b) = T(x) > T(b \varepsilon) \ge T(b)$  due to the strict unceasingness shown above and the nonincreasingness in (b), which is a contradiction. Thus, since  $T(x) \ne T(b)$  for any x < b, we have T(x) > T(b) or T(x) < T(b) for any x < b. However, the latter is impossible due to (b), hence only the former is possible. Consequently, it follows that T(x) is strictly decreasing on  $(-\infty,b]$  instead of  $(-\infty,b)$ .
- (d) Let  $x \ge b$ . Then, since z(x) = b from Lemma 14.1.1(p.89) (a), we have p(z(x)) = 0 due to (6.1.29 (2) (p.26)), hence T(x) = p(z(x))(z(x) x) = 0 on  $[b, \infty)$ . Let x < b. Then, from (c) we have T(x) > T(b) = 0, i.e., T(x) > 0 on  $(-\infty, b)$ .
  - (e) Since p(a) = 1 from (6.1.28(1) (p.26)), we have  $T(x) \ge p(a)(a-x) = a-x$  for any x on  $(-\infty, \infty)$ .
  - (f) Let x < x'. Then, we have

$$T(x) + x = p(z(x))(z(x) - x) + x$$

$$= p(z(x))z(x) + (1 - p(z(x)))x$$

$$\leq p(z(x))z(x) + (1 - p(z(x)))x'$$

$$= p(z(x))(z(x) - x') + x' \leq T(x') + x',$$

implying that T(x) + x is nondecreasing on  $(-\infty, \infty)$ .

- (g) If  $\beta = 1$ , then  $\beta T(x) + x = T(x) + x$ , hence the assertion is true from (f).
- (h) Since  $\beta T(x) + x = \beta(T(x) + x) + (1 \beta)x$ , if  $\beta < 1$ , then  $(1 \beta)x$  is strictly increasing in x, hence the assertion is true from (f).
  - (i) Immediate from the fact that  $T(x) \ge a x$  on  $(-\infty, \infty)$  from (e) and  $T(x) \ge 0$  on  $(-\infty, \infty)$  from (d).
  - (i) From (6.1.19(p.26)) we have

$$\lambda \beta T(\lambda \beta a - s) - s = \lambda \beta \max_{z} p(z)(z - \lambda \beta a + s) - s = \max_{z} p(z)(\lambda \beta z - (\lambda \beta)^{2} a + \lambda \beta s) - s.$$

Let s > s'. Then, we have

$$\lambda \beta T(\lambda \beta a - s) - s - \lambda \beta T(\lambda \beta a - s') + s'$$

$$= \max_{z} p(z)(\lambda \beta z - (\lambda \beta)^{2} a + \lambda \beta s) - \max_{z} p(z)(\lambda \beta z - (\lambda \beta)^{2} a + \lambda \beta s') - (s - s')$$

$$\leq \max_{z} p(z)(s - s')\lambda \beta - (s - s')^{\dagger}$$

$$\leq \max_{z} (s - s')\lambda \beta - (s - s') \quad \text{(due to } p(z) \leq 1 \text{ and } s - s' > 0)$$

$$= (s - s')\lambda \beta - (s - s')$$

$$= -(s - s')(1 - \lambda \beta) \leq (<) 0 \text{ if } \lambda \beta \leq (<) 1.$$

Hence, since  $\lambda \beta T(\lambda \beta a - s) - s \le (<) \lambda \beta T(\lambda \beta a - s') - s'$  if  $\lambda \beta \le (<) 1$ , it follows that  $T(\lambda \beta a - s) - s$  is nonincreasing (strictly decreasing) in s if  $\lambda \beta \le (<) 1$ .

Let us define

$$h(z) = p(z)(z - a)/(1 - p(z)), \quad z > a,$$
  
 $h^* = \sup_{a < z} h(z),$ 

 $<sup>^{\</sup>dagger} \max_{x} g(x) - \max_{x} h(x) \le \max_{x} \{g(x) - h(x)\}.$ 

Below, for a given x let us define the following successive four assertions:

$$A_1(x) = \langle \langle z(x) \rangle a \rangle,$$

$$A_2(x) = \langle \langle T(a,x) \rangle \langle T(z',x,) \text{ for at least one } z' \rangle a \rangle,$$

$$A_3(x) = \langle \langle a - h(z') \rangle \langle x \text{ for at least one } z' \rangle a \rangle,$$

$$A_4(x) = \langle \langle \inf_{z > a} \{a - h(z)\} \rangle \langle x \rangle.$$

**Proposition 14.1.1** For any given x we have  $A_1(x) \Leftrightarrow A_2(x) \Leftrightarrow A_3(x) \Leftrightarrow A_4(x)$ .  $\square$ 

- Proof Letting  $T(z,x) \stackrel{\text{def}}{=} p(z)(z-x)$ , we can rewrite (6.1.19(p.26)) as  $T(x) = \max_z T(z,x) = T(z(x),x)$  (see (6.1.25(p.26))).
- 1. Let  $A_1(x)$  be true for any given x. Suppose  $T(a,x) \ge T(z',x)$  for all  $z' \ge a$ , hence the maximum of T(z,x) for all  $z \ge a$  is attained at z = a, i.e., z(x) = a (see Def. 6.1.1(p.26)), which contradicts  $A_1(x)$ . Hence it must be that T(a,x) < T(z',x) for at least one z' > a, thus  $A_2(x)$  becomes true. Accordingly, we have  $A_1(x) \Rightarrow A_2(x)$ . Suppose  $A_2(x)$  is true for any given x. Then, if z(x) = a, we have  $T(a,x) < T(z',x) \le T(x) = T(z(x),x) = T(a,x)$ , which is a contradiction, hence it must be that z(x) > a due to Lemma 14.1.1(p.89) (c). Accordingly, we have  $A_2(x) \Rightarrow A_1(x)$ . Thus, it follows that  $A_1(x) \Leftrightarrow A_2(x)$  for any given x.
- 2. Since p(a) = 1 from (6.1.28(1) (p.26)), for z' > a (hence  $1 > p(z') \cdots (1)$  from (6.1.28(2) (p.26))) we have

$$T(a,x) - T(z',x)$$

$$= p(a)(a-x) - p(z')(z'-x)$$

$$= a - x - p(z')(z'-x)$$

$$= a - x - p(z')(a-x+z'-a)$$

$$= a - x - p(z')(a-x) - p(z')(z'-a)$$

$$= (1 - p(z'))(a-x) - p(z')(z'-a)$$

$$= (1 - p(z'))(a-x - p(z')(z'-a)/(1 - p(z')))$$

$$= (1 - p(z'))(a - x - h(z'))$$

$$= (1 - p(z'))(a - h(z') - x).$$

Accordingly, due to (1) we immediately obtain  $A_2(x) \Leftrightarrow A_3(x)$  for any given x.

3. Let  $A_3(x)$  be true for any given x. Then clearly  $A_4(x)$  is also true, i.e.,  $A_3(x) \Rightarrow A_4(x)$ . Let  $A_4(x)$  be true for any given x. Then evidently  $a - \tilde{h}(z') < x$  for at least one z' > a, hence  $A_3(x)$  is true, so we have  $A_4(x) \Rightarrow A_3(x)$ . Accordingly, it follows that  $A_3(x) \Leftrightarrow A_4(x)$  for any given x.

From all the above we have  $A_1(x) \Leftrightarrow A_2(x) \Leftrightarrow A_3(x) \Leftrightarrow A_4(x)$ .

#### Lemma 14.1.5

- (a)  $0 < h^* < \infty$ .
- (b)  $x^* = a h^* < a$ .
- (c)  $x^* < (\geq) x \Leftrightarrow z(x) > (=) a$ .
- (d)  $a^* < a$ .
- Proof (a) For any infinitesimal  $\varepsilon > 0$  such that  $a < b \varepsilon < b \cdots$  (II) we have  $0 < p(b \varepsilon) < 1$  from (6.1.29 (1) (p.26)) and (6.1.28 (2) (p.26)), hence  $h(b \varepsilon) = p(b \varepsilon)(b \varepsilon a)/(1 p(b \varepsilon)) > 0$ . If  $b \le z \cdots$  (III), then p(z) = 0 due to (6.1.29 (2) (p.26)), hence h(z) = 0 for  $z \ge b$ . From the above we have  $h^* > 0$  (finite) or  $h^* = \infty$ .

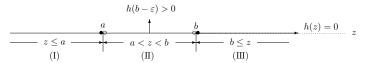


Figure 14.1.3:  $h(b-\varepsilon) > 0$  and h(z) = 0 for  $z \ge b$ 

Assume that  $h^* = \infty$ . Then, there exists at least one z' on a < z' < b such that  $h(z') \ge N$  for any given N > 0. Hence, if the N is given by  $M/\underline{f}^{\dagger}$  with any M > 1, we have  $h(z') \ge M/\underline{f}$  or equivalently  $p(z')(z'-a)/(1-p(z')) \ge M/\underline{f}$ . Hence, noting (6.1.18 (p.26)), we have

$$p(z')(z'-a) \ge (1-p(z'))M/f = (1-\Pr\{z' \le \xi\})M/f = \Pr\{\xi < z'\}M/f \cdots (*)$$

 $<sup>^{\</sup>dagger} \mathrm{See} \, (2.2.4 \text{(p.13)})$ 

where  $\Pr\{\boldsymbol{\xi} < z'\} = \int_a^{z'} f(w) dw \ge \int_a^{z'} \underline{f} dw = (z'-a)\underline{f}$ . Accordingly, since  $p(z')(z'-a) \ge (z'-a)\underline{f}M/\underline{f} = (z'-a)M$ , we have  $p(z') \ge M > 1$  due to z'-a > 0, which is a contradiction. Hence, it must follow that  $h^* < \infty$ .

(b) Since  $A_1(x) \Rightarrow A_4(x)$  due to Proposition 14.1.1, we can rewritten (6.1.27(p.26)) as

$$x^* = \inf\{x \mid \inf_{z>a} \{a - h(z)\} < x\}$$
  
=  $\inf_{z>a} \{a - h(z)\} \cdots (1)$   
=  $a - \sup_{a \le z} h(z) = a - h^* < a$  (due to (a)),

hence (b) holds.

- (c) If  $x^* < x$ , then  $\inf_{z>a} \{a-h(z)\} < x$  from (1), hence z(x)>a due to  $A_4(x) \Rightarrow A_1(x)$ . If  $x^* \geq x$ , then  $\inf_{a < z} \{a-h(z)\} \geq x$  from (1). Now, since  $\inf_{a < z} \{a-h(z)\} \geq x \Leftrightarrow z(x) \leq a$  due to a contraposition of  $A_4(x) \Leftrightarrow A_1(x)$ , hence we obtain z(x)=a due to Lemma 14.1.1(p.89) (c).
- (d) First note  $T(x) \ge p(z')(z'-x)$  for any x and z'. Accordingly, for any sufficiently small  $\varepsilon > 0$  such that  $a + \varepsilon < b$  we have  $p(a + \varepsilon) > 0$  from (6.1.29 (1) (p.26)), hence  $T(a) \ge p(a + \varepsilon)(a + \varepsilon a) = p(a + \varepsilon)\varepsilon > 0$ . Adding a to the inequality yields T(a) + a > a. Thus, we have  $T(x) + x \ge T(a) + a > a$  for any  $x \ge a$  due to Lemma 14.1.4(p.90) (f). Accordingly, if  $a^* \ge a$ , then since  $T(a^*) + a^* \ge T(a) + a > a$ , from Lemma 14.1.4(p.90) (a) we have  $T(a^* \varepsilon) + a^* \varepsilon > a$  for any sufficiently small  $\varepsilon > 0$  or equivalently  $T(a^* \varepsilon) > a (a^* \varepsilon)$ , which contradicts the definition of  $a^*$  (see (6.1.26(p.26))). Therefore, it must be that  $a^* < a$ .

#### Lemma 14.1.6

- (a) T(x) + x is strictly increasing on  $[a^*, \infty)$ .
- (b) T(x) = a x on  $(-\infty, a^*]$  and T(x) > a x on  $(a^*, \infty)$ .
- (c)  $T(0) = a \text{ if } a^* > 0 \text{ and } T(0) = 0 \text{ if } b < 0.$
- (d) If x < y and  $a^* < y$ , then T(x) + x < T(y) + y.  $\square$
- *Proof* (a) From (6.1.25(p.26)) we have

$$T(x) + x = p(z(x))(z(x) - x) + x = p(z(x))z(x) + (1 - p(z(x)))x....(1)$$

o Let  $x^* < x$ . Then z(x) > a from Lemma 14.1.5(p.91) (c), hence p(z(x)) < 1 due to (6.1.28(2)(p.26)), so 1 - p(z(x)) > 0. If x < x', from (1) we have

$$T(x) + x = p(z(x))z(x) + (1 - p(z(x)))x < p(z(x))z(x) + (1 - p(z(x)))x' = p(z(x))(z(x) - x') + x' \le T(x') + x',$$

i.e., T(x) + x is strictly increasing on  $(-\infty, \infty)$ , hence understandably so also on  $[a^*, \infty)$ .

o Let  $x^* \geq x$ . Then z(x) = a from Lemma 14.1.5(p.91) (c), hence p(z(x)) = 1 from  $(6.1.28 \, (1) \, (p.26))$ , so  $T(x) = p(z(x))(z(x) - x) = a - x \cdots (2)$ . Suppose  $a^* < x^*$ . Then, since  $a^* < a^* + 2\varepsilon < x^*$  for an infinitesimal  $\varepsilon > 0$ , we have  $a^* < a^* + \varepsilon < x^* - \varepsilon < x^*$  or equivalently  $x^* > a^* + \varepsilon$ ; accordingly, due to (2) we obtain  $T(a^* + \varepsilon) = a - (a^* + \varepsilon) \cdots (3)$ . Now, due to (6.1.26(p.26)) we have  $T(a^* + \varepsilon) > a - (a^* + \varepsilon)$ , which contradicts (3). Accordingly, it must be that  $x^* \leq a^*$ . Let  $x' > x > a^*$ . Then, since  $x^* < x$ , we have z(x) > a Lemma 14.1.5(p.91) (c), hence p(z(x)) < 1 due to  $(6.1.28 \, (2) \, (p.26))$  or equivalently 1 - p(z(x)) > 0. Thus, from (1) we have

$$T(x) + x = p(z(x))z(x) + (1 - p(z(x)))x < p(z(x))z(x) + (1 - p(z(x)))x' = p(z(x))(z(x) - x') + x' \le T(x') + x',$$

implying that T(x) + x is  $strictly increasing \cdots (4)$  on  $(a^*, \infty)$ . Now, let us assume  $T(x) + x = T(a^*) + a^*$  on  $a^* < x$ , so  $x - a^* > 0$ . Then, for any sufficiently small  $\varepsilon > 0$  such that  $x - a^* > 2\varepsilon$  we have  $x > x - \varepsilon > a^* + \varepsilon > a^*$ , hence  $T(x) + x = T(a^*) + a^* \le T(a^* + \varepsilon) + a^* + \varepsilon < T(x) + x$  due to the nondecreasing in Lemma 14.1.4(p.90) (f) and the strict increasingness shown above, which is a contradiction. Thus, it must be that  $T(x) + x \ne T(a^*) + a^*$  on  $a^* < x$ , so we have  $T(x) + x > T(a^*) + a^*$  or  $T(x) + x < T(a^*) + a^*$  on  $a^* < x$ ; however, the latter is impossible due to the nondecreasing in Lemma 14.1.4(p.90) (f), hence it follows that  $T(x) + x > T(a^*) + a^*$  on  $a^* < x$ . From this fact and (4) it inevitably follows that T(x) + x is strictly increasing on  $a^* \le x$ , i.e., T(x) + x is strictly increasing on not  $T(x) + x = T(a^*) + a^*$  on  $T(x) + x = T(a^*) + a^*$  on T(x) + x =

Accordingly, whether  $x^* < x$  or  $x^* \ge x$ , it follows that T(x) + x is strictly increasing on  $[a^*, \infty)$ .

- (b) Due to (6.1.26(p.26)) we have T(x) > a x for  $x > a^*$ , i.e., T(x) > a x on  $(a^*, \infty)$ , hence the latter half is true. Since  $T(x) \ge a x$  on  $(-\infty, \infty)$  due to Lemma 14.1.4(p.90) (e), we have  $T(x) + x \ge a \cdots$  (5) on  $(-\infty, \infty)$ . Suppose  $T(a^*) + a^* > a$ . Then, for an infinitesimal  $\varepsilon > 0$  we have  $T(a^* \varepsilon) + a^* \varepsilon > a$  due to Lemma 14.1.4(p.90) (a), i.e.,  $T(a^* \varepsilon) > a (a^* \varepsilon)$ , which contradicts the definition of  $a^*$  (see (6.1.26(p.26))). Consequently, we have  $T(a^*) + a^* = a \cdots$  (6) or equivalently  $T(a^*) = a a^*$ . Let  $x < a^*$ . Then, from Lemma 14.1.4(p.90) (f) we have  $T(x) + x \le T(a^*) + a^* = a$ . From the result and (5) we have T(x) + x = a, hence T(x) = a x on  $(-\infty, a^*)$ . From this and (6) it follows that T(x) = a x on  $(-\infty, a^*)$ . Hence the former half is true.
- (c) Let  $a^* > 0$ . Then, since  $0 \in (-\infty, a^*]$ , we have T(0) = a from the former half of (b). We have  $T(0) = \max_z p(z)z \cdots$  (7) from (6.1.19(p.26)). Let b < 0. Then, if  $z \ge b$ , we have p(z)z = 0 from (6.1.29(2)(p.26)) and if z < b < 0, then p(z)z < 0 from (6.1.29(1)(p.26)), hence T(0) = 0 due to (7).
- (d) Let x < y and  $a^* < y$ . If  $x \le a^*$ , then  $T(x) + x \le T(a^*) + a^* < T(y) + y$  due to Lemma 14.1.4(p.90) (f) and (a), and if  $a^* < x$ , then  $a^* \le x < y$ , hence T(x) + x < T(y) + y due to (a). Thus, whether  $x \le a^*$  or  $a^* < x$ , we have  $T(x) + x < \tilde{T}(y) + y$ .

## 14.2 Analogy Replacement Operation $\mathcal{A}_{\mathbb{R}^{\to \mathbb{P}}}$

#### 14.2.1 Three Facts

Let us focus on the three facts below.

 $\bigstar$  Fact 1 First, the following lemma can be obtained.

**Lemma 14.2.1** ( $\mathscr{A}\{T_{\mathbb{P}}\}\$ ) For any  $F \in \mathscr{F}$  we have:

(a)	$T(x)$ is continuous on $(-\infty,\infty) \leftarrow$	$\leftarrow$ Lemma 14.1.4(p.90) (a)
(b)	$T(x)$ is nonincreasing on $(-\infty,\infty)$ $\leftarrow$	$\leftarrow$ Lemma 14.1.4(p.90) (b)
(c)	$T(x)$ is strictly decreasing on $(-\infty, b] \leftarrow$	$\leftarrow$ Lemma 14.1.4(p.90) (c)
(d)	$T(x) + x$ is nondecreasing on $(-\infty, \infty) \leftarrow$	$\leftarrow$ Lemma 14.1.4(p.90) (f)
(e)	$T(x) + x$ is strictly increasing on $[a^*, \infty) \leftarrow$	$\leftarrow$ Lemma 14.1.6(p.92) (a)
(f)	$T(x) = a - x \text{ on } (-\infty, a^*] \text{ and } T(x) > a - x \text{ on } (a^*, \infty) \leftarrow$	$\leftarrow$ Lemma 14.1.6(p.92) (b)
(g)	$T(x) > 0$ on $(-\infty, b)$ and $T(x) = 0$ on $[b, \infty) \leftarrow$	$\leftarrow \text{Lemma 14.1.4(p.90) (d)}$
(h)	$T(x) \ge \max\{0, a - x\} \ on \ (-\infty, \infty) \leftarrow$	$\leftarrow$ Lemma 14.1.4(p.90) (i)
(i)	$T(0) = a \text{ if } a^* > 0 \text{ and } T(0) = 0 \text{ if } b < 0 \leftarrow$	$\leftarrow$ Lemma 14.1.6(p.92) (c)
(j)	$\beta T(x) + x$ is nondecreasing on $(-\infty, \infty)$ if $\beta = 1 \leftarrow$	$\leftarrow$ Lemma 14.1.4(p.90) (g)
(k)	$\beta T(x) + x$ is strictly increasing on $(-\infty, \infty)$ if $\beta < 1 \leftarrow$	$\leftarrow$ Lemma 14.1.4(p.90) (h)
(1)	If $x < y$ and $a^* < y$ , then $T(x) + x < T(y) + y \leftarrow$	$\leftarrow$ Lemma 14.1.6(p.92) (d)
(m)	$\lambda \beta T(\lambda \beta a - s) - s$ is nonincreasing in s and strictly decreasing in s if $\lambda \beta < 1 \leftarrow$	$\leftarrow$ Lemma 14.1.4(p.90) (j)
(n)	$a^{\star} < a \leftarrow$	$\leftarrow$ Lemma 14.1.5(p.91) (d)

Here we shall pay attention to the fact that replacing a and  $\mu$  in Lemma 11.1.1(p.55) ( $\mathscr{A}\{T_{\mathbb{R}}\}$ )(p.55) by  $a^*$  and a respectively yields Lemma 14.2.1(p.93) ( $\mathscr{A}\{T_{\mathbb{R}}\}$ ). Let us represent this replacement by

$$\mathcal{A}_{\mathbb{R}^{\to \mathbb{P}}} = \{ a \to a^{\star}, \ \mu \to a \}. \tag{14.2.1}$$

In other words, applying  $\mathcal{A}_{\mathbb{R}^{\to \mathbb{P}}}$  to the former lemma leads to the latter lemma, i.e.,

Lemma 14.2.1(p.33) 
$$(\mathscr{A}\{T_{\mathbb{P}}\}) = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\text{ Lemma 11.1.1(p.55)} (\mathscr{A}\{T_{\mathbb{R}}\})].$$
 (14.2.2)

Here let us focus on the following fact. The whole description proving Lemma 11.1.1(p.55) is quite different from that proving Lemma 14.2.1(p.93); in other words, no relation exists at all between both descriptions. Nevertheless, what is amazing here is that the whole descriptions of both lemmas are joined together by  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$ . In the paper, we call  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  the analogy replacement operation.

★ Fact 2 Next, note that replacing  $\mu$  in  $\left[\mathcal{L}(s) = L(\lambda\beta\mu - s)\right]$  (see (6.1.5(p.25))) by a yields  $\left[\mathcal{L}(s) = L(\lambda\beta a - s)\right]$  (see (6.1.22(p.26))). This means that applying  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  to the characteristic vector  $(L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}})$  (see (6.1.3(p.25)) - (6.1.6(p.25))) produces  $(L_{\mathbb{R}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}})$  (see (6.1.20(p.26)) - (6.1.23(p.26))), i.e.,

$$(L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}) = \mathcal{A}_{\mathbb{R} \to \mathbb{P}}[(L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}})]. \tag{14.2.3}$$

★ Fact 3 Finally, note that replacing  $\mu$  in  $V_1 = \beta \mu - s$  (see (7.4.1(p.41))) by a yields  $V_1 = \beta a - s$  (see (7.4.5(p.41))). This means that applying  $\mathcal{A}_{\mathbb{R}^{\to \mathbb{P}}}$  to the system of optimality equations SOE{M:1[ $\mathbb{R}$ ][A]} (see Table 7.4.1(p.41)(I)) leads to SOE{M:1[ $\mathbb{P}$ ][A]} (see Table 7.4.1(p.41)(II)), i.e.,

$$SOE\{M:1[\mathbb{P}][A]\} = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[SOE\{M:1[\mathbb{R}][A]\}]. \tag{14.2.4}$$

### 14.2.2 Prefiguration I

Here let us present a prefiguration through which  $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}$  can be obtained *only* by replacing a and  $\mu$  appearing  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}$  by  $a^{\star}$  and a respectively.

First, by  $F_{(a,\mu,b)}$  let us denote the distribution function with the lower bound a, the expectation  $\mu$ , and the upper bound b  $(a < \mu < b)$ . For convenience of reference, below let us copy (14.2.2(p.3)) - (14.2.4(p.3)):

For 
$$F_{(a,\mu,b)}$$
 For  $F_{(a,\mu,b)}$  For  $F_{(a,\mu,b)}$  Lemma 14.2.1(p.3)  $(\mathscr{A}\{T_{\mathbb{P}}\}) = \mathscr{A}_{\mathbb{R} \to \mathbb{P}}[$  Lemma 11.1.1(p.55)  $(\mathscr{A}\{T_{\mathbb{R}}\})$   $]$   $(L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}) = \mathscr{A}_{\mathbb{R} \to \mathbb{P}}[$   $(L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}})$   $]$   $[(1^*)^l$  SOE $\{M:1[\mathbb{P}][A]\}$   $[(1^*)^r]$  Procedure $[\mathbb{P}]$  Procedure $[\mathbb{R}]$ 

Next, closely looking at the flow of all discussions in Chap. 12[p.6l], we see that  $\mathscr{A}\{M:1[\mathbb{R}][A]\}$  was derived *only* from the procedure related to the three terms within the box  $(1^*)^r$  above; here let us denote this procedure by Procedure[ $\mathbb{R}$ ]. Now, for quite the same reason as in Procedure[ $\mathbb{R}$ ] we also see that  $\mathscr{A}\{M:1[\mathbb{P}][A]\}$  will be derived from the procedure related to the three terms

within the box  $(1^*)^l$  above, then let us denote this procedure by Procedure[ $\mathbb{P}$ ]. The flow of the above two procedures can be schematized as below.

Now, since we have the relation  $(1^*)^l = \mathcal{A}_{\mathbb{R}^{\to \mathbb{P}}}[(1^*)^r]$  due to the three Facts in the preceding section, it can be prefigured that this relation will be inherited also between Procedure  $[\mathbb{P}]$  and Procedure  $[\mathbb{R}]$ , i.e.,

$$\operatorname{Procedure}[\mathbb{P}] = \mathcal{A}_{\mathbb{R}^{\to \mathbb{P}}}[\operatorname{Procedure}[\mathbb{R}]],$$

hence also between  $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}$  and  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}$ , i.e.

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\} = \mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}]. \tag{14.2.5}$$

In other words,  $\mathscr{A}\{M:1[\mathbb{P}][A]\}$  can be obtained by applying  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  to  $\mathscr{A}\{M:1[\mathbb{R}][A]\}$ . From the above discussions we see that the above figure can be rewritten as below.

$$\begin{array}{c|c} \operatorname{For} F_{(a,\mu,b)} & \operatorname{For} F_{(a,\mu,b)} \\ \\ \operatorname{Lemma} \ 14.2.1(\operatorname{p.93}) \left( \mathscr{A} \left\{ T_{\mathbb{P}} \right\} \right) & = \ \mathcal{A}_{\mathbb{R} \to \mathbb{P}} [ & \operatorname{Lemma} \ 11.1.1(\operatorname{p.55}) \left( \mathscr{A} \left\{ T_{\mathbb{R}} \right\} \right) \\ \left( L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}} \right) & = \ \mathcal{A}_{\mathbb{R} \to \mathbb{P}} [ & \operatorname{SOE} \{ \operatorname{M}:1[\mathbb{R}][\mathbb{A}] \} \\ \left( 1^{\star} \right)^{l} & \operatorname{SOE} \{ \operatorname{M}:1[\mathbb{P}][\mathbb{A}] \} & = \ \mathcal{A}_{\mathbb{R} \to \mathbb{P}} [ & \operatorname{Procedure}[\mathbb{R}] \\ \downarrow & \downarrow \\ \left( 2^{\star} \right)^{l} & \mathscr{A} \{ \operatorname{M}:1[\mathbb{P}][\mathbb{A}] \} & = \ \mathcal{A}_{\mathbb{R} \to \mathbb{P}} [ & \mathscr{A} \{ \operatorname{M}:1[\mathbb{R}][\mathbb{A}] \} \\ \end{array} \right]$$

Here note that the above discussions is not a proof but a prefiguration.

#### 14.2.3 Prefiguration II

Below is another prefiguration through which the validity of (14.2.5(p.94)) will be confirmed.

First, let us represent the procedure proving  $\mathscr{A}\{M:1[\mathbb{R}][E]\}_{(a,\mu,b)}$  with  $F_{(a,\mu,b)}$  by  $\operatorname{Procedure}[\mathbb{R}]_{(a,\mu,b)}$  (see Section 12.2(p.61)). Now, since  $a^{\star} < a < b$  due to Lemma 14.2.1(p.93) (n), we can express the F with the lower bound  $a^{\star}$ , the expectation a, and the upper bound b as  $F_{(a^{\star},a,b)}$ , hence we can define  $\operatorname{Procedure}[\mathbb{R}]_{(a^{\star},a,b)}$ , proving  $\mathscr{A}\{M:1[\mathbb{R}][E]\}_{(a^{\star},a,b)}$  with  $F_{(a^{\star},a,b)}$ . Here note that  $\operatorname{Procedure}[\mathbb{R}]_{(a^{\star},a,b)}$  is identical to one resulting from replacing a and  $\mu$  in  $\operatorname{Procedure}[\mathbb{R}]_{(a,\mu,b)}$  by  $a^{\star}$  and a respectively, i.e.,

$$\operatorname{Procedure}[\mathbb{R}]_{(a^{\star},a,b)} = \mathcal{A}_{\mathbb{R}^{\to \mathbb{P}}}[\operatorname{Procedure}[\mathbb{R}]_{(a,\mu,b)}].$$

Then, from the three facts in Section 14.2.1(p.33) we can regard Procedure  $[\mathbb{P}]_{(a,\mu,b)}$  as quite the same as Procedure  $[\mathbb{R}]_{(a^{\star},a,b)}$  from the viewpoint of symbolic logic,  $^{\dagger}$  i.e.,

$$\operatorname{Procedure}[\mathbb{P}]_{(a,\mu,b)}\stackrel{\mathtt{s}\text{-logic}}{=}\operatorname{Procedure}[\mathbb{R}]_{(a^{\bigstar},a,b)}$$

hence we have

$$\operatorname{Procedure}[\mathbb{P}]_{(a,\mu,b)}\stackrel{\text{$\mathfrak{s}$-logic}}{=}\operatorname{Procedure}[\mathbb{R}]_{(a^{\star},a,b)}=\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}[\operatorname{Procedure}[\mathbb{R}]_{(a,\mu,b)}].$$

The above relation implies that  $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]\}_{(a,\mu,b)}$  proved by  $\mathrm{Procedure}[\mathbb{P}]_{(a,\mu,b)}$  becomes identical (in the sense of "symbolic logic") to  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}_{(a^\star,a,b)}$  proved by  $\mathrm{Procedure}[\mathbb{R}]_{(a^\star,a,b)}$ , i.e.,

$$\mathscr{A}\{\mathsf{M}{:}1[\mathbb{P}][\mathsf{E}]\}_{(a,\mu,b)}\stackrel{\mathtt{s}\cdot\mathrm{logic}}{=}\mathscr{A}\{\mathsf{M}{:}1[\mathbb{R}][\mathsf{E}]\}_{(a^\star,a,b)}.$$

<sup>&</sup>lt;sup>†</sup>A logic is regarded as reducing deduction to the process which transforms the expressions by representing propositions, the concept of logic, and so on with symbols such as +, -, >, <,  $\lor$ ,  $\land$ ,  $\Rightarrow$ , and so on (Wikipedia)

In other words,  $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]\}_{(a,\mu,b)}$  can be given by  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}_{(a^{\star},a,b)}$  resulting from applying  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  to  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}_{(a,\mu,b)}$ or equivalently from replacing a and  $\mu$  in  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}_{(a,\mu,b)}$  by  $a^\star$  and a respectively, i.e.,

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]\}_{(a,\mu,b)}\stackrel{\mathrm{s}\cdot\mathrm{logic}}{=}\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}_{(a^\star,a,b)}=\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}_{(a,\mu,b)}];$$

#### 14.2.4 Strict Proof

In this section, by dividing the *intuitive* prefiguration in Section 14.2.2(p.93) into several stages, we shall *strictly* prove that (14.2.5(p.94)) holds also theoretically.

- $\square$  First, let us note that Procedure  $[\mathbb{R}]$  deriving  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}$  (see Section 12.2(p.61)) can be restated as below.
  - · First, by applying  $\mathscr{A}\{T_{\mathbb{R}}\}$  (see Lemma 11.1.1(p.55)) to the characteristic vector  $(L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}})$  consisting of (6.1.3(p.25))-(6.1.6(p.25)), we obtain expressions (11.2.3(p.57)) - (11.2.8(p.57)); let us denote these expressions by  $\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}$ .
  - · Next, by applying the  $\mathscr{A}\{T_{\mathbb{R}}\}$  to the  $\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}$ , we get the assertion system  $\mathscr{A}\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}$  (see Lemmas 11.2.1(p.57) -11.3.1(p.59)).
  - · Finally, by applying the system of optimality equations  $SOE\{M:1[\mathbb{R}][E]\}$  (see Table 7.4.1(p.41) (I)) to  $\mathscr{A}\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}$ , we get the assertion system  $\mathscr{A}\{M:1[\mathbb{R}][E]\}\$  (see Tom's 12.2.1(p61) and 12.2.2(p62)).

The above flow of Procedure  $[\mathbb{R}]$  can be schematized as below.

$$\begin{split} \operatorname{Procedure}[\mathbb{R}] \;\; &= \;\; \langle \! \langle \, \mathscr{A}\{T_{\mathbb{R}}\} \Rightarrow (L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}) \rightarrow \{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}, \\ & \mathscr{A}\{T_{\mathbb{R}}\} \Rightarrow \{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\} \rightarrow \mathscr{A}\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}, \\ & \operatorname{SOE}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\} \Rightarrow \mathscr{A}\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\} \rightarrow \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\} \rangle \rangle \end{split}$$

 $\square$  Secondarily, applying  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  to the above flow leads to

$$\begin{split} \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\operatorname{Procedure}[\mathbb{R}]] \; &= \; \left\langle\!\left\langle \left. \mathcal{A}_{\mathbb{R}\to\mathbb{P}} [\mathscr{A}\{T_{\mathbb{R}}\}] \Rightarrow \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[(L_{\mathbb{R}},K_{\mathbb{R}},\mathcal{L}_{\mathbb{R}},\kappa_{\mathbb{R}})] \to \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\{L_{\mathbb{R}},K_{\mathbb{R}},\mathcal{L}_{\mathbb{R}},\kappa_{\mathbb{R}}\}], \\ & \mathcal{A}_{\mathbb{R}\to\mathbb{P}} [\mathscr{A}\{T_{\mathbb{R}}\}] \Rightarrow \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\{L_{\mathbb{R}},K_{\mathbb{R}},\mathcal{L}_{\mathbb{R}},\kappa_{\mathbb{R}}\}] \to \mathcal{A}_{\mathbb{R}\to\mathbb{P}} [\mathscr{A}\{L_{\mathbb{R}},K_{\mathbb{R}},\mathcal{L}_{\mathbb{R}},\kappa_{\mathbb{R}}\}], \\ & \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\operatorname{SOE}\{\mathbb{M}:1[\mathbb{R}][\mathbb{E}]\}] \Rightarrow \mathcal{A}_{\mathbb{R}\to\mathbb{P}} [\mathscr{A}\{L_{\mathbb{R}},K_{\mathbb{R}},\mathcal{L}_{\mathbb{R}},\kappa_{\mathbb{R}}\}] \to \mathcal{A}_{\mathbb{R}\to\mathbb{P}} [\mathscr{A}\{\mathbb{M}:1[\mathbb{R}][\mathbb{E}]\}] \rangle \end{split}$$

 $\Box$  Thirdly, due to (14.2.2(p.93))-(14.2.4(p.93)) we can replace

$$\mathcal{A}_{\mathbb{R} \to \mathbb{P}}[\mathscr{A}\{T_{\mathbb{R}}\}], \quad \mathcal{A}_{\mathbb{R} \to \mathbb{P}}[(L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}})], \quad \mathcal{A}_{\mathbb{R} \to \mathbb{P}}[\mathtt{SOE}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}]$$

in the above flow by

$$\mathscr{A}\{T_{\mathbb{P}}\}, \quad (L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}), \quad \mathtt{SOE}\{\mathsf{M}{:}1[\mathbb{P}][\mathsf{E}]\}$$

respectively. Accordingly, the above flow can be rewritten as follows.

$$\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}[\operatorname{Procedure}[\mathbb{R}]] = \langle\!\langle \underline{\mathscr{A}}\{T_{\mathbb{P}}\} \Rightarrow \underline{(L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{R}})} \to \mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}[\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}],$$

$$\underline{\mathscr{A}}\{T_{\mathbb{P}}\} \Rightarrow \mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}[\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}] \to \mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}[\mathscr{A}\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}],$$

$$\operatorname{SOE}\{\mathsf{M}:1[\mathbb{P}][E]\} \Rightarrow \mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}[\mathscr{A}\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}] \to \mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][E]\}]\rangle\rangle$$

$$(14.2.6)$$

☐ Fourthly, let us focus our attentions on the items without underline in the above flow, i.e.,

$$\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\operatorname{Procedure}[\mathbb{R}]] = \langle\!\langle \mathscr{A}\{T_{\mathbb{P}}\} \Rightarrow (L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}) \to \underline{\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}]},$$

$$\mathscr{A}\{T_{\mathbb{P}}\} \Rightarrow \underline{\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}]} \to \underline{\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}]},$$

$$\operatorname{SOE}\{\mathsf{M}:1[\mathbb{P}][E]\} \Rightarrow \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}] \to \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][E]\}] \rangle\rangle$$

$$(14.2.7)$$

Here  $(L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}})$  can be describes as follows.

$$L(x) \begin{cases} = \lambda \beta a - s - \lambda \beta x \text{ on } (-\infty, a^*] & \cdots (1), \\ > \lambda \beta a - s - \lambda \beta x \text{ on } (a^*, \infty) & \cdots (2), \end{cases}$$

$$(14.2.8)$$

$$K(x) \begin{cases} = \lambda \beta a - s - \delta x & \text{on } (-\infty, a^*] & \cdots (1), \\ > \lambda \beta a - s - \delta x & \text{on } (a^*, \infty) & \cdots (2), \end{cases}$$

$$(14.2.9)$$

$$K(x) \begin{cases} = \lambda \beta a - s - \delta x & \text{on } (-\infty, a^*] & \cdots (1), \\ > \lambda \beta a - s - \delta x & \text{on } (a^*, \infty) & \cdots (2), \end{cases}$$

$$K(x) \begin{cases} > -(1 - \beta)x - s & \text{on } (-\infty, b) & \cdots (1), \\ = -(1 - \beta)x - s & \text{on } [b, \infty) & \cdots (2), \end{cases}$$

$$(14.2.10)$$

$$K(x) + x \ge \beta x - s$$
 on  $(-\infty, \infty)$ , (14.2.11)

$$K(x) + x = \begin{cases} \lambda \beta a - s + (1 - \lambda)\beta x \text{ on } (-\infty, a^{\star}] & \cdots (1), \\ \beta x - s & \text{on } [b, \infty) & \cdots (2), \end{cases}$$

$$(14.2.12)$$

$$K(x_L) = -(1-\beta) x_L \cdots (1), \quad L(x_K) = (1-\beta) x_K \cdots (2),$$
 (14.2.13)

● Direct proof See (A 2.1(p.303))-(A 2.6(p.303)). ■

□ Fifthly, applying  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  to the relations  $\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}$  (see Lemmas 11.2.1(p.57) -11.3.1(p.59)) yields the relations  $\{L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}\}$ , i.e.,

$$\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}] = \{L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}\}. \tag{14.2.14}$$

 $\square$  Finally, noting (14.2.14(p.96)), we can rewrite (14.2.7(p.95)) as below.

$$\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\operatorname{Procedure}[\mathbb{R}]] = \langle\!\langle \mathscr{A}\{T_{\mathbb{P}}\} \Rightarrow (L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{R}}) \rightarrow \{L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}\},$$

$$\mathscr{A}\{T_{\mathbb{P}}\} \Rightarrow \{L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}\} \rightarrow \underline{\mathcal{A}}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}],$$

$$\operatorname{SOE}\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]\} \Rightarrow \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}] \rightarrow \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}] \rangle\!\rangle$$

$$(14.2.15)$$

 $\square$  Now we have

$$\underline{\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}[\mathscr{A}\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}]} = \mathscr{A}\{L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}\}.$$

$$(14.2.16)$$

Accordingly (14.2.15(p.96)) can be rewritten as below.

$$\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\operatorname{Procedure}[\mathbb{R}]] = \langle \langle \mathscr{A}\{T_{\mathbb{P}}\} \Rightarrow (L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{R}}) \rightarrow \{L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}\},$$

$$\mathscr{A}\{T_{\mathbb{P}}\} \Rightarrow \{L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}\} \rightarrow \mathscr{A}\{L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}\},$$

$$\operatorname{SOE}\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]\} \Rightarrow \mathscr{A}\{L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}\} \rightarrow \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}] \rangle \rangle. \tag{14.2.17}$$

 $\square$  Applying (14.2.16(p.96)) to Lemmas 11.2.1(p.57) to 11.3.1(p.59) yields the following lemmas and corollaries:

#### Lemma 14.2.2 ( $\mathscr{A}\{L_{\mathbb{P}}\}$ )

- (a) L(x) is continuous on  $(-\infty, \infty)$ .
- (b) L(x) is nonincreasing on  $(-\infty, \infty)$ .
- (c) L(x) is strictly decreasing on  $(-\infty, b]$ .
- (d) Let s=0. Then  $x_L=b$  where  $x_L>(\leq) x\Leftrightarrow L(x)>(=) 0 \Rightarrow L(x)>(\leq) 0$ .
- (e) Let s > 0.
  - 1.  $x_L$  uniquely exists with  $x_L < b$  where  $x_L > (= (<)) x \Leftrightarrow L(x) > (= (<)) 0$ .
  - 2.  $(\lambda \beta a s)/\lambda \beta \le (>) a^* \Leftrightarrow x_L = (>) (\lambda \beta a s)/\lambda \beta$ .  $\square$
- Proof by analogy Obtained from applying  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  to Lemma 11.2.1(p.57).
- Direct proof See Lemma A 2.2(p.303). ■

### Corollary 14.2.1 $(\mathscr{A}\{L_{\mathbb{P}}\})$

- (a)  $x_L > (\leq) x \Leftrightarrow L(x) > (\leq) 0$ .
- (b)  $x_L \geq (\leq) x \Rightarrow L(x) \geq (\leq) 0.$
- Proof by analogy Obtained from applying  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  to Corollary 11.2.1(p.57).
- Direct proof See Corollary A 2.1(p.303).

#### Lemma 14.2.3 $(\mathscr{A}\{K_{\mathbb{P}}\})$

- (a) K(x) is continuous on  $(-\infty, \infty)$ .
- (b) K(x) is nonincreasing on  $(-\infty, \infty)$ .
- (c) K(x) is strictly decreasing on  $(-\infty, b]$ .
- (d) K(x) is strictly decreasing on  $(-\infty, \infty)$  if  $\beta < 1$ .
- (e) K(x) + x is nondecreasing on  $(-\infty, \infty)$ .
- (f) K(x) + x is strictly increasing on  $[a^*, \infty)$ .
- (g) K(x) + x is strictly increasing on  $(-\infty, \infty)$  if  $\lambda < 1$ .
- (h) If  $x < y \text{ and } a^* < y, \text{ then } K(x) + x < K(y) + y.$
- (i) Let  $\beta = 1$  and s = 0. Then  $x_K = b$  where  $x_K > (\leq) x \Leftrightarrow K(x) > (=) 0 \Rightarrow K(x) > (\leq) 0$ .
- (j) Let  $\beta < 1$  or s > 0.
  - 1. There uniquely exists  $x_K$  where  $x_K > (= (<)) x \Leftrightarrow K(x) > (= (<)) 0$ .
  - 2.  $(\lambda \beta a s)/\delta \le (>) a^* \Leftrightarrow x_K = (>) (\lambda \beta a s)/\delta$ .
  - 3. Let  $\kappa > (= (<)) \ 0$ . Then  $x_K > (= (<)) \ 0$ .  $\square$
- Proof by analogy Obtained from applying  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  to Lemma 11.2.2(p.57).
- Direct proof See Lemma A 2.3(p.303).

#### Corollary 14.2.2 $(\mathscr{A}\{K_{\mathbb{P}}\})$

(a)  $x_K > (\leq) x \Leftrightarrow K(x) > (\leq) 0$ .

- (b)  $x_K \ge (\le) x \Rightarrow K(x) \ge (\le) 0.$
- Proof by analogy Obtained from applying  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  to Corollary 11.2.2(p.58).
- Direct proof See Lemma A 2.2(p.304).

#### Lemma 14.2.4 ( $\mathscr{A}\{L_{\mathbb{P}}/K_{\mathbb{P}}\}$ )

- (a) Let  $\beta = 1$  and s = 0. Then  $x_L = x_K = b$ .
- (b) Let  $\beta = 1$  and s > 0. Then  $x_L = x_K$ .
- (c) Let  $\beta < 1$  and s = 0. Then  $b > (= (<)) 0 \Leftrightarrow x_L > (= (<)) x_K \Rightarrow x_K > (= (=)) 0$ .
- (d) Let  $\beta < 1$  and s > 0. Then  $\kappa > (= (<)) \ 0 \Leftrightarrow x_L > (= (<)) \ x_K \Rightarrow x_K > (= (<)) \ 0$ .  $\square$
- Proof by analogy Obtained from applying  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  to Lemma 11.2.3(p.58).
- Direct proof See Lemma A 2.4(p.304).

#### Lemma 14.2.5 $(\mathscr{A}\{\mathcal{L}_{\mathbb{P}}\})$

- (a)  $\mathcal{L}(s)$  is nonincreasing in s and strictly decreasing in s if  $\lambda \beta < 1$ .
- (b) Let  $\lambda \beta a \geq b$ .
  - 1.  $x_L \leq \lambda \beta a s$ .
  - 2. Let s > 0 and  $\lambda \beta < 1$ . Then  $x_L < \lambda \beta a s$ .
- (c) Let  $\lambda \beta a < b$ . Then, there exists a  $s_{\mathcal{L}} > 0$  such that if  $s_{\mathcal{L}} > (\leq) s$ , then  $x_{\mathcal{L}} > (\leq) \lambda \beta a s$ .  $\square$
- Proof by analogy Obtained from applying  $\mathcal{A}_{\mathbb{R}^{\to \mathbb{P}}}$  to Lemma 11.2.4(p.59).
- Direct proof See Lemma A 2.5(p.305).

#### Lemma 14.2.6 $(\kappa_{\mathbb{P}})$ We have:

- (a)  $\kappa = \lambda \beta a s \text{ if } a^* > 0 \text{ and } \kappa = -s \text{ if } b < 0.$
- (b) Let  $\kappa > (= (<)) \ 0 \Leftrightarrow x_K > (= (<)) \ 0$ .
- Proof by analogy Obtained from applying  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  to Lemma 11.3.1(p.59).
- Direct proof See Lemma A 2.6(p.305).
- □ Since the assertion system  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}[\mathscr{A}\{M:1[\mathbb{R}][E]\}]$  in (14.2.17(p.%)) is derived from SOE{ $M:1[\mathbb{P}][E]$ }, it can be regarded as an assertion system for the model  $M:1[\mathbb{P}][E]$  (see Remark 7.1.1(p.29)), i.e.,  $\mathscr{A}\{M:1[\mathbb{P}][E]\}$ , hence we have

$$\mathscr{A}\{M:1[\mathbb{P}][A]\} = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{M:1[\mathbb{R}][A]\}] \text{ (the same as } (14.2.5(p.94))).$$
 (14.2.18)

Thus (14.2.17(p.96)) can be rewritten as follows.

$$\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\operatorname{Procedure}[\mathbb{R}]] = \langle\!\langle \mathcal{A}\{T_{\mathbb{P}}\} \Rightarrow (L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}) \rightarrow \{L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}\},$$

$$\mathscr{A}\{T_{\mathbb{P}}\} \Rightarrow \{L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}\} \rightarrow \mathscr{A}\{L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}\},$$

$$\operatorname{SOE}\{\mathsf{M}:1[\mathbb{P}][\mathbf{E}]\} \Rightarrow \mathscr{A}\{L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}}\} \rightarrow \mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathbf{E}]\}\rangle\rangle$$

$$(14.2.19)$$

 $\square$  The whole of the r.h.s. of (14.2.19(p.97)) can be regarded as the procedure deriving  $\mathscr{A}\{M:1[\mathbb{P}][E]\}$ , so let us denote it by Procedure  $(\mathbb{P})$ , i.e.,

$$\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\operatorname{Procedure}[\mathbb{R}]] = \operatorname{Procedure}[\mathbb{P}]. \tag{14.2.20}$$

Accordingly, finally it follows that we have

$$\begin{split} \operatorname{Procedure}[\mathbb{P}] \;\; &= \;\; \big\langle \! \; \mathscr{A} \big\{ T_{\mathbb{P}} \big\} \Rightarrow \big( L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}} \big) \to \big\{ L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}} \big\}, \\ & \mathscr{A} \big\{ T_{\mathbb{P}} \big\} \Rightarrow \big\{ L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}} \big\} \to \mathscr{A} \big\{ L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}} \big\}, \\ & \operatorname{SOE} \big\{ \mathsf{M} : 1[\mathbb{P}][\mathsf{E}] \big\} \Rightarrow \mathscr{A} \big\{ L_{\mathbb{P}}, K_{\mathbb{P}}, \mathcal{L}_{\mathbb{P}}, \kappa_{\mathbb{P}} \big\} \to \mathscr{A} \big\{ \mathsf{M} : 1[\mathbb{P}][\mathsf{E}] \big\} \big\rangle \end{split}$$

### 14.3 Analogy Theorem $(\mathbb{R} \leftrightarrow \mathbb{P})$

From (14.2.5(p.94)) we immediately obtain the following theorem.

 $\textbf{Theorem 14.3.1 (analogy } (\mathbb{R} \to \mathbb{P}) \textbf{)} \quad \textit{Let A} \{ M:1[\mathbb{R}][A] \} \ \textit{holds on P} \times \mathscr{F}. \ \textit{Then A} \{ M:1[\mathbb{P}][A] \} \ \textit{holds on P} \times \mathscr{F} \ \textit{where} \}$ 

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]\} = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}]. \quad \Box$$

$$(14.3.1)$$

Then, from the comparison of (I) and (III) of Tables 7.4.1(p.41) we also get

$$SOE\{M:1[\mathbb{P}][A]\} = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[SOE\{M:1[\mathbb{R}][A]\}]. \tag{14.3.2}$$

Moreover, from (13.4.2(p.75)) we obtain the following:

$$\boldsymbol{\theta}(\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}) = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\boldsymbol{\theta}(\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\})] \tag{14.3.3}$$

$$= (a^{\star}, a, b, x_L, x_K, s_{\mathcal{L}}, \kappa, T_{\mathbb{R}}, L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, V_t). \tag{14.3.4}$$

The analogy replacement operation  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  is a *mere* replacement of the two symbols,  $a \to a^*$  and  $\mu \to a$ . Hence, defining its inverse as

$$\mathcal{A}_{\mathbb{P}\to\mathbb{R}} = \{a^* \to a, a \to \mu\},\tag{14.3.5}$$

we can immediately obtain the inverse of the above theorem becomes true as follows.

Theorem 14.3.2 (analogy 
$$(\mathbb{P} \leftarrow \mathbb{R})$$
) Let  $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathbb{A}]\}$  holds on  $\mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]\}$  holds on  $\mathscr{P} \times \mathscr{F}$  where  $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathbb{A}]\} = \mathcal{A}_{\mathbb{P} \rightarrow \mathbb{R}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathbb{A}]\}]$ .  $\square$  (14.3.6)

In addition, as an inverses of (14.3.2(p.98)) and (14.3.3(p.98)) we immediately obtain

$$SOE\{M:1[\mathbb{R}][A]\} = \mathcal{A}_{\mathbb{P}\to\mathbb{R}}[SOE\{M:1[\mathbb{P}][A]\}]. \tag{14.3.7}$$

$$\theta(\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}) = \mathcal{A}_{\mathbb{P}\to\mathbb{R}}[\theta(\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]\})] \tag{14.3.8}$$

$$= (a, \mu, b, x_L, x_K, s_L, \kappa, T_{\mathbb{R}}, L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, V_t). \tag{14.3.9}$$

### 14.4 Derivation of $\mathscr{A}\{M:1[\mathbb{P}][A]\}$

- $\square$  Tom 14.4.1 ( $\mathscr{A}\{M:1[\mathbb{P}][A]\}$ ) Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nondecreasing in t > 0.
- (b)  $\boxed{\text{§ dOITs}_{\tau}\langle \tau \rangle}$  where  $\text{CONDUCT}_{\tau > t > 1}$ .
- Proof by analogy Immediate from applying  $\mathcal{A}_{\mathbb{R}^{\to \mathbb{P}}}$  to Tom 12.2.1(p.61).
- ullet Direct proof See Tom A.3 (p.315) .  $\blacksquare$
- $\label{eq:lambda} \ \, \square \ \, \mbox{Tom 14.4.2 ($\mathscr{A}$\{M:1[$\mathbb{P}$][$\mathbb{A}$]\}$)} \quad \ \, Let \ \beta < 1 \ or \ s > 0.$
- (a)  $V_t$  is nondecreasing in t > 0 and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
- (b) Let  $\beta a \geq b$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
- (c) Let  $\beta a < b$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $a s \leq a^*$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $a-s>a^{\star}$ . Then  $\boxed{\$ \text{ dOITs}_{\tau}\langle \tau \rangle}_{\blacktriangle}$  where  $\texttt{CONDUCT}_{\tau \geq t>1}_{\blacktriangle}$ .
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let b>0 ( $\kappa>0$ ). Then  $\boxed{\$ \text{dOITs}_{\tau>1}\langle \tau \rangle}$  where  $\text{CONDUCT}_{\tau\geq t>1}$ .
    - ii. Let  $b = 0 \ (\kappa = 0)$ .
      - 1. Let  $\beta a s \leq a^*$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
      - 2. Let  $\beta a s > a^{\star}$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  where  $\text{CONDUCT}_{\tau \geq t > 1_{\blacktriangle}}$ .
    - iii. Let  $b < 0 \ (\kappa < 0)$ .
      - 1. Let  $\beta a s \leq a^{\star}$  or  $s_{\mathcal{L}} \leq s$ . Then  $\left[ \bullet \operatorname{dOITd}_{\tau > 1} \langle 1 \rangle \right]_{\parallel}$ .
      - 2. Let  $\beta a s > a^*$  and  $s_{\mathcal{L}} > s$ . Then  $S_1(p.61)$   $\boxed{\$ \blacktriangle}$   $\boxed{\$}$  is true.  $\boxed{\$}$
- ullet Proof by analogy Immediate from applying  $\mathcal{A}_{\mathbb{R} o \mathbb{P}}$  to Tom 12.2.2(p.62).  $\blacksquare$
- Direct proof See Tom A 4.4(p.315) .

#### 14.5 Strict Definition of Analogy

Below let us provide the strict definition for "analogy" that we have indefinitely used so far.

#### Definition 14.5.1 (analogy)

- (a) By  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}[\mathfrak{X}]$  ( $\mathcal{A}_{\mathbb{P}^{\to\mathbb{R}}}[\mathfrak{X}]$ ) let us denote the assertion defined by applying  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  ( $\mathcal{A}_{\mathbb{P}^{\to\mathbb{R}}}$ ) to a given  $\mathfrak{X}$ .
- (b) If  $A\{\mathfrak{X}_2\} = \mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}[A\{\mathfrak{X}_1\}]$  and  $A\{\mathfrak{X}_1\} = \mathcal{A}_{\mathbb{P}^{\to\mathbb{R}}}[A\{\mathfrak{X}_2\}]$ , then  $A\{\mathfrak{X}_1\}$  and  $A\{\mathfrak{X}_2\}$  is said to be analogous, denoted by  $A\{\mathfrak{X}_1\} \bowtie A\{\mathfrak{X}_2\}$ .
- (c) For given two assertion systems  $\mathscr{A}\{\mathfrak{X}_1\}$  and  $\mathscr{A}\{\mathfrak{X}_2\}$  which are one-to-one correspondent, if  $A\{\mathfrak{X}_1\} \bowtie A\{\mathfrak{X}_2\}$  for any pair  $(A\{\mathfrak{X}_1\}, A\{\mathfrak{X}_2\})$  where  $A\{\mathfrak{X}_1\} \in \mathscr{A}\{\mathfrak{X}_1\}$  and  $A\{\mathfrak{X}_2\} \in \mathscr{A}\{\mathfrak{X}_2\}$  are correspondent each other, then  $\mathscr{A}\{\mathfrak{X}_1\}$  and  $\mathscr{A}\{\mathfrak{X}_2\}$  are said to be *analogous*, denoted by  $\mathscr{A}\{\mathfrak{X}_1\} \bowtie \mathscr{A}\{\mathfrak{X}_2\}$ .  $\square$

## 14.6 Analogy-Operation-Free

When no change occurs even if the analogy operation is applied to a given assertion A, the assertion is said to be *free from* the analogy operation, called the *analogy-operation-free assertion*.

**Lemma 14.6.1** Even if the analogy operation is applied to the analogy-operation-free assertion, no change occurs.  $\square$ 

• Proof Evident.

## 14.7 Optimal Price to Propose

**Lemma 14.7.1** ( $\mathscr{A}\{M:1[\mathbb{P}][A]\}$ ) The optimal price  $z_t$  to propose is nondecreasing in t>0.  $\square$ 

# Chapter 15

# Symmetry Theorem $(\mathbb{P} \leftrightarrow \tilde{\mathbb{P}})$

In this chapter we present the methodology deriving  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}$  (buying model with  $\mathbb{P}$ -mechanism) from  $\mathscr{A}\{M:1[\mathbb{P}][A]\}$  (selling model with  $\mathbb{P}$ -mechanism).

### 15.1 Functions $\check{T}$ , $\check{L}$ , $\check{K}$ , and $\check{\mathcal{L}}$ of Type $\mathbb{P}$

Below let us define ones corresponding to the underlying functions that were defined in Section 6.1.3(p.26). First let us define the T-function of Type  $\mathbb{P}$  for  $\check{F} \in \check{\mathscr{F}}$  corresponding to any  $F \in \mathscr{F}$  (see (6.1.19(p.26)) and (6.1.18(p.26))) by

$$\check{T}(x) = \max_{z} \check{p}(z)(z-x)\cdots(1), \qquad \check{p}(z) = \Pr\{z \le \hat{\xi}\}\cdots(2).$$
(15.1.1)

By  $\check{z}(x)$  let us define z maximizing  $\check{p}(z)(z-x)$  if it exists, i.e.,

$$\check{T}(x) = \check{p}(\check{z}(x))(\check{z}(x) - x). \tag{15.1.2}$$

Furthermore, let us define

$$\check{L}(x) = \lambda \beta \check{T}(x) - s, \tag{15.1.3}$$

$$\check{K}(x) = \lambda \beta \check{T}(x) - (1 - \beta)x - s, \tag{15.1.4}$$

$$\check{\mathcal{L}}(s) = \check{L}(\lambda \beta \check{a} - s), \tag{15.1.5}$$

$$\dot{\kappa} = \lambda \beta \dot{T}(0) - s. \tag{15.1.6}$$

Then, let the solutions of  $\check{L}(x) = 0$ ,  $\check{K}(x) = 0$ , and  $\check{\mathcal{L}}(s) = 0$  be denoted by respectively  $x_{\check{L}}$ ,  $x_{\check{K}}$ , and  $s_{\check{\mathcal{L}}}$  if they exist; If multiple solutions exist for each of  $x_{\check{L}}$ ,  $x_{\check{K}}$ , and  $s_{\check{\mathcal{L}}}$ , let us employ the *smallest* as its solution (see Sections 6.2(p.27) (a) and 13.2.1(p.71)). Furthermore, let us define (see Figure 13.1.1(p.70) for  $\check{a}$ ,  $\check{\mu}$ , and  $\check{b}$ )

$$\check{a}^* = \inf\{x \mid \check{T}(x) > \check{a} - x\} \quad (\text{see } (6.1.26(p.26))), \tag{15.1.7}$$

$$\check{x}^* = \inf\{x \mid \check{z}(x) > \check{a}\} \qquad \text{(see (6.1.27(p.26)))}. \tag{15.1.8}$$

By  $\check{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]$  let us define  $\mathsf{M}:1[\mathbb{P}][\mathtt{A}]$  for  $\check{F}\in\check{\mathscr{F}}$  corresponding to any  $F\in\mathscr{F}$ . Then, for the same reason as for  $\mathsf{SOE}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}$  (see Table 7.4.1(p.41) (III)) we can obtain

$$SOE\{\check{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]\} = \{V_1 = \beta\check{a} - s, \ V_t = \max\{\check{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ t > 1\}. \tag{15.1.9}$$

# 15.2 Functions $\check{T}$ , $\check{L}$ , $\check{K}$ , and $\check{\mathcal{L}}$ of Type $\mathbb{P}$

Below let us define ones corresponding to the underlying functions that were defined in Section 6.1.4(p.26). First, let us define the  $\tilde{T}$ -function of  $\tilde{T}$ ype  $\mathbb{P}$  for  $\check{F} \in \check{\mathscr{F}}$  corresponding to any  $F \in \mathscr{F}$  by (see (6.1.32(p.26))).

$$\check{T}(x) = \min_{z} \check{p}(z)(z-x) \cdots (1), \qquad \check{p}(z) = \Pr\{\hat{\boldsymbol{\xi}} \le z\} \cdots (2)$$
(15.2.1)

where by  $\check{z}(x)$  let us define z minimizing  $\check{\tilde{p}}(z)(z-x)$  if it exists, i.e.,

$$\check{T}(x) = \check{p}(\check{z}(x))(\check{z}(x) - x). \tag{15.2.2}$$

Let us define

$$\tilde{L}(x) = \lambda \beta \tilde{T}(x) + s, \qquad (15.2.3)$$

$$\check{K}(x) = \lambda \beta \check{T}(x) - (1 - \beta)x + s, \tag{15.2.4}$$

$$\check{\mathcal{L}}(s) = \check{L}(\lambda\beta\check{b} + s), \tag{15.2.5}$$

$$\dot{\tilde{\kappa}} = \lambda \beta \dot{\tilde{T}}(0) + s \tag{15.2.6}$$

where let us define the solutions of  $\check{L}(x) = 0$ ,  $\check{K}(x) = 0$ , and  $\check{\mathcal{L}}(x) = 0$  by respectively  $x_{\check{L}}$ ,  $x_{\check{K}}$ , and  $s_{\check{\mathcal{L}}}$ ; If multiple solutions exist for each of  $x_{\check{L}}$ ,  $x_{\check{K}}$ , and  $s_{\check{\mathcal{L}}}$ , we shall employ the *largest* as its solution (see Sections 6.2(p.27) (b)). Furthermore let us define (see Figure 13.1.1(p.70) for  $\check{a}$ ,  $\check{\mu}$ , and  $\check{b}$ )

$$\check{b}^* = \sup\{x \mid \check{T}(x) < \check{b} - x\} \quad (\text{see } (6.1.39(p.27))), \tag{15.2.7}$$

$$\dot{\tilde{x}}^* = \sup\{x \mid \tilde{z}(x) < \check{b}\} \qquad \text{(see (6.1.40(p.27)))}. \tag{15.2.8}$$

By  $\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]$  let us define  $\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]$  for  $\check{F}\in\check{\mathscr{F}}$  corresponding to any  $F\in\mathscr{F}$ . Then, for the same reason as for  $\mathsf{SOE}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}$  (see Table 7.4.1(p.41) (IV)) we can obtain

$$SOE\{\tilde{M}:1[\mathbb{P}][A]\} = \{V_1 = \beta \check{b} + s, \ V_t = \min\{\check{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \ \ t > 1\}. \tag{15.2.9}$$

# 15.3 List of Underline Functions of Type $\mathbb P$ and ${\operatorname{\widetilde{T}ype}}\ \mathbb P$

The table below is the list of the four kinds of underline functions of Type  $\mathbb{P}$  and  $\tilde{T}$ ype  $\mathbb{P}$  (see Table 13.2.1(p.71)).

Table 15.3.1: List of the underlying functions of Type  $\mathbb P$  and Type  $\mathbb P$ 

Type P	$ ilde{ t Type} \ \mathbb{P}$
For any $F \in \mathscr{F}$	For $\check{F} \in \check{\mathscr{F}}$ corresponding to any $F \in \mathscr{F}$
$T(x) = \max_{z} p(z)(z - x)$	$\check{T}(x) = \max_{z} \check{p}(z)(z - x)$
$L(x) = \beta T(x) - s$	$\check{L}(x) = \beta \check{T}(x) - s$
$K(x) = \beta T(x) - (1 - \beta)x - s$	$\check{K}(x) = \beta \check{T}(x) - (1 - \beta)x - s$
$\mathcal{L}(x) = L(\beta a - s)$	$\check{\mathcal{L}}\left(x ight)=\check{\mathit{L}}\left(eta\check{a}-s ight)$
See Section 6.1.3(p.26)	See Section 15.1
$\tilde{T}(x) = \min_{z} \tilde{p}(z)(z-x)$	$\check{\tilde{T}}(x) = \min_{z} \check{\tilde{p}}(z)(z - x)$
$\tilde{L}(x) = \beta \tilde{T}(x) + s$	$\check{\tilde{L}}(x) = \beta \check{\tilde{T}}(x) + s$
$\tilde{K}(x) = \beta \tilde{T}(x) - (1 - \beta)x + s$	$\check{K}(x) = \beta \check{T}(x) - (1 - \beta)x + s$
$\tilde{\mathcal{L}}(x) = \tilde{L}(\beta b + s)$	$\check{\mathcal{L}}(x) = \check{\tilde{L}}(\beta\check{b} + s)$
See Section 6.1.4(p.26)	See Section 15.2

### 15.4 Two Kinds of Replacements

### 15.4.1 Correspondence Replacement

**Lemma 15.4.1** ( $C_{\mathbb{P}}$ ) The left side of each equality below is for any  $F \in \mathscr{F}$  and its right side is for  $\check{F} \in \mathscr{F}$  corresponding to the F. Then:

- (a)  $f(\xi) = \check{f}(\hat{\xi}).$
- (b)  $\hat{a} = \check{b}, \quad \hat{a}^* = \check{b}^*, \quad \hat{b} = \check{a}.$
- (c)  $\hat{T}(x) = \check{\tilde{T}}(\hat{x}).$
- (d)  $\hat{L}(x) = \check{\tilde{L}}(\hat{x}).$
- (e)  $\hat{K}(x) = \check{K}(\hat{x})$
- (f)  $\hat{\mathcal{L}}(s) = \hat{\mathcal{L}}(s)$ .
- (g)  $\hat{x}_L = x_{\tilde{L}}$ .
- $(\mathbf{h}) \quad \hat{x}_K = x_{\tilde{K}}.$
- (i)  $s_{\mathcal{L}} = s_{\tilde{\mathcal{L}}}$ .
- (j)  $\hat{\kappa} = \check{\tilde{\kappa}}$ .  $\square$

#### • *Proof* (a) The same as (13.1.8(p.69)).

(The first and third equalities of (b)) The same as the first and third equalities of (13.1.9(p.69)). The second equality will be proven after the proof of (c).

(c) From (6.1.18(p.26)) and (15.2.1(2)(p.101)), we obtain

$$p(z) = \Pr\{-\hat{z} \le -\hat{\xi}\} = \Pr\{\hat{\xi} \le \hat{z}\} = \check{p}(\hat{z}),$$
 (15.4.1)

hence from (6.1.19(p.26)) we have  $T(x) = \max_z \check{p}(\hat{z})(-\hat{z}+\hat{x}) = -\min_z \check{p}(\hat{z})(\hat{z}-\hat{x})$ . Now, in general " $\min_z = \min_{-\infty < z < \infty} = \min_{-\infty < \hat{z} < \infty} = \min_{-\infty < \hat{z} < \infty} = \min_{-\infty < \hat{z} < \infty} = \min_z$ ", hence we have  $T(x) = -\min_{\hat{z}} \check{p}(z)(\hat{z}-\hat{x})$ . Then, without loss of

generality, this can be rewritten as  $T(x) = -\min_z \check{\tilde{p}}(z)(z-\hat{x})$ . Accordingly, since  $T(x) = -\check{T}(\hat{x})$  from (15.2.1 (1) (p.101)), we obtain  $\hat{T}(x) = \check{T}(\hat{x})$ .

(The second equality of (b)) From (6.1.26(p.26)) we have  $a^* = \inf\{-\hat{x} \mid -\hat{T}(x) > -\hat{a} + \hat{x}\} = -\sup\{\hat{x} \mid \hat{T}(x) < \hat{a} - \hat{x}\} = -\sup\{\hat{x} \mid \check{T}(\hat{x}) < \check{b} - \hat{x}\}$  due to (c) and (b). Without loss of generality, this can be rewritten as  $a^* = -\sup\{x \mid \check{T}(x) < \check{b} - x\}$ , hence  $a^* = -\check{b}^*$  due to (15.2.7(p.102)), so that  $\hat{a}^* = \check{b}^*$ .

- (d) From (6.1.20(p.26)) and (c) we have  $L(x) = -\lambda \beta \hat{T}(x) s = -\lambda \beta \hat{T}(\hat{x}) s = -\tilde{L}(\hat{x})$  from (15.2.3(p.101)), hence  $\hat{L}(x) = \tilde{L}(\hat{x})$ .
- (e) From (6.1.21(p.26)) and (c) we have  $K(x) = -\lambda \beta \hat{T}(x) + (1-\beta)\hat{x} s = -\lambda \beta \check{T}(\hat{x}) + (1-\beta)\hat{x} s = -\check{K}(\hat{x})$  from (15.2.4(p.101)), hence  $\hat{K}(x) = \check{K}(\hat{x})$ .
- (f) From (6.1.22(p.26)) we have  $\mathcal{L}(s) = -\hat{L}(\lambda\beta a s) = -\tilde{L}(\lambda\widehat{\beta a} s)$  due to (d). Then, since  $\mathcal{L}(s) = -\tilde{L}(-\lambda\beta a + s) = -\tilde{L}(\lambda\beta\hat{a} + s) = -\tilde{L}(\lambda\beta\hat{b} + s)$  due to (b), we have  $\mathcal{L}(s) = -\tilde{L}(s)$  from (15.2.5(p.101)), hence  $\hat{\mathcal{L}}(s) = \tilde{\mathcal{L}}(s)$ .
- (g) Since  $L(x_L) = 0$  by definition, we have  $-\hat{L}(x_L) = 0$ , i.e.,  $\hat{L}(x_L) = 0$ , hence  $\check{L}(\hat{x}_L) = 0$  from (d), implying that  $\check{L}(x) = 0$  has the solution  $x_{\check{L}} = \hat{x}_L$  by definition.
- (h) Since  $K(x_K) = 0$  by definition, we have  $-\hat{K}(x_K) = 0$ , i.e.,  $\hat{K}(x_K) = 0$ , hence  $\check{K}(\hat{x}_K) = 0$  from (e), implying that  $\check{K}(x) = 0$  has the solution  $x_{\check{k}} = \hat{x}_K$  by definition.
- (i) Since  $\mathcal{L}(s_{\mathcal{L}}) = 0$  by definition, we have  $-\hat{\mathcal{L}}(s_{\mathcal{L}}) = 0$ , i.e.,  $\hat{\mathcal{L}}(s_{\mathcal{L}}) = 0$ , hence  $\check{\mathcal{L}}(s_{\mathcal{L}}) = 0$  from (f), implying that  $\check{\mathcal{L}}(s) = 0$  has the solution  $s_{\check{z}} = s_{\mathcal{L}}$  by definition.
- (j) From (6.1.23(p.26)) we have  $\kappa = -\lambda \beta \hat{T}(0) s = -\lambda \beta \hat{T}(\hat{0}) s$  from (c), hence  $\kappa = -\lambda \beta \hat{T}(0) s = -\tilde{\kappa}$  from (15.2.6(p.101)), thus  $\hat{\kappa} = \tilde{\kappa}$ .

**Definition 15.4.1** (correspondent replacement operation  $\mathcal{C}_{\mathbb{P}}$ ) Let us call the operation of replacing the left-hand side of each equality in Lemma 15.4.1(p.102) by its right-hand side the *correspondence replacement operation*  $\mathcal{C}_{\mathbb{P}}$ .  $\square$ 

**Lemma 15.4.2**  $(\tilde{\mathcal{C}}_{\mathbb{P}})$  The left side of each equality below is for any  $F \in \mathscr{F}$  and its right side is for  $\check{F} \in \check{\mathscr{F}}$  corresponding to the F. Then:

- (a)  $f(\xi) = \check{f}(\hat{\xi}).$
- (b)  $\hat{a} = \check{b}, \quad \hat{b}^* = \check{a}^*, \quad \hat{b} = \check{a}.$
- (c)  $\hat{T}(x) = \check{T}(\hat{x})$ .
- (d)  $\hat{L}(x) = L(\hat{x}).$
- (e)  $\hat{K}(x) = \check{K}(\hat{x}).$
- (f)  $\hat{\mathcal{L}}(s) = \check{\mathcal{L}}(s)$ .
- (g)  $\hat{x}_{\tilde{L}} = \check{x}_L$ .
- (h)  $\hat{x}_{\tilde{K}} = \check{x}_K$ .
- (i)  $s_{\tilde{\mathcal{L}}} = s_{\check{\mathcal{L}}}$ .
- (j)  $\hat{\tilde{\kappa}} = \check{\kappa}$ .
- *Proof* (29.2.3) The same as (13.1.8(p.69)).

(The first and third equalities of (b)) The same as the first and third equation of (13.1.9(p.69)). The second equality will be proven after the proof of (c).

(c) From (6.1.31(p.26)) and (15.1.1(2)(p.101)) we obtain

$$\tilde{p}(z) = \Pr\{-\hat{\xi} \le -\hat{z}\} = \Pr\{\hat{\xi} \ge \hat{z}\} = \Pr\{\hat{z} \le \hat{\xi}\} = \check{p}(\hat{z}),$$
(15.4.2)

hence from (6.1.32 p.26) we have  $\tilde{T}(x) = \min_z \check{p}(\hat{z})(-\hat{z}+\hat{x}) = -\max_z \check{p}(\hat{z})(\hat{z}-\hat{x})$ . Now, in general " $\max_z = \max_{-\infty < z < \infty} = \max_{-\infty < -\hat{z} < \infty} = \max_{-\infty < \hat{z} < \infty} = \max_{-\infty < \hat{z} < \infty} = \max_{-\infty < \hat{z} < \infty} = \max_z$ ", hence we have  $\tilde{T}(x) = -\max_z \check{p}(z)(\hat{z}-\hat{x})$ . Then, without loss of generality, this can be rewritten as  $\tilde{T}(x) = -\max_z \check{p}(z)(z-\hat{x})$ . Accordingly, since  $\tilde{T}(x) = -\check{T}(\hat{x})$  from (15.1.1(1) (p.101)), we obtain  $\hat{T}(x) = \check{T}(\hat{x})$ .

(The second equality of (b)) From (6.1.39(p.27)) we have  $b^* = \sup\{-\hat{x} \mid -\hat{T}(x) < -\hat{b} + \hat{x}\} = -\inf\{\hat{x} \mid \hat{T}(x) > \hat{b} - \hat{x}\} = -\inf\{\hat{x} \mid \check{T}(\hat{x}) > \check{a} - \hat{x}\}$  due to (c) and (b). Without loss of generality, this can be rewritten as  $b^* = -\inf\{\hat{x} \mid \check{T}(x) > \check{a} - x\}$  we have  $b^* = -\check{a}^*$  due to (15.1.7(p.101)) or equivalently  $-b^* = \check{a}^*$ , hence  $\hat{b}^* = \check{a}^*$ .

- (d) From (6.1.33(p.27)) and (c) we have  $\tilde{L}(x) = -\lambda \beta \hat{T}(x) + s = -\lambda \beta \check{T}(\hat{x}) + s = -\check{L}(\hat{x})$  from (15.1.3(p.101)), hence  $\hat{L}(x) = \check{L}(\hat{x})$ .
- (e) From (6.1.34(p.27)) and (c) we have  $\tilde{K}(x) = -\lambda \beta \hat{T}(x) + (1-\beta)\hat{x} + s = -\lambda \beta \check{T}(\hat{x}) + (1-\beta)\hat{x} + s = -\check{K}(\hat{x})$  from (15.1.4(p.101)), hence  $\hat{K}(x) = \check{K}(\hat{x})$ .
- (f) From (6.1.35(p.27)) we have  $\tilde{\mathcal{L}}(s) = -\hat{\tilde{L}}(\lambda\beta b + s)$ , hence from (d) we obtain  $\tilde{\mathcal{L}}(s) = -\check{L}(\lambda\beta b + s) = -\check{L}(\lambda\beta b s) = -\check{L}(\lambda\beta b s) = -\check{L}(\lambda\beta a s)$  due to (b). Accordingly, from (15.1.5(p.101)) we obtain  $\tilde{\mathcal{L}}(s) = -\check{L}(s)$ , hence  $\hat{\tilde{\mathcal{L}}}(s) = \check{\mathcal{L}}(s)$ .
- (g) Since  $\tilde{L}(x_{\tilde{L}}) = 0$  by definition, we have  $-\hat{L}(x_{\tilde{L}}) = 0$ , i.e.,  $\hat{L}(x_{\tilde{L}}) = 0$ , hence  $\check{L}(\hat{x}_{\tilde{L}}) = 0$  from (d), implying that  $\check{L}(x) = 0$  has the solution  $x_{\tilde{L}} = \hat{x}_{\tilde{L}}$  by definition.

- (h) Since  $\tilde{K}(x_{\tilde{K}}) = 0$  by definition, we have  $-\hat{K}(x_{\tilde{K}}) = 0$ , i.e.,  $\hat{K}(x_{\tilde{K}}) = 0$ , hence  $K(\hat{x}_{\tilde{K}}) = 0$  from (e), implying that  $\check{K}(x) = 0$  has the solution  $x_{\check{K}} = \hat{x}_{\check{K}}$  by definition.
- (i) Since  $\tilde{\mathcal{L}}(s_{\tilde{\mathcal{L}}}) = 0$  by definition, we have  $-\hat{\tilde{\mathcal{L}}}(s_{\tilde{\mathcal{L}}}) = 0$ , i.e.,  $\hat{\tilde{\mathcal{L}}}(s_{\tilde{\mathcal{L}}}) = 0$ , hence  $\check{\mathcal{L}}(s_{\tilde{\mathcal{L}}}) = 0$  from (f), implying that  $\check{\mathcal{L}}(s) = 0$ has the solution  $s_{\tilde{L}} = s_{\tilde{L}}$  by definition.
- (j) From (6.1.36(p.27)) we have  $\tilde{\kappa} = -\lambda \beta \tilde{T}(0) + s$ , leading to  $\tilde{\kappa} = -\lambda \beta \tilde{T}(\hat{0}) + s$  from (c), hence  $\tilde{\kappa} = -\lambda \beta \tilde{T}(0) + s = -\tilde{\kappa}$  from (15.1.6(p.101)), thus  $\hat{\tilde{\kappa}} = \check{\kappa}$ .

**Remark 15.4.1** The equality  $\hat{\mu} = \check{\mu}$  in Lemmas 13.3.1(p.72) (b) changes into respectively  $\hat{a}^* = \check{b}^*$  in Lemma 15.4.1(p.102) (b) and the equality  $\hat{\mu} = \check{\mu}$  in (13.1.9(p.69)) changes into  $\hat{b}^* = \check{a}^*$  in Lemma 15.4.2(p.103) (b).

The definition below is the same as Def. 13.3.3(p.73).

Definition 15.4.2 (reflective element and non-reflective element) It should be noted that the left side of each of the equalities in Lemmas 15.4.1(p.102) (i) and 15.4.2(p.103) (i) is respectively  $s_{\mathcal{L}}$  and  $s_{\tilde{\mathcal{L}}}$  without the hat symbol "  $\tilde{\phantom{a}}$ "; in other words,  $s_{\mathcal{L}}$  and  $s_{\tilde{\mathcal{L}}}$ are not subjected to the reflection. For the reason, let us refer to each of  $s_{\mathcal{L}}$  and  $s_{\tilde{\mathcal{L}}}$  as the non-reflective element and to each of all the other elements as the reflective element.  $\square$ 

**Definition 15.4.3** (correspondent replacement operation  $\tilde{\mathcal{C}}_{\mathbb{P}}$ ) Let us call the operation of replacing the left-hand side of each equality in the above lemma by its right-hand side the correspondence replacement operation  $\tilde{\mathcal{C}}_{\mathbb{P}}$ .  $\square$ 

#### 15.4.2Identity Replacement

**Lemma 15.4.3**  $(\mathcal{I}_{\mathbb{P}})$  The left side of each equality below is for  $\check{F} \in \check{\mathscr{F}}$  corresponding to any  $F \in \mathscr{F}$  and the right side is for  $F \in \mathscr{F}$  where  $\check{F} \equiv F \cdots [1^*]$ . † Then:

- (a)  $\check{F}(\xi) = F(\xi) \cdots [2^*] \text{ and } \check{f}(\xi) = f(\xi) \cdots [3^*] \text{ for any } \xi,$
- (b)  $\check{a} = a, \ \check{b}^* = b^*, \ \check{b} = b,$
- $\check{T}(x) = \tilde{T}(x),$ (c)
- $\check{L}(x) = \tilde{L}(x),$ (d)
- (e)  $\check{K}(x) = \tilde{K}(x)$ ,
- (f)  $\tilde{\mathcal{L}}(s) = \tilde{\mathcal{L}}(s)$ ,
- (g)
- (h)
- $x_{\tilde{L}} = x_{\tilde{L}},$   $x_{\tilde{K}} = x_{\tilde{K}},$   $x_{\tilde{K}} = s_{\tilde{L}},$   $s_{\tilde{L}} = s_{\tilde{L}},$
- $\tilde{\tilde{\kappa}} = \tilde{\kappa}$ . (j)
- Proof (a) Clear from [1\*].

(the first and last equalities of (b)) Immediate from (a). The second equality will be proven after the proof of (c).

(c) From (15.2.1 (2) (p.101)) we have  $\check{\tilde{p}}(z) = \Pr{\{\hat{\boldsymbol{\xi}} \leq z\}} = \int_{-\infty}^{z} \check{f}(\xi) d\xi$ . Then, due to [3\*] we have  $\check{\tilde{p}}(z) = \int_{-\infty}^{z} f(\xi) d\xi = \Pr{\{\boldsymbol{\xi} \leq z\}} = \int_{-\infty}^{z} f(\xi) d\xi$ . z} =  $\tilde{p}(z)$  from (6.1.31(p.20)). Hence, we have that  $\tilde{T}(x)$  given by (15.2.1(1)(p.101)) becomes  $\tilde{T}(x) = \min_z \tilde{p}(z)(z-x)$ , which is identical to  $\tilde{T}(x)$  given by (6.1.32(p.26)), i.e.,  $\tilde{\tilde{T}}(x) = \tilde{T}(x)$  for any x.

(the second equality of (b)) From (15.2.7(p.102)) and (c) we have  $\check{b}^{\star} = \sup\{x \mid \tilde{T}(x) < \check{b} - x\}$ , hence from (b) we get  $\check{b}^* = \sup\{x \mid \tilde{T}(x) < b - x\} = b^* \text{ due to } (6.1.39(p.27)).$ 

- (d,e) Noting (c), from (15.2.3(p.101)) and (6.1.33(p.27)) we have  $\tilde{L}(x) = \tilde{L}(x)$ . Similarly, from (15.2.4(p.101)) and (6.1.34(p.27)) we have  $\tilde{K}(x) = \tilde{K}(x)$ .
- (f) (15.2.5(p.101)) becomes  $\check{\mathcal{L}}(s) = \check{\mathcal{L}}(\lambda\beta b + s)$  due to (b). This can be rewritten as  $\check{\mathcal{L}}(s) = \tilde{\mathcal{L}}(\lambda\beta b + s)$  due to (d), which is the same as  $\tilde{\mathcal{L}}(s)$  given by (6.1.35(p.27)), i.e.,  $\hat{\mathcal{L}}(s) = \tilde{\mathcal{L}}(s)$ .
  - (g-i) Evident from (d-f).
  - (j) (15.2.6(p.101)) becomes  $\tilde{\kappa} = \lambda \beta \tilde{T}(0) + s$  due to (c), which is the same as  $\tilde{\kappa}$  given by (6.1.36(p.27)).

**Definition 15.4.4** (identity replacement operation  $\mathcal{I}_{\mathbb{P}}$ ) Let us call the operation of replacing the left-hand of each equality in the above lemma by its right-hand the identity replacement operation  $\mathcal{I}_{\mathbb{P}}$ .

**Lemma 15.4.4**  $(\tilde{\mathcal{I}}_{\mathbb{P}})$  The left side of each equality below is for  $\check{F} \in \check{\mathscr{F}}$  corresponding to any  $F \in \mathscr{F}$  and the right side is for  $F \in \mathscr{F}$  where  $F \equiv \check{F} \cdots [1^*]$ . Then:

- (a)  $\check{F}(\xi) = F(\xi) \cdots [2^*] \text{ and } \check{f}(\xi) = f(\xi) \cdots [3^*] \text{ for any } \xi,$
- (b)  $\check{a} = a, \ \check{a}^* = a^*, \ \check{b} = b,$
- (c)  $\check{T}(x) = T(x)$ ,
- (d)  $\check{L}(x) = L(x)$ ,

<sup>†</sup>See Lemma 13.1.1(p.70) (b)

- $\check{K}(x) = K(x),$
- (f)  $\check{\mathcal{L}}(s) = \mathcal{L}(s)$ ,
- (g)  $x_{\check{L}} = x_L$ ,
- (h)
- $\begin{array}{ll} \text{(h)} & x_{\breve{K}} = x_{K}, \\ \text{(i)} & s_{\breve{\mathcal{L}}} = s_{\mathcal{L}}, \\ \text{(j)} & \breve{\kappa} = \kappa. \end{array}$
- *Proof* (a) Clear from  $[1^*]$ .

(The first and last equalities of b)) Immediate form (a). The second equality will be proven after the proof of (c).

(c) From (15.1.1 (2) (p.101)) we have  $\check{p}(z) = \Pr\{z \leq \hat{\boldsymbol{\xi}}\} = \int_{z}^{\infty} \check{f}(\xi)d\xi$ . Then, due to [3\*] we have  $\check{p}(z) = \int_{z}^{\infty} f(\xi)d\xi = \Pr\{z \leq \boldsymbol{\xi}\} = p(z)$  from (6.1.18(p.26)). Hence, we have that  $\check{T}(x)$  given by (15.1.1 (1) (p.101)) becomes  $\check{T}(x) = \max_{z} p(z)(z-x)$ , which is identical to T(x) given by (6.1.19(p.26)), i.e.,  $\check{T}(x) = T(x)$  for any x.

(the second equality of (b)) From (15.1.7(1) (p.101)) and (c) we have  $\check{a}^* = \inf\{x \mid T(x) > \check{a} - x\}$ , hence from (b) we get  $\check{a}^* = \inf\{x \mid T(x) > a - x\} = a^* \text{ due to } (6.1.26 \text{(p.26)}).$  Thus, the second equality of (b) is true.

- (d,e) Noting (c), from (15.1.3(p.101)) and (6.1.20(p.26)) we have  $\check{L}(x) = L(x)$ . Similarly, from (15.1.4(p.101)) and (6.1.21(p.26)) we have  $\check{K}(x) = K(x)$ .
- (f) (15.1.5(p.101)) becomes  $\check{\mathcal{L}}(s) = \check{\mathcal{L}}(\lambda\beta a s)$  due to (b). This can be rewritten as  $\check{\mathcal{L}}(s) = \mathcal{L}(\lambda\beta a s)$  due to (d), which is the same as  $\mathcal{L}(s)$  given by (6.1.22(p.26)), i.e.,  $\check{\mathcal{L}}(s) = \mathcal{L}(s)$ .
  - (g-i) Evident from (d-f).
  - (j) (15.1.6(p.101)) becomes  $\kappa = \lambda \beta T(0) s$  due to (c), which is the same as  $\kappa$  given by (6.1.23(p.26)).

**Definition 15.4.5** (Identity replacement operation  $\tilde{\mathcal{I}}_{\mathbb{P}}$ ) Let us call the operation of replacing the left-hand of each equality in the above lemma by its right-hand the identity replacement operation  $\mathcal{I}_{\mathbb{P}}$ .  $\square$ 

#### 15.5Scenario of Type $\mathbb{P}$

#### 15.5.1 $Scenario[\mathbb{P}]$

This section provides the scenario deriving  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}$  (buying model with  $\mathbb{P}$ -mechanism) from  $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}$  (selling model with  $\mathbb{P}$ -mechanism), denoted by Scenario  $[\mathbb{P}]$ .

■ Before moving on, here let us carry out a review of Scenario [R]. For convenience of reference, below let us copy the transformation process of the attribute vectors (see (13.5.28(p.77))) in Scenario[ $\mathbb{R}$ ].

- From the above flow of the attribute vectors, we see that Scenario [P] is the same as Scenario [R] only except that
- $\circ$  a and  $\mu$  in  $\theta(\mathscr{A}\{M:1[\mathbb{R}][A]\})$  is replaced  $a^*$  and a in  $\theta(\mathscr{A}\{M:1[\mathbb{P}][A]\})$  (see (14.2.1(p.93))) and
- Lemmas 13.3.1(p.72) and 13.3.3(p.73) are changed into Lemmas 15.4.1(p.102) and 15.4.3(p.104) respectively.

Therefore the above flow of attribute vectors can be rewritten as follows.

Accordingly, it follows that the operation which transforms  $\theta(\mathscr{A}\{M:1[\mathbb{P}][A]\})$  into  $\theta(\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\})$  can be eventually reduced to the operation below:

$$\mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}} \stackrel{\text{def}}{=} \mathcal{I}_{\mathbb{P}} \mathcal{C}_{\mathbb{P}} \mathcal{R} = \left\{ \begin{array}{ccccc} \overline{a}^{\star}, \overline{a}, \overline{b}, x_{L}, x_{K}, s_{\mathcal{L}}, \kappa, T, L, K, \mathcal{L}, V_{t} \\ \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \downarrow \\ b^{\star}, b, a, x_{\widetilde{L}}, x_{\widetilde{K}}, s_{\widetilde{\mathcal{L}}}, \tilde{\kappa}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_{t} \end{array} \right\}.^{\dagger}$$

$$(15.5.3)$$

<sup>&</sup>lt;sup>†</sup>Compare the dash box []] with that in (13.5.29(p.77)).

- Thus, one sees that in Scenario[P] it suffices to change  $\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} = \mathcal{I}_{\mathbb{R}} \mathcal{C}_{\mathbb{R}} \mathcal{R}$  (see (13.5.30(p.77))) into  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}} = \mathcal{I}_{\mathbb{P}} \mathcal{C}_{\mathbb{R}} \mathcal{P}$  above.
- Moreover, from (III) and (IV) of Table 7.4.1(p.41) it can be easily seen that

$$SOE\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]\} = \mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}[SOE\{\mathsf{M}:1[\mathbb{P}][\mathbb{A}]\}]. \tag{15.5.4}$$

From all the above discussions it follows that for quite the same reason as that for which Lemma 13.5.1(p.78) was derived we can immediately obtain Lemma 15.5.1(p.106) below.

**Lemma 15.5.1** Let  $A_{Tom}\{M:1[\mathbb{P}][A]\}$  holds on  $\mathscr{C}\langle A_{Tom}\rangle$ . Then  $A_{Tom}\{\tilde{M}:1[\mathbb{P}][A]\}$  holds on  $\mathscr{C}\langle A_{Tom}\rangle$  where

$$A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]\} = \mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}[A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]\}]. \quad \Box$$
 (15.5.5)

Finally, also for almost the same reason as that for which Theorem 13.5.1(p.80) is derived from Lemma 13.5.1(p.78) we have Theorem 15.5.1(p.106) below.

Theorem 15.5.1 (symmetry theorem  $(\mathbb{P} \to \tilde{\mathbb{P}})$ ) Let  $\mathscr{A}\{M:1[\mathbb{P}][A]\}\ holds\ on\ \mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}\ holds\ on\ \mathscr{P} \times \mathscr{F}$  where

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\} = \mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}]. \quad \Box$$
 (15.5.6)

In addition, we have (see (13.5.54(p.80)))

$$\boldsymbol{\theta}(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]\}) \stackrel{\text{def}}{=} \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}[\boldsymbol{\theta}(\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]\})] \tag{15.5.7}$$

$$= (b^{\star}, b, a, x_{\tilde{L}}, s_{\tilde{\mathcal{L}}}, x_{\tilde{K}}, \tilde{\kappa}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_t). \tag{15.5.8}$$

#### 15.5.2 $\tilde{\mathbf{S}}$ cenario [ $\mathbb{P}$ ]

This section provides the inverse of Scenario  $[\mathbb{R}]$ , i.e., the scenario deriving  $\mathscr{A}\{M:1[\mathbb{P}][A]\}$  (selling model with  $\mathbb{P}$ -mechanism) from  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}$  (buying model with  $\mathbb{P}$ -mechanism), denoted by  $\tilde{S}$ cenario  $[\mathbb{P}]$ .

■ Before moving on, here let us carry out a review of  $\tilde{S}$ cenario[ $\mathbb{R}$ ]. For convenience of reference, below let us copy the transformation process (see (13.8.20(p.86))) of the attribute vectors in Scenario[ $\mathbb{R}$ ].

- From the above we see that  $\tilde{S}$ cenario[ $\mathbb{P}$ ] is the same as  $\tilde{S}$ cenario[ $\mathbb{R}$ ] only except that
  - $\circ$  b and  $\mu$  in  $\theta(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\})$  is replaced  $b^{\star}$  and b in  $\theta(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]\})$  and
  - $\circ$  Lemmas 15.4.1(p.102) and 15.4.3(p.104) used there are changed into Lemmas 15.4.2(p.103) and 15.4.4(p.104) respectively.

Therefore the above flow of attribute vectors can be rewritten as follows.

Accordingly it follows that the operation which transforms  $\theta(\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\})$  into  $\theta(\mathscr{A}\{M:1[\mathbb{P}][A]\})$  can be eventually reduced to the operation below:

$$\mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}} \stackrel{\text{def}}{=} \tilde{\mathcal{I}}_{\mathbb{P}} \tilde{\mathcal{C}}_{\mathbb{P}} \mathcal{R} = \left\{ \begin{array}{cccc} b^{\star}, b, & a, x_{\tilde{L}}, \tilde{\kappa}, x_{\tilde{K}}, s_{\tilde{\mathcal{L}}}, T, L, K, \mathcal{L}, V_{t} \\ \downarrow & \downarrow \\ a^{\star}, a, & b, x_{L}, \kappa, x_{K}, s_{\mathcal{L}}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_{t} \end{array} \right\}.$$

$$(15.5.11)$$

- Thus, one sees that in  $\tilde{S}$ cenario[ $\mathbb{P}$ ] it suffices to change  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}} = \mathcal{I}_{\mathbb{P}} \mathcal{C}_{\mathbb{P}} \mathcal{R}$  (see (15.5.3(p.105))) into  $\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} = \mathcal{I}_{\mathbb{R}} \mathcal{C}_{\mathbb{R}} \mathcal{P}$  above.
- Moreover, from (III) and (IV) of Table 7.4.1(p.41) it can be easily seen that

$$SOE\{M:1[\mathbb{P}][A]\} = S_{\tilde{\mathbb{P}}\to\mathbb{P}}[SOE\{\tilde{M}:1[\mathbb{P}][A]\}]. \tag{15.5.12}$$

From all the above discussions it follows that for quite the same reason as that for which Lemma 13.8.1(p.87) was derived we can immediately obtain Lemma 15.5.2(p.107) below.

**Lemma 15.5.2** Let  $A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}$  holds on  $\mathscr{C}\langle A_{\text{Tom}}\rangle$ . Then  $A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}$  holds on  $\mathscr{C}\langle A_{\text{Tom}}\rangle$  where

$$A_{\text{Tom}}\{\mathsf{M}:1[\mathbb{P}][\mathbb{A}]\} = \mathcal{S}_{\tilde{\mathbb{P}}\to\mathbb{P}}[A_{\text{Tom}}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]\}]. \quad \Box$$
 (15.5.13)

Finally, for the same reason as the one for which Theorem 13.8.1(p.87) is derived from Lemma 13.8.1(p.87) we have Theorem 15.5.2(p.107) below.

Theorem 15.5.2 (symmetry theorem  $(\tilde{\mathbb{P}} \to \mathbb{P})$ ) Let  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$ . Then  $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$ 

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\} = \mathcal{S}_{\tilde{\mathbb{P}}\to\mathbb{P}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}]. \quad \Box$$
 (15.5.14)

From (13.8.32(p.87)) we have

$$\boldsymbol{\theta}(\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}) \stackrel{\text{def}}{=} \mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}}[\boldsymbol{\theta}(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\})] \tag{15.5.15}$$

**15.6** Derivation of 
$$\mathscr{A}\{\tilde{T}_{\mathbb{P}}, \tilde{L}_{\mathbb{P}}, \tilde{K}_{\mathbb{P}}, \tilde{\mathcal{L}}_{\mathbb{P}}^{=}, (\kappa_{\mathbb{P}}^{*})^{a,b, x_{L}, s_{\mathcal{L}}, x_{K}, \kappa, T, L, K, \mathcal{L}, V_{t}).}$$
 (15.5.16)

For the same reason as in Section 28.2.1(p.285) we see that applying  $\mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}$  to  $\mathscr{A}\{T_{\mathbb{P}},L_{\mathbb{P}},K_{\mathbb{P}},\mathcal{L}_{\mathbb{P}},\kappa_{\mathbb{P}}\}$  given by Lemmas 14.2.1(p.93) — 14.2.6(p.97) yields  $\mathscr{A}\{\tilde{T}_{\mathbb{P}}, \tilde{L}_{\mathbb{P}}, \tilde{K}_{\mathbb{P}}, \tilde{\mathcal{L}}_{\mathbb{P}}, \tilde{\kappa}_{\mathbb{P}}\}.$ 

**Lemma 15.6.1**  $(\mathscr{A}\{\tilde{T}_{\mathbb{P}}\})$  For any  $F \in \mathscr{F}$  we have:

- (a)  $\tilde{T}(x)$  is continuous on  $(-\infty, \infty)$ .
- $\tilde{T}(x)$  is nonincreasing on  $(-\infty, \infty)$ .
- $\tilde{T}(x)$  is strictly decreasing on  $[a, -\infty)$ . (c)
- $\tilde{T}(x) + x$  is nondecreasing on  $(-\infty, \infty)$ . (d)
- (e)  $\tilde{T}(x) + x$  is strictly increasing on  $(-\infty, b^*]$ .
- $\tilde{T}(x) = b x$  on  $[b^*, \infty)$  and  $\tilde{T}(x) < b x$  on  $(-\infty, b^*)$ . (f)
- $\tilde{T}(x) < 0$  on  $(a, \infty)$  and T(x) = 0 on  $(-\infty, a]$ . (g)
- (h)  $\tilde{T}(x) \le \min\{0, b - x\} \ on \ (-\infty, \infty).$
- (i)  $\tilde{T}(0) = b \text{ if } b^* \leq 0 \text{ and } \tilde{T}(0) = 0 \text{ if } a > 0.$
- (j)  $\beta \tilde{T}(x) + x$  is nondecreasing on  $(-\infty, \infty)$  if  $\beta = 1$ .
- $\beta \tilde{T}(x) + x$  is strictly increasing on  $(-\infty, \infty)$  if  $\beta < 1$ . (k)
- If x > y and  $b^* > y$ , then  $\tilde{T}(x) + x > \tilde{T}(y) + y$ . (1)
- $\lambda \beta \tilde{T}(\lambda \beta b + s) + s$  is nondecreasing in s and is strictly increasing in s if  $\lambda \beta < 1$ . (m)
- (n)  $b^{\star} > b$ .
- Proof by analogy Immediate from applying  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Lemma 14.2.1(p.93).
- Direct proof See Lemma A 3.7(p.309) .

Applying  $S_{\mathbb{P}\to\tilde{\mathbb{P}}}$  to (14.2.8(p.95))-(14.2.13(p.95)), we obtain the relations below:

$$\tilde{L}(x) \begin{cases} = \lambda \beta b + s - \lambda \beta x \text{ on } [b^{\star}, -\infty) & \cdots (1), \\ < \lambda \beta b + s - \lambda \beta x \text{ on } (-\infty, b^{\star}) & \cdots (2), \end{cases}$$
(15.6.1)

$$\tilde{K}(x) \begin{cases}
 = \lambda \beta b + s - \delta x & \text{on} \quad [b^*, \infty) & \cdots (1), \\
 < \lambda \beta b + s - \delta x & \text{on} \quad (-\infty, b^*) & \cdots (2).
\end{cases}$$
(15.6.2)

$$\tilde{K}(x) \begin{cases}
< -(1-\beta)x + s \text{ on } (a, \infty) & \cdots (1), \\
= -(1-\beta)x + s \text{ on } (-\infty, a] & \cdots (2), \\
\tilde{K}(x) + x \le \beta x + s & \text{on } (-\infty, \infty).
\end{cases}$$
(15.6.3)

$$\tilde{K}(x) + x \le \beta x + s \quad \text{on} \quad (-\infty, \infty).$$
 (15.6.4)

$$\tilde{K}(x) + x = \begin{cases}
\lambda \beta b + s + (1 - \lambda) \beta x \text{ on } [b^*, \infty) & \cdots (1), \\
\beta x + s & \text{on } (-\infty, a] & \cdots (2).
\end{cases}$$
(15.6.5)

$$\tilde{K}(x_{\tilde{L}}) = -(1 - \beta) x_{\tilde{L}} \cdots (1), \quad \tilde{L}(x_{\tilde{K}}) = (1 - \beta) x_{\tilde{K}} \cdots (2).$$
 (15.6.6)

- Proof by analogy Immediate from applying  $S_{\mathbb{P}\to\tilde{\mathbb{P}}}$  to (14.2.8(p.95))-(14.2.13(p.95)).
- Direct proof See (A 3.1(p.309))-(A 3.6(p.310)). ■

#### Lemma 15.6.2 $(\mathscr{A}\{\tilde{L}_{\mathbb{P}}\})$

- (a)  $\tilde{L}(x)$  is continuous on  $(-\infty, \infty)$ .
- (b)  $\tilde{L}(x)$  is nonincreasing on  $(-\infty, \infty)$ .
- (c)  $\tilde{L}(x)$  is strictly decreasing on  $[a, \infty)$ .
- (d) Let s = 0. Then  $x_{\tilde{L}} = a$  where  $x_{\tilde{L}} < (\geq) x \Leftrightarrow \tilde{L}(x) < (=) 0 \Rightarrow \tilde{L}(x) < (\geq) 0$ .
- (e) Let s > 0.
  - 1.  $x_{\tilde{L}}$  uniquely exists with  $x_{\tilde{L}} > a$  where  $x_{\tilde{L}} < (=(>))$   $x \Leftrightarrow \tilde{L}(x) < (=(>))$  0.
  - 2.  $(\lambda \beta b + s)/\lambda \beta \ge (<) b^* \Leftrightarrow x_{\tilde{L}} = (<) (\lambda \beta b + s)/\lambda \beta < (\ge) b^*$ .  $\square$
- Proof by analogy Immediate from applying  $S_{\mathbb{P}\to\tilde{\mathbb{P}}}$  to Lemma 14.2.2(p.96).
- ullet Direct proof See Lemma A 3.8(p.310) .  $\blacksquare$

#### Corollary 15.6.1 $(\mathscr{A}\{\tilde{L}_{\mathbb{P}}\})$

- (a)  $x_{\tilde{L}} < (\geq) x \Leftrightarrow \tilde{L}(x) < (\geq) 0.$
- (b)  $x_{\tilde{L}} \leq (\geq) x \Rightarrow \tilde{L}(x) \leq (\geq) 0.$
- Proof by analogy Immediate from applying  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Corollary 14.2.1(p.96).
- Direct proof See Corollary A 3.2(p.310) . ■

#### Lemma 15.6.3 $(\mathscr{A}\{\tilde{K}_{\mathbb{P}}\})$

- (a)  $\tilde{K}(x)$  is continuous on  $(-\infty, \infty)$ .
- (b)  $\tilde{K}(x)$  is nonincreasing on  $(-\infty, \infty)$ .
- (c)  $\tilde{K}(x)$  is strictly decreasing on  $[a, \infty)$ .
- (d)  $\tilde{K}(x)$  is strictly decreasing on  $(-\infty, \infty)$  if  $\beta < 1$ .
- (e)  $\tilde{K}(x) + x$  is nondecreasing on  $(-\infty, \infty)$ .
- (f)  $\tilde{K}(x) + x$  is strictly increasing on  $(-\infty, b^*]$ .
- (g)  $\tilde{K}(x) + x$  is strictly increasing on  $(-\infty, \infty)$  if  $\lambda < 1$ .
- (h) If x > y and  $b^* > y$ , then  $\tilde{K}(x) + x > \tilde{K}(y) + y$ .
- (i) Let  $\beta = 1$  and s = 0. Then  $x_{\tilde{K}} = a$  where  $x_{\tilde{K}} < (\geq) x \Leftrightarrow \tilde{K}(x) < (=) 0 \Rightarrow \tilde{K}(x) < (\geq) 0$ .
- (j) Let  $\beta < 1$  or s > 0.
  - 1. There uniquely exists  $x_{\tilde{K}}$  where  $x_{\tilde{K}} < (=(>)) x \Leftrightarrow \tilde{K}(x) < (=>)) 0$ .
  - 2.  $(\lambda \beta b + s)/\delta \ge (<) b^* \Leftrightarrow x_{\tilde{K}} = (<) (\lambda \beta b + s)/\delta$ .
  - 3. Let  $\tilde{\kappa} < (=(>)) \ 0$ . Then  $x_{\tilde{K}} < (=(>)) \ 0$ .
- Proof by analogy Immediate from applying  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Lemma 14.2.3(p.96).
- Direct proof See Lemma A 3.9(p.310) .

#### Corollary 15.6.2 $(\mathscr{A}\{\tilde{K}_{\mathbb{P}}\})$

- (a)  $x_{\tilde{K}} < (\geq) x \Leftrightarrow \tilde{K}(x) < (\geq) 0.$
- (b)  $x_{\tilde{K}} \leq (\geq) x \Rightarrow \tilde{K}(x) \leq (\geq) 0.$
- Proof by analogy Immediate from applying  $S_{\mathbb{P}\to\tilde{\mathbb{P}}}$  to Corollary 14.2.2(p.%).
- Direct proof See Corollary A 3.3(p.311) .

#### Lemma 15.6.4 $(\mathscr{A}\{\tilde{L}_{\mathbb{P}}/\tilde{K}_{\mathbb{P}}\})$

- (a) Let  $\beta = 1$  and s = 0. Then  $x_{\tilde{L}} = x_{\tilde{K}} = a$ .
- (b) Let  $\beta = 1$  and s > 0. Then  $x_{\tilde{L}} = x_{\tilde{K}}$ .
- (c) Let  $\beta < 1$  and s = 0. Then  $a < (=(>)) 0 \Leftrightarrow x_{\tilde{L}} < (=(>)) x_{\tilde{K}} \Rightarrow x_{\tilde{K}} < (=(=)) 0$ .
- (d) Let  $\beta < 1$  and s > 0. Then  $\tilde{\kappa} < (=(>))$   $0 \Leftrightarrow x_{\tilde{L}} < (=(>))$   $x_{\tilde{\kappa}} \Rightarrow x_{\tilde{\kappa}} < (=(>))$  0.  $\square$
- Proof by analogy Immediate from applying  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Lemma 14.2.4(p.97).
- Direct proof See Lemma A 3.10(p.311) . ■

#### Lemma 15.6.5 $(\mathscr{A}\{\tilde{\mathcal{L}}_{\mathbb{P}}\})$

- (a)  $\tilde{\mathcal{L}}(s)$  is nondecreasing in s and strictly increasing in s if  $\lambda \beta < 1$ .
- (b) Let  $\lambda \beta b \leq a$ .
  - 1.  $x_{\tilde{L}} \geq \lambda \beta b + s$ .
  - 2. Let s > 0 and  $\lambda \beta < 1$ . Then  $x_{\tilde{L}} > \lambda \beta b + s$ .
- (c) Let  $\lambda \beta b > a$ . Then there exists a  $s_{\tilde{L}} > 0$  such that if  $s_{\tilde{L}} > (\leq) s$ , then  $x_{\tilde{L}} < (\geq) \lambda \beta b + s$ .
- Proof by analogy Immediate from applying  $S_{\mathbb{P}\to\tilde{\mathbb{P}}}$  to Lemma 14.2.5(p.97).
- ullet Direct proof See Lemma A 3.11(p.311) .  $\blacksquare$

#### **Lemma 15.6.6** $(\tilde{\kappa}_{\mathbb{P}})$ We have:

- (a)  $\tilde{\kappa} = \lambda \beta b + s \text{ if } b^* < 0 \text{ and } \tilde{\kappa} = s \text{ if } a > 0.$
- (b) Let  $\beta < 1$  or s > 0. Then  $\tilde{\kappa} < (=(>))$  0. Then  $x_{\tilde{\kappa}} < (=(>))$  0.  $\square$
- Proof by analogy Immediate from applying  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Lemma 14.2.6(p.97).
- Direct proof See Lemma A 3.12(p.312) . ■

## 15.7 Derivation of $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}$

```
\square Tom 15.7.1 (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]\}) Let \beta=1 and s=0.
```

- (a)  $V_t$  is nonincreasing in t > 0.
- (b)  $\boxed{\text{§ dOITs}_{\tau}\langle \tau \rangle}$  where  $\text{CONDUCT}_{\tau \geq t > 1}$ .
- Proof by symmetry Immediate from applying  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Tom 14.4.1(p.98).
- ullet Direct proof See Tom A 4.5 (p.317) .  $\blacksquare$
- $\square$  Tom 15.7.2 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]\}$ ) Let  $\beta<0$  or s>0. Then, for a given starting time  $\tau>1$ :
- (a)  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $\beta b \leq a$ . Then  $\bullet dOITd_{\tau}\langle 1 \rangle_{\parallel}$ .
- (c) Let  $\beta b > a$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $b+s \geq b^*$ . Then  $\bullet dOITd_{\tau}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $b+s < b^{\star}$ . Then  $\boxed{\$ \text{ dOITs}_{\tau}\langle \tau \rangle}_{\blacktriangle}$  where  $\text{CONDUCT}_{\tau \geq t > 1}_{\blacktriangle}$ .
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let a < 0 ( $\tilde{\kappa} < 0$ ). Then subseteq subseteq subseteq where subseteq where subseteq subseteq
    - ii. Let a=0 ( $\tilde{\kappa}=0$ ).
      - 1. Let  $\beta b + s \geq b^*$ . Then  $\bullet dOITd_{\tau}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta b + s < b^{\star}$ . Then  $\boxed{\$ dOITs_{\tau} \langle \tau \rangle}_{\blacktriangle}$  where  $CONDUCT_{\tau \geq t > 1}_{\blacktriangle}$ .
    - iii. Let a > 0 ( $\tilde{\kappa} > 0$ ).
      - 1. Let  $\beta b + s \geq b^*$  or  $s_{\tilde{\mathcal{L}}} \leq s$ . Then  $\bullet dOITd_{\tau}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta b + s < b^*$  and  $s_{\tilde{\mathcal{L}}} > s$ . Then  $S_1(p.61)$  s = 0 is true.
- Proof by symmetry Immediate from applying  $S_{\mathbb{P}\to\tilde{\mathbb{P}}}$  to Tom 14.4.2(p.98).
- Direct proof See Tom  $A 4.6 ext{(p.317)}$  .

### 15.8 Optimal Price to Propose

**Lemma 15.8.1** ( $\mathscr{A}_{Tom}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]\}$ ) The optimal price to propose  $z_t$  is nonincreasing in t>0.  $\square$ 

• *Proof* Obvious from Tom's 15.7.1(p.109) (a) and 15.7.2(p.109) (a) and from (7.2.50(p.32)) and Lemma A 3.3(p.306). ■

#### 15.9 Symmetry-Operation-Free

When no change occurs even if the symmetry operation is applied to a given assertion A, the assertion is said to be *free from* the symmetry operation, called the *symmetry-operation-free assertion*.

**Lemma 15.9.1** Even if the symmetry operation is applied to the symmetry-operation-free assertion, no change occurs. □

• Proof Evident.

## Analogy Theorem $(\tilde{\mathbb{R}} \leftrightarrow \tilde{\mathbb{P}})$

In this chapter we clarify the interrelationship between  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}$  (buying model with  $\mathbb{P}$ -mechanism) and  $\mathscr{A}\{M:1[\mathbb{P}][A]\}$  (selling model with  $\mathbb{P}$ -mechanism).

## 16.1 Relationship between $\tilde{M}:1[\mathbb{P}][A]$ and $\tilde{M}:1[\mathbb{R}][A]$

#### 16.1.1 Assertion System $\mathscr{A}$

First, note the three relations below:

$$\circ \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}] \ (\leftarrow (13.5.53(p.80))), \tag{16.1.1}$$

$$\bullet \, \mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\} = \mathcal{A}_{\mathbb{R} \to \mathbb{P}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}] \ (\leftarrow (14.3.1(p.97))), \tag{16.1.2}$$

$$\bullet \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\} = \mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}] \quad (\leftarrow (15.5.6(p.106))). \tag{16.1.3}$$

Next, the inverses of the above relations were:

$$\bullet \, \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\} = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}] \ (\leftarrow (13.8.31(p.87))), \tag{16.1.4}$$

$$\circ \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\} = \mathcal{A}_{\mathbb{P}\to\mathbb{R}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]\}] \quad (\leftarrow (14.3.6(p.98))), \tag{16.1.5}$$

$$\circ \mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\} = \mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}] \quad (\leftarrow (15.5.14(p.107))). \tag{16.1.6}$$

Then, from  $\bullet$  (16.1.3(p.111)),  $\bullet$  (16.1.2(p.111)), and  $\bullet$  (16.1.4(p.111)) we obtain the relation below:

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]\} = \mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}\mathcal{A}_{\mathbb{R}\to\mathbb{P}}\mathcal{S}_{\tilde{\mathbb{R}}\to\mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}]. \tag{16.1.7}$$

Finally, from  $\circ$  (16.1.1(p.111)),  $\circ$  (16.1.5(p.111)), and  $\circ$  (16.1.6(p.111)) we obtain the relation below:

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}} \mathcal{A}_{\mathbb{P}\to\mathbb{R}} \mathcal{S}_{\tilde{\mathbb{P}}\to\mathbb{P}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}]. \tag{16.1.8}$$

#### 16.1.2 System of Optimality Equations (SOE)

First, note the three relations below:

$$\circ \, \operatorname{SOE}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\} = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\operatorname{SOE}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}] \,\, (\leftarrow \,(13.5.34(\text{p.77})\,)), \tag{16.1.9}$$

$$\bullet \ \operatorname{SOE}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\} = \mathcal{A}_{\mathbb{R} \to \mathbb{P}}[\operatorname{SOE}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}] \ (\leftarrow (14.3.2(p.98))), \tag{16.1.10}$$

$$\bullet \ \mathsf{SOE}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\} = \mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}[\mathsf{SOE}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}] \ \ (\leftarrow (15.5.4(\text{p.106}))), \tag{16.1.11}$$

Next, the inverses of the above relations were:

• 
$$SOE\{M:1[\mathbb{R}][A]\} = S_{\tilde{\mathbb{R}} \to \mathbb{R}}[SOE\{\tilde{M}:1[\mathbb{R}][A]\}] \ (\leftarrow (13.8.25(p.87))),$$
 (16.1.12)

$$\circ \, \mathsf{SOE}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\} = \mathcal{A}_{\mathbb{P} \to \mathbb{R}}[\mathsf{SOE}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]\}] \,\, (\leftarrow (14.3.7(p.98))), \tag{16.1.13}$$

$$\circ \, \operatorname{SOE}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\} = \mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}}[\operatorname{SOE}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}] \ \, (\leftarrow (15.5.12 \scriptscriptstyle (p.107))), \tag{16.1.14}$$

Then, from  $\bullet$  (16.1.11(p.111)),  $\bullet$  (16.1.10(p.111)), and  $\bullet$  (16.1.12(p.111)) we obtain the relation below:

$$SOE\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\} = \mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}} \mathcal{A}_{\mathbb{R}\to\mathbb{P}} \mathcal{S}_{\tilde{\mathbb{R}}\to\mathbb{R}}[SOE\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}], \tag{16.1.15}$$

Finally, from  $\circ$  (16.1.9(p.111)),  $\circ$  (16.1.13(p.111)), and  $\circ$  (16.1.14(p.111)) we obtain the relation below:

$$SOE\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}\,\mathcal{A}_{\mathbb{P}\to\mathbb{R}}\,\mathcal{S}_{\tilde{\mathbb{P}}\to\mathbb{P}}[SOE\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}]. \tag{16.1.16}$$

#### 16.1.3 Attribute Vector $\theta$

First, note the three relations below:

$$\circ \theta(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}) = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\theta(\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\})] \quad (\leftarrow (13.5.54(p.80))), \tag{16.1.17}$$

$$\bullet \ \theta(\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}) = \mathcal{A}_{\mathbb{R} \to \mathbb{P}}[\theta(\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\})] \quad (\leftarrow (14.3.3(p.98))), \tag{16.1.18}$$

$$\bullet \ \theta(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]\}) = \mathcal{S}_{\mathbb{P}_{\rightarrow}\tilde{\mathbb{P}}}[\theta(\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathbb{A}]\})] \quad (\leftarrow (15.5.7(\mathbb{P}.106))), \tag{16.1.19}$$

Next, then the inverses of the above relations were:

• 
$$\theta(\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}) = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}[\theta(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\})] \quad (\leftarrow (13.8.32(p87))),$$
 (16.1.20)

$$\circ \theta(\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}) = \mathcal{A}_{\mathbb{P}\to\mathbb{R}}[\theta(\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]\})] \quad (\leftarrow (14.3.8[p.98])), \tag{16.1.21}$$

$$\circ \; \boldsymbol{\theta}(\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}) = \mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}}[\boldsymbol{\theta}(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\})] \quad (\leftarrow (15.5.15(p.107))), \tag{16.1.22}$$

Then, from • (16.1.19(p.112)), • (16.1.18(p.112)), and • (16.1.20(p.112)) we obtain the relation below:

$$\theta(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]\}) = \mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}\mathcal{A}_{\mathbb{R}\to\mathbb{P}}\mathcal{S}_{\tilde{\mathbb{R}}\to\mathbb{R}}[\theta(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\})]$$

$$(16.1.23)$$

$$= (b^{\star}, b, a, x_{\tilde{L}}, x_{\tilde{K}}, s_{\tilde{L}}, \tilde{\kappa}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{L}, V_{t}) \quad (\leftarrow (15.5.8 (p.106))). \tag{16.1.24}$$

Finally, from  $\circ$  (16.1.17(p.112)),  $\circ$  (16.1.21(p.112)), and  $\circ$  (16.1.22(p.112)) we obtain the relation below:

$$\theta(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}) = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}} \mathcal{A}_{\mathbb{P}\to\mathbb{R}} \mathcal{S}_{\tilde{\mathbb{P}}\to\mathbb{P}}[\theta(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\})]$$

$$(16.1.25)$$

$$= (b, \mu, a, x_{\tilde{L}}, x_{\tilde{K}}, s_{\tilde{\mathcal{L}}}, \tilde{\kappa}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_t) \quad (\leftarrow (13.5.55 (\text{p.80}))). \tag{16.1.26}$$

## 16.2 Symmetry Theorem $(\tilde{\mathbb{R}} \leftrightarrow \tilde{\mathbb{P}})$

Here let us define

$$\mathcal{A}_{\tilde{\mathbb{P}} \to \tilde{\mathbb{P}}} \stackrel{\text{def}}{=} \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}} \mathcal{A}_{\mathbb{R} \to \mathbb{P}} \mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}}, \tag{16.2.1}$$

$$\mathcal{A}_{\tilde{\mathbb{P}} \to \tilde{\mathbb{R}}} \stackrel{\text{def}}{=} \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} \, \mathcal{A}_{\mathbb{P} \to \mathbb{R}} \, \mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}}. \tag{16.2.2}$$

Then (16.1.7(p.111)) and (16.1.8(p.111)) can be expresses as below.

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]\} = \mathcal{A}_{\tilde{\mathbb{P}}_{\sim}\tilde{\mathbb{P}}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}],\tag{16.2.3}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\} = \mathcal{A}_{\tilde{\mathbb{P}} \to \tilde{\mathbb{R}}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]\}]. \tag{16.2.4}$$

(16.2.3(p.112)) implies that the following theorem holds.

**Theorem 16.2.1 (analogy**  $[\tilde{\mathbb{R}} \to \tilde{\mathbb{P}}]$ ) Let  $\mathscr{A}\{\tilde{M}:1[\mathbb{R}][A]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$ . Then  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}\ where$ 

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]\} \stackrel{\text{def}}{=} \mathcal{A}_{\tilde{\mathbb{R}} \to \tilde{\mathbb{P}}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}]. \quad \Box$$
 (16.2.5)

Similarly (16.2.4(p.112)) implies that the following theorem (inverse of the above theorem) holds.

Theorem 16.2.2 (analogy  $[\tilde{\mathbb{R}} \to \tilde{\mathbb{P}}]$ ) Let  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$ . Then  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}\ where$ 

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\} \stackrel{\text{def}}{=} \mathcal{A}_{\tilde{\mathbb{P}} \to \tilde{\mathbb{R}}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]\}]. \quad \Box$$
 (16.2.6)

Then (16.1.15(p.111)) and (16.1.16(p.111)) can be expresses as below.

$$SOE\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\} = \mathcal{A}_{\tilde{\mathbb{R}} \to \tilde{\mathbb{P}}}[SOE\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}], \tag{16.2.7}$$

$$\mathtt{SOE}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\} = \mathcal{A}_{\tilde{\mathbb{P}} \to \tilde{\mathbb{R}}}[\mathtt{SOE}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}]. \tag{16.2.8}$$

Similarly (16.1.23(p.112)) and (16.1.25(p.112)) can be expresses as below.

$$\boldsymbol{\theta}(\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]) = \mathcal{A}_{\tilde{\mathbb{R}} \to \tilde{\mathbb{P}}}[\boldsymbol{\theta}(\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}])],\tag{16.2.9}$$

$$\boldsymbol{\theta}(\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]) = \mathcal{A}_{\tilde{\mathbb{P}} \to \tilde{\mathbb{R}}}[\boldsymbol{\theta}(\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}])]. \tag{16.2.10}$$

## 16.3 The Structure of $\mathcal{A}_{\tilde{\mathbb{P}} \to \tilde{\mathbb{R}}}$

The operation  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}=\mathcal{S}_{\mathbb{P}\to\mathbb{P}}\mathcal{A}_{\mathbb{R}\to\mathbb{P}}\mathcal{S}_{\mathbb{R}\to\mathbb{R}}$  given by (16.2.1(p.112)) means that the three operations are applied in the order of  $\mathcal{S}_{\mathbb{R}\to\mathbb{R}}\to\mathcal{A}_{\mathbb{R}\to\mathbb{P}}\to\mathcal{S}_{\mathbb{P}\to\mathbb{P}}$ . Then, putting this flow in vertically, we have

The above flow can be interpreted as follows:

- First, let us focus attention on elements *outside* the dashbox . Then, we see that first (1)-row changes into (2)-row, next (2)-row is identical to (5)-row, and finally (5)-row changes into (6)-row, which is identical to the original (1)-row. In other words, (1)-row remains unchanged *outside* the dash-box even if these operations are applied.
- $\circ$  Next, let us focus attention on elements *inside* the dashbox  $\square$ . Then, we see that first (1)-row changes into (2)-row, next (2)-row identical to (3)-row, which changes into (4)-row, then (4)-row is identical to (5)-row, and finally (5)-row changes into (6)-row. In other words, b and  $\mu$  in (1)-row change into respectively  $b^*$  and b in (6)-row through the applications of these operations.

From the above we see that the above triple operations can be eventually reduced to the single operation

$$\mathcal{A}_{\tilde{\mathbb{R}} \to \tilde{\mathbb{P}}} \stackrel{\text{def}}{=} \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}} \mathcal{A}_{\mathbb{R} \to \mathbb{P}} \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}} = \left\{ \begin{array}{c|cccc} b, \ \mu, \ a, \ x_{\tilde{L}}, x_{\tilde{K}}, s_{\tilde{\mathcal{L}}}, \tilde{\kappa}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_t \\ \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \downarrow \\ b^*, b, a, x_{\tilde{L}}, x_{\tilde{K}}, s_{\tilde{\mathcal{L}}}, \tilde{\kappa}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_t \end{array} \right\}$$

$$(16.3.1)$$

Removing the unchanged elements from the above  $\mathcal{A}_{\tilde{\mathbb{R}} \to \tilde{\mathbb{P}}}$ , eventually we obtain

$$\mathcal{A}_{\tilde{\mathbb{R}} \to \tilde{\mathbb{P}}} = \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}} \mathcal{A}_{\mathbb{R} \to \mathbb{P}} \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}} = \{ b \to b^*, \ \mu \to b \}. \tag{16.3.2}$$

Similarly, the operation  $\mathcal{A}_{\tilde{\mathbb{P}} \to \tilde{\mathbb{R}}} = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} \mathcal{A}_{\mathbb{P} \to \mathbb{R}} \mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}}$  given by (16.2.2(p.112)) means that the three operations are applied in the order of  $\mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}} \to \mathcal{A}_{\mathbb{P} \to \mathbb{R}} \to \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}$ . Then, putting this flow in vertically, we have

The above flow can be eventually reduced to as follows.

$$\mathcal{A}_{\tilde{\mathbb{P}} \to \tilde{\mathbb{R}}} = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} \, \mathcal{A}_{\mathbb{P} \to \mathbb{R}} \, \mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}} = \{ b^{\star} \to b, \ b \to \mu \}. \tag{16.3.3}$$

## Integrated-Theory

### 17.1 Integrated-Theory

- Let us here again recall Motive 2(p.3) "Does a general theory integrating quadruple-asset-trading-problems exist?", and this motivation was put an end with a successful construction. The complete picture of the integrated-theory can be summarized as follows:
- $\langle 1 \rangle$   $\mathscr{A} \{ T_{\mathbb{R}} \}$  is *proven* (see Lemma 11.1.1(p.55) ).
- $\langle 2 \rangle$   $\mathscr{A}\{L_{\mathbb{R}}, K_{\mathbb{R}}, \mathcal{L}_{\mathbb{R}}, \kappa_{\mathbb{R}}\}$  is *proven* (see Lemmas 11.2.1(p.57) -11.3.1(p.59)).
- $\langle 3 \rangle$   $\mathscr{A}\{M:1[\mathbb{R}][A]\}\ is\ proven\ (see\ Tom's\ 12.2.1(p.61)\ and\ 12.2.2(p.62)).$
- $\langle 4 \rangle$   $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]\}\$ is *derived* (see Tom's 13.7.1(p.83) and 13.7.2(p.84)).
- $\langle 5 \rangle$   $\mathscr{A} \{ T_{\mathbb{P}} \}$  is *proven* (see Lemma 14.2.1(p.93)).
- $\langle 6 \rangle$   $\mathscr{A}\{M:1[\mathbb{P}][A]\}$  is *derived* (see Tom's 14.4.1(p.98) and 14.4.2(p.98)).
- $\langle 7 \rangle$   $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}$  is derived (see Tom's 15.7.1(p.109) and 15.7.2(p.109)).
- (8) The analogous relation between  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}$  and  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}$  is shown (see Theorems 16.2.1(p.112) and 16.2.2(p.112)).
- The above flow,  $\langle 1 \rangle \langle 8 \rangle$ , can be schematized as in Figure 17.1.1(p.115) below where the three shadow-boxes are directly proven and the remaining four frame-boxes are all indirectly derived by applying  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$ ,  $A_{\mathbb{R} \to \mathbb{P}}$ , and  $S_{\mathbb{R} \to \tilde{\mathbb{R}}}$ .

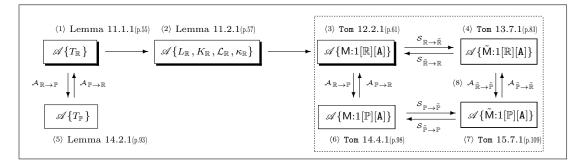


Figure 17.1.1: The whole flow of constructing the integrated-theory

■ The interrelationship among the quadruple assertion systems within the dashbox  $\square$  of Figure 17.1.1(p.115) implies the following. First, an assertion system of M:1[ $\mathbb{R}$ ][A] is defined as a core within the quadruple-asset-trading-models  $\mathcal{Q}(M:1[A])$  and then proven (see Chap. 12(p.61)). Next, the assertion system for each of the remaining three models is derived by sequentially applying the operations  $\mathcal{S}_{\mathbb{R}\to\mathbb{R}}$  and  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  to the core assertion system (see Chaps. 13(p.69) and 14(p.89)). Finally,  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}$  is derived so as to become symmetrical to  $\mathscr{A}\{M:1[\mathbb{P}][A]\}$  by using  $\mathcal{S}_{\mathbb{P}\to\mathbb{P}}$  and  $\mathcal{A}_{\mathbb{P}\to\mathbb{R}}$  (see Chap. 15(p.101) and Chap. 16(p.111)). Since it is proven that any of these operations are reversible, even if any other assertion system within  $\mathcal{Q}(M:1[A])$  is selected as a seed, the same flow as the above can be depicted. Let us refer to the methodology which integrates the quadruple assertion systems in such a fashion as stated above as the integrated-theory. In the conventional methodology, each of the quadruple assertion systems must be separately defined and one by one proven. On the other hand, in our methodology based on the integrated-theory, the number of assertion systems which are defined and proven is only one as a core. In Part 3 that follows we try to apply the integrated-theory to all of the remaining five quadruple-asset-trading-models in Table 3.2.1(p.16) except for  $\mathcal{Q}(M:1[A])$  the analysis of which was already ended. After having finished reading Part 3, readers will realize that the integrated-theory provides a strong tool for the treatment of asset trading problems.

### Market Restriction

### 18.1 Preliminary

As seen from the whole discussions over Chaps. 11(p.55) to 16(p.111), the integrated-theory is constructed under the premise that prices  $\xi$ , whether reservation price or posted price, is defined on the total-DF-space (see (2.2.5(p.13))), i.e.,

$$\mathscr{F} = \{ F \mid -\infty < a < \mu < b < \infty \}. \tag{18.1.1}$$

However, since the prices  $\xi$  in a usual market of the real world are positive, i.e.,  $\xi \in (0, \infty)$ , the above premise, permitting a negative price  $\xi \in (-\infty, 0)$ , must be said to be unrealistic. This chapter provides a methodology working through this problem.

#### 18.2 Market Restriction

Throughout the remaining of this paper, we call the total-DF-space  $\mathscr{F}$  the total market. Now let us refer to the restriction of the total market  $\mathscr{F}$  to a given subset

$$\mathscr{F}' \subseteq \mathscr{F} \tag{18.2.1}$$

as the market restriction of  $\mathscr{F}$  to  $\mathscr{F}'$  and to the  $\mathscr{F}'$  as the restricted market. Throughout this paper let us consider the following three kinds of restricted markets:

$$\mathscr{F}^{+} \stackrel{\text{def}}{=} \{F \mid 0 < a < b\} \quad (positive \ market), \tag{18.2.2}$$

$$\mathscr{F}^{\pm} \stackrel{\text{def}}{=} \{ F \mid a \le 0 \le b \} \quad (mixed \ market), \tag{18.2.3}$$

$$\mathscr{F}^{-} \stackrel{\text{def}}{=} \{ F \mid a < b < 0 \} \quad (negative \ market)$$
 (18.2.4)

where clearly

$$\mathscr{F} = \mathscr{F}^+ \cup \mathscr{F}^\pm \cup \mathscr{F}^-. \tag{18.2.5}$$

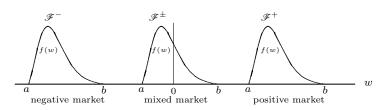


Figure 18.2.1: Three kinds of markets

**Definition 18.2.1** In the present paper, let us represent the restriction of  $\mathscr{F}$  to the above three restricted markets by the same symbols  $\mathscr{F}^+$ ,  $\mathscr{F}^\pm$ , and  $\mathscr{F}^-$  above, called the *positive market restriction*  $\mathscr{F}^+$ , the *mixed market restriction*  $\mathscr{F}^\pm$ , and the *negative market restriction*  $\mathscr{F}^-$  respectively. See Section A 7.5(p.326) for an interesting economic implication brought about by the three market restrictions.  $\square$ 

#### 18.3 Market Restricted Models

Throughout the rest of this paper, let us denote the models defined on the restricted markets  $\mathscr{F}^+$ ,  $\mathscr{F}^\pm$ , and  $\mathscr{F}^-$  by  $\mathsf{Model}^+$ ,  $\mathsf{Model}^\pm$ , and  $\mathsf{Model}^-$  respectively, called the *market restricted models*. For x=1,2,3 and X=A, E let us define:

$$Q(\mathsf{M}:x[\mathsf{X}]^+) \stackrel{\text{def}}{=} \{\mathsf{M}:x[\mathbb{R}][\mathsf{X}]^+, \tilde{\mathsf{M}}:x[\mathbb{R}][\mathsf{X}]^+, \mathsf{M}:x[\mathbb{P}][\mathsf{X}]^+, \tilde{\mathsf{M}}:x[\mathbb{P}][\mathsf{X}]^+\}, \tag{18.3.1}$$

$$Q(\mathsf{M}:x[\mathsf{X}]^{\pm}) \stackrel{\text{def}}{=} \{\mathsf{M}:x[\mathbb{R}][\mathsf{X}]^{\pm}, \tilde{\mathsf{M}}:x[\mathbb{R}][\mathsf{X}]^{\pm}, \mathsf{M}:x[\mathbb{P}][\mathsf{X}]^{\pm}, \tilde{\mathsf{M}}:x[\mathbb{P}][\mathsf{X}]^{\pm}\}, \tag{18.3.2}$$

$$Q(\mathsf{M}:x[\mathsf{X}]^{-}) \stackrel{\mathsf{def}}{=} \{\mathsf{M}:x[\mathbb{R}][\mathsf{X}]^{-}, \tilde{\mathsf{M}}:x[\mathbb{R}][\mathsf{X}]^{-}, \mathsf{M}:x[\mathbb{P}][\mathsf{X}]^{-}, \tilde{\mathsf{M}}:x[\mathbb{P}][\mathsf{X}]^{-}\}. \tag{18.3.3}$$

#### 18.4 Inequalities Resulting From Market Restriction

The lemma below will be used to examine what occurs when the operation of market restriction is applied to results derived by using the integrated-theory constructed on the total market  $\mathscr{F}$ .

Lemma 18.4.1 (positive market  $\mathscr{F}^+$ ) Suppose 0 < a. Then we have:

```
[1] 0 < a < \mu < b. Proof: Evident from (2.2.2(p.12)).
```

[2]  $\beta b \leq b$  for  $0 < \beta \leq 1$ . Proof: Immediate from  $0 < \beta b \leq b$  with  $\beta = 1$ .

[3]  $\beta \mu < b \text{ for } 0 < \beta \leq 1$ . Proof: Immediate from  $0 < \beta \mu < b \text{ with } \beta = 1$ .

[4]  $\beta a < b$  for  $0 < \beta \le 1$ . Proof: Immediate from  $0 < \beta a < b$  with  $\beta = 1$ .

[5]  $a < \beta \mu$  and  $\beta \mu \le a$  are both possible. Proof: Since  $0 < a < \beta \mu$  with  $\beta = 1$ , the former is possible for a  $\beta$  sufficiently close to  $\beta = 1$  and the latter is possible for any sufficiently small  $\beta > 0$ .

[6]  $a < \beta b$  and  $\beta b \le a$  are both possible. Proof: Since  $0 < a < \beta b$  with  $\beta = 1$ , the former is possible for a  $\beta$  sufficiently close to  $\beta = 1$  and the latter is possible for any sufficiently small  $\beta > 0$ .

[7]  $\beta b < b^{\star}$  for  $0 < \beta \le 1$ . Proof: Immediate from  $0 < \beta b < b^{\star}$  with  $\beta = 1$  due to Lemma 15.6.1(p.107) (n).

#### Lemma 18.4.2 (mixed market $\mathscr{F}^{\pm}$ ) Suppose $a \leq 0 \leq b$ . Then we have:

[8]  $a < \beta \mu < b$  for  $0 < \beta \le 1$ . Proof: Let  $\mu = 0$ . Then  $a < \mu = \beta \mu = 0 < b$  for  $0 < \beta \le 1$ . Let  $\mu \ne 0$ . If  $a < \mu < 0$ , then  $a < \beta \mu < 0 \le b$  with  $\beta = 1$ , hence  $a < \beta \mu < 0 \le b$  for  $0 < \beta \le 1$  and if  $0 < \mu < b$ , then  $a \le 0 < \beta \mu < b$  with  $\beta = 1$ , hence  $a \le 0 < \beta \mu < b$  for  $0 < \beta \le 1$ . Accordingly, whether  $a < \mu < 0$  or  $0 < \mu < b$ , we have  $a < \beta \mu < b$  for  $0 < \beta \le 1$ . Thus, whether  $\mu = 0$  or  $\mu \ne 0$ , it follows that  $a < \beta \mu < b$  for  $0 < \beta \le 1$ .

[9]  $\beta a < b$  for  $0 < \beta \le 1$ . Proof: Let  $\beta = 1$ . Then  $\beta a = a < b$ . Let  $\beta < 1$ . If a = 0, then  $\beta a = a = 0 < b$  and if a < 0, then  $\beta a < 0 \le b$ , hence  $\beta a < b$  whether a = 0 or a < 0. Thus, whether  $\beta = 1$  or  $\beta < 1$  (i.e.,  $0 < \beta \le 1$ ) it follows that we have  $\beta a < b$ .

 $\begin{bmatrix} 10 \\ \text{[ref.6892]} \end{bmatrix} a < \beta b \text{ for } 0 < \beta \leq 1.$  Proof: If b > 0, then  $a \leq 0 < b = \beta b$  with  $\beta = 1$ , hence  $a \leq 0 < \beta b$  for  $0 < \beta \leq 1$ . If b = 0, then  $a < b = \beta b = 0$  for  $0 < \beta \leq 1$ . Therefore, whether b > 0 or b = 0, we have  $a < \beta b$  for  $0 < \beta \leq 1$ .

 $[11] a^{\star} < \beta a \text{ for } 0 < \beta \leq 1.$  Proof: Immediate from  $a^{\star} < \beta a \leq 0 \text{ with } \beta = 1 \text{ due to Lemma 14.2.1(p.93) (n)}.$ 

 $[12] \beta b < b^{\star} \ for \ 0 < \beta \leq 1. \quad \text{Proof: Immediate from } 0 \leq \beta b < b^{\star} \ \text{with } \beta = 1 \ \text{due to Lemma } 15.6.1 \text{(p.107) (n)}. \quad \square$ 

#### Lemma 18.4.3 (negative market $\mathscr{F}^-$ ) Suppose b < 0. Then we have:

 $[13]_{\text{prof }7/86]}a < \mu < b < 0.$  Proof: Evident from (2.2.2(p.12)).

 $[14] a \le \beta a \text{ for } 0 < \beta \le 1.$  Proof: Immediate from  $a \le \beta a < 0$  with  $\beta = 1$ .

 $\begin{bmatrix} 15 \\ ref.8068 \end{bmatrix}$   $a < \beta \mu \text{ for } 0 < \beta \leq 1$ . Proof: Immediate from  $a < \beta \mu < 0$  with  $\beta = 1$ .

 $[16]_{\text{thef }7482]} a < \beta b \text{ for } 0 < \beta \leq 1. \quad \text{Proof: Immediate from } a < \beta b < 0 \text{ with } \beta = 1.$ 

[17]  $\beta\mu < b$  and  $b \le \beta\mu$  are both possible. Proof: Since  $\beta\mu < b < 0$  with  $\beta = 1$ , the former is true for a  $\beta$  sufficiently close to  $\beta = 1$  and the latter is true for a sufficiently small  $\beta > 0$ .

[18]  $\beta a < b$  and  $b \le \beta a$  are both possible. Proof: Since  $\beta a < b < 0$  with  $\beta = 1$ , the former is possible for a  $\beta$  sufficiently close to  $\beta = 1$  and the latter is possible for a sufficiently small  $\beta > 0$ .

 $[19] a^{\star} < \beta a \text{ for } 0 < \beta \leq 1. \quad \text{Proof: Immediate from } a^{\star} < \beta a < 0 \text{ with } \beta = 1 \text{ due to Lemma } 14.2.1 \text{(p.93) (n)}. \quad \square$ 

**Definition 18.4.1 (market-restriction-free-assertion)** When no change occurs even if a market restriction is applied to a given assertion, the assertion is said to be *free from* the market restriction, called the *market-restriction-free assertion*.  $\Box$ 

 $\rightarrow$  (s)

**Lemma 18.4.4** Even if a market restriction is applied to a market-restriction-free assertion, no change occurs. □

• Proof Evident.

#### 18.5 Market Restriction

#### **18.5.1** $\mathscr{A}\{M:1[\mathbb{R}][A]\}$

#### 18.5.1.1 Positive Restriction

- $\square$  Pom 18.5.1 ( $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]^+\}$ ) Suppose a>0. Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nondecreasing in t > 0.
- (b)  $\boxed{\text{§ dOITs}_{\tau>1}\langle\tau\rangle}$  where  $\text{CONDUCT}_{\tau\geq t>1}$ .  $\square\to$

• Proof The same as Tom 12.2.1(p.61) due to Lemma 18.4.4(p.118).

```
\square Pom 18.5.2 (\mathscr{A}\{M:1[\mathbb{R}][A]^+\}) Suppose a > 0. Let \beta < 1 or s > 0.
(a) V_t is nondecreasing in t > 0 and converges to a finite V \geq x_K as t \to \infty.
(b) Let \beta \mu \geq b (impossible).
(c) Let \beta \mu < b (always holds).
     1. Let \beta = 1.
           i. Let \mu - s \leq a. Then \boxed{\bullet dOITd_{\tau > 1}\langle 1 \rangle}_{\parallel}.
           ii. Let \mu - s > a. Then \boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle} where CONDUCT_{\tau \geq t > 1}.
     2. Let \beta < 1 and s = 0. Then s = 0 doing where s = 0 where s = 0 where s = 0 where s = 0 and s = 0.
     3. Let \beta < 1 and s > 0.
           i. Let \beta\mu > s. Then \boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle} where \texttt{CONDUCT}_{\tau\geq t>1}_{\blacktriangle} (see Numerical Example 1(p.126)).
           ii. Let s \geq \beta \mu. Then \bullet dOITd_{\tau > 1}\langle 1 \rangle (see Numerical Example 2(p.126)).
• Proof Suppose a > 0, hence b > a > 0 \cdots (1). Let \beta < 1 or s > 0. Then \kappa = \beta \mu - s \cdots (2) from
Lemma 11.3.1(p.59) (a) with \lambda = 1.
   (a) The same as Tom 12.2.2(p.62) (a).
   (b,c) Always \beta \mu < b due to [3(p.118)], hence \beta \mu \geq b is impossible.
   (c1) Let \beta = 1, hence s > 0 due to the assumption \beta < 1 or s > 0.
   (c1i,c1ii) The same as Tom 12.2.2(p.62) (c1i,c1ii).
   (c2) Let \beta < 1 and s = 0. Then, due to (1) it suffices to consider only (c2i) of Tom 12.2.2(p.62).
   (c3) Let \beta < 1 and s > 0.
   (c3i) Let \beta\mu > s. Then, since \kappa > 0 due to (2), it suffices to consider only (c2i) of Tom 12.2.2(p.62).
   (c3ii) Let \beta\mu \leq s. Then, since \kappa \leq 0 due to (2) and since \beta\mu - s \leq 0 < a, it suffices to consider only (c2ii1,c2iii1) of
Tom 12.2.2(p.62).
18.5.1.2 Mixed Restriction
\square Mim 18.5.1 (\mathscr{A}\{M:1[\mathbb{R}][A]^{\pm}\})
                                                Suppose a \le 0 \le b. Let \beta = 1 and s = 0.
       V_t is nondecreasing in t > 0.
       \boxed{\$ dOITs_{\tau>1}\langle \tau \rangle} \wedge where CONDUCT_{\tau\geq t>1} \wedge . \square
• Proof The same as Tom 12.2.1(p.61) due to Lemma 18.4.4(p.118).
\square Mim 18.5.2 (\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]^{\pm}\}) Suppose a \leq 0 \leq b. Let \beta < 1 or s > 0.
(a) V_t is nondecreasing in t > 0 and converges to a finite V \geq x_K as t \to \infty.
(b) Let \beta \mu \geq b (impossible).
(c) Let \beta \mu < b (always holds).
     1. Let \beta = 1.
           i. Let \mu - s \leq a. Then \bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}.
           ii. Let \mu - s > a. Then \boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle} where \text{CONDUCT}_{\tau \geq t > 1}.
     2. Let \beta < 1 and s = 0. Then \bigcirc dOITs<sub>\tau > 1</sub>\langle \tau \rangle \bigcirc where CONDUCT<sub>\tau \ge t > 1</sub>\bigcirc.
     3. Let \beta < 1 and s > 0.
           i. Let s < \beta T(0). Then \boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle} where \text{CONDUCT}_{\tau \geq t > 1}_{\blacktriangle}.
           ii. Let s = \beta T(0).
               1. Let \beta \mu - s \leq a. Then \bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}.
               2. Let \beta \mu - s > a. Then \boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle} where \text{CONDUCT}_{\tau > t > 1}.
          iii. Let s > \beta T(0).
               • Proof Suppose a \le 0 \le b. Let \beta < 1 or s > 0.
```

- - (a) The same as Tom 12.2.2(p.62) (a).
  - (b,c) Always  $\beta \mu < b$  due to [8(p.118)], hence  $\beta \mu \geq b$  is impossible.
  - (c1) Let  $\beta = 1$ , hence s > 0 due to the assumption  $\beta < 1$  or s > 0.
  - (c1i,c1ii) The same as Tom 12.2.2(p.62) (c1i,c1ii).
- (c2) Let  $\beta < 1$  and s = 0. If b > 0, then it suffices to consider only (c2i) of Tom 12.2.2(p.62) and if b = 0, then since always  $\beta\mu - s = \beta\mu > a$  due to [8], it suffices to consider only (c2ii2) of Tom 12.2.2(p.62). Therefore, whether b > 0 or b = 0, we have the
- (c3-c3iii2) Let  $\beta < 1$  and s > 0. Then, the assertions are immediate from Tom 12.2.2(p.62) (c2i-c2iii2) with  $\kappa = \beta T(0) s$  from (6.1.7(p.25)) with  $\lambda = 1$ .

#### 18.5.1.3 Negative Restriction

```
\square Nem 18.5.1 (\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]^-\})
                                                    Suppose b < 0. Let \beta = 1 and s = 0.
       V_t is nondecreasing in t > 0.
        We have [ \circ dOITs_{\tau>1}\langle \tau \rangle ]_{\blacktriangle} where CONDUCT_{\tau\geq t>1}_{\blacktriangle}.
ullet Proof The same as Tom 12.2.1(p.61) due to Lemma 18.4.4(p.118).
\square \quad \text{Nem 18.5.2 } \left( \mathscr{A} \{ \mathsf{M}: 1[\mathbb{R}][\mathtt{A}]^- \} \right) \quad \textit{Suppose } b < 0. \ \textit{Let } \beta < 1 \ \textit{or } s > 0.
(a) V_t is nondecreasing in t > 0 and converges to a finite V \geq x_K as t \to \infty.
      Let \beta \mu \geq b. Then \bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}.
(c) Let \beta \mu < b.
      1. Let \beta = 1.
             i. Let \mu - s \leq a. Then \boxed{\bullet dOITd_{\tau > 1}} \langle 1 \rangle_{\parallel}.
            ii. Let \mu - s > a. Then \odot dOITs_{\tau > 1} \langle \tau \rangle where CONDUCT_{\tau \geq t > 1}.
      2. Let \beta < 1 and s = 0. Then S_1(p.61) S is true.
          Let \beta < 1 and s > 0.
            \begin{array}{ll} \text{i.} & Let \ \beta\mu-s\leq a \ or \ s_{\mathcal{L}}\leq s. \ Then \ \boxed{\bullet \ \text{dOITd}_{\tau>1}\langle 1\rangle}_{\parallel}.\\ \text{ii.} & Let \ \beta\mu-s>a \ and \ s_{\mathcal{L}}>s. \ Then \ \mathbb{S}_1(\text{pfi}) \ \boxed{\$ \bullet \odot \parallel} \ is \ true. \end{array}
• Proof Suppose b < 0 \cdots (1). Let \beta < 1 or s > 0. Then, we have \kappa = -s \cdots (2) from Lemma 11.3.1(p.59) (a). Moreover, in
this case, both \beta \mu \geq b and \beta \mu < b are possible due to [17(p.118)].
   (a,b) The same as Tom 12.2.2(p.62) (a,b).
   (c) Let \beta \mu < b. Then s_{\mathcal{L}} > 0 \cdots (3) from Lemma 11.2.4(p.59) (c).
   (c1) Let \beta = 1, hence s > 0 due to the assumption \beta < 1 or s > 0.
   (c1i,c1ii) The same as Tom 12.2.2(p.62) (c1i,c1ii).
   (c2) Let \beta < 1 and s = 0. Then, due to (1) it suffices to consider only (c2iii1,c2iii2) of Tom 12.2.2(p.62). Since \beta \mu - s = \beta \mu > a
due to [15(p.118)] and since s=0< s_L due to (3), we have Tom 12.2.2(p.62) (c2iii2).
   (c3-c3ii) Let \beta < 1 and s > 0. Then, since \kappa < 0 due to (2), it suffices to consider only
(c2iii1,c2iii2) of Tom 12.2.2(p.62).
18.5.2
                 \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}
18.5.2.1
                Positive Restriction
\square Pom 18.5.3 (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]^+\}) Suppose a>0. Let \beta=1 and s=0.
        V_t is nonincreasing in t > 0.
        We have [ \circ dOITs_{\tau>1}\langle \tau \rangle ]_{\blacktriangle} where CONDUCT_{\tau\geq t>1}_{\blacktriangle}.
• Proof The same as Tom 13.7.1(p.83) due to Lemma 18.4.4(p.118).
\square Pom 18.5.4 (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]^+\}) Suppose a>0. Let \beta<1 or s>0.
(a) V_t is nonincreasing in t > 0 and converges to a finite V \leq x_{\tilde{K}} as t \to \infty.
(b) Let \beta \mu \leq a. Then \boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}
(c) Let \beta \mu > a.
      1. Let \beta = 1.
             i. Let \mu + s \geq b. Then \bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}.
            ii. Let \mu + s < b. Then \boxed{\$ \text{ dOITs}_{\tau \geq 1} \langle \tau \rangle} where \text{CONDUCT}_{\tau \geq t > 1}.
      2. Let \beta < 1 and s = 0. Then S_1(p.61) s = 0 is true.
      3. Let \beta < 1 and s > 0.
             i. Let \beta \mu + s \geq b or s_{\tilde{\mathcal{L}}} \leq s. Then \bullet dOITd_{\mathcal{L}}\langle 1 \rangle
                  Let \beta \mu + s < b and s_{\tilde{\mathcal{L}}} > s. Then S_1(p.61) S is true (see
                 Numerical Example 3(p.127)).
• Proof Suppose a > 0 \cdots (1), hence \tilde{\kappa} = s \cdots (2) from Lemma 13.6.6(p.83) (a). Here note that \mu\beta \leq a and \mu\beta > a are both
possible due to [5(p.118)].
   (a,b) The same as Tom 13.7.2(p.84) (a,b).
   (c) Let \beta \mu > a. Then s_{\tilde{\mathcal{L}}} > 0 \cdots (3) due to Lemma 13.6.5(p.83) (c) with \lambda = 1.
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(c2) Let  $\beta < 1$  and s = 0. Then, since  $\beta \mu + s = \beta \mu < b$  due to [3(p.118)] and since  $s_{\tilde{\ell}} > 0 = s$  from (3), due to (1) it suffices to consider only (c2iii2) of Tom 13.7.2(p.84).

(c3-c3ii) Let  $\beta < 1$  and s > 0. Then, since  $\tilde{\kappa} > 0$  due to (2), it suffices to consider only (c2iii1,c2iii2) of Tom 13.7.2(p.84). ■

 ${\tt Tom}\ 13.7.2 \hbox{(p.84) (c1i,c1ii)}.$ 

(c1-c1ii) Let  $\beta = 1$ , hence s > 0 due to the assumptions  $\beta < 1$  and s > 0. Thus, we have

#### 18.5.2.2 Mixed Restriction

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\square Mim 18.5.3 (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]^{\pm}\}) Suppose a\leq 0\leq b. Let \beta=1 and s=0.
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- (a)  $V_t$  is nonincreasing in t > 0.
- (b) We have  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}$  where  $CONDUCT_{\tau\geq t>1}$ .
- ullet Proof The same as Tom 13.7.1(p.83) due to Lemma 18.4.4(p.118).
- $\square$  Mim 18.5.4 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]^{\pm}\}$ ) Suppose  $a \leq 0 \leq b$ . Let  $\beta < 1$  or s > 0.
- (a)  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V < x_{\kappa}$  as  $t \to \infty$ .
- (b) Let  $\beta \mu \leq a$  (impossible).
- $(c) \quad \ Let \ \beta \mu > a \ ({\rm always \ holds}).$ 
  - 1. Let  $\beta = 1$ .
    - i. Let  $\mu + s \geq b$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $\mu + s < b$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$  where  $CONDUCT_{\tau \geq t > 1}$ .
  - 2. Let  $\beta < 1$  and s = 0. Then  $\boxed{\$ \text{dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  where  $\text{CONDUCT}_{\tau > t > 1}_{\blacktriangle}$ .
  - 3. Let  $\beta < 1$  and s > 0.
    - i. Let  $s < -\beta \tilde{T}(0)$ . Then subseteq doing = 0 where subseteq doing = 0 and subseteq doing = 0 where subseteq doing = 0 and subseteq doing = 0 where subseteq doing = 0 and su
    - ii. Let  $s = -\beta \tilde{T}(0)$ .
      - 1. Let  $\beta \mu + s \geq b$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta \mu + s < b$ . Then [s] dOITs $_{\tau > 1} \langle \tau \rangle$  where CONDUCT $_{\tau \geq t > 1}$ .
    - iii. Let  $s > -\beta \tilde{T}(0)$ .
      - 1. Let  $\beta \mu + s \ge b$  or  $s_{\tilde{\mathcal{L}}} \le s$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta \mu + s < b$  and  $s_{\tilde{\mathcal{L}}} > s$ . Then  $S_1(p.61)$   $s \neq 0$  is true.
- Proof Suppose  $a \leq 0 \leq b$ .
  - (a) The same as Tom 13.7.2(p.84) (a).
  - (b,c) Always  $\beta \mu > a$  due to [8(p.118)], hence  $\beta \mu \leq a$  is impossible. Hence  $s_{\tilde{\mathcal{L}}} > 0 \cdots$  (1) due to Lemma 13.6.5(p.83) (c).
  - (c1-c1ii) The same as Tom 13.7.2(p.84) (c1-c1ii).
- (c2) Let  $\beta < 1$  and s = 0. Let a < 0. Then it suffices to consider only (c2i) of Tom 13.7.2(p.84). Let a = 0. Then  $\beta \mu + s = \beta \mu < b$  due to [8(p.118)], hence it suffices to consider only (c2ii2) of Tom 13.7.2(p.84). Accordingly, whether a < 0 or a = 0, we have the same result.
- (c3-c3iii2) Let  $\beta < 1$  and s > 0. Then, the assertions become true from Tom 13.7.2(p.84) (c2i-c2iii2) with  $\tilde{\kappa} = \beta \tilde{T}(0) + s$  from (6.1.16(p.25)).

#### 18.5.2.3 Negative Restriction

- $\square$  Nem 18.5.3 ( $\mathscr{A}_{Tom}$  { $\widetilde{\mathsf{M}}$ :1[ $\mathbb{R}$ ][ $\mathbb{A}$ ]  $\longrightarrow$  Suppose b < 0. Let  $\beta = 1$  and s = 0.
- (a)  $V_t$  is nonincreasing in t > 0.
- (b) Then  $\bigcirc \text{dOITs}_{\tau>1}\langle \tau \rangle \setminus \text{where CONDUCT}_{\tau\geq t>1}$ .
- *Proof* The same as Tom 13.7.1(p.83) due to Lemma 18.4.4(p.118). ■
- $\square \ \ \text{Nem 18.5.4 } \left( \mathscr{A}_{\text{Tom}} \left\{ \tilde{\mathsf{M}} : 1[\mathbb{R}][\mathbf{A}]^{-} \right\} \right) \quad \ Suppose \ b < 0. \ \ Let \ \beta < 1 \ \ or \ s > 0.$
- (a)  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $\beta \mu \leq a$  (impossible).
- (c) Let  $\beta \mu > a$  (always holds).
  - 1. Let  $\beta = 1$ .
    - i. Let  $\mu + s \ge b$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
    - ii. Let  $\mu + s < b$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$  where  $CONDUCT_{\tau \geq t > 1}$ .
  - 2. Let  $\beta < 1$  and s = 0. Then  $\bigcirc$  dOITs<sub> $\tau > 1$ </sub> $\langle \tau \rangle$  where CONDUCT<sub> $\tau > t > 1$ </sub>.
  - 3. Let  $\beta < 1$  and s > 0.
    - $\text{i.} \quad Let \ \beta\mu < -s. \ \ Then \ \boxed{\$ \ \text{dOITs}_{\tau>1}\langle\tau\rangle}_{\blacktriangle} \ \ where \ \text{CONDUCT}_{\tau\geq t>1_{\blacktriangle}}.$
    - ii. Let  $\beta \mu \geq -s$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
- Proof Suppose  $b < 0 \cdots (1)$ , hence  $a < b < 0 \cdots (2)$ . Then  $\tilde{\kappa} = \beta \mu + s \cdots (3)$  due to Lemma 13.6.6(p.83) (a).
  - (a) The same as Tom 13.7.2(p.84) (a).
  - (b,c) Always  $a < \beta \mu$  due to [15(p.118)], hence  $\beta \mu \le a$  is impossible.
  - (c1-c1ii) The same as the proof of Tom 13.7.2(p.84) (c1-c1ii).

- (c2) Let  $\beta < 1$  and s = 0. Then, due to (2) it suffices to consider only (c2i) of Tom 13.7.2(p.84).
- (c3) Let  $\beta < 1$  and s > 0.
- (c3i) Let  $\beta\mu < -s$ , hence  $\beta\mu + s < 0$ . Hence, since  $\tilde{\kappa} < 0$  due to (3), it suffices to consider only (c2i) of Tom 13.7.2(p.84).
- (c3ii) Let  $\beta\mu \geq -s$ , hence  $\beta\mu + s \geq 0$ . Let  $\beta\mu + s = 0$ . Then, since  $\tilde{\kappa} = 0$  due to (3) and  $\beta\mu + s > b$  due to (2), it suffices to consider only (c2iii) of Tom 13.7.2(p.84). Let  $\beta\mu + s > 0$ . Then, since  $\tilde{\kappa} > 0$  due to (3), it suffices to consider only (c2iii) of Tom 13.7.2(p.84). Accordingly, whether  $\beta\mu + s = 0$  or  $\beta\mu + s > 0$ , we have the same result.

### $\mathbf{18.5.3} \quad \mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}$

#### 18.5.3.1 Positive Restriction

- $\square$  Pom 18.5.5 ( $\mathscr{A}\{M:1[\mathbb{P}][A]^+\}$ ) Suppose a > 0. Let  $\beta = 1$  and s = 0.
- (a)  $V_t$  is nondecreasing in t > 0.
- (b) We have  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}$  where  $CONDUCT_{\tau\geq t>1}$ .
- ullet Proof The same as Tom 14.4.1(p.98) due to Lemma 18.4.4(p.118).
- $\square$  Pom 18.5.6 ( $\mathscr{A}\{M:1[\mathbb{P}][A]^+\}$ ) Suppose a > 0. Let  $\beta < 1$  or s > 0.
- (a)  $V_t$  is nondecreasing in t > 0 and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
- (b) Let  $\beta a \geq b$  (impossible).
- (c) Let  $\beta a < b$  (always holds).
  - 1. Let  $\beta = 1$ .
    - i. Let  $a s \leq a^*$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$
    - ii. Let  $a-s>a^{\star}$ . Then  $\overline{\text{§§ dOITs}_{\tau>1}\langle \tau \rangle}$  where  $\text{CONDUCT}_{\tau\geq t>1}$ .
  - 2. Let  $\beta < 1$  and s = 0. Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  where  $\text{CONDUCT}_{\tau \geq t > 1}_{\blacktriangle}$ .
  - 3. Let  $\beta < 1$  and s > 0.
    - i. Let  $s < \beta T(0)$ . Then  $startion{ starting dollers for the dollers of the starting of the starting dollers for the st$
    - ii. Let  $s = \beta T(0)$ .
      - 1. Let  $\beta a s \leq a^*$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta a s > a^{\star}$ . Then subseteq doing = 0 doing where subseteq doing = 0 where subseteq doing = 0.
    - iii. Let  $s > \beta T(0)$ .
      - 1. Let  $\beta a s \leq a^*$  or  $s_{\mathcal{L}} \leq s$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
      - 2. Let  $\beta a s > a^*$  and  $s_{\mathcal{L}} > s$ . Then  $S_1(p.61)$   $\boxed{\$ \blacktriangle \circledcirc \Vdash}$
- Proof Suppose a > 0, hence  $b > a > 0 \cdots (1)$ .
  - (a) The same as Tom 14.4.2(p.98) (a).
  - (b,c) Always  $\beta a < b$  due to [4(p.118)], hence  $\beta a \ge b$  is impossible.
  - (c1-c1ii) The same as Tom 14.4.2(p.98) (c1-c1ii).
  - (c2) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c2i) of Tom 14.4.2(p.98).
- (c3-c3iii2) Immediate from Tom 14.4.2(p.98) (c2-c2iii2) with  $\kappa=\beta T(0)-s$  from
- (6.1.23(p.26)) with  $\lambda=1$ .

#### 18.5.3.2 Mixed Restriction

- $\square$  Mim 18.5.5 ( $\mathscr{A}\{M:1[\mathbb{P}][A]^{\pm}\}$ ) Suppose  $a \leq 0 \leq b$ . Let  $\beta = 1$  and s = 0.
- (a)  $V_t$  is nondecreasing in t > 0.
- (b) We have  $\boxed{\$ dOITs_{\tau}\langle \tau \rangle}$  where  $CONDUCT_{\tau \geq t > 1}$ .
- *Proof* The same as Tom 14.4.1(p.98) due to Lemma 18.4.4(p.118).
- $\square$  Mim 18.5.6 ( $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]^{\pm}\}$ ) Suppose  $a \leq 0 \leq b$ . Let  $\beta < 1$  or s > 0.
- (a)  $V_t$  is nondecreasing in t > 0 and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
- (b) Let  $\beta a \geq b$  (impossible).
- (c) Let  $\beta a < b$  (always holds).
  - 1. Let  $\beta = 1$ .
    - i. Let  $a s \leq a^*$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
    - ii. Let  $a-s>a^{\star}$ . Then  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$  where  $\text{CONDUCT}_{\tau>t>1}_{\blacktriangle}$ .
  - 2. Let  $\beta < 1$  and s = 0. Then s = 0. Then s = 0. Then s = 0. Then s = 0. Where s = 0.
  - 3. Let  $\beta < 1$  and s > 0.

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i. Let s < \beta T(0). Then subseteq 0 doins, subseteq 0 where subseteq 0 where subseteq 0 is subseteq 0.
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- ii. Let  $s = \beta T(0)$ .
  - 1. Let  $\beta a s \leq a^*$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
  - 2. Let  $\beta a s > a^*$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  where  $CONDUCT_{\tau > t > 1}_{\blacktriangle}$ .
- iii. Let  $s > \beta T(0)$ .
  - 1. Let  $\beta a s \leq a^*$  or  $s_{\mathcal{L}} \leq s$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
  - 2. Let  $\beta a s > a^*$  and  $s_{\mathcal{L}} > s$ . Then  $S_1(p.61)$   $\boxed{\$ \blacktriangle \odot \parallel}$
- Proof Suppose a < 0 < b.
  - (a) The same as Tom 14.4.2(p.98) (a).
  - (b,c) Always  $\beta a < b$  due to [9(p.118)], hence  $\beta a \ge b$  is impossible. .
  - (c1-c1ii) The same as Tom 14.4.2(p.98) (c1-c1ii).
- (c2) Let  $\beta < 1$  and s = 0. If b > 0, the assertion is true from Tom 14.4.2(p.98) (c2i) and if b = 0, then  $\beta a s = \beta a > a^*$  from [11(p.118)], hence the assertion become true from Tom 14.4.2(p.98) (c2ii2). Accordingly, whether b > 0 or b = 0, we have the same result.

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(c3-c3iii2) The same as Tom 14.4.2(p.98) (c2i-c2iii2) with \kappa = \beta T(0) - s from (6.1.23(p.26))) with \lambda = 1.
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#### 18.5.3.3 Negative Restriction

- $\square$  Nem 18.5.5 ( $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]^-\}$ ) Suppose b<0. Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nondecreasing in t > 0.
- (b) We have  $\boxed{\$ dOITs_{\tau}\langle \tau \rangle}$  where  $CONDUCT_{\tau \geq t > 1}$ .
- Proof Immediate from Tom 14.4.1(p.98) due to Lemma 18.4.4(p.118).
- $\square$  Nem 18.5.6 ( $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathbb{A}]^-\}$ ) Suppose b<0. Let  $\beta<1$  or s>0.
- (a)  $V_t$  is nondecreasing in t > 0 and converges to a finite  $\geq x_K$  as  $t \to \infty$ .
- (b) Let  $\beta a \geq b$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
- (c) Let  $\beta a < b$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $a-s \leq a^{\star}$ . Then  $\bullet dOITd_{\tau>1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $a-s>a^{\star}$ . Then  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}$  where  $\text{CONDUCT}_{\tau\geq t>1}$ .
  - 2. Let  $\beta < 1$  and s = 0. Then  $S_1(p.61)$  sample 1.
  - 3. Let  $\beta < 1$  and s > 0.
    - i. Let  $\beta a s \leq a^*$  or  $s_{\mathcal{L}} \leq s$ . Then  $\left[ \bullet \operatorname{dOITd}_{\tau > 1} \langle 1 \rangle \right]_{\parallel}$ .
    - ii. Let  $\beta a s > a^*$  and  $s_{\mathcal{L}} > s$ . Then  $S_1(p.61)$   $\boxed{\$ \blacktriangle \bigcirc \parallel}$
- Proof Suppose  $b < 0 \cdots$  (1), hence  $\kappa = \kappa_{\mathbb{P}} = -s \cdots$  (2) from Lemma 14.2.6(p.97) (a). Then, both  $\beta a \geq b$  and  $\beta a < b$  are possible due to [18(p.118)]. If  $\beta a < b$ , then  $s_{\mathcal{L}} > 0 \cdots$  (3) due to Lemma 14.2.5(p.97) (c) with  $\lambda = 1$ .
  - (a) The same as Tom 14.4.2(p.98) (a).
  - (b) Let  $\beta a \geq b$ . Then, the assertion is true Tom 14.4.2(p.98) (b).
  - (c) Let  $\beta a < b$ .
  - (c1-c1ii) The same as Tom 14.4.2(p.98) (c1-c1ii).
- (c2) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c2iii) of Tom 14.4.2(p.98). In addition, since  $\beta a s = \beta a > a^*$  due to [19(p.118)] and since  $s_{\mathcal{L}} > 0 = s$  due to (3), it suffices to consider only (c2iii2) of Tom 14.4.2(p.98).
  - (c3-c3ii) Let  $\beta < 1$  and s > 0. Then, since  $\kappa < 0$  from (2), it suffices to consider only (c2iii) of Tom 14.4.2(p.98).

#### 18.5.4 $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]\}$

#### 18.5.4.1 Positive Restriction

- $\square$  Pom 18.5.7 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]^+\}$ ) Suppose a>0. Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in t > 0.
- (b) We have  $\boxed{\$ dOITs_{\tau}\langle \tau \rangle}$  where  $CONDUCT_{\tau \geq t > 1}$ .
- *Proof* The same as Tom 15.7.1(p.109) due to Lemma 18.4.4(p.118).
- $\square$  Pom 18.5.8 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]^+\}$ ) Suppose a>0. Let  $\beta<1$  or s>0.
- (a)  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V \geq x_{\tilde{K}}$  as  $t \to \infty$ .

```
(b) Let \beta b \leq a. Then \boxed{\bullet dOITd_{\tau}\langle 1 \rangle}_{\parallel}.
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- (c) Let  $\beta b > a$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $b+s \geq b^{\star}$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau}\langle 1 \rangle}_{\parallel} \rightarrow$
    - ii. Let  $b+s < b^{\star}$ . Then  $\boxed{\$ \text{ dOITs}_{\tau}\langle \tau \rangle}_{\blacktriangle}$  where  $\text{CONDUCT}_{\tau \geq t > 1}_{\blacktriangle}$ .
  - 2. Let  $\beta < 1$  and s = 0. Then  $S_1(p.61)$   $\bigcirc A$   $\bigcirc A$ .
  - 3. Let  $\beta < 1$  and s > 0.
    - i. Let  $\beta b + s \geq b^*$  or  $s_{\tilde{\mathcal{L}}} \leq s$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau}\langle 1 \rangle}_{\parallel}$ .
    - ii. Let  $\beta b + s < b^*$  and  $s_{\tilde{c}} > s$ . Then  $S_1(p.61)$  sample | sam
- Proof Suppose  $a > 0 \cdots$  (1). Then,  $\tilde{\kappa} = s \cdots$  (2) from Lemma 15.6.6(p.108) (a). In this case,  $\beta b \leq a$  and  $\beta b > a$  are both possible due to [6(p.118)], and if  $\beta b > a$ , then  $s_{\tilde{\mathcal{L}}} > 0 \cdots$  (3) due to Lemma 15.6.5(p.108) (c) with  $\lambda = 1$ . In addition, we have
  - (a,b) The same as Tom 15.7.2(p.109) (a,b).
  - (c) Let  $\beta b > a$ .
  - (c1-c1ii)

The same as Tom 15.7.2(p.109) (c1-c1ii).

- (c2) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c2iii) of Tom 15.7.2(p.109). In this case, since  $\beta b + s = \beta b < b^*$  due to [7(p.118)] and since  $s_{\mathcal{L}} > 0 = s$  due to (3), it suffices to consider only (c2iii2) of Tom 15.7.2(p.109).
  - (c3-c3ii) Let  $\beta < 1$  and s > 0. Then, since  $\tilde{\kappa} > 0$  due to (2), it suffices to consider only (c2iii-c2iii2) of Tom 15.7.2(p.109).

#### 18.5.4.2 Mixed Restriction

- $\square$  Mim 18.5.7 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]^{\pm}\}$ ) Suppose  $a\leq 0\leq b$ . Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in t > 0.
- (b)  $\boxed{\$ dOITs_{\tau}\langle \tau \rangle}$  where  $CONDUCT_{\tau \geq t > 1}$ .
- Proof The same as Tom 15.7.1(p.109) due to Lemma 15.7.1(p.109).
- $\square$  Mim 18.5.8 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]^{\pm}\}$ ) Suppose  $a\leq 0\leq b$ . Let  $\beta<1$  or s>0.
- (a)  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V \geq x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $\beta b \leq a$  (impossible).
- (c) Let  $\beta b > a$  (always holds).
  - 1. Let  $\beta = 1$ .
    - i. Let  $b+s \geq b^*$ . Then  $\bullet dOITd_{\tau}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $b+s < b^{\star}$ . Then subseteq doing to doing the subseteq <math>subseteq doing to doing the subseteq doi
  - $2. \quad Let \ \beta < 1 \ and \ s = 0. \ Then \ \boxed{\$ \ \mathrm{dOITs}_{\tau} \langle \tau \rangle}_{\blacktriangle} \ \ where \ \mathrm{CONDUCT}_{\tau \geq t > 1 \ \blacktriangle}.$
  - 3. Let  $\beta < 1$  and s > 0.
    - i. Let  $s < -\beta \tilde{T}(0)$ . Then  $subseteq doing subseteq to doing where <math>\operatorname{CONDUCT}_{\tau \geq t > 1}$ .
    - ii. Let  $s = -\beta \tilde{T}(0)$ .
      - 1. Let  $\beta b + s \geq b^*$ . Then  $\boxed{\bullet dOITd_{\tau}\langle 1 \rangle}_{\parallel}$ .
      - 2. Let  $\beta b + s < b^*$ . Then  $\boxed{\$ \text{ dOITs}_{\tau} \langle \tau \rangle}$  where  $\text{CONDUCT}_{\tau > t > 1}$ .
    - iii. Let  $s > -\beta \tilde{T}(0)$ .
      - 1. Let  $\beta b + s \geq b^*$  or  $s_{\tilde{\mathcal{L}}} \leq s$ . Then  $\bullet dOITd_{\tau}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta b + s < b^*$  and  $s_{\tilde{\mathcal{L}}} > s$ . Then  $S_1(p.61)$   $\boxed{S \blacktriangle \bigcirc B}$
- Proof Let  $b \ge 0 \ge a \cdots (1)$ .
  - (a) The same as Tom 15.7.2(p.109) (a).
  - (b,c) Always  $\beta b > a$  due to [10(p.118)], hence  $\beta b \leq a$  is impossible.
  - (c1-c1ii) The same as Tom 15.7.2(p.109) (c1-c1ii).
- (c2) Let  $\beta < 1$  and s = 0. Then, it suffices to consider only (c2i-c2ii2) of Tom 15.7.2(p.109). Let a < 0. Then, the assertion is true from Tom 15.7.2(p.109) (c2i). Let a = 0. Then, since  $\beta b + s = \beta b < b^*$  due to [12(p.118)], it suffices to consider only (c2ii2) of Tom 15.7.2(p.109). Accordingly, whether a < 0 or a = 0, we have the same result.
- (c3-c3iii2) Let  $\beta < 1$  and s > 0. Then, the assertions hold from Tom 15.7.2(p.109) (c2i-c2iii2) with  $\tilde{\kappa} = \beta \tilde{T}(0) + s$  from (6.1.36(p.27)) with  $\lambda = 1$ .

#### 18.5.4.3 Negative Restriction

(c1-c1ii) The same as Tom 15.7.2(p.109) (c1-c1ii).

with  $\lambda = 1$ .

```
\square Nem 18.5.7 (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]^{-}\}) Suppose b<0. Let \beta=1 and s=0.
(a) V_t is nonincreasing in t > 0.
          We have \bigcirc dOITs_{\tau}\langle \tau \rangle where CONDUCT_{\tau \geq t > 1}.
• Proof The same as Tom 15.7.1(p.109) due to Lemma 18.4.4(p.118). \blacksquare
\square Nem 18.5.8 (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]^{-}\}) Suppose b<0. Let \beta<1 or s>0.
(a) V_t is nonincreasing in t > 0 and converges to a finite V \geq x_{\tilde{K}} as t \to \infty.
(b) Let \beta b \leq a (impossible).
(c) Let \beta b > a (always holds).
       1. Let \beta = 1.
               i. Let b+s \geq b^*. Then \bullet dOITd_{\tau}\langle 1 \rangle_{\parallel}.
              ii. Let b+s < b^{\star}. Then \boxed{\$ \text{ dOITs}_{\tau}\langle \tau \rangle}_{\blacktriangle} where \text{CONDUCT}_{\tau \geq t > 1}_{\blacktriangle}.
       2. Let \beta < 1 and s = 0. Then \boxed{\$ dOITs_{\tau} \langle \tau \rangle}_{\blacktriangle} where CONDUCT_{\tau \geq t > 1}_{\blacktriangle}.
            Let \beta < 1 and s > 0.
               \text{i.} \quad Let \ s < -\beta \tilde{T}(0). \ \ Then \ \boxed{\$ \ \text{dOITs}_{\tau}\langle \tau \rangle}_{\blacktriangle} \ \ where \ \ \text{CONDUCT}_{\tau \geq t > 1\,\blacktriangle}.
              ii. Let s = -\beta \tilde{T}(0).
                   1. Let \beta b + s \geq b^*. Then \bullet dOITd_{\tau}\langle 1 \rangle_{\parallel}.
                   2. \quad Let \ \beta b + s < b^{\star}. \ Then \ \boxed{\$ \ \text{dOITs}_{\tau}\langle \tau \rangle}_{\blacktriangle} \ \ where \ \text{CONDUCT}_{\tau \geq t > 1}_{\blacktriangle}.
             iii. Let -\beta T(0) < s.
                   1. Let \beta b + s \geq b^* or s_{\tilde{\mathcal{L}}} \leq s. Then \bullet dOITd_{\tau}\langle 1 \rangle_{\parallel}.
                   2. Let \beta b + s < b^* and s_{\tilde{\mathcal{L}}} > s. Then S_1(p61) s_{\tilde{\mathcal{L}}} > s.
• Proof Let b < 0, hence a < b < 0 \cdots (1).
    (a) The same as Tom 15.7.2(p.109) (a).
    (b,c) Always \beta b > a due to [16(p.118)], hence \beta b \leq a is impossible.
```

(c3-c3iii2) Let  $\beta < 1$  and s > 0. Then, the assertions hold from Tom 15.7.2(p.109) (c2-c2iii2) with  $\tilde{\kappa} = \beta \tilde{T}(0) + s$  from (6.1.36(p.27))

(c2) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c2i) of Tom 15.7.2(p.109).

#### 18.6 Numerical Example

Numerical Example 1 ( $\mathscr{A}\{M:1[\mathbb{R}][A]\}^+$  (selling model)

This is the example for  $\boxed{\$ \text{dOITs}_{\tau>1}\langle \tau \rangle}_{\bullet}$  in Pom 18.5.2(p.119) (c3i) with  $a=0.01,\ b=1.00,\ \beta=0.98,\ \text{and}\ s=0.05.^{\dagger}$  Then, we have  $x_K=0.6436$  (see Section A 6(p.321)). Figure 18.6.1(p.126) below is the graphs of  $I_{\tau}^t=\beta^{\tau-t}V_t$  for  $\tau=2,3,\cdots,15$  and  $t=1,2,\cdots,\tau$  (see (8.2.3(p.44))). For example, the two points on the line of  $\tau=2$  are given by  $V_2=0.538513$  (•) and  $\beta V_1=0.98\times0.444900=0.436002$  (•), hence  $V_2>\beta V_1$ . Similarly, the three points on the polygonal curve of  $\tau=3$  are given by  $V_3=0.583152$  (•),  $\beta V_2=0.98\times0.538513=0.52774274$  (•), and  $\beta^2 V_1=0.98^2\times0.4449=0.42728196$  (•), hence  $V_3>\beta V_2>\beta^2 V_1$ . Then, the value of t on the horizontal line corresponding to the bullet • provides the optimal initiating time  $t_{\tau}^*$  for each of  $\tau=2,3,\cdots,15$ , i.e.,  $\text{OIT}_{\tau}\langle t_{\tau}^*\rangle$ , so we have  $t_2^*=2,t_3^*=3,\cdots,t_{15}^*=15$  (see  $t_{\tau}^*$ -column of the table below). This result means  $\boxed{\$ \text{dOITs}_{\tau>1}\langle \tau \rangle}_{\bullet}$  for  $\tau=2,3,\cdots,15$ . Since  $V_t-\beta V_t>0$  for  $t=2,3,\cdots,15$  (see values of  $V_t-\beta V_t$ -column in the table below), we have  $L(V_{t-1})>0$  from (12.1.1(p.61)), meaning  $\text{Conduct}_{15\geq t>1.4}$  from (12.1.5(p.61)), i.e., it is strictly optimal to conduct the search on  $15\geq t>1$ .

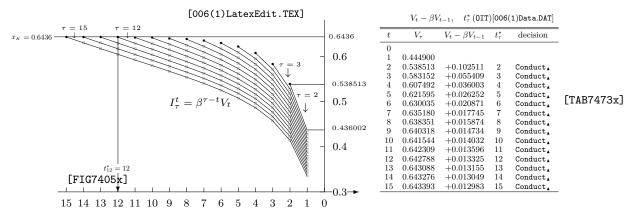


Figure 18.6.1: Graphs of  $I_{\tau}^t = \beta^{\tau-t} V_t$   $(15 \ge \tau \ge 2, \tau \ge t \ge 1)$  where • represents OIT

Numerical Example 2 ( $\mathscr{A}\{M:1[\mathbb{R}][A]\}^+$  (selling model)

This is the example for  $\boxed{\bullet \, \mathrm{dOITd}_{\tau>1}\langle 1 \rangle_{\parallel}}$  in Pom 18.5.2(p.119) (c3ii) with  $a=0.01, b=1.00, \beta=0.98$ , and  $s=0.50^{\dagger}$  The bullet  $\bullet$  in each of the 14 horizontal straight lines in Figure 18.6.2(p.126) below shows that the optimal initiating time  $t_{\tau}^{*}$  degenerates to time 1 (i.e.,  $t_{\tau}^{*}=1$  for  $\tau=2,3,\cdots,15$ ) under Preference Rule 8.2.1(p.45), i.e.,  $\boxed{\bullet \, \mathrm{dOITd}_{\tau=2,3,\cdots,15}\langle 1 \rangle_{\parallel}}$ . The result comes from the fact of  $V_{t}-\beta V_{t}=0$  for  $t=2,3,\cdots,15$  with  $t=2,3,\cdots,15$  (see  $V_{t}-\beta V_{t-1}$ -column in the table below), leading to  $V_{\tau}=\beta V_{\tau-1}=\cdots=\beta^{\tau-1}V_{1}$  for  $\tau=2,3,\cdots,15$ , i.e.,  $I_{\tau}^{\tau}=I_{\tau}^{\tau-1}=\cdots=I_{\tau}^{T}$  for  $\tau=2,3,\cdots,15$ .

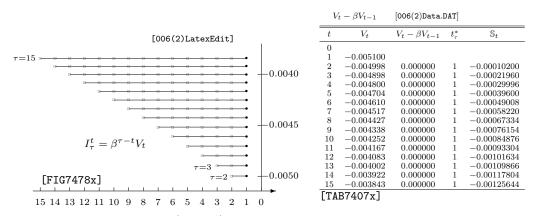


Figure 18.6.2: Graphs of  $I_{\tau}^t = \beta^{\tau-t}V_t$   $(15 \ge \tau \ge 2, \tau \ge t \ge 1)$  where • represents OIT

Note here that numbers in  $V_t$ -column are all negative, meaning that tackling the asset selling problem makes no profits (red ink). Accordingly, if this is of tE-case (see H1(p7) (a)), you must resign to the red ink and if it is of tA-case (see H1(p7) (b)), it suffices to pass over the problem without tackling the selling problem itself. Since  $0.5 \times (a+b) = 0.505$  and since  $V_t < 0 < 0.01 = a$  for  $t = 1, 2, \dots, 15$  (see  $V_t$ -column of the above table), from (A 7.2 (1) (p.323)) we have  $T(V_t) = 0.505 - V_t$  for  $t = 1, 2, \dots, 15$ , hence we have:

```
T(V_1) = 0.505 - (-0.005100) = 0.510100, \quad T(V_6) = 0.505 - (-0.004610) = 0.509610, \quad T(V_{11}) = 0.505 - (-0.004167) = 0.509167, \\ T(V_2) = 0.505 - (-0.00498) = 0.509998, \quad T(V_7) = 0.505 - (-0.004517) = 0.509517, \quad T(V_{12}) = 0.505 - (-0.004083) = 0.509083, \\ T(V_{11}) = 0.505 - (-0.00498) = 0.509998, \quad T(V_{12}) = 0.505 - (-0.004517) = 0.509517, \quad T(V_{12}) = 0.505 - (-0.004083) = 0.509988, \\ T(V_{11}) = 0.505 - (-0.00498) = 0.509998, \quad T(V_{12}) = 0.505 - (-0.004517) = 0.509517, \quad T(V_{12}) = 0.505 - (-0.004083) = 0.509988, \\ T(V_{11}) = 0.505 - (-0.00498) = 0.509998, \quad T(V_{11}) = 0.505 - (-0.004517) = 0.509517, \quad T(V_{11}) = 0.505 - (-0.004083) = 0.509988, \\ T(V_{11}) = 0.505 - (-0.00498) = 0.509998, \quad T(V_{11}) = 0.505 - (-0.004517) = 0.509517, \quad T(V_{11}) = 0.505 - (-0.004083) = 0.509998, \\ T(V_{11}) = 0.505 - (-0.00498) = 0.509998, \quad T(V_{11}) = 0.505 - (-0.004517) = 0.509517, \quad T(V_{11}) = 0.505 - (-0.004083) = 0.509998, \\ T(V_{11}) = 0.505 - (-0.00498) = 0.509998, \quad T(V_{11}) = 0.505 - (-0.004517) = 0.509517, \quad T(V_{11}) = 0.505 - (-0.004083) = 0.509998, \\ T(V_{11}) = 0.505 - (-0.00498) = 0.509998, \quad T(V_{11}) = 0.505 - (-0.004517) = 0.509517, \quad T(V_{11}) = 0.505 - (-0.004083) = 0.509998, \quad T(V_{11}) = 0.505 - (-0.004517) = 0.509517, \quad T(V_{11}) = 0.505 - (-0.004083) = 0.509998, \quad T(V_{11}) = 0.505 - (-0.004517) = 0.509517, \quad T(V_{11}) = 0.505 - (-0.004083) = 0.509998, \quad T(V_{11}) = 0.505 - (-0.004083) = 0.509999, \quad T(V_{11}) = 0.505 - (-0.004083) = 0.5099
```

<sup>&</sup>lt;sup>†</sup>Note that a = 0.01 > 0,  $\beta = 0.98 < 1$ , and s = 0.05 > 0. Then, since  $\mu = (0.01 + 1.00)/2 = 0.505$ , we have  $\beta \mu = 0.98 \times 0.505 = 0.4949 > 0.05 = s$ . Thus, the condition of this assertion is satisfied.

<sup>&</sup>lt;sup>†</sup>Note that a = 0.01 > 0,  $\beta = 0.98 < 1$ , and s = 0.50 > 0. In addition, since  $\mu = (0.01 + 1.00)/2 = 0.505$ , we have  $\beta \mu = 0.98 \times 0.505 = 0.4949 < 0.50 = s$ . Thus, the condition of the assertion is satisfied.

```
T(V_3) = 0.505 - (-0.004898) = 0.509898, \quad T(V_8) = 0.505 - (-0.004427) = 0.509427, \quad T(V_{13}) = 0.505 - (-0.004002) = 0.509002, \\ T(V_4) = 0.505 - (-0.004800) = 0.509800, \quad T(V_9) = 0.505 - (-0.004338) = 0.509338, \quad T(V_{14}) = 0.505 - (-0.003922) = 0.508922, \\ T(V_5) = 0.505 - (-0.004704) = 0.509704, \quad T(V_{10}) = 0.505 - (-0.004252) = 0.509252, \quad T(V_{15}) = 0.505 - (-0.003843) = 0.508843.
```

Since  $S_t = 0.98 \times T(V_{t-1}) - 0.5$  from (7.2.13(p.30)), we get

From the results of the above numerical calculation we have  $\mathbb{S}_t < 0$  for  $15 \ge t > 1$ , hence it is *strictly optimal* to skip the search over  $15 \ge t > 1$  due to (7.2.9[p.30]), i.e.,  $\mathsf{Skip}_{\blacktriangle}$ . However, since  $V_t - \beta V_{t-1} = 0$  for  $15 \ge t > 1$  (see  $(V_t - \beta V_{t-1})$ -column in the above table), we have  $V_{15} = \beta V_{14} = \cdots = \beta^{14} V_1$ , i.e., the profit attained are indifferent over  $15 \ge t > 0$ . This is not a contradiction, which is a false feeling caused by confusion from the jumble of intuition and theory (see Alice 1(p.41)).

### Numerical Example 3 $(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]^+\}$ (buying model)

This is the numerical example for  $\boxed{\odot \text{ ndOIT}_{\tau>t^{\bullet}_{\tau}}\langle t^{\bullet}_{\tau}\rangle_{\parallel}}$  in  $\mathbf{S}_{1}$ (p.61)  $\boxed{\odot \blacktriangle}$  of Pom 18.5.4(p.120) (c3ii) with  $a=0.01,\ b=1.00,\ \beta=0.98,\ \text{and}\ s=0.05.^{\dagger}$  Then, we have  $s_{\tilde{\mathcal{L}}}=0.323274$  (see Section A 6(p.321)). Hence, the optimal initiating time  $t^{*}_{\tau}$  is given by t attaining  $\min_{\tau\geq t>0}I^{t}_{\tau}$  (see  $(8.2.4\text{(p.44)}))^{\bullet}$ . The bullet  $\bullet$  in Figure 18.6.3(p.127) below shows the optimal initiating time for each of  $\tau=2,3,\cdots,15$  (see  $t^{*}_{\tau}$ -column in the table below). From the figure and table we see that  $t^{*}_{\tau}=\tau$  for  $\tau=2,3,\cdots,7,$  i.e.,  $\boxed{\odot \text{ dOITs}_{\tau\geq \tau>1}\langle \tau\rangle}_{\blacktriangle}$  (see  $\mathbf{S}_{1}$ (p.61) (1)) and that  $t^{*}_{\tau}=7$  for  $\tau=8,9,\cdots,15$ , i.e.,  $\boxed{\odot \text{ ndOIT}_{\tau>7}\langle \tau\rangle}_{\blacksquare}$  (see  $\mathbf{S}_{1}$ (p.61) (2)). In the numerical example, note the fact that  $\widetilde{\mathbb{S}}=\tilde{L}(V_{\tau-1})$  are all negative (< 0 (-), i.e.,  $\mathbf{Skip}_{\blacktriangle}$ ) for  $t=2,3,\cdots,7$  and positive (> 0 (+), i.e.,  $\mathbf{Conduct}_{\blacktriangle}$ ) for  $t=8,9,\cdots,15$ . Moreover, note that we have  $V_{t}-\beta V_{t-1}=0$  or equivalently  $V_{t}=\beta V_{t-1}$  for  $t=8,9,\cdots,15$  and  $V_{t}-\beta V_{t-1}<0$  or equivalently  $V_{t}<\beta V_{t-1}$  for  $t=2,3,\cdots,7$  (see  $V_{t}-\beta V_{t-1}$ -column), hence  $V_{15}=\beta V_{14}=\beta^{2}V_{13}=\cdots=\beta^{8}V_{7}<\beta^{9}V_{6}<\beta^{10}V_{5}<\cdots<\beta^{14}V_{1}$  (see  $\beta^{15}-tV_{t}$ -column), so we have  $\boxed{\odot \text{ ndOIT}_{\tau>7}\langle \tau\rangle_{\parallel}}$ .

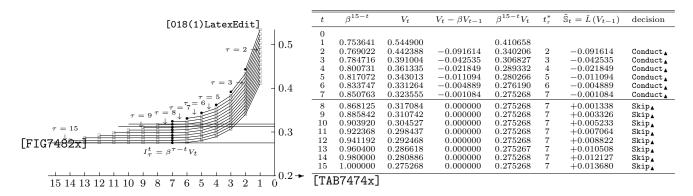


Figure 18.6.3: Graphs of  $I_{\tau}^t = \beta^{\tau - t} V_t \ (15 \ge \tau \ge 2, \tau \ge t \ge 1)$ 

<sup>&</sup>lt;sup>†</sup>Note that a = 0.01 > 0, b = 1.00,  $\beta = 0.98 < 1$ , and s = 0.05 > 0. Then, since  $\mu = (0.01 + 1.00)/2 = 0.505$ , we have  $\beta \mu = 0.98 \times 0.505 = 0.4949$ , hence  $\beta \mu + s = 0.4949 + 0.05 = 0.5449 < 1.00 = b$ . In addition,  ${}^s \bar{c} = 0.323274 > 0.05 = s$ . Thus, the conditions for the assertions are satisfied. <sup>‡</sup>Note that this is a selling model with cost minimization.

## **Diagonal Symmetry**

In Chap. 18(p.117) we showed that the symmetry between a selling problem and a buying problem on  $\mathscr{F}$  may collapse on  $\mathscr{F}^+$ . In this chapter we demonstrate that the selling problem on  $\mathscr{F}^-$  becomes always symmetrical to the buying problem on  $\mathscr{F}^+$  and that the buying problem on  $\mathscr{F}^-$  becomes always symmetrical to the selling problem on  $\mathscr{F}^+$ .

#### 19.1 Model with $\mathbb{R}$ -mechanism

#### 19.1.1 Identicalness of Condition Spaces $\mathscr{C}\langle \mathcal{T}om \rangle$ and $\check{\mathscr{C}}\langle \tilde{\mathcal{T}}om \rangle$

Note here that  $\mathscr{C}\langle \mathsf{Tom}\rangle = \mathscr{P} \times \mathscr{F}$  (see (13.5.50(p.79))) and  $\check{\mathscr{C}}\langle \check{\mathsf{Tom}}\rangle = \mathscr{P} \times \mathscr{F}$  (see (13.5.51(p.80))) are *identical*, i.e.,

$$\mathscr{C}\langle \mathsf{Tom}\rangle \,=\, \mathscr{P}\times \mathscr{F} = \check{\mathscr{C}}\langle \tilde{\mathsf{Tom}}\rangle \qquad , \tag{19.1.1}$$

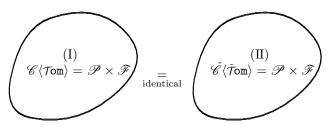


Figure 19.1.1: Identicalness of  $\mathscr{C}\langle \mathcal{T}om \rangle$  and  $\check{\mathscr{E}}\langle \tilde{\mathcal{T}}om \rangle$ 

#### 19.1.2 Collapse of Identicalness by Market Restriction

#### ■ Market Restriction

Let us consider here the market restriction of  $\mathscr{F}$  to a given subset  $\mathscr{F}'$  (see Section 18.2(p.117))), i.e.,

$$\mathscr{F}' \subseteq \mathscr{F}.$$
 (19.1.2)

Then, let us define

$$\mathscr{C}'\langle A_{\mathsf{Tom}}\rangle \stackrel{\text{def}}{=} \{(\boldsymbol{p},F) \mid \boldsymbol{p} \in \mathscr{P}_{A_{\mathsf{Tom}}} \subseteq \mathscr{P}, F \in \mathscr{F}_{A_{\mathsf{Tom}}|\boldsymbol{p}} \subseteq \mathscr{F}'\} \quad (\text{see }(12.3.7(\text{p.65}))), \tag{19.1.3}$$

$$\mathscr{C}'\langle \mathcal{T} \mathsf{om} \rangle \stackrel{\text{def}}{=} \cup_{\mathsf{Tom} \in \mathcal{T} \mathsf{om}} \cup_{A_{\mathsf{Tom}} \in \mathsf{Tom}} \mathscr{C}'\langle A_{\mathsf{Tom}} \rangle \quad (\text{see } (12.3.24(\text{p.67}))). \tag{19.1.4}$$

In addition, let us define

$$\check{\mathscr{F}}' \stackrel{\text{def}}{=} \{ \check{F} \mid F \in \mathscr{F}' \} \qquad (\text{see } (13.1.3(\text{p.69}))) \tag{19.1.5}$$

where

$$\check{\mathscr{F}}' \subseteq \check{\mathscr{F}}.^{\dagger} \tag{19.1.6}$$

Then, let us define

$$\check{\mathscr{E}}'\langle A_{\text{Tom}}\rangle \stackrel{\text{def}}{=} \{(\boldsymbol{p}, \check{F}) \mid \boldsymbol{p} \in \mathscr{P}_{A_{\text{Tom}}} \subseteq \mathscr{P}, \check{F} \in \check{\mathscr{F}}_{A_{\text{Tom}}|\boldsymbol{p}} \subseteq \check{\mathscr{F}}'\} \quad (\text{see } (13.5.18(p.76))), \tag{19.1.7}$$

$$\check{\mathscr{E}}'\langle \mathcal{T} \mathsf{om} \rangle \stackrel{\text{def}}{=} \cup_{\tilde{\mathsf{T}} \mathsf{om} \in \tilde{\mathsf{T}} \mathsf{om}} \cup_{A_{\mathsf{T} \mathsf{om}} \in \mathsf{Tom}} \check{\mathscr{E}}'\langle A_{\mathsf{Tom}} \rangle \quad (\text{see } (13.5.47(\text{p.79}))). \tag{19.1.8}$$

#### ■ Rewrite of Section 12.3(p.63)

Here it should be noted that, even if  $\mathscr{F}$  and  $\mathscr{F}$  in Section 12.3(p.63) are replaced by  $\mathscr{F}'$  and  $\mathscr{F}'$  respectively, we can make quite the similar discussions that have been made there, hence (12.3.25(p.68)) and (12.3.26(p.68)) cab be rewritten as respectively.

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\} \text{ holds on } \mathscr{C}'\langle \mathcal{T}\mathtt{om}\rangle \tag{19.1.9}$$

$$\mathscr{C}'\langle \mathsf{Tom}\rangle = \mathscr{P} \times \mathscr{F}'. \tag{19.1.10}$$

#### ■ Rewrite of Section 12.3(p.63)

Similarly to the above, even if  $\mathscr{F}$  and  $\check{\mathscr{F}}$  in Step  $6 \, (p.78)$  are replaced by  $\mathscr{F}'$  and  $\check{\mathscr{F}}'$  respectively, we can make quite the similar discussions as having been made there except for Lemma 13.5.3(p.80). In this case this lemma can be rewritten as below.

<sup>†</sup>Due to (19.1.2(p.129)) we have  $\check{\mathscr{F}}' = \{\check{F} \mid F \in \mathscr{F}'\} \subseteq \{\check{F} \mid F \in \mathscr{F}\} = \check{\mathscr{F}}.$ 

#### Lemma 19.1.1 We have

$$\check{\mathscr{E}}'\langle \tilde{\mathcal{T}} om \rangle = \mathscr{P} \times \check{\mathscr{F}}'. \quad \Box \tag{19.1.11}$$

● **Proof** For quite the same reason of  $\mathscr{F}$  in (13.5.14 (p.76)) being transformed into  $\check{\mathscr{F}}$  in (13.5.15 (p.76)), we can show that  $\mathscr{F}'$  in (19.1.10 (p.129)) is transformed into  $\check{\mathscr{F}}'$  in (19.1.11 (p.130)). In accordance with this transformation, the completeness of  $\mathcal{T}$ om on  $\mathscr{E}'\langle \mathcal{T}$ om $\rangle = \mathscr{P} \times \mathscr{F}'$  is inherited also to the completeness of  $\tilde{\mathcal{T}}$ om on  $\check{\mathscr{E}}'\langle \tilde{\mathcal{T}}$ om $\rangle = \mathscr{P} \times \check{\mathscr{F}}'$ .

Since it cannot be always proven that  $\mathscr{F}$  is identical to  $\check{\mathscr{F}}$  (i.e.,  $\mathscr{F}' \neq \check{\mathscr{F}}'$ ), we have  $\mathscr{C}'\langle \mathsf{Tom} \rangle \neq \check{\mathscr{C}}'\langle \check{\mathsf{Tom}} \rangle$ , schematized as in Figure 19.1.2(p.130) below.

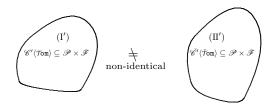


Figure 19.1.2: Non-identicalness of  $\mathscr{C}'\langle \mathcal{T}om \rangle$  and  $\check{\mathscr{E}}'\langle \tilde{\mathcal{T}}om \rangle$ 

Now, since  $\mathscr{F}' \subseteq \mathscr{F}$  due to (19.1.2(p.129)) and  $\check{\mathscr{F}} \subseteq \mathscr{F}$  by definition, we have

$$\mathscr{C}'\langle \mathsf{Tom}\rangle \ = \ \mathscr{P}\times \mathscr{F}'\subseteq \mathscr{P}\times \mathscr{F} = \mathscr{C}\langle \mathsf{Tom}\rangle, \tag{19.1.12}$$

$$\check{\mathcal{E}}'\langle \tilde{\mathcal{T}} \mathsf{om} \rangle = \mathscr{P} \times \check{\mathscr{F}}' \subseteq \mathscr{P} \times \mathscr{F} = \check{\mathcal{E}}\langle \tilde{\mathcal{T}} \mathsf{om} \rangle. \tag{19.1.13}$$

Accordingly, superimposing Figures 19.1.1(p.129) onto 19.1.2(p.130) yields Figure 19.1.3(p.130) below.

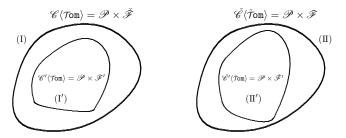


Figure 19.1.3: Superimposition of Figures 19.1.1 onto 19.1.2

The inclusion relations depicted in Figure 19.1.3(p.130) implies that what holds on  $\mathscr{C}\langle \mathcal{T}om \rangle \cdots (I)$  holds also on  $\mathscr{C}'\langle \mathcal{T}om \rangle \cdots (I')$  and what holds on  $\mathscr{E}'\langle \mathcal{T}om \rangle \cdots (II)$  holds on  $\mathscr{E}'\langle \mathcal{T}om \rangle \cdots (II')$ . This fact implies

$$\begin{cases} \text{The validity of Lemma 13.5.2(p.79)}, \text{ which holds on } \mathscr{C}\langle \mathcal{T} om \rangle = \mathscr{F} \times \mathscr{F} \cdots (I) \text{ and } \mathscr{E}\langle \tilde{\mathcal{T}} om \rangle = \mathscr{F} \times \mathscr{F}, \text{ is in its entirety} \\ \text{inherited to } \mathscr{C}'\langle \mathcal{T} om \rangle = \mathscr{F} \times \mathscr{F}' \cdots (I') \text{ and } \mathscr{E}'\langle \tilde{\mathcal{T}} om \rangle = \mathscr{F} \times \mathring{\mathscr{F}}' \cdots (II'). \end{cases}$$

This fact implies hat Lemma 13.5.2(p.79) can be rewritten as Theorem 19.1.1(p.130) below:

**Theorem 19.1.1** Let  $\mathscr{A}\{M:1[\mathbb{R}][A]\}\$ holds on  $\mathscr{P}\times\mathscr{F}'(=\mathscr{C}'\langle\mathcal{T}om\rangle)$ . Then,  $\mathscr{A}\{\tilde{M}:1[\mathbb{R}][A]\}\$ holds on  $\mathscr{P}\times\check{\mathscr{F}}'(=\check{\mathscr{C}}'\langle\tilde{\mathcal{T}}om\rangle)$  where

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]\}]. \quad \Box$$
 (19.1.14)

#### 19.1.3 A Lemma

As the restricted market  $\mathscr{F}'$  (see (19.1.2(p.129))) let us consider here the following three cases:

$$\mathscr{F}' = \mathscr{F}^+ \cdots (1), \quad \mathscr{F}' = \mathscr{F}^\pm \cdots (2), \quad \mathscr{F}' = \mathscr{F}^- \cdots (3).$$
 (19.1.15)

Then  $\check{\mathscr{F}}'$  (see (19.1.5(p.129))) corresponding to each case above can be expressed as below:

$$\check{\mathscr{F}}' = \check{\mathscr{F}}^+ = \{\check{F} \mid F \in \mathscr{F}^+\} \cdots (1), \quad \check{\mathscr{F}}' = \check{\mathscr{F}}^\pm = \{\check{F} \mid F \in \mathscr{F}^\pm\} \cdots (2), \quad \check{\mathscr{F}}' = \check{\mathscr{F}}^- = \{\check{F} \mid F \in \mathscr{F}^-\} \cdots (3) \mathbb{I} 9.1.16)$$

Lemma 19.1.2 We have:

$$\check{\mathscr{F}}^+ = \mathscr{F}^- \cdots (1), \quad \check{\mathscr{F}}^\pm = \mathscr{F}^\pm \cdots (2), \quad \check{\mathscr{F}}^- = \mathscr{F}^+ \cdots (1). \quad \Box$$
 (19.1.17)

Proof of (1) Consider any  $\check{F} \in \check{\mathscr{F}}^+ = \{\check{F} \mid F \in \mathscr{F}^+\}$ . Then, since  $F \in \mathscr{F}^+$ , we have  $F(\xi) = \Pr\{\xi \leq \xi\}$  with  $0 < a < \xi < b$ . Hence, since  $\check{F}(\xi) = \Pr\{\check{\xi} \leq \xi\}$  with  $0 > \hat{a} > \hat{\xi} > \hat{b}$ , we have  $\check{F} \in \mathscr{F}^-$ , so  $\check{\mathscr{F}}^+ \subseteq \mathscr{F}^- \cdots (1^*)$ . Consider any  $\check{F} \in \mathscr{F}^-$ . Then, since  $\check{F}(\xi) = \Pr\{\check{\xi} \leq \xi\}$  with  $a < \hat{\xi} < b < 0$ , we have  $F(\xi) = \Pr\{\xi \leq \xi\}$  with  $\hat{a} > \hat{\xi} = \xi > \hat{b} > 0$ , so  $F \in \mathscr{F}^+$ , hence since  $\check{F} \in \mathscr{F}^+$ , we have  $\mathscr{F}^- \subseteq \mathscr{F}^+$ . From this and  $(1^*)$  we have  $\mathscr{F}^+ = \mathscr{F}^-$ .

Proof of (2) Consider any  $\check{F} \in \check{\mathscr{F}}^{\pm} = \{\check{F} \mid F \in \mathscr{F}^{\pm}\}$ . Then, since  $F \in \mathscr{F}^{\pm}$ , we have  $F(\xi) = \Pr\{\xi \leq \xi\}$  with  $a \leq 0 \leq b$ . Hence, since  $\check{F}(\xi) = \Pr\{\check{\xi} \leq \xi\}$  with  $\hat{a} \geq 0 \geq \hat{b}$ , we have  $\check{F} \in \mathscr{F}^{\pm}$ , so  $\check{\mathscr{F}}^{\pm} \subseteq \mathscr{F}^{\pm} \cdots (2^*)$ . Consider any  $\check{F} \in \mathscr{F}^{\pm}$ . Then, since  $\check{F}(\xi) = \Pr\{\check{\xi} \leq \xi\}$  with  $a \leq 0 \leq b$ , we have  $F(\xi) = \Pr\{\xi \leq \xi\}$  with  $\hat{a} \geq 0 \geq \hat{b}$ , so  $F \in \mathscr{F}^{\pm}$ , hence since  $\check{F} \in \check{\mathscr{F}}^{\pm}$ , we have  $\mathscr{F}^{\pm} \subseteq \check{\mathscr{F}}^{\pm}$ . From this and (2\*) we have  $\check{\mathscr{F}}^{\pm} = \mathscr{F}^{\pm}$ .

Proof of (3) Consider any  $\check{F} \in \check{\mathscr{F}}^- = \{\check{F} \mid F \in \mathscr{F}^-\}$ . Then, since  $F \in \mathscr{F}^-$ , we have  $F(\xi) = \Pr\{\xi \leq \xi\}$  with  $a < \xi < b < 0$ . Hence, since  $\check{F}(\xi) = \Pr\{\check{\xi} \leq \xi\}$  with  $\hat{a} > \hat{\xi} > \hat{b} > 0$ , we have  $\check{F} \in \mathscr{F}^+$ , so  $\check{\mathscr{F}}^- \subseteq \mathscr{F}^+ \cdots (3^*)$ . Consider any  $\check{F} \in \mathscr{F}^+$ . Then, since  $\check{F}(\xi) = \Pr\{\check{\xi} \leq \xi\}$  with  $0 < a < \hat{\xi} < b$ , we have  $F(\xi) = \Pr\{\xi \leq \xi\}$  with  $0 > \hat{a} > \hat{\xi} = \xi > \hat{b}$ , so  $F \in \mathscr{F}^-$ , hence  $\check{F} \in \check{\mathscr{F}}^-$ , we have  $\mathscr{F}^+ \subseteq \check{\mathscr{F}}^-$ . From this and (3\*) we have  $\mathscr{F}^- = \mathscr{F}^+$ .

From (19.1.16(p.130)) and (19.1.17(p.130)) we have

$$\check{\mathscr{F}}' = \mathscr{F}^- \cdots (1), \qquad \check{\mathscr{F}}' = \mathscr{F}^\pm \cdots (2), \qquad \check{\mathscr{F}}' = \mathscr{F}^+ \cdots (3).$$
 (19.1.18)

#### 19.1.4 Diagonal Symmetry

Applying (19.1.15(p.130)) and (19.1.18(p.131)) to Lemma 19.1.1(p.130) produces the following three theorems:

**Theorem 19.1.2** Let  $\mathscr{A}\{M:1[\mathbb{R}][A]^+\}$  holds on  $\mathscr{P}\times\mathscr{F}^+$ . Then,  $\mathscr{A}\{\tilde{M}:1[\mathbb{R}][A]^-\}$  holds on  $\mathscr{P}\times\mathscr{F}^-$  where

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]^{-}\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]^{+}\}]. \quad \Box$$
(19.1.19)

● *Proof* Due to  $(19.1.15\,(1)\,(p.130))$  we can rewrite  $M:1[\mathbb{R}][A]$  in Lemma 19.1.1(p.130) as  $M:1[\mathbb{R}][A]^+$  (see (18.3.1(p.117))). In addition, due to  $(19.1.18\,(1)\,(p.131))$  we can rewrite  $\tilde{M}:1[\mathbb{R}][A]$  in Lemma 19.1.1(p.130) as  $\tilde{M}:1[\mathbb{R}][A]^-$ . Accordingly, Lemma 19.1.1(p.130) can be rewritten as the above theorem.  $\blacksquare$ 

**Theorem 19.1.3** Let  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]^{\pm}\}$  holds on  $\mathscr{P}\times\mathscr{F}^{\pm}$ . Then,  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]^{\pm}\}$  holds on  $\mathscr{P}\times\mathscr{F}^{\pm}$  where  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]^{\pm}\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]^{\pm}\}]. \quad \Box$  (19.1.20)

● *Proof* Due to (19.1.15(2)(p.130)) we can rewrite  $M:1[\mathbb{R}][A]$  in Lemma 19.1.1(p.130) as  $M:1[\mathbb{R}][A]^{\pm}$  (see (18.3.2(p.117))). In addition, due to (19.1.18(2)(p.131)) we can rewrite  $\tilde{M}:1[\mathbb{R}][A]$  in Lemma 19.1.1(p.130) as  $\tilde{M}:1[\mathbb{R}][A]^{\pm}$ . Accordingly, Lemma 19.1.1(p.130) can be rewritten as the above theorem.

**Theorem 19.1.4** Let  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]^-\}$  holds on  $\mathscr{P}\times\mathscr{F}^-$ . Then,  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]^+\}$  holds on  $\mathscr{P}\times\mathscr{F}^+$  where  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]^+\}=\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]^-\}]. \quad \Box$  (19.1.21)

● *Proof* Due to  $(19.1.15\,(3)\,(p.130))$  we can rewrite  $M:1[\mathbb{R}][A]$  in Lemma 19.1.1(p.130) as  $M:1[\mathbb{R}][A]^-$  (see (18.3.3(p.117))). In addition, due to  $(19.1.18\,(3)\,(p.131))$  we can rewrite  $\tilde{M}:1[\mathbb{R}][A]$  in Lemma 19.1.1(p.130) as  $\tilde{M}:1[\mathbb{R}][A]^+$ . Accordingly, Lemma 19.1.1(p.130) can be rewritten as the above theorem.  $\blacksquare$ 

The inverses of the above three theorems can be given as below:

**Theorem 19.1.5** Let  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]^-\}$  holds on  $\mathscr{P}\times\mathscr{F}^-$ . Then,  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]^+\}$  holds on  $\mathscr{P}\times\mathscr{F}^+$  where

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]^{+}\} = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]^{-}\}]. \quad \Box$$

$$(19.1.22)$$

**Theorem 19.1.6** Let  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]^{\pm}\}\ holds\ on\ \mathscr{P}\times\mathscr{F}^{\pm}\ .$  Then,  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]^{\pm}\}\ holds\ on\ \mathscr{P}\times\mathscr{F}^{\pm}\ where$ 

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]^{\pm}\} = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]^{\pm}\}]. \quad \Box$$
(19.1.23)

**Theorem 19.1.7** Let  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]^+\}$  holds on  $\mathscr{P}\times\mathscr{F}^+$ . Then,  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathbb{A}]^-\}$  holds on  $\mathscr{P}\times\mathscr{F}^-$  where

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]^{-}\} = \mathcal{S}_{\widetilde{\mathbb{R}} \to \mathbb{R}}[\mathscr{A}\{\widetilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]^{+}\}]. \quad \Box$$

$$(19.1.24)$$

For convenience of reference, below let us copy (19.1.19(p.131))-(19.1.21(p.131)) and (19.1.22(p.131))-(19.1.24(p.131)).

$$\langle \mathbf{a} \rangle \, \mathcal{A} \{ \tilde{\mathsf{M}} : 1[\mathbb{R}][\mathbf{A}] \}^{-} = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} [\mathcal{A} \{ \mathsf{M} : 1[\mathbb{R}][\mathbf{A}]^{+} \}], \tag{19.1.25}$$

$$\langle \mathbf{b} \rangle \, \mathscr{A} \{ \tilde{\mathsf{M}} : 1[\mathbb{R}][\mathbb{A}] \}^{\pm} = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} [\mathscr{A} \{ \mathsf{M} : 1[\mathbb{R}][\mathbb{A}]^{\pm} \}], \tag{19.1.26}$$

$$\langle \mathbf{c} \rangle \mathscr{A} \{ \tilde{\mathsf{M}}: 1[\mathbb{R}][\mathbf{A}] \}^{+} = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} [\mathscr{A} \{ \mathsf{M}: 1[\mathbb{R}][\mathbf{A}]^{-} \}], \tag{19.1.27}$$

$$\langle \mathbf{a} \rangle \, \mathscr{A} \{ \mathsf{M}: 1[\mathbb{R}][\mathbf{A}] \}^{+} = \mathcal{S}_{\tilde{\mathbb{D}} \to \mathbb{D}} [\mathscr{A} \{ \tilde{\mathsf{M}}: 1[\mathbb{R}][\mathbf{A}]^{-} \} \}, \tag{19.1.28}$$

$$\langle \mathbf{b} \rangle \, \mathscr{A} \{ \mathsf{M}: 1[\mathbb{R}][\mathbf{A}] \}^{\pm} = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}} [\mathscr{A} \{ \tilde{\mathsf{M}}: 1[\mathbb{R}][\mathbf{A}]^{\pm} \} ], \tag{19.1.29}$$

$$\langle \mathbf{c} \rangle \, \mathscr{A} \{ \mathsf{M}: 1[\mathbb{R}][\mathbb{A}] \}^{-} = \mathcal{S}_{\tilde{\mathbb{R}}_{\rightarrow \mathbb{R}}} [\mathscr{A} \{ \tilde{\mathsf{M}}: 1[\mathbb{R}][\mathbb{A}]^{+} \}]. \tag{19.1.30}$$

The above relationships can be schematized as in Figure 19.1.4(p.132) below.

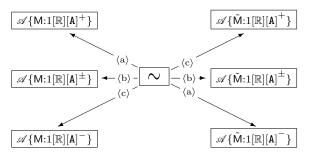


Figure 19.1.4: Symmetrical Relations

**Definition 19.1.1** (diagonal-symmetry) Let us refer to the *aslant* relationships X in Figure 19.1.4(p.132) as the *diagonal-symmetry*, denoted by  $d-\infty$ .  $\square$ 

Thus we have the following corollary.

Corollary 19.1.1 (diagonal symmetry) We have:

$$\leftrightarrow \text{ (b)} \quad \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]^{\pm}\} \quad \sim \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]^{\pm}\} \tag{19.1.32}$$

$$\land (a) \quad \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{A}]^+\} \ \mathsf{d} \sim \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]^-\}$$
 (19.1.33)

#### Exercise 19.1.1

 $\begin{tabular}{ll} $\swarrow$ (c) & \textit{Confirm by yourself that } (19.1.31(p.132)) & \textit{holds in fact by comparing Pom } 18.5.4(p.120) & \textit{and Nem } 18.5.2(p.120) \\ \end{tabular} .$ 

 $\leftarrow$  (b) Confirm by yourself that (19.1.32(p.132)) holds in fact by comparing Mim 18.5.4(p.121) and Mim 18.5.2(p.119).

 $\$  (a) Confirm by yourself that (19.1.33(p.132)) holds in fact by comparing Nem 18.5.4(p.121) and Pom 18.5.2(p.119).

**Remark 19.1.1** (19.1.32(p.132)) implies that the symmetrical relationship on  $\mathscr{F}$  is inherited on  $\mathscr{F}^{\pm}$ .  $\square$ 

### 19.2 Conventional Methodology vs Methodology by Integrated-Theory

#### 19.2.1 Conventional Methodology

In the conventional methodology, analyses are separately and one-by-one performed for each of 16 shadow-boxes \_\_\_ and \_\_\_ in Figure 19.2.1(p.132) below.

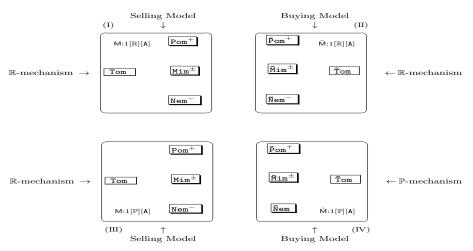


Figure 19.2.1: Conventional Methodology

#### 19.2.2 Methodology by Integrated-Theory

The Figure 19.2.2(p.133) below shows the flow of analyses based on the integrated-theory where

- $\circ S$  in (5\*), (1\*), (2\*), and (6\*) is the symmetry transformation operation (see (20.0.1(p.136)) and (20.0.3(p.136))),
- $\circ$   $\mathcal{A}$  in (3\*) and (4\*) is the analogy replacement operation (see (20.0.5(p.136)) and (20.0.7(p.136))).

In the figure, actual analyses are performed only for the 4 boxes  $\square$ , and the remaining 12 shadow-boxes  $\square$  are all derived from applying the market restrictions  $\mathscr{F}^+$ ,  $\mathscr{F}^\pm$ , and  $\mathscr{F}^-$  to the 4 boxes  $\square$ .

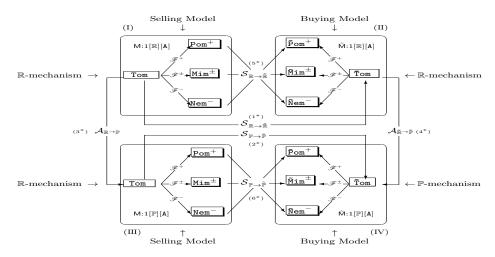


Figure 19.2.2: Operations Based on the Integrated-Theory

#### 19.2.3 Two Possible Simplified Methods

Carefully and in detail looking at the structure of the diagrams in Figure 19.2.2(p.133), we immediately see that there exist the two methods (Method I and Method II) to obtain  $\boxed{\tilde{\mathtt{Pom}}^+}$ . Removing redundant relations within Figure 19.2.2(p.133) produces Figure 19.2.3(p.133) below.

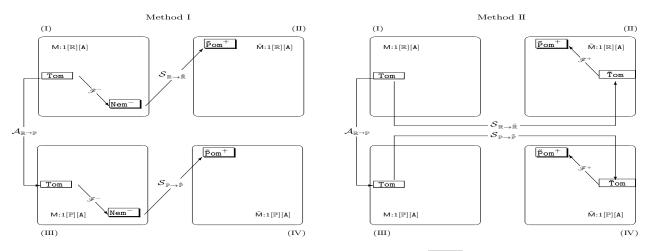


Figure 19.2.3: Two methods to derive Pom<sup>+</sup>

The above two methods can be restated as follows.

Method I. Combination use of the negative restriction ( $\mathscr{F}^-$ ) and diagonal symmetry theorem ( $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}/\mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}$ ) Derivation from applying  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}/\mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}$  to Nem $^-$  derived by applying  $\mathscr{F}^-$  to Tom on  $\mathscr{F}$ ,

$$\begin{split} & \tilde{\mathtt{P}}\mathtt{om}^+ = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} [\mathtt{Nem}^-] = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} [\mathscr{F}^-[\mathtt{Tom}]] = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} \mathscr{F}^-[\mathtt{Tom}], \\ & \tilde{\mathtt{P}}\mathtt{om}^+ = \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}} [\mathtt{Nem}^-] = \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}} [\mathscr{F}^-[\mathtt{Tom}]] = \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}} \mathscr{F}^-[\mathtt{Tom}]. \end{split}$$

Method II. Combination use of the symmetry theorem  $(S_{\mathbb{R}\to\tilde{\mathbb{R}}}/S_{\mathbb{P}\to\tilde{\mathbb{P}}})$  and positive restriction  $(\mathscr{F}^+)$  Derivation from applying  $\mathscr{F}^+$  to  $\tilde{\mathsf{T}}$ om derived by applying  $S_{\mathbb{R}\to\tilde{\mathbb{R}}}/S_{\mathbb{P}\to\tilde{\mathbb{P}}}$  to  $\mathsf{T}$ om,

$$\begin{split} \tilde{\mathbf{P}} \mathbf{om}^+ &= \mathscr{F}^+[\tilde{\mathbf{T}} \mathbf{om}] = \mathscr{F}^+[\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathbf{T} \mathbf{om}]] = \mathscr{F}^+\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathbf{T} \mathbf{om}], \\ \tilde{\mathbf{P}} \mathbf{om}^+ &= \mathscr{F}^+[\tilde{\mathbf{T}} \mathbf{om}] = \mathscr{F}^+[\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}[\mathbf{T} \mathbf{om}]] = \mathscr{F}^+\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}[\mathbf{T} \mathbf{om}]. \end{split}$$

Method I is recommended in the sense that it is simpler than Method II; however, it is often efficient to use the two methods for purposes of the analyses.

#### 19.3 Model with $\mathbb{P}$ -mechanism

Closely looking at the reasoning of discussions for model with  $\mathbb{R}$ -mechanism (see Section 19.1(p.129)), one immediately see that these discussions are not directly related to the price mechanism employed there. This fact implies that they hold also for  $\mathbb{P}$ -mechanism, hence it follows that all of Theorems 19.1.2(p.131)-19.1.7(p.131) hold also for  $\mathbb{P}$ -mechanism. In other words, the diagonal symmetry holds also between  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}$  and  $\mathscr{A}\{M:1[\mathbb{P}][A]\}$ .

**Theorem 19.3.1** Let  $\mathscr{A}\{M:1[\mathbb{P}][A]^+\}$  holds on  $\mathscr{P}\times\mathscr{F}^+$ . Then,  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]^-\}$  holds on  $\mathscr{P}\times\mathscr{F}^-$  where

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]^{-}\} = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]^{+}\}]. \quad \Box$$
 (19.3.1)

**Theorem 19.3.2** Let  $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]^{\pm}\}\ holds\ on\ \mathscr{P}\times\mathscr{F}^{\pm}.$  Then,  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]^{\pm}\}\ holds\ on\ \mathscr{P}\times\mathscr{F}^{\pm}\ where$ 

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]^{\pm}\} = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]^{\pm}\}]. \quad \Box$$
 (19.3.2)

**Theorem 19.3.3** Let  $\mathscr{A}\{M:1[\mathbb{P}][A]^-\}$  holds on  $\mathscr{P}\times\mathscr{F}^-$ . Then,  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]^+\}$  holds on  $\mathscr{P}\times\mathscr{F}^+$  where

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]^{+}\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]^{-}\}]. \quad \Box$$
(19.3.3)

Below are the inverses of the above three theorems.

**Theorem 19.3.4** Let  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]^-\}$  holds on  $\mathscr{P}\times\mathscr{F}^-$ . Then,  $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathbb{A}]^+\}$  holds on  $\mathscr{P}\times\mathscr{F}^+$  where

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]^{+}\} = \mathcal{S}_{\tilde{\mathbb{P}}_{\rightarrow\mathbb{P}}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]^{-}\}]. \quad \Box$$

$$(19.3.4)$$

**Theorem 19.3.5** Let  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]^{\pm}\}\ holds\ on\ \mathscr{P}\times\mathscr{F}^{\pm}\ .$  Then,  $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]^{\pm}\}\ holds\ on\ \mathscr{P}\times\mathscr{F}^{\pm}\ where$ 

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]^{\pm}\} = \mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]^{\pm}\}]. \quad \Box$$

$$(19.3.5)$$

 $\textbf{Theorem 19.3.6} \quad \textit{Let } \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]^+\} \ \textit{holds on } \mathscr{P} \times \mathscr{F}^+ \ \textit{. Then, } \mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]^-\} \ \textit{holds on } \mathscr{P} \times \mathscr{F}^- \ \textit{where } \mathsf{M} \in \mathbb{P}[\mathtt{A}]^+\}$ 

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]^{-}\} = \mathcal{S}_{\tilde{\mathbb{D}} \to \mathbb{P}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]^{+}\}]. \quad \Box$$

$$(19.3.6)$$

Thus, we see that (19.3.1(p.134))-(19.3.3(p.134)) and (19.3.4(p.134))-(19.3.6(p.134)) hold also for  $\mathbb{P}$ -mechanism, hence we have

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}^{-} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]^{+}\}],\tag{19.3.7}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]\}^{\pm} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]^{\pm}\}],\tag{19.3.8}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]\}^{+} = \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]^{-}\}],\tag{19.3.9}$$

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]\}^{+} = \mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]^{-}\}],\tag{19.3.10}$$

$$\mathscr{A}\{\mathsf{M}{:}1[\mathbb{P}][\mathtt{A}]\}^{\pm} = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}{:}1[\mathbb{P}][\mathtt{A}]^{\pm}\}], \tag{19.3.11}$$

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}^{-} = \mathcal{S}_{\tilde{\mathtt{M}} \to \mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]^{+}\}]. \tag{19.3.12}$$

Then we have following corollary (see Corollary 19.1.1(p.132)).

Corollary 19.3.1 (diagonal symmetry) vspace-1.5em

$$\leftrightarrow \text{ (b)} \quad \mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]^{\pm}\} \quad \sim \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]^{\pm}\} \tag{19.3.14}$$

$$\land (a) \quad \mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathbb{A}]^+\} \ \mathsf{d} \sim \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]^-\}$$
 (19.3.15)

Exercise 19.3.1

 $\begin{tabular}{ll} $\swarrow$ (c) & \textit{Confirm by yourself that } (19.3.10 (p.134)) & \textit{holds in fact by comparing Pom } 18.5.6 (p.123) & \textit{and Nem } 18.5.8 (p.123) \\ \end{tabular} .$ 

 $\leftarrow \text{ (b)} \quad \textit{Confirm by yourself that (19.3.11(p.134)) holds in fact by comparing Mim 18.5.6(p.122)} \quad \textit{and Mim 18.5.8(p.124)}.$ 

(a) Confirm by yourself that (19.3.12(p.134)) holds in fact by comparing Nem 18.5.6(p.122) and Pom 18.5.8(p.125).

**Remark 19.3.1** (19.3.14(p.134)) implies that the symmetrical relationship on  $\mathscr{F}$  is inherited on  $\mathscr{F}^{\pm}$ .  $\square$ 

## Conclusions of Part 2 (Integrated-Theory)

Below let us summarize the whole discussions over Chaps. 11(p.55) - 19(p.129).

- $\overline{\overline{C}}$ 1. **Preliminary** (see Chaps. 11(p.55) and 12(p.61))
  - As a preliminary step in constructing the integrated-theory, we first proved the properties of underlying functions (see Chap. 11(p.55)). Using these properties, we then established the assertion system  $\mathscr{A}\{M:1[\mathbb{R}][A]\}$  (see Chap. 12(p.61)).
- $\overline{\mathsf{C}}2$ . Symmetry theorem  $(\mathbb{R} \leftrightarrow \widetilde{\mathbb{R}})$  (see Chap. 13(p.69))

The concept of symmetry between a selling model and a buying model was first vaguely inspired from the pattern of the *yin-yang principle* in an ancient Chinese philosophy. This rather superstitious and shaky concept was mathematically formalized by the introduction of the *reflection operation*  $\mathcal{R}$  (see Section 13.1.1(p.69) and Step 2 (p.75)). After that, through about twenty years of trial-and-errors, this concept led us to the *correspondence replacement operation*  $\mathcal{C}_{\mathbb{R}}$  (see Lemma 13.3.1(p.72) and Step 3 (p.75)), and then to *identity replacement operation*  $\mathcal{I}_{\mathbb{R}}$  (see Lemma 13.3.3(p.73) and Step 4 (p.76)). Finally, the above three operations were compiled into a single operation  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}=\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}$  (see (13.5.30(p.77))), called the *symmetry transformation operation*, yielding Theorem 13.5.1(p.80) (*symmetry theorem*), which derives  $\mathscr{A}\{\tilde{\mathbb{M}}:1[\mathbb{R}][A]\}$  by applying  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}$  to  $\mathscr{A}\{\mathbb{M}:1[\mathbb{R}][A]\}$  in Tom's 12.2.1(p.61) and 12.2.2(p.62).

- $\overline{\overline{\mathsf{C}}}$ 3. Analogy theorem ( $\mathbb{R} \leftrightarrow \mathbb{P}$ ) (see Chap. 14(p.89))
  - In the earlier stage of this study, we did not anticipate at all that there would be a relation between  $\mathbb{R}$ -mechanism-model and  $\mathbb{P}$ -mechanism-model. However, as we proceeded with analyses of both models, we gradually noticed similarities in the procedures for treating both models. This realization led us, as if solving the *jigsaw puzzle*, to the existence of an analogous relation between the two models. This recognition eventually was materialized by the proof of the two lemmas, Lemmas 11.1.1(p.55) and 14.2.1(p.93), which are finally combined into the analogy replacement operation  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  (see (14.2.1(p.93))). This finding produced Theorem 14.3.1(p.97) (analogy theorem), which combines the above two models in a manner that  $\mathscr{A}\{M:1[\mathbb{P}][A]\}$  can be derived by applying the operation to  $\mathscr{A}\{M:1[\mathbb{R}][A]\}$ .
- $\overline{\overline{\mathsf{C}}}4$ . Symmetry theorem ( $\mathbb{P} \leftrightarrow \widetilde{\mathbb{P}}$ ) (see Chap. 15(p.101))

While the symmetry theorem in  $\overline{\overline{C}}2(p.135)$  is for  $\mathbb{R}$ -mechanism-model, we relatively easily succeeded in obtaining the symmetry theorem for  $\mathbb{P}$ -mechanism-model with *symmetry transformation operation*  $\mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}$  (see (15.5.3(p.105))). By applying the operation to  $\mathscr{A}\{M:1[\mathbb{P}][A]\}$  we can obtain  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}$  (see Theorem 15.5.1(p.106)).

 $\overline{\mathsf{C}}$ 5. **Analogy theorem**  $(\widetilde{\mathbb{R}} \leftrightarrow \widetilde{\mathbb{P}})$  (see Chap. 16(p.111))

This theorem (see Theorem 16.2.1(p.112)) was not directly derived but was obtained as a result of combining the three results derived in  $\overline{\overline{C}}2(p.135)$  -  $\overline{\overline{C}}4(p.135)$ .

 $\overline{\mathsf{C}}6$ . Integrated-theory (see Chap. 17(p.115))

The highly distinguishing results in the present paper is the successful construction of the integrated-theory (see Motive 2(p.3) and Chap. 17(p.115)), which can systematically and comprehensively analyze all models included in a given structured-unit-of-models (see Section 3.3(p.16)). The theory consists of the two symmetry theorems (see Theorems 13.5.1(p.80) and 15.5.1(p.106)) and the two analogy theorems (see Theorems 14.3.1(p.97) and 16.2.1(p.112)). The former two combines the asset selling problem and the asset buying problem with the symmetrical relation and the latter two combines the asset trading problem with the  $\mathbb{R}$ -mechanism and the asset trading problem with the  $\mathbb{R}$ -mechanism with the analogouse relation. The integrated-theory plays a decisively important role in the analysis of models in the sense that it provides an absolutely necessary methodology for treating not only all models in the present paper but also all variations of these models (see Chap. 5(p.23) and Section 32.1(p.297)) which will be dealt with in the future.

C7. Collapse of symmetry and analogy (see Chap. 18(p.117))

Here, let us again note that the integrated-theory can be constructed under the premise that the price  $\xi$ , whether  $\mathbb{R}$ -price or  $\mathbb{P}$ -price, is defined on the total market  $\mathscr{F}$  (see (18.1.1(p.117))). Through the integration-theory we clarified that  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}$  (buying model with  $\mathbb{R}$ -mechanism) can be derived so as to be *symmetrical* to  $\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}$  (selling model with  $\mathbb{R}$ -mechanism) and that  $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}$  (selling problem with  $\mathbb{P}$ -mechanism) can be derived so as to be *analogous* to

 $\mathscr{A}\{M:1[\mathbb{R}][A]\}$  (selling problem  $\mathbb{R}$ -mechanism). However, since trading on the normal market in the real world is usually conducted on the positive market  $\mathscr{F}^+$  (see (18.2.2(p.117))), it is an open question whether symmetry and analogy on  $\mathscr{F}$  are inherited by  $\mathscr{F}^+$  (see Chap. 18(p.117)). To approach this problem, in this paper, we employ the methodology of restricting results obtained on  $\mathscr{F}$  to  $\mathscr{F}^+$  by using Lemmas 18.4.1(p.118) - 18.4.3(p.118). Through this methodology, we will show in C2(p.139) and C3(p.140) that the symmetrical relation and the analogouse relation can strikingly collapse on  $\mathscr{F}^+$ .

#### $\overline{\overline{C}}8$ . Diagonal symmetry (see Chap. 19(p.129))

As seen in  $\overline{\overline{C7}}(p.135)$ , symmetry analogy are not *not always* inherited on  $\mathscr{F}^+$  between a selling-problem and a buying problem. However, we verified in Chap. 19(p.129) that symmetry and analogy are *always* inherited between a selling-problem on  $\mathscr{F}^-$  and a buying problem on  $\mathscr{F}^+$ . In Section 19.2.3(p.133) we demonstrated that this result sometimes plays a very interesting role in the analyses of models on restricted markets.

#### $\overline{\mathsf{C}}9$ . Summary of operations

For convenience of reference, let us summarize all operations depicted in Figure 17.1.1(p.115) below.

$$(13.8.21(p.86)) \rightarrow \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}} = \begin{cases} b, \mu, a, x_{\tilde{L}}, x_{\tilde{\kappa}}, s_{\tilde{\mathcal{L}}}, \tilde{\kappa}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_t \\ \downarrow \\ a, \mu, b, x_L, x_K, s_{\mathcal{L}}, \kappa, T, L, K, \mathcal{L}, V_t \end{cases}.$$

$$(20.0.2)$$

$$(15.5.3(\text{p.105})) \rightarrow \qquad \mathcal{S}_{\mathbb{P} \rightarrow \tilde{\mathbb{P}}} = \begin{cases} a^{\star}, a, b, x_{L}, x_{K}, \kappa, s_{\mathcal{L}}, T, L, K, \mathcal{L}, V_{t} \\ \downarrow \quad \downarrow \\ b^{\star}, b, a, x_{\tilde{L}}, x_{\tilde{K}}, \tilde{\kappa}, s_{\tilde{\mathcal{L}}}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_{t} \end{cases} . \tag{20.0.3}$$

$$(15.5.11(\text{p.106})) \rightarrow \qquad \mathcal{S}_{\tilde{\mathbb{P}} \rightarrow \mathbb{P}} = \begin{cases} b^{\star}, b, a, x_{\tilde{L}}, x_{\tilde{K}}, \tilde{\kappa}, s_{\tilde{\mathcal{L}}}, \tilde{T}, \tilde{L}, \tilde{K}, \tilde{\mathcal{L}}, V_{t} \\ \downarrow \\ a^{\star}, a, b, x_{L}, x_{K}, \kappa, s_{\mathcal{L}}, T, L, K, \mathcal{L}, V_{t} \end{cases}.$$

$$(20.0.4)$$

$$(14.2.1(p.33)) \rightarrow \mathcal{A}_{\mathbb{R} \to \mathbb{P}} = \{a \to a^{\star}, \ \mu \to a\}. \tag{20.0.5}$$

$$(14.3.5(p.98)) \rightarrow \mathcal{A}_{\mathbb{P} \to \mathbb{R}} = \{ a^{\star} \to a, \ a \to \mu \}. \tag{20.0.6}$$

$$(16.3.2(\text{p.113})) \rightarrow \mathcal{A}_{\tilde{\mathbb{R}} \to \tilde{\mathbb{P}}} = \{b \to b^{\star}, \ \mu \to b\} = \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}} \mathcal{A}_{\mathbb{R} \to \mathbb{P}} \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}. \tag{20.0.7}$$

$$(16.3.3(\text{p.113})) \rightarrow \mathcal{A}_{\tilde{\mathbb{p}}_{\rightarrow}\tilde{\mathbb{p}}} = \{b^{\star} \rightarrow b, \ b \rightarrow \mu\} = \mathcal{S}_{\mathbb{p}_{\rightarrow}\tilde{\mathbb{p}}} \mathcal{A}_{\mathbb{P} \rightarrow \mathbb{R}} \mathcal{S}_{\tilde{\mathbb{p}}_{\rightarrow}\mathbb{p}}. \tag{20.0.8}$$

# Part 3

## No-Recall-Model

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## Analysis of Model 1

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### $\mathbf{21.1} \quad \mathbf{Search-Allowed-Model 1:} \ \mathcal{Q}\{\mathsf{M}:1[\mathtt{A}]\} = \{\mathsf{M}:1[\mathtt{R}][\mathtt{A}], \tilde{\mathsf{M}}:1[\mathtt{R}][\mathtt{A}], \tilde{\mathsf{M}}:1[\mathtt{P}][\mathtt{A}], \tilde{\mathsf{M}}:1[\mathtt{P}][\mathtt{A}]\}$

All analyses of the search-Allowed-model 1 already completed in Part 2(p51). Below, let us summarize the whole conclusions obtained there.

#### 21.1.1 Conclusion 1 (Search-Allowed-Model 1)

#### C1. Mental Conflict

On  $\mathscr{F}$ , for any  $\beta \leq 1$  and  $s \geq 0$  we have:

- a. The opt- $\mathbb{R}$ -price  $V_t$  in M:1[ $\mathbb{R}$ ][A] (selling model) is nondecreasing in t as in Figure 8.4.1(p.48) (I) (see Tom's 12.2.1(p.61) (a) and 12.2.2(p.62) (a)), hence we have the normal conflict (see Remark 8.4.1(p.48)).
- b. The opt- $\mathbb{P}$ -price  $z_t$  in M:1[ $\mathbb{P}$ ][A] (selling model) is nondecreasing in t as in Figure 8.4.1(p.48) (I) (see Lemma 14.7.1(p.99)), hence we have the normal conflict (see Remark 8.4.1(p.48)).
- c. The opt- $\mathbb{R}$ -price  $V_t$  in  $\tilde{M}:1[\mathbb{R}][A]$  (buying model) is nonincreasing in t as in Figure 8.4.1(p.48) (II) (see Tom's 13.7.1(p.83) (a) and 13.7.2(p.84) (a)), hence we have the normal conflict (see Remark 8.4.1(p.48)).
- d. The opt- $\mathbb{P}$ -price  $z_t$  in M:1[ $\mathbb{P}$ ][A] (buying model) is nonincreasing in t as in Figure 8.4.1(p.48) (II) (see Lemma 15.8.1(p.109)), hence we have the normal conflict (see Remark 8.4.1(p.48)).

The above results can be summarized as below.

A. On  $\mathscr{F}$ , for any  $\beta \leq 1$  and  $s \geq 0$ , whether selling problem or buying problem and whether  $\mathbb{R}$ -mechanism-model or  $\mathbb{P}$ -mechanism-model, we have the normal mental conflict, which coincides with *expectations* in *Examples* 1.3.1(p.5) - 1.3.4(p.6).

#### C2. Symmetry

- a. On  $\mathscr{F}^+$  we have:
  - 1. Let  $\beta = 1$  and s = 0. Then we have:

```
Pom 18.5.3(p.120) \sim Pom 18.5.1(p.118) (\mathscr{A}\{\tilde{M}:1[\mathbb{R}][A]\}^+ \sim \mathscr{A}\{M:1[\mathbb{R}][A]\}^+), Pom 18.5.7(p.123) \sim Pom 18.5.5(p.122) (\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}^+ \sim \mathscr{A}\{M:1[\mathbb{P}][A]\}^+).
```

2. Let  $\beta < 1$  or s > 0. Then we have:

Pom 18.5.4(p.120) 
$$\rightsquigarrow$$
 Pom 18.5.2(p.119)  $(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}^+ \rightsquigarrow \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}^+) \cdots (s^1),$   
Pom 18.5.8(p.123)  $\rightsquigarrow$  Pom 18.5.6(p.122)  $(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}^+ \rightsquigarrow \mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}^+) \cdots (s^2).$ 

- b. On  $\mathscr{F}^{\pm}$ , we have:
  - 1. Let  $\beta = 1$  and s = 0. Then we have:

$$\begin{array}{ll} \text{Mim } 18.5.3 \text{(p.121)} & \sim \text{Mim } 18.5.1 \text{(p.119)} & (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}^{\pm} \sim \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}^{\pm}), \\ \text{Mim } 18.5.7 \text{(p.124)} & \sim \text{Mim } 18.5.5 \text{(p.122)} & (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}^{\pm} \sim \mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}^{\pm}). \end{array}$$

2. Let  $\beta < 1$  or s > 0. Then we have:

$$\begin{array}{ll} \text{Mim } 18.5.4 \text{(p.121)} & \sim \text{Mim } 18.5.2 \text{(p.119)} & (\mathscr{A}\{\tilde{\mathsf{M}}{:}1[\mathbb{R}][\mathtt{A}]\}^{\pm} \sim \mathscr{A}\{\mathsf{M}{:}1[\mathbb{R}][\mathtt{A}]\}^{\pm}), \\ \text{Mim } 18.5.8 \text{(p.124)} & \sim \text{Mim } 18.5.6 \text{(p.122)} & (\mathscr{A}\{\tilde{\mathsf{M}}{:}1[\mathbb{P}][\mathtt{A}]\}^{\pm} \sim \mathscr{A}\{\mathsf{M}{:}1[\mathbb{P}][\mathtt{A}]\}^{\pm}). \end{array}$$

- c. On  $\mathscr{F}^-$ , we have:
  - 1. Let  $\beta = 1$  and s = 0. Then we have:

Nem 18.5.3(p.121) 
$$\sim$$
 Nem 18.5.1(p.120)  $(\mathscr{A}\{\tilde{M}:1[\mathbb{R}][A]\}^- \sim \mathscr{A}\{M:1[\mathbb{R}][A]\}^-)$ ,  
Nem 18.5.7(p.125)  $\sim$  Nem 18.5.5(p.123)  $(\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}^- \sim \mathscr{A}\{M:1[\mathbb{P}][A]\}^-)$ .

2. Let  $\beta < 1$  or s > 0. Then we have:

Nem 
$$18.5.4$$
(p.121)  $\wedge$  Nem  $18.5.2$ (p.120)  $(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}^- \wedge \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}^-) \cdots (s^3),$   
Nem  $18.5.8$ (p.125)  $\wedge$  Nem  $18.5.6$ (p.123)  $(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathtt{A}]\}^- \wedge \mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}^-) \cdots (s^4).$ 

The above results can be summarized as below.

- A. On  $\mathscr{F}^{\pm}$ , for any  $\beta \leq 1$  and  $s \geq 0$ , the symmetry is inherited (see C2b(p.139)).
- B. On  $\mathscr{F}^+$  and  $\mathscr{F}^-$ , if  $\beta=1$  and s=0, the symmetry is inherited (see C2a1(p.139) /C2c1(p.140)).
- C. On  $\mathscr{F}^+$  and  $\mathscr{F}^-$ , if  $\beta < 1$  or s > 0, the symmetry collapses (see  $(s^1)/(s^2)/(s^3)/(s^4)$ ).
- C3. Analogy
  - a. On  $\mathscr{F}^+$  we have:
    - 1. Let  $\beta = 1$  and s = 0. Then we have:

$$\begin{array}{lll} \text{Pom } 18.5.5 \text{(p.122)} &\bowtie \text{Pom } 18.5.1 \text{(p.118)} & (\mathscr{A}\{M:1[\mathbb{P}][A]\}^+ \bowtie \mathscr{A}\{M:1[\mathbb{R}][A]\}^+), \\ \text{Pom } 18.5.7 \text{(p.123)} &\bowtie \text{Pom } 18.5.3 \text{(p.120)} & (\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}^+ \bowtie \mathscr{A}\{\tilde{M}:1[\mathbb{R}][A]\}^+). \end{array}$$

2. Let  $\beta < 1$  or s > 0. Then we have:

Pom 
$$18.5.6$$
(p.122)  $\bowtie$  Pom  $18.5.2$ (p.119)  $(\mathscr{A}\{M:1[\mathbb{P}][A]\}^+ \bowtie \mathscr{A}\{M:1[\mathbb{R}][A]\}^+) \cdots (a^1)$ , Pom  $18.5.8$ (p.123)  $\bowtie$  Pom  $18.5.4$ (p.120)  $(\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}^+ \bowtie \mathscr{A}\{\tilde{M}:1[\mathbb{R}][A]\}^+)$ .

- b. On  $\mathscr{F}^{\pm}$ , we have:
  - 1. Let  $\beta = 1$  and s = 0. Then we have:

$$\begin{array}{lll} \text{Mim } 18.5.5 \text{(p.122)} & \bowtie \text{Mim } 18.5.1 \text{(p.119)} & (\mathscr{A}\{\text{M}:1[\mathbb{P}][\mathbf{A}]\}^{\pm} & \bowtie \mathscr{A}\{\text{M}:1[\mathbb{R}][\mathbf{A}]\}^{\pm}), \\ \text{Mim } 18.5.7 \text{(p.124)} & \bowtie \text{Mim } 18.5.3 \text{(p.121)} & (\mathscr{A}\{\tilde{\mathbf{M}}:1[\mathbb{P}][\mathbf{A}]\}^{\pm} & \bowtie \mathscr{A}\{\tilde{\mathbf{M}}:1[\mathbb{R}][\mathbf{A}]\}^{\pm}). \end{array}$$

2. Let  $\beta < 1$  or s > 0. Then we have:

$$\begin{array}{ll} \text{Mim } 18.5.6 \text{(p.122)} & \bowtie \text{Mim } 18.5.2 \text{(p.119)} & (\mathscr{A}\{\text{M}:1[\mathbb{P}][\mathbf{A}]\}^{\pm} \bowtie \mathscr{A}\{\text{M}:1[\mathbb{R}][\mathbf{A}]\}^{\pm}), \\ \text{Mim } 18.5.8 \text{(p.124)} & \bowtie \text{Mim } 18.5.4 \text{(p.121)} & (\mathscr{A}\{\tilde{\mathbf{M}}:1[\mathbb{P}][\mathbf{A}]\}^{\pm} \bowtie \mathscr{A}\{\tilde{\mathbf{M}}:1[\mathbb{R}][\mathbf{A}]\}^{\pm}). \end{array}$$

- c. On  $\mathscr{F}^-$ , we have:
  - 1. Let  $\beta = 1$  and s = 0. Then we have:

2. Let  $\beta < 1$  or s > 0. Then we have:

Nem 
$$18.5.6$$
(p.123)  $\bowtie$  Nem  $18.5.2$ (p.120)  $(\mathscr{A}\{M:1[\mathbb{P}][A]\}^- \bowtie \mathscr{A}\{M:1[\mathbb{R}][A]\}^-),$   
Nem  $18.5.8$ (p.125)  $\bowtie$  Nem  $18.5.4$ (p.121)  $(\mathscr{A}\{\tilde{M}:1[\mathbb{P}][A]\}^- \bowtie \mathscr{A}\{\tilde{M}:1[\mathbb{R}][A]\}^-)\cdots(a^2).$ 

The above results can be summarized as below.

- A. On  $\mathscr{F}^{\pm}$ , for any  $\beta \leq 1$  and  $s \geq 0$ , the analogy are inherited (see C2b(p.139)).
- B. On  $\mathscr{F}^+$  and  $\mathscr{F}^-$ , if  $\beta = 1$  and s = 0, the analogy is inherited (see C3a1(p.140) /C3c1(p.140)).
- C. On  $\mathscr{F}^+$  and  $\mathscr{F}^-$ , if  $\beta < 1$  or s > 0, the analogy partially collapses (see  $(a^1)/(a^2)$ ).
- C4. Optimal Initiation Time (OIT)
  - a. Let  $\beta = 1$  and s = 0. Then, from

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\begin{array}{l} {\bf Pom} \ 18.5.1 ({\rm p.118}) \ , \ {\bf Mim} \ 18.5.1 ({\rm p.119}) \ , \ {\bf Nem} \ 18.5.1 ({\rm p.120}) \ , \\ {\bf Pom} \ 18.5.3 ({\rm p.120}) \ , \ {\bf Mim} \ 18.5.3 ({\rm p.121}) \ , \ {\bf Nem} \ 18.5.3 ({\rm p.121}) \ , \\ {\bf Pom} \ 18.5.5 ({\rm p.122}) \ , \ {\bf Mim} \ 18.5.5 ({\rm p.122}) \ , \ {\bf Nem} \ 18.5.5 ({\rm p.123}) \ , \\ {\bf Pom} \ 18.5.7 ({\rm p.123}) \ , \ {\bf Mim} \ 18.5.7 ({\rm p.124}) \ , \ {\bf Nem} \ 18.5.7 ({\rm p.125}) \end{array}
```

we obtain Table 21.1.1(p.141) below (the symbol "o" in the table below represents "possible"):

Table 21.1.1: Possible OIT ( $\beta = 1$  and s = 0)

	<b>F</b> +	ℱ±	<i>F</i> -
$\odot$ dOITs $_{ au}\langle  au  angle$			
$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $			
$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	0	0	0
$\odot$ nd0IT $_{ au}\langle t_{ au}^{ullet} angle$ $_{\parallel}$ $\bigcirc$ $_{\parallel}$			
$\odot$ nd0IT $_{\tau}\langle t_{\tau}^{\bullet}\rangle$ $_{\vartriangle}$ $\bigcirc$ $_{\vartriangle}$			
$\odot$ ndOIT $_{\tau}\langle t_{\tau}^{\bullet}\rangle$			
$lacktriangledown$ d0ITd $_{ au}\langle 0  angle$ $\parallel$			
$\bullet$ dOITd $_{\tau}\langle 0 \rangle$ $_{\Delta}$ $\bullet$			
$\bullet$ dOITd $_{\tau}\langle 0 \rangle$ $\bullet$			

- A. Only  $\mathfrak{S}_{\blacktriangle}$  is possible on  $\mathscr{F}^+$ ,  $\mathscr{F}^{\pm}$ , and  $\mathscr{F}^-$ .
- b. Let  $\beta < 1$  or s > 0. Then, from

Pom 18.5.2(p.119), Mim 18.5.2(p.119), Nem 18.5.2(p.120),

Pom  $18.5.4 (\text{p.120}) \,, \,\, \text{Mim} \,\, 18.5.4 (\text{p.121}) \,, \,\, \text{Nem} \,\, 18.5.4 (\text{p.121}) \,,$ 

Pom 18.5.6(p.122), Mim 18.5.6(p.122), Nem 18.5.6(p.123),

Pom 18.5.8 (p.123), Mim 18.5.8 (p.124), Nem 18.5.8 (p.125)

we obtain Table 21.1.2(p.141) below:

Table 21.1.2: Possible OIT  $(\beta < 1 \text{ or } s > 0)$ 

	<i>F</i> +	$\mathscr{F}^\pm$	<i>F</i> -
$\  \  \  \  \  \  \  \  \  \  \  \  \  $			
$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $			
$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	0	0	0
$\odot$ ndOIT $_{ au}\langle t_{ au}^{ullet} angle$ $_{\parallel}$	0	0	0
$\odot$ ndOIT $_{ au}\langle t_{ au}^{ullet} angle$ $_{ riangle}$			
$\odot$ ndOIT $_{ au}\langle t_{ au}^{ullet} angle$ $_{ullet}$			
$lacktriangledown$ d0ITd $_{ au}\langle 0 angle$ $\parallel$	0	0	0
$lacktriangledown$ d0ITd $_{ au}\langle 0  angle$ $\Delta$			
$lacktriangledown$ doith $_{ au}\langle 0 angle$ , $lacktriangledown$			

A. Only  $\mathfrak{S}_{\blacktriangle}$ ,  $\mathfrak{O}_{\parallel}$ , and  $\mathfrak{d}_{\parallel}$  are possible on  $\mathscr{F}^+$ ,  $\mathscr{F}^{\pm}$ , and  $\mathscr{F}^-$ .

The table below is the list of the occurrence percents of  $\bigcirc$ ,  $\bigcirc$ , and  $\bigcirc$  on  $\mathscr{F}$  appearing in  $\blacksquare$  Tom 12.2.1(p.61) and  $\blacksquare$  Tom 12.2.2(p.62) (see Def. 13.7.1(p.83)).

Table 21.1.3: Occurrence percents of (s), (o), and (d) on  $\mathscr{F}$ 

	(S)			0			•		
50.0 % / 5			10.0 % / 1			40.0 % / 4			
® <sub>∥</sub>	S	S <sub>▲</sub>	<b>⊚</b> ∥	<ul><li>Θ<sub>Δ</sub></li></ul>	<b>O</b> _	<b>1</b>	<b>a</b>	<b>Q</b> <sup>v</sup>	
_	×	possible	possible	×	×	possible	×	×	
-%/-	0.0 %/0	50.0 %/5	10.0 %/1	0.0%/0	0.0%/0	40.0 %/4	0.0 %/0	0.0 %/0	

# ${\sf C5.} \quad {\sf Null-Time-Zone} \ {\sf and} \ {\sf Deadline-Engulfing}$

From Table 21.1.3(p.141) above we see that on  $\mathscr{F}$ :

- a. See Remark 8.2.2(p.45) for the noteworthy implication of the symbol  $\blacktriangle$  (strict optimality).
- b. As a whole, we have (§), (o), and (d) at 50.0%, 10.0%, and 40.0% respectively where
  - 1.  $\bigcirc$  cannot be defined due to Remark 8.2.3(p.45).
  - 2.  $\bigcirc_{\parallel}$  is possible (10.0 %).
  - 3.  $\mathbf{d}_{\parallel}$  is possible (40.0%).
  - 4.  $\mathfrak{S}_{\Delta}$  never occur (0.0%).

- 5.  $\bigcirc_{\vartriangle}$  never occur (0.0%).
- 6.  $\mathbf{d}_{\Delta}$  never occur (0.0%).
- 7. (s) is possible (50.0%).
- 8.  $\bigcirc$  never occur (0.0%).
- 9.  $\mathbf{d}_{\mathbf{A}}$  never occur (0.0%).

From the above results we see that on  $\mathscr{F}$ :

- A.  $\odot$  and  $\odot$  causing the null-time-zone are possible at 50.0% (= 10.0% + 40.0%).
- B.  $\bigcirc_{\blacktriangle}$  strictly causing the null-time-zone is impossible (0.0%).
- C. **1** Strictly causing the null-time-zone is impossible (0.0%), i.e., the deadline-engulfing is impossible.

# C6. Diagonal symmetry

See Corollaries 19.1.1(p.132) and 19.3.1(p.134).

# $\mathbf{21.2} \quad \mathbf{Search-Enforced-Model \ 1:} \ \mathcal{Q}\{\mathsf{M}:1[\mathsf{E}]\} = \{\mathsf{M}:1[\mathsf{R}][\mathsf{E}], \tilde{\mathsf{M}}:1[\mathsf{R}][\mathsf{E}], \tilde{\mathsf{M}}:1[\mathsf{P}][\mathsf{E}], \tilde{\mathsf{M}}:1[\mathsf{P}][\mathsf{E}]\}$

# 21.2.1 Preliminary

As ones corresponding to Theorems 13.5.1(p.80), 14.3.1(p.97), and 15.5.1(p.106), let us consider the following three theorems:

Theorem 21.2.1 (symmetry 
$$[\mathbb{R} \to \mathbb{R}]$$
) Let  $\mathscr{A}[M:1[\mathbb{R}][E]]$  holds on  $\mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}[\tilde{M}:1[\mathbb{R}][E]]$  holds on  $\mathscr{P} \times \mathscr{F}$  where 
$$\mathscr{A}[\tilde{M}:1[\mathbb{R}][E]] = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathscr{A}[M:1[\mathbb{R}][E]]]. \quad \Box$$
 (21.2.1)

 $\textbf{Theorem 21.2.2 (analogy}[\mathbb{R} \rightarrow \mathbb{P})]) \quad \textit{Let } \mathscr{A}\{M:1[\mathbb{R}][E]\} \textit{ holds on } \mathscr{P} \times \mathscr{F}. \textit{ Then } \mathscr{A}\{M:1[\mathbb{P}][E]\} \textit{holds on } \mathscr{P} \times \mathscr{F} \textit{ where } \mathbb{R} \cap \mathbb{R}$ 

$$\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]\} = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}]. \quad \Box$$
 (21.2.2)

Theorem 21.2.3 (symmetry  $[\mathbb{P} \to \mathbb{P}]$ ) Let  $\mathscr{A}\{M:1[\mathbb{P}][E]\}$  holds on  $\mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][E]\}$  holds on  $\mathscr{P} \times \mathscr{F}$  where  $\mathscr{A}\{\tilde{M}:1[\mathbb{P}][E]\} = \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}[\mathscr{A}\{M:1[\mathbb{P}][E]\}]. \quad \Box 9039$  (21.2.3)

In order for the above three theorems to hold, the following three relations must be satisfied:

$$SOE\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[SOE\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}], \tag{21.2.4}$$

$$SOE\{M:1[\mathbb{P}][E]\} = \mathcal{A}_{\mathbb{R} \to \mathbb{P}}[SOE\{M:1[\mathbb{R}][E]\}], \tag{21.2.5}$$

$$SOE\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]\} = \mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}[SOE\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]\}],\tag{21.2.6}$$

corresponding to  $(13.5.34 \langle p.77 \rangle)$ ,  $(14.2.4 \langle p.93 \rangle)$ , and  $(15.5.4 \langle p.106 \rangle)$ . Then, for the same reason as in Chap.  $16 \langle p.111 \rangle$  it can be shown that the equality

$$SOE\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]\} = \mathcal{A}_{\tilde{\mathbb{P}}_{\sim,\tilde{\mathbb{P}}}}[SOE\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\}] \tag{21.2.7}$$

holds (corresponding to (16.2.7(p.112))) and that we have the following theorem, corresponding to Theorem 16.2.1(p.112)

**Theorem 21.2.4 (analogy**  $[\mathbb{R} \to \mathbb{P}]$ ) Let  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$ . Then  $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$  where

$$\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]\} = \mathcal{A}_{\tilde{\mathbb{R}}\to\tilde{\mathbb{P}}}[\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\}]. \quad \Box$$
 (21.2.8)

In fact, from the comparisons of (I) and (II), of (I) and (III), of (III) and (IV), and of (II) and (IV) in Table 7.4.2(p.41) we can easily show that (21.2.4(p.142)) - (21.2.7(p.142)) hold.

# **21.2.2** M:1[ $\mathbb{R}$ ][E]

## 21.2.2.1 Analysis

To begin with, let us note that

$$\lambda = 1 \tag{21.2.9}$$

is assumed in the model (see A2(p.19)), hence from (11.2.1(p.56)) we have

$$\delta = 1 \tag{21.2.10}$$

- Tom 21.2.1 ( $\mathscr{A}$ {M:1[ $\mathbb{R}$ ][E]}) Let  $\beta = 1$  and s = 0.
- (a)  $V_t$  is nondecreasing in t > 0.
- (b) We have  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ .  $\square$
- *Proof* Let  $\beta = 1$  and s = 0. Then, from (6.1.4(p.25)) we have  $K(x) = T(x) \ge 0 \cdots (1)$  for any x due to Lemma 11.1.1(p.55) (g).
- (a) From (7.4.10(p.41)) with t=2 we have  $V_2=K(V_1)+V_1\geq V_1$  due to (1). Suppose  $V_{t-1}\leq V_t$ . Then, from Lemma 11.2.2(p.57) (e) we have  $V_t\leq K(V_t)+V_t=V_{t+1}$ . Hence, by induction  $V_{t-1}\leq V_t$  for t>1, i.e.,  $V_t$  is nondecreasing in t>0.
  - (b) From (7.4.9(p.41)) we have  $V_1 = \mu < b \cdots (2)$ . Suppose  $V_{t-1} < b$ . Then, from (7.4.10(p.41)) and

Lemma 11.2.2(p.57) (h) we have  $V_t < K(b) + b = T(b) + b = b$  due to (1) and Lemma 11.1.1(p.55) (g). Accordingly, by induction  $V_{t-1} < b$  for t > 1, hence  $L(V_{t-1}) > 0$  for t > 1 due to Lemma 11.2.1(p.57) (d), thus  $L(V_{t-1}) > 0$  for  $\tau \ge t > 1$ . Then, from (7.4.10(p.41)) and from (6.1.8(p.25)) we have  $V_t - \beta V_{t-1} = K(V_{t-1}) + (1-\beta)V_{t-1} = L(V_{t-1}) > 0$  for  $\tau \ge t > 1$  or equivalently  $V_t > \beta V_{t-1}$  for  $\tau \ge t > 1$ . Hence, since  $V_\tau > \beta V_{\tau-1}$ ,  $V_{\tau-1} > \beta V_{\tau-2}$ ,  $\cdots$ ,  $V_2 > \beta V_1$ , we have  $V_\tau > \beta V_{\tau-1} > \beta^2 V_{\tau-2} > \cdots > \beta^{\tau-1} V_1$ , thus  $t_\tau^* = \tau$  for  $\tau > 1$ , i.e.,  $\left[ \otimes \text{dOITs}_{\tau>1} \langle \tau \rangle \right]_{\bullet}$ .

For explanatory simplicity, let us define the statement below:

- Tom 21.2.2 ( $\mathscr{A}$ {M:1[ $\mathbb{R}$ ][E]}) Let  $\beta < 1$  or s > 0.
- (a)  $V_t$  is nondecreasing in t > 0 and converges to a finite  $V = x_K$  as  $t \to \infty$ .
- (b) Let  $\beta \mu \geq b$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle$   $\triangle$ .
- (c) Let  $\beta \mu < b$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $\mu s \leq a$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $\mu-s>a$ . Then  $\boxed{\$ \ dOITs_{\tau>1}\langle \tau \rangle}$  .
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let b>0 ( $\kappa>0$ ). Then  $\boxed{\text{$\otimes$ dOITs}_{\tau>1}\langle\tau\rangle}_{\blacktriangle}$ .
    - ii. Let  $b = 0 ((\kappa = 0))$ .
      - 1. Let  $\beta \mu s \leq a$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta \mu s > a$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$
    - iii. Let  $b < 0 \ (\kappa < 0)$ .
      - 1. Let  $\beta \mu s \leq a$  or  $s_{\mathcal{L}} \leq s$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\Delta}$ .
      - 2. Let  $\beta \mu s > a$  and  $s_{\mathcal{L}} > s$ . Then  $S_2$   $\bigcirc$   $\bigcirc$  is true.  $\rightarrow$   $\bigcirc$
- Proof Let  $\beta < 1$  or s > 0. From (7.4.10(p.41)) and (6.1.8(p.25)), we have  $V_t \beta V_{t-1} = K(V_{t-1}) + (1-\beta)V_{t-1} = L(V_{t-1}) \cdots$  (1) for t > 1. From (7.4.10(p.41)) with t = 2 we have  $V_2 V_1 = K(V_1) \cdots$  (2).
- (a) Note that  $V_1 = \beta \mu s$  from (7.4.9(p.41)). Then, from Lemma 11.2.2(p.57) (j2) we have  $x_K \ge \beta \mu s$  due to (21.2.9(p.142)) and (21.2.10(p.142)), hence  $x_K \ge V_1 \cdots$  (3). Accordingly, since  $K(V_1) \ge 0$  due to Lemma 11.2.2(p.57) (j1), we have  $V_1 \le V_2$  from
- (2). Suppose  $V_{t-1} \leq V_t$ . Then, from (7.4.10(p.41)) and Lemma 11.2.2(p.57) (e) we have  $V_t \leq K(V_t) + V_t = V_{t+1}$ . Hence, by induction  $V_{t-1} \leq V_t$  for t > 1, i.e.,  $V_t$  is nondecreasing in t > 0. Note (3). Suppose  $V_{t-1} \leq x_K$ . Then, from (7.4.10(p.41)) and Lemma 11.2.2(p.57) (e) we have  $V_t \leq K(x_K) + x_K = x_K$ . Hence, by induction  $V_t \leq x_K$  for t > 0, i.e.,  $V_t$  is upper bounded in t, thus  $V_t$  converges to a finite V as  $t \to \infty$ . Accordingly, from (7.4.10(p.41)) we have V = K(V) + V, hence K(V) = 0, thus  $V = x_K$  due to Lemma 11.2.2(p.57) (j1).
- (b) Let  $\beta\mu \geq b\cdots$  (4). Then  $x_L \leq \beta\mu s$  from Lemma 11.2.4(p.59) (b1), hence  $x_L \leq V_1$  from (7.4.9(p.41)), so  $x_L \leq V_{t-1}$  for t>1 from (a). Accordingly,  $L(V_{t-1}) \leq 0$  for t>1 from Corollary 11.2.1(p.57) (a), hence  $L(V_{t-1}) \leq 0\cdots$  (5) for  $\tau \geq t>1$ . Then, since  $V_t \beta V_{t-1} \leq 0$  for  $\tau \geq t>1$  from (1) or equivalently  $V_t \leq \beta V_{t-1}$  for  $\tau \geq t>1$ , we have  $V_\tau \leq \beta V_{\tau-1}, V_{\tau-1} \leq \beta V_{\tau-2}, \cdots, V_2 \leq \beta V_1$ , so  $V_\tau \leq \beta V_{\tau-1} \leq \beta^2 V_{\tau-2} \leq \cdots \leq \left|\beta^{\tau-1} V_1\right|$ , hence it follows that  $t_\tau^* = 1$  for  $\tau > 1$ , i.e.,  $\boxed{\bullet dOITd_{\tau>1}\langle 1 \rangle}_{\vartriangle}$ .
  - (c) Let  $\beta \mu < b$ .
- (c1) Let  $\beta = 1 \cdots$  (6), hence s > 0 due to the assumption " $\beta < 1$  or s > 0". Then  $x_L = x_K \cdots$  (7) due to Lemma 11.2.3(p.58) (b), hence  $K(x_L) = K(x_K) = 0 \cdots$  (8).

<sup>&</sup>lt;sup>†</sup>The outer side of ( ) is for s=0 and the inner side is for s>0.

- (c1i) Let  $\mu s \le a$ . Then, noting (6), (21.2.9(p.142)), and (21.2.10(p.142)), we have  $x_K = \mu s \cdots$  (9) from Lemma 11.2.2(p.57) (j2), hence  $x_K = V_1$  from (7.4.9(p.41)). Let  $V_{t-1} = x_K$ . Then, from (7.4.10(p.41)) we have  $V_t = K(x_K) + x_K = x_K$ . Accordingly, by induction  $V_{t-1} = x_K$  for t > 1, hence  $V_{t-1} = x_L$  for t > 1 from (7). Then  $L(V_{t-1}) = L(x_L) = 0$  for t > 1, thus  $L(V_{t-1}) = 0$  for  $\tau \ge t > 1$ . Then, since  $V_t \beta V_{t-1} = 0$  for  $\tau \ge t > 1$  from (1) or equivalently  $V_t = \beta V_{t-1}$  for  $\tau \ge t > 1$ , we have  $V_\tau = \beta V_{\tau-1}$ ,  $V_{\tau-1} = \beta V_{\tau-2}, \cdots, V_2 = \beta V_1$ , so  $V_\tau = \beta V_{\tau-1} = \beta^2 V_{\tau-2} = \cdots = \beta^{\tau-1} V_1$ , hence  $t_\tau^* = 1$  for  $\tau > 1$ , i.e.,  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}$  (see Preference-Rule 8.2.1(p.45)).
- (c1ii) Let  $\mu s > a$ . Then, since  $V_1 > a$  from (7.4.9(p.41)), we have  $V_{t-1} > a$  for t > 1 from (a). From (7) and Lemma 11.2.2(p.57) (j2) we have  $x_L = x_K > \mu s = V_1$  from (7.4.9(p.41)). Let  $V_{t-1} < x_L$ . Then, from (7.4.10(p.41)) and Lemma 11.2.2(p.57) (g) we have  $V_t < K(x_L) + x_L = x_L$  due to (8), hence by induction  $V_{t-1} < x_L$  for t > 1. Thus, since  $L(V_{t-1}) > 0$  for t > 1 due to Lemma 11.2.1(p.57) (e1), for the same reason as in the proof of Tom 21.2.1(p.143) (b) we obtain s = 0 doITs $s_{\tau>1} \langle \tau \rangle$ .
  - (c2) Let  $\beta < 1$  and s = 0 (s > 0).
- (c2i) Let b>0 ( $\kappa>0$ ). Then  $x_L>x_K\cdots$  (10) from Lemma 11.2.3(p.58) (c (d)). Now, since  $x_K\geq\beta\mu-s$  due to Lemma 11.2.2(p.57) (j2), we have  $x_K\geq V_1$  from (7.4.9(p.41)). Suppose  $x_K\geq V_{t-1}$ . Then, from (7.4.10(p.41)) and Lemma 11.2.2(p.57) (e) we have  $V_t\leq K(x_K)+x_K=x_K$ . Thus, by induction  $V_{t-1}\leq x_K$  for t>1, hence  $V_{t-1}< x_L$  for t>1 from (10). Accordingly, since  $L(V_{t-1})>0$  for t>1 due to Corollary 11.2.1(p.57) (a), for the same reason as in the proof of Tom 21.2.1(p.143) (b) we obtain s=0 doITs s=0 (s=0).
  - (c2ii) Let b = 0 ( $\kappa = 0$ ). Then  $x_L = x_K \cdots$  (11) from Lemma 11.2.3(p.58) (c (d)), hence  $K(x_L) = K(x_K) = 0 \cdots$  (12).
- (c2ii) Let  $\beta\mu s \leq a$ . Then, since  $x_K = \beta\mu s \cdots$  (13) from Lemma 11.2.2(p.57) (j2), we have  $x_K = V_1$  from (7.4.9(p.41)). Let  $V_{t-1} = x_K$ . Then, from (7.4.10(p.41)) we have  $V_t = K(x_K) + x_K = x_K$ . Accordingly, by induction  $V_{t-1} = x_K$  for t > 1, hence  $V_{t-1} = x_L$  for t > 1 due to (11). Then, since  $L(V_{t-1}) = L(x_L) = 0$  for t > 1, for the same reason as in the proof of (c1i) we have  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}$ .
- (c2ii2) Let  $\beta\mu s > a$ . Then, since  $V_1 > a$  from (7.4.9(p.41)), we have  $V_{t-1} > a$  for t > 1 from (a). From (11) and Lemma 11.2.2(p.57) (j2) we have  $x_L = x_K > \beta\mu s = V_1$ . Let  $V_{t-1} < x_L$ . Then, from (7.4.10(p.41)) and Lemma 11.2.2(p.57) (g) we have  $V_t < K(x_L) + x_L = x_L$  due to (12), hence, by induction  $V_{t-1} < x_L$  for t > 1. Consequently, since  $L(V_{t-1}) > 0$  for t > 1 due to Corollary 11.2.1(p.57) (a), for the same reason as in the proof of Tom 21.2.1(p.143) (b) we obtain s = 0.
  - (c2iii) Let b < 0 ( $\kappa < 0$ ). Then  $x_L < x_K \cdots (14)$  from Lemma 11.2.3(p.58) (c (d)).
- (c2iii1) Let  $\beta\mu s \leq a$ , then  $x_L < x_K = \beta\mu s = V_1$  from (14), Lemma 11.2.2(p.57) (j2) and (7.4.9(p.41)), so  $x_L \leq V_1$ . Let  $s_{\mathcal{L}} \leq s$ , then  $x_L \leq \beta\mu s$  due to Lemma 11.2.4(p.59) (c), hence  $x_L \leq V_1$ . Therefore, whether  $\beta\mu s \leq a$  or  $s_{\mathcal{L}} \leq s$ , we have  $x_L \leq V_1$ , hence  $x_L \leq V_{t-1}$  for t > 1 due to (a). Accordingly, since  $L(V_{t-1}) \leq 0$  for t > 1 from Corollary 11.2.1(p.57) (a), for the same reason as in the proof of (b) we obtain  $\bullet$  dOITd<sub> $\tau > 1$ </sub> $\langle 1 \rangle_{\Delta}$ .
- (c2iii2) Suppose  $\beta\mu s > a$  and  $s_{\mathcal{L}} > s$ . Hence, since  $V_1 > a$  from (7.4.9(p41)), we have  $V_{t-1} > a$  for t > 0 from (a). Then, since  $x_K > x_L > \beta\mu s = V_1 \cdots$  (15) from (14), Lemma 11.2.4(p.59) (c), and (7.4.9(p41)), we have  $K(V_1) > 0$  from Lemma 11.2.2(p.57) (j1), hence  $V_2 > V_1$  from (2). Suppose  $V_{t-1} < V_t$ . Then, from (7.4.10(p41)) and Lemma 11.2.2(p.57) (g) we have  $V_t < K(V_t) + V_t = V_{t+1}$ . Accordingly, by induction we have  $V_{t-1} < V_t$  for t > 1, i.e.,  $V_t$  is strictly increasing in t > 0. Note that  $V_1 < x_L$  due to (15). Assume that  $V_{t-1} < x_L$  for all t > 1, hence  $V \le x_L \cdots$  (16) from (a). Then, since  $V = x_K$  due to (a), we have the contradiction of  $V = x_K > x_L \ge V$  due to (14) and (16). Hence, it is impossible that  $V_{t-1} < x_L$  for all t > 1, implying that there exists  $t_T^* > 1$  such that

from which we have

$$V_1 < V_2 < \dots < V_{t^{\bullet}-1} < x_L \le V_{t^{\bullet}} < V_{t^{\bullet}+1} < \dots$$
 (17),

 $V_{t-1} < x_L, \quad t_{\tau}^{\bullet} \ge t > 1, \qquad x_L \le V_{t_{\tau}^{\bullet}}, \qquad x_L < V_{t-1}, \quad t > t_{\tau}^{\bullet} + 1.$  (21.2.11)

Hence, we have

$$L(V_{t-1}) > 0$$
 ... (18)  $t_{\tau}^{\bullet} \ge t > 1$  ( $\leftarrow$  Corollary 11.2.1(p.57) (a))  
 $L(V_{t_{\tau}^{\bullet}}) \le 0$  ... (19) ( $\leftarrow$  Corollary 11.2.1(p.57) (a))  
 $L(V_{t-1}) = ((< 0))^{\dagger} \cdots (20) t > t_{\tau}^{\bullet} + 1$  ( $\leftarrow$  Lemma 11.2.1(p.57) (d(e1)))

- o Let  $t_{\tau}^{\bullet} \geq \tau > 1$ . Then  $L(V_{t-1}) > 0 \cdots (21)$  for  $\tau \geq t > 1$  from (18). Since  $V_t \beta V_{t-1} > 0$  for  $\tau \geq t > 1$  from (1) and (21), we have  $V_t > \beta V_{t-1}$  for  $\tau \geq t > 1$ , hence  $V_{\tau} > \beta V_{\tau-1}$ ,  $V_{\tau-1} > \beta V_{\tau-2}$ ,  $\cdots$ ,  $V_2 > \beta V_1$ . Therefore, since  $V_{\tau} > \beta V_{\tau-1} > \beta^2 V_{\tau-2} > \cdots > \beta^{\tau-1} V_1$ , we obtain  $t_{\tau}^* = \tau$  for  $t_{\tau}^{\bullet} \geq \tau > 1$ , i.e.,  $\boxed{\$ \text{ dOITs}}_{t_{\tau}^{\bullet} \geq \tau > 1} \langle \tau \rangle_{\bullet}$ , thus  $S_2(1)$  is true. Let us note here that when  $\tau = t_{\tau}^{\bullet}$ , we have  $V_{t_{\tau}^{\bullet}} > \beta V_{t_{\tau-1}^{\bullet}} > \cdots > \beta^{t_{\tau}^{\bullet} 1} V_1 \cdots$  (22).
- Let  $\tau = t_{\tau}^{\bullet} + 1$ . From (1) with  $t = t_{\tau}^{\bullet} + 1$  and (19) we have  $V_{t_{\tau}^{\bullet} + 1} \beta V_{t_{\tau}^{\bullet}} \leq 0$ , hence  $V_{t_{\tau}^{\bullet} + 1} \leq \beta V_{t_{\tau}^{\bullet}}$ . Accordingly, from (22) we have

$$V_{t_{\boldsymbol{\tau}}+1} \leq \beta V_{t_{\boldsymbol{\tau}}} > \beta^2 V_{t_{\boldsymbol{\tau}}-1} > \beta^3 V_{t_{\boldsymbol{\tau}}-2} > \dots > \beta^{t_{\boldsymbol{\tau}}^{\boldsymbol{\tau}}} V_1 \dots (23),$$

thus  $t_{t^{\bullet}_{\tau}+1}^*=t^{\bullet}_{\tau}$ , i.e.,  $\boxed{\odot}$  ndOIT $_{t^{\bullet}_{\tau}+1}\langle t^{\bullet}_{\tau}\rangle|_{\vartriangle}$ , thus S<sub>2</sub>(2) is true.

<sup>†</sup> If s = 0, then  $L(V_{t-1}) = 0$ , or else  $L(V_{t-1}) < 0$ .

• Let  $\tau > t_{\tau}^{\bullet} + 1$ . Since  $L(V_{t_{\tau}^{\bullet}+1}) = (<) 0$  from (20) with  $t = t_{\tau}^{\bullet} + 2$ , we have  $V_{t_{\tau}^{\bullet}+2} = (<) \beta V_{t_{\tau}^{\bullet}+1}$  from (1), hence from (23) we have

$$V_{t_{\tau}^{\bullet}+2} = (\!(<)\!) \; \beta V_{t_{\tau}^{\bullet}+1} \leq \overline{\beta^2 V_{t_{\tau}^{\bullet}}} > \beta^3 V_{t_{\tau}^{\bullet}-1} > \beta^4 V_{t_{\tau}^{\bullet}-2} > \dots > \beta^{t_{\tau}^{\bullet}+1} V_{1}$$

Similarly we have

$$V_{t_{\tau}^{\bullet}+3} = (\!(<)\!) \beta V_{t_{\tau}^{\bullet}+2} = (\!(<)\!) \beta^2 V_{t_{\tau}^{\bullet}+1} \leq \beta^3 V_{t_{\tau}^{\bullet}} > \beta^4 V_{t_{\tau}^{\bullet}-1} > \dots > \beta^{t_{\tau}^{\bullet}+2} V_1.$$

By repeating the same procedure, for  $\tau = t_{\tau}^{\bullet} + 2, t_{\tau}^{\bullet} + 3, \cdots$  we obtain

$$V_{\tau} = (\!(\!)) \beta V_{\tau-1} = (\!(\!)) \cdots = (\!(\!)) \beta^{\tau-t^{\bullet}_{\tau}-2} V_{t^{\bullet}_{\tau}+2} = (\!(\!)) \beta^{\tau-t^{\bullet}_{\tau}-1} V_{t^{\bullet}_{\tau}+1} \leq \beta^{\tau-t^{\bullet}_{\tau}} V_{t^{\bullet}_{\tau}} > \beta^{\tau-t^{\bullet}_{\tau}+1} V_{t^{\bullet}_{\tau}-1} > \cdots > \beta^{\tau-1} V_{1} \cdots (24)$$

• Let s = 0. Then (24) can be written as

$$V_{\tau} = \beta V_{\tau-1} = \dots = \beta^{\tau - t_{\tau}^{\bullet} - 2} V_{t_{\tau}^{\bullet} + 2} = \beta^{\tau - t_{\tau}^{\bullet} - 1} V_{t_{\tau}^{\bullet} + 1} \le \beta^{\tau - t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} > \beta^{\tau - t_{\tau}^{\bullet} + 1} V_{t_{\tau}^{\bullet} - 1} > \dots > \beta^{\tau - 1} V_{1},$$

hence we have  $t_{\tau}^* = t_{\tau}^{\bullet}$ , i.e.,  $\boxed{\bigcirc$  ndOIT $_{\tau > t_{\tau}^{\bullet} + 1} \langle t_{\tau}^{\bullet} \rangle}_{\parallel}$  (see Preference Rule 8.2.1(p.45)), hence  $S_2(3)$  is true.

• Let s > 0. Then (24) can be written as

$$V_{\tau} < \beta V_{\tau-1} < \dots < \beta^{\tau - t_{\tau}^{\bullet} - 2} V_{t_{\tau+2}} < \beta^{\tau - t_{\tau}^{\bullet} - 1} V_{t_{\tau+1}} \le \beta^{\tau - t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} > \beta^{\tau - t_{\tau}^{\bullet} + 1} V_{t_{\tau-1}} > \dots > \beta^{\tau - 1} V_{1}, \tag{21.2.12}$$

hence we have  $t_{\tau}^* = t_{\tau}^{\bullet}$ , i.e.,  $\boxed{\odot \text{ ndOIT}_{\tau > t_{\tau}^{\bullet} + 1} \langle t_{\tau}^{\bullet} \rangle}_{\blacktriangle}$ , hence  $S_2(3)$  is true.

#### 21.2.2.2 Market Restriction

## 21.2.2.2.1 Positive Restriction

- $\square$  Pom **21.2.1** ( $\mathscr{A}\{M:1[\mathbb{R}][E]^+\}$ ) Suppose a > 0. Let  $\beta = 1$  and s = 0.
- (a)  $V_t$  is nondecreasing in t > 0.
- (b) We have  $[\$ dOITs_{\tau>1}\langle \tau \rangle]_{\blacktriangle}$ .
- ullet Proof The same as Tom 21.2.1(p.143) due to Lemma 18.4.4(p.118).
- $\square$  Pom 21.2.2 ( $\mathscr{A}\{M:1[\mathbb{R}][E]^+\}$ ) Suppose a > 0. Let  $\beta < 1$  or s > 0.
- (a)  $V_t$  is nondecreasing in t > 0 and converges to a finite  $V = x_K$  as  $t \to \infty$ .
- (b) Let  $\beta \mu \geq b$  (impossible).
- $(c) \quad \ Let \ \beta \mu < b \ ({\rm always \ holds}).$ 
  - 1. Let  $\beta = 1$ .
    - i. Let  $\mu s \leq a$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
  - 2. Let  $\beta < 1$  and s = 0. Then s = 0. s = 0.
  - 3. Let  $\beta < 1$  and s > 0.
    - i. Let  $\beta \mu > s$ . Then  $subseteq dOITs_{\tau > 1} \langle \tau \rangle$ .
    - ii. Let  $\beta \mu \leq s$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\Delta}$ .
- Proof Suppose a > 0, hence  $b > a > 0 \cdots (1)$ . Then  $\kappa = \beta \mu s \cdots (2)$  from Lemma 11.3.1(p.59) (a) with  $\lambda = 1$ .
  - (a) The same as Tom 21.2.2(p.143) (a).
  - (b,c) Always  $\beta \mu < b$  from [3(p.118)], hence  $\beta \mu \ge b$  is impossible.
  - $(c1\text{-}c1ii) \quad \text{The same as Tom } 21.2.2 \text{(p.143)} \, (c1\text{-}c1ii).$
  - (c2) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c2i) of Tom 21.2.2(p.143).
  - (c3) Let  $\beta < 1$  and s > 0.
  - (c3i) Let  $\beta \mu > s$ , hence  $\kappa > 0$  due to (2). Hence it suffices to consider only (c2i) of Tom 21.2.2(p.143).
  - (c3ii) Let  $\beta\mu \leq s$ , hence  $\kappa \leq 0$  due to (2). Then, since  $\beta\mu s \leq 0 < a$ , it suffices to consider only (c2iii1) of Tom 21.2.2(p.143).

#### 21.2.2.2. Mixed Restriction

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\square Mim 21.2.1 (\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]^{\pm}\})
                                               Suppose a \le 0 \le 0. Let \beta = 1 and s = 0.
(a) V_t is nondecreasing in t > 0.
      We have \odot dOITs_{\tau>1}\langle \tau \rangle.
• Proof The same as Tom 21.2.1(p.143) due to Lemma 18.4.4(p.118).
\square Mim 21.2.2 (\mathscr{A}\{M:1[\mathbb{R}][E]^{\pm}\}) Suppose a \leq 0 \leq b. Let \beta < 1 or s > 0.
      V_t is nondecreasing in t>0 and converges to a finite V>x_K as t\to\infty.
      Let \beta \mu \geq b (impossible).
(b)
(c) Let \beta \mu < b (always holds).
     1. Let \beta = 1.
           i. Let \mu - s \leq a. Then \bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}.
           ii. Let \mu - s > a. Then subseteq dOITs_{\tau > 1} \langle \tau \rangle
     2. Let \beta < 1 and s = 0. Then s = 0 doing t = 1
     3. Let \beta < 1 and s > 0.
           i. Let s < \beta T(0). Then subseteq dOITs_{\tau>1} \langle \tau \rangle.
           ii. Let s = \beta T(0).
               1. Let \beta \mu - s \leq a. Then | \bullet dOITd_{\tau > 1} \langle 1 \rangle |_{\parallel}.
               2. Let \beta \mu - s > a. Then subseteq doing = 0.5
          iii. Let s > \beta T(0).
               1. Let \beta \mu - s \leq a or s_{\mathcal{L}} \leq s. Then \boxed{\bullet \text{ dOITd}_{\tau > 1} \langle 1 \rangle}_{\Delta}.
               2. Let \beta\mu - s > a and s_{\mathcal{L}} > s. Then S_2 \bullet \bullet \bullet is true.
• Proof Suppose a \le 0 \le b. Let \beta < 1 or s > 0.
   (a) The same as Tom 21.2.2(p.143) (a).
   (b,c) Always \beta \mu < b due to [8(p.118)], hence \beta \mu \geq b is impossible.
   (c1) Let \beta = 1, hence s > 0 due to the assumption "\beta < 1 or s > 0".
   (c1i,c1ii) The same as Tom 21.2.2(p.143) (c1i,c1ii).
   (c2) Let \beta < 1 and s = 0. If b > 0, then it suffices to consider only (c2i) of Tom 21.2.2(p.143) and if b = 0, then since always
\beta\mu - s = \beta\mu > a due to [8(p.118)], it suffices to consider only (c2ii2) of Tom 21.2.2(p.143). Therefore, whether b > 0 or b = 0, we
have the same result.
   (c3-c3iii2) Let \beta < 1 and s > 0. Then, the assertions are immediate from Tom 21.2.2(p.143) (c2i-c2iii2) with \kappa = \beta T(0) - s
from (6.1.7(p.25)) with \lambda = 1.
21.2.2.3 Negative Restriction
\square Nem 21.2.1 (\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]^-\})
                                               Suppose b < 0. Let \beta = 1 and s = 0.
      V_t is nondecreasing in t > 0.
       We have \boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}.
• Proof The same as Tom 21.2.1(p.143) due to Lemma 18.4.4(p.118).
\square Nem 21.2.2 (\mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]^-\}) Suppose b < 0. Let \beta < 1 or s > 0.
(a) V_t is nondecreasing in t > 0 and converges to a finite V = x_K as t \to \infty.
(b) Let \beta \mu \geq b. Then \bullet dOITd_{\tau > 1}\langle 1 \rangle_{\Delta}.
(c) Let \beta \mu < b.
     1. Let \beta = 1.
           i. Let \mu - s \leq a. Then \boxed{\bullet \text{ dOITd}_{\tau > 1}} \langle 1 \rangle_{\parallel}.
           ii. Let \mu - s > a. Then \boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}
     2. Let \beta < 1 and s = 0. Then S_2 \bullet \bullet \bullet \bullet is true.
     3. Let \beta < 1 and s > 0.
           i. Let \beta \mu - s \leq a or s_{\mathcal{L}} \leq s. Then \bullet dOITd_{\tau > 1}\langle 1 \rangle_{\Delta}.
           ii. Let \beta\mu - s > a and s_{\mathcal{L}} > s. Then S_2 \textcircled{S} \textcircled{O} \textcircled{I} \textcircled{O} \textcircled{A} \textcircled{O} \textcircled{A} is true.
• Proof Suppose b < 0, hence a < \mu < b < 0 \cdots (1). Hence \kappa = -s \cdots (2) from Lemma 11.3.1(p.59) (a) with \lambda = 1. In addition,
\beta \mu \geq b and \beta \mu < b are both possible due to [17(p.118)].
   (a,b) The same as Tom 21.2.2(p.143)(a,b).
   (c) Let \beta \mu < b.
   (c1-c1ii) The same as Tom 21.2.2(p.143) (c1-c1ii).
   (c2) Let \beta < 1 and s = 0. Then, since b < 0 due to (1), it suffices to consider only (c2iii) of Tom 21.2.2(p.143). In this case,
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(c3-c3ii) Let  $\beta < 1$  and s > 0, hence  $\kappa < 0$  due to (2). Thus, it suffices to consider only (c2iii1-c2iii2) of Tom 21.2.2(p.143).

since  $\beta \mu - s = \beta \mu > \beta a > a$  due to (1) and since  $s_{\mathcal{L}} > 0 = s$  due to Lemma 11.2.4(p.59) (c), it suffices to consider only (c2iii2) of Tom 21.2.2(p.143).

# 21.2.3 $\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]$

## 21.2.3.1 Analysis

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\square Tom 21.2.1 (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\}) Let \beta=1 and s=0.
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- (a)  $V_t$  is nonincreasing in t > 0.
- (b) We have  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ .
- ullet Proof by symmetry Immediate from applying  $\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Tom 21.2.1(p.143).
- $\square$  Tom 21.2.2 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\}$ ) Let  $\beta<1$  or s>0.
- (a)  $V_t$  is nonincreasing in t>0 and converges to a finite  $V=x_{\tilde{K}}$  as  $t\to\infty$ .
- (b) Let  $\beta \mu \leq a$ . Then  $\bullet dOITd_{\tau>1}\langle 1 \rangle_{\Delta}$ .
- (c) Let  $\beta \mu > a$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $\mu + s \geq b$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $\mu + s < b$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$ .
  - 2. Let  $\beta < 1$  and s = 0 ((s > 0)).
    - i. Let a < 0 ( $\tilde{\kappa} < 0$ ). Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$ .
    - ii. Let a = 0 ( $\tilde{\kappa} = 0$ ) .
      - 1. Let  $\beta \mu + s \geq b$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta \mu + s < b$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}$
    - iii. Let a>0 ( $\tilde{\kappa}>0$ ) .
      - 1. Let  $\beta \mu + s \geq b$  or  $s_{\tilde{\mathcal{L}}} \leq s$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\Delta}$ .
      - 2. Let  $\beta\mu + s < b$  and  $s_{\tilde{\mathcal{L}}} > s$ . Then  $S_2$   $\bullet$   $\bullet$   $\bullet$   $\bullet$  is true.  $\Box$
- Proof by symmetry Immediate from applying  $S_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Tom 21.2.2(p.143).

#### 21.2.3.2 Market Restriction

### 21.2.3.2.1 Positive Restriction

- $\square$  Pom 21.2.3 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]^+\}$ ) Suppose a>0. Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in t > 0.
- (b) We have  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ .
- *Proof* The same as Tom 21.2.1(p.147) due to Lemma 18.4.4(p.118).
- $\square$  Pom 21.2.4 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]^+\}$ ) Suppose a>0. Let  $\beta<1$  or s>0.
- (a)  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V = x_{\tilde{k}}$  as  $t \to \infty$ .
- (b) Let  $\beta \mu \leq a$ . Then  $\boxed{\bullet dOITd_{\tau > 1}\langle 1 \rangle}_{\Delta}$ .
- (c) Let  $\beta \mu > a$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $\mu + s \geq b$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $\mu + s < b$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$ .

  - 3. Let  $\beta < 1$  and s > 0.
    - i. Let  $\beta \mu + s \geq b$  or  $s_{\tilde{\mathcal{L}}} \leq s$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\Delta}$ .
- Proof by diagonal-symmetry Immediate from applying  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}$  ((20.0.3(p.136))) to Nem 21.2.2(p.146).
- Direct proof Suppose  $a > 0 \cdots (1)$ , hence  $\tilde{\kappa} = s \cdots (2)$  from Lemma 13.6.6(p.83) (a). Here note that  $\mu\beta \leq a$  and  $\mu\beta > a$  are both possible due to [5(p.118)].
  - (a,b) The same as Tom 21.2.2(p.147)(a,b).
  - (c) Let  $\beta \mu > a$ . Then  $s_{\tilde{\mathcal{L}}} > 0 \cdots$  (3) due to Lemma 13.6.5(p.83) (c) with  $\lambda = 1$ .
- (c1-c1ii) Let  $\beta=1$ , hence s>0 due to the assumptions  $\beta<1$  and s>0. Thus, we have Tom 21.2.2(p.147) (c1i,c1ii).
- (c2) Let  $\beta < 1$  and s = 0. Then, since  $\beta \mu + s = \beta \mu < b$  due to [3(p.118)] and since  $s_{\tilde{\mathcal{L}}} > 0 = s$  from (3), due to (1) it suffices to consider only (c2iii2) of Tom 21.2.2(p.147).
- (c3-c3ii) Let  $\beta < 1$  and s > 0. Then, since  $\tilde{\kappa} > 0$  due to (2), it suffices to consider only (c2iii1,c2iii2) of Tom 21.2.2(p.147).

### 21.2.3.2.2 Mixed Restriction

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\square Mim 21.2.3 (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\}^{\pm}) Suppose a \leq 0 \leq b. Let \beta = 1 and s = 0.
(a) We have \boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\blacktriangle}.
• Proof The same as Tom 21.2.1(p.147) due to Lemma 18.4.4(p.118).
\square Mim 21.2.4 (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]^{\pm}\}) Suppose a\leq 0\leq b. Let \beta<1 or s>0.
(a) V_t is nonincreasing in t > 0 and converges to a finite V < x_{\tilde{K}} as t \to \infty.
(b) Let \beta \mu \leq a (impossible).
(c) Let \beta \mu > a (always holds).
     1. Let \beta = 1.
            i. Let \mu + s \geq b. Then \bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}.
           ii. Let \mu + s < b. Then \boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}
          Let \beta < 1 and s = 0. Then |    dOITs _{\tau > 1} \langle \tau \rangle |_{\blacktriangle} 
           Let \beta < 1 and s > 0.
            i. Let s < -\beta \tilde{T}(0). Then subseteq dOITs_{\tau>1} \langle \tau \rangle.
           ii. Let s = -\beta T(0).
                1. Let \beta \mu + s \geq b. Then \bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}.
                2. Let \beta \mu + s < b. Then subseteq doing = 0
          iii. Let s > -\beta T(0).
                1. Let \beta \mu + s \geq b or s_{\tilde{\mathcal{L}}} \leq s. Then \left[ \bullet \operatorname{dOITd}_{\tau > 1} \langle 1 \rangle \right]_{\Delta}.
                2. Let \beta \mu + s < b and s_{\tilde{\mathcal{L}}} > s. Then S_2  \boxed{\$ \blacktriangle | \lozenge \# | \lozenge \vartriangle | \lozenge \blacktriangle} is true.
• Proof Suppose a \le 0 \le b. Let \beta < 1 or s > 0.
   (a) The same as Tom 21.2.2(p.147) (a).
   (b,c) Always \beta \mu > a due to [8(p.118)], hence \beta \mu \leq a is impossible. Then s_{\tilde{\mathcal{L}}} > 0 due to
Lemma 13.6.5(p.83) (c).
   (c1-c1ii) The same as Tom 21.2.2(p.147) (c-c1ii).
   (c2) Let \beta < 1 and s = 0. Let a < 0. Then it suffices to consider only (c2i) of Tom 21.2.2(p.147). Let a = 0. Now, in this
case, since \beta\mu + s = \beta\mu < b due to [8(p.118)], it suffices to consider only (c2ii2) of Tom 21.2.2(p.147). Accordingly, whether a < 0
or a = 0, we have the same result.
   (c3-c3iii2) Let \beta < 1 and s > 0. Then, the assertions become true from Tom 21.2.2(p.147) (c2i-c2iii2) with \tilde{\kappa} = \beta \tilde{T}(0) + s from
(6.1.16(p.25)).
21.2.3.2.3 Negative Restriction
\square Nem 21.2.3 (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]^-\})
                                                  Suppose b < 0. Let \beta = 1 and s = 0.
(a) V_t is nonincreasing in t > 0.
(b) We have [S] dOITs_{\tau>1}\langle \tau \rangle.
ullet Proof The same as Tom 21.2.2(p.147) due to Lemma 18.4.4(p.118). \blacksquare
\square Nem 21.2.4 (\mathscr{A}_{Tom} {\widetilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{E}]^-}) Suppose b < 0. Let \beta < 1 or s > 0.
(a) V_t is nonincreasing in t > 0 and converges to a finite V \leq x_{\tilde{K}} as t \to \infty.
       Let \beta \mu \leq a (impossible).
(c) Let \beta \mu > a (always holds).
     1. Let \beta = 1.
            i. Let \mu + s \geq b. Then \bullet dOITd_{\tau > 1}\langle 1 \rangle
           ii. Let \mu + s < b. Then [  dOITs_{\tau > 1} \langle \tau \rangle ]_{\blacktriangle}
     2. Let \beta < 1 and s = 0. Then s = 0 doing t = 1
     3. Let \beta < 1 and s > 0.
            i. Let \beta \mu < -s. Then \boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}.
            ii. Let \beta \mu \geq -s. Then \bullet dOITd_{\tau>1}\langle 1 \rangle \triangle.
• Proof Suppose b < 0 \cdots (1), hence a < b < 0 \cdots (2). Then \tilde{\kappa} = \beta \mu + s \cdots (3) due to Lemma 13.6.6(p.83) (a).
   (a) The same as Tom 21.2.2(p.147) (a).
   (b,c) Always a < \beta \mu due to [15(p.118)], hence \beta \mu \le a is impossible.
   (c1-c1ii) The same as the proof of Tom 21.2.2(p.147) (c1-c1ii).
   (c2) Let \beta < 1 and s = 0. Then, due to (2) it suffices to consider only (c2i) of Tom 21.2.2(p.147).
   (c3) Let \beta < 1 and s > 0.
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(c3ii) Let  $\beta\mu \geq -s$ , hence  $\beta\mu + s \geq 0$ . Let  $\beta\mu + s = 0$ . Then, since  $\tilde{\kappa} = 0$  due to (3) and since  $\beta\mu + s = 0 > b$  due to (2), it suffices to consider only (c2ii1) of Tom 21.2.2(p.147). Let  $\beta\mu + s > 0$ . Then, since  $\tilde{\kappa} > 0$  due to (3), it suffices to consider only (c2iii) of Tom 21.2.2(p.147). Then, since  $\beta \mu + s > 0 > b$  due to (1), it suffices to consider only (c2iii1) of Tom 21.2.2(p.147). Accordingly, whether  $\beta \mu + s = 0$  or  $\beta \mu + s > 0$ , we have the same result.

(c3i) Let  $\beta\mu < -s$ , hence  $\beta\mu + s < 0$ . Then, since  $\tilde{\kappa} < 0$  due to (3), it suffices to consider only (c2i) of Tom 21.2.2(p.147).

# **21.2.4** M:1[ $\mathbb{P}$ ][ $\mathbb{E}$ ]

# 21.2.4.1 Analysis

- (a)  $V_t$  is nondecreasing in t > 0.
- (b) We have  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}$
- ullet Proof by analogy The same as Tom 21.2.1(p.143) due to Lemma 14.6.1(p.99).  $\blacksquare$
- $\square$  Tom 21.2.4 ( $\mathscr{A}\{M:1[\mathbb{P}][E]\}$ ) Let  $\beta < 1$  or s > 0.
- (a)  $V_t$  is nondecreasing in t > 0 and converges to a finite  $V = x_K$  as  $t \to \infty$ .
- (b) Let  $\beta a \geq b$ . Then  $\boxed{\bullet dOITd_{\tau > 1}\langle 1 \rangle}_{\Delta}$ .
- (c) Let  $\beta a < b$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $a s \leq a^*$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $a-s>a^{\star}$ . Then  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ .
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let b>0 ( $\kappa>0$ ). Then  $\boxed{\$ dOITs_{\tau>1}\langle \tau\rangle}$
    - ii. Let b = 0 ( $\kappa = 0$ ).
      - 1. Let  $\beta a s \leq a^{\star}$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta a s > a^*$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$ .
    - iii. Let  $b < 0 (\kappa < 0)$ .
      - 1. Let  $\beta a s \leq a^*$  or  $s_{\mathcal{L}} \leq s$ . Then  $\left[ \bullet \operatorname{dOITd}_{\tau > 1} \langle 1 \rangle \right]_{\vartriangle}$ .
      - 2. Let  $\beta a s > a^*$  and  $s_{\mathcal{L}} > s$ . Then  $S_2$   $\bullet$   $\bullet$   $\bullet$   $\bullet$  is true.  $\Box$
- Proof by analogy Immediate from applying  $\mathcal{A}_{\mathbb{R}^{\to \mathbb{P}}}$  (see (20.0.5(p.136))) to Tom 21.2.2(p.143).

Corollary 21.2.1 (optimal price to propose) The optimal price to propose  $z_t$  is nondecreasing in t > 0.  $\square$ 

• *Proof* Immediate from Tom's 21.2.3(p.149) (a) and 21.2.4(p.149) (a) and from (7.2.34(p.31)) and Lemma 14.1.3(p.89).

## 21.2.4.2 Market Restriction

### 21.2.4.2.1 Positive Restriction

- $\square$  Pom 21.2.5 ( $\mathscr{A}\{M:1[\mathbb{P}][E]^+\}$ ) Suppose a > 0. Let  $\beta = 1$  and s = 0.
- (a)  $V_t$  is nondecreasing in t > 0.
- (b) We have [s] dOITs $_{\tau>1}\langle \tau \rangle$ .
- *Proof* The same as Tom 21.2.3(p.149) due to Lemma 18.4.4(p.118). ■
- $\square$  Pom 21.2.6 ( $\mathscr{A}\{M:1[\mathbb{P}][E]^+\}$ ) Suppose a > 0. Let  $\beta < 1$  or s > 0.
- (a)  $V_t$  is nondecreasing in t > 0 and converges to a finite  $V = x_K$  as  $t \to \infty$ .
- (b) Let  $\beta a \geq b$  (impossible).
- (c) Let  $\beta a < b$  (always holds).
  - 1. Let  $\beta = 1$ .
    - i. Let  $a s \leq a^*$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
    - ii. Let  $a-s>a^{\star}$ . Then  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ .
  - 2. Let  $\beta < 1$  and s = 0. Then s = 0.
  - 3. Let  $\beta < 1$  and s > 0.
    - i. Let  $s < \beta T(0)$ . Then  $subseteq dOITs_{\tau>1} \langle \tau \rangle$
    - ii. Let  $s = \beta T(0)$ .
      - 1. Let  $\beta a s \leq a^*$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta a s > a^{\star}$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$ .
    - iii. Let  $s > \beta T(0)$ .
      - 1. Let  $\beta a s \leq a^*$  or  $s_{\mathcal{L}} \leq s$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\Delta}$ .
      - 2. Let  $\beta a s > a^*$  and  $s < s_{\mathcal{L}}$ . Then  $S_2 = \mathbb{S}_2 = \mathbb$
- Proof Suppose a > 0, hence  $b > a > 0 \cdots (1)$ .
  - (a) The same as Tom 21.2.4(p.149) (a).
  - (b,c) Always  $\beta a < b$  from [4(p.118)], hence  $\beta a \ge b$  is impossible.
  - (c1-c1ii) The same as Tom 21.2.4(p.149) (c1-c1ii).
  - (c2) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c2i) of Tom 21.2.4(p.149).
  - (c3) Let  $\beta < 1$  and s > 0.
  - (c3i-c3iii2) Immediate from Tom 21.2.4(p.149) (c2i-c2iii2) due to (2) with  $\kappa = \beta T(0) s \cdots$  (2) from (6.1.23(p.26)).

### 21.2.4.2.2 Mixed Restriction

- $\square$  Mim 21.2.5 ( $\mathscr{A}\{M:1[\mathbb{P}][E]^{\pm}\}$ ) Suppose  $a \leq 0 \leq b$ . Let  $\beta = 1$  and s = 0.
- (a)  $V_t$  is nondecreasing in t > 0.
- (b) We have  $[\$ dOITs_{\tau>1}\langle \tau \rangle]_{\blacktriangle}$ .
- Proof The same as Tom 21.2.3(p.149) due to Lemma 18.4.4(p.118).
- $\square$  Mim 21.2.6 ( $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]^{\pm}\}$ ) Suppose  $a \leq 0 \leq b$ . Let  $\beta < 1$  or s > 0.
- (a)  $V_t$  is nondecreasing in t > 0 and converges to a finite  $V \ge x_K$  as  $t \to \infty$ .
- (b) Let  $\beta a \geq b$  (impossible).
- (c) Let  $\beta a < b$  (always holds).
  - 1. Let  $\beta = 1$ .
    - i. Let  $a s \leq a^*$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $a-s>a^{\star}$ . Then  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ .
  - 2. Let  $\beta < 1$  and s = 0. Then  $\overline{\text{sodo} \text{ITs}_{\tau > 1} \langle \tau \rangle}$
  - $3. \quad Let \ \beta < 1 \ and \ s > 0.$ 

    - ii. Let  $s = \beta T(0)$ .
      - 1. Let  $\beta a s \leq a^{\star}$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
      - 2. Let  $\beta a s > a^*$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}$
    - iii. Let  $s > \beta T(0)$ .
      - 1. Let  $\beta a s \leq a^*$  or  $s_{\mathcal{L}} \leq s$ . Then  $\left[ \bullet \operatorname{dOITd}_{\tau > 1} \langle 1 \rangle \right]_{\vartriangle}$ .
      - 2. Let  $\beta a s > a^*$  and  $s_{\mathcal{L}} > s$ . Then  $S_2$   $\boxed{\$ \blacktriangle \circledcirc \| \circledcirc \vartriangle \circledcirc \blacktriangle}$  is true  $\square$
- Proof Suppose  $a \leq 0 \leq b$ .
  - (a) The same as Tom 21.2.4(p.149) (a).
  - (b,c) Always  $\beta a < b$  due to [9(p.118)], hence  $\beta a \ge b$  is impossible. .
  - (c1-c1ii) The same as Tom 21.2.4(p.149) (c1-c1ii).
- (c2) Let  $\beta < 1$  and s = 0. If b > 0, the assertion is true from Tom 21.2.4(p.149) (c2i) and if b = 0, then  $\beta a s = \beta a > a^*$  from [11(p.118)], hence the assertion become true from Tom 21.2.4(p.149) (c2ii2). Accordingly, whether b > 0 or b = 0, we have the same result.
- (c3-c3iii2) The same as Tom 21.2.4(p.149) (c2i-c2iii2) with  $\kappa = \beta T(0) s$  from (6.1.23(p.26))) with  $\lambda = 1$ .

## 21.2.4.2.3 Negative Restriction

- $\square$  Nem 21.2.5 ( $\mathscr{A}\{M:1[\mathbb{P}][E]^-\}$ ) Suppose b < 0. Let  $\beta = 1$  and s = 0.
- (a)  $V_t$  is nondecreasing in t > 0.
- (b) We have  $[\$ dOITs_{\tau>1}\langle \tau \rangle]_{\blacktriangle}$ .
- *Proof* The same as Tom 21.2.3(p.149) due to Lemma 18.4.4(p.118).
- $\square$  Nem 21.2.6 ( $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]^-\}$ ) Suppose b<0. Let  $\beta<1$  or s>0.
- (a)  $V_t$  is nondecreasing in t > 0 and converges to a finite  $V = x_K$  as  $t \to \infty$ .
- (b) Let  $\beta a \geq b$ . Then  $\bullet dOITd_{\tau>1}\langle 1 \rangle_{\Delta}$ .
- (c) Let  $\beta a < b$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $a s \leq a^*$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $a-s>a^{\star}$ . Then  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ .
  - 2. Let  $\beta < 1$  and s = 0. Then  $S_2$   $\bullet$   $\bullet$   $\bullet$   $\bullet$  is true.
  - 3. Let  $\beta < 1$  and s > 0.
    - i. Let  $\beta a s \leq a^{\star}$  or  $s_{\mathcal{L}} \leq s$ . Then  $\boxed{\bullet \operatorname{dOITd}_{\tau > 1}\langle 1 \rangle}_{\vartriangle}$
    - ii. Let  $\beta a s > a^*$  and  $s < s_{\mathcal{L}}$ . Then  $S_2$   $\boxed{\$ \blacktriangle \circledcirc \Vdash \circledcirc \vartriangle \circledcirc \blacktriangle}$  is true.
- **Proof** Suppose b < 0. Then,  $\kappa = -s \cdots$  (1) from Lemma 14.2.6(p.97) (a). In addition,  $\beta a \ge b$  and  $\beta a < b$  are both possible due to [18(p.118)].
  - (a,b) The same as Tom 21.2.4(p.149) (a,b).
  - (c) Let  $\beta a < b$ .
  - (c1-c1ii) The same as Tom 21.2.4(p.149) (c1-c1ii).
- (c2) Let  $\beta < 1$  and s = 0. Then, it suffices to consider only (c2iii-c2iii2) of Tom 21.2.4(p.149). In this case, since  $\beta a s = \beta a > a^*$  due to [19(p.118)] and since  $s_{\mathcal{L}} > 0 = s$  due to Lemma 14.2.5(p.97) (c), it suffices to consider only (c2iii2) of Tom 21.2.4(p.149).
  - (c3-c3ii) Let  $\beta < 1$  and s > 0, hence  $\kappa < 0$  due to (1). Hence, it suffices to consider only (c2iii1,c2iii2) of Tom 21.2.4(p.149).

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21.2.5 \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]\}
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## 21.2.5.1 Analysis

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\square Tom 21.2.5 (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]\}) Let \beta=1 and s=0.
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- (a)  $V_t$  is nonincreasing in t > 0.
- (b) We have  $\odot dOITs_{\tau>1}\langle \tau \rangle$ .
- ullet Proof by symmetry Immediate from applying  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}$  (see (20.0.3 (p.136))) to Tom 21.2.3 (p.149).
- $\square$  Tom 21.2.6 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]\}$ ) Let  $\beta<1$  or s>0.
- (a)  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V = x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $\beta b \leq a$ . Then  $\bullet dOITd_{\tau>1}\langle 1 \rangle_{\Delta}$ .
- (c) Let  $\beta b > a$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $b+s \geq b^*$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau>1}\langle 1 \rangle}_{\parallel}$ .
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let a < 0 ( $\tilde{\kappa} < 0$ ). Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$
    - ii. Let  $a = 0 ((\tilde{\kappa} = 0))$ .
      - 1. Let  $\beta b + s \geq b^{\star}$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta b + s < b^*$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$ .
    - iii. Let a > 0 ( $\tilde{\kappa} > 0$ ).
      - 1. Let  $\beta b + s \geq b^*$  or  $s_{\tilde{\mathcal{L}}} \leq s$ . Then  $\left[ \bullet \operatorname{dOITd}_{\tau > 1} \langle 1 \rangle \right]_{\Delta}$ .
      - 2. Let  $\beta b + s < b^*$  and  $s_{\tilde{\mathcal{L}}} > s$ . Then  $S_2$   $s_{\tilde{\mathcal{L}}} \circ s_{\tilde{\mathcal{L}}} \circ$
- ullet Proof by symmetry Immediate from applying  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) to Tom 21.2.4(p.149).

Corollary 21.2.2 (optimal price to propose) The optimal price to propose  $z_t$  is nonincreasing in t > 0.

• *Proof* Immediate from Tom's 21.2.5(p.151) (a) and 21.2.6(p.151) (a) and from (7.2.50(p.32)) and Lemma A 3.3(p.306)). ■

### 21.2.5.2 Market Restriction

# 21.2.5.2.1 Positive Restriction

- $\square$  Pom 21.2.7 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]^+\}$ ) Suppose a>0. Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in t > 0.
- (b) We have [s] dOITs $_{\tau>1}\langle \tau \rangle$ .
- *Proof* The same as Tom 21.2.5(p.151) due to Lemma 18.4.4(p.118).
- $\square$  Pom 21.2.8 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]^+\}$ ) Suppose a>0. Let  $\beta<1$  or s>0.
- (a)  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V = x_{\tilde{k}}$  as  $t \to \infty$ .
- (b) Let  $\beta b \leq a$ . Then  $\boxed{\bullet dOITd_{\tau > 1}} \langle 1 \rangle_{\Delta}$ .
- (c) Let  $\beta b > a$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $b+s \geq b^*$ . Then  $\bullet dOITd_{\tau>1}\langle 1 \rangle_{\parallel}$ .
  - 2. Let  $\beta < 1$  and s = 0. Then  $S_2$   $\bullet$   $\bullet$   $\bullet$   $\bullet$  is true.
  - 3. Let  $\beta < 1$  and s > 0.
    - i. Let  $\beta b + s \geq b^*$  or  $s_{\tilde{\mathcal{L}}} \leq s$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\Delta}$ .
    - ii. Let  $\beta b + s < b^*$  and  $s < s_{\tilde{\mathcal{L}}}$ . Then  $S_2$   $\boxed{\$ \blacktriangle \circledcirc \Vdash \circledcirc \vartriangle \circledcirc \blacktriangle}$  is true.
- Proof by diagonal-symmetry Immediate from applying  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}$  ((20.0.3(p.136))) to Nem 21.2.5(p.150).
- Direct proof Suppose  $a > 0 \cdots$  (1). Then,  $\tilde{\kappa} = s \cdots$  (2) from Lemma 15.6.6(p.108) (a). In addition,  $\beta b \leq a$  and  $\beta b > a$  are both possible due to [6(p.118)].
  - (a,b) The same as Tom 21.2.6(p.151)(a,b).
  - (c) Let  $\beta b > a$ .
  - (c1-c1ii) The same as Tom 21.2.6(p.151) (c1-c1ii).
- (c2) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c2iii-c2iii2) of Tom 21.2.6(p.151). In this case, since  $\beta b + s = \beta b < b^*$  due to [7(p.118)] and since  $s_{\tilde{\mathcal{L}}} > 0 = s$  from
- Lemma 15.6.5(p.108) (c) with  $\lambda = 1$ , it suffices to consider only (c2iii2) of Tom 21.2.6(p.151).
  - (c3-c3ii) Let  $\beta < 1$  and s > 0, hence  $\tilde{\kappa} > 0$  due to (2). Hence, it suffices to consider only (c2iii1,c2iii2) of Tom 21.2.6(p.151).

#### 21.2.5.2.2 Mixed Restriction

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\square \text{ Mim 21.2.7 } (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]\}^{\pm}) \quad \text{Suppose } a \leq 0 \leq b. \text{ Let } \beta = 1 \text{ and } s = 0.
(a) V_t is nonincreasing in t > 0.
(b) We \text{ have } [\$ \text{ dOITs}_{\tau > 1}\langle \tau \rangle]_{\blacktriangle}.
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ullet Proof The same as Tom 21.2.5(p.151) due to Lemma 18.4.4(p.118).

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\square Mim 21.2.8 (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]^{\pm}\}) Suppose a\leq 0\leq b. Let \beta<1 or s>0.
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- (a)  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V \geq x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $\beta b \leq a$  (impossible).
- (c) Let  $\beta b > a$  (always holds).
  - 1. Let  $\beta = 1$ .
    - i. Let  $b+s \geq b^*$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau>1}\langle 1 \rangle}_{\parallel}$ .
    - ii. Let  $b+s < b^{\star}$ . Then  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ .

  - 3. Let  $\beta < 1$  and s > 0.
    - i. Let  $s < -\beta \tilde{T}(0)$ . Then subseteq doi: 10.5 doi:
    - ii. Let  $s = -\beta \tilde{T}(0)$ .
      - 1. Let  $\beta b + s \geq b^*$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta b + s < b^*$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$ .
    - iii. Let  $s > -\beta \tilde{T}(0)$ .
      - 1. Let  $\beta b + s \geq b^*$  or  $s_{\tilde{\mathcal{L}}} \leq s$ . Then  $\left[ \bullet \operatorname{dOITd}_{\tau > 1} \langle 1 \rangle \right]_{\Delta}$ .
      - 2. Let  $\beta b + s < b^*$  and  $s_{\tilde{\mathcal{L}}} > s$ . Then  $S_2$   $s_{\tilde{\mathcal{L}}} > s_{\tilde{\mathcal{L}}} > s_{\tilde{\mathcal{L}}} = s_{\tilde{\mathcal{L}}} =$
- Proof Let  $b > 0 > a \cdots (1)$ .
  - (a) The same as Tom 21.2.6(p.151) (a).
  - (b,c) Always  $\beta b > a$  due to [10(p.118)], hence  $\beta b \leq a$  is impossible.
  - (c1-c1ii) The same as Tom 21.2.6(p.151) (c1-c1ii).
- (c2) Let  $\beta < 1$  and s = 0. Then, it suffices to consider only (c2i-c2ii2) of Tom 21.2.6(p.151). Let a < 0. Then, the assertion is true from Tom 21.2.6(p.151) (c2i). Let a = 0. Then, since  $\beta b + s = \beta b < b^*$  due to  $\begin{bmatrix} 12(p.118) \end{bmatrix}$ , it suffices to consider only (c2ii2) of Tom 21.2.6(p.151). Accordingly, whether a < 0 or a = 0, we have the same result.

(c3-c3iii2) Let  $\beta < 1$  and s > 0. Then, the assertions hold from Tom 21.2.6(p.151) (c2i-c2iii2) with  $\tilde{\kappa} = \beta \tilde{T}(0) + s$  from (6.1.36(p.27)) with  $\lambda = 1$ .

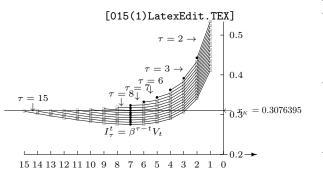
# 21.2.5.2.3 Negative Restriction

- $\square$  Nem 21.2.7 ( $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]^{\mathsf{T}}\}$ ) Suppose a>0. Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in t > 0.
- (b) We have [s] dOITs $_{\tau>1}\langle \tau \rangle$ .
- *Proof* The same as Tom 21.2.5(p.151) due to Lemma 18.4.4(p.118).
- $\square$  Nem 21.2.8 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]^{-}\}$ ) Suppose b<0. Let  $\beta<1$  or s>0.
- (a)  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V \geq x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $\beta b \leq a$  (impossible).
- (c) Let  $\beta b > a$  (always holds).
  - 1. Let  $\beta = 1$ .
    - i. Let  $b+s \geq b^*$ . Then  $\bullet dOITd_{\tau>1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $b + s < b^*$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$
  - 2. Let  $\beta < 1$  and s = 0. Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$
  - 3. Let  $\beta < 1$  and s > 0.
    - i. Let  $s < -\beta \tilde{T}(0)$ . Then  $subseteq dOITs_{\tau>1} \langle \tau \rangle$ .
    - ii. Let  $s = -\beta \tilde{T}(0)$ .
      - 1. Let  $\beta b + s \geq b^*$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
    - iii. Let  $-\beta \tilde{T}(0) < s$ .
      - 1. Let  $\beta b + s \geq b^*$  or  $s_{\tilde{\mathcal{L}}} \leq s$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle |_{\Delta}$ .
      - 2. Let  $\beta b + s < b^*$  and  $s_{\tilde{\mathcal{L}}} > s$ . Then  $S_2$   $s_{\tilde{\mathcal{L}}} \otimes s_{\tilde{\mathcal{L}}} \otimes$

- Proof Let b < 0, hence  $a < b < 0 \cdots (1)$ .
  - (a) The same as Tom 21.2.6(p.151) (a).
  - (b,c) Always  $\beta b > a$  due to [16(p.118)], hence  $\beta b \le a$  is impossible.
  - (c1-c1ii) The same as Tom 21.2.6(p.151) (c1-c1ii).
  - (c2) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c2i) of Tom 21.2.6(p.151).
- (c3-c3iii2) Let  $\beta < 1$  and s > 0. Then, the assertions hold from Tom 21.2.6(p.151) (c2-c2iii2) with  $\tilde{\kappa} = \beta \tilde{T}(0) + s$  from (6.1.36(p.27)) with  $\lambda = 1$ .

## 21.2.6 Numerical Calculation

Numerical Example 4 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]^+\}$  (buying model)



t	$V_t$	$\Delta_{\beta}V_{t}$	$t_{\scriptscriptstyle T}^*$
0			
1	0.544900		
2	0.442388	-0.091614	2
3	0.391004	-0.042535	3
4	0.361335	-0.021849	4
5	0.343013	-0.011094	5
6	0.331264	-0.004889	6
7	0.323555	-0.001084	7
8	0.318422	+0.001338	7
9	0.314972	+0.002918	7
10	0.312638	+0.003965	7
11	0.311053	+0.004667	7
12	0.309973	+0.005141	7
13	0.309236	+0.005462	7
14	0.308732	+0.005681	7
15	0.308388	+0.005830	7
ΔεΙ	$V_t = V_t - \beta V_{t-1}$	015(1)Dat	a.DAT]

Figure 21.2.1: Graphs of  $I_{\tau}^t = \beta^{\tau - t} V_t$  with  $\tau = 2, 3, \dots, 15$  and  $t = 1, 2, \dots, \tau$ 

# 21.2.7 Conclusion 2 (Search-Enforced-Model 1)

# C1. Mental Conflict

On  $\mathscr{F}$ , for any  $\beta \leq 1$  and  $s \geq 0$  we have:

- a. The opt- $\mathbb{R}$ -price  $V_t$  in M:1[ $\mathbb{R}$ ][E] (selling model) is nondecreasing in t as in Figure 8.4.1(p.48) (I) (see Tom's 21.2.1(p.143) (a) and 21.2.2(p.143) (a), hence we have the normal conflict (see Remark 8.4.1(p.48)).
- b. The opt- $\mathbb{P}$ -price  $z_t$  in M:1[ $\mathbb{P}$ ][ $\mathbb{E}$ ] is nondecreasing (selling model) in t as in Figure 8.4.1(p.48) (I) (see Corollary 21.2.1(p.149)), hence we have the normal conflict (see Remark 8.4.1(p.48)).
- c. The opt- $\mathbb{R}$ -price  $V_t$  in  $\tilde{M}:1[\mathbb{R}][E]$  (buying model) is nonincreasing in t as in Figure 8.4.1(p.48) (II) (see Tom's 21.2.1(p.147) (a) and 21.2.2(p.147) (a), hence we have the normal conflict (see Remark 8.4.1(p.48)).
- d. The opt- $\mathbb{P}$ -price  $z_t$  in  $M:1[\mathbb{P}][E]$  (buying model) is nonincreasing in t as in Figure 8.4.1(p.48) (II) (see Corollary 21.2.2(p.151)), hence we have the normal conflict (see Remark 8.4.1(p.48)).

The above results can be summarized as below.

A. On  $\mathscr{F}$ , for any  $\beta \leq 1$  and  $s \geq 0$ , whether selling problem or buying problem and whether  $\mathbb{R}$ -mechanism-model or  $\mathbb{P}$ -mechanism-model, we have the normal mental conflict, which coincides with *expectations* in *Examples* 1.3.1(p.5) - 1.3.4(p.5).

## C2. Symmetry

- a. On  $\mathscr{F}^+$  we have:
  - 1. Let  $\beta = 1$  and s = 0. Then we have:

```
Pom 21.2.3(p.147) \sim Pom 21.2.1(p.145) (\mathscr{A}\{\tilde{M}:1[\mathbb{R}][E]\}^+ \sim \mathscr{A}\{M:1[\mathbb{R}][E]\}^+), Pom 21.2.7(p.151) \sim Pom 21.2.5(p.149) (\mathscr{A}\{\tilde{M}:1[\mathbb{P}][E]\}^+ \sim \mathscr{A}\{M:1[\mathbb{P}][E]\}^+).
```

<sup>†</sup>Since  $a=0.01>0,\,b=1.00,\,\beta=0.98<1,$  and s=0.05>0, we have  $\mu=(0.01+1.00)/2=0.525,\,\beta\mu=0.98\times0.525=0.5145>0.01=a,\,\beta\mu+s=0.5145+0.05=0.5645<1.00=b,$  and  $s=0.05<0.3232736=s_{\tilde{\mathcal{E}}}$ . Thus, the condition of this assertion is satisfied.

2. Let  $\beta < 1$  or s > 0. Then we have:

Pom 21.2.4(p.147) 
$$\rightsquigarrow$$
 Pom 21.2.2(p.145)  $(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\}^+ \rightsquigarrow \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}^+) \cdots (s^1),$   
Pom 21.2.8(p.151)  $\rightsquigarrow$  Pom 21.2.6(p.149)  $(\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]\}^+ \rightsquigarrow \mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]\}^+) \cdots (s^2).$ 

- b. On  $\mathscr{F}^{\pm}$  we have:
  - 1. Let  $\beta = 1$  and s = 0. Then we have:

$$\begin{array}{ll} \text{Mim } 21.2.3 \text{(p.148)} & \sim \text{Mim } 21.2.1 \text{(p.146)} & (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\}^{\pm} \sim \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}^{\pm}), \\ \text{Mim } 21.2.7 \text{(p.152)} & \sim \text{Mim } 21.2.5 \text{(p.150)} & (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]\}^{\pm} \sim \mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]\}^{\pm}). \end{array}$$

2. Let  $\beta < 1$  or s > 0. Then we have:

$$\begin{split} & \text{Mim } 21.2.4 \text{\tiny{(p.148)}} \ \, \sim \text{Mim } 21.2.2 \text{\tiny{(p.146)}} \quad (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\}^{\pm} \ \, \sim \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}^{\pm}), \\ & \text{Mim } 21.2.8 \text{\tiny{(p.152)}} \ \, \sim \text{Mim } 21.2.6 \text{\tiny{(p.150)}} \quad (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]\}^{\pm} \ \, \sim \mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]\}^{\pm}). \end{split}$$

- c. On  $\mathscr{F}^-$  we have:
  - 1. Let  $\beta = 1$  and s = 0. Then we have:

$$\begin{array}{lll} \text{Nem } 21.2.3 \text{(p.148)} & \sim \text{Nem } 21.2.1 \text{(p.146)} & (\mathscr{A}\{\tilde{\mathsf{M}}{:}1[\mathbb{R}][\mathsf{E}]\}^- \sim \mathscr{A}\{\mathsf{M}{:}1[\mathbb{R}][\mathsf{E}]\}^-), \\ \text{Nem } 21.2.7 \text{(p.152)} & \sim \text{Nem } 21.2.5 \text{(p.150)} & (\mathscr{A}\{\tilde{\mathsf{M}}{:}1[\mathbb{P}][\mathsf{E}]\}^- \sim \mathscr{A}\{\mathsf{M}{:}1[\mathbb{P}][\mathsf{E}]\}^-). \\ \end{array}$$

2. Let  $\beta < 1$  or s > 0. Then we have:

The above results can be summarized as below.

- A. On  $\mathscr{F}^{\pm}$ , for any  $\beta \leq 1$  and  $s \geq 0$ , the symmetry is inherited (see C3b(p.154)).
- B. On  $\mathscr{F}^+$  and  $\mathscr{F}^-$ , if  $\beta = 1$  and s = 0, the symmetry is inherited (see C2a1(p.153)/C2c1(p.154)).
- C. On  $\mathscr{F}^+$  and  $\mathscr{F}^-$ , if  $\beta < 1$  or s > 0, the symmetry collapses (see  $(s^1)/(s^2)/(s^3)/(s^4)$ ).
- C3. Analogy
  - a. On  $\mathscr{F}^+$  we have:
    - 1. Let  $\beta = 1$  and s = 0. Then we have:

$$\begin{array}{lll} \text{Pom } 21.2.5 \text{(p.149)} &\bowtie \text{Pom } 21.2.1 \text{(p.145)} & (\mathscr{A}\{M:1[\mathbb{P}][E]\}^+ \bowtie \mathscr{A}\{M:1[\mathbb{R}][E]\}^+), \\ \text{Pom } 21.2.7 \text{(p.151)} &\bowtie \text{Pom } 21.2.3 \text{(p.147)} & (\mathscr{A}\{\tilde{M}:1[\mathbb{P}][E]\}^+ \bowtie \mathscr{A}\{\tilde{M}:1[\mathbb{R}][E]\}^+). \end{array}$$

2. Let  $\beta < 1$  or s > 0. Then we have:

$$\begin{array}{lll} \text{Pom } 21.2.6 \text{(p.149)} & \bowtie \text{Pom } 21.2.2 \text{(p.145)} & (\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathsf{E}]\}^+ \bowtie \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}^+) \cdots (a^1), \\ \text{Pom } 21.2.8 \text{(p.151)} & \bowtie \text{Pom } 21.2.4 \text{(p.147)} & (\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{E}]\}^+ \bowtie \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\}^+). \end{array}$$

- b. On  $\mathscr{F}^{\pm}$  we have:
  - 1. Let  $\beta = 1$  and s = 0. Then we have:

$$\begin{array}{lll} \text{Mim } 21.2.5 \text{(p.150)} & \bowtie \text{Mim } 21.2.1 \text{(p.146)} & (\mathscr{A}\{\mathsf{M}{:}1[\mathbb{P}][\mathsf{E}]\}^{\pm} \bowtie \mathscr{A}\{\mathsf{M}{:}1[\mathbb{R}][\mathsf{E}]\}^{\pm}), \\ \\ \text{Mim } 21.2.7 \text{(p.152)} & \bowtie \text{Mim } 21.2.3 \text{(p.148)} & (\mathscr{A}\{\tilde{\mathsf{M}}{:}1[\mathbb{P}][\mathsf{E}]\}^{\pm} \bowtie \mathscr{A}\{\tilde{\mathsf{M}}{:}1[\mathbb{R}][\mathsf{E}]\}^{\pm}). \end{array}$$

2. Let  $\beta < 1$  or s > 0. Then we have:

- c. On  $\mathscr{F}^-$  we have:
  - 1. Let  $\beta = 1$  and s = 0. Then we have:

Nem 21.2.5(p.150) 
$$\bowtie$$
 Nem 21.2.1(p.146)  $(\mathscr{A}\{M:1[\mathbb{P}][E]\}^- \bowtie \mathscr{A}\{M:1[\mathbb{R}][E]\}^-),$   
Nem 21.2.7(p.152)  $\bowtie$  Nem 21.2.3(p.148)  $(\mathscr{A}\{\tilde{M}:1[\mathbb{P}][E]\}^- \bowtie \mathscr{A}\{\tilde{M}:1[\mathbb{R}][E]\}^-).$ 

2. Let  $\beta < 1$  or s > 0. Then we have:

Nem 21.2.6(p.150) 
$$\bowtie$$
 Nem 21.2.2(p.146)  $(\mathscr{A}\{M:1[\mathbb{P}][E]\}^- \bowtie \mathscr{A}\{M:1[\mathbb{R}][E]\}^-),$   
Nem 21.2.8(p.152)  $\bowtie$  Nem 21.2.4(p.148)  $(\mathscr{A}\{\tilde{M}:1[\mathbb{P}][E]\}^- \bowtie \mathscr{A}\{\tilde{M}:1[\mathbb{R}][E]\}^-) \cdots (a^2).$ 

The above results can be summarized as below.

- A. On  $\mathscr{F}^{\pm}$ , for any  $\beta \leq 1$  and  $s \geq 0$ , the analogy is inherited (see C3b(p.154)).
- B. On  $\mathscr{F}^+$  and  $\mathscr{F}^-$ , if  $\beta=1$  and s=0, then the analogy is inherited (see C3a1(p.154)/C3c1(p.154)).
- C. On  $\mathscr{F}^+$  and  $\mathscr{F}^-$ , if  $\beta < 1$  or s > 0, then the analogy partially collapses (see  $(a^1)/(a^2)$ ).

## C4. Optimal initiating time (OIT)

a. Let  $\beta = 1$  and s = 0. Then, from

Pom 21.2.1(p.145), Mim 21.2.1(p.146), Nem 21.2.1(p.146),

Pom 21.2.3 (p.147), Mim 21.2.3 (p.148), Nem 21.2.3 (p.148),

Pom 21.2.5(p.149), Mim 21.2.5(p.150), Nem 21.2.5(p.150),

Pom 21.2.7(p.151), Mim 21.2.7(p.152), Nem 21.2.7(p.152)

we obtain the following table (the symbol "O" in the table below represents "possible"):

Table 21.2.1: Possible OIT ( $\beta = 1$  and s = 0)

	<b>F</b> +	ℱ±	<i>F</i> -
$\  \  \  \  \  \  \  \  \  \  \  \  \  $			
$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $			
$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	0	0	0
$\odot$ ndOIT $_{ au}\langle t_{ au}^{ullet} angle$ $_{\parallel}$			
$\odot$ ndOIT $_{ au}\langle t_{ au}^{ullet} angle$ $_{ riangle}$			
$\odot$ ndOIT $_{ au}\langle t_{ au}^{ullet} angle$ $lacksquare$			
$lacktriangledown$ d0ITd $_{ au}\langle 0 angle$ $\parallel$			
$lacktriangledown$ d0ITd $_{ au}\langle 0 angle$ $lacktriangledown$ $lacktriangledown$			
$ullet$ dOITd $_{ au}\langle 0 \rangle$ $lack$			

b. ALet Only  $lor_{\bullet}$  is possible nonfront,  $\mathscr{F}^{\pm}$ , and  $\mathscr{F}^{-}$ .

Pom 21.2.2(p.145), Mim 21.2.2(p.146), Nem 21.2.2(p.146),

Pom 21.2.4(p.147), Mim 21.2.4(p.148), Nem 21.2.4(p.148),

Pom 21.2.6(p.149), Mim 21.2.6(p.150), Nem 21.2.6(p.150),

Pom 21.2.8 (p.151), Mim 21.2.8 (p.152), Nem 21.2.8 (p.152)

we obtain the following table:

Table 21.2.2: Possible OIT  $(\beta < 1 \text{ or } s > 0)$ 

	<i>F</i> +	ℱ±	<i>F</i> -
$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $			
$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $			
$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	0	0	0
$\odot$ ndOIT $_{ au}\langle t_{ au}^{ullet} angle$ $\parallel$	0	0	0
$\odot$ ndOIT $_{ au}\langle t_{ au}^{ullet} \rangle$ $_{ riangle}$	0	0	0
$\odot$ ndOIT $_{\tau}\langle t_{\tau}^{\bullet}\rangle$	0	0	0
$lacktriangledown$ dOITd $_{ au}\langle 0  angle$ $lacktriangledown$	0	0	0
lacktriangledown doith $lacktriangledown$ doith $lacktriangledow$	0	0	0
$lacktriangledown$ dOITd $_{ au}\langle 0  angle$ $lacktriangledown$			

The table below is the list of the percents of s, o, and d on  $\mathscr{F}$  appearing in  $\blacksquare$  Tom 21.2.1(p.143) and  $\blacksquare$  Tom 21.2.2(p.143) (see Def. 13.7.1(p.83)).

Table 21.2.3: Occurrence percents of (s), (o), and (d) on  $\mathscr{F}$ 

	s		<b>o</b>					
	41.7%/5		25.0 % / 3		33.3 % / 4			
S <sub>∥</sub>	S	S <sub>▲</sub>	<b>⊚</b> ∥	<ul><li>ο Δ</li></ul>	<b>O</b> _	<b>1</b>	đ۵	<b>Q</b> <sup>v</sup>
_	×	possible	possible	possible	possible	possible	possible	×
-%/-	0.0 %/0	41.7%/5	8.3 % / 1	8.3 % / 1	8.3%/1	16.7%/2	16.7%/2	0.0 %/0

## C5. Null-time-zone and deadline-engulfing

From Table 21.2.3(p.155) above we see that on  $\mathscr{F}$ :

- a. See Remark 8.2.2(p.45) for the noteworthy implication of the symbol (strict optimality).
- b. As a whole we have (s), (o), and (d) at 41.7%, 25.0%, and 33.3% respectively where
  - 1.  $\mathfrak{S}_{\parallel}$  cannot be defined due to Remark 8.2.3(p.45).
  - 2.  $\bigcirc_{\parallel}$  is possible (8.3%).
  - 3.  $\mathbf{d}_{\parallel}$  is possible (16.7%).
  - 4.  $\mathfrak{S}_{\Delta}$  never occur (0.0%).
  - 5.  $\bigcirc_{\vartriangle}$  is possible (3.8%).
  - 6.  $\mathbf{d}_{\Delta}$  is possible (16.7%).
  - 7.  $\textcircled{s}_{\blacktriangle}$  is possible (41.7%).
  - 8.  $\bigcirc_{\blacktriangle}$  is possible (8.3 %).
    - See Tom 21.2.2(p.143) (c2iii2)
  - 9.  $\bullet$  never occur (0.0%).

From the above results we see that on  $\mathscr{F}$ :

- A.  $\odot$  and  $\odot$  causing the null-time-zone are possible at 58.3% (= 25.0% + 33.3%).
- B. ⊙ strictly causing the null-time-zone is possible at 8.3%.

#### C6. Diagonal symmetry

Exercise 21.2.1 Confirm by yourself that the diagonal symmetry below hold in fact:

```
Pom 21.2.3(p.147) d-\sim Nem 21.2.1(p.146),

Pom 21.2.3(p.148) \sim Nem 21.2.1(p.146),

Pom 21.2.5(p.150) d-\sim Nem 21.2.7(p.151),

Pom 21.2.4(p.147) d-\sim Nem 21.2.2(p.146),

Pom 21.2.4(p.148) \sim Nem 21.2.2(p.146),

Pom 21.2.6(p.150) d-\sim Nem 21.2.8(p.151),
```

# 21.3 Conclusions of Model 1

Conclusions 1 (p.139) and 2 (p.153) can be summarized as below.

# C1. Mental Conflict

From C1A(p.139) and C1A(p.153), on  $\mathscr{F}$ , for any  $\beta \leq 1$  and  $s \geq 0$ , whether search-Allowed-model od search-Enforced-model, whether selling problem or buying problem, and whether  $\mathbb{R}$ -mechanism-model or  $\mathbb{P}$ -mechanism-model, we have the normal mental conflict, which coincides with *expectations* in *Examples* 1.3.1(p.5) - 1.3.4(p.6).

## $\overline{\mathsf{C}}2$ . Symmetry

- a. On  $\mathscr{F}^{\pm}$ , for any  $\beta \leq 1$  and  $s \geq 0$ , the symmetry is inherited (see C2A(p.140) and C2A(p.154)).
- b. On  $\mathscr{F}^+$  and  $\mathscr{F}^-$ , if  $\beta=1$  and s=0, the symmetry is inherited (see C2B(p.140) and C2B(p.154)).
- c. On  $\mathscr{F}^+$  and  $\mathscr{F}^-$ , if  $\beta < 1$  or s > 0, the symmetry may collapse on  $\mathscr{F}^+$  and  $\mathscr{F}^-$  (see C2C(p.140) and C2C(p.154)).

## $\overline{C}3$ . Analogy

- a. On  $\mathscr{F}^{\pm}$ , for any  $\beta \leq 1$  and  $s \geq 0$ , the analogy are inherited (see C2A(p.140) and C2A(p.154)).
- b. On  $\mathscr{F}^+$  and  $\mathscr{F}^-$ , if  $\beta=1$  and s=0, the analogy are inherited (see C2B(p.140) and C2B(p.154)).
- c. On  $\mathscr{F}^+$  and  $\mathscr{F}^-$ , if  $\beta < 1$  or s > 0, the analogy may collapse on  $\mathscr{F}^+$  and  $\mathscr{F}^-$  (see C2C(p.140) and C2C(p.154)).

# $\overline{C}4$ . Optimal initiating time (OIT)

On  $\mathscr{F}^+$ ,  $\mathscr{F}^{\pm}$ , and  $\mathscr{F}^-$ , we have:

- a. Let  $\beta=1$  and s=0. Then only  $\mathfrak{S}_{\blacktriangle}$  is possible (see C4aA(p.141) and C4aA(p.155)).
- b. Let  $\beta < 1$  or s > 0. Then:
  - 1. For sA-model we have only  $\S_{\blacktriangle}$ ,  $\bigcirc_{\parallel}$ , and  $\textcircled{d}_{\parallel}$  (see C4bA(p.141)).
  - 2. For sE-model we have  $\S_{\blacktriangle}$ ,  $\bigcirc_{\parallel}$ ,  $\bigcirc_{\vartriangle}$ ,  $\bigcirc_{\blacktriangle}$ ,  $\textcircled{\bullet}_{\parallel}$ , and  $\textcircled{\bullet}_{\vartriangle}$  (see C4bA(p.155)).

Joining Tables 21.1.3(p.141) and 21.2.3(p.155) produces the following table:

Table 21.3.1: Occurance percents of s, o, and d on  $\mathscr{F}$ 

(S)			0			<b>0</b>		
45.5 % / 10			18.2 % / 4			36.3 % / 8		
S <sub>∥</sub>	S	S <sub>▲</sub>	<b>O</b>	<ul><li>ο Δ</li></ul>	<b>O</b> _	<b>①</b>	<b>O</b> <sub>\( \)</sub>	<b>①</b> v
_	×	possible	possible	possible	possible	possible	possible	×
-%/-	0.0%/0	45.5 % / 10	9.0%/2	4.6%/1	4.6%/1	27.3%/6	9.0 % / 2	0.0 %/0

# C5. Null-time-zone and deadline-engulfing

From Table 21.3.1(p.157) above we see that on  ${\mathscr F}$ 

- a. See Remark 8.2.2(p45) for the noteworthy implication of the symbol (strict optimality).
- b. As a whole we have s, o, and d at 45.5%, 18.2%, and 36.3% respectively where
  - 1.  $\mathfrak{S}_{\parallel}$  cannot be defined due to Remark 8.2.3(p.45).
  - 2.  $\bigcirc_{\parallel}$  is possible (9.0%).
  - 3.  $\mathbf{d}_{\parallel}$  is possible (27.3%).
  - 4.  $\mathfrak{S}_{\Delta}$  never occur (0.0%).
  - 5.  $\bigcirc_{\vartriangle}$  is possible (4.6%).
  - 6.  $\mathbf{d}_{\Delta}$  is possible (9.0%).
  - 7.  $\bigcirc$  is possible (45.5%),
  - 8.  $\bigcirc_{\blacktriangle}$  is possible (4.6%).
    - Tom 21.2.2(p.143) (c2iii2)
    - $\mathbf{d}_{\blacktriangle}$  never occur (0.0%).

From the above results we see that:

- A.  $\odot$  and  $\odot$  causing the null-time-zone are possible at 54.5% (= 18.2% + 36.3%).
- B.  $\bigcirc_{\blacktriangle}$  strictly causing the null-time-zone is possible at 4.6%.
- C.  $\mathbf{d}_{\bullet}$  strictly causing the null-time-zone is impossible (0.0%), i.e., the deadline-engulfing is impossible.

# $\overline{\mathsf{C}}6$ . Diagonal symmetry

See C6(p.142) and C6(p.156).

# Chapter 22

# Analysis of Model 2

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# $\mathbf{22.1} \quad \mathbf{Search-Allowed-Model 2:} \quad \mathcal{Q}\{\mathsf{M}:2[\mathtt{A}]\} = \{\mathsf{M}:2[\mathtt{R}][\mathtt{A}], \tilde{\mathsf{M}}:2[\mathtt{R}][\mathtt{A}], \tilde{\mathsf{M}}:2[\mathtt{P}][\mathtt{A}], \tilde{\mathsf{M}}:2[\mathtt{P}][\mathtt{A}]\}$

# 22.1.1 Preliminary

As ones corresponding to Theorems 13.5.1(p.80), 14.3.1(p.97), and 15.5.1(p.106), let us consider the following three theorems:

Theorem 22.1.1 (symmetry 
$$[\mathbb{R} \to \tilde{\mathbb{R}}]$$
) Let  $\mathscr{A}[M:2[\mathbb{R}][A]]$  holds on  $\mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}[\tilde{M}:2[\mathbb{R}][A]]$  holds on  $\mathscr{P} \times \mathscr{F}$  where  $\mathscr{A}[\tilde{M}:2[\mathbb{R}][A]] = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathscr{A}[M:2[\mathbb{R}][A]]]$ .  $\square$  (22.1.1)

Theorem 22.1.2 (analogy 
$$[\mathbb{R} \to \mathbb{P}]$$
) Let  $\mathscr{A}\{M:2[\mathbb{R}][\mathbb{A}]\}\ holds\ on\ \mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}\{M:2[\mathbb{P}][\mathbb{A}]\}\ holds\ on\ \mathscr{P} \times \mathscr{F}\ where$ 

$$\mathscr{A}\{M:2[\mathbb{P}][\mathbb{A}]\} = \mathcal{A}_{\mathbb{R} \to \mathbb{P}}[\mathscr{A}\{M:2[\mathbb{R}][\mathbb{A}]\}]. \quad \Box$$
(22.1.2)

Theorem 22.1.3 (symmetry[
$$\mathbb{P} \to \tilde{\mathbb{P}}$$
]) Let  $\mathscr{A}\{M:2[\mathbb{P}][A]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$ . Then  $\mathscr{A}\{\tilde{M}:2[\mathbb{P}][A]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$  where  $\mathscr{A}\{\tilde{M}:2[\mathbb{P}][A]\}=\mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}[\mathscr{A}\{M:2[\mathbb{P}][A]\}]$ .  $\square$  (22.1.3)

In order for the above three theorems to hold, the following three relations must be satisfied:

$$SOE\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathtt{A}]\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[SOE\{\mathsf{M}:2[\mathbb{R}][\mathtt{A}]\}], \tag{22.1.4}$$

$$SOE\{M:2[\mathbb{P}][A]\} = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[SOE\{M:2[\mathbb{R}][A]\}], \tag{22.1.5}$$

$$\mathrm{SOE}\{\tilde{\mathsf{M}}: 2[\mathbb{P}][\mathtt{A}]\} = \ \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}[\mathrm{SOE}\{\mathsf{M}: 2[\mathbb{P}][\mathtt{A}]\}], \tag{22.1.6}$$

corresponding to (13.5.34(p.77)), (14.2.4(p.93)), and (15.5.4(p.106)). Then, for the same reason as in Chap. 16(p.111) it can be shown that the equality

$$SOE\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{A}]\} = \mathcal{A}_{\tilde{\mathbb{R}} \to \tilde{\mathbb{P}}}[SOE\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{A}]\}]$$
(22.1.7)

holds (corresponding to (16.2.7(p.112))) and that we have the following theorem, corresponding to Theorem 16.2.1(p.112)

Theorem 22.1.4 (analogy 
$$[\tilde{\mathbb{R}} \to \tilde{\mathbb{P}}]$$
) Let  $\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{R}][A]\}$  holds on  $\mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{P}][A]\}$  holds on  $\mathscr{P} \times \mathscr{F}$  where  $\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{P}][A]\} = \mathscr{A}_{\tilde{\mathbb{R}} \to \tilde{\mathbb{P}}}[\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{R}][A]\}]$ .  $\square$  (22.1.8)

In fact, from the comparisons of (I) and (II), of (I) and (III), of (III) and (IV), and of (II) and (IV) in Table 7.4.3(p.41) we can easily show that (22.1.4(p.159)) - (22.1.7(p.159)) hold.

# 22.1.2 A Lemma

The following lemma provides the conditions which determine if each of Theorems 22.1.1(p.159), 22.1.2(p.159), and 22.1.3(p.159) holds by testing whether or not each of (22.1.4(p.159)), (22.1.5(p.159)), and (22.1.6(p.159)) is true.

# Lemma 22.1.1 (M:2[R][A])

- (a) Theorem 22.1.1(p.159) holds.
- (b) Theorem 22.1.3(p.159) holds.
- (c) If  $\rho \leq a^{\star}$  or  $b \leq \rho$ , then Theorem 22.1.2(p.159) holds.
- (d) If  $a^* < \rho < b$ , then Theorem 22.1.2(p.159) does not always hold.  $\square$

• *Proof* (a) From Table 7.4.3(p.41) (I) we have, for any  $\rho \in (-\infty, \infty)$ ,

$$SOE\{M:2[\mathbb{R}][A]\} = \{V_0 = \rho, V_t = \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \quad t > 0\}$$
(22.1.9)

First, applying the operation  $\mathcal{R}$  (see Step 2 (p.75) ) to this leads to

$$\mathcal{R}[SOE\{M:2[\mathbb{R}][\mathbb{A}]\}] = \{-\hat{V}_0 = \rho, -\hat{V}_t = \max\{-\hat{K}(V_{t-1}) - \hat{V}_{t-1}, -\beta\hat{V}_{t-1}\}, \quad t > 0\}$$

$$= \{-\hat{V}_0 = \rho, -\hat{V}_t = -\min\{\hat{K}(V_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \quad t > 0\}$$

$$= \{\hat{V}_0 = -\rho, \ \hat{V}_t = \min\{\hat{K}(V_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \quad t > 0\}$$

$$= \{\hat{V}_0 = \hat{\rho}, -\hat{V}_t = -\min\{\hat{K}(V_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \quad t > 0\}$$

$$(22.1.10)$$

Then, applying  $\mathcal{C}_{\mathbb{R}}$  (see Step 3 (p.75)) to this yields

$$\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathsf{SOE}\{\mathsf{M}:2[\mathbb{R}][\mathsf{A}]\}] = \{\hat{V}_0 = \hat{\rho}, \ \hat{V}_t = \min\{\check{K}(\hat{V}_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \quad t > 0\}. \tag{22.1.11}$$

Finally, applying  $\mathcal{I}_{\mathbb{R}}$  (see Step 4 (p.76)) to this produces

$$\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[SOE\{M:2[\mathbb{R}][\mathbb{A}]\}] = \{\hat{V}_0 = \hat{\rho}, \, \hat{V}_t = \min\{\tilde{K}(\hat{V}_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \quad t > 0\}. \tag{22.1.12}$$

Since this holds for any  $\rho \in (-\infty, \infty)$ , it holds also for  $\hat{\rho} \in (-\infty, \infty)$ , hence holds also for the  $\hat{\hat{\rho}}$ , i.e.,

$$\mathcal{I}_{\mathbb{R}} \mathcal{C}_{\mathbb{R}} \mathcal{R}[\mathsf{SOE}\{\mathsf{M}:2[\mathbb{R}][\mathbf{A}]\}] = \{\hat{V}_0 = \hat{\rho}, \ \hat{V}_t = \min\{\tilde{K}(\hat{V}_{t-1}) + \hat{V}_{t-1}, \beta \hat{V}_{t-1}\}, \quad t > 0\}$$

$$= \{\hat{V}_0 = \rho, \ \hat{V}_t = \min\{\tilde{K}(\hat{V}_{t-1}) + \hat{V}_{t-1}, \beta \hat{V}_{t-1}\}, \quad t > 0\}$$
(22.1.13)

due to  $\rho = \hat{\rho}$ . Now, we have  $\hat{V}_0 = \rho = V_0$  from (7.4.17(p.41)). Suppose  $\hat{V}_{t-1} = V_{t-1}$ . Then, the second term in the r.h.s. of (22.1.13(p.160)) can be rewritten as  $\hat{V}_t = \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} = V_t$ . Thus, by induction  $\hat{V}_t = V_t$  for  $t \geq 0$ . Accordingly (22.1.13(p.160)) can be rewritten as

$$\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[SOE\{M:2[\mathbb{R}][\mathbb{A}]\}] = \{V_0 = \rho, \ V_t = \min\{\tilde{K}(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \quad t > 0,$$
(22.1.14)

which is identical to  $SOE\{\tilde{M}:2[\mathbb{R}][A]\}$  (see Table 7.4.3(p.41) (II)), i.e.,

$$\begin{aligned} & \mathtt{SOE}\{\tilde{\mathsf{M}}{:}2[\mathbb{R}][\mathbb{A}]\} &= \mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathtt{SOE}\{\mathsf{M}{:}2[\mathbb{R}][\mathbb{A}]\}] \\ &= \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathtt{SOE}\{\mathsf{M}{:}2[\mathbb{R}][\mathbb{A}]\}] \quad (\mathrm{see} \ (13.5.30(\mathrm{p.77}))). \end{aligned} \tag{22.1.15}$$

Hence, since (22.1.4(p.159)) holds, it follows that Theorem 22.1.1(p.159) holds.

(b) From Table 7.4.3(p.41) (III) we have, for any  $\rho \in (-\infty, \infty)$ ,

$$\mathtt{SOE}\{\mathsf{M}{:}2[\mathbb{P}][\mathtt{A}]\} = \left\{ \begin{array}{l} V_0 = \rho, \\ V_1 = \max\{\lambda\beta\max\{0, a - \rho\} + \beta\rho - s, \beta\rho\}, \\ V_t = \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\}, \quad t > 1 \end{array} \right\}$$

Applying the operation  $\mathcal{R}$  to this leads to

$$\begin{split} \mathcal{R}[\mathsf{SOE}\{\mathsf{M}:2[\mathbb{P}][\mathtt{A}]\}] \; &= \; \begin{cases} -\hat{V}_0 = \rho, \\ -\hat{V}_1 = \max\{\lambda\beta \max\{0, -\hat{a} - \rho\} + \beta\rho - s, \beta\rho\}, \\ -\hat{V}_t = \max\{-\hat{K}(V_{t-1}) - \hat{V}_{t-1}, -\beta\hat{V}_{t-1}\}, \quad t > 1 \end{cases} \\ &= \; \begin{cases} -\hat{V}_0 = \rho, \\ -\hat{V}_1 = \max\{-\lambda\beta \min\{0, \hat{a} + \rho\} + \beta\rho - s, \beta\rho\}, \\ -\hat{V}_t = -\min\{\hat{K}(V_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \quad t > 1 \end{cases} \\ &= \; \begin{cases} -\hat{V}_0 = \rho, \\ -\hat{V}_1 = -\min\{\hat{K}(V_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \quad t > 1 \end{cases} \\ &= \; \begin{cases} \hat{V}_0 = -\rho, \\ \hat{V}_1 = -\min\{\hat{K}(V_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \quad t > 1 \end{cases} \\ &= \; \begin{cases} \hat{V}_0 = -\rho, \\ \hat{V}_1 = \min\{\lambda\beta \min\{0, \hat{a} + \rho\} + \beta\rho - s, \beta\rho\}, \\ \hat{V}_t = \min\{\hat{K}(V_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \quad t > 1 \end{cases} \\ &= \; \begin{cases} \hat{V}_0 = \hat{\rho}, \\ \hat{V}_1 = \min\{\hat{K}(V_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \quad t > 1 \end{cases} \\ &= \; \begin{cases} \hat{V}_0 = \hat{\rho}, \\ \hat{V}_1 = \min\{\hat{K}(V_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \quad t > 1 \end{cases} \\ \end{pmatrix}. \end{split}$$

Applying  $\mathcal{C}_{\mathbb{P}}$  to this yields

$$\mathcal{C}_{\mathbb{P}}\mathcal{R}[\mathtt{SOE}\{\mathtt{M}{:}2[\mathbb{P}][\mathtt{A}]\}] = \left\{ \begin{array}{l} \hat{V}_0 = \hat{\rho}, \\ \hat{V}_1 = \min\{\lambda\beta\min\{0,\check{b}-\hat{\rho}\} + \beta\hat{\rho} + s, \beta\hat{\rho}\}, \\ \hat{V}_t = \min\{\check{K}\left(\hat{V}_{t-1}\right) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \quad t > 1 \end{array} \right\}.$$

Applying  $\mathcal{I}_{\mathbb{P}}$  to this produces

$$\mathcal{I}_{\mathbb{P}}\mathcal{C}_{\mathbb{P}}\mathcal{R}[\mathrm{SOE}\{\mathsf{M}:2[\mathbb{P}][\mathtt{A}]\}] = \left\{ \begin{array}{l} \hat{V}_0 = \hat{\rho}, \\ \hat{V}_1 = \min\{\lambda\beta\min\{0, b - \hat{\rho}\} + \beta\hat{\rho} + s, \beta\hat{\rho}\}, \\ \hat{V}_t = \min\{\tilde{K}(\hat{V}_{t-1}) + \hat{V}_{t-1}, \beta\hat{V}_{t-1}\}, \quad t > 1 \end{array} \right\}.$$

For the same reason as in the proof of (a), we can replace  $\hat{\rho}$  by  $\rho$ , hence we obtain.

$$\mathcal{I}_{\mathbb{P}}\mathcal{C}_{\mathbb{P}}\mathcal{R}[\mathtt{SOE}\{\mathsf{M}:2[\mathbb{P}][\mathtt{A}]\}] = \left\{ \begin{aligned} V_0 &= \rho, \\ V_1 &= \min\{\lambda\beta\min\{0,b-\rho\} + \beta\rho + s,\beta\rho\}, \\ V_t &= \min\{\tilde{K}(V_{t-1}) + V_{t-1},\beta V_{t-1}\}, \quad t > 1 \end{aligned} \right\},$$

which is the same as  $SOE\{\tilde{M}:2[\mathbb{P}][A]\}$  given by Table 7.4.3(p.41) (IV), hence we have

$$SOE\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathbb{A}]\} = \mathcal{I}_{\mathbb{P}}\mathcal{C}_{\mathbb{P}}\mathcal{R}[SOE\{\mathsf{M}:2[\mathbb{R}][\mathbb{A}]\}]$$
 (22.1.16)

$$= \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}[SOE\{M:2[\mathbb{P}][\mathbb{A}]\}] \quad (\text{see } (15.5.3(\text{p.105}))). \tag{22.1.17}$$

Hence, since (22.1.6(p.159)) holds, it follows that Theorem 22.1.3(p.159) holds.

- (c) Let  $\rho < a^*$  or  $b < \rho$ .
- 1. Let  $\rho \leq a^*$ . Then, since  $\rho \leq a^* < a$  due to Lemma 14.2.1(p.33) (n), we have  $\max\{0, a \rho\} = a \rho \cdots$  (1). In addition, since  $T_{\mathbb{R}}(\rho) = \mu \rho$  from Lemma 11.1.1(p.55) (f) and since  $T_{\mathbb{R}}(\rho) = a \rho$  from Lemma 14.2.1(p.33) (f), we have

$$\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[T_{\mathbb{R}}(\rho)] = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\mu-\rho] = a-\rho = T_{\mathbb{P}}(\rho) = \max\{0, a-\rho\}\cdots(2) \quad \text{(due to (1))}$$

2. Let  $b \le \rho$ . Then, since  $a < b < \rho$ , we have  $\max\{0, a - \rho\} = 0 \cdots$  (3). In addition, since  $T_{\mathbb{R}}(\rho) = 0$  from Lemma 11.1.1(p.55) (g) and since  $T_{\mathbb{P}}(\rho) = 0$  from Lemma 14.2.1(p.93) (g), we have

$$\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[T_{\mathbb{R}}(\rho)] = 0 = T_{\mathbb{P}}(\rho) = \max\{0, a - \rho\} \cdots (4) \quad (\text{due to } (3)).$$

From (2) and (4), whether  $\rho \leq a^*$  or  $b \leq \rho$ , we have

$$\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[T_{\mathbb{R}}(\rho)] = T_{\mathbb{P}}(\rho) = \max\{0, a - \rho\},\tag{22.1.18}$$

hence from (6.1.4(p.25)) we have

$$\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[K_{\mathbb{R}}(\rho)] = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\lambda\beta T_{\mathbb{R}}(\rho) - (1-\beta)\rho - s]$$

$$= \lambda\beta \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[T_{\mathbb{R}}(\rho)] - (1-\beta)\rho - s$$

$$= \lambda\beta \max\{0, a-\rho\} - (1-\beta)\rho - s. \tag{22.1.19}$$

Accordingly, we have

$$\begin{split} \mathcal{A}_{\mathbb{R}\to\mathbb{P}} & [ (7.4.18 (\text{p.4})) \text{ with } t = 1 ] \\ & = \mathcal{A}_{\mathbb{R}\to\mathbb{P}} [ \left\{ V_1 = \max\{K_{\mathbb{R}} \left( V_0 \right) + V_0, \beta V_0 \right\} \right\} ] \\ & = \mathcal{A}_{\mathbb{R}\to\mathbb{P}} [ \left\{ V_1 = \max\{K_{\mathbb{R}} \left( \rho \right) + \rho, \beta \rho \right\} \right\} ] \\ & = \left\{ V_1 = \max\{\mathcal{A}_{\mathbb{R}\to\mathbb{P}} [K_{\mathbb{R}} \left( \rho \right)] + \rho, \beta \rho \right\} \right\} \\ & = \left\{ V_1 = \max\{\lambda \beta \max\{0, a - \rho\} - (1 - \beta)\rho - s + \rho, \beta \rho \} \right\} \quad (\text{due to } (22.1.19 (\text{p.161}))) \\ & = \left\{ V_1 = \max\{\lambda \beta \max\{0, a - \rho\} + \beta \rho - s, \beta \rho \} \right\} \\ & = \left\{ (7.4.22 (\text{p.41})) \right\}. \end{split}$$

The above result means that  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}[(7.4.18(p41)) \text{ with } "t>0"$  is separated into the two cases, (7.4.22(p41)) with "t=1" and (7.4.23(p.41)) "with "t>1". This fact implies that

$$SOE\{M:2[\mathbb{P}][A]\} = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[SOE\{M:2[\mathbb{R}][A]\}]. \tag{22.1.20}$$

Accordingly, since (22.1.5(p.159)) holds whether  $\rho \leq a^*$  or  $b \leq \rho$ , it follows that Theorem 22.1.2(p.159) holds.

(d) Let  $a^* < \rho < b$ . Then, since the same reasoning as in the proof of (c) does not always hold, it follows that Theorem 22.1.2(p.159) does not always hold.

Remark 22.1.1 (pseudo-reflective element  $\rho$ ) Let us recall here that  $\mathcal{R}$  is an operation applied only to attribute elements which depend on the distribution function F (see Section 13.1.1(p.69)). Accordingly, the operation cannot be applied to the constant  $\rho$  which is not related to F, implying that the  $\hat{\rho}$  in the proofs of (a,b) is one resulting from merely rearranging the expression  $-\hat{V}_1 = \rho$  as  $\hat{V}_1 = -\rho \rightarrow \hat{V}_1 = \hat{\rho}$ . However, superficially this transformation  $\rho \rightarrow \hat{\rho}$  seems to be the application of the reflective operation  $\mathcal{R}$  defined in Section 13.1.1(p.69). For this reason, regarding this  $\rho$ , which is originally a non-reflective element, as a reflective element of a sort (see Def. 13.3.3(p.73)), let us call it the pseudo-reflective element.  $\square$ 

# 22.1.3 Diagonal Symmetry

For quite the same reason as in Model 1 (see Chap. 19(p.129)) one sees that the diagonal symmetry holds also for Model 2.

■ Model with  $\mathbb{R}$ -mechanism. In this model we have (see (19.1.25(p.131))-(19.1.30(p.131))):

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{A}]\}^{-} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{A}]^{+}\}],\tag{22.1.21}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathtt{A}]\}^{\pm} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathtt{A}]^{\pm}\}], \tag{22.1.22}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathtt{A}]\}^{+} = \mathcal{S}_{\mathbb{R}\to\hat{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathtt{A}]^{-}\}], \tag{22.1.23}$$

$$\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathbb{R}]\}^{+} = \mathcal{S}_{\mathbb{P}_{\rightarrow\mathbb{R}}}[\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathbb{A}]^{-}\}],\tag{22.1.24}$$

$$\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{R}]\}^{\pm} = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{A}]^{\pm}\}],\tag{22.1.25}$$

$$\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathbb{R}]\}^{-} = \mathcal{S}_{\tilde{\mathbb{M}} \to \mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathbb{A}]^{+}\}]. \tag{22.1.26}$$

Hence we have the following corollary:

## Corollary 22.1.1 We have:

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathtt{A}]\}^{-} \ \mathsf{d}\text{-} \sim \mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathtt{A}]^{+}\} \quad (\mathrm{see}\ (22.1.21(p.162)\ )\ \mathrm{and}\ (22.1.24(p.162)\ )), \tag{22.1.27}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{A}]\}^{\pm} \sim \mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{A}]^{\pm}\} \quad (\text{see } (22.1.22(\text{p.162})) \text{ and } (22.1.25(\text{p.162}))),$$
 (22.1.28)

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathbb{A}]\}^+ d-\sim \mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathbb{A}]^-\} \quad (\text{see } (22.1.23(p.162)) \text{ and } (22.1.26(p.162))). \quad \Box$$
 (22.1.29)

## $\blacksquare$ Model with $\mathbb{P}$ -mechanism. In this model we have:

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{A}]\}^{-} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{P}}}[\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{A}]^{+}\}],\tag{22.1.30}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{A}]\}^{\pm} = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{A}]^{\pm}\}],\tag{22.1.31}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{A}]\}^{+} = \mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}[\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{A}]^{-}\}],\tag{22.1.32}$$

$$\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathbb{A}]\}^{+} = \mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}}[\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathbb{A}]^{-}\}],\tag{22.1.33}$$

$$\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{A}]\}^{\pm} = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{A}]^{\pm}\}],\tag{22.1.34}$$

$$\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{A}]\}^{-} = \mathcal{S}_{\tilde{\mathsf{D}}} \ ,_{\mathbb{P}}[\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{A}]^{+}\}]. \tag{22.1.35}$$

Hence we have the following corollary:

## Corollary 22.1.2 We have:

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathtt{A}]\}^{-} \ \mathtt{d} \sim \mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathtt{A}]^{+}\} \quad (\text{see } (22.1.30(\texttt{p.162})) \ \text{and} \ (22.1.33(\texttt{p.162}))), \tag{22.1.36}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathtt{A}]\}^{\pm} \quad \sim \mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathtt{A}]^{\pm}\} \quad (\text{see } (22.1.31(\text{p.162})) \text{ and } (22.1.34(\text{p.162}))), \tag{22.1.37}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathtt{A}]\}^+ \text{ d-} \sim \mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathtt{A}]^-\} \text{ (see } (22.1.32(\texttt{p.162})) \text{ and } (22.1.35(\texttt{p.162}))). \eqno(22.1.38)$$

# **22.1.4** M:2 $[\mathbb{R}][A]$

## 22.1.4.1 Preliminary

From (7.4.18(p.41)) and (6.1.8(p.25)) we have

$$V_t = \max\{K(V_{t-1}) + (1-\beta)V_{t-1}, 0\} + \beta V_{t-1}$$
  
= \text{max}\{L(V\_{t-1}), 0\} + \beta V\_{t-1}, \quad t > 0, \tag{22.1.39}

hence

$$V_t - \beta V_{t-1} = \max\{L(V_{t-1}), 0\}, \quad t > 0.$$
(22.1.40)

Then, for t > 0 we have

$$V_t = L(V_{t-1}) + \beta V_{t-1} = K(V_{t-1}) + V_{t-1} \quad \text{if } L(V_{t-1}) \ge 0 \quad (\text{see } (6.1.9 (p.25))), \tag{22.1.41}$$

$$V_t = \beta V_{t-1}$$
 if  $L(V_{t-1}) < 0$ . (22.1.42)

Finally, from (7.2.75(p.33)) and from (7.2.71(p.33)) and (7.2.73(p.33)) we have

$$\mathbb{S}_t = L(V_{t-1}) \ge (\le) \ 0 \Rightarrow \mathtt{Conduct}_{t_\Delta}(\mathtt{Skip}_{t_\Delta}), \quad t > 0, \tag{22.1.43}$$

$$\mathbb{S}_t = L(V_{t-1}) > (<) \ 0 \Rightarrow \mathtt{Conduct}_{t \blacktriangle} \ (\mathtt{Skip}_{t \blacktriangle}), \quad t > 0. \tag{22.1.44}$$

## **22.1.4.2** Analysis

#### **22.1.4.2.1** Case of $\beta = 1$ and s = 0

- Tom 22.1.1 ( $\mathscr{A}\{M:2[\mathbb{R}][A]\}$ ) Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\rho \geq b$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\parallel}$ .
- (c) Let  $\rho < b$ . Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}$  where  $Conduct_{\tau\geq t>0}$ .
- Proof Let  $\beta = 1$  and s = 0, hence  $x_L = x_K = b \cdots$  (1) from Lemmas 11.2.3(p.58) (a). Then, since  $K(x) = \lambda T(x) \cdots$  (2) for any x from (6.1.4(p.25)), due to Lemma 11.1.1(p.55) (g) we have  $K(x) \geq 0 \cdots$  (3) for any x and  $K(b) = 0 \cdots$  (4).
- (a) From (7.4.18(p41)) we have  $V_t \ge K(V_{t-1}) + V_{t-1}$  for t > 0, hence  $V_t \ge V_{t-1}$  for t > 0 due to (3). Thus  $V_t$  is nondecreasing in  $t \ge 0$ .
- (b) Let  $\rho \geq b$ , hence  $\rho \geq x_L$  due to (1). Then, since  $V_0 \geq x_L$  from (7.4.17(p.41)), we have  $V_{t-1} \geq x_L$  for t > 0 from (a). Hence, since  $L(V_{t-1}) = 0$  for t > 0 from Lemma 11.2.1(p.57) (d), we have  $V_t \beta V_{t-1} = 0$  for t > 0 from (22.1.40(p.162)), thus  $V_t \beta V_{t-1} = 0$  for  $\tau \geq t > 0$ , i.e.,  $V_t = \beta V_{t-1}$  for  $\tau \geq t > 0$ . Hence, since  $V_\tau = \beta V_{\tau-1} = \cdots = \beta^\tau V_0$ , we have  $t_\tau^* = 0$  for  $\tau > 0$  due to Preference Rule 8.2.1(p.45), i.e.,  $\bullet$  dOITd<sub> $\tau > 0$ </sub>  $\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho < b$ . Then  $V_0 < b$  from (7.4.17(p.41)). Suppose  $V_{t-1} < b$ . Then, from Lemma 11.2.2(p.57) (h) and (7.4.18(p.41)) with  $\beta = 1$  we have  $V_t < \max\{K(b) + b, b\} = \max\{b, b\}$  due to (4), hence  $V_t < b$ . Accordingly, by induction  $V_{t-1} < b \cdots$  (5) for t > 0, so  $V_{t-1} < x_L$  for t > 0 due to (1). Thus, since  $L(V_{t-1}) > 0$  for t > 0 from Lemma 11.2.1(p.57) (d), we have  $L(V_{t-1}) > 0 \cdots$  (6) for  $\tau \ge t > 0$ . Accordingly, from (22.1.40(p.162)) we have  $V_t \beta V_{t-1} > 0$  for  $\tau \ge t > 0$ , i.e.,  $V_t > \beta V_{t-1}$  for  $\tau \ge t > 0$ , hence  $V_\tau > \beta V_{\tau-1} > \cdots > \beta^\tau V_0$ . Accordingly, we have  $t_\tau^* = \tau$  for  $\tau > 0$ , i.e., S(t) = 0. Then Conduct t = 0 for  $t \ge t > 0$  due to (6) and (22.1.44(p.162)).

# **22.1.4.2.2** Case of $\beta < \text{or } s > 0$

For explanatory simplicity, let us define

$$\mathtt{S}_{3} \boxed{ \textcircled{\$ \blacktriangle \circledcirc \Downarrow} } = \left\{ \begin{aligned} & \text{For any } \tau > 1 \text{ there exists } t^{\bullet}_{\tau} > 0 \text{ such that} \\ & (1) \boxed{ \textcircled{\$ dOITs}_{t^{\bullet}_{\tau} \geq \tau > 0} \langle \tau \rangle }_{\blacktriangle} \text{ where } \mathtt{Conduct}_{\tau \geq t > 0 \blacktriangle}, \\ & (2) \boxed{ \textcircled{\$ ndOIT}_{\tau > t^{\bullet}_{\tau}} \langle t^{\bullet}_{\tau} \rangle }_{\parallel} \text{ where } \mathtt{Conduct}_{t^{\bullet}_{\tau} \geq t > 0 \blacktriangle}. \end{aligned} \right\}.$$

- Tom 22.1.2 ( $\mathscr{A}$ {M:2[ $\mathbb{R}$ ][A]}) Let  $\beta < 1$  or s > 0 and let  $\rho < x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \ge 0$ , is strictly increasing in  $t \ge 0$  if  $\lambda < 1$  or  $a < \rho$ , and converges to a finite  $V \ge x_K$  as  $t \to \infty$ .
- (b) Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$  where  $Conduct_{1}$ .  $Below let \tau > 1$ .
  - 2.  $\overline{Let \ \beta = 1}$ .
    - i. Let  $a < \rho$ . Then  $subseteq dOITs_{\tau>1}\langle \tau \rangle$  where  $Conduct_{\tau>t>0}$ .
    - ii. Let  $\rho \leq a$ .
      - 1. Let  $(\lambda \mu s)/\lambda \leq a$ .
        - i. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT $_{\tau > 1}\langle 1 \rangle$   $\parallel$  where Conduct $_{1}$ .
        - ii. Let  $\lambda < 1$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$  where  $Conduct_{\tau > t > 0}$ .
      - 2. Let  $(\lambda \mu s)/\lambda > a$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$  where  $Conduct_{\tau \geq t > 0}$ .
  - 3. Let  $\beta < 1$  and s = 0 ((s > 0)).
    - i. Let  $a < \rho$ .
      - $1. \quad Let \ b \geq 0 \ (\kappa \geq 0) \ . \ Then \ \boxed{\$ \ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle} \ where \ Conduct_{\tau \geq t > 0}_{\blacktriangle}.$
      - 2. Let b < 0 ( $\kappa < 0$ ) . Then  $S_3(p.163)$  S is true.
    - ii. Let  $\rho \leq a$ .
      - 1. Let  $(\lambda \beta \mu s)/\delta \leq a$ .
        - i. Let  $\lambda = 1$ .
          - 1. Let b>0 ( $\kappa>0$ ) . Then  $\odot$  dOITs<sub> $\tau>1$ </sub> $\langle \tau \rangle$  where Conduct<sub> $\tau\geq t>0$ </sub>.
          - 2. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $\odot \text{ ndOIT}_{\tau>1}\langle 1 \rangle$  where  $\text{Conduct}_{1}$ .
        - ii. Let  $\lambda < 1$ .
          - $1. \ \ Let \ \ b \geq 0 \ (\!(\kappa \geq 0)\!) \ . \ \ Then \ \boxed{\$ \ dOITs_{\tau>1}\langle \tau \rangle}_{\blacktriangle} \ \ where \ \ Conduct_{\tau \geq t>0}_{\blacktriangle}.$
          - 2. Let b<0 (( $\kappa<0$ )). Then  $\mathbf{S}_3$ (p.163)  $\boxed{\$}$  is true.
      - 2. Let  $(\lambda \beta \mu s)/\delta > a$ .
        - i. Let  $b \geq 0$  ( $\kappa \geq 0$ ). Then  $startion{$ \otimes dOITs_{\tau>1}\langle \tau \rangle $ }$  where  $Conduct_{\tau \geq t>0}$ .
        - ii. Let b<0 ((  $\kappa<0$  )) . Then  $\mathbf{S}_3$  (p.163)  $\boxed{\$}$  is true.  $\Box$

- Proof Let  $\beta < 1$  or s > 0 and let  $\rho < x_K \cdots$  (1). Then  $V_0 < x_K \cdots$  (2) from (7.4.17(p.41)) and  $K(\rho) > 0 \cdots$  (3) due to Lemma 11.2.2(p.57) (j1). Accordingly, from (7.4.18(p.41)) with t = 1 we have  $V_1 V_0 = V_1 \rho = \max\{K(\rho), \beta\rho \rho\} \ge K(\rho) > 0$  due to (3), hence  $V_1 > V_0 \cdots$  (4).
- (a) Note (4), hence  $V_0 \leq V_1$ . Suppose  $V_{t-1} \leq V_t$ . Then, from (7.4.18(p.41)) and Lemma 11.2.2(p.57) (e) we have  $V_t \leq \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Hence, by induction  $V_t \geq V_{t-1}$  for t > 0, i.e.,  $V_t$  is nondecreasing in  $t \geq 0$ . Again note (4). Suppose  $V_{t-1} < V_t$ . If  $\lambda < 1$ , from Lemma 11.2.2(p.57) (f) we have  $V_t < \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ , and if  $a < \rho$ , then  $a < V_0$  from (7.4.17(p.41)), hence  $a < V_t$  for  $t \geq 0$  due to (a), thus from Lemma 11.2.2(p.57) (g) we have  $V_t < \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Therefore, whether  $\lambda < 1$  or  $a < \rho$ , by induction  $V_{t-1} < V_t$  for t > 0, i.e.,  $V_t$  is strictly increasing in  $t \geq 0$ . Consider a sufficiently large M > 0 with  $\rho \leq M$  and  $\rho \leq M$ , hence  $\rho \leq M$  from (7.4.17(p.41)). Suppose  $\rho V_{t-1} \leq M$ . Then, from Lemma 11.2.2(p.57) (e) and (7.4.18(p.41)) we have  $\rho \leq M$  and  $\rho \leq M$  from (7.4.17(p.41)). Suppose  $\rho V_{t-1} \leq M$ . Then, from Lemma 11.2.2(p.57) (e) and (7.4.18(p.41)) we have  $\rho \leq M$  and  $\rho \leq M$  for  $\rho \leq M$  for  $\rho \leq M$  from (7.4.18(p.41)), we have  $\rho \leq M$  from (7.4.18(p.41)), hence  $\rho V_t \leq M$  for  $\rho \leq M$  from (7.4.18(p.41)), we have  $\rho \leq M$  from (7.4.18(p.41)), hence  $\rho \leq M$  from (7.4.18(p.41)), we have  $\rho \leq M$  from (7.4.18(p.41)), hence  $\rho V_t \leq M$  from (7.4.18(p.41)), we have  $\rho \leq M$  from (7.4.18(p.41)), we have  $\rho \leq M$  from (7.4.18(p.41)), we have  $\rho \leq M$  from (7.4.18(p.41)),
- (b) Let  $x_L \leq \rho$ . Then, since  $x_L \leq V_0$  from (7.4.17(p.4l)), we have  $x_L \leq V_{t-1}$  for t > 0 due to (a), hence  $L(V_{t-1}) \leq 0$  for t > 0 due to Corollary 11.2.1(p.57) (a). Accordingly, since  $V_t \beta V_{t-1} = 0$  for t > 0 from (22.1.40(p.162)), we have  $V_t \beta V_{t-1} = 0$  for  $\tau \geq t > 0$  or equivalently  $V_t = \beta V_{t-1}$  for  $\tau \geq t > 0$ , leading to  $V_\tau = \beta V_{\tau-1} = \cdots = \beta^\tau V_0$ , implying that  $t_\tau^* = 0$  for  $\tau > 0$ , i.e.,  $\left[ \bullet \operatorname{dOITd}_{\tau > 0} \langle 0 \rangle \right]_{\parallel}$ .
  - (c) Let  $\rho < x_L \cdots$  (5), hence  $V_0 < x_L \cdots$  (6) from (7.4.17(p.41)).
- (c1) Since  $L(V_0) = L(\rho) > 0 \cdots$  (7) due to (5) and Corollary 11.2.1(p.57) (a), we have  $V_1 = L(V_0) + \beta V_0 \cdots$  (8) due to (22.1.41(p.162)) with t = 1, hence  $V_1 > \beta V_0 \cdots$  (9). Accordingly, we have  $t_1^* = 1$ , i.e.,  $\boxed{\$ dOITs_1\langle 1 \rangle}_{\blacktriangle} \cdots$  (10) and Conduct<sub>1 \(\Lambda\)</sub> \cdots (11) due to (7) and (22.1.44(p.162)) with t = 1. Below let  $\tau > 1$ .
- (c2) Let  $\beta = 1$ , hence  $s > 0 \cdots$  (12) due to the assumption " $\beta < 1$  or s > 0". Then  $\delta = \lambda \cdots$  (13) from (11.2.1(p.56)) and  $x_L = x_K \cdots$  (14) from Lemma 11.2.3(p.58) (b), hence  $K(x_L) = K(x_K) = 0 \cdots$  (15). Then, from (5) and (14) we have  $\rho < x_K \cdots$  (16).
- (c2i) Let  $a < \rho$ . Then  $a < V_0$  from (7.4.17(p.41)), hence  $a < V_{t-1}$  for t > 0 due to (a). Note (2). Suppose  $V_{t-1} < x_K$ . Then, from (7.4.18(p.41)) with  $\beta = 1$  and Lemma 11.2.2(p.57) (g) we have  $V_t < \max\{K(x_K) + x_K, x_K\} = \max\{x_K, x_K\} = x_K$ . Hence, by induction  $V_{t-1} < x_K$  for t > 0, thus  $V_{t-1} < x_L$  for t > 0 due to (14). Accordingly, since  $L(V_{t-1}) > 0$  for t > 0 from Lemma 11.2.1(p.57) (e1), for almost the same reason as in the proof of Tom 22.1.1(p.163) (c) we have  $\boxed{\text{@ dOITs}_{\tau > 1}\langle \tau \rangle}_{\blacktriangle}$  and  $\text{CONDUCT}_{\tau > t > 0}_{\blacktriangle}$ .
- (c2ii) Let  $\rho \leq a \cdots$  (17). Then  $V_0 \leq a \cdots$  (18) from (7.4.17(p.41)). Here note that (8) can be rewritten as  $V_1 = K(V_0) + V_0 = K(\rho) + \rho \cdots$  (19) due to (6.1.9(p.25)). Then, from (17) and (11.2.7(1)(p.57)) with  $\beta = 1$  we have  $V_1 = \lambda \mu s + (1 \lambda)\rho \cdots$  (20)
- (c2ii) Let  $(\lambda \mu s)/\lambda \leq a$ . Then  $x_K = (\lambda \mu s)/\lambda \leq a \cdots$  (21) from Lemma 11.2.2(p.57) (j2) and (13). Hence  $K(a) \leq 0 \cdots$  (22) from Lemma 11.2.2(p.57) (j1). Note (18). Suppose  $V_{t-1} \leq a$ . Then, from Lemma 11.2.2(p.57) (e) and (7.4.18(p.41)) with  $\beta = 1$  we have  $V_t \leq \max\{K(a) + a, a\} = a$  due to (22), hence by induction  $V_{t-1} \leq a$  for t > 0. Accordingly, from (7.4.18(p.41)) with  $\beta = 1$  and (11.2.7 (1) (p.57)) we have  $V_t = \max\{\lambda \mu s + (1 \lambda)V_{t-1}, V_{t-1}\} \cdots$  (23) for t > 0.
- (c2ii1i) Let  $\lambda=1$ . Then, since  $x_K=\mu-s$  from (21), we have  $V_1=\mu-s=x_K\cdots$  (24) from (20). In addition, from (23) we have  $V_t=\max\{\mu-s,V_{t-1}\}=\max\{x_K,V_{t-1}\}$  for t>0. Note (24). Suppose  $V_{t-1}=x_K$ . Then  $V_t=\max\{x_K,x_K\}=x_K$ . Accordingly, by induction  $V_{t-1}=x_K$  for t>1, thus  $V_{t-1}=x_L$  for t>1 due to (14). Hence  $L(V_{t-1})=L(x_L)=0$  for t>1, so  $L(V_{t-1})=0\cdots$  (25) for  $\tau\geq t>1$ . Then, from (22.1.40(p.162)) we have  $V_t-\beta V_{t-1}=0$  for  $\tau\geq t>1$ , i.e.,  $V_t=\beta V_{t-1}=0$  for  $\tau\geq t>1$ , leading to  $V_\tau=\beta V_{\tau-1}=\cdots=\beta^{\tau-1}V_1$ . From this and (9) we have  $V_\tau=\beta V_{\tau-1}=\cdots=\beta^{\tau-1}V_1>\beta^{\tau}V_0$ , hence  $V_t=1$  for  $V_t=1$  fo
- (c2ii1ii) Let  $\lambda < 1$ . Note (6). Suppose  $V_{t-1} < x_L$ . Then, since  $L(V_{t-1}) > 0$  due to Lemma 11.2.1(p.57) (e1), from (22.1.41(p.162)) and Lemma 11.2.2(p.57) (f) we have  $V_t = K(V_{t-1}) + V_{t-1} < K(x_L) + x_L = x_L$  due to (15). Accordingly, by induction  $V_{t-1} < x_L$  for t > 0, so  $L(V_{t-1}) > 0$  for t > 0 from Lemma 11.2.1(p.57) (e1). Hence, for almost the same reason as in the proof of Tom 22.1.1(p.163) (c) we have  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$  and Conduct $_{\tau \geq t > 0}_{\blacktriangle}$ .
- (c2ii2) Let  $(\lambda \mu s)/\lambda > a$ . Then  $x_K > (\lambda \mu s)/\lambda > a \cdots$  (26) from Lemma 11.2.2(p.57) (j2). Note (6). Suppose  $V_{t-1} < x_L$ . Then  $L(V_{t-1}) > 0$  from Lemma 11.2.1(p.57) (e1), hence  $V_t = K(V_{t-1}) + V_{t-1}$  from (22.1.41(p.162)). Now, since  $a < x_K = x_L$  due to (26) and (14), from Lemma 11.2.2(p.57) (h) we have  $V_t < K(x_L) + x_L = x_L$  due to (15). Accordingly, by induction  $V_{t-1} < x_L \cdots$  (27) for t > 0, thus  $L(V_{t-1}) > 0$  for t > 0 from Lemma 11.2.1(p.57) (e1). Hence, for almost the same reason as in the proof of Tom 22.1.1(p.163) (c) we have  $s = \frac{1}{2} (x_L x_L) + \frac{1}{2} (x_L$ 
  - (c3) Let  $\beta < 1$  and s = 0 (s > 0).
- (c3i) Let  $a < \rho \cdots$  (28). Then, we have  $a < V_0$  from (7.4.17(p.41)), hence  $a < V_{t-1} \cdots$  (29) for t > 0 from (a). Note (4). Suppose  $V_{t-1} < V_t$ . Then, from Lemma 11.2.2(p.57) (g) and (7.4.18(p.41)) we have  $V_t < \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ , hence by induction  $V_{t-1} < V_t$  for t > 0. Accordingly, it follows that  $V_{t-1}$  is strictly increasing in  $t > 0 \cdots$  (30).

(c3i1) Let  $b \ge 0$  ( $\kappa \ge 0$ ). Then,  $x_L \ge x_K \ge 0 \cdots$  (31) from Lemma 11.2.3(p.58) (c (d)). Note (2). Suppose  $V_{t-1} < x_K$ . Then, from (29), Lemma 11.2.2(p.57) (g), and (7.4.18(p.41)) we have  $V_t < \max\{K(x_K) + x_K, \beta x_K\} = \max\{x_K, \beta x_K\} = x_K$  due to  $x_K \ge 0$ . Accordingly, by induction  $V_{t-1} < x_K$  for t > 0. Then, since  $V_{t-1} < x_L$  for t > 0 due to (31), we have  $L(V_{t-1}) > 0$  for t > 0 from Corollary 11.2.1(p.57) (a). Consequently, for almost the same reason as in the proof of Tom 22.1.1(p.163) (c) we have structure (structure (str

(c3i2) Let b < 0 ( $\kappa < 0$ ). Then  $x_L < x_K \cdots$  (32) from Lemma 11.2.3(p.58) (c (d)). Note (6), hence  $V_0 \le x_L$ . Assume that  $V_{t-1} \le x_L$  for all t > 0, hence  $V \le x_L$  due to (a). Then, since  $x_K \le V \cdots$  (33) due to (a), we have the contradiction of  $V \le x_L < x_K \le V$  from (32). Accordingly, it is impossible that  $V_{t-1} \le x_L$  for all t > 0. Therefore, from (6) and (30) we see that there exists  $t_{\tau}^* > 0$  such that

$$V_0 < V_1 < \dots < V_{t^{\bullet}_{\tau}-1} < x_L \le V_{t^{\bullet}_{\tau}} < V_{t^{\bullet}_{\tau}+1} < \dots$$

Hence, for almost the same reason as in the proof of Tom 12.2.2(p.62) (c2iii2) we immediately see that S<sub>3</sub> is true.<sup>‡</sup>

- (c3ii) Let  $\rho \leq a \cdots$  (34), hence  $V_0 \leq a$  from (7.4.17(p.41)). Then, from (19) and (11.2.7(1)(p.57)) we have  $V_1 = \lambda \beta \mu s + (1 \lambda)\beta \rho$ .
- (c3ii1) Let  $(\lambda \beta \mu s)/\delta \le a$ . Then, since  $x_K = (\lambda \beta \mu s)/\delta \le a \cdots$  (35) from Lemma 11.2.2(p.57) (j2), we have  $\delta x_K = \lambda \beta \mu s$ , hence  $V_1 = \delta x_K + (1 \lambda)\beta \rho \cdots$  (36).
- (c3ii1i) Let  $\lambda = 1$ . Then, since  $\delta = 1$  from (11.2.1(p.56)), we have  $x_K = \beta \mu s \le a$  from (35) and  $V_1 = x_K \le a \cdots$  (37) from (36).
- (c3iiii) Let b>0 ( $\kappa>0$ ). Then  $x_L>x_K>0\cdots$  (38) due to Lemma 11.2.3(p.58) (c (d)). Note (37). Suppose  $V_{t-1}=x_K$ . Then, from (7.4.18(p.41)) we have  $V_t=\max\{K(x_K)+x_K,\beta\,x_K\}=\max\{x_K,\beta\,x_K\}=x_K$  due to  $x_K>0$ . Hence, by induction  $V_{t-1}=x_K$  for t>1, thus  $V_{t-1}< x_L$  for t>1 due to (38). Accordingly  $L(V_{t-1})>0$  for t>1 from Corollary 11.2.1(p.57) (a), hence  $L(V_{t-1})>0$  for t>0 due to (7). Therefore, for almost the same reason as in the proof of Tom 22.1.1(p.163) (c) we have S=0 do S=0.
- (c3iii2) Let  $b \le 0$  ( $\kappa \le 0$ ). Then, since  $x_L \le x_K$  due to Lemma 11.2.3(p.58) (c (d)), from (37) we have  $V_1 \ge x_L$ , hence  $V_{t-1} \ge x_L$  for t > 1 from (a), so  $V_{t-1} \ge x_L$  for  $\tau \ge t > 1$ . Accordingly, since  $L(V_{t-1}) \le 0$  for  $\tau \ge t > 1$  from Corollary 11.2.1(p.57) (a), we obtain  $V_t \beta V_{t-1} = 0$  for  $\tau \ge t > 1$  from (22.1.40(p.162)) or equivalently  $V_t = \beta V_{t-1}$  for  $\tau \ge t > 1$ , leading to  $V_\tau = \beta V_{\tau-1} = \cdots = \beta^{\tau-1} V_1$ . From this and (9) we obtain  $V_\tau = \beta V_{\tau-1} = \cdots = \beta^{\tau-1} V_1 > \beta^{\tau} V_0$ , hence  $t_\tau^* = 1$  for  $\tau > 1$ , i.e.,  $\boxed{\bigcirc}$  nd0IT $_{\tau>1}\langle 1 \rangle$ . Then, we have Conduct $_{1,\bullet}$  from (7) and (22.1.44(p.162)) with t=1.
- (c3ii1ii) Let  $\lambda < 1$ . Note (4). Suppose  $V_{t-1} < V_t$ . Then, from (7.4.18(p.41)) and Lemma 11.2.2(p.57) (f) we have  $V_t < \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ , hence by induction  $V_{t-1} < V_t$  for t > 0. Accordingly, it follows that  $V_t$  is strictly increasing in  $t \ge 0 \cdots$  (39).
- (c3ii1ii) Let  $b \ge 0$  ( $\kappa \ge 0$ ). Then  $x_L \ge x_K \ge 0 \cdots$  (40) from Lemma 11.2.3(p.58) (c (d)). Note (2). Suppose  $V_{t-1} < x_K$ . Then, from (7.4.18(p.41)) and Lemma 11.2.2(p.57) (f) we have  $V_t < \max\{K(x_K) + x_K, \beta x_K\} = \max\{x_K, \beta x_K\} = x_K$  due to  $x_K \ge 0$ . Hence, by induction  $V_{t-1} < x_K$  for t > 0, thus  $V_{t-1} < x_L$  for t > 0 due to (40). Accordingly, since  $L(V_{t-1}) > 0$  for t > 0 from Corollary 11.2.1(p.57) (a), for almost the same reason as in the proof of Tom 22.1.1(p.163) (c) we have  $superior (x_K) = x_K + x_$
- (c3ii1ii2) Let b < 0 ( $\kappa < 0$ ). Then  $x_L < x_K$  from Lemma 11.2.3(p.58) (c (d)). Note (6), hence  $V_0 \le x_L$ . Assume that  $V_{t-1} \le x_L$  for all t > 0, hence  $V \le x_L$ . Then, since  $x_K \le V$  from (a), we have the contradiction of  $V \le x_L < x_K \le V$ . Accordingly, it is impossible that  $V_{t-1} \le x_L$  for all t > 0. Therefore, from (6) and (39) we see that there exists  $t_{\tau}^{\bullet} > 0$  such that

$$V_0 < V_1 < \dots < V_{t_{\tau}^{\bullet} - 1} < x_L \le V_{t_{\tau}^{\bullet}} < V_{t_{\tau}^{\bullet} + 1} < \dots,$$

hence for almost the same reason as in the proof of Tom 12.2.2(p.62) (c2iii2) we have  $S_3^{\ddagger}$  is true.

- (c3ii2) Let  $(\lambda \beta \mu s)/\lambda > a \cdots$  (41). Then  $x_K > (\lambda \beta \mu s)/\delta > a \cdots$  (42) from Lemma 11.2.2(p.57) (j2). Let us note here that:
- 1. Let  $\lambda < 1$ . Then  $V_t$  is strictly increasing in  $t \geq 0$  for the same reason as in the proof of (c3ii1ii).
- 2. Let  $\lambda = 1$ . Then  $\beta \mu s > a \cdots$  (43) from (41). Now, since  $K(\rho) + \rho = \beta \mu s$  from (11.2.7 (1) (p.57)) and (34), we have  $V_1 = \beta \mu s$  from (19), hence  $V_1 > a$  from (43), so  $V_{t-1} > a$  for t > 1 from (a). Note (4). Suppose  $V_{t-1} < V_t$ . Then, from (7.4.18(p.41)) and Lemma 11.2.2(p.57) (g) we have  $V_t < \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Accordingly by induction  $V_{t-1} < V_t$  for t > 0, i.e.,  $V_t$  is strictly increasing in t > 0.

Consequently, whether  $\lambda < 1$  or  $\lambda = 1$ , it follows that  $V_t$  is strictly increasing in  $t > 0 \cdots (44)$ .

<sup>&</sup>lt;sup>†</sup>Note that we have  $\boxed{\$ \ \text{dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$  instead of  $\boxed{\$ \ \text{dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$  due to (c1).

 $<sup>{}^{\</sup>ddagger}Note the fine difference between S_3 and S_1(p.61)$ .

<sup>&</sup>lt;sup>‡</sup>Note the fine difference between  $S_3$  and  $S_1$  (p.61).

(c3ii2i) Let  $b \ge 0$  ( $\kappa \ge 0$ ). Then  $x_L \ge x_K \ge 0 \cdots$  (45) from Lemma 11.2.3(p.58) (c (d)). Note (2). Suppose  $V_{t-1} < x_K$ . Then, from (7.4.18(p.41)) and from (42) and Lemma 11.2.2(p.57) (h) we have  $V_t < \max\{K(x_K) + x_K, \beta x_K\} = \max\{x_K, \beta x_K\} = \max\{x_K, \beta x_K\}$  $x_K$  due to  $x_K \ge 0$ . Accordingly, by induction  $V_{t-1} < x_K$  for t > 0, hence  $V_{t-1} < x_L$  for t > 0 from (45), so  $L(V_{t-1}) > 0$ for t > 0 from Corollary 11.2.1(p.57) (a). Hence, for almost the same reason as in the proof of Tom 22.1.1(p.163) (c) we have  $\boxed{$   $\bigcirc \text{dOITs}_{\tau>1}\langle \tau \rangle }$  and  $\text{Conduct}_{\tau\geq t>0}$ .

(c3ii2ii) Let b < 0 ( $\kappa < 0$ ). Then  $x_L < x_K \cdots$  (46) from Lemma 11.2.3(p.58) (c (d)). Note (6). Assume that  $V_{t-1} < x_L$  for all t>0, hence  $V\leq x_L\cdots (47)$ . Now, since  $x_K\leq V$  from (a), we have the contradiction of  $V\leq x_L< x_K\leq V$ . Accordingly, it is impossible that  $V_{t-1} < x_L$  for all t > 0. Therefore, from (44) and (6) we see that there exists  $t_{\tau}^{\bullet} > 0$  such that

$$V_0 < V_1 < \dots < V_{t_{\tau}-1} < x_L \le V_{t_{\tau}} < V_{t_{\tau}+1} < \dots,$$

hence for almost the same reason as in the proof of Tom 12.2.2(p.62) (c2iii2) we have S<sub>3</sub> is true.

- Tom 22.1.3 ( $\mathscr{A}$ {M:2[ $\mathbb{R}$ ][A]}) Let  $\beta < 1$  or s > 0 and let  $\rho = x_K$ .
- (a)  $V_t$  is nondecreasing in t > 0.
- (b) Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\beta < 1$  and  $s = 0 \ (s > 0)$ .
  - 1. Let b>0 ( $\kappa>0$ ) . Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}$  where  $Conduct_{\tau\geq t>0}$ .
  - 2. Let b < 0 ( $\kappa < 0$ ). Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle$ .
- Proof Let  $\beta < 1$  or s > 0 and let  $\rho = x_K$ . Then  $V_0 = x_K \cdots (1)$  from (7.4.17(p.41)), hence  $K(V_0) = K(x_K) = 0 \cdots (2)$ .
- (a) We obtain  $V_1 \geq K(V_0) + V_0 = V_0 \cdots$  (3) from (7.4.18(p.41)) with t = 1 and (2). Suppose  $V_{t-1} \leq V_t$ . Then, from Lemma 11.2.2(p.57) (e) we have  $V_t \leq \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Hence, by induction  $V_t \geq V_{t-1}$  for t > 0, i.e.,  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\beta = 1$ , hence s > 0 due to the assumption " $\beta < 1$  or s > 0". Then  $x_L = x_K$  from Lemma 11.2.3(p.58) (b). Note (1). Suppose  $V_{t-1} = x_K$ . Then, from (7.4.18(p.41)) we have  $V_t = \max\{K(x_K) + x_K, x_K\} = \max\{x_K, x_K\} = x_K$ . Accordingly, by induction  $V_{t-1} = x_K$  for t > 0, hence  $V_{t-1} = x_L$  for t > 0, so  $L(V_{t-1}) = L(x_L) = 0$  for t > 0. Accordingly, for the same reason as in the proof of Tom 22.1.1(p.163) (b) we obtain  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
  - (c) Let  $\beta < 1$  and s = 0 ((s > 0)).
- (c1) Let b > 0 ( $\kappa > 0$ ). Then  $x_L > x_K > 0 \cdots$  (4) from Lemma 11.2.3(p.58) (c (d)). Note (1). Suppose  $V_{t-1} = x_K$ . Then, from (7.4.18(p.41)) we have  $V_t = \max\{K(x_K) + x_K, \beta x_K\} = \max\{x_K, \beta x_K\} = x_K$  due to  $x_K > 0$ . Accordingly, by induction  $V_{t-1} = x_K$  for t > 0, hence  $V_{t-1} < x_L$  for t > 0 due to (4), so  $L(V_{t-1}) > 0$  for t > 0 due to Corollary 11.2.1(p.57) (a). Therefore, for the same reason as in the proof of Tom 22.1.1(p.163) (c) we have  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$  and  $\text{Conduct}_{\tau\geq t>0}_{\blacktriangle}$ .
- (c2) Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then, since  $x_L \leq x_K$  from Lemma 11.2.3(p.58) (c (d)), we have  $x_L \leq V_0$  from (1), hence  $x_L \leq V_{t-1}$ for t > 0 from (a), so  $L(V_{t-1}) \le 0$  for t > 0 due to Corollary 11.2.1(p.57) (a). Then, since  $V_t - \beta V_{t-1} = 0$  for t > 0 from (22.1.40(p.162)), for the same reason as in the proof of Tom 22.1.1(p.163) (b) we obtain  $\bullet$  dOITd $_{\tau>0}$  $\langle 0 \rangle$

ason as in the proof of Tom 22.1.1(p.163) (b) we obtain 
$$\bullet$$
 dult $d_{\tau>0}(0)$ . There exist  $t_{\tau}^{\bullet}$  and  $t_{\tau}^{\circ}$  ( $t_{\tau}^{\bullet} > t_{\tau}^{\circ} \ge 0$ ) such that
$$(1) \bullet doITd_{t_{\tau}^{\bullet} \ge \tau > 0}(0)$$
,
$$(2) \bullet doITs_{\tau>t_{\tau}^{\bullet}}(\tau)$$
, where  $Conduct_{\tau \ge t > t_{\tau}^{\bullet}}$ , ... (1\*) and where  $C \hookrightarrow S_{t_{\tau}^{\circ} \ge t > 0}$ ,  $(C \hookrightarrow S_{t_{\tau}^{\circ} \ge t > 0})$ ,  $(C \hookrightarrow S_{t_{\tau}^{\circ} \ge t > 0}$ 

- Tom 22.1.4 ( $\mathscr{A}$ {M:2[ $\mathbb{R}$ ][A]}) Let  $\beta < 1$  or s > 0 and let  $\rho > x_K$ .
- (a) Let  $\beta = 1$  or  $\rho = 0.$ 
  - 1.  $V_t = \rho \text{ for } t > 0.$
  - 2. Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
  - $3. \quad Let \ x_{\scriptscriptstyle L} > \rho. \ Then \ \boxed{\$ \ \text{dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle} \ \ where \ \text{Conduct}_{\tau \geq t>0\,\blacktriangle}.$
- (b) Let  $\beta < 1$  and  $\rho > 0$  and let s = 0 (s > 0).
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
  - 2. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $| \bullet dOITd_{\tau > 0} \langle 0 \rangle |_{\parallel}$ .
  - 3. Let  $b > 0 ((\kappa > 0))$ .
    - i. Let  $\rho < x_L$ . Then  $subseteq dOITs_{\tau>0}\langle \tau \rangle$  where  $Conduct_{\tau>t>0}$ .
    - ii. Let  $\rho = x_L$ . Then  $\bullet dOITd_1\langle 0 \rangle_{\parallel}$  and  $\odot dOITs_{\tau>1}\langle \tau \rangle_{\blacktriangle}$  where  $Conduct_{\tau>t>0}_{\blacktriangle}$ .
    - iii. Let  $x_L < \rho$ . Then  $S_4$   $\bullet \parallel c_{\neg S\Delta} c_{\neg SA}$  is true.  $\mapsto$

 $\rightarrow$   $\left[ C \rightarrow S \right] _{\blacktriangle}$ 

(c) Let  $\beta < 1$  and  $\rho < 0$  and let s = 0 (s > 0).

<sup>&</sup>lt;sup>†</sup>See Def. 2.2.1(p.12) for the definition of the symbol C→S.

- 1.  $V_t$  is nondecreasing in  $t \geq 0$ .
- $2. \quad Let \ b \leq 0 \ (\!(\kappa \leq 0)\!) \ . \ Then \ \boxed{\bullet \ \mathrm{dOITd}_{\tau>0}\langle 0\rangle}_{\parallel} \, .$
- 3. Let b>0 ( $\kappa>0$ ) . Then  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}$  where  $\text{Conduct}_{\tau\geq t>0}$ .  $\square$
- Proof Let  $\beta < 1$  or s > 0 and let  $\rho > x_K \cdots$  (1). Hence  $V_0 > x_K \cdots$  (2) from (7.4.17(p.41)) and  $K(\rho) < 0 \cdots$  (3) due to Lemma 11.2.2(p.57) (j1). Note that  $V_0 \ge x_K$ . Suppose  $V_{t-1} \ge x_K$ . Then, from (7.4.18(p.41)) and Lemma 11.2.2(p.57) (e) we have  $V_t \ge K(V_{t-1}) + V_{t-1} \ge K(x_K) + x_K = x_K$ . Hence, by induction  $V_{t-1} \ge x_K \cdots$  (4) for t > 0. From (7.4.18(p.41)) with t = 1 we have

$$V_1 - V_0 = V_1 - \rho = \max\{K(V_0) + V_0, \beta V_0\} - \rho = \max\{K(\rho) + \rho, \beta \rho\} - \rho = \max\{K(\rho), -(1-\beta)\rho\} \cdots (5).$$

- (a) Let  $\beta = 1$  or  $\rho = 0$ .
- (a1) Then, since  $-(1-\beta)\rho = 0$ , due to (3) we have  $V_1 V_0 = 0$  from (5), i.e.,  $V_0 = V_1$ . Suppose  $V_{t-1} = V_t$ . Then, from (7.4.18(p.41)) we have  $V_t = \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Thus, by induction  $V_{t-1} = V_t$  for t > 0, i.e.,  $V_0 = V_1 = V_2 = \cdots$ , hence  $V_t = V_0 = \rho$  for t > 0.
- (a2) Let  $x_L \leq \rho$ . Then, since  $x_L \leq V_{t-1}$  for t > 0 from (a1), we have  $L(V_{t-1}) \leq 0$  for t > 0 due to Corollary 11.2.1(p.57) (a), hence  $V_t \beta V_{t-1} = 0$  for t > 0 from (22.1.40(p.162)). Accordingly, for the same reason as in the proof of Tom 22.1.1(p.163) (b) we obtain  $\bullet \text{dOITd}_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (a3) Let  $x_L > \rho$ . Then, since  $x_L > V_{t-1}$  for t > 0 from (a1), we have  $L(V_{t-1}) > 0$  for t > 0 due to Corollary 11.2.1(p.57) (a), hence for the same reason as in the proof of Tom 22.1.1(p.163) (c) we obtain  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$  and Conduct $_{\tau\geq t>0}_{\blacktriangle}$ .
- (b) Let  $\beta < 1 \cdots$  (6) and  $\rho > 0 \cdots$  (7) and let s = 0 (s > 0). Then, since  $-(1 \beta)\rho < 0 \cdots$  (8), from (5) and (3) we have  $V_1 V_0 < 0$ , so  $V_1 > V_0$ , hence  $\rho = V_0 > V_1 \cdots$  (9) from (7.4.17(p.41)).
- (b1) We have  $V_0 \geq V_1$  from (9). Suppose  $V_{t-1} \geq V_t$ . Then, from (7.4.18(p.41)) and Lemma 11.2.2(p.57) (e) we have  $V_t \geq \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Hence, by induction  $V_{t-1} \geq V_t$  for t > 0, i.e.,  $V_t$  is nonincreasing in  $t \geq 0$ . In addition, since  $V_t$  is lower bounded in t due to (4), it follows that  $V_t$  converges to a finite V as  $t \to \infty$ . Accordingly, from (4) we have  $V \geq x_K$ .
- (b2) Let  $b \le 0$  ( $\kappa \le 0$ ). Then, since  $x_L \le x_K$  due to Lemma 11.2.3(p.58) (c (d)), from (4) we have  $V_{t-1} \ge x_L$  for t > 0. Accordingly, since  $L(V_{t-1}) \le 0$  for t > 0 from Corollary 11.2.1(p.57) (a), we have  $V_t \beta V_{t-1} = 0$  for t > 0 from (22.1.40(p.162)), hence for the same reason as in the proof of Tom 22.1.1(p.163) (b) we obtain  $\bullet$  dOITd $_{\tau>0}\langle 0 \rangle_{\parallel}$ .
  - (b3) Let b > 0 (( $\kappa > 0$ )). Then  $x_L > x_K > 0 \cdots$  (10) from Lemma 11.2.3(p.58) (c ((d))).
- (b3i) Let  $\rho < x_L$ . Then, since  $V_0 < x_L$  from (7.4.17(p.41)), we have  $V_{t-1} < x_L$  for t > 0 due to (b1). Therefore, since  $L(V_{t-1}) > 0$  for t > 0 from Corollary 11.2.1(p.57)(a), for the same reason as in the proof of Tom 22.1.1(p.163)(c) we have  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$  and  $\boxed{\text{CONDUCT}_{\tau\geq t>0}_{\blacktriangle}}$ .
- (b3ii) Let  $\rho = x_L \cdots (11)$ . Then, since  $V_0 = x_L$  from (7.4.17(p.41)), we have  $L(V_0) = L(x_L) = 0 \cdots (12)$ , hence from (22.1.42(p.162)) with t = 1 we have  $V_1 = \beta V_0 \cdots (13)$ , so  $t_1^* = 0$ , i.e.,  $\boxed{\bullet \text{dOITd}_1\langle 0 \rangle}_{\parallel}$ . Below let  $\tau > 1$ . From (9) and (11) we have  $V_1 < V_0 = x_L$ . Accordingly, since  $V_{t-1} < x_L$  for t > 1 from (b1), we have  $L(V_{t-1}) > 0 \cdots (14)$  for t > 1 from Corollary 11.2.1(p.57) (a), hence  $L(V_{t-1}) > 0 \cdots (15)$  for  $\tau \ge t > 1$ . Therefore,  $V_t \beta V_{t-1} > 0$  for  $\tau \ge t > 1$  from (22.1.40(p.162)), hence  $V_t > \beta V_{t-1}$  for  $\tau \ge t > 1$ , so that  $V_\tau > \beta V_{\tau-1} > \cdots > \beta^{\tau-1}V_1$ . From this and (13) we obtain  $V_\tau > \beta V_{\tau-1} > \cdots > \beta^{\tau-1}V_1 = \beta^{\tau}V_0$  for  $\tau > 1$ , hence  $t_\tau^* = \tau$  for  $\tau > 1$ , i.e.,  $\boxed{\bullet \text{dOITs}_{\tau > 1}\langle \tau \rangle}_{\bullet}$ . Then Conduct<sub> $t, \bullet$ </sub> for  $\tau \ge t > 1$  due to (15) and (22.1.44(p.162)).
- (b3iii) Let  $x_L < \rho$ , hence  $x_L < V_0 \cdots$  (16) from (7.4.17(p.41)), so  $x_L \le V_0$ . Suppose  $x_L \le V_{t-1} \cdots$  (17) for all t > 0. Then, since  $L(V_{t-1}) \le 0$  for t > 0 from Corollary 11.2.1(p.57) (a), we have  $V_t = \beta V_{t-1}$  for t > 0 from (22.1.42(p.162)), hence  $V_t = \beta^t V_0 = \beta^t \rho > 0$  for  $t \ge 0$  due to (7). Then, since  $\lim_{t\to\infty} V_t = 0$  due to (6), from (10) we have  $x_L > x_K > V_t > 0$  for a sufficiently large t, which contradicts (17). Hence, it is impossible that  $x_L \le V_{t-1}$  for all t > 0. Accordingly, from (16) and (b1) we see that there exist  $t_\tau^{\circ}$  and  $t_\tau^{\bullet}$  ( $t_\tau^{\circ} < t_\tau^{\bullet}$ ) such that

$$V_0 \ge V_1 \ge \cdots \ge V_{t_{-}^{\circ}-1} > V_{t_{-}^{\circ}} = V_{t_{-}^{\circ}+1} = \cdots = V_{t_{-}^{\bullet}-1} = x_L > V_{t_{-}^{\bullet}} \ge V_{t_{-}^{\bullet}+1} \ge \cdots$$
 (18)

Hence, we have

$$x_L > V_{t_{\tau}^{\bullet}}, \quad x_L > V_{t_{\tau}^{\bullet}+1}, \quad \cdots,$$

$$V_{t_{\tau}^{\circ}} = x_L, \quad V_{t_{\tau}^{\circ}+1} = x_L, \quad \cdots, \quad V_{t_{\tau}^{\bullet}-1} = x_L,$$

$$V_0 > x_L, \quad V_1 > x_L, \quad \cdots, \quad V_{t_{\tau}^{\circ}-1} > x_L,$$

or equivalently

$$x_L > V_{t-1} \cdots (19), \qquad t > t_{\tau}^{\bullet},$$
  $V_{t-1} = x_L \cdots (20), \qquad t_{\tau}^{\bullet} \ge t > t_{\tau}^{\circ},$   $V_{t-1} > x_L \cdots (21), \qquad t_{\tau}^{\circ} \ge t > 0.$ 

Accordingly, we have:

<sup>&</sup>lt;sup>†</sup>The inverse of the condition " $\beta=1$  or  $\rho=0$ " is " $\beta<1$  and  $\rho\neq0$ ", which is classified into the two cases of " $\beta<1$  and  $\rho>0$ " and " $\beta<1$  and  $\rho<0$ ", leading to the conditions in (b) and (c) that follows.

- 1. Let  $t_{\tau}^{\bullet} \geq \tau > 0$ . Then, since  $V_{t-1} \geq x_L$  for  $\tau \geq t > 0$  from (20) and (21), we have  $L(V_{t-1}) \leq 0 \cdots$  (22) for  $\tau \geq t > 0$  from Corollary 11.2.1(p.57) (a), hence  $V_t \beta V_{t-1} = 0$  for  $\tau \geq t > 0$  from (22.1.40(p.162)), i.e.,  $V_t = \beta V_{t-1}$  for  $\tau \geq t > 0$ , leading to  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau} V_0 \cdots$  (23), hence  $t_{\tau}^{*} = 0$  for  $t_{\tau}^{\bullet} \geq \tau > 0$ , i.e.,  $\bullet$  doITd $t_{\tau}^{\bullet} \geq \tau > 0$  (3) with  $\tau = t_{\tau}^{\bullet}$  we have  $V_{t_{\tau}^{\bullet}} = \beta V_{t_{\tau-1}} = \cdots = \beta^{t_{\tau}^{\bullet}} V_0 \cdots$  (24),
- 2. Let  $\tau > t_{\tau}^{\bullet}$ . Then, since  $x_L > V_{t-1}$  for  $\tau \geq t > t_{\tau}^{\bullet}$  from (19), we have  $L(V_{t-1}) > 0 \cdots$  (25) for  $\tau \geq t > t_{\tau}^{\bullet}$  from Corollary 11.2.1(p.57) (a), hence  $V_t \beta V_{t-1} > 0$  for  $\tau \geq t > t_{\tau}^{\bullet}$  from (22.1.40(p.162)), i.e.,  $V_t > \beta V_{t-1}$  for  $\tau \geq t > t_{\tau}^{\bullet}$ , leading to  $V_{\tau} > \beta V_{\tau-1} > \cdots > \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} \cdots$  (26). From this and (24) we have

$$V_{\tau} > \beta V_{\tau-1} > \dots > \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} = \beta^{\tau-t_{\tau}^{\bullet}+1} V_{t_{\tau}^{\bullet}-1} = \dots = \beta^{\tau} V_0,$$

hence  $t_{\tau}^* = \tau$  for  $\tau > t_{\tau}^{\bullet}$ , i.e.,  $\boxed{\$ \text{ dOITs}_{\tau > t_{\tau}^{\bullet}}\langle \tau \rangle}_{\blacktriangle}$ , so the former half of  $S_4(2)$  is true.

(i) We have  $\mathtt{Conduct}_{t_{\blacktriangle}}$  for  $\tau \geq t > t_{\tau}^{\bullet} \cdots (27)$  form (25) and (22.1.44(p.162)). Hence the latter half (1\*) of  $\mathtt{S}_{4}(2)$  is true.

Below let us show the latter half  $(2^*)$  and  $(3^*)$  of  $S_4(2)$ .

- (ii) If  $t_{\tau}^{\bullet} \geq t > t_{\tau}^{\circ}$ , then  $L(V_{t-1}) = L(x_L) = 0$  from (20), hence we have  $\operatorname{Skip}_{t^{\Delta}}$  from (22.1.43(p.162)), implying  $\operatorname{C} \hookrightarrow \operatorname{S}_{t^{\Delta}}$  (see Figure 8.2.1(p.44) (II)) or equivalently  $\operatorname{C} \hookrightarrow \operatorname{S}_{t^{\bullet}_{\tau} \geq t > t^{\circ}_{\tau^{\Delta}}}$ . Hence the latter half (2\*) of  $\operatorname{S}_4(2)$  is true.
- (iii) If  $t_{\tau}^{\circ} \geq t > 0$ , then  $L(V_{t-1}) = (<) 0^{\frac{1}{\tau}}$  from (21) and Lemma 11.2.1(p.57) (d (e1)), hence we have  $\operatorname{Skip}_{t^{\Delta}}(\operatorname{Skip}_{t^{\Delta}})$  from (22.1.43(p.162)) ((22.1.44(p.162))), implying  $\operatorname{C} \hookrightarrow \operatorname{S}_{t^{\Delta}}(\operatorname{C} \hookrightarrow \operatorname{S}_{t^{\Delta}})$  or equivalently  $\operatorname{C} \hookrightarrow \operatorname{S}_{t^{2} > t > 0^{\Delta}}(\operatorname{C} \hookrightarrow \operatorname{S}_{t^{2} > t > 0^{\Delta}})$ . Hence the latter half (3\*) of  $\operatorname{S}_{4}(2)$  is true.
- (c) Let  $\beta < 1$  and  $\rho < 0 \cdots (28)$  and let s = 0 (s > 0).
- (c1) Since  $-(1-\beta)\rho > 0$ , from (5) we have  $V_1 V_0 > 0$ , i.e.,  $V_0 < V_1$ , hence  $V_0 \le V_1$ . Suppose  $V_{t-1} \le V_t$ . Then, from (7.4.18(p.41)) and Lemma 11.2.2(p.57) (e) we have  $V_t \le \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Hence, by induction  $V_{t-1} \le V_t$  for t > 0, i.e.,  $V_t$  is nondecreasing in  $t \ge 0$ .
- (c2) Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $x_L \leq x_K$  due to Lemma 11.2.3(p.58) (c (d)), hence from (4) we have  $V_{t-1} \geq x_L$  for t > 0. Accordingly, since  $L(V_{t-1}) \leq 0$  for t > 0 from Corollary 11.2.1(p.57) (a), we have  $V_t \beta V_{t-1} = 0$  for t > 0 from (22.1.40(p.162)), hence for the same reason as in the proof of Tom 22.1.1(p.163) (b) we obtain  $\bullet$  dOITd $_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c3) Let b > 0 ( $\kappa > 0$ ). Then  $x_L > x_K > 0 \cdots$  (29) from Lemma 11.2.3(p.58) (c (d)). Then, since  $\rho < 0 < x_K$  from (28) and (29), we have  $V_0 < x_K$  from (7.4.17(p.41)), hence  $V_0 \le x_K$ . Suppose  $V_{t-1} \le x_K$ , hence  $V_{t-1} < x_L$  form (29), thus  $L(V_{t-1}) > 0$  from Corollary 11.2.1(p.57) (a). Accordingly, from (22.1.41(p.162)) and Lemma 11.2.2(p.57) (e) we have  $V_t = K(V_{t-1}) + V_{t-1} \le K(x_K) + x_K = x_K$ . Hence, by induction  $V_{t-1} \le x_K$  for t > 0, so  $V_{t-1} < x_L$  for t > 0 from (29). Therefore, since  $L(V_{t-1}) > 0 \cdots$  (30) for t > 0 from Corollary 11.2.1(p.57) (a), for the same reason as in the proof of Tom 22.1.1(p.163) (c) we have  $S_t = S_t = S$

# 22.1.4.3 Market Restriction

## 22.1.4.3.1 Positive Restriction

- $\square$  Pom **22.1.1** ( $\mathscr{A}\{M:2[\mathbb{R}][A]^+\}$ ) Suppose a > 0. Let  $\beta = 1$  and s = 0.
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\rho \geq b$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho < b$ . Then  $\[ \odot \]$  dOITs $_{\tau > 0} \langle \tau \rangle \]_{\blacktriangle}$  where Conduct $_{\tau \geq t > 0}_{\blacktriangle}$ .
- *Proof* The same as Tom 22.1.1(p.163) due to Lemma 18.4.4(p.118).
- $\square$  Pom 22.1.2 ( $\mathscr{A}\{M:2[\mathbb{R}][\mathbb{A}]^+\}$ ) Suppose a>0. Let  $\beta<1$  or s>0 and let  $\rho< x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ , is strictly increasing in  $t \geq 0$  if  $\lambda < 1$  or  $a \leq \rho$ , and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
- (b) Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$  where  $Conduct_{1 \blacktriangle}$ .
  - 2. Let  $\beta = 1$ , hence s > 0.
    - i. Let  $a \leq \rho$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1}\langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau \geq t > 0}_{\blacktriangle}$ .
    - ii. Let  $\rho < a$ .
      - 1. Let  $(\lambda \mu s)/\lambda \le a$ .
        - i. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT $_{\tau > 1}\langle 1 \rangle$   $\parallel$  where Conduct $_{1}$ .
        - ii. Let  $\lambda < 1$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau \geq t > 0}_{\blacktriangle}$ .
      - $2. \quad Let \ (\lambda \mu s)/\lambda > a. \ \ Then \ \boxed{\$ \ dOITs_{\tau > 1} \langle \tau \rangle}_\blacktriangle \ \ where \ Conduct_{\tau \geq t > 0}_\blacktriangle.$
  - 3. Let  $\beta < 1$  and s = 0. Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}$  where  $\texttt{Conduct}_{\tau \geq t > 0}$ .

<sup>&</sup>lt;sup>‡</sup>If s = 0, then  $L(V_{t-1}) = 0$ , or else  $L(V_{t-1}) < 0$ .

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4. Let \beta < 1 and s > 0.
            i. Let a < \rho.
                1. Let \lambda \beta \mu \geq s. Then \bigcirc dOITs_{\tau>1} \langle \tau \rangle  where Conduct_{\tau>t>0}.
                2. Let \lambda \beta \mu < s. Then S_3(p.163) s \rightarrow s is true.
            ii. Let \rho \leq a.
                1. Let (\lambda \beta \mu - s)/\delta \leq a.
                    i. Let \lambda = 1.
                        1. Let \beta \mu > s. Then s dOITs_{\tau > 1} \langle \tau \rangle where Conduct_{\tau \geq t > 0}.
                        2. Let \beta \mu \leq s. Then \bigcirc ndOIT<sub>\tau > 1</sub>\langle 1 \rangle<sub>||</sub> where Conduct<sub>1 \( \ldot\)</sub>.
                    ii. Let \lambda < 1.
                        1. Let \lambda \beta \mu \geq s. Then \boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle} where Conduct_{\tau > t > 0}.
                        2. Let \lambda \beta \mu < s. Then S_3(p.163) S^{\bullet} \odot \parallel is true.
                     Let \ (\lambda\beta\mu-s)/\delta>a. \ \ Then \ \boxed{\$ \ dOITs_{\tau>1}\langle\tau\rangle}_\blacktriangle \ \ where \ \ Conduct_{\tau\geq t>0}_\blacktriangle.
• Proof Suppose a > 0 \cdots (1), hence b > a > 0 \cdots (2). Then, we have \kappa = \lambda \beta \mu - s \cdots (3) from
Lemma 11.3.1(p.59) (a).
   (a-c2ii2) The same as Tom 22.1.2(p.163) (a-c2ii2).
   (c3) Let \beta < 1 and s = 0. Then, due to (2) it suffices to consider only (c3i1,c3ii1i1,
c3ii1ii1,c3ii2i) of Tom 22.1.2(p.163).
   (c4) Let \beta < 1 and s > 0.
   (c4i-c4ii1ii2) Immediate from (3) and Tom 22.1.2(p.163) (c3i-c3ii1ii2) with \kappa.
   (c4ii2) Let (\lambda \beta \mu - s)/\delta > a. Then, since (\lambda \beta \mu - s)/\delta > a > 0 due to (1), we have \lambda \beta \mu - s > 0, so that \kappa > 0 due to (3).
Hence, it suffices to consider only (c3ii2i) of Tom 22.1.2(p.163). ■
\square Pom 22.1.3 (\mathscr{A}{M:2[\mathbb{R}][\mathbb{A}]<sup>+</sup>}) Suppose a > 0. Let \beta < 1 or s > 0 and let \rho = x_K.
(a) V_t is nondecreasing in t \geq 0.
(b) Let \beta = 1. Then \bullet dOITd_{\tau > 0} \langle 0 \rangle_{\parallel}.
(c) Let \beta < 1 and s = 0. Then s = 0 where t = 0 where t = 0.
(d) Let \beta < 1 and s > 0.
      1. \quad Let \ \lambda\beta\mu > s. \ \ Then \ \boxed{\$\_dOITs_{\tau>0}\langle\tau\rangle}\_ \ \ where \ \ \mathsf{Conduct}_{\tau\geq t>0}\_.
      2. Let \lambda \beta \mu \leq s. Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}.
• Proof Suppose a > 0, hence b > a > 0 \cdots (1). Then, we have \kappa = \lambda \beta \mu - s \cdots (2) from Lemma 11.3.1(p.59) (a).
   (a,b) The same as Tom 22.1.3(p.166) (a,b).
   (c) Let \beta < 1 and s = 0. Then, due to (1) it suffices to consider only (c1) of Tom 22.1.3(p.166).
   (d) Let \beta < 1 and s > 0.
   (d1,d2) Immediate from (2) and Tom 22.1.3(p.166) (c1,c2) with \kappa.
\square Pom 22.1.4 (\mathscr{A}\{M:2[\mathbb{R}][A]^+\}) Suppose a > 0. Let \beta < 1 or s > 0 and let \rho > x_K.
(a) Let \beta = 1 or \rho = 0.
      1. V_t = \rho \text{ for } t \geq 0.
      2. Let x_L \leq \rho. Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}.
      3. Let x_L > \rho. Then \boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\blacktriangle} where Conduct_{\tau \geq t>0}_{\blacktriangle}.
(b) Let \beta < 1 and \rho > 0 and let s = 0.
      1. V_t is nonincreasing in t \geq 0 and converges to a finite V = x_K as t \to \infty.
      2. Let \rho < x_L. Then subseteq dOITs_{\tau>0} \langle \tau \rangle where conduct_{\tau\geq t>0}.
      3. Let \rho = x_L. Then \boxed{\$ dOITs_{\tau>1}\langle \tau \rangle} where Conduct_{\tau>t>1}.
      4. Let x_L < \rho. Then S_4 \bullet \parallel c \cdot s \land c \cdot s \land s \land s \land t rue.
(c) Let \beta < 1 and \rho > 0 and let s > 0.
      1. V_t is nonincreasing in t > 0 and converges to a finite V = x_K as t \to \infty.
      2. Let \lambda \beta \mu \leq s. Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}.
      3. Let \lambda \beta \mu > s.
            i. Let 
ho < x_{\rm L} . Then \fbox{\$ dOITs_{	au>0}\langle 	au \rangle}_{lacksqrt} where {\tt Conduct}_{	au\geq t>0}_{lacksqrt}.
            Let x_L < \rho. Then S_4 \bullet \parallel c_{\leadsto s \Delta} c_{\leadsto s \Delta} is true (see Numerical Example 5(p.198)).
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- (d) Let  $\beta < 1$  and  $\rho < 0$  and let s = 0.
  - 1.  $V_t$  is nondecreasing in  $t \geq 0$ .
  - 2.  $\boxed{\$ dOITs_{\tau>0}\langle\tau\rangle}$  where  $Conduct_{\tau\geq t>0}$ .
- (e) Let  $\beta < 1$  and  $\rho < 0$  and let s > 0.
  - 1.  $V_t$  is nondecreasing in  $t \geq 0$ .
  - 2. Let  $\lambda \beta \mu \leq s$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
  - 3. Let  $\lambda \beta \mu > s$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle_{\blacktriangle}$  where  $Conduct_{\tau>t>0}_{\blacktriangle}$ .
- Proof Suppose a > 0, hence  $b > \mu > a > 0 \cdots$  (1). Then  $\kappa = \lambda \beta \mu s \cdots$  (2) from Lemma 11.3.1(p.59) (a).
  - (a-a3) The same as Tom 22.1.4(p.166) (a-a3).
- (b-b4) Let  $\beta < 1$  and  $\rho > 0$  and let s = 0. First, (b1) is the same as Tom 22.1.4(p.166) (b1). Next, due to (1) it suffices to consider only (b3i-b3iii) of Tom 22.1.4(p.166).
- (c-c3iii) Let  $\beta < 1$  and  $\rho > 0$  and let s > 0. First, (c1) is the same as Tom 22.1.4(p.166) (b1). Next, due to (1) it suffices to consider only (b3i-b3iii) of Tom 22.1.4(p.166).
- (d-d2) Let  $\beta < 1$  and  $\rho < 0$  and let s = 0. First, (d1) is the same as Tom 22.1.4(p.166) (c1). Next, since  $\kappa = \lambda \beta \mu > 0$  due to (2) and (1), it suffices to consider only (c3) of Tom 22.1.4(p.166).
- (e-e3) Let  $\beta < 1$  and  $\rho < 0$  and let s > 0. First, (e1) is the same as Tom 22.1.4(p.166) (c1). Next, (e2,e3) are the same as Tom 22.1.4(p.166) (c2,c3) with  $\kappa$ .

## 22.1.4.3.2 Mixed Restriction

Omitted.

# 22.1.4.3.3 Negative Restriction

- $\square$  Nem 22.1.1 ( $\mathscr{A}\{M:2[\mathbb{R}][\mathbb{A}]^-\}$ ) Suppose b < 0. Let  $\beta = 1$  and s = 0.
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\rho \geq b$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho \geq b$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (d) Let  $\rho < b$ . Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$  where  $Conduct_{\tau>t>0}_{\blacktriangle}$ .
- Proof The same as Tom 22.1.1(p.163) due to Lemma 18.4.4(p.118).
- $\square$  Nem 22.1.2 ( $\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathbb{A}]^-\}$ ) Suppose b<0. Let  $\beta<1$  or s>0 and let  $\rho< x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ , is strictly increasing in  $t \geq 0$  if  $\lambda < 1$  or  $a \leq \rho$ , and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
- (b) Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle$
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$  where  $Conduct_{1}$ .
  - 2. Let  $\beta = 1$ .
    - i. Let  $a \leq \rho$ . Then  $subseteq dOITs_{\tau>1}\langle \tau \rangle$  where  $conduct_{\tau \geq t>0}$ .
    - ii. Let  $\rho < a$ .
      - 1. Let  $(\lambda \mu s)/\lambda \le a$ .
        - i. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT $_{\tau > 1}\langle 1 \rangle$  where Conduct $_{1}$ .
        - ii. Let  $\lambda < 1$ . Then  $subseteq dOITs_{\tau>1}\langle \tau \rangle$  where  $conduct_{\tau \geq t>0}$ .
      - $2. \quad Let \ (\lambda \mu s)/\lambda > a. \ \ Then \ \boxed{\$ \ \text{dOITs}_{\tau \geq 1} \langle \tau \rangle}_{\blacktriangle} \ \ where \ \text{Conduct}_{\tau \geq t > 0}_{\blacktriangle}.$
  - 3. Let  $\beta < 1$  and s = 0. Then we have  $S_3(p.163)$   $\boxed{\$ \blacktriangle \circledcirc \$ \rfloor}$
  - 4. Let  $\beta < 1$  and s > 0.
    - i. Let  $a<\rho$ . Then  $S_3(p.163)$   $^{\textcircled{\$} \blacktriangle \textcircled{0} \parallel}$  is true.
    - ii. Let  $\rho \leq a$ .
      - 1. Let  $(\lambda \beta \mu s)/\delta \leq a$ .
        - i. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT $_{\tau > 1}\langle 1 \rangle$  where Conduct $_{1}$ .
        - ii. Let  $\lambda < 1$ . Then  $S_3(p.163)$   $\bigcirc A \bigcirc A$  is true.
      - 2. Let  $(\lambda \beta \mu s)/\delta > a$ . Then  $S_3(p.163)$  sample sam
- Proof Suppose  $b < 0 \cdots (1)$ , hence  $a < b < 0 \cdots (2)$  and  $\kappa = -s \cdots (3)$  from Lemma 11.3.1(p.59) (a).

(a-c2ii2) The same as Tom 22.1.2(p.163) (a-c2ii2).

- (c3) Let  $\beta < 1$  and s = 0. Assume  $(\lambda \beta \mu s)/\delta \le a$ . Then, since  $\lambda \beta \mu / \delta \le a$ , we have  $\lambda \beta \mu \le \delta a$ , hence  $\lambda \beta \mu \le \delta a \le \lambda a$  due to (2) and (11.2.2 (1) (p.56)), so that  $\beta \mu \le a$ , which contradicts [15(p.118)]. Thus it must be that  $(\lambda \beta \mu s)/\delta > a$ . From this and (1) it suffices to consider only (c3i2,c3ii2ii) of Tom 22.1.2(p.163).
- (c4-c4ii2) Let  $\beta < 1$  and s > 0. Then  $\kappa < 0$  due to (3). Hence, it suffices to consider only (c3i2,c3ii1i2,c3ii1ii2,c3ii2ii) of Tom 22.1.2(p.163) with  $\kappa$ .

- $\square$  Nem 22.1.3 ( $\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathtt{A}]^-\}$ ) Suppose b<0. Let  $\beta<1$  or s>0 and let  $\rho=x_K$ .
- (a)  $V_t$  is nondecreasing in t > 0.
- (b) We have  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- Proof Suppose  $b < 0 \cdots (1)$ . Then  $\kappa = -s \cdots (2)$  from Lemma 11.3.1(p.59) (a).
  - (a) The same as Tom 22.1.3(p.166) (a).
- (b) Let  $\beta=1$ . Then, it suffices to consider only (b) of Tom 22.1.3(p.166), we have  $\boxed{\bullet \text{dOTTd}_{\tau>0}\langle 0 \rangle}_{\parallel}$ . Let  $\beta<1$ . If s=0, then due to (1) it suffices to consider only (c2) of Tom 22.1.3(p.166) and if s>0, then  $\kappa<0$  due to (2), hence it suffices to consider only (c2) of Tom 22.1.3(p.166). Thus, whether s=0 or s>0, we have  $\boxed{\bullet \text{dOTTd}_{\tau>0}\langle 0 \rangle}_{\parallel}$ . Accordingly, whether  $\beta=1$  or  $\beta<1$ , it eventually follows that we have  $\boxed{\bullet \text{dOTTd}_{\tau>0}\langle 0 \rangle}_{\parallel}$ .
- $\square$  Nem 22.1.4 ( $\mathscr{A}\{M:2[\mathbb{R}][\mathbb{A}]^-\}$ ) Suppose b<0. Let  $\beta<1$  or s>0 and let  $\rho>x_K$ .
- (a) Let  $\beta = 1$  or  $\rho = 0$ .
  - 1.  $V_t = \rho \text{ for } t \geq 0.$
  - 2.  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
  - 3. Let  $x_L > \rho$ . Then  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau\geq t>0}_{\blacktriangle}$ .
- (b) Let  $\beta < 1$  and  $\rho > 0$ .
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
  - 2. We have Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle$
- (c) Let  $\beta < 1$  and  $\rho < 0$ .
  - 1.  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
  - 2. We have  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- Proof Suppose  $b < 0 \cdots (1)$ , hence  $\kappa = -s \cdots (2)$  from Lemma 11.3.1(p.59) (a).
  - (a-a3) The same as Tom 22.1.4(p.166) (a-a3).
  - (b) Let  $\beta < 1$  and  $\rho > 0$ .
  - (b1) The same as Tom 22.1.4(p.166) (b1).
- (b2) If s = 0, then due to (1) it suffices to consider only (b2) of Tom 22.1.4(p.166) and if s > 0, then  $\kappa < 0$  due to (2), hence it suffices to consider only (b2) of Tom 22.1.4(p.166). Thus, whether s = 0 or s > 0, it eventually follows that we have the same result.
  - (c) Let  $\beta < 1$  and  $\rho < 0$ .
  - (c1) The same as Tom 22.1.4(p.166) (c1).
- (c2) If s=0, then due to (1) it suffices to consider only (c2) of Tom 22.1.4(p.166) and if s>0, then  $\kappa<0$  due to (2), hence it suffices to consider only (c2) of Tom 22.1.4(p.166). Thus, whether s=0 or s>0, it eventually follows that we have the same result.

# **22.1.5** $\tilde{M}:2[\mathbb{R}][A]$

## 22.1.5.1 Preliminary

Due to Lemma 22.1.1(p.159) (a), we see that the following Tom's 22.1.1(p.171) -22.1.4(p.172) can be obtained by applying  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Tom's 22.1.1(p.163)-22.1.4(p.166) (see Theorem 22.1.1(p.159)).

# 22.1.5.2 Analysis

# 22.1.5.2.1 Case of $\beta = 1$ and s = 0

- $\square$  Tom 22.1.1 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{A}]\}$ ) Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in t > 0.
- (b) Let  $\rho \leq a$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho > a$ . Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}$  where  $Conduct_{\tau\geq t>0}$ .
- Proof by symmetry Immediate from applying  $S_{\mathbb{R} \to \tilde{\mathbb{R}}}$  to Tom 22.1.1(p.163).

# 22.1.5.2.2 Case of $\beta < 1$ or s > 0

- (a)  $V_t$  is nonincreasing in  $t \geq 0$ , is strictly decreasing in  $t \geq 0$  if  $\lambda < 1$  or  $b > \rho$ , and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $x_{\tilde{L}} \geq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho > x_{\tilde{L}}$ .
  - 1.  $\bigcirc$  dOITs<sub>1</sub> $\langle 1 \rangle$  where Conduct<sub>1</sub>. Below let  $\tau > 1$ .
  - 2. Let  $\beta = 1$ .

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i. Let b > \rho. Then \boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle} where Conduct_{\tau \geq t > 0}.
              ii. Let \rho \geq b.
                    1. Let (\lambda \mu + s)/\lambda \ge b.
                         i. Let \lambda = 1. Then \bigcirc ndOIT_{\tau > 1}\langle 1 \rangle where Conduct_{1}.
                         ii. Let \lambda < 1. Then \boxed{\$} dOITs_{\tau > 1} \langle \tau \rangle \rfloor_{\blacktriangle} where Conduct_{\tau \geq t > 0}_{\blacktriangle}.
                    2. Let (\lambda \mu + s)/\lambda < b. Then [\$] dOITs_{\tau > 1} \langle \tau \rangle where Conduct_{\tau \geq t > 0}.
       3. Let \beta < 1 and s = 0 (s > 0).
               i. Let b > \rho.
                    1. Let a \leq 0 (\tilde{\kappa} \leq 0). Then subseteq dollars_{\tau>1}\langle \tau \rangle where conduct_{\tau \geq t>0}.
                    2. Let a > 0 (\tilde{\kappa} > 0). Then S_3(p.163) sample 1 is true.
              ii. Let \rho \geq b.
                    1. Let (\lambda \beta \mu + s)/\delta \ge b.
                         i. Let \lambda = 1.
                             1. \ \ Let \ a<0 \ (\tilde{\kappa}<0). \ \ Then \ \boxed{\$ \ \text{dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle} \ \ where \ \text{Conduct}_{\tau\geq t>0}_{\blacktriangle}.
                             2. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \boxed{\odot} ndOIT<sub>\tau > 1</sub>\langle 1 \rangle | where Conduct<sub>1</sub>.
                         ii. Let \lambda < 1.
                             1. Let a \leq 0 (\tilde{\kappa} \leq 0). Then startion{$ \otimes dOITs_{\tau>1}\langle \tau \rangle |_{\blacktriangle}$ where <math>Conduct_{\tau \geq t>0}_{\blacktriangle}$.}
                             2. Let a > 0 (\tilde{\kappa} > 0). Then S_3(p.163) | S_{\bullet} | O_{\parallel} | is true.
                    2. Let (\lambda \beta \mu + s)/\delta < b.
                          i. Let a \leq 0 (\tilde{\kappa} \leq 0). Then \boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle} where \text{Conduct}_{\tau \geq t > 0}_{\blacktriangle}.
                         ii. Let a>0 (\tilde{\kappa}>0). Then S_3(p.163) sample 1 is true. \square
ullet Proof by symmetry Immediate from applying \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} to Tom 22.1.2(p.163).
\square Tom 22.1.3 (\mathscr{A}\{M:2[\mathbb{R}][A]\}) Let \beta < 1 or s > 0 and let \rho = x_{\tilde{K}}.
(a) V_t is nonincreasing in t > 0.
(b) Let \beta = 1. Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}.
(c) Let \beta < 1 and s = 0 (s > 0).
       1. Let a < 0 (\tilde{\kappa} < 0). Then subseteq dOITs_{\tau>0} \langle \tau \rangle where conduct_{\tau \geq t>0}.
       2. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \bullet dOITd_{\tau>0}\langle 0 \rangle.
• Proof by symmetry Immediate from applying \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} to Tom 22.1.3(p.166).
\square Tom 22.1.4 (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{A}]\}) Let \beta<1 or s>0 and let \rho< x_{\tilde{K}}.
(a) Let \beta = 1 or \rho = 0.
       1. V_t = \rho \text{ for } t \geq 0.
       2. Let x_{\tilde{L}} \geq \rho. Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}.
       3. \quad Let \ x_{\tilde{L}} < \rho. \ Then \ \boxed{\$ \ \text{dOITs}_{\tau>0}\langle \tau \rangle} \ \blacktriangle \ where \ \text{Conduct}_{\tau>t>0} \blacktriangle.
(b) Let \beta < 1 and \rho < 0 and let s = 0 (s > 0).
       1. V_t is nondecreasing in t \ge 0 and converges to a finite V = x_{\tilde{K}} as t \to \infty.
       2. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \bullet dOITd_{\tau > 0}\langle 0 \rangle
       3. Let a < 0 \ (\tilde{\kappa} < 0).
               i. Let \rho > x_{\tilde{L}}. Then \bigcirc dOITs_{\tau>0}\langle \tau \rangle where Conduct_{\tau\geq t>0}.
              \text{ii.} \quad Let \ \rho = \ x_{\tilde{L}} \ . \ \ Then \ \boxed{\bullet \ \text{dOIT}} \underline{\text{d}_1 \langle 0 \rangle}_{\parallel} \ \ and \ \boxed{\$ \ \text{dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle} \ \ where \ \text{Conduct}_{\tau \geq t > 0}_{\blacktriangle}.
             iii. Let x_{\tilde{L}} > \rho. Then S_4 \bullet \parallel c - s \Delta c - s A is true.
(c) Let \beta < 1 and \rho > 0 and let s = 0 (s > 0).
       1. V_t is nonincreasing in t \geq 0 and converges to a finite V = x_{\tilde{K}} as t \to \infty.
       2. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}.
       3. Let a < 0 (\tilde{\kappa} < 0). Then subseteq dOITs_{\tau>0} \langle \tau \rangle where Conduct_{\tau \geq t>0}.
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• Proof by symmetry Immediate from applying  $\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}$  (see to Tom 22.1.4(p.166).

#### 22.1.5.3 Market Restriction

## 22.1.5.3.1 Positive Restriction

- $\square$  Pom 22.1.5 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{A}]^+\}$ ) Suppose a>0. Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in  $t \geq 0$ .
- (b) Let  $\rho \leq a$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- $(\mathbf{c}) \quad Let \; \rho > a. \; \; Then \; \boxed{\$ \; \mathsf{dOITs}_{\tau > 0} \langle \tau \rangle}_{\blacktriangle} \; \; where \; \mathsf{Conduct}_{\tau \geq t > 0}_{\blacktriangle}.$
- Proof by diagonal-symmetry Immediate from applying  $S_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Nem 22.1.1(p.170) (see (19.1.21(p.131))). ■
- Direct proof The same as Tom 22.1.1(p.171) due to Lemma 18.4.4(p.118).
- $\square$  Pom 22.1.6  $(\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathbb{A}]^+\})$  Suppose a>0. Let  $\beta<1$  or s>0 and let  $\rho>x_{\tilde{K}}$ .
- (a)  $V_t$  is nonincreasing in  $t \geq 0$ , is strictly decreasing in  $t \geq 0$  if  $\lambda < 1$  or  $b \geq \rho$ , and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $x_{\tilde{L}} \geq \rho$ . Then  $\boxed{\bullet dOITd_{\tau>0}\langle 0 \rangle}_{\parallel}$ .
- (c) Let  $\rho > x_{\tilde{L}}$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$  where  $Conduct_{1\blacktriangle}$ . Below let  $\tau > 1$ .
  - 2. Let  $\beta = 1$ .
    - i. Let  $b > \rho$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau \geq t > 0}_{\blacktriangle}$ .
    - ii. Let  $\rho \geq b$ .
      - 1. Let  $(\lambda \mu + s)/\lambda \ge b$ .
        - i. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT $_{\tau > 1}\langle 1 \rangle$  where Conduct $_{1}$ .
        - ii. Let  $\lambda < 1$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$  where  $Conduct_{\tau \geq t > 0}$ .
      - 2. Let  $(\lambda \mu + s)/\lambda < b$ . Then subseteq doi: to the subseteq subseteq <math>t = t + s.
  - 3. Let  $\beta < 1$  and s = 0. Then we have  $S_3(p.163)$   $\boxed{\$ \blacktriangle \circledcirc \blacksquare}$
  - 4. Let  $\beta < 1$  and s > 0.
    - i. Let  $b > \rho$ . Then  $S_3(p.163)$   $\bigcirc S_4 \bigcirc B$  is true.
    - ii. Let  $\rho \geq b$ .
      - 1. Let  $(\lambda \beta \mu + s)/\delta \geq b$ .
        - i. Let  $\lambda = 1$ . Then  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\parallel}$  where  $\texttt{Conduct}_{1_{\blacktriangle}}$ .
        - ii. Let  $\lambda < 1$ . Then  $S_3(p.163)$   $\bigcirc \square$  is true.
      - 2. Let  $(\lambda \beta \mu + s)/\delta < b$ . Then  $S_3(p.163)$   $s \to 0$  is true.  $\Box$
- Proof by diagonal-symmetry Immediate from applying  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Nem 22.1.2(p.170) (see (19.1.21(p.131))). ■
- Direct proof Suppose  $a > 0 \cdots$  (1), hence  $b > a > 0 \cdots$  (2) and  $\tilde{\kappa} = s \cdots$  (3) from Lemma 13.6.6(p.83) (a).

(a-c2ii2) The same as Tom 22.1.2(p.171) (a-c2ii2).

- (c3) Let  $\beta < 1$  and s = 0. Assume  $(\lambda \beta \mu + s)/\delta \ge b$ . Then, since  $\lambda \beta \mu/\delta \ge b$ , we have  $\lambda \beta \mu \ge \delta b$ , hence  $\lambda \beta \mu \ge \delta b \ge \lambda b$  due to (2) and (11.2.2 (1) (p.56)), so that  $\beta \mu \ge b$ , which contradicts [3(p.118)]. Thus, it must be that  $(\lambda \beta \mu + s)/\delta < b$ . From this and (1) it suffices to consider only (c3ii2ii) of Tom 22.1.2(p.171).
- (c4-c4ii2) If  $\beta < 1$  and s > 0, then  $\kappa > 0$  due to (3), hence it suffices to consider only (c3i2,c3ii1i2,c3ii1ii2,c3ii2ii) with  $\kappa$ .
- $\square$  Pom 22.1.7 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathbb{A}]^+\}$ ) Suppose a>0. Let  $\beta<1$  or s>0 and let  $\rho=x_{\tilde{K}}$ .
- (a)  $V_t$  is nonincreasing in  $t \geq 0$ .
- (b) We have  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .  $\square$
- Proof by diagonal-symmetry Immediate from applying  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Nem 22.1.3(p.171) (see (19.1.21(p.131))). ■
- Direct proof Suppose  $a > 0 \cdots (1)$ . Then  $\tilde{\kappa} = s \cdots (2)$  from Lemma 13.6.6(p.83) (a).
  - (a) The same as Tom 22.1.3(p.172) (a).
- (2b) Let  $\beta=1$ . Then it suffices to consider only (b) of Tom 22.1.3(p.172). Let  $\beta<1$ . If s=0, due to (1) it suffices to consider only (c2) of Tom 22.1.3(p.172) and if s>0, then  $\tilde{\kappa}>0$  due to (2), hence it suffices to consider only (c2) of Tom 22.1.3(p.172), thus, whether s=0 or s>0 we have the same result. Accordingly, whether  $\beta=1$  or  $\beta<1$ , it follows that we have the same result.
- $\square$  Pom 22.1.8 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathbb{A}]^+\}$ ) Suppose a>0. Let  $\beta<1$  or s>0 and let  $\rho< x_{\widetilde{K}}$ .
- (a) Let  $\beta = 1$  or  $\rho = 0$ .
  - 1.  $V_t = \rho \text{ for } t \geq 0.$

- 2. Let  $x_{\tilde{L}} \geq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- 3. Let  $x_{\tilde{L}} < \rho$ . Then  $sample dOITs_{\tau} \langle \tau \rangle_{A}$  where  $Conduct_{\tau > t > 0}$ .
- (b) Let  $\beta < 1$  and  $\rho < 0$ .
  - 1.  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
  - 2.  $\bullet dOITd_{\tau>0}\langle 0 \rangle$
- (c) Let  $\beta < 1$  and  $\rho > 0$ .
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
  - 2.  $\bullet dOITd_{\tau>0}\langle 0 \rangle$
- Proof by diagonal-symmetry Immediate from applying  $S_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Nem 22.1.4(p.171) (see (a(p.108))). ■
- Direct proof Suppose  $a > 0 \cdots (1)$ . Then  $\tilde{\kappa} = s \cdots (2)$  from Lemma 13.6.6(p.83) (a).
  - (a-a3) The same as Tom 22.1.4(p.172) (a-a3).
  - (b) Let  $\beta < 1$  and  $\rho < 0$ .
  - (b1) The same as Tom 22.1.4(p.172) (b1).
- (b2) If s = 0, then due to (1) it suffices to consider only (b2) of Tom 22.1.4(p.172) and if s > 0, then  $\tilde{\kappa} > 0$  due to (2), hence it suffices to consider only (b2) of Tom 22.1.4(p.172). Accordingly, whether s = 0 or s > 0, we have the same result.
  - (c) Let  $\beta < 1$  and  $\rho > 0$ .
  - (c1) The same as Tom 22.1.4(p.172) (c1).
- (c2) If s = 0, then due to (1) it suffices to consider only (c2) of Tom 22.1.4(p.172) and if s > 0, then  $\tilde{\kappa} > 0$  due to (2), hence it suffices to consider only (c2) of Tom 22.1.4(p.172). Accordingly, whether s = 0 or s > 0, we have the same result.

#### 22.1.5.3.2 Mixed Restriction

Omitted.

## 22.1.5.3.3 Negative Restriction

Unnecessary.

# **22.1.6** M:2[ $\mathbb{P}$ ][A]

# 22.1.6.1 Preliminary

From (7.4.23(p.41)) and from (6.1.21(p.26)) and (6.1.20(p.26)) we have

$$V_t = \max\{K(V_{t-1}) + (1-\beta)V_{t-1}, 0\} + \beta V_{t-1}$$
  
= \text{max}\{L(V\_{t-1}), 0\} + \beta V\_{t-1}, \quad t > 1, \tag{22.1.45}

hence

$$V_t - \beta V_{t-1} = \max\{L(V_{t-1}), 0\}, \quad t > 1.$$
(22.1.46)

Then, for t > 1 we have

$$V_{t} = L(V_{t-1}) + \beta V_{t-1} = K(V_{t-1}) + V_{t-1} \quad \text{if } L(V_{t-1}) \ge 0$$
(22.1.47)

$$V_t = \beta V_{t-1} \qquad \text{if } L(V_{t-1}) \le 0. \tag{22.1.48}$$

Now, from (7.2.107(p.35)) and from (7.2.103(p.35)) and (7.2.105(p.35)) we have, for t > 1,

$$\mathbb{S}_t = L(V_{t-1}) \ge (\le) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\Delta}}(\mathtt{Skip}_{t_{\Delta}}), \tag{22.1.49}$$

$$\mathbb{S}_t = L(V_{t-1}) > (<) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}}(\mathtt{Skip}_{t_{\blacktriangle}}). \tag{22.1.50}$$

From (7.4.22(p.41)) we have

$$V_1 = \max\{\lambda \beta \max\{0, a - \rho\} - s, 0\} + \beta \rho, \tag{22.1.51}$$

hence

$$V_1 - \beta V_0 = V_1 - \beta \rho = \max\{\lambda \beta \max\{0, a - \rho\} - s, 0\} \ge 0.$$
(22.1.52)

From the comparison of the two terms within { } in the r.h.s. of (22.1.51(p.174)) it can be seen that

$$S_1 = \lambda \beta \max\{0, a - \rho\} \ge (\le) \ s \Rightarrow \mathsf{Conduct}_{1_{\Delta}}(\mathsf{Skip}_{1_{\Delta}}), \tag{22.1.53}$$

$$\mathbb{S}_1 = \lambda\beta \max\{0, a - \rho\} > (<) \ s \Rightarrow \mathtt{Conduct}_{1\blacktriangle}(\mathtt{Skip}_{1\blacktriangle}). \tag{22.1.54}$$

### 22.1.6.2 Analysis

## **22.1.6.2.1** Case of $\beta = 1$ and s = 0

## 22.1.6.2.1.1 Preliminary

Let  $\beta = 1$  and s = 0. Then, from (6.1.21(p.26)), (6.1.20(p.26)), and Lemma 14.2.1(p.33) (g) we have

$$K(x) = L(x) = \lambda T(x) \ge 0 \quad \text{for any } x. \tag{22.1.55}$$

In addition, from (22.1.46(p.174)) we have

$$V_t - \beta V_{t-1} = \max\{\lambda T(V_{t-1}), 0\} = \lambda T(V_{t-1}) \ge 0, \quad t > 1.$$
(22.1.56)

Finally, from (22.1.51(p.174)) we have

$$V_1 = \max\{\lambda \max\{0, a - \rho\}, 0\} + \rho \tag{22.1.57}$$

$$= \lambda \max\{0, a - \rho\} + \rho \quad \text{(due to } \lambda \max\{0, a - \rho\} \ge 0)$$
 (22.1.58)

$$= \max\{\rho, \lambda a + (1 - \lambda)\rho\}. \tag{22.1.59}$$

## **22.1.6.2.1.2** Case of $\rho < a^*$

In this case, due to Lemma 22.1.1(p.159) (c), we can obtain Tom 22.1.1(p.175) below by applying  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  (see (20.0.5(p.136))) to Tom 22.1.1(p.163) with the condition  $\rho \leq a^*$  (see Theorem 22.1.2(p.159)).

**Proposition 22.1.1** ( $\rho \leq a^*$ ) Assume  $\rho \leq a^*$  and let  $\beta = 1$  and s = 0.

- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- Proof Assume  $\rho \leq a^*$  and let  $\beta = 1$  and s = 0.
  - (a) The same as Tom 22.1.1(p.163) (a).
- (b) Due to the assumption  $\rho \le a^*$  we have  $\rho \le a^* < a < b$  from Lemma 14.2.1(p.93) (n). Hence it suffices to consider only (c) of Tom 22.1.1(p.163).

### **22.1.6.2.1.3** Case of $b \le \rho$

In this case, due to Lemma 22.1.1(p.159) (c), we can obtain Tom 22.1.2(p.175) below by applying  $\mathcal{A}_{\mathbb{R}^{\to\mathbb{P}}}$  (see (20.0.5(p.136))) to Tom 22.1.1(p.163) with the condition  $b \leq \rho$  (see Theorem 22.1.2(p.159)).

**Proposition 22.1.2**  $(b \le \rho)$  Assume  $b \le \rho$  and let  $\beta = 1$  and s = 0.

- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b)  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .  $\square$
- Proof Assume  $b \le \rho \cdots (1)$  and let  $\beta = 1$  and s = 0.
  - (a) The same as Tom 22.1.1(p.163) (a).
  - (b) Due to (1) it suffices to consider only (b) of Tom 22.1.1(p.163). ■

# **22.1.6.2.1.4** Case of $a^* < \rho < b$

In this case, Theorem 22.1.2(p.159) does not always hold due to Lemma 22.1.1(p.159) (d), hence  $\mathscr{A}\{M:2[\mathbb{P}][A]\}$  must be directly found.

**Proposition 22.1.3**  $(a^* < \rho < b)$  Assume  $a^* < \rho < b$  and let  $\beta = 1$  and s = 0.

- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $a \leq \rho$ . Then  $\bullet$  dOITd<sub>1</sub> $\langle 0 \rangle_{\parallel}$  and  $\circ$  dOITs<sub> $\tau > 1 \langle \tau \rangle_{\bullet}$ </sub> where Conduct<sub> $\tau \geq t > 1 \land$ </sub> and  $\circ$  double  $\circ$  s<sub>1\(\delta\)</sub>.
- (c) Let  $\rho < a$ . Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}$  where  $Conduct_{\tau\geq t>0}$ .
- Proof Assume  $a^* < \rho < b \cdots$  (1) and let  $\beta = 1$  and s = 0. Then, from (6.1.20[p.26]) and (6.1.21[p.26]) we have  $L(x) = K(x) = \lambda T(x) \ge 0 \cdots$  (2) for any x from Lemma 14.2.1[p.33] (g). Then, since  $\rho < b$  and a < b, from (22.1.59[p.175]) we obtain  $V_1 < \max\{b, \lambda b + (1 \lambda)b\} = \max\{b, b\} = b$ . Suppose  $V_{t-1} < b$ . Then, since  $a^* < b$  due to (1), from (7.4.23[p.41]) with  $\beta = 1$  we have  $V_t < \max\{K(b) + b, b\}$  from Lemma 14.2.3[p.36] (h), hence  $V_t < \max\{\beta b s, b\}$  from (14.2.12(2)(p.35)), so  $V_{t-1} < \max\{b, b\} = b$  due to the assumption " $\beta = 1$  and s = 0". Accordingly, by induction we have  $V_{t-1} < b \cdots$  (3) for t > 1, hence  $T(V_{t-1}) > 0 \cdots$  (4) for t > 1 from Lemma 14.2.1[p.33] (g). Accordingly,  $V_t \beta V_{t-1} > 0$  for t > 1 from (22.1.56[p.175]), i.e.,  $V_t > \beta V_{t-1}$  for t > 1. Then, since  $V_t > \beta V_{t-1}$  for  $\tau \ge t > 1$ , we have  $V_\tau > \beta V_{\tau-1} > \beta^2 V_{\tau-2} > \cdots > \beta^{\tau-1} V_1 \cdots$  (5) for  $\tau > 1$ . In addition, since  $L(V_{t-1}) = \lambda T(V_{t-1}) > 0 \cdots$  (6) for  $\tau \ge t > 1$  due to (4), we have Conduct  $t_{\tau > t > 1} \cdot t \sim (7)$  from (22.1.50[p.174]).
- (a) From (22.1.58(p.175)) and (7.4.21(p.41)) we have  $V_1 V_0 = V_1 \rho = \lambda \max\{0, a \rho\} \ge 0$ , hence  $V_1 \ge V_0 \cdots$  (8). Since  $V_2 \ge K(V_1) + V_1$  from (7.4.23(p.41)) with t = 2, we have  $V_2 V_1 \ge K(V_1) \ge 0$  due to (2), hence  $V_2 \ge V_1 \cdots$  (9). Suppose  $V_t \ge V_{t-1}$ .

Then from (7.4.23(p.41)) and Lemma 14.2.3(p.96) (e) we have  $V_{t+1} = \max\{K(V_t) + V_t, \beta V_t\} \ge \max\{K(V_{t-1}) + V_{t-1}, \beta V_{t-1}\} = V_t$ . Hence, by induction  $V_t \ge V_{t-1}$  for t > 1. From this and (8) we have  $V_t \ge V_{t-1}$  for t > 0, hence it follows that  $V_t$  is nondecreasing in  $t \ge 0$ .

- (b) Let  $a \leq \rho \cdots$  (10), hence  $V_1 = \rho$  from (22.1.58(p.175)), so  $V_1 < b$  due to (1). Then  $V_1 \beta V_0 = V_1 V_0 = \rho \rho = 0$  from (7.4.21(p.41)), hence  $V_1 = \beta V_0 \cdots$  (11), so  $t_1^* = 0$ , i.e.,  $\boxed{\bullet \text{dOITd}_1\langle 0 \rangle}_{\parallel}$ . Below let  $\tau > 1$ . Then, from (5) and (11) we have  $V_{\tau} > \beta V_{\tau-1} > \beta^2 V_{\tau-2} > \cdots > \beta^{\tau-1} V_1 = \beta^{\tau} V_0$  for  $\tau > 1$ , hence  $t_{\tau}^* = \tau$  for  $\tau > 1$ , i.e.,  $\boxed{\$ \text{dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ . Here note Conduct<sub>t</sub> for  $\tau \geq t > 1$  from (7). In addition, since  $\lambda \max\{0, a \rho\} = 0$  due to (10), we have  $\lambda \max\{0, a \rho\} = 0 \leq s$  for any  $s \geq 0$ , hence  $\text{Skip}_{1,\Delta}$  due to (22.1.53(p.174)). Accordingly, it follows that we have  $\text{C} \sim \text{S}_{1,\Delta}$  (see Remark 8.2.1(p.44)).
- (c) Let  $\rho < a \cdots$  (12), hence  $V_1 = \lambda(a \rho) + \rho$  due to (22.1.58(p.175)). Then, from (7.4.21(p.41)) we have  $V_1 \beta V_0 = V_1 V_0 = V_1 \rho = \lambda(a \rho) > 0$ , i.e.,  $V_1 > \beta V_0 \cdots$  (13), hence  $t_1^* = 1$ , i.e.,  $\boxed{\$ \text{ dOITs}_1\langle 1 \rangle}_{\blacktriangle} \cdots$  (14). Below let  $\tau > 1$ . Then, from (5) and (13) we have  $V_{\tau} > \beta V_{\tau-1} > \beta^2 V_{\tau-2} > \cdots > \beta^{\tau-1} V_1 > \beta^{\tau} V_0$  for  $\tau > 1$ , hence  $t_{\tau}^* = \tau$  for  $\tau > 1$ , i.e.,  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ . From the result and (14) we have  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$ . Since  $a \rho > 0$  due to (12), we have  $\lambda \max\{0, a \rho\} > 0 = s$ , implying that we have Conduct<sub>1</sub> due to (22.1.54(p.174)). From this and (7) it follows that Conduct<sub> $\tau>t>0$ </sub>.

# **22.1.6.2.1.5** Integration of Propositions 22.1.1(p.175) – 22.1.3(p.175)

**Lemma 22.1.2** ( $\mathscr{A}\{M:2[\mathbb{P}][A]\}\)$  Let  $\beta = 1$  and s = 0.

- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\rho \leq a^{\star}$ . Then  $\operatorname{\mathfrak{S}} \operatorname{dOITs}_{\tau>0}\langle \tau \rangle$  where  $\operatorname{Conduct}_{\tau\geq t>0}$ .
- (c) Let  $b \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (d) Let  $a^* < \rho < b$ .
  - 1. Let  $a \leq \rho$ . Then  $\boxed{\bullet \ \text{dOITd}_1\langle 0 \rangle}_{\parallel}$  and  $\boxed{\$ \ \text{dOITs}_{\tau > 1}\langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau \geq t > 1}_{\blacktriangle}$  and  $\text{C} \hookrightarrow \text{S}_{1\Delta}$ .
  - 2. Let  $\rho < a$ . Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}$  where  $Conduct_{\tau \geq t>0}$ .
- *Proof* (a) The same as Tom's 22.1.1(p.175) (a), 22.1.2(p.175) (a), and 22.1.3(p.175) (a).
  - (b) The same as Tom 22.1.1(p.175) (b).
  - (c) The same as Tom 22.1.2(p.175) (b).
  - (d-d2) The same as Tom 22.1.3(p.175) (b,c).

**Corollary 22.1.3** Let  $\beta = 1$  and s = 0. Then, the optimal price to propose  $z_t$  is nondecreasing in t.  $\square$ 

• Proof Immediate from Lemma 22.1.2(p.176) (a) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89).

# 22.1.6.2.2 Case of $\beta < 1$ or s > 0

## 22.1.6.2.2.1 Case of $\rho < a^*$

In this case, Theorem 22.1.2(p.159) holds due to Lemma 22.1.1(p.159) (c), hence Tom's 22.1.5(p.176) –22.1.7(p.177) below can be derived by applying  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  (see (20.0.5(p.136))) to Tom's 22.1.2(p.163) –22.1.4(p.166). In the proofs below, let us represent what results from applying  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  to a given Tom by Tom', i.e.,

$$\mathsf{Tom}' = \mathcal{A}_{\mathbb{R} \to \mathbb{P}}[\mathsf{Tom}]. \tag{22.1.60}$$

- $\square$  Tom 22.1.5 ( $\mathscr{A}\{M:2[\mathbb{P}][A]\}$ ) Assume  $\rho \leq a^*$ , let  $\beta < 1$  or s > 0, and let  $\rho < x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ , is strictly increasing in  $t \geq 0$  if  $\lambda < 1$  or  $a < \rho$ , and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
- (b) Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$  where  $Conduct_{1}$ . Below let  $\tau > 1$ .
  - 2. Let  $\beta = 1$ .
    - i. Let  $(\lambda a s)/\lambda \le a^*$ .
      - 1. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT $_{\tau > 1}\langle 1 \rangle$  where Conduct $_{1}$ .
      - $2. \quad Let \ \lambda < 1. \ Then \ \boxed{\$ \ dOITs_{\tau>1}\langle \tau \rangle} \ \blacktriangle \ where \ Conduct_{\tau>t>0} \blacktriangle.$
    - ii. Let  $(\lambda a s)/\lambda > a^{\star}$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  and  $\text{Conduct}_{\tau \geq t > 0}_{\blacktriangle}$ .
  - 3. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let  $(\lambda \beta a s)/\delta \le a^*$ .
      - 1. Let  $\lambda = 1$ .
        - i. Let b>0 ( $\kappa>0$ ). Then  $\boxed{\$ \text{dOITs}_{\tau>1}\langle \tau\rangle}$  where  $\text{Conduct}_{\tau\geq t>0}$ .
        - ii. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $\odot \text{ ndOIT}_{\tau>1}\langle 1 \rangle$  where  $\text{Conduct}_{1_{\blacktriangle}}$ .
      - 2. Let  $\lambda < 1$ .
        - $\text{i. } Let \ b \geq 0 \ (\!(\kappa \geq 0)\!) \ . \ Then \ \boxed{\$ \ \text{dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle} \ where \ \text{Conduct}_{\tau \geq t>0_{\blacktriangle}}.$
        - ii. Let b < 0 ( $\kappa < 0$ ). Then  $S_3(p.163)$  SA  $\odot$  I is true.

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ii. Let (\lambda \beta a - s)/\delta > a^*.
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- 1. Let  $b \geq 0$  ( $\kappa \geq 0$ ). Then subseteq subseteq subseteq where subseteq subseteq subseteq where subseteq subseteq
- 2. Let b < 0 ( $\kappa < 0$ ). Then  $S_3(p.163)$   $\bullet$   $\bullet$  is true.  $\Box$
- Proof by analogy Consider the Tom' resulting from applying  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  to Tom 22.1.2(p.163). Then " $a<\rho$ " in Tom 22.1.2(p.163) (c2i,c3i) changes into " $a^*<\rho$ " in the Tom', which contradicts the assumption  $\rho\leq a^*$ . Accordingly, removing all assertions with " $a^*<\rho$ " from the Tom' leads to Tom 22.1.5 above.

Corollary 22.1.4 ( $\mathscr{A}\{M:2[\mathbb{P}][A]\}$ ) Assume  $\rho \leq a^*$ , let  $\beta < 1$  or s > 0, and let  $\rho < x_K$ . Then, the optimal price to propose  $z_t$  is nondecreasing in  $t \geq 0$ .

- Proof Immediate from Tom 22.1.5(p.176) (26.2.43) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89).
- $\square$  Tom 22.1.6 ( $\mathscr{A}\{M:2[\mathbb{P}][A]\}$ ) Assume  $\rho \leq a^*$ , let  $\beta < 1$  or s > 0, and let  $\rho = x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\beta = 1$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\parallel}$ .
- (c) Let  $\beta < 1$  and  $s = 0 \ (s > 0)$ .
  - 1. Let b>0 ( $\kappa>0$ ) . Then  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau\rangle}$  where  $\texttt{Conduct}_{\tau\geq t>0}$ .
  - 2. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle$ .
- Proof by analogy The same as Tom 22.1.3(p.166) due to Lemma 14.6.1(p.99).

Corollary 22.1.5 ( $\mathscr{A}\{M:2[\mathbb{P}][\mathbb{A}]\}$ ) Assume  $\rho \leq a^*$ , let  $\beta < 1$  or s > 0, and let  $\rho = x_K$ . Then, the optimal price to propose  $z_t$  is nondecreasing in  $t \geq 0$ .

- Proof Immediate from Tom 22.1.6(p.177) (a) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89).
- $\square$  Tom 22.1.7 ( $\mathscr{A}\{M:2[\mathbb{P}][A]\}$ ) Assume  $\rho \leq a^*$ , let  $\beta < 1$  or s > 0, and let  $\rho > x_K$ .
- (a) Let  $\beta = 1$  or  $\rho = 0$ .
  - 1.  $V_t = \rho \text{ for } t \geq 0.$
  - 2. Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
  - 3. Let  $x_L > \rho$ . Then  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau\geq t>0}_{\blacktriangle}$ .
- (b) Let  $\beta < 1$  and  $\rho > 0$  and let s = 0 (s > 0).
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
  - 2. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle$ .
  - 3. Let  $b > 0 ((\kappa > 0))$ .
    - i. Let  $\rho < x_L$ . Then  $subseteq dOITs_{\tau>0}\langle \tau \rangle$  where  $conduct_{\tau>t>0}$ .
    - ii. Let  $\rho = x_L$ . Then  $\bullet dOITd_1\langle 0 \rangle_{\parallel}$  and  $\odot dOITs_{\tau>1}\langle \tau \rangle_{\blacktriangle}$  where  $Conduct_{\tau \geq t>0}_{\blacktriangle}$ .
    - iii. Let  $\rho > x_L$ . Then  $S_4$   $\bullet \parallel c_{\sim S\Delta} c_{\sim SA}$  is true.
- (c) Let  $\beta < 1$  and  $\rho < 0$  and let s = 0 (s > 0) .
  - 1.  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
  - 2. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $\boxed{\bullet \text{dOITd}_{\tau > 0}\langle 0 \rangle}$
  - 3. Let b>0 ( $\kappa>0$ ). Then  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}$  where  $\texttt{Conduct}_{\tau>t>0}$ .  $\square$
- Proof by analogy The same as Tom 22.1.4(p.166) (see Lemma 14.6.1(p.99)).

Corollary 22.1.6 ( $\mathscr{A}[M:2[\mathbb{P}][\mathbb{A}]]$ ) Assume  $\rho \leq a^*$ , let  $\beta < 1$  or s > 0, and let  $\rho > x_K$ .

- (a) Let  $\beta = 1$  or  $\rho = 0$ . Then  $z_t = z(\rho)$  for  $t \ge 0$ , i.e., constant in  $t \ge 0$ .
- (b) Let  $\beta < 1$  and  $\rho > 0$  and let s = 0 (s > 0). Then  $z_t$  is nonincreasing in  $t \ge 0$ .
- (c) Let  $\beta < 1$  and  $\rho < 0$  and let s = 0 (s > 0). Then  $z_t$  is nondecreasing in  $t \ge 0$ .  $\square$
- $\bullet$  *Proof* Immediate from Tom 22.1.7(p.177) (a1,b1,c1) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89) .  $\blacksquare$

# 22.1.6.2.2.2 Case of $b \leq \rho$

In this case, Theorem 22.1.2(p.159) holds due to Lemma 22.1.1(p.159) (c), hence the following Tom's 22.1.8(p.178) –22.1.10(p.178) can be derived by applying  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  (see (20.0.5(p.136))) to

Tom's 22.1.2(p.163) - 22.1.4(p.166):

- $\ \, \square \, \, \text{Tom} \, \, \textbf{22.1.8} \, \, \big( \mathscr{A} \{ \mathsf{M}: 2[\mathbb{P}][\mathtt{A}] \} \big) \quad \, \text{Assume} \, \, b \leq \rho, \, \, \text{let} \, \, \beta < 1 \, \, \text{or} \, \, s > 0, \, \, \text{and} \, \, \text{let} \, \, \rho < \, x_K \, .$
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ , is strictly increasing in  $t \geq 0$  if  $\lambda < 1$ , and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
- (b) Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ \text{ dOITs}_1\langle 1 \rangle}$  where  $\text{Conduct}_{1\blacktriangle}$ . Below let  $\tau > 1$ .
  - 2. Let  $\beta=1$ . Then  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau\geq t>0}_{\blacktriangle}$ .
  - 3. Let  $\beta < 1$  and s = 0 ((s > 0)).
    - i. Let  $b \geq 0$  ( $\kappa \geq 0$ ). Then  $\boxed{\$ \text{ dOITs}_{\tau > 1}\langle \tau \rangle}_{\blacktriangle}$  where  $\texttt{Conduct}_{\tau \geq t > 0}_{\blacktriangle}$ .
    - ii. Let b < 0 ( $\kappa < 0$ ). Then  $S_3(p.163)$  sample 1 is true.  $\square$
- ullet Proof by analogy Consider the Tom' resulting from applying  $\mathcal{A}_{\mathbb{R} \to \mathbb{P}}$  to Tom 22.1.2(p.163). Then " $\rho \leq a$ " in

Tom 22.1.2(p.163) (c2i,c3i) changes into " $\rho \leq a^{\star}$ " in the Tom', hence  $\rho \leq a^{\star} < a < b$  due to

Lemma 14.2.1(p.93) (n), which contradicts the assumption  $b \le \rho$ . Accordingly, removing all assertions with " $\rho \le a$ " from the Tom' leads to Tom 22.1.8 above.

Corollary 22.1.7 Assume  $b \leq \rho$ , let  $\beta < 1$  or s > 0, and let  $\rho < x_K$ . Then  $z_t$  is nondecreasing in  $t \geq 0$ .  $\square$ 

- Proof Immediate from Tom 22.1.8(p.178) (a) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89).
- $\square$  Tom 22.1.9 ( $\mathscr{A}\{M:2[\mathbb{P}][A]\}$ ) Assume  $b \leq \rho$ , let  $\beta < 1$  or s > 0, and let  $\rho = x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\beta < 1$  and s = 0 ((s > 0)).
  - 1. Let b>0 ( $\kappa>0$ ). Then  $\odot$  dOITs $_{\tau>0}\langle \tau \rangle$  where Conduct $_{\tau\geq t>0}$ .
  - 2. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle$ .
- Proof by analogy The same as Tom 22.1.3(p.166) due to Lemma 14.6.1(p.99).

Corollary 22.1.8 Assume  $b \leq \rho$ , let  $\beta < 1$  or s > 0, and let  $\rho = x_K$ . Then  $z_t$  is nondecreasing in  $t \geq 0$ .  $\square$ 

- *Proof* Immediate from Tom 22.1.9(p.178) (a) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89). ■
- $\square$  Tom 22.1.10 ( $\mathscr{A}\{M:2[\mathbb{P}][A]\}$ ) Assume  $b \leq \rho$ , let  $\beta < 1$  or s > 0, and let  $\rho > x_K$ .
- (a) Let  $\beta = 1$  or  $\rho = 0$ .
  - 1.  $V_t = \rho \text{ for } t \geq 0.$
  - 2. Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
  - 3. Let  $x_L > \rho$ . Then  $subseteq dOITs_{\tau>0}\langle \tau \rangle$  where  $Conduct_{\tau\geq t>0}$ .
- (b) Let  $\beta < 1$  and  $\rho > 0$  and let s = 0 (s > 0).
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
  - $2. \quad Let \ b \leq 0 \ (\!(\kappa \leq 0)\!) \ . \ Then \ \bullet \ \mathrm{dOITd}_{\tau>0} \langle 0 \rangle \,|_{\mathbb{H}} \,.$
  - 3. Let  $b > 0 ((\kappa > 0))$ .
    - i. Let  $\rho < x_L$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle$  where  $Conduct_{\tau\geq t>0}$ .
    - ii. Let  $\rho = x_L$ . Then  $\bullet dOITd_1\langle 0 \rangle_{\parallel}$  and  $\odot dOITs_{\tau>0}\langle \tau \rangle_{\blacktriangle}$  where  $Conduct_{\tau\geq t>0}_{\blacktriangle}$ .
    - iii. Let  $x_L < \rho$ . Then  $S_4$   $\bullet \parallel c \sim s \Delta c \sim s \blacktriangle$  is true.
- (c) Let  $\beta < 1$  and  $\rho < 0$  and let s = 0 (s > 0).
  - 1.  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
  - 2. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle$ .
  - 3. Let b>0 ( $\kappa>0$ ) . Then  $\[ \]$  dOITs $_{\tau>0}\langle \tau \rangle \]_{\blacktriangle}$  where  $\[ \]$  Conduct $_{\tau\geq t>0}_{\blacktriangle}$ .
- ullet Proof by analogy The same as Tom 22.1.4(p.166) due to Lemma 14.6.1(p.99).  $\blacksquare$

**Corollary 22.1.9** Assume  $b \le \rho$ , let  $\beta < 1$  or s > 0, and let  $\rho > x_K$ .

- (a) Let  $\beta = 1$  or  $\rho = 0$ . Then  $z_t = z(\rho)$  for  $t \ge 0$ .
- (b) Let  $\beta<1$  and  $\rho>0$  and let  $\,s=0$  ((s>0)) . Then  $z_t$  is nonincreasing in  $t\geq 0.$
- (c) Let  $\beta < 1$  and  $\rho < 0$  and let s = 0 (s > 0). Then  $z_t$  is nondecreasing in  $t \ge 0$ .  $\square$
- $\bullet$  *Proof* Immediate from Tom 22.1.10(p.178) (a1,b1,c1) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89) .  $\blacksquare$

# 22.1.6.2.2.3 Case of $a^{\star} < \rho < b$

In this case, Theorem 22.1.2(p.159) does not always hold due to Lemma 22.1.1(p.159) (d), hence  $\mathscr{A}\{M:2[\mathbb{P}][A]\}$  must be directly found. For convenience of reference, below let us copy (22.1.51(p.174))

$$V_1 = \max\{\lambda \beta \max\{0, a - \rho\} - s, 0\} + \beta \rho. \tag{22.1.61}$$

#### Lemma 22.1.3

- (a) Let  $V_1 \leq x_K$ . Then  $V_t$  is nondecreasing in t > 0.
- (b) Let  $V_1 > x_K$ .
  - 1. Let  $\beta = 1$  or  $V_1 = 0$ . Then  $V_t = V_1$  for t > 0.
  - 2. Let  $\beta < 1$  and  $V_1 > 0$ . Then  $V_t$  is nonincreasing in t > 0.
  - 3. Let  $\beta < 1$  and  $V_1 < 0$ . Then  $V_t$  is nondecreasing in t > 0.  $\square$
- Proof (a) Let  $V_1 
  leq x_K$ . Then,  $K(V_1) 
  leq 0$  due to Corollary 14.2.2(p.96) (b), hence from (7.4.23(p.41)) with t = 2 we have  $V_2 
  leq K(V_1) + V_1 
  leq V_1$ . Suppose  $V_{t-1} 
  leq V_t$ . Then, from (7.4.23(p.41)) and Lemma 14.2.3(p.96) (e) we have  $V_t 
  leq \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Hence, by induction  $V_{t-1} 
  leq V_t$  for t > 1, i.e.,  $V_t$  is nondecreasing in t > 0.
- (b) Let  $V_1 > x_K$ . Then  $K(V_1) \le 0 \cdots (1)$  due to Corollary 14.2.2(p.96) (a). Hence, from (7.4.23(p.41)) with t = 2, hence  $V_2 V_1 = \max\{K(V_1) + V_1, \beta V_1\} V_1 = \max\{K(V_1), -(1-\beta)V_1\} \cdots (2)$ .
- (b1) Let  $\beta = 1$  or  $V_1 = 0$ . Then, since  $-(1 \beta)V_1 = 0$ , from (2) we have  $V_2 V_1 = \max\{K(V_1), 0\} = 0$  due to (1), hence  $V_2 = V_1$ . Suppose  $V_{t-1} = V_1$ . Then from (7.4.23(p.41)) we have  $V_t = \max\{K(V_1) + V_1, \beta V_1\} = V_2 = V_1$ . Hence, by induction we have  $V_t = V_1$  for t > 0.

Below note that  $\overline{\beta} = 1$  or  $V_1 = 0$  (the negation of  $\beta = 1$  or  $V_1 = 0$ ) is " $\beta < 1$  and  $V_1 \neq 0$ ", which can be classified into the two cases, " $\beta < 1$  and  $V_1 > 0$ " and " $\beta < 1$  and  $V_1 > 0$ ".

- (b2) Let  $\beta < 1$  and  $V_1 > 0$ . Then, since  $-(1-\beta)V_1 < 0$ , from (2) we have  $V_2 V_1 \le 0$  due to (1), hence  $V_2 \le V_1$ . Suppose  $V_{t-1} \le V_{t-2}$ . Then, from (7.4.23(p.41)) and Lemma 14.2.3(p.96) (e) we have  $V_t \le \max\{K(V_{t-2}) + V_{t-2}, \beta V_{t-2}\} = V_{t-1}$ . Hence, by induction we have  $V_t \le V_{t-1}$  for t > 1, thus  $V_t$  nonincreasing in t > 0.
- (b3) Let  $\beta < 1$  and  $V_1 < 0$ . Then, since  $-(1-\beta)V_1 > 0$ , from (2) we have  $V_2 V_1 > 0$  or equivalently  $V_2 > V_1$ , so  $V_2 \ge V_1$ . Suppose  $V_{t-1} \ge V_{t-2}$ . Then from (7.4.23(p.41)) and Lemma 14.2.3(p.96) (e) we have  $V_t \ge \max\{K(V_{t-2}) + V_{t-2}, \beta V_{t-2}\} = V_{t-1}$ . Hence, by induction we have  $V_t \ge V_{t-1}$  for t > 1, thus  $V_t$  nondecreasing in t > 0.

Let us define:

$$\mathbf{S}_{5} \overset{\bullet}{\otimes} \bullet \overset{\bullet}{\otimes} \overset$$

**Remark 22.1.2** For explanatory convenience, let us represent " $\beta = 1$  or  $V_1 = 0$ " as  $\{\beta = 1 \cup V_1 = 0\}$ . Then, its negation  $\{\beta = 1 \cup V_1 = 0\}$  can be written as

$$\overline{\{\beta = 1 \cup V_1 = 0\}} = \{\beta < 1 \cap V_1 \neq 0\} = \{\beta < 1 \cap V_1 > 0\} \cup \{\beta < 1 \cap V_1 < 0\}.$$

Without loss of generality, this can be further expressed as

$$\overline{\{\beta = 1 \cup V_1 = 0\}} = \{\beta < 1 \cap s \ge 0 \cap V_1 > 0\} \cup \{\beta < 1 \cap s \ge 0 \cap V_1 < 0\}.$$

Furthermore, since  $\{s \ge 0\}$  can be denoted by  $\{s = 0 \ (s > 0)\}$ , it follows that the above expression can be rewritten as

$$\overline{\{\beta = 1 \cup V_1 = 0\}} = \{\beta < 1 \cap \{s = 0 \ (s > 0)\} \cap \{V_1 > 0\}\} \cup \{\beta < 1 \cap \{s = 0 \ (s > 0)\} \cap \{V_1 < 0\}\}. \quad \Box$$

- Tom 22.1.5 ( $\mathscr{A}\{M:2[\mathbb{P}][A]\}$ ) Assume  $a^* < \rho < b$  and let  $\beta < 1$  or s > 0.
- (a) If  $\lambda\beta \max\{0, a \rho\} \leq s$ , then  $\boxed{\bullet \text{ dOITd}_1\langle 0 \rangle}_{\parallel}$ , or else  $\boxed{\$ \text{ dOITs}_1\langle 1 \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{1\blacktriangle}$ . Below let  $\tau > 1$ .
- (b) Let  $V_1 \leq x_K$ .

- 1.  $V_t$  is nondecreasing in  $t \ge 0$  and converges to a finite  $V \ge x_K$  as  $t \to \infty$ .
- 2. Let  $V_1 \geq x_L$ . Then, if  $\lambda \beta \max\{0, a \rho\} \leq s$ , we have  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 0 \rangle}_{\parallel}$ , or else  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\parallel}$  where  $\boxed{\odot \text{ conduct}_{1 \blacktriangle}}$ .
- 3. Let  $V_1 < x_L$ .
  - i. Let  $\beta = 1$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$  where  $Conduct_{\tau \geq t > 1}$ .
  - ii. Let  $\beta < 1$  and s = 0 (s > 0).
    - 1. Let b>0 ( $\kappa>0$ ). Then  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}$  where  $\text{Conduct}_{\tau\geq t>1}$ .
    - 2. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $S_5$   $\bullet$   $\bullet$  is true.
- (c) Let  $V_1 > x_K$ .
  - 1. Let  $\beta = 1$  or  $V_1 = 0$ .
    - i.  $V_t = V_1 \text{ for } t > 0.$
    - ii. If  $\lambda \max\{0, a \rho\} \leq s$ , then  $\bullet \operatorname{dOITd}_{\tau > 1}\langle 0 \rangle_{\parallel}$ , or else  $\odot \operatorname{ndOIT}_{\tau > 1}\langle 1 \rangle_{\parallel}$  where  $\operatorname{Conduct}_{1.}$ .
  - 2. Let  $\beta < 1$  and s = 0 (s > 0) (see Remark 22.1.2(p.179) above)
    - i. Let  $V_1 > 0$ .
      - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to  $V \geq x_K$  as  $t \to \infty$ .
      - 2. Let  $b > 0 (\kappa > 0)$ . Then

- iii. Let  $V_1 < x_L$  . Then  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}$  where  $Conduct_{\tau\geq t>1}$ .
- 3. Let  $b \leq 0$  ( $\kappa \leq 0$ ). If  $\lambda \beta \max\{0, a \rho\} \leq s$ , then  $\bullet \text{dOITd}_{\tau > 1}\langle 0 \rangle_{\parallel}$ , or else  $\odot \text{ndOIT}_{\tau > 1}\langle 1 \rangle_{\parallel}$  where  $\text{Conduct}_{1_{\blacktriangle}}$ . ii. Let  $V_1 < 0$ .
  - 1.  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
  - 2. Let  $b > 0 ((\kappa > 0))$ .
    - $\text{i. } Let \ V_1 \geq \ x_L \ . \ \textit{If} \ \lambda\beta \max\{0, a-\rho\} \leq s, \ then \ \boxed{\bullet \ \text{dOITd}_{\tau>1}\langle 0\rangle}_{\parallel}, \ \textit{or} \ \textit{else} \ \boxed{\odot \ \text{ndOIT}_{\tau>1}\langle 1\rangle}_{\parallel} \ \textit{where} \ \text{Conduct}_{1\blacktriangle}.$
    - ii. Let  $V_1 < x_L$  . Then  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau \geq t>1}_{\blacktriangle}$ .
  - $3. \quad Let \ b \leq 0 \ (\kappa \leq 0) \ . \ If \ \lambda \beta \ \max\{0, a-\rho\} \leq s, \ then \boxed{\bullet \ dOITd_{\tau>1}\langle 0\rangle_{\parallel}, \ or \ else} \boxed{\odot \ ndOIT_{\tau>1}\langle 1\rangle_{\parallel}} \ \ where \ Conduct_{1\blacktriangle}. \ \ \Box = 0 \ \ (\kappa \leq 0) \ \ dOITd_{\tau>1}\langle 1\rangle_{\parallel} \ \ dOITd_{\tau>1}$
- Proof Assume  $a^* < \rho < b \cdots$  (1) and let  $\beta < 1$  or s > 0.

(a)

- i. Let  $\lambda \beta \max\{0, a \rho\} \leq s$ . Then, since  $\lambda \beta \max\{0, a \rho\} s \leq 0$ , we have  $V_1 \beta V_0 = 0$  from (22.1.52(p.174)), i.e.,  $V_1 = \beta V_0 \cdots (2)$ , hence  $t_1^* = 0$ , i.e.,  $\bullet dOITd_1\langle 0 \rangle_{\parallel}$ .
- ii. Let  $\lambda\beta \max\{0, a-\rho\} > s$ . Then, since  $\lambda\beta \max\{0, a-\rho\} s > 0$ , we have  $V_1 \beta V_0 > 0$  from (22.1.52(p.174)), i.e.,  $V_1 > \beta V_0 \cdots$  (3), hence  $t_1^* = 1$ , i.e.,  $since \lambda\beta \max\{0, a-\rho\} s > 0$ , from the comparison of the two terms within  $\{ \}$  in the r.h.s. of (22.1.51(p.174)) it follows that conducting the search is *strictly* optimal at time t = 1, i.e., Conduct<sub>1</sub>  $\lambda \cdots$  (4).

Below let  $\tau > 1$ .

- (b) Let  $V_1 \leq x_K \cdots (5)$ .
- (b1)  $V_t$  is nondecreasing in t>0 due to Lemma 22.1.3(p.179) (a). Consider a sufficiently large M>0 with  $b\leq M$  and  $V_1\leq M$ . Suppose  $V_{t-1}\leq M$ . Then, from (7.4.23(p.41)) and Lemma 14.2.3(p.96) (e) we have  $V_t\leq \max\{K(M)+M,\beta M\}=\max\{\beta M-s,\beta M\}$  due to (14.2.12 (2) (p.95)), hence  $V_t\leq \max\{M,M\}=M$  due to  $\beta\leq 1$  and  $s\geq 0$ . Accordingly, by induction  $V_t\leq M$  for t>0, i.e.,  $V_t$  is upper bounded in t. Hence  $V_t$  converges to a finite V as  $t\to\infty$ . Then, since  $V=\max\{K(V)+V,\beta M\}\cdots$  (6) from (7.4.23(p.41)), we have  $0=\max\{K(V),-(1-\beta)V\}\cdots$  (7), hence  $K(V)\leq 0$ , so  $V\geq x_K$  due to Lemma 14.2.3(p.96) (j1).
- (b2) Let  $V_1 \ge x_L$ . Then, since  $V_{t-1} \ge x_L$  for t > 1 due to (b1), we have  $L(V_{t-1}) \le 0$  for t > 1 from Corollary 14.2.1(p.96) (a), hence  $V_t \beta V_{t-1} = 0$  for t > 1 from (22.1.46(p.174)), i.e.,  $V_t = \beta V_{t-1}$  for t > 1. Then, since  $V_t = \beta V_{t-1}$  for  $\tau \ge t > 1$ , we have  $V_\tau = \beta V_{\tau-1} = \cdots = \beta^{\tau-1} V_1 \cdots$  (8).
  - i. Let  $\lambda \beta \max\{0, a \rho\} \leq s$ . Then, from (8) and (2) we have  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau-1} V_1 = \beta^{\tau} V_0$ , hence  $t_{\tau}^* = 0$  for  $\tau > 1$ , i.e.,  $\bullet \text{dOITd}_{\tau > 1} \langle 0 \rangle_{\parallel}$ .
  - ii. Let  $\lambda \beta \max\{0, a \rho\} > s$ . Then, from (8) and (3) we have  $V_{\tau} = \beta V_{\tau-1} = \dots = \beta^{\tau-1} V_1 > \beta^{\tau} V_0$ , hence  $t_{\tau}^* = 1$  for  $\tau > 1$ , i.e.,  $\boxed{\bigcirc \text{ndOIT}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ . In addition, we have Conduct<sub>1</sub> from (4).
  - (b3) Let  $V_1 < x_L \cdots (9)$ .
  - (b3i) Let  $\beta = 1$ , hence s > 0 due to the assumption " $\beta < 1$  or s > 0", thus  $x_L = x_K \cdots (10)$  from
- Lemma 14.2.4(p.97) (b). Now, since  $V_1 \geq \beta \rho$  from (7.4.22(p.41)), we have  $V_1 \geq \rho$  due to the assumption  $\beta = 1$ , hence  $a^* < V_1$  due to (1). Accordingly, it follows that  $a^* \leq V_{t-1}$  for t > 1 due to (b1). Note  $V_1 < x_K$  from (9) and (10). Suppose  $V_{t-1} < x_K$ . Then, from Lemma 14.2.3(p.96) (f) and (7.4.23(p.41)) with  $\beta = 1$  we have  $V_t < \max\{K(x_K) + x_K, x_K\} = \max\{x_K, x_K\} = x_K$ . Accordingly, by induction  $V_{t-1} < x_K$  for t > 1, hence  $V_{t-1} < x_L$  for t > 1 due to (10), so  $L(V_{t-1}) > 0$  for t > 1 from Lemma 14.2.2(p.96) (e1). Then, since  $L(V_{t-1}) > 0 \cdots$  (11) for  $\tau \geq t > 1$ , we have  $V_t \beta V_{t-1} > 0$  for  $\tau \geq t > 1$  from (22.1.46(p.174)), i.e.,  $V_t > \beta V_{t-1}$  for  $\tau \geq t > 1$ , hence  $V_\tau > \beta V_{\tau-1} > \cdots > \beta^{\tau-1} V_1$ . In addition, since  $V_1 \geq \beta V_0$  from (22.1.52(p.174)), we have

 $V_{\tau} > \beta V_{\tau-1} > \dots > \beta^{\tau-1} V_1 \ge \beta^{\tau} V_0$ , hence  $t_{\tau}^* = \tau$  for  $\tau > 1$ , i.e.,  $\boxed{\text{$\odot$ dOITs}_{\tau > 1}\langle \tau \rangle}_{\blacktriangle}$ . Then, we have Conduct<sub>t\$</sub> for  $\tau \ge t > 1$  from (11) and (22.1.50(p.174)).

- (b3ii) Let  $\beta < 1$  and s = 0 (s > 0).
- (b3ii1) Let b>0 ( $\kappa>0$ ). Then  $x_L>x_K>0\cdots$  (12) from Lemma 14.2.4(p37) (c (d)). Here note (9) and (b1). Then suppose there exists a t' such that  $V_{t-1}\geq x_L$  for  $t\geq t'$ . Then  $L(V_{t-1})\leq 0$  for  $t\geq t'$  from Corollary 14.2.1(p36) (a), hence  $V_t=\beta V_{t-1}$  for  $t\geq t'$  due to (22.1.48(p.174)). Therefore, we have  $V_t=\beta^{t-t'+1}V_{t'-1}$  for  $t\geq t'$ , leading to  $V=\lim_{t\to\infty}V_t=0< x_K$  due to (12), which contradicts  $V\geq x_K$  in (b1). Accordingly, it follows that  $V_{t-1}< x_L$  for all t>1, hence  $L(V_{t-1})>0$  for t>1 from Corollary 14.2.1(p36) (a). Thus, for the same reason as in the proof of (b3i) we have  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau\rangle}_{\blacktriangle}$  and Conduct $_{\tau\geq t>1}$ . (b3ii2) Let b<0 ( $\kappa<0$ ).
  - Let b=0 ( $\kappa=0$ ). Then  $x_L=x_K=0\cdots$  (13) from Lemma 14.2.4(p.97) (c (d)), hence  $V\geq x_K=x_L=0$  from (b1). Here assume  $V>x_K=0$ . Then, since  $-(1-\beta)V<0$ , we have K(V)=0 from (7), leading to the contradiction  $V=x_K$  due to Lemma 14.2.3(p.96) (j1). Thus it must be that  $V=x_K=0$ . Accordingly, due to (b1) and due to  $V_1< x_L=x_K=V$  from (9) and (13) it follows that there exists a  $t_{\tau}^*>1$  such that

$$V_1 \le V_2 \le \dots \le V_{t_{\tau}^{\bullet} - 1} < x_L = x_K = V_{t_{\tau}^{\bullet}} = V_{t_{\tau}^{\bullet} + 1} = \dots, ^{\dagger}$$

where  $t_{\tau}^{\bullet}$  might be infinity (i.e.,  $t_{\tau}^{\bullet} = \infty$ ). Hence  $V_{t-1} < x_L$  for  $t_{\tau}^{\bullet} \ge t > 1$  and  $V_{t-1} = x_L$  for  $t > t_{\tau}^{\bullet}$ . Thus, from Corollary 14.2.1(p.96) (a) we have

$$L(V_{t-1}) > 0$$
 for  $t_{\tau}^{\bullet} \ge t > 1$  and  $L(V_{t-1}) = 0$  (hence  $L(V_{t-1}) \le 0$ ) for  $t > t_{\tau}^{\bullet} \cdots (14)$ .

• Let b < 0 ( $\kappa < 0$ ). Then  $x_L < x_K$  from Lemma 14.2.4(p.97) (c (d)). Since  $V_1 < x_L$  from (9) and since  $x_L < x_K \le V$  from (b1), there exists  $t_{\tau}^{\bullet}$  such that

$$V_1 < V_2 < \dots < V_{t^{\bullet}-1} < x_L < V_{t^{\bullet}} < V_{t^{\bullet}+1} < \dots$$

hence  $V_{t-1} < x_L$  for  $t^{\bullet}_{\tau} \ge t > 1$  and  $x_L \le V_{t-1}$  for  $t > t^{\bullet}_{\tau}$ . Accordingly, from Corollary 14.2.1(p.%) (a) we have

$$L(V_{t-1}) > 0$$
 for  $t^{\bullet}_{\tau} \ge t > 1$  and  $L(V_{t-1}) \le 0$  for  $t > t^{\bullet}_{\tau} \cdots (15)$ .

From (14) and (15) we have, whether b = 0 ( $\kappa = 0$ ) or b < 0 ( $\kappa < 0$ ) (or equivalently  $b \le 0$  ( $\kappa \le 0$ )),

$$L(V_{t-1}) > 0 \cdots (16)$$
 for  $t_{\tau}^{\bullet} \ge t > 1$ ,

$$L(V_{t-1}) \leq 0 \cdots (17)$$
 for  $t > t_{\tau}^{\bullet}$ .

Accordingly, from (22.1.46(p.174)) we have  $V_t - \beta V_{t-1} > 0$  for  $t_{\tau}^{\bullet} \ge t > 1$  due to (16) and  $V_t - \beta V_{t-1} = 0$  for  $t > t_{\tau}^{\bullet}$  due to (17) or equivalently

$$V_t > \beta V_{t-1} \cdots (18), \quad t_{\tau}^{\bullet} > t > 1, \qquad V_t = \beta V_{t-1} \cdots (19), \quad t > t_{\tau}^{\bullet}$$

1. Let  $t_{\tau}^{\bullet} \geq \tau > 1$ . Then, since  $V_t > \beta V_{t-1} \cdots$  (20) for  $\tau \geq t > 1$  due to (18), for the same reason as in the proof of (b3i) we have  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle\tau\rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau\geq t>1}_{\blacktriangle}$ . Hence (1) of  $S_5$  holds. Then, since (20) with  $\tau = t_{\tau}^{\bullet}$  can be rewritten as  $V_t > \beta V_{t-1}$  for  $t_{\tau}^{\bullet} \geq t > 1$ , we have

$$V_{t^{\bullet}_{\tau}} > \beta V_{t^{\bullet}_{\tau}-1} > \cdots > \beta^{t^{\bullet}_{\tau}-1} V_{1} \cdots (21).$$

2. Let  $\tau > t_{\tau}^{\bullet}$ . Then  $V_t = \beta V_{t-1}$  for  $\tau \geq t > t_{\tau}^{\bullet}$  due to (19), hence

$$V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau - t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} \cdots (22).$$

Hence, from (22) and (21) and from the fact that  $V_1 \geq \beta V_0$  due to (2) and (3) we obtain

$$V_{\tau} = \beta V_{\tau-1} = \dots = \beta^{\tau - t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} > \beta^{\tau - t_{\tau}^{\bullet} + 1} V_{t_{\tau}^{\bullet} - 1} > \dots > \beta^{\tau - 1} V_{1} \ge \beta^{\tau} V_{0},$$

so we have  $t_{\tau}^* = t_{\tau}^{\bullet}$  for  $\tau > t_{\tau}^{\bullet}$ , i.e.,  $\boxed{\odot \text{ ndOIT}_{\tau > t_{\tau}^{\bullet}} \langle t_{\tau}^{\bullet} \rangle}_{\parallel}$ . Then  $\text{Conduct}_{t_{\perp}}$  for  $t_{\tau}^{\bullet} \geq t > 1$  due to (16) and (22.1.50(p.174)). From the above we see that (2) of  $S_5$  holds.

- (c) Let  $V_1 > x_K \cdots (23)$ .
- (c1) Let  $\beta = 1$  or  $V_1 = 0$ .
- (c1i) The same as Lemma 22.1.3(p.179) (b1).
- (c1ii) Since  $V_{\tau} = V_{\tau-1} = \cdots = V_1$  for  $\tau > 0$  from (c1i), we have  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau-1} V_1 \cdots$  (24).
  - i. Let  $\lambda \max\{0, a \rho\} \leq s$ . Then, from (2) and (24) we have  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau-1} V_1 = \beta^{\tau} V_0$ , hence  $t_{\tau}^* = 0$  for  $\tau > 1$ , i.e.,  $\bullet \text{dOITd}_{\tau > 1} \langle 0 \rangle_{\parallel}$ .

<sup>†</sup>Since  $V_t \leq V$  for any t > 0 due to (b1), if  $V \leq V_t$  for a t, then  $V = V_t$ .

- ii. Let  $\lambda \max\{0, a \rho\} > s$ . Then, from (3) and (24) we have  $V_{\tau} = \beta V_{\tau 1} = \dots = \beta^{\tau 1} V_1 > \beta^{\tau} V_0$ , hence  $t_{\tau}^* = 1$  for  $\tau > 1$ , i.e.,  $\boxed{\bigcirc$  ndOIT $_{\tau > 1} \langle 1 \rangle$  where Conduct<sub>1</sub> from (4).
- (c2) Let  $\beta < 1 \cdots (25)$  and s = 0 (s > 0).
- (c2i) Let  $V_1 > 0$ .
- (c2i1) The former half is the same as Lemma 22.1.3(p.179) (b2). The latter half can be proven as follows. Note (23), hence  $V_1 \geq x_K$ . Suppose  $V_{t-1} \geq x_K$ . Then from (7.4.23(p.41)) we have  $V_t \geq K(V_{t-1}) + V_{t-1} \geq K(x_K) + x_K$  due to Lemma 14.2.3(p.96) (e), hence  $V_t \geq x_K$  since  $K(x_K) = 0$ . Accordingly, by induction  $V_t \geq x_K$  for t > 0, i.e.,  $V_t$  is lower bounded in t. Hence  $V_t$  converges to a finite V as  $t \to \infty$ . Then, since  $V = \max\{K(V) + V, \beta V\}$  from (7.4.23(p.41)), we have  $0 = \max\{K(V), -(1-\beta)V\}$ , hence  $K(V) \leq 0$ , so  $V \geq x_K$  due to Lemma 14.2.3(p.96) (j1).
  - (c2i2) Let b > 0 ( $\kappa > 0$ ). Then  $x_L > x_K > 0 \cdots$  (26) from Lemma 14.2.4(p.97) (c (d)).
- (c2i2i) Let  $V_1 > x_L \cdots$  (27), hence  $V_1 \ge x_L$ . Suppose  $V_{t-1} \ge x_L$  for all t > 1. Then, since  $L(V_{t-1}) \le 0$  for t > 1 from Corollary 14.2.1(p.96) (a), we have  $V_t \beta V_{t-1} = 0$  for t > 1 from (22.1.46(p.174)), i.e.,  $V_t = \beta V_{t-1}$  for all t > 1, hence  $V_t = \beta^{t-1}V_1$ . Accordingly, we have  $V = \lim_{t \to \infty} V_t = 0 < x_K$  due to (25) and (26), which contradicts  $V \ge x_K$  in (c2i1). Thus it is impossible that  $x_L \le V_{t-1}$  for all t > 0. Accordingly, due to (27) and (c2i1) it follows that there exist  $t_{\tau}^{\bullet}$  and  $t_{\tau}^{\circ}$  ( $t_{\tau}^{\bullet} > t_{\tau}^{\circ} > 0$ ) such that

$$V_1 \geq V_2 \geq \cdots \geq V_{t_{\tau}^{\circ}-1} > x_L = V_{t_{\tau}^{\circ}} = V_{t_{\tau}^{\circ}+1} = \cdots = V_{t_{\tau}^{\bullet}-1} > V_{t_{\tau}^{\bullet}} \geq V_{t_{\tau}^{\bullet}+1} \geq \cdots.$$

Hence, we have

$$\begin{split} x_L > & V_{t_{\tau}^{\bullet}}, \ x_L > V_{t_{\tau}^{\bullet}+1}, \cdots, \\ V_{t_{\tau}^{\circ}} = & x_L, V_{t_{\tau}^{\circ}+1} = x_L, \cdots, V_{t_{\tau}^{\bullet}-1} = x_L, \\ V_1 > & x_L, V_2 > x_L, \cdots, V_{t_{\tau}^{\circ}-1} > x_L, \end{split}$$

or equivalently

$$egin{align} x_L > V_{t-1} \cdots$$
 (28),  $t > t^{ullet}_{ au}, \ V_{t-1} = x_L \cdots$  (29),  $t^{ullet}_{ au} \ge t > t^{\circ}_{ au}, \ V_{t-1} > x_L \cdots$  (30),  $t^{\circ}_{ au} \ge t > 1.$ 

Accordingly, we have:

- 1. Let  $t_{\tau}^{\bullet} \geq \tau > 1$ . Then, since  $V_{t-1} \geq x_L$  for  $\tau \geq t > 1$  from (29) and (30), we have  $L(V_{t-1}) \leq 0 \cdots$  (31) for  $\tau \geq t > 1$  from Corollary 14.2.1(p.96) (a), hence  $V_t \beta V_{t-1} = 0$  for  $\tau \geq t > 1$  from (22.1.46(p.174)), i.e.,  $V_t = \beta V_{t-1}$  for  $\tau \geq t > 1$ , leading to  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau-1} V_1 \cdots$  (32).
  - i. Let  $\lambda \max\{0, a \rho\} \leq s$ . Then, from (2) and (32) we have  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau-1} V_1 = \beta^{\tau} V_0$ , hence  $t_{\tau}^* = 0$  for  $t_{\tau}^* \geq \tau > 1$ , i.e.,  $\boxed{\bullet \text{ dOITd}_{t_{\tau}^* \geq \tau > 1}\langle 0 \rangle}_{\parallel}$ .
  - ii. Let  $\lambda \max\{0, a \rho\} > s$ . Then, from (3) and (32) we have  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau-1}V_1 > \beta^{\tau}V_0$ , hence  $t_{\tau}^* = 1$  for  $t_{\tau}^* \geq \tau > 1$ , i.e.,  $\boxed{\odot \text{ ndOIT}_{t_{\tau}^* \geq \tau > 1}\langle 1 \rangle}_{\parallel}$  where  $\text{Conduct}_{1, \bullet}$  from (4).

Accordingly  $S_6(1)$  holds. From (32) with  $\tau = t^{\bullet}_{\tau}$  we have  $V_{t^{\bullet}_{\tau}} = \beta V_{t^{\bullet}_{\tau}-1} = \cdots = \beta^{t^{\bullet}_{\tau}-1} V_1 \cdots$  (33).

2. Let  $\tau > t_{\tau}^{\bullet}$ . Then, since  $x_L > V_{t-1}$  for  $\tau \geq t > t_{\tau}^{\bullet}$  from (28), due to Corollary 14.2.1(p.96) (a) we have  $L(V_{t-1}) > 0 \cdots$  (34) for  $\tau \geq t > t_{\tau}^{\bullet}$ . Accordingly, from (22.1.46(p.174)) we have  $V_t - \beta V_{t-1} > 0$  for  $\tau \geq t > t_{\tau}^{\bullet}$  or equivalently  $V_t > \beta V_{t-1}$  for  $\tau \geq t > t_{\tau}^{\bullet}$ , leading to  $V_{\tau} > \beta V_{\tau-1} > \cdots > \beta^{\tau-t_{\tau}^{-}} V_{t_{\tau}^{\bullet}}$ . From this and (33) we have

$$V_{\tau} > \beta V_{\tau-1} > \dots > \beta^{\tau - t_{\tau}^{\bullet}} V_{t^{\bullet}} = \beta^{\tau - t_{\tau}^{\bullet} + 1} V_{t^{\bullet} - 1} = \dots = \beta^{\tau - 1} V_{1} \dots (35).$$

Since  $V_1 \ge \beta V_0$  due to (2) and (3), from (35) we have

$$|V_{\tau}| > \beta V_{\tau-1} > \dots > \beta^{\tau - t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} = \beta^{\tau - t_{\tau}^{\bullet} + 1} V_{t_{\tau}^{\bullet} - 1} = \dots = \beta^{\tau - 1} V_{1} \ge \beta^{\tau} V_{0}.$$

Hence, we have  $t_{\tau}^* = \tau$  for  $\tau > t_{\tau}^{\bullet}$ , i.e.,  $\boxed{\$ \text{ dOITs}_{\tau > t_{\tau}^{\bullet}} \langle \tau \rangle}_{\blacktriangle}$ , thus the former half of  $S_6(2)$  holds. The latter half can be proven as follows

- (i) If  $\tau \geq t > t_{\tau}^{\bullet}$ , then  $Conduct_{t_{\bullet}}$  from (34) and (22.1.50(p.174)).
- (ii) If  $t_{\tau}^{\bullet} \geq t > t_{\tau}^{\circ}$ , then  $V_{t-1} = x_L$  from (29), hence  $L(V_{t-1}) = L(x_L) = 0$ , so  $Skip_{t^{\Delta}}$  from (22.1.49(p.174)), implying that we have  $C \sim S_{t^{\bullet}_{\tau} > t > t^{\circ}_{\tau} \Delta}$  (see Figure 8.2.1(p.44) (II).
- (iii) If  $t_{\tau}^{\circ} \geq t > 1$ , then  $V_{t-1} > x_L$  from (30), hence  $L(V_{t-1}) = (<) 0^{\ddagger}$  from Lemma 14.2.2(p.96) (d (e1)); i.e.,  $Skip_{t^{\Delta}}$  ( $Skip_{t^{\Delta}}$ ) due to (22.1.49(p.174)) ((22.1.50(p.174))), implying that we have  $C \hookrightarrow S_{t_{\tau}^{\circ} \geq t > 1} = (C \hookrightarrow S_{t_{\tau}^{\circ} \geq t > 1})$ .

From the above results we see that the latter half of  $S_6(2)$  holds.

 $<sup>^{\</sup>ddagger} \mbox{If } s = 0, \mbox{ then "= 0" }, \mbox{ or else "< 0"}.$ 

(c2i2ii) Let  $V_1 = x_L$ . Suppose  $V_{t-1} = x_L$  for all t > 1. Then, since  $L(V_{t-1}) = L(x_L) = 0$  for t > 1, we have  $V_t - \beta V_{t-1} = 0$  for all t > 1 from (22.1.46(p.174)), i.e.,  $V_t = \beta V_{t-1}$  for all t > 1, hence  $V_t = \beta^{t-1}V_1$ . Then  $V = \lim_{t \to \infty} V_t = 0 < x_K$  due to (25) and (26), which contradicts  $V \ge x_K$  in (c2i1). Hence, since  $V_{t-1}$  is not equal to  $x_L$  for all t > 1, due to (c2i1) it follows that there exists  $t_T^{\bullet} > 1$  such that

$$V_1 = V_2 = \cdots = V_{t - 1} = x_L > V_{t - 2} \ge V_{t - 2} \ge \cdots$$

or equivalently  $V_{t-1} = x_L$  for  $t^* \ge t > 1$  and  $x_L > V_{t-1}$  for  $t > t^*$ . Thus, due to Corollary 14.2.1(p.96) (a) we have

$$L(V_{t-1}) = L(x_L) = 0 \cdots (36), \quad t_{\tau}^{\bullet} \ge t > 1, \qquad L(V_{t-1}) > 0 \cdots (37), \quad t > t_{\tau}^{\bullet}.$$

Accordingly, we have:

- 1. Let  $t_{\tau}^{\bullet} \geq \tau > 1$ . Then, from (36) and (22.1.46(p.174)) we have  $V_t \beta V_{t-1} = 0$  for  $\tau \geq t > 1$  or equivalently  $V_t = \beta V_{t-1}$  for  $\tau \geq t > 1$ , from which we have  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau-1} V_1$ .
  - i. Let  $\lambda \beta \max\{0, a \rho\} \leq s$ . Then, from (2) we have  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau-1} V_1 = \beta^{\tau} V_0$ , hence  $t_{\tau}^* = 0$  for  $t_{\tau}^{\bullet} \geq \tau > 1$ , i.e.,  $\bullet \text{dOITd}_{t_{\tau}^{\bullet} \geq \tau > 1}(0)$ .
  - ii. Let  $\lambda \beta \max\{0, a \rho\} > s$ . Then, from (3) we have  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau-1}V_1 > \beta^{\tau}V_0$ , hence  $t_{\tau}^* = 1$  for  $t_{\tau}^* \ge \tau > 1$ , i.e.,  $\boxed{\bigcirc$  ndOIT $_{t_{\tau}^* \ge \tau > 1}\langle 1 \rangle_{\parallel}$ . In addition, we have Conduct<sub>1 \(\text{\lambda}\)</sub> from (4).

Accordingly, it follows that  $S_7(1)$  holds.

2. Let  $\tau > t_{\tau}^{\bullet}$ . Then  $L(V_{t-1}) > 0 \cdots$  (38) for  $\tau \geq t > t_{\tau}^{\bullet}$  from (37), hence due to (22.1.46(p.174)) we have  $V_t - \beta V_{t-1} > 0$  for  $\tau \geq t > t_{\tau}^{\bullet}$  or equivalently  $V_t > \beta V_{t-1}$  for  $\tau \geq t > t_{\tau}^{\bullet}$ , leading to  $V_{\tau} > \beta V_{\tau-1} > \cdots > \beta^{\tau - t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} \cdots$  (39). In addition, since  $V_t - \beta V_{t-1} = 0$  for  $t_{\tau}^{\bullet} \geq t > 1$  from (36) and (22.1.46(p.174)), we have  $V_t = \beta V_{t-1}$  for  $t_{\tau}^{\bullet} \geq t > 1$ , leading to

$$V_{t^{\bullet}_{\tau}} = \beta V_{t^{\bullet}_{\tau}-1} = \cdots = \beta^{t^{\bullet}_{\tau}-1} V_1 \cdots (40).$$

From (39) and (40) we have

$$|V_{\tau}| > \beta V_{\tau-1} > \dots > \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} = \beta^{\tau-t_{\tau}^{\bullet}+1} V_{t_{\tau}^{\bullet}-1} = \dots = \beta^{\tau-1} V_{1}.$$

In addition, since  $V_1 \geq \beta^{\tau} V_0$  from (2) and (3), we eventually obtain

$$V_{\tau} > \beta V_{\tau-1} > \dots > \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} = \beta^{\tau-t_{\tau}^{\bullet}+1} V_{t_{\tau}^{\bullet}-1} = \dots = \beta^{\tau-1} V_1 \ge \beta^{\tau} V_0 \cdots (41).$$

Thus  $t_{\tau}^* = \tau$  for  $\tau > t_{\tau}^{\bullet}$ , i.e.,  $\boxed{\$ \text{ dOITs}_{\tau > t_{\tau}^{\bullet}}\langle \tau \rangle}_{\blacktriangle}$ , hence the former half of  $S_{7}(2)$  holds. Then, we have that  $\texttt{Conduct}_{t_{\blacktriangle}}$  for  $\tau \geq t > t_{\tau}^{\bullet}$  due to (38) and (22.1.50(p.174)). Moreover, we have  $\mathtt{Skip}_{t_{\vartriangle}}$  for  $t_{\tau}^{\bullet} \geq t > 1$  due to (36) and (22.1.49(p.174)), so it follows that we have  $\mathtt{pSKIP}_{t_{\vartriangle}}$  for  $t_{\tau}^{\bullet} \geq t > 1$  (see Figure 8.2.1(p.44))(II)) or equivalently  $\mathtt{pSKIP}_{t_{\eth}^{\bullet} \geq t > 1_{\vartriangle}}$ . Hence the latter half of  $S_{7}(2)$  holds.

(c2i2iii) Let  $V_1 < x_L$ . Then  $V_{t-1} < x_L$  for t > 1 due to (c2i1), hence  $L(V_{t-1}) > 0 \cdots$  (42) for t > 1 from Corollary 14.2.1(p.96) (a). Accordingly, since  $L(V_{t-1}) > 0 \cdots$  (43) for  $\tau \ge t > 1$ , we have  $V_t - \beta V_{t-1} > 0$  for  $\tau \ge t > 1$  from (22.1.46(p.174)) or equivalently  $V_t > \beta V_{t-1}$  for  $\tau \ge t > 1$ , hence

$$V_{\tau} > \beta V_{\tau-1} > \dots > \beta^{\tau-1} V_1.$$

Since  $V_1 > \beta V_0$  from (2) and (3), we have

$$\overline{V_{\tau}} > \beta V_{\tau-1} > \dots > \beta^{\tau-1} V_1 \ge \beta^{\tau} V_0,$$

hence we have  $t_{\tau}^* = \tau$  for  $\tau > 1$ , i.e.,  $\boxed{\$ \text{ dOITs}_{\tau > 1}\langle \tau \rangle}_{\blacktriangle}$ . In addition, we have  $\texttt{Conduct}_{t_{\blacktriangle}}$  for  $\tau \geq t > 1$  due to (43) and (22.1.50(p.174)).

(c2i3) Let  $b \leq 0$  ( $\kappa \leq 0$ ), hence  $x_L \leq x_K \cdots$  (44) from Lemma 14.2.4(p.97) (c (d)). Then, from (23) and (c2i1) we have  $V_{t-1} \geq x_K$  for all t > 1, hence  $V_{t-1} \geq x_L$  for all t > 1 due to (44), thus  $L(V_{t-1}) \leq 0$  for all t > 1 from Corollary 14.2.1(p.96) (a). Then, since  $L(V_{t-1}) \leq 0$  for  $\tau \geq t > 1$ , we have  $V_t - \beta V_{t-1} = 0$  for  $\tau \geq t > 1$  from (22.1.46(p.174)) or equivalently  $V_t = \beta V_{t-1}$  for  $\tau \geq t > 1$ , hence

$$V_{\tau} = \beta V_{\tau-1} = \dots = \beta^{\tau-1} V_1.$$

- i. Let  $\lambda \beta \max\{0, a \rho\} \leq s$ . Then, from (2) we have  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau-1} V_1 = \beta^{\tau} V_0$ , hence  $t_{\tau}^* = 0$  for  $\tau > 1$ , i.e.,  $\bullet \text{dOITd}_{\tau > 1}\langle 0 \rangle_{\parallel}$ .
- ii. Let  $\lambda \beta \max\{0, a \rho\} > s$ . Then, from (3) we have  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau-1} V_1 > \beta^{\tau} V_0$ , hence  $t_{\tau}^* = 1$  for  $\tau > 1$ , i.e.,  $\boxed{\bigcirc \text{ndOIT}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ . Then Conduct<sub>1</sub> from (4).

- (c2ii) Let  $V_1 < 0$ .
- (c2ii1) The same as the proof of (c2i1).
- (c2ii2) Let b > 0 ( $\kappa > 0$ ), hence  $x_L > x_K > 0 \cdots$  (45) from Lemma 14.2.4(p.97) (c (d)).
- (c2ii2i) Let  $V_1 \geq x_L$ . Then, since  $V_{t-1} \geq x_L$  for t > 1 due to (c2ii1), we have  $L(V_{t-1}) \leq 0$  for t > 1 from Corollary 14.2.1(p.96) (a), hence  $L(V_{t-1}) \leq 0$  for  $\tau \geq t > 1$ . Thus  $V_t \beta V_{t-1} = 0$  for  $\tau \geq t > 1$  from (22.1.46(p.174)), i.e.,  $V_t = \beta V_{t-1}$  for  $\tau \geq t > 1$ , so

$$V_{\tau} = \beta V_{\tau-1} = \dots = \beta^{\tau-1} V_1.$$

- i. Let  $\lambda\beta \max\{0, a-\rho\} \leq s$ . Then, from (2) we have  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau-1}V_1 = \beta^{\tau}V_0$ , hence  $t_{\tau}^* = 0$  for  $\tau > 1$ , i.e.,  $dOIT_{\tau > 1}\langle 0 \rangle_{\parallel}$ .
- ii. Let  $\lambda\beta \max\{0, a-\rho\} > s$ . Then, from (3) we have  $V_{\tau} = \beta V_{\tau-1} = \cdots = \beta^{\tau-1}V_1 > \beta^{\tau}V_0$ , hence  $t_{\tau}^* = 1$  for  $\tau > 1$ , i.e.,  $\boxed{\odot \text{ ndOIT}_{\tau>1}\langle 1 \rangle_{\parallel}}$ . Then Conduct<sub>1 \( \Lambda\)</sub> from (4).
- (c2ii2ii) Let  $V_1 < x_L$ . Suppose that there exists t' > 1 such that  $x_L \le V_{t-1}$  for t > t'. Then, since  $L(V_{t-1}) \le 0$  for t > t' from Corollary 14.2.1(p.%) (a), we have  $V_t \beta V_{t-1} = 0$  for t > t' due to (22.1.46(p.174)), hence  $V_t = \beta V_{t-1}$  for t > t', so

$$V_t = \beta V_{t-1} = \beta^2 V_{t-2} = \dots = \beta^{t-t'} V_{t'}.$$

Accordingly  $V = \lim_{t\to\infty} V_t = 0 < x_K$  due to (25) and (45), which contradicts  $V \ge x_K$  in (c2ii1), hence it must be that  $V_{t-1} < x_L$  for t > 1. Then, since  $V_{t-1} < x_L$  for  $\tau \ge t > 1$ , we have  $L(V_{t-1}) > 0 \cdots$  (46) for  $\tau \ge t > 1$  from Corollary 14.2.1(p.96) (a), hence  $V_t - \beta V_{t-1} > 0$  for  $\tau \ge t > 1$  from (22.1.46(p.174)) or equivalently  $V_t > \beta V_{t-1}$  for  $\tau \ge t > 1$ , thus

$$V_{\tau} > \beta V_{\tau-1} > \dots > \beta^{\tau-1} V_1.$$

Since  $V_1 \ge \beta V_0$  from (2) and (3), we have

$$|V_{\tau}| > \beta V_{\tau-1} > \dots > \beta^{\tau-1} V_1 \ge \beta^{\tau} V_0,$$

hence  $t_{\tau}^* = \tau$  for  $\tau > 1$ , i.e.,  $\boxed{\$ \text{ dOITs}_{\tau > 1}\langle \tau \rangle}_{\blacktriangle}$ . From (46) and (22.1.50(p.174)) we have  $\texttt{Conduct}_{t\blacktriangle}$  for  $\tau \geq t > 1$ .

(c2ii3) Let  $b \le 0$  ( $\kappa \le 0$ ), hence  $x_L \le x_K \cdots$  (47) from Lemma 14.2.4(p.97) (c (d)). Then, due to (23) and (c2ii1) we have  $V_{t-1} > x_K$  for t > 1, hence  $V_{t-1} > x_L$  for t > 1 from (47), thus  $L(V_{t-1}) \le 0$  for t > 1 from Corollary 14.2.1(p.96) (a). Accordingly, the assertion is true for the same reason as in the proof of (c2ii2i).

Corollary 22.1.10 Assume  $a^* < \rho < b$  and let  $\beta < 1$  or s > 0.

- (a) Let  $V_1 \leq x_K$ . Then  $z_t$  is nondecreasing in t > 0.
- (b) Let  $V_1 > x_K$ .
  - 1. Let  $\beta = 1$  or  $V_1 = 0$ . Then  $z_t = z(V_1)$  for t > 0.
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let  $V_1 > 0$ . Then  $z_t$  is nonincreasing in t > 0.
    - ii. Let  $V_1 < 0$ . Then  $z_t$  is nondecreasing in t > 0.  $\square$

#### 22.1.6.3 Market Restriction

### 22.1.6.3.1 Positive Restriction

### **22.1.6.3.1.1** Case of $\beta = 1$ and s = 0

- $\square$  Pom 22.1.9 ( $\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathbb{A}]^+\}$ ) Suppose a>0. Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\rho \leq a^*$ . Then  $[ \circ dOITs_{\tau>0} \langle \tau \rangle ]_{\blacktriangle}$  where  $Conduct_{\tau\geq t>0}_{\blacktriangle}$ .
- (c) Let  $b \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (d) Let  $a^* < \rho < b$ .
  - 1. Let  $a \leq \rho$ . Then  $\bullet dOITd_1\langle 0 \rangle_{\parallel}$  and  $\odot dOITs_{\tau > 1}\langle \tau \rangle_{\parallel}$  where  $Conduct_{\tau > t > 0}$  and  $pSKIP_1$  ([C-S])
- *Proof* The same as Lemma 22.1.2(p.176) due to Lemma 18.4.4(p.118).

### 22.1.6.3.1.2 Case of $\beta < 1$ or s > 0

# 22.1.6.3.1.2.1 Case of $\rho \leq a^{\star}$

- $\square$  Pom 22.1.10 ( $\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{A}]^+\}$ ) Suppose a>0. Assume  $\rho\leq a^\star$ . Let  $\beta<1$  or s>0 and let  $\rho< x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ \text{ dOITs}_1\langle 1 \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{1\blacktriangle}$ . Below let  $\tau > 1$ .
  - 2. Let  $\beta = 1$ .
    - i. Let  $(\lambda a s)/\lambda \le a^*$ .
      - 1. Let  $\lambda = 1$ . Then  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\parallel}$  where  $\texttt{Conduct}_{1_{\blacktriangle}}$ .
      - 2. Let  $\lambda < 1$ . Then  $subseteq dOITs_{\tau>1}\langle \tau \rangle$  where  $Conduct_{\tau>t>0}$ .
    - ii. Let  $(\lambda a s)/\lambda > a^*$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  and  $Conduct_{\tau > t > 0}_{\blacktriangle}$ .
  - 3. Let  $\beta < 1$  and s = 0. Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau \geq t > 0}_{\blacktriangle}$ .
  - 4. Let  $\beta < 1$  and s > 0.
    - i. Let  $(\lambda \beta a s)/\delta \le a^*$ .
      - 1. Let  $\lambda = 1$ .
        - i. Let  $s < \lambda \beta T(0)$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau \geq t > 0}_{\blacktriangle}$ .
        - ii. Let  $s \geq \lambda \beta T(0)$ . Then  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}$  where Conduct<sub>1</sub>.
      - 2. Let  $\lambda < 1$ .
        - i. Let  $s \leq \lambda \beta T(0)$ . Then  $subseteq doi: 100 \text{ doi: } t > 1 \text{ where } conduct_{\tau \geq t > 0}$ .
        - ii. Let  $s > \lambda \beta T(0)$ . Then  $S_3(p.163)$   $\boxed{\$ \blacktriangle \circledcirc \parallel}$  is true.
    - ii. Let  $(\lambda \beta a s)/\delta > a^*$ .
      - 1. Let  $s \geq \lambda \beta T(0)$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau \geq t > 0}_{\blacktriangle}$ .
      - 2. Let  $s < \lambda \beta T(0)$ . Then  $S_3(p.163)$  sample 1 is true.
- Proof Suppose a > 0, hence  $b > a > 0 \cdots (1)$ . Here note  $\kappa = \lambda \beta T(0) s$  from (6.1.23(p.26)).
  - (a-c2ii) The same as Tom 22.1.5(p.176) (26.2.43-c2ii).
  - (c3) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c3i1i,c3i2i,c3ii1) of Tom 22.1.5(p.176). (c4-c4ii2) The same as Tom 22.1.5(p.176) (c3-c3ii2) with  $\kappa$ .
- $\square$  Pom 22.1.11 ( $\mathscr{A}\{M:2[\mathbb{P}][\mathbb{A}]^+\}$ ) Suppose a>0. Assume  $\rho\leq a^*$ . Let  $\beta<1$  or s>0 and let  $\rho=x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\beta < 1$  and s = 0. Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$  where  $Conduct_{\tau>t>0}_{\blacktriangle}$ .
- (d) Let  $\beta < 1$  and s > 0.
  - 1. Let  $s < \beta \mu T(0)$ . Then  $startion{3 dolls } dolls = 0 \ dolls$
  - 2. Let  $s \geq \beta \mu T(0)$ . Then  $| \bullet dOITd_{\tau} \langle 0 \rangle |_{\parallel}$ .
- Proof Suppose a > 0, hence  $b > a > 0 \cdots$  (1). Here note  $\kappa = \lambda \beta T(0) s$  from (6.1.23(p.26)).
  - (a,b) The same as Tom 22.1.6(p.177)(a,b).
  - (c) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c1) of Tom 22.1.6(p.177).
  - (d-d2) The same as Tom 22.1.6(p.177) (c1,c2) with  $\kappa$ .
- $\square$  Pom 22.1.12 ( $\mathscr{A}\{M:2[\mathbb{P}][A]^+\}$ ) Suppose a>0. Assume  $\rho\leq a^\star$ . Let  $\beta<1$  or s>0 and let  $\rho>x_K$ .
- (a) Let  $\beta = 1$  or  $\rho = 0$ .
  - 1.  $V_t = \rho \text{ for } t \geq 0.$
  - 2. Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
  - 3. Let  $x_L > \rho$ . Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$  where  $Conduct_{\tau \geq t>0}_{\blacktriangle}$ .
- (b) Let  $\beta < 1$  and  $\rho > 0$  and let s = 0.
  - 1.  $V_t$  is nonincreasing in  $t \ge 0$  and converges to a finite V as  $t \to \infty$ .
  - 2. Let  $\rho < x_L$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle$  where  $conduct_{\tau \geq t>0}$ .
  - 3. Let  $\rho = x_L$ . Then  $\bullet dOITd_1\langle 0 \rangle_{\parallel}$  and  $\odot dOITs_{\tau>0}\langle \tau \rangle_{\triangle}$  where  $Conduct_{\tau\geq t>0}$ .
  - 4. Let  $x_L < \rho$ . Then  $S_4$   $\bullet \parallel c \sim s \Delta c \sim s \blacktriangle$  is true.
- (c) Let  $\beta < 1$  and  $\rho > 0$  and let s > 0.
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite V as  $t \to \infty$ .

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2. Let s \geq \beta \mu T(0). Then \boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\parallel}.
      3. Let s < \beta \mu T(0).
              i. Let \rho < x_L. Then subseteq dOITs_{\tau>0} \langle \tau \rangle where Conduct_{\tau\geq t>0}.
                     Let \rho = x_L. Then \bullet dOITd_1\langle 0 \rangle_{\parallel} and \odot dOITs_{\tau>0}\langle \tau \rangle_{\triangle} where Conduct_{\tau \geq t>0}.
                    Let x_L < \rho. Then S_4 \bullet \parallel c \multimap s \land c \multimap s \blacktriangle is true.
(d) Let \beta < 1 and \rho < 0 and let s = 0.
      1. V_t is nondecreasing in t \geq 0 and converges to a finite V as t \to \infty.
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- - 2.  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}$  where  $Conduct_{\tau>t>0}$ .
- (e) Let  $\beta < 1$  and  $\rho < 0$  and let s > 0.
  - 1.  $V_t$  is nondecreasing in t ( $\tau \geq t \geq 0$ ) and converges to a finite V as  $t \to \infty$ .
  - 2. Let  $s \geq \beta \mu T(0)$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ .
  - 3. Let  $s < \beta \mu T(0)$ . Then star down distance denotes the star distance of <math>star down distance denotes the star distance denotes the distance denotes the star distance denotes denote denotes the star distance denotes denote denotes denote denotes denotes denotes denote denotes d
- Proof Suppose a > 0, hence  $b > a > 0 \cdots$  (1). Here note  $\kappa = \lambda \beta T(0) s$  from (6.1.23(p.26)).
  - (a-a3) The same as Tom 22.1.7(p.177) (a-a3).
- (b-b4) Let  $\beta < 1$  and  $\rho > 0$  and let s = 0. Then, due to (1) it suffices to consider only (b1,b3i-b3iii) of Tom 22.1.7(p.177).
  - (c-c3iii) Let  $\beta < 1$  and  $\rho > 0$  and let s > 0. Then, we have the same as Tom 22.1.7(p.177) (b1-b3iii) with  $\kappa$ .
  - (d-d2) Let  $\beta < 1$  and  $\rho < 0$  and let s = 0. Then, due to (1) it suffices to consider only (c1,c3) of Tom 22.1.7(p.177).
  - (e-e3) Let  $\beta < 1$  and  $\rho < 0$  and let s > 0. Then, we have the same as Tom 22.1.7(p.177) (c1-c3) with  $\kappa$ .

# 22.1.6.3.1.2.2 Case of $b \le \rho$

- $\square$  Pom 22.1.13 ( $\mathscr{A}\{M:2[\mathbb{P}][\mathbb{A}]^+\}$ ) Suppose a>0. Assume  $b\leq\rho$ . Let  $\beta<1$  or s>0 and let  $\rho< x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ , is strictly increasing in  $t \geq 0$  if  $\lambda < 1$ , and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
- (b) Let  $x_L \leq \rho$ . Then  $\boxed{\bullet dOITd_{\tau>0}\langle 0 \rangle}_{\parallel}$ .
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$  where  $Conduct_{1 \blacktriangle}$ .  $Below let \tau > 1$ .
  - 2. Let  $\beta = 1$ . Then  $\boxed{\$}$  dOITs<sub> $\tau > 1$ </sub> $\langle \tau \rangle$  where Conduct<sub> $\tau > t > 0$ </sub>.
  - 3. Let  $\beta < 1$  and s = 0. Then s = 0 where t = 0 where t = 0.
  - 4. Let  $\beta < 1$  and s > 0.
    - i. Let  $s \leq \lambda \beta T(0)$ . Then  $subseteq dOITs_{\tau>1} \langle \tau \rangle$  where  $Conduct_{\tau>t>0}$ .
    - ii. Let  $s > \lambda \beta T(0)$ . Then  $S_3(p.163)$   $\boxed{\$ \blacktriangle \circledcirc \Vdash}$  is true.
- Proof Suppose a > 0, hence  $b > a > 0 \cdots (1)$ . Here note  $\kappa = \lambda \beta T(0) s$  from (6.1.23(p.26)).
  - (a-c2) The same as Tom 22.1.8(p.178) (a-c2).
  - (c3) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c3i) of Tom 22.1.8(p.178).
  - (c4-c4ii) Let  $\beta < 1$  and s > 0. Then, we have the same as Tom 22.1.8(p.178) (c3i,c3ii) with  $\kappa$ .
- $\square$  Pom 22.1.14 ( $\mathscr{A}\{M:2[\mathbb{P}][\mathbb{A}]^+\}$ ) Suppose a>0. Assume  $b\leq\rho$ . Let  $\beta<1$  or s>0 and let  $\rho=x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\beta = 1$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\parallel}$ .
- (c) Let  $\beta < 1$  and s = 0. Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$  where  $Conduct_{\tau>t>0}_{\blacktriangle}$ .
- (d) Let  $\beta < 1$  and s > 0.
  - $1. \quad Let \ s < \lambda \beta T(0). \ \ Then \ \boxed{\$ \ \text{dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle} \ \ where \ \text{Conduct}_{\tau\geq t>0\,\blacktriangle}.$
  - 2. Let  $s \geq \lambda \beta T(0)$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\parallel}$ .
- Proof Suppose a > 0, hence  $b > a > 0 \cdots$  (1). Here note  $\kappa = \lambda \beta T(0) s$  from (6.1.23(p.26)).
  - (a,b) The same as Tom 22.1.9(p.178)(a,b).
  - (c) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c1) of Tom 22.1.9(p.178).
  - (d-d2) Let  $\beta < 1$  and s > 0. Then, we have the same as Tom 22.1.9(p.178) (c1,c2) with  $\kappa$ .
- $\square$  Pom 22.1.15 ( $\mathscr{A}\{M:2[\mathbb{P}|[\mathbb{A}]^+\}\}$ ) Suppose a>0. Assume  $b\leq\rho$ . Let  $\beta<1$  or s>0 and let  $\rho>x_K$ .
- (a) Let  $\beta = 1$  or  $\rho = 0$ .
  - 1.  $V_t = \rho \text{ for } t > 0.$
  - 2. Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .

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         3. Let x_L > \rho. Then subseteq dOITs_{\tau>0}\langle \tau \rangle where Conduct_{\tau\geq t>0}.
(b) Let \beta < 1 and \rho > 0 and let s = 0.
         1. V_t is nonincreasing in t \geq 0 and converges to a finite V \geq x_K as t \to \infty.
         2. Let \rho < x_L. Then startion{$ (\$)$ dOITs}_{\tau>0} \langle \tau \rangle _{\blacktriangle} where startion{$ (\$)$ dOITs}_{\tau>0} _{\blacktriangle}.
         3. \quad Let \; \rho = \; x_L \; . \; \; Then \; \boxed{ \bullet \; \mathrm{dOITd}_1\langle 0 \rangle_{\parallel} \; \; and \; \boxed{\$ \; \mathrm{dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle} \; \; where \; \mathrm{Conduct}_{\tau \geq t>0_{\blacktriangle}}.
         4. Let x_L < \rho. Then S_4 \ \bullet \parallel \ c \rightarrow s \triangle \ c \rightarrow s \triangle \ is true.
(c) Let \beta < 1 and \rho > 0 and let s > 0.
         1. V_t is nonincreasing in t \geq 0 and converges to a finite V \geq x_K as t \to \infty.
         2. Let s \geq \lambda \beta T(0). Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}.
         3. Let s < \lambda \beta T(0).
                    i. Let \rho < x_L. Then subseteq dOITs_{\tau>0}\langle \tau \rangle where Conduct_{\tau>t>0}.
                   ii. Let \rho = x_L. Then \bullet dOITd_1\langle 0 \rangle_{\parallel} and \odot dOITs_{\tau>0}\langle \tau \rangle_{\blacktriangle} where Conduct_{\tau>t>0\blacktriangle}.
                  iii. Let x_L < \rho. Then S_4 \bullet \parallel c \sim s \Delta c \sim s A is true.
(d) Let \beta < 1 and \rho < 0 and let s = 0.
         1. V_t is nondecreasing in t \geq 0 and converges to a finite V \geq x_K as t \to \infty.
         2. \boxed{\$ dOITs_{\tau>0}\langle \tau \rangle} where Conduct_{\tau\geq t>0}.
(e) Let \beta < 1 and \rho < 0 and let s > 0.
         1. V_t is nondecreasing in t (\tau \geq t \geq 0).
         2. Let s \geq \lambda \beta T(0). Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}.
         3. \quad Let \ s < \lambda \beta T(0). \ \ Then \ \boxed{\$ \ \text{dOITs}_{\tau>0} \langle \tau \rangle}_{\blacktriangle} \ \ where \ \text{Conduct}_{\tau \geq t>0}_{\blacktriangle}.
• Proof Suppose a > 0, hence b > a > 0 \cdots (1). Here note \kappa = \lambda \beta T(0) - s from (6.1.23(p.26)).
      (a-a3) The same as Tom 22.1.10(p.178) (a-a3).
      (b-b4) Let \beta < 1 and \rho > 0 and let s = 0. Then, due to (1) it suffices to consider only
(b1,b3i-b3iii) of Tom 22.1.10(p.178).
      (c-c3iii) Let \beta < 1 and \rho > 0 and let s > 0. Then, we have the same as
Tom 22.1.10(p.178) (b1-b3iii) with \kappa.
      (d,d2) Let \beta < 1 and \rho < 0 and let s = 0. Then, due to (1) it suffices to consider only
(c1,c3) of Tom 22.1.10(p.178).
      (e-e3) Let \beta < 1 and \rho < 0 and let s > 0. Then, we have the same as
Tom 22.1.10(p.178) (c1-c3) with \kappa.
22.1.6.3.1.2.3 Case of a^* < \rho < b
\square Pom 22.1.16 (\mathscr{A}\{M:2[\mathbb{P}][A]^+\}) Suppose a > 0. Assume a^* \leq \rho < b. Let \beta < 1 or s > 0.
(a) If \lambda\beta \max\{0, a-\rho\} \leq s, then \bullet \text{dOITd}_1\langle 0 \rangle_{\parallel}, or else \odot \text{dOITs}_1\langle 1 \rangle_{\parallel} where \text{Conduct}_{1 \wedge}. Below let \tau > 1.
(b) Let V_1 \leq x_K.
         1. V_t is nondecreasing in t \geq 0 and converges to a finite V \geq x_K as t \to \infty.
         2. Let V_1 \geq x_L. Then, if \lambda \beta \max\{0, a - \rho\} \leq s, we have \bullet \text{dOITd}_{\tau > 1}\langle 0 \rangle_{\parallel}, or else \odot \text{ndOIT}_{\tau > 1}\langle 1 \rangle_{\parallel} where Conduct<sub>1.4</sub>.
         3. Let V_1 < x_L.
                    i. Let \beta = 1. Then \boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle} where Conduct_{\tau \geq t > 1}.
                   \text{ii.} \quad Let \ \beta < 1 \ \ and \ s = 0. \ \ Then \ \boxed{\$ \ \text{dOITs}_{\tau > 1} \langle \tau \rangle} \ _{\blacktriangle} \ \ where \ \ \text{Conduct}_{\tau \geq t > 1} \ _{\blacktriangle}.
                  iii. Let \beta < 1 and s > 0.
                           1. Let s < \lambda \beta T(0). Then subseteq doing subseteq under the subseteq of <math>subseteq doing subseteq doing subseteq under the subseteq doing 
                           2. Let s \geq \lambda \beta T(0). Then S_5 \subseteq S_A \subseteq S_A \subseteq S_B is true.
(c) Let V_1 > x_K.
         1. Let \beta = 1 or V_1 = 0.
                     i. V_t = V_1 \text{ for } t > 0.
```

i. Let  $V_1 > 0$ .

1. V. is nonincreasing in t > 0 and converges to

2. Let  $\beta < 1$  and s = 0.

1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .

 $\text{ii.} \quad \textit{If } \lambda \max\{0, a - \rho\} \leq s, \; \textit{then} \; \boxed{\bullet \; \texttt{dOITd}_{\tau > 1}\langle 0 \rangle}_{\parallel}, \; \textit{or else} \; \boxed{\odot \; \texttt{ndOIT}_{\tau > 1}\langle 1 \rangle}_{\parallel} \; \textit{where} \; \texttt{Conduct}_{1\blacktriangle}.$ 

- 2. Let  $V_1 > x_L$ . Then  $S_6 \odot \mathbb{R} \odot \mathbb{R} \odot \mathbb{R} \odot \mathbb{R} \odot \mathbb{R}$  is true.
- 3. Let  $V_1 = x_L$ . Then  $S_7 \ \boxed{\$ \blacktriangle \odot \parallel \blacktriangle \upharpoonright \circ \blacksquare } \ is true.$

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4. Let V_1 < x_L. Then subseteq dOITs_{\tau>1} \langle \tau \rangle where conduct_{\tau \geq t>0}.
                 ii. Let V_1 < 0.
                       1. Then V_t is nondecreasing in t \geq 0 and converges to a finite V \geq x_K as t \to \infty.
                       2. \quad Let \ V_1 \geq x_L \ . \ If \ \lambda\beta \max\{0, a-\rho\} \leq s, \ then \ \boxed{\bullet \ \text{dOITd}_{\tau>1}\langle 0 \rangle}_{\parallel}, \ or \ else \ \boxed{\odot \ \text{ndOIT}_{\tau>1}\langle 1 \rangle}_{\parallel} \ \ where \ \text{Conduct}_{1_{\blacktriangle}}.
                       3. Let V_1 < x_L. Then subseteq dOITs_{\tau>1} \langle \tau \rangle where subseteq conduct_{\tau \geq t > 1}.
              Let \beta < 1 and s > 0.
                  i. Let V_1 > 0.
                       1. V_t is nonincreasing in t \geq 0 and converges to a finite V \geq x_K as t \to \infty.
                       2. Let s < \lambda \beta T(0).
                             i. Let V_1 > x_L. Then S_6 S_A O I O I C S_C C S_A is true.
                            ii. Let V_1 = x_L. Then S_7 \ \boxed{\$ \blacktriangle \odot \parallel \bullet \parallel c \multimap s \Delta} is true.
                           iii. Let V_1 < x_L. Then sample dOITs_{\tau>1} \langle \tau \rangle_{\blacktriangle} where Conduct_{\tau>t>0}_{\blacktriangle}.
                       3. Let s \geq \lambda \beta T(0). If \lambda \beta \max\{0, a - \rho\} \leq s, then \bullet \text{dOITd}_{\tau > 1}\langle 0 \rangle_{\parallel}, or else \odot \text{ndOIT}_{\tau > 1}\langle 1 \rangle_{\parallel} where Conduct \bullet
                 ii. Let V_1 < 0.
                       1. Then V_t is nondecreasing in t \geq 0 and converges to a finite V \geq x_K as t \to \infty.
                       2. Let s < \lambda \beta T(0).
                             i. Let V_1 \geq x_L. If \lambda \beta \max\{0, a - \rho\} \leq s, then \boxed{\bullet \text{dOITd}_{\tau > 1}\langle 0 \rangle}_{\parallel}, or else \boxed{\odot \text{ndOIT}_{\tau > 1}\langle 1 \rangle}_{\parallel} where \texttt{Conduct}_{1 \blacktriangle}.
                            ii. Let V_1 < x_L. Then subseteq dOITs_{\tau>}\langle \tau \rangle where conduct_{\tau \geq t > 1}.
                       3. Let s \geq \lambda \beta T(0). If \lambda \beta \max\{0, a - \rho\} \leq s, then \bullet dOITd_{\tau > 1}\langle 0 \rangle_{\parallel}, or else \odot ndOIT_{\tau > 1}\langle 1 \rangle_{\parallel} where Conduct_{1}
• Proof Suppose a > 0, hence b > a > 0 \cdots (1). Here note \kappa = \lambda \beta T(0) - s from (6.1.23(p.26)).
     (a-b3i) The same as Tom 22.1.5(p.179) (a-b3i).
     (b3ii) Let \beta < 1 and s = 0. Then, due to (1) it suffices to consider only (b3ii1) of Tom 22.1.5(p.179).
     (b3iii-b3iii2) Let \beta < 1 and s > 0. Then, the two assertions are immediate from
Tom 22.1.5(p.179) (b3ii1,b3ii2) with \kappa.
     (c-c1ii) The same as Tom 22.1.5(p.179) (c-c1ii).
     (c2-c2i4) Let \beta < 1 and s = 0. Then, due to (1) it suffices to consider only
(c2i-c2i1,c2i2i-c2i2iii) of Tom 22.1.5(p.179).
     (c2ii-c2ii3) Due to (1) it suffices to consider only
(c2ii,c2ii1,c2ii2i,c2ii2ii) of Tom 22.1.5(p.179).
     (c3-c3i3) Let \beta < 1 and s > 0. Then, we have the same as Tom 22.1.5(p.179) (c2-c2i1,c2i2i-c2i2iii) with \kappa.
     (c3ii-c3ii3) We have the same as Tom 22.1.5(p.179) (c2ii-c2ii2ii) with \kappa.
22.1.6.3.2 Mixed Restriction
Omitted.
22.1.6.3.3 Negative Restriction
22.1.6.3.3.1 Case of \beta = 1 and s = 0
\square Nem 22.1.5 (\mathscr{A}\{M:2[\mathbb{P}][A]^-\}) Suppose b < 0. Let \beta = 1 and s = 0.
(a) V_t is nondecreasing in t \geq 0.
(b) Let \rho \leq a^*. Then subseteq doing doing to doing the subseteq <math>a^* where a^* conduct a^* where a^* is a^* where a^* and a^* is a^* and a^* and a^* are a^* and a^* is a^* and a^* are a^* and a^* and a^* are a^* are a^* and a^* are a^* are a^* and a^* are a^* and a^* are a^* and a^* are a^* and a^
(c) Let b \leq \rho. Then \bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}.
(d) Let a^* < \rho < b.
        1. Let a \leq \rho. Then \left[ \bullet \operatorname{dOITd}_1\langle 0 \rangle \right]_{\parallel} and \left[ \odot \operatorname{dOITs}_{\tau > 1}\langle \tau \rangle \right]_{\blacktriangle} where \operatorname{Conduct}_{\tau \geq t > 0}_{\blacktriangle} and \operatorname{pSKIP}_1.
        2. Let \rho < a. Then sample dOITs_{\tau>0} \langle \tau \rangle where Conduct_{\tau \geq t>0}.
ullet Proof The same as Lemma 22.1.2(p.176) due to Lemma 18.4.4(p.118). \blacksquare
22.1.6.3.3.2 Case of \beta < 1 or s > 0
22.1.6.3.3.2.1 Case of \rho \le a^*
\square Nem 22.1.6 (\mathscr{A}\{M:2[\mathbb{P}][A]^-\}) Suppose b<0. Assume \rho\leq a^\star. Let \beta<1 or s>0 and let \rho< x_K.
(a) V_t is nondecreasing in t \geq 0.
(b) Let x_L \leq \rho. Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}.
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(c) Let  $\rho < x_L$ .

2. Let  $\beta = 1$ .

1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$  where  $Conduct_{1\blacktriangle}$ .  $Below \ let \ \tau > 1$ .

- i. Let  $(\lambda a s)/\lambda \le a^*$ .
  - 1. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT<sub> $\tau > 1$ </sub> $\langle 1 \rangle$  | where Conduct<sub>1 \( \lambda \)</sub>.
  - 2. Let  $\lambda < 1$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau \geq t > 0}_{\blacktriangle}$ .
- ii. Let  $(\lambda a s)/\lambda > a^*$ . Then subseteq 0 doITs tau > 1 < t
- 3. Let  $\beta < 1$  and s = 0. Then we have  $S_3(p.163)$   $\boxed{S_{\bullet} \mid \odot \parallel}$
- 4. Let  $\beta < 1$  and s > 0.
  - i. Let  $(\lambda \beta a s)/\delta \le a^*$ .
    - 1. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT<sub> $\tau > 1$ </sub> $\langle 1 \rangle$  where Conduct<sub>1 \( \lambda \)</sub>.
    - 2. Let  $\lambda < 1$ . Then  $S_3(p.163)$   $\bullet$  is true.
  - ii. Let  $(\lambda \beta a s)/\delta > a^*$ . Then  $S_3(p.163)$   $\odot \bullet$   $\odot \bullet$  is true.
- *Proof* Suppose b < 0, hence  $a < b < 0 \cdots$  (1) and  $\kappa = -s \cdots$  (2) from Lemma 14.2.6(p.97) (a). Then  $a^* < 0 \cdots$  (3) due to Lemma 14.2.1(p.93) (n) and (1).
  - $(a,c2ii) \quad \text{The same as Tom } 22.1.5 \text{(p.176)} \ (26.2.43,c2ii) \ due \ to \ Lemma \ 18.4.4 \text{(p.118)} \ .$
- (c3) Let  $\beta < 1$  and s = 0. Assume  $(\lambda \beta a s)/\delta \le a^*$ . Then, since  $\lambda \beta a/\delta \le a^*$ , we have  $\lambda \beta a \le \delta a^*$  due to  $(11.2.2\,(1)\,(p.56))$ , hence  $\lambda \beta a \le \delta a^* \le \lambda a^*$  due to  $(11.2.2\,(1)\,(p.56))$  and (3), so that  $\beta a \le a^*$ , which contradicts [19(p.118)]. Thus, it must be that  $(\lambda \beta a s)/\delta > a^*$ . From this it suffices to consider only (c3ii2) of Tom 22.1.5(p.176).
- (c4-c4ii) Let  $\beta < 1$  and s > 0. Then  $\kappa < 0$  due to (2), hence it suffices to consider only (c3i1ii,c3i2ii,c3i2i) of Tom 22.1.5(p.176) with  $\kappa$ .
- $\square \ \text{Nem 22.1.7 ($\mathscr{A}$\{M:2[\mathbb{P}][\mathbb{A}]^-$\}$)} \quad \textit{Suppose } b < 0. \ \textit{Assume } \rho \leq a^\star. \ \textit{Let } \beta < 1 \ \textit{or } s > 0 \ \textit{and let } \rho = x_K.$
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) We have  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- Proof Suppose  $b < 0 \cdots (1)$ . Then  $\kappa = -s \cdots (2)$  from Lemma 14.2.6(p.97) (a).
  - (a) The same as Tom 22.1.6(p.177) (a).
- (b) Let  $\beta=1$ . Then, the assertion is the same as Tom 22.1.6(p.177) (b). Let  $\beta<1$ . If s=0, then due to (1) it suffices to consider only (c2) of Tom 22.1.6(p.177) and if s>0, then  $\kappa<0$  due to (2), hence it suffices to consider only (c2) of Tom 22.1.6(p.177); accordingly, whether s=0 or s>0, we have the same result. Thus, whether  $\beta=1$  or  $\beta<1$ , it eventually follows that we have the same result.
- $\square$  Nem 22.1.8 ( $\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathbb{A}]^-\}$ ) Suppose b<0. Assume  $\rho\leq a^\star$ . Let  $\beta<1$  or s>0 and let  $\rho>x_K$ .
- (a) Let  $\beta = 1$  or  $\rho = 0$ .
  - 1.  $V_t = \rho \text{ for } t \geq 0.$
  - 2. Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
  - 3. Let  $x_L > \rho$ . Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$  where  $Conduct_{\tau>t>0}_{\blacktriangle}$ .
- (b) Let  $\beta < 1$  and  $\rho > 0$ .
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
  - 2. We have  $\bullet dOITd_1\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\beta < 1$  and  $\rho < 0$ .
  - 1.  $V_t$  is nondecreasing in  $t \ge 0$  and converges to a finite  $V \ge x_K$  as  $t \to \infty$ .
  - 2. We have  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- Proof Suppose b < 0, hence  $\kappa = -s \cdots (1)$  from Lemma 14.2.6(p.97) (a).
  - (a-a3) The same as Tom 22.1.7(p.177) (a-a3).
  - (b) Let  $\beta < 1$  and  $\rho > 0$ .
  - (b1) The same as Tom 22.1.7(p.177) (b1).
- (b2) If s = 0, it suffices to consider only (b2) of Tom 22.1.7(p.177) and if s > 0, then  $\kappa < 0$  due to (1), hence it suffices to consider only (b2) of Tom 22.1.7(p.177). Accordingly, whether s = 0 or s > 0, it eventually follows that we have the same results.
  - (c) Let  $\beta < 1$  and  $\rho < 0$ .
  - (c1) The same as Tom 22.1.7(p.177) (c1).
- (c2) If s=0, it suffices to consider only (c2) of Tom 22.1.7(p.177) and if s>0, then  $\kappa<0$  due to (1), hence it suffices to consider only (c2) of Tom 22.1.7(p.177). Accordingly, whether s=0 or s>0, it eventually follows that we have the same results.

### 22.1.6.3.3.2.2 Case of $b \le \rho$

- $\square$  Nem 22.1.9 ( $\mathscr{A}\{M:2[\mathbb{P}][A]^-\}$ ) Suppose b < 0. Assume  $b \le \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho < x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ , is strictly increasing in  $t \geq 0$  if  $\lambda < 1$ , and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .

- (b) Let  $x_L \leq \rho$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\parallel}$ .
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$  where  $Conduct_{1\blacktriangle}$ .  $Below let \tau > 1$ .
  - 2. Let  $\beta = 1$ . Then  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}$  where  $Conduct_{\tau>t>0}$ .
  - 3. Let  $\beta < 1$ . Then  $S_3(p.163)$   $\bigcirc A$   $\bigcirc B$  is true.
- Proof Suppose b < 0. Then  $\kappa = -s \cdots$  (1) from Lemma 14.2.6(p.97) (a).
  - (a-c2) The same as Tom 22.1.8(p.178) (a-c2).
- (c3) Let  $\beta < 1$ . If s = 0, it suffices to consider only (c3ii) of Tom 22.1.8(p.178) and if s > 0, then  $\kappa < 0$  due to (1), hence it suffices to consider only (c3ii) of Tom 22.1.8(p.178). Accordingly, whether s = 0 or s > 0, it eventually follows that we have the same results.
- $\square$  Nem 22.1.10 ( $\mathscr{A}\{M:2[\mathbb{P}][A]^-\}$ ) Suppose b<0. Assume  $b\leq\rho$ . Let  $\beta<1$  or s>0 and let  $\rho=x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) We have  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- Proof Suppose b < 0. Then  $\kappa = -s \cdots$  (1) from Lemma 14.2.6(p.97) (a).
  - (a) The same as Tom 22.1.9(p.178) (a).
- (b) First, let  $\beta=1$ . Then, the assertion is the same as Tom 22.1.9(p.178) (b). Next, let  $\beta<1$ . If s=0, then it suffices to consider only (c2) of Tom 22.1.9(p.178) and if s>0, then  $\kappa<0$  due to (1), hence it suffices to consider only (c2) of Tom 22.1.9(p.178). Thus, whether s=0 or s>0, we have the same results. Accordingly, whether  $\beta=1$  or  $\beta<1$ , it eventually follows that we have the same result.
- $\square$  Nem 22.1.11 ( $\mathscr{A}\{M:2[\mathbb{P}][\mathbb{A}]^-\}$ ) Suppose b<0. Assume  $b\leq\rho$ . Let  $\beta<1$  or s>0 and let  $\rho>x_K$ .
- (a) Let  $\beta = 1$  or  $\rho = 0$ .
  - 1.  $V_t = \rho \text{ for } t \geq 0.$
  - 2. Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
  - 3. Let  $x_L > \rho$ . Then  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau \geq t>0}_{\blacktriangle}$ .
- (b) Let  $\beta < 1$  and  $\rho > 0$ .
  - 1.  $V_t$  is nonincreasing in  $t \ge 0$  and converges to a finite  $V \ge x_K$  as  $t \to \infty$ .
  - 2. We have  $\bullet dOITd_1\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\beta < 1$  and  $\rho < 0$ .
  - 1.  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
  - 2. We have Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- Proof Suppose  $b < 0 \cdots (1)$ , hence  $\kappa = -s \cdots (2)$  from Lemma 14.2.6(p.97) (a).
  - (a-a3) The same as Tom 22.1.10(p.178) (a-a3).
  - (b) Let  $\beta < 1$  and  $\rho > 0$ .
  - (b1) The same as Tom 22.1.10(p.178) (b1).
- (b2) If s=0, then it suffices to consider only (b2) of Tom 22.1.10(p.178) and if s>0, then  $\kappa<0$  due to (2), hence it suffices to consider only (b2) of Tom 22.1.10(p.178). Thus, whether s=0 or s>0, it eventually follows that we have the same result.
  - (c) Let  $\beta < 1$  and  $\rho < 0$ .
  - (c1) The same as Tom 22.1.10(p.178) (c1).
- (c2) If s=0, then it suffices to consider only (c2) of Tom 22.1.10(p.178) and if s>0, then  $\kappa<0$  due to (2), hence it suffices to consider only (c2) of Tom 22.1.10(p.178). Thus, whether s=0 or s>0, it eventually follows that we have the same result.

### 22.1.6.3.3.2.3 Case of $a^* < \rho < b$

- $\square$  Nem **22.1.12** ( $\mathscr{A}\{M:2[\mathbb{P}][\mathbb{A}]^{-}\}$ ) Suppose b < 0. Assume  $a^* \le \rho < b$ . Let  $\beta < 1$  or s > 0.
- (a) If  $\lambda\beta \max\{0, a \rho\} \leq s$ , then  $\boxed{\bullet \ dOITd_1\langle 0 \rangle}_{\parallel}$ , or else  $\boxed{\$ \ dOITs_1\langle 1 \rangle}_{\blacktriangle}$  where  $Conduct_{1}_{\blacktriangle}$ . Below let  $\tau > 1$ .
- (b) Let  $V_1 \leq x_K$ .
  - 1.  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
  - 2. Let  $V_1 \geq x_L$ . Then, if  $\lambda \beta \max\{0, a \rho\} \leq s$ , we have  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 0 \rangle}_{\parallel}$ , or else  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\parallel}$  where Conduct<sub>1.4</sub>.
  - $3. \quad Let V_1 < x_L.$ 
    - i. Let  $\beta=1$ . Then [\$] dOITs $_{\tau>1}\langle \tau \rangle$  where Conduct $_{\tau\geq t>1}$ .
- (c) Let  $V_1 > x_K$ .

- 1. Let  $\beta = 1$  or  $V_1 = 0$ . Then:
  - i.  $V_t = V_1 \text{ for } t > 0.$
  - ii. If  $\lambda \max\{0, a \rho\} \leq s$ , then  $\bullet \operatorname{dOITd}_{\tau > 1}\langle 0 \rangle_{\parallel}$ , or else  $\circ \operatorname{ndOIT}_{\tau > 1}\langle 1 \rangle_{\parallel}$  where  $\operatorname{Conduct}_{1_{\blacktriangle}}$ .
- 2. Let  $\beta < 1$ .
  - i. Let  $V_1 > 0$ .
    - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
    - 2. If  $\lambda\beta \max\{0, a-\rho\} \leq s$ , then  $\left[ \bullet \operatorname{dOITd}_{\tau>1}\langle 0 \rangle \right]_{\parallel}$ , or else  $\left[ \odot \operatorname{ndOIT}_{\tau>1}\langle 1 \rangle \right]_{\parallel}$  where  $\operatorname{Conduct}_{1\blacktriangle}$ .
  - ii. Let  $V_1 < 0$ .
    - 1. Then  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V \geq x_K$  as  $t \to \infty$ .
    - $2. \quad \textit{If } \lambda\beta \max\{0, a-\rho\} \leq s, \; then \; \boxed{\bullet \; \mathsf{dOITd}_{\tau>1}\langle 0\rangle}_{\parallel}, \; or \; else \; \boxed{\odot \; \mathsf{ndOIT}_{\tau>1}\langle 1\rangle}_{\parallel} \; \; where \; \mathsf{Conduct}_{1\blacktriangle}.$
- Proof Suppose  $b < 0 \cdots (1)$ , hence  $\kappa = -s \cdots (2)$  from Lemma 14.2.6(p.97) (a).
  - (a-b3i) The same as Tom 22.1.5(p.179) (a-b3i).
- (b3ii) Let  $\beta < 1$ . If s = 0, then due to (1) it suffices to consider only (b3ii2) of Tom 22.1.5(p.179) and if s > 0, then  $\kappa < 0$  due to (2), hence it suffices to consider only (b3ii2) of Tom 22.1.5(p.179) with  $\kappa$ . Accordingly, whether s = 0 or s > 0, we have the same result.
  - (c) Let  $V_1 > x_K$ .
  - (c1-c1ii) The same as Tom 22.1.5(p.179) (c1-c1ii).
  - (c2) Let  $\beta < 1$ .
  - (c2i) Let  $V_1 > 0$ .
  - (c2i1) The same as Tom 22.1.5(p.179) (c2i1).
- (c2i2) If s = 0, then it suffices to consider only (c2i3) of Tom 22.1.5(p.179) and if s > 0, then  $\kappa < 0$  due to (2), hence it suffices to consider only (c2i3) of Tom 22.1.5(p.179). Consequently, whether s = 0 or s > 0, we have the same result.
  - (c2ii) Let  $V_1 < 0$ .
  - (c2ii1) The same as Tom 22.1.5(p.179) (c2ii1).
- (c2ii2) If s=0, then it suffices to consider only (c2ii3) of Tom 22.1.5(p.179) and if s>0, then  $\kappa<0$  due to (2), hence it suffices to consider only (c2ii3) of Tom 22.1.5(p.179). Consequently, whether s=0 or s>0, we have the same result.

### **22.1.7** M:2[ $\mathbb{P}$ ][A]

# 22.1.7.1 Preliminary

Since Theorem 22.1.3(p.159) holds due to Lemma 22.1.1(p.159) (b), we can derive  $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathtt{A}]\}$  by applying  $\mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) to  $\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathtt{A}]\}$ .

#### **22.1.7.2** Analysis

#### **22.1.7.2.1** Case of $\beta = 1$ and s = 0

- $\square$  Tom 22.1.11 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{A}]\}$ ) Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in  $t \geq 0$ .
- (b) Let  $\rho \geq b^{\star}$ . Then  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}$  where  $\text{Conduct}_{\tau\geq t>0}$ .
- (c) Let  $a \geq \rho$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ .
- (d) Let  $b^* > \rho > a$ .
  - 1. Let  $b \ge \rho$ . Then  $\P \bullet \mathsf{dOITd}_1\langle 0 \rangle_{\parallel}$  and  $\P \bullet \mathsf{dOITs}_{\tau > 1}\langle \tau \rangle_{\blacktriangle}$  where  $\mathsf{Conduct}_{\tau \ge t > 1}_{\blacktriangle}$  and  $\mathsf{pSKIP}_{1_{\vartriangle}}$ .
  - 2. Let  $\rho > b$ . Then  $\boxed{\$ dOITs_{\tau > 0} \langle \tau \rangle}$  where  $Conduct_{\tau \geq t > 0}$ .
- ullet Proof by symmetry Immediate from applying  $\mathcal{S}_{\mathbb{P} \to \widetilde{\mathbb{P}}}$  to Lemma 22.1.2(p.176).

**Corollary 22.1.11** Let  $\beta = 1$  and s = 0. Then  $z_t$  is nonincreasing in  $t \geq 0$ .  $\square$ 

• Proof Immediate from Tom 22.1.11(p.191) (a) and from (7.2.111(p.36)) and Lemma A 3.3(p.306).

### **22.1.7.2.2** Case of $\beta < 1$ or s > 0

### 22.1.7.2.2.1 Case of $\rho > b^{\star \dagger}$

- $\ \, \square \ \, \text{Tom 22.1.12 (} \mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathbb{A}]\}) \quad \, \text{Assume $\rho \geq b^{\star}$. Let $\beta < 1$ or $s > 0$ and let $\rho > x_{\tilde{K}}$.}$
- (a)  $V_t$  is nonincreasing in  $t \geq 0$ , is strictly decreasing in  $t \geq 0$  if  $\lambda < 1$ , and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $x_{\tilde{L}} \geq \rho$ . Then  $\left[ \bullet dOITd_{\tau > 0} \langle 0 \rangle \right]_{\parallel}$ .
- (c) Let  $\rho > x_{\tilde{L}}$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$  where Conduct<sub>1</sub>. Below let  $\tau > 1$ .

<sup>&</sup>lt;sup>†</sup>The condition of  $\rho \geq b^*$  is what results from applying  $\mathcal{S}_{\mathbb{P} \to \overline{\mathbb{P}}}$  to the condition  $\rho \leq a^*$  in Section 22.1.6.2.2.1(p.176).

```
2. Let \beta = 1.
             i. Let (\lambda b + s)/\lambda \geq b^*.
                1. Let \lambda = 1. Then \bigcirc ndOIT_{\tau > 1}\langle 1 \rangle where Conduct<sub>1</sub>.
                 ii. Let (\lambda b + s)/\lambda < b^*. Then \boxed{\$ dOITs_{\tau>1}\langle \tau \rangle} where Conduct_{\tau\geq t>0}.
      3. Let \beta < 1 and s = 0 (s > 0).
             i. Let (\lambda \beta b + s)/\delta \ge b^*.
                 1. Let \lambda = 1.
                     i. Let a<0 (\tilde{\kappa}<0). Then \boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle} where \text{Conduct}_{\tau\geq t>0}.
                    ii. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \bigcirc ndOIT<sub>\tau > 1</sub>\langle 1 \rangle where Conduct<sub>1 \blacktriangle</sub>.
                 2. \quad Let \ \lambda < 1.
                     i. Let a \leq 0 (\tilde{\kappa} \leq 0). Then subseteq dOITs<sub>\tau > 1</sub>\langle \tau \rangle where Conduct<sub>\tau > t > 0</sub>.
                     ii. Let a > 0 (\tilde{\kappa} > 0). Then S_3(p.163) \boxed{\$ \blacktriangle \odot \parallel} is true.
            ii. Let (\lambda \beta b + s)/\delta < b^*.
                 1. Let a \leq 0 (\tilde{\kappa} \leq 0). Then startion{8}{\text{dOITs}_{\tau>1}\langle \tau \rangle} where {\text{Conduct}_{\tau \geq t>0}}.
                 2. Let a > 0 (\tilde{\kappa} > 0). Then S_3(p.163) \bullet is true. \Box
• Proof by symmetry Immediate from applying S_{\mathbb{P}\to\tilde{\mathbb{P}}} to Tom 22.1.5(p.176).
Corollary 22.1.12 Assume \rho \geq b^*, let \beta < 1 or s > 0, and let \rho > x_{\tilde{K}}. Then z_t is nonincreasing in t \geq 0. \square

    Proof Immediate from Tom 22.1.12(p.191) (a) and from (7.2.111(p.36)) and Lemma A 3.3(p.306).

\square Tom 22.1.13 (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathbb{A}]\}) Assume \rho \geq b^{\star}. Let \beta < 1 or s > 0 and let \rho = x_{\tilde{\kappa}}. Then, for a given starting time \tau > 0:
(a) V_t is nonincreasing in t \geq 0.
(b) Let \beta = 1. Then \bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}.
(c) Let \beta < 1 and s = 0 (s > 0).
      1. Let a < 0 (\tilde{\kappa} < 0). Then \odot dOITs<sub>\tau > 0</sub>\langle \tau \rangle and Conduct<sub>\tau \ge t > 0</sub>.
      2. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \bullet dOITd_{\tau > 0}\langle 0 \rangle.
• Proof by symmetry Clear from applying S_{\mathbb{P}\to\tilde{\mathbb{P}}} to Tom 22.1.6(p.177).
Corollary 22.1.13 Assume \rho \geq b^*. Let \beta < 1 or s > 0 and let \rho = x_{\tilde{K}}. Then z_t is nonincreasing in t \geq 0. \square
• Proof Immediate from Tom 22.1.13(p.192) (a) and from (7.2.111(p.36)) and Lemma A 3.3(p.306). ■
\square Tom 22.1.14 (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathtt{A}]\}) Assume \rho \geq b^{\star}. Let \beta < 1 or s > 0 and let \rho < x_{\tilde{K}}.
(a) Let \beta = 1 or \rho = 0.
      1. V_t = \rho \text{ for } t \geq 0.
      2. Let x_{\tilde{L}} \geq \rho. Then | \bullet dOITd_{\tau > 0} \langle 0 \rangle |_{\parallel}.
      3. Let x_{\tilde{L}} < \rho. Then \odot dOITs_{\tau>0} \langle \tau \rangle where Conduct_{\tau>t>0}.
(b) Let \beta < 1 and \rho > 0 and let s = 0 (s > 0).
      1. V_t is nondecreasing in t \geq 0 and converges to a finite V \leq x_{\tilde{K}} as t \to \infty.
      2. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \bullet dOITd_{\tau>0}\langle 0 \rangle
      3. Let a < 0 \ (\tilde{\kappa} < 0).
             i. Let \rho > x_{\tilde{L}}. Then subseteq dOITs_{\tau>0}\langle \tau \rangle where conduct_{\tau\geq t>0}.
            ii. Let \rho = x_{\tilde{L}}. Then \boxed{\bullet \text{ dOITd}_1\langle 0 \rangle} where \boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle} where \boxed{\text{Conduct}_{\tau\geq t>0}}.
           iii. Let \rho < x_{\tilde{L}}. Then S_4 \bullet \parallel c_{\sim S\Delta} c_{\sim SA} is true.
(c) Let \beta < 1 and \rho < 0 and let s = 0 (s > 0).
      1. V_t is nonincreasing in t \geq 0 and converges to a finite V \leq x_{\tilde{K}} as t \to \infty.
      2. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \bullet dOITd_{\tau>0}\langle 0 \rangle
      3. Let a < 0 (\tilde{\kappa} < 0). Then sample doing = 0 where sample doing = 0. sample doing = 0.
• Proof by symmetry Immediate from applying \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}} to Tom 22.1.7(p.177).
Corollary 22.1.14 Assume \rho \geq b^*. Let \beta < 1 or s > 0 and let \rho < x_{\tilde{K}}.
      Let \beta = 1 or \rho = 0. Then z_t is constant in t (z_t = z(\rho) \text{ for } t \geq 0).
```

(b) Let β < 1 and ρ > 0. Then z<sub>t</sub> is nondecreasing in t ≥ 0 for any s ≥ 0.
(c) Let β < 1 and ρ < 0. Then z<sub>t</sub> is nonincreasing in t ≥ 0 for any s ≥ 0.

Lemma A 3.3(p.306). ■

• Proof by symmetry Evident from Tom 22.1.14(p.192) (a1,b1,c1) and from (7.2.111(p.36)) and

### 22.1.7.2.2.2 Case of $a \geq \rho^{\dagger}$

 $\square$  Tom 22.1.15 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathbb{A}]\}$ ) Assume  $a \geq \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho > x_{\tilde{K}}$ .

- (a)  $V_t$  is nonincreasing in  $t \geq 0$ , is strictly decreasing in  $t \geq 0$  if  $\lambda < 1$ , and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $x_{\tilde{L}} \geq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho > x_{\tilde{L}}$ .
  - 1.  $\boxed{\$ \text{ dOITs}_1\langle 1 \rangle}$  where  $\text{Conduct}_{1\blacktriangle}$ . Below let  $\tau > 1$ .
  - 2. Let  $\beta=1$ . Then  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}$  where  $\text{Conduct}_{\tau\geq t>0}$ .
  - 3. Let  $\beta < 1$  and s = 0 ((s > 0)).
    - i. Let  $a \leq 0$  ( $\tilde{\kappa} \leq 0$ ). Then subseteq subseteq subseteq where subseteq where subseteq subseteq
    - ii. Let a>0 ( $\tilde{\kappa}>0$ ) . Then  $S_3(p.163)$   $\boxed{\$ \blacktriangle \circledcirc \|}$  is true.  $\square$
- Proof by symmetry Immediate from applying  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Tom 22.1.8(p.178).

Corollary 22.1.15 Assume  $a \ge \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho > x_{\tilde{K}}$ . Then  $z_t$  is nonincreasing in  $t \ge 0$ .  $\square$ 

- *Proof* Evident from Tom 22.1.15(p.193) (a) and from (7.2.111(p.36)) and Lemma A 3.3(p.306). ■
- $\square$  Tom 22.1.16 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathtt{A}]\}$ ) Assume  $a \geq \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho = x_{\tilde{K}}$ .
- (a)  $V_t$  is nonincreasing in  $t \geq 0$ .
- (b) Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\beta < 1$  and s = 0 (s > 0).
  - 1. Let a < 0 ( $\tilde{\kappa} < 0$ ). Then  $subseteq dOITs_{\tau > 0} \langle \tau \rangle$  and  $conduct_{\tau \geq t > 0}$ .
  - 2. Let  $a \geq 0$  ( $\tilde{\kappa} \geq 0$ ). Then  $\boxed{\bullet \text{dOITd}_{\tau>0}\langle 0 \rangle}$ .
- Proof by symmetry Immediate from applying  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Tom 22.1.9(p.178).

Corollary 22.1.16 Assume  $a \ge \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho = x_{\tilde{K}}$ . Then  $z_t$  is nonincreasing in  $t \ge 0$ .  $\square$ 

- *Proof* Evident from Tom 22.1.16(p.193) (a) and from (7.2.111(p.36)) and Lemma A 3.3(p.306). ■
- $\square$  Tom 22.1.17 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathtt{A}]\}$ ) Assume  $a \geq \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho < x_{\tilde{K}}$ .
- (a) Let  $\beta = 1$  or  $\rho = 0$ .
  - 1.  $V_t = \rho \text{ for } t \geq 0.$
  - 2. Let  $x_{\tilde{L}} \geq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
  - 3. Let  $x_{\tilde{L}} < \rho$ . Then  $sample dollets_{\tau>0} \langle \tau \rangle$  where  $conduct_{\tau \geq t>0}$ .
- (b) Let  $\beta < 1$  and  $\rho > 0$  and let s = 0 (s > 0).
  - 1.  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
  - 2. Let  $a \geq 0$  ( $\tilde{\kappa} \geq 0$ ). Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ .
  - 3. Let  $a < 0 \ (\tilde{\kappa} < 0)$ .
    - i. Let  $\rho > x_{\tilde{L}}$ . Then  $subseteq dOITs_{\tau>0}\langle \tau \rangle$  where  $conduct_{\tau\geq t>0}$ .
    - ii. Let  $\rho = x_{\tilde{L}}$ . Then  $\boxed{\bullet \text{ dOITd}_1\langle 0 \rangle}_{\parallel}$  where  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$  where  $\texttt{Conduct}_{\tau\geq t>0}_{\blacktriangle}$ .
    - iii. Let  $x_{\tilde{L}} > \rho$ . Then  $S_4$   $\bullet \parallel c_{\sim S\Delta} c_{\sim SA}$  is true.
- (c) Let  $\beta < 1$  and  $\rho < 0$  and let s = 0 (s > 0).
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
  - 2. Let  $a \geq 0$  ( $\tilde{\kappa} \geq 0$ ). Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
  - 3. Let a < 0 ( $\tilde{\kappa} < 0$ ). Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle$  where  $Conduct_{\tau>t>0}$ .
- ullet Proof by symmetry Immediate from applying  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Tom 22.1.10(p.178).

Corollary 22.1.17 Assume  $a \ge \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho < x_{\tilde{K}}$ .

- (a) Let  $\beta = 1$  or  $\rho = 0$ . Then  $z_t = z(\rho)$  for  $t \ge 0$ .
- (b) Let  $\beta < 1$  and  $\rho > 0$  and let s = 0 (s > 0). Then  $z_t$  is nondecreasing in  $t \ge 0$ .
- (c) Let  $\beta < 1$  and  $\rho < 0$  and let s = 0 (s > 0). Then  $z_t$  is nonincreasing in  $t \ge 0$ .

 $<sup>^\</sup>dagger$ The condition of  $a \geq \rho$  is what results from applying  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to the condition of  $b \leq \rho$  in Section 22.1.6.2.2.2(p.178).

### 22.1.7.2.2.3 Case of $b^* > \rho > a^{\dagger}$

Let us here note that (22.1.61(p.179)) changes as follows.

$$V_1 = \min\{\lambda\beta \min\{0, b - \rho\} + s, 0\} + \beta\rho.^{\dagger}$$
(22.1.62)

 $\square$  Tom 22.1.18 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathtt{A}]\}$ ) Assume  $b^*>\rho>a$ . Let  $\beta<1$  or s>0.

- (a) If  $\lambda\beta\min\{0,\rho-b\} \geq -s$ , then  $\boxed{\bullet \ \text{dOITd}_1\langle 0\rangle}_{\parallel}$ , or else  $\boxed{\$ \ \text{dOITs}_1\langle 1\rangle}_{\blacktriangle}$  where  $\text{Conduct}_{1}_{\blacktriangle}$ . Below let  $\tau > 1$ .
- (b) Let  $V_1 \geq x_{\tilde{K}}$ .
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
  - 2. Let  $V_1 \leq x_{\tilde{L}}$ . Then, if  $\lambda \beta \min\{0, \rho b\} \geq -s$ , we have  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 0 \rangle}_{\parallel}$ , or else  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\parallel}$  where  $\texttt{Conduct}_{1 \blacktriangle}$ .
  - 3. Let  $V_1 > x_{\tilde{L}}$ .
    - i. Let  $\beta=1$ . Then  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}$  where  $\text{Conduct}_{\tau\geq t>1}$ .
    - ii. Let  $\beta < 1$  and s = 0 (s > 0).
      - 1. Let a<0 ( $\tilde{\kappa}<0$ ) . Then  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau\rangle}$  where  $\texttt{Conduct}_{\tau\geq t>1}$ .
      - 2. Let  $a \geq 0$  ( $\tilde{\kappa} \geq 0$ ). Then  $S_5$  sample 1 is true.
- (c) Let  $V_1 < x_{\tilde{K}}$ .
  - 1. Let  $\beta = 1$  or  $V_1 = 0$ .
    - i.  $V_t = V_1 \text{ for } t > 0.$
    - ii. If  $\lambda \min\{0, \rho b\} \ge -s$ , then  $\left[ \bullet \operatorname{dOITd}_{\tau > 1} \langle 0 \rangle \right]_{\parallel}$ , or else  $\left[ \odot \operatorname{ndOIT}_{\tau > 1} \langle 1 \rangle \right]_{\parallel}$  where  $\operatorname{Conduct}_{1 \blacktriangle}$ .
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let  $V_1 < 0$ .
      - 1.  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V \leq x_{\tilde{\kappa}}$  as  $\tau \to \infty$ .
      - 2. Let a < 0 ( $\tilde{\kappa} < 0$ ). Then
        - i. Let  $V_1 < x_{\tilde{L}}$ . Then  $S_6$   $\bullet \mid \bullet \mid \odot \mid c \rightarrow s \land c \rightarrow s \land s \land$
        - ii. Let  $V_1 = x_{\tilde{L}}$ . Then  $S_7$   $\bullet \Vdash \odot \Vdash c \multimap s \triangle$  is true.
        - iii. Let  $V_1 > x_{\tilde{L}}$ . Then  $subseteq dOITs_{\tau>1}\langle \tau \rangle$  where  ${\tt Conduct}_{\tau \geq t>0}$ .
      - $3. \quad Let \ \ a \geq 0 \ (\!(\tilde{\kappa} \geq 0\!)\!) \ . \ \ If \ \lambda\beta \min\{0, \rho b\} \geq -s, \ then \ \boxed{\bullet \ dOITd_{\tau > 1}\langle 0\rangle}_{\parallel}, \ or \ else \ \boxed{\odot \ ndOIT_{\tau > 1}\langle 1\rangle}_{\parallel} \ \ where \ Conduct_{1_{\blacktriangle}}.$
    - ii. Let  $V_1 > 0$ .
      - 1. Then  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \leq x_{\tilde{K}}$  as  $\tau \to \infty$ .
      - 2. Let a < 0 ( $\tilde{\kappa} < 0$ ). Then
        - i. Let  $V_1 \leq x_{\tilde{L}}$ . If  $\lambda \beta \min\{0, \rho b\} \geq -s$ , then  $\left[ \bullet \operatorname{dOITd}_{\tau > 1}\langle 0 \rangle_{\parallel}, \text{ or else } \left[ \odot \operatorname{ndOIT}_{\tau > 1}\langle 1 \rangle_{\parallel} \text{ where } \operatorname{Conduct}_{1A} \right]$ .
        - ii. Let  $V_1 > x_{\tilde{L}}$ . Then  $\boxed{\$ dOITs_{\tau} > \langle \tau \rangle}$  where  $Conduct_{\tau > t > 1}$ .
      - $3. \quad Let \ \ a \geq 0 \ (\!(\tilde{\kappa} \geq 0)\!) \ \ . \ \ If \ \lambda\beta \min\{0, \rho b\} \geq -s, \ then \ \boxed{\bullet \ dOITd_{\tau > 1}\langle 0\rangle}_{\parallel}, \ or \ else \ \boxed{\odot \ ndOIT_{\tau > 1}\langle 1\rangle}_{\parallel} \ \ where \ Conduct_{1_{\blacktriangle}}. \ \ \Box$
- Proof by symmetry Immediate from applying  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Tom 22.1.5(p.179).

Corollary 22.1.18 Assume  $b^* > \rho > a$ . Let  $\beta < 1$  or s > 0:

- (a) Let  $V_1 \geq x_{\tilde{K}}$ . Then  $z_t$  is nonincreasing in t > 0.
- (b) Let  $V_1 < x_{\tilde{K}}$ . Then
  - 1. Let  $\beta = 1$  or  $V_1 = 0$ . Then  $z_t$  is constant in t > 0 ( $z_t = z(V_1)$  for t > 0).
  - 2. Let  $\beta < 1$ .
    - i. Let  $V_1 < 0$ . Then  $z_t$  is nondecreasing in t > 0 for any  $s \ge 0$ .
    - ii. Let  $V_1 > 0$ . Then  $z_t$  is nonincreasing in t > 0 for any  $s \ge 0$ .
- *Proof* Immediate from Tom 22.1.18(p.194) (b1,c1i,c2i1,c2ii1) and from (7.2.111(p.36)) and Lemma A 3.3(p.306).

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<sup>†</sup>The condition of b^{\star} > \rho > a is what results from applying S_{\mathbb{P} \to \tilde{\mathbb{P}}} to the condition of a^{\star} < \rho < b in Section 22.1.6.2.2.3(p.179).
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 $-\hat{V}_1 = \max\{\lambda\beta\max\{0,-\hat{a}+\hat{
ho}\}-s,0\}-\beta\hat{
ho}$  (apply the reflection to (22.1.61(p.179)))

 $\hat{V}_1 = -\max\{\lambda\beta\max\{0, -\hat{a} + \hat{\rho}\} - s, 0\} + \beta\hat{\rho}$  (multiply the above by -1)

=  $\min\{-\lambda\beta \max\{0, -\hat{a} + \hat{\rho}\} + s, 0\} + \beta\hat{\rho}$  (arrangement the above)

=  $\min\{\lambda\beta\min\{0,\hat{a}-\hat{\rho}\}+s,0\}+\beta\hat{\rho}$  (arrangement the above)

 $\hat{V}_1 \ = \ \min\{\lambda\beta\min\{0,\check{b}-\hat{\rho}\}+s,0\} + \beta\hat{\rho} \quad \text{(apply $\mathcal{I}_{\mathbb{R}}$ to the above)}$ 

 $\hat{V}_1 \ = \ \min\{\lambda\beta\min\{0,b-\hat{\rho}\}+s,0\} + \beta\hat{\rho} \quad \text{(apply $\mathcal{C}_{\mathbb{R}}$ to the above)}$ 

 $V_1 = \min\{\lambda\beta\min\{0, b-\rho\} + s, 0\} + \beta\rho$  (remove the hat symbol ^)

 $<sup>^{\</sup>dagger}$ See Remark 22.1.2(p.179).

### 22.1.7.3 Market Restriction

#### 22.1.7.3.1 Positive Restriction

### **22.1.7.3.1.1** Case of $\beta = 1$ and s = 0

- $\square$  Pom 22.1.17 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{A}]^+\}$ ) Suppose a>0. Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in  $t \geq 0$ .
- (b) Let  $\rho \geq b^{\star}$ . Then  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}$  where  $\texttt{Conduct}_{\tau\geq t>0}$ .
- (c) Let  $a \geq \rho$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ .
- (d) Let  $b^* > \rho > a$ .
  - 1. Let  $b \geq \rho$ . Then  $\bullet dOITd_1\langle 0 \rangle_{\parallel}$  and  $\odot dOITs_{\tau > 1}\langle \tau \rangle_{\blacktriangle}$  where  $Conduct_{\tau \geq t > 0}_{\blacktriangle}$  and  $C \hookrightarrow S_{1\Delta}$ .
  - 2. Let  $\rho > b$ . Then  $\boxed{\$ dOITs_{\tau > 0} \langle \tau \rangle}_{\blacktriangle}$  where  $Conduct_{\tau \geq t > 0}_{\blacktriangle}$ .  $\square$
- Proof by diagonal-symmetry Immediate from applying  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) to Nem 22.1.5(p.188) (see (19.3.10(p.134))). ■
- Direct proof The same as Tom 22.1.11(p.191) due to Lemma 18.4.4(p.118).

#### 22.1.7.3.1.2 Case of $\beta < 1$ or s > 0

### 22.1.7.3.1.2.1 Case of $\rho > b^*$

- $\square$  Pom 22.1.18 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathbb{A}]^+\}$ ) Suppose a>0. Assume  $\rho\geq b^\star$ . Let  $\beta<1$  or s>0 and let  $\rho>x_{\tilde{\kappa}}$ .
- (a)  $V_t$  is nonincreasing in  $t \geq 0$ , is strictly decreasing in  $t \geq 0$  if  $\lambda < 1$ , and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $x_{\tilde{L}} \geq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho > x_{\tilde{L}}$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$  and  $Conduct_{1}$ .  $Below let \tau > 1$ .
  - 2. Let  $\beta = 1$ .
    - i. Let  $(\lambda b + s)/\lambda \ge b^*$ .
      - 1. Let  $\lambda = 1$ . Then  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\parallel}$  where  $\texttt{Conduct}_{1_{\blacktriangle}}$ .
      - 2. Let  $\lambda < 1$ . Then  $subseteq doing doing to <math>t_{\tau \geq t > 0}$ . Where  $t_{\tau \geq t > 0}$ .
    - ii. Let  $(\lambda b + s)/\lambda < b^{\star}$ . Then  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$  where  $Conduct_{\tau\geq t>0}_{\blacktriangle}$ .
  - 3. Let  $\beta < 1$  and s > 0. Then we have  $S_3(p.163)$   $\boxed{\$ \blacktriangle \circledcirc \Vdash}$ .
  - 4. Let  $\beta < 1$  and s > 0.
    - i. Let  $(\lambda \beta b + s)/\delta \geq b^*$ .
      - 1. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT<sub> $\tau > 1$ </sub> $\langle 1 \rangle$  where Conduct<sub>1</sub>.
      - 2. Let  $\lambda < 1$ . Then  $S_3(p.163)$   $\bullet$  is true.
    - ii. Let  $(\lambda \beta b + s)/\delta < b^*$ . Then  $S_3(p.163)$  subseteq 0.163 is true. subseteq
- Proof by diagonal-symmetry Immediate from applying  $S_{\mathbb{P}\to\tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) to Nem 22.1.6(p.188) (see (19.3.10(p.134))). ■
- Direct proof Suppose  $a > 0 \cdots$  (1), hence  $b > a > 0 \cdots$  (2) and  $b^* > 0 \cdots$  (3) from Lemma 15.6.1(p.107) (n) and (2). Then we have  $\tilde{\kappa} = s \cdots$  (4) from Lemma 15.6.6(p.108) (a).
  - (a-c2ii) The same as Tom 22.1.12(p.191) (a-c2ii).
- (c3) Let  $\beta < 1$  and s = 0. Assume  $(\lambda \beta b + s)/\delta \ge b^*$ . Then since  $\lambda \beta b/\delta \ge b^*$ , we have  $\lambda \beta b \ge \delta b^*$  from (11.2.2 (1) (p.56)), hence  $\lambda \beta b \ge \delta b^* \ge \lambda b^*$  due to (3), so that  $\beta b \ge b^*$ , which contradicts [7(p.118)]. Thus it must be that  $(\lambda \beta b + s)/\delta < b^*$ . From this it suffices to consider only (c3ii2) of Tom 22.1.12(p.191).
- (c4-c4ii) Let  $\beta < 1$  and s > 0. Then  $\kappa > 0$  due (2), hence it suffices to consider only (c3i1ii,c3i2ii,c3ii2) of Tom 22.1.12(p.191); accordingly, whether s = 0 or s > 0, we have the same result.
- $\square \text{ Pom 22.1.19 } \left( \mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathbb{A}]^+\} \right) \quad \text{Suppose } a>0. \text{ Assume } \rho \geq b^\star. \text{ Let } \beta < 1 \text{ or } s>0 \text{ and let } \rho = x_{\tilde{K}}.$
- (a)  $V_t$  is nonincreasing in t > 0.
- (b) We have  $\boxed{\bullet dOITd_{\tau>0}\langle 0\rangle}_{\parallel}$ .  $\square$
- Proof by diagonal-symmetry Immediate from applying  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) to Nem 22.1.7(p.189) (see (19.3.10(p.134))). ■
- Direct proof Suppose a > 0. Then  $\tilde{\kappa} = s \cdots$  (1) from Lemma 15.6.6(p.108) (a).
  - (a) The same as Tom 22.1.13(p.192) (a).
- (b) Let  $\beta=1$ . Then, we have  $\boxed{\bullet \ \text{dOITd}_{\tau>0}\langle 0\rangle}_{\parallel}$  from Tom 22.1.13(p.192) (b). Let  $\beta<1$ . Then, if s=0, it suffices to consider only (c2) of Tom 22.1.13(p.192) and if s>0, then  $\tilde{\kappa}>0$  due to (1), hence it suffices to consider only (c2) of Tom 22.1.13(p.192); accordingly, whether s=0 or s>0, we have the same results. Therefore, whether  $\beta=1$  or  $\beta<1$ , we have the same result.

- 196  $\square$  Pom 22.1.20 ( $\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{P}][\mathbb{A}]^+\}$ ) Suppose a>0. Assume  $\rho\geq b^\star$ . Let  $\beta<1$  or s>0 and let  $\rho< x_{\tilde{K}}$ . (a) Let  $\beta = 1$  or  $\rho = 0$ . 1.  $V_t = \rho \text{ for } t > 0.$ 2. Let  $x_{\tilde{L}} \geq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ . 3. Let  $x_{\tilde{L}} < \rho$ . Then  $subseteq 0.01Ts_{\tau>0} \langle \tau \rangle_{\perp}$  where  $conduct_{\tau>t>0}$ . (b) Let  $\beta < 1$  and  $\rho > 0$ . 1.  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ . 2.  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ . (c) Let  $\beta < 1$  and  $\rho < 0$ . 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .  $\bullet$  d0ITd<sub> $\tau>0$ </sub> $\langle 0 \rangle$ <sub>||.  $\square$ </sub> • Proof by diagonal-symmetry Immediate from applying  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) to Nem 22.1.8(p.189) (see (19.3.10(p.134)). • Direct proof Suppose  $a > 0 \cdots (1)$ . Then  $\tilde{\kappa} = s \cdots (2)$  from Lemma 15.6.6(p.108) (a).  $\mbox{(a-a3)} \quad \mbox{The same as Tom } 22.1.14 \mbox{(p.192) (a-a3)}.$ (b-b2) Let  $\beta < 1$  and  $\rho > 0$ . First, we have the same as Pom 22.1.14(b1). Next, if s = 0, then due to (1) it suffices to consider only (b2) of Tom 22.1.14(p.192) and if s > 0, then since  $\tilde{\kappa} > 0$  from (2), it suffices to consider only (b2) of Tom 22.1.14(p.192). Thus, whether s = 0 or s > 0, we have the same result. (c-c2) Let  $\beta < 1$  and  $\rho < 0$ . First, we have the same as Pom 22.1.14(c1). Next, if s = 0, then due to (1) it suffices to consider only (c2) of Tom 22.1.14(p.192) and if s > 0, then since  $\tilde{\kappa} > 0$  from (2), it suffices to consider only (c2) of Tom 22.1.14(p.192). Thus, whether s = 0 or s > 0, we have the same result. **22.1.7.3.1.2.2** Case of  $a \ge \rho$  $\square$  Pom 22.1.21 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathbb{A}]^+\}$ ) Suppose a>0. Assume  $a\geq\rho$ . Let  $\beta<1$  or s>0 and let  $\rho>x_{\tilde{K}}$ . (a)  $V_t$  is nonincreasing in  $t \geq 0$ , is strictly decreasing in  $t \geq 0$  if  $\lambda < 1$ , and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ . (b) Let  $x_{\tilde{L}} \geq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ . (c) Let  $\rho > x_{\tilde{L}}$ . 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$  where  $Conduct_{1 \blacktriangle}$ .  $Below \ let \ \tau > 1$ . 3. Let  $\beta < 1$ . Then  $S_3(p.163)$   $\bigcirc A$   $\bigcirc A$  is true.  $\square$ • Proof by diagonal-symmetry Immediate from applying  $S_{\mathbb{P} \to \mathbb{P}}$  (see (20.0.3(p.136))) to Nem 22.1.9(p.189) (see (19.3.10(p.134))). ■ • Direct proof Suppose  $a > 0 \cdots (1)$ . Then  $\tilde{\kappa} = s \cdots (2)$  from Lemma 15.6.6(p.108) (a). (a-c2) The same as Tom 22.1.15(p.193) (a-c2). (c3) Let  $\beta < 1$ . Then, if s = 0, then due to (1) it suffices to consider only (c3ii) of Tom 22.1.15(p.193) and if s > 0, then  $\tilde{\kappa} > 0$ due to (2), hence it suffices to consider only (c3ii) of Tom 22.1.15(p.193). Thus, whether s = 0 or s > 0, we have the same result.  $\square$  Pom 22.1.22 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathbb{A}]^+\}$ ) Suppose a>0. Assume  $a>\rho$ . Let  $\beta<1$  or s>0, and let  $\rho=x_{\tilde{K}}$ . (a)  $V_t$  is nonincreasing in  $t \geq 0$ . (b) We have  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .  $\square$
- Proof by diagonal-symmetry Immediate from applying  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) to Nem 22.1.10(p.190) (see (22.1.32(p.162))). ■
- Direct proof Suppose  $a > 0 \cdots (1)$ . Then  $\tilde{\kappa} = s \cdots (2)$  from Lemma 15.6.6(p.108) (a).
  - (a) The same as Tom 22.1.16(p.193) (a).
- (b) Let  $\beta=1$ . Then  $\boxed{\bullet \ dOITd_{\tau>0}\langle 0\rangle}_{\parallel}$  from Tom 22.1.16(p.193) (b). Let  $\beta<1$ . Then, if s=0, then due to (1) it suffices to consider only (c2) of Tom 22.1.16(p.193), and if s>0, then  $\tilde{\kappa}\geq 0$  due to (2), hence it suffices to consider only (c2) of Tom 22.1.16(p.193) with  $\tilde{\kappa}$ ; accordingly, whether s=0 or s>0, we have  $\boxed{\bullet \ dOITd_{\tau>0}\langle 0\rangle}_{\parallel}$ . Thus, whether  $\beta=1$  or  $\beta<1$ , we have  $\boxed{\bullet \ dOITd_{\tau>0}\langle 0\rangle}_{\parallel}$ .
- $\square$  Pom 22.1.23 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathbb{A}]^{+}\}$ ) Suppose a>0. Assume  $a>\rho$ . Let  $\beta<1$  or s>0 and let  $\rho< x_{\tilde{K}}$ .
- (a) Let  $\beta = 1$  or  $\rho = 0$ .
  - 1.  $V_t = \rho \text{ for } t > 0.$

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2. Let x_{\tilde{L}} \geq \rho. Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}.
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- 3. Let  $x_{\tilde{L}} < \rho$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle$  where  $Conduct_{\tau\geq t>0}$ .
- (b) Let  $\beta < 1$  and  $\rho > 0$ .
  - 1.  $V_t$  is nondecreasing in  $t \ge 0$  and converges to a finite  $V \le x_{\tilde{K}}$  as  $t \to \infty$ .
  - 2.  $\bullet dOITd_{\tau>0}\langle 0 \rangle$
- (c) Let  $\beta < 1$  and  $\rho < 0$ .
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
  - 2.  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .  $\square$
- Proof by diagonal-symmetry Immediate from applying  $S_{\mathbb{P}\to\tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) to Nem 22.1.11(p.190) (see (19.3.10(p.134))).
- Direct proof Suppose  $a > 0 \cdots (1)$ , hence b > a > 0. Then  $\tilde{\kappa} = s \cdots (2)$  from Lemma 15.6.6(p.108) (a).
  - (a-a3) The same as Tom 22.1.17(p.193) (a-a3).
  - (b) Let  $\beta < 1$  and  $\rho > 0$ .
  - (b1) The same as Pom 22.1.17(b1).
- (b2) If s=0, then due to (1) it suffices to consider only (b2) of Tom 22.1.17(p.193) and if s>0, then  $\tilde{\kappa}>0$  from (2), hence it suffices to consider only (b2) of Tom 22.1.17(p.193). Thus, whether s=0 or s>0, we have the same result.
  - (c1) The same as Pom c1(b1).
- (c2) If s=0, then due to (1) it suffices to consider only (c2) of Tom 22.1.17(p.193) and if s>0, then  $\tilde{\kappa}>0$  from (2), hence it suffices to consider only (c2) of Tom 22.1.17(p.193). Thus, whether s=0 or s>0, we have the same result.

# 22.1.7.3.1.2.3 Case of $b^{\star} > \rho > b$

- $\square \quad \text{Pom 22.1.24 } \left( \mathscr{A} \{ \mathbb{M} : 2[\mathbb{P}][\mathbb{A}]^\top \} \right) \quad Suppose \ a > 0. \ Assume \ b^\star > \rho > b. \ Let \ \beta < 1 \ or \ s > 0.$
- (a) If  $\lambda\beta\min\{0,\rho-b\} \geq -s$ , then  $\bullet dOITd_1\langle 0\rangle_{\parallel}$ , or else  $\odot dOITs_1\langle 1\rangle_{\blacktriangle}$  where  $Conduct_{1\blacktriangle}$ . Below let  $\tau > 1$ .
- (b) Let  $V_1 \geq x_{\tilde{K}}$ .
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
  - 2. Let  $V_1 \leq x_{\tilde{L}}$ . Then, if  $\lambda \beta \max\{0, \rho b\} \leq s$ , we have  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 0 \rangle}_{\parallel}$ , or else  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\parallel}$  where  $\texttt{Conduct}_{1 \blacktriangle}$ .
  - 3. Let  $V_1 > x_{\tilde{L}}$ .
    - i. Let  $\beta = 1$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau \geq t > 1}_{\blacktriangle}$ .
    - ii. Let  $\beta < 1$ . Then  $S_5$   $\bigcirc$   $\bigcirc$   $\bigcirc$  is true.
- (c) Let  $V_1 < x_{\tilde{K}}$ .
  - 1. Let  $\beta = 1$  or  $V_1 = 0$ . Then:
    - i.  $V_t = V_1 \text{ for } t > 0.$
    - ii. If  $\lambda \min\{0, \rho b\} \ge -s$ , then  $\boxed{\bullet \text{dOITd}_{\tau > 1}\langle 0 \rangle}_{\parallel}$ , or else  $\boxed{\odot \text{ndOIT}_{\tau > 1}\langle 1 \rangle}_{\parallel}$  where Conduct<sub>1.4</sub>.
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let  $V_1 < 0$ .
      - 1.  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
      - $2. \quad \textit{If } \lambda\beta \min\{0, \rho b\} \geq -s, \ then \ \boxed{\bullet \ \text{dOITd}_{\tau > 1}\langle 0 \rangle}_{\parallel}, \ \textit{or else} \ \boxed{\odot \ \text{ndOIT}_{\tau > 1}\langle 1 \rangle}_{\parallel} \ \textit{where} \ \text{Conduct}_{1_{\blacktriangle}}.$
    - ii. Let  $V_1 > 0$ .
      - 1. Then  $V_t$  is nonincreasing in  $t \ge 0$  and converges to a finite  $V \le x_{\tilde{K}}$  as  $t \to \infty$  where  $V = x_{\tilde{K}}$  if the immediate initiation is strictly optimal for any  $\tau \gg 0$ .
      - $2. \quad \textit{If } \lambda\beta \min\{0,\rho-b\} \geq -s, \; then \; \boxed{\bullet \; \text{dOITd}_{\tau>1}\langle 0\rangle}_{\parallel}, \; or \; else \; \boxed{\odot \; \text{ndOIT}_{\tau>1}\langle 1\rangle}_{\parallel} \; where \; \text{Conduct}_{1\blacktriangle}.$
- Proof by diagonal-symmetry Immediate from applying  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) to Nem 22.1.12(p.190) (see (19.3.10(p.134))). ■
- Direct proof Suppose  $a > 0 \cdots (1)$ . Then  $\tilde{\kappa} = s \cdots (2)$  from Lemma 15.6.6(p.108) (a).
  - (a-b3i) The same as Tom 22.1.18(p.194) (a-b3i).
- (b3ii) Let  $\beta < 1$ . If s = 0, due to (1) it suffices to consider only (b3ii2) of Tom 22.1.18(p.194) and if s > 0, then  $\tilde{\kappa} > 0$  due to (2), hence it suffices to consider only (b3ii2) of Tom 22.1.18(p.194). Accordingly, whether s = 0 or s > 0, we have the same result.
  - (c) Let  $V_1 < x_{\tilde{K}}$ .
  - (c1-c1ii) The same as Tom 22.1.18(p.194) (c1-c1ii).
  - (c2) Let  $\beta < 1$  and s = 0 (s > 0).
  - (c2i,c2i1) The same as Tom 22.1.18(p.194) (c2i,c2i1).
  - (c2i2) The same as Tom 22.1.18(p.194) (23.3.2).

<sup>†</sup>See Remark 22.1.2(p.179).

(c2ii,c2ii1) The same as Tom 22.1.18(p.194) (c2ii,c2ii1).

(c2ii2) If s=0, then due to (1) it suffices to consider only (c2ii3) of Tom 22.1.18(p.194) and if s>0, then  $\tilde{\kappa}>0$  due to (2), hence t suffices to consider only (c2ii3) of Tom 22.1.18(p.194). Thus, whether s=0 or s>0, we have the same result.

#### 22.1.7.3.1.2.4 Mixed Restriction

Omitted.

### 22.1.7.3.1.2.5 Negative Restriction

Unnecessary.

### 22.1.8 Numerical Calculation

Numerical Example 5  $(\mathscr{A}\{M:2[\mathbb{R}][A]^+\}$  (selling model)

This is the example for caps = 0.05 of S<sub>4</sub> sap = 0.01 of S<sub>5</sub> sap = 0.01 of S<sub>6</sub> sap = 0.01 of S<sub>7</sub> sap = 0.01 of S<sub>7</sub> sap = 0.01 of S<sub>7</sub> sap = 0.01 of S<sub>8</sub> sap

- 1. Since  $\Delta_{\beta}V_1 = \Delta_{\beta}V_2 = \Delta_{\beta}V_3 = \Delta_{\beta}V_4 = 0$  (see  $\Delta_{\beta}V_t$ -column in the table below), we have  $V_4 = \beta V_3$ ,  $V_3 = \beta V_2$ ,  $V_2 = \beta V_1$ , and  $V_1 = \beta V_0$ , implying that it becomes indifferent to skip the search up to the deadline  $t_d = 0$  on t = 4, 3, 2, 1 (see Preference Rule 8.2.1(p.45)), i.e.,  $\bullet$  dOITd $_{\tau=4,3,2,1}\langle 0 \rangle$ . On the other hand, since  $L(V_{t-1}) < 0$  for  $1 \le t \le 4$  (see  $L(V_{t-1})$ -column in the table below), it follows that it is strictly optimal to skip the search up to the deadline 0 (see (22.1.44(p.162))) for  $1 \le t \le \tau = 4$ , i.e.,  $\bullet$  dOITd $_{\tau=4,3,2,1}\langle 0 \rangle$ . Although the above two results "indifferent" and "strictly optimal" seem to contradict each other at a glance, it is what is caused by the jumble of intuition and theory (see Alice 1(p.44)).
- 2. Each of the graphs for  $\tau = 6, 7, \dots, 15$  shows that the optimal initiating time is strictly, i.e.,  $\boxed{\$ \text{ dOITs}_{6 \le \tau \le 15} \langle \tau \rangle}_{\blacktriangle}$ , meaning that the immediate initiation is strictly optimal and that conducting the search is strictly optimal at time  $t = 6, 7, \dots, 15$  (Conduct $_{\blacktriangle}$ ) and skipping the search becomes strictly optimal at time t = 5, 4, 3, 2, 1 after that (see  $L(V_{t-1})$ -column in the table below), implying that we have  $C \hookrightarrow S_{\blacktriangle}$  (see Remark 8.2.1(p.44)) occurs.

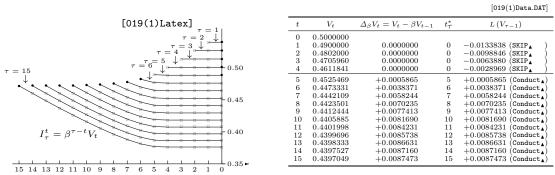


Figure 22.1.1: Graphs of  $I_{\tau}^{t} = \beta^{\tau - t} V_{t} \ (15 \ge \tau > 1, \tau \ge t > 0)$ 

# 22.1.9 Conclusion 3 (Search-Allowed-Model 2)

### C1. Mental Conflict

On  $\mathscr{F}^+$ , we have:

- a. Let  $\beta = 1$  and s = 0.
  - 1. The opt- $\mathbb{R}$ -price  $V_t$  in M:2[ $\mathbb{R}$ ][A] (selling model) is nondecreasing in  $t^{\bullet}$  as in Figure 8.4.1(p.48) (I), hence we have the normal conflict (see Remark 8.4.1(p.48)).
  - 2. The opt- $\mathbb{P}$ -price  $z_t$  in M:2[ $\mathbb{P}$ ][A] (selling model) is nondecreasing in  $t^{A^b}$  as in Figure 8.4.1(p.48) (I), hence we have the normal conflict (see Remark 8.4.1(p.48)).
  - 3. The opt- $\mathbb{R}$ -price  $V_t$  in  $\tilde{\mathsf{M}}:2[\mathbb{R}][\mathbb{A}]$  (buying model) is nonincreasing in  $t^{\mathsf{T}^c}$  as in Figure 8.4.1(p.48) (II), hence we have the normal conflict (see Remark 8.4.1(p.48)).
  - 4. The opt- $\mathbb{P}$ -price  $z_t$  in  $\tilde{\mathsf{M}}$ :2[ $\mathbb{P}$ ][A] (buying model) is nonincreasing in  $t^{\mathsf{T}^d}$  as in Figure 8.4.1(p.48) (II), hence we have the normal conflict (see Remark 8.4.1(p.48)).
    - ·  $\mathbf{A}^{\mathbf{a}} \leftarrow \text{Tom's } 22.1.1(\text{p.163}) (\mathbf{a}).$
    - ·  $^{\mathbf{b}}$   $\leftarrow$  Corollaries 22.1.3(p.176).
    - ·  $\mathbf{V}^{c} \leftarrow \text{Tom's } 22.1.1(p.171) (a).$
    - $\cdot$   $\mathbf{I}^{d}$   $\leftarrow$  Corollaries 22.1.11(p.191).
- b. Let  $\beta < 1$  or s > 0.

<sup>&</sup>lt;sup>†</sup>Note that  $a=0.01>0,~\rho=0.5>0,~\beta=0.98<1,~\text{and}~s=0.1>0.$  In addition, since  $\mu=(1.00+0.01)/2=0.505,~\text{we have}~\lambda\beta\mu=0.34643>0.1=s.$  Furthermore, we have  $x_L=0.4627674<0.5=\rho.$  Thus the condition of the assertion is satisfied.

- 1. The opt- $\mathbb{R}$ -price  $V_t$  in M:2[ $\mathbb{R}$ ][A] (selling model) is nondecreasing  $^{\mathbf{A}^{\mathbf{a}}}$ , constant  $^{\mathbb{R}^{\mathbf{a}}}$ , or nonincreasing in  $t^{\mathbf{T}^{\mathbf{a}}}$  as in Figure 8.4.2(p.48) (I), hence we have the abnormal conflict (see Remark 8.4.2(p.48)).
- 2. The opt- $\mathbb{P}$ -price  $z_t$  in M:2[ $\mathbb{P}$ ][A] (selling model) is nondecreasing  $^{\bullet}$ , constant  $^{\parallel}$  , or nonincreasing in  $t^{\bullet}$  as in Figure 8.4.2(p.48) (I), hence we have the abnormal conflict (see Remark 8.4.2(p.48)).
- 3. The opt- $\mathbb{R}$ -price  $V_t$  in  $\tilde{\mathbb{M}}:2[\mathbb{R}][A]$  (buying model) is nondecreasing  $^{\bullet^c}$ , constant  $^{\parallel^c}$ , or nonincreasing in  $t^{\P^c}$  as in Figure 8.4.2(p.48) (II), hence we have the abnormal conflict (see Remark 8.4.2(p.48)).
- 4. The opt- $\mathbb{P}$ -price  $z_t$  in  $\tilde{\mathsf{M}}$ :2[ $\mathbb{P}$ ][A] (buying model) is nondecreasing  $^{\bullet}$ , constant  $\mathbb{P}^d$ , or nonincreasing in  $t^{\bullet}$  as in Figure 8.4.2(p.48) (II), hence we have the abnormal conflict (see Remark 8.4.2(p.48)).

```
 \begin{array}{lll} \cdot & \stackrel{\mathbf{i}^{a}}{\leftarrow} & \leftarrow 22.1.2(\text{p.163}) \, (a), \ 22.1.3(\text{p.166}) \, (a), \ 22.1.4(\text{p.166}) \, (c1). \\ & \parallel^{a} & \leftarrow \text{Tom } 22.1.4(\text{p.166}) \, (a1)). \\ & \stackrel{\mathbf{r}^{a}}{\leftarrow} & \leftarrow \text{Tom } 22.1.4(\text{p.166}) \, (b1). \\ & \stackrel{\mathbf{i}^{b}}{\leftarrow} & \leftarrow 22.1.4(\text{p.177}), \ 22.1.5(\text{p.177}), \ 22.1.6(\text{p.177}) \, (c), \\ & & 22.1.7(\text{p.178}), \ 22.1.8(\text{p.178}), \ 22.1.9(\text{p.178}) \, (c), \ 22.1.10(\text{p.184}) \, (a,b2ii). \\ & \parallel^{b} & \leftarrow \text{Corollary } 22.1.6(\text{p.177}) \, (a), \ 22.1.9(\text{p.178}) \, (a), \ 22.1.10(\text{p.184}) \, (b1). \\ & \stackrel{\mathbf{t}^{b}}{\leftarrow} & \leftarrow \text{Corollaries } 22.1.6(\text{p.177}) \, (b), \ 22.1.9(\text{p.178}) \, (b), \ 22.1.10(\text{p.184}) \, (b2i). \\ & \stackrel{\mathbf{t}^{c}}{\leftarrow} & \leftarrow \text{Tom } 22.1.4(\text{p.172}) \, (b1). \\ & \parallel^{c} & \leftarrow \text{Tom } 22.1.4(\text{p.172}) \, (a1). \\ & \stackrel{\mathbf{t}^{c}}{\leftarrow} & \leftarrow 22.1.2(\text{p.171}) \, (a), \ 22.1.3(\text{p.172}) \, (a), \ 22.1.4(\text{p.172}) \, (c1). \\ & \stackrel{\mathbf{d}^{d}}{\leftarrow} & \leftarrow \text{Corollaries } 22.1.14(\text{p.192}) \, (b), \ 22.1.17(\text{p.193}) \, (b), \ 22.1.18(\text{p.194}) \, (b2i). \\ & \parallel^{d} & \leftarrow \text{Corollaries } 22.1.17(\text{p.193}) \, (a), \ 22.1.18(\text{p.194}) \, (b1). \\ & \stackrel{\mathbf{t}^{d}}{\leftarrow} & \leftarrow 22.1.2(\text{p.172}), \ 22.1.13(\text{p.192}), \ 22.1.14(\text{p.192}) \, (c), \\ & 22.1.15(\text{p.193}), \ 22.1.16(\text{p.193}), \ 22.1.17(\text{p.193}) \, (c), \ 22.1.18(\text{p.194}) \, (a), \text{b2ii}). \\ & \end{array}
```

The above results can be summarized as below.

- A. If  $\beta=1$  and s=0, then, on  $\mathscr{F}^+$ , whether selling problem or buying problem and whether  $\mathbb{R}$ -mechanism-model or  $\mathbb{P}$ -mechanism-model, we have the normal mental conflict, which coincides with *expectations* in *Examples* 1.3.1(p.5) 1.3.4(p.6).
- B. If  $\beta < 1$  or s > 0, then, on  $\mathscr{F}^+$ , whether selling problem or buying problem and whether  $\mathbb{R}$ -mechanism-model or  $\mathbb{P}$ -mechanism-model, we have the abnormal mental conflict, which does not coinside with *expectations* in *Examples* 1.3.1(p.5) 1.3.4(p.6).

# C2. Symmetry

On  $\mathscr{F}^+$ , we have:

a. Let  $\beta = 1$  and s = 0. Then we have:

Pom 22.1.5(p.173) 
$$\sim$$
 Pom 22.1.1(p.168)  $(\mathscr{A}\{\tilde{M}:2[\mathbb{R}][A]\}^+ \sim \mathscr{A}\{M:2[\mathbb{R}][A]\}^+),$   
Pom 22.1.17(p.195)  $\sim$  Pom 22.1.9(p.184)  $(\mathscr{A}\{\tilde{M}:2[\mathbb{P}][A]\}^+ \sim \mathscr{A}\{M:2[\mathbb{P}][A]\}^+).$ 

b. Let  $\beta < 1$  or s > 0. Then we have

The above results can be summarized as below.

- A. Let  $\beta = 1$  and s = 0. Then the symmetry is inherited.
- B. Let  $\beta < 1$  or s > 0. Then the symmetry collapses.

# C3. Analogy

On  $\mathscr{F}^+$ , for any  $\beta \leq 1$  and  $s \geq 0$  we have:

a. We have:

The above results can be summarized as below.

A. The analogy collapses.

# C4. Optimal initiating time (OIT)

a. Let  $\beta = 1$  and s = 0. Then, from

Table 22.1.1: Possible OIT ( $\beta = 1$  and s = 0)

		$\mathscr{A}\{M{:}2[\mathbb{R}][\mathtt{A}]^+\}$	$\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}][\mathtt{A}]^+\}$	$\mathscr{A}\{M{:}2[\mathbb{P}][\mathtt{A}]^+\}$	$\mathscr{A}\{\tilde{M}{:}2[\mathbb{P}][\mathtt{A}]^+\}$
$\odot$ dOITs $_{ au}\langle  au  angle$	$\odot_{\parallel}$				
$\  \   \  \   \  \   \  \   \  \   \  \ $	${f S}_{\Delta}$				
$\$ dOITs $_{ au}\langle  au  angle$	S <sub>▲</sub>	0	0	0	0
$\odot$ nd0IT $_{ au}\langle t_{ au}^{ullet} angle$ $_{\parallel}$	<b>O</b>				
$\odot$ ndOIT $_{ au}\langle t_{ au}^{ullet} angle$ $_{ riangle}$	$\odot_{\Delta}$				
$\odot$ ndOIT $_{ au}\langle t_{ au}^{ullet} angle$ $_{ullet}$	⊚▲				
$\bullet$ d0ITd $_{ au}\langle 0 \rangle$	<b>1</b>	0	0	0	0
$\bullet$ dOITd $_{\tau}\langle 0 \rangle$	₫△				
$\bullet$ dOITd $_{\tau}\langle 0 \rangle$	<b>①</b> ^				

From the above table, we see that:

- A. Only  $\textcircled{s}_{\blacktriangle}$  and  $\textcircled{d}_{\parallel}$  are possible on  $\mathscr{F}^{+}$ .
- b. Let  $\beta < 1$  or s > 0. Then, from

Pom 22.1.2(p.168), Pom 22.1.3(p.169), Pom 22.1.4(p.169), Pom 22.1.5(p.173), Pom 22.1.6(p.173), Pom 22.1.7(p.173), Pom 22.1.8(p.173), Pom 22.1.10(p.185), Pom 22.1.11(p.185), Pom 22.1.12(p.185),  ${\tt Pom}\ 22.1.13 \hbox{(p.186)}\ ,$ Pom 22.1.14(p.186),  ${\tt Pom}\ 22.1.15 ({\tt p.186})\ ,$  ${\tt Pom}\ 22.1.16 \hbox{(p.187)}\ ,$ Pom 22.1.19(p.195),  ${\tt Pom}\ 22.1.20 ({\tt p.196})\ ,$  ${\tt Pom}\ 22.1.21 (p.196)\ ,$  ${\tt Pom}\ 22.1.22 (p.196)\ ,$  ${\tt Pom}\ 22.1.23 ({\tt p.196})\ ,$  ${\tt Pom}\ 22.1.24 {\scriptsize (p.197)}\,,$ 

we have the following table:

Table 22.1.2: Possible OIT  $(\beta < \text{or } s > 0)$ 

		$\mathscr{A}\{M{:}2[\mathbb{R}][\mathtt{A}]^+\}$	$\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}]{[\mathtt{A}]}^+\}$	$\mathscr{A}\{M{:}2[\mathbb{P}][\mathtt{A}]^+\}$	$\mathscr{A}\{\tilde{M}{:}2[\mathbb{P}][\mathtt{A}]^+\}$
$\odot$ dOITs $_{ au}\langle  au  angle$	$\odot_{\parallel}$				
$\otimes$ d0ITs $_{ au}\langle  au  angle$	${f S}_{\Delta}$				
$\otimes$ d0ITs $_{ au}\langle  au  angle$	S <sub>▲</sub>	0	0	0	0
$\odot$ nd0IT $_{ au}\langle t_{ au}^{ullet} angle$ $_{\parallel}$	<b>O</b>	0	0	0	0
$\odot$ ndOIT $_{ au}\langle t_{ au}^{ullet} angle$ $_{ riangle}$	$\odot_{\Delta}$				
$\odot$ ndOIT $_{ au}\langle t_{ au}^{ullet} angle$ $_{ullet}$	⊚▲				
$ullet$ d0ITd $_{ au}\langle 0  angle$	<b>①</b>	0	0	0	0
$ullet$ d0ITd $_{ au}\langle 0 \rangle$	₫△				
$\bullet$ d0ITd $_{ au}\langle 0 \rangle$	<b>①</b> ^				

From the above table, we see that:

A. Only  $\S$ ,  $\mathbf{d}_{\parallel}$ , and  $\bigcirc_{\parallel}$  is possible.

The table below is the list of the occurrence percents \$,  $\bigcirc$ , and  $\bigcirc$  on  $\mathscr{F}$  (See  $\blacksquare$  Tom 22.1.1(p.163), Tom 22.1.2(p.163), Tom 22.1.3(p.166), Tom 22.1.4(p.166), and Tom 22.1.5(p.179).

Table 22.1.3: Occurrence percents of s, o, and d on  $\mathscr{F}^+$ 

	<u>s</u>		<ul><li>@</li></ul>					
47.5%/29			21.3 % / 13			31.2 % / 19		
SII	Sa	S <sub>▲</sub>	<b>O</b>	<ul><li>Θ<sub>Δ</sub></li></ul>	<b>O</b> _	<b>1</b>	۵	Q٧
_	×	possible	possible	×	×	possible	×	×
-%/-	0.0%/0	47.5 % / 29	21.3 % / 13	0.0%/0	0.0 %/0	31.2 %/ 19	0.0 %/0	0.0 %/0

#### C5. Null-time-zone and deadline-engulfing

From Table 22.1.3(p.201) above we see that on  $\mathscr{F}$ :

- a. See Remark 8.2.2(p.45) for the noteworthy implication of the symbol (strict optimality).
- b. As a whole we have (S), (O), and (d) at 47.5%, 21.3%, and 31.2% respectively where
  - 1. (s) cannot be defined due to Remark 8.2.3(p.45).
  - 2.  $\bigcirc_{\parallel}$  is possible (21.3%).
  - 3.  $\mathbf{d}_{\parallel}$  is possible (31.2%).
  - 4.  $\bigcirc$  never occur (0.0%).
  - 5.  $\bigcirc_{\triangle}$  never occur (0.0%).
  - 6.  $\mathbf{d}_{\Delta}$  never occur (0.0%).
  - 7. (s) **△** is possible (47.5 %).
  - 8.  $\bigcirc$  a never occurs (0.0%).
  - 9.  $\bullet$  never occurs (0.0%).

From the above results we see that:

- A.  $\odot$  and  $\odot$  causing the null-time-zone are possible at 52.5% (= 21.3% + 31.2%).
- B.  $\bigcirc_{\blacktriangle}$  strictly causing the null-time-zone is impossible (0.0%).
- C. **1** Strictly causing the null-time-zone is impossible (0.0%), i.e., the deadline-engulfing is impossible.

# C6. Diagonal Symmetry

Exercise 22.1.1 Confirm by yourself that the following relations hold in fact.

Pom $22.1.5$ (p.173)	d- $\sim$ Nem $22.1.1$ (p.170)	$(\mathbb{R}\text{-mechanism}),$
${\tt Pom}\ 22.1.6 {\scriptsize (p.173)}$	d- $\sim$ Nem $22.1.2$ (p.170)	$(\mathbb{R}\text{-mechanism}),$
${\tt Pom}\ 22.1.7 {\scriptsize (p.173)}$	d- $\sim$ Nem $22.1.3$ (p.171)	$(\mathbb{R}\text{-mechanism}),$
${\tt Pom}\ 22.1.8 {\scriptsize (p.173)}$	d- $\sim$ Nem $22.1.4$ (p.171)	$(\mathbb{R}\text{-mechanism}).$
${\tt Pom}\ 22.1.17 {\scriptsize (p.195)}$	$\texttt{d-} \sim \texttt{Nem} \ 22.1.5 \texttt{(p.188)}$	$(\mathbb{P}\text{-mechanism}),$
${\tt Pom}\ 22.1.18 {\scriptsize (p.195)}$	d- $\sim$ Nem $22.1.6$ (p.188)	$(\mathbb{P}\text{-mechanism}),$
${\tt Pom}\ 22.1.19 {\scriptsize (p.195)}$	$\texttt{d-} {\color{red} \sim} \texttt{Nem} \ 22.1.7 (\texttt{p.189})$	$(\mathbb{P}\text{-mechanism}),$
${\tt Pom}\ 22.1.20 (p.196)$	$\texttt{d-} \sim \texttt{Nem} \ 22.1.8 \texttt{(p.189)}$	$(\mathbb{P}\text{-mechanism}),$
${\tt Pom}\ 22.1.21 {\rm (p.196)}$	$\texttt{d-} \sim \texttt{Nem} \ 22.1.9 (\texttt{p.189})$	$(\mathbb{P}\text{-mechanism}),$
${\tt Pom}\ 22.1.22 {\rm (p.196)}$	$\texttt{d-} \sim \texttt{Nem} \ 22.1.10 (\texttt{p.190})$	$(\mathbb{P}\text{-mechanism}),$
${\tt Pom}\ 22.1.23 {\rm (p.196)}$	$\texttt{d-} \sim \texttt{Nem} \ 22.1.11(\texttt{p.190})$	$(\mathbb{P}\text{-mechanism}),$
${\tt Pom}\ 22.1.24 {\scriptsize (p.197)}$	$\texttt{d-} {\sim} \texttt{Nem} \ 22.1.12 (\texttt{p.190})$	( $\mathbb{P}$ -mechanism). $\square$

# C7. $C \rightarrow S$ On $\mathscr{F}^+$ , we have (see (A5b(p.12))):

 $\text{Let } \beta < 1 \text{ or } s > 0. \text{ Then from Pom's } 22.1.4 \text{(p.169)} \,, \, 22.1.12 \text{(p.185)} \,, \, 22.1.15 \text{(p.186)} \,, \, \text{and } 22.1.16 \text{(p.187)} \text{ we have the following table:} \\ \text{Pom's } 22.1.4 \text{(p.169)} \,, \, 22.1.12 \text{(p.185)} \,, \, 22.1.12 \text{(p.186)} \,, \, 22.1.12 \text{(p.187)} \\ \text{Pom's } 22.1.12 \text{(p.187)} \,, \, 22.1.12 \text{(p.187)} \,,$ 

Table 22.1.4: $C \rightarrow S \ (\beta < 1 \text{ or } s > 0)$						
	$\mathscr{A}\{M{:}2[\mathbb{R}][\mathtt{A}]^+\}$	$\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}]{[\mathtt{A}]}^+\}$	$\mathscr{A}\{M{:}2[\mathbb{P}][\mathtt{A}]^+\}$	$\mathscr{A}\{\tilde{M}{:}2[\mathbb{P}]{[\mathtt{A}]}^+\}$		
(a) C→S <sub>△</sub>	0		0			
(b) C~→S <sub>▲</sub>	0		0			

- a.  $C \sim S_{\Delta}$  occurs only for  $M:2[\mathbb{R}][A]^+$  and  $M:2[\mathbb{P}][A]^+$  (both are a selling model).
- b.  $C \rightarrow S_{\blacktriangle}$  occurs only for  $M:2[\mathbb{R}][\mathbb{A}]^+$  and  $M:2[\mathbb{P}][\mathbb{A}]^+$  (both are a selling model).
  - Tom 22.1.4(p.166) (b3iii),
  - Tom 22.1.5(p.179) (c2i2i),
  - Tom 22.1.5(p.179) (c2i2ii).

# $\mathbf{22.2} \quad \mathbf{Search\text{-}Enforced\text{-}Model} \ \ \mathbf{2:} \ \ \mathcal{Q}\{\mathsf{M}\text{:}2[\mathtt{E}]\} = \{\mathsf{M}\text{:}2[\mathtt{R}][\mathtt{E}], \tilde{\mathsf{M}}\text{:}2[\mathtt{R}][\mathtt{E}], \tilde{\mathsf{M}}\text{:}2[\mathtt{P}][\mathtt{E}], \tilde{\mathsf{M}}\text{:}2[\mathtt{P}][\mathtt{E}]\}$

### 22.2.1 Theorems

As ones corresponding to Theorems 21.2.1(p.142), 21.2.2(p.142), and 21.2.3(p.142), let us consider here the following three theorems:

Theorem 22.2.1 (symmetry[
$$\mathbb{R} \to \mathbb{R}$$
])) Let  $\mathscr{A}\{M:2[\mathbb{R}][E]\}\ holds\ on\ \mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}\{\tilde{M}:2[\mathbb{R}][E]\}\ holds\ on\ \mathscr{P} \times \mathscr{F}\ where$ 

$$\mathscr{A}\{\tilde{M}:2[\mathbb{R}][E]\} = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathscr{A}\{M:2[\mathbb{R}][E]\}]. \quad \Box \qquad (22.2.1)$$

Theorem 22.2.2 (analogy[
$$\mathbb{R} \to \mathbb{P}$$
]) Let  $\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$ . Then  $\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}\ where$ 

$$\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]\} = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}]. \quad \Box \qquad (22.2.2)$$

Theorem 22.2.3 (symmetry 
$$[\mathbb{P} \to \mathbb{P}]$$
) Let  $\mathscr{A}\{M:2[\mathbb{P}][E]\}$  holds on  $\mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}\{\tilde{M}:2[\mathbb{P}][E]\}$  holds on  $\mathscr{P} \times \mathscr{F}$  where  $\mathscr{A}\{\tilde{M}:2[\mathbb{P}][E]\}=\mathcal{S}_{\mathbb{P}_{\to}\mathbb{P}}[\mathscr{A}\{M:2[\mathbb{P}][E]\}]$ .  $\square$  (22.2.3)

In order for the above three theorems to hold, the following three relations must be satisfied:

$$SOE\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[SOE\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}], \tag{22.2.4}$$

$$SOE\{M:2[\mathbb{P}][E]\} = \mathcal{A}_{\mathbb{R} \to \mathbb{P}}[SOE\{M:2[\mathbb{R}][E]\}], \tag{22.2.5}$$

$$SOE\{\tilde{M}:2[\mathbb{P}|[E]\} = S_{\mathbb{P}\to\tilde{\mathbb{P}}}[SOE\{M:2[\mathbb{P}|[E]\}], \tag{22.2.6}$$

corresponding to (21.2.4(p.142)), (21.2.5(p.142)), and (21.2.6(p.142)). Then, for the same reason as in Chap. 16(p.111) it can be shown that the equality

$$SOE\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{A}]\} = \mathcal{A}_{\tilde{\mathbb{P}} \to \tilde{\mathbb{P}}}[SOE\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{A}]\}] \tag{22.2.7}$$

holds (corresponding to (21.2.7(p.142))) and that we have the following theorem, corresponding to Theorem 21.2.4(p.142).

Theorem 22.2.4 (analogy 
$$[\tilde{\mathbb{R}} \to \tilde{\mathbb{P}}]$$
) Let  $\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{R}][E]\}\ holds\ on\ \mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{P}][E]\}\ holds\ on\ \mathscr{P} \times \mathscr{F}$  where  $\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{P}][E]\}=\mathscr{A}_{\tilde{\mathbb{R}}\to\tilde{\mathbb{P}}}[\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{R}][E]\}]$ .  $\square$  (22.2.8)

In fact, from the comparison of (I) and (II) and of (III) and (IV) in Table 7.4.4(p.41) it can be easily shown that (22.2.4(p.202)) and (22.2.6(p.202)) hold; however, from the comparison of (I) and (III) in Table 7.4.4(p.41) we can immediately see that (22.2.5(p.202)) does not always hold.

### 22.2.2 A Lemma

The following lemma provides the conditions on which whether each of Theorems 22.2.1(p.202), 22.2.2(p.202), and 22.2.3(p.202) holds or not.

### Lemma 22.2.1

- (a) Theorem 22.2.1(p.202) always hold.
- (b) Theorem 22.2.3(p.202) always hold.
- (c) Let  $\rho \leq a^*$  or  $b \leq \rho$ . Then Theorem 22.2.2(p.202) holds.
- (d) Let  $a^{\star} < \rho < b$ . Then Theorem 22.2.2(p.202) does not always hold.  $\square$
- ullet Proof (a,b) From the comparisons of (I) and (II) in Table 7.4.4(p.41) and that of (III) and (IV) in Table 7.4.4(p.41) we see that (22.2.4(p.202)) and (22.2.6(p.202)) hold, hence Theorems 22.2.1(p.202) and 22.2.3 hold.
- (c,d) From the comparison of (I) and (III) in Table 7.4.4(p.41) we see that (22.2.5(p.202)) does not always hold, hence it follows that Theorem 22.2.2(p.202) does not always hold. The proofs for the two assertions (c,d) are the same as those of Lemma 22.1.1(p.159) (c,d).

### 22.2.3 Diagonal Symmetry

For quite the same reason as in Model 1 (see Chap. 19(p.129)) one sees that the diagonal symmetry holds also for Model 2.

 $\blacksquare$  Model with  $\mathbb{R}$ -mechanism Then we have:

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^{-} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]^{+}\}],\tag{22.2.9}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^{\pm} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]^{\pm}\}],\tag{22.2.10}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^{+} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]^{-}\}],\tag{22.2.11}$$

$$\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathbb{R}]\}^{+} = \mathcal{S}_{\tilde{\mathbb{P}}_{\rightarrow\mathbb{R}}}[\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathbb{A}]^{-}\}],\tag{22.2.12}$$

$$\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathtt{R}]\}^{\pm} = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathtt{A}]^{\pm}\}],\tag{22.2.13}$$

$$\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{R}]\}^{-} = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{A}]^{+}\}]. \tag{22.2.14}$$

Hence we have the following corollary.

Corollary 22.2.1 We have:

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^+ \text{ d-} \sim \mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]^-\} \quad (\text{see } (22.1.21(\text{p.162})) \text{ and } (22.1.24(\text{p.162}))), \tag{22.2.15}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^{\pm} \quad \sim \mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]^{\pm}\} \quad (\text{see } (22.1.22(\text{p.162})) \text{ and } (22.1.25(\text{p.162}))), \tag{22.2.16}$$

 $\blacksquare$  Model with  $\mathbb{P}$ -mechanism. In this model we have;

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]\}^{-} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]^{+}\}],\tag{22.2.18}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]\}^{\pm} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]^{\pm}\}],\tag{22.2.19}$$

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]\}^{+} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]^{-}\}], \tag{22.2.20}$$

$$\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]\}^+ = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]^-\}], \tag{22.2.21}$$

$$\mathscr{A}\{\mathsf{M}{:}2[\mathbb{P}][\mathsf{E}]\}^{\pm} = \mathcal{S}_{\tilde{\mathbb{R}} \to \mathbb{R}}[\mathscr{A}\{\tilde{\mathsf{M}}{:}2[\mathbb{P}][\mathsf{E}]^{\pm}\}], \tag{22.2.22}$$

$$\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]\}^{-} = \mathcal{S}_{\tilde{\mathbb{P}} \to \mathbb{P}}[\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]^{+}\}]. \tag{22.2.23}$$

Hence we have the following corollary.

#### Corollary 22.2.2 We have:

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]\}^+ \text{ d-} \sim \mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]^-\} \text{ (see } (22.1.21(\texttt{p.162})) \text{ and } (22.1.24(\texttt{p.162}))),$$
 (22.2.24)

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]\}^{\pm} \sim \mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]^{\pm}\} \quad (\text{see } (22.1.22(\text{p.162})) \text{ and } (22.1.25(\text{p.162}))),$$
 (22.2.25)

$$\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]\}^- \ \mathsf{d}-\mathcal{N}\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]^+\} \ (\text{see } (22.1.23(\text{p.162})) \ \text{and} \ (22.1.26(\text{p.162}))). \ \Box \ (22.2.26)$$

# **22.2.4** M:2[ $\mathbb{R}$ ][ $\mathbb{E}$ ]

#### 22.2.4.1 Preliminary

From (7.4.28(p.41)) and (6.1.8(p.25)) we have

$$V_t - \beta V_{t-1} = K(V_{t-1}) + (1 - \beta)V_{t-1} = L(V_{t-1}), \quad t > 0.$$
(22.2.27)

# 22.2.4.2 Analysis

# **22.2.4.2.1** Case of $\beta = 1$ and s = 0

■ Tom 22.2.1 ( $\mathscr{A}$ {M:2[ $\mathbb{R}$ ][ $\mathbb{E}$ ]}) Let  $\beta = 1$  and s = 0.

- (a)  $V_t$  is nondecreasing in t > 0.
- (b) Let  $\rho \geq b$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\parallel}$ .
- (c) Let  $\rho < b$ . Then  $\boxed{\$ dOITs_{\tau > 0} \langle \tau \rangle}$ .
- Proof Let  $\beta = 1$  and s = 0. Then, since  $K(x) = \lambda T(x) \cdots (1)$  from (6.1.4(p.25)), we have  $K(x) \geq 0 \cdots (2)$  for any x due to Lemma 11.1.1(p.55) (g).
  - (a) From (7.4.28(p.41)) and (2) we obtain  $V_t \geq V_{t-1}$  for t > 0, i.e.,  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\rho \geq b$ . Then, since  $b \leq V_0$  from (7.4.27(p.41)), we have  $b \leq V_{t-1}$  for t > 0 from (a), hence  $L(V_{t-1}) = 0$  for t > 0 from Lemma 11.2.1(p.57) (d), thus  $V_t = \beta V_{t-1}$  for t > 0 from (22.2.27(p.203)). Then, since  $V_t = \beta V_{t-1}$  for  $\tau \geq t > 0$ , we have  $V_\tau = \beta V_{\tau-1} = \beta^2 V_{\tau-2} = \cdots = \beta^\tau V_0$ , hence  $t_\tau^* = 0$  for  $\tau > 0$ , i.e.,  $\bullet$  doITd $_{\tau>0}\langle 0 \rangle_{\parallel}$  (see Preference Rule 8.2.1(p.45)).
- (c) Let  $\rho < b$ . Then  $V_0 < b \cdots$  (3) from (7.4.27(p.41)). Let  $V_{t-1} < b$ . Then, since  $V_t < K(b) + b$  from (7.4.28(p.41)) and Lemma 11.2.2(p.57) (h), we have  $V_t < \beta b s = b$  from  $(11.2.7\,(2)\,(p.57))$  and the assumptions " $\beta = 1$  and s = 0". Hence, by induction  $V_{t-1} < b$  for t > 0, so  $L(V_{t-1}) > 0$  for t > 0 from Lemma 11.2.1(p.57) (d). Accordingly,  $V_t \beta V_{t-1} > 0$  for t > 0 from (22.2.27(p.203)) or equivalently  $V_t > \beta V_{t-1}$  for t > 0. Then, since  $V_t > \beta V_{t-1}$  for  $\tau \ge t > 0$ , we have  $V_\tau > \beta V_{\tau-1} > \beta^2 V_{\tau-2} > \cdots > \beta^\tau V_0$ , hence  $t_\tau^* = \tau$  for  $\tau > 0$ , i.e., [\$] dOITs $_{\tau>0}(\tau)$ .

# 22.2.4.2.2 Case of $\beta < 1$ or s > 0

Let us define

Remark 22.2.1  $S_8$  is the same as  $S_2$ (p.143) except that the inequalities of  $\tau > 1$ ,  $t^{\bullet}_{\tau} > 1$ , and  $t^{\bullet}_{\tau} \geq \tau > 1$  in  $S_2$  changes into  $\tau > 0$ , t > 0, and  $t^{\bullet}_{\tau} \geq \tau > 0$  respectively in  $S_8$ .  $\square$ 

- $\blacksquare \ \, \text{Tom} \ \, \textbf{22.2.2} \, \left( \mathscr{A} \{ \mathsf{M}{:}2[\mathbb{R}][\mathsf{E}] \} \right) \quad Let \, \beta < 1 \, \ or \, s > 0 \, \ and \, \, let \, \rho < \, x_{\scriptscriptstyle K} \, .$
- (a)  $V_t$  is nondecreasing in  $t \ge 0$ , is strictly increasing in  $t \ge 0$  if  $\lambda < 1$  or  $a < \rho$ , and converges to a finite  $V = x_K$  as  $t \to \infty$ .
- (b) Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}$ .
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}_{\blacktriangle}$ . Below let  $\tau > 1$ .
  - 2. Let  $\beta = 1$ .
    - i. Let  $a < \rho$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$ .
    - ii. Let  $\rho \leq a$ .
      - 1. Let  $(\lambda \mu s)/\lambda \le a$ .
        - i. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT $_{\tau > 1}\langle 1 \rangle$
        - ii. Let  $\lambda < 1$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$ .
      - 2. Let  $(\lambda \mu s)/\lambda > a$ . Then S dOITs  $_{\tau > 1}\langle \tau \rangle$
  - 3. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let  $a < \rho$ .
      - 1. Let  $b \geq 0$  ( $\kappa \geq 0$ ). Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$ .
      - 2. Let b < 0 ( $\kappa < 0$ ). Then  $S_8$   $\bullet$   $\bullet$   $\bullet$  is true.  $\mapsto$
    - ii. Let  $\rho \leq a$ .
      - 1. Let  $(\lambda \beta \mu s)/\delta \leq a$ .
        - i. Let  $\lambda = 1$ .
          - 1. Let b>0 ( $\kappa>0$ ). Then  $\boxed{\$ dOITs_{\tau>1}\langle \tau\rangle}$
          - 2. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $\bigcirc$  ndOIT $_{\tau>1}\langle 1 \rangle$   $_{\triangle}$ .
        - ii. Let  $\lambda < 1$ 
          - 1. Let  $b \geq 0$  ( $\kappa \geq 0$ ). Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$ .
          - 2. Let b < 0 ( $\kappa < 0$ ). Then  $S_8$   $\bullet$   $\bullet$   $\bullet$  is true.  $\rightarrow$

 $\rightarrow \odot_{\blacktriangle}$ 

- 2. Let  $(\lambda \beta \mu s)/\delta > a$ .
  - i. Let  $b \geq 0$  ( $\kappa \geq 0$ ). Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$
- ii. Let b < 0 ( $\kappa < 0$ ). Then  $S_8$   $\bullet$   $\bullet$   $\bullet$  is true.  $\Box \mapsto$   $\bullet \bullet$
- Proof Let  $\beta < 1$  or s > 0 and let  $\rho < x_K \cdots$  (1). Then  $V_0 < x_K \cdots$  (2) from (7.4.27(p.41)) and  $K(\rho) > 0$  due to Lemma 11.2.2(p.57) (j1). Since  $V_1 = K(\rho) + \rho \cdots$  (3) from (7.4.28(p.41)) with t = 1, we have  $V_1 V_0 = V_1 \rho = K(\rho) > 0$ , hence  $V_1 > V_0 \cdots$  (4).
- (a) Note (4), hence  $V_0 \leq V_1$ . Suppose  $V_{t-1} \leq V_t$ . Then, due to Lemma 11.2.2(p.57) (e) we have  $V_t \leq K(V_t) + V_t = V_{t+1}$  from (7.4.28(p.41)). Hence, by induction  $V_t \geq V_{t-1}$  for t > 0, i.e.,  $V_t$  is nondecreasing in  $t \geq 0$ . Note again (4). Suppose  $V_{t-1} < V_t$ . If  $\lambda < 1$ , from Lemma 11.2.2(p.57) (f) we have  $V_t < K(V_t) + V_t = V_{t+1}$ . If  $a < \rho$ , then  $a < V_0$  from (7.4.27(p.41)), hence  $a < V_{t-1}$  for t > 0 due to the nondecreasing of  $V_t$ , so from Lemma 11.2.2(p.57) (g) we have  $V_t < K(V_t) + V_t = V_{t+1}$ . Therefore, whether  $\lambda < 1$  or  $a < \rho$ , by induction we have  $V_{t-1} < V_t$  for t > 0, i.e.,  $V_t$  is strictly increasing in  $t \geq 0$ . Consider a sufficiently large M > 0 with  $\rho \leq M$  and  $b \leq M$ , hence from (7.4.27(p.41)) we have  $V_0 \leq M$ . Suppose  $V_{t-1} \leq M$ . Then, from Lemma 11.2.2(p.57) (e) we have  $V_t \leq K(M) + M = \beta M s$  due to (11.2.7(2)(p.57)), hence  $V_t \leq M$  due to the assumptions " $\beta \leq 1$  and  $s \geq 0$ ". Accordingly, by induction  $V_t \leq M$  for  $t \geq 0$ , i.e.,  $V_t$  is upper bounded in t. Hence  $V_t$  converges to a finite V as  $t \to \infty$ . Thus V = K(V) + V from (7.4.28(p.41)), hence K(V) = 0, so  $V = x_K$  due to Lemma 11.2.2(p.57) (j1).
- (b) Let  $x_L \leq \rho$ . Then, since  $x_L \leq V_0$  from (7.4.27(p.4l)), we have  $x_L \leq V_{t-1}$  for t > 0 due to (a), hence  $L(V_{t-1}) \leq 0$  for t > 0 due to Corollary 11.2.1(p.57) (a), thus  $V_t \beta V_{t-1} \leq 0$  for t > 0 from (22.2.27(p.203)) or equivalently  $V_t \leq \beta V_{t-1}$  for t > 0. Accordingly, since  $V_t \leq \beta V_{t-1}$  for  $\tau \geq t > 0$ , we have  $V_\tau \leq \beta V_{\tau-1} \leq \beta^2 V_{\tau-2} \leq \cdots \leq |\beta^\tau V_0|$ , hence  $t_\tau^* = 0$  for  $\tau > 0$ , i.e.,  $|\bullet| \text{dOITd}_{\tau>0}(0)|_{\Delta}$ .
- (c) Let  $\rho < x_L \cdots$  (5). Then  $V_0 < x_L \cdots$  (6) from (7.4.27(p.41)), hence  $L(V_0) > 0 \cdots$  (7) due to Corollary 11.2.1(p.57) (a).
- (c1) Since  $V_1 \beta V_0 = L(V_0) > 0$  from (22.2.27(p.203)) with t = 1 and (7), we have  $V_1 > \beta V_0$ , hence  $t_1^* = 1$ , i.e.,  $\boxed{\$ \text{ dOITs}_1\langle 1 \rangle}_{\blacktriangle} \cdots (8)$ . Below let  $\tau > 1 \cdots (9)$ .
- (c2) Let  $\beta = 1$ , hence s > 0 due to the assumption " $\beta < 1$  or s > 0". Then  $\delta = \lambda$  from (11.2.1(p.56)) and  $x_L = x_K \cdots$  (10) from Lemma 11.2.3(p.58) (b), hence  $K(x_L) = K(x_K) = 0 \cdots$  (11).
- (c2i) Let  $a < \rho$ . Then  $a < V_0$  from (7.4.27(p.41)), hence  $a < V_{t-1}$  for t > 0 due to (a). Note (2). Suppose  $V_{t-1} < x_K$ . Then, from (7.4.28(p.41)) and Lemma 11.2.2(p.57) (g) we have  $V_t < K(x_K) + x_K = x_K$ . Hence, by induction  $V_{t-1} < x_K$  for t > 0. Then, since  $V_{t-1} < x_L$  for t > 0 due to (10), we have  $L(V_{t-1}) > 0$  for t > 0 from Lemma 11.2.1(p.57) (e1), hence for the same reason as in the proof of Tom 22.2.1(p.23) (c) we have  $\boxed{\$}$  dOITs<sub> $\tau > 1$ </sub> $\langle \tau \rangle$ .
  - (c2ii) Let  $\rho \leq a$ , hence  $V_0 \leq a \cdots$  (12) from (7.4.27(p.41)). Then, from (3) and (11.2.7 (1) (p.57)) we have  $V_1 = \lambda \mu s + (1 \lambda)\rho$ .
- (c2ii1) Let  $(\lambda \mu s)/\lambda \le a$ . Then  $x_K = (\lambda \mu s)/\lambda \le a \cdots$  (13) from Lemma 11.2.2(p.57) (j2). Hence  $K(a) \le 0$  from Lemma 11.2.2(p.57) (j1). Note (12). Suppose  $V_{t-1} \le a$ . Then, from (7.4.28(p.41)) and Lemma 11.2.2(p.57) (e) we have  $V_t \le K(a) + a \le a$

a, hence by induction  $V_{t-1} \le a$  for t > 0. Accordingly, from (7.4.28(p.41)) and (11.2.7(1)(p.57)) we have  $V_t = \lambda \mu - s + (1 - \lambda)V_{t-1} \cdots (14)$  for t > 0.

(c2ii1i) Let  $\lambda = 1$ . Then, we have  $x_K = \mu - s$  from (13) and  $V_t = \mu - s$  for t > 0 from (14), hence  $V_t = x_K$  for t > 0, so  $V_{t-1} = x_K$  for t > 1. Accordingly,  $V_{t-1} = x_L$  for t > 1 due to (10). Then  $L(V_{t-1}) = L(x_L) = 0$  for t > 1, hence  $V_t - \beta V_{t-1} = 0$  for t > 1 from (22.2.27(p.203)) or equivalently  $V_t = \beta V_{t-1}$  for t > 1. Then, since  $V_t = \beta V_{t-1}$  for  $\tau \ge t > 1$ , we have  $V_\tau = \beta V_{\tau-1} \cdots = \beta^{\tau-1} V_1$  for  $\tau > 1$ . From this and (4) we have  $V_\tau = \beta V_{\tau-1} = \beta^2 V_{\tau-2} = \cdots = \beta^{\tau-1} V_1 > \beta^\tau V_0$ , hence  $t_\tau^* = 1$  for  $\tau > 1$ , i.e.,  $\boxed{\odot}$  nd0IT $_{\tau>1}\langle 1 \rangle$ .

(c2ii1ii) Let  $\lambda < 1$ . Note (6). Suppose  $V_{t-1} < x_L$ . Then, we have  $V_t < K(x_L) + x_L = x_L$  from Lemma 11.2.2(p.57) (f) and (11). Accordingly, by induction  $V_{t-1} < x_L$  for t > 0, hence  $L(V_{t-1}) > 0$  for t > 0 from Lemma 11.2.1(p.57) (e1). Thus, for the same reason as in the proof of Tom 22.2.1(p.203) (c) we have  $\boxed{\$}$  dOITs<sub> $\tau > 1$ </sub> $\langle \tau \rangle$ .

(c2ii2) Let  $(\lambda \mu - s)/\lambda > a$ . Then  $x_K > (\lambda \mu - s)/\lambda > a$  from Lemma 11.2.2(p.57) (j2), hence  $x_L > a$  from (10). Note (6). Suppose  $V_{t-1} < x_L$ . Then, we have  $V_t < K(x_L) + x_L = x_L$  from Lemma 11.2.2(p.57) (h) and (11). Accordingly, by induction  $V_{t-1} < x_L \cdots$  (15) for t > 0, hence  $L(V_{t-1}) > 0$  for t > 0 due to

Lemma 11.2.1(p.57) (e1). Consequently, for the same reason as in the proof of Tom 22.2.1(p.203) (c) we obtain  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ .

- (c3) Let  $\beta < 1$  and s = 0 ((s > 0)).
- (c3i) Let  $a < \rho \cdots$  (16). Then, since  $a < V_0$  from (7.4.27(p.41)), we have  $a < V_{t-1}$  for t > 0 due to (a).
- (c3i1) Let  $b \ge 0$  ( $\kappa \ge 0$ ). Then  $x_L \ge x_K \cdots$  (17) from Lemma 11.2.3(p.58) (c (d)). Note (2). Suppose  $V_{t-1} < x_K$ . Then, from (7.4.28(p.41)) and Lemma 11.2.2(p.57) (g) we have  $V_t < K(x_K) + x_K = x_K$ . Accordingly, by induction  $V_{t-1} < x_K$  for t > 0, hence  $V_{t-1} < x_L$  for t > 0 due to (17). Therefore, since  $L(V_{t-1}) > 0$  for t > 0 from Corollary 11.2.1(p.57) (a), for the same reason as in the proof of Tom 22.2.1(p.203) (c) we obtain [8] dOITs  $_{\tau > 1} \langle \tau \rangle$ .
- (c3i2) Let b < 0 ( $\kappa < 0$ ). Then  $x_L < x_K \cdots$  (18) from Lemma 11.2.3(p.58) (c (d)). Note (6). Suppose  $V_{t-1} < x_L$  for all t > 0, hence  $V \le x_L$ . Now, since  $V = x_K$  due to (a), we have  $x_L < V$  due to (18), which is a contradiction. Hence, it is impossible that  $V_{t-1} < x_L$  for all t > 0. In addition, from (6) and the strict increasingness of  $V_t$  due to (a), it follows that there exists  $t_T^{\bullet} > 0$  such that

$$V_0 < V_1 < \dots < V_{t^{\bullet}-1} < x_L \le V_{t^{\bullet}} < V_{t^{\bullet}+1} < V_{t^{\bullet}+2} < \dots$$

from which we have

$$V_{t-1} < x_L, \ t_{\tau}^{\bullet} \ge t > 0, \qquad x_L \le V_{t_{\tau}^{\bullet}}, \qquad x_L < V_{t-1}, \ t > t_{\tau}^{\bullet} + 1.$$
 (22.2.28)

Hence, we have

$$L(V_{t-1}) > 0$$
  $\cdots$  (19),  $t_{\tau}^{\bullet} \ge t > 0$  (due to Corollary 11.2.1(p.57) (a))  $L(V_{t_{\tau}^{\bullet}}) \le 0$   $\cdots$  (20), (due to Corollary 11.2.1(p.57) (a))  $L(V_{t-1}) = (<0)^{\dagger} \cdots (21), t > t_{\tau}^{\bullet} + 1$  (due to Lemma 11.2.1(p.57) (d(e1)))

• Let  $t_{\tau}^{\bullet} \geq \tau > 0$ . Then  $L(V_{t-1}) > 0 \cdots$  (22) for  $\tau \geq t > 0$  from (19). Hence, for the same reason as in Tom 22.2.1(p.203) (c) we obtain  $\boxed{\$ \text{ dOITs}_{\tau}\langle \tau \rangle}_{\bullet}$  for  $t_{\tau}^{\bullet} \geq \tau > 0$ . Accordingly,  $S_8(1)$  is true. Now, since  $V_t - \beta V_{t-1} > 0$  for  $\tau \geq t > 0$  from (22.2.27(p.203)) and (22), we have  $V_t > \beta V_{t-1}$  for  $\tau \geq t > 0$ , hence

$$V_{\tau} > \beta V_{\tau-1} > \beta^2 V_{\tau-2} > \dots > \beta^{\tau} V_0.$$

Accordingly, when  $\tau = t_{\tau}^{\bullet}$ , we have

$$V_{t_{\tau}} > \beta V_{t_{\tau}-1} > \dots > \beta^{t_{\tau}} V_0 \cdots (23)$$

• Let  $\tau = t_{\tau}^{\bullet} + 1$ . From (22.2.27(p.203)) with  $t = t_{\tau}^{\bullet} + 1$  and (20) we have  $V_{t_{\tau}^{\bullet}+1} - \beta V_{t_{\tau}^{\bullet}} = L(t_{\tau}^{\bullet}) \leq 0$ , hence  $V_{t_{\tau}^{\bullet}+1} \leq \beta V_{t_{\tau}^{\bullet}}$ . Accordingly, from (23) we have

$$V_{t_{\tau}^{\bullet}+1} \leq \beta V_{t_{\tau}^{\bullet}} > \beta^{2} V_{t_{\tau}^{\bullet}-1} > \beta^{3} V_{t_{\tau}^{\bullet}-2} > \dots > \beta^{t_{\tau}^{\bullet}+1} V_{0} \dots (24),$$

thus  $t_{t_{\tau}+1}^* = t_{\tau}^{\bullet}$ , i.e.,  $\bigcirc$  ndOIT $_{t_{\tau}+1}\langle t_{\tau}^{\bullet} \rangle \mid_{\Delta}$ , so that S<sub>8</sub>(2) is true.

• Let  $\tau > t_{\tau}^{\bullet} + 1$ . Since  $L(V_{t_{\tau}^{\bullet}+1}) = (<) 0$  from (21) with  $t = t_{\tau}^{\bullet} + 2$ , we have  $V_{t_{\tau}^{\bullet}+2} = (<) \beta V_{t_{\tau}^{\bullet}+1}$  from (22.2.27(p.203)), hence from (24) we have

$$V_{t_{\tau}^{\bullet}+2} = (\!(<)\!) \beta V_{t_{\tau}^{\bullet}+1} \leq \beta^2 V_{t_{\tau}^{\bullet}} > \beta^3 V_{t_{\tau}^{\bullet}-1} > \beta^4 V_{t_{\tau}^{\bullet}-2} > \dots > \beta^{t_{\tau}^{\bullet}+2} V_0$$

Similarly we have

$$V_{t^{\bullet}+3} = (\langle \rangle) \beta V_{t^{\bullet}+2} = (\langle \rangle) \beta^{2} V_{t^{\bullet}+1} \le \beta^{3} V_{t^{\bullet}} > \beta^{4} V_{t^{\bullet}-1} > \dots > \beta^{t^{\bullet}_{\tau}+3} V_{0}.$$

By repeating the same procedure, for  $\tau = t_{\tau}^{\bullet} + 2, t_{\tau}^{\bullet} + 3, \cdots$  we obtain

$$V_{\tau} = (<) \beta V_{\tau-1} = (<) \cdots = (<) \beta^{\tau-t_{\tau}^{\bullet}-2} V_{t_{\tau}^{\bullet}+2} = (<)$$

$$\beta^{\tau-t_{\tau}^{\bullet}-1} V_{t_{\tau}^{\bullet}+1} \le \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} > \beta^{\tau-t_{\tau}^{\bullet}+1} V_{t_{\tau}^{\bullet}-1} > \cdots > \beta^{\tau} V_{0} \cdots (25)$$

<sup>†</sup> If s = 0, then  $L(V_{t-1}) = 0$ , or else  $L(V_{t-1}) < 0$ .

• Let s = 0. Then (25) can be written as

$$V_{\tau} = \beta V_{\tau-1} = \dots = \beta^{\tau - t_{\tau}^{\bullet} - 2} V_{t_{\tau}^{\bullet} + 2} = \beta^{\tau - t_{\tau}^{\bullet} - 1} V_{t_{\tau}^{\bullet} + 1} \le \beta^{\tau - t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} > \beta^{\tau - t_{\tau}^{\bullet} + 1} V_{t_{\tau}^{\bullet} - 1} > \dots > \beta^{\tau} V_{0},$$

hence  $t_{\tau}^* = t_{\tau}^{\bullet}$ , i.e.,  $\boxed{\odot \text{ ndOIT}_{\tau > t_{\tau}^{\bullet} + 1} \langle t_{\tau}^{\bullet} \rangle}_{\parallel}$  (see Preference Rule 8.2.1(p.45)), hence  $S_8(3)$  is true.

 $\circ$  Let s > 0. Then (25) can be written as

$$V_{\tau} < \beta V_{\tau-1} < \dots < \beta^{\tau - t_{\tau}^{\bullet} - 2} V_{t_{\tau}^{\bullet} + 2} < \beta^{\tau - t_{\tau}^{\bullet} - 1} V_{t_{\tau}^{\bullet} + 1} \le \beta^{\tau - t_{\tau}^{\bullet} - 1} V_{t_{\tau}^{\bullet}} > \beta^{\tau - t_{\tau}^{\bullet} + 1} V_{t_{\tau}^{\bullet} - 1} > \dots > \beta^{\tau} V_{0}, \tag{22.2.29}$$

hence  $t_{\tau}^* = t_{\tau}^{\bullet}$ , i.e.,  $\boxed{\odot \text{ ndOIT}_{\tau > t_{\tau}^{\bullet} + 1} \langle t^{\circ} \rangle}_{\blacktriangle}$ , hence  $S_8(3)$  is true.

- (c3ii) Let  $\rho \leq a$ , hence  $V_0 \leq a$  from (7.4.27(p.41)). Then, from (3) and (11.2.7 (1) (p.57)) we have  $V_1 = \lambda \beta \mu s + (1 \lambda)\beta \rho$ . (c3ii1) Let  $(\lambda \beta \mu s)/\delta \leq a$ . Then  $x_K = (\lambda \beta \mu s)/\delta \leq a \cdots$  (26) from Lemma 11.2.2(p.57) (j2(p.58)). Hence  $V_1 = \delta x_K + (1 \lambda)\beta \rho \cdots$  (27).
- (c3iii) Let  $\lambda = 1$ , hence  $\delta = 1$  from (11.2.1(p.56)). Thus, from (26) and (27) we have  $x_K = \beta \mu s \le a$  and  $V_1 = x_K \le a \cdots (28)$ .
- (c3ii1i) Let b > 0 ( $\kappa > 0$ ). Then  $x_L > x_K \cdots$  (29) due to Lemma 11.2.3(p.58) (c (d)). Note (28). Suppose  $V_{t-1} = x_K$ . Then, from (7.4.28(p.41)) we have  $V_t = K(x_K) + x_K = x_K$ . Accordingly, by induction  $V_{t-1} = x_K$  for t > 1, hence  $V_{t-1} < x_L$  for t > 1 due to (29), thus  $L(V_{t-1}) > 0$  for t > 1 from Corollary 11.2.1(p.57) (a). Hence, from (7) we obtain  $L(V_{t-1}) > 0$  for t > 0. Accordingly, for almost the same reason as in the proof of Tom 22.2.1(p.203) (c) we obtain S dOITs  $T_{t-1} < T_{t-1} <$
- (c3ii1i2) Let  $b \le 0$  ( $\kappa \le 0$ ). Then, since  $x_L \le x_K$  from Lemma 11.2.3(p.58) (c (d)), we have  $V_1 \ge x_L$  from (28), hence  $V_{t-1} \ge x_L$  for t > 1 from (a). Accordingly, since  $L(V_{t-1}) \le 0$  for t > 1 from Corollary 11.2.1(p.57) (a), we have  $L(V_{t-1}) \le 0$  for  $\tau \ge t > 1$ , thus  $V_t \beta V_{t-1} \le 0$  for  $\tau \ge t > 1$  from (22.2.27(p.203)), i.e.,  $V_t \le \beta V_{t-1}$  for  $\tau \ge t > 1$ . Hence  $V_\tau \le \beta V_{\tau-1} \le \cdots \le \beta^{\tau-1}V_1 \cdots$  (30). Now, from (7.4.27(p.41)), (4), (28), and (29) we have  $\rho = V_0 < V_1 = x_K < x_L$ , hence  $L(\rho) > 0$  from Corollary 11.2.1(p.57) (a). In addition, from (3) and (7.4.27(p.41)) we have  $V_1 \beta V_0 = V_1 \beta \rho = K(\rho) + \rho \beta \rho = K(\rho) + (1-\beta)\rho = L(\rho) > 0$  from (6.1.8(p.25)), hence  $V_1 > \beta V_0$ . Accordingly, from (30) we have  $V_\tau \le \beta V_{\tau-1} \le \beta^2 V_{\tau-2} \le \cdots \le \beta^{\tau-1}V_1 > \beta^\tau V_0$  for  $\tau > 1$ , hence  $t_\tau^* = 1$  for  $\tau > 1$ , i.e.,  $\boxed{\odot}$  ndOIT $_{\tau>1}\langle 1 \rangle$  of

(c3ii1ii) Let  $\lambda < 1$ .

- (c3iiiii) Let  $b \ge 0$  ( $\kappa \ge 0$ ). Then  $x_L \ge x_K \cdots$  (31) from Lemma 11.2.3(p.58) (c (d)). Note (2). Suppose  $V_{t-1} < x_K$ . Then, from Lemma 11.2.2(p.57) (f) we have  $V_t < K(x_K) + x_K = x_K$ . Hence, by induction  $V_{t-1} < x_K$  for t > 0, so  $V_{t-1} < x_L$  for t > 0 due to (31). Accordingly, since  $L(V_{t-1}) > 0$  for t > 0 from Corollary 11.2.1(p.57) (a), for the same reason as in the proof of Tom 22.2.1(p.203) (c) we obtain sample s
- (c3ii1ii2) Let b < 0 ( $\kappa < 0$ ). Then  $x_L < x_K \cdots$  (32) from Lemma 11.2.3(p.58) (c (d)). Note (6). Assume that  $V_{t-1} < x_L$  for all t > 0, hence  $V \le x_L$  due to (a). Now, since  $V = x_K$  from (a), we have the contradiction  $x_L < V$  from (32). Hence, it is impossible that  $V_{t-1} < x_L$  for all t > 0. From this and the strict increasingness of  $V_t$  due to (a), it follows that there exists  $t_{\tau}^* > 0$  such that

$$V_0 < V_1 < \dots < V_{t_{-}-1} < x_L \le V_{t_{-}} < V_{t_{-}+1} < V_{t_{-}+2} < \dots \to x_K.$$

(c3ii2) Let  $(\lambda \beta \mu - s)/\delta > a \cdots$  (33). Then  $x_K > (\lambda \beta \mu - s)/\delta > a$  from Lemma 11.2.2(p.57) (j2).

- 1. Let  $\lambda < 1$ . Then  $V_t$  is strictly increasing in  $t \geq 0$  due to (a).
- 2. Let  $\lambda=1$ , hence  $\delta=1$  from (11.2.1(p56)), so  $\beta\mu-s>a$  from (33). Now  $K(x)\geq\beta\mu-s-x$  for any x from (11.2.4(p.57)) or equivalently  $K(x)+x\geq\beta\mu-s$  for any x, so  $V_1\geq\beta\mu-s>a$  from (3). Accordingly  $V_{t-1}>a$  for t>1 due to (a). Note (4). Suppose  $V_{t-1}< V_t$ . Then, from Lemma 11.2.2(p.57) (g) we have  $V_t< K(V_t)+V_t=V_{t+1}$ . Accordingly, by induction we have  $V_{t-1}< V_t$  for t>0, i.e.,  $V_t$  is strictly increasing in  $t\geq0$ .

From the above, whether  $\lambda < 1$  or  $\lambda = 1$ , we see that  $V_t$  is strictly increasing in t > 0.

- (c3ii2i) Let  $b \ge 0$  ( $\kappa \ge 0$ ). Then  $x_L \ge x_K \cdots$  (34) from Lemma 11.2.2(p.57) (c (d)). From the above strict increasingness of  $V_t$  in  $t \ge 0$  and (a) we have  $V_{t-1} < V = x_K$  for t > 0, hence  $V_{t-1} < x_L$  for t > 0 from (34). Thus, since  $L(V_{t-1}) > 0$  for t > 0 from Corollary 11.2.1(p.57) (a), for the same reason as in the proof of Tom 22.2.1(p.203) (c) we obtain sample sample
- (c3ii2ii) Let b < 0 ( $\kappa < 0$ ). Then  $x_L < x_K \cdots$  (35) from Lemma 11.2.3(p.58) (c (d)). Note (6). Suppose  $V_{t-1} < x_L$  for all t > 0, hence  $V \le x_L$ . Now, since  $V = x_K$  from (a), we have  $x_L < V$  from (35), which is a contradiction. Accordingly, it is impossible that  $V_{t-1} < x_L$  for all t > 0. From this, (6), and the above strict increasingness of  $V_t$  in  $t \ge 0$  it follows that there exists  $t_{\tau}^* > 0$  such that

$$V_0 < V_1 < \dots < V_{t^{\bullet}_{\tau}-1} < x_L \le V_{t^{\bullet}_{\tau}} < V_{t^{\bullet}_{\tau}+1} < V_{t^{\bullet}_{\tau}+2} < \dots \rightarrow x_K.$$

Accordingly, for the same reason as in the proof of (c3i2) we can immediately see that the assertion holds true.

■ Tom 22.2.3 ( $\mathscr{A}\{M:2[\mathbb{R}][E]\}$ ) Let  $\beta < 1$  or s > 0 and let  $\rho = x_K$ .

- (a)  $V_t = x_K = \rho \text{ for } t > 0.$
- (b) Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\beta < 1$  and s = 0 ((s > 0)).
  - 1. Let b > 0 ( $\kappa > 0$ ). Then subseteq doints  $tau_{\tau > 0} \langle \tau \rangle$ .
  - 2. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}$ .  $\square$
- Proof Let  $\beta < 1$  or s > 0 and let  $\rho = x_K$ . Hence  $V_0 = \rho = x_K \cdots (1)$  from (7.4.27(p.41)).
- (a) Note (1). Suppose  $V_{t-1} = x_K$ . Then, from (7.4.28(p.41)) we have  $V_t = K(x_K) + x_K = x_K$ . Hence, by induction  $V_t = x_K = \rho$  for  $t \ge 0$ .
- (b) Let  $\beta=1$ , hence s>0 due to the assumption " $\beta<1$  or s>0". Then  $x_L=x_K$  from Lemma 11.2.3(p.58) (b). Accordingly, since  $V_{t-1}=x_L$  for t>0 from (a), we have  $L(V_{t-1})=L(x_L)=0$  for t>0, hence for the same reason as in the proof of Tom 22.2.1(p.203) (b) we obtain  $\bullet$  dOITd $_{\tau>0}\langle 0 \rangle_{\parallel}$ .
  - (c) Let  $\beta < 1$  and s = 0 ((s > 0)).
- (c1) Let b > 0 ( $\kappa > 0$ ). Then, since  $x_L > x_K$  from Lemma 11.2.3(p.58) (c (d)), we have  $x_L > x_K = V_{t-1}$  for t > 0 from (a), hence  $L(V_{t-1}) > 0$  for t > 0 due to Corollary 11.2.1(p.57) (a), thus for the same reason as in the proof of Tom 22.2.1(p.203) (c) we obtain  $\boxed{\$ \text{dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$ .
- (c2) Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $x_L \leq x_K$  from Lemma 11.2.3(p.58) (c (d)). Hence, since  $x_L \leq x_K = V_{t-1}$  for t > 0 from (a), we have  $L(V_{t-1}) \leq 0$  for t > 0 due to Corollary 11.2.1(p.57) (a), hence  $V_t \beta V_{t-1} \leq 0$  for t > 0 from (22.2.27(p.203)) or equivalently  $V_t \leq \beta V_{t-1}$  for t > 0. Accordingly, since  $V_t \leq \beta V_{t-1}$  for  $\tau \geq t > 0$ , we have  $V_\tau \leq \beta V_{\tau-1} \leq \beta^2 V_{\tau-2} \leq \cdots \leq \beta^\tau V_0$ , thus  $t_\tau^* = 0$  for  $\tau > 0$ , i.e.,  $\mathrm{dOIT}_{\tau > 0} \langle 0 \rangle_\Delta$ .

$$\mathbf{S}_{9} \overset{\textcircled{\otimes}_{\Delta} \bullet_{\Delta} \bullet_{\Delta}}{\bullet_{\Delta}} = \begin{cases} \text{For any } \tau > 0 \text{ there exists } t^{\bullet} > 0 \text{ such that} \\ (1) & \bullet \text{dOITd}_{\tau=1}\langle 0 \rangle_{\parallel} \left( \bullet \text{dOITd}_{\tau=1}\langle 0 \rangle_{\Delta} \right), \\ (2) & \textcircled{\otimes} \text{dOITs}_{\tau > t^{\bullet}}\langle \tau \rangle_{\Delta} \text{ or } \bullet \text{dOITd}_{\tau > t^{\bullet}}\langle 0 \rangle_{\Delta}, \\ (3) & \bullet \text{dOITd}_{t^{\bullet} \geq \tau > 1}\langle 0 \rangle_{\Delta} \left( \bullet \text{dOITd}_{t^{\bullet} \geq \tau > 1}\langle 0 \rangle_{\Delta} \right). \end{cases}$$

 $\blacksquare$  Tom 22.2.4 ( $\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}$ ) Let  $\beta<1$  or s>0 and let  $\rho>x_K$ .

- (a)  $V_t$  is nonincreasing in  $t \ge 0$ , is strictly decreasing in t > 0 if  $\lambda < 1$ , and converges to a finite  $V = x_K$  as  $to \to \infty$ .
- (b) Let  $\rho < x_L$ . Then  $\boxed{\$ dOITs_{\tau>0} \langle \tau \rangle}_{\blacktriangle}$ .
- (c) Let  $\rho = x_L$ . Then  $\bullet dOITd_1\langle 0 \rangle_{\parallel}$  and  $\circ dOITs_{\tau>1}\langle \tau \rangle_{\blacktriangle}$ .
- (d) Let  $\rho > x_L$ .
  - 1. Let  $\beta = 1$ . Then  $\left[ \bullet dOITd_{\tau > 0} \langle 0 \rangle \right]_{\Delta}$ .
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).

i. Let 
$$b \leq 0$$
 ( $\kappa \leq 0$ ). Then  $\left[ \bullet \operatorname{dOITd}_{\tau>0} \langle 0 \rangle \right]_{\vartriangle}$  ( $\left[ \bullet \operatorname{dOITd}_{\tau>0} \langle 0 \rangle \right]_{\blacktriangle}$ ).  $\mapsto$ 

ii. Let 
$$b > 0$$
 ( $\kappa > 0$ ). Then  $S_9$   $\stackrel{\textcircled{S}_{\triangle}}{\bullet}$   $\bullet$  is true.  $\square \mapsto$ 

- Proof Let  $\beta < 1$  or s > 0 and let  $\rho > x_K$ . Then  $V_0 > x_K \cdots$  (1) from (7.4.27(p.41)) and  $K(\rho) < 0 \cdots$  (2) from Lemma 11.2.2(p.57) (j1). From (7.4.28(p.41)) with t = 1 and from (7.4.27(p.41)) we have  $V_1 V_0 = K(V_0) = K(\rho) < 0$ , hence  $V_1 < V_0 \cdots$  (3). In addition, from (22.2.27(p.203)) with t = 1 we have  $V_1 \beta V_0 = L(V_0) = L(\rho) \cdots$  (4) from (7.4.27(p.41)).
- (a) Note (3), hence  $V_0 \geq V_1$ . Suppose  $V_{t-1} \geq V_t$ . Then, from (7.4.28(p.41)) and Lemma 11.2.2(p.57) (e) we have  $V_t \geq K(V_t) + V_t = V_{t+1}$ . Hence, by induction  $V_{t-1} \geq V_t$  for t > 0, i.e.,  $V_t$  is nonincreasing in  $t \geq 0$ . Let  $\lambda < 1$ . Note again (3). Suppose  $V_{t-1} > V_t$ . Then, from Lemma 11.2.2(p.57) (f) we have  $V_t > K(V_t) + V_t = V_{t+1}$ . Hence, by induction  $V_{t-1} > V_t$  for t > 0, i.e.,  $V_t$  is strictly decreasing in  $t \geq 0$ . Note (1), hence  $V_0 \geq x_K$ . Suppose  $V_{t-1} \geq x_K$ . Then, from (7.4.28(p.41)) and Lemma 11.2.2(p.57) (e) we have  $V_t \geq K(x_K) + x_K = x_K$ . Hence, by induction  $V_{t-1} \geq x_K \cdots$  (5) for t > 0, i.e.,  $V_t$  is lower bounded in t. Thus, it follows that  $V_t$  converges to a finite V as  $t \to \infty$ . Hence, since V = K(V) + V from (7.4.28(p.41)), we have K(V) = 0, thus  $V = x_K$  due to Lemma 11.2.2(p.57) (j1).
- (b) Let  $\rho < x_L$ . Then, since  $V_0 < x_L$  from (7.4.27(p.41)), we have  $V_{t-1} < x_L$  for t > 0 due to (a). Therefore, since  $L(V_{t-1}) > 0$  for t > 0 from Corollary 11.2.1(p.57)(a), for the same reason as in the proof of Tom 22.2.1(p.203)(c) we obtain  $\boxed{\$ \text{dOITs}_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$ .
- (c) Let  $\rho = x_L \cdots$  (6). Then, since  $L(\rho) = L(x_L) = 0$ , we have  $V_1 \beta V_0 = 0$  from (4) or equivalently  $V_1 = \beta V_0 \cdots$  (7), hence  $\bullet dOITd_1\langle 0 \rangle_{\parallel}$ . Below, let  $\tau > 1$ . Now, since  $V_1 = K(\rho) + \rho < \rho$  from (7.4.28(p.41)) with t = 1 and (2), we have  $V_{t-1} < \rho$  for t > 1 from (a), hence  $V_{t-1} < x_L$  for t > 1 due to (6), so  $L(V_{t-1}) > 0$  for t > 1 from Corollary 11.2.1(p.57) (a). Accordingly, since  $L(V_{t-1}) > 0$  for  $\tau \ge t > 1$ , we have  $V_t \beta V_t > 0$  for  $\tau \ge t > 1$  due to (22.2.27(p.203)) or equivalently  $V_t > \beta V_t$  for  $\tau \ge t > 1$ , from which we have  $V_\tau > \beta V_{\tau-1} > \cdots > \beta^{\tau-1}V_1$ . Hence, from (7) we have

$$|V_{\tau}| > \beta V_{\tau-1} > \dots > \beta^{\tau-1} V_1 = \beta^{\tau} V_0.$$

Accordingly, we obtain  $t_{\tau}^* = \tau$  for  $\tau > 1$ , i.e.,  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$ .

- (d) Let  $x_L < \rho \cdots$  (8), hence  $x_L < V_0 \cdots$  (9) from (7.4.27(p.41)). Thus, if s = (>) 0, then  $L(V_0) = (<) 0 \cdots$  (10) from Lemma 11.2.1(p.57) (d(e1)), hence  $V_1 \beta V_0 = (<) 0$  from (4) or equivalently  $V_1 = (<) \beta V_0 \cdots$  (11).
- (d1) Let  $\beta = 1$ , hence s > 0 due to the assumption " $\beta < 1$  or s > 0". Then  $L(V_0) < 0$  from (10), hence  $V_1 < \beta V_0 \cdots$  (12) from (22.2.27(p.203)). Now, since  $x_L = x_K$  due to Lemma 11.2.3(p.58) (b), from (5) we have  $V_{t-1} \ge x_L$  for t > 0, hence  $L(V_{t-1}) \le 0$  for t > 0 due to Lemma 11.2.1(p.57) (e1), thus  $V_t \beta V_{t-1} \le 0$  for t > 0 from (22.2.27(p.203)). Then, since  $V_t \beta V_{t-1} \le 0$  for  $\tau \ge t > 0$ , we have  $V_t \le \beta V_{t-1}$  for  $\tau \ge t > 0$ , leading to

$$V_{\tau} \leq \beta V_{\tau-1} \leq \dots \leq \beta^{\tau-1} V_1 \leq \beta^{\tau} V_0.$$

Hence we have  $t_{\tau}^* = 0$  for  $\tau > 0$ , i.e.,  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\Delta}$ .

- (d2) Let  $\beta < 1$  and s = 0 ((s > 0)).
- (d2i) Let  $b \le 0$  ( $\kappa \le 0$ ). Then  $x_L \le x_K$  due to Lemma 11.2.3(p.58) (c (d)). Hence, from (5) we have  $V_{t-1} \ge x_L$  for t > 0, hence  $L(V_{t-1}) \le 0$  for t > 0 due to Corollary 11.2.1(p.57) (a), so  $V_t \beta V_{t-1} \le 0$  for t > 0 from (22.2.27(p.203)). Then, since  $V_t \beta V_{t-1} \le 0$  for  $\tau \ge t > 0$ , we have  $V_t \le \beta V_{t-1}$  for  $\tau \ge t > 0$ , leading to

$$V_{\tau} \leq \beta V_{\tau-1} \leq \dots \leq \beta^{\tau-1} V_1 \leq \beta^{\tau} V_0.$$

Due to (11) the inequality can be rewritten as

$$V_{\tau} \leq \beta V_{\tau-1} \leq \cdots \leq \beta^{\tau-1} V_1 = (<) |\beta^{\tau} V_0|,$$

hence  $t_{\tau}^* = 0$  for  $\tau > 0$ , i.e.,  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\Lambda}$  ( $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\Lambda}$ ).

(d2ii) Let b > 0 ( $\kappa > 0$ ). Then  $x_L > x_K > 0 \cdots$  (13) from Lemma 11.2.3(p.58) (c (d)). Hence, from (3) and (9) and from the nonincreasingness of  $V_t$  and the convergency of  $V_t$  to  $V = x_K$  due to (a) we see that there exists  $t^{\bullet} > 0$  such that

$$V_0 > V_1 \ge V_2 \ge \cdots \ge V_{t^{\bullet}-1} \ge x_L > V_{t^{\bullet}} \ge V_{t^{\bullet}+1} \ge \cdots \to x_K \cdots (14)$$

or equivalently  $V_0 > x_L$ ,  $V_{t-1} \ge x_L$  for  $t^{\bullet} \ge t > 1$ , and  $x_L > V_{t-1}$  for  $t > t^{\bullet}$ . Hence, we have

$$L(V_{t-1}) > 0$$
,  $t > t^{\bullet}$ , due to Corollary 11.2.1(p.57) (a),  $L(V_{t-1}) \le 0$ ,  $t^{\bullet} \ge t > 1$ , due to Corollary 11.2.1(p.57) (a),  $L(V_0) = (<) 0$  due to Lemma 11.2.1(p.57) (d((e1))).

Hence, from (22.2.27(p.203)) we have

$$V_t > \beta V_{t-1} \cdots (15), \quad t > t^{\bullet}, \qquad V_t \leq \beta V_{t-1} \cdots (16), \quad t^{\bullet} \geq t > 1, \qquad V_1 = (<) \beta V_0 \cdots (17).$$

- $\langle A \rangle$  Let  $\tau = 1$ . Then, since  $V_1 = (\langle \rangle) \beta V_0$  due to (17), we have  $\bullet dOITd_{\tau=1}\langle 0 \rangle | (\bullet dOITd_{\tau=1}\langle 0 \rangle)_{\blacktriangle}$ , hence (1) of  $S_9$  holds.
- $\langle B \rangle$  Let  $t^{\bullet} \geq \tau > 1$ . Then, since  $V_t \leq \beta V_{t-1}$  for  $\tau \geq t > 1$  from (16), we have

$$V_{\tau} \leq \beta V_{\tau-1} \leq \dots \leq \beta^{\tau-1} V_1,$$

hence

$$V_{\tau} \leq \beta V_{\tau-1} \leq \cdots \leq \beta^{\tau-1} V_1 = (<) \beta^{\tau} V_0 \cdots (18), \quad t^{\bullet} \geq \tau > 0,$$

from (17) or equivalently

$$I_{\tau}^{\tau} \leq I_{\tau}^{\tau-1} \leq \cdots \leq I_{\tau}^{1} = (<) I_{\tau}^{0} \cdots (19), \quad t^{\bullet} \geq \tau > 0.$$

Thus  $t_{\tau}^* = 0$  for  $t^{\bullet} \geq \tau > 0$ , i.e.,  $\bullet dOITd_{t_{\tau}^{\bullet} \geq \tau > 1}\langle 0 \rangle$  ( $\bullet dOITd_{t_{\tau}^{\bullet} \geq \tau > 1}\langle 0 \rangle$ ), hence (2) of  $S_9$  holds. Now, from (18) with  $\tau = t^{\bullet}$  we have

$$V_{t^{\bullet}} < \beta V_{t^{\bullet}-1} < \dots < \beta^{t^{\bullet}-1} V_1 = ((<)) \beta^{t^{\bullet}} V_0 \dots (20).$$

 $\langle \mathcal{C} \rangle$  Let  $\tau > t^{\bullet} \, (>0)$ , hence  $\tau > 1$ . From (15) with  $\tau \geq t > t^{\bullet}$  we have

$$V_{\tau} > \beta V_{\tau-1} > \dots > \beta^{\tau-t^{\bullet}-1} V_{t^{\bullet}+1} > \beta^{\tau-t^{\bullet}} V_{t^{\bullet}} \cdots (21), \quad \tau > t^{\bullet}.$$

Combining (21) and (20) leads to

$$V_{\tau} > \beta V_{\tau-1} > \dots > \beta^{\tau-t^{\bullet}-1} V_{t^{\bullet}+1} > \beta^{\tau-t^{\bullet}} V_{t^{\bullet}} \le \beta^{\tau-t^{\bullet}+1} V_{t^{\bullet}-1} \le \dots \le \beta^{\tau-1} V_{1} = ( \langle \rangle ) \beta^{\tau} V_{0}, \quad \tau > t^{\bullet},$$

or equivalently

$$I_{\tau}^{\tau} > I_{\tau}^{\tau-1} > I_{\tau}^{\tau-2} > \cdots > I_{\tau}^{t^{\bullet}+1} > I_{\tau}^{t^{\bullet}} < I_{\tau}^{t^{\bullet}-1} < \cdots < I_{\tau}^{1} = (<) I_{\tau}^{0} \cdots (22), \quad \tau > t^{\bullet}.$$

Hence we have  $\boxed{\$ \text{ dOITs}_{\tau>t^{\bullet}}\langle \tau \rangle}$  or  $\boxed{\bullet \text{ dOITd}_{\tau>t^{\bullet}}\langle 0 \rangle}$ , thus (3) of  $\mathbb{S}_9$  holds.  $\blacksquare$ 

#### 22.2.4.3 Market Restriction

#### 22.2.4.3.1 Positive Restriction

### **22.2.4.3.1.1** Case of $\beta = 1$ and s = 0

- $\square$  Pom 22.2.1 ( $\mathscr{A}\{M:2[\mathbb{R}][E]^+\}$ ) Suppose a > 0. Let  $\beta = 1$  and s = 0.
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\rho \geq b$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho < b$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle$
- *Proof* The same as Tom 22.2.1(p.203) due to Lemma 18.4.4(p.118).

#### **22.2.4.3.1.2** Case of $\beta < 1$ or s > 0

- $\square$  Pom 22.2.2 ( $\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]^+\}$ ) Suppose a>0. Let  $\beta<1$  or s>0 and let  $\rho< x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ , is strictly increasing in  $t \geq 0$  if  $\lambda < 1$  or  $a \leq \rho$ , and converges to a finite  $V = x_K$  as  $t \to \infty$ .
- (b) Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}$ .
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}_{\blacktriangle}$ . Below let  $\tau > 1$ .
  - 2. Let  $\beta = 1$ .
    - i. Let  $a \leq \rho$ . Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$ .
    - ii. Let  $\rho < a$ .
      - 1. Let  $(\lambda \mu s)/\lambda \leq a$ .
        - i. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT $_{\tau > 1}\langle 1 \rangle$ .
    - 2. Let  $(\lambda \mu s)/\lambda > a$ . Then  $\boxed{\$ dOITs_{\tau > 0} \langle \tau \rangle}_{\blacktriangle}$ .
  - 3. Let  $\beta < 1$  and s = 0. Then  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}$ .
  - 4. Let  $\beta < 1$  and s > 0.
    - i. Let  $a \leq \rho$ .
      - 1. Let  $\lambda \beta \mu \geq s$ . Then  $\boxed{\$ dOITs_{\tau>0} \langle \tau \rangle}$ . IvsD
      - 2. Let  $\lambda\beta\mu < s$ . Then  $S_8(p.203)$  sample sample
    - ii. Let  $\rho < a$ .
      - 1. Let  $(\lambda \beta \mu s)/\delta \leq a$ .
        - i. Let  $\lambda = 1$ .

          - 2. Let  $\beta \mu \leq s$ . Then  $\bigcirc$  ndOIT<sub> $\tau > 1$ </sub> $\langle 1 \rangle$ <sub> $\triangle$ </sub>.
        - ii. Let  $\lambda < 1$ .
          - 1. Let  $\lambda \beta \mu \geq s$ . Then  $\boxed{\$}$  dOITs $_{\tau>0} \langle \tau \rangle |_{\blacktriangle}$ .
          - 2. Let  $\lambda\beta\mu < s$ . Then  $S_8(p.203)$   $\bigcirc A \bigcirc A \bigcirc A$  is true.
      - 2. Let  $(\lambda \beta \mu s)/\delta > a$ .
        - i. Let  $\lambda \beta \mu \geq s$ . Then  $subseteq dOITs_{\tau > 1} \langle \tau \rangle$ .
        - ii. Let  $\lambda \beta \mu < s$ . Then  $S_8(p.203)$   $\boxed{\$ \blacktriangle \circledcirc \parallel \circledcirc \vartriangle \circledcirc \blacktriangle}$  is true.
- Proof Suppose a > 0, hence  $b > a > 0 \cdots$  (1). Then  $\kappa = \lambda \beta \mu s \cdots$  (2) from Lemma 11.3.1(p.59) (a).

(a-c2ii2) The same as Tom 22.2.2(p.204) (a-c2ii2).

(c3) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c3i1,c3ii1i1,c3ii1i1,c3ii2i) of Tom 22.2.2(p.204).

(c4-c4ii2ii) Let  $\beta < 1$  and s < 0. Then, due to (2) it suffices to consider only (c3-c3ii2ii) of Tom 22.2.2(p.204) with  $\kappa$ .

- $\square$  Pom 22.2.3 ( $\mathscr{A}\{M:2[\mathbb{R}][\mathbb{E}]^+\}$ ) Suppose a>0. Let  $\beta<1$  or s>0 and let  $\rho=x_K$ .
- (a)  $V_t = x_K = \rho \text{ for } t > 0.$
- (b) Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\beta < 1$  and s = 0. Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$ .
- (d) Let  $\beta < 1$  and s > 0.
  - 1. Let  $\lambda \beta \mu > s$ . Then  $\boxed{\$ dOITs_{\tau > 0} \langle \tau \rangle}_{\blacktriangle}$ .
  - 2. Let  $\lambda \beta \mu \leq s$ . Then  $\left[ \bullet dOITd_{\tau > 0} \langle 0 \rangle \right]_{\Delta}$ .

• Proof Suppose a > 0, hence  $b > a > 0 \cdots$  (1). Then  $\kappa = \lambda \beta \mu - s \cdots$  (2) from Lemma 11.3.1(p.59) (a). (a,b) The same as Tom 22.2.3(p.207) (a,b). (c) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (c1) of Tom 22.2.3(p.207). (d,d2) Let  $\beta < 1$  and s > 0. Then, due to (2) it suffices to consider only (c1,c2) of Tom 22.2.3(p.207).  $\square$  Pom 22.2.4 ( $\mathscr{A}\{M:2[\mathbb{R}][E]^+\}$ ) Suppose a>0. Let  $\beta<1$  or s>0 and let  $\rho>x_K$ . (a)  $V_t$  is nonincreasing in  $t \geq 0$ , is strictly decreasing in t > 0 if  $\lambda < 1$ , and converges to  $V = x_K$  as to  $t \to \infty$ . Let  $\rho < x_L$ . Then subseteq 0 dOITs  $_{\tau>0} \langle \tau \rangle$  $\rightarrow$  s (c) Let  $\rho = x_L$ . Then  $\boxed{\bullet \text{ dOITd}_1\langle 0 \rangle}_{\parallel}$  and  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$  for  $\tau > 1$ . (d) Let  $\rho > x_L$ . 1. Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\Delta}$ . 3. Let  $\beta < 1$  and s > 0. i. Let  $\lambda \beta \mu \leq s$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle$ . ii. Let  $\lambda\beta\mu > s$ . Then  $S_9(p.207)$   $\boxed{\$_{\Delta} \bullet_{\Delta}}$  is true (see Numerical Example 6(p.233)) • Proof Suppose a > 0. Then  $b > a > 0 \cdots$  (1). We have  $\kappa = \lambda \beta \mu - s \cdots$  (2) from Lemma 11.3.1(p.59) (a). (a-d1) The same as Tom 22.2.4(p.207) (a-d1). (d2) Let  $\beta < 1$  and s = 0. Then, due to (1) it suffices to consider only (d2ii) of Tom 22.2.4(p.207). (d3,d3ii) Let  $\beta < 1$  and s > 0. Then, due to (2) it suffices to consider only (d2i,d2ii) of Tom 22.2.4(p.207) with  $\kappa$ . 22.2.4.3.2 Mixed Restriction Omitted. 22.2.4.3.3 Negative Restriction 22.2.4.3.3.1 Case of  $\beta = 1$  and s = 0 $\square$  Nem 22.2.1 ( $\mathscr{A}\{M:2[\mathbb{R}][\mathbb{E}]^-\}$ ) Suppose b < 0. Let  $\beta = 1$  and s = 0. (a)  $V_t$  is nondecreasing in  $t \geq 0$ . (b) Let  $\rho \geq b$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ . (c) Let  $\rho < b$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle$ . • *Proof* The same as Tom 22.2.1(p.203) due to Lemma 18.4.4(p.118). 22.2.4.3.3.2 Case of  $\beta < 1$  or s > 0 $\square$  Nem 22.2.2 ( $\mathscr{A}\{M:2[\mathbb{R}][\mathbb{E}]^-\}$ ) Suppose b<0. Let  $\beta<1$  or s>0 and let  $\rho< x_K$ . (a)  $V_t$  is nondecreasing in  $t \geq 0$ , is strictly increasing in  $t \geq 0$  if  $\lambda < 1$  or  $a \leq \rho$ , and converges to a finite  $V = x_K$  as  $t \to \infty$ . (b) Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}$ (c) Let  $\rho < x_L$ . 1.  $\bigcirc \text{ dOITs}_1\langle 1 \rangle$  . Below let  $\tau > 1$ . 2. Let  $\beta = 1$ . i. Let  $a \leq \rho$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle$ . ii. Let  $\rho < a$ . 1. Let  $(\lambda \mu - s)/\lambda \leq a$ . i. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT<sub> $\tau > 1$ </sub> $\langle 1 \rangle$ <sub>||</sub>. 2. Let  $(\lambda \mu - s)/\lambda > a$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle_{\blacktriangle}$ . 3. Let  $\beta < 1$  and s = 0.  $S_8(p.203)$   $\bullet \bullet \circ \bullet$  is true. 4. Let  $\beta < 1$ . i. Let  $a \leq \rho$ .  $S_8(p.203)$   $\bullet$   $\bullet$   $\bullet$   $\bullet$  is true.

ii. Let  $\rho < a$ .

1. Let  $(\lambda \beta \mu - s)/\delta \leq a$ .

i. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT $_{\tau > 1}\langle 1 \rangle$   $\triangle$ .

- Proof Suppose b < 0, hence  $a < b < 0 \cdots (1)$ . Then  $\kappa = -s \cdots (2)$  from Lemma 11.3.1(p.59) (a).
  - (a-c2ii2) The same as Tom 22.2.2(p.204) (a-c2ii2).
- (c3) Let  $\beta < 1$  and s = 0. Assume  $(\lambda \beta \mu s)/\delta \le a$ . Then, since  $\lambda \beta \mu/\delta \le a$ , we have  $\lambda \beta \mu \le \delta a$  due to  $(11.2.2\,(1)\,(\text{p.56})\,)$ , hence  $\lambda \beta \mu \le \delta a \le \lambda a$  due to  $(11.2.2\,(1)\,(\text{p.56})\,)$  and (1), so  $\beta \mu \le a$ , which contradicts [15(p.118)]. Thus, it must be that  $(\lambda \beta \mu s)/\delta > a$ . From this it suffices to consider only (c3i2,c3ii2ii) of Tom 22.2.2(p.204).
- (c4-c4ii2) Let  $\beta < 1$  and s > 0. Then  $\kappa < 0$  due to (2), hence it suffices to consider only (c3i2,c3ii1i2,c3ii1ii2,c3ii2ii) of Tom 22.2.2(p.204).
- $\square$  Nem 22.2.3 ( $\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]^-\}$ ) Suppose b<0. Let  $\beta<1$  or s>0 and let  $\rho=x_K$ .
- (a)  $V_t = x_K = \rho \text{ for } t > 0.$
- (b) Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\beta < 1$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\Delta}$ .
- Proof Suppose  $b < 0 \cdots (1)$ . Then  $\kappa = -s \cdots (2)$  from Lemma 11.3.1(p.59) (a).
  - (a,b) The same as Tom 22.2.3(p.207) (a,b).
- (c) If s=0, then due to (1) it suffices to consider only (c2) of Tom 22.2.3(p.207) and if s>0, then  $\kappa<0$  due to (2), hence it suffices to consider only (c2) of Tom 22.2.3(p.207). Thus, whether s=0 or s>0, we have the same result.
- $\square$  Nem 22.2.4 ( $\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]^-\}$ ) Suppose b<0. Let  $\beta<1$  or s>0 and let  $\rho>x_K$ .
- (a)  $V_t$  is nonincreasing in  $t \geq 0$ , is strictly decreasing in t > 0 if  $\lambda < 1$ , and converges to  $V = x_K$  as to  $t \to \infty$ .
- (b) Let  $\rho < x_L$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle_{A}$ .
- (c) Let  $\rho = x_L$ . Then  $\boxed{\bullet \text{ dOITd}_1\langle 0 \rangle}_{\parallel}$  and  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$  for  $\tau > 1$ .
- (d) Let  $\rho > x_L$ .
  - 1. Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\Delta}$ .
  - 2. Let  $\beta < 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\Delta}$  ( $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{A}$ ).
- Proof Suppose  $b < 0 \cdots (1)$ . Then  $\kappa = -s \cdots (2)$  from Lemma 11.3.1(p.59) (a).
  - (a-d1) The same as Tom 22.2.4(p.207) (a-d1).
- (d2) If s = 0, then due to (1) it suffices to consider only (d2i) of Tom 22.2.4(p.207) and if s > 0, then  $\kappa < 0$  due to (2), hence it suffices to consider only (d2i) of Tom 22.2.4(p.207). Thus, whether s = 0 or s > 0, we have the same result.

# **22.2.5** $\tilde{M}:2[\mathbb{R}][E]$

Due to Lemma 22.2.1(p.202) (a), we see that the following Tom's 22.2.1(p.201) -22.2.4(p.212) can be obtained by applying  $\mathcal{S}_{\mathbb{R}\to\mathbb{R}}$  (see (20.0.1(p.136))) to Tom's 22.2.1(p.203) -22.2.4(p.207) (see Theorem 22.2.1(p.202)).

### 22.2.5.1 Analysis

#### **22.2.5.1.1** Case of $\beta = 1$ and s = 0

- $\square$  Tom 22.2.1 ( $\mathscr{A}\{M:2[\mathbb{R}][E]\}$ ) Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in  $t \geq 0$ .
- (b) Let  $\rho \leq a$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\rho > a$ . Then  $\odot dOITs_{\tau>0}\langle \tau \rangle$ .
- Proof by symmetry Immediate from applying  $\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}$  to Tom 22.2.1(p.203).

### 22.2.5.1.2 Case of $\beta < 1$ or s > 0

- (a)  $V_t$  is nonincreasing in  $t \ge 0$ , is strictly decreasing in  $t \ge 0$  if  $\lambda < 1$  or  $b > \rho$ , and converges to a finite  $V = x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $x_{\tilde{L}} \geq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}$ .
- (c) Let  $\rho > x_{\tilde{L}}$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$ . Below let  $\tau > 1$ .
  - 2. Let  $\beta = 1$ .

    - ii. Let  $\rho \geq b$ .
      - 1. Let  $(\lambda \mu + s)/\lambda \geq b$ .
        - i. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT $_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
        - ii. Let  $\lambda < 1$ . Then S dOITs  $_{\tau > 0} \langle \tau \rangle$ .
      - 2. Let  $(\lambda \mu + s)/\lambda < b$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$
  - 3. Let  $\beta < 1$  and s = 0 (s > 0).

```
i. Let b > \rho.
                 1. Let a \leq 0 (\tilde{\kappa} \leq 0). Then subseteq doing = 0.
                   2. Let a > 0 (\tilde{\kappa} > 0). Then S_8 \bullet \bullet \bullet \bullet is true.
             ii. Let \rho > b.
                  1. Let (\lambda \beta \mu + s)/\delta \geq b.
                       i. Let \lambda = 1.
                           1. Let a < 0 (\tilde{\kappa} < 0). Then subseteq dOITs_{\tau > 1} \langle \tau \rangle.
                           2. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \odot \text{ ndOIT}_{\tau > 1} \langle 1 \rangle_{\Delta}.
                      ii. Let \lambda < 1.
                           1. Let a \leq 0 (\tilde{\kappa} \leq 0). Then subseteq dOITs_{\tau>1}\langle \tau \rangle.
                           2. Let a > 0 (\tilde{\kappa} > 0). Then S_8 \bullet \bullet \bullet \bullet is true.
                  2. Let (\lambda \beta \mu + s)/\delta < b.
                       i. Let a \leq 0 (\tilde{\kappa} \leq 0). Then \boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}.
                      ii. Let a > 0 (\tilde{\kappa} > 0). Then S_8 \bullet \bullet \bullet is true. \Box
ullet Proof by symmetry Immediate from applying \mathcal{S}_{\mathbb{R} 	o \tilde{\mathbb{R}}} to Tom 22.2.2(p.204). \blacksquare
\square Tom 22.2.3 (\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}) Let \beta < 1 or s > 0 and let \rho = x_{\tilde{K}}.
(a) V_t = x_{\tilde{K}} = \rho \text{ for } t \geq 0.
(b) Let \beta = 1. Then \boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\parallel}.
(c) Let \beta < 1 and s = 0 (s > 0).
      1. Let a < 0 (\tilde{\kappa} < 0). Then subseteq dOITs_{\tau>0} \langle \tau \rangle.
      2. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}. \square
ullet Proof by symmetry Immediate from applying \mathcal{S}_{\mathbb{R} 	o \widetilde{\mathbb{R}}} to Tom 22.2.3(p.207).
\square Tom 22.2.4 (\mathscr{A}\{M:2[\mathbb{R}][E]\}) Let \beta < 1 or s > 0 and let \rho < x_{\tilde{K}}.
(a) V_t is nondecreasing in t \geq 0, is strictly increasing in t > 0 if \lambda < 1, and converges to V = x_{\tilde{K}} as to t \to \infty.
(b) Let \rho > x_{\tilde{L}}. Then subseteq dOITs_{\tau>0} \langle \tau \rangle.
(c) Let \rho = x_{\tilde{L}}. Then \bullet dOITd_1\langle 0 \rangle_{\parallel} and \odot dOITs_{\tau>1}\langle \tau \rangle_{\blacktriangle}.
(d) Let \rho < x_{\tilde{L}}.
      1. Let \beta = 1. Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}.
      2. Let \beta < 1 and s = 0 (s > 0).
              i. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \bullet dOITd_{\tau>0}\langle 0 \rangle (\bullet dOITd_{\tau>0}\langle 0 \rangle).
             ii. Let a < 0 (\tilde{\kappa} < 0). Then S_9 \stackrel{\textcircled{\textcircled{$}}_{\triangle}}{\bullet} \stackrel{\bullet}{\bullet} is true. \square
ullet Proof by symmetry Immediate from applying \mathcal{S}_{\mathbb{R} 	o \tilde{\mathbb{R}}} to Tom 22.2.4(p.207). \blacksquare
22.2.5.2 Market Restriction
22.2.5.2.1 Positive Restriction
22.2.5.2.1.1 Case of \beta = 1 and s = 0
\square Pom 22.2.5 (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]^+\}) Suppose a>0. Let \beta=1 and s=0.
(a) V_t is nonincreasing in t \geq 0.
(b) Let \rho \leq a. Then \boxed{\bullet \text{ dOITd}_{\tau>0}\langle 0 \rangle}_{\parallel}.
(c) Let \rho > a. Then \boxed{\$ dOITs_{\tau > 0} \langle \tau \rangle}.
• Proof by diagonal-symmetry Immediate from applying S_{\mathbb{R} \to \tilde{\mathbb{R}}} (see (20.0.1(p.136))) to
Nem 22.2.1(p.210) (see (19.1.21(p.131))).
• Direct proof The same as Tom 22.2.1(p.211) due to Lemma 18.4.4(p.118).
22.2.5.2.1.2 Case of \beta < 1 or s > 0
\square Pom 22.2.6 (\mathscr{A}[\tilde{\mathsf{M}}:2[\mathbb{R}][E]^+]) Suppose a>0. Let \beta<1 or s>0 and let \rho>x_{\tilde{\kappa}}.
(a) V_t is nonincreasing in t \geq 0, is strictly decreasing in t \geq 0 if \lambda < 1 or b \geq \rho, and converges to a finite V = x_{\tilde{K}} as t \to \infty.
(b) Let x_{\tilde{L}} \geq \rho. Then \bullet dOITd_{\tau}\langle 0 \rangle_{\Delta}.
(c) Let \rho > x_{\tilde{L}}.
      1. \boxed{\$ dOITs_1\langle 1 \rangle}_{\blacktriangle}. Below let \tau > 1.
      2. Let \beta = 1.
```

i. Let  $b \geq \rho$ . Then  $| \otimes dOITs_{\tau} \langle \tau \rangle |_{\blacktriangle}$ 

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ii. Let \rho > b.
                 1. Let (\lambda \mu + s)/\lambda \ge b.
                     i. Let \lambda = 1. Then \bigcirc ndOIT_{\tau > 1}\langle 1 \rangle_{\parallel}.
                     ii. Let \lambda < 1. Then subseteq dOITs_{\tau>0} \langle \tau \rangle.
                 2. Let (\lambda \mu + s)/\lambda < b. Then \boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}
      3. Let \beta < 1 and s = 0. Then we have S_8(p.203) \boxed{ \odot \blacktriangle \odot \blacktriangle \odot \blacktriangle \odot \blacktriangle }
      4. Let \beta < 1 and s > 0.
             i. Let b \geq \rho. Then S_8(p.203) \bigcirc A \bigcirc A \bigcirc A is true.
            ii. Let \rho > b.
                 1. Let (\lambda \beta \mu + s)/\delta \geq b.
                     i. Let \lambda = 1. Then \bigcirc ndOIT_{\tau > 1}\langle 1 \rangle \triangle.
                     ullet Proof by diagonal-symmetry Immediate from applying \mathcal{S}_{\mathbb{R} 	o \tilde{\mathbb{R}}} (see (20.0.1(p.136))) to
Nem 22.2.2(p.210) (see (19.1.21(p.131))).
• Direct proof Suppose a > 0 \cdots (1), hence b > a > 0 \cdots (2). Then \tilde{\kappa} = s \cdots (3) from Lemma 13.6.6(p.83) (a).
   (a-c2ii2) The same as Tom 22.2.2(p.211) (a-c2ii2).
   (c3) Let \beta < 1 and s = 0. Assume (\lambda \beta \mu + s)/\delta \ge b. Then, since \lambda \beta \mu/\delta \ge b, we have \lambda \beta \mu \ge \delta b from (11.2.2 (1) (p.56)), hence
\lambda \beta \mu \geq \delta b \geq \lambda b due to (2), so \beta \mu \geq b, which contradicts [3(p.118)]. Thus, it must be that (\lambda \beta \mu + s)/\delta < b. From this it suffices
to consider only (c3i2,c3ii2ii) of Tom 22.2.2(p.211).
   (c4-c4ii2) Let \beta < 1 and s > 0. Then \kappa < 0 due to (2), hence it suffices to consider only
(c3i2,c3ii1i2,c3ii1ii2,c3ii2ii) of Tom 22.2.2(p.204) with \kappa.
\square Pom 22.2.7 (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]^{\top}\}) Suppose a>0. Let \beta<1 or s>0 and let \rho=x_{\tilde{K}}.
(a) V_t = x_{\kappa} = \rho.
(b) Let \beta = 1. Then \bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}.
(c) Let \beta < 1. Then \boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\Delta}.
ullet Proof by diagonal-symmetry Immediate from applying \mathcal{S}_{\mathbb{R} 	o \tilde{\mathbb{R}}} (see (20.0.1(p.136))) to
Nem 22.2.3(p.211) (see (19.1.21(p.131))).
• Direct proof Suppose a > 0 \cdots (1). Then \tilde{\kappa} = s \cdots (2) from Lemma 13.6.6(p.83) (a).
   (a,b) The same as Tom 22.2.3(p.212) (a,b).
   (c) If s=0, then due to (1) it suffices to consider only (c2) of Tom 22.2.3(p.212) and if s>0, then \tilde{\kappa}>0 due to (2), hence it
suffices to consider only (c2) of Tom 22.2.3(p.212) with \tilde{\kappa}. Accordingly, whether s=0 or s>0, we have the same result.
\square Pom 22.2.8 (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]^+\}) Suppose a>0. Let \beta<1 or s>0 and let \rho< x_{\tilde{K}}.
(a) V_t is nondecreasing in t > 0, is strictly increasing in t > 0 if \lambda < 1, and converges to V = x_{\tilde{K}} as to t \to \infty.
(b) Let \rho > x_{\tilde{L}}. Then subseteq dOITs_{\tau>0} \langle \tau \rangle.
(c) \quad Let \; \rho = \; x_{\tilde{L}} \; . \; \; Then \; \boxed{ \bullet \; \mathrm{dOITd}_1\langle 0 \rangle}_{\parallel} \; \; and \; \boxed{ \circledcirc \; \mathrm{dOITs}_{\tau > 1}\langle \tau \rangle}_{\blacktriangle}
(d) Let \rho < x_{\tilde{L}}.
      1. Let \beta = 1. Then \bullet dOITd_{\tau>0}\langle 0 \rangle \triangle.
      2. Let \beta < 1. Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\triangle} (\bullet dOITd_{\tau>0}\langle 0 \rangle_{\blacktriangle}).
• Proof by diagonal-symmetry Immediate from applying S_{\mathbb{R}\to\tilde{\mathbb{R}}} (see (20.0.1(p.136))) to
Nem 22.2.4(p.211) (see (19.1.21(p.131))).
• Direct proof Suppose a > 0 \cdots (1). Then \tilde{\kappa} = s \cdots (2) from Lemma 13.6.6(p.83) (a).
   (a-d1) The same as Tom 22.2.4(p.212) (a-d1).
   (d2) If s = 0, due to (1) it suffices to consider only (d2i) of Tom 22.2.4(p.212) and if s > 0, then \tilde{\kappa} > 0 due to (2), hence it
suffices to consider only (d2i) of Tom 22.2.4(p.212) (d2i) with \tilde{\kappa}. Accordingly, whether s=0 or s>0, we have the same result.
                                                                   The diagonal symmetry holds between \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]^+\} and \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]^-\}, i.e.,
Remark 22.2.2 (diagonal symmetry)
                                                                       \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]^+\}\ \mathsf{d}-\sim \mathscr{A}\{\mathsf{M}:1[\mathbb{R}][\mathsf{E}]^-\}.
In fact it can be confirmed that the following relations hold:
                                                 \mathcal{A}\{\text{Pom } 22.2.5(\text{p.212})\}
                                                                                         = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}} [\mathscr{A} \{ \text{Nem } 22.2.1 (p.210) \}] \cdots (1),
                                                 \mathcal{A}\{\text{Pom } 22.2.6(p.212)\}
                                                                                         =\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[\mathscr{A}\{\text{Nem }22.2.2(p.210)}\}]\cdots(2),
                                                 \mathcal{A}\{\text{Pom } 22.2.7(\text{p.213})\}
                                                                                         =\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathscr{A}\{\text{Nem } 22.2.3(\text{p.211})\}] \cdots (3),
                                                                                         =\mathcal{S}_{\mathbb{R}	o	ilde{\mathbb{R}}}[\mathscr{A}\{	ext{Nem }22.2.4	ext{(p.211)}\}] \cdots (4). \square
                                                 \mathcal{A}\{\text{Pom } 22.2.8(\text{p.213})\}
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#### 22.2.5.2.2 Mixed Restriction

Omitted.

#### 22.2.5.2.3 Negative Restriction

Unnecessary.

## **22.2.6** M:2[ $\mathbb{P}$ ][ $\mathbb{E}$ ]

#### 22.2.6.1 Preliminary

From (7.4.33(p.41)) and from (6.1.21(p.26)) and (6.1.20(p.26)) we have

$$V_t - \beta V_{t-1} = K(V_{t-1}) + (1 - \beta)V_{t-1} = L(V_{t-1}), \quad t > 1.$$
(22.2.30)

From (7.4.32(p.41)) we have

$$V_1 - \beta V_0 = V_1 - \beta \rho = \lambda \beta \max\{0, a - \rho\} - s. \tag{22.2.31}$$

## 22.2.6.2 Analysis

#### **22.2.6.2.1** Case of $\beta = 1$ and s = 0

Let  $\beta = 1$  and s = 0. Then, from (22.2.30(p.214)) and (6.1.20(p.26)) we have

$$V_t - \beta V_{t-1} = \lambda T(V_{t-1}) \ge 0, \quad t > 1,$$
 (22.2.32)

due to Lemma 14.2.1(p.93) (g). From (7.4.32(p.41)) we have

$$V_1 = \lambda \max\{0, a - \rho\} + \rho \tag{22.2.33}$$

$$= \max\{\rho, \lambda a + (1 - \lambda)\rho\}. \tag{22.2.34}$$

#### **22.2.6.2.1.1** Case of $\rho < a^*$

In this case, Theorem 22.2.2(p.202) holds due to Lemma 22.2.1(p.202) (c). Hence, Proposition 22.2.1 below can be derived by applying  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  (see (20.0.5(p.136))) to Tom 22.2.1(p.203).

**Proposition 22.2.1** ( $\rho \le a^*$ ) Assume  $\rho \le a^*$ . Let  $\beta = 1$  and s = 0.

- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b)  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$ .  $\square$
- Proof by analogy Assume  $\rho \leq a^*$ . Let  $\beta = 1$  and s = 0.
  - (a) The same as Tom 22.2.1(p.203) (a).
- (b) Since (b,c) of Tom 22.2.1(p.203) have none of a and  $\mu$ , even if  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  is applied the two assertions, no change occurs (see Lemma 14.6.1(p.99)). However, since  $\rho \leq a^* < a < b$  due to the assumption  $\rho \leq a^*$  and Lemma 14.2.1(p.93) (n), it follows that only (c) of Tom 22.2.1(p.203) holds.

#### **22.2.6.2.1.2** Case of $b \leq \rho$

In this case, Theorem 22.2.2(p.202) holds due to Lemma 22.2.1(p.202) (c). Hence, Proposition 22.2.2 below can be derived by applying  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  (see (20.0.5(p.136))) to Tom 22.2.1(p.203).

**Proposition 22.2.2**  $(b \le \rho)$  Assume  $b \le \rho$ . Let  $\beta = 1$  and s = 0.

- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b)  $\bullet dOITd_{\tau>0}\langle 0\rangle_{\parallel}$ .  $\square$
- Proof by analogy Assume  $b \le \rho$ . Let  $\beta = 1$  and s = 0.
  - (a) The same as Tom 22.2.1(p.203) (a).
  - (b) Due to the assumption  $b \leq \rho$ , only (b) of Tom 22.2.1(p.203) holds.

#### **22.2.6.2.1.3** Case of $a^* < \rho < b$

In this case, Theorem 22.2.2(p.202) does not always hold due to Lemma 22.2.1(p.202) (d). Hence, Proposition 22.2.3 below must be directly proven.

**Proposition 22.2.3**  $(a^* < \rho < b)$  Assume  $a^* < \rho < b$ . Let  $\beta = 1$  and s = 0.

- (a)  $V_t$  is nondecreasing in t > 0.
- (b) Let  $a \leq \rho$ . Then  $\boxed{\bullet \text{ dOITd}_1\langle 0 \rangle}$  and  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}$ .
- (c) Let  $\rho < a$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle$ .

• Proof Assume  $a^* < \rho < b \cdots$  (1) and let  $\beta = 1$  and s = 0. Then  $L(x) = K(x) = \lambda T(x) \ge 0 \cdots$  (2) for any x from (6.1.20(p.26)) and (6.1.21(p.26)) and from Lemma 14.2.1(p.33) (g). Since  $V_0 < b$  from (1) and (7.4.31(p.41)), we have  $L(V_0) = \lambda T(V_0) = \lambda T(\rho) > 0 \cdots$  (3) from (2) and Lemma 14.2.1(p.33) (g). Then, since  $\rho < b$  and a < b, from (22.2.34(p.214)) we obtain  $V_1 < \max\{b, \lambda b + (1-\lambda)b\} = \max\{b, b\} = b$ . Suppose  $V_{t-1} < b$ . Then, since  $a^* < b$  from (1), we have  $V_t < K(b) + b$  from (7.4.33(p.41)) and Lemma 14.2.3(p.36) (h), hence  $V_t < \beta b - s$  from (14.2.12(2)(p.35)), so  $V_{t-1} < b$  due to the assumption " $\beta = 1$  and s = 0". Accordingly, by induction  $V_{t-1} < b$  for t > 1, hence  $T(V_{t-1}) > 0 \cdots$  (4) for t > 1 from Lemma 14.2.1(p.33) (g). Thus  $V_t - \beta V_{t-1} > 0$  for t > 1 from (22.2.32(p.214)) or equivalently  $V_t > \beta V_{t-1}$  for t > 1. Then, since  $V_t > \beta V_{t-1}$  for  $\tau \ge t > 1$ , we have

$$V_{\tau} > \beta V_{\tau-1} > \beta^2 V_{\tau-2} > \dots > \beta^{\tau-1} V_1 \cdots (5), \qquad \tau > 1.$$

In addition, from (2) we have  $L(V_{t-1}) = \lambda T(V_{t-1}) > 0 \cdots$  (6) for t > 1 due to (4), so  $L(V_{t-1}) > 0$  for t > 0 due to (3).

- (a) From (22.2.33(p.214)) and (7.4.31(p.41)) we have  $V_1 V_0 = V_1 \rho = \lambda \max\{0, a \rho\} \ge 0$ , hence  $V_1 \ge V_0 \cdots$  (7). From (7.4.33(p.41)) with t = 2 we have  $V_2 V_1 = K(V_1) > 0$  due to (6) with t = 2, hence  $V_2 > V_1$ , so  $V_2 \ge V_1 \cdots$  (8). Suppose  $V_t \ge V_{t-1}$ . Then from (7.4.33(p.41)) and Lemma 14.2.3(p.96) (e) we have  $V_{t+1} = K(V_t) + V_t \ge K(V_{t-1}) + V_{t-1} = V_t$ . Hence, by induction  $V_t \ge V_{t-1}$  for t > 1. From this and (7) we have  $V_t \ge V_{t-1}$  for t > 0, hence it follows that  $V_t$  is nondecreasing in  $t \ge 0$ .
- (b) Let  $a \leq \rho$ , hence  $V_1 = \lambda \max\{0, a \rho\} + \rho = \rho$  from (7.4.32(p.41)), so  $V_1 < b$  due to (1). Then, since  $V_1 \beta V_0 = V_1 V_0 = \rho \rho = 0$ , we have  $V_1 = \beta V_0 \cdots$  (9), hence  $t_1^* = 0$ , i.e.,  $\bullet$  dOITd<sub>1</sub>(0)<sub>||</sub>. Below let  $\tau > 1$ . Then, from (5) and (9) we have

$$|V_{\tau}| > \beta V_{\tau-1} > \beta^2 V_{\tau-2} > \dots > \beta^{\tau-1} V_1 = \beta^{\tau} V_0,$$

hence  $t_{\tau}^* = \tau$  for  $\tau > 1$ , i.e.,  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$ .

(c) Let  $\rho < a$ . Then, since  $V_1 = \lambda(a - \rho) + \rho$  due to (7.4.32(p.41)), we have  $V_1 - \beta V_0 = V_1 - V_0 = V_1 - \rho = \lambda(a - \rho) > 0$ , i.e.,  $V_1 > \beta V_0$ , hence  $t_1^* = 1 \cdots$  (10). Let  $\tau > 1$ . Then, from (5) we have

$$|V_{\tau}| > \beta V_{\tau-1} > \beta^2 V_{\tau-2} > \dots > \beta^{\tau-1} V_1 > \beta^{\tau} V_0, \qquad \tau > 1,$$

hence  $t_{\tau}^* = \tau$  for  $\tau > 1$ , hence  $\boxed{\$ \text{ dOITs}_{\tau > 1}\langle \tau \rangle}_{\blacktriangle}$ . From this and (10) we have  $t_{\tau}^* = \tau$  for  $\tau > 0$ , i.e.,  $\boxed{\$ \text{ dOITs}_{\tau > 0}\langle \tau \rangle}_{\blacktriangle}$ .

#### **22.2.6.2.1.4** Integration of Propositions 22.2.1(p.214) -22.2.3(p.214)

**Lemma 22.2.2** ( $\mathscr{A}\{M:2[\mathbb{P}][E]\}\)$  Let  $\beta = 1$  and s = 0.

- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\rho \leq a^{\star}$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle$ .
- (c) Let  $b \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (d) Let  $a^* < \rho < b$ .
  - 1. Let  $a \leq \rho$ . Then  $\bullet dOITd_1\langle 0 \rangle_{\parallel}$  and  $\odot dOITs_{\tau>1}\langle \tau \rangle_{\blacktriangle}$ .
  - $2. \quad Let \ \rho < a. \ Then \ \boxed{\$ \ dOITs_{\tau>0} \langle \tau \rangle}_\blacktriangle. \quad \Box$
- *Proof* (a) The same as Propositions 22.2.1(p.214) (a), 22.2.2(p.214) (a), and 22.2.3(p.214) (a).
  - (b) The same as Proposition 22.2.1(p.214) (b).
  - (c) The same as Proposition 22.2.2(p.214) (b).
  - (d-d2) The same as Proposition 22.2.3(p.214) (b,c).  $\blacksquare$

Corollary 22.2.3 (M:2[ $\mathbb{P}$ ][ $\mathbb{E}$ ]) Let  $\beta = 1$  and s = 0. Then,  $z_t$  is nondecreasing in  $t \geq 0$ .  $\square$ 

 $\bullet$  *Proof* Immediate from Lemma 22.2.2(p.215) (a) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89).

#### 22.2.6.2.2 Case of $\beta < 1$ or s > 0

#### **22.2.6.2.2.1** Case of $\rho \le a^*$

In this case, Theorem 22.2.2(p.202) holds due to Lemma 22.2.1(p.202) (c), hence Tom's 22.2.5(p.215)-22.2.7(p.216) below can be derived by applying  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  (see (20.0.5(p.136))) to Tom's 22.2.2(p.204)-22.2.4(p.207). In the proofs below, let us represent what results from applying  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  to a given Tom by Tom' (see (22.1.60(p.176))).

- (a)  $V_t$  is nondecreasing in  $t \geq 0$ , is strictly increasing in  $t \geq 0$  if  $\lambda < 1$ , and converges to a finite  $V = x_K$  as  $t \to \infty$ .
- (b) Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle |_{\Delta}$ .
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$ . Below let  $\tau > 1$ .
  - 2. Let  $\beta = 1$ .
    - i. Let  $(\lambda a s)/\lambda \le a^*$ .
      - 1. Let  $\lambda = 1$ . Then  $\bigcirc$   $ndOIT_{\tau > 1}\langle 1 \rangle$

```
ii. Let (\lambda a - s)/\lambda > a^*. Then \boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}
3. Let \beta < 1 and s = 0 (s > 0).
     i. Let (\lambda \beta a - s)/\delta \leq a^*.
```

1. Let  $\lambda = 1$ .

i. Let b>0 ( $\kappa>0$ ). Then  $\boxed{\$ dOITs_{\tau>1}\langle \tau\rangle}_{\blacktriangle}$ .

ii. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $\bigcirc$  ndOIT<sub> $\tau > 1$ </sub> $\langle 1 \rangle$ <sub> $\Delta$ </sub>.

2. Let  $\lambda < 1$ .

i. Let  $b \geq 0$  ( $\kappa \geq 0$ ). Then  $subseteq dOITs_{\tau>1}\langle \tau \rangle$ .

ii. Let b < 0 ( $\kappa < 0$ ). Then  $S_8$   $\circ$   $\circ$   $\circ$   $\circ$   $\circ$   $\circ$  is true.

ii. Let  $(\lambda \beta a - s)/\delta > a^*$ .

1. Let  $b \geq 0$  ( $\kappa \geq 0$ ). Then  $\odot$  dOITs $_{\tau>0}\langle \tau \rangle$ 

2. Let b < 0 ( $\kappa < 0$ ). Then  $S_8$   $\bullet$   $\bullet$   $\bullet$   $\bullet$  is true.  $\Box$ 

ullet Proof by analogy Consider the Tom' resulting from applying  $\mathcal{A}_{\mathbb{R} \to \mathbb{P}}$  to Tom 22.2.2 (p.204). Then " $a < \rho$ " in Tom 22.2.2(p.20)(c2i,c3i) changes into " $a^* < \rho$ " in the Tom', which contradicts the assumption  $\rho \le a^*$ . Accordingly, removing all assertions with " $a^* < \rho$ " from the Tom' leads to Tom 22.2.5 above.

Corollary 22.2.4 (M:2[ $\mathbb{P}$ ][ $\mathbb{E}$ ]) Assume  $\rho \leq a^*$ . Let  $\beta < 1$  or s > 0 and let  $\rho < x_K$ . Then,  $z_t$  is nondecreasing in  $t \geq 0$ .  $\square$ 

• Proof Immediate from Tom 22.2.5(p.215) (a) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89).

 $\square$  Tom 22.2.6 ( $\mathscr{A}\{M:2[\mathbb{P}[E]\}\}$ ) Assume  $\rho \leq a^*$ . Let  $\beta < 1$  or s > 0 and let  $\rho = x_K$ .

- (a)  $V_t = x_K = \rho \text{ for } t \geq 0.$
- (b) Let  $\beta = 1$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\parallel}$ .
- (c) Let  $\beta < 1$  and s = 0 ((s > 0)).
  - 1. Let b > 0 ( $\kappa > 0$ ). Then  $\boxed{\$ dOITs_{\tau > 0} \langle \tau \rangle}$ .
  - 2. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle$ .
- Proof by analogy The same as Tom 22.2.3(p.207) due to Lemma 14.6.1(p.99).

Corollary 22.2.5 (M:2[P][E]) Assume  $\rho \leq a^*$ . Let  $\beta < 1$  or s > 0 and let  $\rho = x_K$ . Then, the optimal price to propose is given by  $z_t = z(\rho)$  for  $t \geq 0$ .  $\square$ 

• Proof Immediate from Tom 22.2.6(p.216) (a) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89).

 $\square$  Tom 22.2.7 ( $\mathscr{A}\{M:2[\mathbb{P}][E]\}$ ) Assume  $\rho \leq a^*$ . Let  $\beta < 1$  or s > 0 and let  $\rho > x_K$ .

- (a)  $V_t$  is nonincreasing in  $t \geq 0$ , is strictly decreasing in t > 0 if  $\lambda < 1$ , and converges to  $V = x_K$  as to  $t \to \infty$ .
- (b) Let  $\rho < x_L$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle$ .
- (c) Let  $\rho = x_L$ . Then  $\bullet dOITd_1\langle 0 \rangle \land and \circ dOITs_{\tau>1}\langle \tau \rangle \land A$ .
- (d) Let  $\rho > x_L$ .
  - 1. Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\Delta}$ .
  - 2. Let  $\beta < 1$  and s = 0 ((s > 0)).
    - i. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle$  ( $\bullet dOITd_{\tau>0}\langle 0 \rangle$ ).
    - ii. Let b > 0 ( $\kappa > 0$ ). Then  $S_9$   $\bullet \triangle$   $\bullet \triangle$  is true.  $\square$
- Proof by analogy The same as Tom 22.2.4(p.207) due to Lemma 14.6.1(p.99).

Corollary 22.2.6 (M:2[P][E]) Assume  $\rho \leq a^*$ . Let  $\beta < 1$  or s > 0 and let  $\rho > x_K$ . Then, the optimal price to propose  $z_t$  is nonincreasing in  $t \geq 0$ .  $\square$ 

ullet Proof Immediate from Tom 22.2.7(p.216) (a) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89).

## **22.2.6.2.2.2** Case of $b \le \rho$

In this case, Theorem 22.2.2(p.202) holds due to Lemma 22.2.1(p.202) (c). Hence Tom's 22.2.8-22.2.10 below can be derived by applying  $\mathcal{A}_{\,\mathbb{R}\to\mathbb{P}}$  to Tom's 22.2.2 (p.204) -- 22.2.4 (p.207) .

 $\square$  Tom 22.2.8 ( $\mathscr{A}\{M:2[\mathbb{P}][E]\}$ ) Assume  $b \leq \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho < x_K$ .

- (a)  $V_t$  is nondecreasing in  $t \geq 0$ , is strictly increasing in  $t \geq 0$  if  $\lambda < 1$ , and converges to a finite  $V = x_K$  as  $t \to \infty$ .
- (b) Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}$ .
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$ . Below let  $\tau > 1$ .

```
2. Let \beta = 1. Then \boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}.
```

3. Let  $\beta < 1$  and s = 0 (s > 0).

i. Let 
$$b \geq 0$$
 ( $\kappa \geq 0$ ). Then  $\odot$  dOITs $_{\tau>1}\langle \tau \rangle$ 

ii. Let 
$$b<0$$
 (( $\kappa<0$ )). Then  $\mathbf{S}_8$  (S) (O) (O)  $\Delta$  is true.  $\Box$ 

• Proof by analogy Consider the Tom' resulting from applying  $\mathcal{A}_{\mathbb{R}\to\mathbb{P}}$  to Tom 22.2.2(p.204). Then " $\rho \leq a$ " in (c2ii,c3ii) of Tom 22.2.2(p.204) changes into " $\rho \leq a^*$ " in the Tom', hence  $\rho \leq a^* < a < b$  due to Lemma 14.2.1(p.93) (n), which contradicts the assumption  $b \leq \rho$ . Accordingly, removing all assertions with " $\rho \leq a$ " from the Tom' leads to Tom 22.2.8 above. ■

Corollary 22.2.7 (M:2[ $\mathbb{P}$ ][ $\mathbb{E}$ ] ) Assume  $b \leq \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho < x_K$ . Then, the optimal price to propose  $z_t$  is nondecreasing in  $t \geq 0$ .  $\square$ 

- *Proof* Immediate from Tom 22.2.8(p.216) (a) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89). ■
- $\square$  Tom 22.2.9 ( $\mathscr{A}\{M:2[\mathbb{P}][E]\}$ ) Assume  $b \leq \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho = x_K$ .
- (a)  $V_t = x_K = \rho \text{ for } t \geq 0.$
- (b) Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\beta < 1$  and s = 0 (s > 0).
  - 1. Let  $b \ge 0$  ( $\kappa \ge 0$ ). Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$ .
  - 2. Let b < 0 ( $\kappa < 0$ ). Then  $\boxed{\bullet dOITd_{\tau > 0}\langle 0 \rangle}$ .
- Proof by analogy The same as Tom 22.2.3(p.207) due to Lemma 14.6.1(p.99).

Corollary 22.2.8 (M:2[P][E]) Assume  $b \le \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho = x_K$ . Then, the optimal price to propose is given by  $z_t = z(\rho)$  for  $t \ge 0$ .  $\square$ 

- Proof Immediate from Tom 22.2.9(p.217) (a) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89).
- $\square$  Tom 22.2.10 ( $\mathscr{A}\{M:2[\mathbb{P}][E]\}$ ) Assume  $b \leq \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho > x_K$ .
- (a)  $V_t$  is nonincreasing in  $t \geq 0$ , is strictly decreasing in t > 0 if  $\lambda < 1$ , and converges to  $V = x_K$  as to  $t \to \infty$ .
- (b) Let  $\rho = x_L$ . Then  $\bullet dOITd_1\langle 0 \rangle_{\triangle}$  and  $\odot dOITs_{\tau>1}\langle \tau \rangle_{\blacktriangle}$ .
- (c) Let  $\rho > x_L$ .
  - 1. Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle$   $\triangle$ .
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle$  ( $\bullet dOITd_{\tau>0}\langle 0 \rangle$ ).
    - ii. Let b > 0 ( $\kappa > 0$ ). Then  $S_9$   $\bigcirc$   $\bigcirc$   $\bigcirc$  is true.  $\square$
- Proof by analogy Assume  $b \le \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho > x_K$ . In this case, even if  $\mathcal{A}_{\mathbb{R} \to \mathbb{P}}$  is applied to Tom 22.2.4(p.207), it can be easily confirmed that no change occurs (see Lemma 14.6.1(p.99)). However, if the condition  $\rho < x_L$  is added, we encounter the following contradiction. Then we have  $b \le \rho < x_L \cdots$  (1). Now, since  $0 = L(x_L) = \lambda \beta T(x_L) s$  and  $T(x_L) = 0$  from Lemma 14.2.1(p.93) (g), we have 0 = -s, hence s = 0, so we have  $x_L = b$  due to Lemma 14.2.2(p.96) (d), which is a contradicts (1). Accordingly, the condition  $\rho < x_L$  becomes impossible. This result implies that the assertion (b) with  $\rho \ge x_L$  in Tom 22.2.4(p.207) must be omitted; accordingly, it follows that we have Tom 22.2.10 above. ■

Corollary 22.2.9 (M:2[P][E] ) Assume  $b \le \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho > x_K$ . Then, the optimal price to propose  $z_t$  is nonincreasing in  $t \ge 0$ .  $\square$ 

• Proof Immediate from Tom 22.2.10(p.217) (a) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89).

#### 22.2.6.2.2.3 Case of $a^* < \rho < b$

In this case, Theorem 22.2.2(p.202) does not always hold due to Lemma 22.2.1(p.202) (d). Hence, Tom 22.2.5(p.218) below must be directly proven. For explanatory convenience, let us define:

$$\mathbf{S}_{10} \overset{\textcircled{\otimes}\vartriangle}{\bullet} \overset{\bullet}\vartriangle = \begin{cases} \text{We have:} \\ (1) \text{ Let } \lambda \max\{0, a - \rho\} < s. \text{ Then } \overset{\textcircled{\otimes}}\bullet \mathtt{dOITs}_{\tau > 1} \langle \tau \rangle \vartriangle_\vartriangle \text{ or } \bullet \mathtt{dOITd}_{\tau > 0} \langle 0 \rangle \vartriangle_\vartriangle. \end{cases}$$

$$(2) \text{ Let } \lambda \max\{0, a - \rho\} \geq s. \text{ Then } \overset{\textcircled{\otimes}}\bullet \mathtt{dOITs}_{\tau > 1} \langle \tau \rangle \vartriangle_\vartriangle.$$

$$\mathbf{S}_{11} \overset{\textcircled{\otimes}\vartriangle}{\bullet} \overset{\textcircled{\otimes}\blacktriangle} \overset{\textcircled{\otimes}\clubsuit} \overset{\textcircled{\bigstar}\bigstar} \overset{$$

$$\mathbf{S}_{12} \begin{tabular}{lll} \textbf{There exists } t^\bullet_{\tau} > 1 \text{ such that:} \\ (1) & \text{If } \lambda\beta \max\{0, a - \rho\} < s, \text{ then} \\ & \text{i.} & \bullet \text{dOITd}_{t^\bullet_{\tau} \geq \tau > 0}\langle 0 \rangle_{\blacktriangle}, \\ & \text{ii.} & \bullet \text{dOITs}_{\tau > t^\bullet_{\tau}}\langle \tau \rangle_{\vartriangle} \text{ or } \bullet \text{dOITd}_{\tau > t^\bullet_{\tau}}\langle 0 \rangle_{\vartriangle}. \\ (2) & \text{If } \lambda\beta \max\{0, a - \rho\} \geq s, \text{ then} \\ & \text{i.} & \bullet \text{ndOIT}_{t^\bullet_{\tau} \geq \tau > 1}\langle 1 \rangle_{\parallel}, \\ & \text{ii.} & \bullet \text{dOITs}_{\tau > t^\bullet_{\tau}}\langle \tau \rangle_{\blacktriangle}. \\ \end{tabular}$$

For convenience of reference, below let us copy  $(7.4.\overline{32}_{(p.41)})$ 

$$V_1 = \lambda \beta \max\{0, a - \rho\} + \beta \rho - s. \tag{22.2.35}$$

 $\blacksquare \ \text{Tom 22.2.5 } \left( \mathscr{A} \{ \mathsf{M} : 2[\mathbb{P}][\mathsf{E}] \} \right) \quad \textit{Assume } \ a^\star < \rho < b. \ \textit{Let } \beta < 1 \ \textit{or } s > 0.$ 

- (a) If  $\lambda\beta \max\{0, a-\rho\} \leq s$ , then  $\boxed{\bullet \text{ dOITd}_1\langle 0 \rangle}_{\vartriangle}$ , or else  $\boxed{\$ \text{ dOITs}_1\langle 1 \rangle}_{\blacktriangle}$ . Below let  $\tau > 1$ .
- (b) Let  $V_1 \leq x_K$ .
  - 1.  $V_t$  is nondecreasing in t > 0 and converges to a finite  $V = x_K$  as  $t \to \infty$ .
  - 2. Let  $V_1 \geq x_L$ . If  $\lambda \beta \max\{0, a \rho\} \leq s$ , then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 0 \rangle}_{\Delta}$ , or else  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\Delta}$ .
  - 3. Let  $V_1 < x_L$ .
    - i. Let  $\beta = 1$ . Then  $S_{10}$   $\bigcirc$   $\bigcirc$  is true.
    - ii. Let  $\beta < 1$  and s = 0 (s > 0).
      - 1. Let b > 0 ( $\kappa > 0$ ). Then  $S_{10}$   $\bigcirc$   $\bigcirc$  is true.
      - 2. Let b=0 ( $\kappa=0$ ). If  $\lambda\beta \max\{0,a-\rho\} < s$ , then  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\vartriangle}$  or  $\boxed{\bullet dOITd_{\tau>1}\langle 0 \rangle}_{\vartriangle}$ , or else  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\vartriangle}$ .
      - 3. Let b < 0 ( $\kappa < 0$ ). Then  $S_{11}$   $\stackrel{\textcircled{S}_{\triangle}}{\otimes}$   $\stackrel{\textcircled{S}_{\blacktriangle}}{\otimes}$   $\stackrel{\textcircled{O}_{\triangle}}{\circ}$  is true.
- (c) Let  $V_1 > x_K$ .
  - 1.  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V = x_K$  as  $t \to \infty$ .
  - 2. Let  $\beta = 1$ . If  $\lambda \max\{0, a \rho\} < s$ , then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 0 \rangle}_{\blacktriangle}$ , or else  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\vartriangle}$ .  $\mapsto$
  - 3. Let  $\beta < 1$  and s = 0 ((s > 0)).
    - i. Let  $b > 0 ((\kappa > 0))$ .
      - 1. Let  $V_1 < x_L$ . Then  $S_{10}$   $\bigcirc$   $\bigcirc$  is true.
      - 2. Let  $V_1 = x_L$ . Then  $S_{12}$   $S_{\Delta} S_{\Delta} S_{\Delta}$
    - ii. Let  $b \leq 0$  ( $\kappa \leq 0$ ). If  $\lambda \beta \max\{0, a \rho\} \leq s$ , then  $\bullet \text{dOITd}_{\tau > 1}\langle 0 \rangle$  , or else  $\bullet \text{dOIT}_{\tau > 1}\langle 1 \rangle$ .
- Proof Assume  $a^* < \rho < b \cdots$  (1) and let  $\beta < 1$  or s > 0.
- (a) If  $\lambda\beta \max\{0, a \rho\} \leq s$ , then  $V_1 \leq \beta V_0$  from (22.2.31(p214)) or equivalently  $V_1 \leq \beta V_0 \cdots (2)$ , hence  $t_1^* = 0$ , i.e.,  $\boxed{\bullet \text{dOITd}_1\langle 0 \rangle}_{\vartriangle} \cdots (3)$ , or else  $\boxed{V_1 > \beta V_0 \cdots (4)}$ , hence  $t_1^* = 1$ , i.e.,  $\boxed{\$ \text{dOITs}_1\langle 1 \rangle}_{\blacktriangle} \cdots (5)$ . Below let  $\tau > 1$ .
  - (b) Let  $V_1 \leq x_K \cdots$  (6), hence  $K(V_1) \geq 0 \cdots$  (7) from Lemma 14.2.3(p.96) (j1).
- (b2) Let  $V_1 \ge x_L$ . Then, since  $x_L \le V_{t-1}$  for t > 1 due to (b1), we have  $L(V_{t-1}) \le 0$  for t > 1 from Corollary 14.2.1(p.96) (a), thus  $L(V_{t-1}) \le 0$  for  $\tau \ge t > 1$ . Accordingly, since  $V_t \le \beta V_{t-1}$  for  $\tau \ge t > 1$  from (22.2.30(p.214)), we have

$$V_{\tau} \leq \beta V_{\tau-1} \leq \cdots \leq \beta^{\tau-1} V_1 \cdots (9), \qquad \tau > 1.$$

(1) Let  $\lambda\beta \max\{0, a-\rho\} \leq s$ . Then, from (2) and (9) we have

$$V_{\tau} \leq \beta V_{\tau-1} \leq \beta^2 V_{\tau-2} \leq \cdots \leq \beta^{\tau-1} V_1 \leq \beta^{\tau} V_0$$

hence  $t_{\tau}^* = 0$  for  $\tau > 1$ , i.e.,  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 0 \rangle}_{\Delta}$ .

(2) Let  $\lambda\beta \max\{0, a-\rho\} > s$ . Then, from (4) and (9) we have

$$V_{\tau} \leq \beta V_{\tau-1} \leq \beta^2 V_{\tau-2} \leq \dots \leq \beta^{\tau-1} V_1 > \beta^{\tau} V_0$$

hence  $t_{\tau}^* = 1$  for  $\tau > 1$ , i.e.,  $\boxed{\bigcirc \text{ndOIT}_{\tau > 1}\langle 1 \rangle}_{\triangle}$ .

- (b3) Let  $V_1 < x_L \cdots (10)$ .
- (b3i) Let  $\beta = 1 \cdots$  (11), hence s > 0 due to the assumption " $\beta < 1$  or s > 0". Then  $x_L = x_K \cdots$  (12) from Lemma 14.2.4(p.97) (b), hence  $V_{t-1} \leq x_L$  for t > 1 due to (8). Accordingly, since  $V_{t-1} \leq x_L$  for  $\tau \geq t > 1$ , we have  $L(V_{t-1}) \geq 0$  for  $\tau \geq t > 1$  from Lemma 14.2.2(p.96) (e1), hence  $V_t \geq \beta V_{t-1}$  for  $\tau \geq t > 1$  from (22.2.30(p.214)), so

$$V_{\tau} \ge \beta V_{\tau-1} \ge \beta^2 V_{\tau-2} \ge \cdots \ge \beta^{\tau-1} V_1 \cdots (13), \quad \tau > 1.$$

(A) Let  $\lambda \max\{0, a - \rho\} < s$ , hence  $\lambda \beta \max\{0, a - \rho\} < s$  due to (11). Then  $V_1 - \beta V_0 < 0 \cdots (14)$  from (22.2.31(p.214)) or equivalently  $V_1 < \beta V_0 \cdots (15)$ . Hence, from (13) we have

$$|V_{\tau}| \ge \beta V_{\tau-1} \ge \beta^2 V_{\tau-2} \ge \cdots \ge \beta^{\tau-1} V_1 < \beta^{\tau} V_0 \cdots (16), \quad \tau > 1.$$

Thus, we have  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\triangle}$  or  $\boxed{\bullet dOITd_{\tau>0}\langle 0 \rangle}_{\triangle}$ , hence (1) of  $S_{10}$  is true.

(B) Let  $\lambda \max\{0, a - \rho\} \ge s$ , hence  $\lambda \beta \max\{0, a - \rho\} \ge s$  due to (11). Then  $V_1 - \beta V_0 \ge 0$  from (22.2.31(p.214)) or equivalently  $V_1 \ge \beta V_0$  from (22.2.31(p.214)). Then, from (13) we have

$$|V_{\tau}| \ge \beta V_{\tau-1} \ge \beta^2 V_{\tau-2} \ge \dots \ge \beta^{\tau-1} V_1 \ge \beta^{\tau} V_0,$$

hence  $t_{\tau}^* = \tau$  for  $\tau > 1$ , i.e.,  $\boxed{\$ \text{ dOITs}_{\tau > 1}\langle \tau \rangle}_{\vartriangle}$ , thus (2) of  $S_{10}$  holds.

(b3ii) Let  $\beta < 1 \cdots (17)$  and s = 0 (s > 0).

(b3ii1) Let b > 0 (( $\kappa > 0$ )). Then  $x_L > x_K > 0 \cdots$  (18) from Lemma 14.2.4(p.97) (c (d)). Accordingly, from (8) we have  $V_{t-1} \le x_K < x_L$  for t > 1, hence  $L(V_{t-1}) > 0$  for t > 1 from Corollary 14.2.1(p.96) (a), thus  $L(V_{t-1}) > 0$  for  $\tau \ge t > 1$ . Accordingly, since  $V_t > \beta V_{t-1}$  for  $\tau \ge t > 1$  from (22.2.30(p.214)), we have

$$V_{\tau} > \beta V_{\tau-1} > \dots > \beta^{\tau-1} V_1 \dots (19) \quad \tau > 1.$$

- (1) Let  $\lambda \beta \max\{0, a \rho\} < s$ . Then for the same reason as in (A) we have (1) of  $S_{10}$ .
- (2) Let  $\lambda\beta \max\{0, a-\rho\} \geq s$ . Then for the same reason as in (B) we have (2) of  $S_{10}$ .

(b3ii2) Let b=0 ( $\kappa=0$ ). Then  $x_L=x_K$  from Lemma 14.2.4(p.97) (c (d)). Accordingly, from (6) and (b1) we have  $V_{t-1} \leq x_K$  for t>1, hence  $V_{t-1} \leq x_K=x_L$  for  $\tau \geq t>1$ . Therefore, from Corollary 14.2.1(p.96) (b) we have  $L(V_{t-1}) \geq 0 \cdots$  (20) for  $\tau \geq t>1$ , hence  $V_t-\beta V_{t-1} \geq 0$  for  $\tau \geq t>1$  from (22.2.30(p.214)) or equivalently  $V_t \geq \beta V_{t-1}$  for  $\tau \geq t>1$ , leading to

$$V_t > \beta V_{t-1} > \dots > \beta^{t-1} V_1.$$

(1) Let  $\lambda\beta \max\{0, a-\rho\} \leq s$ . Then, since  $V_1 \leq \beta V_0$  from (22.2.31(p.214)), we have

$$|V_{\tau}| > \beta V_{\tau-1} > \beta^2 V_{\tau-2} > \dots > \beta^{\tau-1} V_1 < \beta^{\tau} V_0$$

hence  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\vartriangle}$  or  $\boxed{\bullet dOITd_{\tau>1}\langle 0 \rangle}_{\vartriangle}$ .

(2) Let  $\lambda\beta \max\{0, a-\rho\} > s$ . Then, since  $V_1 > \beta V_0$  from (22.2.31(p.214)), we have

$$|V_{\tau}| > \beta V_{\tau-1} > \beta^2 V_{\tau-2} > \dots > \beta^{\tau-1} V_1 > \beta^{\tau} V_0$$

(b3ii3) Let b < 0 ( $\kappa < 0$ ), hence  $x_L < x_K \le 0 \cdots$  (21) from Lemma 14.2.4(p.97) (c (d)). Then, from (10) we have  $V_1 < x_L < x_K = V$  due to (b1). Accordingly, due to the nondecreasing of  $V_t$  it follows that there exists  $t_{\tau}^{\bullet} > 1$  such that

$$V_1 \leq V_2 \leq \cdots \leq V_{t^{\bullet}_{\tau}-1} < x_L \leq V_{t^{\bullet}_{\tau}} \leq V_{t^{\bullet}_{\tau}+1} \leq \cdots$$

Hence  $V_{t-1} < x_L$  for  $t^{\bullet}_{\tau} \ge t > 1$  and  $x_L \le V_{t-1}$  for  $t > t^{\bullet}_{\tau}$ . Therefore, from Corollary 14.2.1(p.%) (a) we have

$$L(V_{t-1}) > 0 \cdots (22), \quad t_{\tau}^{\bullet} \ge t > 1, \qquad L(V_{t-1}) \le 0 \cdots (23), \quad t > t_{\tau}^{\bullet}.$$

• Let  $t^{\tau}_{\tau} \geq \tau > 1$ . Then, since  $L(V_{t-1}) > 0$  for  $\tau \geq t > 1$  from (22), we have  $V_t - \beta V_{t-1} > 0$  for  $\tau \geq t > 1$  from (22.2.30(p.214)) or equivalently  $V_t > \beta V_{t-1}$  for  $\tau \geq t > 1$ , so

$$V_{\tau} > \beta V_{\tau-1} > \dots > \beta^{\tau-1} V_1 \dots (24).$$

(1) Let  $\lambda\beta \max\{0, a-\rho\}\rho < s$ . Then, since  $V_1 < \beta V_0$  from (22.2.31(p.214)), we have

$$|V_{\tau}| > \beta V_{\tau-1} > \dots > \beta^{\tau-1} V_1 < \beta^{\tau} V_0$$

from (24), hence  $t_{\tau}^* = \tau$  or  $t_{\tau}^* = 0$  for  $t_{\tau}^{\bullet} \geq \tau > 1$ , i.e.,  $\boxed{\$ \text{ dOITs}_{t_{\tau}^{\bullet} \geq \tau > 1} \langle \tau \rangle}_{\Delta}$  or  $\boxed{\bullet \text{ dOITd}_{t_{\tau}^{\bullet} \geq \tau > 1} \langle 0 \rangle}_{\Delta}$ . Accordingly (1i) of  $S_{11}$  holds.

(2) Let  $\lambda\beta \max\{0, a-\rho\}\rho \geq s$ . Then, since  $V_1 \geq \beta V_0$  from (22.2.31(p.214)), we have

$$|V_{\tau}| > \beta V_{\tau-1} > \dots > \beta^{\tau-1} V_1 \ge \beta^{\tau} V_0$$

from (24), hence  $t_{\tau}^* = \tau$ , i.e.,  $\boxed{\text{$\odot$ dOITs}_{t_{\tau}^{\bullet} \geq \tau > 1}\langle \tau \rangle}_{\blacktriangle}$ . Accordingly (2i) of  $S_{11}$  holds.

 $\circ$  Let  $\tau > t_{\tau}^{\bullet}$ . Since  $L(V_{t-1}) \leq 0$  for  $\tau \geq t > t_{\tau}^{\bullet}$  from (23), we have  $V_t \leq \beta V_{t-1}$  for  $\tau \geq t > t_{\tau}^{\bullet}$  from (22.2.30(p.214)), hence

$$V_{\tau} \leq \beta V_{\tau-1} \leq \cdots \leq \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} \cdots (25), \quad \tau > t_{\tau}^{\bullet}.$$

From (22) and (22.2.30(p.214)) we have  $V_t > \beta V_{t-1}$  for  $t_{\tau}^{\bullet} \ge t > 1$ , hence

$$V_{t^{\bullet}} > \beta V_{t^{\bullet}-1} > \cdots > \beta^{t^{\bullet}_{\tau}-1} V_1 \cdots (26).$$

From (25) and (26) we have

$$V_{\tau} \leq \beta V_{\tau-1} \leq \cdots \leq \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} > \beta^{\tau-t_{\tau}^{\bullet}+1} V_{t_{\tau}^{\bullet}-1} > \beta^{\tau-t_{\tau}^{\bullet}+2} V_{t_{\tau}^{\bullet}-2} > \cdots > \beta^{\tau-1} V_{1} \cdots (27)$$

(1) Let  $\lambda \beta \max\{0, a - \rho\} < s$ . Then, since  $V_1 < \beta V_0$  from (22.2.31(p.214)), we have

$$V_{\tau} \leq \beta V_{\tau-1} \leq \dots \leq \overline{\beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}}} > \beta^{\tau-t_{\tau}^{\bullet}+1} V_{t_{\tau}^{\bullet}-1} > \beta^{\tau-t_{\tau}^{\bullet}+2} V_{t_{\tau}^{\bullet}-2} > \dots > \beta^{\tau-1} V_{1} < \overline{\beta^{\tau} V_{0}},$$

Hence, we have  $t_{\tau}^* = t_{\tau}^{\bullet}$  or  $t_{\tau}^* = 0$  for  $\tau > t_{\tau}^{\bullet}$ , i.e.,  $\boxed{\odot}$  ndOIT $_{\tau > t_{\tau}^{\bullet}} \langle t_{\tau}^{\bullet} \rangle |_{\Delta}$  or  $\boxed{\bullet}$  dOITd $_{\tau > t_{\tau}^{\bullet}} \langle 0 \rangle |_{\Delta}$ . Accordingly (1ii) of  $S_{11}$  holds.

(2) Let  $\lambda\beta \max\{0, a-\rho\} \geq s$ . Then, since  $V_1 \geq \beta V_0$  from (22.2.31(p.214)), from (27) we have

$$V_{\tau} \leq \beta V_{\tau-1} \leq \dots \leq \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} > \beta^{\tau-t_{\tau}^{\bullet}+1} V_{t_{\tau}^{\bullet}-1} > \beta^{\tau-t_{\tau}^{\bullet}+2} V_{t_{\tau}^{\bullet}-2} > \dots > \beta^{\tau-1} V_{1} \geq \beta^{\tau} V_{0},$$

hence  $t_{\tau}^* = t_{\tau}^{\bullet}$  for  $\tau > t_{\tau}^{\bullet}$ , i.e.,  $\boxed{\odot \text{ndOIT}_{\tau > t_{\tau}^{\bullet}} \langle t_{\tau}^{\bullet} \rangle}_{\vartriangle}$ . Accordingly (2ii) of  $S_{11}$  holds.

- (c) Let  $V_1 > x_K \cdots (28)$ , hence  $K(V_1) < 0 \cdots (29)$  due to Lemma 14.2.3(p.96) (j1).
- (c1) From (7.4.33(p.41)) with t=2 we have  $V_2=K(V_1)+V_1< V_1\cdots$  (30) due to (29), hence  $V_2\leq V_1$ . Suppose  $V_t\leq V_{t-1}$ . Then, from Lemma 14.2.3(p.96) (e) we have  $V_{t+1}=K(V_t)+V_t\leq K(V_{t-1})+V_{t-1}=V_t$ . Hence, by induction  $V_t\leq V_{t-1}$  for t>1, i.e.,  $V_t$  is nonincreasing in t>0. Note (28), hence  $V_1\geq x_K$ . Suppose  $V_{t-1}\geq x_K$ . Then, since  $V_t\geq K(x_K)+x_K=x_K$  from Lemma 14.2.3(p.96) (e), by induction we have  $V_t\geq x_K\cdots$  (31) for t>0, i.e.,  $V_t$  is lower bounded in t, hence  $V_t$  converges to a finite V. Then, we have  $V=x_K$  for the same reason as in the proof of (b1).
- (c2) Let  $\beta = 1$ , hence s > 0 due to the assumption " $\beta < 1$  or s > 0". Then, since  $x_L = x_K \cdots$  (32) from Lemma 14.2.4(p.97) (b), we have  $V_{t-1} \ge x_L$  for t > 1 from (31). Accordingly  $L(V_{t-1}) \le 0$  for t > 1 from Lemma 14.2.2(p.96) (e1), hence  $L(V_{t-1}) \le 0$  for  $\tau \ge t > 1$ , so  $V_t \le \beta V_{t-1}$  for  $\tau \ge t > 1$  from (22.2.30(p.214)), leading to  $V_{\tau} \le \beta V_{\tau-1} \le \cdots \le \beta^{\tau-1} V_1$ .
  - (1) Let  $\lambda\beta \max\{0, a-\rho\} < s$ . Then, since  $V_1 < \beta V_0$  from (22.2.31(p.214)), we have

$$V_{\tau} \leq \beta V_{\tau-1} \leq \dots \leq \beta^{\tau-1} V_1 < \beta^{\tau} V_0,$$

hence  $t_{\tau}^* = 0$  for  $\tau > 1$ , i.e.,  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 0 \rangle}_{\blacktriangle}$ .

(2) Let  $\lambda\beta \max\{0, a-\rho\} \geq s$ . Then, since  $V_1 \geq \beta V_0$  from (22.2.31(p.214)) we have

$$V_{\tau} \leq \beta V_{\tau-1} \leq \cdots \leq \beta^{\tau-1} V_1 \geq \beta^{\tau} V_0,$$

hence  $t_{\tau}^* = 1$  for  $\tau > 1$ , i.e.,  $\boxed{\odot \text{ ndOIT}_{\tau > 1} \langle 1 \rangle}_{\Delta}$ .

- (c3) Let  $\beta < 1 \cdots (33)$  and s = 0 (s > 0).
- (c3i) Let b > 0 (( $\kappa > 0$ )). Then  $x_L > x_K > 0 \cdots$  (34) from Lemma 14.2.4(p.97) (c ((d))).
- (c3i1) Let  $V_1 < x_L$ , hence  $x_L > V_{t-1}$  for t > 1 from (c1). Accordingly, since  $L(V_{t-1}) > 0$  for t > 1 from Corollary 14.2.1(p.96) (a), we have  $V_t \beta V_{t-1} > 0$  for t > 1 due to (22.2.30(p.214)) or equivalently  $V_t > \beta V_{t-1}$  for t > 1, hence  $V_t > \beta V_{t-1}$  for t > 1, leading to

$$V_{\tau} > \beta V_{\tau-1} > \dots > \beta^{\tau-1} V_1 \cdots (35)$$
.

- (1) Let  $\lambda\beta \max\{0, a-\rho\} < s$ . Then for the same reason as in  $(A_{(p,219)})$  we have (1) of  $S_{10}$ .
- (2) Let  $\lambda\beta \max\{0, a-\rho\} \geq s$ . Then for the same reason as in (B(p.219)) we have (2) of  $S_{10}$ .

(c3i2) Let  $V_1 = x_L$ . Then, since  $V_1 = x_L > x_K = V$  from (34) and (c1), there exists  $t_{\tau}^{\bullet} > 1$  such that

$$V_1 = V_2 = \cdots = V_{t^{\bullet}_{\tau}-1} = x_L > V_{t^{\bullet}_{\tau}} \ge V_{t^{\bullet}_{\tau}+1} \ge \cdots,$$

i.e.,  $V_{t-1} = x_L$  for  $t^{\bullet}_{\tau} \ge t > 1$  and  $x_L > V_{t-1}$  for  $t > t^{\bullet}_{\tau}$ . Hence, from Corollary 14.2.1(p.96) (a) we have

$$L(V_{t-1}) = L(x_L) = 0 \cdots (36), \quad t_{\tau}^{\bullet} \ge t > 1, \qquad L(V_{t-1}) > 0 \cdots (37), \quad t > t_{\tau}^{\bullet}$$

Accordingly, from (22.2.30(p.214)) we have  $V_t - \beta V_{t-1} = 0$  for  $t^{\bullet}_{\tau} \ge t > 1$  and  $V_t - \beta V_{t-1} > 0$  for  $t > t^{\bullet}_{\tau}$  or equivalently

$$V_t = \beta V_{t-1} \cdots (38), \quad t_{\tau}^{\bullet} \ge t > 1, \qquad V_t > \beta V_{t-1} \cdots (39), \quad t > t_{\tau}^{\bullet}.$$

• Let  $t_{\tau}^{\bullet} \geq \tau > 1$ . Then, we have  $V_t = \beta V_{t-1}$  for  $\tau \geq t > 1$  from (38), leading to

$$V_{\tau} = \beta V_{\tau-1} = \dots = \beta^{\tau-1} V_1 \dots (40).$$

(1) Let  $\lambda \beta \max\{0, a - \rho\} < s$ . Then, since  $V_1 < \beta V_0$  from (22.2.31(p.214)), we have

$$V_{\tau} = \beta V_{\tau-1} = \dots = \beta^{\tau-1} V_1 < \beta^{\tau} V_0$$

hence  $t_{\tau}^* = 0$  for  $t_{\tau}^{\bullet} \geq \tau > 1$ , i.e.,  $\bullet \text{ dOITd}_{t_{\tau}^{\bullet} \geq \tau > 1}(0)$ , hence (1i) of  $S_{12}$  holds.

(2) Let  $\lambda \beta \max\{0, a - \rho\} \geq s$ . Then, since  $V_1 \geq \beta V_0$  from (22.2.31(p.214)), we have

$$V_{\tau} = \beta V_{\tau-1} = \dots = \beta^{\tau-1} V_1 > \beta^{\tau} V_0$$

for  $t_{\tau}^{\bullet} \geq \tau > 1$ , hence  $t_{\tau}^{*} = 1$  for  $t_{\tau}^{\bullet} \geq \tau > 1$ , i.e.,  $\boxed{\bigcirc \text{ndOIT}_{t_{\tau}^{\bullet} \geq \tau > 1}\langle 1 \rangle}_{\parallel}$ , hence (2i) of  $S_{12}$  holds.

From (40) with  $\tau = t_{\tau}^{\bullet}$  we have

$$V_{t^{\bullet}} = \beta V_{t^{\bullet}-1} = \cdots = \beta^{t^{\bullet}_{\tau}-1} V_1 \cdots (41).$$

 $\circ$  Let  $\tau > t_{\tau}^{\bullet}$ . Then, we have  $V_t > \beta V_{t-1}$  for  $\tau > t > t_{\tau}^{\bullet}$  from (39), leading to

$$V_{\tau} > \beta V_{\tau-1} > \cdots > \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} \cdots (42).$$

From this and (41) we have

$$V_{\tau} > \beta V_{\tau-1} > \dots > \beta^{\tau - t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} = \beta^{\tau - t_{\tau}^{\bullet} + 1} V_{t_{\tau}^{\bullet} - 1} = \dots = \beta^{\tau - 1} V_{1}.$$

(1) Let  $\lambda\beta \max\{0, a-\rho\} < s$ . Then, since  $V_1 < \beta V_0$  from (22.2.31(p.214)), we have

$$|V_{\tau}| > \beta V_{\tau-1} > \dots > \beta^{\tau - t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} = \beta^{\tau - t_{\tau}^{\bullet} + 1} V_{t_{\tau}^{\bullet} - 1} = \dots = \beta^{\tau - 1} V_{1} < \beta^{\tau} V_{0},$$

hence  $t_{\tau}^* = \tau$  or  $t_{\tau}^* = 0$  for  $\tau > t_{\tau}^{\bullet}$ , i.e.,  $\boxed{\$ \text{ dOITs}_{\tau > t_{\tau}^{\bullet}} \langle \tau \rangle}_{\vartriangle}$  or  $\boxed{\bullet \text{ dOITd}_{\tau > t_{\tau}^{\bullet}} \langle 0 \rangle}_{\vartriangle}$ , thus (1ii) of  $S_{12}$  holds.

(2) Let  $\lambda\beta \max\{0, a-\rho\} \geq s$ . Then, since  $V_1 \geq \beta V_0$  from (22.2.31(p.214)), we have

$$V_{\tau} > \beta V_{\tau-1} > \dots > \beta^{\tau-t_{\tau}^{\bullet}} V_{t^{\bullet}} = \beta^{\tau-t_{\tau}^{\bullet}+1} V_{t^{\bullet}-1} = \dots = \beta^{\tau-1} V_{1} > \beta^{\tau} V_{0}$$

for  $\tau > t_{\tau}^{\bullet}$ , hence  $t_{\tau}^{*} = \tau$  for  $\tau > t_{\tau}^{\bullet}$ , i.e.,  $\boxed{\text{$\odot$ dOITs}_{\tau > t_{\tau}^{\bullet}}\langle \tau \rangle}_{\blacktriangle}$ , hence (2ii) of  $S_{12}$  holds.

(c3i3) Let  $V_1 > x_L \cdots$  (43). Then, since  $V_1 > x_L > x_K = V$  from (34) and (c1), due to the nonincreasingness of  $V_t$  it follows that there exists  $t_{\tau}^{\bullet} > 1$  such that

$$V_1 \geq V_2 \geq \cdots \geq V_{t^{\bullet}-1} > x_L \geq V_{t^{\bullet}} \geq V_{t^{\bullet}+1} \geq \cdots$$

from which  $V_{t-1} > x_L$  for  $t^{\bullet}_{\tau} \ge t > 1$  and  $x_L \ge V_{t-1}$  for  $t > t^{\bullet}_{\tau}$ . Hence, from Corollary 14.2.1(p.%) (a) we have

$$L(V_{t-1}) \le 0 \cdots (44), \quad t_{\tau}^{\bullet} \ge t > 1, \qquad L(V_{t-1}) \ge 0 \cdots (45), \quad t > t_{\tau}^{\bullet}.$$

○ Let  $t_{\tau}^{\bullet} \ge \tau > 1$ . Then  $L(V_{t-1}) \le 0$  for  $\tau \ge t > 1$  from (44), hence  $V_t - \beta V_{t-1} \le 0$  for  $\tau \ge t > 1$  from (22.2.30(p.214)), we have  $V_t \le \beta V_{t-1}$  for  $\tau \ge t > 1$ . Hence

$$V_{\tau} < \beta V_{\tau-1} < \beta^2 V_{\tau-2} < \dots < \beta^{\tau-1} V_1 \cdots (46)$$
.

(1) Let  $\lambda \beta \max\{0, a - \rho\} < s$ . Then, since  $V_1 < \beta V_0$  from (22.2.31(p.214)), we have

$$V_{\tau} \le \beta V_{\tau-1} \le \dots \le \beta^{\tau-1} V_1 < \overline{\beta^{\tau} V_0},$$

hence  $t_{\tau}^* = 0$  for  $t_{\tau}^{\bullet} \geq \tau > 1$ , i.e.,  $\bullet dOITd_{t_{\tau}^{\bullet} > \tau > 1}\langle 0 \rangle$ , so (1i) of  $S_{13}$  holds.

(2) Let  $\lambda\beta \max\{0, a-\rho\} \geq s$ . Then, since  $V_1 \geq \beta V_0$  from (22.2.31(p.214)), we have

$$V_{\tau} \leq \beta V_{\tau-1} \leq \dots \leq \left| \beta^{\tau-1} V_1 \right| \geq \beta^{\tau} V_0$$

for  $t_{\tau}^{\bullet} \geq \tau > 1$ , hence  $t_{\tau}^{*} = 1$  for  $t_{\tau}^{\bullet} \geq \tau > 1$ , i.e.,  $\boxed{\bigcirc \text{ndOIT}_{t_{\tau}^{\bullet} \geq \tau > 1}\langle 1 \rangle}_{\Delta}$ , hence (2i) of  $S_{13}$  holds.

From (46) with  $\tau = t_{\tau}^{\bullet}$  we have

$$V_{t\bullet} \leq \beta V_{t\bullet-1} \leq \cdots \leq \beta^{t^{\bullet}_{\tau}-1} V_1 \cdots (47).$$

o Let  $\tau > t_{\tau}^{\bullet}$ . Then  $L(V_{t-1}) \geq 0$  for  $\tau \geq t > t_{\tau}^{\bullet}$  from (45), hence  $V_t - \beta V_{t-1} \geq 0$  for  $\tau \geq t > t_{\tau}^{\bullet}$  from (22.2.30(p.214)) or equivalently  $V_t \geq \beta V_{t-1}$  for  $\tau \geq t > t_{\tau}^{\bullet}$ , leading to

$$V_{\tau} \geq \beta V_{\tau-1} \geq \dots \geq \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}}.$$

Hence, from (47) we have

$$V_{\tau} \geq \beta V_{\tau-1} \geq \cdots \geq \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} \leq \beta^{\tau-t_{\tau}^{\bullet}+1} V_{t_{\tau}^{\bullet}-1} \leq \cdots \leq \beta^{\tau-1} V_{1} \cdots (48).$$

(1) Let  $\lambda \beta \max\{0, a - \rho\} < s$ . Since  $V_1 - \beta V_0 < 0 \cdots$  (49) from (22.2.31(p.214)) or equivalently  $V_1 < \beta V_0 \cdots$  (50). Then, from (48) and (50) we have

$$V_{\tau} \geq \beta V_{\tau-1} \geq \dots \geq \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} \leq \beta^{\tau-t_{\tau}^{\bullet}+1} V_{t_{\tau}^{\bullet}-1} \leq \dots \leq \beta^{\tau-1} V_{1} < \beta^{\tau} V_{0}$$

hence Thus, we obtain  $\boxed{\$ dOITs_{\tau}\langle \tau \rangle}_{\Delta}$  or  $\boxed{\bullet dOITd_{\tau}\langle 0 \rangle}_{\Delta}$ , hence (1ii) of  $S_{13}$  holds.

(2) Let  $\lambda \beta \max\{0, a - \rho\} \ge s$ . Then  $V_1 - \beta V_0 \ge 0$  from (22.2.31(p.214)), hence  $V_1 \ge \beta V_0$ . Then, from (48) we have

$$V_{\tau} \geq \beta V_{\tau-1} \geq \cdots \geq \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\bullet}} \leq \beta^{\tau-t_{\tau}^{\bullet}+1} V_{t_{\bullet}-1} \leq \cdots \leq \beta^{\tau-2} V_{2} \leq \beta^{\tau-1} V_{1} \geq \beta^{\tau} V_{0}.$$

Thus, we have  $\boxed{\$ dOITs_{\tau}\langle \tau \rangle}_{\Delta}$  or  $\boxed{\bullet dOITd_{\tau}\langle 0 \rangle}_{\Delta}$ , hence (2ii) of  $S_{13}$  holds.

(c3ii) Let  $b \leq 0$  ( $\kappa \leq 0$ ). Then, since  $x_L \leq x_K$  from Lemma 14.2.4(p.97) (c (d)), we have  $V_1 > x_K \geq x_L$  from (28), hence  $V_{t-1} \geq x_K \geq x_L$  for t > 1 due to (c1). Accordingly  $L(V_{t-1}) \leq 0$  for t > 1 from Corollary 14.2.1(p.96) (a), hence  $V_t - \beta V_{t-1} \leq 0$  for t > 1 from (22.2.30(p.214)) or equivalently  $V_t \leq \beta V_{t-1}$  for t > 1. Accordingly, since  $V_t \leq \beta V_{t-1}$  for  $\tau \geq t > 1$ , we have

$$V_{\tau} < \beta V_{\tau-1} < \dots < \beta^{\tau-1} V_1 \cdots (51).$$

(1) Let  $\lambda\beta \max\{0, a-\rho\} \leq s$ . Then, since  $V_1 \leq \beta V_0$  from (22.2.31(p.214)), we have

$$V_{\tau} \leq \beta V_{\tau-1} \leq \cdots \leq \beta^{\tau-1} V_1 \leq \beta^{\tau} V_0$$

from (51), hence  $t_{\tau}^* = 0$  for  $\tau > 1$ , i.e.,  $\bullet dOITd_{\tau > 1}\langle 0 \rangle_{\Delta}$ .

(2) Let  $\lambda \beta \max\{0, a - \rho\} > s$ . Then, since  $V_1 > \beta V_0$  from (22.2.31(p.214)), we have

$$V_{\tau} \le \beta V_{\tau-1} \le \dots \le \beta^{\tau-1} V_1 > \beta^{\tau} V_0,$$

from (51), hence  $t_{\tau}^* = 1$  for  $\tau > 1$ , i.e.,  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\vartriangle}$ .

Corollary 22.2.10 (M:2[P][E]) Assume  $a^* < \rho < b$ . Let  $\beta < 1$  or s > 0.:

- (a) Let  $x_K \geq V_1$ . Then  $z_t$  is nondecreasing in t > 0.
- (b) Let  $x_K < V_1$ . Then  $z_t$  is nonincreasing in t > 0.
- Proof Immediate from Tom 22.2.5(p.218) (b1,c1) and from (7.2.94(p.35)) and Lemma 14.1.3(p.89).

#### 22.2.6.3 Market Restriction

#### 22.2.6.3.1 Positive Restriction

#### 22.2.6.3.1.1 Case of $\beta = 1$ and s = 0

- $\square$  Pom **22.2.9** ( $\mathscr{A}\{M:2[\mathbb{P}][E]^+\}$ ) Suppose a > 0. Let  $\beta = 1$  and s = 0.
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ .
- (b) Let  $\rho \leq a^*$ . Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$ .
- (c) Let  $b \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- (d) Let  $a^* < \rho < b$ .
  - 1. Let  $a \leq \rho$ . Then  $\boxed{\bullet \ \text{dOITd}_1\langle 0 \rangle}_{\parallel}$  and  $\boxed{\$ \ \text{dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ .
  - 2. Let  $\rho < a$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle$ .
- *Proof* The same as Lemma 22.2.2(p.215) due to Lemma 18.4.4(p.118). ■

#### 22.2.6.3.1.2 Case of $\beta < 1$ or s > 0

#### **22.2.6.3.1.2.1** Case of $\rho \le a^*$

- $\square$  Pom 22.2.10 ( $\mathscr{A}\{M:2[\mathbb{P}][E]^+\}$ ) Suppose a>0. Assume  $\rho \leq a^*$ . Let  $\beta < 1$  or s>0 and let  $\rho < x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \ge 0$ , is strictly increasing in  $t \ge 0$  if  $\lambda < 1$  or  $a^* < \rho$ , and converges to a finite  $V = x_K$  as  $t \to \infty$ .
- (b) Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}$ .
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}_{\blacktriangle}$ . Below let  $\tau > 1$ .
  - 2. Let  $\beta = 1$ .
    - i. Let  $(\lambda a s)/\lambda \le a^*$ .
      - 1. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT $_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\lambda < 1$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle_{\blacktriangle}$ .
    - ii. Let  $(\lambda a s)/\lambda > a^{\star}$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 0} \langle \tau \rangle}_{\blacktriangle}$ .

  - 4. Let  $\beta < 1$  and s > 0.
    - i. Let  $(\lambda \beta a s)/\delta \leq a^*$ .
      - 1. Let  $\lambda = 1$ .
        - i. Let  $s < \lambda \beta T(0)$ . Then  $subseteq doi: 10.5 \text{doiss}_{\tau>0} \langle \tau \rangle$ .
        - ii. Let  $s \geq \lambda \beta T(0)$ . Then  $\bigcirc$  ndOIT<sub> $\tau > 1$ </sub> $\langle 1 \rangle$ <sub> $\triangle$ </sub>.
      - 2. Let  $\lambda < 1$ .
        - i. Let  $s \leq \lambda \beta T(0)$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle$ .
        - ii. Let  $s > \lambda \beta T(0)$ . Then  $S_8(p.203)$   $S_{\bullet} \odot B_{\bullet} \odot A_{\bullet}$  is true
    - ii. Let  $(\lambda \beta a s)/\delta > a^*$ .
      - 1. Let  $s \leq \lambda \beta T(0)$ . Then  $startion{3}{\circ} dOITs_{\tau>0} \langle \tau \rangle$
      - 2. Let  $s > \lambda \beta T(0)$ . Then  $S_8(p.203)$   $S_{\bullet} \odot I \odot \Delta \odot \Delta$  is true.
- Proof Suppose a>0, hence  $b>a>0\cdots (1)$ . Then  $\kappa=\lambda\beta T(0)-s\cdots (2)$  from (6.1.23(p.26)).
  - $\hbox{(a-c2ii)}\quad The\ same\ as\ \mbox{Tom}\ 22.2.5\mbox{(p.215)}\ \mbox{(a-c2ii)}.$
  - (c3) Due to (1) it suffices to consider only (c3i1i,c3i2i,c3ii1) of Tom 22.2.5(p2l5).
  - (c4-c4ii2) Immediate from (2) and Tom 22.2.5(p.215) (c3-c3ii2) with  $\kappa$  due to (2).
- $\square$  Pom 22.2.11 ( $\mathscr{A}\{M:2[\mathbb{P}][E]^+\}$ ) Suppose a>0. Assume  $\rho\leq a^*$ . Let  $\beta<1$  or s>0 and let  $\rho=x_K$ .
- (a)  $V_t = x_K = \rho \text{ for } t \geq 0.$
- (b) Let  $\beta = 1$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\parallel}$ .
- (c) Let  $\beta < 1$  and s = 0. Then s = 0 doing t > 0.
- (d) Let  $\beta < 1$  and s > 0.
  - 1. Let  $s < \lambda \beta T(0)$ . Then  $startion{ starting dollers for the starting of the starting of the starting density of the start$
  - 2. Let  $s \geq \lambda \beta T(0)$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}$ .
- Proof Suppose a > 0, hence  $b > a > 0 \cdots (1)$ . Then  $\kappa = \lambda \beta T(0) s \cdots (2)$  from (6.1.23(p.26)).
  - (a,b) The same as Tom 22.2.6(p.216) (a,b).
  - (c) Due to (1) it suffices to consider only (c1) of Tom 22.2.6(p.216).
  - (d-d2) Immediate from (2) and Tom 22.2.6(p.216) (c1,c2) with  $\kappa$ .
- $\square$  Pom 22.2.12 ( $\mathscr{A}\{M:2[\mathbb{P}][\mathbb{E}]^+\}$ ) Suppose a>0. Assume  $\rho\leq a^\star$ . Let  $\beta<1$  or s>0 and let  $\rho>x_K$ .
- (a)  $V_t$  is nonincreasing in  $t \ge 0$ , is strictly decreasing in t > 0 if  $\lambda < 1$ , and converges to  $V = x_K$  as to  $t \to \infty$ .
- (b) Let  $\rho < x_L$ . Then S dOITs  $_{\tau > 0} \langle \tau \rangle$ .
- (c) Let  $\rho = x_L$ . Then  $\boxed{\bullet dOITd_1\langle 0 \rangle}_{\vartriangle}$  and  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ .
- (d) Let  $\rho > x_L$ .
  - 1. Let  $\beta = 1$ . Then  $\left[ \bullet dOITd_{\tau > 0} \langle 0 \rangle \right]_{\Delta}$ .
  - 2. Let  $\beta < 1$  and s = 0. Then  $S_9(p.207)$   $\bigcirc S_{\Delta} \bigcirc \bullet_{\Delta} \bigcirc \bullet_{\Delta}$  is true.
  - 3. Let  $\beta < 1$  and s > 0.
    - $\mathrm{i.} \quad Let \ s \geq \lambda \beta T(0). \ \ Then \ \ \boxed{\bullet \ \mathrm{dOITd}_{\tau>0}\langle 0\rangle}_{\vartriangle} \ \ \left(\boxed{\bullet \ \mathrm{dOITd}_{\tau>0}\langle 0\rangle}_{\blacktriangle}\right) \ .$
    - ii. Let  $s < \lambda \beta T(0)$ . Then  $S_9(p.207)$   $\bigcirc S_{\Delta} \bigcirc \bullet \triangle$  is true.

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• Proof Suppose a > 0, hence b > a > 0 \cdots (1). Then \kappa = \lambda \beta T(0) - s \cdots (2) from (6.1.23(p.26)).
   (a-d1) The same as Tom 22.2.7(p.216) (a-d1).
   (d2) Due to (1) it suffices to consider only (d2ii) of Tom 22.2.7(p.216).
   (d3,d3ii) Immediate from (2) and Tom 22.2.7(p.216) (d2i,d2ii) with \kappa.
22.2.6.3.1.2.2 Case of b < \rho
\square Pom 22.2.13 (\mathscr{A}\{M:2[\mathbb{P}][E]^+\}) Suppose a>0. Assume b\leq\rho. Let \beta<1 or s>0 and let \rho< x_K.
(a) V_t is nondecreasing in t \geq 0, is strictly increasing in t \geq 0 if \lambda < 1, and converges to a finite V = x_K as t \to \infty.
(b) Let x_L \leq \rho. Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}.
(c) Let \rho < x_L.
     1. \boxed{\$ dOITs_1\langle 1 \rangle}. Below let \tau > 1.
     2. Let \beta = 1. Then subseteq doing = 0.5
     3. Let \beta < 1 and s = 0. Then s \neq 0 doing s \neq 0.
     4. Let \beta < 1 and s > 0.
          i. Let s \leq \lambda \beta T(0). Then subseteq dOITs_{\tau>0} \langle \tau \rangle.
          ii. Let s > \lambda \beta T(0). Then S_8(p.203) \bigcirc A \bigcirc A \bigcirc A is true.
• Proof Suppose a > 0, hence b > a > 0 \cdots (1). Then \kappa = \lambda \beta T(0) - s \cdots (2) from (6.1.23(p.26)).
   (a-c2) The same as Tom 22.2.8(p.216) (a-c2).
   (c3) Due to (1) it suffices to consider only (c3i) of Tom 22.2.8(p.216).
   (c4-c4ii) Immediate from (2) and Tom 22.2.8(p.216) (c3i,c3ii) with \kappa.
\square Pom 22.2.14 (\mathscr{A}\{M:2[\mathbb{P}][E]^+\}) Suppose a>0. Assume b\leq\rho. Let \beta<1 or s>0 and let \rho=x_K.
(a) V_t = x_K = \rho \text{ for } t \geq 0.
(b) Let \beta = 1. Then \bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}.
(c) Let \beta < 1 and s = 0. Then \mathfrak{S} dOITs_{\tau>0} \langle \tau \rangle
(d) Let \beta < 1 and s > 0.
     1. Let s < \lambda \beta T(0). Then subseteq dOITs_{\tau>0} \langle \tau \rangle.
     2. Let s \geq \lambda \beta T(0). Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}.
• Proof Suppose a > 0, hence b > a > 0 \cdots (1). Then \kappa = \lambda \beta T(0) - s \cdots (2) from (6.1.23(p.26)).
   (a,b) The same as Tom 22.2.9(p.217) (a,b).
   (c) Due to (1) it suffices to consider only (c1) of Tom 22.2.9(p.217).
   (d-d2) Immediate from (2) and Tom 22.2.9(p.217) (c1,c2) with \kappa.
\square Pom 22.2.15 (\mathscr{A}\{M:2[\mathbb{P}][E]^+\}) Suppose a>0. Assume b\leq\rho. Let \beta<1 or s>0 and let \rho>x_K.
(a) V_t is nonincreasing in t \geq 0, is strictly decreasing in t > 0 if \lambda < 1, and converges to V = x_K as to t \to \infty.
(b) Let \rho = x_L. Then \boxed{\bullet dOITd_1\langle 0 \rangle}_{\triangle} and \boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\blacktriangle}.
(c) Let \rho > x_L.
     1. Let \beta = 1. Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}.
     3. Let \beta < 1 and s > 0.
           i. Let s \geq \lambda \beta T(0). Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta} (\bullet dOITd_{\tau>0}\langle 0 \rangle_{A}).
          • Proof Suppose a > 0, hence b > a > 0 \cdots (1). Then \kappa = \lambda \beta T(0) - s \cdots (2) from (6.1.23(p.26)).
   (a-c1) The same as Tom 22.2.10(p.217) (a-c1).
   (c2) Due to (1) it suffices to consider only (c2ii) of Tom 22.2.10(p.217).
   (c3-c3ii) Immediate from (2) and Tom 22.2.10(p.217) (c2i,c2ii) with \kappa.
22.2.6.3.1.2.3 Case of a^* < \rho < b
\square Pom 22.2.16 (\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]^+\}) Suppose a>0. Assume a^*\leq \rho < a. Let \beta<1 or s>0.
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(a) If  $\lambda\beta \max\{0, a-\rho\} < s$ , then  $\boxed{\bullet \ \text{dOITd}_1\langle 0 \rangle}_{\vartriangle}$ , or else  $\boxed{\$ \ \text{dOITs}_1\langle 1 \rangle}_{\blacktriangle}$ . Below let  $\tau > 1$ .

1.  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V = x_K$  as  $t \to \infty$ 

(b) Let  $x_K \geq V_1$ .

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2. Let x_L \leq V_1. If \lambda \beta \max\{0, a - \rho\} \leq s, then \bullet \text{dOITd}_{\tau > 1}\langle 0 \rangle_{\Delta}, or else \bullet \text{dOIT}_{\tau > 1}\langle 1 \rangle_{\Delta}.
      3. Let x_L > V_1.
            i. Let \beta = 1. Then S_{10}(p.217) \bigcirc S_{\Delta} \bigcirc \Phi_{\Delta} is true.
            ii. Let \beta < 1 and s = 0. Then S_{10}(p.217) \bigcirc \triangle \bigcirc \triangle is true.
           iii. Let \beta < 1 and s > 0.
                1. Let s < \lambda \beta T(0). Then S_{10}(p.217) s_{\Delta} \bullet_{\Delta} is true.
                 2. Let s = \lambda \beta T(0). If \lambda \beta \max\{0, a - \rho\} < s, then \boxed{\$ \text{dOITs}_{\tau > 1} \langle \tau \rangle}_{\vartriangle} or \boxed{\bullet \text{dOITd}_{\tau > 1} \langle 0 \rangle}_{\vartriangle},
                     or else \bigcirc dOITs_{\tau>1}\langle \tau \rangle \triangle.
                      Let s > \lambda \beta T(0). Then S_{11}(p.217) \bigcirc \triangle \bigcirc \triangle \bigcirc \triangle \bigcirc \triangle is true.
(c) Let x_K < V_1.
      1. V_t is nonincreasing in t \geq 0 and converges to a finite V = x_K as t \to \infty.
      2. Let \beta = 1. If \lambda \beta \max\{0, a - \rho\} < s, then \left[ \bullet \operatorname{dOITd}_{\tau > 1} \langle 0 \rangle \right]_{\blacktriangle}, or else \left[ \odot \operatorname{ndOIT}_{\tau > 1} \langle 1 \rangle \right]_{\vartriangle}.
      3. Let \beta < 1 and s = 0.
            i. Let x_L > V_1. Then S_{10}(p.217) \bigcirc \triangle is true.
            iii. Let x_L < V_1. Then S_8(p.203) S_{\bullet} \odot I \odot \Delta \odot \Delta is true.
      4. Let \beta < 1 and s > 0.
             i. Let s < \lambda \beta T(0).
                1. Let x_L > V_1. Then S_{10}(p.217) \stackrel{\text{s}_{\triangle}}{-} \bullet \stackrel{\text{l}}{-} is true.
                 2. Let x_L = V_1. Then S_{12}(p.218) S_{\Delta} S_{\Delta} O_{\Delta} O_{\Delta} is true.
                 3. Let x_L < V_1. Then S_8(p.203) S_{\bullet} \odot | O_{\bullet} \odot A is true.
            ii. Let s \geq \lambda \beta T(0). If \lambda \beta \max\{0, a - \rho\} < s, then \bullet \operatorname{dOITd}_{\tau > 1}\langle 0 \rangle_{\mathbb{A}}, or else \bullet \operatorname{dOITd}_{\tau > 1}\langle 1 \rangle_{\mathbb{A}}.
• Proof Suppose a > 0, hence b > a > 0 \cdots (1). Then, we have \kappa = \lambda \beta T(0) - s \cdots (2) from (6.1.23(p.26)).
   (a-b3i) The same as Tom 22.2.5(p.218) (a-b3i).
   (b3ii) Due to (1) it suffices to consider only (b3ii1) of Tom 22.2.5(p.218).
   (b3iii-b3iii3) The same as Tom 22.2.5(p.218) (b3ii1-b3ii3).
   (c-c2) Immediate from (2) and Tom 22.2.5(p.218) (c-c2).
   (c3-c3iii) Due to (1) it suffices to consider only (c3i1-c3i3) of Tom 22.2.5(p218).
   (c4-c4ii) Immediate from (2) and Tom 22.2.5(p.218) (c3i-c3ii). ■
22.2.6.3.2 Mixed Restriction
Omitted.
22.2.6.3.3 Negative Restriction
22.2.6.3.3.1 Case of \beta = 1 and s = 0
\square \ \ \text{Nem 22.2.5 (} \mathscr{A}\{\mathsf{M}{:}2[\mathbb{P}][\mathsf{E}]^-\}) \quad \  Suppose \ b<0. \ Let \ \beta=1 \ and \ s=0.
(a) V_t is nondecreasing in t > 0.
(b) Let \rho \leq a^*. Then subseteq dOITs_{\tau>0} \langle \tau \rangle_{\blacktriangle}.
(c) Let b \leq \rho. Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}.
(d) Let a^* < \rho < b.
      1. Let a \leq \rho. Then \bullet dOITd_1\langle 0 \rangle and \otimes dOITs_{\tau>1}\langle \tau \rangle.
      2. Let \rho < a. Then subseteq dOITs_{\tau>0} \langle \tau \rangle.
• Proof The same as Lemma 22.2.2(p.215) due to Lemma 18.4.4(p.118).
22.2.6.3.3.2 Case of \beta < 1 or s > 0
22.2.6.3.3.2.1 Case of \rho \le a^*
\square Nem 22.2.6 (\mathscr{A}\{M:2[\mathbb{P}][E]^-\}) Suppose b<0. Assume \rho\leq a^\star. Let \beta<1 or s>0 and let \rho< x_K.
(a) V_t is nondecreasing in t \geq 0, is strictly increasing in t \geq 0 if \lambda < 1 or a^* < \rho, and converges to a finite V = x_K as
      t \to \infty.
(b) Let x_L \leq \rho. Then | \bullet dOITd_{\tau > 0} \langle 0 \rangle |_{\Delta}.
(c) Let \rho < x_L.
      1. \boxed{\$ dOITs_1\langle 1 \rangle}. Below let \tau > 1.
      2. Let \beta = 1.
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i. Let  $(\lambda a - s)/\lambda < a^*$ .

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1. Let \lambda = 1. Then \bigcirc ndOIT<sub>\tau > 1</sub>\langle 1 \rangle<sub>||</sub>.
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- ii. Let  $(\lambda a s)/\lambda > a^*$ . Then  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\blacktriangle}$ .
- 3. Let  $\beta < 1$  and s = 0. Then  $S_8(p.203)$   $\boxed{\$ \blacktriangle \circledcirc \Vdash \circledcirc \vartriangle \circledcirc \blacktriangle}$ .
- 4. Let  $\beta < 1$  and s > 0.
  - i. Let  $(\lambda \beta a s)/\delta \le a^*$ .
    - 1. Let  $\lambda = 1$ . Then  $\bigcirc$  ndOIT<sub> $\tau > 1$ </sub> $\langle 1 \rangle$   $_{\triangle}$ .
    - 2. Let  $\lambda < 1$ . Then  $S_8(p.203)$   $\boxed{\$ \blacktriangle \circledcirc \Vdash \circledcirc \vartriangle \circledcirc \blacktriangle}$  is true.
- *Proof* Suppose  $b < 0 \cdots (1)$ , hence  $a^* < a < b < 0 \cdots (2)$  from Lemma 14.2.1(p.93) (n). Then  $\kappa = -s \cdots (3)$  from Lemma 14.2.6(p.97) (a).
  - (a-c2ii) The same as Tom 22.2.5(p.215) (a-c2ii).
- (c3) Let  $\beta < 1$  and s = 0. Assume  $(\lambda \beta a s)/\delta \le a^{\star}$ . Then, since  $\lambda \beta a/\delta \le a^{\star}$ , we have  $\lambda \beta a \le \delta a^{\star}$  from (11.2.2(1) (p.56)), hence  $\lambda \beta a \le \delta a^{\star} \le \lambda a^{\star}$  due to (2), so  $\beta a \le a^{\star}$ , which contradicts [19(p.118)]. Thus it must be that  $(\lambda \beta \mu s)/\delta > a^{\star}$ . From this it suffices to consider only (c3ii2) of Tom 22.2.5(p.215).
- (c4-c4ii) Let  $\beta < 1$  and s > 0. Then  $\kappa < 0$  due to (3), hence it suffices to consider only (c3i1ii,c3i2ii,c3i2i) of Tom 22.2.5(p.215) with  $\kappa$ .
- $\square$  Nem 22.2.7 ( $\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]^-\}$ ) Suppose b<0. Assume  $\rho\leq a^\star$ . Let  $\beta<1$  or s>0 and let  $\rho=x_K$ .
- (a)  $V_t = x_K = \rho \text{ for } t \geq 0.$
- (b) We have  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}$ .
- Proof Suppose b < 0. Then  $\kappa = -s \cdots$  (1) from Lemma 14.2.6(p.97) (a).
  - (a) The same as Tom 22.2.6(p.216)(a,b).
- (b) Let  $\beta=1$ . Then we have  $\boxed{\bullet \text{ dOITd}_{\tau>0}\langle 0\rangle}_{\parallel}$  from Tom 22.2.6(p.216) (b). Let  $\beta<1$ . Then, if s=0, due to (1) it suffices to consider only (c2) of Tom 22.2.6(p.216) and if s>0, then  $\kappa<0$  due to (1), hence it suffices to consider only (c2) of Tom 22.2.6(p.216) with  $\kappa$ . Thus, whether s=0 or s>0, we have the same result. Accordingly, whether  $\beta=1$  or  $\beta<1$ , we have the same result.
- $\square$  Nem 22.2.8 ( $\mathscr{A}\{M:2[\mathbb{P}][E]^-\}$ ) Suppose b<0. Assume  $\rho\leq a^\star$ . Let  $\beta<1$  or s>0 and let  $\rho>x_K$ .
- (a)  $V_t$  is nonincreasing in  $t \ge 0$ , is strictly decreasing in t > 0 if  $\lambda < 1$ , and converges to  $V = x_K$  as to  $t \to \infty$ .
- (b) Let  $\rho < x_L$ . Then  $subseteq dOITs_{\tau>0} \langle \tau \rangle$ .
- (c) Let  $\rho = x_L$ . Then  $\bullet dOITd_1\langle 0 \rangle_{\Delta}$  and  $\odot dOITs_{\tau > 1}\langle \tau \rangle_{\bullet}$ .
- (d) Let  $\rho > x_L$ .
  - 1. Let  $\beta = 1$ . Then  $\left[ \bullet dOITd_{\tau > 0} \langle 0 \rangle \right]_{\Delta}$ .
  - 2. Let  $\beta < 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle$   $\land$  ( $\bullet dOITd_{\tau > 0}\langle 0 \rangle$ ).
- Proof Suppose  $b < 0 \cdots (1)$ . Then  $\kappa = -s \cdots (2)$  from Lemma 14.2.6(p.97) (a).
  - (a-d1) The same as Tom 22.2.7(p.216) (a-d1).
- (d2) If s=0, then due to (1) it suffices to consider only (d2i) of Tom 22.2.7(p.216) and if s>0, then  $\kappa<0$  due to (2), hence it suffices to consider only (d2i) of Tom 22.2.7(p.216). Thus, whether s=0 or s>0, we have the same result.

#### 22.2.6.3.3.2.2 Case of $b \le \rho$

- $\square$  Nem 22.2.9 ( $\mathscr{A}\{M:2[\mathbb{P}[E]^-\}\}$ ) Suppose b < 0. Assume  $b \le \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho < x_K$ .
- (a)  $V_t$  is nondecreasing in  $t \ge 0$ , is strictly increasing in  $t \ge 0$  if  $\lambda < 1$ , and converges to a finite  $V = x_K$  as  $t \to \infty$ .
- (b) Let  $x_L \leq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}$ .
- (c) Let  $\rho < x_L$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}$ . Below let  $\tau > 1$ .

  - 3. Let  $\beta < 1$ . Then  $S_8(p.203)$   $\bullet \bullet \bullet \bullet \bullet$  is true.
- Proof Suppose  $b < 0 \cdots (1)$ . Then  $\kappa = \kappa_{\mathbb{P}} = -s \cdots (2)$  from Lemma 14.2.6(p.97) (a).
  - (a,c2) The same as Tom 22.2.8(p.216) (a,c2).
- (c3) If s=0, then due to (1) it suffices to consider only (c3ii) of Tom 22.2.8(p.216) and if s>0, then  $\kappa<0$  due to (2), hence it suffices to consider only (c3ii) of Tom 22.2.8(p.216). Thus, whether s=0 or s>0, we have the same result.
- $\square$  Nem 22.2.10 ( $\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]^-\}$ ) Suppose b<0. Assume  $b\leq\rho$ . Let  $\beta<1$  or s>0 and let  $\rho=x_K$ .

- (a)  $V_t = x_K = \rho \text{ for } t \geq 0.$
- (b) Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\beta < 1$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}$ .
- Proof Suppose  $b < 0 \cdots (1)$ . Then  $\kappa = -s \cdots (2)$  from Lemma 14.2.6(p.97) (a).
  - (a) The same as Tom 22.2.9(p.217) (a).
  - (b) Let  $\beta = 1$ . Then we have  $\boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}$  from Tom 27.2.23(p.274) (b).
- (c) Let  $\beta < 1$ . Then, if s = 0, then due to (1) it suffices to consider only (c2) of Tom 22.2.9(p.217) and if s > 0, then  $\kappa < 0$  due to (2), hence it suffices to consider only (c2) of Tom 22.2.9(p.217). Accordingly, whether s = 0 or s > 0, we have the same result.
- $\square \ \text{Nem 22.2.11 } (\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]^-\}) \quad \textit{Suppose } b < 0. \ \textit{Assume } b \leq \rho. \ \textit{Let } \beta < 1 \ \textit{or } s > 0 \ \textit{and let } \rho > x_K.$
- (a)  $V_t$  is nonincreasing in  $t \geq 0$ , is strictly decreasing in t > 0 if  $\lambda < 1$ , and converges to  $V = x_K$  as to  $t \to \infty$ .
- (b) Let  $\rho = x_L$ . Then  $\boxed{\bullet dOITd_1\langle 0 \rangle}_{\land}$  and  $\boxed{\$ dOITs_{\tau > 1}\langle \tau \rangle}_{\blacktriangle}$ .
- (c) Let  $\rho > x_L$ .
  - 1. Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}$ .
  - $2. \quad Let \ \beta < 1. \ Then \ \boxed{ \bullet \ \text{dOITd}_{\tau > 0} \langle 0 \rangle}_{\vartriangle} \ \left( \boxed{ \bullet \ \text{dOITd}_{\tau > 0} \langle 0 \rangle}_{\blacktriangle} \right) \ .$
- Proof Suppose  $b < 0 \cdots (1)$ . Then  $\kappa = -s \cdots (2)$  from Lemma 14.2.6(p.97) (a).
  - (a-c1) The same as Tom 22.2.10(p.217) (a-c1).
- (c2) If s = 0, then due to (1) it suffices to consider only (c2i) of Tom 22.2.10(p.217) and if s > 0, then  $\kappa < 0$  due to (2), hence it suffices to consider only (c2i) of Tom 22.2.10(p.217). Thus, whether s = 0 or s > 0, we have the same result.

#### 22.2.6.3.3.2.3 Case of $a^* < \rho < b$

- $\square$  Nem 22.2.12 ( $\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]^-\}$ ) Suppose b<0. Assume  $a^\star \leq \rho < a$ . Let  $\beta < 1$  or s>0.
- (a) If  $\lambda\beta \max\{0, a \rho\} < s$ , then  $\boxed{\bullet \text{ dOITd}_1\langle 0 \rangle}_{\vartriangle}$ , or else  $\boxed{\$ \text{ dOITs}_1\langle 1 \rangle}_{\blacktriangle}$ . Below let  $\tau > 1$ .
- (b) Let  $V_1 \leq x_K$ .
  - 1.  $V_t$  is nondecreasing in  $t \ge 0$  and converges to a finite  $V = x_K$  as  $t \to \infty$ .
  - 2. Let  $V_1 \geq x_L V_1$ . If  $\lambda \beta \max\{0, a \rho\} \leq s$ , then  $\boxed{\bullet \ \text{dOITd}_{\tau > 1}\langle 0 \rangle}_{\Delta}$ , or else  $\boxed{\odot \ \text{ndOIT}_{\tau > 1}\langle 1 \rangle}_{\Delta}$ .
  - 3. Let  $V_1 < x_L$ .
    - i. Let  $\beta = 1$ . Then  $S_{10}(p.217)$   $\bigcirc S_{\Delta} \bigcirc A$  is true.
    - ii. Let  $\beta < 1$ . Then  $S_{11}(p.217)$   $\bigcirc S_{\Delta} \bigcirc S_{\bullet} \bigcirc A_{\Delta}$  is true.
- (c) Let  $V_1 > x_K$ .
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V = x_K$  as  $t \to \infty$
  - 2. If  $\lambda\beta \max\{0, a-\rho\} < s$ , then  $\boxed{\bullet \ \text{dOITd}_{\tau>1}\langle 0 \rangle}_{\blacktriangle}$ , or else  $\boxed{\odot \ \text{ndOIT}_{\tau>1}\langle 1 \rangle}_{\vartriangle}$ .
- Proof Suppose  $b < 0 \cdots (1)$ , hence  $\kappa = -s \cdots (2)$  from Lemma 14.2.6(p.97) (a).
  - (a-b3i) The same as Tom 22.2.5(p.218) (a-b3i).
- (b3ii) Let  $\beta < 1$ . If s = 0, then due to (1) it suffices to consider only (b3ii3) of Tom 22.2.5(p.218) and if s > 0, then  $\kappa < 0$  due to (2), hence it suffices to consider only (b3ii3) of Tom 22.2.5(p.218). Thus, whether s = 0 or s > 0, we have the same result.
  - (c) Let  $V_1 > x_K$ .
  - (c1) The same as Tom 22.2.5(p.218) (c1)
- (c2) Let  $\beta=1$ . Then, we have the same as Tom 22.2.5(p.218) (c2). Let  $\beta<1$ . Then, if s=0, then due to (1) it suffices to consider only (c3ii) of Tom 22.2.5(p.218) and if s>0, then  $\kappa<0$  from (2), hence it suffices to consider only (c3ii) of Tom 22.2.5(p.218). Thus, whether s=0 or s>0, we have the same result. Accordingly, whether  $\beta=1$  or  $\beta<1$ , it eventually follows that we have the same result.

## **22.2.7** $\tilde{M}:2[\mathbb{P}][E]$

#### 22.2.7.1 Preliminary

Since Theorem 22.2.3(p.202) holds due to Lemma 22.2.1(p.202) (b), we can derive  $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]\}$  by applying  $\mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) to  $\mathscr{A}\{\mathsf{M}:2[\mathbb{P}][\mathsf{E}]\}$ .

#### 22.2.7.2 Analysis

## 22.2.7.2.1 Case of $\beta = 1$ and s = 0

- $\square$  Tom 22.2.11 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]\}$ ) Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in  $t \geq 0$ .
- (b) Let  $\rho \geq b^*$ . Then  $\boxed{\text{§ dOITs}_{\tau>0}\langle \tau \rangle}$
- (c) Let  $a \ge \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle$

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(d) Let b^* > \rho > a.
      1. Let b \geq \rho. Then \bullet dOITd_1\langle 0 \rangle_{\parallel} and \odot dOITs_{\tau > 1}\langle \tau \rangle_{\blacktriangle}.
      • Proof by symmetry Immediate from applying S_{\mathbb{P}\to\tilde{\mathbb{P}}} to Lemma 22.2.2(p.215).
Corollary 22.2.11 (\tilde{M}:2[\mathbb{P}][\mathbb{E}] ) Let \beta = 1 and s = 0. Then, z_t is nonincreasing in t \geq 0. \square
• Proof Immediate from Tom 22.2.11(p.227) (a) and from (7.2.111(p.36)) and Lemma A 3.3(p.306).
22.2.7.2.2 Case of \beta < 1 or s > 0
22.2.7.2.2.1 Case of \rho > b^*
\label{eq:continuous_problem} \mbox{$\square$ Tom 22.2.12 ($\mathscr{A}$\{M:2[\mathbb{P}][E]$\})$} \quad \mbox{$Assume$ $\rho \geq b^{\star}$. Let $\beta < 1$ or $s > 0$ and let $\rho > x_{\tilde{K}}$.}
(a) V_t is nonincreasing in t \geq 0, is strictly decreasing in t \geq 0 if \lambda < 1, and converges to a finite V = x_{\tilde{K}} as t \to \infty.
(b) Let x_{\tilde{L}} \geq \rho. Then | \bullet dOITd_{\tau > 0} \langle 0 \rangle |_{\Delta}.
(c) Let \rho > x_{\tilde{L}}.
      1. \boxed{\$ dOITs_1\langle 1 \rangle}_{\blacktriangle}. Below let \tau > 1.
      2. Let \beta = 1.
             i. Let (\lambda b + s)/\lambda \geq b^*.
                 1. Let \lambda = 1. Then \bigcirc ndOIT_{\tau > 1}\langle 1 \rangle.
                 ii. Let (\lambda b + s)/\lambda < b^{\star}. Then \boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}.
      3. Let \beta < 1 and s = 0 (s > 0).
             i. Let (\lambda \beta b + s)/\delta \geq b^*.
                 1. Let \lambda = 1.
                     i. Let a < 0 (\tilde{\kappa} < 0). Then subseteq dOITs_{\tau > 1} \langle \tau \rangle.
                     ii. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle_{\Delta}.
                 2. Let \lambda < 1.
                      i. Let a \leq 0 (\tilde{\kappa} \leq 0). Then s dOITs _{\tau>1}\langle \tau \rangle
                     ii. Let a > 0 (\tilde{\kappa} > 0) . Then S_8 \bullet \bullet \bullet \bullet is true.
            ii. Let (\lambda \beta b + s)/\delta < b^*.
                 1. Let a \leq 0 (\tilde{\kappa} \leq 0). Then \boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle} .
                 2. Let a > 0 (\tilde{\kappa} > 0). Then S_8 \bullet \bullet \bullet \bullet is true. \Box
• Proof by symmetry Immediate from applying \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}} to Tom 22.2.5(p.215).
Corollary 22.2.12 (\tilde{M}:2[\mathbb{P}][E]) Assume \rho \geq b^*. Let \beta < 1 or s > 0 and let \rho > x_{\tilde{K}}. Then, z_t is nonincreasing in t \geq 0. \square
• Proof Immediate from Tom 22.2.12(p.228) (a) and from (7.2.111(p.36)) and Lemma A 3.3(p.306). ■
\square Tom 22.2.13 (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]\}) Assume \rho \geq b^{\star}. Let \beta < 1 or s > 0 and let \rho = x_{\tilde{K}}.
(a) V_t = x_{\tilde{K}} = \rho \text{ for } t \geq 0.
(b) Let \beta = 1. Then \bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}.
(c) Let \beta < 1 and s = 0 (s > 0).
      1. Let a < 0 (\tilde{\kappa} < 0). Then \odot \text{dOITs}_{\tau > 0} \langle \tau \rangle.
      2. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \bullet dOITd_{\tau > 0}(0)
• Proof by symmetry Immediate from applying S_{\mathbb{P} \to \tilde{\mathbb{P}}} to Tom 22.2.6(p.216).
Corollary 22.2.13 (\tilde{\mathbb{M}}: 2[\mathbb{P}][E]) Assume \rho \geq b^*. Let \beta < 1 or s > 0 and let \rho = x_{\tilde{k}}. Then, z_t = z(\rho) for t \geq 0. \square

    Proof Immediate from Tom 22.2.13(p.228) (a) and from (7.2.111(p.36)) and Lemma A 3.3(p.306).

\square Tom 22.2.14 (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]\}) Assume \rho \geq b^{\star}. Let \beta < 1 or s > 0 and let \rho < x_{\tilde{K}}.
(a) V_t is nondecreasing in t \geq 0, is strictly increasing in t > 0 if \lambda < 1, and converges to V = x_{\tilde{K}} as to t \to \infty.
(b) Let \rho > x_{\tilde{L}}. Then subseteq dOITs_{\tau>0} \langle \tau \rangle.
(c) Let \rho = x_{\tilde{L}}. Then \bullet dOITd_1\langle 0 \rangle_{\Delta} and \bullet dOITs_{\tau>1}\langle \tau \rangle_{\Delta}.
(d) Let \rho < x_{\tilde{L}}.
      1. Let \beta = 1. Then \bullet dOITd_{\tau > 0}\langle 0 \rangle_{\Delta}.
      2. Let \beta < 1 and s = 0 (s > 0).
             i. Let a \geq 0 (\tilde{\kappa} \geq 0). Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta} (\bullet dOITd_{\tau>0}\langle 0 \rangle_{A}).
             ii. Let a < 0 (\tilde{\kappa} < 0). Then S_9 \stackrel{\textcircled{\$}_{\triangle}}{\bullet} \stackrel{\bullet}{\bullet} is true. \square
ullet Proof by symmetry Immediate from applying \mathcal{S}_{\mathbb{P} 	o \tilde{\mathbb{P}}} to Tom 22.2.7(p.216).
Corollary 22.2.14 (\tilde{\mathsf{M}}:2[\mathbb{P}[\mathbb{E}] ) Assume \rho \geq b^{\star}. Let \beta < 1 or s > 0 and let \rho < x_{\tilde{K}}. Then, z_t is nondecreasing in t \geq 0. \square
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• Proof Immediate from Tom 22.2.14(p.228) (a) and from (7.2.111(p.36)) and Lemma A 3.3(p.306).

#### 22.2.7.2.2. Case of $a \ge \rho$

 $\square$  Tom 22.2.15 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]\}$ ) Assume  $a \geq \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho > x_{\tilde{K}}$ .

- (a)  $V_t$  is nonincreasing in  $t \geq 0$ , is strictly decreasing in  $t \geq 0$  if  $\lambda < 1$ , and converges to a finite  $V = x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $x_{\tilde{L}} \geq \rho$ . Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle_{\Delta}$ .
- (c) Let  $\rho > x_{\tilde{L}}$ .
  - 1.  $\boxed{\$ dOITs_1\langle 1 \rangle}_{\blacktriangle}$ . Below let  $\tau > 1$ .

  - 3. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let  $a \leq 0$  ( $\tilde{\kappa} \leq 0$ ). Then  $\boxed{\$ dOITs_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$ .
    - ii. Let a>0 (  $\tilde{\kappa}>0$  ) . Then  $\mathbf{S}_8$  S  $\bullet$  0 | 0  $\bullet$  0  $\bullet$  is true.  $\Box$
- ullet Proof by symmetry Immediate from  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Tom 22.2.8(p.216).  $^{\dagger}$

Corollary 22.2.15 ( $\tilde{\mathsf{M}}$ :2[ $\mathbb{P}$ ][ $\mathbb{E}$ ]) Assume  $a \geq \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho > x_{\tilde{K}}$ . Then,  $z_t$  is nonincreasing in  $t \geq 0$ .

- Proof Immediate from Tom 22.2.15(p.229) (a) and from (7.2.111(p.36)) and Lemma A 3.3(p.306).
- $\square$  Tom 22.2.16 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]\}$ ) Assume  $a \geq \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho = x_{\tilde{K}}$ .
- (a)  $V_t = x_{\tilde{K}} = \rho \text{ for } t \geq 0.$
- (b) Let  $\beta = 1$ . Then  $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ .
- (c) Let  $\beta < 1$  and s = 0 (s > 0).
  - 1. Let  $a \leq 0$  ( $\tilde{\kappa} \leq 0$ ). Then subseteq 0 doins,  $a \leq 0$  ( $a \leq 0$ ).
  - 2. Let a > 0 ( $\tilde{\kappa} > 0$ ). Then  $\bullet dOITd_{\tau > 0} \langle 0 \rangle$   $\triangle$ .
- Proof by symmetry Immediate from  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Tom 22.2.9(p.217).

Corollary 22.2.16 ( $\tilde{\mathsf{M}}$ :2[ $\mathbb{P}$ ][ $\mathsf{E}$ ] ) Assume  $a \geq \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho = x_{\tilde{K}}$ . Then,  $z_t = z(\rho)$  for  $t \geq 0$ .  $\square$ 

- Proof Immediate from Tom 22.2.16(p.229) (a) and from (7.2.111(p.36)) and Lemma A 3.3(p.306).
- $\square$  Tom 22.2.17 ( $\mathscr{A}\{M:2[\mathbb{P}][E]\}$ ) Assume  $a \ge \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho < x_{\tilde{K}}$ .
- (a)  $V_t$  is nondecreasing in  $t \geq 0$ , is strictly increasing in t > 0 if  $\lambda < 1$ , and converges to  $V = x_{\tilde{K}}$  as to  $t \to \infty$ .
- (b) Let  $\rho = x_{\widetilde{L}}$ . Then  $\bullet dOITd_1\langle 0 \rangle_{\Delta}$  and  $\odot dOITs_{\tau > 1}\langle \tau \rangle_{\Delta}$ .
- (c) Let  $\rho < x_{\tilde{L}}$ .
  - 1. Let  $\beta = 1$ . Then  $\left[ \bullet dOITd_{\tau > 0} \langle 0 \rangle \right]_{\Delta}$ .
  - 2. Let  $\beta < 1$  and s = 0 ((s > 0)).
    - i. Let  $a \geq 0$  ( $\tilde{\kappa} \geq 0$ ). Then  $\bullet dOITd_{\tau>0}\langle 0 \rangle$  ( $\bullet dOITd_{\tau>0}\langle 0 \rangle$ ).
    - ii. Let a < 0 ( $\tilde{\kappa} < 0$ ). Then  $S_9$   $\stackrel{\textcircled{\$} \triangle}{\bullet}$   $\stackrel{\bullet}{\bullet}$  is true.  $\square$
- Proof by symmetry Immediate from  $\mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Tom 22.2.10(p.217).  $^{\ddagger}$

Corollary 22.2.17 (M:2[ $\mathbb{P}$ ][ $\mathbb{E}$ ] ) Assume  $a \geq \rho$ . Let  $\beta < 1$  or s > 0 and let  $\rho < x_{\tilde{K}}$ . Then,  $z_t$  is nondecreasing in  $t \geq 0$ .

Proof Immediate from Tom 22.2.17(p.229) (a) and from (7.2.111(p.36)) and Lemma A 3.3(p.306).

#### 22.2.7.2.2.3 Case of $b^* > \rho > a$

By applying  $S_{\mathbb{P}\to\mathbb{P}}$  in Theorem 22.2.3(p.202), we see that  $S_{10}(p.217) - 26.1.12$  change as follows respectively:

$$\mathbf{S}_{14} \overset{\textcircled{\$}\vartriangle}{\bullet} \bullet \vartriangle = \begin{cases} \text{We have:} \\ (1) \text{ Let } \lambda \min\{0, \rho - b\} > -s. \text{ Then } \overset{\textcircled{\$}}{\bullet} \text{ doITs}_{\tau > 1} \langle \tau \rangle_{\vartriangle} \text{ or } \bullet \text{ doITd}_{\tau > 0} \langle 0 \rangle_{\vartriangle}. \\ (2) \text{ Let } \lambda \min\{0, \rho - b\} \leq -s. \text{ Then } \overset{\textcircled{\$}}{\bullet} \text{ doITs}_{\tau > 1} \langle \tau \rangle_{\vartriangle}. \end{cases}$$

$$\mathbf{S}_{15} \overset{\textcircled{\$}\vartriangle}{\bullet} \overset{\textcircled{\$}\blacktriangle}{\bullet} \overset{\textcircled{\$}\blacktriangle}{\bullet} \overset{\textcircled{\$}\blacktriangle}{\bullet} \bullet \vartriangle \bullet \bullet \Longrightarrow$$

$$= \begin{cases} \text{There exists } t^{\bullet}_{\tau} > 1 \text{ such that:} \\ (1) \text{ If } \lambda \beta \min\{0, \rho - b\} > -s, \text{ then} \\ \text{i. } \overset{\textcircled{\$}}{\bullet} \text{ doITs}_{t^{\bullet}_{\tau} \geq \tau > 1} \langle \tau \rangle_{\vartriangle} \text{ or } \bullet \text{ doITd}_{t^{\bullet}_{\tau} \geq \tau > 1} \langle 0 \rangle_{\vartriangle}, \\ \text{ii. } \overset{\textcircled{\$}}{\bullet} \text{ ndoIT}_{\tau > t^{\bullet}_{\tau}} \langle t^{\bullet}_{\tau} \rangle_{\vartriangle} \text{ or } \bullet \text{ doITd}_{\tau > t^{\bullet}_{\tau}} \langle 0 \rangle_{\vartriangle}. \\ (2) \text{ If } \lambda \beta \min\{0, \rho - b\} \leq -s, \text{ then} \\ \text{i. } \overset{\textcircled{\$}}{\bullet} \text{ doITs}_{t^{\bullet}_{\tau} \geq \tau > 1} \langle \tau \rangle_{\blacktriangle}, \\ \text{ii. } \overset{\textcircled{\$}}{\bullet} \text{ ndoIT}_{\tau > t^{\bullet}_{\tau}} \langle t^{\bullet}_{\tau} \rangle_{\vartriangle}. \end{cases}$$

 $<sup>^{\</sup>dagger}S_{8}$  does not change by the application of the operation.

 $<sup>^{\</sup>ddagger}S_{9}$  does not change by the application of the operation.

$$\mathbf{S}_{16} \begin{tabular}{lll} \textbf{There exists } t^{\bullet}_{\boldsymbol{\tau}} > 1 \text{ such that:} \\ \textbf{(1)} & & & & & & & & & & \\ \textbf{(1)} & & & & & & & & \\ \textbf{(1)} & & & & & & & & \\ \textbf{(1)} & & & & & & & \\ \textbf{(1)} & & & & & & & \\ \textbf{(2)} & & & & & & & \\ \textbf{(2)} & & & & & & \\ \textbf{(3)} & & & & & \\ \textbf{(2)} & & & & & \\ \textbf{(4)} & & & & & \\ \textbf{(5)} & & & & & \\ \textbf{(5)} & & & & & \\ \textbf{(5)} & & & & & \\ \textbf{(6)} & & & & \\ \textbf{(1)} & & & & \\ \textbf{(2)} & & & & \\ \textbf{(2)} & & & & \\ \textbf{(3)} & & & & \\ \textbf{(1)} & & & & \\ \textbf{(2)} & & & & \\ \textbf{(3)} & & & & \\ \textbf{(4)} & & & & \\ \textbf{(5)} & & & & \\ \textbf{(5)} & & & & \\ \textbf{(5)} & & & \\ \textbf{(6)} & & & \\ \textbf{(7)} & & & & \\ \textbf{(7)} & & & & \\ \textbf{(7)} & & & & \\ \textbf{(8)} & & & \\ \textbf{(9)} & & & & \\ \textbf{(1)} & & & \\ \textbf{(1)} & & & & \\ \textbf{(1)} & & & & \\ \textbf{(1)} & & & & \\ \textbf{(2)} & & & & \\ \textbf{(3)} & & & & \\ \textbf{(4)} & & & & \\ \textbf{(5)} & & & & \\ \textbf{(5)} & & & & \\ \textbf{(5)} & & & & \\ \textbf{(6)} & & & & \\ \textbf{(7)} & & & & \\ \textbf{(7)} & & & & \\ \textbf{(7)} & & & & \\ \textbf{(8)} & & & & \\ \textbf{(1)} & & & & \\ \textbf{(1)} & & & & \\ \textbf{(2)} & & & & \\ \textbf{(2)} & & & & \\ \textbf{(2)} & & & & \\ \textbf{(3)} & & & & \\ \textbf{(4)} & & & & \\ \textbf{(5)} & & & & \\ \textbf{(5)} & & & \\ \textbf{(5)} & & & \\ \textbf{(5)} & & & \\ \textbf{(6)} & & & \\ \textbf{(7)} & & & \\ \textbf{(7)} & & & & \\ \textbf{(7)} & & & & \\ \textbf{(8)} & & & \\ \textbf{(9)} & & & & \\ \textbf{(1)} & & & \\ \textbf{(1)} & & & & \\ \textbf{(1)} & & & & \\ \textbf{(2)} & & & \\ \textbf{(2)} & & & \\ \textbf{(2)} & & & & \\ \textbf{(3)} & & & \\ \textbf{(4)} & & & \\ \textbf{(4)} & & & \\ \textbf{(5)} & & & \\ \textbf{(6)} & & & \\ \textbf{(7)} & & & \\ \textbf{(7)} & & & \\ \textbf{(7)} & & & \\ \textbf{(8)} & & & \\ \textbf$$

Moreover, note that (22.2.35(p.218)) can be changed into

$$V_1 = \lambda \beta \min\{0, \rho - b\} + \beta \rho + s. \tag{22.2.36}$$

 $\ \, \boxdot{\text{Tom 22.2.18}} \, \left( \mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]\} \right) \quad \textit{Assume } b^{\star} \geq \rho > a. \ \textit{Let } \beta < 1 \ \textit{or } s > 0.$ 

- (a) If  $\lambda\beta\min\{0,\rho-b\} \geq -s$ , then  $\boxed{\bullet \text{ dOITd}_1\langle 0 \rangle}_{\vartriangle}$ , or else  $\boxed{\$ \text{ dOITs}_1\langle 1 \rangle}_{\blacktriangle}$ . Below let  $\tau > 1$ .
- (b) Let  $V_1 \geq x_{\tilde{K}}$ .
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V = x_{\tilde{K}}$  as  $t \to \infty$ .
  - 2. Let  $V_1 \leq x_{\tilde{L}}$ . If  $\lambda \beta \min\{0, \rho b\} \geq -s$ , then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 0 \rangle}_{\Delta}$ , or else  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\Delta}$ .
  - 3. Let  $V_1 > x_{\tilde{L}}$ .
    - i. Let  $\beta = 1$ . Then  $S_{14}$   $\bigcirc \triangle$  is true.
    - ii. Let  $\beta < 1$  and s = 0 (s > 0).
      - 1. Let a < 0 ( $\tilde{\kappa} < 0$ ). Then  $S_{14}$   $\stackrel{\textcircled{\$}_{\triangle}}{\bullet}$  is true.
      - $2. \quad Let \ \ a=0 \ (\!(\tilde{\kappa}=0)\!) \ . \ \ If \ \lambda\beta \min\{0,\rho-b\}>-s, \ then \ \boxed{\$ \ dOITs_{\tau>1}\langle\tau\rangle}_{\vartriangle} \ \ or \ \boxed{\$ \ dOITd_{\tau>1}\langle0\rangle}_{\vartriangle}, \ or \ else \ \boxed{\$ \ dOITs_{\tau>1}\langle\tau\rangle}_{\vartriangle}$
      - 3. Let a > 0 ( $\tilde{\kappa} > 0$ ). Then  $S_{15}$   $\stackrel{\textcircled{\$}_{\triangle}}{}$   $\stackrel{\textcircled{\$}_{\triangle}}{}$   $\stackrel{\textcircled{\$}_{\triangle}}{}$  is true.
- (c) Let  $V_1 < x_{\tilde{K}}$ .
  - 1.  $V_t$  is nondecreasing in  $t \ge 0$  and converges to a finite  $V = x_{\tilde{K}}$  as  $t \to \infty$ .
  - 2. Let  $\beta = 1$ . If  $\lambda \beta \min\{0, \rho b\} > -s$ , then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 0 \rangle}_{\Delta}$ , or else  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\blacktriangle}$ .
  - 3. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let a < 0 ( $\tilde{\kappa} < 0$ ).
      - 1. Let  $V_1 \geq x_{\tilde{L}}$ . Then  $S_{14} \ \odot \triangle \$  is true.

      - 3. Let  $V_1 < x_{\tilde{L}}$ . Then  $S_{17} \stackrel{\textcircled{\$} \triangle}{\longrightarrow} \stackrel{\textcircled{\triangle}}{\longrightarrow} \stackrel{\bigstar}{\longrightarrow} is true$ .
    - ii. Let  $a \geq 0$  ( $\tilde{\kappa} \geq 0$ ). If  $\lambda \beta \min\{0, \rho b\} > -s$ , then  $\bullet \text{dOITd}_{\tau > 1}\langle 0 \rangle$  , or else  $\odot \text{ndOIT}_{\tau > 1}\langle 1 \rangle$  .  $\square$
- Proof by symmetry Immediate from  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$  to Tom 22.2.5(p.218).

Corollary 22.2.18 ( $\tilde{\mathsf{M}}$ :2[ $\mathbb{P}$ ][ $\mathbb{E}$ ] ) Assume  $b^* \geq \rho > a$ . Let  $\beta < 1$  or s > 0.

- (a) Let  $V_1 \geq x_{\tilde{K}}$ . Then  $z_t$  is nonincreasing in t > 0.
- (b) Let  $V_1 < x_{\tilde{K}}$ . Then  $z_t$  is nondecreasing in t > 0.  $\square$
- Proof Immediate from Tom 22.2.18(p.230) (b1,c1) and from (7.2.111(p.36)) and Lemma A 3.3(p.306).

 $<sup>^{\</sup>dagger}V_1 = \lambda\beta \min\{0, b - \rho\} + \beta\rho + s \text{ (see (7.4.25(p.41)))}.$ 

## 22.2.7.3 Market Restriction 22.2.7.3.1 Positive Restriction **22.2.7.3.1.1** $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]^{\top}\}$ 22.2.7.3.1.1.1 Case of $\beta = 1$ and s = 0 $\square$ Pom 22.2.17 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}[\mathsf{E}]^+\}\}$ ) Suppose a>0. Let $\beta=1$ and s=0. (a) $V_t$ is nonincreasing in $t \geq 0$ . (b) Let $\rho \geq b^*$ . Then $subseteq dOITs_{\tau>0} \langle \tau \rangle$ . (c) Let $a \geq \rho$ . Then $\bullet dOITd_{\tau > 0}\langle 0 \rangle_{\parallel}$ . (d) Let $b^* > \rho > a$ . 1. Let $b \geq \rho$ . Then $\bullet dOITd_1\langle 0 \rangle$ and $\circ dOITs_{\tau>1}\langle \tau \rangle$ . • Proof by diagonal-symmetry Immediate from applying $S_{\mathbb{P} \to \mathbb{P}}$ (see (20.0.3(p.136))) to Nem 22.2.5(p.225). • Direct proof The same as Tom 22.2.11(p.227) due to Lemma 18.4.4(p.118). 22.2.7.3.1.1.2 Case of $\beta < 1$ or s > 022.2.7.3.1.1.2.1 Case of $\rho \ge b^*$ $\square$ Pom 22.2.18 ( $\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{P}][\mathbb{E}]^+\}$ ) Suppose a>0. Assume $\rho\geq b^\star$ . Let $\beta<1$ or s>0 and let $\rho>x_{\tilde{K}}$ . (a) $V_t$ is nonincreasing in $t \geq 0$ , is strictly decreasing in $t \geq 0$ if $\lambda < 1$ , and converges to a finite $V = x_{\tilde{K}}$ as $t \to \infty$ . (b) Let $x_{\tilde{L}} \geq \rho$ . Then $\left[ \bullet dOITd_{\tau > 0} \langle 0 \rangle \right]_{\Delta}$ . (c) Let $\rho > x_{\tilde{L}}$ . 1. $\boxed{\$ dOITs_1\langle 1 \rangle}$ and $Conduct_1$ . Below let $\tau > 1$ . 2. Let $\beta = 1$ . i. Let $(\lambda b + s)/\lambda \ge b^*$ . 1. Let $\lambda = 1$ . Then $\bigcirc$ ndOIT $_{\tau > 1}\langle 1 \rangle$ ii. Let $(\lambda b + s)/\lambda < b^{\star}$ . Then $\boxed{\$ dOITs_{\tau > 0} \langle \tau \rangle}_{\blacktriangle}$ . 3. Let $\beta < 1$ and s = 0. Then $S_8 \ \odot \ \odot \ \odot \ \odot \ \Delta \ \odot \ \bullet \$ is true. 4. Let $\beta < 1$ and s > 0. i. Let $(\lambda \beta b + s)/\delta \ge b^*$ . 1. Let $\lambda = 1$ . Then $\bigcirc$ ndOIT $_{\tau}\langle 1 \rangle$ $_{\triangle}$ . ii. Let $(\lambda \beta b + s)/\delta < b^*$ . Then $S_8(p.203)$ $\bullet \bullet \bullet \bullet \bullet$ is true. • Proof by diagonal-symmetry Immediate from applying $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$ (see (20.0.3(p.136))) to Nem 22.2.6(p.225) (see (22.2.20(p.203))). • Direct proof Suppose $a>0\cdots (1)$ , hence $b^*>b>a>0\cdots (2)$ from Lemma 15.6.1(p.107) (n). Then we have $\tilde{\kappa}=s\cdots (3)$ from Lemma 15.6.6(p.108) (a). (a-c2ii) The same as Tom 22.2.12(p.228) (a-c2ii). (c3) Let $\beta < 1$ and s = 0, hence $\tilde{\kappa} = 0$ due to (3). Assume $(\lambda \beta b + s)/\delta \ge b^*$ . Then since $\lambda \beta b/\delta \ge b^*$ , we have $\lambda \beta b \ge \delta b^*$ from $(11.2.2\,(1)\,(p.56))$ , hence $\lambda\beta b \geq \delta b^* \geq \lambda b^*$ due to (2), so $\beta b \geq b^*$ , which contradicts [7(p.118)]. Thus it must be that $(\lambda\beta b+s)/\delta < b^*$ . From this it suffices to consider only (c3ii2) of Tom 22.2.12(p.228). (c4-c4ii) Let $\beta < 1$ and s > 0. Then $\tilde{\kappa} > 0$ from (3), hence it suffices to consider only (c3i1ii,c3i2ii,c3ii2) of Tom 22.2.12(p.228) with $\kappa$ .

- $\square$  Pom 22.2.19 ( $\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{P}][\mathsf{E}]^+\}$ ) Suppose a>0. Assume  $\rho\geq b^\star$ . Let  $\beta<1$  or s>0 and let  $\rho=x_{\tilde{K}}$ .
- (a)  $V_t = x_{\tilde{K}} = \rho \text{ for } t \geq 0.$
- (b) We have  $| \bullet dOITd_{\tau>0} \langle 0 \rangle |_{\parallel}$ .
- Proof by diagonal-symmetry Immediate from applying  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) to Nem 22.2.7(p.226) (see (22.2.20(p.203))).
- Direct proof Let  $a > 0 \cdots (1)$ , then  $\tilde{\kappa} = s \cdots (2)$  from Lemma 15.6.6(p.108) (a).
  - (a) The same as Tom 22.2.13(p.228) (a).
- (b) Let  $\beta = 1$ . Then we have Tom 22.2.13(p.228) (a). Let  $\beta < 1$ . Then, if s = 0, due to (1) it suffices to consider only (c2) of Tom 22.2.13(p.228) and if s>0, then  $\tilde{\kappa}>0$  from (2), hence it suffices to consider only (c2 of Tom 22.2.13(p.228). Thus, whether s=0 or s>0, we have the same result.

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\square Pom 22.2.20 (\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{P}][\mathbb{E}]^+\}) Suppose a>0. Assume \rho\geq b^\star. Let \beta<1 or s>0 and let \rho< x_{\tilde{K}}.
(a) V_t is nondecreasing in t > 0, is strictly increasing in t > 0 if \lambda < 1, and converges to V = x_{\tilde{K}} as to t \to \infty.
(b) Let \rho > x_{\tilde{L}}. Then S dOITs _{\tau > 0} \langle \tau \rangle
(c) Let \rho = x_{\tilde{L}}. Then \boxed{\bullet dOITd_1\langle 0 \rangle}_{\Delta} and \boxed{\$ dOITs_{\tau > 1}\langle \tau \rangle}_{\blacktriangle}.
(d) Let \rho < x_{\tilde{L}}.
     1. Let \beta = 1. Then \bullet dOITd_{\tau > 0}\langle 0 \rangle_{\Delta}.
     2. Let \beta < 1. Then \bullet dOITd_{\tau>0}\langle 0 \rangle_{\triangle} (\bullet dOITd_{\tau>0}\langle 0 \rangle_{\blacktriangle}).
ullet Proof by diagonal-symmetry Immediate from applying \mathcal{S}_{\mathbb{P} 	o \tilde{\mathbb{P}}} (see (20.0.3(p.136))) to
Nem 22.2.8(p.226) (see (22.2.20(p.203))).
• Direct proof Suppose a > 0 \cdots (1). Then \tilde{\kappa} = s \cdots (2) due to Lemma 15.6.6(p.108) (a).
   (a-d1) The same as Tom 22.2.14(p.228) (a-d1).
   (d2) If s = 0, due to (1) it suffices to consider only (d2i) of Tom 22.2.14(p.228) and if s > 0, then \tilde{\kappa} > 0 due to (2), hence it
suffices to consider only (d2i) of Tom 22.2.14(p.228). Thus, whether s = 0 or s > 0, we have the same result.
22.2.7.3.1.1.2.2 Case of a \ge \rho
\square Pom 22.2.21 (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]^+\}) Suppose a>0. Assume a\geq\rho. Let \beta<1 or s>0 and let \rho>x_{\tilde{K}}.
(a) V_t is nonincreasing in t \geq 0, is strictly decreasing in t \geq 0 if \lambda < 1, and converges to a finite V = x_{\tilde{K}} as t \to \infty.
(b) Let x_{\tilde{L}} \geq \rho. Then \bullet dOITd_{\tau > 0}\langle 0 \rangle_{\Delta}.
(c) Let \rho > x_{\tilde{L}}.
     1. \boxed{\$ dOITs_1\langle 1 \rangle}_{\blacktriangle}. Below let \tau > 1.
     • Proof by diagonal-symmetry Immediate from applying S_{\mathbb{P} \to \tilde{\mathbb{P}}} (see (20.0.3(p.136))) to
Nem 22.2.9(p.226) (see (22.2.20(p.203))).
• Direct proof Suppose a > 0 \cdots (1). Then \tilde{\kappa} = s \cdots (2) from Lemma 15.6.6(p.108) (a).
   (a-c2) The same as Tom 22.2.15(p.229) (a-c2).
   (c3) If s = 0, due to (1) it suffices to consider only (c3ii) of Tom 22.2.15(p.229) and if s > 0, then \tilde{\kappa} > 0 due to (2), hence it
suffices to consider only (c3ii) of Tom 22.2.15(p.229). Thus, whether s=0 or s>0, we have the same result.
\square Pom 22.2.22 (\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{P}][\mathbb{E}]^+\}) Suppose a>0. Assume a\geq\rho. Let \beta<1 or s>0 and let \rho=x_{\tilde{K}}.
(a) V_t = x_{\tilde{K}} = \rho \text{ for } t \geq 0.
(b) Let \beta = 1. Then we have \bullet dOITd_{\tau>0}\langle 0 \rangle_{\parallel}.
(c) Let \beta < 1. Then we have \boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\Delta}.
• Proof by diagonal-symmetry Immediate from applying \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}} (see (20.0.3(p.136))) to
Nem 22.2.10(p.226) (see (22.2.20(p.203))).
• Direct proof Suppose a > 0 \cdots (1). Then \tilde{\kappa} = s \cdots (2) from Lemma 15.6.6(p.108) (a).
   (a) The same as Tom 22.2.16(p.229) (a).
   (b) The same as Tom 22.2.16(p.229) (b).
   (c) Let \beta < 1. If s = 0, due to (1) it suffices to consider only (c2) of Tom 22.2.16(p.229). If s > 0, then \tilde{\kappa} > 0 due to (2), hence
it suffices to consider only (c2) of Tom 22.2.16(p.229). Thus, whether s=0 or s>0, we have the same result.
\square Pom 22.2.23 (\mathscr{A}\{\tilde{\mathbb{M}}:2[\mathbb{P}][\mathbb{E}]^+\}) Suppose a>0. Assume a\geq\rho. Let \beta<1 or s>0 and let \rho< x_{\tilde{K}}.
(a) V_t is nondecreasing in t \geq 0, is strictly increasing in t > 0 if \lambda < 1, and converges to V = x_{\tilde{K}} as to t \to \infty.
(b) Let \rho = x_{\tilde{L}}. Then \bullet dOITd_1\langle 0 \rangle_{\Delta} and \circ dOITs_{\tau>1}\langle \tau \rangle_{\Delta}.
(c) Let \rho < x_{\tilde{L}}.
     1. Let \beta = 1. Then | \bullet dOITd_{\tau > 0} \langle 0 \rangle |_{\Delta}.
     2. Let \beta < 1 and let s = 0 (s > 0). Then \bullet dOITd_{\tau > 0} \langle 0 \rangle |_{\Delta} (\bullet dOITd_{\tau > 0} \langle 0 \rangle |_{\Delta}).
• Proof by diagonal-symmetry Immediate from applying S_{\mathbb{P} \to \tilde{\mathbb{P}}} (see (20.0.3(p.136))) to
Nem 22.2.11(p.227) (see (22.2.20(p.203))).
• Direct proof Suppose a > 0 \cdots (1). Then \tilde{\kappa} = s \cdots (2) due to Lemma 15.6.6(p.108) (a).
   (a,b) The same as Tom 22.2.17(p.229) (a,b).
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(c) Let  $\rho < x_{\tilde{L}}$ .

- (c1) Let  $\beta = 1$ . Then we have  $\boxed{\bullet \text{ dOITd}_{\tau > 0}\langle 0 \rangle}_{\Delta}$  from Tom 22.2.17(p.229) (c1).
- (c2) Let  $\beta < 1$ . If s = 0, then due to (2) it suffices to consider only (c2i) of Tom 22.2.17(p.229) and if s > 0, then  $\tilde{\kappa} > 0$  due to (2), hence it suffices to consider only (c2i) of Tom 22.2.17(p.229). Thus, whether s = 0 or s > 0, we have the same result.

#### 22.2.7.3.1.1.2.3 Case of $b^* > \rho > a$

- $\square$  Pom 22.2.24 ( $\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]^+\}$ ) Suppose a>0. Assume  $b^*\geq\rho>a$ . Let  $\beta<1$  or s>0.
- (a) If  $\lambda\beta \max\{0, \rho b\} \leq s$ , then  $\boxed{\bullet \text{ dOITd}_1\langle 0 \rangle}_{\vartriangle}$ , or else  $\boxed{\$ \text{ dOITs}_1\langle 1 \rangle}_{\blacktriangle}$ . Below let  $\tau > 1$ .
- (b) Let  $V_1 > x_{\tilde{K}}$ .
  - 1.  $V_t$  is nonincreasing in  $t \geq 0$  and converges to a finite  $V = x_{\tilde{K}}$  as  $t \to \infty$ .
  - 2. Let  $V_1 \geq x_{\tilde{L}}$ . If  $\lambda \beta \max\{0, \rho b\} \leq s$ , then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 0 \rangle}_{\Delta}$ , or else  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\Delta}$ .
  - 3. Let  $V_1 > x_{\tilde{L}}$ .
    - i. Let  $\beta = 1$ . Then  $S_{14}(p.229)$   $\bigcirc S_{\Delta} \bigcirc \bullet_{\Delta}$  is true.
    - ii. Let  $\beta < 1$ . Then  $S_{15}(p.229)$   $S_{\Delta} S_{\Delta} O_{\Delta} O_{\Delta}$  is true.
- (c) Let  $V_1 < x_{\tilde{K}}$ .
  - 1.  $V_t$  is nondecreasing in  $t \geq 0$  and converges to a finite  $V = x_{\tilde{K}}$  as  $t \to \infty$ .
  - 2. If  $\lambda\beta \max\{0, \rho b\} < s$ , then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 0 \rangle}_{\blacktriangle}$ , or else  $\boxed{\odot \text{ ndOIT}_{\tau > 1}\langle 1 \rangle}_{\vartriangle}$
- Proof by diagonal-symmetry Immediate from applying  $\mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) to Nem 22.2.12(p.227) (see (22.2.20(p.203))). ■
- Direct proof Suppose  $a > 0 \cdots$  (1), hence b > a > 0. Then  $\tilde{\kappa} = s \cdots$  (2) due to Lemma 15.6.6(p.108) (a).
  - (a-b3i) The same as Tom 22.2.18(p.230) (a-b3i).
- (b3ii) Let  $\beta < 1$ . If s = 0, then due to (1) it suffices to consider only (b3ii3) of Tom 22.2.18(p.230) and if s > 0, then  $\tilde{\kappa} > 0$  due to (2), hence it suffices to consider only (b3ii3) of Tom 22.2.18(p.230). Thus, whether s = 0 or s > 0, we have the same result.
  - (c1) The same as Tom 22.2.18(p.230) (c1).
- (c2) If  $\beta = 1$ , then it suffices to consider only (c2) of Tom 22.2.18(p.230) and if  $\beta < 1$ , whether s = 0 or s > 0, it suffices to consider only (c3ii) of Tom 22.2.18(p.230). Accordingly, whether  $\beta = 1$  or  $\beta < 1$ , we have the same result.

#### 22.2.7.3.2 Mixed Restriction

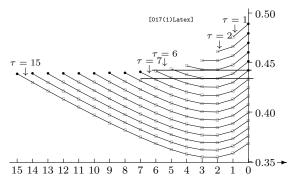
Omitted.

#### 22.2.7.3.3 Negative Restriction

Unnecessary.

#### 22.2.7.4 Numerical Calculation

Numerical Example 6 ( $\mathscr{A}[\mathbb{R}][\mathbb{E}]^+$ ) (selling model) This example is for the assertion in Pom 22.2.4(p.210) (d3ii) in which a>0,  $\rho>x_K$ ,  $\rho>x_L$ ,  $\beta<1$ , s>0, and  $\lambda\beta\mu>s$ . As an example let a=0.01, b=1.00,  $\lambda=0.7$ ,  $\beta=0.98$ , s=0.1, and  $\rho=0.5$ .† where  $x_L=0.462767$  and  $x_K=0.439640$ . The symbols • in the figure below shows the optimal initiating times  $t_{15\geq \tau\geq 1}^*$  (see the  $t_{\tau}^*$ -column in the table of Figure 22.2.2(p.233) below).



t	$V_t$	$\Delta_{\beta}V_{t}$	$t_{ au}^*$		
0	0.5000000				
1	0.4766162	-0.0133838	1		
2	0.4619911	-0.0050927	1		
3	0.4530367	+0.0002854	1		
4	0.4476274	+0.0036514	1		
5	0.4443866	+0.0057117	1		
6	0.4424547	+0.0069558	1		
7	0.4413065	+0.0077009	7		
8	0.4406253	+0.0081449	8		
9	0.4402216	+0.0084088	9		
10	0.4399825	+0.0085653	10		
11	0.4398410	+0.0086581	11		
12	0.4397572	+0.0087130	12		
13	0.4397076	+0.0087456	13		
14	0.4396783	+0.0087648	14		
15	0.4396609	+0.0087762	15		
$\Delta_{\beta}V_t = V_t - \beta V_{t-1}$ [017(1)Data.DAT]					

Graphs of  $I_{\tau}^t = \beta^{\tau - t} V_t$  with  $15 \ge \tau > 0$  and  $\tau \ge t \ge 0$  [FIG7498x]

Figure 22.2.2: Graphs of  $I_{\tau}^t = \beta^{\tau-t}V_t$  for  $15 \ge \tau \ge 2$  and  $\tau \ge t \ge 1$ 

 $<sup>^{\</sup>dagger}V_{1} = \lambda\beta\min\{0, b - \rho\} + \beta\rho + s \text{ (see (7.4.25(p.41)))}.$ 

<sup>&</sup>lt;sup>†</sup>We have  $\rho = 0.5 > 0.462767 = x_L$ ,  $\beta = 0.98 < 1$ , and s = 0.1 > 0. Since  $\mu = (0.01 + 1.00)/2 = 0.505$ , we have  $\lambda \beta \mu = 0.7 \times 0.98 \times 0.505 = 0.34634 > 0.1 = s$ . Thus the condition of this assertion is confirmed.

Scaling up the graphs for  $\tau = 6$  and  $\tau = 7$  in the above figure, we have the figure below. This figure demonstrates that the optimal initiating time shifts from 0 to 7 when the starting time changes from  $\tau = 6$  to  $\tau = 7$ .

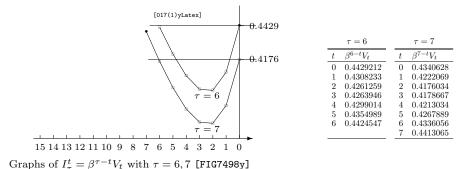


Figure 22.2.3: Graphs of  $I_{\tau}^{t} = \beta^{\tau-t}V_{t}$  for  $\tau = 6$  and  $\tau = 7$ 

#### 22.2.7.5 Conclusion 4 (Search-Enforced-Model 2)

#### C1. Mental Conflict

On  $\mathscr{F}^+$ , we have:

- a. Let  $\beta = 1$  and s = 0.
  - 1. The opt- $\mathbb{R}$ -price  $V_t$  in M:2[ $\mathbb{R}$ ][E] (selling model) is nondecreasing in  $t^{4a}$  as in Figure 8.4.1(p.48) (I), hence we have the normal conflict (see Remark 8.4.1(p.48)).
  - 2. The opt- $\mathbb{P}$ -price  $z_t$  in M:2[ $\mathbb{P}$ ][E] (selling model) is nondecreasing in  $t^{\bullet}$  as in Figure 8.4.1(p.48) (I), hence we have the normal conflict (see Remark 8.4.1(p.48)).
  - 3. The opt- $\mathbb{R}$ -price  $V_t$  in  $\tilde{\mathsf{M}}$ :2[ $\mathbb{R}$ ][E] (buying model) is nonincreasing in  $t^{\P^c}$  as in Figure 8.4.1(p.48) (II), hence we have the normal conflict (see Remark 8.4.1(p.48)).
  - 4. The opt- $\mathbb{P}$ -price  $z_t$  in  $\tilde{M}:2[\mathbb{P}][E]$  (buying model) is nonincreasing in t as in Figure 8.4.1(p.48) (II), hence we have the normal conflict (see Remark 8.4.1(p.48)),  $\mathbf{r}^d$ .
  - $\cdot$  'a  $\leftarrow$  Tom 22.2.1(p.203) (a)
  - ·  $^{1^{\text{b}}} \leftarrow \text{Corollary } 22.2.3(p.215)$
  - $\cdot$   $\mathbf{v}^{c} \leftarrow \mathtt{Tom} \ 22.2.1(p.211) \ (a)$
  - $\cdot \ {}^{\mathbf{t}^{\mathbf{d}}} \leftarrow \mathbf{Corollary} \ 22.2.11 (\texttt{p.228}) \, .$

## b. Let $\beta < 1$ or s > 0.

- 1. The opt- $\mathbb{R}$ -price  $V_t$  in  $M:2[\mathbb{R}][E]$  (selling model) is nondecreasing in  $t^{\mathbf{1}^a}$ , constant  $\mathbb{R}^a$ , or nonincreasing in  $t^{\mathbf{1}^a}$  as in Figure 8.4.2(p.48) (I), hence we have the abnormal conflict (see Remark 8.4.2(p.48)).
- 2. The opt- $\mathbb{P}$ -price  $z_t$  in M:2[ $\mathbb{P}$ ][E] (selling model) is nondecreasing in  $t^{\bullet}$ , constant  $|^{b}$ , or nonincreasing in  $t^{\bullet}$  as in Figure 8.4.2(p.48) (I), hence we have the abnormal conflict (see Remark 8.4.2(p.48)).
- 3. The opt- $\mathbb{R}$ -price  $V_t$  in  $\widetilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]$  (buying model) is nondecreasing in  $t^{\bullet^c}$ , constant  $|^c$ , or nonincreasing in  $t^{\bullet^c}$  as in Figure 8.4.2(p.48) (II), hence we have the abnormal conflict (see Remark 8.4.2(p.48)).
- 4. The opt- $\mathbb{P}$ -price  $z_t$  in  $\tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]$  (buying model) is nondecreasing in  $t^{\mathbf{I}^d}$ , constant  $\mathbb{P}^d$ , or nonincreasing in  $t^{\mathbf{I}^d}$  as in Figure 8.4.2(p.48) (II), hence we have the abnormal conflict (see Remark 8.4.2(p.48)).

The above results can be summarized as below.

A. If  $\beta = 1$  and s = 0, then, on  $\mathscr{F}^+$ , whether selling problem or buying problem and whether  $\mathbb{R}$ -mechanism-model or  $\mathbb{P}$ -mechanism-model, we have the normal mental conflict, which coincides with *expectations* in *Examples* 1.3.1(p5) - 1.3.4(p.6).

B. If  $\beta < 1$  or s > 0, then, on  $\mathscr{F}^+$ , whether selling problem or buying problem and whether  $\mathbb{R}$ -mechanism-model or  $\mathbb{P}$ -mechanism-model, we have the abnormal mental conflict, which does not coinside with *expectations* in *Examples* 1.3.1(p.5) - 1.3.4(p.6).

#### C2. Symmetry

On  $\mathscr{F}^+$ , we have:

a. Let  $\beta = 1$  and s = 0. Then we have:

	Pom $22.2.5$ (p.212)	$\sim$ Pom $22.2.1$ (p.209)	$(\mathscr{A}\{\tilde{M}:2[\mathbb{R}][E]\}^+ \sim \mathscr{A}\{M:2[\mathbb{R}][E]\}^+),$
	Pom $22.2.17$ (p.231)	$\sim \texttt{Pom} \ 22.2.9 (\texttt{p.222})$	$(\mathscr{A}\{\tilde{M}{:}2[\mathbb{P}][E]\}^+ \sim \mathscr{A}\{M{:}2[\mathbb{P}][E]\}^+).$
b.	Let $\beta < 1$ or $s > 0$ . Then we have:		
	Pom $22.2.6$ (p.212)	$\not \sim \texttt{Pom} \ 22.2.2(\texttt{p.209})$	$(\mathscr{A}\{\tilde{M}:2[\mathbb{R}][E]\}^+ \not\sim \mathscr{A}\{M:2[\mathbb{R}][E]\}^+)$
	Pom $22.2.7$ (p.213)	$\not \sim \texttt{Pom} \ 22.2.3 \texttt{(p.209)}$	$(\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}][E]\}^+ \not\sim \mathscr{A}\{M{:}2[\mathbb{R}][E]\}^+)$
	${\tt Pom}\ 22.2.8 {\scriptsize (p.213)}$	$\not \sim \texttt{Pom} \ 22.2.4 (\texttt{p.210})$	$(\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}][E]\}^+ \not \!$
	Pom $22.2.18$ (p.231)	$\not \sim \texttt{Pom} \ 22.2.10 (\texttt{p.223})$	$(\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}][E]\}^+ \not \!$
	Pom $22.2.19$ (p.231)	$\not \sim \mathtt{Pom}\ 22.2.11(\mathtt{p.223})$	$(\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}][E]\}^+ \not \!$
	Pom $22.2.20$ (p.232)	$\not \sim \texttt{Pom} \ 22.2.12 \texttt{(p.223)}$	$(\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}][E]\}^+ \not \!$
	Pom $22.2.21$ (p.232)	$\not \sim \texttt{Pom} \ 22.2.13 \texttt{(p.224)}$	$(\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}][E]\}^+ \not \!$
	${\tt Pom}\ 22.2.22 \hbox{(p.232)}$	$\not \sim \texttt{Pom} \ 22.2.14 (\texttt{p.224})$	$(\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}][E]\}^+ \not\sim \mathscr{A}\{M{:}2[\mathbb{R}][E]\}^+)$
	Pom $22.2.23$ (p.232)	$\not \sim \texttt{Pom} \ 22.2.15 (\texttt{p.224})$	$(\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}][E]\}^+ \not \!$
	Pom $22.2.24$ (p.233)	$\not \sim \texttt{Pom} \ 22.2.16 (\texttt{p.224})$	$(\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}][E]\}^+ \not \!$

The above results can be summarized as below.

- A. Let  $\beta = 1$  and s = 0. Then the symmetry is always inherited (see C2a(p.235)).
- B. Let  $\beta < 1$  or s > 0. Then the symmetry always collapses (see C2b(p.235)).

#### C3. Analogy

a. On  $\mathscr{F}^+$ , for any  $\beta \leq 1$  and  $s \geq 0$  we have:

```
(\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^+ \not\bowtie \mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}^+)
Pom 22.2.9(p.222)
                                                      Pom 22.2.1(p.209)
Pom 22.2.10(p.223)
                                                     \triangleright Pom 22.2.2(p.209)
                                                                                                   (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^+ \bowtie \mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}^+)
                                                                                                   (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^+\bowtie\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}^+)\cdots(*)
Pom 22.2.11(p.223)
                                                     \bowtie Pom 22.2.3(p.209)
Pom 22.2.12(p.223)
                                                     \bowtie \text{ Pom } 22.2.4(\text{p.210}) \quad (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^+ \bowtie \mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}^+)
                                                                                                   (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^+ \bowtie \mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}^+)
Pom 22.2.17(p.231)
                                                     Pom 22.2.5(p.212)
Pom 22.2.18(p.231)
                                                     \bowtie \text{ Pom } 22.2.6 \text{ (p.212)} \quad (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^+ \bowtie \mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}^+)
Pom 22.2.19(p.231)
                                                     \bowtie \text{ Pom } 22.2.7 \text{ (p.213)} \quad (\mathscr{A}\{M:2[\mathbb{R}][\mathsf{E}]\}^+ \bowtie \mathscr{A}\{M:2[\mathbb{R}][\mathsf{E}]\}^+)
                                                                                                    (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^+ \bowtie \mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}^+)
{\tt Pom}\ 22.2.20 (p.232)
                                                     \triangleright Pom 22.2.8(p.213)
Pom 22.2.21(p.232)
                                                     Pom 22.2.6(p.212)
                                                                                                  (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^+ \bowtie \mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}^+)
                                                                                                   (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^+\bowtie\mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}^+)\cdots(**)
Pom 22.2.22(p.232)
                                                     \bowtie Pom 22.2.7(p.213)
                                                                                                    (\mathscr{A}\{\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^+ \bowtie \mathscr{A}\{\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}^+)
Pom 22.2.23(p.232)
                                                     \triangleright Pom 22.2.8(p.213)
```

The above results can be summarized as below.

A. The analogy collapses except (\*) and (\*\*).

## C4. Optimal initiating time (OIT)

On  $\mathscr{F}^+$ , we have:

a. Let  $\beta = 1$  and s = 0. Then, from

Pom 22.2.1(p.209), Pom 22.2.5(p.212), Pom 22.2.9(p.222), Pom 22.2.17(p.231), we obtain the following table.

Table 22.2.3: Possible OIT on  $\mathscr{F}^+$   $(\beta=1 \text{ and } s=0)$ 

		$\mathscr{A}\{M{:}2[\mathbb{R}][E]^+\}$	$\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}]{[E]}^+\}$	$\mathscr{A}\{M{:}1[\mathbb{P}][E]^+\}$	$\mathscr{A}\{\tilde{M}{:}2[\mathbb{P}]{[E]}^+\}$
$\odot$ dOITs $_{ au}\langle au angle$	$\odot_{\parallel}$				
$\odot$ dOITs $_{ au}\langle au angle$	${f S}_{\Delta}$				
$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	S <sub>▲</sub>	0	0	0	0
$\odot$ nd0IT $_{ au}\langle t_{ au}^{ullet} angle$ $_{\parallel}$	<b>⊚</b> ∥				
$\odot$ nd0IT $_{ au}\langle t_{ au}^{ullet} angle$ $_{ riangle}$	$\odot_{\Delta}$				
$\odot$ ndOIT $_{ au}\langle t_{ au}^{ullet} angle$ $_{ullet}$	⊚▲				
$ullet$ dOITd $_{ au}\langle 0 \rangle$	<b>1</b>	0	0	0	0
$\bullet \operatorname{dOITd}_\tau\langle 0\rangle  \big _{\scriptscriptstyle \triangle}$	ⓓℴ				
$ \boxed{ \bullet \ \mathtt{dOITd}_{\tau} \langle 0 \rangle } \boxed{ _{\blacktriangle} } $	<b>@</b> ^				

From the above table we see that:

A. Only  $\mathfrak{S}_{\Lambda}$  and  $\mathfrak{A}_{\parallel}$  are possible on  $\mathscr{F}^+$ .

### b. Let $\beta < 1$ or s > 0. Then, from

Pom $22.2.4$ (p.210),	Pom $22.2.12$ (p.223),	Pom $22.2.15$ (p.224),	${\tt Pom}\ 22.2.16 ({\tt p.224})\ ,$	${\tt Pom}\ 22.2.24 ({\tt p.233})\ ,$
${\tt Pom}\ 22.2.2({\tt p.209})\ ,$	Pom $22.2.3(p.209)$ ,	Pom $22.2.4(p.210)$ ,	Pom $22.2.6(p.212)$ ,	${\tt Pom}\ 22.2.8 ({\tt p.213})\ ,$
${\tt Pom}\ 22.2.10 ({\tt p.223})\ ,$	${\tt Pom}\ 22.2.11 ({\tt p.223})\ ,$	${\tt Pom}\ 22.2.13 ({\tt p.224})\ ,$	${\tt Pom}\ 22.2.14 {\scriptsize (p.224)}\ ,$	${\tt Pom}\ 22.2.16 ({\tt p.224})\ ,$
${\tt Pom}\ 22.2.18 {\scriptsize (p.231)},$	${\tt Pom}\ 22.2.20 ({\tt p.232})\ ,$	${\tt Pom}\ 22.2.23({\tt p.232})\ ,$	${\tt Pom}\ 22.2.16 \hbox{\scriptsize (p.224)}\ ,$	${\tt Pom}\ 22.2.21 ({\tt p.232})\ ,$
Pom 22.2.7(p.213).	Pom 22.2.19(n 231).	Pom 22.2.22(n 232)	Pom 22.2.22(n 232)	

we obtain the following table:

Table 22.2.4: Possible OIT on  $\mathscr{F}^+$  ( $\beta < 1$  or s > 0)

		$\mathscr{A}\{M{:}2[\mathbb{R}][E]^+\}$	$\mathscr{A}\{\tilde{M}{:}2[\mathbb{R}]{[E]}^+\}$	$\mathscr{A}\{M{:}1[\mathbb{P}][E]^+\}$	$\mathscr{A}\{\tilde{M}{:}2[\mathbb{P}]{[E]}^+\}$
$\  \   $ $\  \   $ $\  \   $ $\  \   $ $\  \   $ $\  \   $ $\  \   $ $\  \   $	$\odot_{\parallel}$				
$\  \   \  \   \  \   \  \   \  \   \  \ $	${f S}_{\Delta}$	0	0	0	0
$\  \   \  \   \  \   \  \   \  \   \  \ $	S <sub>▲</sub>	0	0	0	0
$\odot$ nd0IT $_{ au}\langle t_{ au}^{ullet} angle$ $_{\parallel}$	<b>O</b>	0	0	0	0
$\odot$ nd0IT $_{ au}\langle t_{ au}^{ullet} angle$ $_{ riangle}$	$\odot_{\Delta}$	0	0	0	0
$\odot$ nd0IT $_{ au}\langle t_{ au}^{ullet} angle$ $_{ullet}$	⊚▲	0	0	0	0
$ullet$ d0ITd $_{ au}\langle 0 \rangle$	<b>1</b>	0	0	0	0
$ullet$ d0ITd $_{ au}\langle 0 \rangle$	<b>∂</b> ∆	0	0	0	0
$\bullet$ d0ITd $_{ au}\langle 0 \rangle$	<b>①</b> ^	0	0	0	0

From the above table we see that:

A.  $(S)_{\Delta}$ ,  $(O)_{\parallel}$ ,  $(S)_{\blacktriangle}$ ,  $(O)_{\blacktriangle}$ ,  $(O)_{\Delta}$ ,  $(O)_{\bot}$ ,  $(O)_{\bot}$ , and  $(O)_{\blacktriangle}$  are possible on  $\mathscr{F}^+$ .

The table below is the list of the occurrence percents (§), ( $\odot$ ), and (3) on  $\mathscr{F}$  (see  $\blacksquare$  Tom 22.2.1(p.203), Tom 22.2.2(p.204), Tom 22.2.3(p.207), Tom 22.2.3(p.207), Tom 22.2.3(p.204), and Tom 22.2.5(p.218)).

Table 22.2.5: Occurance percents of s, o, and d on  $\mathscr{F}^+$ 

	s		<u></u>				<b>①</b>	
41.4%/29			24.3 % / 17			24.3 % / 17 34.3 % / 24		
S <sub>∥</sub>	S	S <sub>▲</sub>	<b>O</b> II	<ul><li>Θ<sub>Δ</sub></li></ul>	<b>O</b> _	<b>①</b>	<b>a</b>	<b>Q</b> <sup>v</sup>
_	possible	possible	possible	possible	possible	possible	possible	possible
-%/-	12.9 %/9	28.5%/20	5.7%/4	14.3 %/ 10	4.3%/3	5.7%/4	21.5%/15	7.1 % / 5

## C5. Null-time-zone and deadline-engulfing

From Table 22.2.5(p.236) above we see that on  $\mathscr{F}$ :

- a. See Remark 8.2.2(p.45) for the noteworthy implication of the symbol  ${\color{red} \blacktriangle}$  (strict optimality).
- b. As a whole we have (8), (0), and (1) occur at 41.4%, 24.3%, and 34.3% respectively where
  - 1.  $\mathfrak{S}_{\parallel}$  cannot be defined due to Preference Rule 8.2.1(p.45).
  - 2.  $\bigcirc_{\parallel}$  is possible (5.7%).
  - 3.  $\mathbf{d}_{\parallel}$  is possible (5.7%).
  - 4.  $\mathfrak{S}_{\Delta}$  is possible (12.9%).
  - 5.  $\bigcirc_{\vartriangle}$  is possible (14.3%).
  - 6.  $\mathbf{d}_{\Delta}$  is possible (21.5 %).
  - 7. (S)  $_{\blacktriangle}$  is possible (28.5%).
  - 8.  $\bigcirc$   $\blacktriangle$  is possible (4.3%).
    - $\bullet \ \, {\tt Tom} \ \, 22.2.2 \hbox{\scriptsize (p.204)} \, \big( c3i2, c3ii1ii2, c3ii2i \big).$
  - 9.  $\mathbf{d}_{\bullet}$  is possible (7.1%).
    - Tom 22.2.4(p.207) (d2i,d2ii).
    - Tom 22.2.5(p.218) (c2,c3i2,c3i3).

From the above results we see that:

- A.  $\odot$  and  $\bullet$  causing the null-time-zone are possible at 58.6% (= 24.3% + 34.3%).
- B.  $\bigcirc$  strictly causing the null-time-zone is possible at 4.3%.
- C. ♠ strictly causing the null-time-zone are possible at 7.1%, i.e., the deadline-engulfing is possible.

#### C6. Diagonal Symmetry

Exercise 22.2.1 Confirm by yourself that the following relations hold in fact.

${\tt Pom}\ 22.2.5 ({\tt p.212})$	$\texttt{d-} {\color{red} \sim} \texttt{Nem} \ 22.2.1 (\texttt{p.210})$	$(\mathbb{R}\text{-mechanism}),$
${\tt Pom}\ 22.2.6 (p.212)$	$\texttt{d-} \sim \texttt{Nem} \ 22.2.2(\texttt{p.210})$	$(\mathbb{R}\text{-mechanism}),$
${\tt Pom}\ 22.2.7 (p.213)$	$\texttt{d-} \sim \texttt{Nem} \ 22.2.3 \texttt{(p.211)}$	$(\mathbb{R}\text{-mechanism}),$
${\tt Pom}\ 22.2.8 {\scriptsize (p.213)}$	$\texttt{d-} {\color{red} \sim} \texttt{Nem} \ 22.2.4 (\texttt{p.211})$	$(\mathbb{R}\text{-mechanism}).$
Pom $22.2.17$ (p.231)	d- $\sim$ Nem $22.2.5$ (p.225)	$(\mathbb{P}\text{-mechanism}),$
Pom $22.2.18$ (p.231)	d- $\sim$ Nem $22.2.6$ (p.225)	$(\mathbb{P}\text{-mechanism}),$
Pom 22.2.19(p.231)	d- $\sim$ Nem $22.2.7$ (p.226)	$(\mathbb{P}\text{-mechanism}),$
Pom 22.2.20(p.232)	d- $\sim$ Nem $22.2.8$ (p.226)	$(\mathbb{P}\text{-mechanism}),$
Pom 22.2.21(p.232)	d- $\sim$ Nem $22.2.9$ (p.226)	$(\mathbb{P}\text{-mechanism}),$
Pom 22.2.22(p.232)	d- $\sim$ Nem $22.2.10$ (p.226)	$(\mathbb{P}\text{-mechanism}),$
Pom 22.2.23(p.232)	d- $\sim$ Nem $22.2.11$ (p.227)	$(\mathbb{P}\text{-mechanism}),$
Pom 22.2.24(p.233)	d- $\sim$ Nem $22.2.12$ (p.227)	( $\mathbb{P}$ -mechanism). $\square$

## 22.3 Conclusions of Model 2

Conclusions 3(p.198) and 4(p.234) can be summed up as below.

#### $\overline{\mathsf{C}}1$ . Mental Conflict

On  $\mathscr{F}^+$ , from C1A(p.199) and C1B(p.199) and from C1A(p.234) and C1B(p.235). we have:

- A. If  $\beta=1$  and s=0, then, on  $\mathscr{F}^+$ , whether search-Allowed-model or search-Enforced-model, whether selling problem or buying problem, and whether  $\mathbb{R}$ -mechanism-model or  $\mathbb{P}$ -mechanism-model, we have the normal mental conflict, which coincides with *expectations* in *Examples* 1.3.1(p.5) 1.3.4(p.6).
- B. If  $\beta < 1$  or s > 0, then, on  $\mathscr{F}^+$ , whether search-Allowed-model or search-Enforced-model, whether selling problem or buying problem, and whether  $\mathbb{R}$ -mechanism-model or  $\mathbb{P}$ -mechanism-model, we have the abnormal mental conflict, which does not coinside with *expectations* in *Examples* 1.3.1(p.5) 1.3.4(p.6).

#### $\overline{\mathsf{C}}2$ . Symmetry

On  $\mathscr{F}^+$ , we have:

- a. If  $\beta = 1$  and s = 0, the symmetry is always inherited (see C2A(p.199) and C2A(p.235)).
- b. if  $\beta < 1$  or s > 0, the symmetry always collapses (see C2B(p.199) and C2B(p.235)).

## $\overline{\mathsf{C}}3$ . Analogy

On  $\mathscr{F}^+$ , we have:

a. For any  $\beta \leq 1$  and  $s \geq 0$ , the analogy collapse (see C3A(p.200) and C3A(p.235)) except (\*) and (\*\*) of C3(p.235).

#### C4. Optimal Initiating Time (OIT)

- a. Let  $\beta = 1$  and s = 0. Then we have  $(s)_{\blacktriangle}$  and  $(t)_{\parallel}$  on  $\mathscr{F}^+$  (see C4aA(p.200) and C4aA(p.236)).
- b. Let  $\beta < 1$  or s > 0.
  - 1. For sA-model we have  $\textcircled{s}_{\blacktriangle}$ ,  $\textcircled{o}_{\parallel}$ , and  $\textcircled{d}_{\parallel}$  (see C4A(p.200)).
  - 2. For sE-model we have  $\textcircled{S}_{\Delta}, \textcircled{S}_{\blacktriangle}, \textcircled{O}_{\parallel}, \textcircled{O}_{\Delta}, \textcircled{O}_{\blacktriangle}, \textcircled{O}_{\parallel}, \textcircled{O}_{\Delta}, \text{ and } \textcircled{O}_{\blacktriangle} \text{ (see C19.3.9(p.134))}.$

Joining Tables 22.1.3(p.201) and 22.2.5(p.236) produces the following table:

Table 22.3.1: Percents (frequencies) of (s), (o), and (d) on  $\mathscr{F}^+$ 

(S)			<u></u>			<b>0</b>		
	44.2 % / 58		23.0 % / 30 32.8 % / 43			32.8%/43		
$\odot_{\parallel}$	S <sub>A</sub>	S <sub>▲</sub>	<b>⊚</b> ∥	<ul><li>Θ<sub>Δ</sub></li></ul>	<b>O</b> _	<b>O</b>	۵۵	۵
_	possible	possible	possible	possible	possible	possible	possible	possible
-%/-	6.8%/9	37.4 %/49	13.2%/17	7.5%/10	2.3%/3	17.5%/23	11.5%/15	3.8%/5

## $\overline{\mathsf{C}}5.$ Null-time-zone and deadline-engulfing

From Table 22.3.1(p.237) above we see that on  $\mathscr{F}$ :

- a. See Remark 8.2.2(p.45) for the noteworthy implication of the symbol (strict optimality).
- b. As a whole we have  $\bigcirc$ ,  $\bigcirc$ , and  $\bigcirc$  at 44.2%, 23.0%, and 32.8% where
  - 1.  $\mathfrak{S}_{\parallel}$  cannot be defined due to Preference Rule 8.2.1(p.45).
  - 2.  $\bigcirc_{\parallel}$  is possible (13.2 %).
  - 3.  $\mathbf{d}_{\parallel}$  is possible (17.5 %).
  - 4.  $\bigcirc$  is possible (6.8 %).
  - 5.  $\bigcirc_{\vartriangle}$  is possible (7.5%).
  - 6.  $\mathbf{d}_{\Delta}$  is possible (11.5%).
  - 7.  $\bigcirc$  is possible (37.4%).
  - 8.  $\bigcirc_{\blacktriangle}$  is possible (2.3%).
    - Tom 22.2.2(p.204) (c3i2,c3ii1ii2,c3ii2i).
  - 9.  $\mathbf{d}_{\bullet}$  is possible (3.8%).
    - Tom 22.2.4(p.207) (d2i,d2ii).
    - Tom 22.2.5(p.218) (c2,c3i2,c3i3).

From the above results we see that:

- A.  $\odot$  and  $\odot$  causing the null-time-zone are possible at 55.8% (= 23.0% + 32.8%).
- B. O and O strictly causing the null-time-zone are possible at 2.3% and 3.8% respectively.

#### C6. Diagonal Symmetry

See C6(p.201) and C6(p.237).

## Chapter 23

## Analysis of Model 3

#### 23.1 Reduction

#### Definition 23.1.1 (reduction)

(a) If it is always optimal to reject the intervening quitting penalty price  $\rho$  in Model 3, then it follows that Model 3 is substantively reduced to Model 2 in which the  $\rho$  is not defined, schematized as

Model 3 
$$\rightarrow$$
 Model 2. (23.1.1)

Let us represent this model reduction as the model-running-back; in other words, Model 3 in "downstream" runs back to Model 2 in "upstream".

(b) Let us define

 $\mathbf{Accept}_{t\geq 0}(\rho) \triangleright \mathbf{Stop} \stackrel{\text{def}}{=} \left\{ \text{Accept the intervening quitting penalty price } \rho \text{ at any given time point on } t\geq 0 \right. \}$   $\text{and stop the process} \right\}. \tag{23.1.2}$ 

Let us represent the reduction of this optimal decision rule (odr) as  $odr \mapsto Accept_{t>0}(\rho) \triangleright Stop$ .

(c) Let us schematize the above two reductions as

 $\mathbf{Lemma~23.1.1} \quad Let~\mathtt{Accept}_{t \geq 0}(\rho) \, {\triangleright}\, \mathtt{Stop}~holds.~Then$ 

- (a) Let  $\beta = 1$ . Then we have  $\mathbf{d}_{\parallel}$  for any  $\rho$ .
- (b) Let  $\beta < 1$  and  $\rho < 0$ . Then we have  $\mathbf{d}_{\blacktriangle}$ .
- (c) Let  $\beta < 1$  and  $\rho = 0$ . Then we have  $\mathbf{0}_{\parallel}$ .
- (d) Let  $\beta < 1$  and  $\rho > 0$ . Then we have (s).
- (e) Let  $\rho \geq 0$ . Then we have  $\mathfrak{S}_{\Delta}$ .  $\square$
- Proof If  $Accept_{t\geq 0}(\rho) \triangleright Stop \text{ holds, then we have } V_t = \rho \text{ for } t>0 \text{ from } (7.4.38(p.41)), (7.4.44(p.41)), (7.4.52(p.41)), and (7.4.58(p.41)), we have <math>I_{\tau}^t = \beta^{\tau-t}\rho \text{ for } t>0 \text{ from } (8.2.3(p.41)).$ 
  - (a) Let  $\beta=1$ . Then  $\beta^0\rho=\beta^1\rho=\cdots=\beta^\tau\rho=\rho$  for any  $\rho$ , hence  $I_{\tau}^{\tau}=I_{\tau}^{\tau-1}=\cdots=I_{\tau}^0=\rho$ , so  $t_{\tau}^*=0$ , i.e.,  $\mathbf{d}_{\parallel}$ .
  - (b) Let  $\beta < 1$  and  $\rho < 0$ . Then  $\beta^0 \rho < \beta^1 \rho < \dots < \beta^\tau \rho$ , hence  $I_\tau^\tau < I_\tau^{\tau 1} < \dots < I_\tau^0$ , so  $t_\tau^* = 0$ , i.e.,  $\mathbf{d}_{\blacktriangle}$ .
  - (c) Let  $\beta < 1$  and  $\rho = 0$ . Then  $\beta^0 \rho = \beta^1 \rho = \dots = \beta^{\tau} \rho = 0$ , hence  $I_{\tau}^{\tau} = I_{\tau}^{\tau 1} = \dots = I_{\tau}^{0}$ , so  $t_{\tau}^* = \tau = 0$ , i.e.,  $\mathbf{d}_{\parallel}$ .
  - (d) Let  $\beta < 1$  and  $\rho > 0$ . Then  $\beta^0 \rho > \beta^1 \rho > \dots > \beta^\tau \rho$ , hence  $I_\tau^\tau > I_\tau^{\tau-1} > \dots > I_\tau^0$ , so  $t_\tau^* = \tau$ , i.e.,  $\textcircled{s}_\blacktriangle$ .
  - (e) Let  $\rho \geq 0$ . Then  $\beta^0 \rho \geq \beta^1 \rho \geq \cdots \geq \beta^{\tau} \rho$  for any  $0 < \beta \leq 1$ , hence  $I_{\tau}^{\tau} \geq I_{\tau}^{\tau-1} \geq \cdots \geq I_{\tau}^{0}$ , so  $t_{\tau}^* = \tau$ , i.e.,  $\mathfrak{S}_{\Delta}$ .

## 23.2 Search-Allowed-Model 3: $\mathcal{Q}\{M:3[A]\} = \{M:3[R][A], \tilde{M}:3[R][A], M:3[R][A], \tilde{M}:3[R][A]\}$

#### 23.2.1 Theorems

As ones corresponding to Theorems 13.5.1(p.80), 14.3.1(p.97), and 15.5.1(p.106) let us consider the following three theorems:

Theorem 23.2.1 (symmetry 
$$[\mathbb{R} \to \tilde{\mathbb{R}}]$$
) Let  $\mathscr{A}[M:3[\mathbb{R}][A]\}$  holds on  $\mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}[\tilde{M}:3[\mathbb{R}][A]\}$  holds on  $\mathscr{P} \times \mathscr{F}$  where  $\mathscr{A}[\tilde{M}:3[\mathbb{R}][A]] = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathscr{A}[M:3[\mathbb{R}][A]]]$ .  $\square$  (23.2.1)

Theorem 23.2.2 (analogy  $[\mathbb{R} \to \mathbb{P}]$ ) Let  $\mathscr{A}\{M:3[\mathbb{R}][A]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$ . Then  $\mathscr{A}\{M:3[\mathbb{P}][A]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$  where

$$\mathscr{A}\{\mathsf{M}:3[\mathbb{P}][\mathsf{A}]\} = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{\mathsf{M}:3[\mathbb{R}][\mathsf{A}]\}]. \quad \Box$$
 (23.2.2)

Theorem 23.2.3 (symmetry(
$$\mathbb{P} \to \tilde{\mathbb{P}}$$
) Let  $\mathscr{A}\{M:3[\mathbb{P}][\mathbb{A}]\}\ holds\ on\ \mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}\{\tilde{M}:3[\mathbb{P}][\mathbb{A}]\}\ holds\ on\ \mathscr{P} \times \mathscr{F}\ where$ 

$$\mathscr{A}\{\tilde{M}:3[\mathbb{P}][\mathbb{A}]\} = \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}[\mathscr{A}\{M:3[\mathbb{P}][\mathbb{A}]\}]. \quad \Box \qquad (23.2.3)$$

In order for the above three theorems to hold, the following three relations must be satisfied:

$$SOE\{\tilde{\mathsf{M}}:3[\mathbb{R}][\mathtt{A}]\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[SOE\{\mathsf{M}:3[\mathbb{R}][\mathtt{A}]\}], \tag{23.2.4}$$

$$\mathtt{SOE}\{\mathsf{M}{:}3[\mathbb{P}][\mathtt{A}]\} = \mathcal{A}_{\mathbb{R} \to \mathbb{P}}[\mathtt{SOE}\{\mathsf{M}{:}3[\mathbb{R}][\mathtt{A}]\}], \tag{23.2.5}$$

$$SOE\{\tilde{\mathsf{M}}:3[\mathbb{P}][\mathtt{A}]\} = \mathcal{S}_{\mathbb{P}\to\tilde{\mathbb{P}}}[SOE\{\mathsf{M}:3[\mathbb{R}][\mathtt{A}]\}], \tag{23.2.6}$$

corresponding to (13.5.34(p.77)), (14.2.4(p.93)), and (15.5.4(p.106)). Now, from the comparison of (I) and (II) and (IV) in Table 7.4.5(p.41) it can be easily shown that (23.2.4(p.240)) and (23.2.6(p.240)) hold. However, from the comparison of (I) and (III) in Table 7.4.5(p.41) we can immediately see that (23.2.5(p.240)) does not always hold, hence it follows that also Theorem 23.2.2(p.239) does not always hold.

#### 23.2.2 A Lemma

The following lemma determines if Theorem 23.2.2(p.239) holds by testing whether or not each of (23.2.5(p.249)) is true.

#### Lemma 23.2.1

- (a) Theorem 23.2.1(p.239) always hold.
- (b) Theorem 23.2.3(p.240) always hold.
- (c) Let  $\rho \leq a^*$  or  $b \leq \rho$ . Then Theorem 23.2.2(p.239) holds.
- (d) Let  $a^* < \rho < b$ . Then Theorem 23.2.2(p.239) does not always hold.  $\square$
- *Proof* Almost the same as the proof of Lemma 22.1.1(p.159).

#### **23.2.3** M: $3[\mathbb{R}][A]$

 $\blacksquare$  Tom 23.2.1 ( $\mathscr{A}\{M:3[\mathbb{R}][A]\}$ )

- (a) Let  $\rho \leq x_K$  or  $\rho \leq 0$ . Then  $M:3[\mathbb{R}][A] \to M:2[\mathbb{R}][A]$ .
- (b) Let  $\rho \geq x_K$  and  $\rho \geq 0$ . Then we have  $\operatorname{odr} \mapsto \operatorname{Accept}_{t \geq 0}(\rho) \triangleright \operatorname{Stop}$ .  $\square$
- Proof From (7.4.39(p.41)) with t=1 and (7.4.37(p.41)) we have  $U_1=\max\{K(V_0)+\rho,\beta V_0)\}=\max\{K(\rho)+\rho,\beta \rho\}\cdots$  (1), hence  $U_1-\rho=\max\{K(\rho),-(1-\beta)\rho\}\cdots$  (2). From (7.4.38(p.41)) with t=1 we have  $V_1\geq \rho=V_0$ . Then, from (7.4.39(p.41)) with t=2 and Lemma 11.2.2(p.57) (e) we have  $U_2=\max\{K(V_1)+V_1,\beta V_1\}=\max\{K(V_0)+V_0,\beta V_0\}=U_1$ . Suppose  $U_{t-1}\geq U_{t-2}$ , hence from (7.4.38(p.41)) we have  $V_{t-1}=\max\{\rho,U_{t-1}\}\geq\max\{\rho,U_{t-2}\}=V_{t-2}$ . Then, from (7.4.39(p.41)) we have  $U_t\geq\max\{K(V_{t-2})+V_{t-2},\beta V_{t-2}\}=U_{t-1}$  due to Lemma 11.2.2(p.57) (e). Thus, by induction we have  $U_t\geq U_{t-1}$  for t>1, i.e., we have that  $U_t$  is nondecreasing in  $t>0\cdots$  (3).
- (a) Let  $\rho \leq x_K$  or  $\rho \leq 0$ . Suppose  $\rho \leq x_K$ , hence  $K(\rho) \geq 0 \cdots$  (4) from Corollary 11.2.2(p.58) (b). Then, from (1) we have  $U_1 \geq K(\rho) + \rho \geq \rho$ . Hence  $U_t \geq \rho$  for t > 0 due to (3). Suppose  $\rho \leq 0$ , hence  $-(1-\beta)\rho \geq 0$ . Then, noting (4), from (2) we have  $U_1 \rho \geq 0$ , i.e.,  $U_1 \geq \rho$ , so  $U_t \geq \rho$  for t > 0 due to (3). Accordingly, whether  $\rho \leq x_K$  or  $\rho \leq 0$ , we have  $U_t \geq \rho$  for t > 0, meaning that it is always optimal to reject the intervening quitting penalty price  $\rho$  for any t > 0. This fact is the same as the event "the intervening quitting penalty price  $\rho$  does not exist on any time t > 0"; in other words, it follows that M:3[ $\mathbb{R}$ ][A] is substantially reduced to M:2[ $\mathbb{R}$ ][A] which has not an intervening quitting penalty price  $\rho$ , i.e., M:3[ $\mathbb{R}$ ][A]  $\longrightarrow$  M:2[ $\mathbb{R}$ ][A].
- (b) Let  $\rho \geq x_K$  and  $\rho \geq 0 \cdots$  (5), hence  $K(\rho) \leq 0 \cdots$  (6) from Corollary 11.2.2(p.58) (a) and  $-(1-\beta)\rho \leq 0$ . Then, since  $U_1 \rho \leq 0$  from (2), we have  $U_1 \leq \rho \cdots$  (7). Suppose  $U_{t-1} \leq \rho$ . Then  $V_{t-1} = \rho$  from (7.4.38(p.41)), hence from (7.4.39(p.41)) we have  $U_t = \max\{K(\rho) + \rho, \beta\rho\} = U_1 \leq \rho$  due to (1) and (7). Accordingly, by induction  $U_t \leq \rho$  for t > 0, meaning that it is always optimal to accept the intervening quitting penalty price  $\rho$  at all time  $t \geq 0$  and stop the process. Hence we have odr  $\mapsto$  Accept<sub>t>0</sub>( $\rho$ )  $\triangleright$  Stop.

#### **23.2.4** $\tilde{M}:3[\mathbb{R}][A]$

- $\square$  Tom 23.2.1 ( $\mathscr{A}\{\widetilde{\mathsf{M}}:3[\mathbb{R}][\mathsf{A}]\}$ )
- (a) Let  $\rho \geq x_{\tilde{K}}$  or  $\rho \geq 0$ . Then  $M:3[\mathbb{R}][A] \rightarrow M:2[\mathbb{R}][A]$ .
- (b) Let  $\rho \geq x_{\tilde{K}}$  and  $\rho \geq 0$ . Then we have  $\operatorname{odr} \mapsto \operatorname{Accept}_{t \geq 0}(\rho) \triangleright \operatorname{Stop}$ .
- Proof by symmetry Immediately from applying  $S_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Tom 23.2.1(p.240) due to Lemma 23.2.1(p.240) (a).

#### **23.2.5** M: $3[\mathbb{P}][A]$

#### 23.2.5.1 Case of $\rho \leq a^*$ or $b \leq \rho$

- $\square$  Tom 23.2.2 ( $\mathscr{A}\{M:3[\mathbb{P}][A]\}$ ) Assume  $\rho \leq a^*$  or  $b \leq \rho$ . Then:
- (a) Let  $\rho \leq x_K$  or  $\rho \leq 0$ . Then  $M:3[\mathbb{P}][A] \rightarrow M:2[\mathbb{P}][A]$ .
- $\text{(b)} \quad Let \; \rho \geq \; x_{\scriptscriptstyle K} \; \; and \; \rho \geq 0. \; \; Then \; we \; have \; \mathsf{odr} \; \mapsto \; \mathsf{Accept}_{t \geq 0}(\rho) \, \triangleright \, \mathsf{Stop}. \quad \Box$
- Proof by analogy The same as Tom 23.2.1(p.240) due to Lemma 14.6.1(p.99).

#### 23.2.5.2 Case of $a^* < \rho < b$

- Proof by analogy Assume  $a^* < \rho < b$  and let  $\beta = 1$  and s = 0. Then, from (6.1.21(p.26)) we have  $K(x) = \lambda T(x) \ge 0 \cdots (1)$  for any x due to Lemma 14.2.1(p.93) (g). From (7.4.45(p.41)) we have  $U_1 \ge \beta \rho = \rho$ . Suppose  $U_{t-1} \ge \rho$ . Then, from (7.4.44(p.41)) we have  $V_{t-1} = U_{t-1} \ge \rho$ , hence from (7.4.46(p.41)) we obtain  $U_t \ge \beta V_{t-1} = V_{t-1} \ge \rho$ . Thus, by induction  $U_t \ge \rho$  for t > 0. Accordingly, for the same reason as in the proof of Tom 23.2.1(p.24) (a) we have M:3[P][A]  $\rightarrow$  M:2[P][A].
- $\blacksquare \ \, \text{Tom 23.2.2 (} \mathscr{A}\{\mathsf{M}:3[\mathbb{P}][\mathtt{A}]\}) \quad \ \, \textit{Assume $a^{\star}<\rho< b$. Let $\beta<1$ or $s>0$.}$
- (a) Let  $\lambda \beta \max\{0, a \rho\} (1 \beta)\rho \ge s$  or  $-(1 \beta)\rho \ge 0$ . Then  $M:3[\mathbb{P}][A] \twoheadrightarrow M:2[\mathbb{P}][A]$ .
- (b) Let  $\lambda \beta \max\{0, a \rho\} (1 \beta)\rho \le s$  and  $-(1 \beta)\rho \le 0$ .
  - 1. Let  $\tau = 1$ . Then we have  $odr \mapsto Accept_1(\rho) \triangleright Stop.^{\dagger}$
  - 2. Let  $\tau > 1$ . Then:
    - i. Let  $\rho \leq x_K$ . Then M:3[ $\mathbb{P}$ ][A]  $\rightarrow M:2[\mathbb{P}]$ [A]
    - ii. Let  $\rho \geq x_K$ . Then we have odr  $\mapsto$  Accept<sub>t>0</sub> $(\rho) \triangleright$  Stop.  $^{\dagger}$
- Proof Assume  $a^* < \rho < b$ . Let  $\beta < 1$  or s > 0. From (7.4.45(p.41)) we have

$$U_1 - \rho = \max\{\lambda\beta \max\{0, a - \rho\} - (1 - \beta)\rho - s, -(1 - \beta)\rho\} \cdots (1)$$

(a) Let  $\lambda\beta \max\{0, a - \rho\} - (1 - \beta)\rho \ge s$  or  $-(1 - \beta)\rho \ge 0$ , hence  $U_1 - \rho \ge 0$  from (1) or equivalently  $U_1 \ge \rho \cdots$  (2). Then, since  $V_1 = U_1 \cdots$  (3) from (7.4.44(p.41)) with t = 1, from (7.4.46(p.41)) with t = 2 we have  $U_2 = \max\{K(V_1) + V_1, \beta V_1\} = \max\{K(U_1) + U_1, \beta U_1\} \cdots$  (4). Hence, from (2), Lemma 14.2.3(p.96) (e), and (6.1.21(p.26)) we have

$$U_2 \ge \max\{K(\rho) + \rho, \beta\rho\}$$

$$= \max\{\lambda\beta T(\rho) - (1-\beta)\rho - s + \rho, \beta\rho\}$$

$$= \max\{\lambda\beta T(\rho) + \beta\rho - s, \beta\rho\}.$$

Then, from Lemma 14.2.1(p.93) (h) we have  $U_2 \geq \max\{\lambda\beta\max\{0, a-\rho\} + \beta\rho - s, \beta\rho\} = U_1$  due to (7.4.45(p.41)). Suppose  $U_{t-1} \geq U_{t-2}$ , so  $V_{t-1} \geq \max\{\rho, U_{t-2}\} = V_{t-2}$  from (7.4.44(p.41)). Hence, from (7.4.46(p.41)) and Lemma 14.2.3(p.96) (e) we have  $U_t \geq \max\{K(V_{t-2}) + V_{t-2}, \beta V_{t-2}\} = U_{t-1}$ . Accordingly, by induction  $U_t \geq U_{t-1}$  for t > 1, i.e.,  $U_t$  is nondecreasing in t > 0. Hence, from (2) we have  $U_t \geq \rho$  for t > 0. Therefore, for almost the same reason as in the proof of Tom 23.2.1(p.240) (a) we have  $M:3[\mathbb{P}][A] \rightarrow M:2[\mathbb{P}][A]$ .

- (b) Let  $\lambda \beta \max\{0, a \rho\} (1 \beta)\rho \le s$  and  $-(1 \beta)\rho \le 0$ . Then  $U_1 \rho \le 0$  from (1), i.e.,  $U_1 \le \rho \cdots$  (6).
- (b1) Let  $\tau = 1$ . Then (6) implies that it is optimal to accept the intervening quitting penalty price  $\rho$  at t = 1 and stop the process, i.e., odr  $\mapsto$  Accept<sub>1</sub>( $\rho$ ) $\triangleright$ Stop.
- (b2) Let  $\tau > 1$ . Due to (6) we have  $V_1 = \rho$  from (7.4.44(p.41)) with t = 1, hence  $U_2 = \max\{K(\rho) + \rho, \beta\rho\} \cdots$  (7) from (7.4.46(p.41)) with t = 2.
- (b2i) Let  $\rho \leq x_K$ . Then  $K(\rho) \geq 0$  from Lemma 14.2.3(p.%) (j1), hence from (7) we have  $U_2 \geq K(\rho) + \rho \geq \rho$ . Suppose  $U_{t-1} \geq \rho$ , hence  $V_{t-1} = U_{t-1} = \rho$  from (7.4.44(p.41)). Then, from (7.4.46(p.41)) and Lemma 14.2.3(p.%) (e) we have  $U_t \geq \max\{K(\rho) + \rho, \beta\rho\} \geq K(\rho) + \rho \geq \rho$ . Accordingly, by induction we have  $U_t \geq \rho$  for t > 1. Thus the assertion holds for the same reason as in the proof of Lemma 23.2.1(p.240) (a).
- (b2ii) Let  $\rho \geq x_K$ , hence  $K(\rho) < 0$  from Lemma 14.2.3(p.96) (j1). Then, from (7) we have  $U_2 \leq \max\{\rho, \beta\rho\} \cdots$  (8). If  $\beta < 1$ , then  $\rho \geq 0$  from (5), hence  $U_2 \leq \max\{\rho, \rho\} = \rho$  and if  $\beta = 1$ , then  $U_2 \leq \max\{\rho, \rho\} = \rho$ . Accordingly, whether  $\beta < 1$  or  $\beta = 1$ , we have  $U_2 \leq \rho$  for t > 0. Suppose  $U_{t-1} \leq \rho$ , hence  $V_{t-1} = \rho$  from (7.4.44(p.41)). Then, from (7.4.46(p.41)) we have  $U_t = \max\{K(\rho) + \rho, \beta\rho\} = U_2 \leq \rho$ . Accordingly, by induction we have  $U_t \leq \rho$  for t > 1. Hence, from (6) we have  $U_t \leq \rho$  for t > 0. Thus, for the same reason as in the proof of Tom 23.2.1(p.240) (b) it follows that the assertion holds.

#### **23.2.6** $\tilde{M}:3[\mathbb{P}][A]$

#### 23.2.6.1 Case of $\rho \geq b^*$ or $a \geq \rho$

- $\square$  Tom 23.2.4 ( $\mathscr{A}\{\tilde{\mathsf{M}}:3[\mathbb{P}][\mathtt{A}]\}$ ) Assume  $\rho \geq b^{\star}$  or  $a \geq \rho$ .
- (a) Let  $\rho \geq x_{\tilde{K}}$  or  $\rho \geq 0$ . Then  $\tilde{\mathsf{M}}:3[\mathbb{P}][\mathbb{A}] \to \tilde{\mathsf{M}}:2[\mathbb{P}][\mathbb{A}]$ .
- (b) Let  $\rho \leq x_{\tilde{K}}$  and  $\rho \leq 0$ . Then we have  $\operatorname{odr} \mapsto \operatorname{Accept}_{\tau}(\rho) \triangleright \operatorname{Stop}$ .  $\square$
- Proof by symmetry Immediate from applying  $S_{\mathbb{P} \to \mathbb{P}}$  (see (20.0.3(p.136))) due to Lemma 23.2.1(p.240) (b).

<sup>&</sup>lt;sup>†</sup>In this case, we have four possibilities for the optimal initiating time (OIT):  $\mathbf{0}_{\parallel}$ ,  $\mathbf{0}_{\blacktriangle}$ ,  $\mathbf{0}_{\blacktriangle}$ , and  $\mathbf{0}_{\vartriangle}$ .

#### 23.2.6.2 Case of $b^* > \rho > a$

- Proof by symmetry Immediate from applying  $S_{\mathbb{P}\to\tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) due to Lemma 23.2.1(p.240) (b).  $\square$  Tom 23.2.6 ( $\mathscr{A}\{\tilde{\mathbb{M}}:3[\mathbb{P}][\mathbb{A}]\}$ ) Assume  $b^*>\rho>a$ . Let  $\beta<1$  or s>0.
- (a) Let  $-\lambda\beta\min\{0,\rho-b\}+(1-\beta)\rho\geq 0$  or  $(1-\beta)\rho\geq 0$ . Then  $\tilde{\mathsf{M}}:3[\mathbb{P}][\mathtt{A}] \twoheadrightarrow \tilde{\mathsf{M}}:2[\mathbb{P}][\mathtt{A}]$ .
- (b) Let  $-\lambda \beta \min\{0, \rho b\} + (1 \beta)\rho < s \text{ and } (1 \beta)\rho < 0.$ 
  - 1. Let  $\tau = 1$ . Then we have  $odr \mapsto Accept_1(\rho) \triangleright Stop$ .
  - 2. Let  $\tau > 1$ .
    - i. Let  $\rho > x_{\tilde{K}}$ . Then  $\tilde{\mathsf{M}}:3[\mathbb{P}][\mathbb{A}] \twoheadrightarrow \tilde{\mathsf{M}}:2[\mathbb{P}][\mathbb{A}]$ .
    - ii. Let  $\rho \leq x_{\tilde{K}}$ . Then we have  $\mathrm{odr} \mapsto \mathrm{Accept}_{t \geq 0}(\rho) \triangleright \mathrm{Stop}$ .  $\square$
- Proof by symmetry Immediate from applying  $S_{\mathbb{P}\to\tilde{\mathbb{P}}}$  (see (20.0.3(p.136))) due to Lemma 23.2.1(p.240) (b).

#### 23.2.7 Conclusion 5 (Search-Allowed-Model 3)

Model 3 (search-Allowed-model) is reduced to either of the following two cases (see (23.1.3(p.239))):

Case A  $M/\tilde{M}:3[\mathbb{R}/\mathbb{P}][A] \rightarrow M/\tilde{M}:2[\mathbb{R}/\mathbb{P}][A]$  where

- 1.  $M:3[\mathbb{R}][A] \rightarrow rM:2[\mathbb{R}][A]$ ; see Tom 23.2.1(p.240) (a),
- 2.  $\tilde{\mathsf{M}}:3[\mathbb{R}][\mathtt{A}] \twoheadrightarrow r\tilde{\mathsf{M}}:2[\mathbb{R}][\mathtt{A}];$  see Tom 23.2.1(p.240) (a),
- 3.  $M:3[\mathbb{P}][A] \rightarrow rM:2[\mathbb{P}][A]$ ; see Tom 23.2.2(p.240) (a), 23.2.3(p.241), and 23.2.2(p.241) (a,b2i),
- 4.  $\tilde{M}:3[\mathbb{P}][A] \rightarrow r\tilde{M}:2[\mathbb{P}][A]$ ; see Tom 23.2.4(p.241) (a), 23.2.5(p.242), and 23.2.6(p.242) (a,b2i).

Case B odr  $\mapsto$  Accept<sub>t \geq 0</sub>( $\rho$ )  $\triangleright$  Stop where

- 1. For  $M:3[\mathbb{R}][A]$ , see Tom 23.2.1(p.240) (b),
- 2. For  $\tilde{M}:3[\mathbb{R}][A]$ , see Tom 23.2.1(p.240) (b),
- 3. For  $M:3[\mathbb{P}][A]$ , see Tom 23.2.2(p.240) (b),23.2.2(p.241) (b1,b2ii),
- 4. For  $\tilde{M}:3[\mathbb{P}][A]$ , see Tom 23.2.4(p.241) (b),23.2.6(p.242) (b1.b2ii).

## $\mathbf{23.3} \quad \mathbf{Search-Enforced-Model \ 3:} \ \mathcal{Q}\{\mathsf{M}:3[\mathtt{E}]\} = \{\mathsf{M}:3[\mathtt{R}][\mathtt{E}], \tilde{\mathsf{M}}:3[\mathtt{R}][\mathtt{E}], \tilde{\mathsf{M}}:3[\mathtt{P}][\mathtt{E}], \tilde{\mathsf{M}}:3[\mathtt{P}][\mathtt{E}]\}$

#### 23.3.1 Preliminary

As the ones corresponding to Theorems 23.2.1(p.239), 23.2.2(p.239), and 23.2.3(p.240) let us consider the following three theorems:

Theorem 23.3.1 (symmetry[
$$\mathbb{R} \to \mathbb{R}$$
]) Let  $\mathscr{A}[M:3[\mathbb{R}][E]]$  holds on  $\mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}[\tilde{M}:3[\mathbb{R}][E]]$  holds on  $\mathscr{P} \times \mathscr{F}$  where  $\mathscr{A}[\tilde{M}:3[\mathbb{R}][E]] = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathscr{A}[M:3[\mathbb{R}][E]]]$ .  $\square$  (23.3.1)

Theorem 23.3.2 (analogy  $[\mathbb{R} \to \mathbb{P}]$ ) Let  $\mathscr{A}\{\mathsf{M}:3[\mathbb{R}][\mathsf{E}]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}$ . Then  $\mathscr{A}\{\mathsf{M}:3[\mathbb{P}][\mathsf{E}]\}\ holds\ on\ \mathscr{P}\times\mathscr{F}\ where$   $\mathscr{A}\{\mathsf{M}:3[\mathbb{P}][\mathsf{E}]\}=\mathscr{A}_{\mathbb{R}\to\mathbb{P}}[\mathscr{A}\{\mathsf{M}:3[\mathbb{R}][\mathsf{E}]\}].$   $\square$  (23.3.2)

Theorem 23.3.3 (symmetry[
$$\mathbb{P} \to \mathbb{P}$$
])) Let  $\mathscr{A}\{M:3[\mathbb{P}][E]\}\ holds\ on\ \mathscr{P} \times \mathscr{F}$ . Then  $\mathscr{A}\{\tilde{M}:3[\mathbb{P}][E]\}\ holds\ on\ \mathscr{P} \times \mathscr{F}$  where  $\mathscr{A}\{\tilde{M}:3[\mathbb{P}][E]\}=\mathcal{S}_{\mathbb{P}\to \tilde{\mathbb{P}}}[\mathscr{A}\{M:3[\mathbb{P}][E]\}]$ .  $\square$  (23.3.3)

In order for the above three theorems to hold, the following three relations must be satisfied:

$$SOE\{\tilde{\mathsf{M}}:3[\mathbb{R}][\mathsf{E}]\} = \mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[SOE\{\mathsf{M}:3[\mathbb{R}][\mathsf{E}]\}], \tag{23.3.4}$$

$$SOE\{M:3[\mathbb{P}][E]\} = \mathcal{A}_{\mathbb{R}\to\mathbb{P}}[SOE\{M:3[\mathbb{R}][E]\}], \tag{23.3.5}$$

$$SOE\{\tilde{M}:3[\mathbb{P}][E]\} = S_{\mathbb{P}\to\tilde{\mathbb{P}}}[SOE\{M:3[\mathbb{P}][E]\}], \tag{23.3.6}$$

corresponding to (23.2.4(p.240)), (23.2.5(p.240)), and (23.2.6(p.240)). Now, from the comparison of (I) and (II) and of (III) and (IV) in Table 7.4.6(p.41) it can be easily shown that (23.3.4(p.242)) and (23.3.6(p.242)) hold. However, from the comparison of (I) and (III) in Table 7.4.6(p.41) we can immediately see that (23.3.5(p.242)) does not hold, hence it follows that also Theorem 23.3.2(p.242) does not always hold.

#### 23.3.2 A Lemma

#### Lemma 23.3.1

- (a) Theorem 23.3.1(p.242) always hold.
- (b) Theorem 23.3.3(p.242) always hold.
- (c) Let  $\rho \leq a^*$  or  $b \leq \rho$ . Then Theorem 23.3.2(p.242) holds.
- (d) Let  $a^* < \rho < b$ . Then Theorem 23.3.2(p.242) does not always hold.  $\square$
- Proof Almost the same as the proof of Lemma 22.1.1(p.159).

#### **23.3.3** M:3[ $\mathbb{R}$ ][E]

- $\blacksquare$  Tom 23.3.1 ( $\mathscr{A}\{M:3[\mathbb{R}][E]\}$ )
- (a) Let  $\rho \leq x_K$ . Then  $M:3[\mathbb{R}][E] \to M:2[\mathbb{R}][E]$ .
- (b) Let  $\rho \geq x_K$ . Then we have  $\operatorname{odr} \mapsto \operatorname{Accept}_{\tau \geq t \geq 0}(\rho) \triangleright \operatorname{Stop.}^{\dagger}$
- Proof From (7.4.53(p.41)) with t=1 and (7.4.51(p.41)) we have  $U_1=K(\rho)+\rho\cdots$  (1) and from (7.4.52(p.41)) with t=1 we have  $V_1\geq \rho=V_0$ . Then, from (7.4.53(p.41)) with t=2 and Lemma 11.2.2(p.57) (e) we have  $U_2=K(V_1)+V_1\geq K(\rho)+\rho=U_1$ . Suppose  $U_{t-1}\geq U_{t-2}$ , hence  $V_{t-1}\geq \max\{\rho,U_{t-2}\}=V_{t-2}$  from (7.4.52(p.41)). Then from (7.4.53(p.41)) we have  $U_t=K(V_{t-1})+V_{t-1}\geq K(V_{t-2})+V_{t-2}=U_{t-1}$  due to Lemma 11.2.2(p.57) (e) Thus, by induction we have  $U_t\geq U_{t-1}$  for t>1, i.e.,  $U_t$  is nondecreasing in  $t>0\cdots$  (2).
- (a) Let  $\rho \leq x_K$ , hence  $K(\rho) \geq 0$  from Corollary 11.2.2(p.58) (b). Then, from (1) we have  $U_1 \geq \rho$ . Hence  $U_t \geq \rho$  for t > 0 due to (2). Accordingly, for almost the same reason as in the proof of Tom 23.2.1(p.240) (a) we have  $\tilde{M}:3[\mathbb{R}][E] \to \tilde{M}:2[\mathbb{R}][E]$ .
- (b) Let  $\rho \geq x_K$ , hence  $K(\rho) \leq 0 \cdots$  (3) from Corollary 11.2.2(p.58) (a). Then, from (1) we have  $U_1 \leq \rho$ . Suppose  $U_{t-1} \leq \rho$ . Then  $V_{t-1} = \rho$  from (7.4.52(p.41)), hence from (7.4.53(p.41)) we have  $U_t = K(\rho) + \rho \leq \rho$  due to (3). Accordingly, by induction  $U_t \leq \rho$  for t > 0, so we have odr  $\mapsto$  Accept<sub> $\tau > t > 0$ </sub>( $\rho$ )  $\triangleright$  Stop for the same reason as in Tom 23.2.1(p.240) (b).

## **23.3.4** $\tilde{M}:3[\mathbb{R}][E]$

- $\square$  Tom 23.3.1 ( $\mathscr{A}\{\tilde{\mathsf{M}}:3[\mathbb{R}][\mathsf{E}]\}$ ) For any  $\beta \leq 1$  and  $s \geq 0$  we have:
- (a) Let  $\rho \leq x_{\tilde{K}}$ . Then  $\tilde{M}:3[\mathbb{R}][E] \to \tilde{M}:2[\mathbb{R}][E]$ .
- (b) Let  $\rho \leq x_{\tilde{K}}$ . Then we have  $\operatorname{odr} \mapsto \operatorname{Accept}_{\tau > t > 0}(\rho) \triangleright \operatorname{Stop}$ .  $\square$
- Proof by symmetry Immediate from applying  $S_{\mathbb{R} \to \mathbb{R}}$  (see (20.0.1(p.136))) due to Lemma 23.3.1(p.242) (a).

#### **23.3.5** M: $3[\mathbb{P}][E]$

## 23.3.5.1 Case of $\rho \leq a^{\star}$ or $b \leq \rho$

In this case, we can use Lemma 23.3.1(p.242) (c) to prove Tom 23.3.2(p.243) below.

- $\square$  Tom 23.3.2 ( $\mathscr{A}\{M:3[\mathbb{P}][E]\}$ ) Assume  $\rho \leq a^*$  or  $b \leq \rho$ .
- (a) Let  $\rho \leq x_K$ . Then  $M:3[\mathbb{P}][E] \rightarrow M:2[\mathbb{P}][E]$ .
- (b) Let  $\rho \geq x_K$ . Then we have  $\operatorname{odr} \mapsto \operatorname{Accept}_{\tau \geq t \geq 0}(\rho) \triangleright \operatorname{Stop}$ .  $\square$
- ullet Proof by analogy The same as Tom 23.3.1(p.243) due to Lemma 14.6.1(p.99).  $\blacksquare$

#### 23.3.5.2 Case of $a^* < \rho < b$

In this case, Tom's 23.3.2(p.243) and 23.3.3(p.243) below must be directly proven due to Lemma 23.3.1(p.242) (d).

- Tom 23.3.2 ( $\mathscr{A}\{M:3[\mathbb{P}][E]\}$ ) Assume  $a^* < \rho < b$  and let  $\beta = 1$  and s = 0. Then we have  $M:3[\mathbb{P}][E] \rightarrow M:2[\mathbb{P}][E]$ .  $\square$
- Proof Suppose  $a^* < \rho < b$  and let  $\beta = 1$  and s = 0. From (6.1.21(p.26)) we have  $K(x) = \lambda T(x) \ge 0 \cdots (1)$  for any x due to Lemma 14.2.1(p.93) (g). Now, from (7.4.59(p.41)) we have  $U_1 = \lambda \max\{0, a \rho\} + \rho \ge \rho$  due to  $\max\{0, a \rho\} \ge 0$ . Suppose  $U_{t-1} \ge \rho$ . Then, since  $V_{t-1} = U_{t-1}$  due to (7.4.58(p.41)), from (7.4.60) we have  $U_t = K(U_{t-1}) + U_{t-1} \ge U_{t-1}$  due to (1), hence  $U_t \ge \rho$ . Accordingly, by induction  $U_t \ge \rho$  for t > 0, implying that it is optimal to reject the intervening quitting penalty price  $\rho$  for any t > 1. Thus, for almost the same as in the proof of Tom 23.2.1(p.240) (a) we have  $M:3[\mathbb{P}][E] \longrightarrow M:2[\mathbb{P}][E]$ .
- Tom 23.3.3 ( $\mathscr{A}$ {M:3[ $\mathbb{P}$ ][E]}) Assume  $a^* < \rho < b$  and let  $\beta < 1$  or s > 0.
- (a) Let  $\lambda \beta \max\{0, a \rho\} (1 \beta)\rho \ge s$ . Then  $\mathsf{M}:3[\mathbb{P}][\mathsf{E}] \twoheadrightarrow \mathsf{M}:2[\mathbb{P}][\mathsf{E}]$ .
- (b) Let  $\lambda \beta \max\{0, a \rho\} (1 \beta)\rho \le s$ .
  - 1. Let  $\tau = 1$ . Then we have  $\operatorname{odr} \mapsto \operatorname{Accept}_{t=1}(\rho) \triangleright \operatorname{Stop}$ .
  - $2. \quad Let \; \tau > 1. \; Then$ 
    - i. Let  $\rho \leq x_K$ . Then  $M:3[\mathbb{P}][E] \to M:2[\mathbb{P}][E]$ .
    - ii. Let  $\rho \geq x_K$ . Then we have  $\mathrm{odr} \mapsto \mathrm{Accept}_{\tau \geq t \geq 0}(\rho) \triangleright \mathrm{Stop}$ .
- Proof Suppose  $a^* < \rho < b$ . Let  $\beta < 1$  or s > 0. From (7.4.59(p.41)) we have

$$U_1 - \rho = \lambda \beta \max\{0, a - \rho\} - (1 - \beta)\rho - s \cdots (1).$$

(a) Let  $\lambda\beta \max\{0, a-\rho\} - (1-\beta)\rho \geq s$ , hence  $U_1 \geq \rho \cdots$  (2) from (1). Then, since  $V_1 = U_1 \cdots$  (3) from (7.4.58(p41)) with t=1, we have  $U_2 = K(U_1) + U_1 \cdots$  (4) from (7.4.60(p.41)) with t=2. Hence, from (2), Lemma 14.2.3(p.96) (e), and (6.1.21(p.26)) we have  $U_2 \geq K(\rho) + \rho = \lambda\beta T(\rho) - (1-\beta)\rho - s + \rho = \lambda\beta T(\rho) + \beta\rho - s$ . Then, from Lemma 14.2.1(p.93) (h) we have  $U_2 \geq \lambda\beta \max\{0, a-\rho\} + \beta\rho - s = U_1$  due to (7.4.59(p.41)). Suppose  $U_{t-1} \geq U_{t-2}$ , hence  $V_{t-1} \geq \max\{\rho, U_{t-2}\} = V_{t-2}$  from

<sup>&</sup>lt;sup>†</sup>In this case, we have four possibilities for the optimal initiating time (OIT):  $\mathbf{0}_{\parallel}$ ,  $\mathbf{0}_{\blacktriangle}$ ,  $\mathbf{3}_{\blacktriangle}$ , and  $\mathbf{5}_{\vartriangle}$  (see Lemma 23.1.1(p.239)).

(7.4.58(p.41)). Then, from Lemma 14.2.3(p.96) (e) we have  $U_t \geq K(V_{t-2}) + V_{t-2} = U_{t-1}$ . Accordingly, by induction  $U_t \geq U_{t-1}$  for t > 1, i.e.,  $U_t$  is nondecreasing in t > 0. Hence, from (2) we have  $U_t \geq \rho$  for t > 0, implying that it is optimal to reject the intervening quitting penalty price  $\rho$  for any t > 1. Therefore, for the same as in the proof of Tom 23.2.1(p.240) (a) we have  $M:3[\mathbb{P}][E] \to M:2[\mathbb{P}][E]$ .

- (b) Let  $\lambda \beta \max\{0, a \rho\} (1 \beta)\rho \le s \cdots$  (5). Then  $U_1 \rho \le 0$  from (1), i.e.,  $U_1 \le \rho \cdots$  (6).
- (b1) Let  $\tau=1$ . Now (6) implies that it is optimal to accept the intervening quitting penalty price  $\rho$  at the starting time t=1 and the process stops, hence we have  $\mathtt{odr} \mapsto \mathtt{Accept}_{t=1}(\rho) \triangleright \mathtt{Stop}$ .
- (b2) Let  $\tau > 1$ . Now, due to (6) we have  $V_1 = \rho$  from (7.4.58(p.41)) with t = 1, thus  $U_2 = K(\rho) + \rho \cdots$  (7) from (7.4.60(p.41)) with t = 2.
- (b2i) Let  $\rho \leq x_K$ , hence  $K(\rho) \geq 0$  from Lemma 14.2.3(p.%) (j1). Then, from (7) we have  $U_2 \geq \rho$ . Suppose  $U_{t-1} \geq \rho$ , hence  $V_{t-1} = U_{t-1}$  from (7.4.58(p.41)). Then, from (7.4.60(p.41)) and Lemma 14.2.3(p.%) (e) we have  $U_t = K(U_{t-1}) + U_{t-1} \geq K(\rho) + \rho \geq \rho$ . Hence, by induction  $U_t \geq \rho$  for t > 1, implying that it is optimal to reject the intervening quitting penalty price  $\rho$  for any t > 1. Thus, for almost the same as in the proof of Lemma 23.2.1(p.24) (a) we have M:3[P][E]  $\rightarrow$  M:2[P][E].
- (b2ii) Let  $\rho \geq x_K$ . Then  $K(\rho) \leq 0 \cdots$  (8) from Lemma 14.2.3(p.96) (j1). Hence  $U_2 \leq \rho$  from (7). Suppose  $U_{t-1} \leq \rho$ , hence  $V_{t-1} = \rho$  from (7.4.58(p.41)). Then, from (7.4.60(p.41)) we have  $U_t = K(\rho) + \rho \leq \rho \cdots$  (9) due to (8). Thus, by induction  $U_t \leq \rho$  for t > 1. From this and (6) we have  $U_t \leq \rho$  for t > 0, hence we have odr  $\mapsto \mathsf{Accept}_{\tau \geq t \geq 0}(\rho) \triangleright \mathsf{Stop}$  for the same reason as in the proof of Tom 23.2.1(p.240) (b) we have that the assertion holds.

#### **23.3.6** $M:3[\mathbb{P}][E]$

#### **23.3.6.1** Case of $\rho \geq b^*$ or $a \geq \rho$

- $\square$  Tom 23.3.3 ( $\mathscr{A}\{\tilde{\mathsf{M}}:3[\mathbb{P}][\mathsf{E}]\}$ ) Assume  $\rho \geq b^*$  or  $a \geq \rho$  and let  $\beta \leq 1$  and  $s \geq 0$ .
- (a) Let  $\rho \geq x_{\tilde{K}}$ . Then  $\tilde{\mathsf{M}}:3[\mathbb{P}][\mathsf{E}] \to \tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]$ .
- $\text{(b)} \quad Let \ \rho \leq \ x_{\tilde{K}} \, . \ Then \ we \ have \ \text{odr} \mapsto \ \texttt{Accept}_{\tau > t > 0}(\rho) \, \triangleright \, \texttt{Stop}.$
- Proof by symmetry Immediate from applying  $S_{\mathbb{P}\to \tilde{\mathbb{P}}}$  (see (20.0.2(p.136))) to Tom 23.3.2(p.23).

#### **23.3.6.2** Case of $b^* > \rho > a$

- Proof by symmetry Immediate from applying  $S_{\mathbb{P}\to \tilde{\mathbb{P}}}$  (see (20.0.2(p.136))) to Tom 23.3.2(p.243).
- $\square$  Tom 23.3.5 ( $\mathscr{A}\{M:3[\mathbb{P}][E]\}$ ) Assume  $b^* > \rho > a$  and let  $\beta < 1$  or s > 0.
- (a) Let  $-\lambda\beta \min\{0, \rho b\} + (1 \beta)\rho \ge s$ . Then  $\tilde{\mathsf{M}}:3[\mathbb{P}][\mathsf{E}] \twoheadrightarrow \tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]$ .
- (b) Let  $-\lambda \beta \min\{0, \rho b\} + (1 \beta)\rho \le s$ .
  - $1. \quad Let \ \tau = 1. \ Then \ we \ have \ \mathrm{odr} \mapsto \mathtt{Accept}_{t=1}(\rho) \, \triangleright \, \mathtt{Stop}.$
  - 2. Let  $\tau > 1$ . Then
    - i. Let  $\rho > x_{\tilde{K}}$ . Then  $\tilde{\mathsf{M}}:3[\mathbb{P}][\mathsf{E}] widtharpoons \tilde{\mathsf{M}}:2[\mathbb{P}][\mathsf{E}]$
    - ii. Let  $\rho \leq x_{\tilde{K}}$ . Then  $\operatorname{odr} \mapsto \operatorname{Accept}_{\tau > t > 0}(\rho) \triangleright \operatorname{Stop}$ .
- Proof by symmetry Immediate from applying  $S_{\mathbb{P} \to \tilde{\mathbb{P}}}$  (see (20.0.2(p.136))) to Tom 23.3.3(p.243).

#### 23.3.7 Conclusion 6 (Search-Enforced-Model 3)

This model (search-Enforced-model) is reduced to either of the following two cases (see (23.1.3(p.239))):

Case A we have  $M/M:3[\mathbb{R}/\mathbb{P}][E] \rightarrow M/M:2[\mathbb{R}/\mathbb{P}][E]$  where

- 1.  $\mathsf{M}:3[\mathbb{R}][\mathsf{E}] \twoheadrightarrow r\mathsf{M}:2[\mathbb{R}][\mathsf{E}];$  see Tom 23.3.1(p.243) (a),
- 2.  $\tilde{M}:3[\mathbb{R}][E] \rightarrow r\tilde{M}:2[\mathbb{R}][E]$ ; see Tom 23.3.1(p.243) (a),
- 3.  $M:3[\mathbb{P}][E] \rightarrow rM:2[\mathbb{P}][E]$ ; see Tom 23.3.2(p.243) (a), 23.3.2(p.243), and 23.3.3(p.243) (a,b2i),
- $4. \ \ \tilde{\mathsf{M}}: 3[\mathbb{P}][\mathsf{E}] \twoheadrightarrow r \tilde{\mathsf{M}}: 2[\mathbb{P}][\mathsf{E}]; \ see \ \mathsf{Tom} \ 23.3.3(\texttt{p.244}) \ (a), \ 23.3.4(\texttt{p.244}), \ and \ 23.3.5(\texttt{p.244}) \ (a,b2i).$

 $\mathsf{Case} \,\, \mathsf{B} \quad \mathsf{We} \,\, \mathsf{have} \,\, \mathsf{odr} \mapsto \, \mathsf{Accept}_{\tau \geq t \geq 0}(\rho) \! \triangleright \! \mathsf{Stop} \,\, \mathsf{where}$ 

- 1. For  $M:3[\mathbb{R}][E]$ , see Tom 23.3.1(p.243) (b),
- 2. For  $\tilde{M}:3[\mathbb{R}][E]$ , see Tom 23.3.1(p.243) (b),
- 3. For  $M:3[\mathbb{P}][E]$ , see Tom 23.3.2(p.243) (b),23.3.3(p.243) (b1,b2ii),
- 4. For  $\tilde{M}:3[\mathbb{P}][E]$ , see Tom 23.3.3(p.244) (b),23.3.5(p.244) (b1,b2ii).

## 23.4 Conclusions of Model 3

This model (whether search-Enforced-model or search-Allowed-model) is reduced to either of the following two cases (see Conclusions 5 (p.242) and 6 (p.244):

- $\overline{\mathsf{C}}1.$  We have  $\mathsf{M}/\widetilde{\mathsf{M}}:3[\mathbb{R}/\mathbb{P}][\mathsf{A}/\mathsf{E}] \to \mathsf{M}/\widetilde{\mathsf{M}}:2[\mathbb{R}/\mathbb{P}][\mathsf{A}/\mathsf{E}].$
- C2. We have  $\operatorname{odr} \mapsto \operatorname{Accept}_{\tau \geq t \geq 0}(\rho) \triangleright \operatorname{Stop}_{\tau}(\rho)$

# Chapter 24

## Conclusions of Part 3 (No-Recall-Model)

Below is the summary of Sections 21.3(p.156), 22.3(p.237), and 23.4(p.244).

## 24.1 Models 1/2

## $\overline{\overline{C}}1$ . Mental Conflict

Here let the adverb "always" means "whether search-Allowed-model or search-Enforced-model, whether selling model or buying model, and whether  $\mathbb{R}$ -mechanism-model or  $\mathbb{P}$ -mechanism-model". Then,  $\overline{C}1$ (p.156) and  $\overline{C}1$ (p.237) cwn be rewritten as follows.

a. Model 1

Let  $\beta \leq 1$  and  $s \geq 0$ . Then, on  $\mathscr{F}$ , we always have the normal mental conflict, which coincides with *expectations* in *Examples* 1.3.1(p.5) - 1.3.4(p.6).

- b. Model 2
  - 1. Let  $\beta = 1$  and s = 0. Then, on  $\mathscr{F}^+$ , we always have the normal mental conflict, which coincides with *expectations* in *Examples* 1.3.1(p.5) 1.3.4(p.6).
  - 2. Let  $\beta < 1$  or s > 0. Then, on  $\mathscr{F}^+$ , we always have the abnormal mental conflict, which does not coinside with *expectations* in *Examples* 1.3.1(p.5) 1.3.4(p.6).

## $\overline{\overline{C}}2$ . Symmetry

- a. On  $\mathscr{F}^+$ :
  - 1. Let  $\beta=1$  and s=0. Then, for both Model 1 and Model 2, the symmetry is always inherited (see  $\overline{\mathsf{C}}2\mathsf{b}(p.156)$  and  $\overline{\mathsf{C}}2\mathsf{a}(p.237)$ ).
  - 2. Let  $\beta < 1$  or s > 0. Then, for both Model 1 and Model 2, the symmetry may collapse (see  $\overline{C}2c(p.156)$  and  $\overline{C}2b(p.237)$ ).

## $\overline{\overline{C}}3$ . Analogy

- a. Model 1 On  $\mathscr{F}^+$ :
  - 1. Let  $\beta = 1$  and s = 0. Then the analogy is inherited (see C5b3(p.157)).
  - 2. Let  $\beta < 1$  or s > 0. Then analogy is may collapses (see C3c(p.156)).
- b. Model 2 On  $\mathscr{F}^+$ :
  - 1. For any  $\beta \leq 1$  and  $s \geq 0$ , the analogy may collapse (see C3a(p.237)).

## $\overline{\overline{\mathsf{C}}}4$ . Optimal Initiating Time (0IT)

On  $\mathscr{F}^+$ :

- a. Let  $\beta = 1$  and s = 0.
  - 1. For Model 1, only S<sub>▲</sub> is possible (see C2b2(p.139) and C4aA(p.155)).
  - 2. For Model 2, only  $\textcircled{s}_{\perp}$  and  $\textcircled{d}_{\parallel}$  are possible (see C4aA(p.200) and C4aA(p.236)). What is remarkable here is that  $\textcircled{d}_{\parallel}$  (deadline-engulfing) occurs even in the simplest case of " $\beta=1$  and s=0" (see C4aA(p.236)).
- b. Let  $\beta < 1$  or s > 0.
  - 1. For Model 1,  $\mathfrak{S}_{\blacktriangle}$ ,  $\mathfrak{O}_{\parallel}$ ,  $\mathfrak{O}_{\vartriangle}$ ,  $\mathfrak{O}_{\blacktriangle}$ ,  $\mathfrak{O}_{\parallel}$ , and  $\mathfrak{O}_{\vartriangle}$  are possible (see C4b(p.156)).
  - 2. For Model 2,  $\textcircled{S}_{\vartriangle}$ ,  $\textcircled{S}_{\blacktriangle}$ ,  $\textcircled{O}_{\parallel}$ ,  $\textcircled{O}_{\vartriangle}$ ,  $\textcircled{O}_{\blacktriangle}$ ,  $\textcircled{d}_{\parallel}$ ,  $\textcircled{d}_{\vartriangle}$ , and  $\textcircled{d}_{\blacktriangle}$  are possible.

Joining Tables 21.3.1(p.157) and 22.3.1(p.237) produces the following table:

Table 24.1.1: Occurance percents of (s), (o), and (d) on  $\mathscr{F}$ 

	§					<b>①</b>		
	44.4 % / 68 22.2 % / 34 33.4 % / 51		22.2 % / 34 33					
S <sub>∥</sub>	Sδ	S <sub>▲</sub>	<b>⊚</b> ∥	<ul><li>Φ</li></ul>	<b>O</b> _	<b>1</b>	<b>(</b> )	<b>①</b> ,
_	possible	possible	possible	possible	possible	possible	possible	possible
-%/-	5.9 % / 9	38.6 % / 59	12.4 %/19	7.2 %/ 11	2.6 %/4	19.0 %/ 29	11.1 %/ 17	3.2%/5

## $\overline{\overline{C}}5$ . Null-time-zone and deadline-engulfing

From Table 24.1.1(p.246) above, we see that on  $\mathscr{F}$ :

- a. See Remark 8.2.2(p.45) for the noteworthy implication of the symbol (strict optimality).
- b. As a whole, we have (§), (©), and (1) at 44.4%, 22.2%, and 33.4% respectively where
  - 1. (s) cannot be defined due to Preference Rule 8.2.1(p.45).
  - 2.  $\bigcirc_{\parallel}$  is possible (12.4%).
  - 3.  $\mathbf{d}_{\parallel}$  is possible (19.0%).
  - 4. (s) never occur (5.9%).
  - 5.  $\bigcirc_{\vartriangle}$  is possible (7.2%).
  - 6.  $\mathbf{d}_{\Delta}$  is possible (11.1%).
  - 7. \$ is possible (38.6%) (see Remark 8.2.2(p.45)),
  - 8.  $\bigcirc_{\blacktriangle}$  is possible(2.6%).
    - o Tom 21.2.2(p.143) (c2iii2)
    - o Tom 22.2.2(p.204) (c3i2,c3ii1ii2,c3ii2i).
  - 9.  $\bullet$  is possible (3.2%).
    - $\circ$  Tom 22.2.4(p.207) (d2i,d2ii).
    - $\circ$  Tom 22.2.5(p.218) (c2,c3i2,c3i3).

The following three are especially noteworthy findings:

- A.  $\odot$  and  $\odot$  causing the null-time-zone occur at the percentage of 55.6% (= 22.2% + 33.4%).
- B. **d** causing the deadline-engulfing occurs at the percentage of 33.4%.
- C. (a) and (b) a causing the deadline-engulfing occurs at the percentages of 2.6% and 3.2% respectively.
- D.  $\mathbf{0}_{\parallel}$  causing the deadline-engulfing occurs even in the simplest case of " $\beta=1$  and s=0" (see  $\overline{\overline{C}}4a2(p.245)$ ).

## $\overline{\mathsf{C}}6$ . Diagonal symmetry

See  $\overline{\mathsf{C}}6(p.157)$  and  $\overline{\mathsf{C}}6(p.238)$ .

 $\overline{\mathsf{C}}$ 7.  $\mathsf{C} \leadsto \mathsf{S}$  (Conduct  $\leadsto \mathsf{Skip}$ ) (see Def. 2.2.1(p.12) and Remark 8.2.1(p.44))

It is only for  $M:2[\mathbb{R}][A]^+$  and  $M:2[\mathbb{P}][A]^+$  with  $\beta < 1$  or s > 0 (see Table 22.1.4(p.201)) that we have observed  $C \sim S$ . It is usual to assume that once conducting a search is optimal, it will become optimal to continue conducting the search afterward. However, we demonstrated that this expectation does not always hold. In other words, it can become optimal to skip the search after initially continuing it for a while.

## 24.2 Models 3

## $\overline{\overline{C}}9$ . Reduction

Model 3 is reduced to the following two cases (see Section 23.4(p.244)):

- a. We have the model-running-back  $M/\tilde{M}:3[\mathbb{R}/\mathbb{P}][A/E] \rightarrow M/\tilde{M}:2[\mathbb{R}/\mathbb{P}][A/E]$ .
- b. We have the odr-reduction odr  $\mapsto$  Accept $_{\tau>t>0}(\rho) \triangleright$  Stop.

# Part 4

# ${\bf Recall\text{-}Model}$

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# Chapter 25

# **Definitions of Models**

# 25.1 Future Subjects

E.S. 2 (future subject) In the recall-model with  $\mathbb{R}$ -mechanism it suffices to memorize only the best of prices which have been rejected so far. Against this, in the recall-model with  $\mathbb{P}$ -mechanism it is hard to define the best price itself. For this reason, in this chapter we exclude the application of the integrated-theory to the latter model, which is left as a subject to be tackled in the future (see F2(p.297)).  $\square$ 

For convenience of reference, below let us copy Table 3.2.2(p.16) where ———— represents the model excluded for the above reason.

Table 25.1.1: The 24 recall-models

	${\tt ASP}[\mathbb{R}]$	$\mathtt{ABP}[\mathbb{R}]$	$\mathtt{ASP}[\mathbb{P}]$	$\mathtt{ABP}[\mathbb{P}]$
$Q\{rM:1[A]\} =$	$\{ \mathrm{rM}:1[\mathbb{R}][\mathtt{A}],$	$r ilde{M}{:}1[\mathbb{R}][\mathtt{A}],$	-rM:1[ℙ][A]-,	$-r\tilde{M}:1[\mathbb{P}][\mathtt{A}]$
$Q\{rM:1[E]\} =$	$\ \ \{\ rM{:}1[\mathbb{R}][E],$	$r ilde{M}{:}1[\mathbb{R}][E],$	-rM:1[ℙ][E]-,	$-r\tilde{M}:1[\mathbb{P}][E]$
$\mathcal{Q}\{rM{:}2[\mathtt{A}]\} =$	$\{ \mathrm{rM} : 2[\mathbb{R}][\mathtt{A}],$	$r ilde{M}{:}2[\mathbb{R}][\mathtt{A}],$	-rM:2[ℙ][A]-,	$-r\tilde{M}{:}2[\mathbb{P}][\mathtt{A}]$
$Q\{rM:2[E]\} =$	$\{ \ rM{:}2[\mathbb{R}][E],$	$r ilde{M}{:}2[\mathbb{R}][E],$	$rM:2[\mathbb{P}][E]$ ,	$-r\tilde{M}:2[\mathbb{P}][E]$
$Q\{rM:3[A]\} =$	$\{ \text{ rM:} 3[\mathbb{R}][A],$	$r\tilde{M}{:}3[\mathbb{R}][\mathtt{A}],$	-rM:3[₽][A]-,	<u>-rÑ:3[ℙ][A]</u> }
$Q\{rM:3[E]\} =$	$\{ \ rM{:}3[\mathbb{R}][E],$	$r\tilde{M}{:}3[\mathbb{R}][E],$	rM:3[₽][E]-,	$-r\tilde{M}:3[\mathbb{P}][E]$

# 25.2 Model 1

# $\mathbf{25.2.1} \quad \mathbf{Search\text{-}Enforced\text{-}Model 1:} \ \mathcal{Q}\{\mathbf{rM}:1[\mathbb{E}]\} = \{\mathbf{rM}:1[\mathbb{R}][\mathbb{E}], \mathbf{r\tilde{M}}:1[\mathbb{R}][\mathbb{E}], \mathbf{r\tilde{M}}:1[\mathbb{R}][\mathbb{E}], \mathbf{r\tilde{M}}:1[\mathbb{R}][\mathbb{E}], \mathbf{r\tilde{M}}:1[\mathbb{R}][\mathbb{E}]\}$

# **25.2.1.1** $rM:1[\mathbb{R}][E]$

This is the most basic model of the selling model with recall, which is identical to  $M:1[\mathbb{R}][E]$  (see Section 4.1.1.1.1(p.19)) except that the price to be accepted is the best among the prices rejected so far.

# **25.2.1.2** $r\tilde{M}:1[\mathbb{R}][E]$

This is the most basic model of the buying model with recall, which is the same as  $\tilde{M}:1[\mathbb{R}][E]$  (see Section 4.1.1.1.2(p.20)) except that the price to be accepted is the best of prices rejected so far.

#### $\mathbf{25.2.2} \quad \mathbf{Search-Allowed-Model 1:} \ \mathcal{Q}_{\mathbf{rM}:\mathbf{1}[\mathbf{A}]} = \{\mathbf{rM}:\mathbf{1}[\mathbf{R}][\mathbf{A}], \ \mathbf{r\tilde{M}}:\mathbf{1}[\mathbf{R}][\mathbf{A}], \ \mathbf{r\tilde{M}}:\mathbf{1}[\mathbf{P}][\mathbf{A}], \mathbf{r\tilde{M}}:\mathbf{1}[\mathbf{R}][\mathbf{A}], \mathbf{r\tilde{M}}:\mathbf{1}[\mathbf{R}][\mathbf{R}], \mathbf{r\tilde{M}}:\mathbf{1}[\mathbf{R}][\mathbf{R}][\mathbf{R}], \mathbf{r\tilde{M}}:\mathbf{1}[\mathbf{R}][\mathbf{$

This is the same model as the one described in Section 25.2.1(p.249), except that the search is allowed.

# 25.3 Model 2

This model is defined by adding the terminal quitting penalty price  $\rho$  to Model 1 as described in Section 25.2(p.249).

# 25.4 Model 3

This model is defined by adding the intervening quitting penalty price  $\rho$  to Model 2 as described in Section 25.3(p.249).

# 25.5 Best Price

# Definition 25.5.1 (best price)

- (a) In the selling model M (buying model  $\tilde{M}$ ) let us refer to the highest y of buying prices (the highest y of selling prices) which have been offered and rejected as the best price y.
- (b) By  $\mathsf{Accept}_t\langle y\rangle$  ( $\mathsf{Reject}_t\langle y\rangle$ ) let us denote "Accept (Reject) the best price y at time t".  $\square$

Remark 25.5.1 When the process initiates at a given time t, there exist no best price since no search activity is conducted before that.  $\square$ 

# Chapter 26

# **Systems of Optimality Equations**

For this model we consider only  $\mathbb{R}$ -mechanism-model (see  $\overline{\text{F.S.}}$  2(p.249)).

# **26.1** Model 1

#### 26.1.1 Search-Allowed-Model 1

#### **26.1.1.1** $rM:1[\mathbb{R}][A]$

By  $v_t(y)$   $(t \ge 0)$  and  $V_t$  (t > 0) let us denote the maximum total expected present discounted *profit* from initiating the process at time t with the best price y and with no best price respectively, expressed as

$$v_0(y) = y, (26.1.1)$$

$$v_t(y) = \max\{y, V_t(y)\}, \quad t > 0,$$
 (26.1.2)

$$V_1 = \beta \mathbf{E}[\boldsymbol{\xi}] - s = \beta \mu - s, \tag{26.1.3}$$

$$V_t = \max\{\beta \mathbf{E}[v_{t-1}(\xi)] - s, \beta V_{t-1}\} \quad t > 1, \tag{26.1.4}$$

where  $V_t(y)$  is the maximum total expected present discounted profit from rejecting the best price y, expressed as

$$V_t(y) = \max\{\beta \mathbf{E}[v_{t-1}(\max\{\xi, y\})] - s, \beta v_{t-1}(y)\}, \quad t > 0.$$
(26.1.5)

The system of optimality equations of this model is given by

$$SOE\{rM:1[\mathbb{R}][A]\} = \{(26.1.1(p.251)) - (26.1.5(p.251))\}. \tag{26.1.6}$$

For convenience let us define

$$V_0(y) = y. (26.1.7)$$

Then (26.1.2(p.251)) holds for  $t \ge 0$ , i.e.,

$$v_t(y) = \max\{y, V_t(y)\}, \quad t \ge 0.$$
 (26.1.8)

From (26.1.4(p.251)) and (26.1.5(p.251)) with t = 1 we have respectively

$$V_1(y) = \max\{\beta \mathbf{E}[\max\{\boldsymbol{\xi}, y\}] - s, \beta y\}$$
(26.1.9)

$$= \max\{K(y) + y, \beta y\} \qquad \text{(from (6.1.10(p.25)) with } \lambda = 1) \tag{26.1.10}$$

$$= \max\{L(y) + \beta y, \beta y\} \quad \text{(from (6.1.9(p.25)))}. \tag{26.1.11}$$

$$= \max\{L(y), 0\} + \beta y. \tag{26.1.12}$$

Let us here define

$$S_t = \beta(\mathbf{E}[v_{t-1}(\xi)] - V_{t-1}) - s, \quad t > 1. \tag{26.1.13}$$

Then, (26.1.4(p.251)) can be rewritten as

$$V_t = \max\{S_t, 0\} + \beta V_{t-1}, \quad t > 1, \tag{26.1.14}$$

implying that

$$\mathbb{S}_t \ge (\le) \ 0 \Rightarrow \mathtt{Conduct}_t \ (\mathtt{Skip}_t), \quad t > 1.$$
 (26.1.15)

More strictly

$$\mathbb{S}_t \ge (\le) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\triangle}} \ (\mathtt{Skip}_{t_{\triangle}}). \tag{26.1.16}$$

$$\mathbb{S}_t = (=) \ 0 \Rightarrow \mathsf{Conduct}_{t\parallel} \ (\mathsf{Skip}_{t\parallel}). \tag{26.1.17}$$

$$\mathbb{S}_t > (<) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}} \ (\mathtt{Skip}_{t_{\blacktriangle}}).$$
 (26.1.18)

Furthermore let us define

$$S_t(y) = \beta(\mathbf{E}[v_{t-1}(\max\{\xi, y\})] - v_{t-1}(y)) - s, \quad t > 0.$$
(26.1.19)

Then (26.1.5(p.251)) can be rewritten as

$$V_t(y) = \max\{S_t(y), 0\} + \beta v_{t-1}(y), \quad t > 0, \tag{26.1.20}$$

implying that

$$\mathbb{S}_t(y) \ge (\le) \ 0 \Rightarrow \mathsf{Conduct}_t \ (\mathsf{Skip}_t), \quad t > 0.$$
 (26.1.21)

More strictly

$$\mathbb{S}_t(y) \ge (\le) \ 0 \Rightarrow \mathsf{Conduct}_{t_{\Delta}}(\mathsf{Skip}_{t_{\Delta}}).$$
 (26.1.22)

$$\mathbb{S}_t(y) = (=) \ 0 \Rightarrow \mathsf{Conduct}_{t \parallel} \ (\mathsf{Skip}_{t \parallel}). \tag{26.1.23}$$

$$\mathbb{S}_t(y) > (<) \ 0 \Rightarrow \mathsf{Conduct}_{t_{\mathbf{A}}} \ (\mathsf{Skip}_{t_{\mathbf{A}}}).$$
 (26.1.24)

From the comparison of the two terms within  $\{\ \}$  in the right-hand side of (26.1.2(p.251)) we see that the decision "whether or not to accept the best price y" can be prescribed as follows:

$$\begin{array}{lll} y \geq V_t(y) & \Rightarrow & \mathtt{Accept}_t\langle y \rangle \text{ and the process stops } \mathbf{I} \\ y \leq V_t(y) & \Rightarrow & \mathtt{Reject}_t\langle y \rangle \text{ and } \mathtt{Conduct}_t/\mathtt{Skip}_t^{\ \dagger} \end{array} \right\} \quad t > 0$$

## **26.1.1.2** $\tilde{rM}:1[\mathbb{R}][A]$

By  $v_t(y)$   $(t \ge 0)$  and  $V_t$  (t > 0) let us denote the minimum total expected present discounted cost from initiating the process at time t with the best price y and with no best price respectively, expressed as

$$v_0(y) = y,$$
 (26.1.26)

$$v_t(y) = \min\{y, V_t(y)\}, \quad t > 0,$$
 (26.1.27)

$$V_1 = \beta \mathbf{E}[\xi] + s = \beta \mu + s,$$
 (26.1.28)

$$V_t = \min\{\beta \mathbf{E}[v_{t-1}(\xi)] + s, \beta V_{t-1}\} \quad t > 1, \tag{26.1.29}$$

where  $V_t(y)$  is the minimum total expected present discounted cost from rejecting the best price y, expressed as

$$V_t(y) = \min\{\beta \mathbf{E}[v_{t-1}(\min\{\xi, y\})] + s, \beta v_{t-1}(y)\}, \quad t > 0.$$
(26.1.30)

The system of optimality equations of this model is given by

$$SOE\{r\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbf{A}]\} = \{(26.1.26(p.252)) - (26.1.30(p.252))\}. \tag{26.1.31}$$

For convenience let us define

$$V_0(y) = y. (26.1.32)$$

Then (26.1.27(p.252)) holds for  $t \ge 0$ , i.e.,

$$v_t(y) = \min\{y, V_t(y)\}, \quad t > 0.$$
 (26.1.33)

Let us define

$$\tilde{\mathbb{S}}_t = \beta(\mathbf{E}[v_{t-1}(\xi)] - V_{t-1}) + s, \quad t > 1.$$
(26.1.34)

Then (26.1.29(p.252)) can be rewritten as

$$V_t = \min\{\tilde{S}_t, 0\} + \beta V_{t-1}, \quad t > 1, \tag{26.1.35}$$

implying that

$$\tilde{\mathbb{S}}_t \le (\ge) \ 0 \Rightarrow \mathtt{Conduct}_t \ (\mathtt{Skip}_t), \quad t > 1.$$
 (26.1.36)

More strictly

$$\tilde{\mathbb{S}}_t \le (\ge) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\Delta}} \ (\mathtt{Skip}_{t^{\Delta}}).$$
 (26.1.37)

$$\tilde{\mathbb{S}}_t = (=) \ 0 \Rightarrow \mathsf{Conduct}_{t \parallel} \ (\mathsf{Skip}_{t \parallel}). \tag{26.1.38}$$

$$\tilde{\mathbb{S}}_t < (>) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}} \ (\mathtt{Skip}_{t_{\blacktriangle}}).$$
 (26.1.39)

Let us define

$$\tilde{S}_t(y) = \beta(\mathbf{E}[v_{t-1}(\min\{\xi, y\})] - v_{t-1}(y)) + s, \quad t > 0.$$
(26.1.40)

Then (26.1.30(p.252)) can be rewritten as, for any y,

$$V_t(y) = \min\{\tilde{S}_t(y), 0\} + \beta v_{t-1}(y), \quad t > 0, \tag{26.1.41}$$

implying that

<sup>&</sup>lt;sup>†</sup>The symbol "/" means "or", i.e., "CONDUCT<sub>t</sub> or SKIP<sub>t</sub>".

$$\tilde{\mathbb{S}}_t(y) \le (\ge) \ 0 \Rightarrow \mathtt{Conduct}_t \ (\mathtt{Skip}_t), \quad t > 0.$$
 (26.1.42)

More strictly

$$\tilde{\mathbb{S}}_t(y) \le (\ge) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\triangle}}(\mathtt{Skip}_{t_{\triangle}}).$$
 (26.1.43)

$$\tilde{\mathbb{S}}_t(y) = (=) \ 0 \Rightarrow \mathtt{Conduct}_{t\parallel} \ (\mathtt{Skip}_{t\parallel}). \tag{26.1.44}$$

$$\tilde{\mathbb{S}}_t(y) < (>) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}}(\mathtt{Skip}_{t_{\blacktriangle}}).$$
 (26.1.45)

From the comparison of the two terms within  $\{\ \}$  in the right-hand side of (26.1.27(p.252)) we see that the decision "whether or not to accept the best price y" can be prescribed as follows:

$$\begin{array}{lll} y \leq V_t(y) & \Rightarrow & \mathtt{Accept}_t\langle y \rangle \text{ and the process stops } \mathbf{I} \\ y \geq V_t(y) & \Rightarrow & \mathtt{Reject}_t\langle y \rangle \text{ and } \mathtt{Conduct}_t/\mathtt{Skip}_t \end{array} \right\} \quad t > 0$$

#### 26.1.2 Search-Enforced-Model 1

#### **26.1.2.1** $rM:1[\mathbb{R}][E]$

This is the most basic model with recall [43,Sak1961], the system of optimality equations of which is given as below. By  $v_t(y)$   $(t \ge 0)$  and  $V_t$  (t > 0) let us denote the maximum total expected present discounted *profit* from initiating the process at time t with the best price y and with no best price respectively, expressed as

$$v_0(y) = y, (26.1.47)$$

$$v_t(y) = \max\{y, V_t(y)\}, \quad t > 0,$$
 (26.1.48)

$$V_t = \beta \mathbf{E}[v_{t-1}(\xi)] - s, \quad t > 0,$$
 (26.1.49)

where  $V_t(y)$  is the maximum total expected present discounted profit from rejecting the best price y, expressed as

$$V_t(y) = \beta \mathbf{E}[v_{t-1}(\max\{\xi, y\})] - s, \quad t > 0.$$
(26.1.50)

The system of optimality equations of this model is given by

$$SOE\{rM:1[\mathbb{R}][E]\} = \{(26.1.47(p.253)) - (26.1.50(p.253))\}. \tag{26.1.51}$$

For convenience let us define

$$V_0(y) = y. (26.1.52)$$

Then (26.1.48(p.253)) holds for  $t \ge 0$ , i.e.,

$$v_t(y) = \max\{y, V_t(y)\}, \quad t \ge 0.$$
 (26.1.53)

From (26.1.49(p.253)) and (26.1.50(p.253)) with t=1 we have respectively

$$V_1 = \beta \mathbf{E}[\xi] - s = \beta \mu - s,$$
 (26.1.54)

$$V_1(y) = \beta \mathbf{E}[\max{\lbrace \boldsymbol{\xi}, y \rbrace}] - s \tag{26.1.55}$$

$$= K(y) + y \quad \text{(from (6.1.10(p.25)) with } \lambda = 1)$$
 (26.1.56)

$$= L(y) + \beta y \quad \text{(from (6.1.9[p.25]))}. \tag{26.1.57}$$

From the comparison of the two terms within  $\{\ \}$  in the right-hand side of (26.1.48(p.253)) we see that the decision "whether or not to accept the best price y" can be prescribed as follows:

## **26.1.2.2** $\tilde{rM}:1[\mathbb{R}][E]$

By  $v_t(y)$   $(t \ge 0)$  and  $V_t$  (t > 0) let us denote the minimum total expected present discounted *cost* from initiating the process at time t with the best price y and with no best price respectively, expressed as

$$v_0(y) = y, (26.1.59)$$

$$v_t(y) = \min\{y, V_t(y)\}, \quad t > 0,$$
 (26.1.60)

$$V_t = \beta \mathbf{E}[v_{t-1}(\xi)] + s, \quad t > 0,$$
 (26.1.61)

where  $V_t(y)$  is the minimum total expected present discounted cost from rejecting the best price y, expressed as

$$V_t(y) = \beta \mathbf{E}[v_{t-1}(\min\{\xi, y\})] + s, \quad t > 0.$$
(26.1.62)

The system of optimality equations of this model is given by

$$SOE\{r\tilde{M}:1[\mathbb{R}][E]\} = \{(26.1.59(p.253)) - (26.1.62(p.253))\}. \tag{26.1.63}$$

For convenience let us define

$$V_0(y) = y. (26.1.64)$$

Then (26.1.60(p.253)) holds for  $t \ge 0$ , i.e.,

$$v_t(y) = \min\{y, V_t(y)\}, \quad t \ge 0.$$
 (26.1.65)

From the comparison of the two terms within  $\{\ \}$  in the right-hand side of (26.1.60(p.253)) we see that the decision "whether or not to accept the best price y" can be prescribed as follows:

$$y \leq V_t(y) \Rightarrow \operatorname{Accept}_t\langle y \rangle \text{ and the process stops } \mathbf{I}$$
 $y \geq V_t(y) \Rightarrow \operatorname{Reject}_t\langle y \rangle \text{ and the search is conducted}$   $t > 0.$  (26.1.66)

# 26.2 Mode 2

#### 26.2.1 Search-Allowed-Model 2

#### **26.2.1.1** $rM:2[\mathbb{R}][A]$

By  $v_t(y)$   $(t \ge 0)$  and  $V_t$   $(t \ge 0)$  let us denote the maximum total expected present discounted *profit* from initiating the process at time t with the best price y and with no best price respectively, expressed as

$$v_0(y) = \max\{y, \rho\} \tag{26.2.1}$$

$$v_t(y) = \max\{y, V_t(y)\}, \quad t > 0,$$
 (26.2.2)

$$V_0 = \rho, \tag{26.2.3}$$

$$V_t = \max\{\lambda \beta \, \mathbf{E}[v_{t-1}(\boldsymbol{\xi})] + (1-\lambda)\beta V_{t-1} - s, \beta V_{t-1}\}, \quad t > 0, \tag{26.2.4}$$

where  $V_t(y)$  (t>0) is the maximum total expected present discounted profit from rejecting the best price y, expressed as

$$V_t(y) = \max\{\lambda \beta \mathbf{E}[v_{t-1}(\max\{\xi, y\})] + (1 - \lambda)\beta v_{t-1}(y) - s, \beta v_{t-1}(y)\}, \quad t > 0.$$
(26.2.5)

The system of optimality equations of this model is given by

$$SOE\{rM:2[\mathbb{R}][A]\} = \{(26.2.1(p.254)) - (26.2.5(p.254))\}. \tag{26.2.6}$$

For convenience let us define

$$V_0(y) = \rho. (26.2.7)$$

Then (26.2.2(p.254)) holds for  $t \geq 0$  instead of t > 0, i.e.,

$$v_t(y) = \max\{y, V_t(y)\}, \quad t \ge 0, \tag{26.2.8}$$

From (26.2.4(p.254)) and (26.2.5(p.254)) with t = 1 we have respectively

$$V_1 = \max\{\lambda \beta \mathbf{E}[\max\{\boldsymbol{\xi}, \rho\}] + (1 - \lambda)\beta \rho - s, \beta \rho\}$$
(26.2.9)

$$= \max\{K(\rho) + \rho, \beta\rho\} \quad (\text{see } (6.1.10(p.25))) \tag{26.2.10}$$

$$= \max\{L(\rho) + \beta \rho, \beta \rho\} \quad (\text{see } (6.1.9(p.25))) \tag{26.2.11}$$

$$= \max\{L(\rho), 0\} + \beta\rho, \tag{26.2.12}$$

$$V_1(y) = \max\{\lambda \beta \mathbf{E}[\max\{\max\{\xi, y\}, \rho\}] + (1 - \lambda)\beta \max\{y, \rho\} - s, \beta \max\{y, \rho\}\}$$
 (26.2.13)

 $= \max\{\lambda\beta \mathbf{E}[\max\{\boldsymbol{\xi}, \max\{y, \rho\}] + (1 - \lambda)\beta \max\{y, \rho\} - s, \beta \max\{y, \rho\}\}\}$ 

$$= \max\{K(\max\{y,\rho\}) + \max\{y,\rho\}, \beta \max\{y,\rho\}\} \quad (\text{see } (6.1.10(p.25)))$$
 (26.2.14)

$$= \max\{L(\max\{y,\rho\}) + \beta \max\{y,\rho\}, \beta \max\{y,\rho\}\} \quad (\text{see } (6.1.9(p.5)))$$
 (26.2.15)

$$= \max\{L(\max\{y,\rho\}), 0\} + \beta \max\{y,\rho\}. \tag{26.2.16}$$

Now let us define

$$S_t = \lambda \beta(\mathbf{E}[v_{t-1}(\xi)] - V_{t-1}) - s, \quad t > 0.$$
(26.2.17)

Then, (26.2.4(p.254)) can be rewritten as

$$V_t = \max\{S_t, 0\} + \beta V_{t-1}, \quad t > 0, \tag{26.2.18}$$

implying that

$$\mathbb{S}_t \ge (\le) \ 0 \Rightarrow \mathtt{Conduct}_t \ (\mathtt{Skip}_t), \quad t > 0. \tag{26.2.19}$$

More strictly

$$\mathbb{S}_t \ge (\le) \ 0 \Rightarrow \mathsf{Conduct}_{t_\Delta} \ (\mathsf{Skip}_{t_\Delta}).$$
 (26.2.20)

$$\mathbb{S}_t = (=) \ 0 \Rightarrow \mathtt{Conduct}_{t \parallel} \ (\mathtt{Skip}_{t \parallel}). \tag{26.2.21}$$

$$\mathbb{S}_t > (<) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}} \ (\mathtt{Skip}_{t_{\blacktriangle}}). \tag{26.2.22}$$

In addition, let us define

$$S_t(y) = \lambda \beta (\mathbf{E}[v_{t-1}(\max\{\xi, y\})] - v_{t-1}(y)) - s, \quad t > 0.$$
 (26.2.23)

Then (26.2.5(p.254)) can be rewritten as, for any y,

$$V_t(y) = \max\{\mathbb{S}_t(y), 0\} + \beta v_{t-1}(y), \quad t > 0, \tag{26.2.24}$$

implying that

$$\mathbb{S}_t(y) \ge (\le) \ 0 \Rightarrow \mathtt{Conduct}_t \ (\mathtt{Skip}_t), \quad t > 0.$$
 (26.2.25)

More strictly

$$\mathbb{S}_{t}(y) \ge (\le) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\Delta}} \ (\mathtt{Skip}_{t_{\Delta}}). \tag{26.2.26}$$

$$\mathbb{S}_t(y) = (=) \ 0 \Rightarrow \mathtt{Conduct}_{t\parallel} \ (\mathtt{Skip}_{t\parallel}). \tag{26.2.27}$$

$$\mathbb{S}_t(y) > (<) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}}(\mathtt{Skip}_{t_{\blacktriangle}}).$$
 (26.2.28)

From the comparison of the two terms within  $\{\ \}$  in the right-hand side of (26.2.2(p.254)) we see that the decision "whether or not to accept the best price y" can be prescribed as follows:

$$\begin{array}{lll} y \geq V_t(y) & \Rightarrow & \mathsf{Accept}_t\langle y \rangle \text{ and the process stops } \mathbf{I} \\ y \leq V_t(y) & \Rightarrow & \mathsf{Reject}_t\langle y \rangle \text{ and } \mathsf{Conduct}_t/\mathsf{Skip}_t \end{array} \right\} \quad t > 0$$

# **26.2.1.2** $r\tilde{M}:2[\mathbb{R}][A]$

By  $v_t(y)$   $(t \ge 0)$  and  $V_t$   $(t \ge 0)$  let us denote the minimum total expected present discounted *cost* from initiating the process at time t with the best price y and with no best price respectively, expressed as

$$v_0(y) = \min\{y, \rho\} \tag{26.2.30}$$

$$v_t(y) = \min\{y, V_t(y)\}, \quad t > 0,$$
 (26.2.31)

$$V_0 = \rho, \tag{26.2.32}$$

$$V_t = \min\{\lambda \beta \,\mathbf{E}[v_{t-1}(\boldsymbol{\xi})] + (1-\lambda)\beta V_{t-1} + s, \beta V_{t-1}\}, \quad t > 0, \tag{26.2.33}$$

where  $V_t(y)$  (t > 0) is the minimum total expected present discounted cost from rejecting the best price y, expressed as

$$V_t(y) = \min\{\lambda \beta \mathbf{E}[v_{t-1}(\min\{\xi, y\})] + (1 - \lambda)\beta v_{t-1}(y) + s, \beta v_{t-1}(y)\}, \quad t > 0.$$
(26.2.34)

The system of optimality equations of this model is given by

$$SOE\{r\tilde{M}:2[\mathbb{R}][A]\} = \{(26.2.30(p.25)) - (26.2.34(p.25))\}.$$
(26.2.35)

For convenience, let us define

$$V_0(y) = \rho. (26.2.36)$$

Then (26.2.31(p.255)) holds for  $t \ge 0$  instead of t > 0, i.e.,

$$v_t(y) = \min\{y, V_t(y)\}, \quad t \ge 0.$$
 (26.2.37)

Let us define

$$\tilde{\mathbb{S}}_t = \lambda \beta (\mathbf{E}[v_{t-1}(\xi)] - V_{t-1}) + s, \quad t > 0.$$
 (26.2.38)

Then (26.2.33(p.255)) can be rewritten as

$$V_t = \min\{\tilde{S}_t, 0\} + \beta V_{t-1}, \quad t > 0, \tag{26.2.39}$$

implying that

$$\tilde{\mathbb{S}}_t \le (\ge) \ 0 \Rightarrow \mathsf{Conduct}_t \ (\mathsf{Skip}_t).$$
 (26.2.40)

More strictly

$$\tilde{\mathbb{S}}_t \le (\ge) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\Delta}} \ (\mathtt{Skip}_{t_{\Delta}}).$$
 (26.2.41)

$$\tilde{\mathbb{S}}_t = (=) \ 0 \Rightarrow \mathtt{Conduct}_{t \parallel} \ (\mathtt{Skip}_{t \parallel}). \tag{26.2.42}$$

$$\tilde{\mathbb{S}}_t < (>) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}} \ (\mathtt{Skip}_{t_{\blacktriangle}}).$$
 (26.2.43)

In addition, let us define

$$\tilde{\mathbb{S}}_{t}(y) = \lambda \beta(\mathbf{E}[v_{t-1}(\min\{\xi, y\})] - v_{t-1}(y)) + s, \quad t > 0.$$
(26.2.44)

Then (26.2.34(p.255)) can be rewritten as, for any y,

$$V_t(y) = \min\{\tilde{\mathbb{S}}_t(y), 0\} + \beta v_{t-1}(y), \quad t > 0,$$
(26.2.45)

implying that

$$\tilde{\mathbb{S}}_t(y) \le (\ge) \ 0 \Rightarrow \mathtt{Conduct}_t \ (\mathtt{Skip}_t), \quad t > 0.$$
 (26.2.46)

More strictly

$$\tilde{\mathbb{S}}_t(y) \le (\ge) \ 0 \Rightarrow \mathtt{Conduct}_{t_\Delta} \ (\mathtt{Skip}_{t_\Delta}).$$
 (26.2.47)

$$\tilde{\mathbb{S}}_t(y) = (=) \ 0 \Rightarrow \mathsf{Conduct}_{t \parallel} \ (\mathsf{Skip}_{t \parallel}). \tag{26.2.48}$$

$$\tilde{\mathbb{S}}_t(y) < (>) \ 0 \Rightarrow \mathtt{Conduct}_{t_{\blacktriangle}}(\mathtt{Skip}_{t_{\blacktriangle}}).$$
 (26.2.49)

From the comparison of the two terms within  $\{\ \}$  in the right-hand side of (26.2.31(p.25)) we see that the decision "whether or not to accept the best price y" can be prescribed as follows:

$$\begin{array}{lll} y \leq V_t(y) & \Rightarrow & \mathtt{Accept}_t\langle y \rangle \text{ and the process stops } \mathbf{I} \\ y \geq V_t(y) & \Rightarrow & \mathtt{Reject}_t\langle y \rangle \text{ and } \mathtt{Conduct}_t/\mathtt{Skip}_t \end{array} \right\} \quad t > 0$$

# 26.2.2 Search-Enforced-Model 2

#### **26.2.2.1** $rM:2[\mathbb{R}][E]$

By  $v_t(y)$   $(t \ge 0)$  and  $V_t$   $(t \ge 0)$  let us denote the maximum total expected present discounted *profit* from initiating the process at time t with the best price y and with no best price respectively, expressed as

$$v_0(y) = \max\{y, \rho\} \tag{26.2.51}$$

$$v_t(y) = \max\{y, V_t(y)\}, \quad t > 0,$$
 (26.2.52)

$$V_0 = \rho,$$
 (26.2.53)

$$V_t = \lambda \beta \, \mathbf{E}[v_{t-1}(\xi)] + (1 - \lambda)\beta V_{t-1} - s, \quad t > 0, \tag{26.2.54}$$

where  $V_t(y)$  (t > 0) is the maximum total expected present discounted profit from rejecting the best price y, expressed as

$$V_t(y) = \lambda \beta \mathbf{E}[v_{t-1}(\max\{\xi, y\})] + (1 - \lambda)\beta v_{t-1}(y) - s, \quad t > 0.$$
(26.2.55)

The system of optimality equations of this model is given by

$$SOE\{rM:2[\mathbb{R}][E]\} = \{(26.2.51(p.256)) - (26.2.55(p.256))\}. \tag{26.2.56}$$

For convenience, let us define

$$V_0(y) = \rho. (26.2.57)$$

Then (26.2.52(p.256)) holds for  $t \ge 0$ , i.e.,

$$v_t(y) = \max\{y, V_t(y)\}, \quad t \ge 0. \tag{26.2.58}$$

From (26.2.54(p.256)) and (26.2.55(p.256)) with t = 1 we have respectively

$$V_{1} = \lambda \beta \mathbf{E}[\max\{\xi, \rho\}] + (1 - \lambda)\beta \rho - s$$
  
=  $K(\rho) + \rho$  (from (6.1.10(p.25))) (26.2.59)

$$= L(\rho) + \beta \rho \quad \text{(from (6.1.9(p.25)))}, \tag{26.2.60}$$

 $V_1(y) = \lambda \beta \mathbf{E} \left[ \max \left\{ \max \left\{ \xi, y \right\}, \rho \right\} \right] + (1 - \lambda) \beta \max \left\{ y, \rho \right\} - s$ 

 $= \lambda \beta \mathbf{E} \left[ \max \{ \boldsymbol{\xi}, \max \{ y, \rho \} \} \right] + (1 - \lambda) \beta \max \{ y, \rho \} - s$ 

$$= K(\max\{y,\rho\}\}) + \max\{y,\rho\} \quad \text{(from (6.1.10(p.25)))} \tag{26.2.61}$$

 $= L\left(\max\{y,\rho\}\}\right) + \beta \max\{y,\rho\} \quad \text{(from (6.1.9(p.25)))}. \tag{26.2.62}$ 

From the comparison of the two terms within  $\{\ \}$  in the right-hand side of (26.2.52(p.256)) we see that the decision "whether or not to accept the best price y" can be prescribed as follows:

## **26.2.2.2** $\tilde{rM}:2[\mathbb{R}][E]$

By  $v_t(y)$   $(t \ge 0)$  and  $V_t$   $(t \ge 0)$  let us denote the minimum total expected present discounted *cost* from initiating the process at time t with the best price y and with no best price respectively, expressed as

$$v_0(y) = \min\{y, \rho\} \tag{26.2.64}$$

$$v_t(y) = \min\{y, V_t(y)\}, \quad t > 0,$$
 (26.2.65)

$$V_0 = \rho,$$
 (26.2.66)

$$V_t = \lambda \beta \, \mathbf{E}[v_{t-1}(\xi)] + (1 - \lambda)\beta V_{t-1} + s, \quad t > 0, \tag{26.2.67}$$

where  $V_t(y)$  is the minimum total expected present discounted cost from rejecting the best price y, expressed as

$$V_t(y) = \lambda \beta \mathbf{E}[v_{t-1}(\min\{\xi, y\})] + (1 - \lambda)\beta v_{t-1}(y) + s, \quad t > 0.$$
(26.2.68)

The system of optimality equations of this model is given by

$$SOE\{r\tilde{M}: 2[\mathbb{R}][E]\} = \{(26.2.64(p.250)) - (26.2.68(p.257))\}. \tag{26.2.69}$$

For convenience, let us define

$$V_0(y) = \rho. (26.2.70)$$

Then (26.2.65(p.256)) holds for  $t \ge 1$ , i.e.,

$$v_t(y) = \min\{y, V_t(y)\}, \quad t \ge 0. \tag{26.2.71}$$

From the comparison of the two terms within  $\{\ \}$  in the right-hand side of (26.2.65(p.256)) we see that the decision "whether or not to accept the best price y" can be prescribed as follows:

# 26.3 Mode: 3

### 26.3.1 Search-Allowed-Model 3

#### **26.3.1.1** $rM:3[\mathbb{R}][A]$

By  $v_t(y)$   $(t \ge 0)$  and  $V_t$   $(t \ge 0)$  let us denote the maximum total expected present discounted *profit* from initiating the process at time t with the best price y and with no best price respectively, expressed as

$$v_0(y) = \max\{y, \rho\} \tag{26.3.1}$$

$$v_t(y) = \max\{y, \rho, U_t(y)\}, \quad t > 0,$$
 (26.3.2)

$$V_0 = \rho, \tag{26.3.3}$$

$$V_t = \max\{\rho, U_t\}, \quad t > 0. \tag{26.3.4}$$

where  $U_t(y)$  in (26.3.2(p.257)) is the maximum total expected present discounted profit from rejecting both y and  $\rho$ , expressed as

$$U_t(y) = \max\{\lambda \beta \mathbf{E}[v_{t-1}(\max\{\xi, y\})] + (1 - \lambda)\beta v_{t-1}(y) - s, \beta v_{t-1}(y)\}, \quad t > 0.$$
 (26.3.5)

where  $U_t$  in (26.3.4(p.257)) is the maximum total expected present discounted profit from rejecting  $\rho$ , expressed as

$$U_t = \max\{\lambda \beta \,\mathbf{E}[v_{t-1}(\boldsymbol{\xi})] + (1-\lambda)\beta V_{t-1} - s, \beta V_{t-1}\}, \quad t > 0, \tag{26.3.6}$$

The system of optimality equations of this model is given by

$$SOE\{rM:3[\mathbb{R}][A]\} = \{(26.3.1(p.257)) - (26.3.6(p.257))\}. \tag{26.3.7}$$

For convenience, let us define

$$U_0(y) = \rho \cdots (1), \qquad U_0 = \rho \cdots (2).$$
 (26.3.8)

Then (26.3.2(p.257)) holds for  $t \ge 0$  instead of t > 0, i.e.,

$$v_t(y) = \max\{y, \rho, U_t(y)\} \cdots (1), \qquad V_t = \max\{\rho, U_t\} \cdots (2), \quad t \ge 0.$$
 (26.3.9)

#### **26.3.1.2** $\vec{r}$ M:3[ $\mathbb{R}$ ][A]

By  $v_t(y)$   $(t \ge 0)$  and  $V_t$   $(t \ge 0)$  let us denote the minimum total expected present discounted *cost* from initiating the process at time t with the best price y and with no best price respectively, expressed as

$$v_0(y) = \min\{y, \rho\} \tag{26.3.10}$$

$$v_t(y) = \min\{y, \rho, U_t(y)\}, \quad t > 0,$$
 (26.3.11)

$$V_0 = \rho, (26.3.12)$$

$$V_t = \min\{\rho, U_t\}, \quad t > 0, \tag{26.3.13}$$

where  $U_t(y)$  in (26.3.11(p.257)) is the minimum total expected present discounted cost from rejecting both y and  $\rho$ , expressed as

$$U_t(y) = \min\{\lambda \beta \mathbf{E}[v_{t-1}(\min\{\xi, y\})] + (1 - \lambda)\beta v_{t-1}(y) + s, \beta v_{t-1}(y)\}, \quad t > 0.$$
 (26.3.14)

and where  $U_t$  in (26.3.13(p.25)) is the minimum total expected present discounted cost from rejecting  $\rho$ , expressed as

$$U_t = \min\{\lambda \beta \mathbf{E}[v_{t-1}(\xi)] + (1-\lambda)\beta V_{t-1} + s, \beta V_{t-1}\}, \quad t > 0,$$
(26.3.15)

The system of optimality equations of this model is given by

$$SOE\{r\tilde{M}:3[\mathbb{R}][A]\} = \{(26.3.10(p.257)) - (26.3.15(p.258))\}. \tag{26.3.16}$$

For convenience, let us define

$$U_0(y) = \rho \cdots (1), \qquad U_0 = \rho \cdots (2).$$
 (26.3.17)

Then (26.3.11(p.257)) and (26.3.13(p.257)) hold for  $t \ge 0$  instead of t > 0, i.e.,

$$v_t(y) = \min\{y, \rho, U_t(y)\} \cdots (1), \qquad V_t = \min\{y, U_t\} \cdots (2), \quad t \ge 0.$$
 (26.3.18)

# 26.3.2 Search-Enforced-Model 3

# **26.3.2.1** $rM:3[\mathbb{R}][E]$

By  $v_t(y)$   $(t \ge 0)$  and  $V_t$   $(t \ge 0)$ let us denote the maximum total expected present discounted *profit* from initiating the process at time t with the best price y and with no best price respectively, expressed as

$$v_0(y) = \max\{y, \rho\},\tag{26.3.19}$$

$$v_t(y) = \max\{y, \rho, U_t(y)\}, \quad t > 0,$$
 (26.3.20)

$$V_0 = \rho,$$
 (26.3.21)

$$V_t = \max\{\rho, U_t\}, \quad t > 0. \tag{26.3.22}$$

where  $U_t(y)$  in (26.3.20(p.28)) is the maximum total expected present discounted profit from rejecting both y and  $\rho$ , expressed as

$$U_t(y) = \lambda \beta \mathbf{E}[v_{t-1}(\max\{\xi, y\})] + (1 - \lambda)\beta v_{t-1}(y) - s, \quad t > 0.$$
(26.3.23)

and where  $U_t$  in (26.3.22(p.258)) is the maximum total expected present discounted profit from rejecting  $\rho$ , expressed as

$$U_t = \lambda \beta \mathbf{E}[v_{t-1}(\xi)] + (1 - \lambda)\beta V_{t-1} - s, \quad t > 0.$$
(26.3.24)

The system of optimality equations of this model is given by

$$SOE\{rM:3[\mathbb{R}][E]\} = \{(26.3.19(p.258)) - (26.3.24(p.258))\}. \tag{26.3.25}$$

For convenience, let us define

$$U_0(y) = \rho \cdots (1), \qquad U_0 = \rho \cdots (2).$$
 (26.3.26)

Then (26.3.20(p.258)) and (26.3.22(p.258)) hold for  $t \ge 0$  instead of t > 0, i.e.,

$$v_t(y) = \max\{y, \rho, U_t(y)\} \cdots (1), \qquad V_t = \max\{\rho, U_t\} \cdots (2), \quad t \ge 0.$$
 (26.3.27)

# **26.3.2.2** $\tilde{rM}:3[\mathbb{R}][E]$

By  $v_t(y)$   $(t \ge 0)$  and  $V_t$   $(t \ge 0)$  let us denote the minimum total expected present discounted *cost* from initiating the process at time t with the best price y and with no best price respectively, expressed as

$$v_0(y) = \min\{y, \rho\} \tag{26.3.28}$$

$$v_t(y) = \min\{y, \rho, U_t(y)\}, \quad t > 0,$$
 (26.3.29)

$$V_0 = \rho, (26.3.30)$$

$$V_t = \min\{\rho, U_t\}. \tag{26.3.31}$$

where  $U_t(y)$  in (26.3.29(p.258)) is the minimum total expected present discounted cost from rejecting both y and  $\rho$ , expressed as

$$U_t(y) = \lambda \beta \mathbf{E}[v_{t-1}(\min\{\xi, y\})] + (1 - \lambda)\beta v_{t-1}(y) + s, \quad t > 0.$$
(26.3.32)

and where  $U_t$  in (26.3.31(p.258)) is the minimum total expected present discounted cost from rejecting  $\rho$ , expressed as

$$U_t = \lambda \beta \, \mathbf{E}[v_{t-1}(\xi)] + (1 - \lambda)\beta V_{t-1} + s, \quad t > 0, \tag{26.3.33}$$

The system of optimality equations of this model is given by

$$SOE\{r\tilde{\mathsf{M}}:3[\mathbb{R}][\mathsf{E}]\} = \{(26.3.28(p.258)) - (26.3.33(p.258))\}. \tag{26.3.34}$$

For convenience, let us define

$$U_0(y) = \rho \cdots (1), \qquad U_0 = \rho \cdots (2).$$
 (26.3.35)

Then (26.3.29(p.258)) and (26.3.31(p.258)) hold for  $t \ge 0$  instead of t > 0, i.e.,

$$v_t(y) = \min\{y, \rho, U_t(y)\} \cdots (1), \qquad V_t = \min\{y, U_t\} \cdots (2), \quad t \ge 0.$$
 (26.3.36)

# 26.4 Reservation Value

 $\langle a \rangle$  t-reservation-value (no-recall-model).

Consider the selling model with no recall. Here recall (8.2.2(p.43)), i.e.,

$$w \ge (\le) V_t \Rightarrow \mathsf{Accept}_t(w) \ (\mathsf{Reject}_t(w)),$$
 (26.4.1)

meaning that the reservation value of the model is given by  $V_t$ , which depends on t. Then we say that  $V_t$  is the t-dependent reservation-value or t-reservation-value for short.

 $\langle b \rangle$  t-reservation-value (recall-model).

Consider the selling model with recall. Here, by  $A_t(y)$  let us represent the profit from accepting the best price y at a given time t, so  $A_t(y) = y$ , and by  $R_t(y)$  the profit from rejecting the best price y at a given time t, so  $R_t(y) = V_t(y)$  (see (26.1.48(p.253))). Here let us define

$$AR_t(y) \stackrel{\text{def}}{=} A_t(y) - B_t(y) = y - V_t(y). \tag{26.4.2}$$

Then suppose that there exists  $y_t^*$  such that

$$\mathtt{AR}_t(y) \geq (\leq) \ 0 \Leftrightarrow y \geq (\leq) \ V_t(y) \Leftrightarrow y \geq (\leq) \ y_t^* \Rightarrow \mathtt{Accept}_t\langle y \rangle \ (\mathtt{Reject}_t\langle y \rangle) \quad (\mathtt{see} \ (26.1.58 (\texttt{p.253}))), \qquad (26.4.3)$$

implying that the reservation value of the model is given by  $y_t^*$ , which depends on t. Then we say that  $y_t^*$  is the t-reservation-value.

 $\langle c \rangle$  c-reservation-value.

If  $V_t$  and  $y_t^*$  are constant in t, then we say that each of  $V_t$  and  $y_t^*$  is the constant reservation-value or the c-reservation-value for short.

# 26.5 Systems of Optimality Equations

Below are the systems of optimality equations for the 12 models.

```
\begin{array}{lll} rM:1[\mathbb{R}][A] & \to \mbox{Section } 26.1.1.1(\mbox{$p.251$})\,, & r\tilde{M}:1[\mathbb{R}][A] & \to \mbox{Section } 26.1.2.2(\mbox{$p.252$})\,, \\ rM:1[\mathbb{R}][E] & \to \mbox{Section } 26.1.2.1(\mbox{$p.253$})\,, & r\tilde{M}:1[\mathbb{R}][E] & \to \mbox{Section } 26.1.2.2(\mbox{$p.253$})\,, \\ rM:1[\mathbb{R}][A] & \to \mbox{Section } 26.2.1.1(\mbox{$p.254$})\,, & r\tilde{M}:1[\mathbb{R}][A] & \to \mbox{Section } 26.2.1.2(\mbox{$p.255$})\,, \\ rM:1[\mathbb{R}][E] & \to \mbox{Section } 26.2.2.1(\mbox{$p.256$})\,, & r\tilde{M}:1[\mathbb{R}][E] & \to \mbox{Section } 26.3.1.2(\mbox{$p.257$})\,, \\ rM:1[\mathbb{R}][E] & \to \mbox{Section } 26.3.2.1(\mbox{$p.258$})\,, & r\tilde{M}:1[\mathbb{R}][E] & \to \mbox{Section } 26.3.2.2(\mbox{$p.258$})\,, \\ r\tilde{M}:1[\mathbb{R}][E] & \to \mbox{Section } 26.3.2.2(\mbox{$p.258$})\,, \\ \end{array}
```

# Chapter 27

# Analysis of Model 1

# 27.1 Search-Allowed-Model 1

27.1.1 rM:1[ $\mathbb{R}$ ][A]

27.1.1.1 Lemmas

27.1.1.1.1 Preliminary

Lemma 27.1.1 (rM:1[ $\mathbb{R}$ ][ $\mathbb{A}$ ]) We have  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\vartriangle}$ .  $\square$ 

• Proof Since  $V_t \geq \beta V_{t-1}$  for t > 1 from (26.1.4(p.251)), we have  $V_t \geq \beta V_{t-1}$  for  $\tau \geq t > 1$ , hence  $V_\tau \geq \beta V_{\tau-1}$ ,  $V_{\tau-1} \geq \beta V_{\tau-2}$ ,  $\cdots$ ,  $V_2 \geq \beta V_1$ , leading to  $V_\tau \geq \beta V_{\tau-1} \geq \beta^2 V_{\tau-1} \geq \cdots \geq \beta^{\tau-1} V_1$ . Thus, we have  $t_\tau^* = \tau$  for  $\tau > 0$ , i.e.,  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}_{\vartriangle}$ .

#### Lemma 27.1.2 (rM:1[ $\mathbb{R}$ ][ $\mathbb{A}$ ])

- (a)  $v_t(y)$  and  $V_t(y)$  are nondecreasing in y for  $t \geq 0$ .
- (b)  $v_t(y)$  and  $V_t(y)$  are nondecreasing in  $t \ge 0$  and t > 0 respectively.
- (c)  $V_t$  is nondecreasing in t > 0.  $\square$
- Proof (a)  $v_0(y)$  is nondecreasing in y from (26.1.1(p.251)). Suppose  $v_{t-1}(y)$  is nondecreasing in y. Then  $V_t(y)$  is nondecreasing in y from (26.1.5(p.251)), hence  $v_t(y)$  is nondecreasing in y from (26.1.8(p.251)). Accordingly, by induction  $v_t(y)$  is nondecreasing in y for  $t \ge 0$ . Then  $v_{t-1}(y)$  is nondecreasing in y for t > 0, hence  $V_t(y)$  is nondecreasing in y for t > 0 from (26.1.5(p.251)). In addition,  $V_0(y)$  is nondecreasing in y from (26.1.7(p.251)), hence it follows that  $V_t(y)$  is nondecreasing in y for  $t \ge 0$
- (b) Clearly  $v_1(y) \ge y = v_0(y)$  for any y from (26.1.2[p.25]) with t = 1 and (26.1.1[p.25]). Suppose  $v_{t-1}(y) \ge v_{t-2}(y)$  for any y. Then, from (26.1.5[p.25]) we have  $V_t(y) \ge \max\{\beta \mathbf{E}[v_{t-2}(\max\{\xi,y\})] s, \beta v_{t-2}(y)\} = V_{t-1}(y)$  for any y. Hence, from (26.1.8[p.25]) we have  $v_t(y) \ge \max\{y, V_{t-1}(y)\} = v_{t-1}(y)$  for any y. Thus, by induction  $v_t(y)$  is nondecreasing in  $t \ge 0$  for any y. Since  $v_{t-1}(y)$  is nondecreasing in t > 0 for any y, it follows that  $V_t(y)$  is nondecreasing in t > 0 for any y from (26.1.5[p.25]).
- (c) From (26.1.4(p.251)) with t=2 we have  $V_2 \geq \beta \mathbf{E}[v_1(\boldsymbol{\xi})] s$ . In addition, since  $v_1(\boldsymbol{\xi}) \geq \boldsymbol{\xi}$  for any  $\boldsymbol{\xi}$  from (26.1.2(p.251)) with t=1, we have  $V_2 \geq \beta \mathbf{E}[\boldsymbol{\xi}] s = \beta \mu s = V_1$  due to (26.1.3(p.251)). Suppose  $V_{t-1} \geq V_{t-2}$ . Now, since  $V_{t-1}(\boldsymbol{\xi}) \geq V_{t-2}(\boldsymbol{\xi})$  from (b), we have  $v_{t-1}(\boldsymbol{\xi}) = \max\{\boldsymbol{\xi}, V_{t-1}(\boldsymbol{\xi})\} \geq \max\{\boldsymbol{\xi}, V_{t-2}(\boldsymbol{\xi})\} = v_{t-2}(\boldsymbol{\xi})$  for any  $\boldsymbol{\xi}$  due to (26.1.8), hence from (26.1.4(p.251)) we have  $V_t \geq \max\{\beta \mathbf{E}[v_{t-2}(\boldsymbol{\xi})] s, \beta V_{t-2}\} = V_{t-1}$ . Thus, by induction  $V_t \geq V_{t-1}$  for t>1, i.e.,  $V_t$  is nondecreasing in t>0.

Since  $1 = \mathbf{E}[1] = \mathbf{E}[I(\boldsymbol{\xi} > y) + I(\boldsymbol{\xi} \le y)]$ , we can rewrite (26.1.19(p.252)) as follows.

$$\mathbb{S}_{t}(y) = \beta \left( \mathbf{E}[v_{t-1}(\max\{\xi, y\})I(\xi > y) + v_{t-1}(\max\{\xi, y\})I(\xi \le y)] - v_{t-1}(y)(\mathbf{E}[I(\xi > y) + I(\xi \le y)]) \right) - s 
= \beta \left( \mathbf{E}[v_{t-1}(\max\{\xi, y\})I(\xi > y) + v_{t-1}(\max\{\xi, y\})I(\xi \le y)] - \mathbf{E}[v_{t-1}(y)I(\xi > y) + v_{t-1}(y)I(\xi \le y)] \right) - s 
= \beta \mathbf{E}[(v_{t-1}(\max\{\xi, y\}) - v_{t-1}(y))I(\xi > y) + (v_{t-1}(\max\{\xi, y\}) - v_{t-1}(y))I(\xi \le y)] - s 
= \beta \mathbf{E}[(v_{t-1}(\xi) - v_{t-1}(y))I(\xi > y) + (v_{t-1}(y) - v_{t-1}(y))I(\xi \le y)] - s 
= \beta \mathbf{E}[(v_{t-1}(\xi) - v_{t-1}(y))I(\xi > y)] - s, \quad t > 0.$$
(27.1.1)

Note here that

$$\max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\} = \max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\} (I(\boldsymbol{\xi} > y) + I(\boldsymbol{\xi} \le y))$$
$$= \max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\} I(\boldsymbol{\xi} > y) + \max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\} I(\boldsymbol{\xi} \le y).$$

Now, due to Lemma 27.1.2(p.261) (a), if  $\xi > y$ , then  $v_{t-1}(\xi) \ge v_{t-1}(y)$  or equivalently  $v_{t-1}(\xi) - v_{t-1}(y) \ge 0$  and if  $\xi \le y$ , then  $v_{t-1}(\xi) \le v_{t-1}(y)$  or equivalently  $v_{t-1}(\xi) - v_{t-1}(y) \le 0$ . Hence we have

<sup>†</sup>From (26.1.10(p.251)) and (26.1.7(p.251)) we have  $V_1(y) - V_0(y) = \max\{K(y), -(1-\beta)y\}$ . Let  $x_K < y$  and  $\beta < 1$ . Then K(y) < 0 due to Lemma 11.2.2(p.57) (j1) and  $-(1-\beta)y < 0$  for a y > 0, hence  $V_1(y) - V_0(y) < 0$ , i.e.,  $V_1(y) < V_0(y)$ . Thus  $V_t(y)$  does not become nondecreasing in  $t \ge 0$  for any y.

$$\max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\} = (v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y))I(\boldsymbol{\xi} > y).$$

Thus (27.1.1(p.261)) can be rewritten as

$$S_t(y) = \beta \mathbf{E}[\max\{v_{t-1}(\xi) - v_{t-1}(y), 0\}] - s, \quad t > 0.$$
(27.1.2)

Then, we have

$$S_{1}(y) = \beta \mathbf{E}[\max\{v_{0}(\xi) - v_{0}(y), 0\}] - s$$

$$= \beta \mathbf{E}[\max\{\xi - y, 0\}] - s \quad (\leftarrow (26.1.1(p.251)))$$

$$= \beta T(y) - s \quad (\leftarrow (6.1.1(p.25)))$$

$$= L(y) \quad (\leftarrow (6.1.3(p.25)) \text{ with } \lambda = 1).$$
(27.1.3)

Lemma 27.1.3 (rM:1[R][A])

- (a)  $S_t(y)$  is nonincreasing in y for t > 0.
- (b)  $\mathbb{S}_t(y) \leq L(y)$  for any t > 0 and y.
- (c) Let  $x_L \leq y$ . Then  $\mathbb{S}_t(y) \leq 0$  for t > 0.  $\square$
- *Proof* (a) Immediate from (27.1.2(p.262)) and Lemma 27.1.2(p.261) (a).
  - (b) First, (27.1.2(p.262)) can be rewritten as

$$\mathbb{S}_{t}(y) = \beta \mathbf{E} \max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\} I(y \leq \boldsymbol{\xi}) + \max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\} I(\boldsymbol{\xi} < y)] - s$$

$$= \beta \mathbf{E} [\max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\} I(y \leq \boldsymbol{\xi})] + \beta \mathbf{E} [\max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\} I(\boldsymbol{\xi} < y)] - s \cdots (1).$$

Next, we have:

o Let 
$$y \leq \boldsymbol{\xi} \cdots \boldsymbol{(2)}$$
. Now  $v_0(\boldsymbol{\xi}) - v_0(y) = \boldsymbol{\xi} - y \leq \boldsymbol{\xi} - y$  from (26.1.1(p.251)). Suppose  $v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y) \leq \boldsymbol{\xi} - y \cdots \boldsymbol{(3)}$  (induction hypothesis).

From (26.1.8(p.251)) we have

$$v_t(\xi) - v_t(y) \le \max\{\xi - y, V_t(\xi) - V_t(y)\} \cdots (4).$$

Then, from (26.1.5(p.251)) we have

$$V_{t}(\boldsymbol{\xi}) - V_{t}(y) = \max \left\{ \beta \operatorname{\mathbf{E}}_{\boldsymbol{\xi}'}[v_{t-1}(\max\{\boldsymbol{\xi}', \boldsymbol{\xi}\})] - s, \beta v_{t-1}(\boldsymbol{\xi}) \right\} - \max \left\{ \beta \operatorname{\mathbf{E}}_{\boldsymbol{\xi}'}[v_{t-1}(\max\{\boldsymbol{\xi}', y\})] - s, \beta v_{t-1}(y) \right\}^{\ddagger} \\ \leq \max \left\{ \beta \operatorname{\mathbf{E}}_{\boldsymbol{\xi}'}[v_{t-1}(\max\{\boldsymbol{\xi}', \boldsymbol{\xi}\}) - v_{t-1}(\max\{\boldsymbol{\xi}', y\})], \beta(v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y)) \right\} \\ = \beta \max \left\{ \operatorname{\mathbf{E}}_{\boldsymbol{\xi}'}[v_{t-1}(\max\{\boldsymbol{\xi}', \boldsymbol{\xi}\}) - v_{t-1}(\max\{\boldsymbol{\xi}', y\})], v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y) \right\}.$$

Here from (3) we have

$$v_{t-1}(\max\{\xi',\xi\}) - v_{t-1}(\max\{\xi',y\}) \le \max\{\xi',\xi\}) - \max\{\xi',y\} \le \max\{0,\xi-y\}.$$

From this and (3) we obtain

$$V_t(\boldsymbol{\xi}) - V_t(y) \leq \beta \max\{\mathbf{E}_{\boldsymbol{\xi}'}[\max\{0, \boldsymbol{\xi} - y\}], \boldsymbol{\xi} - y\}$$
$$= \beta \max\{\max\{0, \boldsymbol{\xi} - y\}, \boldsymbol{\xi} - y\}$$
$$= \beta \max\{\boldsymbol{\xi} - y, 0\}.$$

In addition, since  $\xi - y > 0$  due to (2), we have

$$V_t(\boldsymbol{\xi}) - V_t(y) \le \beta(\boldsymbol{\xi} - y) \le \boldsymbol{\xi} - y.$$

Hence, from (4) we have  $v_t(\xi) - v_t(y) \leq \xi - y$ . Accordingly, by induction it follows that  $v_t(\xi) - v_t(y) \leq \xi - y$  for  $t \geq 0$ , so  $v_{t-1}(\xi) - v_{t-1}(y) \leq \xi - y$  for t > 1. Thus we have

$$\beta \mathbf{E}[\max\{v_{t-1}(\xi) - v_{t-1}(y), 0\}I(y \leq \xi)] \leq \beta \mathbf{E}[\max\{\xi - y, 0\}I(y \leq \xi)] \cdots (5).$$

• Let  $\xi < y$ . Then  $v_{t-1}(\xi) \le v_{t-1}(y)$  from Lemma 27.1.2(p.261) (a) or equivalently  $v_{t-1}(\xi) - v_{t-1}(y) \le 0 = \max\{\xi - y, 0\}$ , hence

$$\beta \mathbf{E}[\max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\} I(\boldsymbol{\xi} < y)] \leq \beta \mathbf{E}[\max\{\max\{\boldsymbol{\xi} - y, 0\}, 0\} I(\boldsymbol{\xi} < y)]$$
$$= \beta \mathbf{E}[\max\{\boldsymbol{\xi} - y, 0\} I(\boldsymbol{\xi} < y)] \cdots (6).$$

From (1) and from (5) and (6) we have

$$S_{t}(y) \leq \beta \mathbf{E}[\max\{\xi - y, 0\}I(y \leq \xi)] + \beta \mathbf{E}[\max\{\xi - y, 0\}I(\xi < y)] - s$$

$$= \beta \mathbf{E}[\max\{\xi - y, 0\}(I(y \leq \xi) + I(\xi < y))] - s$$

$$= \beta \mathbf{E}[\max\{\xi - y, 0\}] - s$$

$$= \beta T(y) - s \quad (\text{see } (6.1.1(\text{p.25})))$$

$$= L(y) \quad (\text{see } (6.1.3(\text{p.25}))).$$

(c) If  $x_L \leq y$ , then  $L(y) \leq 0$  from Corollary 11.2.1(p.57) (a), hence  $\mathbb{S}_t(y) \leq 0$  from (b).

<sup>†</sup>Note here that this inequality means a group of all pairs  $(\xi, y)$  satisfying this inequality itself. Hence, if  $\max\{\xi', y\} \leq \max\{\xi', \xi\}$ , the pair  $(\max\{\xi', y\}, \max\{\xi', \xi\})$  is also an element of the group.

<sup>&</sup>lt;sup>‡</sup>  $\mathbf{E}_{\xi'}$  represent the expectation as to  $\boldsymbol{\xi'}$ .

#### 27.1.1.1.2 Case of s = 0

**Lemma 27.1.4** (rM:1[ $\mathbb{R}$ ][ $\mathbb{A}$ ]) Let s = 0. Then  $\mathbb{S}_t(y) \geq 0$  for all y and t > 0.  $\square$ 

• Proof If s = 0, from (27.1.2(p.262)) we have  $\mathbb{S}_t(y) = \beta \mathbf{E}[\max\{v_{t-1}(\xi) - v_{t-1}(y), 0\}] \geq 0$  for all y and t > 0.

# **27.1.1.1.3** Case of $\beta = 1$ and s > 0

**Lemma 27.1.5** (rM:1[ $\mathbb{R}$ ][A]) Let  $\beta = 1$  and s > 0.

- (a) Let  $y \geq x_K$ . Then  $y = V_t(y)$  for  $t \geq 0$ .
- (b) Let  $y \leq x_K$ . Then  $y \leq V_t(y)$  for  $t \geq 0$ .
- (c)  $y \leq V_t(y)$  for any y and t > 0.  $\square$
- Proof Let  $\beta = 1$  and s > 0.
  - (a,b) Evident for t=0 from (26.1.7(p.251)). Suppose that  $y \ge (\le) x_K \Rightarrow y = (\le) V_{t-1}(y)$  (induction hypothesis).
  - o Let  $y \geq x_K$ , hence  $K(y) \leq 0 \cdots$  (1) from Lemma 11.2.2(p.57) (j1). Due to the induction hypothesis we have  $v_{t-1}(y) = y \cdots$  (2) from (26.1.2(p.251)). Then, from Lemma 27.1.3(p.262) (b) we have  $\mathbb{S}_t(y) \leq L(y) = T(y) s = K(y)$  from (6.1.3(p.25))) and (6.1.4(p.25)) due to the assumptions  $\beta = 1$  and  $\lambda = 1$ , so  $\mathbb{S}_t(y) \leq 0$  due to (1). Hence, from (26.1.20(p.252)) we have  $V_t(y) = \beta v_{t-1}(y) = v_{t-1}(y)$ , thus  $V_t(y) = y$  from (2). This completes the induction.
  - o Let  $y \leq x_K$ , hence  $K(y) \geq 0 \cdots$  (3) from Lemma 11.2.2(p.57) (j1). From (26.1.5(p.251)) we have  $V_t(y) \geq \mathbf{E}[v_{t-1}(\max\{\boldsymbol{\xi},y\})] s$ . Since  $v_{t-1}(\max\{\boldsymbol{\xi},y\}) \geq \max\{\boldsymbol{\xi},y\}$  for any  $\boldsymbol{\xi}$  and y from (26.1.8(p.251)), we get  $V_t(y) \geq \mathbf{E}[\max\{\boldsymbol{\xi},y\}] s = K(y) + y$  from (6.1.10(p.25)) with  $\beta = 1$  and  $\lambda = 1$ . Thus, we obtain  $V_t(y) \geq y$  due to (3). This completes the induction.
  - (c) Immediate from (a,b).

#### **27.1.1.1.4** Case of $\beta < 1$ and s > 0

#### **27.1.1.4.1** Case of $\kappa > 0$

**Lemma 27.1.6** ( $\mathscr{A}\{rM:1[\mathbb{R}][A]\}$ ) Let  $\beta < 1$  and s > 0 and let  $\kappa > 0$ .

- (a) Let  $y \geq x_K$ . Then  $y \geq V_t(y)$  for  $t \geq 0$ .
- (b) Let  $y \leq x_K$ . Then  $x_K \geq V_t(y) \geq y$  for  $t \geq 0$ .  $\square$
- Proof Let  $\beta < 1$  and s > 0 and let  $\kappa > 0$ . Then, from Lemma 11.2.3(p.58) (d) we have  $x_L > x_K > 0 \cdots$  (1).
  - (a,b) The two assertions are evident for t = 0 from (26.1.7(p.251)). Suppose that

$$y \ge (\le) \ x_K \Rightarrow y \ge V_{t-1}(y) \cdots (2) \ (y \le V_{t-1}(y) \le x_K \cdots (3))$$
 (induction hypothesis),

hence  $y \ge (\le) \ x_K \Rightarrow v_{t-1}(y) = y \cdots (4) \ (v_{t-1}(y) = V_{t-1}(y) \cdots (5))$  from (26.1.2(p.251)).

- Let  $y \ge x_K \cdots (6)$ , hence  $0 < y \cdots (7)$  due to (1). Then  $v_{t-1}(y) = y \cdots (8)$  due to (4).
  - 1. Let  $x_L \geq y \; (\geq x_K) \cdots$  (9). Then  $L(y) \geq 0 \cdots$  (10) due to Lemma 11.2.1(p.57) (e1) and  $K(y) \leq 0 \cdots$  (11) due to Lemma 11.2.2(p.57) (j1). Now, since  $\mathbb{S}_t(y) \leq L(y) \cdots$  (12) for any y from Lemma 27.1.3(p.262) (b), from (26.1.20(p.252)) and from (12), (4), and (10) we have  $V_t(y) \leq \max\{L(y), 0\} + \beta y = L(y) + \beta y = K(y) + y \leq y$  due to (6.1.9(p.25)) and (11).
  - 2. Let  $y \geq x_L \ (> x_K) \cdots (13)$ , hence  $L(y) \leq 0 \cdots (14)$  due to Lemma 11.2.1(p.57) (e1). Then we have  $\mathbb{S}_t(y) \leq L(y) \leq 0 \cdots (15)$  from Lemma 27.1.3(p.262) (b), hence from (26.1.20(p.252)) we have  $V_t(y) = \beta v_{t-1}(y) = \beta y \leq y$  due to (4) and (7).

From the above, if  $y \ge x_K$ , then whether for  $x_L \ge y$  or for  $y \ge x_L$ , we have  $y \ge V_t(y)$  for  $t \ge 0$ . This completes the induction, i.e., it follows that (a) holds.

○ Let  $y \leq x_K \cdots (16)$ , hence  $K(y) \geq 0 \cdots (17)$  from Lemma 11.2.2(p.57) (j1). Since  $V_t(y) \geq \beta \mathbf{E}[v_{t-1}(\max\{\xi,y\})] - s$  from (26.1.5(p.251)) and since  $v_{t-1}(\max\{\xi,y\}) \geq \max\{\xi,y\}$  from (26.1.8(p.251)), we have  $V_t(y) \geq \beta \mathbf{E}[\max\{\xi,y\})] - s = K(y) + y$  from (6.1.10(p.25)) with  $\lambda = 1$ , hence  $V_t(y) \geq y$  due to (17). Since  $\max\{\xi,y\} \leq \max\{\xi,x_K\}$  for any  $\xi$  due to (16), from Lemma 27.1.2(p.261) (a) we have  $v_{t-1}(\max\{\xi,y\}) \leq v_{t-1}(\max\{\xi,x_K\}) \cdots (18)$  for any  $\xi$ . Furthermore, since  $\max\{\xi,x_K\} \geq x_K$  for any  $\xi$ , due to (2) we have  $V_{t-1}(\max\{\xi,x_K\}) \leq \max\{\xi,x_K\}$  for any  $\xi$ , hence from (26.1.8(p.251)) we have  $v_{t-1}(\max\{\xi,x_K\}) = \max\{\xi,x_K\}$  for any  $\xi$ . In addition, since  $v_{t-1}(y) = V_{t-1}(y) \leq x_K$  due to (5) and (3), from (26.1.5(p.251)) we have  $V_t(y) \leq \max\{\xi,x_K\} = x_K$  since  $x_K > 0$  due to (1). This completes the induction.  $\blacksquare$ 

#### $27.1.1.1.4.2 \quad \text{Case of } \kappa \leq 0$

**Lemma 27.1.7** ( $\mathscr{A}\{\mathbf{rM}:1[\mathbb{R}][\mathbb{A}]\}$ ) Let  $\beta < 1$  and s > 0 and let  $\kappa \leq 0$ .

- (a) Let  $y \ge 0$ . Then  $y \ge V_t(y)$  for  $t \ge 0$ .
- (b) Let  $y \leq 0$ . Then  $y \leq V_t(y)$  for  $t \geq 0$ .  $\square$
- Proof Let  $\beta < 1$  and s > 0 and let  $\kappa \leq 0$ . Then, from Lemma 11.2.3(p.58) (d) we have  $x_L \leq x_K \leq 0 \cdots$  (1). Due to (26.1.7(p.251)) the two assertions clearly hold for t = 0. Suppose that  $y \geq (\leq) 0 \Rightarrow V_{t-1}(y) \leq (\geq) y$  (induction hypothesis), hence  $v_{t-1}(y) = y$  ( $v_{t-1}(y) = V_{t-1}(y)$ ).
  - (a) Let  $y \ge 0 \cdots (2)$ . Then, since  $x_L \le y$  from (1), we have  $\mathbb{S}_t(y) \le 0$  for t > 0 due to

Lemma 27.1.3(p.262) (c). Therefore, from (26.1.14(p.251)) we obtain  $V_t(y) = \beta V_{t-1}(y)$ , hence due to the induction hypothesis we have  $V_t(y) \le \beta y \le y$  due to  $\beta < 1$  and (2). This completes the induction.

(b) Let  $y \leq 0 \cdots$  (3). Now, since  $V_t(y) \geq \beta v_{t-1}(y)$  from (26.1.5(p.251)) and since  $v_{t-1}(y) \geq y$  from (26.1.8(p.251)), we have  $V_t(y) \geq \beta y \geq y$  due to  $\beta < 1$  and (3). This completes the induction.

#### 27.1.1.2 Analysis

#### $\blacksquare$ Tom 27.1.1 ( $\mathscr{A}\{rM:1[\mathbb{R}][A]\}$ )

- (a) Let s = 0. Then  $rM:1[\mathbb{R}][A] \hookrightarrow rM:1[\mathbb{R}][E]$ .
- (b) Let s > 0.
  - 1. We have  $\boxed{\$ dOITs_{\tau>0}\langle \tau \rangle}_{\triangle}$ .

  - 3. Let  $\beta < 1$ .
    - i. Let  $\kappa > 0$ .
      - 1.  $\blacktriangle Let \ y \geq x_K$ . Then  $y \geq V_t(y)$  for  $t \geq 0$ .
      - 2.  $\blacktriangle Let \ y \leq x_K$ . Then  $y \leq V_t(y)$  for  $t \geq 0$ .
    - ii. Let  $\kappa \leq 0$ .
      - 1.  $\Diamond Let \ y \geq 0 \ (i.e., \mathscr{F}^+)$ . Then  $y \geq V_t(y)$  for  $t \geq 0$ .
      - 2.  $\blacktriangle Let \ y \leq 0 \ (i.e., \mathscr{F}^-). \ Then \ y \leq V_t(y) \ for \ t \geq 0.$
- Proof (a) Let s = 0. Then, from Lemma 27.1.4(p.263) we have  $\mathbb{S}_t(y) \geq 0$  for all y and t > 0, hence it is optimal to Conduct<sub>t</sub> for all y and t > 0 due to (26.1.21(p.252)). This fact implies that rM:1[ $\mathbb{R}$ ][A] which is originally a search-Allowed-model migrates ( $\hookrightarrow$ ) over to rM:1[ $\mathbb{R}$ ][E] (see Def. 12.2.2(p.63)) which is a search-Enforced-model.
  - (b) Let s > 0.
  - (b1) The same as Lemma 27.1.1(p.261).
  - (b2) The same as Lemma 27.1.5(p.263) (c).
  - (b3) Let  $\beta < 1$ .
  - (b3i-b3i2) The same as Lemma 27.1.6(p.263).
  - (b3ii-b3ii2) The same as Lemma 27.1.7(p.264).

# 27.1.1.3 Flow of Optimal Decision Rules

- ♣ Flow-ODR 1 (rM:1[R][A]) (Accept₀(y) ▷ Stop) Let s > 0 and β = 1 (see Tom 27.1.1(p.264) (♣b2)) or let s > 0, β < 1, κ ≤ 0, and y ≤ 0 (see Tom 27.1.1(p.264) (♣b3ii2) ( $\mathscr{F}^-$ )). Then, the inequality  $y ≤ V_t(y)$  for any t and y means that even if the process is initiated at any time t, it is optimal to reject the best price y at that time. Accordingly, it follows that each time a price ξ is proposed, the current best price y continues to be enlarged to  $y \stackrel{\text{def}}{=} \max\{y, \xi\}$ , and the process terminates by accepting the best price y at the deadline t = 0, i.e., Accept₀(y) ▷ Stop.
- ♠ Flow-ODR 2 (r $\tilde{\mathsf{M}}$ :1[ $\mathbb{R}$ ][A]) (c-reservation-price) From Tom 27.1.1(p.264) ( $\spadesuit$  b3i1, $\spadesuit$  b3i2) and (26.1.25(p.252)) we have the following relations for  $\tau \geq t \geq 0$ :

$$\left\{ \begin{aligned} y \geq x_K &\Rightarrow \mathsf{Accept}_t \langle y \rangle \ and \ the \ process \ stops \ \mathbf{I} \\ y \leq x_K &\Rightarrow \mathsf{Reject}_t \langle y \rangle \ and \ \mathsf{Conduct}_t / \mathsf{Skip}_t \end{aligned} \right.$$

Namely, the optimal reservation value is given by  $x_K$ , which is constant in t.

 $\diamond$  Flow-ODR 3 (rM:1[ $\mathbb{R}$ ][A]) (Accept $_{t_{\tau}^*}(y) \triangleright$  Stop) Let s > 0,  $\beta < 1$ ,  $\kappa \leq 0$ , and  $y \geq 0$  (see Tom 27.1.1(p.264) ( $\diamond$ b3ii1) ( $\mathscr{F}^+$ )). Then the inequality  $y \geq V_t(y)$  for  $t \geq 0$  implies that when the process initiates at the optimal initiating time  $t_{\tau}^*$ , it is optimal to accept the best price y at that time and stop the process.  $\square$ 

<sup>&</sup>lt;sup>†</sup>Note that we have  $\boxed{\$ \text{ dOITs}_{\tau>0}\langle \tau \rangle}_{\vartriangle}$  also for any  $s\geq 0$ .

<sup>&</sup>lt;sup>†</sup>This is true also for s = 0.

Definition 27.1.1 (reduction) In Tom 27.1.1(p.264) (a) we demonstrated an example that a search-Allowed-model migrates over to a search-Enforced-model, represented as

$$rM:1[\mathbb{R}][A] \hookrightarrow rM:1[\mathbb{R}][E]. \tag{27.1.4}$$

Accordingly, adding "model-migration" and "odr-Accept/Stop" to "model-running-back" and "odr-Accept/Stop" in (23.1.3(p.239)), we have

$$\text{Reduction} \left\{ \begin{array}{l} \text{model reduction} & \left\{ \begin{array}{l} \text{model-running-back } ( \ \twoheadrightarrow ) \\ \text{model-migration} & ( \ \looparrowright ) \end{array} \right. \\ \text{odr reduction} & \left\{ \text{odr-Accept/Stop} & ( \ \mapsto ) \end{array} \right. \end{array} \right.$$

#### 27.1.1.4 Market Restriction

# 27.1.1.4.1 Positive Restriction

- $\square$  Pom 27.1.1 ( $\mathscr{A}\{\mathbf{rM}:1[\mathbb{R}][\mathbb{A}]^+\}$ ) Suppose a>0.
- (a) Let s = 0. Then  $rM:1[\mathbb{R}][A]^+ \hookrightarrow rM:1[\mathbb{R}][E]^+$ .
- (b) Let s > 0.

1. We have 
$$[ \otimes dOITs_{\tau>1} \langle \tau \rangle ]_{\vartriangle} \rightarrow$$

- $2. \quad Let \ \beta=1. \ Then \ we \ have \ {\tt odr} \mapsto {\tt Accept}_0(y) \, {\tt \triangleright} \, {\tt Stop}.$
- 3. Let  $\beta < 1$ .
  - i. Let  $\beta \mu > s$ . Then we have c-reservation-price.

ii. Let 
$$\beta \mu \leq s$$
. Then we have  $\boxed{\bullet \text{ dOITd}_{\tau>0}\langle 1 \rangle}_{\parallel} \rightarrow \rightarrow \bigcirc$ 

- *Proof* Suppose a > 0, hence it suffices to consider y such that  $0 < a < y < b \cdots$  (1). Then  $\kappa = \beta \mu s \cdots$  (2) from Lemma 11.3.1(p.59) (a) with  $\lambda = 1$ .
  - (a) The same as Tom 27.1.1(p.264) (a).
  - (b) Let s > 0.
  - (b1) The same as Tom 27.1.1(p.264) (b1).
  - (b2) Evident from Tom 27.1.1(p.264) (b2) and \*Flow-ODR 1.
  - (b3) Let  $\beta < 1$ .
- (b3i) Let  $\beta\mu > s$ , hence  $\kappa > 0$  due to (2). Thus, it suffices to consider only Tom 27.1.1(p.264) ( $\spadesuit$  b3i1, $\spadesuit$  b3i2), hence we have  $\clubsuit$  Flow-ODR 2.
  - (b3ii) Let  $\beta \mu \leq s$ , hence  $\kappa \leq 0 \cdots$  (3) due to (2). In this case, due to (1) it suffices to consider only

Tom 27.1.1(p.264) (\$\display \text{b3ii1}\$). Then, since it suffices to consider \$\xi\$ such that  $0 < a < \xi < b$, we have $\xi \ge V_{t-1}(\xi)$ for $t > 1$, hence $v_{t-1}(\xi) = \xi$ from (26.1.8(p.251)). Thus, from (26.1.4(p.251)) we have $V_t = \max\{\beta \mathbf{E}[\xi] - s, \beta V_{t-1}\} = \max\{\beta \mu - s, \beta V_{t-1}\} = \max\{\kappa, \beta V_{t-1}\}$ for $t > 1$. First $V_1 = \beta \mu - s = \kappa \le 0$ from (26.1.3(p.251)) and (3) or equivalently $V_1 = \beta^0 \kappa \le 0$. Suppose $V_{t-1} = \beta^{t-2} \kappa \le 0$. Then $V_t = \max\{\kappa, \beta \beta^{t-2} \kappa\} = \max\{\kappa, \beta^{t-1} \kappa\} = \beta^{t-1} \kappa \le 0$ due to (3). Thus by induction we have $V_t = \beta^{t-1} \kappa \le 0$ for $t > 1$. Accordingly, we have $V_t - \beta V_{t-1} = \beta^{t-1} \kappa - \beta \beta^{t-1} \kappa = \beta^{t-1} \kappa - \beta^{t-1} \kappa = 0$, hence $V_t = \beta V_{t-1}$ for $t > 1$. Accordingly, we get $V_\tau = \beta V_{\tau-1} = \beta^2 V_{\tau-2} = \cdots = \beta^{\tau-1} V_1$, i.e., $t^*_\tau = 1$ for $\tau > 1$ or equivalently \begin{array}{c} \oldsymbol{\delta} \delta \text{OIIId}_{\tau>1}(1) \end{array}.$ 

#### 27.1.1.4.2 Mixed Restriction

Omitted.

#### 27.1.1.4.3 Negative Restriction

- $\square$  Nem 27.1.1 ( $\mathscr{A}\{\mathbf{rM}:1[\mathbb{R}][A]^-\}$ ) Suppose b<0.
- (a) Let s = 0. Then  $rM:1[\mathbb{R}][A]^- \hookrightarrow rM:1[\mathbb{R}][E]^-$ .
- (b) Let s > 0.

1. We have 
$$[s]$$
 dOITs $_{\tau>1}\langle \tau \rangle]_{\vartriangle} \rightarrow$ 

- 2. We have  $odr \mapsto Accept_0(y) \triangleright Stop$ .  $\square$
- **Proof** Suppose b < 0, hence it suffices to consider y such that  $a < y < b < 0 \cdots (1)$ . Then, since  $\kappa = -s$  from Lemma 11.3.1(p.59) (a), we have  $\kappa \le 0 \cdots (2)$  for any  $s \ge 0$ .
  - (a) The same as Tom 27.1.1(p.264) (a).
  - (b) Let s > 0.
  - (b1) The same as Tom 27.1.1(p.264) (b1).
- (b2) In this case, due to (1) it suffices to consider only Tom 27.1.1(p.264) (\*b3ii2). If  $\beta = 1$ , then  $y \leq V_t(y)$  for  $t \geq 0$  from Tom 27.1.1(p.264) (\*b2) and if  $\beta < 1$ , then from Tom 27.1.1(p.264) (\*b3ii2) we have  $y \leq V_t(y)$  for  $t \geq 0$ . Hence, whether  $\beta = 1$  or  $\beta < 1$ , we have  $y \leq V_t(y)$  for  $t \geq 0$ . Accordingly, it follows that we have Accept<sub>0</sub>(y) > Stop from \*Flow-ODR 1.

# 27.1.2 $\tilde{rM}:1[\mathbb{R}][A]$

#### 27.1.2.1 Preliminary

For almost the same reason as in Section 27.2.2.1(p.274) it can be confirmed that  $SOE\{r\tilde{M}:1[\mathbb{R}][A]\}$  (see (26.1.31(p.252))) is symmetrical to  $SOE\{rM:1[\mathbb{R}][A]\}$  (see (26.1.6(p.251))). Hence it follows that Scenario[ $\mathbb{R}$ ](p.75) can be applied also to  $\mathscr{A}\{rM:1[\mathbb{R}][A]\}$ .

#### 27.1.2.2 Derivation of $\mathscr{A}\{r\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{A}]\}$

- $\square$  Tom 27.1.1 ( $\mathscr{A}\{r\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}$ )
- (a) Let s = 0. Then  $r\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}] \hookrightarrow r\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]$ .
- (b) Let s > 0.
  - 1. We have [S] dOITs $_{\tau>1}\langle \tau \rangle$   $\rightarrow$   $\rightarrow$
  - 2. Let  $\beta = 1$ . Then  $y \ge V_t(y)$  for  $t \ge 0$  and any t.
  - 3. Let  $\beta < 1$ .
    - i. Let  $\tilde{\kappa} < 0$ .
      - 1.  $\blacktriangle Let \ y \leq x_{\tilde{K}}$ . Then  $y \leq V_t(y)$  for  $t \geq 0$ .
      - 2.  $\blacktriangle Let \ y \geq x_{\tilde{K}}$ . Then  $y \geq V_t(y)$  for  $t \geq 0$ .
    - ii. Let  $\tilde{\kappa} \geq 0$ .
      - 1.  $\diamond Let \ y \leq 0 \ (i.e., \mathscr{F}^-)$ . Then  $y \leq V_t(y)$  for  $t \geq 0$ .
      - 2.  $\star Let \ y \geq 0 \ (i.e., \mathscr{F}^+). \ Then \ y \geq V_t(y) \ for \ t \geq 0.$
- Proof by symmetry Immediate from applying  $S_{\mathbb{R} \to \tilde{\mathbb{R}}}$  (see in (20.0.1(p.136))) to Tom 27.1.1(p.264).

#### 27.1.2.3 Flow of Optimal Decision Rules

- ♣ Flow-ODR 4 (rM:1[R][A]) (Accept<sub>0</sub>(y) ▷ Stop) Let s > 0 and β = 1 (see Tom 27.1.1(p.266) (♣b2)) or let s > 0, β < 1,  $\tilde{κ} ≤ 0$ , and y ≤ 0 (see Tom 27.1.1(p.266) (♣b3ii2) ( $\mathscr{F}^+$ )). Then, the inequality  $y ≥ V_t(y)$  for any t and y means that even if the process is initiated at any time t, it is optimal to reject all prices proposed. Accordingly, it follows that each time a price ξ, the current best price y continues to be reduced to  $y \stackrel{\text{def}}{=} \max\{y, \xi\} (\min\{y, \xi\})$ , and the process terminates by accepting the best price y at the deadline t = 0, i.e., Accept<sub>0</sub>(y) ▷ Stop.
- ♠ Flow-ODR 5 ( $\mathbf{r}\tilde{\mathsf{M}}$ :1[ $\mathbb{R}$ ][A]) (c-reservation-price) From Tom 27.1.1(p.266) (♠ b3i1,♠ b3i2) and (26.1.46(p.253)) we have the following relations for  $\tau \geq t \geq 0$ :

$$\left\{ \begin{aligned} y &\leq \ x_{\tilde{K}} \ \Rightarrow \ \mathsf{Accept}_t \langle y \rangle \ and \ the \ process \ stops \ \mathbf{I} \\ y &\geq \ x_{\tilde{K}} \ \Rightarrow \ \mathsf{Reject}_t \langle y \rangle \ and \ \mathsf{Conduct}_t / \mathsf{Skip}_t \end{aligned} \right.$$

Namely, the optimal reservation value is given by  $x_{\tilde{K}}$ , which is constant in t.

 $\diamond$  Flow-ODR  $\mathbf{6}$  (rM:1[ $\mathbb{R}$ ][A]) (Accept $_t(y) \triangleright$  Stop) Let s>0,  $\beta<1$ ,  $\tilde{\kappa}\geq0$ , and  $y\leq0$  (see Tom 27.1.1(p.266) ( $\diamond$ b3ii1) ( $\mathscr{F}^-$ )). Then the inequality  $y\leq V_t(y)$  for  $t\geq0$  implies that when the process initiates at the optimal initiating time  $t_{\tau}^*$ , it is optimal to accept the best price y at that time and stop the process.  $\square$ 

#### 27.1.2.4 Market Restriction

# 27.1.2.4.1 Positive Restriction

- $\square$  Pom 27.1.2 ( $\mathscr{A}\{\mathbf{r}\tilde{\mathsf{M}}:1[\mathbb{R}][\mathbb{A}]^+\}$ ) Suppose a>0.
- (a) Let s = 0. Then  $r\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]^+ \hookrightarrow r\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]^+$ .
- (b) Let s > 0.
  - 1. We have  $[ \odot dOITs_{\tau>1} \langle \tau \rangle ]_{\vartriangle} \rightarrow$
  - 2. We have  $odr \mapsto Accept_0(y) \triangleright Stop$ .  $\square$
- Proof Suppose a>0. Below consider only y with  $0< a\leq y\leq b$ , hence  $y\geq 0\cdots$  (1). Moreover, since  $\tilde{\kappa}=s$  from Lemma 13.6.6(p.83) (a), we have  $\tilde{\kappa}\geq 0\cdots$  (2) for any  $s\geq 0$ .

 $\rightarrow$  (s)

- (a) The same as Tom 27.1.1(p.266) (a).
- (b) Let s > 0.
- (b1) The same as Tom 27.1.1(p.266) (b1).
- (b2) If  $\beta=1$ , then  $y\geq V_t(y)$  for  $t\geq 0$  from Tom 27.1.1(p.266) (b2). If  $\beta<1$ , then due to (2) and (1) it suffices to consider only Tom 27.1.1(p.266) (\* b3ii2), hence we have  $y\geq V_t(y)$  for  $t\geq 0$ . Accordingly, whether  $\beta=1$  or  $\beta<1$ , we have  $y\geq V_t(y)$  for  $t\geq 0$ . Thus, it follows that we have  $Accept_0(y) \triangleright Stop$  (\* Flow-ODR 4).
- Remark 27.1.1 (diagonal symmetry) Pom 27.1.2 can be also derived by applying  $\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Nem 27.1.1.

#### 27.1.2.4.2 Mixed Restriction

Omitted.

#### 27.1.2.4.3 Negative Restriction

Unnecessary.

# 27.1.3 Conclusion 7 (Search-Allowed-Model 1)

The following six cases are possible:

- C1 We have  $\mathscr{A}\{\tilde{rM}:1[\mathbb{R}][A]\}^+ \wedge \mathscr{A}\{\tilde{rM}:1[\mathbb{R}][A]\}^+$ .
- C2 We have  $rM/\tilde{M}:1[\mathbb{R}][A]^+ \hookrightarrow rM/\tilde{M}:1[\mathbb{R}][E]^+$ .
- C3 We have odr  $\mapsto$  Accept<sub>0</sub>(y)  $\triangleright$  Stop for rM/ $\tilde{M}$ :1[ $\mathbb{R}$ ][ $\mathbb{A}$ ]<sup>+</sup>.
- C4 We have  $\mathfrak{S}_{\Delta}$  for  $rM/\tilde{M}:1[\mathbb{R}][A]^+$ .
- C5 We have  $\mathbf{d}_{\parallel}$  for rM:1[ $\mathbb{R}$ ][ $\mathbb{A}$ ]<sup>+</sup>.
- C6 We have c-reservation-price for rM:1[ $\mathbb{R}$ ][ $\mathbb{A}$ ]<sup>+</sup>.  $\square$

C1	Compare P	om 27.1.2(n.266)	and Pom 2	7 1 1 (n 265)

- C2 See Pom 27.1.1(p.265) (a) and Pom 27.1.2(p.266) (a).
- C3 See Pom 27.1.1(p.265) (b2) and Pom 27.1.2(p.266) (b2).
- C4 See Pom 27.1.1(p.265) (b1) and Pom 27.1.2(p.266) (b1).
- C5 See Pom 27.1.1(p.265) (b3ii).
- C6 See Pom 27.1.1(p.265) (b3i). ■

# 27.2 Search-Enforced-Model 1

# 27.2.1 rM:1[R][E]

Below let us define

$$\mathbb{V}_t \stackrel{\text{def}}{=} V_t - \beta V_{t-1}, \quad t > 1. \tag{27.2.1}$$

#### **27.2.1.1** Some Lemmas

#### Lemma 27.2.1 (rM:1[ $\mathbb{R}$ ][E])

- (a)  $v_t(y)$  and  $V_t(y)$  are nondecreasing in y for  $t \geq 0$ .
- (b)  $v_t(y)$  and  $V_t(y)$  are nondecreasing in  $t \ge 0$  and  $t > 0^{\dagger}$  respectively for any y.
- (c)  $V_t$  is nondecreasing in t > 0.  $\square$
- Proof (a)  $v_0(y)$  is nondecreasing in y from (26.1.47(p.253)). Suppose  $v_{t-1}(y)$  is nondecreasing in y. Then  $V_t(y)$  is nondecreasing in y from (26.1.50(p.253)), hence  $v_t(y)$  is nondecreasing in y from (26.1.48(p.253)). Thus, by induction  $v_t(y)$  is nondecreasing in y and  $t \ge 0$ . Then  $v_{t-1}(y)$  is nondecreasing in y for t > 0, hence  $V_t(y)$  is also nondecreasing in y for t > 0 from (26.1.50(p.253)). In addition,  $V_0(y)$  is nondecreasing in y from (26.1.52(p.253)), hence it follows that  $V_t(y)$  is nondecreasing in y for  $t \ge 0$ .
- (b) Clearly  $v_1(y) \ge y = v_0(y)$  for any y from (26.1.48 (p.253)) with t = 1 and (26.1.47 (p.253)). Suppose  $v_{t-1}(y) \ge v_{t-2}(y)$  for any y. Then, from (26.1.50 (p.253)) we have  $V_t(y) \ge \beta \mathbf{E}[v_{t-2}(\max\{\xi,y\})] s = V_{t-1}(y)$  for any y. Hence, from (26.1.48 (p.253)) we have  $v_t(y) \ge \max\{y, V_{t-1}(y)\} = v_{t-1}(y)$  for any y. Thus, by induction  $v_t(y) \ge v_{t-1}(y)$  for t > 0 and any y, i.e.,  $v_t(y)$  is nondecreasing in  $t \ge 0$  for any y. Accordingly, since  $v_{t-1}(y) \ge v_{t-2}(y)$  for t > 1 and any y, from (26.1.50 (p.253)) we have  $V_t(y) \ge \beta \mathbf{E}[v_{t-2}(y)] s = V_{t-1}(y)$  for t > 1 and any y, hence  $V_t(y)$  is nondecreasing in t > 0 for any y.
  - (c) We have  $v_{t-1}(y)$  is nondecreasing in t>0 for any y due to (b), hence  $V_t$  is nondecreasing in t>0 from (26.1.49(p.253)).

#### Lemma 27.2.2 (rM:1[R][E])

- (a) Let  $x_K \leq y$ . Then  $V_t(y) \leq y$  for  $t \geq 0$ .
- (b) Let  $y \leq x_K$ . Then  $y \leq V_t(y) \leq x_K$  for  $t \geq 0$ .  $\square$
- Proof <sup>‡</sup> (a) Let  $x_K \leq y$ . Then  $K(y) \leq 0 \cdots$  (1) from Corollary 11.2.2(p.58) (a). Now, from (26.1.52(p.253)) we clearly have  $V_0(y) \leq y$ . Suppose  $V_{t-1}(y) \leq y$ , hence  $v_{t-1}(y) = y$  from (26.1.48(p.253)). Then, since  $x_K \leq y \leq \max\{\boldsymbol{\xi}, y\}$  for any  $\boldsymbol{\xi}$ , we have  $v_{t-1}(\max\{\boldsymbol{\xi}, y\}) = \max\{\boldsymbol{\xi}, y\}$ . Accordingly, from (26.1.50(p.253)) we have  $V_t(y) = \beta \mathbf{E}[\max\{\boldsymbol{\xi}, y\}] s = K(y) + y \cdots$  (2) due to (6.1.10(p.25)) with  $\lambda = 1$ , hence  $V_t(y) \leq y$  due to (1). This completes the induction.
- (b) Let  $y \le x_K \cdots$  (3). Then  $K(y) \ge 0 \cdots$  (4) from Corollary 11.2.2(p.58) (b). Now, from (26.1.53(p.253)) we have  $v_{t-1}(\max\{\boldsymbol{\xi},y\}) \ge \max\{\boldsymbol{\xi},y\}$  for any t > 0,  $\boldsymbol{\xi}$ , and y, hence from (26.1.50(p.253)) and (6.1.10(p.25)) with  $\lambda = 1$  we have  $V_t(y) \ge \beta[\max\{\boldsymbol{\xi},y\}] s = 0$

<sup>†</sup>It cannot be always guaranteed that  $V_1(y) \ge V_0(y)$ . For example, let  $\beta < 1$  or s > 0 and let  $y > x_K$ . Then, from (26.1.56(p.253)) and (26.1.52(p.253)) we have  $V_1(y) - V_0(y) = K(y) < 0$  due to Lemma 11.2.2(p.57) (j1), i.e.,  $V_1(y) < V_0(y)$ .

<sup>&</sup>lt;sup>‡</sup>Although (a) and (b) are already proven in [43,Sakaguchi,1961], we anew prove herein the two by using properties of the underlying function K(x).

K(y) + y for t > 0, so  $V_t(y) \ge y$  for t > 0 due to (4). In addition, since  $V_0(y) \ge y$  from (26.1.52(p.253)), it follows that  $V_t(y) \ge y$  for  $t \ge 0$ . Now, since  $\max\{\boldsymbol{\xi},y\} \le \max\{\boldsymbol{\xi},x_K\}$  for any  $\boldsymbol{\xi}$  due to (3), from Lemma 27.2.1(p.267) (a) we have  $v_{t-1}(\max\{\boldsymbol{\xi},y\}) \le v_{t-1}(\max\{\boldsymbol{\xi},x_K\}) \cdots$  (5) for any  $\boldsymbol{\xi}$  and t > 0. Since  $x_K \le \max\{\boldsymbol{\xi},x_K\}$  for any  $\boldsymbol{\xi}$ , due to (a) we have  $V_{t-1}(\max\{\boldsymbol{\xi},x_K\}) \le \max\{\boldsymbol{\xi},x_K\}$  for any  $\boldsymbol{\xi}$  and t > 0, hence  $v_{t-1}(\max\{\boldsymbol{\xi},x_K\}) = \max\{\max\{\boldsymbol{\xi},x_K\},V_t(\max\{\boldsymbol{\xi},x_K\})\} = \max\{\boldsymbol{\xi},x_K\}$  for any  $\boldsymbol{\xi}$  and t > 0 from (26.1.53(p.253)), so from (5) we have  $v_{t-1}(\max\{\boldsymbol{\xi},y\}) \le \max\{\boldsymbol{\xi},x_K\}$  for any  $\boldsymbol{\xi}$  and t > 0. Thus, from (26.1.50(p.253)) and (6.1.10(p.25)) with  $\lambda = 1$  we have  $V_t(y) \le \beta \mathbf{E}[\max\{\boldsymbol{\xi},x_K\}] - s = K(x_K) + x_K = x_K$  for t > 0.

Since  $V_t(y)$  is nondecreasing in t > 0 from Lemma 27.2.1(p.267) (b) and is upper bounded in t from Lemma 27.2.2(p.267) (a,b), it converges to a finite V(y) as  $t \to \infty$ , hence so also do  $v_t(y)$ ,  $V_t$ , and  $V_t$  (see (27.2.1(p.267)). Then, defining these limits by v(y), V, and V, from (26.1.50(p.253)), (26.1.48(p.253)), (26.1.49(p.253)), and (27.2.1(p.267)) we have:

$$V(y) = \beta \mathbf{E}[v(\max\{\boldsymbol{\xi}, y\})] - s, \tag{27.2.2}$$

$$v(y) = \max\{y, V(y)\}, \tag{27.2.3}$$

$$V = \beta \mathbf{E}[v(\boldsymbol{\xi})] - s, \tag{27.2.4}$$

$$\mathbb{V} = (1 - \beta)V. \tag{27.2.5}$$

# Lemma 27.2.3 (rM:1[ $\mathbb{R}$ ][ $\mathbb{E}$ ])

- (a) Let  $x_K \leq y$ . Then  $V(y) \leq y$ .
- (b) Let  $y \leq x_K$ . Then  $y \leq V(y) \leq x_K$ .  $\square$
- Proof Immediate from Lemma 27.2.2(p.267).

# Lemma 27.2.4 (rM:1[ $\mathbb{R}$ ][E]) Let $\beta < 1$ .

- (a) Let  $y \leq x_K$ . Then  $V(y) = x_K$ .
- (b)  $v(y) = \max\{y, x_K\}$  for any y.
- (c)  $V = x_K$ .
- (d) Let  $\kappa > (= (<)) \ 0$ . Then  $\mathbb{V} > (= (<)) \ 0$ .  $\square$
- *Proof* Let  $\beta < 1$ .
  - (a) Let  $y \leq x_K \cdots (1)$ . Now, (27.2.2(p.268)) can be rewritten as

$$V(y) = \beta \mathbf{E}[v(\max\{\boldsymbol{\xi},y\})I(x_K < \boldsymbol{\xi})] + \beta \mathbf{E}[v(\max\{\boldsymbol{\xi},y\})I(\boldsymbol{\xi} \leq x_K)] - s \cdots (2).$$

If  $x_K < \xi$ , then  $y < \xi$  from (1), hence  $x_K < \xi = \max\{\xi, y\}$ . Thus, from Lemma 27.2.3(p.268) (a) we have  $V(\max\{\xi, y\}) \le \max\{y, \xi\} = \xi$ , so from (27.2.3(p.268)) we have  $v(\max\{\xi, y\}) = \max\{\max\{\xi, y\}, V(\max\{\xi, y\})\} = \max\{y, \xi\} = \xi$  due to . Therefore, (2) can rewritten as

$$V(y) = \beta \mathbf{E}[\boldsymbol{\xi}I(x_K < \boldsymbol{\xi})] + \beta \mathbf{E}[v(\max\{\boldsymbol{\xi}, y\})I(\boldsymbol{\xi} \le x_K)] - s \cdots \boldsymbol{(3)}.$$

In addition, since  $v(\max\{\boldsymbol{\xi},y\}) = \max\{\max\{\boldsymbol{\xi},y\}, V(\max\{\boldsymbol{\xi},y\})\}$  from (27.2.3(p.268)) for  $\boldsymbol{\xi}$  and  $\boldsymbol{y}$ , we can rewrite (3) as

$$V(y) = \beta \mathbf{E}[\boldsymbol{\xi}I(x_K < \boldsymbol{\xi})] + \beta \mathbf{E}[\max\{\max\{\boldsymbol{\xi},y\},V(\max\{\boldsymbol{\xi},y\})\}I(\boldsymbol{\xi} \le x_K)] - s.\cdots(\boldsymbol{4})$$

To prove (a) it suffices to show the following two:

1. Any given function  $V'(y) = x_K \cdots (5)$  with  $y \leq x_K$  is a solution of the functional equation (4), i.e.,

$$V'(y) = \beta \mathbf{E}[\xi I(x_K < \xi)] + \beta \mathbf{E}[\max\{\max\{\xi, y\}, V'(\max\{\xi, y\})\}I(\xi \le x_K)] - s....(6)$$

To prove this, first let us show that substituting the equality  $V'(y) = x_K$  with  $y \le x_K$  for the r.h.s. of (6) yields  $x_K$ , hence, as a result, its l.h.s. becomes equal to  $x_K$ , i.e.,  $V'(y) = x_K$ , implying that (5) is a solution of the functional equation (6). Below let us show this.

Let  $\boldsymbol{\xi} \leq x_K$ . Then  $\max\{y, \boldsymbol{\xi}\} \leq \max\{x_K, x_K\} = x_K \cdots \boldsymbol{(7)}$  due to  $\boldsymbol{(1)}$ , hence  $V'(\max\{y, \boldsymbol{\xi}\}) = x_K$  due to  $\boldsymbol{(5)}$ . Consequently, we get

r.h.s of (6) = 
$$\beta \mathbf{E}[\xi I(x_K < \xi)] + \beta \mathbf{E}[x_K I(\xi \le x_K)] - s$$
  
=  $\beta \mathbf{E}[\max\{\xi, x_K\}I(x_K < \xi)] + \beta \mathbf{E}[\max\{\xi, x_K\}I(\xi \le x_K)] - s$   
=  $\beta \mathbf{E}[\max\{\xi, x_K\}] - s$   
=  $K(x_K) + x_K$  (See (6.1.10(p.25))) with  $\lambda = 1$   
=  $x_K$ .

Accordingly, it follows that  $V'(y) = x_K$  with  $y \leq x_K$  is a solution of the functional equation (4).

2. The solution is unique Suppose there exists another solution Z(y) with  $y \leq x_K$  where  $V'(y) \neq Z(y)$  for at least one  $y \leq x_K$ . Then, let  $z(y) \stackrel{\text{def}}{=} \max\{y, Z(y)\} \cdots (8)$  with  $y \leq x_K$  (see (27.2.3(p.268))). Accordingly, we have (see (3))

$$Z(y) = \beta \mathbf{E}[\boldsymbol{\xi}I(x_K < \boldsymbol{\xi})] + \beta \mathbf{E}[z(\max\{\boldsymbol{\xi}, y\})I(\boldsymbol{\xi} \le x_K)] - s.\cdots(9)$$

Hence, from (3) and (9) we have

$$|V'(y) - Z(y)| = |\beta \mathbf{E}[(v'(\max\{\xi, y\}) - z(\max\{\xi, y\}))I(\xi \le x_K)]|$$
  
 
$$\le \beta \mathbf{E}[|v'(\max\{\xi, y\}) - z(\max\{\xi, y\})|I(\xi \le x_K)]. \cdots (1)$$

Now, in general

$$|v'(y) - z(y)| = |\max\{y, V'(y)\} - \max\{y, Z(y)\}| \le \max\{0, |V'(y) - Z(y)|\} = |V'(y) - Z(y)|$$

for any y, hence we have

$$|v'(\max\{\xi,y\}) - z(\max\{\xi,y\})| \le |V'(\max\{\xi,y\}) - Z(\max\{\xi,y\})| \cdots (11).$$

for any y and  $\xi$ . Thus, from (10) we have

$$|V'(y) - Z(y)| \le \beta \mathbf{E}[|V'(\max\{\xi, y\}) - Z(\max\{\xi, y\})|I(\xi \le x_K)] \cdots (12).$$

Let  $\nu = \max_{y \le x_K} |V'(y) - Z(y)| \cdots$  (13) where  $\nu > 0 \cdots$  (14), hence  $|V'(y) - Z(y)| \le \nu \cdots$  (15) for  $y \le x_K$ . If  $\xi \le x_K$ , then  $\max\{\xi, y\} \le \max\{x_K, x_K\} = x_K \cdots$  (16), hence  $|V'(\max\{\xi, y\}) - Z(\max\{\xi, y\})| \le \nu$  due to (15). Accordingly, from (12) we have

$$|V'(y) - Z(y)| \le \beta \mathbf{E}[\nu I(\boldsymbol{\xi} \le x_K)] = \beta \nu \mathbf{E}[I(\boldsymbol{\xi} \le x_K)] = \beta \nu \Pr\{\boldsymbol{\xi} \le x_K\} = \beta \nu F(x_K).$$

Thus, we have  $\nu \leq \beta \nu F(x_K) \cdots$  (17) due to the definition (13). In addition, since  $\beta \nu F(x_K) \leq \beta \nu$  due to  $F(x_K) \leq 1$ , we have  $\nu \leq \beta \nu$  from (17), leading to the contradiction  $1 \leq \beta$  due to (14). Accordingly, the solution of (4) must be unique. Since the original V(y) satisfy (4), it eventually follows that  $V(y) = x_K$  with  $y \leq x_K$  must be the unique solution of (4).

- (b) If  $x_K \leq y$ , from Lemma 27.2.3(p.268) (a) and (27.2.3(p.268)) we have  $v(y) = y = \max\{y, x_K\}$ . If  $y \leq x_K$ , then from Lemma 27.2.3(p.268) (b) and (27.2.3(p.268)) we have v(y) = V(y) and from (a) we have  $V(y) = x_K$ , hence it follows that  $v(y) = V(y) = x_K = \max\{y, x_K\}$ . Thus, whether  $x_K \leq y$  or  $y \leq x_K$ , we have  $v(y) = \max\{y, x_K\}$ .
- (c) Since  $v(\boldsymbol{\xi}) = \max\{\boldsymbol{\xi}, x_K\}$  for any  $\boldsymbol{\xi}$  due to (b), from (27.2.4(p.268)) we have  $V = \beta \mathbf{E}[\max\{\boldsymbol{\xi}, x_K\}] s = K(x_K) + x_K = x_K$  (see (6.1.10(p.25))).
- (d) Let  $\kappa > (=(<))$  0. Then, since  $x_{\kappa} > (=(<))$  0 due to Lemma 11.3.1(p.59) (b), from (c) we have V > (=(<)) 0, hence the assertion becomes true from (27.2.5(p.268)).

Here, let us define

$$\ell_t(y) \stackrel{\text{def}}{=} v_t(y) - \beta v_{t-1}(y), \quad t > 0.$$
 (27.2.6)

Then, from (27.2.1(p.267)) and (26.1.49(p.253)) we have

$$\mathbb{V}_t = \beta \mathbf{E}[v_{t-1}(\boldsymbol{\xi})] - s - \beta(\beta \mathbf{E}[v_{t-2}(\boldsymbol{\xi})] - s)$$
(27.2.7)

$$= \beta \mathbf{E}[v_{t-1}(\xi) - \beta v_{t-2}(\xi)] - (1 - \beta)s$$
 (27.2.8)

$$= \beta \mathbf{E}[\ell_{t-1}(\xi)] - (1-\beta)s, \quad t > 1. \tag{27.2.9}$$

Here, for any y let us define

$$A(y) \stackrel{\text{def}}{=} \ell_2(y) - \ell_1(y). \tag{27.2.10}$$

#### Lemma 27.2.5 (rM:1[R][E])

- (a) Let  $x_K \leq y$ . Then A(y) = 0.
- (b) Let  $y \leq x_K$ . Then A(y) is nondecreasing in y.
- (c)  $A(y) \leq 0$  for any y.  $\square$
- Proof (a) Let  $x_K \leq y$ . Then  $V_2(y) \leq y$  and  $V_1(y) \leq y$  from Lemma 27.2.2(p.267) (a), hence from (26.1.53(p.253)) we have  $v_2(y) = v_1(y) = y$ . In addition,  $v_0(y) = y$  from (26.1.47(p.253)). Thus, since  $\ell_2(y) = v_2(y) \beta v_1(y) = (1 \beta)y$  and  $\ell_1(y) = v_1(y) \beta v_0(y) = (1 \beta)y$ , we have  $A(y) = 0 \cdots (1)$ .
  - (b) Let  $y \le x_K \cdots (2)$ . Now, from Lemma 27.2.2(p.267) (b) with t = 1, 2 and (26.1.48(p.253)) with t = 1, 2 we have

$$v_1(y) = V_1(y) = \beta \mathbf{E}[\max{\{\xi, y\}}] - s \qquad \text{(see (26.1.55(p.253)))}$$

$$= K(y) + y$$
 (see (6.1.10(p.25)) with  $\lambda = 1$ ), (27.2.12)

$$v_2(y) = V_2(y) = \beta \mathbf{E}[v_1(\max\{\boldsymbol{\xi},y\})] - s \quad (\text{see } (26.1.50(p.253)) \text{ with } t = 2). \tag{27.2.13}$$

Hence, we have

$$\ell_1(y) = v_1(y) - \beta v_0(y) = v_1(y) - \beta y \quad (\text{see } (26.1.47(\text{p.253}))),$$
  
$$\ell_2(y) = v_2(y) - \beta v_1(y) = \beta \mathbf{E}[v_1(\max\{\boldsymbol{\xi},y\})] - s - \beta v_1(y),$$

from which we obtain

$$A(y) = \beta \mathbf{E}[v_1(\max\{\xi, y\})] - s - (1+\beta)v_1(y) + \beta y,$$

which can be rewritten as

$$A(y) = \beta \mathbf{E}[v_1(\max\{\xi, y\})I(\xi < x_K) + v_1(\max\{\xi, y\})I(x_K \le \xi)] - s - (1 + \beta)v_1(y) + \beta y.$$
 (27.2.14)

If  $\xi < x_K$ , due to (2) we have  $\max\{\xi, y\} \le \max\{x_K, x_K\} = x_K$ , hence from (27.2.12(p.269)) we have

$$v_1(\max\{\xi, y\}) = K(\max\{\xi, y\}) + \max\{\xi, y\}.$$
 (27.2.15)

If  $x_K \leq \xi$ , then since  $x_K \leq \xi \leq \max\{\xi, y\}$  for any y, from Lemma 27.2.2(p.267) (a) we have  $V_1(\max\{\xi, y\}) \leq \max\{\xi, y\}$ , hence from (26.1.48(p.253)) with t = 1 we obtain

$$v_1(\max\{\xi, y\}) = \max\{\xi, y\}.$$
 (27.2.16)

Accordingly, from (27.2.14(p.270)), (27.2.15(p.270)), and (27.2.16(p.270)) we have

$$A(y) = \beta \mathbf{E} [(K(\max\{\xi, y\}) + \max\{\xi, y\}) I(\xi < x_K) + \max\{\xi, y\} I(x_K \le \xi)] - s - (1 + \beta)v_1(y) + \beta y$$

$$= \beta \mathbf{E} [K(\max\{\xi, y\}) I(\xi < x_K) + \max\{\xi, y\} (I(\xi < x_K) + I(x_K \le \xi))] - s - (1 + \beta)v_1(y) + \beta y$$

$$= \beta \mathbf{E} [K(\max\{\xi, y\}) I(\xi < x_K) + \max\{\xi, y\}] - s - (1 + \beta)v_1(y) + \beta y^{\dagger}$$

$$= \beta \mathbf{E} [K(\max\{\xi, y\}) I(\xi < x_K)] + \beta \mathbf{E} [\max\{\xi, y\}] - s - (1 + \beta)v_1(y) + \beta y.$$
(27.2.17)

Using (27.2.11(p.269)), we can rewrite the above as

$$A(y) = \beta \mathbf{E}[K(\max\{\xi, y\})I(\xi < x_K)] + v_1(y) - (1+\beta)v_1(y) + \beta y$$
  
= \beta \mathbf{E}[K(\max\{\xi, y\})I(\xi < x\_K)] - \beta(v\_1(y) - y). (27.2.18)

Furthermore, since  $v_1(y) - y = K(y)$  due to (27.2.12(p.269)), we can rewrite (27.2.18(p.270)) above as

$$A(y) = \beta \mathbf{E}[K(\max\{\boldsymbol{\xi}, y\})I(\boldsymbol{\xi} < x_K)] - \beta K(y)$$

$$= \beta \mathbf{E}[K(\max\{\boldsymbol{\xi}, y\})I(\boldsymbol{\xi} < x_K) - K(y)]$$

$$= \beta \mathbf{E}[B(\boldsymbol{\xi}, y)]$$
(27.2.19)

where

$$B(\boldsymbol{\xi}, y) \stackrel{\text{def}}{=} K(\max\{\boldsymbol{\xi}, y\}) I(\boldsymbol{\xi} < x_K) - K(y). \tag{27.2.20}$$

Now we have:

- 1 Let  $x_K \leq \boldsymbol{\xi}$ . Then, since  $I(\boldsymbol{\xi} < x_K) = 0$ , we have  $B(\boldsymbol{\xi}, y) = -K(y)$ , which is nondecreasing in  $y \leq x_K$  from Lemma 11.2.2(p.57) (b).
- 2 Let  $\boldsymbol{\xi} < x_K$ . Then, since  $I(\boldsymbol{\xi} < x_K) = 1$ , we have  $B(\boldsymbol{\xi}, y) = K(\max\{\boldsymbol{\xi}, y\}) K(y)$  for  $y \le x_K$ . Thus, if  $y \le \boldsymbol{\xi}$ , then  $B(\boldsymbol{\xi}, y) = K(\boldsymbol{\xi}) K(y)$ , which is nondecreasing in  $y \le \boldsymbol{\xi}$  due to Lemma 11.2.2(p.57) (b) and if  $\boldsymbol{\xi} < y$ , then since  $\boldsymbol{\xi} < x_K$  due to (2), we have  $I(\boldsymbol{\xi} < x_K) = 1$ , hence  $B(\boldsymbol{\xi}, y) = K(y) K(y) = 0$  for  $y \le x_K$ , which can be regarded as nondecreasing in  $y > \boldsymbol{\xi}$ . Therefore, whether  $y \le \boldsymbol{\xi}$  or  $\boldsymbol{\xi} < y$  it follows that  $B(\boldsymbol{\xi}, y)$  is nondecreasing in  $y \le x_K$ .

From the above two results, whether  $x_K \leq \boldsymbol{\xi}$  or  $\boldsymbol{\xi} < x_K$  it follows that  $B(\boldsymbol{\xi}, y)$  is nondecreasing in  $y \leq x_K$ . Hence, from (27.2.19(p.270)) we see that A(y) is nondecreasing in  $y \leq x_K$ .

(c) Immediate from (a,b) and the fact that A(y) is continuous on  $(-\infty,\infty)$ .

## Lemma 27.2.6 (rM:1[ $\mathbb{R}$ ][ $\mathbb{E}$ ])

- (a)  $\ell_t(y)$  is nonincreasing in t > 0 for any y.
- (b)  $V_t$  is nonincreasing in  $t \geq 1$ .  $\square$
- Proof (a) From Lemma 27.2.5(p.269) (c) and (27.2.10(p.269)) we have  $\ell_2(y) \leq \ell_1(y)$  for any y. Suppose that  $\ell_{t-1}(y) \leq \ell_{t-2}(y)$  for any y (induction hypothesis).
- 1. Let  $x_K \leq y$ . Then, since  $V_t(y) \leq y$  for  $t \geq 0$  due to Lemma 27.2.2(p.267) (a), we have  $V_{t-1}(y) \leq y$  for  $t \geq 1$ , hence  $v_t(y) = y$  for  $t \geq 0$  and  $v_{t-1}(y) = y$  for  $t \geq 1$  from (26.1.53(p.253)). Thus, from (27.2.6(p.269)) we have  $\ell_t(y) = (1-\beta)y$  for  $t \geq 1$ , hence  $\ell_{t-1}(y) = (1-\beta)y$  for  $t \geq 2$ , so  $\ell_t(y) = \ell_{t-1}(y)$  for  $t \geq 2$ , thus  $\ell_t(y) \leq \ell_{t-1}(y)$  for  $t \geq 2$ . Accordingly, it follows that  $\ell_t(y)$  is nonincreasing in  $t \geq 1$  or equivalently in t > 0 on  $x_K \leq y$ .

 $<sup>^{\</sup>dagger}I(\boldsymbol{\xi}<\,x_{K}\,)+I(\,x_{K}\,\leq\boldsymbol{\xi})=1.$ 

2. Let  $y \le x_K$ . Then, since  $y \le V_t(y)$  for  $t \ge 0$  and  $y \le V_{t-1}(y)$  for t > 0 from Lemma 27.2.2(p.267) (b), we have  $v_t(y) = V_t(y)$  for  $t \ge 0$  and  $v_{t-1}(y) = V_{t-1}(y)$  for  $t \ge 1$  from (26.1.53(p.253)), hence from (27.2.6(p.269)) and (26.1.50(p.253)) we have

$$\ell_{t}(y) = V_{t}(y) - \beta V_{t-1}(y)$$

$$= \beta \mathbf{E}[v_{t-1}(\max\{\xi, y\})] - s - \beta (\beta \mathbf{E}[v_{t-2}(\max\{\xi, y\})] - s)$$

$$= \beta \mathbf{E}[v_{t-1}(\max\{\xi, y\}) - \beta v_{t-2}(\max\{\xi, y\})] - (1 - \beta)s$$

$$= \beta \mathbf{E}[\ell_{t-1}(\max\{\xi, y\})] - (1 - \beta)s, \quad t \ge 1.$$

Thus, we have

$$\ell_{t-1}(y) = \beta \mathbf{E}[\ell_{t-2}(\max\{\xi, y\})] - (1 - \beta)s, \quad t \ge 2.$$

Here, since  $\ell_{t-1}(\max\{\boldsymbol{\xi},y\}) \leq \ell_{t-2}(\max\{\boldsymbol{\xi},y\})$  due to the induction hypothesis, we have

$$\ell_t(y) \le \beta \mathbf{E}[\ell_{t-2}(\max\{\xi, y\})] - (1 - \beta)s = \ell_{t-1}(y), \quad t > 1.$$

Accordingly, by induction we have  $\ell_t(y) \le \ell_{t-1}(y)$  for  $t \ge 2$  on  $y \le x_K$ , i.e.,  $\ell_t(y)$  is nonincreasing in  $t \ge 1$  on  $y \le x_K$ . From the above two results, whether  $x_K \le y$  or  $y \le x_K$  it follows that  $\ell_t(y)$  is nonincreasing in t > 0.

(b) Immediate from (a(p.270)) and (27.2.9(p.269)).

# 27.2.1.2 Analysis

From (26.1.49(p.253)) with t = 2 we have

$$\begin{split} V_2 &= \beta \, \mathbf{E}[v_1(\xi)] - s \\ &= \beta \, \mathbf{E}[\max\{\xi, V_1(\xi)\}] - s \qquad \text{(see (26.1.48(p.253)) with } t = 1) \\ &= \beta \, \mathbf{E}[\max\{\xi, K(\xi) + \xi\}] - s \qquad \text{(see (26.1.56(p.253)) with } y = \xi) \\ &= \beta \, \mathbf{E}[\max\{0, K(\xi)\} + \xi] - s \\ &= \beta \, \mathbf{E}[\max\{0, K(\xi)\}] + \beta \, \mathbf{E}[\xi] - s \\ &= \beta \, \mathbf{E}[\max\{0, K(\xi)\}] + \beta \mu - s. \end{split}$$

Then (27.2.1(p.267)) with t=2 can be rewritten as

$$\begin{split} \mathbb{V}_2 &= V_2 - \beta V_1 \\ &= \beta \, \mathbf{E} [\max\{0, K(\boldsymbol{\xi})\}] + \beta \mu - s - \beta (\beta \mu - s) \quad (\text{see } (26.1.54 \text{(p.253)})) \\ &= \beta \, \mathbf{E} [\max\{0, K(\boldsymbol{\xi})\}] + (1 - \beta) (\beta \mu - s) \\ &= \beta \, \mathbf{E} [\max\{0, K(\boldsymbol{\xi})\} I(\boldsymbol{\xi} < x_K) + \max\{0, K(\boldsymbol{\xi})\} I(x_K \le \boldsymbol{\xi})] + (1 - \beta) (\beta \mu - s). \end{split}$$

Due to Corollary 11.2.2(p.58) (a) we have  $K(\xi) > 0$  for  $\xi < x_K$  and  $K(\xi) \le 0$  for  $x_K \le \xi$ , hence we have

$$V_2 = \beta \mathbf{E}[K(\xi)I(\xi < x_K)] + (1 - \beta)(\beta \mu - s). \tag{27.2.21}$$

Let us define

- Tom 27.2.1 ( $\mathscr{A}\{rM:1[\mathbb{R}][E]\}$ ) For any  $\tau > 1$ :
- (a) We have:
  - 1. Let  $y \geq x_K$ . Then  $y \geq V_t(y)$  for  $t \geq 0$ .
  - 2. Let  $y \leq x_K$ . Then  $y \leq V_t(y)$  for  $t \geq 0$ .
- (b) Let  $\beta = 1$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\triangle}$ .
- (c) Let  $\beta < 1$ .
  - 1. Let  $\beta \mu s \geq 0$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\land}$ .
  - 2. Let  $\beta \mu s < 0$  and  $\beta \mu s < a$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\blacktriangle}$ .
  - 3. Let  $\beta\mu s < 0$  and  $\beta\mu s \ge a$  (hence a < 0).
    - i. Let  $\mathbb{V}_2 \leq 0$ . Then  $\bullet dOITd_{\tau>1}\langle 1 \rangle_{\Delta}$ .
    - ii. Let  $\mathbb{V}_2 > 0$ .

      - 2. Let  $\kappa < 0$ . Then we have  $S_{18}(p.271)$   $\bigcirc \triangle \bigcirc \triangle \bigcirc \triangle$ .  $\mapsto$

- Proof Since  $\lambda = 1$  is assumed in the model, we have  $\delta = 1$  (See (11.2.1(p.56))), hence  $(\lambda \beta \mu s)/\delta = \beta \mu s \cdots$  (1) and  $K(a) = \beta \mu s a \cdots$  (2) from (11.2.4 (1) (p.57)).
  - (a1,a2) The same as Lemma 27.2.2(p.267) (a,b).
- (b) Let  $\beta=1$ . Then, from (27.2.1(p.207)) we have  $\mathbb{V}_t=V_t-\beta V_{t-1}=V_t-V_{t-1}$  for t>1, hence  $\mathbb{V}_t\geq 0$  for t>1 due to Lemma 27.2.1(p.207) (c) or equivalently  $V_t\geq \beta V_{t-1}$  for t>1. Thus, since  $V_t\geq \beta V_{t-1}$  for  $\tau\geq t>1$ , we have  $V_\tau\geq \beta V_{\tau-1}$ ,  $V_{\tau-1}\geq \beta V_{\tau-2}, \cdots, V_2\geq \beta V_1$ , hence  $V_\tau\geq \beta V_{\tau-1}\geq \beta^2 V_{\tau-2}\geq \cdots \geq \beta^{\tau-1}V_1$ , so  $t_\tau^*=\tau$  for  $\tau>1$ , i.e.,  $\boxed{\$ \text{ dOITs}_\tau\langle\tau\rangle}_{\Delta}$ .
  - (c) Let  $\beta < 1$ .
- (c1) Let  $\beta\mu s \ge 0$ , hence  $V_1 \ge 0$  from (26.1.54(p.253)). Then  $V_t \ge V_{t-1} \ge V_1 \ge 0$  for t > 1 from Lemma 27.2.1(p.267) (c). Hence, from (27.2.1(p.267)) we have  $\mathbb{V}_t = V_t \beta V_{t-1} \ge V_{t-1} \beta V_{t-1} = (1-\beta)V_{t-1} \ge 0$  for t > 1. Then, since  $V_t \ge \beta V_{t-1}$  for t > 1, for the same reason as in the proof of (b) we have  $\boxed{\$ \text{ dOITs}_{\tau}\langle \tau \rangle}_{\Delta}$ .
- (c2) Let  $\beta\mu s < 0 \cdots$  (3) and  $\beta\mu s < a$ . Then, from (2) we have K(a) < 0, hence  $x_K < a$  from Lemma 11.2.2(p.57) (j1). Below it suffices to consider only  $y \in [a,b]$  such that  $x_K < a \le y$ . Then, since  $V_t(y) \le y$  for  $t \ge 0$  from Lemma 27.2.2(p.267) (a), we have  $v_t(y) = y$  for  $t \ge 0$  from (26.1.53(p.253)), hence  $v_{t-1}(y) = y$  for t > 0, so from (27.2.6(p.269)) we have  $\ell_t(y) = v_t(y) \beta v_{t-1}(y) = y \beta y = (1-\beta)y$  for t > 0. Accordingly, since  $\ell_{t-1}(\xi) = (1-\beta)\xi$  for t > 1 and  $\xi \in [a,b]$ , from (27.2.9(p.269)) we obtain  $\mathbb{V}_t = V_t \beta V_{t-1} = \beta \mathbf{E}[(1-\beta)\xi] (1-\beta)s = \beta(1-\beta)\mathbf{E}[\xi] (1-\beta)s = \beta(1-\beta)\mu (1-\beta)s = (1-\beta)(\beta\mu s) < 0$  for t > 1 due to (3). Then, since  $V_t < \beta V_{t-1}$  for t > 1, we have  $V_t < \beta V_{t-1}$  for  $\tau \ge t > 1$ . Accordingly, since  $V_\tau < \beta V_{\tau-1}$ ,  $V_{\tau-1} < \beta V_{\tau-2}$ ,  $\cdots$ ,  $V_2 < \beta V_1$ , we have  $V_\tau < \beta V_{\tau-1} < \beta^2 V_{\tau-2} < \cdots < \beta^{\tau-1} V_1$ , hence  $t_\tau^* = \tau$  for  $\tau > 1$ , i.e.,  $\boxed{\bullet}$  dOITd $_{\tau>1}(1)$ .
- (c3) Let  $\beta\mu s < 0 \cdots$  (4) and  $\beta\mu s \ge a$ , hence a < 0. Then, since  $K(a) \ge 0$  from (2), we have  $a \le x_K \cdots$  (5) from Lemma 11.2.2(p.57) (j1).
- (c3i) Let  $\mathbb{V}_2 \leq 0$ . Then, since  $\mathbb{V}_t \leq 0$  for t > 1 from Lemma 27.2.6(p.270) (b), we have  $\mathbb{V}_t \leq 0$  for  $\tau \geq t > 1$ . Hence, since  $V_\tau \beta V_{\tau-1} \leq 0$  for  $\tau \geq t > 1$  from (27.2.1(p.267)), we have  $V_\tau \leq \beta V_{\tau-1}$  for  $\tau \geq t > 1$ . Accordingly, since  $V_\tau \leq \beta V_{\tau-1}$ ,  $V_{\tau-1} \leq \beta V_{\tau-2}, \cdots, V_2 \leq \beta V_1$ , we have  $V_\tau \leq \beta V_{\tau-1} \leq \cdots \leq \beta^{\tau-1} V_1$ , so  $t_\tau^* = 1$  for  $\tau > 1$ , i.e.,  $\bullet$  dOITd $_{\tau>1}\langle 1 \rangle$ .
  - (c3ii) Let  $\mathbb{V}_2 > 0 \cdots (6)$ .
- (c3ii1) Let  $\kappa \geq 0$ . Then  $\mathbb{V} \geq 0$  due to Lemma 27.2.4(p.268) (d). Hence, from (6) and Lemma 27.2.6(p.270) (b) we have  $\mathbb{V}_t \geq 0$  for t > 1, hence we obtain  $\boxed{\$}$  dOITs $_{\tau > 1} \langle \tau \rangle$  for the same reason as in the proof of (c1).
- (c3ii2) Let  $\kappa < 0$ . Then  $\mathbb{V} < 0$  due to Lemma 27.2.4(p.268) (d). Hence, from (6), and Lemma 27.2.6(p.270) (b) it follows that there exist  $t_{\tau}^{\circ}$  and  $t_{\tau}^{\bullet}$  ( $t_{\tau}^{\circ} \geq t_{\tau}^{\bullet} > 1$ ) such that

$$\mathbb{V}_2 \geq \cdots \geq \mathbb{V}_{t^{\bullet}_{\underline{\bullet}}-1} \geq \mathbb{V}_{t^{\bullet}_{\underline{\bullet}}} > 0 \geq \mathbb{V}_{t^{\bullet}_{\underline{\bullet}}+1} \geq \mathbb{V}_{t^{\bullet}_{\underline{\bullet}}+1} \geq \cdots \geq \mathbb{V}_{t^{\circ}_{\underline{\bullet}}} > \mathbb{V}_{t^{\circ}_{\underline{\bullet}}+1} \geq \cdots$$

or equivalently

$$\mathbb{V}_t \geqslant 0 \cdots (1^*), \quad t_{\tau}^{\bullet} \geq t > 1, \qquad 0 \geq \mathbb{V}_t \cdots (2^*), \quad t_{\tau}^{\circ} \geq t > t_{\tau}^{\bullet}, \qquad 0 \geqslant \mathbb{V}_t \cdots (3^*), \quad t > t_{\tau}^{\circ}.$$

- [1] Let  $t^{\bullet}_{\tau} \geq \tau > 1$ . Then, since  $\mathbb{V}_{t} > 0$  for  $\tau \geq t > 1$  due to (1\*), for almost the same reason as in the proof of (b) we have  $V_{\tau} > \beta V_{\tau-1} > \cdots > \beta^{\tau-1} V_{1} \cdots$  (7), hence  $t^{*}_{\tau} = \tau$  for  $t^{\bullet}_{\tau} \geq \tau > 1$ , i.e.,  $\boxed{\$ \text{ dOITs}_{t^{\bullet}_{\tau} \geq \tau > 1} \langle \tau \rangle}_{\bullet} \cdots$  (8). From (7) with  $\tau = t^{\bullet}_{\tau}$  we have  $V_{t^{\bullet}_{\tau}} > \beta V_{t^{\bullet}_{\tau}-1} > \beta^{2} V_{t^{\bullet}_{\tau}-2} > \cdots > \beta^{t^{\bullet}_{\tau}-1} V_{1}.$
- [2] Since  $V_{t^{\bullet}_{\tau}+1} \leq 0$  due to  $(2^*)$ , we have  $V_{t^{\bullet}_{\tau}+1} \leq \beta V_{t^{\bullet}_{\tau}}$  from (27.2.1 (p.267)). Hence

$$V_{t_{-}^{\bullet}+1} \leq \beta V_{t_{-}^{\bullet}} > \beta^2 V_{t_{-}^{\bullet}-1} > \beta^3 V_{t_{-}^{\bullet}-2} > \cdots > \beta^{t_{\tau}^{\bullet}} V_1 \cdots (9),$$

so  $t_{t_{\tau}^*+1}^* = t_{\tau}^*$  or equivalently  $\boxed{\odot \text{ ndOIT}_{t_{\tau}^*+1}\langle t_{\tau}^* \rangle}_{\Delta}$   $\cdots$  (10). Since  $\mathbb{V}_{t_{\tau}^*+2} \leq 0$  due to (2\*), we have  $V_{t_{\tau}^*+2} \leq \beta V_{t_{\tau}^*+1}$ . Hence, from (9) we have

$$V_{t_{-}+2} \le \beta V_{t_{-}+1} \le \beta^2 V_{t_{-}} > \beta^3 V_{t_{-}-1} > \beta^4 V_{t_{-}-2} > \dots > \beta^{t_{\tau}+1} V_1,$$

so  $t_{t_{\tau}^{\bullet}+2}^{*} = t_{\tau}^{\bullet}$  or equivalently we have  $\boxed{\textcircled{ndOIT}_{t_{\tau}^{\bullet}+2}\langle t_{\tau}^{\bullet}\rangle}_{\vartriangle} \cdots$  (11). Similarly we obtain  $\boxed{\textcircled{ndOIT}_{t_{\tau}^{\bullet}+3}\langle t_{\tau}^{\bullet}\rangle}_{\vartriangle} \cdots$  (12),  $\boxed{\textcircled{ndOIT}_{t_{\tau}^{\bullet}+4}\langle t_{\tau}^{\bullet}\rangle}_{\vartriangle} \cdots$  (13),  $\cdots$  Since  $\mathbb{V}_{t_{\tau}^{\circ}} \leq 0$  due to  $(2^{*})$ , we have  $V_{t_{\tau}^{\circ}} \leq \beta V_{t_{\tau}^{\circ}-1}$ . Hence

$$V_{t_{\tau}^{\circ}} \leq \beta V_{t_{\tau}^{\circ}-1} \leq \cdots \leq \beta^{t_{\tau}^{\circ}-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} > \beta^{t_{\tau}^{\circ}-t_{\tau}^{\bullet}+1} V_{t_{\tau}^{\bullet}-1} > \cdots > \beta^{t_{\tau}^{\circ}-1} V_{1} \cdots (14),$$

so  $t_{t_{\tau}^{\circ}}^{*} = t_{\tau}^{\bullet}$  or equivalently  $\boxed{\odot \text{ ndOIT}_{t_{\tau}^{\circ}}\langle t_{\tau}^{\bullet} \rangle}_{\Delta} \cdots$  (15). Hence, from (10), (11), (12), (13), ..., (15) we have  $\boxed{\odot \text{ ndOIT}_{t_{\tau}^{\circ} \geq \tau > t_{\tau}^{\bullet}}\langle t_{\tau}^{\bullet} \rangle}_{\Delta} \cdots$  (16).

[3] Since  $\mathbb{V}_{t_{\tau}^{\circ}+1} < 0$  due to (3), we have  $V_{t_{\tau}^{\circ}+1} < \beta V_{t_{\tau}^{\circ}}$ , hence from (14) we get

$$V_{t_{\tau}^{\circ}+1} < \beta V_{t_{\tau}^{\circ}} \le \beta^{2} V_{t_{\tau}^{\circ}-1} \le \dots \le \beta^{t_{\tau}^{\circ}-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} \le \beta^{t_{\tau}^{\circ}-t_{\tau}^{\bullet}+1} V_{t_{\tau}^{\bullet}} > \beta^{t_{\tau}^{\circ}-t_{\tau}^{\bullet}+2} V_{t_{\tau}^{\bullet}-1} > \dots > \beta^{t_{\tau}^{\circ}} V_{1},$$

so  $t_{t^*+1}^* = t_{\tau}^{\bullet}$  or equivalently  $\boxed{\textcircled{ndOIT}_{t_{\tau}^{\circ}+1}\langle t_{\tau}^{\bullet}\rangle}_{\blacktriangle}$ . Similarly, since  $\mathbb{V}_{t_{\tau}^{\circ}+2} < 0$ , we have  $\boxed{\textcircled{ndOIT}_{t_{\tau}^{\circ}+3}\langle t_{\tau}^{\bullet}\rangle}_{\blacktriangle}$ . In general, we have  $\boxed{\textcircled{ndOIT}_{\tau>t_{\tau}^{\circ}}\langle t_{\tau}^{\bullet}\rangle}_{\blacktriangle} \cdots (17)$ .

From [1]-[3] above we see that (8), (16), and (17) can be summarized as  $S_{18}(p.271)$   $\bigcirc \triangle \bigcirc \triangle \bigcirc \triangle$ .

#### 27.2.1.3 Flow of Optimal Decision Rules

\* Flow-ODR 7 (rM:1[ $\mathbb{R}$ ][E]) (c-reservation-price) From Tom 27.2.1(p.27l) (\* a1,\* a2) and (26.1.58(p.253)) we have the following decision rule for  $\tau \geq t > 0$ :

$$\left\{ \begin{aligned} y \geq & \ x_K \ \Rightarrow \ \mathsf{Accept}_t \langle y \rangle \ \mathrm{and \ the \ process \ stops} \ \mathsf{I} \\ y \leq & \ x_K \ \Rightarrow \ \mathsf{Reject}_t \langle y \rangle \ \mathrm{and \ the \ search \ is \ conducted} \end{aligned} \right.$$

Namely, the optimal reservation value is given by  $x_K$ , which is constant in t.

**Definition 27.2.1** (myopic property) c-reservation-price implies that the optimal decision of any point in time t > 1 is identical to that of time 1 at which the process terminates a period hence, i.e., the deadline, implying that the optimal decision is the same as "behave as if the process terminates a period hence", called the *myopic property*.  $\Box$ 

#### 27.2.1.4 Market Restriction

#### 27.2.1.4.1 Positive Restriction

- $\square$  Pom 27.2.1 ( $\mathscr{A}\{\mathbf{r}\mathsf{M}:1[\mathbb{R}][\mathsf{E}]^+\}$ ) Suppose a>0.
- (a) We have c-reservation-price (\*Flow-ODR 7).
- (b) Let  $\beta = 1$ . Then  $\bigcirc$  dOITs<sub> $\tau > 1$ </sub> $\langle \tau \rangle$
- (c) Let  $\beta < 1$ .
  - 1. Let  $\beta \mu s \ge 0$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}$
  - 2. Let  $\beta \mu s < 0$ . Then  $\boxed{\bullet dOITd_{\tau > 1}\langle 1 \rangle}$
- Proof Suppose  $a > 0 \cdots$  (1). Then  $\kappa = \beta \mu s$  from Lemma 11.3.1(p.59) (a).
  - (a) Clear from Lemma 27.2.1(p.271) (\*a1,\*a2) and \*Flow-ODR 7.
  - (b) The same as Tom 27.2.1(p.271) (b).
  - (c) Let  $\beta < 1$ .
  - (c1) The same as Tom 27.2.1(p.271) (c1).
  - (c2) Let  $\beta\mu s < 0$ . Then, since  $\beta\mu s < a$  due to (1), we have Tom 27.2.1(p.271) (c2).

# 27.2.1.4.2 Mixed Restriction

Omitted.

## 27.2.1.4.3 Negative Restriction

- $\square$  Nem 27.2.1 ( $\mathscr{A}\{\mathbf{r}\mathsf{M}:1[\mathbb{R}][\mathsf{E}]^-\}$ ) Suppose b<0.
- (a) We have c-reservation-price (\* Flow-ODR 7).
- (b) Let  $\beta = 1$ . Then  $\bigcirc$  dOITs<sub> $\tau > 1$ </sub> $\langle \tau \rangle$
- (c) Let  $\beta < 1$ .
  - 1. Let  $\beta \mu s < a$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1} \langle 1 \rangle}$
  - 2. Let  $\beta \mu s \ge a$ .
    - i. Let  $\mathbb{V}_2 \leq 0$ . Then  $\bullet dOITd_{\tau>1}\langle 1 \rangle$
    - ii. Let  $\mathbb{V}_2 > 0$ .
      - 1. Let s = 0. Then  $subseteq dOITs_{\tau>1}\langle \tau \rangle_{\Delta}$
      - 2. Let s > 0. Then we have  $S_{18}(p.271)^{\boxed{\S \blacktriangle} \odot \vartriangle \odot \blacktriangle}$
- Proof Suppose b < 0. Then  $a < \mu < b < 0$ , hence  $\beta \mu < 0$ , so  $\beta \mu s < 0 \cdots$  (1) for any  $s \ge 0$ . Then  $\kappa = -s \cdots$  (2) from Lemma 11.3.1(p.59) (a).
  - (a) Clear from Lemma 27.2.1(p.271) (\*a1,\*a2) and \*Flow-ODR 7.
  - (b) The same as Tom 27.2.1(p.271) (b).
  - (c) Let  $\beta < 1$ .
  - (c1) Let  $\beta \mu s < a$ . Then, due to (1) we have Tom 27.2.1(p.271) (c2).
  - (c2) Let  $\beta \mu s \ge a$ . Then, due to (1) we have Tom 27.2.1(p.271) (c3i-c3ii2).
  - (c2i) Let  $V_2 \le 0$ . Then we have Tom 27.2.1(p.271) (c3i).
  - (c2ii) Let  $V_2 > 0$ .
  - (c2ii1) Let s = 0. Then  $\kappa = 0$  due to (2), hence we have Tom 27.2.1(p.271) (c3ii1).
  - (c2ii2) Let s > 0. Then  $\kappa < 0$  due to (2), hence we have Tom 27.2.1(p.271) (c3ii2).

# 27.2.2 $\tilde{rM}:1[\mathbb{R}][E]$

# 27.2.2.1 Symmetry of $SOE\{rM:1[\mathbb{R}][E]\}$ and $SOE\{r\tilde{M}:1[\mathbb{R}][E]\}$

Here let us show that  $SOE\{r\tilde{M}:1[\mathbb{R}][E]\}$  (see (26.1.63(p.254))) is symmetrical to  $SOE\{rM:1[\mathbb{R}][E]\}$  (see (26.1.51(p.253))), which is a necessary condition under which  $\mathscr{A}\{r\tilde{M}:1[\mathbb{R}][E]\}$  can be derived by applying  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to  $\mathscr{A}\{rM:1[\mathbb{R}][E]\}$  given by Tom 27.2.1(p.271).

1. For convenience of reference, below let us copy (26.1.47(p.253))-(26.1.50(p.253)):

(1\*): 
$$v_0(y) = y$$
, (2\*):  $v_t(y) = \max\{y, V_t(y)\}$ , (3\*):  $V_t = \beta \mathbf{E}[v_{t-1}(\boldsymbol{\xi})] - s$ , (4\*):  $V_t(y) = \beta \mathbf{E}[v_{t-1}(\max\{\boldsymbol{\xi}, y\})] - s$ . Then we have

$$SOE\{rM:1[\mathbb{R}][E]\} = \{(1^*), (2^*), (3^*), (4^*)\}.$$

2. Applying the reflection operation  $\mathcal{R}$  to the above four equalities yields:

$$(1^*)': -\hat{v}_0(-\hat{y}) = -\hat{y}, \quad (2^*)': -\hat{v}_t(-\hat{y}) = \max\{-\hat{y}, -\hat{V}_t(-\hat{y})\} = -\min\{\hat{y}, \hat{V}_t(-\hat{y})\}, \quad (3^*)': -\hat{V}_t = \beta \mathbf{E}[-\hat{v}_{t-1}(-\hat{\xi})] - s, \\ (4^*)': -\hat{V}_t(-\hat{y}) = \beta \mathbf{E}[-\hat{v}_{t-1}(\max\{-\hat{\xi}, -\hat{y}\})] - s = \beta \mathbf{E}[-\hat{v}_{t-1}(-\min\{\hat{\xi}, \hat{y}\})] - s,$$

which can be rearranged as:

$$(1^*)': \hat{v}_0(-\hat{y}) = \hat{y}, \quad (2^*)': \hat{v}_t(-\hat{y}) = \min\{\hat{y}, \hat{V}_t(-\hat{y})\}, \quad (3^*)': \hat{V}_t = \beta \mathbf{E}[\hat{v}_{t-1}(-\hat{\boldsymbol{\xi}})] + s, \\ (4^*)': \hat{V}_t(-\hat{y}) = \beta \mathbf{E}[\hat{v}_{t-1}(-\min\{\hat{\boldsymbol{\xi}}, \hat{y}\})] + s. \text{ Then we have}$$

$$\mathcal{R}[\mathtt{SOE}\{r\mathsf{M}{:}1[\mathbb{R}][\mathsf{E}]\}] = \{(1^*)',\,(2^*)',\,(3^*)',\,(4^*)'\}.$$

3. We have  $\mathbf{E}[\hat{v}_{t-1}(-\hat{\boldsymbol{\xi}})] = \mathbf{E}[\hat{v}_{t-1}(\boldsymbol{\xi})] = \int_{-\infty}^{\infty} \hat{v}_{t-1}(\xi) f(\xi) d\xi = \int_{-\infty}^{\infty} \hat{v}_{t-1}(\xi) \check{f}(\hat{\xi}) d\xi$  (see Lemma 13.3.1(p.72) (a): the application of the correspondence replacement operation  $\mathcal{C}_{\mathbb{R}}$ ). Let  $\eta \stackrel{\text{def}}{=} \hat{\xi} = -\xi$ , hence  $d\eta = -d\xi$ . Then  $\mathbf{E}[\hat{v}_{t-1}(-\hat{\boldsymbol{\xi}})] = -\int_{-\infty}^{\infty} \hat{v}_{t-1}(-\eta)\check{f}(\eta) d\eta = \int_{-\infty}^{\infty} \hat{v}_{t-1}(-\eta)\check{f}(\eta) d\eta = \check{\mathbf{E}}[\hat{v}_{t-1}(-\eta)] \cdots (\bullet)$ . Similarly we have  $\mathbf{E}[\hat{v}_{t-1}(-\min\{\hat{\boldsymbol{\xi}},\hat{y}\})] = \check{\mathbf{E}}[\hat{v}_{t-1}(-\min\{\eta,\hat{y}\})]$ . Hence  $(1^*)' - (4^*)'$  can be rewritten as:

$$(1^*)'': \hat{v}_0(-\hat{y}) = \hat{y}, \quad (2^*)'': \hat{v}_t(-\hat{y}) = \min\{\hat{y}, \hat{V}_t(-\hat{y})\}, \quad (3^*)'': \hat{V}_t = \beta \, \check{\mathbf{E}}[\hat{v}_{t-1}(-\boldsymbol{\eta})] + s,$$

$$(4^*)'': \hat{V}_t(-\hat{y}) = \beta \, \check{\mathbf{E}}[\hat{v}_{t-1}(-\min\{\boldsymbol{\eta}, \hat{y}\})] + s,$$
 so we have

$$\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathtt{SOE}\{r\mathsf{M}{:}1[\mathbb{R}][\mathtt{E}]\}] = \{(1^*)'', (2^*)'', (3^*)'', (4^*)''\}.$$

4. Let us replace  $\check{f}(\eta)$  by  $f(\eta)$  in  $(\bullet)$  (see Lemma 13.3.3(p.73) (a); the application of the identity replacement operation  $\mathcal{I}_{\mathbb{R}}$ ). Then,  $(\bullet)$  can be rearranged as  $\check{\mathbf{E}}[\hat{v}_{t-1}(-\eta)] = \int_{-\infty}^{\infty} \hat{v}_{t-1}(-\eta)f(\eta)d\eta = \int_{-\infty}^{\infty} \hat{v}_{t-1}(-\xi)f(\xi)d\xi^{\dagger} = \mathbf{E}[\hat{v}_{t-1}(-\xi)]$ . Similarly  $\check{\mathbf{E}}[\hat{v}_{t-1}(-\min\{\eta,\hat{y}\})] + s = \mathbf{E}[\hat{v}_{t-1}(-\min\{\xi,\hat{y}\})] + s$ . Accordingly  $(1^*)'' - (4^*)''$  can be rewritten as;

$$(1^*)''': \hat{v}_0(-\hat{y}) = \hat{y}, \quad (2^*)''': \hat{v}_t(-\hat{y}) = \min\{\hat{y}, \hat{V}_t(-\hat{y})\}, \quad (3^*)''': \hat{V}_t = \beta \mathbf{E}[\hat{v}_{t-1}(-\boldsymbol{\xi})] + s, \\ (4^*)''': \hat{V}_t(-\hat{y}) = \beta \mathbf{E}[\hat{v}_{t-1}(-\min\{\boldsymbol{\xi}, \hat{y}\})] + s. \text{ Then we have}$$

$$\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[SOE\{rM:1[\mathbb{R}][E]\}] = \{(1^*)^{\prime\prime\prime}, (2^*)^{\prime\prime\prime}, (3^*)^{\prime\prime\prime}, (4^*)^{\prime\prime\prime}\}.$$

5. Since  $(1^*)''' - (4^*)'''$  hold for any given  $y \in (-\infty, \infty)$ , they holds also for  $\hat{y} \in (-\infty, \infty)$ , hence  $(1^*)''' - (4^*)'''$  hold for  $\hat{y} \in (-\infty, \infty)$ . Accordingly, since  $\hat{y} = y$ , it follows that they hold also for any given y. Thus, we obtain the following:

$$(1^*)'''': \hat{v}_0(-y) = y, \quad (2^*)'''': \hat{v}_t(-y) = \min\{y, \hat{V}_t(-y)\}, \quad (3^*)'''': \hat{V}_t = \beta \mathbf{E}[\hat{v}_{t-1}(-\boldsymbol{\xi})] + s,$$
 
$$(4^*)'''': \hat{V}_t(-y) = \beta \mathbf{E}[\hat{v}_{t-1}(-\min\{\boldsymbol{\xi},y\})] + s. \text{ Then we have }$$

$$\mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathsf{SOE}\{\mathsf{rM}:1|\mathbb{R}][\mathsf{E}]\}] = \{(1^*)'''',(2^*)'''',(3^*)'''',(4^*)''''\}. \tag{27.2.22}$$

6. Note here that  $SOE\{r\tilde{M}:1[\mathbb{R}][E]\}$  can be given by (26.1.59(p.253))-(26.1.62(p.253)), i.e.,

$$(1^*)'''''$$
:  $v_0(y) = y$ ,  $(2^*)'''''$ :  $v_t(y) = \min\{y, V_t(y)\}$ ,  $(3^*)'''''$ :  $V_t = \beta \mathbf{E}[v_{t-1}(\boldsymbol{\xi})] + s$ ,  $(4^*)'''''$ :  $V_t(y) = \beta \mathbf{E}[v_{t-1}(\min\{\boldsymbol{\xi},y\})] + s$ . Then we have

$$\mathtt{SOE}\{r\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\} = \{(1^*)''''', (2^*)''''', (3^*)''''', (4^*)'''''\}. \tag{27.2.23}$$

7. From  $(1^*)''''$  and  $(1^*)'''''$  we have  $\hat{v}_0(-y) = y = v_0(y)$  for any y, i.e.,  $(1^*)'''' = (1^*)'''''$  for t = 0. Suppose  $\hat{v}_{t-1}(-y) = v_{t-1}(y)$  for any y. Thus  $(3^*)'''' = (3^*)'''''$ . Then, from  $(4^*)''''$  we have  $\hat{V}_t(-y) = \beta \mathbf{E}[v_{t-1}(\min\{\boldsymbol{\xi},y\})] + s = V_t(y)$ , so  $(4^*)'''' = (4^*)'''''$  for any y. Hence, from  $(2^*)''''$  we have  $\hat{v}_t(-y) = \min\{y, V_t(y)\} = v_t(y)$ , so  $(2^*)'''' = (2^*)'''''$ . Accordingly, by induction  $\hat{v}_{t-1}(-y) = v_{t-1}(y)$  for any t > 0, so  $(1^*)'''' = (1^*)'''''$ . Thus it follows that (27.2.22(p.274)) is identical to (27.2.23(p.274)), so we have

$$\mathtt{SOE}\{r\tilde{\mathsf{M}}:1[\mathbb{R}][\mathtt{E}]\} = \mathcal{I}_{\mathbb{R}}\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathtt{SOE}\{r\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}] = \mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}[\mathtt{SOE}\{r\mathsf{M}:1[\mathbb{R}][\mathtt{A}]\}] \quad (\mathrm{see} \ (13.5.30(p.77))),$$

meaning that  $SOE\{r\tilde{M}:1[\mathbb{R}][E]\}$  is symmetrical to  $SOE\{rM:1[\mathbb{R}][E]\}$ 

<sup>†</sup>without loss of generality

## 27.2.2. Derivation of $\mathscr{A}\{r\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\}$

As it was demonstrated that  $SOE\{rM:1[\mathbb{R}][E]\}$  is symmetrical to  $SOE\{rM:1[\mathbb{R}][E]\}$ , we see that  $\mathscr{A}\{rM:1[\mathbb{R}][E]\}$  can be obtained by applying Scenario  $[\mathbb{R}](p.75)$  to  $\mathscr{A}\{rM:1[\mathbb{R}][E]\}$  given by Tom 27.2.1(p.271). Before conducting its application, let us apply  $\mathcal{S}_{\mathbb{R}\to \bar{\mathbb{R}}}$  to  $\mathbb{V}_2$ given by (27.2.21(p.27l)). First let us apply the reflection operation  $\mathcal{R}$  to  $\mathbb{V}_2$  given by (27.2.21(p.27l)). Here note that (27.2.21(p.27l))is expressed as

$$\mathbb{V}_2 = \beta \int_{-\infty}^{\infty} K(\xi) I(\xi < x_K) f(\xi) d\xi + (1 - \beta)(-\beta \mu + s).$$

Hence we have

$$\mathcal{R}[\mathbb{V}_2] = \hat{\mathbb{V}}_2 = -\mathbb{V}_2 = \beta \int_{-\infty}^{\infty} -K(\xi)I(-\xi > -x_K)f(\xi)d\xi + (1-\beta)(-\beta\mu + s)$$
$$= \beta \int_{-\infty}^{\infty} \hat{K}(\xi)I(\hat{\xi} > \hat{x}_K)f(\xi)d\xi + (1-\beta)(\beta\hat{\mu} + s)\cdots(*).$$

Then, applying the replacement  $\eta = \hat{\xi} = -\xi$  (hence  $d\eta = -d\xi$ ),  $\hat{\mu} = \check{\mu}$ ,  $\hat{K}(\xi) = \check{K}(\hat{\xi})$ , and  $\hat{x}_K = x_{\check{K}}$  (see Lemma 13.3.1(p.72)(b,e,h) to (\*) leads to

$$\begin{split} \mathcal{R}[\mathbb{V}_2] &= -\beta \int_{\infty}^{-\infty} \check{\check{K}}(\hat{\xi}) I(\eta > x_{\check{K}}) \check{f}(\eta) d\eta + (1 - \beta) (\beta \check{\mu} + s) \\ &= \beta \int_{-\infty}^{\infty} \check{\check{K}}(\eta) I(\eta > x_{\check{K}}) \check{f}(\eta) d\eta + (1 - \beta) (\beta \check{\mu} + s) \\ &= \beta \int_{-\infty}^{\infty} \check{\check{K}}(\xi) I(\xi > x_{\check{K}}) \check{f}(\xi) dx + (1 - \beta) (\beta \check{\mu} + s) \quad \text{(without loss of generality)} \end{split}$$

Since the above replacement means the application of  $\mathcal{C}_{\mathbb{R}}$  to  $\mathcal{R}[\mathbb{V}_2]$ , i.e.,  $\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathbb{V}_2] = \mathcal{R}[\mathbb{V}_2]$ , we have

$$\mathcal{C}_{\mathbb{R}}\mathcal{R}[\mathbb{V}_2] = \beta \int_{-\infty}^{\infty} \check{K}(\xi) I(\xi > x_{\check{\kappa}}) \check{f}(\xi) d\xi + (1 - \beta) (\beta \check{\mu} + s).$$

Furthermore, applying the identity replacement operation  $\mathcal{I}_{\mathbb{R}}$  to this (see Lemma 13.3.3(p.73) (e,h)) yields

$$\mathcal{I}_{\mathbb{R}} \mathcal{C}_{\mathbb{R}} \mathcal{R}[\mathbb{V}_2] = \beta \int_{-\infty}^{\infty} \tilde{K}(\xi) I(\xi > x_{\tilde{K}}) f(\xi) d\xi + (1 - \beta) (\beta \mu + s))$$
$$= \beta \mathbf{E}[\tilde{K}(\xi) I(\xi > x_{\tilde{K}})] + (1 - \beta) (\beta \mu + s).$$

Noting (13.5.30(p.77)), we can rewrite the above as

$$\tilde{\mathbb{V}}_2 \stackrel{\text{def}}{=} \mathcal{S}_{\mathbb{P} \to \tilde{\mathbb{P}}}[\mathbb{V}_2] = \beta \mathbf{E}[\tilde{K}(\boldsymbol{\xi})I(\boldsymbol{\xi} > x_{\tilde{K}})] + (1 - \beta)(\beta \mu + s).$$

Then we have the following Tom.

- $\square$  Tom 27.2.1 ( $\mathscr{A}\{\tilde{rM}:1[\mathbb{R}][E]\}$ )
- (a) We have:
  - 1. Let  $y \leq x_{\tilde{K}}$ . Then  $y \leq V_t(y)$  for  $t \geq 0$ .
  - 2. Let  $y \geq x_{\tilde{K}}$ . Then  $y \geq V_t(y)$  for  $t \geq 0$ .
- (b) Let  $\beta = 1$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\triangle}$ .
- (c) Let  $\beta < 1$ .
  - 1. Let  $\beta \mu + s \leq 0$ . Then  $\boxed{\$ dOITs_{\tau > 1} \langle \tau \rangle}_{\triangle}$ .
  - 2. Let  $\beta \mu + s > 0$  and  $\beta \mu + s > b$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1} \langle 1 \rangle}_{\blacktriangle}$ .
  - 3. Let  $\beta \mu + s > 0$  and  $\beta \mu + s \le b$  (hence b > 0).
    - i. Let  $\tilde{\mathbb{V}}_2 \geq 0$ . Then  $\left[ \bullet dOITd_{\tau > 1} \langle 1 \rangle \right]_{\Delta}$ .
    - ii. Let  $\tilde{\mathbb{V}}_2 < 0$ .

      - 1. Let  $\tilde{\kappa} \leq 0$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1}\langle \tau \rangle}_{\vartriangle}$ . 2. Let  $\tilde{\kappa} > 0$ . Then we have  $\texttt{S}_{18}(\texttt{p.27l})$   $\boxed{\$ \blacktriangle}$   $\boxed{\$ \blacktriangle}$   $\boxed{\$}$   $\boxed{\$}$
- ullet Proof by symmetry Immediately obtained from applying  $\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}$  to Tom 27.2.1(p.271).

#### 27.2.2.3 Flow of Optimal Decision Rules

\* Flow-ODR 8  $(r\tilde{M}:1[\mathbb{R}][E])$ (c-reservation-price) From Tom 27.2.1(p.275) (\* a1,\*a2) and (26.1.66(p.254)) we have the following decision rule for  $\tau \geq t > 0$ .

Namely, the optimal reservation value is given by  $x_{\tilde{k}}$ , which is constant in t.

#### 27.2.2.4 Market Restriction

#### 27.2.2.4.1 Positive Restriction

- $\square$  Pom 27.2.2 ( $\mathscr{A}\{\tilde{\mathbf{r}}\mathbb{M}:1[\mathbb{R}][E]^+\}$ ) Suppose a>0.
- (a) We have c-reservation-price.
- (b) Let  $\beta = 1$ . Then  $\bigcirc \text{dOITs}_{\tau > 1} \langle \tau \rangle$
- (c) Let  $\beta < 1$ .
  - 1. Let  $\beta \mu + s > b$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}$
  - 2. Let  $\beta \mu + s \leq b$ .
    - i. Let  $\tilde{\mathbb{V}}_2 \geq 0$ . Then  $\boxed{\bullet dOITd_{\tau > 1}\langle 1 \rangle}_{\Delta}$
    - ii. Let  $\tilde{\mathbb{V}}_2 < 0$ .
      - 1. Let s = 0. Then  $subseteq dOITs_{\tau>1}\langle \tau \rangle$
      - 2. Let s>0. Then we have  $S_{18(p.271)}$   $\circ \land \circ \land \circ \land$
- Proof Suppose a > 0. Then  $\mu > a > 0$ , hence  $\beta \mu > 0$ , so  $\beta \mu + s > 0 \cdots$  (1) for any  $s \geq 0$ . Then  $\tilde{\kappa} = s$  from Lemma 13.6.6(p.83) (a).
  - (a) Clear from Lemma 27.2.1(p.275) (\*a1,\*a2) and \*Flow-ODR 8.
  - (b) The same as Tom 27.2.1(p.275) (b).
  - (c) Let  $\beta < 1$ .
  - (c1) Let  $\beta \mu + s > b$ . Then, due to (1) we have Tom 27.2.1(p.275) (c2).
  - (c2-c2ii2) Let  $\beta \mu + s \leq b$ . Then, due to (1) we have Tom 27.2.1(p.275) (c3i-c3ii2).

Remark 27.2.1 (diagonal symmetry) Since Pom 27.2.2 can be derived by applying  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}$  to Nem 27.2.1(p.273), we see that the diagonal symmetry holds between both, i.e.,

$$\mathscr{A}\{\texttt{Pom}\ 27.2.2(\texttt{p.276})\} = \mathcal{S}_{\mathbb{R} \to \widetilde{\mathbb{R}}}[\mathscr{A}\{\texttt{Nem}\ 27.2.1(\texttt{p.273})\}] \quad \Box$$

#### 27.2.2.4.2 Mixed Restriction

Omitted.

# 27.2.2.4.3 Negative Restriction

Unnecessary.

# 27.2.3 Conclusion 8 (Search-Enforced-Model 1)

The following five cases are possible:

- C1. We have  $\mathscr{A}\{r\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]\}^+ \not \sim \mathscr{A}\{r\mathsf{M}:1[\mathbb{R}][\mathsf{E}]\}^+$ .
- C2. We have  $\mathfrak{S}_{\Delta}$  for  $rM/\tilde{M}:1[\mathbb{R}][E]^+$ .
- C3. We have  $\bigcirc_{\vartriangle \blacktriangle}$  for  $r\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{E}]^+$ .
- C4. We have  $\mathbf{G}_{\Delta}$  for  $rM/\tilde{M}:1[\mathbb{R}][E]^+$ .
- C5. We have c-reservation-price for  $rM/\tilde{M}:1[\mathbb{R}][E]^+$ .  $\square$
- C1 Compare Pom 27.2.2(p.276) and Pom 27.2.1(p.273).
- C2 See Pom 27.2.1(p.273) (b,c1) and Pom 27.2.2(p.276) (b,c2ii1,c2ii2).
- C3 See Pom 27.2.2(p.276) (c2ii2).
- C4 See Pom 27.2.1(p.273) (c2) and Pom 27.2.2(p.276) (c1,c2i).
- C5 See Pom 27.2.1(p.273) (a) and Pom 27.2.2(p.276) (a).

# Chapter 28

# Analysis of Model 2

#### 28.1 Search-Allowed-Model 2

#### 28.1.1 $\mathbf{r}\mathsf{M}:2[\mathbb{R}][\mathsf{A}]$

#### 28.1.1.1 Preliminary

Let us define

$$V_t^{\diamond}(y) \stackrel{\text{def}}{=} V_t(y) - y, \quad t \ge 0, \quad (\text{see } (26.2.7(\text{p.254})) \text{ and } (26.2.5(\text{p.254})))$$
 (28.1.1)

$$v_t^{\diamond}(y) \stackrel{\text{def}}{=} v_t(y) - y = \max\{0, V_t^{\diamond}(y)\}, \quad t \ge 0, \quad (\text{see } (26.2.8 \text{(p.254)})) \tag{28.1.2}$$

where

$$V_0^{\diamond}(y) = V_0(y) - y = \rho - y$$
 (see (26.2.7(p.254))), (28.1.3)

$$v_0^{\diamond}(y) = v_0(y) - y = \max\{0, \rho - y\} \quad (\text{see } (26.2.1 \text{(p.254)})).$$
 (28.1.4)

Then, from (26.2.5(p.254)) we have

$$\begin{split} V_{t}^{\diamond}(y) &= \max\{\lambda\beta \, \mathbf{E}[v_{t-1}^{\diamond}(\max\{\boldsymbol{\xi},y\}) + \max\{\boldsymbol{\xi},y\}] + (1-\lambda)\beta(v_{t-1}^{\diamond}(y)+y) - s, \beta(v_{t-1}^{\diamond}(y)+y)\} - y \\ &= \max\{\lambda\beta \, \mathbf{E}[v_{t-1}^{\diamond}(\max\{\boldsymbol{\xi},y\})] + (1-\lambda)\beta v_{t-1}^{\diamond}(y) + \lambda\beta \, \mathbf{E}[\max\{\boldsymbol{\xi},y\}] + (1-\lambda)\beta y - s, \beta v_{t-1}^{\diamond}(y) + \beta y\} - y \\ &= \max\{\lambda\beta \, \mathbf{E}[v_{t-1}^{\diamond}(\max\{\boldsymbol{\xi},y\})] + (1-\lambda)\beta v_{t-1}^{\diamond}(y) + K(y) + y, \beta v_{t-1}^{\diamond}(y) + \beta y\} - y \quad (\text{see } (6.1.10 (\text{p.25}))) \\ &= \max\{\lambda\beta \, \mathbf{E}[v_{t-1}^{\diamond}(\max\{\boldsymbol{\xi},y\})] + (1-\lambda)\beta v_{t-1}^{\diamond}(y) + K(y), \beta v_{t-1}^{\diamond}(y) - (1-\beta)y\}, \quad t > 0. \end{split}$$

By  $y_t^{\diamond}$  let us denote the solution of the equation  $V_t^{\diamond}(y) = 0$  for  $t \geq 0$  if it exists, i.e.,

$$V_t^{\diamond}(y_t^{\diamond}) = 0, \quad t > 0.$$
 (28.1.6)

If multiple solutions exist, it is defined to be the *smallest* of them. Let us define

$$\mathbb{V}_t \stackrel{\text{def}}{=} V_t - \beta V_{t-1}, \quad t > 0. \tag{28.1.7}$$

Then, from (26.2.12(p.254)) and (26.2.3(p.254)) we have

$$V_1 = V_1 - \beta V_0 = \max\{L(\rho), 0\}. \tag{28.1.8}$$

From (26.2.1(p.254)) and (26.2.3(p.254)) we have  $v_0(\xi) - V_0 = \max\{\xi, \rho\} - \rho = \max\{\xi - \rho, 0\}$ , hence from (26.2.17(p.254)) with t = 1 we get

$$\mathbb{S}_{1} = \lambda \beta \mathbf{E}[v_{0}(\xi) - V_{0}] - s 
= \lambda \beta \mathbf{E}[\max{\{\xi - \rho, 0\}}] - s 
= \lambda \beta T(\rho) - s = L(\rho) \text{ (see (6.1.1(p.25)) and (6.1.3(p.25)))}.$$
(28.1.9)

Now (26.2.23(p.255)) can be rewritten as

$$\mathbb{S}_{t}(y) = \lambda \beta \mathbf{E}[(v_{t-1}(\max\{\xi, y\}) - v_{t-1}(y))] - s 
= \lambda \beta \mathbf{E}[(v_{t-1}(\max\{\xi, y\}) - v_{t-1}(y))I(y < \xi) + (v_{t-1}(\max\{\xi, y\}) - v_{t-1}(y))I(\xi \le y)] - s 
= \lambda \beta \mathbf{E}[(v_{t-1}(\xi) - v_{t-1}(y))I(y < \xi) + (v_{t-1}(y) - v_{t-1}(y))I(\xi \le y)] - s 
= \lambda \beta \mathbf{E}[(v_{t-1}(\xi) - v_{t-1}(y))I(y < \xi)] - s.$$
(28.1.10)

From (26.2.1(p.254)) we have  $v_0(\xi) - v_0(y) = \max\{\xi, \rho\} - \max\{y, \rho\} \le \max\{\xi - y, 0\}$  for any  $\xi$  and y, hence from (28.1.10(p.277))with t = 1 we have

$$\mathbb{S}_1(y) = \lambda \beta \, \mathbf{E}[(v_0(\boldsymbol{\xi}) - v_0(y))I(y < \boldsymbol{\xi})] - s \le \lambda \beta \, \mathbf{E}[\max\{\boldsymbol{\xi} - y, 0\}I(y < \boldsymbol{\xi})] - s.$$

Then, since  $\max\{\xi - y, 0\} \ge 0$  and  $I(y < \xi) \le 1$ , we get  $\max\{\xi - y, 0\}I(y < \xi) \le \max\{\xi - y, 0\}$ , hence

$$S_1(y) \le \lambda \beta \mathbf{E}[\max\{\xi - y, 0\}] - s \tag{28.1.11}$$

$$= \lambda \beta T(y) - s = L(y) \text{ (see (6.1.1(p.25)) and (6.1.3(p.25)))}.$$
 (28.1.12)

# 28.1.1.2 Preliminary

#### Lemma 28.1.1 (rM: $2[\mathbb{R}][A]$ )

- (a)  $v_t(y)$  and  $V_t(y)$  are nondecreasing in y for  $t \geq 0$ .
- (b)  $V_t^{\diamond}(y)$  is nonincreasing in y for  $t \geq 0$ .  $\square$
- Proof (a) Clearly  $v_0(y)$  is nondecreasing in y from (26.2.1(p.254)). Suppose  $v_{t-1}(y)$  is nondecreasing in y. Then  $V_t(y)$  is nondecreasing in y from (26.2.5(p.254)), hence  $v_t(y)$  is nondecreasing in y from (26.2.8(p.254)). Thus by induction  $v_t(y)$  is nondecreasing in y for  $t \ge 0$ . Then  $v_{t-1}(y)$  is nondecreasing in y for t > 0, hence  $V_t(y)$  is also nondecreasing in y for t > 0 from (26.2.5(p.254)). In addition, since  $V_0(y)$  can be regarded as nondecreasing in y from (26.2.7(p.254)), it follows that  $V_t(y)$  is nondecreasing in y for  $t \ge 0$ .
- (b)  $V_0^{\diamond}(y)$  is nonincreasing in y from (28.1.3(p.277)). Suppose  $V_{t-1}^{\diamond}(y)$  is nonincreasing in y, hence  $v_{t-1}^{\diamond}(y)$  is also nonincreasing in y from (28.1.2(p.277)). In addition, since K(y) and  $-(1-\beta)y$  are both nonincreasing in y (see Lemma 11.2.2(p.57) (b)), it follows from (28.1.5(p.277)) that  $V_t^{\diamond}(y)$  is also nonincreasing in y. Thus, by induction  $V_t^{\diamond}(y)$  is also nonincreasing in y for  $t \geq 0$ .

If  $y < (\geq) \boldsymbol{\xi}$ , then  $v_{t-1}(\boldsymbol{\xi}) \geq (\leq) v_{t-1}(y)$  for t > 0 due to Lemma 28.1.1(p.278) (a) or equivalently  $v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y) \geq (\leq) 0$  for t > 0. Then, since

$$\max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\}$$

$$= \max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\} I(y < \boldsymbol{\xi}) + \max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\} I(y \ge \boldsymbol{\xi})$$

$$= (v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y)) I(y < \boldsymbol{\xi}) + 0 \times I(y \ge \boldsymbol{\xi})$$

$$= (v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y)) I(y < \boldsymbol{\xi}),$$

we can rewrite (28.1.10(p.277)) as

$$S_t(y) = \lambda \beta \mathbf{E}[\max\{v_{t-1}(\boldsymbol{\xi}) - v_{t-1}(y), 0\}] - s, \quad t > 0.$$
(28.1.13)

**Lemma 28.1.2** (rM:2[ $\mathbb{R}$ ][A]) Let  $\beta = 1$  or s = 0.

- (a) Let  $\beta = 1$ . Then  $y \leq V_t(y)$  for any y and t > 0.
- (b) Let s = 0. Then  $\mathbb{S}_t(y) \geq 0$  for any y and t > 0.  $\square$
- $\bullet \ \textit{Proof} \quad \text{(a)} \quad \text{If } \beta = 1, \text{ from } (26.2.5 \text{(p.254)}) \text{ and } (26.2.2 \text{(p.254)}) \text{ we have } V_t(y) \geq \beta v_{t-1}(y) = v_{t-1}(y) \geq y \text{ for any } y \text{ and any } t > 0.$ 
  - (b) If s = 0, from (28.1.13(p.278)) we have  $\mathbb{S}_t(y) = \beta \mathbf{E} [\max\{v_{t-1}(\boldsymbol{\xi}) v_{t-1}(y), 0\}] \ge 0$  for any y and t > 0.

**Lemma 28.1.3** (rM:2[ $\mathbb{R}$ ][A]) Let  $\beta < 1$  and s > 0.

- (a)  $\lim_{y\to-\infty} V_t^{\diamond}(y) = \infty \text{ for } t\geq 0.$
- (b)  $\lim_{y\to\infty} V_t^{\diamond}(y) = -\infty \text{ for } t>0.$
- (c) The solution  $y_t^{\diamond}$  exists for t > 0 such that
  - 1. Let  $y \ge y_t^{\diamond}$ . Then  $V_t(y) \le y$  for t > 0.
  - 2. Let  $y \leq y_t^{\diamond}$ . Then  $V_t(y) \geq y$  for t > 0.  $\square$
- Proof Let  $\beta < 1$  and s > 0.
- (a) Obviously  $V_0^{\diamond}(y) \to \infty$  as  $y \to -\infty$  from (28.1.3(p.277)). Suppose  $V_{t-1}^{\diamond}(y) \to \infty$  as  $y \to -\infty$ . Then  $v_{t-1}^{\diamond}(y) \to \infty$  as  $y \to -\infty$  from (28.1.2(p.277)). Hence, from (28.1.5(p.277)) we have  $V_t^{\diamond}(y) \to \infty$  as  $y \to -\infty$  due to the facts that  $K(y) \to \infty$  as  $y = -\infty$  due to (11.2.4 (1) (p.57)) and that  $-(1-\beta)y \to \infty$  as  $y \to -\infty$ . Thus, by induction  $V_{t-1}^{\diamond}(y) \to \infty$  as  $y \to -\infty$  for  $t \ge 0$ , i.e.,  $\lim_{y \to -\infty} V_t^{\diamond}(y) = \infty$  for  $t \ge 0$ .
- (b) Evidently  $v_0^{\diamond}(y) \to 0$  as  $y \to \infty$  from (28.1.4 (p.277)). Suppose  $v_{t-1}^{\diamond}(y) \to 0$  as  $y \to \infty$ . Noting that  $K(y) \to -\infty$  as  $y \to \infty$  from (11.2.5 (2) (p.57)) and that  $-(1-\beta)y \to -\infty$  as  $y \to \infty$ , from (28.1.5 (p.277)) we have  $V_t^{\diamond}(y) \to -\infty$  for  $t \ge 0$  as  $y \to \infty$ . Hence, from (28.1.2 (p.277)) we have  $v_t^{\diamond}(y) \to 0$  as  $y \to \infty$ . Thus, by induction  $v_t^{\diamond}(y) \to 0$  for any  $t \ge 0$  as  $y \to \infty$ , hence  $v_{t-1}^{\diamond}(y) \to 0$  for any t > 0 as  $y \to \infty$ . Then, for the same reason as just above we have  $V_t^{\diamond}(y) \to -\infty$  for t > 0 as  $y \to \infty$ , i.e.,  $\lim_{y \to \infty} V_t^{\diamond}(y) = -\infty$  for t > 0.
- (c) From (a,b) and Lemma 28.1.1(p.278) (b) we see that there exists the solution  $y_t^{\diamond}$ , and then clearly we have  $\geq (\leq) y_t^{\diamond} \Rightarrow V_t^{\diamond}(y) \leq (\geq) 0 \Leftrightarrow V_t(y) \leq (\geq) y$  for t > 0 from (28.1.1(p.277)).

**Lemma 28.1.4** (rM:2[ $\mathbb{R}$ ][A]) Let  $\beta < 1$  and s > 0.

- (a) Let  $y \leq 0$ . Then  $V_t(y) \geq y$  for t > 0.
- (b) Let y > 0.
  - 1. Let  $y \ge y_t^{\diamond}$ . Then  $V_t(y) \le y$  for t > 0,
  - 2. Let  $y \leq y_t^{\diamond}$ . Then  $V_t(y) \geq y$  for t > 0

where  $y_t^{\diamond} \geq 0$  for t > 0.

- Proof Let  $\beta < 1$  and s > 0. Since  $V_1(y) \ge K(\max\{y, \rho\}) + \max\{y, \rho\}$  for any y from (26.2.14(p.254)) and since  $\max\{y, \rho\} \ge y$  for any y, we obtain  $V_1(y) \ge K(y) + y \cdots (1)$  for any y due to Lemma 11.2.2(p.57) (e).
- (a) Let  $y \le 0 \cdots (2)$ . Since  $V_t(y) \ge \beta v_{t-1}(y)$  for t > 0 from (26.2.5(p.254)) and since  $v_{t-1}(y) \ge y$  for t > 0 from (26.2.2(p.254)), we have  $V_t(y) \ge \beta v_{t-1}(y) \ge \beta y$  for t > 0. Then, since  $\beta y \ge y$  due to (2), we have  $V_t(y) \ge y$  for t > 0.
  - (b) Let  $y > 0 \cdots (3)$ .
  - (b1,b2) The same as Lemma 28.1.3(p.278) (c1,b1).  $\blacksquare$

# **28.1.1.3** Analysis

- $\blacksquare$  Tom 28.1.1 ( $\mathscr{A}\{rM:2[\mathbb{R}][A]\}$ )
- (a) Let s = 0. Then  $rM:2[\mathbb{R}][A] \hookrightarrow rM:2[\mathbb{R}][E]$ .
- (b) Let  $\beta = 1$ .
  - 1. We have  $y \leq V_t(y)$  for any y and  $t \geq 0$ .
  - 2. We have the future-subject  $\mathbb{F}.\mathbb{S}.$  3 (the conditions for  $\mathbb{S}$ ,  $\mathbb{O}$ , and  $\mathbb{O}$ )
- (c) Let  $\beta < 1$  and s > 0.
  - 1. We have  $\bigcirc$  dOITs  $_{\tau \geq 0}\langle \tau \rangle$   $_{\triangle}$ .
  - 2. Let  $y \leq 0$ . Then  $y \leq V_t(y)$  for  $t \geq 0$ .
  - 3. Let  $y \ge 0$ .
    - i.  $\blacktriangle Let \ y \geq y_t^{\diamond}$ . Then  $V_t(y) \leq y$  for  $t \geq 0$ .
    - ii.  $\bullet$  Let  $y \leq y_t^{\diamond}$ . Then  $y \leq V_t(y)$  for  $t \geq 0$ .  $\square$
- Proof (a) Let s=0. Then, from Lemma 28.1.2(p.278) (b) we see that it is always optimal to Conduct<sub>t</sub> the search due to (26.2.25(p.255)), implying that  $rM:2[\mathbb{R}][A]$ , which is originally a search-Allowed-model, is substantially reduced to  $rM:2[\mathbb{R}][E]$ , which is a search-Enforced-model. In other words,  $rM:2[\mathbb{R}][A]$  migrates to  $rM:2[\mathbb{R}][E]$ , represented as  $rM:2[\mathbb{R}][A] \hookrightarrow rM:2[\mathbb{R}][E]$  (see Def. 12.2.2(p.63)).
  - (b) Let  $\beta = 1$ .
  - (b1) The same as Lemma 28.1.2(p.278) (a).
  - (b2) The subject of future study—
  - (c) Let  $\beta < 1$  and s > 0.
- (c1) From (26.2.4(p.254)) we have  $V_t \geq \beta V_{t-1}$  for  $\tau \geq t > 0$ , hence  $V_{\tau} \geq \beta V_{\tau-1}$ ,  $V_{\tau-1} \geq \beta V_{t-2}$ ,  $\cdots$ ,  $V_1 \geq \beta V_0$ , so  $V_{\tau} \geq \beta V_{\tau-1} \geq \beta^2 V_{t-2} \geq \cdots \geq \beta^{\tau} V_0$ . Accordingly, we have  $t_{\tau}^* = \tau$  for  $\tau \geq 0$ , i.e.,  $\boxed{\$ \text{ dOITs}_{\tau \geq 0} \langle \tau \rangle}_{\Delta}$ .
  - (c2) The same as Lemma 28.1.4(p.278) (a).
  - (c3-c3ii) The same as Lemma 28.1.4(p.278) (b-b2).  $\blacksquare$

#### 28.1.1.4 Flow of Optimal Decision Rules

- ♣ Flow-ODR 9 (rM:2[ℝ][A]) (Accept₀(y)⊳Stop) Let β = 1. Then, the inequality  $y \le V_t(y)$  for any y and  $t \ge 0$  (see Tom 28.2.1(p.28) (♣a1)) means that even if the process is initiated at any time t, it is optimal to reject the best price y at that time. Accordingly, it follows that each time a price  $\xi$  is proposed, the current best price y continues to be enlarged to  $y \stackrel{\text{def}}{=} \max\{y, \xi\}$ , and the process terminates by accepting the best price y at the deadline t = 0, i.e., Accept₀(y)⊳Stop.  $\square$
- ♣ Flow-ODR 10 (rM:2[R][A]) (t-reservation-price) Let  $\beta$  < 1 or s > 0. Then, from Tom 28.1.1(p.279) (♠c3i,♠c3ii) and (26.2.29(p.255)) we have the following relations for  $\tau \ge t \ge 0$ :

Namely, the optimal reservation value is given by  $y_t^{\diamond}$ , which is constant in t.  $\square$ 

## 28.1.1.5 Market Restriction

#### 28.1.1.5.1 Positive Restriction

- $\square$  Pom 28.1.1 ( $\mathscr{A}\{\mathbf{rM}:2[\mathbb{R}][\mathbb{A}]\}^+$ ) Suppose a>0.
- (a) Let s = 0. Then  $rM:2[\mathbb{R}][A]^+ \hookrightarrow M:2[\mathbb{R}][E]^+$ .
- (b) Let  $\beta = 1$ .
  - 1. We have  $odr \mapsto Accept_0(y) \triangleright Stop$ .
  - 2. We have the same unsolved subject as F.S 3(p.279) (the conditions for (S), ( $\odot$ ), and ( $\odot$ ).
- (c) Let  $\beta < 1$  and s > 0.
  - 1. We have  $\boxed{\$ dOITs_{\tau \geq 0} \langle \tau \rangle} \rightarrow$

 $\rightarrow$  (s)

- $2. \hspace{0.5cm} We \hspace{0.1cm} have \hspace{0.1cm} t\text{-reservation-price}.$
- Proof Suppose a > 0. Then it suffices to consider only y with y > a > 0.
  - (a) The same as Tom 28.1.1(p.279) (a).
  - (b) Let  $\beta = 1$ .
  - (b1) Clear from \*Flow-ODR 9.
  - (b2) The subject of future study ——
  - (c) Let  $\beta < 1$  and s > 0.
  - (c1) The same as Tom 28.1.1(p.279) (c1).
  - (c2) Clear from Tom 28.1.1(p.279) (♠c3i,♠c3ii). ■

#### 28.1.1.5.2 Mixed Restriction

Omitted.

# 28.1.1.5.3 Negative Restriction

Omitted.

# **28.1.2** $\tilde{rM}:2[\mathbb{R}][A]$

# **28.1.2.1** Derivation of $\mathscr{A}\{\tilde{rM}:2[\mathbb{R}][A]\}$

For almost the same reason as in Section 27.2.2.1(p.274) it can be confirmed that  $SOE[rM:2[\mathbb{R}][A]]$  (see (26.2.35(p.255))) is symmetrical to  $SOE[rM:2[\mathbb{R}][A]]$  (see (26.2.6(p.254))). This results implies that applying  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Tom 28.1.1(p.279) for  $rM:2[\mathbb{R}][E]$  (selling model) yields lemmas for  $r\tilde{M}:2[\mathbb{R}][E]$  (buying model).

- $\square$  Tom 28.1.1 ( $\mathscr{A}\{r\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{A}]\}$ )
- (a) Let s = 0. Then  $r\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{A}] \hookrightarrow r\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]$ .
- (b) Let  $\beta = 1$ .

  - 2. We have the same unsolved subject as F.S. 3(p.279).
- (c) Let  $\beta < 1$  and s > 0.
  - 1. We have star doing = 0 doing triangle = 0 doing triangle = 0.

  - 3. Let  $y \leq 0$ .
    - i.  $\bullet$  Let  $y \leq \tilde{y}_t^{\diamond}$ . Then  $y \leq V_t(y)$  for  $t \geq 0$ .
    - ii.  $\blacktriangle Let \ y \geq \tilde{y}_t^{\diamond}$ . Then  $y \geq V_t(y)$  for  $t \geq 0$ .  $\square$
- Proof by symmetry Obtained by applying  $S_{\mathbb{R}\to\tilde{\mathbb{R}}}$  to Tom 28.1.1(p.279).

# 28.1.2.2 Flow of Optimal Decision Rules

- ♣ Flow-ODR 11 (rM:2[R][E]) (Accept<sub>0</sub>(y) ▷ Stop) Let  $\beta = 1$  (see Tom 28.1.1(p.280) (♣b1)). Then, the inequality  $y \ge V_t(y)$  for any y and  $t \ge 0$  means that even if the process is initiated at any time t, it is optimal to reject the best price y at that time. Accordingly, it follows that each time a price  $\xi$  is proposed, the current best price y continues to be reduced to  $y \stackrel{\text{def}}{=} \min\{y, \xi\}$ , and the process terminates by accepting the best price y at the deadline t = 0, i.e., Accept<sub>0</sub>(y) ▷ Stop.  $\square$
- ♣ Flow-ODR 12 (rM:2[ $\mathbb{R}$ ][ $\mathbb{E}$ ]) (t-reservation-price) Let  $\beta < 1$  and s > 0 and let  $y \leq 0$ . Then, from Tom 28.1.1( $\mathbb{P}$ 280) (♣c3i,♠c3ii) and (26.2.50( $\mathbb{P}$ 256)) we have the following relations for  $\tau \geq t \geq 0$ :

Namely, the optimal reservation value is given by  $\tilde{y}_t^{\diamond}$ , which is constant in t.  $\square$ 

#### 28.1.2.3 Market Restriction

# 28.1.2.3.1 Positive Restriction

- $\square$  Pom 28.1.2  $(\mathscr{A}\{\mathbf{r}\tilde{\mathsf{M}}:2[\mathbb{R}][\mathbb{A}]^+\})$  Suppose a>0.
- (a) Let s = 0. Then  $r\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{A}]^+ \hookrightarrow r\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]^+$ .
- (b) Let  $\beta = 1$ .
  - 1.  $\bullet$  We have odr  $\mapsto$  Accept<sub>0</sub>(y)  $\triangleright$  Stop.
  - 2. We have the same unsolved subject as  $\overline{\text{F.S.}}$  3(p.279).
- (c) Let  $\beta < 1$  and s > 0.

1. We have 
$$\boxed{\$ dOITs_{\tau \geq 0}\langle \tau \rangle}_{\vartriangle} \rightarrow \bigcirc$$

- 2.  $\bullet$  We have odr  $\mapsto$  Accept<sub>0</sub>(y)  $\triangleright$  Stop.
- Proof Suppose a > 0. Then it suffices to consider only y > a > 0.
  - (a) The same as Tom 28.1.1(p.280) (a).
  - (b) Let  $\beta = 1$ .
  - (b1) Immediate from Tom 28.1.1(p.280) (\*b1) and \*Flow-ODR 11(p.280).
  - (b2) The subject of future study —
  - (c) Let  $\beta < 1$  and s > 0.
  - (c1) The same as Tom 28.1.1(p.280) (c1).
  - (c2) Immediate Tom 28.1.1(p.280) (\*c2) and \*Flow-ODR 9.

#### 28.1.2.3.2 Mixed Restriction

Omitted.

# 28.1.2.3.3 Negative Restriction

Omitted.

# 28.1.3 Conclusion 9 (Search-Allowed-Model 2)

The following six cases are possible:

- C1 We have  $\mathscr{A}\{\tilde{rM}:2[\mathbb{R}][A]\}^+ \wedge \mathscr{A}\{\tilde{rM}:2[\mathbb{R}][A]\}^+$ .
- C2 We have  $rM/\tilde{M}:2[\mathbb{R}][A]^+ \hookrightarrow rM/\tilde{M}:2[\mathbb{R}][E]^+$ .
- C3 We have  $(s)_{\Delta}$  for  $rM/\tilde{M}:2[\mathbb{R}][A]^+$ .
- C4 We have odr  $\mapsto Accept_0(y) \triangleright Stop \text{ for } rM/\tilde{M}:2[\mathbb{R}][A]^+ \text{ (i.e., } \bullet \text{)}.$
- C5 We have t-reservation-price for rM:2[ $\mathbb{R}$ ][ $\mathbb{A}$ ]<sup>+</sup>.
- C6 We have the future subject [F.S] 3.

C1	Compare Pom 28.1.2(p.280)	and Pom 28.1.1(p.279)	١.
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- C2 See Pom 28.1.1(p.279) (a) and Pom 28.1.2(p.280) (a).
- C3 See Pom 28.1.1(p.279) (c1) and Pom 28.1.2(p.280) (c1).
- C4 See Pom 28.1.1(p.279) (b1) and Pom 28.1.2(p.280) (b1,c2).
- C5 See Pom 28.1.1(p.279) (c2).
- C6 See Pom 28.1.1(p.279) (b2) and Pom 28.1.2(p.280) (b2).

# 28.2 Search-Enforced-Model 2

# **28.2.1** $rM:2[\mathbb{R}][E]$

#### 28.2.1.1 Preliminary

Let us define

$$v_t^{\diamond}(y) = v_t(y) - y, \quad t \ge 0,$$
 (28.2.1)

$$V_t^{\diamond}(y) = V_t(y) - y, \quad t \ge 0.$$
 (28.2.2)

Then, from (26.2.58(p.256)) we have

$$v_t^{\diamond}(y) = \max\{0, V_t^{\diamond}(y)\} \ge 0, \quad t \ge 0,$$
 (28.2.3)

where

$$v_0^{\diamond}(y) = v_0(y) - y = \max\{0, \rho - y\} \quad (\text{see } (26.2.51(\text{p.256}))),$$
 (28.2.4)

$$V_0^{\diamond}(y) = V_0(y) - y = \rho - y \quad (\text{see } (26.2.57(p.256)))$$
 (28.2.5)

Furthermore, from (26.2.55(p.256)) we have

$$\begin{split} V_{t}^{\diamond}(y) &= \lambda \beta \, \mathbf{E}[v_{t-1}^{\diamond}(\max\{\boldsymbol{\xi},y\}) + \max\{\boldsymbol{\xi},y\}] + (1-\lambda)\beta(v_{t-1}^{\diamond}(y)+y) - s - y \\ &= \lambda \beta \, \mathbf{E}[v_{t-1}^{\diamond}(\max\{\boldsymbol{\xi},y\})] + (1-\lambda)\beta \, v_{t-1}^{\diamond}(y) + \lambda \beta \, \mathbf{E}[\max\{\boldsymbol{\xi},y\}] + (1-\lambda)\beta y - s - y \\ &= \lambda \beta \, \mathbf{E}[v_{t-1}^{\diamond}(\max\{\boldsymbol{\xi},y\})] + (1-\lambda)\beta \, v_{t-1}^{\diamond}(y) + K(y) + y - y \quad t > 0 \quad (\leftarrow (6.1.10 \text{(p.25)})) \\ &= \lambda \beta \, \mathbf{E}[v_{t-1}^{\diamond}(\max\{\boldsymbol{\xi},y\})] + (1-\lambda)\beta \, v_{t-1}^{\diamond}(y) + K(y), \quad t \ge 0. \end{split} \tag{28.2.6}$$

By  $y_t^{\diamond}$  let us denote the solution of the equation  $V_t^{\diamond}(y) = 0$  if it exists, i.e.,

$$V_t^{\diamond}(y_t^{\diamond}) = 0, \quad t > 0.$$
 (28.2.7)

If multiple solutions exist, it is defined to be the smallest of them.

# 28.2.1.2 Lemmas

Lemma 28.2.1 (rM:2[R][E])

- (a)  $v_t(y)$  and  $V_t(y)$  are nondecreasing in y for  $t \geq 0$ .
- (b)  $V_t^{\diamond}(y)$  is nonincreasing in y for  $t \geq 0$ .  $\square$

- Proof (a)  $v_0(y)$  is nondecreasing in y from (26.2.51(p.256)). Suppose  $v_{t-1}(y)$  is nondecreasing in y. Then  $V_t(y)$  is nondecreasing in y from (26.2.55(p.256)), hence  $v_t(y)$  is also nondecreasing in y from (26.2.58(p.256)). Thus, by induction  $v_t(y)$  is nondecreasing in y for  $t \ge 0$ . Then  $v_{t-1}(y)$  is nondecreasing in y for t > 0, hence  $V_t(y)$  is also nondecreasing in y for t > 0 from (26.2.55(p.256)). In addition, since  $V_0(y)$  can be regarded as nondecreasing in y from (26.2.57(p.256)), it follows that  $V_t(y)$  is nondecreasing in y for t > 0.
- (b)  $V_0^{\diamond}(y)$  is nonincreasing in y from (28.2.4(p.281)). Suppose  $V_{t-1}^{\diamond}(y)$  is nonincreasing in y, hence  $V_{t-1}^{\diamond}(y)$  is also nonincreasing in y from (28.2.3(p.281)). Accordingly, from (28.2.6(p.281)) and Lemma 11.2.2(p.57) (b)) we see that  $V_t^{\diamond}(y)$  is also nonincreasing in y. This completes the induction.

**Lemma 28.2.2** (rM:2[ $\mathbb{R}$ ][ $\mathbb{E}$ ]) Let  $\beta = 1$  and s = 0. Then  $V_t(y) \geq y$  for any y and t > 0.  $\square$ 

● Proof Let  $\beta = 1$  and s = 0, hence  $K(y) = \lambda T(y)$  from (6.1.4(p.25)). Then, from (28.2.6(p.281)) we have  $V_t^{\diamond}(y) = \lambda \mathbf{E}[v_{t-1}^{\diamond}(\max\{\boldsymbol{\xi},y\})] + (1-\lambda)v_{t-1}^{\diamond}(y) + \lambda T(y)$  for  $t \geq 0$ . Now, for any  $\boldsymbol{\xi}$  and y we have that  $v_{t-1}^{\diamond}(\max\{\boldsymbol{\xi},y\}) \geq 0$  and  $v_{t-1}^{\diamond}(y) \geq 0$  for t > 0 from (28.2.3(p.281)) and that  $T(y) \geq 0$  due to Lemma 11.1.1(p.55)(g), hence it follows that  $V_t^{\diamond}(y) \geq 0$  for any y and t > 0 or equivalently  $V_t(y) \geq y$  for any y and t > 0 from (28.2.2(p.281)). ■

**Lemma 28.2.3** (rM:2[ $\mathbb{R}$ ][E]) Let  $\beta < 1$  or s > 0.

- (a)  $\lim_{y\to-\infty} V_t^{\diamond}(y) = \infty \text{ for } t \geq 0.$
- (b)  $\lim_{y\to\infty} V_t^{\diamond}(y) < 0 \text{ for } t > 0.$
- (c) The sequence  $y_1^{\diamond}, y_2^{\diamond}, \cdots$  exists where

$$y \le (\ge) y_t^{\diamond} \Rightarrow V_t^{\diamond}(y) \ge (\le) 0. \quad \Box$$
 (28.2.8)

- Proof Let  $\beta < 1$  or s > 0.
- (a) We have  $V_0^{\diamond}(y) \to \infty$  as  $y \to -\infty$  from (28.2.5(p.281)). Suppose  $V_{t-1}^{\diamond}(y) \to \infty$  as  $y \to -\infty$ . Then  $v_{t-1}^{\diamond}(y) \to \infty$  as  $y \to -\infty$  from (28.2.3(p.281)). In addition, since  $K(y) \to \infty$  as  $y = -\infty$  due to (11.2.4(1)(p.57)), from (28.2.6(p.281)) we see that  $V_t^{\diamond}(y) \to \infty$  as  $y \to -\infty$ . This completes the induction.
- (b) We have  $v_0^{\diamond}(y) \to 0$  as  $y \to \infty$  from (28.2.4(p.281)). Suppose  $v_{t-1}^{\diamond}(y) \to 0$  as  $y \to \infty$ . Then, the first and second terms of the right-hand side of (28.2.6(p.281)) converge to 0 as  $y \to \infty$ . In addition, due to (11.2.5 (2) (p.57)), if  $\beta = 1$ , then s > 0 due to the assumption " $\beta < 1$  or s > 0", hence K(y) = -s < 0 for any y and if  $\beta < 1$ , then  $K(y) \to -\infty < 0$  as  $y \to \infty$ , so  $\lim_{y \to \infty} K(y) < 0$  whether  $\beta = 1$  or  $\beta < 1$ . Hence, it follows that  $\lim_{y \to \infty} V_t^{\diamond}(y) < 0$ . Thus, from (28.2.3(p.281)) we have  $v_t^{\diamond}(y) \to 0$  as  $y \to \infty$ . Hence, by induction we have  $v_t^{\diamond}(y) \to 0$  as  $y \to \infty$  for  $t \ge 0$ . Accordingly, since  $v_{t-1}^{\diamond}(y) \to 0$  as  $y \to \infty$  for t > 0, for quite the same reason as the above we have  $\lim_{y \to \infty} V_{t-1}^{\diamond}(y) < 0$  for t > 0.
  - (c) Immediate from (a,b) and Lemma 28.2.1(p.281) (b).

**Lemma 28.2.4** (rM:2[ $\mathbb{R}$ ][E]) Let  $\rho \leq x_K$ . Then for any  $y \in [a,b]$  we have:

- (a)  $v_t(y)$  and  $V_t(y)$  are nondecreasing in  $t \geq 0$ .
- (b)  $v_t(y)$  and  $V_t(y)$  converges to finite v(y) and V(y) respectively as  $t \to \infty$ .
- (c)  $V_t^{\diamond}(y)$  is nondecreasing in  $t \geq 0$ .
- (d)  $y_t^{\diamond}$  is nondecreasing in t > 0.
- (e)  $V_t$  is nondecreasing in  $t \geq 0$ .
- Proof Let  $\rho \leq x_K$  and consider only  $y \in [a,b] \cdots (1)$ . Then  $K(\rho) \geq 0 \cdots (2)$  from Corollary 11.2.2(p.58) (b).
- (a) Since  $\max\{y,\rho\} \ge \rho$  for any y, from (26.2.61(p.256)) and Lemma 11.2.2(p.57) (e) we have  $V_1(y) \ge K(\rho) + \rho \ge \rho \cdots$  (3) due to (2). Hence, from (26.2.52(p.256)) with t=1 we have  $v_1(y) = \max\{y,V_1(y)\} \ge \max\{y,\rho\} = v_0(y)$  for any y from (26.2.51(p.256)). Suppose  $v_{t-1}(y) \ge v_{t-2}(y)$  for any y. Then, from (26.2.55(p.256)) we have  $V_t(y) \ge \lambda\beta \mathbf{E}[v_{t-2}(\max\{\boldsymbol{\xi},y\})] + (1-\lambda)\beta v_{t-2}(y) s = V_{t-1}(y)$  for any y. Hence, from (26.2.58(p.256)) we have  $v_t(y) \ge \max\{y,V_{t-1}(y)\} = v_{t-1}(y)$  for any y. Thus, by induction  $v_t(y)$  is nondecreasing in  $t \ge 0$  for any y. Then  $v_{t-1}(y)$  is nondecreasing in t > 0 for any y, hence  $V_t(y)$  is nondecreasing in  $t \ge 0$  for any y. From (3) and (26.2.57(p.256)) we have  $V_1(y) \ge V_0(y)$ . Accordingly, it follows that  $V_t(y)$  is nondecreasing in  $t \ge 0$  for any y.
- (b) Below let us consider only  $y \in [a,b]$  and  $\boldsymbol{\xi} \in [a,b]^{\dagger}$ ; in addition, consider a sufficiently large M>0 such that  $b\leq M$  and  $\rho\leq M$ . Then we have  $V_0(y)\leq M$  from (26.2.57(p.256)). Suppose  $V_{t-1}(y)\leq M\cdots(4)$  for any  $y\in [a,b]$ , hence from (26.2.52(p.256)) we have  $v_{t-1}(y)\leq \max\{M,M\}=M$  and  $\max\{\boldsymbol{\xi},y\}\in [a,b]$ , we have  $V_{t-1}(\max\{\boldsymbol{\xi},y\})\leq M$  due to (4). Thus, from (26.2.52(p.256)) we have  $v_{t-1}(\max\{\boldsymbol{\xi},y\})=\max\{\max\{\boldsymbol{\xi},y\},V_{t-1}(\max\{\boldsymbol{\xi},y\})\}\leq \max\{M,M\}=M$ . Hence, from (26.2.55(p.256)) we have  $V_t(y)\leq \lambda\beta \mathbf{E}[M]+(1-\lambda)\beta M-s=\lambda\beta M+(1-\lambda)\beta M-s=\beta M-s\leq M$ , i.e.,  $V_t(y)$  is upper bounded in t. Accordingly, due to (a) it follows that  $V_t(y)$  converge to a finite V(y) as  $t\to\infty$ .
  - (c) Immediate from (28.2.2(p.281)) and (a).
  - (d) Evident from Lemma 28.2.1(p.281) (b), Lemma 28.2.4(p.282) (c), and Lemma 28.2.3(p.282) (c) (see Figure A 7.2(p.323) (I)).
- (e) From (26.2.59(p.256)) and (2) we have  $V_1 \ge \rho = V_0$  from (26.2.53(p.256)). Suppose  $V_{t-1} \ge V_{t-2}$ . Since  $v_{t-1}(\boldsymbol{\xi}) \ge v_{t-2}(\boldsymbol{\xi})$  for any  $\boldsymbol{\xi}$  due to (a), from (26.2.54(p.256)) we have  $V_t \ge \lambda \beta \mathbf{E}[v_{t-2}(\boldsymbol{\xi})] + (1-\lambda)\beta V_{t-2} s = V_{t-1}$ . This completes the induction.

**Lemma 28.2.5** (rM:2[ $\mathbb{R}$ ][ $\mathbb{E}$ ]) Let  $\beta < 1$  or s > 0.

 $<sup>^{\</sup>dagger}a \leq y \leq b \leq M$  and  $a \leq \xi \leq b \leq M$ .

- (a) Let  $y \ge y_t^{\diamond}$ . Then  $y \ge V_t(y)$  for t > 0.
- (b) Let  $y \leq y_t^{\diamond}$ . Then  $y \leq V_t(y)$  for t > 0.  $\square$
- *Proof* The same as Lemma 28.2.3(p.282) (c) and (28.2.2(p.281)).

From (26.2.63(p.256)) and the two inequalities in Tom 28.2.5(p.282) (a,b) we have the following decision rule:

#### 28.2.1.3 Analysis

 $\blacksquare$  Tom 28.2.1 ( $\mathscr{A}\{rM:2[\mathbb{R}][E]\}$ )

- (a) Let  $\beta = 1$  and s = 0.
  - 1. We have  $y \leq V_t(y)$  for any y and  $t \geq 0$ .
  - 2. We have the future subject  $\boxed{\text{F.S.}}$  4 (the conditions for  $\boxed{\$}$ ,  $\boxed{\$}$ , and  $\boxed{\$}$ ).
- (b) Let  $\beta < 1$  or s > 0.
  - 1.  $\blacktriangle Let \ y \ge y_t^{\diamond}$ . Then  $y \ge V_t(y)$  for  $t \ge 0$ .
  - 2.  $\blacktriangle Let \ y \leq y_t^{\diamond}$ . Then  $y \leq V_t(y)$  for  $t \geq 0$ .
  - 3. We have the future subject  $\overline{\text{F.S.}}$  5 (the conditions for  $\overline{\text{(s)}}$ ,  $\overline{\text{(o)}}$ , and  $\overline{\text{(d)}}$ ).  $\Box$
- Proof (a) Let  $\beta = 1$  and s = 0.
  - (a1) The same as Lemma 28.2.2(p.282).
  - (a2) The subject of future study——
  - (b) Let  $\beta < 1$  or s > 0.
  - (b1,b2) The same as Lemma 28.2.5(p.282).
  - (b3) The subject of future study——

#### 28.2.1.4 Flow of Optimal Decision Rules

- ♣ Flow-ODR 13 (rM:2[R][E]) (Accept₀(y) ▷ Stop) Let β = 1 and s = 0 (see Tom 28.2.1(p.28) (♣a1)). Then, the inequality  $y ext{ ≤ } V_t(y)$  for any y and  $t ext{ ≥ 0 means that even if the process is initiated at any time t, it is optimal to reject the best price y at that time. Accordingly, it follows that each time a price <math>\xi$  is proposed, the current best price y continues to be enlarged to  $y \stackrel{\text{def}}{=} \max\{y, \xi\}$ , and the process terminates by accepting the best price y at the deadline t = 0, i.e., Accept₀(y) ▷ Stop. □
- ♦ Flow-ODR 14 (rM:2[ $\mathbb{R}$ ][E]) (t-reservation-price) Let  $\beta < 1$  or s > 0. Then, from Tom 28.2.1(p.283) (♠ b1,♠ b2)

and (26.1.25(p.252)) we have the following relations for  $\tau \geq t \geq 0$ :

$$\left\{ \begin{aligned} y &\geq y_t^{\diamond} \ \Rightarrow \ \mathsf{Accept}_t \langle y \rangle \ and \ the \ process \ stops \ \mathbf{I} \\ y &\leq y_t^{\diamond} \ \Rightarrow \ \mathsf{Reject}_t \langle y \rangle \ and \ \mathsf{Conduct}_t / \mathsf{Skip}_t \end{aligned} \right.$$

Namely, the optimal reservation value is given by  $y_t^{\diamond}$ , which is constant in t.

#### 28.2.1.5 Market Restriction

# 28.2.1.5.1 Positive Restriction

- $\square$  Pom 28.2.1 ( $\mathscr{A}\{\mathbf{rM}:2[\mathbb{R}][\mathsf{E}]\}^+$ ) Suppose a>0.
- (a) Let  $\beta = 1$  and s = 0.
  - 1. We have  $Accept_0(y) \triangleright Stop$  (see  $\clubsuit Flow-ODR$  13).
  - 2. We have the same unsolved subject as  $\overline{\text{F.S.}}$  4(p.283).
- (b) Let  $\beta < 1$  or s > 0.
  - 1. We have t-reservation-price (see \*Flow-ODR 14).
  - 2. We have the same unsolved subject as  $\overline{\text{F.S.}}$  5(p.283).  $\square$
- *Proof* Suppose a > 0.
  - (a) Let  $\beta = 1$  and s = 0.
  - (a1) Obvious from Tom 28.2.1(p.283) (\*a1).
  - (a2) The subject of future study—
  - (b) Let  $\beta < 1$  or s > 0.
  - (b1) Evident from Tom 28.2.1(p.283) (♠b1,♠b2). ■
  - (b2) The subject of future study——  $\blacksquare$

#### 28.2.1.5.2 Mixed Restriction

Omitted.

#### 28.2.1.5.3 Negative Restriction

Unnecessary.

# **28.2.2** $r\tilde{M}:2[\mathbb{R}][E]$

#### 28.2.2.1 Preliminary

Let us define

$$\tilde{v}_t^{\diamond}(y) = v_t(y) - y, \quad t \ge 0,$$
(28.2.10)

$$\tilde{V}_t^{\diamond}(y) = V_t(y) - y, \quad t \ge 0.$$
 (28.2.11)

Then, from (26.2.71(p.257)) we have

$$\tilde{v}_t^{\diamond}(y) \; = \; \min\{0, \tilde{V}_t^{\diamond}(y)\}, \quad t \geq 0. \tag{28.2.12}$$

By  $\tilde{y}_t^{\diamond}$  let us denote the solution of the equation  $\tilde{V}_t^{\diamond}(y) = 0, t > 0$ , it exists, i.e.,

$$\tilde{V}_t^{\diamond}(\tilde{y}_t^{\diamond}) = 0. \tag{28.2.13}$$

If multiple solutions exist, it is defined to be the largest of them. Now, we have

$$\tilde{v}_0^{\diamond}(y) = \min\{0, \rho - y\} \quad (\leftarrow (26.2.64(p.256))), \tag{28.2.14}$$

$$\tilde{V}_{0}^{\diamond}(y) = \rho - y \quad (\leftarrow (26.2.70 \text{(p.257)})). \tag{28.2.15}$$

**Lemma 28.2.6**  $(\mathbf{r}\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}])$  We have  $\tilde{y}_t^{\diamond} = \hat{y}_t^{\diamond} (=-y_t^{\diamond})$  for t>0 (see (28.2.7(p.281)) for  $y_t^{\diamond}$ ).

• Proof First, note that (26.2.68(p.257)) can be rewritten as follows.

$$V_t(y) = \lambda \beta \int_{-\infty}^{\infty} v_{t-1}(\min\{\xi, y\}) f(\xi) d\xi + (1 - \lambda) \beta v_{t-1}(y) + s, \quad t > 0.$$

Next, replacing  $f(\xi)$  in the above expression by  $\check{f}(\hat{\xi})$  (see (13.1.8(p.69))) leads to

$$\begin{split} V_{t}(y) &= \lambda \beta \int_{-\infty}^{\infty} v_{t-1}(\min\{\xi, y\}) \check{f}(\hat{\xi}) d\xi + (1 - \lambda) \beta v_{t-1}(y) + s \\ &= \lambda \beta \int_{-\infty}^{\infty} v_{t-1}(\min\{-\hat{\xi}, -\hat{y}\}) \check{f}(\hat{\xi}) d\xi + (1 - \lambda) \beta v_{t-1}(y) + s \\ &= \lambda \beta \int_{-\infty}^{\infty} v_{t-1}(-\max\{\hat{\xi}, \hat{y}\}) \check{f}(\hat{\xi}) d\xi + (1 - \lambda) \beta v_{t-1}(y) + s, \quad t > 0. \end{split}$$

Then, let  $\eta \stackrel{\text{def}}{=} \hat{\xi} = -\xi$ , hence  $d\eta = -d\xi$ . Then, the above expression can be rearranged as

$$\begin{split} V_{t}(y) &= -\lambda \beta \int_{\infty}^{-\infty} v_{t-1}(-\max\{\eta, \hat{y}\}) \check{f}(\eta) d\eta + (1-\lambda) \beta v_{t-1}(y) + s \\ &= \lambda \beta \int_{-\infty}^{\infty} v_{t-1}(-\max\{\eta, \hat{y}\}) \check{f}(\eta) d\eta + (1-\lambda) \beta v_{t-1}(y) + s \\ &= \lambda \beta \int_{-\infty}^{\infty} v_{t-1}(-\max\{\xi, \hat{y}\}) \check{f}(\xi) d\xi + (1-\lambda) \beta v_{t-1}(y) + s \quad \text{(without loss of generality)}. \\ &= \lambda \beta \int_{-\infty}^{\infty} v_{t-1}(-\max\{\xi, \hat{y}\}) f(\xi) d\xi + (1-\lambda) \beta v_{t-1}(y) + s \quad \text{(see (13.1.10(p.70)))}. \end{split}$$

Applying the reflection operation  $\mathcal{R}$  to the above expression yields

$$-\hat{V}_{t}(-\hat{y}) = -\lambda \beta \int_{-\infty}^{\infty} \hat{v}_{t-1}(-\max\{\xi, \hat{y}\}) f(\xi) d\xi - (1-\lambda)\beta \hat{v}_{t-1}(-\hat{y}) + s$$
$$= -\lambda \beta \mathbf{E}[\hat{v}_{t-1}(-\max\{\xi, \hat{y}\})] - (1-\lambda)\beta \hat{v}_{t-1}(-\hat{y}) + s, \quad t > 0.$$

Multiplying the above expression by -1 yields

$$\hat{V}_t(-\hat{y}) = \lambda \beta \mathbf{E}[\hat{v}_{t-1}(-\max\{\xi, \hat{y}\})] + (1-\lambda)\beta \hat{v}_{t-1}(-\hat{y}) - s, \quad t > 0.\cdots (1).$$

Now, since (1) holds for any y with  $-\infty < y < \infty$ , it holds also for  $\hat{y}$  since  $\infty > \hat{y} > -\infty$  or equivalently  $-\infty < \hat{y} < \infty$ , hence we have

$$\hat{V}_{t}(-\hat{\hat{y}}) = \lambda \beta \mathbf{E}[\hat{v}_{t-1}(-\max\{\boldsymbol{\xi}, \hat{\hat{y}}\})] + (1 - \lambda)\beta \hat{v}_{t-1}(-\hat{\hat{y}}) - s, \quad t > 0.\cdots(2).$$

Since  $\hat{y} = y$ , we can rewrite (2) as

$$\hat{V}_t(-y) = \lambda \beta \mathbf{E}[\hat{v}_{t-1}(-\max\{\xi,y\})] + (1-\lambda)\beta \hat{v}_{t-1}(-y) - s \cdots (3).$$

o Below let us temporarily represent the symbols "v" and "V" used in rM:2[ $\mathbb{R}$ ][ $\mathbb{E}$ ] in Section 26.2.2.1( $\mathbb{P}$ .256) by "z" and "Z" respectively. Then (26.2.51( $\mathbb{P}$ .256)), (26.2.57( $\mathbb{P}$ .256)), and (26.2.55( $\mathbb{P}$ .256)) can be rewritten as respectively

$$z_0(y) = \max\{y, \rho\} \cdots (4),$$

$$z_t(y) = \max\{y, Z_t(y)\} \cdots (5), \quad t > 0,$$

$$Z_0(y) = \rho \cdots (6),$$

$$Z_t(y) = \lambda \beta \mathbf{E}[z_{t-1}(\max\{\xi, y\})] + (1 - \lambda)\beta z_{t-1}(y) - s \cdots (7), \quad t > 0.$$

In addition, let  $Z_t^{\diamond}(y) \stackrel{\text{def}}{=} Z_t(y) - y \cdots$  (8) and  $z_t^{\diamond}(y) \stackrel{\text{def}}{=} z_t(y) - y = \max\{0, Z_t^{\diamond}(y)\}$ . Then we have  $Z_t^{\diamond}(y_t^{\diamond}) = 0$  and  $z_t(y_t^{\diamond}) - y_t^{\diamond} = 0$  (see (28.2.7(p.281))).

- o Since  $V_0(y) = \rho \cdots$  (9) from (26.2.70(p.257)), we have  $-\hat{V}_0(-\hat{y}) = -\hat{\rho}$ , hence  $\hat{V}_0(-\hat{y}) = \hat{\rho}$ . Since the equality holds for any  $y \in (-\infty, \infty)$  and any  $\rho \in (-\infty, \infty)$ , so also does for  $\hat{y} \in (-\infty, \infty)$  and  $\hat{\rho} \in (-\infty, \infty)$ . Hence since  $\hat{V}_0(-\hat{y}) = \hat{\rho}$ , we have  $\hat{V}_0(-y) = \rho \cdots$  (10).
- o From (10) and (6) we have  $\hat{V}_0(-y) = \rho = Z_0(y)$ . Suppose  $\hat{V}_{t-1}(-y) = Z_{t-1}(y)$ . Then, from (26.2.71(p.257)) we have  $v_{t-1}(y) = \min\{-\hat{y}, -\hat{V}_{t-1}(-\hat{y})\} = -\max\{\hat{y}, \hat{V}_{t-1}(-\hat{y})\} = -\max\{\hat{y}, Z_{t-1}(\hat{y})\} = -z_{t-1}(\hat{y})$

due to (5). Hence, since  $\hat{v}_{t-1}(y) = z_{t-1}(\hat{y})$ , we have

$$\hat{v}_{t-1}(-y) = \hat{v}_{t-1}(\hat{y}) = z_{t-1}(\hat{y}) = z_{t-1}(y),$$

hence since  $\hat{v}_{t-1}(-\max\{\boldsymbol{\xi},y\}) = z_{t-1}(\max\{\boldsymbol{\xi},y\})$ . Accordingly, (3) can be rewritten as

$$\hat{V}_t(-y) = \lambda \beta \mathbf{E}[z_{t-1}(\max\{\xi, y\})] + (1 - \lambda)\beta z_{t-1}(y) - s = Z_t(y) \quad (\text{see } (7)).$$

Hence, since  $-V_t(-y)=Z_t(y)$ , we have  $V_t(-y)=-Z_t(y)$ . Since the equality holds for any  $y\in(-\infty,\infty)$ , so also does for  $\hat{y}\in(-\infty,\infty)$ , hence  $V_t(-\hat{y})=-Z_t(\hat{y})$ , so  $V_t(y)=-Z_t(\hat{y})$ . Now, from (28.2.13(p.284)) and (28.2.11(p.284)) we have

$$0 = \tilde{V}_t(\tilde{y}_t^{\diamond}) = V_t(\tilde{y}_t^{\diamond}) - \tilde{y}_t^{\diamond} = -Z_t(\hat{\tilde{y}}_t^{\diamond}) - \tilde{y}_t^{\diamond} = -Z_t(\hat{\tilde{y}}_t^{\diamond}) + \hat{\tilde{y}}_t^{\diamond} = -(Z_t(\hat{\tilde{y}}_t^{\diamond}) - \hat{\tilde{y}}_t^{\diamond}) = -Z_t^{\diamond}(\hat{\tilde{y}}_t^{\diamond})$$

due to (8) or equivalently  $Z_t^{\diamond}(\hat{\tilde{y}}_t^{\diamond}) = 0$ . Hence, we have  $y_t^{\diamond} = \hat{\tilde{y}}_t^{\diamond}$  by definition, or equivalently  $\hat{\tilde{y}}_t^{\diamond} = y_t^{\diamond}$ , so  $-\tilde{y}_t^{\diamond} = y_t^{\diamond}$ , hence  $\tilde{y}_t^{\diamond} = -y_t^{\diamond} = \hat{y}_t^{\diamond}$ .

#### **28.2.2.2** Derivation of $\mathscr{A}\{\tilde{rM}:2[\mathbb{R}][E]\}$

For almost the same reason as in Section 27.2.2.1(p.274) it can be confirmed that  $SOE\{r\tilde{M}:2[\mathbb{R}][E]\}$  (see (26.2.69(p.257))) is symmetrical to  $SOE\{rM:2[\mathbb{R}][E]\}$  (see (26.2.56(p.256))). This results implies that applying  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Tom 28.2.1(p.283) for  $rM:2[\mathbb{R}][E]$  yields lemmas for  $r\tilde{M}:2[\mathbb{R}][E]$ .

- $\square$  Tom 28.2.1 ( $\mathscr{A}\{r\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}$ )
- (a) Let  $\beta = 1$  and s = 0.
  - 1. We have  $y \ge V_t(y)$  for  $t \ge 0$  and any y.
  - 2. We have the same unsolved subject as  $\boxed{\text{F.S.}}$  4(p.283).
- (b) Let  $\beta < 1$  or s > 0.
  - 1.  $\blacktriangle Let \ y \leq \tilde{y}_t^{\diamond}$ . Then  $V_t(y) \geq y$  for  $t \geq 0$ .
  - 2.  $\blacktriangle Let \ y \geq \tilde{y}_t^{\diamond}$ . Then  $y \geq V_t(y)$  for  $t \geq 0$ .
  - 3. We have the same unsolved subject as  $\overline{\text{F.S}}$  5(p.283).  $\Box$
- ullet Proof by symmetry Immediate from applying  $\mathcal{S}_{\mathbb{R} \to \tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Tom 28.2.1(p.283).

From (26.2.63(p.256)) and the two inequalities in Tom 28.2.5(p.282) (a,b) we have the following decision rule:

#### 28.2.2.3 Flow of Optimal Decision Rules

- \* Flow-ODR 15 (rM:2[R][E]) (Accept<sub>0</sub>(y)>Stop) Let  $\beta=1$  and s=0 (see Tom 28.2.1(p.285) (\*a1)). Then, the inequality  $y\leq V_t(y)$  for any y and  $t\geq 0$  means that even if the process is initiated at any time t, it is optimal to reject the best price y at that time. Accordingly, it follows that each time a price  $\xi$  is proposed, the current best price y continues to be reduced to  $y\stackrel{\text{def}}{=} \min\{y,\xi\}$ , and the process terminates by accepting the best price y at the deadline t=0, i.e., Accept<sub>0</sub>(y)>Stop.  $\square$
- $\bullet$  Flow-ODR 16 (rM:2[ $\mathbb{R}$ ][E]) (t-reservation-price) Let  $\beta < 1$  or s > 0. Then, from Tom 28.2.1(0.285) ( $\bullet$  b1. $\bullet$  b2)

and (26.1.25(p.252)) we have the following relations for  $\tau \geq t \geq 0$ :

$$\left\{ \begin{array}{l} y \leq \tilde{y}_t^{\diamond} \ \Rightarrow \ \mathsf{Accept}_t\langle y \rangle \ and \ the \ process \ stops \ \mathbf{I} \\ y \geq \tilde{y}_t^{\diamond} \ \Rightarrow \ \mathsf{Reject}_t\langle y \rangle \ and \ \mathsf{Conduct}_t/\mathsf{Skip}_t \end{array} \right.$$

Namely, the optimal reservation value is given by  $\tilde{y}_t^{\diamond}$ , which is constant in t.  $\square$ 

#### 28.2.2.4 Market Restriction

#### 28.2.2.4.1 Positive Restriction

- $\square$  Pom 28.2.2  $(\mathscr{A}\{\tilde{\mathbf{r}M}:2[\mathbb{R}][E]\}^+)$  Assume a>0.
- (a) Let  $\beta = 1$  and s = 0.
  - 1.  $\bullet$  We have  $Accept_0(y) \triangleright Stop$ .
  - 2. We have the same unsolved subject as  $\overline{\text{F.S}}$  4(p.283).
- (b) Let  $\beta < 1$  or s > 0.
  - 1.  $\bullet$  We have t-reservation-price.
  - 2. We have the same unsolved subject as  $\boxed{\text{F.S}}$  5(p.283).
- *Proof* Suppose a > 0.
  - (a) Let  $\beta = 1$  and s = 0..
  - (a1) Obvious from Tom 28.2.1(p.285) (\*a) and \*Flow-ODR 15.
  - (a2) The subject of future study—
  - (b) Let  $\beta < 1$  or s > 0.
  - (b1) Evident from Tom 28.2.1(p.285) ( $\spadesuit$ b1, $\spadesuit$ b2) and  $\clubsuit$ Flow-ODR 16.
  - (b2) The subject of future study ■

#### 28.2.2.4.2 Mixed Restriction

Omitted.

#### 28.2.2.4.3 Negative Restriction

Unnecessary.

#### 28.2.3 Conclusion 10 (Search-Enforced-Model 2)

The following four cases are possible:

- C1 We have  $\mathscr{A}\{r\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]\}^+ \sim \mathscr{A}\{r\mathsf{M}:2[\mathbb{R}][\mathsf{E}]\}^+$ .
- C2 We have odr  $\mapsto$  Accept<sub>0</sub> $(y) \triangleright$  Stop for rM/ $\tilde{\mathsf{M}}$ :2 $[\mathbb{R}][\mathsf{E}]^+$  (i.e., **1**).
- C3 We have t-reservation-price for  $rM/\tilde{M}:2[\mathbb{R}][E]^+$ .
- C4 We have the same unsolved subject as  $\mathbb{F}.\mathbb{S}$  4(p.283) and  $\mathbb{F}.\mathbb{S}$  5(p.283) for rM/ $\mathbb{M}$ :2[ $\mathbb{R}$ ][ $\mathbb{E}$ ]<sup>+</sup>.  $\square$

- C2 See Pom 28.2.1(p.283) (a1) and Pom 28.2.2(p.286) (a1).
- C3 See Pom 28.2.1(p.283) (b1) and Pom 28.2.2(p.286) (b1).
- C4 See Pom 28.2.1(p.283) (a2,b2) and Pom 28.2.2(p.286) (a2,b2).

C1 Compare Pom 28.2.2(p.286) and 28.2.1(p.283).

# Chapter 29

# Analysis of Model 3

#### 29.1 Search-Allowed-Model 3

Lemma 29.1.1 We have

- (a)  $v_t(y)$  is nondecreasing in  $t \ge 0$  for any y.
- (b) Let  $\rho \leq 0$ . Then  $U_t$  is nondecreasing in  $t \geq 0$ .
- (c) Let  $\rho \geq x_K$  and  $\rho \geq 0$ . Then  $U_t \leq \rho$  for  $t \geq 0$  and  $v_t(y) \leq \max\{y, \rho\}$  for  $t \geq 0$ .
- Proof (a) From (26.3.2(p.257)) with t=1 and (26.3.1(p.257)) we have  $v_1(y) \ge \max\{y,\rho\} = v_0(y)$  for any y. Suppose  $v_{t-1}(y) \ge v_{t-2}(y)$  for any y. Then, from (26.3.5(p.257)) we have

$$U_t(y) \ge \max\{\lambda\beta \mathbf{E}[v_{t-2}(\max\{\xi,y\})] + (1-\lambda)\beta v_{t-2}(y) - s, \beta v_{t-2}(y)\} = U_{t-1}(y)$$

for any y, so from (26.3.2[p.257]) we have  $v_t(y) \ge \max\{y, \rho, U_{t-1}(y)\} = v_{t-1}(y)$  for any y. Thus, by induction we have  $v_t(y) \ge v_{t-1}(y)$  for any y and t > 0. Accordingly, it follows that  $v_t(y)$  is nondecreasing in  $t \ge 0$ .

(b) Let  $\rho \leq 0$ . From (26.3.6(p.257)) with t=1 and (26.3.3(p.257)) we have  $U_1 \geq \beta V_0 = \beta \rho \geq \rho = U_0$  from  $(26.3.8\,(2)\,(p.257))$ . Suppose  $U_t \geq U_{t-1}$ . Then, since  $v_{t-1}(\xi) \geq v_{t-2}(\xi)$  for any  $\xi$  from (a) and since  $V_t \geq \max\{\rho, U_{t-1}\} = V_{t-1}$  from (26.3.4(p.257)), we have

$$U_t \ge \max\{\lambda \beta \mathbf{E}[v_{t-2}(\xi)] + (1-\lambda)\beta V_{t-2} - s, \beta V_{t-2}\} = U_{t-1}$$

from (26.3.6(p.257)). This completes the induction.

(c) Let  $\rho \geq x_K$  and  $\rho \geq 0 \cdots$  (1). Then, we have  $K(\rho) \leq 0 \cdots$  (2) from Corollary 11.2.2(p.58) (a) and we have  $K(\max\{y,\rho\}) \leq 0 \cdots$  (3) for any y due to  $\max\{y,\rho\} \geq \rho \geq x_K$ . Clearly, we have  $U_0 \leq \rho$  from (26.3.8 (2) (p.257)) and  $v_0(y) \leq \max\{y,\rho\}$  for any y from (26.3.1(p.257)). Suppose  $U_{t-1} \leq \rho$  and  $v_{t-1}(y) \leq \max\{y,\rho\} \cdots$  (4) for any y, hence  $V_{t-1} = \rho$  from (26.3.4(p.257)). Then, from (26.3.6(p.257)) we have

$$U_t \le \max\{\lambda\beta \mathbf{E}[\max\{\boldsymbol{\xi},\rho\}] + (1-\lambda)\beta\rho - s, \beta\rho\} = \max\{K(\rho) + \rho, \beta\rho\}$$

from (6.1.10(p.25)), hence  $U_t \leq \max\{\rho, \beta\rho\} = \rho$  due to (2) and (1). Since  $v_{t-1}(\max\{\xi, \rho\}) \leq \max\{\xi, \rho\}$  for any  $\xi$  and y due to (4), from (26.3.5(p.257)) we have

```
U_t(y) \leq \max\{\lambda\beta \mathbf{E}[\max\{\max\{\xi,y\},\rho\}] + (1-\lambda)\beta \max\{y,\rho\} - s,\beta \max\{y,\rho\}\}\}
= \max\{\lambda\beta \mathbf{E}[\max\{\xi,\max\{y,\rho\}\}] + (1-\lambda)\beta \max\{y,\rho\} - s,\beta \max\{y,\rho\}\}\}
= \max\{K(\max\{y,\rho\}) + \max\{y,\rho\},\beta \max\{y,\rho\}\}
```

from (6.1.10(p.25)). Hence  $U_t(y) \leq \max\{\max\{y,\rho\}, \beta\{\max\{y,\rho\}\}\} = \max\{y,\rho\}\}$  due to (3) and  $\max\{y,\rho\} \geq \rho \geq 0$  for any y. Accordingly, from (26.3.2(p.257)) we have  $v_t(y) \leq \max\{y,\rho,\max\{y,\rho\}\} = \max\{y,\rho\}$ . This complete the inductions.

- $\blacksquare$  Tom 29.1.1 ( $\mathscr{A}\{rM:3[\mathbb{R}][A]\}$ )
- (a) Let  $\rho \leq x_K$  or  $\rho \leq 0$ . Then we have  $rM:3[\mathbb{R}][A] \rightarrow rM:2[\mathbb{R}][A]$ .
- (b) Let  $\rho \geq x_K$  and  $\rho \geq 0$ . Then we have  $(s)_{\triangle}$  where odr  $\mapsto$  Accept<sub>\tau</sub>(\rho) \rightarrow Stop.  $\Box$
- *Proof* From (26.3.6(p.257)) with t = 1, (26.3.1(p.257)), and (26.3.3(p.257)) we have

$$U_1 = \max\{\lambda\beta \mathbf{E}[\max\{\boldsymbol{\xi}, \rho\}] + (1 - \lambda)\beta\rho - s, \beta\rho\} = \max\{K(\rho) + \rho, \beta\rho\} \cdots (1)$$

due to (6.1.10(p.25)).

(a) Let  $\rho \leq x_K$ , hence  $K(\rho) \geq 0 \cdots$  (2) from Corollary 11.2.2(p.58) (b). Since  $v_{t-1}(\boldsymbol{\xi}) \geq \max\{\boldsymbol{\xi}, \rho\}$  for any  $\boldsymbol{\xi}$  and t > 0 from (26.3.2(p.257))) and since  $V_t \geq \rho$  for t > 0 from (26.3.4(p.257))), from (26.3.6(p.257))) and (6.1.10(p.25)) we have

$$U_t \geq \max\{\lambda\beta \mathbf{E}[\max\{\boldsymbol{\xi},\rho\}] + (1-\lambda)\beta\rho - s, \beta\rho\} = \max\{K(\rho) + \rho, \beta\rho\} \geq K(\rho) + \rho \geq \rho$$

for any t > 0 due to (2). Let  $\rho \le 0$ , hence  $-(1-\beta)\rho \ge 0$ . From (1) we have  $U_1 - \rho = \max\{K(\rho), -(1-\beta)\rho\} \ge 0$ , so  $U_1 \ge \rho$ ; accordingly, we have  $U_t \ge \rho$  for t > 0 from Lemma 29.1.1(p.287) (b). Consequently, whether  $\rho \le x_K$  or  $\rho \le 0$ , it follows that  $U_t \ge \rho$  for t > 0. This fact means that "Reject the intervening quitting penalty price  $\rho$  for all t > 0", implying "Behave as if there does not exist the intervening quitting penalty price  $\rho$ "; in other words, it eventually follows that  $rM:3[\mathbb{R}][A]$  is reduced to the model without the intervening quitting penalty price  $\rho$ , i.e.,  $rM:2[\mathbb{R}][A]$ .

(b) Let  $\rho \geq x_K$  and  $\rho \geq 0$ . Then, we have  $U_t \leq \rho$  for  $\tau \geq t \geq 0$  from Lemma 29.1.1(p.287) (c), meaning "Accept the intervening quitting penalty price  $\rho$  and the process stops" for  $\tau \geq t > 0$ ; in other words, we have  $\mathtt{odr} \mapsto \mathtt{Accept}_t(\rho) \triangleright \mathtt{Stop}$  for  $\tau \geq \tau > 0$  (see (23.1.2(p.239))). The proof of  $\S_{\Delta}$  is the same as the proof of  $\mathtt{Tom}\ 29.2.1(p.289)$  (b2) for  $\rho \geq 0$ .

# **29.1.1** $r\tilde{M}:3[\mathbb{R}][A]$

In the same way as in Section 27.2.2.1(p.274) we can easily verify that  $SOE\{r\tilde{M}:3[\mathbb{R}][A]\}=\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[SOE\{rM:3[\mathbb{R}][A]\}]$  (see (26.3.16(p.258)) and (26.3.7(p.257))). Hence, we can apply  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}$  (see (20.0.1(p.136))) to Tom 29.1.1(p.287), yielding the following Tom (see Lemma 13.10.1(p.87)).  $\Box$  Tom 29.1.1 ( $\mathscr{A}\{r\tilde{M}:3[\mathbb{R}][A]\}$ )

- (a) Let  $\rho \geq x_{\tilde{K}}$  or  $\rho \geq 0$ . Then we have  $r\tilde{\mathsf{M}}:3[\mathbb{R}][\mathsf{A}] \to r\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{A}]$ .
- (b) Let  $\rho \leq x_{\tilde{K}}$  and  $\rho \leq 0$ . Then we have  $\mathfrak{S}_{\Delta}$  where  $\mathsf{odr} \mapsto \mathsf{Accept}_t(\rho) \triangleright \mathsf{Stop}$ .  $\square$

#### 29.1.2 Conclusion 11 (Search-Allowed-Model 3)

The following two cases are possible:

- C1. We have  $rM/\tilde{M}:3[\mathbb{R}][A] \rightarrow rM/\tilde{M}:2[\mathbb{R}][A]$ .
- C2. We have  $\operatorname{odr} \mapsto \operatorname{Accept}_{\tau}(\rho) \triangleright \operatorname{Stop} \text{ where } \mathfrak{S}_{\vartriangle} \text{ for } \operatorname{rM}/\widetilde{M}:3[\mathbb{R}][A]. \square$
- C1 See Tom 29.1.1(p.287) (a) and Tom 29.1.1(p.288) (a).
- C2 See Tom 29.1.1(p.287) (b) and Tom 29.1.1(p.288) (b).

#### 29.2 Search-Enforced-Model 3

#### **29.2.1** rM: $3[\mathbb{R}][E]$

**Lemma 29.2.1** Let  $\rho \geq x_K$ . Then  $U_t \leq \rho$  and  $v_t(y) \leq \max\{y, \rho\}$  for any y and  $t \geq 0$ .

• Proof Let  $\rho \geq x_K$ , hence  $\max\{y, \rho\} \geq \rho \geq x_K$  for any y. Then, from Corollary 11.2.2(p.58) (a) we have  $K(\rho) \leq 0 \cdots$  (1) and  $K(\max\{y, \rho\}) \leq 0 \cdots$  (2) for any y. Now  $U_0 \leq \rho$  from (26.3.26 (2) (p.258)) and  $v_0(y) \leq \max\{y, \rho\}$  for any y from (26.3.19(p.258)). Suppose  $U_{t-1} \leq \rho$  and  $v_{t-1}(y) \leq \max\{y, \rho\}$  for any y, hence  $V_{t-1} = \rho$  from (26.3.22(p.258)) and  $v_{t-1}(\max\{\xi, y\}) \leq \max\{\max\{\xi, y\}, \rho\}$  for any  $\xi$  and y. Then, from (26.3.24(p.258)) we have

$$U_t \le \lambda \beta \mathbf{E}[\max{\{\boldsymbol{\xi}, \rho\}}] + (1 - \lambda)\beta \rho - s = K(\rho) + \rho$$

due to (6.1.10(p.25)), hence  $U_t \leq \rho$  due to (1). In addition, from (26.3.23(p.258)) we have

$$U_t(y) \leq \lambda \beta \mathbf{E}[\max\{\max\{\xi, y\}, \rho\}] + (1 - \lambda)\beta \max\{y, \rho\} - s$$
$$= \lambda \beta \mathbf{E}[\max\{\xi, \max\{y, \rho\}\}] + (1 - \lambda)\beta \max\{y, \rho\} - s$$
$$= K(\max\{y, \rho\}) + \max\{y, \rho\}$$

from (6.1.10(p.25)), hence  $U_t(y) \le \max\{y, \rho\}$  from (2). Accordingly, from (26.3.20(p.258)) we have  $v_t(y) \le \max\{y, \rho, \max\{y, \rho\}\} = \max\{y, \rho\}$ . This complete the inductions.

# $\blacksquare$ Tom **29.2.1** ( $\mathscr{A}\{rM:3[\mathbb{R}][E]\}$ )

- (a) Let  $\rho \leq x_K$ . Then we have  $rM:3[\mathbb{R}][E] \rightarrow rM:2[\mathbb{R}][E]$ .
- (b) Let  $\rho \geq x_K$ .
  - $1. \quad \textit{We have } \mathsf{odr} \mapsto \mathsf{Accept}_t(\rho) \, \triangleright \, \mathsf{Stop} \; \textit{for} \; \tau \geq t \geq 0.$
  - 2. Let  $\rho \geq 0 \ (\rho \leq 0)$ . Then we have  $\mathfrak{S}_{\Delta}$   $(\mathfrak{d}_{\Delta})$ .
- Proof (a) Let  $\rho \leq x_K$ , hence  $K(\rho) \geq 0 \cdots$  (1) from Corollary 11.2.2(p.58) (b). Since  $V_{t-1} \geq \rho$  for t > 0 from (26.3.22(p.258))) and since  $v_{t-1}(y) \geq \max\{y, \rho\}$  for any  $y, \rho$ , and t > 0 from (26.3.20(p.258))), from (26.3.24(p.258))) we have

$$U_t \ge \lambda \beta \mathbf{E}[\max{\{\boldsymbol{\xi}, \rho\}}] + (1 - \lambda)\beta \rho - s = K(\rho) + \rho, \quad t > 0$$

from (6.1.10(p.25)), hence  $U_t \ge \rho$  for t > 0 from (1). This fact means that "Reject the intervening quitting penalty price  $\rho$  for all t > 0", implying "Behave as if there does not exist the intervening quitting penalty price  $\rho$ "; in other words, it follows that rM:3[ $\mathbb{R}$ ][ $\mathbb{E}$ ] is reduced to the model without the intervening quitting penalty  $\rho$ ", i.e., rM:2[ $\mathbb{R}$ ][ $\mathbb{E}$ ].

- (b) Let  $\rho \geq x_K$ .
- (b1) Then, we have  $U_t \leq \rho$  for  $\tau \geq t \geq 0$  from Lemma 29.2.1(p.288), meaning that "Always accept the intervening quitting penalty  $\rho$  and the process stops" is optimal for  $\tau \geq t > 0$ ; in other words, we have  $\operatorname{odr} \mapsto \operatorname{Accept}_t(\rho) \triangleright \operatorname{Stop}$  for  $\tau \geq t > 0$  (see (23.1.2(p.239))). Then since  $V_t = \rho$  for  $\tau \geq t \geq 0$  from (26.3.22(p.258)), we have  $I_\tau^t = \beta^{\tau t}V_t = \beta^{\tau t}\rho$  for  $\tau \geq t \geq 0$  from (8.2.3(p.44)).
- (b2) If  $\rho \geq 0$ , then since  $\beta^0 \rho \geq \beta^1 \rho \geq \cdots \geq \beta^{\tau} \rho$ , we have  $I_{\tau}^{\tau} \geq I_{\tau}^{\tau-1} \geq \cdots \geq I_{\tau}^{0}$ , hence  $\boxed{\$ dOITs_{\tau} \langle \tau \rangle}_{\vartriangle}$  and if  $\rho \leq 0$ , then since  $\beta^0 \rho \leq \beta^1 \rho \leq \cdots \leq \beta^{\tau} \rho$ , we have  $I_{\tau}^{\tau} \leq I_{\tau}^{\tau-1} \leq \cdots \leq I_{\tau}^{0}$ , hence  $\boxed{\bullet dOITd_{\tau} \langle 0 \rangle}_{\vartriangle}$ .

# 29.2.2 $\tilde{r}M:3[\mathbb{R}][E]$

In the same way as in Section 27.2.2.1(p.274) we can easily verify that  $SOE\{r\tilde{M}:3[\mathbb{R}][E]\}=\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}[SOE\{rM:3[\mathbb{R}][E]\}]$  (see (26.3.34(p.258)) and (26.3.25(p.258))). Hence we can apply  $\mathcal{S}_{\mathbb{R}\to\tilde{\mathbb{R}}}$  to Tom 29.2.1(p.288), yielding the following Tom.

#### $\square$ Tom 29.2.1 ( $\mathscr{A}\{r\tilde{\mathsf{M}}:3[\mathbb{R}][\mathsf{E}]\}$ )

- (a) Let  $\rho \geq x_{\tilde{K}}$ . Then we have  $r\tilde{\mathsf{M}}:3[\mathbb{R}][\mathsf{E}] \twoheadrightarrow r\tilde{\mathsf{M}}:2[\mathbb{R}][\mathsf{E}]$ .
- (b) Let  $\rho \leq x_{\tilde{K}}$ .
  - $1. \quad We \ have \ \mathrm{odr} \mapsto \ \mathrm{Accept}_t(\rho) \, \triangleright \, \mathrm{Stop} \ for \ \tau \geq t \geq 0.$
  - 2. If  $\rho \leq 0 \ (\rho \geq 0)$ , then we have  $\mathfrak{S}_{\Delta}$   $(\mathfrak{d}_{\Delta})$ .

# 29.2.3 Conclusion 12 (Search-Enforced-Model 3)

The following three cases are possible:

- C1. We have  $rM/\tilde{M}:3[\mathbb{R}][E] \rightarrow rM/\tilde{M}:2[\mathbb{R}][E]$ .
- C2. We have  $\operatorname{odr} \mapsto \operatorname{Accept}_{\tau}(\rho) \triangleright \operatorname{Stop} \text{ if } \rho \geq 0 \text{ (i.e., } \textcircled{S}_{\vartriangle}) \text{ and } \operatorname{Accept}_{0}(\rho) \triangleright \operatorname{Stop} \text{ if } \rho < 0 \text{ (i.e., } \textcircled{d}_{\vartriangle}). \ \Box$

C1 See Tom 29.2.1(p.288) (a) and Tom 29.2.1(p.289) (a).

C2 See Tom 29.2.1(p.289)(b1,b2).

# Chapter 30

# Conclusion of Part 4 (Recall-Model)

For details, see Conclusions 7 (p.267), 8 (p.276), 9 (p.281), 10 (p.286), 11 (p.288), and 12 (p.289).

## 30.1 Models 1/2

#### $\overline{\overline{C}}1$ . Mental Conflict

- a. For rModel 1 we have the c-reservation-price (see C6(p.267) and C5(p.276)), which is called myopic property (see Def. 27.2.1(p.273)).
- b. For rModel 2 we have the t-reservation-price (see C5(p.281) and C3(p.286)).
- c. Now, it was already shown in [43,Sak1961] that rModel 1 (sE-model) has c-reservation-price, and after that any variation of this model with the myopic property has not been posed and examined to date; for this reason, we have continued to think as if this property is a general one for all recall models. However, we demonstrated above that this property does not hold in rModel 2; in other words, it follows that this is not a property holding for all recall-models.

# $\overline{\overline{C}}_2$ . Symmetry

- a. For rModel 1, the symmetry collapses for both sA-model (see C1(p.267)) and sE-model (see C1(p.276)).
- b. For rModel 2, the symmetry collapses for sA-model (see C1(p.281)) but is inherited for sE-model (see C1(p.286)).

# $\overline{\overline{C}}3$ . Optimal Initiating Time

For rModel 1 with a more complicated structure than no-recall-model, at the beginning we imagined that it would be rather difficult to mathematically (analytically) find conditions for (S), (O), and (O). However, fortunately we succeeded in finding the conditions: see C4(p.267) and C2(p.276) for (O), and C5(p.267) and C4(p.276) for (O) What should be noted here is that also (O) and (O) (strictness) exist (see C3(p.276) and C4(p.276)).

# $\overline{\overline{C}}4$ . Future study

In rModel 2 we did not succeed in finding the conditions for  $\bigcirc$  and  $\bigcirc$ . Mathematical analyses identifying these conditions are left as a future study (see  $\boxed{\text{F.S}}$  3(p.279),  $\boxed{\text{F.S}}$  4(p.283), and  $\boxed{\text{F.S}}$  5(p.283)).

#### E Reduction

- a. We have the mode-migration  $\text{rM}/\tilde{M}:1/2[\mathbb{R}][A]^+ \hookrightarrow \text{rM}/\tilde{M}:1[\mathbb{R}][E]^+$  (see C2(p.267)/C2(p.281)).
- b. We have the odr-reduction odr  $\mapsto$  Accept<sub>0</sub>(y)  $\triangleright$  Stop for sA-model 1/2 (see C3(p.267)/C4(p.281)).

# 30.2 Models 3

#### $\overline{\overline{C}}6$ . Reduction

- a. We have the model-running-back  $rM/\tilde{M}:3[\mathbb{R}][A/E] \rightarrow rM/\tilde{M}:2[\mathbb{R}][A/E]$  (see C1(p.288) and C1(p.289)).
- b. We have the odr-reduction odr  $\mapsto$  Accept $_{\tau}(\rho) \triangleright$  Stop (see C2(p.289) and C2(p.288)).

# Part 5

# Conclusion

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# Chapter 31

# Overall Conclusions of This Paper

#### 31.1 List of Conclusions

Below we list a variety of conclusions presented in Chaps. 9(p.49), 20(p.135), 24(p.245), and 30(p.291).

#### $\overline{\overline{C}}_{1}$ . Conclusion of Part 1 (Prologue)

See Chap. 9(p.49), which can be summarized as follows.

- a. Two motives of the study This study was initiated by the two motives described Section 1.1(p.3).
- b. Decision theory as physics The Philosophical foundation of this paper rooted in the concept of "decision theory as physics" (see Section 1.2(p3)), which supports this study.
- c. Quadruple-asset-trading-problems We provided an overview of asset trading problems addressed in the paper, reffered to as the quadruple-asset-trading-problems (see Section 1.3(p.4)). Our key focus is not on analyzing each problem independently but on clarifing the interconnectedness among these problems.
- d. Mental conflict As illustrated in Examples 1.3.1(p.5)-1.3.4(p.6), the normal (typical) mental conflict experienced by a leading trader (see Remark 8.4.1(p.48)) can be intuitively understood. However, the abnormal mental conflict (see Remark 8.4.2(p.48)) is more challenging to grasp immediately. Nontheless, it is indeed possible to understand it (see  $\overline{\overline{C}}$ ??(p.??)).
- e. Discount factor A selling problem is framed as a *profit* maximization problem, while a buying problem is a *cost* minimization problem. The managerial and economical implications of the discount factor for *profit* have been well-documented in many standard textbooks [39, Ross]. In this paper, we offer a persuasive explanation of its implication for *cost* (see A12(p.13)).
- f. Underlying function The underlying functions T, L, K, and  $\mathcal{L}$  defined in Chap. 6(p.25) are essential for analyzing all the models discussed in this paper. While the function T has been previously defined in existing literature, the other three functions are introduced here for the first time.
- g. Time concepts Among the various novel concepts introduced in this paper, the following five time points are particularly noteworthy; recognizing time  $t_r$ , starting time  $t_s$ , initiating time  $\tau$ , stopping time t, and deadline 0 (see H1(p.7) and Section 8.1(p.43)).
- h. Optimal initiating time The best of conceivable initiating times  $t_r \ge \tau \ge 0$  is called the *optimal initiating time* (OIT), represented by  $t_{\tau}^*$  (see (8.2.4(p.44))). If  $t_{\tau}^* = t_s$ , then it is denoted by (s). If  $t_s > t_{\tau}^* > 0$ , then (s). If  $t_{\tau}^* = 0$ , then (s) (see Section 8.2.4.3(p.45)).
- i. Null-Time-Zone and Deadline-Engulfing The introduction of the optimal initiating time naturally leads to the concepts of the null-time-zone (see Sections 8.2.4.5(p.46)) and the deadline engulfing (see 8.2.4.6(p.46)). These two concepts are novel and were first introduced in this paper. It is no exaggeration to say that they represent the most significant discoveries in this study. These results suggest the need for a comprehensive re-examination of conclusions in nearly all conventional studies conducted by veriouse researchers up to this point.

#### C2. Conclusion of Part 2 (Integrated-Theory)

See Chap. 20(p.135), which can be summarized as follows.

- a. Symmetry and analogy In Chaps. 13(p.69) and 15(p.101), we clarified the symmetrical relationship between an asset selling problem and an asset buying problem, whether using the  $\mathbb{R}$ -mechanism or the  $\mathbb{P}$ -mechanism. Additionally, in Chaps. 14(p.89) and 16(p.111) we derived the analogous relationship between an asset trading problem with the  $\mathbb{R}$ -mechanism and an asset buying problem with the  $\mathbb{P}$ -mechanism, regardless of whether it is a selling or buying problem.
- b. Construction of integrated theory The integrated-theory (see Chap. 17(p.115)) is constructed through a dual-directional combination of the four symmetry theorems (Theorems 13.5.1(p.80), 13.8.1(p.87), 13.5.1(p.80), and Theorems 15.5.2(p.107)) and four analogy theorems (Theorems 14.3.1(p.97), 14.3.2(p.98), 16.2.1(p.112), and 16.2.2(p.112)).

- c. Collapse of symmetry and analogy The integrated-theory is built on the premise that the price  $\xi$ , whether a reservation price or a posted price, is defined on the total market  $\mathscr{F}$ , i.e., on  $\xi \in (-\infty, \infty)$ . This implies that the price  $\xi$  can become negative, which is irrational from a practical standpoint. To avoid this irrationality, the price must be defined on the positive market  $\mathscr{F}^+$ , i.e.,  $\xi \in (0, \infty)$ . We refer to the restriction of  $(-\infty, \infty)$  to  $(0, \infty)$  as the market restriction (see Chap. 18(p.117)). This restriction leads to the collapse of symmetry and analogy (see  $\overline{\overline{\mathbb{C}}}2a2(p.245)$  and  $\overline{\overline{\mathbb{C}}}3b1(p.245)$ ).
- d. Diagonal Symmetry We demonstrated in Section 19.2.3(p.133) that the market restriction introduces the interesting event where "a selling problem on  $\mathscr{F}^-$  can always become symmetrical to a buying problem on  $\mathscr{F}^+$ ", termed diagonal symmetry (see Chap. 19(p.129)). This becomes a useful tool for the analysi of models.

# $\overline{\overline{C}}_3$ . Cconclusion of Part 3 (No-Recall-Model)

See Chap. 24(p.245), which can be summarized as follows.

- a. Mental Conflict Here again refer to  $\overline{\overline{C}}1(p.245)$ , which can be rewritten as follows. It is only for Model 2 with  $\beta < 1$  and s > 0 that we have the abnormal mental conflict; in other words, for all the other cases we have the normal mental conflict.
- b. Symmetry For details, see  $\overline{\overline{C}}2(p.245)$ ; On  $\mathscr{F}^+$ , whether Model 1 or Model 2, the symmetry is inherited if  $\beta=1$  and s=0, or else it may collapse (see  $\overline{\overline{C}}2(p.245)$ ).
- c. Analogy For details, see  $\overline{\overline{C}}3(p.245)$ ; On  $\mathscr{F}^+$ , for Model 1, the analogy is inherited if  $\beta=1$  and s=0, or else it is may collapses, and for Model 1, whether " $\beta=1$  and s=0" or "if  $\beta<1$  or s>0", the analogy may collapse.
- d. Optimal initiating time For details, see  $\overline{\overline{C}}4(p.245)$ ; What is remarkable here is that 1 (deadline-engulfing) occurs even in the simplest case of " $\beta=1$  and s=0" (see  $\overline{\overline{C}}4a2(p.245)$ ).
- e. Null-time-zone and deadline-engulfing For details, see  $\overline{\overline{C}}5(p.246)$ ;  $\odot$  and  $\bullet$  causing the null-time-zone occur at 55.6% (see  $\overline{\overline{C}}5A(p.246)$ ) and  $\bullet$  causing the dead-engulfing occur at 33.4% (see  $\overline{\overline{C}}5B(p.246)$ ).
- f. Diagonal Symmetry For details, see  $\overline{\overline{C}}6$ (p.246).
- g. C··S (Conduct··Skip) For details, see  $\overline{\overline{C}}7(p.246)$ ; It is only for M:2[ $\mathbb{R}$ ][A]<sup>+</sup> and M:2[ $\mathbb{P}$ ][A]<sup>+</sup> that this rare event becomes possible. For details, see  $\overline{\overline{C}}7(p.246)$
- h. Reduction For details, see  $\overline{\overline{C}}9(p.246)$ .

#### 74. Conclusion of Part 4 (Recall-Model)

See Chap. 30(p.291), which can be summarized as follows.

- a. Monotonicity of opt- $\mathbb{R}/\mathbb{P}$ -price For details, See  $\overline{\overline{C}}1(p.291)$ ; It is only for rModel 1 that we have c-reservation-price (see  $\overline{\overline{C}}1a(p.291)$ ). This property is called the *myopic property* (see Def. 27.2.1(p.273) and  $\overline{\overline{C}}1c(p.291)$ ).
- b. Symmetry For details, See  $\overline{\overline{C}}2(p.291)$ ; For rModel 1, the symmetry collapses for both sA-model and sE-model, and for rModel 2, it collapses for sA-model but is inherited for sE-model.
- c. Optimal initiating time For details, See  $\overline{\overline{C}}3(p.291)$ ; It is only for rM:1[ $\mathbb{R}$ ][E] (see Tom 27.2.1(p.271)) that the analytical discussions for  $\widehat{S}$ ,  $\widehat{\bigcirc}$ , and  $\widehat{\bullet}$  become possible (see  $\overline{\overline{C}}3(p.291)$ ). Discussions for other models are all left for future studies.
- d. Reduction For details, see  $\overline{\overline{C}}_{5(p.291)}$  and  $\overline{\overline{C}}_{6(p.291)}$ ,
- e. Future studies While mathematical analyses identifying the conditions for  $\odot$  and  $\bullet$  are possible for Model 1/2 (see  $\overline{\overline{C}}3(p.291)$ ), it is impossible for Model 3, which is left for future studies (see  $\overline{\overline{C}}4(p.291)$ ).

#### 31.2 General Overview of Conclusions

Distilling the essence from all conclusions listed in Section 31.1(p.293) leads us to the following general overview, which constitute the bedrock of this entire paper.

# $\overline{\overline{\mathsf{C}}}$ 5. Philosycal Backgroung

The study in this paper was proposed by Prof. Shizuo Senju on March 31, 1966, and a while later I (Ikuta) was led to the following two naive motivations (see Section 1.1(p.3)).

Motive 1: Is a buying problem always symmetrical to a selling problem ?

Motive 2: Is it possible for a general theory integrating quadruple-asset-trading-problems to exist?

Enlightened by the thought background of the professor who is "a doctor of engineering", a few years later I (Ikuta, the first author of this paper) obtained PhD (Eng.) under his research guidance. Before long, I found myself down the middle of the philosophy of "decision theory as physics" (see Section 1.2(p3)). On a different note, more than 10 years later, Mr. Kang (the second author) who was a student in my seminar, also obtained PhD (Mgt. Sci.&Eng.) under my research guidance. After that, he actively worked for several years as a business consultant. During that time, he matured into a person with a sense of realism while retaining a scholarly perspective. However, his intellectual curiosity about the underlying structure of various questions in real-world problems eventually led him back into the academic world. Many discussions with him were very valuable for me, which exerted considerable influence on the writing of this paper.

#### **C**6. Time Concepts

Before long, we (Ikuta and Kang), as natural scientists, were led, as an inevitable result, to the concepts of the four time points: recognizing time, starting time, initiating time, and deadline (see H1(p.7) and Section 8.1(p.43)).\*

# $\overline{\overline{C}}$ 7. Null-Time-Zone and Deadline-Engulfing

Now, it is natural that the concept of the "initiating time" inevitably yields the concept of "optimal initiating time" (see (8.2.4(p.44))). Then, it can be immediately recognized that there exists the three types of optimal initiating time; (so (starting time), (o) (nondegenerate time), and (d) (deadline) (see Section 8.2.4.3(p.45)), and we were then led to discover two unexpected phenomena; null-time-zone (see Section 8.2.4.5(p.46)) and deadline-engulfing (see Section 8.2.4.6(p.46) and Alice 3(p.46)). These two phenomena were the most significant discoveries in this entire study, as they necessitate a comprehensive re-examination of almost all results obtained thus far in conventional researches, which had not introduced the concept of initiating time. As seen from Table 24.1.1(p.246), the two optimal initiating times, (o) and (d), that cause the singular properties, null-time-zone and deadline-engulfing, can occur at notable percentages of 22.2% and 33.4% respectively. In addition, the strictly optimal initiating times, (o) and (d) are possible at the percentages of 2.6% and 3.2%. What is furthermore striking is that these occurrences are possible even in the simplest case of  $\beta = 0$  and s = 0 (see  $\overline{C}5D(p.246)$ ).

#### **C**8. Integrated-Theory

We have previousely assumed, without strong evidence, that the existence of the symmetrical relationship between a selling problem and a buying problem is intuitively predictable, and indeed we succeeded in theoretically proving it. As a result, we successfully derived two symmetry theorems, Theorem 13.5.1(p.80) and Theorem 13.8.1(p.87), which are connected with an operation defined by (13.5.29(p.77)). On the other hand, at earlier stage of this study, we did not anticipate the existence of a relationship between a trading problem with a  $\mathbb{R}$ -mechanism and a trading problem with a  $\mathbb{R}$ -mechanism. However, through countless arrangements and rearrangements, similarly to solving a jigsaw puzzle, we noticed similarities between the two problems. Constantly, we developed two lemmas, Lemmas 11.1.1(p.55) and 14.2.1(p.93), which are connected with an operation defined by (14.2.1(p.33)). This led to the derivation of two analogy theorems, Theorems 14.3.1(p.97) and 14.3.2(p.98), combining the above two problems. The integrated-theory that we aimed to construct in this paper is represented by a quadrangular structure bi-directionally connected by these four theorems (see Figure 17.1.1(p.115)). This accomplished the aim of the objective in Motive 2(p.3).

#### <u>C</u>9. Collapse of Symmetry

At that time, we were grappling with the conflict between mathematical thinking and physical thinking; "A price  $\xi$  should be defined whether on  $(-\infty, \infty)$  or on  $(0, \infty)$ ". It is clear that defining the price  $\xi$  on  $(-\infty, \infty)$  makes its mathematical treatment easier than on  $(0, \infty)$ ; however, it should be defined on  $(0, \infty)$  in the usual transaction market of this actual world. Then, we brought solutions to this problem by formulating the methodology of transforming results obtained on  $(-\infty, \infty)$  into ones on  $(0, \infty)$ ", i.e., the market restriction (see Chap. 18(p.117)). Now, since the construction of the integrated-theory is based on the premise that the price  $\xi$  is defined on the total market  $\mathscr{F} = (-\infty, \infty)$ , restricting the market to the positive domain  $\mathscr{F}^+ = (0, \infty)$  naturally leads to the collapses of symmetry and analogy; indeed, we demonstrated in Parts 3(p.137) that both collapses occur. This achieved the aim of the objective in Motive 1(p.3).

- To an interest the conflict of the first in this paper that the normal mental conflict and the abnormal mental conflict are clearly defined and discussed. Although the former would have been implicitly understooded, there would be no researchers so far who noticed the existence of the latter. In this sense, this existence can be said to be one of the most significant discoveries.
- $\overline{\overline{C}}$ 11. **Reduction** Refer to  $\overline{\overline{C}}$ 3h(p.294) for no-recall-model and to  $\overline{\overline{C}}$ 4d(p.294) for recall-model.

# $\overline{\overline{C}}$ 12. Others

- a. Finiteness of the planning horizon Here note that the existence of the deadline implies that decision problems dealt with in this paper are all process with the *finite* planning horizon (see H1d(p.7)).
- b. Recall model Although the above conclusions,  $\overline{\overline{C}}5(p.294)$ - $\overline{\overline{C}}12(p.295)$ , are all based on asset trading problems with no recall, the same holds also for asset trading problems with recall except for discussions on trading problems with  $\mathbb{P}$ -mechanism (see F2(p.291)) and on conditions for \$,  $\circledcirc$ , and a (see  $\overline{\overline{C}}4(p.291)$ ).

This study ends with the above general overview today, September  $16,\,2024.$ 

<sup>\*</sup>At this stage the term "initiating time" was not yet defined.

# Chapter 32

# **Future Study**

# 32.1 Future Subjects

#### F1. See F.S 1(p.24)

In Capter 5(p23), we presented 9 variations of the basic models of asset trading problems. Since there are three models (Models 1/2/3 (see (B(p.15)))) exist for each variation, there are a total  $27 = 9 \times 3$  variations. Furthermore, since each variation has 2 types of models (seelling model and buying model (see (A(p.15)))), there are  $54 = 27 \times 2$  variations in total. Moreover, since each variation has 2 types of models (search-Enforced-model and search-Allowed-model (see (D(p.15)))), there are  $108 = 54 \times 2$  variations. In addition, since each variation has the 2 models ( $\mathbb{R}$ -mechanism-model and  $\mathbb{P}$ -mechanism-model (see (C(p.15)))), there are  $216 = 108 \times 2$  variations overall. Finally, discussions involving the optimal initiating time (see Section 8.2.4(p.44)) are added, and the following mixed variations can be independently proposed:

- o Model with several search areas and limited search budget
- Model with uncertain deadline and mechanism switching
- $\circ\,$  Model with limited search budget, uncertain deadline, and mechanism switching
- o Model with several search areas, limited search budget, uncertain deadline, and mechanism switching
- o Model with recall, several search areas, limited search budget, uncertain deadline, and mechanism switching
- $\circ\,$  Model with uncertain recall, uncertain deadline, and mechanism switching

From all the above, it is clear that the number of variations to be addressed is astronomical. In dealing with the vast amount of these variations, the integrated-theory will become a powerful tools; analyzing them without this theory would be nearly impossiblet.

#### F2. See F.S 2(p.249)

In Part 4(p.247) we applied the integrated theory to the recall-model with  $\underline{\mathbb{R}\text{-mechanism}}$ , where it is sufficient to memorize only the best of once-rejected prices. However, in the recall-model with  $\underline{\mathbb{P}\text{-mechanism}}$ , we face the difficulty of determining which of the once-rejected prices should be memorized. This problem remains one of the most perplexing unsolved issues.

#### F3. See $\overline{\text{F.S}}$ 3(p.279), $\overline{\text{F.S}}$ 4(p.283), and $\overline{\text{F.S}}$ 5(p.283)

In the recall-model, under what conditions do each of (s), (o), and (o) occur? This is one of the most challenging study subjects remaining in this paper. However, at present, we unfortunately do not have any theoretical (mathematical) methodologies for addressing this problem. It remains a thorny issue that affects all models proposed in F1 above.

#### F4. Numerical Experiment

In general, numerical calculation involves computing a given expression by substituting numerical values for constants, parameters, variables, etc. In this paper, we perform numerical calculations from two distinct perspectives. One is to reconfirm results that have already been proven, and the other is to exemplify expectations that are difficult to prove theoretically and/or mathematically. We refer to the former as the *numerical example* and the latter as the *numerical experiment*, i.e.,

$$numerical calculation = \begin{cases} numerical example, \\ numerical experiment. \end{cases} (32.1.1)$$

Throughout the paper we have:

Numerical Example's 
$$1(p.126)$$
,  $2(p.126)$ ,  $3(p.127)$ ,  $4(p.153)$ ,  $5(p.198)$ , and  $6(p.233)$   
Numerical Experiment  $1(p.325)$ .

When confronting problems that are analytically difficult to address, such as those in F1(p.297)-F3(p.297), the only methodology available to us will presumably be numerical experiments.

# Appendix

# A 1 Direct Proof of Underlying Functions of Type $\mathbb{R}$

In this appendix we provide the direct proofs for all lemmas in Section 13.6(p.81) in which they were proven by using Theorem 13.5.1(p.80) (symmetry theorem).

# $\mathbf{A} \ \mathbf{1.1} \quad \mathscr{A} \{ \tilde{T}_{\mathbb{R}} \}$

For convenience of reference, below let us copy Lemma 13.6.1(p81).

**Lemma A 1.1**  $(\mathscr{A}\{\tilde{T}_{\mathbb{R}}\})$  For any  $F \in \mathscr{F}$ :

- (a)  $\tilde{T}(x)$  is continuous on  $(-\infty, \infty)$ .
- (b)  $\tilde{T}(x)$  is nonincreasing on  $(-\infty, \infty)$ .
- (c)  $\tilde{T}(x)$  is strictly decreasing on  $[a, \infty)$ .
- (d)  $\tilde{T}(x) + x$  is nondecreasing on  $(-\infty, \infty)$ .
- (e)  $\tilde{T}(x) + x$  strictly increasing on  $(-\infty, b]$ .
- (f)  $\tilde{T}(x) = \mu x$  on  $[b, \infty)$  and  $\tilde{T}(x) < \mu x$  on  $(-\infty, b)$ .
- (g)  $\tilde{T}(x) < 0$  on  $(a, \infty)$  and  $\tilde{T}(x) = 0$  on  $(-\infty, a]$ .
- (h)  $\tilde{T}(x) \le \min\{0, \mu x\}$  on  $x \in (-\infty, \infty)$ .
- (i)  $\tilde{T}(0) = 0 \text{ if } a > 0 \text{ and } \tilde{T}(0) = \mu \text{ if } b < 0.$
- (j)  $\beta \tilde{T}(x) + x$  is nondecreasing on  $(-\infty, \infty)$  if  $\beta = 1$ .
- (k)  $\beta \tilde{T}(x) + x$  is strictly increasing on  $(-\infty, \infty)$  if  $\beta < 1$ .
- (1) If x > y and b > y, then  $\tilde{T}(x) + x > \tilde{T}(y) + y$ .
- (m)  $\lambda \beta \tilde{T}(\lambda \beta \mu + s) + s$  is nondecreasing in s and is strictly increasing in s if  $\lambda \beta < 1$ .
- (n)  $b > \mu$ .  $\square$
- *Proof* First, for any x and y let us prove the following two inequalities:

$$-(x-y)F(y) \ge \tilde{T}(x) - \tilde{T}(y) \ge -(x-y)F(x) \cdots (1),$$
  
$$(x-y)(1-F(y)) \ge \tilde{T}(x) + x - \tilde{T}(y) - y \ge (x-y)(1-F(x)) \cdots (2).$$

Then, let  $\tilde{T}(x,y) \stackrel{\text{def}}{=} \mathbf{E}[(\boldsymbol{\xi}-x)I(\boldsymbol{\xi}< y)]$  for any x and  $y.^{\ddagger}$  Since  $1 \geq I(\boldsymbol{\xi}< y) \geq 0$  and since  $\min\{\boldsymbol{\xi}-x,0\} \leq 0$  and  $\min\{\boldsymbol{\xi}-x,0\} \leq \min\{\boldsymbol{\xi}-x,0\} \leq \min\{\boldsymbol{\xi}-x,0\}I(\boldsymbol{\xi}< y) \leq (\boldsymbol{\xi}-x)I(\boldsymbol{\xi}< y)$ , hence from (6.1.11(p.25)) we get  $\tilde{T}(x) \leq \mathbf{E}[(\boldsymbol{\xi}-x)I(\boldsymbol{\xi}< y)] = \tilde{T}(x,y)$ . Accordingly, for any x and y we have

$$\tilde{T}(x) - \tilde{T}(y) < \tilde{T}(x,y) - \tilde{T}(y) = \mathbf{E}[(\boldsymbol{\xi} - x)I(\boldsymbol{\xi} < y)] - \mathbf{E}[(\boldsymbol{\xi} - y)I(\boldsymbol{\xi} < y)] = -(x - y)\mathbf{E}[I(\boldsymbol{\xi} < y)].$$

Since  $I(\boldsymbol{\xi} \geq y) + I(\boldsymbol{\xi} < y) = 1$ , we have  $\tilde{T}(x) - \tilde{T}(y) \leq -(x - y)(\mathbf{E}[1 - I(\boldsymbol{\xi} \geq y)]) = -(x - y)(1 - \mathbf{E}[I(\boldsymbol{\xi} \geq y)])$ . Then, since

$$\mathbf{E}[I(\xi \ge y)] = \int_{-\infty}^{\infty} I(\xi \ge y) f(\xi) d\xi = \int_{y}^{\infty} 1 \times f(\xi) d\xi = \int_{y}^{\infty} f(\xi) d\xi = \Pr\{\xi > y\} = 1 - \Pr\{\xi \le y\} = 1 - F(y),$$

<sup>&</sup>lt;sup>‡</sup>If a given statement S is true, then I(S) = 1, or else I(S) = 0.

we have  $\tilde{T}(x) - \tilde{T}(y) \leq -(x-y)F(y)$ , hence the far left inequality of (1) holds. Multiplying both sides of the inequality by -1 leads to  $-\tilde{T}(x) + \tilde{T}(y) \geq (x-y)F(y)$  or equivalently  $\tilde{T}(y) - \tilde{T}(x) \geq -(y-x)F(y)$ . Then, interchanging the notations x and y yields  $\tilde{T}(x) - \tilde{T}(y) \geq -(x-y)F(x)$ , hence the far right inequality of (1) holds. (2) is immediate from adding x-y to (1). Let us note here that  $\tilde{T}(x)$  defined by (6.1.11(p.25)) can be rewritten as

$$\tilde{T}(x) = \mathbf{E}[\min\{\boldsymbol{\xi} - x, 0\}I(b \ge \boldsymbol{\xi})] + \mathbf{E}[\min\{\boldsymbol{\xi} - x, 0\}I(\boldsymbol{\xi} > b)]. \cdots (3)$$

$$= \mathbf{E}[\min\{\boldsymbol{\xi} - x, 0\}I(\boldsymbol{\xi} \ge a)] + \mathbf{E}[\min\{\boldsymbol{\xi} - x, 0\}I(a > \boldsymbol{\xi})]. \cdots (4).$$

- (a,b) Immediate from the fact that  $\min\{\xi x, 0\}$  is continuous and nonincreasing in  $x \in (-\infty, \infty)$  for any given  $\xi$ .
- (c) Let x>y>a. Then, since -(x-y)<0 and F(y)>0 due to  $(2.2.1\,(2,3)\,(\text{p.l2}))$ , we have -(x-y)F(y)<0, hence  $0>\tilde{T}(x)-\tilde{T}(y)$  from (1), i.e.,  $\tilde{T}(y)>\tilde{T}(x)$ , so  $\tilde{T}(x)$  is strictly decreasing on  $(a,\infty)\cdots(5)$ . Suppose  $\tilde{T}(a)=\tilde{T}(x)$  for any x>a, hence x-a>0. Then, for any sufficiently small  $\varepsilon>0$  such that  $x-a>2\varepsilon>0$  we have  $a< a+\varepsilon< x-\varepsilon< x$ , hence  $\tilde{T}(a)=\tilde{T}(x)<\tilde{T}(a+\varepsilon)\leq \tilde{T}(a)$  due to (5) and (b), which is a contradiction. Thus it must be that  $\tilde{T}(a)\neq \tilde{T}(x)$  for any x>a, i.e.,  $\tilde{T}(a)>\tilde{T}(x)$  or  $\tilde{T}(a)<\tilde{T}(x)$  for any x>a. Since the latter is impossible due to (b), it follows that  $\tilde{T}(a)>\tilde{T}(x)$  for any x>a. From this and (5) it eventually follows that  $\tilde{T}(x)$  is strictly decreasing on  $[a,\infty)$  instead of  $(a,\infty)$ .
- (d) Evident from the fact that  $\tilde{T}(x) + x = \mathbf{E}[\min\{\boldsymbol{\xi}, x\}]$  from (6.1.11(p.25)) and that  $\min\{\boldsymbol{\xi}, x\}$  is nondecreasing in x for any  $\boldsymbol{\xi}$ .
- (e) Let b>x>y, hence F(x)<1 due to  $(2.2.1\,(1,2)\,(\text{p.}12)\,)$ . Then, since (x-y)(1-F(x))>0, we have  $\tilde{T}(x)+x>\tilde{T}(y)+y$  from (2), i.e.,  $\tilde{T}(x)+x$  is strictly increasing on  $(-\infty,b)\cdots$  (6). Suppose  $\tilde{T}(b)+b=\tilde{T}(x)+x$  for any x< b. Then, for any sufficiently small  $\varepsilon>0$  such that  $b-x>\varepsilon$  we have  $x< x+\varepsilon< b$ , hence  $\tilde{T}(b)+b=\tilde{T}(x)+x<\tilde{T}(x+\varepsilon)+x+\varepsilon\leq \tilde{T}(b)+b$  due to (6) and (d), which is a contradiction. Thus,  $\tilde{T}(x)+x\neq \tilde{T}(b)+b$  for x< b, i.e.,  $\tilde{T}(x)+x>\tilde{T}(b)+b$  or  $\tilde{T}(x)+x<\tilde{T}(b)+b$  for x< b. Since the former is impossible due to (d), it must be that  $\tilde{T}(x)+x<\tilde{T}(b)+b$  for x< b. From this and (6) it follows that  $\tilde{T}(x)+x$  is strictly increasing on  $(-\infty,b]$ .
- (f) Let  $x \geq b$ . If  $b \geq \xi$ , then  $x \geq \xi$ , hence  $\min\{\xi x, 0\} = \xi x$ , and if  $\xi > b$ , then  $f(\xi) = 0$  due to (2.2.3 (3) (p.33)). Thus, from (3) we have  $\tilde{T}(x) = \mathbf{E}[(\xi x)I(b \geq \xi)] + 0 = \mathbf{E}[(\xi x)I(b \geq \xi)] + \mathbf{E}[(\xi x)I(\xi > b)] = \mathbf{E}[(\xi x)(I(b \geq \xi) + I(\xi > b))] = \mathbf{E}[\xi x] = \mu x,^{\dagger}$  hence the former half is true. Then, since  $\tilde{T}(b) = \mu b$  or equivalently  $\tilde{T}(b) + b = \mu$ , if b > x, from (e) we have  $\tilde{T}(x) + x < \tilde{T}(b) + b = \mu$ , hence  $\tilde{T}(x) < \mu x$ , so the latter half is true.
- (g) Let  $a \ge x$ . If  $\xi \ge a$ , then  $\xi \ge x$ , hence  $\min\{\xi x, 0\} = 0$  and if  $a > \xi$ , then  $f(\xi) = 0$  due to (2.2.3(1)(p.13)), hence  $\mathbf{E}[\min\{\xi x, 0\}I(a > \xi)] = 0$ . Accordingly, we have  $\tilde{T}(x) = 0$  from (4), hence the latter half is true. Let x > a. Then, since  $\tilde{T}(x) < \tilde{T}(a)$  from (c) and since  $\tilde{T}(a) = 0$  from the fact stated just above, we have  $\tilde{T}(x) < 0$  for x > a, hence the former half is true.
- (h) From (f) we have  $\tilde{T}(x) \leq \mu x$  for any x and from (g) we have  $\tilde{T}(x) \leq 0$  for any x, thus it follows that  $\tilde{T}(x) \leq \min\{0, \mu x\}$  for any x.
- (i) From (6.1.11(p.25)) we have  $\tilde{T}(0) = \mathbf{E}[\min\{\boldsymbol{\xi},0\}] = \mathbf{E}[\min\{\boldsymbol{\xi},0\}I(a \leq \boldsymbol{\xi} \leq b)]$ . If a > 0, then  $0 \leq \boldsymbol{\xi}$ , hence  $\min\{\boldsymbol{\xi},0\} = 0$ , so  $\tilde{T}(0) = \mathbf{E}[0] = 0$ , and if b < 0, then  $\boldsymbol{\xi} < 0$ , hence  $\min\{\boldsymbol{\xi},0\} = \boldsymbol{\xi}$ , so  $\tilde{T}(0) = \mathbf{E}[\boldsymbol{\xi}] = \mu$ .
  - (j) If  $\beta = 1$ , then  $\beta \tilde{T}(x) + x = \tilde{T}(x) + x$ , hence the assertion is true from (d).
- (k) Since  $\beta \tilde{T}(x) + x = \beta (\tilde{T}(x) + x) + (1 \beta)x$ , if  $\beta < 1$ , then  $(1 \beta)x$  is strictly increasing in x, hence the assertion is true from (d).
- (1) Let x > y and b > y. If  $x \ge b$ , then  $\tilde{T}(x) + x \ge \tilde{T}(b) + b > \tilde{T}(y) + y$  due to (d,e), and if b > x, then b > x > y, hence  $\tilde{T}(x) + x > \tilde{T}(y) + y$  due to (e).
  - (m) From (6.1.11(p.25)) we have

$$\begin{split} \lambda\beta\tilde{T}(\lambda\beta\mu+s)+s &= \lambda\beta\operatorname{\mathbf{E}}[\min\{\boldsymbol{\xi}-\lambda\beta\mu-s,0\}]+s\\ &= \operatorname{\mathbf{E}}[\min\{\lambda\beta\boldsymbol{\xi}-(\lambda\beta)^2\mu-\lambda\beta s,0\}]+s\\ &= \operatorname{\mathbf{E}}[\min\{\lambda\beta\boldsymbol{\xi}-(\lambda\beta)^2\mu+(1-\lambda\beta)s,s\}], \end{split}$$

which is nondecreasing in s and strictly increasing in s if  $\lambda \beta < 1$ .

(n) Evident from (2.2.2(p.12)). ■

#### A 1.2 $\mathscr{A}\{\tilde{L}_{\mathbb{R}}\}, \mathscr{A}\{\tilde{K}_{\mathbb{R}}\}, \mathscr{A}\{\tilde{\mathcal{L}}_{\mathbb{R}}\}, \text{ and } \tilde{\kappa}_{\mathbb{R}}$

From (6.1.13(p.25)) and (6.1.14(p.25)) and from Lemma A 1.1(p.298) (f) we obtain, noting (11.2.1(p.50)),

$$\tilde{L}(x) \begin{cases}
 = \lambda \beta \mu + s - \lambda \beta x \text{ on } [b, -\infty) & \cdots (1), \\
 < \lambda \beta \mu + s - \lambda \beta x \text{ on } (-\infty, b) & \cdots (2),
\end{cases}$$
(A 1.1)

$$\tilde{K}(x) \begin{cases}
 = \lambda \beta \mu + s - \delta x & \text{on } [b, \infty) & \cdots (1), \\
 < \lambda \beta \mu + s - \delta x & \text{on } (-\infty, b) & \cdots (2).
\end{cases}$$
(A 1.2)

 $<sup>^{\</sup>dagger}I(b\geq\boldsymbol{\xi})+I(\boldsymbol{\xi}>b)=1.$ 

In addition, from (6.1.14(p.25)) and Lemma A 1.1(p.298) (g) we have

$$\tilde{K}(x) \begin{cases}
< -(1-\beta)x + s & \text{on } (a,\infty) & \cdots (1), \\
= -(1-\beta)x + s & \text{on } (-\infty,a] & \cdots (2),
\end{cases}$$
(A 1.3)

hence we obtain

$$\tilde{K}(x) + x \le \beta x + s \quad \text{on} \quad (-\infty, \infty).$$
 (A 1.4)

Then, from (A 1.2 (1) (p.299)) and (A 1.3 (2) (p.300)) we get

$$\tilde{K}(x) + x = \begin{cases}
\lambda \beta \mu + s + (1 - \lambda)\beta x \text{ on } [b, \infty) & \cdots (1), \\
\beta x + s & \text{on } (-\infty, a] & \cdots (2).
\end{cases}$$
(A 1.5)

Since  $\tilde{K}(x) = \tilde{L}(x) - (1-\beta)x$  from (6.1.14(p.25)) and (6.1.13(p.25)), if  $x_{\tilde{L}}$  and  $x_{\tilde{K}}$  exist, then

$$\tilde{K}(x_{\tilde{L}}) = -(1-\beta) x_{\tilde{L}} \cdots (1), \qquad \tilde{L}(x_{\tilde{K}}) = (1-\beta) x_{\tilde{K}} \cdots (2). \tag{A 1.6}$$

### Lemma A 1.2 $(\mathscr{A}\{\tilde{L}_{\mathbb{R}}\})$

- (a)  $\tilde{L}(x)$  is continuous on  $(-\infty, \infty)$ .
- (b)  $\tilde{L}(x)$  is nonincreasing on  $(-\infty, \infty)$ .
- (c)  $\tilde{L}(x)$  is strictly decreasing on  $[a, \infty)$ .
- $\text{(d)} \quad \text{Let } s=0. \ \text{Then} \ \ x_{\tilde{L}}=a \ \text{where} \ \ x_{\tilde{L}}<(\geq) \ x \Leftrightarrow \tilde{L}\left(x\right)<(=) \ 0 \Rightarrow \tilde{L}\left(x\right)<(\geq) \ 0.$
- (e) Let s > 0.
  - 1.  $x_{\tilde{L}}$  uniquely exists with  $x_{\tilde{L}} > a$  where  $x_{\tilde{L}} < (=(>))$   $x \Leftrightarrow \tilde{L}(x) < (=(>))$  0.
  - 2.  $(\lambda \beta \mu + s)/\lambda \beta \ge (<) b \Leftrightarrow x_{\tilde{L}} = (<) (\lambda \beta \mu + s)/\lambda \beta \ge (<) b$ .
- *Proof* (a-c) Immediate from (6.1.13(p.25)) and Lemma A 1.1(p.298) (a-c).
- (d) Let s=0. Then, since  $\tilde{L}(x)=\lambda\beta\tilde{T}(x)$ , from Lemma A 1.1(p.298) (g) we have  $\tilde{L}(x)=0$  for  $a\geq x$  and  $\tilde{L}(x)<0$  for x>a, hence  $x_{\tilde{L}}=a$  by the definition of  $x_{\tilde{L}}$  (see Section 6.2(p.27) (b)), so  $x_{\tilde{L}}<(\geq) x\Rightarrow \tilde{L}(x)<(=) 0$ . The inverse is true by contraposition. In addition, since  $\tilde{L}(x)=0\Rightarrow \tilde{L}(x)\geq 0$ , we have  $\tilde{L}(x)<(=) 0\Rightarrow \tilde{L}(x)<(\geq) 0$ .
  - (e) Let s > 0.
- (e1) From (A 1.1 (1) (p.299)) and from  $\lambda > 0$  and  $\beta > 0$  we have  $\tilde{L}(x) < 0$  for a sufficiently large x > 0 such that  $x \ge b$ . In addition, we have  $\tilde{L}(a) = \lambda \beta \tilde{T}(a) + s = s > 0$  from Lemma A 1.1 (p.298) (g). Hence, from (c) it follows that  $x_{\tilde{L}}$  uniquely exists. The inequality  $x_{\tilde{L}} > a$  is immediate from  $\tilde{L}(a) > 0$  and (c). The latter half is evident.
- (e2) If  $(\lambda \beta \mu + s)/\lambda \beta \ge (<) b$ , from (A 1.1(p.299)) we have  $\tilde{L}((\lambda \beta \mu + s)/\lambda \beta) = (<) \lambda \beta \mu + s \lambda \beta (\lambda \beta \mu + s)/\lambda \beta = 0$ , hence  $x_{\tilde{L}} = (<) (\lambda \beta \mu + s)/\lambda \beta \ge (<) b$  from (e1).

#### Corollary A 1.1 $(\mathscr{A}\{\tilde{L}_{\mathbb{R}}\})$

- (a)  $x_{\tilde{L}} < (\geq) x \Leftrightarrow \tilde{L}(x) < (\geq) 0.$
- (b)  $x_{\tilde{L}} \leq (\geq) x \Rightarrow \tilde{L}(x) \leq (\geq) 0.$
- Proof (a) "\(\Rightarrow\)" is immediate from Lemma A 1.2(p.300) (d,e1). "\(\Limin\)" is evident by contraposition.
- (b) Since  $x_{\tilde{L}} < (\geq) x \Rightarrow \tilde{L}(x) < (\geq) 0$  due to (a) and since  $\tilde{L}(x) < (\geq) 0 \Rightarrow \tilde{L}(x) \leq (\geq) 0$ , we have  $x_{\tilde{L}} < (\geq) x \Rightarrow \tilde{L}(x) \leq (\geq) 0$ . In addition, if  $x_{\tilde{L}} = x$ , then  $\tilde{L}(x) = \tilde{L}(x_{\tilde{L}}) = 0$  or equivalently  $x_{\tilde{L}} = x \Rightarrow \tilde{L}(x) = 0$ , hence  $x_{\tilde{L}} = x \Rightarrow \tilde{L}(x) \leq 0$ . Accordingly, it follows that  $x_{\tilde{L}} \leq (\geq) x \Rightarrow \tilde{L}(x) \leq (\geq) 0$ .

#### Lemma A 1.3 $(\mathscr{A}\{\tilde{K}_{\mathbb{R}}\})$

- (a)  $\tilde{K}(x)$  is continuous on  $(-\infty, \infty)$ .
- (b)  $\tilde{K}(x)$  is nonincreasing on  $(-\infty, \infty)$ .
- (c)  $\tilde{K}(x)$  is strictly decreasing on  $[a, \infty)$ .
- (d)  $\tilde{K}(x)$  is strictly decreasing on  $(-\infty, \infty)$  if  $\beta < 1$ .
- (e)  $\tilde{K}(x) + x$  is nondecreasing on  $(-\infty, \infty)$ .
- (f)  $\tilde{K}(x) + x$  is strictly increasing on  $(-\infty, \infty)$  if  $\lambda < 1$ .
- (g)  $\tilde{K}(x) + x$  is strictly increasing on  $(-\infty, b]$ .
- (h) If x > y and b > y, then  $\tilde{K}(x) + x > \tilde{K}(y) + y$ .
- (i) Let  $\beta = 1$  and s = 0. Then  $x_{\tilde{K}} = a$  where  $x_{\tilde{K}} < (\geq) x \Leftrightarrow \tilde{K}(x) < (=) 0 \Rightarrow \tilde{K}(x) < (\geq) 0$ .
- (j) Let  $\beta < 1$  or s > 0.
  - 1. There uniquely exists  $x_{\tilde{K}}$  where  $x_{\tilde{K}} < (=(>)) x \Leftrightarrow \tilde{K}(x) < (=(>)) 0$ .

- 2.  $(\lambda \beta \mu + s)/\delta \ge (<) b \Leftrightarrow x_{\tilde{K}} = (<) (\lambda \beta \mu + s)/\delta$ .
- 3. Let  $\tilde{\kappa} < (=(>)) \ 0$ . Then  $x_{\tilde{\kappa}} < (=(>)) \ 0$ .  $\square$
- *Proof* (a-c) Immediate from (6.1.14(p.25)) and Lemma A 1.1(p.298) (a-c).
  - (d) Immediate from (6.1.14(p.25)) and Lemma A 1.1(p.298) (b).
  - (e) From (6.1.14(p.25)) we have

$$\tilde{K}(x) + x = \lambda \beta \tilde{T}(x) + \beta x + s = \lambda \beta (\tilde{T}(x) + x) + (1 - \lambda) \beta x + s \cdots (1),$$

hence the assertion holds from Lemma A 1.1(p.298) (d).

- (f) Obvious from (1) and Lemma A 1.1(p.298) (d).
- (g) Clearly from (1) and Lemma A 1.1(p.298) (e).
- (h) Let x > y and b > y. If  $x \ge b$ , then  $\tilde{K}(x) + x \ge \tilde{K}(b) + b > \tilde{K}(y) + y$  due to (e,g), and if b > x, then b > x > y, hence  $\tilde{K}(x) + x > \tilde{K}(y) + y$  due to (g). Thus, whether  $x \ge b$  or b > x, we have  $\tilde{K}(x) + x > \tilde{K}(y) + y$
- (i) Let  $\beta=1$  and s=0. Then, since  $\tilde{K}(x)=\lambda \tilde{T}(x)$  due to (6.1.14(p.25)), from Lemma A 1.1(p.28) (g) we have  $\tilde{K}(x)=0$  for  $a\geq x$  and  $\tilde{K}(x)<0$  for x>a, so  $x_{\tilde{K}}=a$  by the definition of  $x_{\tilde{K}}$  (see Section 6.2(p.27)(b)). Hence  $x_{\tilde{K}}<(\geq) \ x\Rightarrow \tilde{K}(x)<(=) \ 0$ . The inverse holds by contraposition. In addition, since  $\tilde{K}(x)=0\Rightarrow \tilde{K}(x)\geq 0$ , we have  $\tilde{K}(x)<(=) \ 0\Rightarrow \tilde{K}(x)<(\geq) \ 0$ .
  - (j) Let  $\beta < 1$  or s > 0.
  - (j1) This proof consists of the following six steps:
- First note (A 1.3 (2) (p.300)). If  $\beta < 1$ , then  $\tilde{K}(x) > 0$  for any sufficiently small x < 0 with  $x \ge a$  and if s > 0, then, whether  $\beta < 1$  or  $\beta = 1$ , we have  $\tilde{K}(x) > 0$  for any sufficiently small x < 0 with  $x \le a$ . Hence, whether  $\beta < 1$  or s > 0, we have  $\tilde{K}(x) > 0$  for any sufficiently small x < 0 with  $x \le a$ .
- Next note (A 1.2 (1) (p.299)). Then, since  $\delta > 0$  from (11.2.2 (1) (p.56)), whether  $\beta < 1$  or s > 0 we have K(x) < 0 for any sufficiently large x > 0 with  $x \ge b$ .
- Hence, whether  $\beta < 1$  or s > 0, it follows that there exists the solution  $x_K$ .
- Let  $\beta < 1$ . Then, the solution  $x_{\tilde{K}}$  is unique from (d).
- Let s>0. If  $\beta<1$ , the solution  $x_{\tilde{K}}$  is unique for the reason just above. If  $\beta=1$ , we have  $\tilde{K}(a)=s>0$  from (A 1.3 (2) (p.300)), hence  $x_{\tilde{K}}>a$  due to (c), so  $\tilde{K}(x)$  is strictly decreasing on the neighbourhood of  $x=x_{\tilde{K}}$  due to (c), thus the solution  $x_{\tilde{K}}$  is unique. Therefore, whether  $\beta<1$  or  $\beta=1$ , it follows that the solution  $x_{\tilde{K}}$  is unique.
- Hence, whether  $\beta < 1$  or s > 0, it follows that the solution  $x_{\tilde{K}}$  is unique.

From all the above, whether  $\beta < 1$  or s > 0, it eventually follows that the solution  $x_{\tilde{K}}$  uniquely exists.

- (j2) Let  $(\lambda \beta \mu + s)/\delta \ge (<)$  b. Then, from (A 1.2 (1(2)) (p.299)) we have  $\tilde{K}((\lambda \beta \mu + s)/\delta) = (<) \lambda \beta \mu + s \delta(\lambda \beta \mu + s)/\delta = 0$ , hence  $x_{\tilde{K}} = (<) (\lambda \beta \mu + s)/\delta$  due to (j1). The inverse is true by contraposition.
  - (j3) If  $\tilde{\kappa} < (=(>)) 0$ , then  $\tilde{K}(0) < (=(>)) 0$  from (6.1.17(p.25)), hence  $x_{\tilde{K}} < (=(>)) 0$  from (j1).

#### Corollary A 1.2 $(\mathscr{A}\{\tilde{K}_{\mathbb{R}}\})$

- (a)  $x_{\tilde{K}} < (\geq) x \Leftrightarrow \tilde{K}(x) < (\geq) 0.$
- (b)  $x_{\tilde{K}} \leq (\geq) x \Rightarrow \tilde{K}(x) \leq (\geq) 0.$
- Proof (a) Clearly  $x_{\tilde{K}} < (\geq) x \Rightarrow \tilde{K}(x) < (\geq) 0$  due to Lemma A 1.3(p.300) (i,j1). The inverse holds by contraposition.
- (b) Since  $x_{\tilde{K}} < (\geq) x \Rightarrow \tilde{K}(x) < (\geq) 0$  due to (a) and since  $\tilde{K}(x) < (\geq) 0 \Rightarrow \tilde{K}(x) \leq (\geq) 0$ , we have  $x_{\tilde{K}} < (\geq) x \Rightarrow \tilde{K}(x) \leq (\geq) 0$ . In addition, if  $x_{\tilde{K}} = x$ , then  $\tilde{K}(x) = \tilde{K}(x_{\tilde{K}}) = 0$  or equivalently  $x_{\tilde{K}} = x \Rightarrow \tilde{K}(x) = 0$ , hence  $x_{\tilde{K}} = x \Rightarrow \tilde{K}(x) \leq 0$ . Accordingly, it follows that  $x_{\tilde{K}} \leq (\geq) x \Rightarrow \tilde{K}(x) \leq (\geq) 0$ .

#### Lemma A 1.4 $(\mathscr{A}\{\tilde{L}_{\mathbb{R}}/\tilde{K}_{\mathbb{R}}\})$

- (a) Let  $\beta = 1$  and s = 0. Then  $x_{\tilde{L}} = x_{\tilde{K}} = a$ .
- (b) Let  $\beta = 1$  and s > 0. Then  $x_{\tilde{L}} = x_{\tilde{K}}$ .
- (c) Let  $\beta < 1$  and s = 0. Then  $a < (= (>)) 0 \Rightarrow x_{\tilde{L}} < (= (>)) x_{\tilde{K}} < (= (=)) 0$ .
- (d) Let  $\beta < 1$  and s > 0. Then  $\tilde{\kappa} < (=(>)) 0 \Rightarrow x_{\tilde{L}} < (=(>)) x_{\tilde{\kappa}} < (=(>)) 0$ .  $\square$
- Proof (a) If  $\beta=1$  and s=0, then  $x_{\tilde{L}}=a$  from Lemma A 1.2(p.300) (d) and  $x_{\tilde{K}}=a$  from Lemma A 1.3(p.300) (i), hence  $x_{\tilde{L}}=x_{\tilde{K}}=a$ .
  - (b) Let  $\beta = 1$  and s > 0. Then  $\tilde{K}(x_{\tilde{L}}) = 0$  from (A 1.6 (1) (p.300)), hence  $x_{\tilde{K}} = x_{\tilde{L}}$  from Lemma A 1.3(p.300) (j1).
  - (c) Let  $\beta < 1$  and s = 0. Then  $x_{\tilde{L}} = a \cdots (1)$  from Lemma A 1.2(p300) (d).
- o If a < 0, then  $x_{\tilde{L}} < 0$ , hence  $\tilde{K}(x_{\tilde{L}}) > 0$  from (A 1.6 (1) (p.300)), hence  $x_{\tilde{L}} < x_{\tilde{K}}$  from Lemma A 1.3(p.300) (j1), and if a = (>) 0, then  $x_{\tilde{L}} = (>)$  0, hence  $\tilde{K}(x_L) = (<)$  0 from (A 1.6 (1) (p.300)), so  $x_{\tilde{L}} = (>)$   $x_{\tilde{K}}$  from Lemma A 1.3(p.300) (j1). Accordingly, we have " $\Rightarrow$ " holds and its inverse " $\Leftarrow$ " is immediate by contraposition. Thus the first relation " $\Leftrightarrow$ " holds.

- $\circ \ \text{If } a < 0, \text{ from } (6.1.17(\texttt{p.25})) \text{ we have } \tilde{K}(0) = \lambda \beta \tilde{T}(0) < 0 \text{ due to Lemma A } 1.1(\texttt{p.298})(\texttt{g}), \text{ hence } x_{\tilde{K}} < 0 \cdots \texttt{(2)} \text{ from Lemma A } 1.3(\texttt{p.300})(\texttt{j1}), \\ \text{and if } a = (>) \ 0, \text{ from } (6.1.17(\texttt{p.25})) \text{ we have } \tilde{K}(0) = \lambda \beta \tilde{T}(0) = 0 \text{ due to Lemma A } 1.1(\texttt{p.298})(\texttt{g}), \text{ hence } x_{\tilde{K}} = 0 \text{ from Lemma A } 1.3(\texttt{p.300})(\texttt{j1}) \\ \text{or equivalently } x_{\tilde{K}} = (=) \ 0. \text{ Accordingly, we have the } second \ relation \ "\Rightarrow".$
- (d) Let  $\beta < 1$  and s > 0. Now, since  $\tilde{\kappa} = \tilde{K}(0)$  from (6.1.17(p25)), if  $\tilde{\kappa} < (=(>))$  0, then  $\tilde{K}(0) < (=(>))$  0, thus  $x_{\tilde{K}} < (=(>))$  0 ··· (3) from Lemma A 1.3(p.300) (j1). Accordingly  $\tilde{L}(x_{\tilde{K}}) < (=(>))$  0 from (A 1.6 (2) (p.300)), hence  $x_{\tilde{L}} < (=(>))$   $x_{\tilde{K}}$  from Lemma A 1.2(p.300) (e1). Thus " $\Rightarrow$ " holds and its inverse " $\Leftarrow$ " is immediate by contraposition. The last " $\Rightarrow$ " is immediate from (3).

#### Lemma A 1.5 $(\mathscr{A}\{\tilde{\mathcal{L}}_{\mathbb{R}}\})$

- (a)  $\tilde{\mathcal{L}}(s)$  is nondecreasing in s and strictly increasing in s if  $\lambda \beta < 1$ .
- (b) Let  $\lambda \beta \mu \leq a$ .
  - 1.  $x_{\tilde{L}} \geq \lambda \beta \mu + s$ .
  - 2. Let s > 0 and  $\lambda \beta < 1$ . Then  $x_{\tilde{L}} > \lambda \beta \mu + s$ .
- (c) Let  $\lambda \beta \mu > a$ . Then, there exists a  $s_{\tilde{L}} > 0$  such that if  $s_{\tilde{L}} > (\leq) s$ , then  $x_{\tilde{L}} < (\geq) \lambda \beta \mu + s$ .  $\square$
- **Proof** (a) From (6.1.15(p.25)) and (6.1.13(p.25)) we have  $\tilde{\mathcal{L}}(s) = \tilde{L}(\lambda\beta\mu + s) = \lambda\beta\tilde{T}(\lambda\beta\mu + s) + s\cdots$  (1), hence the assertion holds from Lemma A 1.1(p.298) (m).
  - (b) Let  $\lambda \beta \mu < a$ . Then, from (1) we have  $\tilde{\mathcal{L}}(0) = \lambda \beta \tilde{T}(\lambda \beta \mu) = 0 \cdots$  (2) due to Lemma A 1.1(p.298) (g).
- (b1) Since  $s \geq 0$ , from (a) we have  $\tilde{\mathcal{L}}(s) \geq \tilde{\mathcal{L}}(0) = 0$  due to (2) or equivalently  $\tilde{\mathcal{L}}(\lambda\beta\mu + s) \geq 0$  due to (1), hence  $x_{\tilde{\mathcal{L}}} \geq \lambda\beta\mu + s$  from Corollary A 1.1(p.300) (a).
- (b2) Let s > 0 and  $\lambda \beta < 1$ . Then, from (a) we have  $\tilde{\mathcal{L}}(s) > \tilde{\mathcal{L}}(0) = 0 \cdots$  (3) due to (2) or equivalently  $\tilde{\mathcal{L}}(\lambda \beta \mu + s) > 0$ , hence  $x_{\tilde{\mathcal{L}}} > \lambda \beta \mu + s$  from Lemma A 1.2(p.300) (e1).
- (c) Let  $\lambda\beta\mu > a$ . From (1) we have  $\tilde{\mathcal{L}}(0) = \lambda\beta\tilde{T}(\lambda\beta\mu) < 0$  due to Lemma A 1.1(p.298)(g). Noting (A 1.1(1)(p.299)), for any sufficiently large s>0 such that  $\lambda\beta\mu + s\geq b$  and  $\lambda\beta\mu + s>0$  we have  $\tilde{\mathcal{L}}(s) = \tilde{L}(\lambda\beta\mu + s) = \lambda\beta\mu + s \lambda\beta(\lambda\beta\mu + s) = (1-\lambda\beta)(\lambda\beta\mu + s)\geq 0$ . Accordingly, due to (a) it follows that there exists the solution  $s_{\tilde{\mathcal{L}}}>0$  of  $\tilde{\mathcal{L}}(s)=0$ . Then  $\tilde{\mathcal{L}}(s)<0$  for  $s< s_{\tilde{\mathcal{L}}}$  and  $\tilde{\mathcal{L}}(s)\geq 0$  for  $s\geq s_{\tilde{\mathcal{L}}}$  or equivalently  $\tilde{L}(\lambda\beta\mu + s)<0$  for  $s< s_{\tilde{\mathcal{L}}}$  and  $\tilde{L}(\lambda\beta\mu + s)\geq 0$  for  $s\geq s_{\tilde{\mathcal{L}}}$ . Hence, from Corollary A 1.1(p.300) (a) we get  $s_{\tilde{\mathcal{L}}}<\lambda\beta\mu + s$  for  $s< s_{\tilde{\mathcal{L}}}$  and  $s_{\tilde{\mathcal{L}}}>\lambda\beta\mu + s$  for  $s\geq s_{\tilde{\mathcal{L}}}$ .

#### Lemma A 1.6 $(\tilde{\kappa}_{\mathbb{R}})$ We have:

- (a)  $\tilde{\kappa} = s \text{ if } a > 0 \text{ and } \tilde{\kappa} = \lambda \beta \mu + s \text{ if } b < 0.$
- (b) Let  $\beta < 1$  or s > 0. Then  $\tilde{\kappa} < (=(>)) 0 \Leftrightarrow x_{\tilde{\kappa}} < (=(>)) 0$ .
- *Proof* (a) Immediate from (6.1.16(p.25)) and Lemma A 1.1(p.298) (i).
- (b) Let  $\beta < 1$  or s > 0. Then, if  $\tilde{\kappa} < (=(>))$  0, we have  $\tilde{K}(0) < (=(>))$  0 from (6.1.17(p.25)), hence  $x_{\tilde{K}} < (=(>))$  0 from Lemma A 1.3(p.300) (j3). Thus " $\Rightarrow$ " was proven. Its inverse " $\Leftarrow$ " is immediate by contraposition.

# A 2 Direct Proof of Underlying Functions of Type $\mathbb{P}$

#### $\mathbf{A} \ \mathbf{2.1} \quad \mathscr{A} \{T_{\mathbb{P}}\}$

For convenience of reference, below let us copy Lemma 14.2.1(p.93).

#### **Lemma A 2.1** $(\mathscr{A}\{T_{\mathbb{P}}\})$ For any $F \in \mathscr{F}$ we have:

- (a) T(x) is continuous on  $(-\infty, \infty)$ .
- (b) T(x) is nonincreasing on  $(-\infty, \infty)$ .
- (c) T(x) is strictly decreasing on  $(-\infty, b]$ .
- (d) T(x) + x is nondecreasing on  $(-\infty, \infty)$ .
- (e) T(x) + x is strictly increasing on  $[a^*, \infty)$ .
- (f) T(x) = a x on  $(-\infty, a^*]$  and T(x) > a x on  $(a^*, \infty)$ .
- (g) T(x) > 0 on  $(-\infty, b)$  and T(x) = 0 on  $[b, \infty)$ .
- (h)  $T(x) \ge \max\{0, a x\}$  on  $(-\infty, \infty)$ .
- (i)  $T(0) = a \text{ if } a^* > 0 \text{ and } T(0) = 0 \text{ if } b < 0.$
- (j)  $\beta T(x) + x$  is nondecreasing on  $(-\infty, \infty)$  if  $\beta = 1$ .
- (k)  $\beta T(x) + x$  is strictly increasing on  $(-\infty, \infty)$  if  $\beta < 1$ .
- (1) If x < y and  $a^* < y$ , then T(x) + x < T(y) + y.
- (m)  $\lambda \beta T(\lambda \beta a s) s$  is nonincreasing in s and strictly decreasing in s if  $\lambda \beta < 1$ .
- (n)  $a^* < a$ .  $\square$

## **A 2.2** $\mathscr{A}\{L_{\mathbb{P}}\},\,\mathscr{A}\{K_{\mathbb{P}}\},\,\mathscr{A}\{\mathcal{L}_{\mathbb{P}}\},\,\mathrm{and}\,\,\kappa_{\mathbb{P}}$

Noting Lemma A 2.1(p.302) (f), from (6.1.20(p.26)) and (6.1.21(p.26)) we obtain

$$L(x) \begin{cases} = \lambda \beta a - s - \lambda \beta x & \text{on } (-\infty, a^*] & \cdots (1), \\ > \lambda \beta a - s - \lambda \beta x & \text{on } (a^*, \infty) & \cdots (2), \end{cases}$$
(A 2.1)

$$K(x) \begin{cases} = \lambda \beta a - s - \delta x & \text{on } (-\infty, a^{\star}] & \cdots (1), \\ > \lambda \beta a - s - \delta x & \text{on } (a^{\star}, \infty) & \cdots (2). \end{cases}$$
(A 2.2)

In addition, from (6.1.21(p.26)) and Lemma A 2.1(p.302) (g) we have

$$K(x) \begin{cases} > -(1-\beta)x - s & \text{on } (-\infty, b) & \cdots (1), \\ = -(1-\beta)x - s & \text{on } [b, \infty) & \cdots (2), \end{cases}$$
(A 2.3)

from which we obtain

$$K(x) + x \ge \beta x - s$$
 on  $(-\infty, \infty)$ . (A 2.4)

Then, from (A 2.2 (1) (p.303)) and (A 2.3 (2) (p.303)) we get

$$K(x) + x = \begin{cases} \lambda \beta a - s + (1 - \lambda) \beta x \text{ on } (-\infty, a^*] & \cdots (1), \\ \beta x - s & \text{on } [b, \infty) & \cdots (2). \end{cases}$$
(A 2.5)

Since  $K(x) = L(x) - (1 - \beta)x$  from (6.1.21(p.26)) and (6.1.20(p.26)), if  $x_L$  and  $x_K$  exist, then

$$K(x_L) = -(1 - \beta) x_L \cdots (1), \quad L(x_K) = (1 - \beta) x_K \cdots (2).$$
 (A 2.6)

#### Lemma A 2.2 $(\mathscr{A}\{L_{\mathbb{P}}\})$

- (a) L(x) is continuous on  $(-\infty, \infty)$ .
- (b) L(x) is nonincreasing on  $(-\infty, \infty)$ .
- (c) L(x) is strictly decreasing on  $(-\infty, b]$ .
- (d) Let s = 0. Then  $x_L = b$  where  $x_L > (\leq) x \Leftrightarrow L(x) > (=) 0 \Rightarrow L(x) > (\leq) 0$ .
- (e) Let s > 0.
  - 1.  $x_L$  uniquely exists with  $x_L < b$  where  $x_L > (= (<)) x \Leftrightarrow L(x) > (= (<)) 0$ .
  - 2.  $(\lambda \beta a s)/\lambda \beta \leq (>) a^* \Leftrightarrow x_L = (>) (\lambda \beta a s)/\lambda \beta > (\leq) a^*$ .  $\square$
- *Proof* (a-c) Immediate from (6.1.20(p.26)) and Lemma A 2.1(p.302) (a-c).
- (d) Let s=0. Then, since  $L(x)=\lambda\beta T(x)$ , from Lemma A 2.1(p.302) (g) we have L(x)>0 for x< b and L(x)=0 for  $b\leq x$ , hence  $x_L=b$  by the definition of  $x_L$  (see Section 6.2(p.27) (a)), thus  $x_L>(\leq)x\Rightarrow L(x)>(=)0$ . The inverse is true by contraposition. In addition, since  $L(x)=0\Rightarrow L(x)\leq 0$ , we have  $L(x)>(=)0\Rightarrow L(x)>(\leq)0$ .
  - (e) Let s > 0.
- (e1) From (A 2.1 (1) (p.303)) and from  $\lambda > 0$  and  $\beta > 0$  we have L(x) > 0 for a sufficiently small x < 0 such that  $x \le a^*$ . In addition, we have  $L(b) = \lambda \beta T(b) s = -s < 0$  from Lemma A 2.1(p.302) (g). Hence, from (a,c) it follows that  $x_L$  uniquely exists. The inequality  $x_L < b$  is immediate from L(b) < 0. The latter half is evident.
- (e2) If  $(\lambda \beta a s)/\lambda \beta \le (>) a^*$ , from (A 2.1 (1(2)) (p.303)) we have  $L((\lambda \beta a s)/\lambda \beta) = (>) \lambda \beta a s \lambda \beta (\lambda \beta a s)/\lambda \beta = 0$ , hence  $x_L = (>) (\lambda \beta a s)/\lambda \beta$  from (e1).

# Corollary A 2.1 $(\mathscr{A}\{L_{\mathbb{P}}\})$

- (a)  $x_L > (\leq) x \Leftrightarrow L(x) > (\leq) 0$ .
- (b)  $x_L \ge (\le) x \Rightarrow L(x) \ge (\le) 0.$
- Proof (a) "⇒" is immediate from Lemma A 2.2(p.303) (d,e2). "←" is evident by contraposition.
- (b) Since  $x_L > (\leq) x \Rightarrow L(x) > (\leq) 0$  due to (a) and since  $L(x) > (\leq) 0 \Rightarrow L(x) \geq (\leq) 0$ , we have  $x_L > (\leq) x \Rightarrow L(x) \geq (\leq) 0$ . In addition, if  $x_L = x$ , then  $L(x) = L(x_L) = 0$  or equivalently  $x_L = x \Rightarrow L(x) = 0$ , hence  $x_L = x \Rightarrow L(x) \geq 0$ . Accordingly, it follows that  $x_L \geq (\leq) x \Rightarrow L(x) \geq (\leq) 0$ .

#### Lemma A 2.3 $(\mathscr{A}\{K_{\mathbb{P}}\})$

- (a) K(x) is continuous on  $(-\infty, \infty)$ .
- (b) K(x) is nonincreasing on  $(-\infty, \infty)$ .
- (c) K(x) is strictly decreasing on  $(-\infty, b]$ .
- (d) K(x) is strictly decreasing on  $(-\infty, \infty)$  if  $\beta < 1$ .
- (e) K(x) + x is nondecreasing on  $(-\infty, \infty)$ .

- (f) K(x) + x is strictly increasing on  $(-\infty, \infty)$  if  $\lambda < 1$ .
- (g) K(x) + x is strictly increasing on  $[a^*, \infty)$ .
- (h) If x < y and  $a^* < y$ , then K(x) + x < K(y) + y.
- (i) Let  $\beta = 1$  and s = 0. Then  $x_K = b$  where  $x_K > (\leq) x \Leftrightarrow K(x) > (=) 0 \Rightarrow K(x) > (\leq) 0$ .
- (j) Let  $\beta < 1$  or s > 0.
  - 1. There uniquely exists  $x_K$  where  $x_K > (= (<)) x \Leftrightarrow K(x) > (= (<)) 0$ .
  - 2.  $(\lambda \beta a s)/\delta \le (>) a^* \Leftrightarrow x_K = (>) (\lambda \beta a s)/\delta$ .
  - 3. Let  $\kappa > (=(<)) \ 0$ . Then  $x_K > (=(<)) \ 0$ .  $\square$
- *Proof* (a-c) Immediate from (6.1.21(p.26)) and Lemma A 2.1(p.302) (a-c).
  - (d) Immediate from (6.1.21(p.26)) and Lemma A 2.1(p.302) (b).
- (e) From (6.1.21(p.26)) we have  $K(x) + x = \lambda \beta T(x) + \beta x s = \lambda \beta (T(x) + x) + (1 \lambda)\beta x s \cdots (1)$ , hence the assertion holds from Lemma A 2.1(p.302) (d).
  - (f) Obvious from (1) and Lemma A 2.1(p.302) (d).
  - (g) Clearly from (1) and Lemma A 2.1(p.302) (e).
- (h) Let x < y and  $a^\star < y$ . If  $x \le a^\star$ , then  $K(x) + x \le K(a^\star) + a^\star < K(y) + y$  due to (e,g). If  $a^\star < x$ , then  $a^\star < x < y$ , hence K(x) + x < K(y) + y due to (g). Thus, whether  $x \le a^\star$  or  $a^\star < x$ , we have K(x) + x < K(y) + y
- (i) Let  $\beta = 1$  and s = 0. Then, since  $K(x) = \lambda T(x)$  due to (6.1.21 (p.30)), from Lemma A 2.1 (p.302) (g) we have K(x) = 0 for  $b \le x$  and K(x) > 0 for x < b, so that  $x_K = b$  due to the definition in Section 6.2(p.27) (a). Hence  $x_K > (\le) x \Rightarrow K(x) > (=) 0$ . The inverse holds by contraposition. In addition, since  $K(x) = 0 \Rightarrow K(x) \le 0$ , we have  $K(x) > (=) 0 \Rightarrow K(x) > (\le) 0$ .
  - (j) Let  $\beta < 1$  or s > 0.
  - (j1) This proof consists of the following six steps:
- First note (A 2.3 (2) (p.303)). If  $\beta < 1$ , then K(x) < 0 for any sufficiently large x > 0 with  $x \ge b$  and if s > 0, then, whether  $\beta < 1$  or  $\beta = 1$ , we have K(x) < 0 for any sufficiently large x > 0 with  $x \ge b$ . Hence, whether  $\beta < 1$  or s > 0, we have K(x) < 0 for any sufficiently large x > 0 with  $x \ge b$ .
- Next note (A 2.2 (1) (p.303)). Then, since  $\delta > 0$  from (11.2.2 (1) (p.56)), whether  $\beta < 1$  or s > 0 we have K(x) > 0 for any sufficiently small x < 0 with  $x \le a^*$ .
- Hence, whether  $\beta < 1$  or s > 0, it follows that there exists the solution  $x_K$ .
- Let  $\beta < 1$ . Then, the solution  $x_K$  is unique from (d).
- o Let s > 0. If  $\beta < 1$ , the solution  $x_K$  is unique for the reason just above. If  $\beta = 1$ , we have K(b) = -s < 0 from (A 2.3 (2) (p.30)), hence  $x_K < b$  due to (c), so K(x) is strictly decreasing on the neighbourhood of  $x = x_K$  due to (c), thus the solution  $x_K$  is unique. Therefore, whether  $\beta < 1$  or  $\beta = 1$ , it follows that the solution  $x_K$  is unique.
- Hence, whether  $\beta < 1$  or s > 0, it follows that the solution  $x_K$  is unique.

From all the above, whether  $\beta < 1$  or s > 0, it eventually follows that the solution  $x_K$  uniquely exists.

- (j2) Let  $(\lambda \beta a s)/\delta \le (>) a^*$ . Then, from (A 2.2 (1(2)) (p.303)) we have  $K((\lambda \beta a s)/\delta) = (>) \lambda \beta a s \delta(\lambda \beta a s)/\delta = 0$ , hence  $x_K = (>) (\lambda \beta a s)/\delta$  due to (j1). The inverse is true by contraposition.
  - (j3) If  $\kappa > (= (<)) 0$ , then K(0) > (= (<)) 0 from (6.1.24(p.26)), hence  $x_K > (= (<)) 0$  from (j1).

#### Corollary A 2.2 $(\mathscr{A}\{K_{\mathbb{P}}\})$

- (a)  $x_K > (\leq) x \Leftrightarrow K(x) > (\leq) 0$ .
- (b)  $x_K \ge (\le) x \Rightarrow K(x) \ge (\le) 0.$
- Proof (a) Clearly  $x_K > (\leq) x \Rightarrow K(x) > (\leq) 0$  due to Lemma A 2.3(p.303) (i,j1). The inverse holds by contraposition.
- (b) Since  $x_K > (\leq) x \Rightarrow K(x) > (\leq) 0$  due to (a) and since  $K(x) > (\leq) 0 \Rightarrow K(x) \geq (\leq) 0$ , we have  $x_K > (\leq) x \Rightarrow K(x) \geq (\leq) 0$ . In addition, if  $x_K = x$ , then  $K(x) = K(x_K) = 0$  or equivalently  $x_K = x \Rightarrow K(x) = 0$ , hence  $x_K = x \Rightarrow K(x) \geq 0$ . Accordingly, it follows that  $x_K \geq (\leq) x \Rightarrow K(x) \geq (\leq) 0$ .

#### Lemma A 2.4 $(\mathscr{A}\{L_{\mathbb{P}}/K_{\mathbb{P}}\})$

- (a) Let  $\beta = 1$  and s = 0. Then  $x_L = x_K = b$ .
- (b) Let  $\beta = 1$  and s > 0. Then  $x_L = x_K$ .
- (c) Let  $\beta < 1$  and s = 0. Then  $b > (= (<)) \ 0 \Rightarrow x_L > (= (<)) \ x_K > (= (=)) \ 0$ .
- (d) Let  $\beta < 1$  and s > 0. Then  $\kappa > (= (<)) \ 0 \Rightarrow x_L > (= (<)) \ x_K > (= (<)) \ 0$ .  $\square$
- Proof (a) If  $\beta=1$  and s=0, then  $x_L=b$  from Lemma A 2.2(p.303) (d) and  $x_K=b$  from Lemma A 2.3(p.303) (i), hence  $x_L=x_K=b$ .
- (b) Let  $\beta = 1$  and s > 0. Then  $K(x_L) = 0$  from (A 2.6 (1) (p.303)), hence  $x_K = x_L$  from Lemma A 2.3(p.303) (j1).
  - (c) Let  $\beta < 1$  and s = 0. Then  $x_L = b \cdots (1)$  from Lemma A 2.2(p.303) (d).

- o If b > 0, then  $x_L > 0$ , hence  $K(x_L) < 0$  from (A 2.6 (1) (p.303)), so  $x_L > x_K$  from Lemma A 2.3 (p.303) (j1), and if b = (<) 0, then  $x_L = (<) 0$ , hence  $K(x_L) = (>) 0$  from (A 2.6 (1) (p.303)), so  $x_L = (<) x_K$  from Lemma A 2.3 (p.303) (j1). Accordingly, we have " $\Rightarrow$ " holds and its inverse " $\Leftarrow$ " is immediate by contraposition. Thus the first relation " $\Leftrightarrow$ " holds.
- o If b > 0, from (6.1.24(p.26)) we have  $K(0) = \lambda \beta T(0) > 0$  due to Lemma A 2.1(p.302) (g), hence  $x_K > 0 \cdots$  (2) from Lemma A 2.3(p.303) (j1), and if b = (<) 0, from (6.1.24(p.26)) we have  $K(0) = \lambda \beta T(0) = 0$  due to Lemma 22.2.1(p.237) (g), hence  $x_K = 0$  from Lemma A 2.3(p.303) (??) or equivalently  $x_K = (=) 0$ . Accordingly, we have the second relation " $\Rightarrow$ ".
- (d) Let  $\beta < 1$  and s > 0. Now, from (6.1.24(p.26)) and (6.1.23(p.26)), if  $\kappa > (= (<)) 0$ , then K(0) > (= (<)) 0, thus  $x_K > (= (<)) 0$  from Lemma A 2.3(p.303) (j1). Accordingly  $L(x_K) > (= (<)) 0$  from (A 2.6(2)(p.303)), hence  $x_L > (= (<)) x_K$  from Lemma A 2.2(p.303) (e1).

#### Lemma A 2.5 $(\mathscr{A}\{\mathcal{L}_{\mathbb{P}}\})$

- (a)  $\mathcal{L}(s)$  is nonincreasing in s and is strictly decreasing in s if  $\lambda \beta < 1$ .
- (b) Let  $\lambda \beta a \geq b$ .
  - 1.  $x_L \leq \lambda \beta a s$ .
  - 2. Let s > 0 and  $\lambda \beta < 1$ . Then  $x_L < \lambda \beta a s$ .
- (c) Let  $\lambda \beta a < b$ . Then, there exists a  $s_{\mathcal{L}} > 0$  such that if  $s_{\mathcal{L}} > (\leq) s$ , then  $x_{\mathcal{L}} > (\leq) \lambda \beta a s$ .  $\square$
- Proof (a) From (6.1.22(p.26)) and (6.1.20(p.26)) we have  $\mathcal{L}(s) = L(\lambda \beta a s) = \lambda \beta T(\lambda \beta a s) s$ , hence the assertion holds from Lemma A 2.1(p.302) (m).
- (b) Let  $\lambda \beta a \geq b$ . Then, from (6.1.22(p.26)) and (6.1.20(p.26)) we have  $\mathcal{L}(0) = L(\lambda \beta a) = \lambda \beta T(\lambda \beta a) = 0 \cdots (1)$  due to Lemma A 2.1(p.302) (g).
- (b1) Since  $s \ge 0$ , from (a) we have  $\mathcal{L}(s) \le \mathcal{L}(0) = 0$  due to (1) or equivalently  $L(\lambda \beta a s) \le 0$ , hence  $x_L \le \lambda \beta a s$  from Corollary A 2.1(p.303) (a).
- (b2) Let s > 0 and  $\lambda \beta < 1$ . Then, from (a) we have  $\mathcal{L}(s) < \mathcal{L}(0) = 0$  due to (1) or equivalently  $L(\lambda \beta a s) < 0$ , thus  $x_L < \lambda \beta a s$  from Lemma A 2.2(p.303) (e1).
- (c) Let  $\lambda\beta a < b$ . From (6.1.22(p.26)) we have  $\mathcal{L}(0) = \lambda\beta T(\lambda\beta a) > 0$  due to Lemma A 2.1(p.302) (g). Noting (A 2.1 (1) (p.303)), for any sufficiently large s > 0 such that  $\lambda\beta a s \le a^*$  and  $\lambda\beta a s < 0$  we have  $\mathcal{L}(s) = L(\lambda\beta a s) = \lambda\beta a s \lambda\beta(\lambda\beta a s) = (1 \lambda\beta)(\lambda\beta a s) \le 0$ . Accordingly, due to (a) it follows that there exists the solution  $s_{\mathcal{L}} > 0$  of  $\mathcal{L}(s) = 0$ . Then  $\mathcal{L}(s) > 0$  for  $s < s_{\mathcal{L}}$  and  $\mathcal{L}(s) \le 0$  for  $s \ge s_{\mathcal{L}}$  or equivalently  $L(\lambda\beta a s) > 0$  for  $s < s_{\mathcal{L}}$  and  $L(\lambda\beta a s) \le 0$  for  $s \ge s_{\mathcal{L}}$ . Hence, from Corollary A 2.1(p.303) (a) we get  $x_{\mathcal{L}} > \lambda\beta a s$  for  $s < s_{\mathcal{L}}$  and  $x_{\mathcal{L}} \le \lambda\beta a s$  for  $s \ge s_{\mathcal{L}}$ .

#### Lemma A 2.6 ( $\mathscr{A}\{\kappa_{\mathbb{P}}\}$ ) We have:

- (a)  $\kappa = \lambda \beta a s \text{ if } a^* > 0 \text{ and } \kappa = -s \text{ if } b < 0.$
- (b) Let  $\beta < 1$  or s > 0, Then  $\kappa > (= (<)) 0 \Leftrightarrow x_K > (= (<)) 0$ .  $\square$
- Proof (a) Immediate from (6.1.23(p.26)) and Lemma A 2.1(p.302) (i).
- (b) Let  $\beta < 1$  or s > 0. Then, if  $\kappa > (=(<))$  0, we have K(0) > (=(<)) 0 from (6.1.24(p.26)), hence  $x_{\kappa} > (=(<))$  0 from Lemma A 2.3(p.303) (j1). Thus " $\Rightarrow$ " was proven. Its inverse " $\Leftarrow$ " is immediate by contraposition.

# A 3 Direct Proof of Underlying Functions of $\tilde{\mathbf{T}}\mathbf{ype}~\mathbb{P}$

#### $\mathbf{A} \ \mathbf{3.1} \quad \mathscr{A} \{ \tilde{T}_{\mathbb{P}} \}$

#### Lemma A 3.1

- (a) Let  $x \le a$ . Then z(x) = a
- (b) Let a < x. Then a < z(x) < x.
- (c)  $z(x) \leq b$  for any x.  $\square$
- Proof (a) Let  $x \le a$ . If  $a < z \cdots (II)$ , then x < z, hence  $\tilde{p}(z)(z x) > 0$  due to (6.1.41 (2) (p.27)), and if  $z \le a \cdots (I)$ , then  $\tilde{p}(z)(z x) = 0$  due to (6.1.41 (1) (p.27)) (see Figure A 3.1(p.305) below). Hence z(x) = a due to Def. 6.1.2(p.27).



Figure A 3.1: Case  $x \leq a$ 

(b) Let a < x. If  $x \le z \cdots$  (III), then  $\tilde{p}(z)(z-x) \ge 0$ , if  $a < z < x \cdots$  (II), then  $\tilde{p}(z)(z-x) < 0$  due to (6.1.41 (2) (p.27)), and if  $z \le a \cdots$  (I), then  $\tilde{p}(z)(z-x) = 0$  due to (6.1.41 (1) (p.27)) (see Figure A 3.2(p.306) below). Hence, z(x) is given by z on a < z < x, i.e., a < z(x) < x.



Figure A 3.2: Case a < x

(c) Assume that z(x) > b for a certain x. Then, since  $\tilde{p}(z(x)) = 1 = \tilde{p}(b)$  due to (6.1.42(2) (p27)), from (6.1.38(p27)) we have  $\tilde{T}(x) = z(x) - x > b - x = \tilde{p}(b)(b - x) \ge \tilde{T}(x)$ , which is a contradiction. Hence, it must be that  $z(x) \le b$  for any x.

Corollary A 3.1  $a \le z(x) \le b$  for any x.  $\square$ 

• Proof Evident from Lemma A 3.1(p.305).

**Lemma A 3.2**  $\tilde{p}(z)$  is nondecreasing on  $(-\infty, \infty)$  and strictly increasing in  $z \in [a, b]$ .  $\square$ 

• Proof The former half is immediate from (6.1.31(p.26)). For  $a \le z' < z \le b$  we have  $\tilde{p}(z) - \tilde{p}(z') = \Pr\{\xi \le z\} - \Pr\{\xi \le z'\} = \Pr\{z' < \xi \le z\} = \int_{z'}^{z} f(\xi)d\xi > 0$  (See (2.2.3 (2) (p.13) )), hence p(z) > p(z'), i.e., p(z) is strictly increasing on [a, b]. ■

**Lemma A 3.3** z(x) is nondecreasing on  $(-\infty, \infty)$ .  $\square$ 

• Proof From (6.1.38(p.27)), for any x and y we have

$$\begin{split} \tilde{T}(x) &= \tilde{p}(z(x))(z(x) - x) \\ &= \tilde{p}(z(x))(z(x) - y) - (x - y)\tilde{p}(z(x)) \\ &\geq \tilde{T}(y) - (x - y)\tilde{p}(z(x)) \\ &= \tilde{p}(z(y))(z(y) - y) - (x - y)\tilde{p}(z(x)) \\ &= \tilde{p}(z(y))\big(z(y) - x + (x - y)\big) - (x - y)\tilde{p}(z(x)) \\ &= \tilde{p}(z(y))(z(y) - x) + (x - y)(\tilde{p}(z(y)) - \tilde{p}(z(x))) \\ &\geq \tilde{T}(x) + (x - y)(\tilde{p}(z(y)) - \tilde{p}(z(x))). \end{split}$$

Hence  $0 \ge (x-y)(\tilde{p}(z(y))-\tilde{p}(z(x)))$ . Let x>y. Then  $0 \ge \tilde{p}(z(y))-\tilde{p}(z(x))$  or equivalently  $\tilde{p}(z(x)) \ge \tilde{p}(z(y))\cdots$  (1). Since  $a \le z(x) \le b$  and  $a \le z(y) \le b$  from Corollary A 3.1(p306), if z(x) < z(y), then  $\tilde{p}(z(x)) < \tilde{p}(z(y))$  from Lemma A 3.2(p306), which contradicts (1). Hence, it must be that  $z(x) \ge z(y)$ , i.e., z(x) is nondecreasing in  $x \in (-\infty, \infty)$ .

#### Lemma A 3.4

- (a)  $\tilde{T}(x)$  is continuous on  $(-\infty, \infty)$ .
- (b)  $\tilde{T}(x)$  is nonincreasing on  $(-\infty, \infty)$ .
- (c)  $\tilde{T}(x)$  is strictly decreasing on  $[a, \infty)$ .
- (d)  $\tilde{T}(x) < 0$  on  $(a, \infty)$  and  $\tilde{T}(x) = 0$  on  $(-\infty, a]$ .
- (e)  $\tilde{T}(x) \leq b x$  on  $(-\infty, \infty)$ .
- (f)  $\tilde{T}(x) + x$  is nondecreasing on  $(-\infty, \infty)$ .
- (g)  $\beta \tilde{T}(x) + x$  is nondecreasing on  $(-\infty, \infty)$  if  $\beta = 1$ .
- (h)  $\beta \tilde{T}(x) + x$  is strictly increasing on  $(-\infty, \infty)$  if  $\beta < 1$ .
- (i)  $\tilde{T}(x) \leq \min\{0, b x\}$  for any  $x \in (-\infty, \infty)$ .
- (j)  $\lambda \beta \tilde{T}(\lambda \beta b + s) + s$  is nondecreasing in s and is strictly increasing in s if  $\lambda \beta < 1$ .
- Proof (a,b) Immediate from the fact that  $\tilde{p}(z)(z-x)$  in (6.1.32(p.26)) is continuous and nonincreasing in  $x \in (-\infty, \infty)$  for any z.
- (c) Let x'>x>a. Then z(x)>a from Lemma A 3.1(p.35) (b). Accordingly, since  $\tilde{p}(z(x))>0$  due to  $(6.1.41\ (2)\ (p.27))$  and since z(x)-x>z(x)-x', from (6.1.38(p.27)) we have  $\tilde{T}(x)=\tilde{p}(z(x))(z(x)-x)>\tilde{p}(z(x))(z(x)-x')\geq \tilde{T}(x')$ , i.e.,  $\tilde{T}(x)$  is strictly decreasing on  $(a,\infty)\cdots$  (1). Assume  $\tilde{T}(a)=\tilde{T}(x)$  for a given x>a, so x-a>0. Then, for any sufficiently small  $\varepsilon>0$  such that  $x-a>2\varepsilon>0$  we have  $a< a+\varepsilon< x-\varepsilon< x$ , hence  $\tilde{T}(a)=\tilde{T}(x)<\tilde{T}(a+\varepsilon)\leq \tilde{T}(a)$  due to the strict unceasingness shown just above and the nonincreasingness in (b), which is a contradiction. Thus, since  $\tilde{T}(x)\neq \tilde{T}(a)$  for any x>a, we have  $\tilde{T}(x)<\tilde{T}(a)$  or  $\tilde{T}(x)>\tilde{T}(a)$  for any x>a. However, the latter is impossible due to (b), hence only the former holds, i.e.,  $\tilde{T}(x)<\tilde{T}(a)$  for any x>a. From this and (1) it eventually follows that  $\tilde{T}(x)$  is strictly decreasing on  $[a,\infty)$  instead of on  $(a,\infty)$ .
- (d) Let  $x \leq a$ . Then, since z(x) = a from Lemma A 3.1(p.305) (a), we have  $\tilde{p}(z(x)) = 0$  due to  $(6.1.41 \, (1) \, (p.27))$ , hence  $\tilde{T}(x) = \tilde{p}(z(x))(z(x) x) = 0$  on  $(-\infty, a]$ , so  $\tilde{T}(a) = 0$ . Let x > a. Then, from (c) we have  $\tilde{T}(x) < \tilde{T}(a) = 0$ , i.e.,  $\tilde{T}(x) < 0$  on  $(a, \infty)$ .

- (e) From (6.1.32(p.26)) and (6.1.42(2)(p.27)) we see that  $\tilde{T}(x) \leq \tilde{p}(b)(b-x) = b-x$  for any x on  $(-\infty, \infty)$ .
- (f) For x' < x we have, from (6.1.38(p.27)),

$$\begin{split} \tilde{T}(x) + x &= \tilde{p}(z(x))(z(x) - x) + x \\ &= \tilde{p}(z(x))z(x) + (1 - \tilde{p}(z(x)))x \\ &\geq \tilde{p}(z(x))z(x) + (1 - \tilde{p}(z(x)))x' \\ &= \tilde{p}(z(x))(z(x) - x') + x' \geq \tilde{T}(x') + x', \end{split}$$

hence it follows that  $\tilde{T}(x) + x$  is nondecreasing in x on  $(-\infty, \infty)$ ,

- (g) If  $\beta = 1$ , then  $\beta \tilde{T}(x) + x = T(x) + x$ , hence the assertion is true from (f).
- (h) Since  $\beta \tilde{T}(x) + x = \beta (\tilde{T}(x) + x) + (1 \beta)x$ , if  $\beta < 1$ , then  $(1 \beta)x$  is strictly increasing in x, hence the assertion is true from (f).
  - (i) Since  $\tilde{T}(x) \leq b x$  for any x from (e) and  $\tilde{T}(x) \leq 0$  for any x from (d), we have  $\tilde{T}(x) \leq \min\{0, b x\}$  for any  $x \in (-\infty, \infty)$ .
  - (j) From (6.1.32(p.26)) we have

$$\begin{split} \lambda \beta \tilde{T}(\lambda \beta b + s) + s &= \lambda \beta \min_{z} \tilde{p}(z) (z - \lambda \beta b - s) + s \\ &= \min_{z} \tilde{p}(z) (\lambda \beta z - (\lambda \beta)^{2} b - \lambda \beta s) + s. \end{split}$$

Then, for s > s' we have

$$\lambda \beta \tilde{T}(\lambda \beta b + s) + s - \lambda \beta \tilde{T}(\lambda \beta b + s') - s'$$

$$= \min_{z} p(z)(\lambda \beta z - (\lambda \beta)^{2}b - \lambda \beta s) - \min_{z} p(z)(\lambda \beta z - (\lambda \beta)^{2}b - \lambda \beta s') + (s - s')$$

$$\geq \min_{z} -p(z)\lambda \beta (s - s') + (s - s')^{\dagger}$$

$$\geq \min_{z} -(s - s')\lambda \beta + (s - s') \quad \text{(due to } p(z) \leq 1 \text{ and } s - s' > 0)$$

$$= -(s - s')\lambda \beta + (s - s')$$

$$= (s - s')(1 - \lambda \beta) \geq (>) 0 \text{ if } \lambda \beta \leq (<) 1.$$

Hence, since  $\lambda \beta \tilde{T}(\lambda \beta b + s) + s \geq (>) \lambda \beta \tilde{T}(\lambda \beta b + s') + s'$  if  $\lambda \beta \leq (<) 1$ , it follows that  $\lambda \beta \tilde{T}(\lambda \beta b + s) + s$  is nondecreasing in s and strictly increasing in s if  $\lambda \beta < 1$ .

Let us define

$$\tilde{h}(z) = \tilde{p}(z)(z - b)/(1 - \tilde{p}(z)), \quad z < b,$$
  
$$\tilde{h}^* = \inf_{z < b} \tilde{h}(z),$$

Below, for any x let us define the following successive four assertions:

$$A_1(x) = \langle \langle z(x) \rangle \rangle,$$

$$A_2(x) = \langle \langle \tilde{T}(b,x) \rangle \rangle \tilde{T}(z',x,) \text{ for at least one } z' \langle b \rangle \rangle,$$

$$A_3(x) = \langle \langle b - \tilde{h}(z') \rangle x \text{ for at least one } z' \langle b \rangle \rangle,$$

$$A_4(x) = \langle \langle \sup_{z < b} \{b - \tilde{h}(z)\} \rangle x \rangle.$$

**Proposition A 3.1** For any x we have  $A_1(x) \Leftrightarrow A_2(x) \Leftrightarrow A_3(x) \Leftrightarrow A_4(x)$ .  $\square$ 

- Proof Letting  $\tilde{T}(z,x) \stackrel{\text{def}}{=} \tilde{p}(z)(z-x)$ , we can rewrite (6.1.32(p.26)) as  $\tilde{T}(x) = \min_z \tilde{T}(z,x) = \tilde{T}(z(x),x)$  (see (6.1.38(p.27))).
- 1. Let  $A_1(x)$  be true for any x. Suppose  $\tilde{T}(b,x) \leq \tilde{T}(z',x)$  for all z' < b. Then the minimum of  $\tilde{T}(z,x)$  is attained at z = b (see Def. 6.1.2(p.27)), i.e., z(x) = b, which contradicts  $A_1(x)$ . Hence it must be that  $\tilde{T}(b,x) > \tilde{T}(z',x)$  for at least one z' < b, thus  $A_2(x)$  becomes true. Accordingly, we have  $A_1(x) \Rightarrow A_2(x)$ . Suppose  $A_2(x)$  is true for any x. Then, if z(x) = b, we have  $\tilde{T}(b,x) > \tilde{T}(z',x) \geq \tilde{T}(x) = \tilde{T}(z(x),x) = \tilde{T}(b,x)$ , which is a contradiction, hence it must be that z(x) < b due to Lemma A 3.1(p.36) (c); accordingly, we have  $A_2(x) \Rightarrow A_1(x)$ . Thus, it follows that we have  $A_1(x) \Leftrightarrow A_2(x)$  for any given x.
- 2. Since  $\tilde{p}(b) = 1$  from (6.1.42(2) (p.27)), for z' < b we have

$$\begin{split} \tilde{T}(b,x) &- \tilde{T}(z',x) \\ &= \tilde{p}(b)(b-x) - \tilde{p}(z')(z'-x) \\ &= b-x - \tilde{p}(z')(z'-x) \\ &= b-x - \tilde{p}(z')(b-x+z'-b) \\ &= b-x - \tilde{p}(z')(b-x) - \tilde{p}(z')(z'-b) \\ &= (1-\tilde{p}(z'))(b-x) - \tilde{p}(z')(z'-b) \\ &= (1-\tilde{p}(z'))(b-x-\tilde{p}(z')(z'-b)/(1-\tilde{p}(z'))) \\ &= (1-\tilde{p}(z'))(b-x-\tilde{h}(z')) \\ &= (1-\tilde{p}(z'))(b-\tilde{h}(z')-x). \end{split}$$

 $<sup>^{\</sup>dagger}\min a(x) - \min b(x) \ge \min\{a(x) - b(x)\}.$ 

Accordingly, noting  $1 > \tilde{p}(z')$  due to (6.1.42(1)(p.27)), we immediately see that  $A_2(x) \Leftrightarrow A_3(x)$  for any given x.

3. Let  $A_3(x)$  be true for any x. Then clearly  $A_4(x)$  is also true, i.e.,  $A_3(x) \Rightarrow A_4(x)$ . Let  $A_4(x)$  be true for any x. Then evidently  $b - \tilde{h}(z') > x$  for at least one z' < b, hence  $A_3(x)$  is true, so we have  $A_4(x) \Rightarrow A_3(x)$ . Accordingly, it follows that  $A_3(x) \Leftrightarrow A_4(x)$  for any given x.

From all the above we have  $A_1(x) \Leftrightarrow A_2(x) \Leftrightarrow A_3(x) \Leftrightarrow A_4(x)$ .

#### Lemma A 3.5

- (a)  $-\infty < \tilde{h}^* < 0$ .
- (b)  $\tilde{x}^* = b \tilde{h}^* > b$ .
- (c)  $\tilde{x}^* > (\leq) x \Leftrightarrow z(x) < (=) b.$
- (d)  $b^* > b$ .
- Proof (a) For any infinitesimal  $\varepsilon > 0$  such that  $a < a + \varepsilon < b \cdots$  (II) we have  $0 < \tilde{p}(a + \varepsilon) < 1$  from (6.1.41 (2) (p.27)) and (6.1.42 (1) (p.27)), hence,  $\tilde{h}(a + \varepsilon) = \tilde{p}(a + \varepsilon)(a + \varepsilon b)/(1 \tilde{p}(a + \varepsilon)) < 0$ . If  $z \le a \cdots$  (I), then  $\tilde{p}(z) = 0$  due to (6.1.41 (1) (p.27)), hence  $\tilde{h}(z) = 0$  for  $z \le a$ . From the above we have  $\tilde{h}^* < 0$  (finite) or  $\tilde{h}^* = -\infty$ .

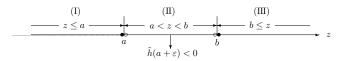


Figure A 3.3:  $\tilde{h}(z) = 0$  for  $z \le a$  and  $\tilde{h}(a + \varepsilon) < 0$ 

Assume that  $\tilde{h}^* = -\infty$ . Then, there exists at least one z' on a < z' < b such that  $\tilde{h}(z') \le -N$  for any given N > 0. Hence, if the N is given by  $M/\underline{f}$  (see (2.2.4 p.l3)) with any M > 1, i.e.,  $N = M/\underline{f}$ , we have  $\tilde{h}(z') \le -M/\underline{f}$ , so  $\tilde{p}(z')(z'-b)/(1-\tilde{p}(z')) \le -M/\underline{f}$ . Hence, noting (6.1.31 p.26), we have

$$\tilde{p}(z')(z'-b) \leq -(1-\tilde{p}(z'))M/f = -(1-\Pr\{\xi \leq z'\})M/f = -\Pr\{z' < \xi\}M/f \cdots (*)$$

where  $\Pr\{z' < \xi\} = \int_{z'}^{b} f(w) dw \ge \int_{z'}^{b} \underline{f} dw = (b - z')\underline{f}$ . Accordingly, since  $\tilde{p}(z')(z' - b) \le -(b - z')\underline{f}M/\underline{f} = (z' - b)M$ , we have  $\tilde{p}(z') \ge M > 1$  due to z' - b < 0, which is a contradiction. Hence, it must follow that  $\tilde{h}^* > -\infty$ .

(b) Since  $A_1(x) \Rightarrow A_4(x)$  due to Proposition A 3.1, we can rewrite (6.1.40(p.27)) as

$$\begin{split} \tilde{x}^{\star} &= \sup\{x \mid \sup_{z < b} \{b - \tilde{h}(z)\} > x\} \\ &= \sup_{z < b} \{b - \tilde{h}(z)\} \cdots \textbf{(1)} \\ &= b - \inf_{z < b} \tilde{h}(z) = b - \tilde{h}^{\star} > b \end{split}$$

due to (a), hence (b) holds.

- (c) Let  $\tilde{x}^{\star} > x$ , hence  $\sup_{z < b} \{b \tilde{h}(z)\} > x$  from (1), so z(x) < b due to  $A_4(x) \Rightarrow A_1(x)$ . Let  $\tilde{x}^{\star} \leq x$ , hence  $\sup_{z < b} \{b \tilde{h}(z)\} \leq x$  from (1). Now, since  $\sup_{z < b} \{b \tilde{h}(z)\} \leq x \Rightarrow z(x) \geq b$  due to the contraposition of  $A_4(x) \Leftrightarrow A_1(x)$ , we obtain z(x) = b due to Lemma A 3.1(p.305) (c).
- (d) First note  $\tilde{T}(x) \leq \tilde{p}(z')(z'-x)$  for any x and z'. Accordingly, for any sufficiently small  $\varepsilon > 0$  such that  $a < b \varepsilon$  we have  $\tilde{p}(b-\varepsilon) > 0$  from  $(6.1.41\ (2)\ (p.27)\ )$ , hence  $\tilde{T}(b) \leq \tilde{p}(b-\varepsilon)(b-\varepsilon-b) = -\tilde{p}(b-\varepsilon)\varepsilon < 0$ , so adding b to the both sides of this inequality yields  $\tilde{T}(b) + b < b$ , so  $\tilde{T}(x) + x \leq \tilde{T}(b) + b < b$  for  $x \leq b$  due to Lemma A  $3.4(p.306)\ (f)$ . Accordingly, if  $b^* \leq b$ , we have  $\tilde{T}(b^*) + b^* \leq \tilde{T}(b) + b < b$ , hence from Lemma A  $3.4(p.306)\ (a)$  we have  $\tilde{T}(b^*+\varepsilon) + b^* + \varepsilon < b$  for any sufficiently small  $\varepsilon > 0$ , so  $\tilde{T}(b^*+\varepsilon) < b (b^*+\varepsilon)$ , which contradicts the definition of  $b^*$  (see (6.1.39(p.27))). Therefore, it must follow that  $b^* > b$ .

#### Lemma A 3.6

- (a)  $\tilde{T}(x) + x$  is strictly increasing on  $(-\infty, b^*]$ .
- (b)  $\tilde{T}(x) = b x$  on  $[b^*, \infty)$  and  $\tilde{T}(x) < b x$  on  $(-\infty, b^*)$ .
- (c)  $\tilde{T}(0) = b \text{ if } b^* < 0 \text{ and } \tilde{T}(0) = 0 \text{ if } a > 0.$
- (d) If x > y and  $b^* > y$ , then  $\tilde{T}(x) + x > \tilde{T}(y) + y$ .  $\square$
- *Proof* (a) From (6.1.38(p.27)) we have

$$\tilde{T}(x) + x = \tilde{p}(z(x))(z(x) - x) + x = \tilde{p}(z(x))z(x) + (1 - \tilde{p}(z(x)))x....(1)$$

• Let  $\tilde{x}^* > x$ . Then z(x) < b from Lemma A 3.5(p.308) (c), hence  $\tilde{p}(z(x)) < 1$  due to (6.1.42 (1) (p.27)), so  $1 - \tilde{p}(z(x)) > 0$ . If x > x', from (1) we have

$$\tilde{T}(x) + x > \tilde{p}(z(x))z(x) + (1 - \tilde{p}(z(x)))x' = \tilde{p}(z(x))(z(x) - x') + x' \ge \tilde{T}(x') + x',$$

i.e.,  $\tilde{T}(x) + x$  is strictly increasing on  $(-\infty, \infty)$ , hence understandably so also on  $(-\infty, b^*]$ .

o Let  $\tilde{x}^* \leq x$ . Then z(x) = b from Lemma A 3.5 (p.308) (c), hence  $\tilde{p}(z(x)) = 1$  from  $(6.1.42\ (2)\ (p.27)\ )$ , so  $\tilde{T}(x) = \tilde{p}(z(x))(z(x) - x) = b - x \cdots$  (2). Suppose  $b^* > \tilde{x}^*$ . Then, since  $b^* > b^* - 2\varepsilon > \tilde{x}^*$  for an infinitesimal  $\varepsilon > 0$ , we have  $b^* > b^* - \varepsilon > \tilde{x}^* + \varepsilon > \tilde{x}^*$  or equivalently  $\tilde{x}^* < b^* - \varepsilon$ ; accordingly, due to (2) we obtain  $\tilde{T}(b^* - \varepsilon) = b - (b^* - \varepsilon) \cdots$  (3). Now, due to (6.1.39(p.27)) we have  $\tilde{T}(b^* - \varepsilon) < b - (b^* - \varepsilon)$ , which contradicts (3). Accordingly, it must be that  $\tilde{x}^* \geq b^*$ . Let  $x' < x < b^*$ . Then, since  $\tilde{x}^* > x$ , we have z(x) < b Lemma A 3.5(p.308) (c), hence  $\tilde{p}(z(x)) < 1$  due to  $(6.1.42\ (1)\ (p.27))$  or equivalently  $1 - \tilde{p}(z(x)) > 0$ . Thus, from (1) we have

$$\tilde{T}(x) + x > \tilde{p}(z(x))z(x) + (1 - \tilde{p}(z(x)))x' = \tilde{p}(z(x))(z(x) - x') + x' \ge \tilde{T}(x') + x',$$

implying that  $\tilde{T}(x) + x$  is strictly increasing on  $(-\infty, b^*) \cdots$  (4). Now let us assume  $\tilde{T}(b^*) + b^* = \tilde{T}(x) + x$  for any  $x < b^*$ . Then, for any sufficiently small  $\varepsilon > 0$  such that  $b^* - x > 2\varepsilon > 0$  we have  $x < x + \varepsilon < b^* - \varepsilon < b^*$ , hence  $\tilde{T}(b^*) + b^* = \tilde{T}(x) + x < \tilde{T}(x+\varepsilon) + x + \varepsilon \leq \tilde{T}(b^*) + b^*$  due to (4) and Lemma A 3.4(p.3%) (f), which is a contradiction. Thus,  $\tilde{T}(x) + x \neq \tilde{T}(b^*) + b^*$  for  $x < b^*$ , i.e.,  $\tilde{T}(x) + x > \tilde{T}(b^*) + b^*$  or  $\tilde{T}(x) + x < \tilde{T}(b^*) + b^*$  for  $x < b^*$ ; however, the former is impossible due to the nondecreasing in Lemma A 3.4(p.3%) (f), hence it follows that  $\tilde{T}(x) + x < \tilde{T}(b^*) + b^*$  for  $x < b^*$ . From this and (4) it inevitably follows that  $\tilde{T}(x) + x$  is strictly increasing on  $(-\infty, b^*]$  instead of  $(-\infty, b^*)$ .

Accordingly, whether  $\tilde{x}^* > x$  or  $\tilde{x}^* \leq x$ , it follows that  $\tilde{T}(x) + x$  is strictly increasing on  $(-\infty, b^*]$ .

- (b) Due to (6.1.39(p.27)) we have  $\tilde{T}(x) < b x$  for  $x < b^*$ , i.e.,  $\tilde{T}(x) < b x$  on  $(-\infty, b^*)$ , hence the latter half is true. Since  $\tilde{T}(x) \le b x$  on  $(-\infty, \infty)$  due to Lemma A 3.4(p.306) (e), we have  $\tilde{T}(x) + x \le b \cdots$  (5) on  $(-\infty, \infty)$ . Suppose  $\tilde{T}(b^*) + b^* < b$ . Then, for an infinitesimal  $\varepsilon > 0$  we have  $\tilde{T}(b^* + \varepsilon) + b^* + \varepsilon < b$  due to Lemma A 3.4(p.306) (a), i.e.,  $\tilde{T}(b^* + \varepsilon) < b (b^* + \varepsilon)$ , which contradicts the definition of  $b^*$  (see (6.1.39(p.27))). Consequently, it must be that  $\tilde{T}(b^*) + b^* = b \cdots$  (6) or equivalently  $\tilde{T}(b^*) = b b^*$ . Let  $x > b^*$ . Then, from Lemma A 3.4(p.306) (f) we have  $\tilde{T}(x) + x \ge \tilde{T}(b^*) + b^* = b$ . From this and (5) it must be that  $\tilde{T}(x) + x = b$  on  $(b^*, \infty)$ , hence  $\tilde{T}(x) = b x$  on  $(b^*, \infty)$ . From this and (6) it follows that  $\tilde{T}(x) = b x$  on  $[b^*, \infty)$ . Hence the former half is true.
- (c) Let  $b^* < 0$ . Then, since  $0 \in [b^*, \infty)$ , we have  $\tilde{T}(0) = b$  from the former half of (b). Now we have  $\tilde{T}(0) = \min_z \tilde{p}(z)z \cdots$  (7) from (6.1.32(p.26)). Let a > 0. Then, if  $z \le a$ , we have  $\tilde{p}(z)z = 0$  from (6.1.41(1)(p.27)) and if z > a > 0, then  $\tilde{p}(z)z > 0$  from (6.1.41(2)(p.27)). Hence it follows that  $\tilde{T}(0) = 0$  due to (7).
- (d) Let x>y and  $b^*>y$ . If  $x\geq b^*$ , then  $\tilde{T}(x)+x\geq \tilde{T}(b^*)+b^*>\tilde{T}(y)+y$  due to Lemma A 3.4(p.306) (f) and (a), and if  $b^*>x$ , then  $b^*\geq x>y$ , hence  $\tilde{T}(x)+x>\tilde{T}(y)+y$  due to (a). Thus, whether  $x\geq b^*$  or  $b^*>x$ , we have  $\tilde{T}(x)+x>\tilde{T}(y)+y$ .

All the results obtained above (see Lemmas A 3.1(p.305) -A 3.6(p.308)) can be complied into Lemma A 3.7(p.309) below.

#### **Lemma A 3.7** $(\mathscr{A}\{\tilde{T}_{\mathbb{P}}\})$ For any $F \in \mathscr{F}$ we have:

1101 (\$\tilde{\pi} \left( \tilde{\pi} \right) \right) 101 wing 1 \tilde{\pi} \	
$\tilde{T}(x)$ is continuous on $(-\infty,\infty) \leftarrow$	$\leftarrow$ Lemma A 3.4(p.306) (a)
$\tilde{T}(x)$ is nonincreasing on $(-\infty,\infty)$ $\leftarrow$	$\leftarrow$ Lemma A 3.4(p.306) (b)
$\tilde{T}(x)$ is strictly decreasing on $[a,\infty) \leftarrow$	$\leftarrow$ Lemma A 3.4(p.306) (c)
$\tilde{T}(x) + x$ is nondecreasing on $(-\infty, \infty) \leftarrow$	$\leftarrow$ Lemma A 3.4(p.306) (f)
$\tilde{T}(x) + x$ is strictly increasing on $(-\infty, b^{\star}] \leftarrow$	$\leftarrow$ Lemma A 3.6(p.308) (a)
$\tilde{T}(x) = b - x \text{ on } [b^{\star}, \infty) \text{ and } T(x) < b - x \text{ on } (-\infty, b^{\star}) \leftarrow$	$\leftarrow$ Lemma A 3.6(p.308) (b)
$\tilde{T}(x) < 0 \text{ on } (a, \infty) \text{ and } T(x) = 0 \text{ on } (-\infty, a] \leftarrow$	$\leftarrow$ Lemma A 3.4(p.306) (d)
$\tilde{T}(x) \leq \min\{0, b - x\} \ on \ (-\infty, \infty) \leftarrow$	$\leftarrow \text{ Lemma A } 3.4 \text{(p.306) (i)}$
$\tilde{T}(0) = b \text{ if } b^* < 0 \text{ and } T(0) = 0 \text{ if } a > 0 \leftarrow$	$\leftarrow$ Lemma A 3.6(p.308) (c)
$\beta \tilde{T}(x) + x$ is nondecreasing on $(-\infty, \infty)$ if $\beta = 1 \leftarrow$	$\leftarrow$ Lemma A 3.4(p.306) (g)
$\beta \tilde{T}(x) + x$ is strictly increasing on $(-\infty, \infty)$ if $\beta < 1 \leftarrow$	$\leftarrow$ Lemma A 3.4(p.306) (h)
If $x > y$ and $b^* > y$ , then $T(x) + x > T(y) + y \leftarrow$	$\leftarrow$ Lemma A 3.6(p.308) (d)
$\lambda \beta \tilde{T}(\lambda \beta b + s) + s$ is nondecreasing in $s$ and strictly increasing in $s$ if $\lambda \beta < 1 \leftarrow$	$\leftarrow$ Lemma A 3.4(p.306) (j)
$b^{\star} > b \leftarrow$	$\leftarrow$ Lemma A 3.5(p.308) (d)
	$\begin{split} \tilde{T}(x) \ is \ nonincreasing \ on \ (-\infty,\infty) \leftarrow \\ \tilde{T}(x) \ is \ strictly \ decreasing \ on \ [a,\infty) \leftarrow \\ \tilde{T}(x) + x \ is \ nondecreasing \ on \ (-\infty,\infty) \leftarrow \\ \tilde{T}(x) + x \ is \ strictly \ increasing \ on \ (-\infty,b^*] \leftarrow \\ \tilde{T}(x) = b - x \ on \ [b^*,\infty) \ and \ T(x) < b - x \ on \ (-\infty,b^*) \leftarrow \\ \tilde{T}(x) < 0 \ on \ (a,\infty) \ and \ T(x) = 0 \ on \ (-\infty,a] \leftarrow \\ \tilde{T}(x) \le \min\{0,b-x\} \ on \ (-\infty,\infty) \leftarrow \\ \tilde{T}(0) = b \ if \ b^* < 0 \ and \ T(0) = 0 \ if \ a > 0 \leftarrow \\ \beta \tilde{T}(x) + x \ is \ nondecreasing \ on \ (-\infty,\infty) \ if \ \beta = 1 \leftarrow \\ \beta \tilde{T}(x) + x \ is \ strictly \ increasing \ on \ (-\infty,\infty) \ if \ \beta < 1 \leftarrow \\ If \ x > y \ and \ b^* > y, \ then \ T(x) + x > T(y) + y \leftarrow \\ \lambda \beta \tilde{T}(\lambda \beta b + s) + s \ is \ nondecreasing \ in \ s \ and \ strictly \ increasing \ in \ s \ if \ \lambda \beta < 1 \leftarrow \\ \end{split}$

#### $\mathbf{A} \ \mathbf{3.2} \quad \mathscr{A}\{\tilde{L}_{\mathbb{P}}\}, \, \mathscr{A}\{\tilde{K}_{\mathbb{P}}\}, \, \mathscr{A}\{\tilde{\mathcal{L}}_{\mathbb{P}}\}, \, \mathbf{and} \, \, \tilde{\kappa}_{\mathbb{P}}$

From (6.1.33(p.27)) and (6.1.34(p.27)) and from Lemma A 3.7(p.309) (f) we obtain, noting (11.2.1(p.56)),

$$\tilde{L}(x) \begin{cases} = \lambda \beta b + s - \lambda \beta x \text{ on } [b^*, -\infty) & \cdots (1), \\ < \lambda \beta b + s - \lambda \beta x \text{ on } (-\infty, b^*) & \cdots (2), \end{cases}$$
(A 3.1)

$$\tilde{K}(x) \begin{cases}
= \lambda \beta b + s - \delta x & \text{on} \quad [b^*, \infty) & \cdots (1), \\
< \lambda \beta b + s - \delta x & \text{on} \quad (-\infty, b^*) & \cdots (2).
\end{cases}$$
(A 3.2)

In addition, from (6.1.34(p.27)) and Lemma A 3.7(p.309) (g) we have

$$\tilde{K}(x) \begin{cases}
< -(1-\beta)x + s \text{ on } (a,\infty) & \cdots (1), \\
= -(1-\beta)x + s \text{ on } (-\infty, a] & \cdots (2),
\end{cases}$$
(A 3.3)

hence we obtain

$$\tilde{K}(x) + x \le \beta x + s$$
 on  $(-\infty, \infty)$ . (A 3.4)

Then, from (A 3.2 (1) (p.309)) and (A 3.3 (2) (p.310)) we get

$$\tilde{K}(x) + x = \begin{cases}
\lambda \beta b + s + (1 - \lambda) \beta x \text{ on } [b^*, \infty) & \cdots (1), \\
\beta x + s & \text{on } (-\infty, a] & \cdots (2).
\end{cases}$$
(A 3.5)

Since  $\tilde{K}(x) = \tilde{L}(x) - (1-\beta)x$  from (6.1.34(p.27)) and (6.1.33(p.27)), if  $x_{\tilde{L}}$  and  $x_{\tilde{K}}$  exist, then

$$\tilde{K}(x_{\tilde{L}}) = -(1-\beta) x_{\tilde{L}} \cdots (1), \quad \tilde{L}(x_{\tilde{K}}) = (1-\beta) x_{\tilde{K}} \cdots (2). \tag{A 3.6}$$

#### Lemma A 3.8 $(\tilde{L}_{\mathbb{P}})$

- (a)  $\tilde{L}(x)$  is continuous on  $(-\infty, \infty)$ .
- (b)  $\tilde{L}(x)$  is nonincreasing on  $(-\infty, \infty)$ .
- (c)  $\tilde{L}(x)$  is strictly decreasing on  $[a, \infty)$ .
- (d) Let s=0. Then  $x_{\tilde{L}}=a$  where  $x_{\tilde{L}}<(\geq)$   $x\Leftrightarrow \tilde{L}(x)<(=)$   $0\Rightarrow \tilde{L}(x)<(\geq)$  0.
- (e) Let s > 0.
  - 1.  $x_{\tilde{L}}$  uniquely exists with  $x_{\tilde{L}} > a$  where  $x_{\tilde{L}} < (=(>))$   $x \Leftrightarrow \tilde{L}(x) < (=(>))$  0.
  - 2.  $(\lambda \beta b + s)/\lambda \beta \ge (<) b^* \Leftrightarrow x_{\tilde{L}} = (<) (\lambda \beta b + s)/\lambda \beta < (\ge) b^*$ .  $\square$
- *Proof* (a-c) Immediate from (6.1.33(p.27)) and Lemma A 3.7(p.309) (a-c).
- (d) Let s=0. Then, since  $\tilde{L}(x)=\lambda\beta\tilde{T}(x)$ , from Lemma A 3.7(p.309) (g) we have  $\tilde{L}(x)=0$  for  $a\geq x$  and  $\tilde{L}(x)<0$  for x>a, hence  $x_{\tilde{L}}=a$  by definition (see Section 6.2(p.27) (b)), so  $x_{\tilde{L}}<(\geq)x\Rightarrow \tilde{L}(x)<(=)0$ . The inverse is true by contraposition. In addition, since  $\tilde{L}(x)=0\Rightarrow \tilde{L}(x)\geq 0$ , we have  $\tilde{L}(x)<(=)0\Rightarrow \tilde{L}(x)<(\geq)0$ .
  - (e) Let s > 0.
- (e1) From  $(A\ 3.1\ (1)\ (p309))$  and the assumption of  $\lambda>0$  and  $\beta>0$  we have  $\tilde{L}(x)<0$  for a sufficiently large x>0 such that  $x>b^{\star}$ . In addition, we have  $\tilde{L}(a)=\lambda\beta\tilde{T}(a)+s=s>0$  from Lemma A 3.7(p309) (g). Hence, from (a,c) it follows that  $x_{\tilde{L}}$  uniquely exists. The inequality  $x_{\tilde{L}}>a$  is immediate from  $\tilde{L}(a)>0$  and (c). The latter half is evident.
- (e2) If  $(\lambda\beta b + s)/\lambda\beta \ge (<) b^*$ , from (A 3.1(p.309)) we have  $\tilde{L}((\lambda\beta b + s)/\lambda\beta) = (<) \lambda\beta b + s \lambda\beta(\lambda\beta b + s)/\lambda\beta = 0$ , hence  $x_{\tilde{L}} = (<) (\lambda\beta b + s)/\lambda\beta$  from (e1).

#### Corollary A 3.2 $(\tilde{L}_{\mathbb{P}})$

- (a)  $x_{\tilde{L}} < (\geq) x \Leftrightarrow \tilde{L}(x) < (\geq) 0.$
- (b)  $x_{\tilde{L}} < (>) x \Rightarrow \tilde{L}(x) < (>) 0. \square$
- **Proof** (a) Clearly  $x_{\tilde{L}} < (\geq) x \Rightarrow \tilde{L}(x) < (\geq) 0$  from Lemma A 3.8(p.310) (d,e1). The inverse is true by contraposition.
- (b) Since  $x_{\tilde{L}} < (\geq) x \Rightarrow \tilde{L}(x) < (\geq) 0$  due to (a) and since  $\tilde{L}(x) < (\geq) 0 \Rightarrow \tilde{L}(x) \leq (\geq) 0$ , we have  $x_{\tilde{L}} < (\geq) x \Rightarrow \tilde{L}(x) \leq (\geq) 0$ . In addition, if  $x_{\tilde{L}} = x$ , then  $\tilde{L}(x) = \tilde{L}(x_{\tilde{L}}) = 0 \leq 0$  or equivalently  $x_{\tilde{L}} = x \Rightarrow \tilde{L}(x) \leq 0$ , hence it follows that  $x_{\tilde{L}} \leq (\geq) x \Rightarrow \tilde{L}(x) \leq (\geq) 0$ .

#### Lemma A 3.9 $(\tilde{K}_{\mathbb{P}})$

- (a)  $\tilde{K}(x)$  is continuous on  $(-\infty, \infty)$ .
- (b)  $\tilde{K}(x)$  is nonincreasing on  $(-\infty, \infty)$ .
- (c)  $\tilde{K}(x)$  is strictly decreasing on  $[a, \infty)$ .
- (d)  $\tilde{K}(x)$  is strictly increasing on  $(-\infty, \infty)$  if  $\beta < 1$ .
- (e)  $\tilde{K}(x) + x$  is nondecreasing on  $(-\infty, \infty)$ .
- (f)  $\tilde{K}(x) + x$  is strictly increasing on  $(-\infty, \infty)$  if  $\lambda < 1$ .
- (g) K(x) + x is strictly increasing on  $(-\infty, b^*]$ .
- (h) If x > y and  $b^* > y$ , then  $\tilde{K}(x) + x > \tilde{K}(y) + y$ .
- (i) Let  $\beta = 1$  and s = 0. Then  $x_{\tilde{K}} = a$  where  $x_{\tilde{K}} < (\geq) x \Leftrightarrow \tilde{K}(x) < (=) 0 \Rightarrow \tilde{K}(x) < (\geq) 0$ .
- (j) Let  $\beta < 1$  or s > 0.
  - 1. There uniquely exists  $x_{\tilde{K}}$  where  $x_{\tilde{K}} < (=(>)) x \Leftrightarrow \tilde{K}(x) < (=(>)) 0$ .
  - 2.  $(\lambda \beta b + s)/\delta \ge (<) b^* \Leftrightarrow x_{\tilde{K}} = (<) (\lambda \beta b + s)/\delta$ .

- 3. Let  $\tilde{\kappa} < (=(>)) \ 0$ . Then  $x_{\tilde{\kappa}} < (=(>)) \ 0$ .  $\square$
- *Proof* (a-c) Evident from (6.1.34(p.27)) and Lemma A 3.7(p.309) (a-c).
  - (d) Evident from Lemma A 3.7(p.309) (b) and (6.1.34(p.27)).
  - (e) From (6.1.34(p.27)) we have

$$\tilde{K}(x) + x = \lambda \beta \tilde{T}(x) + \beta x + s = \lambda \beta (\tilde{T}(x) + x) + (1 - \lambda) \beta x + s \cdots (1),$$

hence the assertion is immediate from Lemma A 3.7(p.309) (d).

- (f) Evident from (1) and Lemma A 3.7(p.309) (d).
- (g) Evident from (1) and Lemma A 3.7(p.309) (e).
- (h) Let x > y and  $b^* > y$ . If  $x \ge b^*$ , then  $\tilde{K}(x) + x \ge \tilde{K}(b^*) + b^* > \tilde{K}(y) + y$  due to (e,g), and if  $b^* > x$ , then  $b^* > x > y$ , hence  $\tilde{K}(x) + x > \tilde{K}(y) + y$  due to (g).
- (i) Let  $\beta=1$  and s=0. Then, since  $\tilde{K}(x)=\lambda \tilde{T}(x)$  due to (6.1.34(p.27)), from Lemma A 3.7(p.309) (g) we have  $\tilde{K}(x)=0$  for  $a\geq x$  and  $\tilde{K}(x)<0$  for x>a, so  $x_{\tilde{K}}=a$  by the definition of  $x_{\tilde{K}}$  (See Section 6.2(p.27)(b)). Hence  $x_{\tilde{K}}<(\geq) x\Rightarrow \tilde{K}(x)<(=) 0$ . The inverse is immediate by contraposition. In addition, since  $\tilde{K}(x)=0\Rightarrow \tilde{K}(x)\geq 0$ , we have  $\tilde{K}(x)<(=) 0\Rightarrow \tilde{K}(x)<(\geq) 0$ .
  - (j) Let  $\beta < 1$  or s > 0.
- (j1) First note (A 3.3 (2) (p310)). Then, if  $\beta=1$ , then s>0, hence  $\tilde{K}(x)=s>0$  for any  $x\leq a$  and if  $\beta<1$ , then  $\tilde{K}(x)>0$  for any sufficiently small x<0 such that x<a. Hence, whether  $\beta=1$  or  $\beta<1$  (for any  $0<\beta\leq1$ ), we have  $\tilde{K}(x)>0$  for any sufficiently small x. Next, for any sufficiently large x>0 such that  $x\geq b^*$ , from (A 3.2 (1) (p309)) we have  $\tilde{K}(x)<0$  since to  $\delta>0$  due to (11.2.2 (1) (p56)). Hence, it follows that there exists the solution  $x_{\tilde{K}}$  for any  $0<\beta\leq1$ . Let  $\beta<1$ . Then, the solution is unique due to (d). Let  $\beta=1$ , hence s>0. Then, since  $\tilde{K}(a)=s>0$  from (A 3.3 (2) (p310)), we have  $x_{\tilde{K}}>a$ , hence  $\tilde{K}(x)$  is strictly decreasing on the neighbourhood of  $x=x_{\tilde{K}}$  due to (c), implying that the solution  $x_{\tilde{K}}$  is unique. Therefore, for any  $0<\beta\leq1$  the solution is unique. Thus, the latter half is immediate.
- (j2) Let  $(\lambda \beta b + s)/\delta \ge (<) b^*$ . Then, from (A 3.2 (1(2)) (p.309)) we have  $\tilde{K}((\lambda \beta b + s)/\delta) = (<) \lambda \beta b + s \delta(\lambda \beta b + s)/\delta = 0$ , hence  $x_{\tilde{K}} = (<) (\lambda \beta b + s)/\delta$  due to (j1). Its inverse is also true by contraposition.
  - (j3) If  $\tilde{\kappa} < (=(>)) 0$ , then  $\tilde{K}(0) < (=(>)) 0$  from (6.1.37(p.27)), hence  $x_{\tilde{K}} < (=(>)) 0$  from (j1).

The corollary below is used when it is not specified whether s > 0 or s = 0.

#### Corollary A 3.3 $(\tilde{K}_{\mathbb{P}})$

- (a)  $x_{\tilde{K}} < (\geq) x \Leftrightarrow \tilde{K}(x) < (\geq) 0.$
- (b)  $x_{\tilde{K}} \leq (\geq) x \Rightarrow \tilde{K}(x) \leq (\geq) 0.$
- Proof (a) Clearly  $x_{\tilde{K}} < (\geq) x \Rightarrow \tilde{K}(x) < (\geq) 0$  due to Lemma A 3.9(p.310) (i,j1). The inverse is immediate by contraposition.
- (b) Since  $x_{\tilde{K}} < (\geq) x \Rightarrow \tilde{K}(x) < (\geq) 0$  due to (a) and since  $\tilde{K}(x) < (\geq) 0 \Rightarrow \tilde{K}(x) \leq (\geq) 0$ , we have  $x_{\tilde{K}} < (\geq) x \Rightarrow \tilde{K}(x) \leq (\geq) 0$ . In addition, if  $x_{\tilde{K}} = x$ , then  $\tilde{K}(x) = \tilde{K}(x_{\tilde{K}}) = 0 \leq 0$ , hence it follows that  $x_{\tilde{K}} \leq (\geq) x \Rightarrow \tilde{K}(x) \leq (\geq) 0$ .

#### Lemma A 3.10 $(\tilde{L}_{\mathbb{P}}/\tilde{K}_{\mathbb{P}})$

- (a) Let  $\beta = 1$  and s = 0. Then  $x_{\tilde{L}} = x_{\tilde{K}} = a$ .
- (b) Let  $\beta = 1$  and s > 0. Then  $x_{\tilde{L}} = x_{\tilde{K}}$ .
- (c) Let  $\beta < 1$  and s = 0. Then  $a < (=(>)) 0 \Rightarrow x_{\tilde{L}} < (=(>)) x_{\tilde{K}} < (=(=)) 0$ .
- (d) Let  $\beta < 1$  and s > 0. Then  $\tilde{\kappa} < (=(>)) 0 \Rightarrow x_{\tilde{L}} < (=(>)) x_{\tilde{\kappa}} < (=(>)) 0$ .  $\square$
- ullet Proof (a) If  $\beta=1$  and s=0, then  $x_{\tilde{L}}=a$  from Lemma A 3.8(p.310) (d) and  $x_{\tilde{K}}=a$  from Lemma A 3.9(p.310) (i), hence  $x_{\tilde{L}}=x_{\tilde{K}}=a$ .
- (b) Let  $\beta=1$  and s>0. Then  $\tilde{K}(x_{\tilde{L}})=0$  from (A 3.6 (1) (p.310)), hence  $x_{\tilde{K}}=x_{\tilde{L}}$  from Lemma A 3.9(p.310) (j1).
- (c) Let  $\beta < 1$  and s = 0. Then  $x_{\tilde{L}} = a \cdots$  (1) from Lemma A 3.8(p.310) (d). Suppose a < 0. Then, since  $x_{\tilde{L}} < 0$ , we have  $\tilde{K}(x_{\tilde{L}}) > 0$  from (A 3.6 (1) (p.310)), hence  $x_{\tilde{K}} > x_{\tilde{L}}$  from Lemma A 3.9(p.310) (j1). Furthermore, from (6.1.37(p.27)) and (6.1.36(p.27)) we have  $\tilde{K}(0) = \lambda \beta \tilde{T}(0) < 0$  due to Lemma A 3.7(p.309) (g), hence  $x_{\tilde{K}} < 0$  from Lemma A 3.9(p.310) (j1). Suppose a = (>) 0. Then, since  $x_{\tilde{L}} = (>)$  0 from (1), we have  $\tilde{K}(x_{\tilde{L}}) = (<)$  0 due to (A 3.6 (1) (p.310)), hence  $x_{\tilde{L}} = (>)$   $x_{\tilde{K}}$  from Lemma A 3.9(p.310) (j1). Furthermore, from (6.1.37(p.27)) and (6.1.36(p.27)) we have  $\tilde{K}(0) = \lambda \beta \tilde{T}(0) = 0$  due to Lemma A 3.7(p.309) (g), hence  $x_{\tilde{K}} = (=)$  0 from Lemma A 3.9(p.310) (j1).
- (d) Let  $\beta < 1$  and s > 0. Since  $\tilde{\kappa} = \tilde{K}(0)$  from (6.1.37(p.27)), if  $\tilde{\kappa} < (=(>))$  0, then  $\tilde{K}(0) < (=(>))$  0, hence  $x_{\tilde{\kappa}} < (=(>))$  0 from Lemma A 3.9(p.310) (j1). Accordingly  $\tilde{L}(x_{\tilde{\kappa}}) < (=(>))$  0 from (A 3.6 (2) (p.310)), so  $x_{\tilde{L}} < (=(>))$   $x_{\tilde{\kappa}}$  from Lemma A 3.8(p.310) (e1).

#### Lemma A 3.11 $(\tilde{\mathcal{L}}_{\mathbb{P}})$

- (a)  $\tilde{\mathcal{L}}(s)$  is nondecreasing in s.
- (b) If  $\lambda \beta < 1$ , then  $\tilde{\mathcal{L}}(s)$  is strictly increasing in s.
- (c) Let  $\lambda \beta b \leq a$ .
  - 1.  $x_{\tilde{L}} \geq \lambda \beta b + s$ .

- 2. Let s > 0 and  $\lambda \beta < 1$ . Then  $x_{\tilde{L}} > \lambda \beta b + s$ .
- (d) Let  $\lambda \beta b > a$ . Then, there exists a  $s_{\tilde{\mathcal{L}}} > 0$  such that if  $s_{\tilde{\mathcal{L}}} > (\leq) s$ , then  $x_{\tilde{\mathcal{L}}} < (\geq) \lambda \beta b + s$ .  $\square$
- Proof (a,b) From (6.1.35(p.27)) and (6.1.33(p.27)) we have  $\tilde{\mathcal{L}}(s) = \lambda \beta \tilde{T}(\lambda \beta b + s) + s \cdots$  (1), hence the assertions are true from Lemma A 3.7(p.309) (m).
  - (c) Let  $\lambda \beta \mu \leq a$ . Then, from (1) we have  $\tilde{\mathcal{L}}(0) = \lambda \beta \tilde{T}(\lambda \beta b) = 0 \cdots$  (2) due to Lemma A 3.7(p.309) (g).
- (c1) Since  $s \ge 0$ , from (a) we have  $\tilde{\mathcal{L}}(s) \ge \tilde{\mathcal{L}}(0) = 0$  due to (2) or equivalently  $\tilde{\mathcal{L}}(\lambda \beta b + s) \ge 0$ , hence  $x_{\tilde{\mathcal{L}}} \ge \beta b + s$  from Corollary A 3.2(p.310) (a).
- (c2) Let s > 0 and  $\lambda \beta < 1$ . Then, from (b) we have  $\tilde{\mathcal{L}}(s) > \tilde{\mathcal{L}}(0) = 0$  due (2), hence  $\tilde{\mathcal{L}}(\lambda \beta b + s) > 0$ , so  $x_{\tilde{\mathcal{L}}} > \lambda \beta b + s$  from Lemma A 3.8(p.310) (e1).
- (d) Let  $\lambda\beta b>a$ . From (1) we have  $\tilde{\mathcal{L}}(0)=\lambda\beta\tilde{T}(\lambda\beta b)<0$  due to Lemma A 3.7(p.309) (g). Noting (A 3.1 (1) (p.309)), for any sufficiently large s>0 such that  $\lambda\beta b+s\geq b^*$  and  $\lambda\beta b+s>0$  we have  $\tilde{\mathcal{L}}(s)=\tilde{L}(\lambda\beta b+s)=\lambda\beta b+s-\lambda\beta(\lambda\beta b+s)=(1-\lambda\beta)(\lambda\beta b+s)\geq 0$ . Accordingly, due to (a) it follows that there exists a  $s_{\tilde{\mathcal{L}}}>0$  where  $\tilde{\mathcal{L}}(s)<0$  for  $s< s_{\tilde{\mathcal{L}}}$  and  $\tilde{\mathcal{L}}(s)\geq 0$  for  $s\geq s_{\tilde{\mathcal{L}}}$ , or equivalently,  $\tilde{L}(\lambda\beta b+s)<0$  for  $s< s_{\tilde{\mathcal{L}}}$  and  $\tilde{L}(\lambda\beta b+s)\geq 0$  for  $s\geq s_{\tilde{\mathcal{L}}}$ . Hence, from Corollary A 3.2(p.310) (a) we have  $s_{\tilde{\mathcal{L}}}<\beta b+s$  for  $s< s_{\tilde{\mathcal{L}}}$  and  $s_{\tilde{\mathcal{L}}}>\beta b+s$  for  $s< s_{\tilde{\mathcal{L}}}$  and  $s_{\tilde{\mathcal{L}}}>\beta b+s$  for  $s< s_{\tilde{\mathcal{L}}}>0$ .

Lemma A 3.12 ( $\mathscr{A}\{\tilde{\kappa}_{\mathbb{P}}\}$ ) We have:

- (a)  $\tilde{\kappa} = \lambda \beta b + s \text{ if } b^* < 0 \text{ and } \tilde{\kappa} = s \text{ if } a > 0.$
- (b) Let  $\beta < 1$  or s > 0. Then  $\tilde{\kappa} < (=(>)) 0 \Leftrightarrow x_{\tilde{\kappa}} < (=(>)) 0$ .
- *Proof* (a) Immediate from (6.1.36(p.27)) and Lemma A 3.7(p.309) (i).
- (b) Let  $\beta < 1$  or s > 0. Then, if  $\tilde{\kappa} > (=(<))$  0, we have  $\tilde{K}(0) > (=(<))$  0 from (6.1.37(p.27)), hence  $x_{\tilde{\kappa}} > (=(<))$  0 from Lemma A 3.9(p.310) (j1). Thus " $\Rightarrow$ " was proven. Its inverse " $\Leftarrow$ " is immediate by contraposition.

# A 4 Direct Proof of Assertion Systems

### $\mathbf{A} \mathbf{4.1} \quad \mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}$

Since  $\tilde{K}(x) + (1 - \beta)x = \tilde{L}(x)$  for any x due to (6.1.14(p.25)) and (6.1.13(p.25)), from (7.4.4(p.41)) we have

$$V_t - \beta V_{t-1} = \min\{\tilde{L}(V_{t-1}), 0\}, \quad t > 1.$$
(A 4.1)

Accordingly:

1. If  $\tilde{L}(V_{t-1}) \leq 0$ , then  $V_t - \beta V_{t-1} = \tilde{L}(V_{t-1})$ , hence

$$V_t = \tilde{L}(V_{t-1}) + \beta V_{t-1} = \tilde{K}(V_{t-1}) + V_{t-1}, \quad t > 1.$$
(A 4.2)

2. If  $\tilde{L}(V_{t-1}) \geq 0$ , then  $V_t - \beta V_{t-1} = 0$  or equivalently

$$V_t = \beta V_{t-1}, \quad t > 1..$$
 (A 4.3)

Now, from (7.4.4(p.41)) with t=2 we have

$$V_2 - V_1 = \min\{\tilde{K}(V_1), -(1-\beta)V_1\}. \tag{A 4.4}$$

Finally, from (A 4.1(p.312)) we see that

$$\tilde{L}(V_{t-1}) < (>) 0 \Rightarrow \mathsf{Conduct}_{t_{\blacktriangle}}(\mathsf{Skip}_{t_{\blacktriangle}})^{\dagger}.$$
 (A 4.5)

In this model let us note that the search must be necessarily conducted at time t = 1 (see Remark 4.1.3(p.20) (b)) and that

$$\lambda = 1 \cdots (1) \text{ (see } A2(p.20)), \qquad \delta = 1 \cdots (2) \text{ (see } (11.2.1(p.56))).$$
 (A 4.6)

- $\square$  Tom A 4.1 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}$ ) Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in t > 0.
- (b) We have  $\boxed{\$ dOITs_{\tau}\langle \tau \rangle}_{\blacktriangle}$  where  $Conduct_{\tau \geq t > 1}_{\blacktriangle}$ .
- Proof Let  $\beta = 1$  and s = 0. Then, from (6.1.14 (p.25)) we have  $\tilde{K}(x) = \tilde{T}(x) \leq 0 \cdots (1)$  for any x due to Lemma A 1.1 (p.298) (g), hence from (7.4.4 (p.41)) and (1) we have  $V_t = \min{\{\tilde{T}(V_{t-1}) + V_{t-1}, V_{t-1}\}} = \min{\{\tilde{T}(V_{t-1}), 0\}} + V_{t-1} = \tilde{T}(V_{t-1}) + V_{t-1} \cdots (2)$  for t > 1.
- (a) Since  $V_2 = \tilde{T}(V_1) + V_1$ , we have  $V_2 \leq V_1$  due to (1). Suppose  $V_{t-1} \geq V_t$ . Then, from Lemma A 1.1(p.298) (d) we have  $V_t \geq \tilde{T}(V_t) + V_t = V_{t+1}$ . Hence, by induction  $V_{t-1} \geq V_t$  for t > 1, i.e.,  $V_t$  is nonincreasing in t > 0.

<sup>†</sup>See Section 7.1(p.29).

(b) Since  $V_1 = \mu$  from (7.4.3(p41)), we have  $V_1 > a$ . Suppose  $V_{t-1} > a$ . Then, noting b > a, from (2) we have  $V_t > \tilde{T}(a) + a = a$  due to Lemma A 1.1(p.298)(1,g). Accordingly, by induction  $V_{t-1} > a$  for t > 1, hence  $V_{t-1} > x_{\tilde{L}}$  for t > 1 due to Lemma A 1.2(p.300)(d), thus  $\tilde{L}(V_{t-1}) < 0$  for t > 1 due to Lemma A 1.2(p.300)(e1), so  $\tilde{L}(V_{t-1}) < 0 \cdots (3)$  for  $\tau \ge t > 1$ . Hence, from (A 4.1(p.312)) we obtain  $V_t - \beta V_{t-1} < 0$  for  $\tau \ge t > 1$ , i.e.,  $V_t < \beta V_{t-1}$  for  $\tau \ge t > 1$ . Accordingly  $V_{\tau} < \beta V_{\tau-1} < \cdots < \beta^{\tau-1}V_1$ , hence  $t_{\tau}^* = \tau$  for  $\tau > 1$ , i.e., s dOITs  $\tau$  s 1. Then Conduct t for  $\tau \ge t > 1$  due to (3) and (A t (5(p.312)).

Let us define

$$\mathtt{S}_{19} \boxed{ \begin{tabular}{l} \texttt{S}_{19} \hline \texttt{$\otimes$} \blacktriangle \hline \texttt{$\otimes$} \blacksquare \\ \hline \end{bmatrix} = \left\{ \begin{array}{l} \texttt{For any $\tau > 1$ there exists $t^{\bullet}_{\tau} > 1$ such that} \\ (1) & \boxed{ \begin{tabular}{l} \textcircled{$\otimes$} \mathtt{dOITs} t^{\bullet}_{\tau} \geq \tau > 1 \langle \tau \rangle \\ (2) & \boxed{ \begin{tabular}{l} \textcircled{$\otimes$} \mathtt{dOITs} t^{\bullet}_{\tau} \langle t^{\bullet}_{\tau} \rangle \\ \hline \end{bmatrix}_{\mathbb{R}} \ \text{where } \mathtt{Conduct}_{\tau \geq t > 1}_{\blacktriangle}. \\ \\ \end{array} \right. \right\}$$

- $\square$  Tom A 4.2 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{R}][\mathsf{A}]\}$ ) Let  $\beta<1$  or s>0.
- (a)  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $\beta \mu \leq a$ . Then  $\boxed{\bullet dOITd_{\tau>1}\langle 1 \rangle}_{\parallel}$ .
- (c) Let  $\beta \mu > a$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $\mu + s \ge b$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
    - $\text{ii.} \quad Let \ \mu+s < b. \ \ Then \ \boxed{\$ \ \text{dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle} \ \ where \ \text{Conduct}_{\tau \geq t>1_{\blacktriangle}}.$
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let a < 0 ( $\tilde{\kappa} < 0$ ). Then  $subseteq dOITs_{\tau > 1} \langle \tau \rangle$  where  $Conduct_{\tau > t > 1}$ .
    - ii. Let a = 0 ( $\tilde{\kappa} = 0$ ).
      - 1. Let  $\beta \mu + s \geq b$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1} \langle 1 \rangle}_{\parallel}$ .
      - 2. Let  $\beta \mu + s < b$ . Then  $\boxed{\text{§ dOITs}_{\tau > 1} \langle \tau \rangle}_{\blacktriangle}$  where  $\texttt{Conduct}_{\tau \geq t > 1}_{\blacktriangle}$ .
    - iii. Let a > 0 ( $\tilde{\kappa} > 0$ ).
      - 1. Let  $\beta \mu + s \geq b$  or  $s_{\tilde{\mathcal{L}}} \leq s$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
      - 2. Let  $\beta\mu + s < b$  and  $s_{\tilde{\mathcal{L}}} > s$ . Then  $S_{19}$ [p.313]  $\bullet \bullet$  \*|| is true.  $\Box$
- *Proof* Let  $\beta < 1$  or s > 0. Note here (A 4.6 (1,2) (p.312)).
- (a) Since  $x_{\tilde{K}} \leq (\beta \mu + s)/\delta = \beta \mu + s = V_1$  due to Lemma A 1.3(p.300) (j2) and (7.4.3(p.41)), we have  $\tilde{K}(V_1) \leq 0$  due to Lemma A 1.3(p.300) (j1), hence  $V_2 V_1 \leq 0$  from (A 4.4(p.41)), i.e.,  $V_1 \geq V_2$ . Suppose  $V_{t-1} \geq V_t$ . Then, from (7.4.4(p.41)) and Lemma A 1.3(p.300) (e) we have  $V_t \geq \min\{\tilde{K}(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Hence, by induction  $V_{t-1} \geq V_t$  for t > 1, i.e.,  $V_t$  is nonincreasing in t > 0. Consider a sufficiently small M < 0 such that  $\beta \mu + s \geq M$  and  $a \geq M$ , hence  $V_1 \geq M$ . Suppose  $V_{t-1} \geq M$ . Then, from Lemma A 1.3(p.300) (e) and (A 1.5 (2) (p.300)) we have  $V_t \geq \min\{\tilde{K}(M) + M, \beta M\} = \min\{\beta M + s, \beta M\} \geq \min\{M, M\} = M$  due to  $\beta \leq 1$  and  $s \geq 0$ . Hence, by induction  $V_t \geq M$  for t > 0, i.e.,  $V_t$  is lower bounded in t. Accordingly  $V_t$  converges to a finite V as  $t \to \infty$ . Then, from (7.4.4(p.41)) we have  $V = \min\{\tilde{K}(V) + V, \beta V\}$ , hence  $0 = \min\{\tilde{K}(V), -(1-\beta)\beta V\}$ . Thus, since  $\tilde{K}(V) \geq 0$ , we have  $V \leq x_{\tilde{K}}$  from Lemma A 1.3(p.300) (j1).
- (b) Let  $\beta\mu \leq a\cdots$  (1). Then  $x_{\tilde{L}}\geq \beta\mu+s=V_1$  from Lemma A 1.5(p.302) (b1) with  $\lambda=1$  and  $\delta=1$ , hence  $x_{\tilde{L}}\geq V_{t-1}$  for t>1 from (a). Accordingly, since  $\tilde{L}(V_{t-1})\geq 0$  for t>1 due to Corollary A 1.1(p.300) (a), we have  $\tilde{L}(V_{t-1})\geq 0$  for  $\tau\geq t>1$ . Hence, from (A 4.3(p.312)) we have  $V_t=\beta V_{t-1}$  for  $\tau\geq t>1$ . Thus  $V_\tau=\beta V_{\tau-1}=\cdots=\beta^{\tau-1}V_1$ , i.e.,  $I_\tau^\tau=I_\tau^{\tau-1}=\cdots=I_\tau^\tau$ . Hence  $t_\tau^*=1$  for  $\tau>1$  (see Preference Rule 8.2.1(p.45)), i.e.,  $|\bullet|$  dOITd $_\tau\langle 1\rangle$  for  $\tau>1$ .
  - (c) Let  $\beta \mu > a$ .
- (c1) Let  $\beta = 1 \cdots$  (2), hence s > 0 due to the assumption " $\beta < 1$  or s > 0" of the lemma. Then  $(\lambda \beta \mu + s)/\delta = \mu + s \cdots$  (3) due to (2) and (A 4.6 (1,2) (p.312)). In addition, since  $x_{\tilde{L}} = x_{\tilde{K}} \cdots$  (4) from Lemma A 1.4(p.301) (b), we have  $\tilde{K}(x_{\tilde{L}}) = \tilde{K}(x_{\tilde{K}}) = 0 \cdots$  (5).
- (c1i) Let  $\mu + s \ge b$ . Then  $x_{\tilde{L}} = x_{\tilde{K}} = \mu + s = V_1$  from (4), Lemma A 1.3(p300) (j2), (3), and (7.4.3(p41)). Accordingly, since  $x_{\tilde{L}} \ge V_{t-1}$  for t > 1 from (a), we have  $\tilde{L}(V_{t-1}) \ge 0$  for t > 1 due to Lemma A 1.2(p300) (e1). Hence, for the same reason as in the proof of (b) we obtain  $\bullet \text{dOITd}_{\tau}\langle 1 \rangle_{\parallel}$  for  $\tau > 1$ .
- (c1ii) Let  $\mu + s < b$ . Then  $x_{\tilde{L}} = x_{\tilde{K}} < \mu + s = V_1 < b$  from (4), Lemma A 1.3(p.300) (j2), and (7.4.3(p.41)), hence  $b > V_{t-1}$  for t > 1 from (a). Suppose  $V_{t-1} > x_{\tilde{L}}$ , hence  $\tilde{L}(V_{t-1}) < 0$  from

Lemma A 1.2(p300) (e1). Then, from (A 4.2(p312)), Lemma A 1.3(p300) (g), and (5) we have  $V_t > \tilde{K}(x_{\tilde{L}}) + x_{\tilde{L}} = x_{\tilde{L}}$ . Accordingly, by induction  $V_{t-1} > x_{\tilde{L}}$  for t > 1, hence,  $\tilde{L}(V_{t-1}) < 0$  for t > 1 from

Lemma A 1.2(p.300) (e1). Thus, for the same reason as in the proof of Tom A 4.1(p.312) (b) we have  $\boxed{\$ \text{ dOITs}_{\tau}\langle \tau \rangle}_{\blacktriangle}$  for  $\tau > 1$  and  $\text{Conduct}_{t\blacktriangle}$  for  $\tau \geq t > 1$ .

- (c2) Let  $\beta < 1$  and s = 0 (s > 0).
- (c2i) Let a<0 ( $\tilde{\kappa}<0$ ). Then  $x_{\tilde{L}}< x_{\tilde{\kappa}}<0\cdots$  (6) from Lemma A 1.4(p301) (c (d)). Now, since  $x_{\tilde{\kappa}}\leq\beta\mu+s$  due to Lemma A 1.3(p300) (j2) with  $\lambda=1$  and  $\delta=1$ , we have  $x_{\tilde{\kappa}}\leq V_1$  from (7.4.3(p41)). Suppose  $x_{\tilde{\kappa}}\leq V_{t-1}$ . Then, from Lemma A 1.3(p300) (e) we have  $V_t\geq\min\{\tilde{K}(x_{\tilde{\kappa}})+x_{\tilde{\kappa}},\beta\,x_{\tilde{\kappa}}\}=\min\{x_{\tilde{\kappa}},\beta\,x_{\tilde{\kappa}}\}=x_{\tilde{\kappa}}$  due to  $x_{\tilde{\kappa}}<0$ . Accordingly, by induction

 $V_{t-1} \geq x_{\tilde{K}}$  for t > 1, hence  $V_{t-1} > x_{\tilde{L}}$  for t > 1 from (6), thus  $\tilde{L}(V_{t-1}) < 0$  for t > 1 due to Corollary A 1.1(p.300) (a). Hence, for the same reason as in the proof of Tom A 4.1(p.312) (b) we have  $\boxed{\$$  dOITs $_{\tau}\langle \tau \rangle}_{\blacktriangle}$  for  $\tau > 1$  and CONDUCT $_{t}_{\blacktriangle}$  for  $\tau \geq t > 1$ .

- (c2ii) Let a=0 ( $\tilde{\kappa}=0$ ). Then  $x_{\tilde{L}}=x_{\tilde{K}}\cdots$  (7) from Lemma A 1.4(p.301) (c (d)).
- (c2ii1) Let  $\beta\mu + s \geq b$ . Then,  $x_{\tilde{K}} = \beta\mu + s = V_1$  from Lemma A 1.3(p.300) (j2) and (7.4.3(p.41)). Suppose  $V_{t-1} = x_{\tilde{K}}$ , hence  $V_{t-1} = x_{\tilde{L}}$  from (7), thus  $\tilde{L}(V_{t-1}) = \tilde{L}(x_{\tilde{L}}) = 0$ . Then, from (A 4.2(p.312)) we have  $V_t = \tilde{K}(x_{\tilde{K}}) + x_{\tilde{K}} = x_{\tilde{K}}$ . Accordingly, by induction  $V_{t-1} = x_{\tilde{K}}$  for t > 1, hence  $V_{t-1} = x_{\tilde{L}}$  for t > 1 due to (7). Then, since  $\tilde{L}(V_{t-1}) = \tilde{L}(x_{\tilde{L}}) = 0$  for t > 1, we have  $V_t = \beta V_{t-1}$  for t > 1 from (A 4.3(p.312)), hence, for the same reason as in the proof of (b) we obtain  $\bullet$  d0ITd $_{\tau}(1)$  for  $\tau > 1$ .
- (c2ii2) Let  $\beta\mu+s < b$ . Then, since  $V_1 < b$  from (7.4.3 (p.41)), we have  $V_{t-1} < b$  for t>1 due to (a). In addition, we have  $x_{\tilde{K}} < \beta\mu+s=V_1$  from Lemma A 1.3 (p.300) (j2). Suppose  $x_{\tilde{K}} < V_{t-1}$ , hence  $x_{\tilde{L}} < V_{t-1}$  from (7). Then, since  $\tilde{L}(V_{t-1}) < 0$  due to Lemma A 1.2 (p.300) (e1), from (A 4.2 (p.312)) and Lemma A 1.3 (p.300) (g) we have  $V_t > \tilde{K}(x_{\tilde{K}}) + x_{\tilde{K}} = x_{\tilde{K}}$ . Hence, by induction  $x_{\tilde{K}} < V_{t-1}$  for t>1, thus  $x_{\tilde{L}} < V_{t-1}$  for t>1 due to (7). Accordingly, since  $\tilde{L}(V_{t-1}) < 0$  for t>1 due to Corollary A 1.1 (p.300) (a), for the same reason as in the proof of Tom A 4.1 (p.312) (b) we have  $\boxed{\$}$  dOITs $_{\tau} \langle \tau \rangle$  for  $\tau>1$  and Conduct $_{\tau}$  for  $\tau \geq t>1$ .
  - (c2iii) Let a > 0 ( $\tilde{\kappa} > 0$ ). Then  $x_{\tilde{L}} > x_{\tilde{K}} \cdots$  (8) from Lemma A 1.4(p.301) (c (d)).
- (c2iii1) Let  $\beta\mu+s\geq b$  or  $s_{\tilde{\mathcal{L}}}\leq s$ . First, let  $\beta\mu+s\geq b$ . Then, since  $x_{\tilde{k}}=\beta\mu+s=V_1$  from Lemma A 1.3(p300) (j2), we have  $x_{\tilde{\mathcal{L}}}>V_1$  from (8), hence  $x_{\tilde{\mathcal{L}}}\geq V_1$ . Next, let  $s_{\tilde{\mathcal{L}}}\leq s$ . Then, since  $x_{\tilde{\mathcal{L}}}\geq \beta\mu+s$  due to Lemma A 1.5(p302) (c), we have  $x_{\tilde{\mathcal{L}}}\geq V_1$  from (7.4.3(p41)). Accordingly, whether  $\beta\mu+s\geq b$  or  $s_{\tilde{\mathcal{L}}}\leq s$ , we have  $x_{\tilde{\mathcal{L}}}\geq V_1$ , so  $x_{\tilde{\mathcal{L}}}\geq V_{t-1}$  for t>1 due to (a). Hence, since  $\tilde{\mathcal{L}}(V_{t-1})\geq 0$  for t>1 from Corollary A 1.1(p300) (a), for the same reason as in the proof of (b) we obtain  $\bullet$  d0ITd $_{\tau}\langle 1\rangle_{\parallel}$  for  $\tau>1$ .
- (c2iii2) Let  $\beta\mu+s < b\cdots$  (9) and  $s < s_{\tilde{\mathcal{L}}}$ . Then, from (8) and Lemma A 1.5(p.302) (c) we have  $x_{\tilde{K}} < x_{\tilde{L}} < \beta\mu+s = V_1\cdots$  (10), hence  $\tilde{K}(V_1) < 0\cdots$  (11) from Lemma A 1.3(p.300) (j1). In addition, since  $V_1 < b$  due to (9) and (7.4.3(p.41)), we have  $V_{t-1} < b$  for t > 0 from (a). Now, from (A 4.4(p.312)) and (11) we have  $V_2 V_1 < 0$ , i.e.,  $V_2 < V_1$ . Suppose  $V_{t-1} > V_t$ . Then, from (7.4.4(p.41)) and Lemma A 1.3(p.300) (g) we have  $V_t > \min\{\tilde{K}(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Accordingly, by induction  $V_{t-1} > V_t$  for t > 1, i.e.,  $V_t$  is strictly decreasing in t > 0. Note that  $V_1 > x_{\tilde{L}}$  due to (10), so  $V_1 \ge x_{\tilde{L}}$ . Assume that  $V_{t-1} \ge x_{\tilde{L}}$  for all t > 1, hence  $V \ge x_{\tilde{L}}$ . Now, from (8) and  $V \le x_{\tilde{K}}$  in (a) we have the contradiction of  $V \le x_{\tilde{K}} < x_{\tilde{L}} \le V$ . Hence, it is impossible that  $V_{t-1} \ge x_{\tilde{L}}$  for all t > 1, implying that there exists  $t_{\tau}^{\bullet} > 1$  such that

$$V_1 > V_2 > \dots > V_{t^{\bullet}_{\tau}-1} > x_{\tilde{L}} \ge V_{t^{\bullet}_{\tau}} > V_{t^{\bullet}_{\tau}+1} > V_{t^{\bullet}_{\tau}+2} > \dots,$$
 (A 4.7)

from which

$$V_{t-1} > x_{\tilde{L}}, \quad t_{\tau}^{\bullet} \ge t > 1, \qquad x_{\tilde{L}} \ge V_{t-1}, \quad t > t_{\tau}^{\bullet}.$$
 (A 4.8)

Therefore, from Corollary A 1.1(p.300) (a) we have  $\tilde{L}(V_{t-1}) < 0 \cdots (12)$  for  $t^{\bullet}_{\tau} \geq t > 1$  and  $\tilde{L}(V_{t-1}) \geq 0 \cdots (13)$  for  $t > t^{\bullet}_{\tau}$ .

- 1. Let  $t_{\tau}^{\bullet} \geq \tau > 1$ . Then, since  $\tilde{L}(V_{t-1}) < 0 \cdots$  (14) for  $\tau \geq t > 1$  from (12), for the same reason as in the proof of Tom A 4.1(p.312) (b) we have  $\boxed{\$ \text{ dOITs}_{\tau}\langle \tau \rangle}_{\bullet}$  for  $t_{\tau}^{\bullet} \geq \tau > 1$  and  $\text{Conduct}_{t,\bullet}$  for  $\tau \geq t > 1$ . Hence  $S_{19}(p.313)$  (1) is true.
- 2. Let  $\tau > t^{\bullet}$ . First, let  $\tau \geq t > t_{\tau}^{\bullet}$ . Then, since  $\tilde{L}(V_{t-1}) \geq 0$  for  $\tau \geq t > t_{\tau}^{\bullet}$  from (13), we have  $V_t = \beta V_{t-1}$  for  $\tau \geq t > t_{\tau}^{\bullet}$  from (A 4.3(p.312)), thus

$$V_{\tau} = \beta V_{\tau-1} = \beta^2 V_{\tau-2} = \dots = \beta^{\tau - t_{\tau}^{\bullet}} V_{t^{\bullet}} \cdots (15).$$

Next, let  $t_{\tau}^{\bullet} \ge t > 1$ . Then, from (12) and (A 4.1(p.312)) we have  $V_t - \beta V_{t-1} < 0$  for  $t_{\tau}^{\bullet} \ge t > 1$ , i.e.,  $V_t < \beta V_{t-1}$  for  $t_{\tau}^{\bullet} \ge t > 1$ , hence

$$V_{t_{\tau}^{\bullet}} < \beta V_{t_{\tau}^{\bullet}-1} < \beta^{2} V_{t_{\tau}^{\bullet}-2} < \dots < \beta^{t_{\tau}^{\bullet}-1} V_{1} \dots (16).$$

From (15) and (16) we have

$$V_{\tau} = \beta V_{\tau-1} = \beta^2 V_{\tau-2} = \dots = \beta^{\tau - t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} < \beta^{\tau - t_{\tau}^{\bullet} + 1} V_{t_{\tau}^{\bullet} - 1} < \beta^{\tau - t_{\tau}^{\bullet} + 2} V_{t_{\tau}^{\bullet} - 2} < \dots < \beta^{\tau - 1} V_{1},$$

hence we obtain  $t_{\tau}^* = t_{\tau}^{\bullet}$  for  $\tau > t_{\tau}^{\bullet}$  due to Preference Rule 8.2.1(p.45), i.e.,  $\boxed{\odot \text{ ndOIT}_{\tau}\langle t_{\tau}^{\bullet}\rangle}_{\parallel}$  for  $\tau > 1$ . In addition, we have Conduct<sub>t \( \Lambda\)</sub> for  $t_{\tau}^* \geq t > 1$  due to (12) and (A 4.5(p.312)). Hence S<sub>19</sub>(p.313) (2) is true.

#### $\mathbf{A} \ \mathbf{4.2} \quad \mathscr{A} \{\mathsf{M}:1[\mathbb{P}][\mathsf{A}]\}$

Since  $K(x) + (1 - \beta)x = L(x)$  for any x due to (6.1.21(p.26)) and (6.1.20(p.26)), from (7.4.6(p.41)) we have

$$V_t - \beta V_{t-1} = \max\{L(V_{t-1}), 0\} \ge 0, \quad t > 1.$$
(A 4.9)

Accordingly:

1. If  $L(V_{t-1}) \ge 0$ , then  $V_t - \beta V_{t-1} = L(V_{t-1})$ , hence

$$V_{t} = L(V_{t-1}) + \beta V_{t-1} = K(V_{t-1}) + V_{t-1}, \quad t > 1.$$
(A 4.10)

2. If  $L(V_{t-1}) \leq 0$ , then  $V_t - \beta V_{t-1} = 0$  or equivalently

$$V_t = \beta V_{t-1}, \quad t > 1..$$
 (A 4.11)

Now, from (7.4.6(p.41)) with t=2 we have

$$V_2 - V_1 = \max\{K(V_1), -(1-\beta)V_1\}. \tag{A 4.12}$$

Finally, from (A4.9(p.314)) we see that

$$L(V_{t-1}) > (<) 0 \Rightarrow \mathsf{Conduct}_{t_{\bullet}}(\mathsf{Skip}_{t_{\bullet}}).$$
 (A 4.13)

In this model let us note that the search must be necessarily conducted at time t = 1 (see Remark 4.1.3(p.20) (b)) and that

$$\lambda = 1 \cdots (1)$$
 (see  $A2(p.20)$ ),  $\delta = 1 \cdots (2)$  (see  $(11.2.1(p.56))$ ). (A 4.14)

- $\square$  Tom A 4.3 ( $\mathscr{A}\{M:1[\mathbb{P}][A]\}$ ) Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nondecreasing in t > 0.
- (b)  $\boxed{\$ dOITs_{\tau}\langle \tau \rangle}$  where  $Conduct_{\tau > t > 1}$ .
- Proof Let  $\beta = 1$  and s = 0. Then, from (6.1.21(p.26)) we have  $K(x) = T(x) \ge 0 \cdots (1)$  for any x due to Lemma A 2.1(p.302) (g), hence from (7.4.6(p.41)) and (1) we have  $V_t = \max\{T(V_{t-1}) + V_{t-1}, V_{t-1}\} = \max\{T(V_{t-1}), 0\} + V_{t-1} = T(V_{t-1}) + V_{t-1} \cdots (2)$  for t > 1.
- (a) Since  $V_2 = T(V_1) + V_1$ , we have  $V_2 \ge V_1$  due to (1). Suppose  $V_{t-1} \le V_t$ . Then, from Lemma A 2.1(p.302) (d) we have  $V_t \le T(V_t) + V_t = V_{t+1}$ . Hence, by induction  $V_{t-1} \le V_t$  for t > 1, i.e.,  $V_t$  is nondecreasing in t > 0.
- (b) Since  $V_1 = a$  from (7.4.5(p.41)), we have  $V_1 < b$ . Suppose  $V_{t-1} < b$ . Then, noting  $a^* < a < b$  due to Lemma A 2.1(p.302) (n), from (2) we have  $V_t < T(b) + b = b$  due to Lemma A 2.1(p.302) (c,g). Accordingly, by induction  $V_{t-1} < b$  for t > 1, hence  $L(V_{t-1}) > 0$  for t > 1 due to Lemma A 2.2(p.303) (d), so  $L(V_{t-1}) > 0 \cdots$  (3) for  $\tau \ge t > 1$ . Hence, from (A 4.9(p.314)) we obtain  $V_t \beta V_{t-1} > 0$  for  $\tau \ge t > 1$ , i.e.,  $V_t > \beta V_{t-1}$  for  $\tau \ge t > 1$ . Accordingly  $V_\tau > \beta V_{\tau-1} > \cdots > \beta^{\tau-1} V_1$ , hence  $t^*_\tau = \tau$  for  $\tau > 1$ , i.e.,  $v_t > 0$  for  $v_t > 0$ . Then Conduct  $v_t > 0$  for  $v_t > 0$  and (A 4.13(p.315)).

Let us define

$$\mathbf{S}_{20} \boxed{ \begin{tabular}{ll} \hline \$ \bullet & \bullet & \bullet \\ \hline \$ \bullet & \bullet & \bullet \\ \hline \end{tabular} = \left\{ \begin{array}{ll} \begin{tabular}{ll} For any $\tau > 1$ there exists $t^{\bullet}_{\tau} > 1$ such that \\ \hline (1) & \hline $(\$ \bullet \bullet \bullet) \end{tabular} there $\mathsf{Conduct}_{\tau \geq t > 1 \, \blacktriangle}$, \\ \hline (2) & \hline $(\$ \bullet \bullet \bullet) \end{tabular} there $\mathsf{Conduct}_{\tau \geq t > 1 \, \blacktriangle}$. \\ \hline \end{tabular} \right\}$$

- $\square$  Tom A 4.4 ( $\mathscr{A}\{\mathsf{M}:1[\mathbb{P}][\mathtt{A}]\}$ ) Let  $\beta<1$  or s>0.
- (a)  $V_t$  is nondecreasing in t > 0 and converges to a finite  $V \ge x_K$  as  $t \to \infty$ .
- (b) Let  $\beta a \geq b$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
- (c) Let  $\beta a < b$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $a s \leq a^*$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $a-s>a^{\star}$ . Then  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$  where  $\text{Conduct}_{\tau\geq t>1}_{\blacktriangle}$ .
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let b>0 ( $\kappa>0$ ). Then  $\odot$  dOITs  $_{\tau>1}\langle \tau \rangle$  where Conduct  $_{\tau\geq t>1}$ .
    - ii. Let b = 0 ( $\kappa = 0$ ).
      - 1. Let  $\beta a s \leq a^*$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
      - 2. Let  $\beta a s > a^*$ . Then  $\boxed{\$ \text{ dOITs}_{\tau > 1} \langle \tau \rangle}$  where  $\text{Conduct}_{\tau > t > 1}$ .
    - iii. Let b < 0 ( $\kappa < 0$ ).
      - 1. Let  $\beta a s \leq a^*$  or  $s_{\mathcal{L}} \leq s$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
      - 2. Let  $\beta a s > a^*$  and  $s_{\mathcal{L}} > s$ . Then  $S_{20}(p.315)$   $\boxed{ \circ \blacktriangle * \parallel }$  is true.  $\Box$
- *Proof* Let  $\beta < 1$  or s > 0. First note (A 4.14(p.315))
- (a) Since  $x_K \geq (\lambda \beta a s)/\delta = \beta a s = V_1$  due to Lemma A 2.3(p.303) (j2) and (7.4.5(p.41)), we have  $K(V_1) \geq 0$  due to Lemma A 2.3(p.303) (j1), hence  $V_2 V_1 \geq 0$  from (A 4.12(p.315)), i.e.,  $V_1 \leq V_2$ . Suppose  $V_{t-1} \leq V_t$ . Then, from (7.4.6(p.41)) and Lemma A 2.3(p.303) (e) we have  $V_t \leq \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Hence, by induction  $V_{t-1} \leq V_t$  for t > 1, i.e.,  $V_t$  is nondecreasing in t > 0. Consider a sufficiently large M > 0 such that  $\beta a s \leq M$  and  $b \leq M$ , hence  $V_1 \leq M$ . Suppose  $V_{t-1} \leq M$ . Then, from Lemma A 2.3(p.303) (e) and (A 2.5 (2) (p.303)) we have  $V_t \leq \max\{K(M) + M, \beta M\} = \max\{\beta M s, \beta M\} \leq \max\{M, M\} = M$  due to  $\beta \leq 1$  and  $s \geq 0$ . Hence, by induction  $V_t \leq M$  for t > 0, i.e.,  $V_t$  is upper bounded in t. Accordingly  $V_t$  converges to a

finite V as  $t \to \infty$ . Then, from (7.4.6(p.41)) we have  $V = \max\{K(V) + V, \beta V\}$ , hence  $0 = \max\{K(V), -(1-\beta)\beta V\}$ . Thus, since  $K(V) \le 0$ , we have  $V \ge x_K$  from Lemma A 2.3(p.303) (j1).

- (b) Let  $\beta a \geq b \cdots$  (1). Then  $x_L \leq \beta a s = V_1$  from Lemma A 2.5(p305) (b1) with  $\lambda = 1$  and  $\delta = 1$ , hence  $x_L \leq V_{t-1}$  for t > 1 from (a). Accordingly, since  $L(V_{t-1}) \leq 0$  for t > 1 due to Corollary A 2.1(p303) (a), we have  $L(V_{t-1}) \leq 0$  for  $\tau \geq t > 1$ . Hence, from (A 4.11(p315)) we have  $V_t = \beta V_{t-1}$  for  $\tau \geq t > 1$ . Thus  $V_\tau = \beta V_{\tau-1} = \cdots = \beta^{\tau-1}V_1$ , i.e.,  $I_\tau^\tau = I_\tau^{\tau-1} = \cdots = I_\tau^1$ , hence  $I_\tau^\tau = 1$  for  $I_\tau^\tau = 1$  for
  - (c) Let  $\beta a < b$ .
- (c1) Let  $\beta = 1 \cdots$  (2), hence s > 0 due to the assumption " $\beta < 1$  or s > 0" of the lemma. Then  $(\lambda \beta a s)/\delta = a s \cdots$  (3) due to (2) and (A 4.14 (2) (p.315)). In addition, since  $x_L = x_K \cdots$  (4) from Lemma A 2.4(p.304) (b), we have  $K(x_L) = K(x_K) = 0 \cdots$  (5).
- (c1i) Let  $a-s \le a^*$ . Then  $x_L = x_K = a-s = V_1$  from (4), Lemma A 2.3(p.303) (j2), (3), and (7.4.5(p.41)). Accordingly, since  $x_L \le V_{t-1}$  for t > 1 from (a), we have  $L(V_{t-1}) \le 0$  for t > 1 due to Lemma A 2.2(p.303) (e1). Hence, for the same reason as in the proof of (b) we obtain  $\bullet$  dOITd $_{\tau}\langle 1 \rangle_{\parallel}$  for  $\tau > 1$ .
- (c1ii) Let  $a-s>a^{\star}$ . Then  $x_{L}=x_{K}>a-s=V_{1}>a^{\star}$  from (4), Lemma A 2.3(p.303) (j2), and (7.4.5(p.41)), hence  $a^{\star}< V_{t-1}$  for t>1 from (a). Suppose  $V_{t-1}< x_{L}$ , hence  $L(V_{t-1})>0$  from Lemma A 2.2(p.303) (e1). Then, from (A 4.10(p.314)), Lemma A 2.3(p.303) (g), and (4) we have  $V_{t}< K(x_{L})+x_{L}=K(x_{K})+x_{L}=x_{L}$ . Accordingly, by induction  $V_{t-1}< x_{L}$  for t>1, hence  $L(V_{t-1})>0$  for t>1 from Lemma A 2.2(p.303) (e1). Thus, for the same reason as in the proof of Tom A 4.3(p.315) (b) we have  $[ \otimes \text{dOITs}_{\tau}\langle \tau \rangle ]_{\blacktriangle}$  for  $\tau>1$  and Conduct  $t_{L}$  for  $\tau\geq t>1$ .
  - (c2) Let  $\beta < 1$  and s = 0 (s > 0).
- (c2i) Let b>0 ( $\kappa>0$ ). Then  $x_L>x_K>0\cdots$  (6) from Lemma A 2.4(p.304) (c (d)). Now, since  $x_K\geq\beta a-s$  due to Lemma A 2.3(p.303) (j2) with  $\lambda=1$  and  $\delta=1$ , we have  $x_K\geq V_1$  from (7.4.5(p.41)). Suppose  $x_K\geq V_{t-1}$ . Then, from Lemma A 2.3(p.303) (e) we have  $V_t\leq\max\{K(x_K)+x_K,\beta x_K\}=\max\{x_K,\beta x_K\}=x_K$  due to  $x_K>0$ . Accordingly, by induction  $V_{t-1}\leq x_K$  for t>1, hence  $V_{t-1}< x_L$  for t>1 from (6), thus  $L(V_{t-1})>0$  for t>1 due to Corollary A 2.1(p.303) (a). Hence, for the same reason as in the proof of Tom A 4.3(p.315) (b) we have s=00 do s=01 and conduct s=01 and conduct s=02 for s=03.
  - (c2ii) Let b=0 ( $\kappa=0$ ). Then  $x_L=x_K\cdots$  (7) from Lemma A 2.4(p.304) (c (d)).
- (c2ii1) Let  $\beta a s \leq a^*$ . Then,  $x_K = \beta a s = V_1$  from Lemma A 2.3(p.303) (j2) and (7.4.5(p.41)). Suppose  $V_{t-1} = x_K$ , hence  $V_{t-1} = x_L$  from (7), thus  $L(V_{t-1}) = L(x_L) = 0$ . Then, from (A 4.10(p.314)) we have  $V_t = K(x_K) + x_K = x_K$ . Accordingly, by induction  $V_{t-1} = x_K$  for t > 1, hence  $V_{t-1} = x_L$  for t > 1 due to (7). Then, since  $L(V_{t-1}) = L(x_L) = 0$  for t > 1, we have  $V_t = \beta V_{t-1}$  for t > 1 from (A 4.11(p.315)), hence, for the same reason as in the proof of (b) we obtain  $\boxed{\bullet \text{dOITd}_{\tau}\langle 1 \rangle}_{\parallel}$  for  $\tau > 1$ .
- (c2ii2) Let  $\beta a-s>a^\star$ . Then, since  $V_1>a^\star$ , we have  $V_{t-1}>a^\star$  for t>1 due to (a). In addition, we have  $x_K>\beta a-s=V_1$  from Lemma A 2.3(p.303) (j2) and (7.4.5(p.41)). Suppose  $x_K>V_{t-1}$ , hence  $x_L>V_{t-1}$  from (7). Then, since  $L(V_{t-1})>0$  due to Corollary A 2.1(p.303) (a), from (A 4.10(p.314)) and Lemma A 2.3(p.303) (g) we have  $V_t< K(x_K)+x_K=x_K$ . Hence, by induction  $x_K>V_{t-1}$  for t>1, thus  $x_L>V_{t-1}$  for t>1 due to (7). Accordingly, since  $L(V_{t-1})>0$  for t>1 due to Corollary A 2.1(p.303) (a), for the same reason as in the proof of Tom A 4.3(p.315) (b) we have [\$] dOITs  $_{\tau}\langle \tau \rangle$  for  $\tau>1$  and Conduct  $_{\tau}$  for  $\tau\geq t>1$ .
  - (c2iii) Let b < 0 ( $\kappa < 0$ ). Then  $x_L < x_K \cdots$  (8) from Lemma A 2.4(p.304) (c (d)).
- (c2iii1) Let  $\beta a s \leq a^\star$  or  $s_{\mathcal{L}} \leq s$ . First, let  $\beta a s \leq a^\star$ . Then, since  $x_K = \beta a s = V_1$  from Lemma A 2.3(p.303) (j2), we have  $x_L < V_1$  from (8), hence  $x_L \leq V_1$ . Next, let  $s_{\mathcal{L}} \leq s$ . Then, since  $x_L \leq \beta a s$  due to Lemma A 2.5(p.305) (c), we have  $x_L \leq V_1$  and (7.4.5(p.41)). Accordingly, whether  $\beta a s \leq a^\star$  or  $s_{\mathcal{L}} \leq s$ , we have  $x_L \leq V_1$ , so  $x_L \leq V_{t-1}$  for t > 1 due to (a). Hence, since  $L(V_{t-1}) \leq 0$  for t > 1 from Corollary A 2.1(p.303) (a), for the same reason as in the proof of (b) we obtain  $\bullet$  d0ITd $_{\tau}\langle 1 \rangle_{\parallel}$  for  $\tau > 1$ .
- (c2iii2) Let  $\beta a s > a^* \cdots$  (9) and  $s < s_{\mathcal{L}}$ . Then, from (8) and Lemma A 2.5(p305) (c) we have  $x_K > x_L > \beta a s = V_1 \cdots$  (10), hence  $K(V_1) > 0 \cdots$  (11) from Lemma A 2.3(p303) (j1). In addition, since  $V_1 > a^*$  due to (9), we have  $V_{t-1} > a^*$  for t > 0 from (a). Now, from (A 4.12(p315)) and (11) we have  $V_2 V_1 > 0$ , i.e.,  $V_2 > V_1$ . Suppose  $V_{t-1} < V_t$ . Then, from (7.4.6(p41)) and Lemma A 2.3(p303) (g) we have  $V_t < \max\{K(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Accordingly, by induction  $V_{t-1} < V_t$  for t > 1, i.e.,  $V_t$  is strictly increasing in t > 0. Note that  $V_1 < x_L$  due to (10). Assume that  $V_{t-1} \le x_L$  for all t > 1, hence  $V \le x_L$ . Now, from (8) and  $V \ge x_K$  due to (a) we have the contradiction  $V \ge x_K > x_L \ge V$ . Hence, it is impossible that  $V_{t-1} \le x_L$  for all t > 1, implying that there exists  $t_{\tau}^* > 1$  such that

$$V_1 < V_2 < \dots < V_{t_{\tau}^{\bullet} - 1} < x_L \le V_{t_{\tau}^{\bullet}} < V_{t_{\tau}^{\bullet} + 1} < V_{t_{\tau}^{\bullet} + 2} < \dots,$$
 (A 4.15)

from which

$$V_{t-1} < x_L, \quad t_{\tau}^{\bullet} \ge t > 1, \qquad x_L \le V_{t-1}, \quad t > t_{\tau}^{\bullet}.$$
 (A 4.16)

Therefore, from Corollary A 2.1(p.303) (a) we have  $L(V_{t-1}) > 0 \cdots (12)$  for  $t^{\bullet}_{\tau} \ge t > 1$  and  $L(V_{t-1}) \le 0 \cdots (13)$  for  $t > t^{\bullet}_{\tau}$ .

- 1. Let  $t_{\tau}^{\bullet} \geq \tau > 1$ . Then, since  $L(V_{t-1}) > 0 \cdots (14)$  for  $\tau \geq t > 1$  from (12), for the same reason as in the proof of Tom A 4.3(p.315) (b) we have  $\boxed{\textcircled{3} \text{ dOITs}_{\tau} \langle \tau \rangle}_{\bullet}$  for  $t_{\tau}^{\bullet} \geq \tau > 1$  and Conduct<sub>to</sub> for  $\tau \geq t > 1$ . Hence  $S_{20}$ (p.315) (1) is true.
- 2. Let  $\tau > t_{\tau}^{\bullet}$ . Firstly, let  $\tau \geq t > t_{\tau}^{\bullet}$ . Then, since  $L(V_{t-1}) \leq 0$  for  $\tau \geq t > t_{\tau}^{\bullet}$  from (13), we have  $V_t = \beta V_{t-1}$  for  $\tau \geq t > t_{\tau}^{\bullet}$  from (A 4.11(p.315)), thus

$$V_{\tau} = \beta V_{\tau-1} = \beta^2 V_{\tau-2} = \dots = \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} \cdots (15).$$

Next, let  $t_{\tau}^{\bullet} \geq t > 1$ . Then, from (12) and (A 4.9(p.314)) we have  $V_t - \beta V_{t-1} > 0$  for  $t_{\tau}^{\bullet} \geq t > 1$ , i.e.,  $V_t > \beta V_{t-1}$  for  $t^{\bullet} \geq t > 1$ , hence

$$V_{t_{\tau}^{\bullet}} > \beta V_{t_{\tau}^{\bullet}-1} > \beta^2 V_{t_{\tau}^{\bullet}-2} > \dots > \beta^{t_{\tau}^{\bullet}-1} V_1 \cdots (16).$$

From (15) and (16) we have

$$V_{\tau} = \beta V_{\tau-1} = \beta^2 V_{\tau-2} = \dots = \beta^{\tau - t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} > \beta^{\tau - t_{\tau}^{\bullet} + 1} V_{t_{\tau}^{\bullet} - 1} > \beta^{\tau - t_{\tau}^{\bullet} + 2} V_{t_{\tau}^{\bullet} - 2} > \dots > \beta^{\tau - 1} V_{1},$$

hence we obtain  $t_{\tau}^* = t_{\tau}^{\bullet}$  for  $\tau > t_{\tau}^{\bullet}$  due to Preference Rule 8.2.1(p.45), i.e.,  $\boxed{\odot \text{ ndOIT}_{\tau} \langle t_{\tau}^{\bullet} \rangle}_{\parallel}$  for  $\tau > t_{\tau}^{\bullet}$ . In addition, we have Conduct<sub>t A</sub> for  $t^{\bullet} \geq t > 1$  due to (12) and (A 4.13(p.315)). Hence S<sub>20</sub>(p.315) (2) is true.

### $\mathbf{A} \ \mathbf{4.3} \quad \mathscr{A} \{ ilde{\mathsf{M}} : 1[\mathbb{P}][\mathtt{A}] \}$

Since  $\tilde{K}(x) + (1 - \beta)x = \tilde{L}(x)$  due to (6.1.34(p.27)) and (6.1.33(p.27)), from (7.4.8(p.41)) we have

$$V_t - \beta V_{t-1} = \min\{\tilde{L}(V_{t-1}), 0\} \le 0, \quad t > 1.$$
(A 4.17)

Accordingly:

1. If  $\tilde{L}(V_{t-1}) \leq 0$ , then  $V_t - \beta V_{t-1} = \tilde{L}(V_{t-1})$  or equivalently

$$V_t = \tilde{L}(V_{t-1}) + \beta V_{t-1} = \tilde{K}(V_{t-1}) + V_{t-1}, \quad t > 1.$$
(A 4.18)

2. If  $\tilde{L}(V_{t-1}) \geq 0$ , then  $V_t - \beta V_{t-1} = 0$  or equivalently

$$V_t = \beta V_{t-1}, \quad t > 1..$$
 (A 4.19)

Now, from (7.4.8(p.41)) with t=2 we have

$$V_2 - V_1 = \min\{\tilde{K}(V_1), -(1-\beta)V_1\}. \tag{A 4.20}$$

Finally, from (A 4.17(p.317)) we see that

$$\tilde{L}(V_{t-1}) < (>) 0 \Rightarrow \mathsf{Conduct}_{\mathsf{L}}(\mathsf{Skip}_{t}). \tag{A 4.21}$$

In this model let us note that the search must be necessarily conducted at time t = 1 (see Remark 4.1.3(p.20) (b)) and that

$$\lambda = 1 \cdots (1)$$
 (see  $A2(p.20)$ ),  $\delta = 1$  (see (11.2.1(p.56))). (A 4.22)

- $\square$  Tom A 4.5 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathsf{A}]\}$ ) Let  $\beta=1$  and s=0.
- (a)  $V_t$  is nonincreasing in t > 0.
- (b) We have  $\boxed{\$ dOITs_{\tau}\langle \tau \rangle}_{\blacktriangle}$  where  $Conduct_{\tau \geq t > 1}_{\blacktriangle}$ .
- Proof Let  $\beta = 1$  and s = 0. Then, from (6.1.34(p27)) we have  $\tilde{K}(x) = \tilde{T}(x) \leq 0 \cdots (1)$  for any x due to Lemma A 3.7(p.309) (g), hence from (7.4.8(p.41)) and (1) we have  $V_t = \min\{\tilde{T}(V_{t-1}) + V_{t-1}, V_{t-1}\} = \tilde{T}(V_{t-1}) + V_{t-1} \cdots (2)$  for t > 1.
- (a) Since  $V_2 = \tilde{T}(V_1) + V_1$  from (2), we have  $V_2 \leq V_1$  due to (1). Suppose  $V_{t-1} \geq V_t$ . Then, from (2) and Lemma A 3.7(p.309) (d) we have  $V_t \geq \tilde{T}(V_t) + V_t = V_{t+1}$ . Hence, by induction  $V_{t-1} \geq V_t$  for t > 1, i.e.,  $V_t$  is nonincreasing in t > 0.
- (b) Since  $V_1=b$  from (7.4.7 (p.41)), we have  $V_1>a$ . Suppose  $V_{t-1}>a$ . Then, noting  $b^*>b>a$  due to Lemma A 3.7 (p.309) (n), from (2) we have  $V_t>\tilde{T}(a)+a=a$  due to Lemma A 3.7 (p.309) (l,g). Accordingly, by induction  $V_{t-1}>a$  for t>1, hence  $\tilde{L}(V_{t-1})<0$  for t>1 due to Lemma A 3.8 (p.310) (d), thus  $\tilde{L}(V_{t-1})<0\cdots$  (3) for  $\tau\geq t>1$ . Hence, from (A 4.17 (p.317)) we obtain  $V_t-\beta V_{t-1}<0$  for  $\tau\geq t>1$ , i.e.,  $V_t<\beta V_{t-1}$  for  $\tau\geq t>1$ . Accordingly  $V_\tau<\beta V_{\tau-1}<\cdots<\beta^{\tau-1}V_1$ , hence  $t_\tau^*=\tau$  for  $\tau>1$ , i.e.,  $subset{subset}$  do  $subset{subset}$  for  $\tau>1$ . Then  $subset{conduct}$  for  $\tau\geq t>1$  due to (3) and (A  $subset{subset}$ ).

Let us define

$$\mathbf{S}_{21} \boxed{ \begin{tabular}{ll} \hline $\mathbf{S}_{21}$ \hline \hline $\mathbf{S}_{\mathbf{A}}$ \hline $\mathbf{S}_{\mathbf{A}}$ \hline $\mathbf{S}_{\mathbf{A}}$ \hline $\mathbf{S}_{\mathbf{A}}$ \hline $\mathbf{S}_{\mathbf{A}}$ \hline \hline $\mathbf{$$

 $\square$  Tom A 4.6 ( $\mathscr{A}\{\tilde{\mathsf{M}}:1[\mathbb{P}][\mathbb{A}]\}$ ) Let  $\beta<1$  or s>0.

- (a)  $V_t$  is nonincreasing in t > 0 and converges to a finite  $V \leq x_{\tilde{K}}$  as  $t \to \infty$ .
- (b) Let  $\beta b \leq a$ . Then  $\bullet dOITd_{\tau>1}\langle 1 \rangle_{\parallel}$ .
- (c) Let  $\beta b > a$ .
  - 1. Let  $\beta = 1$ .
    - i. Let  $b+s \geq b^*$ . Then  $\bullet dOITd_{\tau>1}\langle 1 \rangle_{\parallel}$ .
    - ii. Let  $b+s < b^{\star}$ . Then  $\boxed{\$ \text{ dOITs}_{\tau>1}\langle \tau \rangle}_{\blacktriangle}$  where  $\texttt{Conduct}_{\tau \geq t>1}_{\blacktriangle}$ .
  - 2. Let  $\beta < 1$  and s = 0 (s > 0).
    - i. Let a < 0 ( $\tilde{\kappa} < 0$ ). Then subseteq dOITs $_{\tau > 1} \langle \tau \rangle$  where Conduct $_{\tau \geq t > 1}$ .
    - ii. Let a = 0 ( $\tilde{\kappa} = 0$ ).
      - 1. Let  $\beta b + s \geq b^*$ . Then  $\bullet dOITd_{\tau > 1}\langle 1 \rangle_{\parallel}$ .
      - $2. \quad Let \ \beta b + s < b^{\star}. \ \ Then \ \boxed{\$ \ \text{dOITs}_{\tau} \langle \tau > 1 \rangle}_{\blacktriangle} \ \ where \ \ \text{Conduct}_{\tau \geq t > 1_{\blacktriangle}}.$
    - iii. Let a > 0 ( $\tilde{\kappa} > 0$ ).
      - 1. Let  $\beta b + s \geq b^*$  or  $s_{\tilde{\mathcal{L}}} \leq s$ . Then  $\boxed{\bullet \text{ dOITd}_{\tau > 1}\langle 1 \rangle}_{\parallel}$ .
      - 2. Let  $\beta b + s < b^*$  and  $s < s_{\tilde{c}}$ . Then  $S_{21} \circ A * \Delta$  is true.  $\square$
- *Proof* Let  $\beta < 1$  or s > 0. First note (A 4.22 (1,2) (p.317)).
- (a) Since  $x_{\tilde{K}} \leq (\beta b + s)/\delta = \beta b + s = V_1$  due to Lemma A 3.9(p.310) (j2) and (7.4.7(p.41)), we have  $\tilde{K}(V_1) \leq 0$  due to Lemma A 3.9(p.310) (j1), hence  $V_2 V_1 \leq 0$  from (A 4.20(p.317)), i.e.,  $V_1 \geq V_2$ . Suppose  $V_{t-1} \geq V_t$ . Then, from (7.4.8(p.41)) and Lemma A 3.9(p.310) (e) we have  $V_t \geq \min\{\tilde{K}(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Hence, by induction  $V_{t-1} \geq V_t$  for t > 1, i.e.,  $V_t$  is nonincreasing in t > 0. Consider a sufficiently small M < 0 such that  $\beta b + s \geq M$  and  $a \geq M$ , hence  $V_1 \geq M$ . Suppose  $V_{t-1} \geq M$ . Then, from Lemma A 3.9(p.310) (e) and (A 3.5 (2) (p.310)) we have  $V_t \geq \min\{\tilde{K}(M) + M, \beta M\} = \min\{\beta M + s, \beta M\} \geq \min\{M, M\} = M$  due to  $\beta \leq 1$  and  $s \geq 0$ . Hence, by induction  $V_t \geq M$  for t > 0, i.e.,  $V_t$  is lower bounded in t. Accordingly  $V_t$  converges to a finite V as  $t \to \infty$ . Then, from (7.4.8(p.41)) we have  $V = \min\{\tilde{K}(V) + V, \beta V\}$ , hence  $0 = \min\{\tilde{K}(V), -(1-\beta)\beta V\}$ . Thus, since  $\tilde{K}(V) \geq 0$ , we have  $V \leq x_{\tilde{K}}$  from Lemma A 3.9(p.310) (j1).
- (b) Let  $\beta b \leq a \cdots$  (1). Then  $x_{\tilde{L}} \geq \beta b + s = V_1$  from Lemma A 3.11(p.311) (c1) with  $\lambda = 1$  and  $\delta = 1$ , hence  $x_{\tilde{L}} \geq V_{t-1}$  for t > 1 from (a). Accordingly, since  $\tilde{L}(V_{t-1}) \geq 0$  for t > 1 due to Corollary A 3.2(p.310) (a), we have  $\tilde{L}(V_{t-1}) \geq 0$  for  $\tau \geq t > 1$ . Hence, from (A 4.19(p.317)) we have  $V_t = \beta V_{t-1}$  for  $\tau \geq t > 1$ . Thus, we have  $V_\tau = \beta V_{\tau-1} = \cdots = \beta^{\tau-1} V_1$ , i.e.,  $I_\tau^\tau = I_\tau^{\tau-1} = \cdots = I_\tau^1$ , hence  $I_\tau^\tau = I_\tau^\tau =$ 
  - (c) Let  $\beta b > a$ .
- (c1) Let  $\beta = 1 \cdots$  (2), hence s > 0 due to the assumption " $\beta < 1$  or s > 0" of the lemma. Then, we see that  $(\lambda \beta b + s)/\delta = b + s \cdots$  (3) due to (2(p.318)) and (A.4.22(p.317)). In addition, since  $x_{\tilde{L}} = x_{\tilde{K}} \cdots$  (4) from Lemma A 3.10(p.311) (b), we have  $\tilde{K}(x_{\tilde{L}}) = \tilde{K}(x_{\tilde{K}}) = 0 \cdots$  (5).
- (c1i) Let  $b+s \geq b^*$ . Then  $x_{\tilde{L}} = x_{\tilde{K}} = b+s = V_1$  from (4), Lemma A 3.9(p.310) (j2, (3), and (7.4.7(p.41)). Accordingly, since  $x_{\tilde{L}} \geq V_{t-1}$  for t > 1 from (a), we have  $\tilde{L}(V_{t-1}) \geq 0$  for t > 1 due to Corollary A 3.2(p.310) (a). Hence, for the same reason as in the proof of (b) we obtain  $\bullet \text{dOITd}_{\tau}(1)$  for  $\tau > 1$ .
- (c1ii) Let  $b+s < b^*$ . Then  $x_{\tilde{L}} = x_{\tilde{K}} < b+s = V_1 < b^*$  from (4), Lemma A 3.9(p.310) (j2), and (7.4.7(p.41)), hence  $b^* > V_{t-1}$  for t > 1 from (a). Suppose  $V_{t-1} > x_{\tilde{L}}$ , hence  $\tilde{L}(V_{t-1}) < 0$  from Corollary A 3.2(p.310) (a). Then, from (A 4.18(p.317)), Lemma A 3.9(p.310) (g), and (5) we have  $V_t > \tilde{K}(x_{\tilde{L}}) + x_{\tilde{L}} = x_{\tilde{L}}$ . Accordingly, by induction  $V_{t-1} > x_{\tilde{L}}$  for t > 1, hence,  $\tilde{L}(V_{t-1}) < 0$  for t > 1 from

Corollary A 3.2(p.310) (a). Thus, for the same reason as in the proof of Tom A 4.5(p.317) (b) we have  $\boxed{\text{$\odot$ dOITs}_{\tau}\langle\tau\rangle}_{\blacktriangle}$  for  $\tau>1$ , and Conduct<sub>t $\blacktriangle$ </sub> for  $\tau\geq t>1$ .

- (c2) Let  $\beta < 1$  and s = 0 ((s > 0)).
- (c2i) Let a<0 ( $\tilde{\kappa}<0$ ). Then  $x_{\tilde{L}}< x_{\tilde{\kappa}}<0\cdots$  (6) from Lemma A 3.10(p311) (c (d)). Now, since  $x_{\tilde{\kappa}}\leq \beta b+s$  due to Lemma A 3.9(p310) (j2) with  $\lambda=1$  and  $\delta=1$ , we have  $x_{\tilde{\kappa}}\leq V_1$  from (7.4.7(p.41)). Suppose  $x_{\tilde{\kappa}}\leq V_{t-1}$ . Then, from Lemma A 3.9(p310) (e) we have  $V_t\geq \min\{\tilde{K}(x_{\tilde{\kappa}})+x_{\tilde{\kappa}},\beta\,x_{\tilde{\kappa}}\}=\min\{x_{\tilde{\kappa}},\beta\,x_{\tilde{\kappa}}\}=x_{\tilde{\kappa}}$  due to  $x_{\tilde{\kappa}}<0$ . Accordingly, by induction  $V_{t-1}\geq x_{\tilde{\kappa}}$  for t>1, hence  $V_{t-1}>x_{\tilde{L}}$  for t>1 from (6), thus  $\tilde{L}(V_{t-1})<0$  for t>1 due to Corollary A 3.2(p310) (a). Hence, for the same reason as in the proof of Tom A 4.5(p317) (b) we have s=00 doi: s=01.
  - (c2ii) Let a=0 ( $\tilde{\kappa}=0$ ). Then  $x_{\tilde{L}}=x_{\tilde{K}}\cdots$  (7) from Lemma A 3.10(p.311) (c (d)).
- (c2ii1) Let  $\beta b + s \geq b^{\star}$ . Then,  $x_{\tilde{K}} = \beta b + s = V_1$  from Lemma A 3.9(p.310) (j2) and (7.4.7(p.41)). Suppose  $V_{t-1} = x_{\tilde{K}}$ , hence  $V_{t-1} = x_{\tilde{L}}$  from (7), thus  $\tilde{L}(V_{t-1}) = \tilde{L}(x_{\tilde{L}}) = 0$ . Then, from (A 4.18(p.317)) we have  $V_t = \tilde{K}(x_{\tilde{K}}) + x_{\tilde{K}} = x_{\tilde{K}}$ . Accordingly, by induction  $V_{t-1} = x_{\tilde{K}}$  for t > 1, hence  $V_{t-1} = x_{\tilde{L}}$  for t > 1 due to (7). Then, since  $\tilde{L}(V_{t-1}) = \tilde{L}(x_{\tilde{L}}) = 0$  for t > 1, we have  $V_t = \beta V_{t-1}$  for t > 1 from (A 4.19(p.317)), hence, for the same reason as in the proof of (b) we obtain  $\boxed{\bullet \text{dOITd}_{\tau}\langle 1 \rangle}_{\parallel}$  for  $\tau > 1$ .
- (c2ii2) Let  $\beta b + s < b^{\star}$ . Then, since  $V_1 < b^{\star}$  from (7.4.7 p.4l), we have  $V_{t-1} < b^{\star}$  for t > 1 due to (a). In addition, we have  $x_{\tilde{K}} < \beta b + s = V_1$  from Lemma A 3.9 p.3l0 (j2). Suppose  $x_{\tilde{K}} < V_{t-1}$ , hence  $x_{\tilde{L}} < V_{t-1}$  from (7). Then, since  $\tilde{L}(V_{t-1}) < 0$  due to Corollary A 3.2 p.3l0 (a), from (A 4.18 p.3l7) and Lemma A 3.9 p.3l0 (g) we have  $V_t > \tilde{K}(x_{\tilde{K}}) + x_{\tilde{K}} = x_{\tilde{K}}$ . Hence, by induction  $x_{\tilde{K}} < V_{t-1}$  for t > 1, thus  $x_{\tilde{L}} < V_{t-1}$  for t > 1 due to (7). Accordingly, since  $\tilde{L}(V_{t-1}) < 0$  for t > 1 due to Corollary A 3.2 p.3l0 (a), for the same reason as in the proof of Tom A 4.5 p.3l7) (b) we have 3.2 p.3l0 for  $\tau > 1$ , and Conduct<sub>t.</sub> for  $\tau \ge t > 1$ .
  - (c2iii) Let a>0 ( $\tilde{\kappa}>0$ ). Then  $x_{\tilde{L}}>x_{\tilde{K}}\cdots$  (8) from Lemma A 3.10(p.311) (c (d)).

(c2iii1) Let  $\beta b + s \geq b^{\star}$  or  $s_{\tilde{\mathcal{L}}} \leq s$ . First let  $\beta b + s \geq b^{\star}$ . Then, since  $x_{\tilde{K}} = \beta b - s = V_1$  from Lemma A 3.9(p.310) (j2), we have  $x_{\tilde{\mathcal{L}}} > V_1$  from (8), hence  $x_{\tilde{\mathcal{L}}} \geq V_1$ . Next let  $s_{\tilde{\mathcal{L}}} \leq s$ . Then, since  $x_{\tilde{\mathcal{L}}} \geq \beta b + s$  due to Lemma A 3.11(p.311) (d), we have  $x_{\tilde{\mathcal{L}}} \geq V_1$ . Accordingly, whether  $\beta b + s \geq b$  or  $s_{\tilde{\mathcal{L}}} \leq s$ , we have  $x_{\tilde{\mathcal{L}}} \geq V_1$ , thus  $x_{\tilde{\mathcal{L}}} \geq V_{t-1}$  for t > 1 due to (a). Hence, since  $\tilde{\mathcal{L}}(V_{t-1}) \geq 0$  for t > 1 from Corollary A 3.2(p.310) (a), for the same reason as in the proof of (b) we obtain  $\bullet$  d0ITd $_{\tau}\langle 1 \rangle_{\parallel}$  for  $\tau > 1$ .

(c2iii2) Let  $\beta b + s < b^* \cdots$  (9) and  $s < s_{\tilde{\mathcal{L}}}$ . Then, from (8) and Lemma A 3.11(p311) (d) we have  $x_{\tilde{K}} < x_{\tilde{L}} < \beta b + s = V_1 \cdots$  (10), hence  $\tilde{K}(V_1) < 0 \cdots$  (11) from Lemma A 3.9(p310) (j1). In addition, since  $V_1 < b^*$  due to (9), we have  $V_{t-1} < b^*$  for t > 0 from (a). Now, from (A 4.20(p317)) and (11) we have  $V_2 - V_1 < 0$ , i.e.,  $V_2 < V_1$ . Suppose  $V_{t-1} > V_t$ . Then, from Lemma A 3.9(p310) (g) we have  $V_t > \min\{\tilde{K}(V_t) + V_t, \beta V_t\} = V_{t+1}$ . Accordingly, by induction  $V_{t-1} > V_t$  for t > 1, i.e.,  $V_t$  is strictly decreasing in t > 0. Note that  $V_1 > x_{\tilde{L}}$  due to (10). Assume that  $V_{t-1} \ge x_{\tilde{L}}$  for all t > 1, hence  $V \ge x_{\tilde{L}}$  due to (a). Then, from (8) and  $V \le x_{\tilde{K}}$  due to (a) we have the contradiction of  $V \le x_{\tilde{K}} < x_{\tilde{L}} \le V$ . Hence, it is impossible that  $V_{t-1} \ge x_{\tilde{L}}$  for all t > 1, implying that there exists  $t_{\tau}^{\bullet} > 1$  such that

$$V_1 > V_2 > \dots > V_{t^*-1} > x_{\tilde{L}} \ge V_{t^*} > V_{t^*+1} > V_{t^*+2} > \dots,$$
 (A 4.23)

from which

$$V_{t-1} > x_{\tilde{L}}, \quad t_{\tau}^{\bullet} \ge t > 1, \qquad x_{\tilde{L}} \ge V_{t-1}, \quad t > t_{\tau}^{\bullet}.$$
 (A 4.24)

Therefore, from Corollary A 3.2(p.310) (a) we have  $\tilde{L}(V_{t-1}) < 0 \cdots (12)$  for  $t^{\bullet} \geq t > 1$  and  $\tilde{L}(V_{t-1}) \geq 0 \cdots (13)$  for  $t > t^{\bullet}$ .

- 1. Let  $t_{\tau}^{\bullet} \geq \tau > 1$ . Then, since  $\tilde{L}(V_{t-1}) < 0 \cdots (14)$  for  $\tau \geq t > 1$  from (12), for the same reason as in the proof of Tom A 4.5(p317) (b) we have  $\boxed{\$ \text{ dOITs}_{\tau}\langle \tau \rangle}_{\bullet}$  for  $\tau > 1$ , and Conduct<sub>t</sub> for  $\tau \geq t > 1$ . Hence  $\mathbf{S}_{21}$ (p317) (1) is true.
- 2. Let  $\tau > t_{\tau}^{\bullet}$ . Firstly, let  $\tau \geq t > t_{\tau}^{\bullet}$ . Then, since  $\tilde{L}(V_{t-1}) \geq 0$  for  $\tau \geq t > t_{\tau}^{\bullet}$  from (13), we have  $V_t = \beta V_{t-1}$  for  $\tau \geq t > t_{\tau}^{\bullet}$  from (A 4.19(p.317)), thus

$$V_{\tau} = \beta V_{\tau-1} = \beta^2 V_{\tau-2} = \dots = \beta^{\tau-t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}} \cdots (15).$$

Next, let  $t_{\tau}^{\bullet} \geq t > 1$ . Then, from (12) and (A 4.17(p.317)) we have  $V_t - \beta V_{t-1} < 0$  for  $t_{\tau}^{\bullet} \geq t > 1$ , i.e.,  $V_t < \beta V_{t-1}$  for  $t_{\tau}^{\bullet} \geq t > 1$ , hence

$$V_{t_{\tau}^{\bullet}} < \beta V_{t_{\tau}^{\bullet}-1} < \beta^2 V_{t_{\tau}^{\bullet}-2} < \dots < \beta^{t_{\tau}^{\bullet}-1} V_1 \cdots (16).$$

From (15) and (16) we have

$$V_{\tau} = \beta V_{\tau-1} = \beta^2 V_{\tau-2} = \dots = \boxed{\beta^{\tau - t_{\tau}^{\bullet}} V_{t_{\tau}^{\bullet}}} < \beta^{\tau - t_{\tau}^{\bullet} + 1} V_{t_{\tau}^{\bullet} - 1} < \beta^{\tau - t_{\tau}^{\bullet} + 2} V_{t_{\tau}^{\bullet} - 2} < \dots < \beta^{\tau - 1} V_{1},$$

hence we obtain  $t_{\tau}^* = t_{\tau}^{\bullet}$  for  $\tau > t_{\tau}^{\bullet}$  due to Preference Rule 8.2.1(p.45), i.e.,  $\boxed{\odot \text{ ndOIT}_{\tau}\langle t_{\tau}^{\bullet}\rangle}$  for  $\tau > t_{\tau}^{\bullet}$ . In addition, we have Conduct<sub>t A</sub> for  $t_{\tau}^{\bullet} \geq t > 1$  due to (12) and (A 4.21(p.317)). Hence S<sub>21</sub>(2) is true.

#### A 5 Optimal Initiating Time of Markovian Decision Processes

This section defines the optimal initiating time (OIT) for Markovian decision processes (MDP) [22,Howard,1960][39,Ross], which can be regarded as the most general model of decision processes.

#### A 5.1 Standard Definition of Markovian Decision Processes

#### A 5.1.1 Maximization MDP

Let the process be in a state i at a time t (see Figure 2.2.1(p.11)), and if an action x is taken at that time, then a reward r(i,x) can be obtained and the present state i changes into j at the next time t-1 with a known probability p(j|i,x). By  $v_t(i)$  let us denote the maximum of the total expected present discounted profit gained over a given planning horizon starting from a time t in a state i. Then we have

$$v_t(i) = \max_x \{ r(i, x) + \beta \sum_i p(j|i, x) v_{t-1}(j) \}, \quad t > 0,$$
(A 5.1)

where  $v_0(i)$  is a profit specified for a reason inherent in the process; in many cases,  $v_0(i) = \max_x r(i, x)$ . Let us call the decision process the maximization MDP.

#### A 5.1.2 Minimization MDP

This is the inverse of the maximization MDP where if an action x is taken at a given time t in a state i, a  $cost\ c(i,x)$  must be paid. By  $v_t(i)$  let us denote the minimum of the total expected present discounted cost over a given planning horizon from starting a time t in a state i. Then we have

$$v_t(i) = \min_x \{ c(i, x) + \beta \sum_i p(j|i, x) v_{t-1}(j) \}, \quad t > 0,$$
(A 5.2)

where  $v_0(i)$  is a cost specified for a reason inherent in the process; in many cases,  $v_0(i) = \min_x c(i, x)$ . Let us call the decision process the minimization MDP.

#### A 5.2 Optimal Initiating Time

#### A 5.2.1 Initiating State $i_{\circ}$

Assume that a common state  $i_{\circ}$  is defined for any given initiating time  $t \geq 0$ , and let us define

$$V_t \stackrel{\text{def}}{=} v_t(i_\circ), \quad t \le \tau.$$
 (A 5.3)

# A 5.2.2 Relationship between $V_{[\tau]}$ and $V_{\beta[\tau]}$ (see Section 8.2.4.2(p.45))

In this section, by using some examples, let us demonstrate that the monotonicity of

$$V_{[\tau]} = \{V_{\tau}, V_{\tau-1}, V_{\tau-2}, \cdots, V_{t_{qd}}\} \quad \text{(original sequence)}$$

is not always inherited to

$$V_{\beta[\tau]} = \{V_{\tau}, \beta V_{\tau-1}, \beta^2 V_{\tau-2}, \cdots, \beta^{\tau} V_{t_{qd}}\} \quad (\beta\text{-adjusted sequence}).$$

Below let

 $\square$  Example 1.5.1 (maximization MDP) Suppose  $V_{[\tau]}$  is strictly increasing in t where

$$V_{\tau} > V_{\tau-1} > V_{\tau-2} > \dots > V_0 > 0.$$

In this case, as seen in Figure A 5.1(p.320) below, we have  $V_{\tau} > \beta V_{\tau-1} > \beta^2 V_{\tau-2} > \dots > \beta^{\tau} V_0 > 0$ , i.e., the monotonicity of  $V_{[\tau]}$  is inherited to  $V_{\beta[\tau]}$  where the optimal initiating time is given by  $t_{16}^* = 16$  (§).  $\Box$ 

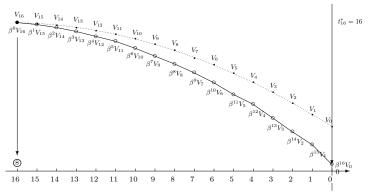


Figure A 5.1: Inheritance of monotonicity

 $\square$  Example 1.5.2 (maximization MDP) Suppose  $V_{[\tau]}$  is strictly increasing in t where

$$V_{\tau} > \beta V_{\tau-1} > V_{\tau-2} > \dots > V_{\tau-t'} > 0 > V_{\tau-t'-1} > \dots > V_0.$$

In this case, as seen in Figure A 5.2(p.320) below, the monotonicity in  $V_{[\tau]}$  collapses in  $V_{\beta[\tau]}$  where the optimal initiating time is given by  $t_{16}^* = 16$  (§).  $\Box$ 

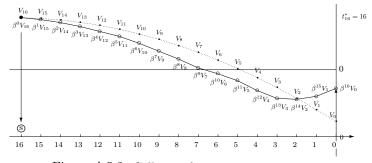


Figure A 5.2: Collapse of monotonicity

 $\square$  Example 1.5.3 (maximization MDP) Suppose  $V_{[\tau]}$  is strictly decreasing in t where

$$0 < V_{\tau} < \beta V_{\tau-1} < V_{\tau-2} < \dots < V_0.$$

In this case, as seen in Figure A 5.3(p.321) below, the monotonicity in  $V_{[\tau]}$  collapses in  $V_{\beta[\tau]}$  where the optimal initiating time is given by  $t_{16}^* = 6$ , i.e., nondegenerate ( $\odot$ ).  $\square$ 

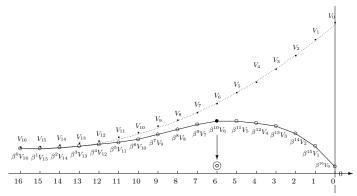


Figure A 5.3: Collapse of monotonicity

 $\square$  Example 1.5.4 (minimization MDP) Suppose  $V_{[\tau]}$  is strictly decreasing in t where

$$0 < V_{\tau} < \beta V_{\tau - 1} < \dots < V_{\tau - t'} < 0 < V_{\tau - t' - 1} < \dots < V_0.$$

In this case, as seen in Figure A 5.4(p.321) below, the monotonicity in  $V_{[\tau]}$  collapses in  $V_{\beta[\tau]}$  where the optimal initiating time is given by  $t_{16}^* = 16$  (§).  $\Box$ 

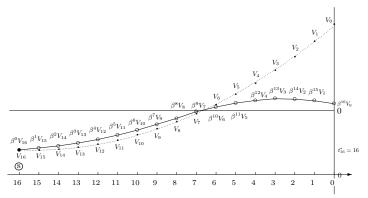


Figure A 5.4: Collapse of monotonicity

# A 6 Calculation of Solutions $x_K$ , $x_L$ , and $s_L$

The following lemma is used to numerically calculate the solutions  $x_K$ ,  $x_L$ , and  $s_L$  (see Section 6.2(p.27)).

#### Lemma A 6.1 $(x_K, x_L, s_L)$

- (a)  $\min\{a, (\lambda \beta \mu s)/\delta\} \le x_K \le \max\{b, 0\}.$
- (b)  $\min\{a, (\lambda \beta \mu s)/\lambda\} \leq x_L \leq b.$
- (c)  $0 \le s_{\mathcal{L}} \le \lambda \beta \mu \min\{a, 0\}.$
- Proof (a)
  - $\circ \text{ Let } x \leq a \cdots \text{(1)}. \text{ Now, from } (11.2.4\,(1)\,\text{(p.57)}) \text{ we have } K(x) = \delta\big((\lambda\beta\mu s)/\delta x\big), \text{ hence } K(x) \geq 0 \text{ for } x \leq (\lambda\beta\mu s)/\delta.$  From this and (1) we have  $K(x) \geq 0$  for  $x \leq \min\{a, (\lambda\beta\mu s)/\delta\}, \text{ hence } K(\min\{a, (\lambda\beta\mu s)/\delta\}) \geq 0.$ 
    - 1. Let  $K(\min\{a,(\lambda\beta\mu-s)/\delta\}) > 0$ . Then  $\min\{a,(\lambda\beta\mu-s)/\delta\} < x_K \cdots$  (2) due to Corollary 11.2.2(p.58) (a).
    - 2. Let  $K(\min\{a, (\lambda \beta \mu s)/\delta\}) = 0$ .
      - · If  $\beta = 1$  and s = 0, then  $\min\{a, (\lambda \beta \mu s)/\delta\} \ge x_K$  due to Lemma 11.2.2(p.57) (i). Since  $\min\{a, (\lambda \beta \mu s)/\delta\} \le a < b = x_K$  from Lemma 11.2.2(p.57) (i), we have  $\min\{a, (\lambda \beta \mu s)/\delta\} = x_K$ .
      - · If  $\beta < 1$  or s > 0, then  $\min\{a, (\lambda \beta \mu s)/\delta\} = x_K$  due to Lemma 11.2.2(p.57) (j1).

Accordingly, whether " $\beta = 1$  and s = 0" or " $\beta < 1$  or s > 0", we have  $\min\{a, (\lambda \beta \mu - s)/\delta\} = x_K \cdots$  (3).

Thus, from (2) and (3) we have  $\min\{a, (\lambda \beta \mu - s)/\delta\} \leq x_K \cdots (4)$ .

○ Let  $b \le x \cdots$  (5). Now, from (11.2.5 (2) (p.57)) we have  $K(x) \le 0$  for  $0 \le x$ . From this and (5) we have  $K(x) \le 0$  for  $\max\{b,0\} \le x$ , hence  $0 \ge K(\max\{b,0\})$ . Accordingly, we have  $x_K \le \max\{b,0\} \cdots$  (6) due to Corollary 11.2.2(p.58) (a).

From (4) and (6) the assertion becomes true.

(b)

- Let  $x \leq a \cdots$  (7). Now, from (11.2.3 (1) (p.57)) we have  $L(x) = \lambda \beta ((\lambda \beta \mu s)/\lambda \beta x)$ , hence  $L(x) \geq 0$  for  $x \leq (\lambda \beta \mu s)/\lambda \beta$ . From this and (7) we have  $L(x) \geq 0$  for  $x \leq \min\{a, (\lambda \beta \mu - s)/\lambda \beta\}$ , hence  $L(\min\{a, (\lambda \beta \mu - s)/\lambda \beta\}) \geq 0$ .
  - 1. Let  $L(\min\{a, (\lambda\beta\mu s)/\lambda\beta\}) > 0$ . Then  $\min\{a, (\lambda\beta\mu s)/\lambda\beta\} < x_L \cdots (8)$  due to Corollary 11.2.1(p.57) (a).
  - 2. Let  $L(\min\{a, (\lambda \beta \mu s)/\lambda \beta\}) = 0$ .
    - · If s=0, then  $\min\{a,(\lambda\beta\mu-s)/\lambda\beta\} \ge x_L$  due to Lemma 11.2.1(p.57) (d). Since  $\min\{a,(\lambda\beta\mu-s)/\lambda\beta\} \le a < b=x_L$  from Lemma 11.2.1(p.57) (d), hence  $\min\{a,(\lambda\beta\mu-s)/\lambda\beta\} = x_L$ .
    - · If s > 0, then  $\min\{a, (\lambda \beta \mu s)/\lambda \beta\} = x_L$  due to Lemma 11.2.1(p.57) (e1).

Accordingly, whether s = 0 or s > 0, we have  $\min\{a, (\lambda \beta \mu - s)/\lambda \beta\} = x_L \cdots (9)$ .

Thus, from (8) and (9) we have  $\min\{a, (\lambda \beta \mu - s)/\lambda \beta\} \leq x_L \cdots (10)$ .

○ Let  $b \le x \cdots$  (11). Then, from (6.1.3(p.25)) and Lemma 11.1.1(p.55) (g) we have  $L(x) = -s \le 0$ , hence  $0 \ge L(b)$ . Accordingly, due to Corollary 11.2.1(p.57) (a) we have  $x_L \le b \cdots$  (12).

From (10) and (12) the assertion becomes true.

(c) From (6.1.5(p.25)) and (6.1.3(p.25)) we have  $\mathcal{L}(0) = L(\lambda\beta\mu) = \lambda\beta T(\lambda\beta\mu) \ge 0 \cdots (13)$  due to

Lemma 11.1.1(p.55) (g). Now, for a sufficiently large s>0 such that  $\lambda\beta\mu-s\leq a$  and  $\lambda\beta\mu-s\leq 0\cdots$  (14) we have  $s\geq \lambda\beta\mu-a$  and  $s\geq \lambda\beta\mu$ , hence  $s\geq \max\{\lambda\beta\mu-a,\lambda\beta\mu\}=\lambda\beta\mu+\max\{-a,0\}=\lambda\beta\mu-\min\{a,0\}\cdots$  (15). Then, from (6.1.5(p.25)), (6.1.3(p.25)), and Lemma 11.1.1(p.55) (f) we have

$$\mathcal{L}(s) = \lambda \beta T(\lambda \beta \mu - s) - s = \lambda \beta (\mu - \lambda \beta \mu + s) - s = \lambda \beta \mu - \lambda \beta (\lambda \beta \mu - s) - s = (1 - \lambda \beta)(\lambda \beta \mu - s).$$

Hence, since  $1 \ge \lambda \beta$ , due to (14) we have  $\mathcal{L}(s) \le 0$  for  $s \ge \lambda \beta \mu - \min\{a, 0\}$  due to (15), so  $\mathcal{L}(\lambda \beta \mu - \min\{a, 0\}) \le 0$ . From this and (13) we have  $\mathcal{L}(0) \ge 0 \ge \mathcal{L}(\lambda \beta \mu - \min\{a, 0\})$ , hence due to Lemma 11.2.4(p.59) (a) we have  $0 \le s_{\mathcal{L}} \le \lambda \beta \mu - \min\{a, 0\}$ .

# A 6.1 Calculation of Solutions $x_{\tilde{k}}$ , $x_{\tilde{L}}$ , and $s_{\tilde{L}}$

Lemma A 6.2 ( $x_{\tilde{K}}, x_{\tilde{L}}, s_{\tilde{L}}$ )

- (a)  $\max\{b, (\lambda \beta \mu + s)/\delta\} \ge x_{\tilde{K}} \ge \min\{a, 0\}.$
- (b)  $\max\{b, (\lambda\beta\mu + s)/\lambda\beta\} \ge x_{\tilde{L}} \ge a$ .
- (c)  $0 \le s_{\tilde{\mathcal{L}}} \le -\lambda \beta \mu + \max\{b, 0\}.$
- ullet Proof Applying the operation  ${\mathcal R}$  to Lemma A 6.1(p.321) leads to
- $\langle \mathbf{a} \rangle \quad \min\{-\hat{a}, (-\lambda\beta\hat{\mu} s)/\delta\} \le -\hat{x}_K \le \max\{-\hat{b}, 0\}.$
- $\langle \mathbf{b} \rangle = \min\{-\hat{a}, (-\lambda \beta \hat{\mu} s)/\lambda\}\beta \le -\hat{x}_L \le -\hat{b}.$
- $\langle c \rangle \quad 0 \le s_{\mathcal{L}} \le -\lambda \beta \hat{\mu} \min\{-\hat{a}, 0\}.$

The above can be rewritten as below:

- $\langle a \rangle \max\{\hat{a}, (\lambda \beta \hat{\mu} + s)/\delta\} \le -\hat{x}_K \le -\min\{\hat{b}, 0\}.$
- $\langle \mathbf{b} \rangle \max\{\hat{a}, (\lambda \beta \hat{\mu} + s)/\lambda\}\beta \le -\hat{x}_L \le -\hat{b}.$
- $\langle c \rangle \quad 0 \le s_{\mathcal{L}} \le -\lambda \beta \hat{\mu} + \max{\{\hat{a}, 0\}}.$

The above can be rewritten as below:

- $\langle \mathbf{a} \rangle = \max\{\hat{a}, (\lambda \beta \hat{\mu} + s) / \delta \ge \hat{x}_K \ge \min\{\hat{b}, 0\}.$
- $\langle \mathbf{b} \rangle = \max\{\hat{a}, (\lambda \beta \hat{\mu} + s)/\lambda\}\beta \geq \hat{x}_L \geq \hat{b}.$
- $\langle c \rangle \quad 0 \le s_{\mathcal{L}} \le -\lambda \beta \hat{\mu} + \max{\{\hat{a}, 0\}}.$

Applying the operation  $\mathcal{C}_{\mathbb{R}}$  (see Lemma 13.3.1(p.72) (b,g,h,i) to the above yields

- $\langle a \rangle \max\{\check{b}, (\lambda \beta \check{\mu} + s)/\delta\} \ge x_{\check{\kappa}} \ge \min\{\check{a}, 0\}.$
- $\langle \mathbf{b} \rangle = \max\{\check{b}, (\lambda \beta \check{\mu} + s)/\lambda\}\beta \geq x_{\check{L}} \geq \check{a}.$
- $\langle c \rangle \quad 0 \le s_{\tilde{c}} \le -\lambda \beta \check{\mu} + \max\{\check{b}, 0\}.$

Finally, applying the operation  $\mathcal{I}_{\mathbb{R}}$  (see Lemma 13.3.3(p.73) (b,g,h,i), we obtain (a)-(c) of this lemma.

# A 7 Others

### A 7.1 Monotonicity of Solution

**Proposition A 7.1** In general, for the solution  $x_t$  of a given equation  $g_t(x) = 0$  we have:

Case A Let  $g_t(x)$  is nondecreasing in x for all t.

- (I) If  $g_t(x)$  is nondecreasing in t for all x, then  $x_t$  is nonincreasing in t.
- (II) If  $g_t(x)$  is nonincreasing in t for all x, then  $x_t$  is nondecreasing in t.

Case B Let  $g_t(x)$  is nonincreasing in x for all t.

- (III) If  $g_t(x)$  is nondecreasing in t for all x, then  $x_t$  is nondecreasing in t.
- (IV) If  $g_t(x)$  is nonincreasing in t for all x, then  $x_t$  is nonincreasing in t.  $\square$
- $\bullet$  *Proof* Evident from Figures A 7.1(p.323) and A 7.2(p.323) below:

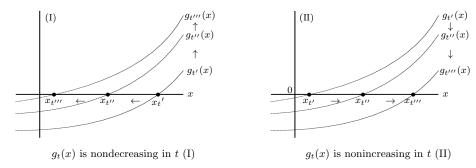


Figure A 7.1: Case A:  $g_t(x)$  is nondecreasing in x

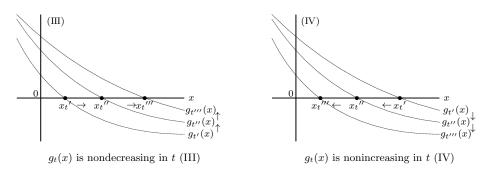


Figure A 7.2: Case B:  $g_t(x)$  is nonincreasing in x

## A 7.2 Uniform Probability Density Function

For given a and b such as  $-\infty < a < b < \infty$  let consider the uniform probability density function:

$$f(x) = \begin{cases} 0, & x < a, \\ 1/(b-a), & a \le x \le b, \\ 0, & b < x, \end{cases}$$
 (A 7.1)

where the expectation is  $\mu = 0.5(a+b)$ . Then we have:

$$T(x) = \begin{cases} 0.5(a+b) - x, & x \le a, & \cdots (1), \\ 0.5(b-x)^2/(b-a), & a \le x \le b, & \cdots (2), \\ 0, & b \le x, & \cdots (3), \end{cases}$$
(A 7.2)

where (1) and (3) are immediate from Lemma 11.1.1(p.55) (f,g). Let  $a \le x \le b \cdots$  (2). Then, from (6.1.2(p.25)) we have:

$$\begin{split} T(x) &= \int_a^b \max\{\xi - x, 0\} (b - a)^{-1} d\xi \\ &= \int_x^b (\xi - x) (b - a)^{-1} d\xi \\ &= (b - a)^{-1} \int_0^{b - x} \eta d\eta \quad (\eta = \xi - x) = 0.5(b - x)^2 / (b - a). \end{split}$$

# A 7.3 Graphs of $T_{\mathbb{R}}(x)$

From Lemma 11.1.1(p.55) (b,f,g) one immediately sees that  $T_{\mathbb{R}}(x)$  can be depicted as in Figure A 7.3(p.324) (I) below. Similarly, from Lemma 11.2.2(p.57) (b, (11.2.4 (1) (p.57)), and (11.2.5 (2) (p.57))) we immediately see that  $K_{\mathbb{R}}(x)$  can be depicted as in Figure A 7.3(p.324) (II) below.

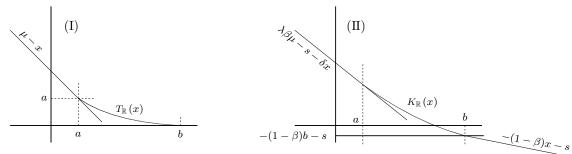


Figure A 7.3: Graph of  $T_{\mathbb{R}}(x)$  and  $K_{\mathbb{P}}(x)$ 

#### A 7.4 Graph of $T_{\mathbb{P}}(x)$

From Lemma 14.2.1(p.93) (b,f,g) we immediately see that  $T_{\mathbb{P}}(x)$  can be depicted as in Figure A 7.4 below.

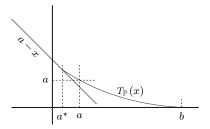


Figure A 7.4: Graph of  $T_{\mathbb{P}}(x)$ 

Here note that  $a^* < a$  (see Lemma 14.2.1(p.93) (n)).

When f(x) is the uniform distribution function (see (A 7.1(p.323))), we can obtain the  $a^*$  as below. Then we have:

$$\begin{split} p(z) &= 1 & \text{for } z \leq a & \text{from (6.1.28 (1) (p.26))}, \\ p(z) &= \int_z^b f(\xi) d\xi = \int_z^b 1/(b-a) d\xi = (b-z)/(b-a) & \text{for } a \leq z \leq b \text{ from (6.1.18 (p.26))}, \\ p(z) &= 0 & \text{for } b \leq z & \text{from (6.1.29 (2) (p.26))}. \end{split}$$

Hence we get

$$T(z,x) \stackrel{\text{def}}{=} p(z)(z-x) = \begin{cases} z-x, & z \le a & \cdots \text{(1)}, \\ (b-z)(z-x)/(b-a), & a \le z \le b & \cdots \text{(2)}, \\ 0, & b \le z & \cdots \text{(3)}. \end{cases}$$

Then (6.1.19(p.26)) can be expressed as

$$T(x) = \max_{z} T(z, x) = T(z(x), x) \cdots (4).$$

Here let us define

$$g^*(z,x) = (b-z)(z-x)/(b-a), \quad z, x \in (-\infty, \infty),$$

which is a quadratic expression of z for any given x. By  $z^*(x)$  let us denote z attaining the maximum of  $g^*(z,x)$  for a given  $x \in (-\infty,\infty)$ . Then clearly

$$z^*(x) = (b+x)/2 \cdots (5).$$

Note that  $g^*(z, x)$  can be depicted as the three possible *smooth* curves (dotted curve) in Figure A 7.5(p.325) below, depending on a value that  $z^*(x)$  takes on, i.e.,

$$z^*(x) \le a$$
 ...(i)  
 $a \le z^*(x) \le b$  ...(ii)  
 $b \le z^*(x)$  ...(iii)

Accordingly, noting (1) - (3), we see that T(z, x) can be depicted as the three possible *broken* curves (bold curve), each of which has the line z - x with the angle  $45^{\circ}$  on  $z \le a$  and the horizontal line (z-axis) on  $b \le z$ .

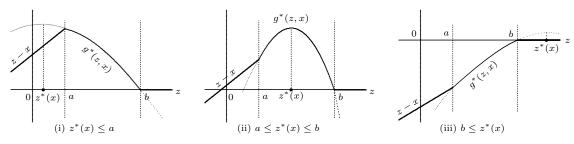


Figure A 7.5: Graph of  $g^*(z,x)$  (smooth curve) and T(z,x) (broken curve)

Here note that the T(z, x) is given by the broken curve (see (1) - (3)) and that z maximizing the broken curve is given by z(x) (see (4)). Then, from (5) and Figure A 7.5(p.325) we see that

1. Let  $z^*(x) \leq a \cdots (1)$ , i.e.,  $(b+x)/2 \leq a$ , hence  $x \leq 2a-b$ . Then, by definition we have

$$z(x) = a \cdots (6), \quad x \le 2a - b.$$

Hence, from (4) and (1) we have  $T(x) = T(a, x) = a - x \cdot \cdot \cdot \cdot (7)$  on  $x \le 2a - b$ .

2. Let  $a < z^*(x) \le b \cdots (2)$ , i.e.,  $a < (b+x)/2 \le b$ , hence  $2a - b < x \le b$ . Then, by definition we have

$$z(x) = z^*(x) = (b+x)/2 > a \cdots (8), \quad 2a-b < x \le b.$$

Hence, from (4) and (2) we have

$$T(x) = T(z^*(x), x) = (b - z^*(x))(z^*(x) - x)/(b - a) = (b - x)^2/4(b - a), \quad 2a - b < x \le b.$$

Now, since

$$m(x) \stackrel{\text{def}}{=} T(x) - a + x = ((b-x)^2 - 4(b-a)(a-x))/4(b-a),$$

we have

$$m'(x) = (x - 2a + b)/2(b - a) > 0, \quad 2a - b < x \le b,$$

hence m(x) is strictly increasing on  $2a-b < x \le b$ . In addition to the fact, since it can be easily confirmed that m(2a-b) = 0, it follows that m(x) > 0 on  $2a-b < x \le b$ , hence m(x) = T(x)-a+x > 0 on  $2a-b < x \le b$  or equivalently  $T(x) > a-x \cdots$  (9) on  $2a-b < x \le b$ .

3. Let  $b \le z^*(x) \cdots (3)$ , i.e.,  $b \le (b+x)/2$ , hence  $b \le x$ . Then, by definition we have

$$z(x) = b > a \cdots (10), \quad b \le x.$$

Hence T(x) = T(b, x) = 0 from (4), hence  $T(x) = 0 \ge b - x > a - x \cdots$  (11) on  $b \le x$ .

Collecting up (7), (9), and (11), we have

$$T(x) \begin{cases} = a - x, & x \le 2a - b, \\ > a - x, & 2a - b < x \le b, \\ > a - x, & b < x. \end{cases}$$
 (A 7.3)

Accordingly, noting (6.1.26(p.26)) and Figure A 7.4(p.324), from (A 7.3(p.325)) we immediately see that

$$a^* = 2a - b \cdots (1). \tag{A 7.4}$$

Similarly, collecting up (6), (8), and (10), we have

$$z(x) \begin{cases} = a, & x \le 2a - b, \\ > a, & 2a - b < x \le b, \\ > a, & b \le x. \end{cases}$$
 (A 7.5)

Accordingly, noting (6.1.27(p.26)), we immediately see that

$$x^* = 2a - b \cdots (2). \tag{A 7.6}$$

Numerical Experiment 1 (Discontinuity of z(x) (Dr. Mong Shan Ee)) z(x) is not always continuous in  $x = x^*$ ; in fact we can demonstrate a numerical example in which z(x) is not continuous in  $x = x^*$ . For example let us consider F(w) with f(w) such that  $f(w) \approx 0.05701$  on [0.1, 0.599], f(w) is a triangle on [0.599, 0.7] with its maximum at w = 0.6, and  $f(w) \approx 0.06982$  on [0.7, 3.0]. Then we have  $z(x) \approx 0.599$  for  $x \le 0.48568$  and  $z(x) \approx 1.7$  for x < 0.48568, i.e., z(x) is discontinuous at x = 0.48568.  $\square$ 

#### A 7.5 Economic Implications of Market Partition

The three restricted markets defined in Section 18.2(p.117) implies the following:

- Positive market  $\mathscr{F}^+$  In an asset trading problem in the real world, the price is usually positive, i.e., the problem is defined on the positive market  $\mathscr{F}^+$ , called the *input market* in the sense that all goods are first input in the market.
- o Mixed market  $\mathscr{F}^{\pm}$  For example, suppose you must waste a piece of well-worn furniture, say a book cabinet, sofa bed and so on. For such a good, normally the two kinds of receiving-sides (buyers) may appear: One who pays some money on the ulterior motive that some profit might be obtained by reselling it and the other who requires some money for the reason that some cost may be incurred for its disposal. This market can be regarded as a market in which the positive market and the negative market are mixed; let us call the market the *secondhand market*.
- Negative market  $\mathscr{F}^-$  The trading problem in A3.5(p.17) is defined on this market; let us call the market the junk market.  $\square$

Remark A 7.1 (life of durable goods) A new durable good (automobile, house furnishings, TV and so on) is first placed on the positive market  $\mathscr{F}^+$  (input market), deteriorates year by year, a while later is drove to the mixed market  $\mathscr{F}^\pm$  (second-hand market), before long moves into the negative market  $\mathscr{F}^-$  (junk market), and then finally is recycled or dumped. This deterioration flow implies that the probability density functions of price transfers from right to left as seen in Figure A 7.6(p326) below.  $\square$ 

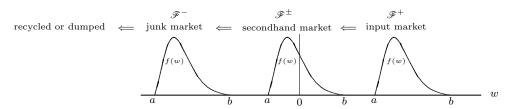


Figure A 7.6: Deterioration transition of goods (life of goods)

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Many decision theories discussed by researchers have traditionally been framed as mathematical theories. In contrast, this paper approaches "decision" as a subject of study within the natural sciences (see Section 1.2(p3)). It is important to note that some researchers may have objections to this viewpoint. However, one should recognize that the truth of mathematics resides within mathematics itself, and the truth of physics resides within physics; there is no direct relationship between these two types of truth. To illustrate, physicists sometimes refer to the term "mathematics" as "arithmetic", using it merely as a tool, akin to how carpenters use hammers. While a good hammer is necessary for building a good structure, it would be a mistake to think that a good structure cannot be built without a good hammer. As Albert Einstein famously stated:

As far as the laws of mathematics refer to reality, they are not certain, and as far as they are certain, they do not refer to reality.

— Albert Einstein —



This paper, which began with a proposition by Dr. Professor Shizuo Senju on March 31, 1966 concludes with this apothegm on September 16, 2024.

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