

An Approach to the Dimension Theory of Continuous Geometry from the Standpoint of Boolean Valued Analysis

By

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Abstract

Recently Boolean valued analysis (i.e., analysis based on Boolean valued set theory) has been extensively studied by G. Takeuti [14–16]. The main purpose of this paper is to show, by using this technique, that any continuous geometry can be viewed as an irreducible continuous geometry in its center valued set theory. This makes the transition from irreducible continuous geometries to reducible ones automatic.

§ 1. Introduction

Boolean valued set theory was introduced in 1966 by D. Scott and R. Solovay as a reformulation of P. J. Cohen's forcing techniques, which have been applied successfully to many significant independence results of set theory. Recently G. Takeuti [14–16] has applied this generalized set theory to various areas of analysis like Hilbert spaces, von Neumann algebras, harmonic analysis, etc. This approach reduces many formidable concepts and intractable theories in analysis to much easier and more familiar ones (e.g., self-adjoint operators as real numbers in a Boolean valued sense). The significance of Boolean algebras in analysis has been recognized at latest since M. H. Stone's classical work in the 1930s, but it is Boolean valued analysis that succeeded in showing its significance in its full power. As a slogan, we may say that *wherever there is a complete Boolean algebra, there must be a Boolean valued analysis on it!*

By the way, J. von Neumann [10] introduced continuous geometry in the middle of the 1930s as a lattice-theoretical generalization of projective geometry, whose subject had just turned out to be no other than irreducible

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finite-dimensional complemented modular lattices from a lattice-theoretical viewpoint. He succeeded in developing a dimension theory for irreducible continuous geometries, but failed to generalize it to the reducible case. This difficulty was overcome by some Japanese mathematicians, say, T. Iwamura [3] and Y. Kawada et al. [6] in the middle of the 1940s.

The main purpose of this paper is to show that a possibly reducible continuous geometry is no other than an irreducible continuous geometry in some Boolean valued sense. This viewpoint makes the transition from irreducible to reducible continuous geometries automatic. In particular, it shows very clearly why the dimensions of reducible continuous geometries should be represented by real valued continuous functions on some appropriate topological space, while those of irreducible continuous geometries are represented simply by real numbers. After reviewing Boolean valued analysis and continuous geometry in Sections 2 and 3 respectively, we give the details of our approach in Section 4.

Last but not least, this paper was inspired most by G. Takeuti's [16] Boolean valued approach to von Neumann algebras and S. Maeda's [9] treatment of dimension theory. The results of this paper could be generalized, e.g., to the framework of S. Maeda [9] without difficulty*, but here we prefer concentrating on one of the most typical cases to pursuing their full generalizations.

§ 2. Boolean Valued Analysis

Let \mathcal{B} be a complete Boolean algebra. We define $V_\alpha^{(\mathcal{B})}$ by transfinite induction on ordinal α as follows:

- (1) $V_0^{(\mathcal{B})} = \phi$,
- (2) $V_\alpha^{(\mathcal{B})} = \{u \mid u: \mathcal{D}(u) \rightarrow \mathcal{B} \text{ and } \mathcal{D}(u) \subseteq \bigcup_{\xi < \alpha} V_\xi^{(\mathcal{B})}\}$.

Then the Boolean valued universe $V^{(\mathcal{B})}$ of Scott-Solovay is defined as follows:

$$V^{(\mathcal{B})} = \bigcup_{\alpha \in \text{On}} V_\alpha^{(\mathcal{B})}, \text{ where On is the class of all ordinal numbers.}$$

$V^{(\mathcal{B})}$ can be considered to be a Boolean valued model of set theory by defining $\llbracket u \in v \rrbracket$ and $\llbracket u = v \rrbracket$ for $u, v \in V^{(\mathcal{B})}$ with the following properties

* Such a generalization has been attempted by K. Eda (Tsukuba University).

- (1) $\llbracket u \in v \rrbracket = \sup_{y \in \mathcal{D}(v)} (v(y) \wedge \llbracket u = y \rrbracket),$
- (2) $\llbracket u = v \rrbracket = \inf_{x \in \mathcal{D}(u)} (u(x) \Rightarrow \llbracket x \in v \rrbracket) \wedge \inf_{y \in \mathcal{D}(v)} (v(y) \Rightarrow \llbracket y \in u \rrbracket),$

and by assigning a Boolean value $\llbracket \varphi \rrbracket$ to each formula φ without free variables inductively as follows:

- (1) $\llbracket \neg \varphi \rrbracket = \neg \llbracket \varphi \rrbracket = 1 - \llbracket \varphi \rrbracket,$
- (2) $\llbracket \varphi_1 \vee \varphi_2 \rrbracket = \llbracket \varphi_1 \rrbracket \vee \llbracket \varphi_2 \rrbracket,$
- (3) $\llbracket \varphi_1 \wedge \varphi_2 \rrbracket = \llbracket \varphi_1 \rrbracket \wedge \llbracket \varphi_2 \rrbracket,$
- (4) $\llbracket \forall x \varphi(x) \rrbracket = \inf_{u \in \mathcal{V}(\mathcal{B})} \llbracket \varphi(u) \rrbracket,$
- (5) $\llbracket \exists x \varphi(x) \rrbracket = \sup_{u \in \mathcal{V}(\mathcal{B})} \llbracket \varphi(u) \rrbracket.$

The following theorem is fundamental to Boolean valued analysis.

Theorem 2.1. *If φ is a theorem of ZFC, then so is $\llbracket \varphi \rrbracket = 1$.*

Now we present several elementary properties of $\mathcal{V}(\mathcal{B})$ without proofs.

Proposition 2.2.

- (1) $\llbracket \exists x \in u \varphi(x) \rrbracket = \sup_{x \in \mathcal{D}(u)} (u(x) \wedge \llbracket \varphi(x) \rrbracket),$
- (2) $\llbracket \forall x \in u \varphi(x) \rrbracket = \inf_{x \in \mathcal{D}(u)} (u(x) \Rightarrow \llbracket \varphi(x) \rrbracket).$

The class \mathcal{V} of all sets can be embedded into $\mathcal{V}(\mathcal{B})$ by transfinite induction as follows.

$$\check{y} = \{ \langle \check{x}, 1 \rangle \mid x \in y \} \text{ for } y \in \mathcal{V}.$$

Proposition 2.3. *For $x, y \in \mathcal{V}$,*

- (1) $\llbracket \check{x} \in \check{y} \rrbracket = \begin{cases} 1 & \text{if } x \in y \\ 0 & \text{otherwise.} \end{cases}$
- (2) $\llbracket \check{x} = \check{y} \rrbracket = \begin{cases} 1 & \text{if } x = y \\ 0 & \text{otherwise.} \end{cases}$

A subset $\{b_\alpha\}$ of \mathcal{B} is called a *partition of unity* if $\sup_\alpha b_\alpha = 1$ and $b_\alpha \wedge b_\beta = 0$ for any $\alpha \neq \beta$. Given a partition of unity $\{b_\alpha\}$ and a subset $\{u_\alpha\}$ of $\mathcal{V}(\mathcal{B})$,

it can be proved easily that:

Proposition 2.4. *There exists an element u of $V^{(\mathcal{B})}$ such that $\llbracket u = u_\alpha \rrbracket \geq b_\alpha$ for any α . Furthermore this u is determined uniquely in the sense that $\llbracket u = v \rrbracket = 1$ for any $v \in V^{(\mathcal{B})}$ with the above property.*

The above u is denoted by $\sum_{\alpha} u_{\alpha} b_{\alpha}$ or $u_{\alpha_1} b_{\alpha_1} + \cdots + u_{\alpha_n} b_{\alpha_n}$ if $\{b_{\alpha}\}$ is a finite set. Then we have

Proposition 2.5. $\llbracket \varphi(\sum_{\alpha} u_{\alpha} b_{\alpha}) \rrbracket = \sup (\llbracket \varphi(u_{\alpha}) \rrbracket \wedge b_{\alpha})$.

The techniques of partitions of unity gives the following two propositions.

Proposition 2.6 (The Maximum Principle). *Let φ be a formula. Then there exists a $u \in V^{(\mathcal{B})}$ such that $\llbracket \varphi(u) \rrbracket = \llbracket \exists x \varphi(x) \rrbracket$.*

Proposition 2.7. *Let $\varphi(x)$ be a formula with only x as a free variable and $\llbracket \varphi(u) \rrbracket = 1$ for some $u \in V^{(\mathcal{B})}$. Then*

$$(1) \quad \llbracket \forall x(\varphi(x) \Rightarrow \psi(x)) \rrbracket = \inf_{\llbracket \varphi(u) \rrbracket = 1} \llbracket \psi(u) \rrbracket,$$

$$(2) \quad \llbracket \exists x(\varphi(x) \wedge \psi(x)) \rrbracket = \sup_{\llbracket \varphi(u) \rrbracket = 1} \llbracket \psi(u) \rrbracket.$$

We define the *interpretation* $X^{(\mathcal{B})}$ of $X = \{x \mid \varphi(x)\}$ with respect to $V^{(\mathcal{B})}$ to be $\{u \in V^{(\mathcal{B})} \mid \llbracket \varphi(u) \rrbracket = 1\}$, assuming that it is not empty. For technical convenience, if X is a set, then $X^{(\mathcal{B})}$ is usually considered to be a set by choosing a representative from an equivalence class $\{v \in V^{(\mathcal{B})} \mid \llbracket u = v \rrbracket = 1\}$. Then, by Proposition 2.7, we have $X^{(\mathcal{B})} \times \{1\} \in V^{(\mathcal{B})}$ and $\llbracket X = X^{(\mathcal{B})} \times \{1\} \rrbracket = 1$.

Let $D \subseteq V^{(\mathcal{B})}$. A function $g: D \rightarrow V^{(\mathcal{B})}$ is called *extensional* if $\llbracket d = d' \rrbracket \leq \llbracket g(d) = g(d') \rrbracket$ for any $d, d' \in D$. A \mathcal{B} -valued set $u \in V^{(\mathcal{B})}$ is said to be *definite* if

$$u(d) = 1 \text{ for any } d \in \mathcal{D}(u).$$

Then we have the following characterization theorem of extensional maps.

Theorem 2.8. *Let $u, v \in V^{(\mathcal{B})}$ be definite and $D = \mathcal{D}(u)$. Then there is a bijective correspondence between $f \in V^{(\mathcal{B})}$ satisfying $\llbracket f : u \rightarrow v \rrbracket = 1$ and extensional maps $\varphi: D \rightarrow v^{(\mathcal{B})}$, where $v^{(\mathcal{B})} = \{u \mid \llbracket u \in v \rrbracket = 1\}^*$. The correspondence is given by the relation $\llbracket f(d) = \varphi(d) \rrbracket = 1$ for any $d \in D$.*

* This is also considered to be a set by the above method.

We conclude this section by considering what the real numbers in $V^{(\mathcal{B})}$ look like. First of all, we note that the set of all natural numbers in $V^{(\mathcal{B})}$ is $\check{\omega}$ and the set of all rational numbers in $V^{(\mathcal{B})}$ is $\check{\mathbb{Q}}$. We define a real number to be the lower half line without the endpoint of a Dedekind cut. Thus “ a is a real number” is expressed formally by

$$a \subseteq \mathbb{Q} \wedge \exists s \in \mathbb{Q} (s \in a) \wedge \exists s \in \mathbb{Q} (s \in a) \wedge \forall s \in \mathbb{Q} (s \in a \Leftrightarrow \exists t \in \mathbb{Q} (s < t \wedge t \in a)).$$

Let \mathcal{Q} be the Stone space of \mathcal{B} . Then \mathcal{B} is isomorphic to the clopen subsets of \mathcal{Q} , assigning a clopen set $E(b)$ to each $b \in \mathcal{B}$. Since \mathcal{B} is complete, the closure of every open subset of \mathcal{Q} is open (cf. Ogasawara [11; Chapter 2, §4]). In particular, every regular open subset of \mathcal{Q} is clopen. Therefore, if we denote the Borel σ -field of \mathcal{Q} and the σ -ideal of meager Borel subsets of \mathcal{Q} by \mathcal{S} and \mathcal{I} respectively, then \mathcal{B} is σ -isomorphic to \mathcal{S}/\mathcal{I} (cf. Takeuti and Zaring [13; §3, Theorem 3.14]). For any S in \mathcal{S} , we denote by $[S]$ the corresponding element in \mathcal{B} by this isomorphism. By using a similar argument to Takeuti [14; Chapter 2, §2], we can establish a correspondence between $\mathbb{R}^{(\mathcal{B})}$ and the set $B_{\mathbb{R}}(\mathcal{Q})$ of all real Borel functions on \mathcal{Q} . The correspondence is given by the relation $[[\check{r} \in u]] = [\{x \in \mathcal{Q} \mid r < f(x)\}]$. By identifying real Borel functions on \mathcal{Q} which are equal except meager sets, this correspondence can be made bijective. Since every real Borel function on \mathcal{Q} is equal to some real continuous function on \mathcal{Q} except meager sets (cf. Ogasawara [11; Chapter 2, §4]) and no two different real continuous functions on \mathcal{Q} can not be equal even except meager sets (cf. Takeuti and Zaring [13; §3, Theorem 3.23]), we have

Theorem 2.9. *There is a bijective correspondence between $\mathbb{R}^{(\mathcal{B})}$ and $C_{\mathbb{R}}(\mathcal{Q})$, where $C_{\mathbb{R}}(\mathcal{Q})$ denotes the set of all real continuous functions on \mathcal{Q} .*

§ 3. Continuous Geometry

Let L be a lattice. Then for any directed set D , a family $\{a_\delta\}_{\delta \in D}$ of L is called a *monotone increasing system* (a *monotone decreasing system*) if $\delta_1 \leq \delta_2$ implies $a_{\delta_1} \leq a_{\delta_2}$ ($a_{\delta_2} \leq a_{\delta_1}$, resp.). A *continuous geometry* is a complete complemented modular lattice L satisfying the following continuity axioms:

(1)
$$\sup_{\delta \in D} (a_\delta \wedge b) = (\sup_{\delta \in D} a_\delta) \wedge b$$

for any monotone increasing system $\{a_\delta\}_{\delta \in D}$ of L ;

$$(2) \quad \inf_{\delta \in D} (a_\delta \vee b) = (\inf_{\delta \in D} a_\delta) \vee b$$

for any monotone decreasing system $\{a_\delta\}_{\delta \in D}$ of L .

Throughout the rest of this section, L is assumed to be a continuous geometry unless stated to the contrary. An element z of L is called *central* if $(a \vee b) \wedge z = (a \wedge z) \vee (b \wedge z)$ for any $a, b \in L$. The set of all central elements of L , which is known to be a complete Boolean algebra and to be closed under sup and inf, is called the *center* of L and denoted by $Z(L)$. Obviously $1, 0 \in Z(L)$. If $Z(L) = \{1, 0\}$, then L is called *irreducible*. Otherwise L is called *reducible*. For any element $a \in L$, there is a least element $z \in Z(L)$ with respect to the property $a \leq z$, which is called the *central envelope* of a and denoted by $e(a)$.

Two elements a, b of L are called *perspective* and written $a \sim b$ if they have a common complement, i.e., $a \vee x = b \vee x = 1$ and $a \wedge x = b \wedge x = 0$ for some $x \in L$. It is known that perspectivity satisfies the transitive law in continuous geometry and so is an equivalence relation. We write $a < b$ or $b > a$ if $a \sim b_1 < b$ for some $b_1 \in L$. Then we have the following characterization theorem of irreducibility in terms of \sim and $<$.

Theorem 3.1 (cf. Maeda [7; Chap. 4, §2]). *A continuous geometry L is irreducible iff one of the three relations $a < b, a \sim b, b < a$ holds for any $a, b \in L$.*

The fundamental theorem of the dimension theory for irreducible continuous geometries goes as follows:

Theorem 3.2 (cf. Maeda [7; Chap. 5, §2]). *Let L be an irreducible continuous geometry. Then there exists a unique real valued function f on L such that:*

- (1) $0 \leq f(a) \leq 1$ for any $a \in L$;
- (2) $f(0) = 0$ and $f(1) = 1$;
- (3) $f(a \vee b) + f(a \wedge b) = f(a) + f(b)$ for any $a, b \in L$.

§ 4. The Construction of \tilde{L} from L

Let L be an arbitrary continuous geometry. Let $\mathcal{B} = Z(L)$. The main purpose of this section is to construct a derived continuous geometry \tilde{L} in $V^{(\mathcal{B})}$ and then to establish some correspondences between L and \tilde{L} , which will enable us to derive the dimension theory of reducible continuous geometries from that of irreducible continuous geometries without much effort.

Proposition 4.1. *For any $a, b \in L$, there is a largest central element z of L with respect to the property $a \wedge z = b \wedge z$.*

Proof. We write $Z(a,b)$ for $\{z \in Z(L) \mid a \wedge z = b \wedge z\}$. If $z \in Z(a,b)$ and $z \geq z' \in Z(L)$ then $a \wedge z' = a \wedge z \wedge z' = b \wedge z \wedge z' = b \wedge z'$ and so $z' \in Z(a,b)$. If $z_1, z_2 \in Z(a,b)$, then $a \wedge (z_1 \vee z_2) = (a \wedge z_1) \vee (a \wedge z_2) = (b \wedge z_1) \vee (b \wedge z_2) = b \wedge (z_1 \vee z_2)$ and so $z_1 \vee z_2 \in Z(a,b)$. Therefore $Z(a,b)$ is an ideal. Thus, using the continuity axiom of continuous geometry, we have $(\sup Z(a,b)) \wedge a = \sup_{z \in Z(a,b)} (z \wedge a) = \sup_{z \in Z(a,b)} (z \wedge b) = (\sup Z(a,b)) \wedge b$, which implies $\sup Z(a,b) \in Z(a,b)$. This is the desired element.

For any $a, b \in L$, we write $e(a,b)$ for the element whose existence was established in the above proposition.

Now we define a binary relation R on \check{L} in $V^{(\mathcal{B})}$ as follows:

$$R = \{ \langle \langle a, b \rangle^{\vee}, e(a, b) \rangle \mid a, b \in L \} .$$

Then we have:

Proposition 4.2. $\llbracket R \text{ is an equivalence relation on } \check{L} \rrbracket = 1$.

Proof. This follows readily from the fact that for any $a, b, c \in L$,

- (1) $R(\langle a, a \rangle^{\vee}) = 1$;
- (2) $R(\langle a, b \rangle^{\vee}) = R(\langle b, a \rangle^{\vee})$;
- (3) $R(\langle a, b \rangle^{\vee}) \wedge R(\langle b, c \rangle^{\vee}) \leq R(\langle a, c \rangle^{\vee})$.

Therefore we can consider the quotient set of \check{L} with respect to the equivalence relation R in $V^{(\mathcal{B})}$, which is denoted by \check{L} . For any $a \in L$, the equivalence class of \check{a} with respect to R in $V^{(\mathcal{B})}$ is denoted by \tilde{a} . Then it is easy to see that:

Proposition 4.3. $\llbracket \tilde{a} = \tilde{b} \rrbracket = e(a, b)$ for any $a, b \in L$. In particular, $\llbracket \tilde{a} = \tilde{b} \rrbracket = 1$ iff $a = b$.

Proof. $\llbracket \tilde{a} = \tilde{b} \rrbracket = \llbracket \check{a} R \check{b} \rrbracket = e(a, b)$.

Now we consider partitions of unity in $V^{(\mathcal{B})}$.

Proposition 4.4. *For any partition of unity $\{z_{\alpha}\}$ and any family $\{a_{\alpha}\}$ of L with the same index set, we have*

$$\sum \tilde{a}_{\alpha} z_{\alpha} = (\sup_{\alpha} (a_{\alpha} \wedge z_{\alpha}))^{\sim} .$$

Proof. It is easy to see, by dint of the continuity axiom, that

$$(\sup_{\mathfrak{a}} (a_{\mathfrak{a}} \wedge z_{\mathfrak{a}})) \wedge z_{\mathfrak{a}} = a_{\mathfrak{a}} \wedge z_{\mathfrak{a}} .$$

Therefore, $z_{\mathfrak{a}} \leq e (\sup_{\mathfrak{a}} (a_{\mathfrak{a}} \wedge z_{\mathfrak{a}}), a_{\mathfrak{a}}) = \llbracket (\sup_{\mathfrak{a}} (a_{\mathfrak{a}} \wedge z_{\mathfrak{a}}))^{\sim} = \tilde{a}_{\mathfrak{a}} \rrbracket$ by Proposition 4.3.

Corollary 4.5. $(\tilde{L})^{(\mathfrak{B})} = \{\tilde{a} \mid a \in L\}$.

Now we would like to make \tilde{L} a lattice in $V^{(\mathfrak{B})}$.

Proposition 4.6. For any $a_1, a_2, b_1, b_2 \in L$,

- (1) $\llbracket \tilde{a}_1 = \tilde{a}_2 \rrbracket \wedge \llbracket \tilde{b}_1 = \tilde{b}_2 \rrbracket \leq \llbracket (a_1 \vee b_1)^{\sim} = (a_2 \vee b_2)^{\sim} \rrbracket ,$
- (2) $\llbracket \tilde{a}_1 = \tilde{a}_2 \rrbracket \wedge \llbracket \tilde{b}_1 = \tilde{b}_2 \rrbracket \leq \llbracket (a_1 \wedge b_1)^{\sim} = (a_2 \wedge b_2)^{\sim} \rrbracket .$

Proof. We deal only with (1). If $a_1 \wedge z = a_2 \wedge z$ and $b_1 \wedge z = b_2 \wedge z$ for some $z \in Z(L)$, then $(a_1 \vee b_1) \wedge z = (a_1 \wedge z) \vee (b_1 \wedge z) = (a_2 \wedge z) \vee (b_2 \wedge z) = (a_2 \vee b_2) \wedge z$. Thus (1) follows readily by dint of Proposition 4.3.

By dint of Theorem 2.8 and the above proposition, we can safely define lattice operations \vee and \wedge on \tilde{L} in $V^{(\mathfrak{B})}$ as follows:

- (1) $\tilde{a} \vee \tilde{b} = (a \vee b)^{\sim} ,$
- (2) $\tilde{a} \wedge \tilde{b} = (a \wedge b)^{\sim} .$

By dint of Corollary 4.3, it is almost trivial to see that:

Theorem 4.7. $\llbracket \tilde{L} \text{ is a continuous geometry} \rrbracket = 1$.

We denote $\{\tilde{z} \mid z \in Z(L)\} \times \{1\}$ by \tilde{Z} . Then it is also trivial to see that:

Theorem 4.8. $\llbracket \text{The center of } \tilde{L} \text{ is } \tilde{Z} \rrbracket = 1$.

Theorem 4.9. $\llbracket \tilde{L} \text{ is an irreducible continuous geometry} \rrbracket = 1$.

Proof. For $z \in Z(L)$, we have

$$\llbracket \tilde{z} = \tilde{1} \vee \tilde{z} = \tilde{0} \rrbracket = \llbracket \tilde{z} = \tilde{1} \rrbracket \vee \llbracket \tilde{z} = \tilde{0} \rrbracket = z \vee \neg z = 1 .$$

Then the theorem follows from Theorems 4.7 and 4.8.

Now any theorem in irreducible continuous geometries can be transferred automatically to that on \tilde{L} in $V^{(\mathfrak{B})}$. As an application of this principle, we can obtain the fundamental theorem of the dimension theory for continuous geometries in its general form from that for irreducible continuous geometries.

Theorem 4.10. *For any continuous geometry L , there exists a unique function f from L to $C_{\mathbb{R}}(\mathcal{Q})$ (the value of f at $a \in L$ is denoted by f_a rather than $f(a)$) satisfying the following properties:*

- (1) $0 \leq f_a(\mathfrak{p}) \leq 1$ for any $\mathfrak{p} \in \mathcal{Q}$;
- (2) For any central element $z \in L$, $f_z(\mathfrak{p}) = \begin{cases} 1 & \text{if } \mathfrak{p} \in E(z) \\ 0 & \text{otherwise;} \end{cases}$
- (3) $f_{a \vee b}(\mathfrak{p}) + f_{a \wedge b}(\mathfrak{p}) = f_a(\mathfrak{p}) + f_b(\mathfrak{p})$ for any $\mathfrak{p} \in \mathcal{Q}$.

Proof. By using Theorem 2.8, we can easily see that there is a bijective correspondence between real valued functions on \tilde{L} in $V^{(\mathcal{B})}$ and functions f from L to $C_{\mathbb{R}}(\mathcal{Q})$ satisfying the following property (*).

(*) For any $a, b \in L$ and any $z \in Z(L)$, if $a \wedge z = b \wedge z$, then f_a and f_b coincide on $E(z)$.

Since the functions f with the three properties of the theorem satisfies the property (*). the theorem follows readily from Theorems 3.2 and 4.9.

We give some further correspondences between L and \tilde{L} .

Proposition 4.11. *For any $a \in L$, $e(a) = \llbracket \tilde{a} \neq \tilde{0} \rrbracket$.*

Proof. $e(a) = \neg e(a, 0) = \neg \llbracket \tilde{a} = \tilde{0} \rrbracket = \llbracket \tilde{a} \neq \tilde{0} \rrbracket$.

For any $a, b \in L$, we write $a \leq b$ iff for any $z \in Z(L)$, either $z \wedge a < z \wedge b$ or $z \wedge a = z \wedge b = 0$.

Proposition 4.12. *For any $a, b \in L$, $a \leq b$ iff $\llbracket \tilde{a} > \tilde{b} \rrbracket = 0$.*

For any $a, b \in L$, we write $a \ll b$ iff for any $z \in Z(L)$, either $z \wedge a < z \wedge b$ or $z \wedge a = z \wedge b = 0$.

Proposition 4.12. *For any $a, b \in L$, $a \ll b$ iff $\llbracket \tilde{a} > \tilde{b} \rrbracket = 0$.*

Proof. By Theorems 3.1 and 4.9, $\llbracket \tilde{a} > \tilde{b} \vee \tilde{a} \sim \tilde{b} \vee \tilde{a} < \tilde{b} \rrbracket = 1$. Therefore $\llbracket \tilde{a} > \tilde{b} \rrbracket = 0$ iff $\llbracket \tilde{a} \sim \tilde{b} \vee \tilde{a} < \tilde{b} \rrbracket = 1$ iff $a \ll b$.

Theorem 4.13. *For any continuous geometry L , L is of type k ($1 \leq k \leq \infty$) iff \tilde{L} is of type k in $V^{(\mathcal{B})}$.*

To conclude this section, we consider an intriguing problem whether every irreducible continuous geometry in $V^{(\mathcal{B})}$ is of the form \tilde{L} for some appropriate continuous geometry L . Our answer is positive.

Theorem 4.14. *Let \mathcal{B} be an arbitrary complete Boolean algebra. Then any irreducible continuous geometry in $V^{(\mathcal{B})}$ is, up to isomorphism, of the form \tilde{L} for some continuous geometry L whose center is \mathcal{B} .*

Proof. Let \hat{L} be an irreducible continuous geometry in $V^{(\mathcal{B})}$. Let $L = \{u \in V^{(\mathcal{B})} \mid \llbracket u \in \hat{L} \rrbracket = 1\}$. It is easy to see that L is a continuous geometry with the derived lattice structure from \hat{L} . Now we would like to determine the center of L . It is easy to see that $a \in L$ is central iff $\llbracket a \text{ is central} \rrbracket = 1$. But since \hat{L} is irreducible in $V^{(\mathcal{B})}$, $\llbracket a \text{ is central} \rrbracket = \llbracket a = 1 \vee a = 0 \rrbracket$. Therefore, there is a bijective correspondence between $Z(L)$ and \mathcal{B} , assigning to $z \in Z(L)$ $\llbracket z = 1 \rrbracket \in \mathcal{B}$ and conversely assigning to $x \in \mathcal{B}$ $(1x + 0 \neg x) \in Z(L)$. Thus we can identify $Z(L)$ with \mathcal{B} . Now it remains to show that $\llbracket a = b \rrbracket = e(a, b)$ for any $a, b \in L$. But, for any $x \in \mathcal{B}$, we have $\llbracket (1x + 0 \neg x) \wedge a = (1x + 0 \neg x) \wedge b \rrbracket = (\llbracket 1 \wedge a = 1 \wedge b \rrbracket \wedge x) \vee (\llbracket 0 \wedge a = 0 \wedge b \rrbracket \wedge \neg x) = (\llbracket a = b \rrbracket \wedge x) \vee \neg x$. Therefore $(1x + 0 \neg x) \leq e(a, b)$ iff $x \leq \llbracket a = b \rrbracket$. This completes the proof.

Theorems 4.9 and 4.14 show that continuous geometries in V whose center is \mathcal{B} and irreducible continuous geometries in $V^{(\mathcal{B})}$ are the same things from different viewpoints. However the transition from one viewpoint to the other is fruitful enough to yield seemingly formidable concepts and theorems from simpler ones automatically.

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* This is a German translation of Maeda [7].

** This is his Princeton lecture notes during 1935–1937 edited by I. Halperin after his death.

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