

NON-NEGATIVELY CURVED C-TOTALLY REAL SUBMANIFOLDS IN A SASAKIAN MANIFOLD

By

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Dedicated to Professor Y. Tashiro on his 60th birthday

§ 0. Introduction.

Several authors have investigated minimal totally real submanifolds in a complex space form and obtained many interesting results. Recently F. Urbano [6] and Y. Ohnita [4] have studied pinching problems on their curvatures and stated some theorems.

On the other hand, in a $(2n+1)$ -dimensional Sasakian space form of constant ϕ -sectional curvature $c(>-3)$, if a submanifold M is perpendicular to the structure vector field, then M is said to be *C-totally real*. For such a submanifold M , it is well-known that if the mean curvature vector field of M is parallel, then M is minimal. S. Yamaguchi, M. Kon and T. Ikawa [8] obtained that if the squared length of the second fundamental form of M is less than $n(n+1)(c+3)/4(2n-1)$, then M is totally geodesic. Furthermore, D. E. Blair and K. Ogiue [2] proved that if the sectional curvature of M is a greater than $(n-2)(c+3)/4(2n-1)$, then M is totally geodesic.

In this paper, we consider a curvature-invariant *C-totally real* submanifold M in a Sasakian manifold with η -parallel mean curvature vector field. Then M is not necessary minimal. Making use of methods of [3] and [4], we prove that if the sectional curvature of M is positive, then M is totally geodesic.

In Sec. 1, we recall the differential operators on the unit sphere bundle of a Riemannian manifold. Sec. 2 is devoted to stating about fundamental formulas on a *C-totally real* submanifold in a Sasakian manifold. In Sec. 3, we prove Theorems and Corollaries. Throughout this paper all manifolds are always C^∞ , oriented, connected and complete. The author wishes to thank Professor S. Yamaguchi for his help.

§ 1. A differential operator defined by A. Gray.

Let M be an n -dimensional Riemannian manifold and $\Gamma(M)$ the Lie algebra

of vector fields on M . Denote by \langle, \rangle , ∇ and $R_{XY} := [\nabla_X, \nabla_Y] - \nabla_{[X, Y]}$ ($X, Y \in \Gamma(M)$) the metric tensor of M , the Riemannian connection on M and the curvature tensor of M , respectively. The Ricci tensor ρ of M is given by

$$(1.1) \quad \rho_{XY} := \sum_{a=1}^n \langle R_{e_a X} Y, e_a \rangle \quad \text{for } X, Y \in \Gamma(M),$$

where $\{e_1, \dots, e_n\}$ is an arbitrary local orthonormal frame field. For $m \in M$ we denote by M_m the tangent space to M at m . Then we write R_{wxyz} in place of $\langle R_{wxy} z, z \rangle$ for $w, x, y, z \in M_m$ and shall sometimes use such expressions as $R_{x^\alpha y^\beta}$ instead of $R_{x e_{\alpha(m)} y e_{\beta(m)}}$.

Now we define the unit sphere bundle $S(M)$ of M by

$$S(M) = \{(m, x) : m \in M, x \in M_m, \langle x, x \rangle = 1\}.$$

For any unit vector x in a fibre S_m we take an orthonormal basis $\{e_1, \dots, e_n\}$ of M_m such that $x = e_1$. Denote by (y_2, \dots, y_n) the corresponding system of normal coordinates defined on a neighborhood of x in S_m .

LEMMA A [3]. *Let $F: S_m \rightarrow \mathbf{R}$ be a function. Then we have*

$$\frac{\partial^{\alpha_2 + \dots + \alpha_n} F}{\partial y_2^{\alpha_2} \dots \partial y_n^{\alpha_n}}(m, x) = \frac{\partial^{\alpha_2 + \dots + \alpha_n}}{\partial u_2^{\alpha_2} \dots \partial u_n^{\alpha_n}} F((\cos r)x + \left(\frac{\sin r}{r}\right) \sum_{i=2}^n u_i e_i)(0),$$

where we have set $r^2 = \sum_{i=2}^n u_i^2$.

Next we lift the frame $\{e_1, \dots, e_n\}$ to an orthonormal basis $\{f_1, \dots, f_n; g_2, \dots, g_n\}$ of the tangent space $S(M)_{(m, x)}$, where we require that f_1, \dots, f_n are horizontal and g_2, \dots, g_n are vertical. Denote by $(x_1, \dots, x_n; y_2, \dots, y_n)$ the corresponding normal coordinate system on a neighborhood of (m, x) in $S(M)$. We define a second-order linear differential operator $L(\lambda, \mu)$ by

$$L(\lambda, \mu)_{(m, x)} := \left[\sum_{a=1}^n \frac{\partial^2}{\partial x_a^2} - \lambda \sum_{\alpha, \beta=2}^n p_{\alpha\beta} \frac{\partial^2}{\partial y_\alpha \partial y_\beta} + \mu \sum_{\alpha=2}^n q_\alpha \frac{\partial}{\partial y_\alpha} \right]_{(m, x)},$$

where $p_{\alpha\beta}(m, x) := R_{x\beta\alpha x}$, $q_\alpha(m, x) := \rho_{\alpha x}$ and λ, μ are constants to be chosen later. This definition is independent of the choice of normal coordinates at (m, x) . Hence $L(\lambda, \mu)_{(m, x)}$ is well-defined. Here we note that the sign of the second term in the right hand side is minus because of the definition on curvature tensor.

For a compact Riemannian manifold M , we define an inner product $(,)$ on the space of functions by $(f, g) := \int_M f g_* 1$. Then the differential operator $L(\lambda, \mu)$ is self-adjoint with respect to $(,)$ provided that $\lambda = -\mu$ (cf. [3]).

If f is a real-valued function on $S(M)$, we denote by $\text{grad}^u f$ and $\text{grad}^h f$ the

vertical and horizontal components of $\text{grad } f$ respectively.

LEMMA B [3]. *In a compact Riemannian manifold M , we have*

$$\int_{S(M)} [f L(\lambda, -\lambda)(f)(m, x) + |\text{grad}^h f|^2(m, x) + \lambda K_{x(\text{grad}^v f)(x)}] *1 = 0,$$

where the letter K indicates the sectional curvature of M .

§ 2. Fundamental formulas.

Let M be a submanifold of a Riemannian manifold N . We denote by the same \langle, \rangle the Riemannian metrics of M and N , and by $\bar{\nabla}$ (resp. ∇) the Riemannian connection of N (resp. M) respectively. In the sequel the letters W, X, Y and Z (resp. V) will always denote any vector fields tangent (resp. normal) to M . Then the Gauss and Weingarten formulas are respectively given by

$$(2.1) \quad \bar{\nabla}_X Y = \nabla_X Y + B(X, Y),$$

$$(2.2) \quad \bar{\nabla}_X V = -A_V X + D_X V,$$

where B (resp. A) and D are the second fundamental form (resp. shape operator) and the normal connection of M respectively. Then first and second covariant derivatives of B are respectively defined by

$$(2.3) \quad (\tilde{\nabla}_X B)(Y, Z) = D_X B(Y, Z) - B(\nabla_X Y, Z) - B(Y, \nabla_X Z),$$

$$(2.4) \quad (\tilde{\nabla}_{WX}^2 B)(Y, Z) = D_W(\tilde{\nabla}_X B)(Y, Z) - (\tilde{\nabla}_{r_W X} B)(Y, Z) \\ - (\tilde{\nabla}_X B)(\nabla_W Y, Z) - (\tilde{\nabla}_X B)(Y, \nabla_W Z)$$

Denoting by \bar{R} the Riemannian curvature tensor of N and putting as $(\bar{R}_{WX} Y)^n$ the normal part of $\bar{R}_{WX} Y$, we have the equation of Codazzi:

$$(2.5) \quad (\bar{R}_{WX} Y)^n = (\tilde{\nabla}_W B)(X, Y) - (\tilde{\nabla}_X B)(W, Y).$$

If $(\bar{R}_{WX} Y)^n$ vanishes identically, then we call such a submanifold M *curvature-invariant*.

From (2.4), the formula of Ricci with respect to the second covariant derivative of B is given by

$$(2.6) \quad (\tilde{\nabla}_{WX}^2 B)(Y, Z) - (\tilde{\nabla}_{XW}^2 B)(Y, Z) \\ = R_{WX}^D B(X, Z) - B(R_{WX} Y, Z) - B(Y, R_{WX} Z),$$

where $R_{WX}^D := [DW, DX] + D[W, X]$ indicates the normal curvature tensor of M .

From now on let M be an n -dimensional C -totally real submanifold in a $(2n+1)$ -dimensional Sasakian manifold N with structure (ϕ, ξ, η) . Then it is shown that ([7], [8], [9], [11])

$$(2.7) \quad \langle B(Y, Z), \xi \rangle = 0,$$

$$(2.8) \quad DX\phi Y = -\langle X, Y \rangle \xi + \phi \nabla_X Y,$$

$$(2.9) \quad \langle R_{WX}^D \phi Y, \phi Z \rangle = \langle R_{WX} Y, Z \rangle - \langle W, Z \rangle \langle X, Y \rangle + \langle W, Y \rangle \langle X, Z \rangle,$$

$$(2.10) \quad \langle (\tilde{\nabla}_X B)(Y, Z), \xi \rangle = -\langle B(Y, Z), \phi X \rangle.$$

For such a C -totally real submanifold M , we state the definitions as follows:

DEFINITION [11]. We say that the mean curvature vector field of M is η -parallel if

$$(2.11) \quad \sum_{a=1}^n \langle (\tilde{\nabla}_W B)(e_a, e_a), \phi X \rangle = 0.$$

We say that the second fundamental form of M is η -parallel if

$$(2.12) \quad \langle \tilde{\nabla}_W B(Y, Z), \phi X \rangle = 0.$$

If M has η -parallel mean curvature vector field, then the equations (2.8) and (2.10) yield

$$\begin{aligned} & \sum_{a=1}^n \langle (\tilde{\nabla}_{WX}^2 B)(e_a, e_a), \phi Y \rangle \\ &= -\sum_{a=1}^n [\langle (\tilde{\nabla}_X B)(e_a, e_a), DW\phi Y \rangle + 2\langle (\tilde{\nabla}_X B)(\nabla_W e_a, e_a), \phi Y \rangle] \\ &= -\sum_{a=1}^n [-\langle W, Y \rangle \langle B(e_a, e_a), \phi X \rangle + 2\langle \tilde{\nabla}_X B(\nabla_W e_a, e_a), \phi Y \rangle]. \end{aligned}$$

Taking the normal coordinate system, we can state the following.

LEMMA 2.1. *If M has η -parallel mean curvature vector field, then we have*

$$(2.13) \quad \sum_{a=1}^n \langle (\tilde{\nabla}_{WX}^2 B)(e_a, e_a), \phi Y \rangle = -\sum_{a=1}^n \langle W, Y \rangle \langle B(e_a, e_a), \phi X \rangle.$$

§ 3. C -totally real submanifolds.

Throughout this section let M be an n -dimensional curvature-invariant C -totally real submanifold in a $(2n+1)$ -dimensional Sasakian manifold. We denote the components of the second fundamental form B by

$$(3.1) \quad h_{\alpha\beta\gamma} := \langle B(e_\alpha, e_\beta), \phi e_\gamma \rangle \quad \text{for } 1 \leq \alpha, \beta, \gamma \leq n.$$

As M is C -totally real, we find that h is symmetric, i.e.,

$$(3.2) \quad h_{\alpha\beta\gamma} = h_{\alpha\gamma\beta} = h_{\beta\alpha\gamma} \quad \text{for } 1 \leq \alpha, \beta, \gamma \leq n.$$

The components of first and second covariant derivatives of B with respect to $\phi\Gamma(M)$ are respectively expressed as

$$(3.3) \quad (\nabla_\alpha h)_{\beta\gamma\delta} := \langle \tilde{\nabla}_\alpha B(e_\beta, e_\gamma), \phi e_\delta \rangle \quad \text{for } 1 \leq \alpha, \beta, \gamma, \delta \leq n,$$

$$(3.4) \quad (\nabla_{\alpha\beta}^2 h)_{\gamma\delta\epsilon} := \langle \tilde{\nabla}_{\alpha\beta}^2 B(e_\gamma, e_\delta), \phi e_\epsilon \rangle \quad \text{for } 1 \leq \alpha, \beta, \gamma, \delta, \epsilon \leq n.$$

Since M is curvature-invariant, then, from (2.5) and (3.3), we find that $\nabla_\alpha h$ is symmetric with respect to $\phi\Gamma(M)$, i.e.,

$$(3.5) \quad (\nabla_\alpha h)_{\beta\gamma\delta} = (\nabla_\beta h)_{\alpha\gamma\delta} \quad \text{for } 1 \leq \alpha, \beta, \gamma, \delta \leq n.$$

We consider a function f on $S(M)$ defined by $f(m, x) = h_{xxx}$ for any point $(m, x) \in S(M)$ and then prove the following Lemma to use later.

LEMMA 3.1. *Let M be an n -dimensional curvature-invariant C -totally real submanifold in a $(2n+1)$ -dimensional Sasakian manifold N . If M has η -parallel mean curvature vector field, then we have $L(1/3, -1/3)(f) = 0$.*

PROOF. We take any point (m, x) of $S(M)$. For each $\alpha, 1 \leq \alpha \leq n$, let $\gamma_\alpha(s)$ be a geodesic in M such that $\gamma_\alpha(0) = m$ and $\gamma'_\alpha(0) = e_\alpha$. Then we denote a vector field by parallel translating of x along γ_α as the same letter x . By virtue of (2.7)–(2.10), we obtain

$$\begin{aligned} \left(\frac{\partial^2 f}{\partial x_\alpha^2} \right) (m, x) &= \langle \phi x, D_\alpha \tilde{\nabla}_\alpha B(x, x) \rangle + \langle D_\alpha \phi x, \tilde{\nabla}_\alpha B(x, x) \rangle \quad \text{at } m \\ &= \langle \phi x, \tilde{\nabla}_{\alpha\alpha}^2 B(x, x) \rangle + x_\alpha \langle \phi e_\alpha, B(x, x) \rangle \quad \text{at } m \\ &= (\nabla_{\alpha\alpha}^2 h)_{xxx} + x_\alpha h_{\alpha xx}, \end{aligned}$$

where we have put $x_\alpha := \langle e_\alpha, x \rangle$, which implies

$$(3.6) \quad \sum_{\alpha=1}^n \left(\frac{\partial^2 f}{\partial x_\alpha^2} \right) (m, x) = \sum_{\alpha=1}^n (\nabla_{\alpha\alpha}^2 h)_{xxx} + h_{xxx}.$$

From (2.6), (2.9), (3.2) and (3.5), we can verify

$$\begin{aligned}
(\mathcal{P}_{\alpha\alpha}^2 h)_{xxx} &= (\mathcal{P}_{\alpha x}^2 h)_{\alpha xx} \\
&= \langle \phi x, (\tilde{\mathcal{P}}_{xx}^2 B)(x, e_\alpha) \rangle + \langle \phi x, R_{\alpha x}^D B(x, e_\alpha) \rangle \\
&\quad - \langle \phi x, B(R_{\alpha x} x, e_\alpha) \rangle - \langle \phi x, B(x, R_{\alpha x} e_\alpha) \rangle \quad \text{at } m \\
&= \langle \phi x, (\tilde{\mathcal{P}}_{xx}^2 B)(e_\alpha, e_\alpha) \rangle - \langle B(x, e_\alpha), R_{\alpha x}^D \phi x \rangle \\
&\quad - \langle B(x, e_\alpha), \phi R_{\alpha x} x \rangle - \langle B(x, x), \phi R_{\alpha x} e_\alpha \rangle \quad \text{at } m \\
&= (\mathcal{P}_{xx}^2 h)_{\alpha\alpha x} + \sum_{\beta=1}^n [-2h_{\beta\alpha x} R_{\alpha x \beta} - h_{\beta xx} R_{\alpha x \beta} \\
&\quad + \delta_{\alpha\beta} h_{\beta\alpha x} - h_{\beta\alpha x} x_\alpha x_\beta],
\end{aligned}$$

from which follows that

$$(3.7) \quad \sum_{\alpha=1}^n (\mathcal{P}_{\alpha\alpha}^2 h)_{xxx} = \sum_{\alpha=1}^n [(\mathcal{P}_{xx}^2 h)_{\alpha\alpha x} - 2 \sum_{\beta=1}^n h_{\beta\alpha x} R_{\alpha x \beta} + h_{\alpha xx} \rho_{\alpha x} + h_{\alpha\alpha x}] - h_{xxx}.$$

Thus it is shown from (3.6) and (3.7) that

$$(3.8) \quad \sum_{\alpha=1}^n \left(\frac{\partial^2 f}{\partial x_\alpha^2} \right) (m, x) = \sum_{\alpha=1}^n [(\mathcal{P}_{xx}^2 h)_{\alpha\alpha x} - 2 \sum_{\beta=1}^n R_{\alpha x \beta} h_{\alpha\beta x} + \rho_{\alpha x} h_{\alpha xx} + h_{\alpha\alpha x}].$$

From the definition of f , we have

$$\begin{aligned}
(3.9) \quad & f((\cos r)x + \left(\frac{\sin r}{r}\right) \sum_{\tau>1} u_\tau e_\tau) \\
&= (\cos r)^3 h_{xxx} + 3(\cos r)^2 \left(\frac{\sin r}{r}\right) \sum_{\tau>1} u_\tau h_{\tau xx} \\
&\quad + 3(\cos r) \left(\frac{\sin r}{r}\right)^2 \sum_{\tau, \delta>1} u_\tau u_\delta h_{\delta \tau x} + \left(\frac{\sin r}{r}\right)^3 \sum_{\tau, \delta, \epsilon>1} u_\tau u_\delta u_\epsilon h_{\epsilon \delta \tau} \\
&= (\cos r)^3 h_{xxx} + 3(\cos r)^2 \left(\frac{\sin r}{r}\right) \sum_{\tau>1} u_\tau h_{\tau xx} \\
&\quad + (\cos r) \left(\frac{\sin r}{r}\right)^2 \sum_{\tau>1} (3h_{\tau xx} - h_{xxx}) u_\tau^2 \\
&\quad + 6(\cos r) \left(\frac{\sin r}{r}\right)^2 \sum_{\tau>\delta>1} u_\tau u_\delta h_{\tau \delta x} + \left(\frac{\sin r}{r}\right)^3 \sum_{\tau, \delta, \epsilon>1} u_\tau u_\delta u_\epsilon h_{\epsilon \delta \tau}
\end{aligned}$$

because of $r^2 = \sum_{\tau=2}^n u_\tau^2$. Applying Lemma A to (3.9), we find

$$(3.10) \quad \frac{\partial f}{\partial y_\alpha} (m, x) = 3h_{\alpha xx} \quad \text{for } 2 \leq \alpha \leq n,$$

$$(3.11) \quad \frac{\partial^2 f}{\partial y_\alpha \partial y_\beta} (m, x) = -3h_{xxx} \delta_{\alpha\beta} + 6h_{\alpha\beta x} \quad \text{for } 2 \leq \alpha, \beta \leq n.$$

We see from (3.8), (3.10) and (3.11) that

$$(3.12) \quad L(1/3, -1/3)(f)(m, x) = \sum_{\alpha=1}^n [(\nabla_{xx}^2 h)_{\alpha\alpha x} + h_{\alpha\alpha x}].$$

On the other hand, the equation (2.13) is rewritten as

$$(3.13) \quad \sum_{\alpha=1}^n (\nabla_{\beta\delta}^2 h)_{\alpha\alpha\gamma} = -\sum_{\alpha=1}^n \delta_{\beta\gamma} h_{\delta\alpha\alpha} \quad \text{for } 1 \leq \beta, \gamma, \delta \leq n.$$

Combining (3.12) with (3.13), we have

$$L(1/3, -1/3)(f)(m, x) = 0.$$

THEOREM 3.1. *Let M be an n -dimensional compact curvature-invariant C -totally real submanifold in a $(2n+1)$ -dimensional Sasakian manifold with η -parallel mean curvature vector field. If the sectional curvature of M is positive, then M is totally geodesic.*

PROOF. As M has positive sectional curvature, $L(1/3, -1/3)$ is elliptic. From the above hypothesis we have $L(1/3, -1/3)(f) = 0$. By maximum principle [10], f is constant on $S(M)$. Since f is an odd function, it must be zero. Thus M is totally geodesic.

COROLLARY 3.2. *Let M be an n -dimensional compact C -totally real submanifold in a $(2n+1)$ -dimensional Sasakian space form with η -parallel mean curvature vector field. If the sectional curvature of M is positive, then M is totally geodesic.*

PROOF. If the ϕ -sectional curvature of Sasakian space form N is denoted by c , then the Riemannian curvature tensor \bar{R} of N restricted to M is given by

$$\bar{R}_{WX}Y = \frac{c+3}{3}[\langle Y, X \rangle W - \langle Y, W \rangle X],$$

which means clearly that M is curvature-invariant. By Theorem 3.1, M is totally geodesic.

REMARK 1. If the normal connection of M is flat, then, from (2.9), M is of constant curvature 1, so that we have the same result as those in Theorem 3.1 or Corollary 3.2.

REMARK 2. As a Corollary of Theorem 3.1, we can state the Blair-Ogiue's Theorem in the introduction of this paper.

THEOREM 3.3. *Let M be an n -dimensional compact curvature-invariant C -totally real submanifold in a $(2n+1)$ -dimensional Sasakian manifold with η -parallel mean curvature vector field. If the sectional curvature of M is non-negative, then M has η -parallel second fundamental form.*

PROOF. By use of Lemma 3.1, we have $L(1/3, -1/3)(f) = 0$. Applying Lemma B, we find that $\text{grad}^h f$ must be identically zero. From (3.2) and (3.5), the fact that $\text{grad}^h f = 0$ is equivalent to saying that the second fundamental form is η -parallel.

COROLLARY 3.4. *Let M be an n -dimensional compact C -totally real submanifold in a $(2n+1)$ -dimensional Sasakian space form with η -parallel mean curvature vector field. If the sectional curvature of M is non-negative, then M has η -parallel second fundamental form.*

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