

CURVATURE BOUND AND TRAJECTORIES FOR MAGNETIC FIELDS ON A HADAMARD SURFACE

By

Toshiaki ADACHI

Introduction.

On a complete oriented Riemannian manifold M , a closed 2-form B is called a *magnetic field*. Let Ω denote the skew symmetric operator $\Omega: TM \rightarrow TM$ defined by $\langle u, \Omega(v) \rangle = B(u, v)$ for every $u, v \in TM$. We call a smooth curve γ a *trajectory* for B if it satisfies the equation $\nabla_{\dot{\gamma}} \dot{\gamma} = \Omega(\dot{\gamma})$. Since Ω is skew symmetric, we find that every trajectory has constant speed and is defined for $-\infty < t < \infty$. We shall call a trajectory *normal* if it is parametrized by its arc length. When γ is a trajectory for B , the curve σ defined by $\sigma(t) = \gamma(\lambda t)$ with some constant λ is a trajectory for λB . We call the norm $\|B_x\|$ of the operator $B_x: T_x M \times T_x M \rightarrow \mathbf{R}$ the *strength* of the magnetic field at the point x . For the trivial magnetic field $B = 0$, the case without the force of a magnetic field, trajectories are nothing but geodesics. In term of physics it is a trajectory of a charged particle under the action of the magnetic field. For a classical treatment and physical meaning of magnetic fields see [8].

On a Riemann surface M we can write down $B = f \cdot \text{Vol}_M$ with a smooth function f and the volum form Vol_M on M . When f is a constant function, the case of constant strength, the magnetic field is called *uniform*. On surfaces of constant curvature the feature of trajectories are well-known for every uniform magnetic field $k \cdot \text{Vol}_M$. On a Euclidean plane \mathbf{R}^2 they are circles (in usual sense of Euclidean geometry) of radius $1/|k|$. On a sphere $S^2(c)$ they are small circles with prime period $2\pi/\sqrt{k^2 + c}$. In these cases all trajectories are closed. On a hyperbolic plane $H^2(-c)$ of constant curvature $-c$, the situation is different. In his paper [4] Comtet showed that the feature of trajectories changes according to the strength of a uniform magnetic field $k \cdot \text{Vol}_M$. When the strength $|k|$ is greater than \sqrt{c} , normal trajectories are still closed, hence bounded, but if $|k| \leq \sqrt{c}$ they are unbounded simple curves, in particular, if $|k| = \sqrt{c}$ they are horocycles. In the preceding paper [2] we studied trajectories for Kähler magnetic fields $k \cdot B_f$,

which are scalar multiples of the Kähler form B_j , on a manifold of complex space form. On a complex projective plane all trajectories for Kähler magnetic fields are closed. But on a complex hyperbolic space $CH^n(-c)$ of constant holomorphic sectional curvature $-c$, normal trajectories for Kähler magnetic fields have similar properties as of trajectories for uniform magnetic fields on a hyperbolic plane. Their feature depend on the strength of a Kähler magnetic field; trajectories are bounded, horocyclic, or unbounded according to the strength is greater, equal to, or smaller than \sqrt{c} . In this context it is quite natural to pose the following problem. Consider a Hadamard manifold, which is a simply connected complete Riemannian manifold of nonpositive curvature $-\beta^2 \leq \text{Riem}_M \leq -\alpha^2$, $\beta \geq \alpha \geq 0$. Are they true that all trajectories are unbounded if the strength is smaller than α and that all trajectories are bounded if the strength is greater than β ? In this note we shall concerned with this problem on a Hadamard surface.

THEOREM 1. *Let $B = f \cdot \text{Vol}_M$ be a magnetic field with $|f| \leq \alpha$ on a Hadamard surface M of curvature $\text{Riem}_M \leq -\alpha^2$. Then every normal trajectory for B is unbounded for both directions.*

For Hadamard manifolds we have an important notion of ideal boundary. We denote by $\bar{M} = M \cup M(\infty)$ the compactification of a Hadamard surface M with its ideal boundary $M(\infty)$. For a two-sides unbounded curve γ on M , if $\lim_{t \rightarrow \infty} \gamma(t)$ and $\lim_{t \rightarrow -\infty} \gamma(t)$ exist in \bar{M} we denote these points by $\gamma(\infty)$ and $\gamma(-\infty)$ respectively, and call that γ has points of infinity. If we review the Comtet's result from this point of view, it assures the following. On $H^2(-c)$ every trajectory γ for a uniform magnetic field $k \cdot \text{Vol}_{H^2(-c)}$ with $|k| \leq \sqrt{c}$ has points of infinity $\gamma(\infty), \gamma(-\infty)$. When $|k| = \pm\sqrt{c}$ they coincide $\gamma(\infty) = \gamma(-\infty)$, and they are distinct when $|k| < \sqrt{c}$. We show that a similar property holds for general Hadamard surfaces.

THEOREM 2. *Let $B = f \cdot \text{Vol}_M$ be a magnetic field with $|f| \leq \alpha$ on a Hadamard surface M of curvature $\text{Riem}_M \leq -\alpha^2 \leq 0$. Suppose either $f \leq 0$ or $f \geq 0$ except on a compact subset of M . We then have the following.*

- (1) *Every normal trajectory for B has points of infinity.*
- (2) *If $|f| < \alpha$ except on a compact subset of M , every normal trajectory has two distinct points at infinity.*

§1. A note on γ -Jacobi fields.

We shall show our theorems by applying the Rauch's comparison theorem. Let $\mathbf{B} = f \cdot \text{Vol}_M$ be a magnetic field on a oriented surface M . We denote by Ω_0 the skew symmetric operator associated with the uniform magnetic field Vol_M . Clearly the skew symmetric operator associated with \mathbf{B} is of the form $\Omega = f \cdot \Omega_0$. For a normal trajectory γ for \mathbf{B} , we denote by $V_t(s)$ the γ -Jacobi field along the geodesic $s \rightarrow \sigma(t, s) = \exp_{\gamma(t)} s \Omega_0(\dot{\gamma})$ with $V_t(0) = \dot{\gamma}(t)$. This Jacobi field V_t is perpendicular to $\sigma(t, \cdot)$ and is obtained by the variation $\{\sigma(t + \varepsilon, \cdot)\}_\varepsilon$ of geodesics; $V_t(s) = \frac{\partial}{\partial t} \sigma(t, s)$.

For the sake of reader's convenience, we recall the explicit formula for normal trajectories and γ -Jacobi fields for uniform magnetic fields on surfaces of constant curvature.

EXAMPLE 1. On a Euclidean plane \mathbf{R}^2 , trajectories for the uniform magnetic fields of strength k satisfy the following equation:

$$\gamma(t) = \left(\frac{1}{k} \cos(kt - \theta), \frac{1}{k} \sin(kt - \theta) \right) + (\xi_1, \xi_2).$$

The variation of geodesics is given by

$$\sigma(t, s) = \left(\frac{1}{k} (1 - ks) \cos(kt - \theta), \frac{1}{k} (1 - ks) \sin(kt - \theta) \right) + (\xi_1, \xi_2)$$

and the γ -Jacobi field is

$$V_t(s) = (1 - ks) \dot{\gamma}(t),$$

hence it vanishes at $s_0 = 1/k$. The point $\sigma(t, 1/k) = (\xi_1, \xi_2)$ is usually called the center of γ .

EXAMPLE 2. On a sphere $S^2(c) = \{x = \{(x_1, x_2, x_3) \in \mathbf{R}^3 \mid \langle x, x \rangle = x_1^2 + x_2^2 + x_3^2 = 1\}$ of sectional curvature c , the trajectory γ for the uniform magnetic field of strength k satisfies the following equation when $\gamma(0) = x \in S^2(c)$, $\dot{\gamma}(0) = u \in U_x S^2(c) \simeq \{\xi \in \mathbf{R}^3 \mid \langle x, \xi \rangle = 0, \langle \xi, \xi \rangle = c\}$:

$$\begin{aligned} \gamma(t) = & \frac{1}{k^2 + c} (k^2 + c \cdot \cos \sqrt{k^2 + ct}) \cdot x \\ & + \frac{1}{\sqrt{k^2 + c}} \sin \sqrt{k^2 + ct} \cdot u + \frac{k}{k^2 + c} (1 - \cos \sqrt{k^2 + ct}) \cdot \Omega_0(u). \end{aligned}$$

Since the variation of geodesics is given by

$$\sigma(t, s) = \gamma(t) \cos \sqrt{cs} + \Omega_0(\dot{\gamma}(t)) \cdot \frac{1}{\sqrt{c}} \sin \sqrt{cs}$$

hence

$$V_t(s) = \dot{\gamma}(t) (\cos \sqrt{cs} - \frac{k}{\sqrt{c}} \sin \sqrt{cs}).$$

Therefore it vanishes at $s_0 = \frac{1}{\sqrt{c}} \tan^{-1} \sqrt{c} / k$. The point $\sigma(t, s_0)$ and the trajectory γ can be regarded as a pole and a latitude line of this sphere.

EXAMPLE 3. On the hyperbolic plane $H^2(-c) = \{x = (x_0, x_1, x_2) \in \mathbb{R}^3 | \langle x, x \rangle = -x_0^2 + x_1^2 + x_2^2 = -1, x_0 \geq 1\}$ of constant sectional curvature $-c$, the trajectory of the uniform magnetic field of strength k satisfies the following equation if $\gamma(0) = x$ and $\dot{\gamma}(0) = u \in U_x H^2(-c) \simeq \{\xi \in \mathbb{R}^3 | \langle x, \xi \rangle = 0, \langle \xi, \xi \rangle = c\}$:

$$\begin{aligned} \gamma(t) = & \frac{1}{c-k^2} (-k^2 + c \cdot \cosh \sqrt{c-k^2} t) \cdot x + \frac{1}{\sqrt{c-k^2}} \sinh \sqrt{c-k^2} t \cdot u \\ & + \frac{k}{c-k^2} (-1 + \cosh \sqrt{c-k^2} t) \cdot \Omega_0(u), \quad \text{when } 0 \leq k < \sqrt{c}, \end{aligned}$$

$$\gamma(t) = (1 + \frac{ct^2}{2})x + tu + \frac{\sqrt{ct^2}}{2} \Omega_0(u), \quad \text{when } k = \sqrt{c},$$

$$\begin{aligned} \gamma(t) = & \frac{1}{k^2-c} (k^2 - c \cdot \cos \sqrt{k^2-ct}) \cdot x + \frac{1}{\sqrt{k^2-c}} \sin \sqrt{k^2-ct} \cdot u \\ & + \frac{k}{k^2-c} (1 - \cos \sqrt{k^2-ct}) \cdot \Omega_0(u), \quad \text{when } k > \sqrt{c}. \end{aligned}$$

The variation of geodesics is given by

$$\sigma(t, s) = \gamma(t) \cosh \sqrt{cs} + \Omega_0(\dot{\gamma}(t)) \cdot \frac{1}{\sqrt{c}} \sinh \sqrt{cs}$$

hence

$$V_t(s) = \dot{\gamma}(t) (\cosh \sqrt{cs} - \frac{k}{\sqrt{c}} \sinh \sqrt{cs}).$$

Therefore if $|k| > \sqrt{c}$ the γ -Jacobi field vanishes at $s_0 = \frac{1}{\sqrt{c}} \tanh^{-1} \sqrt{c} / k = \frac{1}{2\sqrt{c}} \log \frac{k + \sqrt{c}}{k - \sqrt{c}}$. If $|k| \leq \sqrt{c}$ it does not vanish. When $k = \sqrt{c}$, the case that γ is a horocycle, the point $\gamma(\infty) = \gamma(-\infty)$ on the ideal boundary can be regarded as the vanishing point of the γ -Jacobi field; $\lim_{s \rightarrow \infty} V_t(s) = 0$.

§2. Proofs.

We are now in the position to prove theorems. Let γ be a trajectory for the magnetic field $f \cdot \text{Vol}_M$ with $|f| \leq \alpha$ on a Hadamard surface M of curvature $\text{Riem}_M \leq -\alpha^2$. We compare the norm of the γ -Jacobi field V_t with the norm of γ -Jacobi fields for uniform magnetic fields on a hyperbolic space. Since we have

$$\nabla_{\frac{\partial \sigma}{\partial s}} V_t(0) = \frac{\partial}{\partial s} \frac{\partial}{\partial t} \sigma(t, s) \Big|_{s=0} = \frac{\partial}{\partial t} \Omega_0(\dot{\gamma}(t)) = -f(\gamma(t))\dot{\gamma}(t),$$

we get the following estimate by the Rauch's comparison theorem;

$$\|V_t(s)\| \geq \cosh \alpha s - \frac{1}{\alpha} f(\gamma(t)) \sinh \alpha s.$$

This guarantees that if $|f(\gamma(t))| \leq \alpha$ then V_t does not vanish anywhere and $\liminf_{s \rightarrow \pm\infty} \exp(-\alpha s) \cdot \|V_t(s)\| \geq \frac{1}{2}(1 - |f(\gamma(t))|/\alpha)$ for every t . Since M is diffeomorphic to an Euclidean plane, we find that the geodesic $\sigma(t_1, \cdot)$ and $\sigma(t_2, \cdot)$ do not intersect each other if $t_1 \neq t_2$.

Let $S_r(p)$ denote the geodesic circle $\{x \in M \mid d(x, p) = r\}$ of radius r centered at p . If we suppose $\gamma|_{[0, \infty)}$ is tangent to a geodesic circle $S_r(\gamma(0))$ at $\gamma(t_0)$, then $\sigma(t_0, \cdot)$ passes $\gamma(0)$, which is a contradiction. We therefore have

PROPOSITION. *The trajectory rays $\gamma|_{[0, \infty)}$ and $\gamma|_{(-\infty, 0]}$ cross only once to every geodesic circle $S_r(\gamma(0))$.*

This proposition leads us to Theorem 1. In order to see Theorem 2, we denote by u_t for $t \neq 0$ the unit tangent vector at $p = \gamma(0)$ such that the geodesic emanating from p with the initial speed u_t joins p and $\gamma(t)$. We set $u_0 = \dot{\gamma}(0)$. Since γ is unbounded in both directions, we may treat the case that f is nonpositive (or nonnegative) on M . We then find the smooth curve $(u_t)_{t \in (0, \infty)}$ on $U_p M \simeq S^1$ rotates counterclockwisely if $f \geq 0$ and rotates clockwise if $f \leq 0$. If we suppose $u_{t_0} = \pm \Omega_0(u_0)$ for some t_0 , then $\sigma(0, \cdot)$ passes $\gamma(t_0)$. Hence we find that $\{u_t\}_t \subset U_p M \setminus \{\pm \Omega_0(u_0)\}$ and the limit $u_\infty = \lim_{t \rightarrow \infty} u_t$ exists. Similarly, we find that the limit $u_{-\infty} = \lim_{t \rightarrow -\infty} u_t$ exists. We therefore get that γ has points at infinity;

$$\gamma(\infty) = \rho_{u_\infty}(\infty) \quad \text{and} \quad \gamma(-\infty) = \rho_{u_{-\infty}}(\infty),$$

where ρ_v denote the geodesic with $\dot{\rho}(0) = v$. Now we suppose that γ has a single point at infinity: $\gamma(\infty) = \gamma(-\infty)$. This means $u_\infty = u_{-\infty}$, hence $\gamma(\infty) = \sigma(t, \infty)$ for every t . This can not occur when $f < \alpha$. We get the conclusion of Theorem 2.

In view of our proof, we can conclude the following.

REMARK. Consider a magnetic field $B = f \cdot \text{Vol}_M, |f| \leq \alpha$, on a Hadamard surface M of curvature $\text{Riem}_M \leq -\alpha^2 < 0$.

(1) A trajectory γ for B has a single point at infinity $\gamma(\infty) = \gamma(-\infty)$ if and only if all the geodesic $\sigma(t, \cdot)$ converges to that point $\sigma(t, \infty) = \gamma(\infty)$.

(2) If a trajectory γ has a single point at infinity, then the magnetic angle at that point is $\pi/2$. Here the magnetic angle means the angle between the outer tangent vector of γ and the outer tangent vector of geodesics ρ with $\rho(\infty) = \gamma(\infty)$ (c.f.[2]).

REMARK. Let $B = k \cdot \text{Vol}_M, |k| < \alpha$ be a uniform magnetic field on a Hadamard surface M of bounded negative curvature $-\beta^2 \leq \text{Riem}_M \leq -\alpha^2 < 0$. We have a positive ε such that the angle $\sphericalangle(\dot{\gamma}(0), \dot{\rho}(0))$ between a trajectory γ for B and a geodesic ρ with $\gamma(0) = \rho(0)$ and $\gamma(\infty) = \rho(\infty)$ is always not greater than $\pi - \varepsilon$.

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Department of Mathematics
Nagoya Institute of Technology
Gokiso, Showa-ku, Nagoya 466
Japan
e-mail address: d43019a@nucc.cc.nagoya-u.ac.jp