

## LOCAL INJECTIVITY OF PRYM MAPS FOR SOME FAMILIES OF COMPACT RIEMANN SURFACES

By

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### Introduction.

In this paper we consider some families of double coverings of compact Riemann surfaces (or complete irreducible non-singular algebraic curves over  $\mathbf{C}$ ) allowing ramifications, and we study the Prym varieties of these double coverings.

Let  $\pi: \tilde{R} \rightarrow R$  be a double covering, where  $\tilde{R}$  and  $R$  are compact Riemann surfaces of genera  $\tilde{g}$  and  $g$ , and  $J(\tilde{R})$  and  $J(R)$  be Jacobians of  $\tilde{R}$  and  $R$ , respectively. If  $\pi$  has  $2n$  branch points, we have  $\tilde{g} = 2g + n - 1$  by means of the Riemann-Hurwitz relation. We denote by  $\iota$  the generator of the Galois group of  $\tilde{R}/R$ . Moreover we denote by the same  $\iota$  the involution of  $J(\tilde{R})$  induced by that of  $\tilde{R}/R$ . The norm map  $Nm: J(\tilde{R}) \rightarrow J(R)$  is defined by the induced map on divisor classes given by  $D \rightarrow \pi(D)$  ( $D$  a divisor on  $\tilde{R}$ ). The Prym variety  $P = P(\tilde{R}/R)$  of  $\tilde{R}/R$  (or  $(\tilde{R}, \iota)$ ) is defined by the connected component containing the origin of the kernel of  $Nm$ , and we have an isogeny  $\iota_*: J(R) \times P \rightarrow J(\tilde{R})$  naturally (see Mumford [5], Fay [5], Sasaki [7]). The process taking Prym varieties defines the so-called Prym map  $P: \tilde{R}/R \rightarrow P(\tilde{R}/R)$  from the family of  $(\tilde{R}, \iota)$ 's to the moduli space of polarized abelian varieties.

In case of unramified double coverings, Mumford [5] states some beautiful results concerning the relative dimension of the Prym map. For double coverings with ramification points, however, the contribution of those points to the Prym map might be unknown.

In this paper we will calculate the relative dimension of the Prym map for some typical examples of  $\tilde{R}/R$  with  $2n$  ( $n \geq 1$ ) ramification points.

We consider the following three families of compact Riemann surfaces parametrized by  $t$  or  $t_i$ 's:

$$\begin{aligned} \text{(I)} \quad \tilde{R}_t: y^4 &= (x-1-t)(x^2+x+1) && \text{genus } 3 \\ R_t: y^2 &= (x-1-t)(x^2+x+1) && \text{genus } 1 \end{aligned}$$

$$(II) \quad \check{R}_t: y^6=(x-1-t)(x^2+x+1) \quad \text{genus 4}$$

$$R_t: y^3=(x-1-t)(x^2+x+1) \quad \text{genus 1}$$

$$(III) \quad \check{R}_{t_1, t_2, t_3}: y^4=(x-1-t_1)(x-\rho-\rho t_2)(x-\rho^2-\rho^2 t_3)$$

$$\times(x-\rho^3)(x-\rho^4) \quad \text{genus 6}$$

$$R_{t_1, t_2, t_3}: y^2=(x-1-t_1)(x-\rho-\rho t_2)(x-\rho^2-\rho^2 t_3)$$

$$\times(x-\rho^3)(x-\rho^4) \quad \text{genus 2,}$$

where  $\rho=\exp(2\pi i/5)$ .

(I) is an example for  $n=2$ , and (II), (III) are for  $n=3$ .

Hereafter we write  $\check{R}$  and  $R$  instead of  $\check{R}_t$ ,  $\check{R}_{t_1, t_2, t_3}$  and  $R_t$ ,  $R_{t_1, t_2, t_3}$  for the sake of convenience occasionally.

In case (I) or (III), the surface  $\check{R}$  has an automorphism  $T$  of order 4 defined by  $T: (x, y) \rightarrow (x, iy)$  where  $i=\sqrt{-1}$ , and the involution  $T^2: (x, y) \rightarrow (x, -y)$ . In case (II),  $\check{R}$  has an automorphism  $T$  of order 6 defined by  $T: (x, y) \rightarrow (x, \sigma y)$  where  $\sigma=\exp(2\pi i/6)$  and the involution  $T^3: (x, y) \rightarrow (x, -y)$ .

$\langle T \rangle$  will denote the group generated by  $T$  and as usual  $\check{R}/\langle T \rangle$  will denote the surface obtained by identifying points on  $\check{R}$  which are equivalent under the action of  $\langle T \rangle$  on  $\check{R}$ . In case (I) or (III),  $\check{R}/\langle T^2 \rangle$  is canonically isomorphic to  $R$ , and in case (II),  $\check{R}/\langle T^3 \rangle$  is canonically isomorphic to  $R$ .

Under these notations, we can give our main results as follows:

**THEOREM 1** (*Joint work with Sasaki*). *In case (I), the Prym variety  $P$  has a period matrix of the form*

$$\begin{pmatrix} I_2 & i & 0 \\ 0 & 0 & i \end{pmatrix}.$$

*That is to say,  $P$  is isomorphic to the product  $J \times J$  where  $J=\mathbf{C}/\langle 1, i \rangle$ .*

**THEOREM 2**. *In case (II) the Prym variety  $P$  has a period matrix of the form  $(I_3, II)$  where  $II$  is the following:*

$$II = \frac{1}{2(1-\sigma)\{(2+\sigma)+z\}} \begin{pmatrix} (1+\sigma)+z & 1-\sigma^2 & 2 \\ 1-\sigma^2 & 3(\sigma-2) & 2(1-\sigma)(1+z) \\ 2 & 2(1-\sigma)(1+z) & 2\sigma+2\sigma(1-\sigma)z \end{pmatrix},$$

where  $z = \left( \int_{B_3} \omega_1 \right) / \left( \int_{A_3} \omega_1 \right)$  is the modulus of the surface  $\hat{R}$ , and

$$\hat{R}: y^2=(x-1-t)(x^2+x+1) \quad \text{and} \quad \sigma=\exp(2\pi i/6).$$

**THEOREM 3**. *In case (III), the Prym variety  $P$  has a period matrix of the*

form (I, II) where II is the following :

$$\Pi = \begin{pmatrix} -1/2+i/s & 1/2-ip/s & -iq/s & (1-i)/2-ir/s \\ 1/2-ip/s & i/2+ip^2/s & (1-i)/2+ipq/s & i+ipr/s \\ -iq/s & (1-i)/2+ipq/s & -(1-i)+iq^2/s & -i+iqr/s \\ (1-i)/2-ir/s & i+ipr/s & -i+iqr/s & i+ir^2/s \end{pmatrix}$$

where

$$p = \frac{\int_{A_3} \omega_1}{\int_{A_4} \omega_1} + (1-i) \frac{\int_{B_3} \omega_1}{\int_{A_4} \omega_1} + (1-i), \quad q = (i-1) \frac{\int_{B_3} \omega_1}{\int_{A_4} \omega_1} + (i-1),$$

$$r = (1-i) \frac{\int_{A_3} \omega_1}{\int_{A_4} \omega_1} - 2i \frac{\int_{B_3} \omega_1}{\int_{A_4} \omega_1} - (1-i) \frac{\int_{B_4} \omega_1}{\int_{A_4} \omega_1} - (1+i),$$

$$s = -2p^2 - q^2 - 2pq + 4p - 2r - 2.$$

THEOREM 4. In case (I), the Kodaira-Spencer map

$$\kappa : T_{s,0} \longrightarrow H^1(\tilde{R}, \mathcal{F}_{\tilde{R}}) \quad \text{is given by}$$

$$\kappa((\partial/\partial t)_0) = (3x)^{-1} y^4 \partial_x.$$

THEOREM 5. In case (II), the Kodaira-Spencer map  $\kappa$  is given by

$$\kappa((\partial/\partial t)_0) = (1/3)x^2 \partial_x.$$

THEOREM 6. In case (III), the Kodaira-Spencer map  $\kappa$  is given by

$$\kappa \begin{pmatrix} (\partial/\partial t_1)_0 \\ (\partial/\partial t_2)_0 \\ (\partial/\partial t_3)_0 \end{pmatrix} = \frac{1}{5} \begin{pmatrix} 1 & 1 & 1 \\ \rho^2 & \rho^3 & \rho^4 \\ \rho^4 & \rho & \rho^3 \end{pmatrix} \begin{pmatrix} x^4 \partial_x \\ x^3 \partial_x \\ x^2 \partial_x \end{pmatrix},$$

where  $\rho = \exp(2\pi i/5)$ .

(The above notations in Theorem 4, 5, 6 are explained in §2.)

OBSERVATION. In case (I), the parameter  $t$  is not reflected in the Prym variety as a variable, that is to say, the Prym is uniquely determined. In case (II),  $t$  is reflected as a variable, and in case (III),  $t_1, t_2$  and  $t_3$  are reflected as independent variables in the Prym.

In section 1, we find a canonical homology basis and we compute the period matrix of  $J(\tilde{R})$  in each case. Moreover, by the operation of a second order

transformation, we obtain the period matrix of the Prym variety. In section 2, we calculate the Kodaira-Spencer map and we give not only to prove the independency of parameter  $t_i$ 's but also to the explicit representation of influence of parameters on the Prym variety.

I would like to express my hearty thanks to Professor T. Sekiguchi for his advices and encouragement during the preparation of this paper. In particular, he informed and taught me the notion and method of Kodaira-Spencer map and gave me some instructive suggestions. Also I would like to thank Professor R. Sasaki for his stimulative suggestions in our conversations which gave me the motivation of this paper.

### §1. Period matrices and Prym varieties.

In this section, we shall construct the period matrices of surfaces in cases (I), (II) and (III), according to Farkas' method [1], [9].

$$\text{CASE (I). } \tilde{R}: y^4=(x-1-t)(x^2+x+1)$$

$$R: y^2=(x-1-t)(x^2+x+1)$$

where  $1+t \neq \infty$ ,  $\exp(2\pi i/3)$ ,  $\exp(4\pi i/3)$ .

Here we have an automorphis  $T: (x, y) \rightarrow (x, iy)$  of  $\tilde{R}$ .

Then  $\tilde{R}$  is regarded as a double covering of  $R$  with the involution  $T^2: (x, y) \rightarrow (x, -y)$ .

Since we can easily examine the divisors of differentials, we obtain a basis of the vector space of holomorphic differentials given by

$$\omega_1=y^{-3}dx, \quad \omega_2=y^{-3}xdx, \quad \omega_3=y^{-2}dx.$$

Then we see

$$(1) \quad \begin{cases} T\omega_j=i\omega_j, & T^2\omega_j=-\omega_j & (j=1, 2) \\ T\omega_3=-\omega_3, & T^2\omega_3=\omega_3 \end{cases}$$

that is to say,  $\omega_1$  and  $\omega_2$  are the anti  $T^2$ -invariant differentials and  $\omega_3$  is  $T^2$ -invariant differential. So,  $\omega_1$  and  $\omega_2$  are the differentials which correspond to the differentials of Prym variety and  $\omega_3$  is considered as a differential of  $R$  by the natural projection  $\tilde{R} \rightarrow R = \tilde{R}/\langle T^2 \rangle$ .

Here we construct a canonical homology basis on  $\tilde{R}$  (cf. [6], [3]). We consider the following closed curves  $\alpha, \beta, \gamma$  and  $\delta$  on  $x$ -sphere as illustrated in Fig. 1.

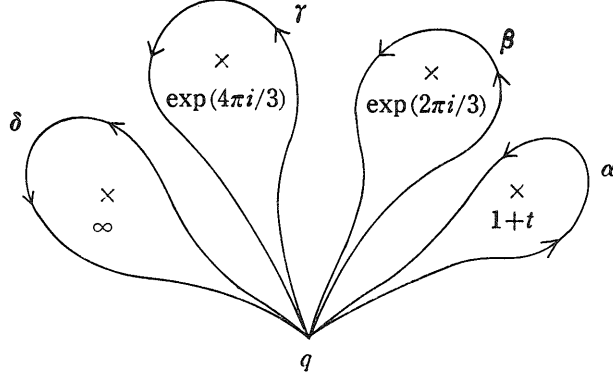


Fig. 1

$y$  has four branches  $y_1, y_2(=iy_1), y_3(=-y_1), y_4(=-iy_1)$ . Let  $\alpha_j$  be the lifting of  $\alpha$  which is a path from  $y_j$ -branch to  $y_{j+1}$ -branch ( $j=1, 2, 3$ ) and  $\alpha_4$  be the lifting of  $\alpha$  from  $y_4$ -branch to  $y_1$ -branch. In the same way, let  $\beta_j, \gamma_j$  and  $\delta_j$  be the liftings of  $\beta, \gamma$  and  $\delta$ , respectively.

Then we get the following relations

$$(2) \quad \begin{cases} \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 \sim 0 & \beta_1 + \beta_2 + \beta_3 + \beta_4 \sim 0 \\ \gamma_1 + \gamma_2 + \gamma_3 + \gamma_4 \sim 0 & \delta_1 + \delta_2 + \delta_3 + \delta_4 \sim 0 \\ \alpha_1 + \beta_2 + \gamma_3 + \delta_4 \sim 0 & \alpha_2 + \beta_3 + \gamma_4 + \delta_1 \sim 0 \\ \alpha_3 + \beta_4 + \gamma_1 + \delta_2 \sim 0 & \alpha_4 + \beta_1 + \gamma_2 + \delta_3 \sim 0 \end{cases}$$

where  $\alpha + \beta$  denotes the composition of  $\alpha$  and  $\beta$  by joining the final point of  $\alpha$  and the initial point of  $\beta$ , and  $\sim$  means homotopic equivalence.

Then a canonical homology basis is represented as follows;

$$(3) \quad \begin{cases} A_1 = \alpha_1 - \delta_1 - \delta_4 + \alpha_4 & B_1 = -\alpha_2 + \delta_2 + \gamma_3 - \beta_3 \\ A_2 = \alpha_1 - \beta_1 & B_2 = -\alpha_1 + \gamma_1 \\ A_3 = \alpha_3 - \beta_3 & B_3 = -\alpha_3 + \gamma_3 \end{cases}$$

Here  $A_2$  and  $B_2$  are considered as a canonical homology basis of  $R$  by the natural projection  $\tilde{R} \rightarrow R$ . We illustrate this homology basis in Appendix.

Then, from (2), we see the following

$$(4) \quad \begin{cases} T^2 A_1 \approx -A_1 & T^2 A_2 \approx A_3 \\ T^2 B_1 \approx -B_1 & T^2 B_2 \approx B_3 \end{cases}$$

$$(5) \quad \begin{cases} A_1 \approx -A_3 - B_2 - T A_2 - T B_2 \\ B_1 \approx -T A_2 + B_3 - A_2 - B_2 \end{cases}$$

where  $\approx$  means homological equivalence.

We put  $\int_{A_j} \omega_i = a_{ij}$ ,  $\int_{B_j} \omega_i = b_{ij}$ .

From (1) and (4), we see that

$$a_{13} = -a_{12}, \quad a_{23} = -a_{22}, \quad a_{31} = 0, \quad a_{32} = a_{33},$$

$$b_{13} = -b_{12}, \quad b_{23} = -b_{22}, \quad b_{31} = 0, \quad b_{32} = b_{33}.$$

We put

$$\begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}^{-1} \begin{pmatrix} \omega_1 \\ \omega_2 \end{pmatrix}, \quad \phi_3 = \omega_3 / a_{32}$$

$$\begin{pmatrix} b'_{12} & b'_{12} \\ b'_{21} & b'_{22} \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}^{-1} \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}, \quad \tau = b_{32} / a_{32}.$$

Then

$$\left( \int_{A_j} \phi_i \right) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 1 & 1 \end{pmatrix}, \quad \left( \int_{B_j} \phi_i \right) = \begin{pmatrix} b'_{11} & b'_{12} & -b'_{12} \\ b'_{21} & b'_{22} & -b'_{22} \\ 0 & \tau & \tau \end{pmatrix}.$$

From (1) and (5), we see that

$$1 = \int_{A_1} \phi_1 = -\int_{A_3} \phi_1 - \int_{B_2} \phi_1 - \int_{T A_2} \phi_1 - \int_{T B_2} \phi_1 = -b'_{12} + i b'_{12}$$

or  $b'_{12} = -(1+i)/2$ .

By the same way, we see that

$$b'_{11} = 1+i, \quad b'_{21} = -(1+i), \quad b'_{22} = i.$$

We put

$$\varphi_1 = \phi_1, \quad \varphi_2 = (\phi_2 + \phi_3)/2, \quad \varphi_3 = (\phi_3 - \phi_2)/2.$$

Then we see that

PROPOSITION 1.  $\tilde{R}$  has a period matrix of the form

$$\left( \int_{A_j} \varphi_i, \int_{B_j} \varphi_i \right) = \begin{pmatrix} 1+i & -(1+i)/2 & (1+i)/2 \\ I_3, & -(1+i)/2 & (\tau+i)/2 & (\tau-i)/2 \\ (1+i)/2 & (\tau-i)/2 & (\tau+i)/2 \end{pmatrix}$$

where  $I_3$  is the  $3 \times 3$  identity matrix and  $\tau$  is the modulus of  $R$  with respect to

the homology basis on  $\tilde{R}$  determined by the natural projection  $\tilde{R} \rightarrow R$ .

Recall that in general there are  $2g \times 2g$  integral matrices  $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$  which act on Siegel space  $\mathfrak{S}_g$  in the following fashion  $\mathfrak{S}_g \ni \pi \rightarrow (A\pi + B)(C\pi + D)^{-1} \in \mathfrak{S}_g$  where  $A, B, C, D$  are  $g \times g$  integral matrices,  $A^t B$  and  $C^t D$  are symmetric and  $A^t D - B^t C = mI$ . If  $m=1$ , the action is so called the element of the Siegel modular group or linear transformation, while the more general type of transformation is called an  $m$ -th order transformation ([1]).

PROPOSITION 2. *There is a second order transformation of  $\mathfrak{S}_2$  which maps the period matrix of  $\tilde{R}$  to the matrix*

$$\begin{pmatrix} II & 0 \\ 0 & \tau \end{pmatrix} \text{ where } II = \begin{pmatrix} (1+i)/2 & -(1+i)/2 \\ -(1+i)/2 & i \end{pmatrix} \in \mathfrak{S}_2.$$

PROOF. The proof is by computation. We take  $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$  where

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 1 & 1 \end{pmatrix}, \quad D = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 1 & 1 \end{pmatrix}, \quad B = C = 0.$$

Then a simple computation gives above result.

PROPOSITION 3. *There is a linear transformation of  $\mathfrak{S}_2$  which maps  $II$  to the matrix  $\begin{pmatrix} i & 0 \\ 0 & i \end{pmatrix} \in \mathfrak{S}_2$ .*

PROOF. We take  $\begin{pmatrix} A & B \\ C & D \end{pmatrix} \in S_P(2, \mathbf{Z})$  where

$$A = \begin{pmatrix} -1 & 0 \\ 1 & 1 \end{pmatrix}, \quad B = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}, \quad C = \begin{pmatrix} -1 & 0 \\ -1 & -1 \end{pmatrix}, \quad D = 0.$$

Above matrix  $II$  or  $\begin{pmatrix} i & 0 \\ 0 & i \end{pmatrix}$  is the period matrix of the Prym variety. As a consequence of this, we have

THEOREM 1. *In case (I), the Prym variety  $P$  has a period matrix of the form  $\begin{pmatrix} I_2 & i & 0 \\ 0 & i & i \end{pmatrix}$ . That is to say,  $P$  is isomorphic to the product  $J \times J$  where  $J = \mathbf{C}/\langle 1, i \rangle$ .*

CASE (II).  $\tilde{R}: y^6 = (x-1-t)(x^2+x+1)$

$R: y^3 = (x-1-t)(x^2+x+1)$

where  $1+t \neq \infty$ ,  $\exp(2\pi i/3)$ ,  $\exp(4\pi i/3)$ .

Here  $T: (x, y) \rightarrow (x, \sigma y)$  where  $\sigma = \exp(2\pi i/6)$ . Then  $\tilde{R}$  is regarded as a double covering of  $R$  with the involution

$$T^3: (x, y) \longrightarrow (x, -y).$$

Since we can easily examine the divisors of differentials, we obtain a basis of the vector space of holomorphic differentials given by

$$\omega_1 = y^{-3} dx, \quad \omega_2 = y^{-5} dx, \quad \omega_3 = y^{-5} x dx, \quad \omega_4 = y^{-4} dx.$$

Then we see

$$(6) \quad \begin{cases} T\omega_1 = -\omega_1, & T\omega_2 = \sigma\omega_2, & T\omega_3 = \sigma^2\omega_3 \\ T^3\omega_1 = -\omega_1, & T^3\omega_2 = -\omega_2, & T^3\omega_3 = -\omega_3 \end{cases} \quad (i=2, 3).$$

So,  $\omega_1$ ,  $\omega_2$  and  $\omega_3$  are the anti  $T^3$ -invariant differentials and  $\omega_4$  is  $T^3$ -invariant differential. Hence  $\omega_1$ ,  $\omega_2$  and  $\omega_3$  are the differentials of the Prym variety and  $\omega_4$  is considered as the differential of  $R$  by the natural projection  $\tilde{R} \rightarrow R$ .

Here we construct a canonical homology basis on  $\tilde{R}$ . We consider the following closed curves  $\alpha$ ,  $\beta$ ,  $\gamma$  and  $\delta$  on  $x$ -sphere as in Fig. 1.  $y$  has six branches  $y_1$ ,  $y_2(=\sigma y_1)$ ,  $y_3(=\sigma^2 y_1)$ ,  $y_4(=-y_1)$ ,  $y_5(=-\sigma y_1)$  and  $y_6(=-\sigma^2 y_1)$ . Let  $\alpha_i$  be the lifting of  $\alpha$  which a path from  $y_i$ -branch to  $y_{i+1}$ -branch ( $i=1, \dots, 5$ ) and  $\alpha_6$  be the lifting from  $y_6$ -branch to  $y_1$ -branch. In the same way, let  $\beta_i$  and  $\gamma_i$  be the liftings of  $\beta$  and  $\gamma$ , respectively. We must pay attention to the lifting of  $\delta$ , for the branch points over infinity are of order 1. Let  $\delta_i$  be the lifting of  $\delta$  from  $y_i$ -branch to  $y_{i+3}$ -branch ( $i=1, 2, 3$ ) and  $\delta_j$  be the lifting from  $y_j$ -branch to  $y_{j-3}$ -branch ( $j=4, 5, 6$ ). Here we get the following relations

$$(7) \quad \begin{cases} \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 + \alpha_5 + \alpha_6 \sim 0, & \beta_1 + \beta_2 + \beta_3 + \beta_4 + \beta_5 + \beta_6 \sim 0 \\ \gamma_1 + \gamma_2 + \gamma_3 + \gamma_4 + \gamma_5 + \gamma_6 \sim 0, & \delta_1 + \delta_4 \sim 0, & \delta_2 + \delta_5 \sim 0, & \delta_3 + \delta_6 \sim 0 \\ \alpha_1 + \beta_2 + \gamma_3 + \delta_4 \sim 0, & \alpha_2 + \beta_3 + \gamma_4 + \delta_5 \sim 0, & \alpha_3 + \beta_4 + \gamma_5 + \delta_6 \sim 0 \\ \alpha_4 + \beta_5 + \gamma_6 + \delta_1 \sim 0, & \alpha_5 + \beta_6 + \gamma_1 + \delta_2 \sim 0, & \alpha_6 + \beta_1 + \gamma_2 + \delta_3 \sim 0 \end{cases}$$

Then a canonical homology basis is represented as follows;

$$(8) \quad \begin{cases} A_1 = \gamma_1 + \gamma_2 + \gamma_3 - \delta_1 & B_1 = \delta_3 - \gamma_5 - \gamma_4 - \gamma_3 \\ A_2 = \alpha_2 + \alpha_3 + \alpha_4 - \delta_2 & B_2 = \beta_3 + \beta_4 + \beta_5 - \alpha_5 - \alpha_4 - \alpha_3 \\ A_3 = \alpha_1 - \beta_1 & B_3 = \gamma_1 - \alpha_1 \\ A_4 = \alpha_4 - \beta_4 & B_4 = \gamma_4 - \alpha_4. \end{cases}$$



Here,  $A_3$  and  $B_3$  are considered as a canonical homology basis of  $R$  by the natural projection  $\tilde{R} \rightarrow R$ . We illustrate this homology basis in Appendix.

Then, from (6), (7) and (8), we get the following

$$(9) \quad \begin{cases} T^3 A_1 \approx -A_1 & T^3 A_2 \approx -A_2 & T^3 A_3 \approx A_4 \\ T^3 B_1 \approx -B_2 & T^3 B_2 \approx -B_2 & T^3 B_3 \approx B_4 \end{cases}$$

$$(10) \quad \begin{cases} A_1 \approx -T A_4 - B_4 - T B_4 & B_1 \approx +A_3 + B_3 + T^2 B_4 \\ A_2 \approx -T^2 A_4 + B_3 & B_2 \approx -T^2 A_3 - A_4 - T A_4. \end{cases}$$

We put

$$\int_{A_j} \omega_i = a_{ij}, \quad \int_{B_j} \omega_i = b_{ij}.$$

From (6) and (9), we see that

$$\begin{aligned} a_{41} = a_{42} = b_{41} = b_{42} = 0, \quad a_{43} = a_{44}, \quad b_{43} = b_{44} \\ a_{i4} = -a_{i3}, \quad b_{i4} = -b_{i3} \quad (i=1, 2, 3). \end{aligned}$$

From (6) and (10), we see that

$$\begin{aligned} a_{11} &= \int_{A_1} \omega_1 = - \int_{T A_4} \omega_1 - \int_{B_4} \omega_1 - \int_{T B_4} \omega_1 = \int_{A_4} \omega_1 = a_{14} = -a_{13} \\ a_{12} &= \int_{A_2} \omega_1 = - \int_{T^2 A_4} \omega_1 + \int_{B_3} \omega_1 = - \int_{A_4} \omega_1 + \int_{B_3} \omega_1 = a_{13} + b_{13} \\ b_{11} &= \int_{B_1} \omega_1 = \int_{A_3} \omega_1 + \int_{B_3} \omega_1 + \int_{T^2 B_4} \omega_1 = a_{13} + b_{13} - b_{13} = a_{13} \\ b_{12} &= \int_{B_2} \omega_1 = - \int_{T^2 A_3} \omega_1 - \int_{A_4} \omega_1 - \int_{T A_4} \omega_1 = -a_{13}. \end{aligned}$$

By the same way

$$\begin{aligned} a_{21} &= -\sigma^2 a_{23} + (1 - \sigma^2) b_{23}, & a_{22} &= -\sigma a_{23} + b_{23} \\ a_{31} &= -\sigma^2 a_{33} + (1 - \sigma^2) b_{33}, & a_{32} &= -\sigma a_{33} + b_{33} \\ b_{21} &= a_{23} + (1 + \sigma) b_{23}, & b_{22} &= 2a_{23} \\ b_{31} &= a_{33} + (1 + \sigma) b_{33}, & b_{32} &= 2a_{33}. \end{aligned}$$

We put  $a_{13} = k$ ,  $b_{13} = l$ ,  $b_{43}/a_{43} = \tau$ .

$$(a_{ij})^{-1} \begin{pmatrix} \omega_1 \\ \omega_2 \\ \omega_3 \end{pmatrix} = \begin{pmatrix} \phi_1 \\ \phi_2 \\ \phi_3 \end{pmatrix}, \quad \omega_4/a_{43} = \phi_4.$$

Then

$$\left( \int_{A_j} \phi_i \right) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & 1 \end{pmatrix}, \quad \left( \int_{B_j} \phi_i \right) = \begin{pmatrix} 2b'_{11} & 2b'_{12} & b'_{13} & -b'_{13} \\ 2b'_{21} & 2b'_{22} & b'_{23} & -b'_{23} \\ 2b'_{31} & 2b'_{32} & b'_{33} & -b'_{33} \\ 0 & 0 & \tau & \tau \end{pmatrix}$$

where

$$(11) \quad \begin{cases} 2b'_{11} = \frac{(1+\sigma)k+l}{(1-\sigma)\{(2+\sigma)k+l\}} & 2b'_{21} = 2b'_{12} = \frac{(1+\sigma)k}{(2+\sigma)k+l} \\ b'_{31} = b'_{13} = \frac{k}{(1-\sigma)\{(2+\sigma)k+l\}} & b'_{32} = b'_{23} = \frac{k+l}{(2+\sigma)k+l} \\ 2b'_{22} = \frac{-3k}{(2+\sigma)k+l} & b'_{33} = \frac{\sigma\{k+(1-\sigma)l\}}{(1-\sigma)\{(2+\sigma)k+l\}}. \end{cases}$$

We put  $\varphi_i = \phi_i$  ( $i=1, 2$ ),  $\varphi_3 = (\phi_3 + \phi_4)/2$ ,  $\varphi_4 = (\phi_4 - \phi_3)/2$ . Then we see that

PROPOSITION 4.  $\tilde{R}$  has a period matrix of the form

$$\left( \int_{A_j} \varphi_i, \int_{B_j} \varphi_i \right) = \begin{pmatrix} 2b'_{11} & 2b'_{12} & b'_{13} & -b'_{13} \\ 2b'_{12} & 2b'_{22} & b'_{23} & -b'_{23} \\ b'_{13} & b'_{23} & (b'_{33} + \tau)/2 & -(b'_{33} - \tau)/2 \\ -b'_{13} & -b'_{23} & -(b'_{33} - \tau)/2 & (b'_{33} + \tau)/2 \end{pmatrix}$$

where  $b'_{ij}$  is that in (11) and  $\tau$  is the modulus of  $R$  with respect to the homology basis on  $R$  determined by the natural projection from  $\tilde{R} \rightarrow R$ .

PROPOSITION 5. The modulus  $\tau$  is  $\omega^2$  ( $\omega = \exp(2\pi i/3)$ ).

PROOF. The proof is a direct calculation.

PROPOSITION 6. There is a second order transformation of  $\mathfrak{S}_4$  which maps the period matrix of  $\tilde{R}$  to the matrix  $\begin{pmatrix} \Pi & 0 \\ 0 & \omega^2 \end{pmatrix}$  where

$$\Pi = \begin{pmatrix} b'_{11} & b'_{12} & b'_{13} \\ b'_{12} & b'_{22} & b'_{23} \\ b'_{13} & b'_{23} & b'_{33} \end{pmatrix} \in \mathfrak{S}_3.$$

PROOF. We take a second order transformation  $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix}$  of  $\mathfrak{S}_4$  where

$$A = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & 1 \end{pmatrix}, \quad B=C=0, \quad D = \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & 1 \end{pmatrix},$$

Summalizing above results, we have

THEOREM 2. *In case (II), the Prym variety  $P$  has a period matrix of the form  $(I_3, II)$  where  $II$  is that in Proposition 6, that is*

$$II = \frac{1}{2(1-\sigma)\{(2+\sigma)+z\}} \begin{pmatrix} (1+\sigma)+z & 1-\sigma^2 & 2 \\ 1-\sigma^2 & -3(1-\sigma) & 2(1-\sigma)(1+z) \\ 2 & 2(1-\sigma)(1+z) & 2\sigma+2\sigma(1-\sigma)z \end{pmatrix}$$

where  $z=l/k = \left(\int_{B_3} \omega_1\right) / \left(\int_{A_3} \omega_1\right)$ .

PROPOSITION 7.  $z$  is corresponding to the modulus of the surface  $\hat{R}: y^2 = (x-1-t)(x^2+x+1)$ .

PROOF.  $\tilde{R}/\langle T^2 \rangle$  is canonically isomorphic to  $\hat{R}$  and  $\omega_1$  is the holomorphic differential which corresponds to the differential of  $\hat{R}$  and  $A_3, B_3$  are the homology basis on  $\hat{R}$  determined by the natural projection from  $\tilde{R} \rightarrow \hat{R}$ .

CASE (III)  $\tilde{R}: y^4 = (x-1-t_1)(x-\rho(1+t_2))(x-\rho^2(1+t_3))(x-\rho^3)(x-\rho^4)$

$R: y^2 = (x-1-t_1)(x-\rho(1+t_2))(x-\rho^2(1+t_3))(x-\rho^3)(x-\rho^4)$

where  $1+t_1, \rho(1+t_2), \rho^2(1+t_3), \rho^3, \rho^4$  and  $\infty$  are distinct.

$$T: (x, y) \longrightarrow (x, iy).$$

Then  $\hat{R}$  is regarded as a double covering of  $R$  with the involution

$$T^2: (x, y) \longrightarrow (x, -y).$$

Since we can easily examine the divisors of differentials, we obtain a basis of the vector space of holomorphic differentials given by

$$\omega_1 = y^{-1}dx, \quad \omega_2 = y^{-3}dx, \quad \omega_3 = y^{-3}xdx, \quad \omega_4 = y^{-3}x^2dx,$$

$$\omega_5 = y^{-2}dx, \quad \omega_6 = y^{-2}xdx,$$

Then we see

$$(12) \quad \begin{cases} T\omega_1 = -i\omega_1, T\omega_i = i\omega_i, T\omega_j = -\omega_j \\ T^2\omega_1 = -\omega_1, T^2\omega_i = -\omega_i, T^2\omega_j = \omega_j \end{cases} \quad (i=2, 3, 4, j=5, 6)$$

namely,  $\omega_1, \omega_2, \omega_3$  and  $\omega_4$  are anti  $T^2$ -invariant differentials and  $\omega_5$  and  $\omega_6$  are  $T^2$ -invariant differentials. So  $\omega_1, \omega_2, \omega_3$  and  $\omega_4$  are differentials of Prym variety, and  $\omega_5$  and  $\omega_6$  are considered as differentials of  $R$  by the natural projection  $\tilde{R} \rightarrow R = \tilde{R}/\langle T^2 \rangle$ .

Here we construct a canonical homology basis on  $\tilde{R}$ . We consider the following closed curves  $\alpha, \beta, \gamma, \delta, \varepsilon$  and  $\zeta$  on  $x$ -sphere in Fig. 2.

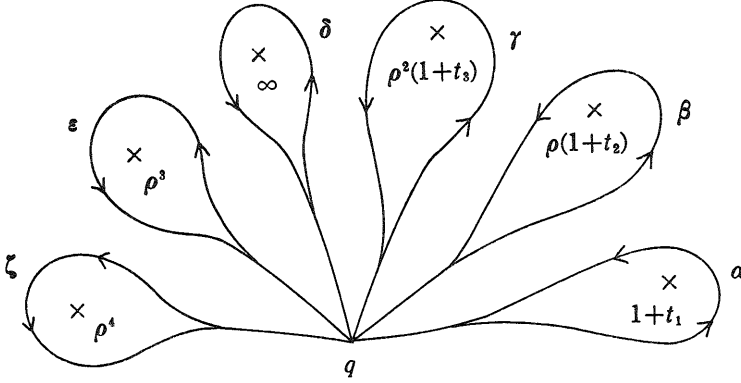


Fig. 2.

$y$  has four branches  $y_1, y_2 (=iy_1), y_3 (= -y_1)$  and  $y_4 (= -iy_1)$ . Let  $\alpha_i$  be the lifting of  $\alpha$  which is a path from  $y_i$ -branch to  $y_{i+1}$ -branch ( $i=1, 2, 3$ ) and  $\alpha_4$  be the lifting of  $\alpha$  from  $y_4$ -branch to  $y_1$ -branch. In the same way, let  $\beta_i, \gamma_i, \delta_i, \varepsilon_i$  and  $\zeta_i$  be the liftings of  $\beta, \gamma, \delta, \varepsilon$  and  $\zeta$ , respectively. Here we get the following relations

$$(13) \quad \begin{cases} \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 \sim 0, & \beta_1 + \beta_2 + \beta_3 + \beta_4 \sim 0, & \gamma_1 + \gamma_2 + \gamma_3 + \gamma_4 \sim 0 \\ \delta_1 + \delta_3 + \delta_2 + \delta_4 \sim 0, & \varepsilon_1 + \varepsilon_2 + \varepsilon_3 + \varepsilon_4 \sim 0, & \zeta_1 + \zeta_2 + \zeta_3 + \zeta_4 \sim 0 \\ \alpha_1 + \beta_2 + \gamma_3 + \delta_4 + \varepsilon_3 + \zeta_4 \sim 0, & \alpha_2 + \beta_3 + \gamma_4 + \delta_1 + \varepsilon_4 + \zeta_1 \sim 0 \\ \alpha_3 + \beta_4 + \gamma_1 + \delta_2 + \varepsilon_1 + \zeta_2 \sim 0, & \alpha_4 + \beta_1 + \gamma_2 + \delta_3 + \varepsilon_2 + \zeta_3 \sim 0 \end{cases}$$

Then a canonical homology basis is represented as follows

$$(14) \quad \begin{cases} A_1 = \zeta_4 + \zeta_1 - \gamma_1 - \gamma_4, & A_2 = \beta_3 + \beta_4 + \varepsilon_1 + \varepsilon_2, & A_3 = \alpha_1 - \beta_1 \\ A_4 = \gamma_1 + \delta_2, & A_5 = \alpha_3 - \beta_3, & A_6 = \gamma_3 + \delta_4 \\ B_1 = -\gamma_3 + \delta_3 + \varepsilon_2 + \beta_3 - \alpha_3 + \zeta_3, & B_2 = \beta_3 - \alpha_3 - \zeta_2 - \gamma_1 + \delta_1 - \varepsilon_3 \\ B_3 = \zeta_1 - \alpha_1, & B_4 = \varepsilon_1 - \gamma_1, & B_5 = \zeta_3 - \alpha_3, & B_6 = \varepsilon_3 - \gamma_3 \end{cases}$$

Here,  $A_3, B_3, A_4$  and  $B_4$  are considered as a canonical homology basis of  $R$  by the natural projection  $\hat{R} \rightarrow R$ . We illustrate this homology basis in Appendix.

Then, from (12), (13) and (14), we get the following

$$(15) \quad \begin{cases} T^2 A_1 \approx -A_1 & T^2 A_2 \approx -A_2 & T^2 A_3 \approx A_3 & T^2 A_4 \approx A_4 \\ T^2 B_1 \approx -B_1 & T^2 B_2 \approx -B_2 & T^2 B_3 \approx B_3 & T^2 B_4 \approx B_4 \end{cases}$$

$$(16) \quad \begin{cases} A_1 \approx A_3 + T A_3 - T A_4 - A_6 - T B_3 - T B_4 - 2B_5 - T B_6 - B_6 \\ A_2 \approx 2A_3 + T A_3 - A_4 - T A_4 + T A_5 - T B_3 - B_5 \\ B_1 \approx -T A_3 + T A_4 - A_5 + A_6 + T B_4 + B_5 + T B_6 + B_6 \\ B_2 \approx A_3 - T A_4 - A_5 + T A_6 - T B_3 - T B_4 - B_5 - B_6 \end{cases}$$

We put

$$\int_{A_j} \omega_i = a_{ij}, \quad \int_{B_j} \omega_i = b_{ij}.$$

From (15), we see that

$$\begin{aligned} a_{51} = a_{52} = a_{61} = a_{62} = 0, \quad a_{53} = a_{55}, \quad a_{54} = a_{56}, \quad a_{63} = a_{65}, \\ a_{64} = a_{66}, \quad a_{13} = -a_{15}, \quad a_{14} = -a_{16}, \quad a_{23} = -a_{25}, \quad a_{24} = -a_{26}, \\ a_{33} = -a_{35}, \quad a_{34} = -a_{36}, \quad a_{43} = -a_{45}, \quad a_{44} = -a_{46}. \end{aligned}$$

There are same relations in  $\{b_{ij}\}$ .

We put

$$\begin{aligned} \begin{pmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \\ a_{41} & a_{42} & a_{43} & a_{44} \end{pmatrix}^{-1} \begin{pmatrix} \omega_1 \\ \omega_2 \\ \omega_3 \\ \omega_4 \end{pmatrix} &= \begin{pmatrix} \phi_1 \\ \phi_2 \\ \phi_3 \\ \phi_4 \end{pmatrix}, \\ \begin{pmatrix} a_{53} & a_{54} \\ a_{63} & a_{64} \end{pmatrix}^{-1} \begin{pmatrix} \omega_5 \\ \omega_6 \end{pmatrix} &= \begin{pmatrix} \phi_5 \\ \phi_6 \end{pmatrix}, \quad \begin{pmatrix} a_{53} & a_{54} \\ a_{63} & a_{64} \end{pmatrix}^{-1} \begin{pmatrix} b_{53} & b_{54} \\ b_{63} & b_{64} \end{pmatrix} = (\pi_{ij}) = \pi \\ \begin{pmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \\ a_{41} & a_{42} & a_{43} & a_{44} \end{pmatrix}^{-1} \begin{pmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{pmatrix} &= \begin{pmatrix} 2b'_{11} & 2b'_{12} & b'_{13} & b'_{14} \\ 2b'_{21} & 2b'_{22} & b'_{23} & b'_{24} \\ 2b'_{31} & 2b'_{32} & b'_{33} & b'_{34} \\ 2b'_{41} & 2b'_{42} & b'_{43} & b'_{44} \end{pmatrix} \end{aligned}$$

where, from Riemann's equation,  $b'_{ij} = b'_{ji}$ ,  $\pi_{12} = \pi_{21}$ . Then

$$\left( \int_{A_j} \phi_i \right) = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \end{pmatrix}$$

$$\left( \int_{B_j} \phi_i \right) = \begin{pmatrix} 2b'_{11} & 2b'_{12} & b'_{13} & b'_{14} & -b'_{13} & -b'_{14} \\ 2b'_{12} & 2b'_{22} & b'_{23} & b'_{24} & -b'_{23} & -b'_{24} \\ 2b'_{13} & 2b'_{23} & b'_{33} & b'_{34} & -b'_{33} & -b'_{34} \\ 2b'_{14} & 2b'_{24} & b'_{34} & b'_{44} & -b'_{34} & -b'_{44} \\ 0 & 0 & \pi_{11} & \pi_{12} & \pi_{11} & \pi_{12} \\ 0 & 0 & \pi_{12} & \pi_{22} & \pi_{12} & \pi_{22} \end{pmatrix}.$$

We put

$$\phi_i = C_i \omega_1 + \check{\phi}_i \quad (i=1, 2, 3, 4)$$

where  $\check{\phi}_i$  are linear combinations of  $\omega_2$ ,  $\omega_3$  and  $\omega_4$ . Since  $C_i$  is the  $i$ -th entry of the first column of  $(a_{ij})^{-1}_{1 \leq i, j \leq 4}$ ,

$$a_{11}C_1 + a_{12}C_2 + a_{13}C_3 + a_{14}C_4 = 1.$$

We put

$$\int_{A_3} \omega_1 = a_{13} = k \quad \int_{A_4} \omega_1 = a_{14} = l$$

$$\int_{B_4} \omega_1 = b_{14} = m \quad \int_{B_4} \omega_1 = b_{14} = n.$$

Then

$$\int_{TA_3} \phi_i = \int_{TA_3} (C_i \omega_1 + \check{\phi}_i) = 2iC_i k - i \int_{A_3} \phi_i, \quad \int_{TA_4} \phi_i = 2iC_i l - i \int_{A_4} \phi_i$$

$$\int_{TB_3} \phi_i = 2iC_i m - i \int_{B_3} \phi_i, \quad \int_{TB_4} \phi_i = 2iC_i n - i \int_{B_4} \phi_i.$$

From (16), we see that

$$1 = \int_{A_1} \phi_1 = \int_{A_3} \phi_1 + \int_{TA_3} \phi_1 - \int_{TA_4} \phi_1 - \int_{A_6} \phi_1 - \int_{TB_3} \phi_1 - \int_{TB_4} \phi_1$$

$$- 2 \int_{B_5} \phi_1 - \int_{TB_5} \phi_1 - \int_{B_6} \phi_1$$

or

$$1=2iC_1(k-l-n)+2b'_{13}+(1+i)b'_{14}.$$

We have the following relations similarly,

$$\begin{aligned} 0 &= -2iC_1(l+m) + (1+i)b'_{12} \\ 2b'_{11} &= 2iC_1(-k+l-m+n) - (1-i)b'_{13} - (1+i)b'_{14} \\ 2b'_{12} &= -2iC_1(2l+m+n) + (1+i)(b'_{13}+b'_{14}) \\ 0 &= 2iC_2(k-l-n) + 2b'_{23} + (1+i)b'_{24} \\ 1 &= -2iC_2(l+m) + (1+i)b'_{23} \\ 2b'_{12} &= 2iC_2(-k+l-m+n) - (1-i)b'_{23} - (1+i)b'_{24} \\ 2b'_{22} &= -2iC_2(2l+m+n) + (1+i)(b'_{23}+b'_{24}) \\ 0 &= (1-i) + 2iC_3(k-l-n) + 2b'_{33} + (1+i)b'_{34} \\ 0 &= 2 - 2iC_3(l+m) + (1+i)b'_{33} \\ 2b'_{13} &= (1+i) + 2iC_3(-k+l-m+n) - (1-i)b'_{33} - (1+i)b'_{34} \\ 2b'_{23} &= 2 - 2iC_3(2l+m+n) + (1+i)(b'_{33}+b'_{34}) \\ 0 &= (1+i) + 2iC_4(k-l-n) + 2b'_{34} + (1+i)b'_{44} \\ 0 &= -(1-i) - 2iC_4(l+m) + (1+i)b'_{34} \\ 2b'_{14} &= -(1+i) + 2iC_4(-k+l-m+n) - (1-i)b'_{34} - (1+i)b'_{44} \\ 2b'_{24} &= 2i - 2iC_4(2l+m+n) + (1+i)(b'_{34}+b'_{44}) \end{aligned}$$

From the above relations, we have

$$(17) \left\{ \begin{array}{l} 2b'_{11} = -1 + 2i/s, \quad 2b'_{12} = 1 - 2ip/s, \quad b'_{13} = -iq/s \\ b'_{14} = (1-i)/2 - ir/s, \quad 2b'_{22} = i + 2ip^2/s, \quad b'_{23} = (1-i)/2 + ipq/s \\ b'_{24} = i + ipr/s, \quad b'_{33} = -(1-i) + iq^2/s, \quad b'_{34} = -i + iqr/s \\ b'_{44} = i + ir^2/s \\ \text{where } p = k/l + (1-i)m/l + (1-i) \\ q = -(1-i)m/l - (1-i) \\ r = (1-i)k/l - 2im/l - (1-i)n/l - (1+i) \\ s = -2p^2 - q^2 - 2pq + 4p - 2r - 2 \end{array} \right.$$

REMARK 1. In (17),  $p$ ,  $q$  and  $r$  are represented as other forms. Indeed, we put

$$\begin{pmatrix} a_{22} & a_{23} & a_{24} \\ a_{32} & a_{33} & a_{34} \\ a_{42} & a_{43} & a_{44} \end{pmatrix}^{-1} \begin{pmatrix} a_{21} \\ a_{31} \\ a_{41} \end{pmatrix} = \begin{pmatrix} p' \\ q' \\ r' \end{pmatrix}$$

then, we can find  $p=p'$ ,  $q=q'$  and  $r=r'$  by means of concrete calculation. Furthermore, we put

$$\begin{aligned} \Delta(\hat{A}_3, \hat{A}_4, \hat{B}_3) &= \det \begin{pmatrix} a_{23} & a_{24} & b_{23} \\ a_{33} & a_{34} & b_{33} \\ a_{43} & a_{44} & b_{43} \end{pmatrix}, & \Delta(\hat{A}_3, \hat{A}_4, \hat{B}_4) &= \det \begin{pmatrix} a_{23} & a_{24} & b_{24} \\ a_{33} & a_{34} & b_{34} \\ a_{43} & a_{44} & b_{44} \end{pmatrix} \\ \Delta(\hat{A}_3, \hat{B}_3, \hat{B}_4) &= \det \begin{pmatrix} a_{23} & b_{23} & b_{24} \\ a_{33} & b_{33} & b_{34} \\ a_{43} & b_{43} & b_{44} \end{pmatrix}, & \Delta(\hat{A}_4, \hat{B}_3, \hat{B}_4) &= \det \begin{pmatrix} a_{24} & b_{23} & b_{24} \\ a_{34} & b_{33} & b_{34} \\ a_{44} & b_{43} & b_{44} \end{pmatrix} \end{aligned}$$

Then, we see, by means of calculation,

$$(18) \quad \begin{cases} p = (1-i) + \frac{\Delta(\hat{A}_3, \hat{A}_4, \hat{B}_4)}{\Delta(\hat{A}_3, \hat{A}_4, \hat{B}_3)} \\ q = -(1-i) - 2 \frac{\Delta(\hat{A}_3, \hat{A}_4, \hat{B}_3)}{\Delta(\hat{A}_3, \hat{A}_4, \hat{B}_4)} + (1+i) \frac{\Delta(\hat{A}_4, \hat{B}_3, \hat{B}_4)}{\Delta(\hat{A}_3, \hat{A}_4, \hat{B}_3)} \\ r = (1-i) + (1-i) \frac{\Delta(\hat{A}_3, \hat{A}_4, \hat{B}_4)}{\Delta(\hat{A}_3, \hat{A}_4, \hat{B}_3)} - (1+i) \frac{\Delta(\hat{A}_4, \hat{B}_3, \hat{B}_4)}{\Delta(\hat{A}_3, \hat{A}_4, \hat{B}_3)} \end{cases}$$

or from (17)

$$(19) \quad \begin{cases} \frac{\Delta(\hat{A}_3, \hat{A}_4, \hat{B}_4)}{\Delta(\hat{A}_3, \hat{A}_4, \hat{B}_3)} = k/l + (1-i)m/l \\ \frac{\Delta(\hat{A}_4, \hat{B}_3, \hat{B}_4)}{\Delta(\hat{A}_3, \hat{A}_4, \hat{B}_3)} = (1-i)k/l - im/l \\ \frac{\Delta(\hat{A}_3, \hat{B}_3, \hat{B}_4)}{\Delta(\hat{A}_3, \hat{A}_4, \hat{B}_3)} = -in/l + (1-i) \end{cases}$$

We put

$$\varphi_i = \phi_i, \quad \varphi_{i+2} = (\phi_{i+2} + \phi_{i+4})/2, \quad \varphi_{i+4} = (\phi_{i+4} - \phi_{i+2})/2 \quad (i=1, 2).$$

Then we see that

PROPOSITION 8.  $\tilde{R}$  has a period matrix of the form

$$\left( \int_{A_j} \varphi_i, \int_{B_j} \varphi_i \right) = \begin{pmatrix} 2L & M & -M \\ I_6 & M & (\pi+S)/2 & (\pi-S)/2 \\ -M & (\pi-S)/2 & (\pi+S)/2 \end{pmatrix}$$



where

$$L = \begin{pmatrix} -1/2+i/s & 1/2-ip/s \\ 1/2-ip/s & i/2+ip^2/s \end{pmatrix}, \quad M = \begin{pmatrix} -iq/s & (1-i)/2-ir/s \\ (1-i)/2+ipq/s & i+ipr/s \end{pmatrix}$$

$$S = \begin{pmatrix} -(1-i)+iq^2/s & -i+iqr/s \\ -i+iqr/s & i+ir^2/s \end{pmatrix}, \quad \pi = \begin{pmatrix} \pi_{11} & \pi_{12} \\ \pi_{12} & \pi_{22} \end{pmatrix}.$$

Furthermore,  $\pi$  is the period matrix for  $R$  with respect to the homology basis on  $R$  determined by the natural projection  $\tilde{R} \rightarrow R$ .

PROPOSITION 9. *There is a second order transformation of  $\mathfrak{S}_6$  which maps the period matrix of  $\tilde{R}$  to the matrix*

$$\begin{pmatrix} \Pi & 0 \\ 0 & \pi \end{pmatrix} \quad \text{where} \quad \Pi = \begin{pmatrix} L & M \\ M & S \end{pmatrix} \in \mathfrak{S}_4.$$

PROOF. We take the second transformation  $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$  of  $\mathfrak{S}_6$  where

$$A = \begin{pmatrix} I_2 & 0 & 0 \\ 0 & I_2 & -I_2 \\ 0 & I_2 & I_2 \end{pmatrix}, \quad B = C = 0, \quad D = \begin{pmatrix} 2I_2 & 0 & 0 \\ 0 & I_2 & -I_2 \\ 0 & I_2 & I_2 \end{pmatrix}.$$

THEOREM 3. *In case (III), the Prym variety  $P$  has a period matrix of the form  $(I_4, \Pi)$  where  $\Pi$  is that in proposition 9, that is,*

$$\Pi = \begin{pmatrix} -1/2+i/s & 1/2-ip/s & -iq/s & (1-i)/2-ir/s \\ 1/2-ip/s & i/2+ip^2/s & (1-i)/2+ipq/s & i+ipr/s \\ -iq/s & (1-i)/2+ipq/s & -(1-i)+iq^2/s & -i+iqr/s \\ (1-i)/2-ir/s & i+ipr/s & -i+iqr/s & i+ir^2/s \end{pmatrix}.$$

REMARK 2.  $\Pi$  has three parameters  $p$ ,  $q$  and  $r$ . These parameters are independent, but the strict proof will be given at §2.

## §2. Kodaira-Spencer map and local injectivity.

First we recall the Kodaira-Spencer map associated with a deformation according to Sekiguchi's paper ([8], [4]).

Let  $S$  be a  $k$ -scheme,  $o \in S$  a  $k$ -rational point and  $\pi: X \rightarrow S$  be a smooth and proper morphism. Denote  $X_o$  the fibre over  $o \in S$ .

We have a short exact sequence of sheaves on  $X$ ;

$$0 \longrightarrow \mathcal{T}_{X/S} \longrightarrow \mathcal{T}_X \longrightarrow \pi^* \mathcal{T}_S \longrightarrow 0$$

defining the relative tangent sheaf  $\mathcal{T}_{X/S}$ . By restriction this to  $X_0$ , we obtain an exact sequence

$$0 \longrightarrow \mathcal{T}_{X_0} \longrightarrow \mathcal{T}_X \otimes_{\mathcal{O}_{X_0}} \longrightarrow \mathcal{T}_{S_0} \otimes_k \mathcal{O}_{X_0} \longrightarrow 0.$$

From the exact sequence of cohomology, we obtain the so-called Kodaira-Spencer map

$$\kappa: T_{S,0} \longrightarrow H^1(X_0, \mathcal{T}_{X_0}).$$

From now on, we will compute this map exactly in our cases by Sekiguchi's method.

CASE (I). In the above general theory,  $k=\mathbf{C}$

$$X = \tilde{R}_t: y^4 = (x-1-t)(x^2+x+1)$$

$$X_0 = \tilde{R}_0: y^4 = x^3 - 1$$

$$S = \text{Spec}(\mathbf{C}[t]/(t^2)).$$

A smooth model of  $\tilde{R}_t$  is given by

$$\tilde{R}_t = \mathcal{U}_t \cup \mathcal{V}_t$$

with

$$\mathcal{U}_t = \text{Spec}(\mathbf{C}[t][X, Y]/(Y^4 - (X^3 - 1) - t(X^2 + X + 1)))$$

$$= \text{Spec}(\mathbf{C}[t][x, y])$$

$$\mathcal{V}_t = \text{Spec}(\mathbf{C}[U, V]/(V^4 + U^4 - U + t(U^4 + U^3 + U^2)))$$

$$= \text{Spec}(\mathbf{C}[t][u, v])$$

and

$$\mathcal{U}_t \cap \mathcal{V}_t = \text{Spec}(\mathbf{C}[t][x, y, x^{-1}]) = \text{Spec}(\mathbf{C}[t][u, v, u^{-1}])$$

where 
$$\begin{cases} x = u^{-1} \\ y = u^{-1}v \end{cases} \quad \text{or} \quad \begin{cases} X = U^{-1} \\ Y = U^{-1}V \end{cases}$$

By using the Čech cohomology over the covering  $\{\mathcal{U}_t, \mathcal{V}_t\}$  of  $\tilde{R}_t$ , we can compute the cohomology groups  $H^i(\tilde{R}_t, \mathcal{T})$  for a coherent sheaf  $\mathcal{T}$  on  $\tilde{R}_t$ . In particular, we obtain the following:

LEMMA 1.

(i) A basis of  $H^0(\tilde{R}_t, \Omega_{\tilde{R}_t})$  is given by

$$\omega_1 = y^{-3} dx, \quad \omega_2 = y^{-3} x dx, \quad \omega_3 = y^{-2} dx.$$

(ii) A basis of  $H^0(\check{R}_t, \Omega^{\otimes 2})$  is given by

$$\begin{aligned}\Omega_1 = \omega_1^2 &= y^{-6}(dx)^2, & \Omega_2 = \omega_1\omega_2 &= y^{-6}x(dx)^2, & \Omega_3 = \omega_2^2 &= y^{-6}x^2(dx)^2, \\ \Omega_4 = \omega_3^2 &= y^{-4}(dx)^2, & \Omega_4 = \omega_1\omega_3 &= y^{-5}(dx)^2, & \Omega_6 = \omega_2\omega_3 &= y^{-5}x(dx)^2.\end{aligned}$$

(iii) A basis of  $H^1(\check{R}_t, \check{\Omega}_{\check{R}_t})$  is given by

$$\begin{aligned}\theta_1 &= x^{-1}y^6\partial_x, & \theta_2 &= x^{-2}y^6\partial_x, & \theta_3 &= x^{-3}y^6\partial_x, \\ \theta_4 &= x^{-1}y^4\partial_x, & \theta_5 &= x^{-1}y^5\partial_x, & \theta_6 &= x^{-2}y^5\partial_x,\end{aligned}$$

where  $\partial_x$  is the derivation on  $\mathbf{C}[x, y]$  defined by

$$\partial_x(x)=1, \quad \partial_x(y)=dy/dx.$$

PROOF. (i) is mentioned in §1. (ii) is asserted by Max Noether's theorem.

(iii) First, we have to compute  $H^1(\check{R}_t, \Omega_{\check{R}_t})$ . We see

$$\begin{aligned}\Gamma(\mathcal{O}_t, \Omega_{\check{R}_t}) &= \mathbf{C}[x, y]y^{-3}dx \quad \text{and} \quad \Gamma(\mathcal{C}\mathcal{V}_t, \Omega_{\check{R}_t}) = \mathbf{C}[u, v]v^{-3}du \\ \Gamma(\mathcal{O}_t, \Omega_{\check{R}_t}) \cap \Gamma(\mathcal{C}\mathcal{V}_t, \Omega_{\check{R}_t}) &= \mathbf{C}[x^{-1}, x^{-1}y]y^{-3}x dx.\end{aligned}$$

Therefore  $x^{-1}dx$  is a basis of  $H^1(\check{R}_t, \Omega_{\check{R}_t})$ . From Serre duality theorem, corresponding to a basis of  $H^0(\check{R}_t, \Omega^{\otimes 2})$ , we obtain

$$H^1(\check{R}_t, \check{\Omega}_{\check{R}_t}) = \langle x^{-1}y^6\partial_x, x^{-2}y^6\partial_x, x^{-3}y^6\partial_x, x^{-1}y^5\partial_x, x^{-2}y^5\partial_x, x^{-1}y^4\partial_x \rangle$$

where  $\check{\Omega}_{\check{R}_t}$  coincides the tangent sheaf  $\mathcal{T}_{\check{R}_t}$  of  $\check{R}_t$ .

We look for derivations over  $\mathbf{C}$ :

$$\mathcal{D}: \mathbf{C}[t][x, y] \longrightarrow \mathbf{C}[t][x, y] \quad \text{and} \quad \mathcal{D}: \mathbf{C}[t][u, v] \longrightarrow \mathbf{C}[t][u, v]$$

such that

$$\mathcal{D}(t)=1 \quad \text{and} \quad \tilde{\mathcal{D}}(t)=1.$$

If  $\mathcal{D}$  and  $\tilde{\mathcal{D}}$  are such derivations, then we get the following; Since

$$y^4 = x^3 - 1 - t(x^2 + x + 1) \quad \text{and} \quad v^4 = -u(u^3 - 1) - tu^2(u^2 + u + 1),$$

$$(1) \quad 4y^3\mathcal{D}(y) = \{3x^2 - t(2x + 1)\}\mathcal{D}(x) - (x^2 + x + 1),$$

$$(1') \quad 4v^3\tilde{\mathcal{D}}(v) = \{-4u^3 + 1 - tu(4u^2 + 3u + 2)\}\tilde{\mathcal{D}}(u) - u^2(u^2 + u + 1).$$

Put

$$(2) \quad \begin{cases} \mathcal{D}(x) = (A + By + Cy^2 + Dy^3) + (G + Hy + Jy^2 + Ky^3)t \\ \mathcal{D}(y) = (L + My + Ny^2 + Py^3) + (Q + Ry + Sy^2 + Ty^3)t \end{cases}$$

$$(2)' \quad \begin{cases} \tilde{\mathcal{D}}(u) = (\tilde{A} + \tilde{B}v + \tilde{C}v^2 + \tilde{D}v^3) + (\tilde{G} + \tilde{H}v + \tilde{J}v^2 + \tilde{K}v^3)t \\ \tilde{\mathcal{D}}(v) = (\tilde{L} + \tilde{M}v + \tilde{N}v^2 + \tilde{P}v^3) + (\tilde{Q} + \tilde{R}v + \tilde{S}v^2 + \tilde{T}v^3)t. \end{cases}$$

From (1), (2), (1') and (2'), we get

$$(3) \quad \begin{cases} 4M(x^3-1)=3Ax^2-(x^2+x+1) \\ 4N(x^3-1)=3Bx^2 \\ 4P(x^3-1)=3Cx^2 \\ 4L=3Dx^2 \\ -4M(x^2+x+1)+4R(x^3-1)=-A(2x+1)+3Gx^2 \\ -4N(x^2+x+1)+4S(x^3-1)=-B(2x+1)+3Hx^2 \\ -4P(x^2+x+1)+4T(x^3-1)=-C(2x+1)+3Jx^2 \\ 4Q=D(2x+1)+3Kx^2 \end{cases}$$

$$(3)' \quad \begin{cases} 4\tilde{M}(-u^4+u)=\tilde{A}(-4u^3+1)-(u^4+u^3+u^2) \\ 4\tilde{N}(-u^4+u)=\tilde{B}(-4u^3+1) \\ 4\tilde{P}(-u^4+u)=\tilde{C}(-4u^3+1) \\ 4\tilde{L}(-u^4+u)=\tilde{D}(-4u^3+1) \\ -4\tilde{M}(u^4+u^3+u^2)+4\tilde{R}(-u^4+u)=-\tilde{A}(4u^3+3u^2+2u)+\tilde{G}(-4u^3+1) \\ -4\tilde{N}(u^4+u^3+u^2)+4\tilde{S}(-u^4+u)=-\tilde{B}(4u^3+3u^2+2u)-\tilde{H}(-4u^3+1) \\ -4\tilde{P}(u^4+u^3+u^2)+4\tilde{T}(-u^4+u)=-\tilde{C}(4u^3+3u^2+2u)+\tilde{J}(-4u^3+1) \\ 4\tilde{Q}=-\tilde{D}(4u^3+3u^2+2u)+\tilde{K}(-4u^3+1) \end{cases}$$

In these equalities, we may put

$$B=C=D=H=J=K=N=P=L=S=T=Q=0$$

and

$$\tilde{B}=\tilde{C}=\tilde{D}=\tilde{H}=\tilde{J}=\tilde{K}=\tilde{N}=\tilde{P}=\tilde{L}=\tilde{S}=\tilde{T}=\tilde{Q}=0.$$

Then, we get

$$(4) \quad \begin{cases} 4M(x^3-1)=3Ax^2-(x^2+x+1) \\ -4M(x^2+x+1)+4R(x^3-1)=-A(2x+1)+3Gx^2 \end{cases}$$

$$(4)' \quad \begin{cases} 4\tilde{M}(-u^4+u)=\tilde{A}(-4u^3+1)-(u^4+u^3+u^2) \\ -4\tilde{M}(u^4+u^3+u^2)+4\tilde{R}(-u^4+u)=-\tilde{A}(4u^3+3u^2+2u)+\tilde{G}(-4u^3+1). \end{cases}$$

Here, we can put

$$(5) \quad \begin{cases} A=(x^2+x+1)/3, & M=(x+1)/4 \\ G=-(x^2+x+1)/3, & R=-(3x+2)/12, \end{cases}$$

$$(5') \quad \begin{cases} \tilde{A} = -u(u^2 + u + 1)/3, & \tilde{M} = -(4u^2 + 4u + 1)/12 \\ \tilde{G} = u(u-1)(u^2 + u + 1)/3, & \tilde{R} = (4u^3 + u - 1)/12. \end{cases}$$

Therefore, by (2), (2'), (5) and (5'), we get

$$(6) \quad \begin{cases} \mathcal{D}(x) = (x^2 + x + 1)/3 - (x^2 + x + 1)t/3 \\ \mathcal{D}(y) = (x+1)y/4 - (3x+2)yt/12 \end{cases}$$

$$(6') \quad \begin{cases} \tilde{\mathcal{D}}(u) = -u(u^2 + u + 1)/3 + u(u-1)(u^2 + u + 1)t/3 \\ \tilde{\mathcal{D}}(v) = -u(4u^2 + 4u + 1)v/12 + (4u^3 + u - 1)vt/12. \end{cases}$$

Now we put

$$\bar{\mathcal{D}} = \mathcal{D} \pmod{t} \quad \bar{\tilde{\mathcal{D}}} = \tilde{\mathcal{D}} \pmod{t}$$

Then we get

$$\begin{aligned} \bar{\mathcal{D}}(x) &= \bar{\mathcal{D}}(u^{-1}) = -u^{-2}\bar{\mathcal{D}}(u) = (u+1+u^{-1})/3 = (x+1+x^{-1})/3 \\ \bar{\tilde{\mathcal{D}}}(y) &= \bar{\tilde{\mathcal{D}}}(u^{-1}v) = u^{-2}\{u\bar{\tilde{\mathcal{D}}}(v) - v\bar{\tilde{\mathcal{D}}}(u)\} = (4u)^{-1}v = y/4. \end{aligned}$$

Hence on  $\mathcal{V}_0 \cap \mathcal{V}_0$ , we get

$$(7) \quad \begin{cases} (\bar{\mathcal{D}} - \bar{\tilde{\mathcal{D}}})(x) = (x^2 + x + 1)/3 - (x+1+x^{-1})/3 = (x^2 - x^{-1})/3 = y^4/3x \\ (\bar{\mathcal{D}} - \bar{\tilde{\mathcal{D}}})(y) = (x+1)y/4 - y/4 = xy/4 = (y^4/3x)(dy/dx) \end{cases}$$

Here, we notice that

$$\kappa((\partial/\partial t)_0) = (\bar{\mathcal{D}} - \bar{\tilde{\mathcal{D}}}) \in H^1(\tilde{R}_0, \mathcal{F}_{R_0})$$

and from (7),

$$\bar{\mathcal{D}} - \bar{\tilde{\mathcal{D}}} = (3x)^{-1}y^4\partial_x.$$

Therefore, from lemma 1 (iii), we could prove the following

**THEOREM 4.** *The Kodaira-Spencer map  $\kappa: T_{S,0} \rightarrow H^1(\tilde{R}_0, \mathcal{F}_{\tilde{R}_0})$  is given by*

$$(8) \quad \kappa((\partial/\partial t)_0) = (3x)^{-1}y^4\partial_x = \theta_4/3.$$

**REMARK 3.** Theorem 4 is an alternative proof of the fact that there is no contribution of the parameter  $t$  to Prym variety (This is a direct result of Theorem 1). Indeed, from Serre duality,  $\theta_4$  corresponds to  $\Omega_4$  which is a quadratic differential for  $R$ , while  $\Omega_4 = \omega_3^2$  does not corresponds to Prym variety since  $\omega_3$  is not a Prym differential.

$$\text{CASE (II)} \quad X = \tilde{R}_t: y^6 = (x-1-t)(x^2+x+1)$$

$$X_0 = \tilde{R}_0: y^6 = x^3 - 1$$

$$S = \text{Spec}(\mathbf{C}[t]/(t^2))$$

A smooth model of  $\check{R}_t$  is given by

$$\check{R}_t = \mathcal{U}_t \cup \mathcal{CV}_t$$

with

$$\begin{aligned} \mathcal{U}_t &= \text{Spec}(\mathbf{C}[t][X, Y]/(Y^6 - (X^3 - 1) + t(X^2 + X + 1))) \\ &= \text{Spec}(\mathbf{C}[t][x, y]) \end{aligned}$$

$$\begin{aligned} \mathcal{CV}_t &= \text{Spec}(\mathbf{C}[t][U, V]/(1 - (V^3 - U^6) + t(V^2U^2 + VU^4 + U^6))) \\ &= \text{Spec}(\mathbf{C}[t][u, v]) \end{aligned}$$

and

$$\mathcal{U}_t \cap \mathcal{CV}_t = \text{Spec}(\mathbf{C}[t][x, y, y^{-1}]) = \text{Spec}(\mathbf{C}[t][u, v, u^{-1}])$$

where

$$x = u^{-2}v \quad y = u^{-1}.$$

LEMMA 2.

(i) A basis of  $H^0(\check{R}_t, \Omega_{\check{R}_t})$  is given by

$$\omega_1 = y^{-3}dx, \quad \omega_2 = y^{-6}dx, \quad \omega_3 = y^{-5}xdx, \quad \omega_4 = y^{-4}dx$$

(iii) A basis of  $H^0(\check{R}_t, \Omega^{\otimes 2})$  is given by

$$\begin{aligned} \Omega_1 = \omega_1^2 &= y^{-6}(dx)^2, & \Omega_2 = \omega_1\omega_2 &= y^{-9}(dx)^2, & \Omega_3 = \omega_1\omega_3 &= y^{-8}x(dx)^2 \\ \Omega_4 = \omega_2^2 &= y^{-12}(dx)^2, & \Omega_5 = \omega_2\omega_3 &= y^{-11}x(dx)^2, & \Omega_6 = \omega_3^2 &= y^{-10}x^2(dx)^2 \\ \Omega_7 = \omega_1\omega_4 &= y^{-7}(dx)^2, & \Omega_8 = \omega_2\omega_4 &= y^{-10}(dx)^2, & \Omega_9 = \omega_3\omega_4 &= y^{-9}x(dx)^2 \end{aligned}$$

(iii) A basis of  $H^1(\check{R}_t, \check{\Omega}_{\check{R}_t})$  is given by

$$\begin{aligned} \theta_1 &= x^2\partial_x, & \theta_2 &= x^2y^2\partial_x, & \theta_3 &= xy^2\partial_x \\ \theta_4 &= x^2y^4\partial_x, & \theta_5 &= xy^4\partial_x, & \theta_6 &= y^4\partial_x \\ \theta_7 &= x^2y\partial_x, & \theta_8 &= x^2y^3\partial_x, & \theta_9 &= xy^3\partial_x \end{aligned}$$

PROOF. The proof of the above is the same as the lemma 1 and is therefore omitted.

We look for derivations over  $\mathbf{C}$

$$\mathcal{D} : \mathbf{C}[t][x, y] \longrightarrow \mathbf{C}[t][x, y] \quad \text{and} \quad \check{\mathcal{D}} : \mathbf{C}[t][u, v] \longrightarrow \mathbf{C}[t][u, v]$$

Since

$$y^6 = x^3 - 1 - t(x^2 + x + 1) \quad \text{and} \quad v^3 = u^6 + 1 + t(u^2v^2 + u^4v + u^8),$$

we get the following

$$(9) \quad 6y^5\mathcal{D}(y) = \{3x^2 - t(2x + 1)\}\mathcal{D}(x) - (x^2 + x + 1)$$

and

$$(9') \quad \{3v^2 - t(2u^2v + u^4)\} \tilde{\mathcal{D}}(v) = \{6u^5 + t(2uv^2 + 4u^3v + 6u^5)\} \tilde{\mathcal{D}}(u) + (u^2v^2 + u^4v + u^6).$$

Put

$$(10) \quad \begin{cases} \mathcal{D}(x) = A + By + Cy^2 + Dy^3 + Ey^4 + Fy^5 + t(G + Hy + Iy^2 + Jy^3 + Ky^4 + Ly^5) \\ \mathcal{D}(y) = M + Ny + Oy^2 + Py^3 + Qy^4 + Ry^5 + t(S + Ty + Uy^2 + Vy^3 + Wy^4 + Zy^5) \end{cases}$$

$$(10') \quad \begin{cases} \tilde{\mathcal{D}}(u) = \tilde{A} + \tilde{B}v + \tilde{C}v^2 + t(\tilde{D} + \tilde{E}v + \tilde{F}v^2) \\ \tilde{\mathcal{D}}(v) = \tilde{G} + \tilde{H}v + \tilde{I}v^2 + t(\tilde{J} + \tilde{K}v + \tilde{L}v^2) \end{cases}$$

From (9), (10), (9') and (10'), we get

$$(11) \quad \begin{cases} 6N(x^3-1) = 3Ax^2 - (x^2 + x + 1) \\ 6O(x^3-1) = 3Bx^2 \\ 6P(x^3-1) = 3Cx^2 \\ 6Q(x^3-1) = 3Dx^2 \\ 6R(x^3-1) = 3Ex^2 \\ 6M = 3Fx^2 \\ -6N(x^2 + x + 1) + 6T(x^3-1) = -A(2x+1) + 3Gx^2 \\ -6O(x^2 + x + 1) + 6U(x^3-1) = -B(2x+1) + 3Hx^2 \\ -6P(x^2 + x + 1) + 6V(x^3-1) = -C(2x+1) + 3Ix^2 \\ -6Q(x^2 + x + 1) + 6W(x^3-1) = -D(2x+1) + 3Jx^2 \\ -6R(x^2 + x + 1) + 6Z(x^3-1) = -E(2x+1) + 3Kx^2 \\ 6S = -F(2x+1) + 3Lx^2 \\ 3\tilde{H}(u^6+1) = 6\tilde{A}u^5 + u^6 \\ 3\tilde{I}(u^6+1) = 6\tilde{B}u^5 + u^4 \\ 3\tilde{G} = 6\tilde{C}u^5 + u^2 \\ -\tilde{G}u^4 + 3\tilde{H}u^6 + \tilde{I}u^2(u^6+1) + 3\tilde{K}(u^6+1) \\ \quad = 6\tilde{A}u^5 + 2\tilde{B}u(u^6+1) + 4\tilde{C}u^3(u^6+1) + 6\tilde{D}u^6 \\ -2\tilde{G}u^2 + 2\tilde{H}u^4 + 3\tilde{I}u^6 + 3\tilde{L}(u^6+1) = 4\tilde{A}u^3 + 6\tilde{B}u^5 + 2\tilde{C}u + 6\tilde{E}u^5 \\ \tilde{H}u^2 + 2\tilde{I}u^4 + 3\tilde{J} = 2\tilde{A}u + 4\tilde{B}u^3 + 6\tilde{C}u^5 + 6\tilde{F}u^5 \end{cases}$$

In these we may put

$$B = C = D = E = F = H = I = J = K = L = 0$$

$$M = O = P = Q = R = S = U = V = W = Z = 0$$

and

$$\check{C} = \check{F} = \check{J} = 0.$$

Moreover we can put

$$(12) \quad \begin{cases} A = (x^2 + x + 1)/3, & G = -(x^2 + x + 1)/3 \\ N = (x + 1)/6, & T = -(3x + 2)/18 \end{cases}$$

$$(12') \quad \begin{cases} \tilde{A} = u^7/6, & \tilde{B} = u^5/6, & \tilde{D} = u^7/18, & \tilde{G} = u^2/3 \\ \tilde{H} = u^6/3, & \tilde{I} = u^4/3, & \tilde{K} = u^6/9, & \tilde{L} = 2u^4/9. \end{cases}$$

Therefore, by (10), (10'), (12) and (12'), we get

$$(13) \quad \begin{cases} \mathcal{D}(x) = (x^2 + x + 1)/3 - (x^2 + x + 1)t/3 \\ \mathcal{D}(y) = (x + 1)(y/6 - (3x + 2)yt/18) \end{cases}$$

$$(13') \quad \begin{cases} \tilde{\mathcal{D}}(u) = (u^7 + u^5v)/6 + (u^7 + 2u^5v)t/18 \\ \tilde{\mathcal{D}}(v) = (u^2 + u^6v + u^4v^2)/3 + (2u^4v + u^6v^2)t/9. \end{cases}$$

Now we put

$$\bar{\mathcal{D}} \equiv \mathcal{D}, \quad \check{\mathcal{D}} \equiv \tilde{\mathcal{D}} \pmod{t}.$$

Then, we get

$$\check{\mathcal{D}}(x) = \check{\mathcal{D}}(u^{-2}v) = u^{-3} \{u\check{\mathcal{D}}(v) - 2v\check{\mathcal{D}}(u)\} = 1/3$$

$$\check{\mathcal{D}}(y) = -u^{-2}\check{\mathcal{D}}(u) = -(x+1)y^{-5}/6$$

Hence on  $\mathcal{U}_0 \cap \mathcal{V}_0$ , we get

$$(14) \quad \begin{cases} (\bar{\mathcal{D}} - \check{\mathcal{D}})(x) = (x^2 + x)/3 \\ (\bar{\mathcal{D}} - \check{\mathcal{D}})(y) = (x^2/3)(dy/dx) + (x/3)(dy/dx). \end{cases}$$

Here  $\kappa((\partial/\partial t)_0) = \bar{\mathcal{D}} - \check{\mathcal{D}}$  is determined by the part  $(x^2/3)\partial_x$  and  $(x/3)\partial_x$  is a boundary component from lemma 2, (iii). Therefore, we could prove the following

**THEOREM 5.** *The Kodaira-Spencer map  $\kappa: T_{S,0} \rightarrow H^1(\hat{R}_0, \mathcal{F}_{\hat{R}_0})$  is given by*

$$(15) \quad \kappa((\partial/\partial t)_0) = (x^2/3)\partial_x = \theta_1/3.$$

**REMARK 4.** Theorem 5 shows that there is the contribution of the parameter  $t$  to Prym variety. Indeed, from Serre duality,  $\theta_1$  corresponds to  $\Omega_1$  which is the quadratic differential for  $\hat{R}$ , and  $\Omega_1 = \omega_1^2$  corresponds to Prym since  $\omega_1$  is a Prym differential.

CASE (III)



$$X = \tilde{R}_{t_1, t_2, t_3} : y^4 = (x-1-t_1)(x-\rho-\rho t_2)(x-\rho^2-\rho^2 t_3)(x-\rho^3)(x-\rho^4)$$

$$X_0 = \tilde{R}_{0,0,0} : y^4 = x^5 - 1$$

$$S = \text{Spec}(\mathbf{C}[[t_1, t_2, t_3]])$$

For our purpose, we may consider  $\tilde{R}_{t_1, 0, 0}$ ,  $\tilde{R}_{0, t_2, 0}$  and  $\tilde{R}_{0, 0, t_3}$  separately. So we reset

$$X = \tilde{R}_{t_1, 0, 0} = \tilde{R}_{t_1} : y^4 = (x-1-t_1)(x^4 + x^3 + x^2 + x + 1)$$

$$S = \text{Spec}(\mathbf{C}[t_1]/(t_1^2))$$

A smooth model of  $\tilde{R}_{t_1}$  is given by

$$\tilde{R}_{t_1} = \mathcal{U}_{t_1} \cup \mathcal{C}\mathcal{V}_{t_1}$$

with

$$\begin{aligned} \mathcal{U}_{t_1} &= \text{Spec}(\mathbf{C}[t_1][X, Y]/(Y^4 - (X^5 - 1) + t_1(X^4 + X^3 + X^2 + X + 1))) \\ &= \text{Spec}(\mathbf{C}[t_1][x, y]) \end{aligned}$$

$$\begin{aligned} \mathcal{C}\mathcal{V}_{t_1} &= \text{Spec}(\mathbf{C}[t_1][U, V]/(U - V^5 + U^5 + t_1(UV^4 + U^2V^3 + U^3V^2 + U^4V + U^5))) \\ &= \text{Spec}(\mathbf{C}[t_1][u, v]) \end{aligned}$$

and

$$\mathcal{U}_{t_1} \cap \mathcal{C}\mathcal{V}_{t_1} = \text{Spec}(\mathbf{C}[t_1][x, y, y^{-1}]) = \text{Spec}(\mathbf{C}[t_1][u, v, u^{-1}])$$

where

$$x = u^{-1}v \quad y = u^{-1}$$

LEMMA 3.

(i) A basis of  $H^0(X, \Omega_X)$  is given by

$$\begin{aligned} \omega_1 &= y^{-1}dx, & \omega_2 &= y^{-3}dx, & \omega_3 &= y^{-3}xdx \\ \omega_4 &= y^{-3}x^2dx, & \omega_5 &= y^{-2}dx, & \omega_6 &= y^{-2}xdx \end{aligned}$$

(ii) A basis of  $H^0(X, \Omega_X^{\otimes 2})$  is given by

$$\begin{aligned} \Omega_1 &= \omega_1^2 = y^{-2}(dx)^2, & \Omega_2 &= \omega_1\omega_2 = y^{-4}(dx)^2, & \Omega_3 &= \omega_1\omega_3 = y^{-4}x(dx)^2 \\ \Omega_4 &= \omega_1\omega_4 = y^{-4}x^2(dx)^2, & \Omega_5 &= \omega_2^2 = y^{-6}(dx)^2, & \Omega_6 &= \omega_2\omega_3 = y^{-6}x(dx)^2 \\ \Omega_7 &= \omega_2\omega_4 = y^{-6}x^2(dx)^2, & \Omega_8 &= \omega_3\omega_4 = y^{-6}x^3(dx)^2, & \Omega_9 &= \omega_4^2 = y^{-6}x^4(dx)^2 \\ \Omega_{10} &= \omega_1\omega_5 = y^{-3}(dx)^2, & \Omega_{11} &= \omega_1\omega_6 = y^{-3}x(dx)^2, & \Omega_{12} &= \omega_2\omega_5 = y^{-5}(dx)^2 \\ \Omega_{13} &= \omega_2\omega_6 = y^{-5}x(dx)^2, & \Omega_{14} &= \omega_3\omega_6 = y^{-5}x^2(dx)^2, & \Omega_{15} &= \omega_4\omega_6 = y^{-5}x^3(dx)^2 \end{aligned}$$

(iii) A basis of  $H^1(X, \check{\Omega}_X)$  is given by

$$\theta_1 = y^{-2}x^4\partial_x, \quad \theta_2 = x^4\partial_x, \quad \theta_3 = x^3\partial_x, \quad \theta_4 = x^2\partial_x, \quad \theta_5 = x^4y^2\theta_x$$

$$\begin{aligned}\theta_6 &= x^3 y^2 \partial_x, & \theta_7 &= x^2 y^2 \partial_x, & \theta_8 &= x y^2 \partial_x, & \theta_9 &= y^2 \partial_x, & \theta_{10} &= y^{-1} x^4 \partial_x \\ \theta_{11} &= y^{-1} x^3 \partial_x, & \theta_{12} &= x^4 y \partial_x, & \theta_{13} &= x^3 y \partial_x, & \theta_{14} &= x^2 y \partial_x, & \theta_{15} &= x y \partial_x\end{aligned}$$

PROOF. The proof is omitted as lemma 2.

We look for derivations over  $\mathbf{C}$

$$\mathcal{D}_1: \mathbf{C}[t_1][x, y] \longrightarrow \mathbf{C}[t_1][x, y], \quad \tilde{\mathcal{D}}_1: \mathbf{C}[t_1][u, v] \longrightarrow \mathbf{C}[t_1][u, v]$$

such that

$$\mathcal{D}_1(t_1) = 1, \quad \tilde{\mathcal{D}}_1(t_1) = 1.$$

Since

$$y^4 = (x^5 - 1) - t_1(x^4 + x^3 + x^2 + x + 1)$$

and

$$v^5 = u^5 + u + t_1(uv^4 + u^2v^3 + u_6v^2 + u^4v + u^5),$$

we get the following

$$(16) \quad 4y^3 \mathcal{D}_1(y) = \{5x^4 - t_1(4x^3 + 3x^2 + 2x + 1)\} \mathcal{D}_1(x) - (x^4 + x^3 + x^2 + x + 1)$$

$$(16') \quad \{5v^4 - t_1(4uv^3 + 3u^2v^2 + 2u^3v + u^4)\} \tilde{\mathcal{D}}_1(v) - (uv^4 + u^2v^3 + u^3v^2 + u^4v + u^5) \\ = \{(5u^4 + 1) + t_1(v^4 + 2uv^3 + 3u^2v^2 + 4u^3v + 5u^4)\} \tilde{\mathcal{D}}_1(u)$$

Put

$$(17) \quad \begin{cases} \mathcal{D}_1(x) = A + B y + C y^2 + D y^3 + t_1(E + F y + G y^2 + H y^3) \\ \mathcal{D}_1(y) = I + J y + K y^2 + L y^3 + t_1(M + N y + P y^2 + Q y^3) \end{cases}$$

$$(17') \quad \begin{cases} \tilde{\mathcal{D}}_1(u) = \tilde{A} + \tilde{B} v + \tilde{C} v^2 + \tilde{D} v^3 + \tilde{R} v^4 + t_1(\tilde{E} + \tilde{F} v + \tilde{G} v^2 + \tilde{H} v^3 + \tilde{S} v^4) \\ \tilde{\mathcal{D}}_1(v) = \tilde{I} + \tilde{J} v + \tilde{K} v^2 + \tilde{L} v^3 + \tilde{W} v^4 + t_1(\tilde{M} + \tilde{N} v + \tilde{P} v^2 + \tilde{Q} v^3 + \tilde{Z} v^4). \end{cases}$$

From (16), (17), (16') and (17'), we get

$$(18) \quad \begin{cases} 4J(x^5 - 1) = 5Ax^4 - (x^4 + x^3 + x^2 + x + 1) \\ 4K(x^5 - 1) = 5Bx^4 \\ 4L(x^5 - 1) = 5Cx^4 \\ 4I = 5Dx^4 \\ -4J(x^4 + x^3 + x^2 + x + 1) + 4N(x^5 - 1) = -A(4x^3 + 3x^2 + 2x + 1) + 5Ex^4 \\ -4K(x^4 + x^3 + x^2 + x + 1) + 4P(x^5 - 1) = -B(4x^3 + 3x^2 + 2x + 1) + 5Fx^4 \\ -4L(x^4 + x^3 + x^2 + x + 1) + 4Q(x^5 - 1) = -C(4x^3 + 3x^2 + 2x + 1) + 5Gx^4 \\ 4M = -D(4x^3 + 3x^2 + 2x + 1) + 5Hx^4 \end{cases}$$

$$(18') \left\{ \begin{array}{l} \tilde{A}(5u^4+1)+u^5=5\tilde{J}(u^5+u) \\ \tilde{B}(5u^4+1)+u^4=5\tilde{K}(u^5+u) \\ \tilde{C}(5u^4+1)+u^3=5\tilde{L}(u^5+u) \\ \tilde{D}(5u^4+1)+u^2=5\tilde{W}(u^5+u) \\ \tilde{R}(5u^4+1)+u=5\tilde{I} \\ 5\tilde{A}u^4+\tilde{B}(u^5+u)+2\tilde{C}u(u^5+u)+3\tilde{D}u^2(u^5+u)+4\tilde{R}u^3(u^5+u)+\tilde{E}(5u^4+1) \\ \quad =-Iu^4+5\tilde{J}u^5+\tilde{K}u(u^5+u)+2\tilde{L}u^2(u^5+u)+3\tilde{W}u^3(u^5+u)+5\tilde{N}(u^5+u) \\ 4\tilde{A}u^3+5\tilde{B}u^4+\tilde{C}(u^5+u)+2\tilde{D}u(u^5+u)+3\tilde{R}u^2(u^5+u)+\tilde{F}(5u^4+1) \\ \quad =-2\tilde{I}u^3+4\tilde{J}u^4+5\tilde{K}u^5+\tilde{L}u(u^5+u)+2\tilde{W}u^2(u^5+u)+5\tilde{P}(u^5+u) \\ 3\tilde{A}u^2+4\tilde{B}u^3+5\tilde{C}u^5+\tilde{D}(u^5+u)+2\tilde{R}u(u^5+u)+\tilde{G}(5u^4+1) \\ \quad =-3\tilde{I}u^2+3\tilde{J}u^3+4\tilde{K}u^4+5\tilde{L}u^5+\tilde{W}u(u^5+u)+5\tilde{Q}(u^5+u) \\ 2\tilde{A}u+3\tilde{B}u^2+4\tilde{C}u^3+5\tilde{D}u^4+\tilde{R}(u^5+u)+\tilde{H}(5u^4+1) \\ \quad =-4\tilde{I}u+2\tilde{J}u^2+3\tilde{K}u^3+4\tilde{L}u^4+5\tilde{W}u^5+5\tilde{Z}(u^5+u) \\ \tilde{A}+2\tilde{B}u+3\tilde{C}u^2+4\tilde{D}u^3+5\tilde{R}u^4+\tilde{S}(5u^4+1) \\ \quad =\tilde{J}u+2\tilde{K}u^2+3\tilde{L}u^3+4\tilde{W}u^4+5\tilde{M} \end{array} \right.$$

In these equalities, we may put

$$(19) \left\{ \begin{array}{l} A=(x^4+x^3+x^2+x+1)/5 \quad J=(x^3+x^2+x+1)/4 \\ N=-(10x^3+9x^2+7x+4)/20 \quad E=-2(x^4+x^3+x^2+x+1)/5 \\ B=C=D=F=G=H=I=K=L=M=P=Q=0 \end{array} \right.$$

$$(19') \left\{ \begin{array}{l} \tilde{A}=u^5/4 \quad \tilde{B}=u^4/4 \quad \tilde{C}=u^3/4 \quad \tilde{D}=u^2/4 \quad \tilde{R}=-u \\ \tilde{J}=u^4/4 \quad \tilde{K}=u^3/4 \quad \tilde{L}=u^2/4 \quad \tilde{W}=u/4 \quad \tilde{I}=-u^5 \\ \tilde{E}=u^5/4 \quad \tilde{F}=u^4/2 \quad \tilde{G}=3u^3/4 \quad \tilde{H}=u^2 \quad \tilde{Z}=0 \\ \tilde{S}=0 \quad \tilde{M}=-u^5. \end{array} \right.$$

Therefore, by (17), (17'), (19) and (19'), we get

$$(20) \left\{ \begin{array}{l} \mathcal{D}_1(x)=(x^4+x^3+x^2+x+1)/5-2t_1(x^4+x^3+x^2+x+1)/5 \\ \mathcal{D}_1(y)=(x^3+x^2+x+1)y/4-t_1(10x^3+9x^2+7x+4)y/20 \end{array} \right.$$

$$(20') \left\{ \begin{array}{l} \mathcal{D}_1(u)=(u^5+u^4v+u^3v^2+u^2v^3-4uv^4)/4+t_1(u^5+2u^4v+3u^3v^2+4u^2v^3)/4 \\ \mathcal{D}_1(v)=(-4u^5+u^4v+u^3v^2+u^2v^3+uv^4)/4+t_1(-4u^5-3u^4v-2u^3v^2-u^2v^3)/4 \end{array} \right.$$

Now we put

$$\bar{\mathcal{D}}_1 \equiv \mathcal{D}_1 \quad \bar{\mathcal{D}}_1 \equiv \bar{\mathcal{D}}_1 \pmod{t_1}.$$

Then we get

$$\begin{aligned} \bar{\mathcal{D}}_1(x) &= \bar{\mathcal{D}}(uv^{-1}) = u^{-2} \{u\bar{\mathcal{D}}_1(v) - v\bar{\mathcal{D}}_1(u)\} \\ &= u^{-2} \{(-4u^6 + u^5v + u^4v^2 + u^2v^3 + u^2v^4) - (u^5v + u^4v^2 + u^3v^3 + u^2v^4 - 4uv^5)\} / 4 \\ &= -u^4 + u^{-1}v^5 = -u^4 + u^{-1}(u^5 + u) = 1 \\ \bar{\mathcal{D}}_1(y) &= \bar{\mathcal{D}}_1(u^{-1}) = -u^{-2}\bar{\mathcal{D}}_1(u) = -(1+x+x^2+x^3-4x^4)y^{-3}/4. \end{aligned}$$

Hence on  $\mathcal{V}_0 \cap \mathcal{V}_0$ , we get

$$(21) \quad \begin{cases} (\bar{\mathcal{D}}_1 - \bar{\mathcal{D}}_1)(x) = (x^4 + x^3 + x^2)/5 + (x-4)/5 \\ (\bar{\mathcal{D}}_1 - \bar{\mathcal{D}}_1)(y) = (x^3 + x^2 + x + 1)y/4 + (1+x+x^2+x^3-4x^4)y^{-3}/4 \\ \quad \quad \quad = (x^4 + x^3 + x^2)(5x^4)(4y^3)^{-1}/5 + (x-4)(5x^4)(4y^3)^{-1}/5 \end{cases}$$

Hence  $\kappa((\partial/\partial t_1)_0) = \bar{\mathcal{D}}_1 - \bar{\mathcal{D}}_1$  is determined by the part  $(x^4 + x^3 + x^2)\partial_x/5$  and  $(x-4)\partial_x/5$  is a boundary component from lemma 3 (iii), that is

$$(22) \quad \kappa((\partial/\partial t_1)_0) = (x^4 + x^3 + x^2)\partial_x/5 = (\theta_2 + \theta_3 + \theta_4)/5.$$

Next, we reset

$$X = \tilde{R}_{0, t_2, 0} = \tilde{R}_{t_2}: y^4 = (x-1)(x-\rho-\rho t_2)(x-\rho^2)(x-\rho^3)(x-\rho^4).$$

This equation is obtained by setting

$$x = \rho X, \quad y = Y \quad \text{and} \quad t_2 = t_1$$

in the equation of  $\tilde{R}_{t_1, 0, 0}: Y^4 = (X-1-t_1)(X-\rho)(X-\rho^2)(X-\rho^3)(X-\rho^4)$ . Hence,  $\bar{\mathcal{D}}_2$  and  $\bar{\mathcal{D}}_2$  which are corresponding derivations to  $\tilde{R}_{t_2}$  must satisfy the following

$$\begin{aligned} (\bar{\mathcal{D}}_2 - \bar{\mathcal{D}}_2)(x) &= (\bar{\mathcal{D}}_1 - \bar{\mathcal{D}}_1)(\rho X) = \rho(\bar{\mathcal{D}}_1 - \bar{\mathcal{D}}_1)(X) = \rho(X^4 + X^3 + X^2)/5 \\ &= (\rho^2 x^4 + \rho^3 x^3 + \rho^4 x^2)/5 \\ (\bar{\mathcal{D}}_2 - \bar{\mathcal{D}}_2)(y) &= (\bar{\mathcal{D}}_1 - \bar{\mathcal{D}}_1)(Y) = (X^4 + X^3 + X^2)(5X^4)(4Y^3)^{-1}/5 \\ &= (\rho^2 x^4 + \rho^3 x^3 + \rho^4 x^2)(5x^4)(4y^3)^{-1}/5 \end{aligned}$$

Therefore

$$(23) \quad \kappa((\partial/\partial t_2)_0) = (\bar{\mathcal{D}}_2 - \bar{\mathcal{D}}_2) = (\rho^2 \theta_2 + \rho^3 \theta_3 + \rho^4 \theta_4)/5.$$

Next, we reset again

$$X = \tilde{R}_{0, 0, t_3} = \tilde{R}_{t_3}: y^4 = (x-1)(x-\rho)(x-\rho^2-\rho^2 t_3)(x-\rho^3)(x-\rho^4)$$

This equation is obtained by setting

$$x = \rho^2 X, \quad y = Y, \quad t_3 = t_1$$

in the equation of  $\tilde{R}_{t_1, 0, 0}$ .

Hence,  $\mathcal{D}_3, \tilde{\mathcal{D}}_3$  which are corresponding derivations to  $\tilde{R}_{t_3}$  must satisfy the following

$$\begin{aligned} (\bar{\mathcal{D}}_3 - \tilde{\bar{\mathcal{D}}}_3)(x) &= (\bar{\mathcal{D}}_1 - \tilde{\bar{\mathcal{D}}}_1)(\rho^2 X) = \rho^2 (\bar{\mathcal{D}}_1 - \tilde{\bar{\mathcal{D}}}_1)(X) = \rho^2 (X^4 + X^3 + X^2)/5 \\ &= (\rho^4 x^4 + \rho x^3 + \rho^3 x^2)/5 \\ (\bar{\mathcal{D}}_3 - \tilde{\bar{\mathcal{D}}}_3)(y) &= (\bar{\mathcal{D}}_1 - \tilde{\bar{\mathcal{D}}}_1)(Y) = (X^4 + X^3 + X^2)/5 \\ &= (\rho^4 x^4 + \rho x^3 + \rho^3 x^2)(5x^4)(4y^3)^{-1}/5. \end{aligned}$$

Therefore

$$(24) \quad \kappa((\partial/\partial t_3)_0) = (\bar{\mathcal{D}}_3 - \tilde{\bar{\mathcal{D}}}_3) = (\rho^4 \theta_2 + \rho \theta_3 + \rho^3 \theta_4)/5.$$

From (22), (23) and (24), we could prove the following theorem for the family  $X = \tilde{R}_{t_1, t_2, t_3}$

**THEOREM 6.** *The Kodaira-Spencer map  $\kappa: T_{S, 0} \rightarrow H^1(X, \mathcal{T}_X)$  is given by*

$$(25) \quad \kappa \begin{pmatrix} (\partial/\partial t_1)_0 \\ (\partial/\partial t_2)_0 \\ (\partial/\partial t_3)_0 \end{pmatrix} = \frac{1}{5} \begin{pmatrix} 1 & 1 & 1 \\ \rho^2 & \rho^3 & \rho^4 \\ \rho^4 & \rho & \rho^3 \end{pmatrix} \begin{pmatrix} \theta_2 \\ \theta_3 \\ \theta_4 \end{pmatrix}.$$

**COROLLARY.**  *$\kappa$  is injective.*

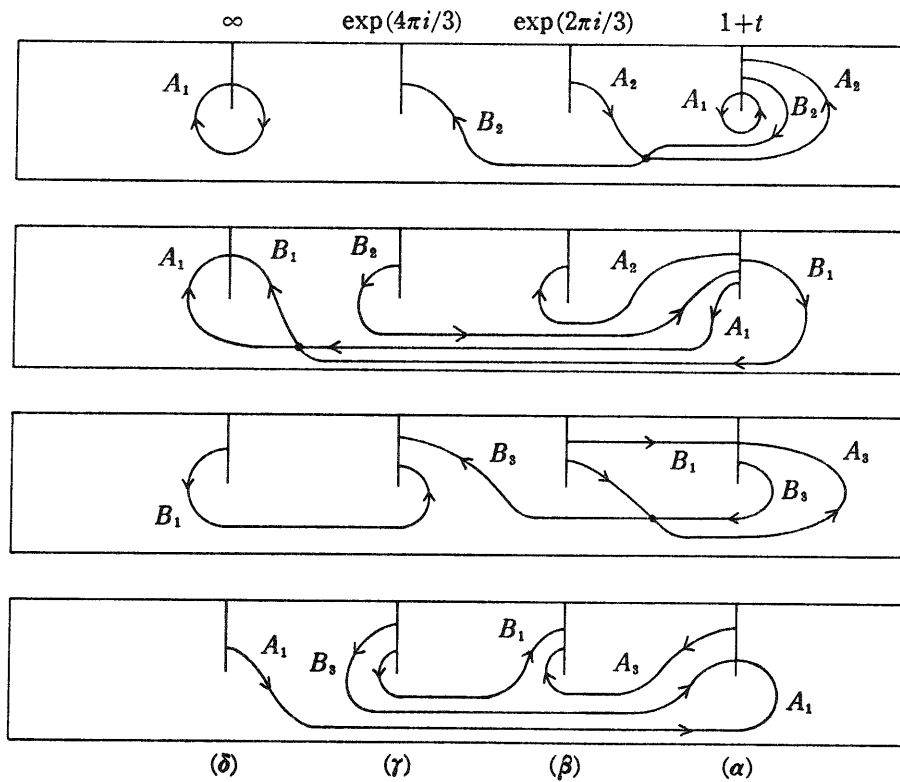
**PROOF.** It is clear since the matrix in (25) is nonsingular.

**REMARK 5.** Theorem 6 and Corollary show that  $t_1, t_2$  and  $t_3$  are independent parameters of Prym variety. Indeed  $\theta_2, \theta_3$  and  $\theta_4$  correspond to  $\Omega_2 = \omega_1 \omega_2, \Omega_3 = \omega_1 \omega_3$  and  $\Omega_4 = \omega_1 \omega_4$  where  $\omega_1, \omega_2, \omega_3$  and  $\omega_4$  are Prym differentials and the injectivity asserts their independency.

**Appendix.**

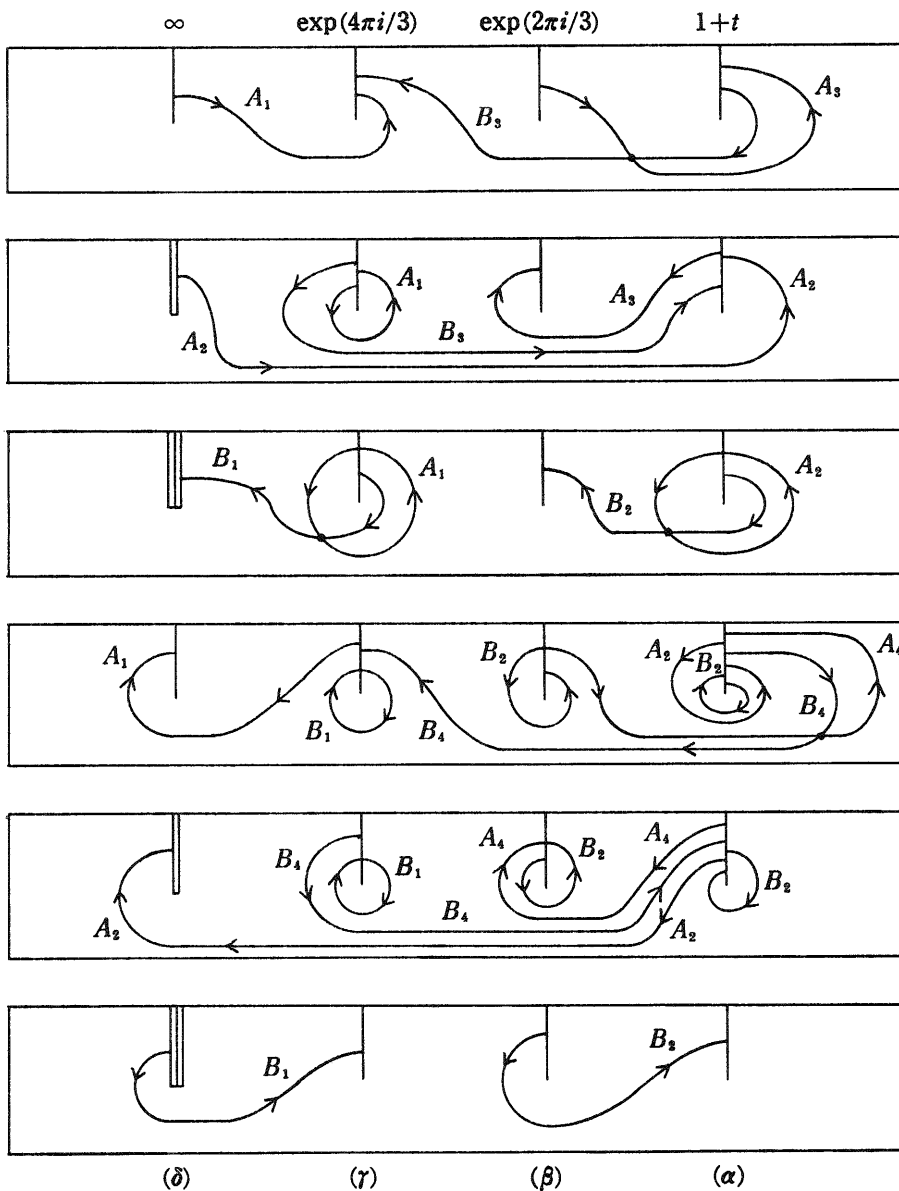
1. A canonical homology basis of the Riemann surface defined by

$$y^4 = (x-1-t)(x^2+x+1).$$



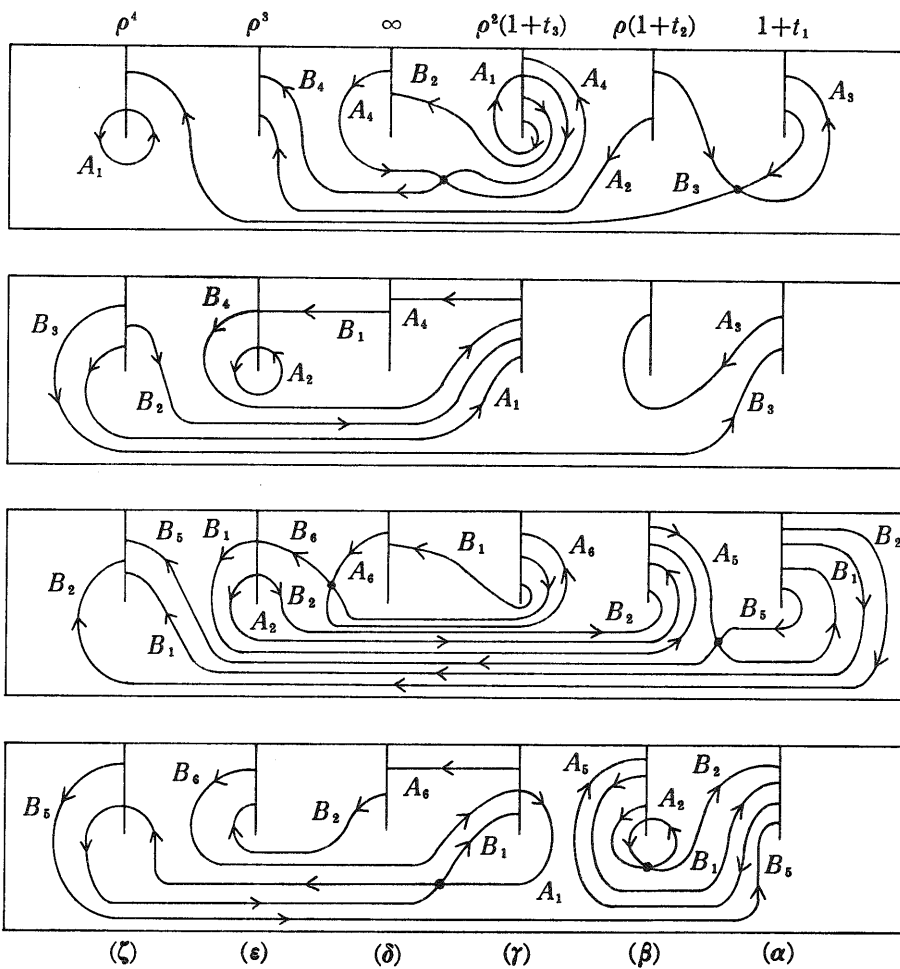
2. A canonical homology basis of the Riemann surface defined by

$$y^6 = (x-1-t)(x^2+x+1).$$



3. A canonical homology basis of the Riemann surface defined by

$$y^4 = (x - 1 - t_1)(x - \rho - \rho t_2)(x - \rho^2 - \rho^2 t_3)(x - \rho^3)(x - \rho^4).$$





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