# APPROXIMATIVE SHAPE III <br> -FIXED POINT THEOREMS- 

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## § 0. Introduction.

This paper is a continuation of [45-46]. We introduced approximative shape in [45], and discussed approximative shape properties of spaces and generalized ANRs in [46]. In this paper we shall discuss approximative shape properties of maps and fixed point theorems.

The Lefschetz-Hopf fixed point theorem is a well-known fixed point theorem formulated in homological or cohomological terms. It was first discovered by Lefschetz for compact manifolds and then extended by him to manifolds with boundary. Hopf gave a completly different and simple proof for finite polyhedra and then Lefschetz extended it to compact metric ANRs (see Lefschetz [33]). It was extended to compact metric $\mathrm{AANR}_{M} \mathrm{~s}$ by Granas [22], to compact metric $\mathrm{AANR}_{C} \mathrm{~S}$ by Clapp [9] and to metric $\mathrm{AANR}_{C} \mathrm{~S}$ by Powers [40].

Borsuk [3,5] introduced nearly extendable sets, in notation NE-sets, and nearly extendable maps, in notation NE-maps, between compact metric spaces. He $[4,6]$ showed the Lefschetz-Hopf fixed point theorem for NE-maps and Gauthier [19-21] extended it to NE-maps between compact spaces.

Borsuk and Ulam [7] introduced symmetric products. This notion was generalized as $G$-product where $G$ is a subgroup of all permutations of coordinates. Maxwell [36] showed a fixed point theorem for maps into $G$-products of finite polyhedra. The Maxwell fixed point theorem contains the LefschetzHopf fixed point theorem as a special case. The Maxwell fixed point theorem is extended to maps into $G$-products of compact metric ANRs by Masih [35] and to maps into $G$-products of compact metric AANR $_{N}$ s by Vora [42].

In this paper we investigate the following topics. In §1 we introduce NEsets and NE-maps between arbitrary spaces. We show that the notions of apapproximative movability and NE-sets are equivalent. We show that the notions. of $\mathrm{AANR}_{c}$ and NE-sets are equivalent for compact metric spaces, but not for compact spaces. This gives a negative answer to a question of Gauthier [20]. In §2 we show that products, suspensions and cones preserve NE-maps. In § 3

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we investigate approximative shape properties of hyperspaces. In §4 we show that $G$-products induce shape functors. In $\S 5$ we introduce Maxwell homomorphisms for shapings and investigate their properties. In § 6 we show the Maxwell fixed point theorem for NE-maps between compact spaces. It contains the Lefschetz-Hopf fixed point theorem for NE-maps between compact spaces. Our proofs depend only on the Maxwell and the Lefschetz-Hopf fixed point theorems for finite polyhedra.

We show the fixed point property of cones and hyperspaces of approximatively movable compact spaces. These give partial answers to questions raised by Rogers [41] and Nadler [39].

We assume that the reader is familiar with the theory of ANRs and with shape theory. Borsuk [1] and Hu [23] are standard textboogs for the theory of ANRs. Borsuk [2] and Mardešić and Segal [34] are standard textbooks for shape theory. For undefined notations and terminology see Hu [23] and Mardešić and Segal [34], which is quoted by MS [34]. We use the same notations and terminology as in [45-46]. We quote results in [45-46] as follows; for example (I. 3.3) and (II. 5.5) denote theorem (3.3) in [45] and theorem (5.5) in [46], respectively.

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## § 1. Nearly extendable maps.

The notions of nearly extendable maps and nearly extendable sets were introduced by Borsuk [3-6] for compact metric spaces and then by Gauthier [1921] for compact spaces. Dugundji [11] introduced the notion of Borsuk presentations. In this section we show that resolutions and approximative resolutions are better than Borsuk presentations. We discuss these notions for arbitrary maps and spaces, and we study their properties.

Let $(\mathscr{X}, \mathcal{U})=\left\{\left(X_{a}, \mathcal{U}_{a}\right), p_{a^{\prime}, a}, A\right\}$ and $(\mathscr{G}, \mathcal{V})=\left\{\left(Y_{b}, \mathcal{V}_{b}\right), q_{b^{\prime}, b}, B\right\}$ be approximative inverse systems in TOP. Let $\boldsymbol{f}=\left\{f, f_{b}: b \in B\right\}:(\mathscr{X}, \mathcal{Q}) \rightarrow(q, \mathcal{Q})$ be an approximative system map in TOP.

We say that $\boldsymbol{f}$ is nearly extendable provided that it satisfies the following condition:
(NE) For each $b \in B$ there exists $a_{0}>f(b)$ with the property; for each $b^{\prime}>b$ there exists a map $h: X_{a_{0}} \rightarrow Y_{b^{\prime}}$ such that $\left(f_{0} p_{a_{0}, f(b)}, q_{b^{\prime}, b} h\right)<s t \subset \cup_{b}$.
(1.1) Lemma. Let $\boldsymbol{f}, \boldsymbol{f}^{\prime}:(\mathfrak{X}, \mathcal{U}) \rightarrow(\mathscr{q}, \mathcal{C})$ be approximative system maps and
$\boldsymbol{f} \equiv: \boldsymbol{f}^{\prime}$. If $\boldsymbol{f}$ is nearly extendable, then so is $\boldsymbol{f}^{\prime}$.
Proof. We put $f^{\prime}=\left\{f^{\prime}, f_{o}^{\prime}: b \in B\right\}$. Without loss of generality we may assume that $\boldsymbol{f}=: \boldsymbol{f}^{\prime}$ and show that $\boldsymbol{f}^{\prime}$ satisfies (NE). Take any $b \in B$ and then by (AI3) there exists $b_{1}>b$ such that $q_{b_{1}, b}^{-1} \mathcal{V}_{b}>s t \mathcal{V}_{b_{1}}$. By the assumption there exists $a_{1}>f\left(b_{1}\right)$ satisfying (NE) for $\boldsymbol{f}$ and $b_{1}$. Since $\boldsymbol{f}$ satisfies (AM2) and $\boldsymbol{f}=: \boldsymbol{f}^{\prime}$, there exists $a_{2}>f(b), f^{\prime}(b), a_{1}$ such that

$$
\begin{align*}
& \left(f_{b} p_{a_{2}, f(b)}, q_{b_{1}, b} f_{b_{1}} p_{a_{2}, f\left(b_{1}\right)}\right)<\mathcal{V}_{b} \quad \text { and }  \tag{1}\\
& \left(f_{b} p_{a_{2}, f(b)}, f_{b}^{\prime} p_{a_{2}, f^{\prime}(b)}\right)<\mathcal{V}_{b} .
\end{align*}
$$

Take any $b_{2}>b$ and then there exists $b_{3}>b_{1}, b_{2}$. By the choice of $a_{1}$ there exists a map $k: X_{a_{1}} \rightarrow Y_{o_{3}}$ such that

$$
\begin{equation*}
\left(f_{b_{1}} p_{a_{1}, f\left(b_{1}\right)}, q_{b_{3}, b_{1}} k\right)<s t \subset \cup_{b_{1}} . \tag{3}
\end{equation*}
$$

By (3) and the choice of $b_{1}$

$$
\begin{equation*}
\left(q_{b_{1}, b} f_{b_{1}} p_{a_{2}, f\left(b_{1}\right)}, q_{b_{3}, b} k p_{a_{2}, a_{1}}\right)<\mathcal{V}_{b} . \tag{4}
\end{equation*}
$$

From (1), (2) and (4)

$$
\begin{equation*}
\left(f_{b}^{\prime} p_{a_{2}, f^{\prime}(b)}, q_{o_{3}, b k}, k p_{a_{2}, a_{1}}\right)<s t \subset \nabla_{b} \tag{5}
\end{equation*}
$$

(5) means that $a_{2}$ and the map $q_{b_{3}, b_{2}} k p_{a_{2}, a_{1}}: X_{a_{2}} \rightarrow Y_{b_{2}}$ satisfy (NE) for $f^{\prime}$ and $b$. Hence $\boldsymbol{f}^{\prime}$ is nearly extendable.

Thus by (1.1) we say that [ $\boldsymbol{f}$ ] is nearly extendable provided that $\boldsymbol{f}$ is nearly extendable. Let $\boldsymbol{g}=\left\{g, g_{c}: c \in C\right\}:(\mathcal{q}, \mathcal{Q}) \rightarrow(\mathscr{X}, \mathscr{W})=\left\{\left(Z_{c}, \mathscr{W}_{c}\right), r_{c^{\prime}, c}, C\right\}$ be an approximative system map.
(1.2) Lemma. If one of $[\boldsymbol{f}]$ and $[\boldsymbol{g}]$ is nearly extendable, then so is $[\boldsymbol{g}][\boldsymbol{f}]$.

Proof. Let $u: C \rightarrow C$ be a 1 -refinement function of $(\mathscr{X}, \mathscr{W})$. Then $[g][f]$ $=[\boldsymbol{r}(u)(\boldsymbol{g} \boldsymbol{f})]$. First we assume that $[\boldsymbol{g}]$ is nearly extendable and show that $\boldsymbol{r}(u)(\boldsymbol{g f})$ is nearly extendable. Take any $c \in C$. By the assumption there exists $b_{0}>g u(c)$ satisfying (NE) for $\boldsymbol{g}$ and $u(c)$. By (AM2) there exists $a_{0}>f g u(c), f\left(b_{0}\right)$ such that

$$
\begin{equation*}
\left(f_{g u(c)} p_{a_{0}, f g u(c)}, q_{b_{0}, g u(c)} f_{b_{0}} p_{a_{0}, f\left(b_{0}\right)}\right)<C V_{g u(c)} . \tag{1}
\end{equation*}
$$

Take any $c_{1}>c$. By the choice of $b_{0}$ there exists a map $k: Y_{b_{0}} \rightarrow Z_{u\left(c_{1}\right)}$ such that


$$
\begin{equation*}
\left(r_{u(c), c} g_{u(c)} q_{b_{0}, g u(c)} f_{b_{0}} p_{a_{0}, f\left(b_{0}\right)}, r_{u\left(c_{1}\right), c k} k f_{b_{0}} p_{a_{0}, f\left(b_{0}\right)}\right)<\mathscr{W}_{c} . \tag{2}
\end{equation*}
$$

By (1)
(3) $\quad\left(r_{u(c), c} g_{u(c)} f_{g u(c)} p_{a_{0}, f g u(c)}, r_{u(c), c} g_{u(c)} q_{b_{0}, g u(c)} f_{b_{0}} p_{a_{0} . f\left(b_{0}\right)}\right)<\mathscr{W}_{c}$.

By (2) and (3) $\left(r_{u(c), c} g_{u(c)} f_{g u(c)} p_{a_{0}, f g u(c)}, r_{u\left(c_{1}\right), c} k f_{b_{0}} p_{a_{0}, f\left(b_{0}\right)}\right)<s t W_{c}$. This means that $a_{0}$ and the map $r_{u\left(c_{1}\right), c_{1}} k f_{b_{0}} p_{a_{0}, f\left(b_{0}\right)}: X_{a_{0}} \rightarrow Z_{c_{1}}$ satisfy the required condition. Then $\boldsymbol{r}(u)(\boldsymbol{g} \boldsymbol{f})$ is nearly extendable and hence so is $[\boldsymbol{g}][\boldsymbol{f}]$.

Next we assume that $[\boldsymbol{f}]$ is nearly extendable and show that $[\boldsymbol{g}][\boldsymbol{f}]$ is nearly extendable. Take any $c \in C$. By the assumption there exists $a_{0}>f g u(c)$ satisfying (NE) for $f$ and $g u(c)$. Take any $c_{1}>c$. By (AM2) there exists $b_{0}>$ $g u\left(c_{1}\right), g u(c)$ such that

$$
\begin{equation*}
\left(g_{u(c)} q_{b_{0}, g u(c)}, r_{u\left(c_{1}\right), u(c)} g_{u\left(c_{1}\right)} q_{b_{0}, g u\left(c_{1}\right)}\right)<\mathscr{W}_{u(c)} \tag{4}
\end{equation*}
$$

By the choice of $a_{0}$ there exists a map $k: X_{a_{0}} \rightarrow Y_{b_{0}}$ such that ( $f_{g u(c)} p_{a_{0}, f g u(c)}$, $\left.q_{b_{0}, g u(c)} k\right)<s t \mathcal{V}_{g u(c)}$. Since $u$ is a 1 -refinement function, by (AM1) and (2.2)

$$
\begin{equation*}
\left(r_{u(c), c} g_{u(c)} f_{g u(c)} p_{a_{0, f} g u(c)}, r_{u(c), c} g_{u(c)} q_{b_{0}, g u(c)} k\right)<\mathscr{W}_{c} \tag{5}
\end{equation*}
$$

By (4) $\left(r_{u(c), c} g_{u(c)} q_{b_{0}, g u(c)} k, r_{u\left(c_{1}\right), c} g_{u\left(c_{1}\right)} q_{b_{0}, g u\left(c_{1}\right)} k\right)<\mathscr{W}_{c}$. Then by this and (5) $\left(r_{u(c), c} g_{u(c)} f_{g u(c)} p_{a_{0} f g u(c)}, r_{u\left(c_{1}\right), c} g_{u\left(c_{1}\right)} q_{b_{0}, g u\left(c_{1}\right)} k\right)<s t W_{c}$. This means that $a_{0}$ and the map $r_{u\left(c_{1}\right), c_{1}} g_{u\left(c_{1}\right)} q_{b_{0}, g u\left(c_{1}\right)} k: X_{a_{0}} \rightarrow Z_{c_{1}}$ satisfy the required condition. Then $\boldsymbol{r}(u)(\boldsymbol{g} \boldsymbol{f})$ is nearly extendable and hence so is $[\boldsymbol{g}][\boldsymbol{f}]$.
(1.3) Corollary. Let $(\mathscr{X}, \mathcal{U})$ be an approximative inverse system. Then the following statements are equivalent:
(i) $1_{(x, U)}:(\mathscr{X}, \mathcal{U}) \rightarrow(\mathcal{X}, \mathcal{U})$ is nearly extendable.
(ii) Any approximative system map $\boldsymbol{f}:(\mathscr{X}, \mathcal{U}) \rightarrow(\mathscr{G}, \mathcal{V})$ is nearly extendable for each approximative inverse system (q, $\mathcal{V}$ ).
(iii) Any approximative system map $\boldsymbol{f}:(\mathscr{y}, \mathcal{V}) \rightarrow(\mathfrak{X}, \mathcal{U})$ is nearly extendable for each approximative inverse system (q, CV).

Let $f: X \rightarrow Y$ be a map. Let $\boldsymbol{p}: X \rightarrow(\mathcal{X}, \mathcal{U}), \boldsymbol{p}^{\prime}: X \rightarrow(\mathscr{X}, \mathcal{U})^{\prime}$ and $\boldsymbol{q}: Y \rightarrow(\mathscr{Y}, \mathcal{V})$, $\boldsymbol{q}^{\prime}: Y \rightarrow(\mathscr{q}, \mathcal{V})^{\prime}$ be approximative AP-resolutions. Let $\boldsymbol{f}:(\mathcal{X}, \mathcal{Q}) \rightarrow(\mathscr{q}, \mathcal{V})$ and $\boldsymbol{f}^{\prime}:(\mathscr{X}, \mathscr{Q})^{\prime} \rightarrow(\mathscr{Y}, \mathcal{V})^{\prime}$ be approximative resolutions of $f$ with respect to $\boldsymbol{p}, \boldsymbol{q}$ and $\boldsymbol{p}^{\prime}, \boldsymbol{q}^{\prime}$ respectively.
(1.4) LEMMA. If $\boldsymbol{f}$ is nearly extendable, then so is $\boldsymbol{f}^{\prime}$.
(1.4) follows from (I.5.1), (iv) of (I.5.3) and (1.1).

Let $\quad \boldsymbol{p}=\left\{p_{a}: a \in A\right\}: X \rightarrow \mathcal{X}=\left\{X_{a}, p_{a^{\prime}, a}, A\right\} \quad$ and $\quad \boldsymbol{q}=\left\{q_{b}: b \in B\right\}: Y \rightarrow a y=$ $\left\{Y_{b}, q_{b^{\prime}, b}, B\right\}$ be AP-resolutions. Let $\boldsymbol{f}=\left\{f, f_{b}: b \in B\right\}: \mathcal{X} \rightarrow a j$ be a system map and $(\boldsymbol{f}, \boldsymbol{p}, \boldsymbol{q})$ an $\mathbf{A P}$-resolution of $f$. We say that $(\boldsymbol{f}, \boldsymbol{p}, \boldsymbol{q})$ is nearly extendable provided that it satisfies the following condition:
$(\mathrm{NE})_{1}$ For each $b \in B$ and for each $c \mathcal{C} \in \mathcal{C}_{o v}\left(Y_{b}\right)$ there exists $a_{0}>f(b)$ with
the property; for each $b^{\prime}>b$ there exists a map $k: X_{a_{0}} \rightarrow Y_{b^{\prime}}$ such that $\left(f_{b} p_{a_{0}, f(b)}, q_{b^{\prime}, b} k\right)<\mathcal{C} V$.
(1.5) Lemma. Let $(\boldsymbol{f}, \boldsymbol{p}, \boldsymbol{q})$ and $(\boldsymbol{g}, \boldsymbol{r}, \boldsymbol{s})$ be AP-resolutions of $f$. If $(\boldsymbol{f}, \boldsymbol{p}, \boldsymbol{q})$ satisfies (NE) $)_{1}$, then so does ( $\boldsymbol{g}, \boldsymbol{r}, \boldsymbol{s}$ ).

Proof. Put $\boldsymbol{r}=\left\{r_{c}: c \in C\right\}: X \rightarrow \mathcal{R}=\left\{R_{c}, r_{c^{\prime}, c}, C\right\}, \boldsymbol{s}=\left\{s_{d}: d \in D\right\}: Y \rightarrow \mathcal{S}=$ $\left\{S^{d}, s_{d^{\prime}, d}, D\right\}$ and $\boldsymbol{g}=\left\{g, g_{d}: d \in D\right\}$. Take any $d \in D$ and any $\mathscr{W} \in \mathcal{C} o v\left(S_{d}\right)$. Take $\mathscr{W}_{1} \in \mathcal{C o v}\left(S_{d}\right)$ such that $s t \mathscr{W}_{1}<\mathscr{W}$. There exist $\mathscr{W}_{2}, \mathscr{W}_{3} \in \mathcal{C}$ ov $\left(S_{d}\right)$ such that $\mathscr{W}_{2}$ satisfies (R2) for $r$ and $\mathscr{W}_{1}$, and $\mathscr{W}_{3}$ satisfies (R2) for $\boldsymbol{q}$ and $\mathscr{W}_{1}$. Take $\mathscr{W}_{4} \in$ $\mathcal{C}_{o v}\left(S_{d}\right)$ such that $s t \mathscr{W}_{4}<\mathscr{W}_{2} \wedge \mathscr{W}_{3}$. By (R1) there exist $b \in B$ and a map $h: Y_{b} \rightarrow S_{d}$ such that

$$
\begin{equation*}
\left(h q_{b}, s_{d}\right)<\mathscr{W}_{4} . \tag{1}
\end{equation*}
$$

By the assumption there exists $a_{0}>f(b)$ satisfying (NE) ${ }_{1}$ for ( $\boldsymbol{f}, \boldsymbol{p}, \boldsymbol{q}$ ), $b$ and $h^{-1} \mathscr{W}_{1}$. By (R1) there exist $c_{0}>g(d)$ and a map $i: R_{c_{0} \rightarrow X_{a_{0}}}$ such that ( $i r_{c_{0}}, p_{a_{0}}$ ) $<\left(h f_{b} p_{a_{0}, f(b)}\right)^{-1} \mathscr{W}_{4}$. Thus $\left(h f_{b} p_{a_{0}, f(b)} i r_{c_{0}}, h f_{b} p_{f(b)}\right)<\mathscr{W}_{4}$. Since $f_{b} p_{f(b)}=q_{b} f$ by (RM2),

$$
\begin{equation*}
\left(h f_{b} p_{a_{0}, f(b)} i r_{c_{0}}, h q_{b} f\right)<\mathscr{W}_{4} . \tag{2}
\end{equation*}
$$

By (1) $\left(h q_{b} f, s_{d} f\right)<\mathscr{W}_{4}$. Since $s_{d} f=g_{d} r_{g(d)}=g_{d} r_{c_{0}, g(d)} r_{c_{0}}$ by (RM2),

$$
\begin{equation*}
\left(h q_{b} f, g_{d} r_{c_{0}, g(d)} r_{c_{0}}\right)<\mathscr{W}_{4} . \tag{3}
\end{equation*}
$$

By (2) and (3) $\left(h f_{0} p_{a_{0}, f(b)} i r_{c_{0}}, g_{d} r_{c_{0}, g(d)} r_{c_{0}}\right)<s t W_{4}<W_{2}$. By the choice of $\mathscr{W}_{2}$ there exists $c_{1}>c_{0}$ such that

$$
\begin{equation*}
\left(h f_{b} p_{a_{0}, f(b)} i r_{c_{1}, c_{0}}, g_{d} r_{c_{1}, g(d)}\right)<\mathscr{W}_{1} . \tag{4}
\end{equation*}
$$

We now show that $c_{1}$ is the required index. Take and $d_{1}>d$. By (R1) there exist $b_{1}>b$ and a map $j: Y_{b_{1}} \rightarrow S_{d_{1}}$ such that $\left(j q_{o_{1}}, s_{d_{1}}\right)<s_{d_{1}, q}^{-1} \mathscr{W}_{4}$. Thus $\left(s_{d_{1}, d j} q_{o_{1}}, s_{d}\right)<\mathscr{W}_{4}$ and then by (1) $\left(h q_{b_{1}, b} q_{b_{1}}, s_{d_{1}, d} j q_{b_{1}}\right)<s t \mathscr{W}_{4}<\mathscr{W}_{3}$. By the choice of $\mathscr{W}_{3}$ there exists $b_{2}>b_{1}$ such that

$$
\begin{equation*}
\left(h q_{b_{2}, b}, s_{d_{1}, d} j q_{b_{2}, b_{1}}\right)<\mathscr{W}_{1} . \tag{5}
\end{equation*}
$$

By the choice of $a_{0}$ there exists a map $k: X_{a_{0} \rightarrow Y_{b_{2}}}$ such that ( $f_{0} p_{a_{0}, f(b)}, q_{b_{2}, b} k$ ) $<h^{-1} \mathscr{W}_{1}$. Thus

$$
\begin{equation*}
\left(h f_{b} p_{a_{0}, f(0)} i r_{c_{1}, c_{0}}, h q_{b_{2}, b} k i r_{c_{1}, c_{0}}\right)<\mathscr{W}_{1} . \tag{6}
\end{equation*}
$$

By (5) ( $\left.h q_{b_{2}, b} k i r_{c_{1}, c_{0}}, s_{d_{1}, d} j q_{c_{2}, b_{1}} k i r_{c_{1}, c_{0}}\right)<W_{1}$. From this, (4) and (6) ( $g_{d} r_{c_{1}, g(d)}$, $\left.s_{d_{1}, d} j q_{b_{2}, b_{1}} k i r_{c_{1}, c_{0}}\right)<s t \mathscr{W}_{1}<\mathscr{W}$. This means that $c_{1}$ and the map $j q_{b_{2}, o_{1}} k i r_{c_{1}, c_{0}}: R_{c_{1}}$ $\rightarrow S_{d_{1}}$ satisfy (NE) for $(\boldsymbol{g}, \boldsymbol{r}, \boldsymbol{s})$. Hence $(\boldsymbol{g}, \boldsymbol{r}, \boldsymbol{s})$ is nearly extendable.

By (I.4.9) there exist approximative ANR-resolutions $\boldsymbol{p}: X \rightarrow(\mathscr{X}$, Ø) $\boldsymbol{q}: Y \rightarrow$ $(q, \mathcal{V})$ and an approximative resolution $\boldsymbol{f}:(\mathcal{X}, \mathcal{Q}) \rightarrow(q, \mathcal{V})$ of $f$ with respect to $\boldsymbol{p}$ and $\boldsymbol{q}$ such that $(\boldsymbol{f}, \boldsymbol{p}, \boldsymbol{q})$ is an ANR-resolution of $f$.
(1.6) Lemma. $\boldsymbol{f}$ satisfies (NE) iff $(\boldsymbol{f}, \boldsymbol{p}, \boldsymbol{q})$ satisfies (NE) ${ }_{1}$.

In the same way as in (II. 1.6) we can easily show (1.6). Thus from (1.4)(1.6) we have the following:
(1.7) Theorem. Let $f: X \rightarrow Y$ be a map. Then the following statements are equivalent:
(i) Any/some approximative AP-resolution of $f$ is nearly extendable.
(ii) Any/some AP-resolution of $f$ is nearly extendable.

Thus we say that a map $f: X \rightarrow Y$ is a nearly extendable map, in notation NE-map, provided that it satisfies one of the conditions in (1.7). A space $X$ is a nearly extendable set, in notation NE-set, provided that $1_{X}: X \rightarrow X$ is an NE-map.
(1.8) Corollary. Let $f: X \rightarrow Y$ and $g: Y \rightarrow Z$ be maps. If one of maps $f$ and $g$ is an NE-map, then so is $g f$.
(1.9) Corollary. Let $X$ be a space. Then the following statements are equivalent:
(i) $X$ is an NE-set.
(ii) Any map $f: X \rightarrow Y$ is an NE-map for any space $Y$.
(iii) Any map $f: Y \rightarrow X$ is an NE-map for any space $Y$.
(1.10) Lemma. A map $f: X \rightarrow Y$ is nearly extendable iff so is $C T(f): C T(X)$ $\rightarrow C T(Y)$.
(1.10) follows from (I.6.8), (I.6.10), (1.1) and (1.2).
(1.11) Lemma. Let $(\mathcal{X}, \mathcal{Q})$ be an approximative inverse system. Then $(\mathfrak{X}, \mathcal{Q})$ is $A M$ iff $1_{(X, \mathscr{)}}:(\mathscr{X}, \mathscr{U}) \rightarrow(X, \mathcal{U})$ is nearly extendable.

Proof. First we assume that $(X, \mathcal{U})$ is AM. Take any $a \in A$. By the assumption there exists $a_{0}>a$ satisfying (AM) for $a$. Take any $a^{\prime}>a$. By the choice of $a_{0}$ there exists a map $r: X_{a_{0}} \rightarrow X_{a^{\prime}}$ such that $\left(p_{a_{0} a}, p_{a^{\prime}, a} r\right)<\mathcal{U}_{a}$. Thus $\left(1_{X_{a}} p_{a_{0}, a}, p_{a^{\prime}, a} r\right)<s t \mathcal{U}_{a}$ and hence $1_{(X, q)}$ is nearly extendable.

Next we assume that $1_{(x, q)}$ is nearly extendable. Take any $a \in A$. Then there exists $a_{1}>a$ such that $p_{a_{1}, a}^{-1} \mathscr{V}_{a}>s t \mathscr{G}_{a_{1}}$. Since $1_{(x, \mathscr{V})}$ is nearly extendable,
there exists $a_{2}>a_{1}$ satisfying (NE) for $1_{(x, y)}$ and $a_{1}$. Take any $a^{\prime}>a$ and take any $a_{3}>a^{\prime}, a_{1}$. By the choice of $a_{2}$ there exists a map $r: X_{a_{2}} \rightarrow X_{a_{3}}$ such that $\left(1_{x_{1}} p_{a_{2}, a_{1}}, p_{a_{3}, a_{1}} r\right)<s t \mathcal{U}_{a_{1}}$. Thus ( $\left.p_{a_{2}, a}, p_{a_{3}, a} r\right)<\mathcal{U}_{a}$. This means that $a_{2}$ and the map $p_{a_{3}, a^{\prime}} r: X_{a_{2}} \rightarrow X_{a^{\prime}}$ satisfying (AM) for ( $\mathfrak{X}, \mathscr{Q}$ ) and $a$. Hence $(\mathscr{X}, \mathcal{U})$ is AM.
(1.11) implies the following:
(1.12) Theorem. A space $X$ is an NE-set iff $X$ is AM.

We now consider Borsuk's approach to NE-maps. Let $X$ and $Y$ be paracompact $M$-spaces and let $f: X \rightarrow Y$ be a map. By (I. 3.17) there exist closed embeddings $h_{X}: X \rightarrow M_{X}$ and $h_{Y}: Y \rightarrow M_{Y}$ into $\operatorname{AR}(\mathbf{P M}) \mathrm{S} M_{X}$ and $M_{Y}$. We say that $f$ is nearly extendable with respect to $h_{X}$ and $h_{Y}$ provided that there exists a map $F: M_{X} \rightarrow M_{Y}$ satisfying the following two conditions:
(NE1) $F \mid h_{X}(X)=h_{Y} f h_{X}^{-1}$.
(NE2) For each $\mathcal{V} \in \mathcal{C}_{o v}\left(M_{Y}\right)$ there exists a neighborhood $U_{0}$ of $h_{X}(X)$ in $M_{X}$ with the following property; for each neighborhood $V$ of $h_{Y}(Y)$ in $M_{Y}$ there exists a map $g: U_{0} \rightarrow V$ such that $\left(F \mid U_{0}, j g\right)<Q$. Here $j: V \rightarrow M_{Y}$ is the inclusion map.

We say that $F$ realizes the NE-property of $f$ with respect to $h_{X}$ and $h_{Y}$.
(1.13) Lemma. If $F$ realizes the NE-property of $f$ with respect to $h_{X}$ and $h_{Y}$ and $F^{\prime}: M_{X} \rightarrow M_{Y}$ satisfies (NE1), then $F^{\prime}$ also realizes the NE-property of $f$ with respect to $h_{X}$ and $h_{\dot{r}}$.

It is not difficult to show (1.13). Thus the choice of maps $F: M_{Y} \rightarrow M_{Y}$ satisfying (NE1) is immaterial. Let $h_{X}^{\prime}: X \rightarrow M_{X}^{\prime}$ and $h_{Y}^{\prime}: Y \rightarrow M_{Y}^{\prime}$ be closed embeddings into $\operatorname{AR}(\mathbf{P M}) \mathrm{s} M_{X}^{\prime}$ and $M_{Y}^{\prime}$.
(1.14) Lemma. If $f$ is nearly extendable with respect to $h_{X}$ and $h_{Y}$, then $f$ is nearly extendable with respect to $h_{x}^{\prime}$ and $h_{Y}^{\prime}$.

By a straightforward argument we can show (1.14). Thus we may say that $f$ is a nearly extendable map, in notation NE-map, in the sense of Borsuk provided that $f$ is nearly extendable with respect to any/some $h_{X}$ and $h_{Y}$.
(1.15) Theorem. Let $X$ and $Y$ be paracompact $M$-spaces and let $f: X \rightarrow Y$ be a map. Then $f$ is nearly extendable in our sense iff $f$ is nearly extendable in the sense of Borsuk.

Proof. By (I. 3.17) there exist $\operatorname{AR}(\mathbf{P M}) \mathrm{S} M_{X}$ and $M_{Y}$ which contain $X$ and
$Y$ as closed subsets, respectively. Then there exists a map $F: M_{X} \rightarrow M_{Y}$ such that $F \mid X=f$. By using $F$ and (1.4.10) we have $\operatorname{ANR}(\mathbf{P M})$-resolutions $\boldsymbol{p}=$ $\left\{p_{a}: a \in A\right\}: X \rightarrow \mathcal{A} q\left(X, M_{X}\right)=\left\{U_{a}, p_{a^{\prime}, a}, A\right\}, \boldsymbol{q}=\left\{q_{b}: b \in B\right\}: Y \rightarrow \mathcal{A} \mathscr{}\left(Y, M_{Y}\right)=$ $\left\{V_{b}, q_{b^{\prime}, b}, B\right\}$ and a resolution $\boldsymbol{f}=\left\{f, f_{b}: b \in B\right\}: \mathcal{A} \mathscr{}\left(X, M_{X}\right) \rightarrow \mathcal{A} \mathcal{U}\left(Y, M_{Y}\right)$ of $f$ with respect to $\boldsymbol{p}$ and $\boldsymbol{q}$. By (ii) of (1.3.17) we may assume that all $U_{a}$ and $V_{b}$ are $\operatorname{ANR}(\mathbf{P M})$-open neighberhoods of $h_{X}(X)$ and $h_{Y}(Y)$ in $M_{X}$ and $M_{Y}$, respectively.

First we assume that $f$ is nearly extendable in the sense of Borsuk and show that $\boldsymbol{f}$ satisfies $(\mathrm{NE})_{1}$. Take any $b \in B$ and any $C V^{\prime} \in \mathcal{C}_{o v}\left(V_{b}\right)$. By (ii) of (I.3.17) there exists $b_{1}>b$ such that $V_{b_{1}} \subset \bar{V}_{b_{1}} \subset V_{b}$. Put $\mathcal{V}=\left\{V: V \in \mathcal{V}^{\prime}\right\} \cup$ $\left\{M_{Y}-\bar{V}_{b_{1}}\right\} \in \mathcal{C}_{o v}\left(M_{Y}\right)$. There exists a neigborhood $U$ of $X$ in $M_{X}$ satisfying (NE2) for $\mathcal{V}$. By (ii) of (I. 3.17) there exists $a_{0}>f(b)$ such that $U_{a_{0}} \subset U_{f(b)} \cap U$. We show that $a_{0}$ is the required index. Take any $b^{\prime}>b$ and then there exists $b_{2}>b^{\prime}, b_{1}$ such that $V_{b_{2}} \subset V_{b_{1}} \cap V_{b^{\prime}}$. By the choice of $U$ there exists a map $g: U \rightarrow V_{b_{2}}$ such that

$$
\begin{equation*}
(F \mid U, j g)<Q . \tag{1}
\end{equation*}
$$

Here $j: V_{b_{2} \rightarrow} \rightarrow M_{Y}$ is the inclusion map.
For each $x \in U_{a_{0}}$ by (1) there exists $K \in \mathcal{C}$ such that $F(x), g(x) \in K$. However $g(x) \in V_{b_{2}} \subset \bar{V}_{b_{1}}$ and $F(x) \in V_{b}$ because $U_{a_{0}} \subset U_{f(b)} \subset F^{-1}\left(V_{b}\right)$. Thus $K \in \mathcal{V}^{\prime}$ by the definition of $\sigma$. Since $F(x)=f_{b} p_{a_{0}, f(b)}(x)$ and $g(x)=\left(q_{b_{2}, b} g \mid U_{a_{0}}\right)(x)$, this means that $\left(f_{b} p_{a_{0}, f(b)}, q_{b^{\prime}, o r}\right)<\mathcal{V}^{\prime}$, where $r=q_{b_{2}, b^{\prime}} g \mid U_{a_{0}}: U_{a_{0} \rightarrow V_{b^{\prime}}}$. Thus $\boldsymbol{f}$ satisfies ( NE$)_{1}$ and hence it is nearly extendable in our sense.

Next we assume that $\boldsymbol{f}$ is nearly extendable in our sense and show that $f$ is nearly extendable in the sense of Borsuk. Take any $\mathbb{V} \in \mathcal{C} o v\left(M_{Y}\right)$. Since $M_{Y}$ is an $\operatorname{ANR}(\mathbf{P M})$-neigborhood of $Y$ in $M_{Y}, V_{b}=M_{Y}$ for some $b \in B$. By the assumption there exists $a_{0}>f(b)$ satisfying (NE) for $b$ and $Q$. Take any neigborhood $V$ of $Y$ in $M_{Y}$ and then by (ii) of (I. 3.17) there exists $b_{1}>b$ such that $V_{b_{1}} \subset V$. By the choice of $a_{0}$ there exists a map $g: U_{a_{0}} \rightarrow V_{b_{1}}$ such that $\left(f_{b} p_{a_{0}, f(b)}, q_{b_{1}, b}\right)<Q$. Hence $\left(F \mid U_{a_{0}}, j g^{\prime}\right)<\mathcal{V}$ where $g^{\prime}=k g: U_{a_{0} \rightarrow V}$, and $k: V_{b_{1} \rightarrow V}, j: V \rightarrow M_{Y}$ are the inclusion maps. Hence $f$ is nearly extendable in the sense of Borsuk.

The following gives an answer to a question in Gauthier [20].
(1.15) Theorem. The notions of $\operatorname{AANR}_{C}(\mathbf{P M})$ and NE -sets are equivalent for compact metric spaces, but are not equivalent for compact spaces.
(1.15) follows from (II. 2.5), (II. 5.10), (II. 6.12) and (1.12).

Let $\boldsymbol{p}: X \rightarrow \mathscr{X}$ be a resolution and $f: X \rightarrow Y$ a map. We say that $f$ is ap-
proximatively extendable with respect to $p$ provided that it satisfies the following :
(AE) For any $\mathcal{Q} \in \mathcal{C} o v(Y)$ there exist $a \in A$ and a map $g_{a}: X_{a} \rightarrow Y$ such that $\left(f, g_{a} p_{a}\right)<\mathbb{C}$.
(1.16) Lemma. Let $\boldsymbol{p}$ and $\boldsymbol{p}^{\prime}$ be AP-resolutions of $X$. If $f$ is approximatively extendable with respect to $\boldsymbol{p}$, then so is $f$ with respect to $\boldsymbol{p}^{\prime}$.

We easily show (1.16). Thus we may say that $f$ is an approximatively extendable map, in notation AE-map, provided that $f$ is approximatively extendable with respect to any/some AP-resolution of $X$.
(1.17) Lemma. Let $f: X \rightarrow Y$ and $g: Y \rightarrow Z$ be maps. If one of $f$ and $g$ is an AE-map, then so is $g f$.
(1.18) Lemma. Let $f: X \rightarrow Y$ be a map. If $f$ is an AE-map, then $C T(f): C T(X)$ $\rightarrow C T(Y)$ is an AE-map.
(1.19) Proposition. If a map $f: X \rightarrow Y$ is an AE-map, then $f$ is an NEmap.
(1.20) Theorem. A space $X$ is IAM iff $1_{X}: X \rightarrow X$ is an AE-map.

Proof. Let $\boldsymbol{p}: X \rightarrow \mathscr{X}$ be an $\mathbf{A P}$-resolution. We assume that $X$ is IAM. Then $\boldsymbol{p}$ is IAM and then $\boldsymbol{p}$ satisfies ( $C$ ) by (II. 2.14). Thus for each $\mathcal{U} \in \operatorname{Cov}(X)$ there exist $a \in A$ and a map $r: X_{a} \rightarrow X$ such that $\left(r p_{a}, 1_{X}\right)<\mathcal{U}$. This means that $1_{X}: X \rightarrow X$ is an AE-map.

Next, we assume that $1_{X}$ is an AE-map. Then for each $U \in \mathcal{C}_{o v}(X)$ there exist $a \in A$ and a map $r: X_{a} \rightarrow X$ such that $\left(r p_{a}, 1_{X}\right)<\mathcal{U}$. Thus $\boldsymbol{p}$ satisfies ( $C$ ) and then $\boldsymbol{p}$ is IAM by (II. 2.14). Hence $X$ is IAM.
(1.21) Theorem. Let $X$ be a space. Then the following statements are equivalent:
(i) $X$ is an AP.
(ii) $1_{X}: X \rightarrow X$ is an AE-map.
(iii) Any map $f: X \rightarrow Y$ is an AE-map for any space $Y$.
(iv) Any map $f: Y \rightarrow X$ is an AE-map for any space $Y$.

This follows from (II. 2.17), (1.17) and (1.20).

## § 2. Products, suspensions and cones.

In this section we shall show that product, suspension and cone preserve AE- and NE-maps between compact spaces. Some results are proved by Borsuk [3-6] for maps between compact metric spaces.

In this section all spaces are compact spaces. Let $C$ be a non-empty set. Let $X_{c}$ and $Y_{c}$ be non-empty spaces and $f_{c}: X_{c} \rightarrow Y_{c}$ maps for $c \in C$. Let $X=$ $\pi\left\{X_{c}: c \in C\right\}$ and $Y=\pi\left\{Y_{c}: c \in C\right\}$ be product spaces. Let $f=\pi\left\{f_{c}: c \in C\right\}: X \rightarrow Y$ be the product of the maps $f_{c}$. Let $\boldsymbol{p}^{c}=\left\{p_{a}^{c}: a \in A(c)\right\}: X_{c} \rightarrow(\mathscr{X}, \mathscr{U})^{c}=\left\{\left(X_{a}^{c}, \mathcal{U}_{a}^{c}\right)\right.$, $\left.p_{a^{c}, a}^{c}, A(c)\right\}$ and $\boldsymbol{q}^{c}=\left\{q_{b}^{c}: b \in B(c)\right\}: Y_{c} \rightarrow(q, \mathcal{C})^{c}=\left\{\left(Y_{b}^{c}, \mathcal{C}_{b}^{c}\right), q_{b^{\prime}, b}^{c}, B(c)\right\}$ be approximative finite polyhedral resolutions of $X_{c}$ and $Y_{c}$ for each $c \in C$, respectively.

We may assume that $A(c) \cap A\left(c^{\prime}\right)=\varnothing$ and $B(c) \cap B\left(c^{\prime}\right)=\varnothing$ for $c, c^{\prime} \in C$ with $c \neq c^{\prime}$. Let $A=\cup\{A(c): c \in C\}$ and $B=\cup\{B(c): c \in C\}$ and $M=\{m: m$ is a non empty finite subset of $C\}$. Take any $m=\left\{c_{1}, c_{2}, \cdots, c_{k}\right\} \in M$. We say that a function $g: m \rightarrow A$ is a choice function provided that $g\left(c_{i}\right) \in A\left(c_{i}\right)$ for $c_{i} \in m$. Let $F(A)=\{g: m \in M$ and $g: m \rightarrow A$ is a choice function $\}$. Let $g: m \rightarrow A$ and $g^{\prime}: m \rightarrow A$ be choice functions. We say that $g^{\prime}>g$ provided that $m^{\prime} \supset m$ and $g^{\prime}(c)>g(c)$ in $A(c)$ for $c \in m$. Since all $A(c)$ are cofinite and directed, $(F(A),>)$ forms a cofinite directed set. Similarly we may define a cofinite $\operatorname{directed} \operatorname{set}(F(B),>)$.

For each choice function $g: m \rightarrow A$ we define a space $X_{g}$, a covering $U_{g} \in$ $\mathcal{C}_{o v}\left(X_{g}\right)$ and a map $p_{g}: X \rightarrow X_{g}$ as follows: To simplify notations sometimes ai and ci denote $a_{i}$ and $c_{i}$, respectively. $X_{g}=X_{g(c 1)} \times X_{g(c 2)} \times \cdots \times X_{g(c k)} ; U_{g}=$ $\mathcal{U}_{g(c i)}^{c 1} \times \cdots \times \mathcal{U}_{g(c k)}^{c k}=\left\{U_{1} \times \cdots \times U_{k}: U_{i} \in \mathcal{U}_{g(c i)}^{c i}\right.$ for $\left.i=1,2, \cdots, k\right\}$ and $p_{g}\left(\left(x_{c}\right)\right)=$ $\left(p_{g(c 1)}^{c 1}\left(x_{c 1}\right), \cdots, p_{g(c k)}^{c k}\left(x_{c k}\right)\right)$ for each $\left(x_{c}\right) \in X$. For $g^{\prime}>g$ we define a map $p_{g^{\prime}, g}: X_{g^{\prime}} \rightarrow X_{g}$ as follows: $p_{g^{\prime}, g}\left(x_{c 1}, x_{c 2}, \cdots, x_{c k}, x_{c k+1}, \cdots, x_{c k^{\prime}}\right)=\left(p_{g^{\prime}(c 1), g(c 1)}^{c 1}\left(x_{c 1}\right)\right.$, $\left.\cdots, p_{g^{\prime}(c k), g(c k)}^{c k}\left(x_{c k}\right)\right)$ for each $\left(x_{c 1}, \cdots, x_{c k^{\prime}}\right) \in X_{g^{\prime}}$. Here $g^{\prime}: m^{\prime}=\left\{c_{1}, c_{2}, \cdots\right.$, $\left.c_{k}, c_{k+1}, \cdots, c_{k^{\prime}}\right\} \rightarrow A$.

It is not difficult by (I.3.13) and (I.7.1) to show that ( $X, \mathcal{U})=\left\{\left(X_{g}, \mathcal{U}_{g}\right)\right.$, $\left.p_{g^{\prime}, g}, F(A)\right\}$ forms an approximative finite polyhedral inverse system and $\boldsymbol{p}=$ $\left\{p_{g}: g \in F(A)\right\}: X \rightarrow(\mathcal{X}, \mathcal{U})$ is an approximative finite polyhedral resolution of $X$. In the same way we can construct an approximative finite polyhedral resolution $\boldsymbol{q}=\left\{q_{h}: h \in F(B)\right\}: Y \rightarrow(q, \mathcal{C})=\left\{\left(Y_{h}, \mathcal{V}_{h}\right), q_{h^{\prime}, h}, F(B)\right\}$ of $Y$.

Let $\boldsymbol{f}^{c}=\left\{f_{j}^{c}, f_{b}^{c}: b \in B(c)\right\}:(\mathfrak{X}, \mathcal{U})^{c} \rightarrow(q, \mathcal{V})^{c}$ be an approximative resolution of $f_{c}$ with respect to $\boldsymbol{p}^{c}$ and $\boldsymbol{q}^{c}$ for each $c \in C$. We define a function $f: F(B) \rightarrow$ $F(A)$ and maps $f_{h}: X_{f(h)} \rightarrow Y_{h}$ for $h \in F(B)$ as follows: Take any choice function $h: m \rightarrow B$. We define a choice function $f(h): m \rightarrow A$ by $f(h)(c)=f^{c}(h(c))$ for $c \in m$. We define a map $f_{h}: X_{f(h)} \rightarrow Y_{h}$ by $f_{h}\left(x_{1}, x_{2}, \cdots, x_{k}\right)=\left(f_{h(c 1)}^{\left.c \frac{1}{c}\right)}\left(x_{1}\right), \cdots\right.$, $\left.f_{h(c k)}^{c h}\left(x_{k}\right)\right)$ for $\left(x_{1}, \cdots, x_{k}\right) \in X_{f(h)}$. It is not difficult to show that $\boldsymbol{f}=\left\{f, f_{h}: h \in\right.$
$F(B)\}:(X, \mathcal{X}) \rightarrow(\mathscr{Y}, \mathcal{C})$ forms an approximative resolution of $f$ with respect to $\boldsymbol{p}$ and $\boldsymbol{q}$.
(2.1) Theorem. (i) $f$ is an AE-map iff all $f_{c}$ are AE-maps.
(ii) $f$ is an NE-map iff all $f_{c}$ are NE-maps.

Proof. We show (ii). In a similar way we can show (i). First we assume that all $f_{c}$ are NE-maps and show that $f$ is an NE-map. Take any $h \in$ $F(B)$ and put $h: m=\left\{c_{1}, c_{2}, \cdots, c_{k}\right\} \rightarrow B$. There exists $a_{i} \in A\left(c_{i}\right)$ with $a_{i}>f^{c i} h\left(c_{i}\right)$ satisfying (NE) for $\boldsymbol{f}_{c i}$ and $h\left(c_{i}\right)$. We define a choice function $g: m \rightarrow A$ by $g\left(c_{i}\right)$ $=a_{i}$ for $i=1,2, \cdots, k$, and then $g>f(h)$. We show that $g$ is the required map. Take any $h^{\prime} \in F(B)$ with $h^{\prime}>h$ and put $h^{\prime}: m^{\prime}=\left\{c_{1}, c_{2}, \cdots, c_{k}, c_{k+1}, \cdots, c_{k^{\prime}}\right\} \rightarrow B$. By the choice of $a_{i}$ there exist maps $r_{i}: X_{a i}^{c i} \rightarrow Y_{h^{\prime}(c i)}^{c i}$ such that

$$
\begin{equation*}
\left(q_{h^{c}(c i), h(c i)}^{c i} r_{i}, f_{n}^{c i}(c i) p_{a i}^{b i}, f_{h(c i)}^{c i}\right)<s t \subset V_{h}^{c i}(c i) \quad \text { for } i=1,2, \cdots, k . \tag{1}
\end{equation*}
$$

We define a map $r: X_{g} \rightarrow Y_{h^{\prime}}$ by $r=j \pi\left\{r_{i}: i=1,2, \cdots k\right\}$. Here $j: Y_{h^{\prime}(c 1)}^{c_{1}} \times Y_{h^{\prime}\left(c_{2}\right)}^{c_{2}}$ $\times \cdots \times Y_{h^{\prime}(c k)}^{c k} \rightarrow Y_{h^{\prime}}$ is a natural inclusion map. Then by (1) we have that $\left(q_{h^{\prime}, h} r, f_{h} p_{g, f(h)}\right)<s t \subset \emptyset_{h}$. Hence $\boldsymbol{f}$ satisfies (NE) and then $f$ is an NE-map.

Next we assume that $f$ is an NE-map and show that all $f_{c}$ are NE-maps. Take any $c_{0} \in C$ and any $b \in B\left(c_{0}\right)$. We define a choice function $h_{0}:\left\{c_{0}\right\} \rightarrow B$ by $h_{0}\left(c_{0}\right)=b$. By the assumption there exists $g>f\left(h_{0}\right)$ satisfying (NE) for $\boldsymbol{f}$ and $h_{0}$. Put $g\left(c_{0}\right)=a_{0}$ and then $a_{0}>f_{c 0}(b)$. We show that $a_{0}$ is the required index. Take any $b^{\prime} \in B\left(c_{0}\right)$ with $b^{\prime}>b$. We define a choice function $h^{\prime}:\left\{c_{0}\right\} \rightarrow B$ by $h^{\prime}\left(c_{0}\right)=b^{\prime}$. Since $h^{\prime}>h$, by the choice of $g$ there exists a map $r: X_{g} \rightarrow X_{h^{\prime}}=Y_{b^{\prime}}^{c}$ such that

$$
\begin{equation*}
\left(f_{h_{0}} p_{g, f\left(h_{0}\right)}, q_{h^{\prime}, h^{2}} r\right)<s t \mathcal{V}_{h_{0}} \tag{2}
\end{equation*}
$$

We define a map $r^{\prime}: X_{a 0}^{c 0} \rightarrow Y_{a 0}^{c 0}$ by $r^{\prime}=r j$. Here $j: X_{a 0}^{c 0} \rightarrow X_{g}$ is the inclusion map. Thus by (2) $\left(f_{b}^{c 0} p_{a 0, f_{c 0}(b)}^{c 0}, q_{b^{2}, b}^{c 0} r^{\prime}\right)<s t \mathcal{V}_{b}$. Then $f_{c 0}$ is an NE-map and hence all $f_{c}$ are NE-maps.

By a straightforward argument we can show the following:
(2.2) Lemma. We assume that $C$ is finite. Then $X$ satisfies the condition $M$ iff all $X_{c}$ satisfy the condition $M$.
(2.3) Corollary. (i) $X$ is an AP iff all $X_{c}$ are APs.
(ii) $X$ is AM iff all $X_{c}$ are AM.
(iii) $X$ is an $\mathrm{AANR}_{c}$ for COM iff all $X_{c}$ are $\mathrm{AANR}_{C}$ for $\mathbf{C O M}$.
(iv) $X$ is an AAR for COM iff all $X_{c}$ are AAR for COM.
(v) When $C$ is finite, $X$ is an $\mathrm{AANR}_{N}$ for $\mathbf{C O M}$ iff all $X_{c}$ are $\mathrm{AANR}_{N}$ for COM.

Proof. (i) and (iii) follow from (II. 5.10), (1.21) and (2.1). (ii) follows from (1.12) and (2.1). (iv) follows from (i), (II. 5.12) and the following fact: $X$ has trivial shape iff all $X_{c}$ have trivial shape. (v) follows from (II. 5.11), (i) and (2.2).

Let $I$ be the unit interval. Cone $(X)$ denotes the quotient space $X \times I / X \times\{1\}$ and $t_{X}: X \times I \rightarrow \operatorname{Cone}(X)$ the quotient map. Then any map $f: X \rightarrow Y$ induces the unique map $\operatorname{Cone}(f): \operatorname{Cone}(f) \rightarrow \operatorname{Cone}(Y)$ satisfying $\operatorname{Cone}(f) t_{X}=t_{Y}\left(f \times 1_{I}\right)$. Let $\mathscr{Z} \in \mathcal{C}_{o o}(X \times I)$ and put $\mathcal{Z}^{*}=\left\{t_{X}(s t(X \times\{1\}, \mathcal{Z}))\right\} \cup\left\{t_{X}(Z): Z \in \mathcal{Z}\right.$ and $Z \cap(X \times\{1\})$ $=\varnothing\}$. Then $\mathcal{Z}^{*}$ forms a covering of Cone $(X)$.

Let $g=\left\{I_{i}, r_{j, i}, N\right\}$ be an inverse sequence such that $I_{i}=I$ and $r_{j, i}=1_{I}$ for all $j \geqq i$. Let $r_{i}=1_{I}: I \rightarrow I_{i}$ for all $i$. Then $r=\left\{r_{i}: i \in N\right\}: I \rightarrow \mathscr{g}$ forms an POLresolution. By (I. 3.8) there are coverings $\mathscr{W}_{i} \in \mathcal{C}_{o v}\left(I_{i}\right)$ such that $r: I \rightarrow(\mathcal{g}, \mathscr{W})=$ $\left\{\left(I_{i}, \mathscr{W}_{i}\right), r_{j, i}, N\right\}$ forms an approximative POL-resolution. Let $\boldsymbol{p}=\left\{p_{a}: a \in A\right\}$ : $X \rightarrow(\mathscr{X}, \mathcal{U})=\left\{\left(X_{a}, \mathcal{U}_{a}\right), p_{a^{\prime}, a}, A\right\}$ be an approximative finite polyhedral resolution of a space $X$. Let $A \times N$ be the directed product set. We define $X_{(a, i)}, p_{(a, i)}$ : $X \times I \rightarrow X_{(a, i)}$ and $p_{\left(a^{\prime}, i^{\prime}\right),(a, i)}: X_{\left(a^{\prime}, i^{\prime}\right)} \rightarrow X_{(a, i)}$ for $\left(a^{\prime}, i^{\prime}\right)>(a, i)$ as follows: $X_{(a, i)}$ $=X_{a} \times I_{i}, \quad p_{(a, i)}=p_{a} \times r_{i}$ and $p_{\left(a^{\prime}, i^{\prime}\right),(a, i)}=p_{a^{\prime}, a} \times r_{i^{\prime}, i}$. It is easy to show that $\boldsymbol{p} \times \boldsymbol{r}=\left\{p_{(a, i)}:(a, i) \in A \times N\right\}: X \times I \rightarrow(\mathfrak{X}, \mathcal{U}) \times(\mathcal{G}, \mathscr{W})=\left\{\left(X_{(a, i)}, \mathcal{U}_{a} \times \mathscr{W}_{i}\right), p_{\left(a^{\prime}, i^{\prime}\right),(a, i)}\right.$, $A \times N\}$ forms an approximative polyhedral resolution. Similarly we have an approximative polyhedral resolution $\boldsymbol{q} \times \boldsymbol{r}: Y \times I \rightarrow(q, \mathcal{V}) \times(\mathcal{G}, \mathscr{W})$ for an approximative polyhedral resolution $\boldsymbol{q}=\left\{q_{b}: b \in B\right\}: Y \rightarrow(q, \mathcal{C})=\left\{\left(Y_{b}{ }^{‘} \mathcal{V}_{b}\right), q_{b^{\prime}, b}, B\right\}$ of a space $Y$.

Let $\boldsymbol{f}=\left\{f, f_{b}: b \in B\right\}:(\mathscr{X}, \mathscr{Q}) \rightarrow(q, \mathcal{V})$ be an approximative resolution of a $\operatorname{map} f: X \rightarrow Y$ with respect to $\boldsymbol{p}$ and $\boldsymbol{q}$. We put $\boldsymbol{f} \times 1_{I}=\left\{f \times 1_{N}, f_{b} \times 1_{I}:(b, i) \in\right.$ $B \times N\}$. Then $\boldsymbol{f} \times 1_{I}:(\mathfrak{X}, \mathscr{U}) \times(\mathcal{g}, \mathscr{W}) \rightarrow\left(a_{\mathcal{g}}, \mathcal{V}\right) \times(\mathcal{g}, \mathscr{W})$ forms an approximative resolution of $f \times 1_{I}$ with respect to $\boldsymbol{p} \times \boldsymbol{r}$ and $\boldsymbol{q} \times \boldsymbol{r}$.

Maps $p_{(a, i)}: X \times I \rightarrow X_{a} \times I_{i}$ and $p_{\left(a^{\prime}, i^{\prime}\right),(a, i)}: X_{a^{\prime}} \times I_{i^{\prime}} \rightarrow X_{a} \times I_{i}$ induce maps $p_{(a, i)}^{\prime}: \operatorname{Cone}(X) \rightarrow X_{a} \times I_{i} / X_{a} \times\{1\}=X_{(a, i)}^{\prime}\left(=\operatorname{Cone}\left(X_{a}\right)\right)$ and $p_{\left(a^{\prime}, i^{\prime}\right),(a, i)}^{\prime}: X_{\left(a^{\prime}, i^{\prime}\right)}^{\prime}$ $\rightarrow X_{(a, i)}^{\prime}$. Moreover $(\mathscr{X}, \mathscr{U})^{\prime}=\left\{\left(X_{(a, i)}^{\prime},\left(\mathcal{U}_{a} \times \mathscr{W}_{i}\right)^{*}\right), p_{\left(a^{\prime}, i^{\prime}\right),(a, i)}^{\prime}, A \times N\right\}$ forms an approximative inverse system. It is not difficult to show that $\boldsymbol{p}^{\prime}=\left\{p_{(a, i)}^{\prime}:(a, i)\right.$ $\in A \times N\}: \operatorname{Cone}(X) \rightarrow(\mathscr{X}, \mathcal{U})^{\prime}$ is an approximative polyhedral resolution. Similarly $\boldsymbol{q}^{\prime}=\left\{q_{(b, i)}^{\prime}:(b, i) \in B \times N\right\}: \operatorname{Cone}(Y) \rightarrow(q, \mathcal{V})^{\prime}=\left\{\left(Y_{(b, i)}^{\prime},\left(\mathcal{V}_{b} \times \mathscr{W}_{i}\right)^{*}\right), q_{(b, i)}^{\prime}, B \times N\right\}$ forms an approximative polyhedral resolution. Maps $f_{b} \times 1_{I}: X_{(f(b), i)}=X_{f(b)} \times I_{i}$ $\rightarrow Y_{(b, i)}=Y_{b} \times I_{i}$ induce maps $f_{(b, i)}^{\prime}: X_{(f(b), i)}^{\prime} \rightarrow Y_{(b, i)}^{\prime}$. It is not difficult to show that $\boldsymbol{f}^{\prime}=\left\{f \times 1_{N}, f_{(b, i)}^{\prime}, B \times N\right\}:(\mathscr{X}, \mathcal{U})^{\prime} \rightarrow(\mathcal{Y}, \mathcal{Q})^{\prime}$ forms an approximative resolution of Cone $(f)$ with respect to $\boldsymbol{p}^{\prime}$ and $\boldsymbol{q}^{\prime}$.
(2.4) Theorem. (i) $f$ is an AE-map iff Cone $(f)$ : $\operatorname{Cone}(X) \rightarrow \operatorname{Cone}(Y)$ is an AE-map.
(ii) $f$ is an NE-map iff Cone $(f)$ is an NE-map.

Proof. We show (ii). In a similar way we can show (i). First we assume that $\boldsymbol{f}$ is an NE-map. We show that $\boldsymbol{f}^{\prime}$ satisfies (NE). Take any $(b, i) \in$ $B \times N$. Since $\boldsymbol{f}$ satisfies (NE), there exists $a>f(b)$ satisfying (NE) for $\boldsymbol{f}$ and $b$. We show that $(a, i)$ is the required index. To do so take any $\left(b^{\prime}, i^{\prime}\right)>(b, i)$. By the choice of $a$ there exists a map $r: X_{a} \rightarrow Y_{b^{\prime}}$ such that

$$
\begin{equation*}
\left(f_{b} p_{a, f(b)}, q_{b^{\prime}, b r}\right)<s t \subset \mathcal{V}_{b} \tag{1}
\end{equation*}
$$

The map $r \times 1_{I}: X_{a} \times I \rightarrow Y_{b^{\prime}} \times I$ induces a map $r^{\prime}: X_{(a, i)}^{\prime} \rightarrow Y_{\left(b^{\prime}, i^{\prime}\right)}^{\prime}$. By (1) $\left(f_{(b, i)}^{\prime} p_{(a, i),(f(b), i)}^{\prime}, q_{\left(b^{\prime}, i^{\prime}\right),(b, i)}^{\prime} r^{\prime}\right)<s t\left(\left(C V_{b} \times \mathscr{W}_{i}\right)^{*}\right)$. This means that $\boldsymbol{f}^{\prime}$ satisfies (NE) and hence Cone $(f)$ is an NE-map.

Next we assume that Cone $(f)$ is an NE-map. Then $\boldsymbol{f}^{\prime}$ satisfies (NE). We show that $\boldsymbol{f}$ satisfies (NE). Take any $b \in B$. Put $\mathscr{W}=\{[0,2 / 6),(1 / 6,3 / 6),(2 / 6$, $4 / 6),(3 / 6,5 / 6),(4 / 6,1]\} \in \mathcal{C} \operatorname{oo}(I) . \mathrm{By}(\mathrm{R} 1)$ there exists $i \in N$ such that $\mathscr{W}>r_{i}^{-1} \mathscr{W}_{i}$ $=\mathscr{W}_{i}$. There exists $(a, j)>(f(b), i)$ satisfying (NE) for $\boldsymbol{f}^{\prime}$ and $(b, i)$. We show that $a>f(b)$ is the required index. To do so take any $b^{\prime}>b$. By the choice of $(a, j)$ there exists a map $k: X_{(a, j)}^{\prime} \rightarrow Y_{\left(b^{\prime}, i\right)}^{\prime}$ such that $\left(f_{(b, i)}^{\prime} p_{(a, j),(f(b), i)}^{\prime}, q_{\left(b^{\prime}, i\right),(b, i)}^{\prime} k\right)$ $<s t\left(\left(\mathcal{V}_{b} \times \mathscr{W}_{i}\right)^{*}\right)$. By the choice of $i\left(f_{(b, i)}^{\prime} p_{(a, j),(f(b), i)}^{\prime} t_{X_{a}}, q_{\left(b^{\prime}, i\right),(b, i)}^{\prime} k t_{X_{a}}\right)<s t\left(\left(\mathcal{V}_{b}\right.\right.$ $\left.\times \mathscr{W})^{*}\right)$. Since $f_{(b, i)}^{\prime} p_{(a, j),(f(b), i)}^{\prime} t_{X_{a}}=t_{Y_{b}}\left(f_{b} p_{a, f(b)} \times 1_{I}\right)$, for each $x \in X_{a}$ there exists $V \in \mathscr{V}_{b}$ such that
(2) $\quad t_{Y_{b}}\left(f_{b} p_{a, f(b)}(x), 0\right), q_{\left(b^{\prime}, i\right),(b, i)}^{\prime} k t_{X_{a}}(x, 0) \in t_{Y_{b}}\left(s t\left(V, C V_{b}\right) \times[0,4 / 6)\right)$.

Thus $\quad k t_{X_{a}}(x, 0) \in t_{Y_{b^{\prime}}}\left(Y_{b^{\prime}} \times[0,4 / 6)\right)$. Since $\quad t_{Y_{b^{\prime}}} \mid Y_{b^{\prime}} \times[0,4 / 6): Y_{b^{\prime}} \times[0,4 / 6) \rightarrow$ $t_{Y_{b^{\prime}}}\left(Y_{b^{\prime}} \times[0,4 / 6)\right)$ is a homeomorphism, we can define a map $k^{\prime}: X_{a} \rightarrow Y_{b^{\prime}}$ by $k^{\prime}(x)=u t_{\overline{b_{l}},}^{1}, k t_{X_{a}}(x, 0)$ for $x \in X_{a}$. Here $u: Y_{b^{\prime}} \times I \rightarrow Y_{b^{\prime}}$ is the projection. Then (2) means that $f_{b} p_{a, f(b)}(x), q_{b^{\prime}, b} k^{\prime}(x) \in s t\left(V, \mathcal{V}_{b}\right)$. Hence $\left(f_{b} p_{a, f(b)}, q_{b^{\prime}, b} k^{\prime}\right)<s t \subset V_{b}$ and $f$ is an NE-map.
(2.5) Corollary. (i) $X$ is an AP iff Cone $(X)$ is an AP.
(ii) $X$ is AM iff Cone $(X)$ is AM.
(iii) $X$ is an $\operatorname{AANR}_{C}$ for COM iff $\operatorname{Cone}(X)$ is an AAR for COM.

Proof. (i) follows from (1.21) and (2.4). (ii) follows from (1.12) and (2.4). (iii) follows from (II. 5.10), (II. 5.12) and the following fact: $\operatorname{Cone}(X)$ is contractible and hence has the trivial shape.
$S(X)$ denotes the suspension of $X$. A map $f: X \rightarrow Y$ induces a map $S(f): S(X)$ $\rightarrow S(Y)$.
(2.6) Theorem. (i) $f$ is an AE-map iff $S(f)$ is an AE-map.
(ii) $f$ is an NE-map iff $S(f)$ is an NE-map.
(2.7) Corollary. (i) $X$ is an AP iff $S(X)$ is an AP.
(ii) $\quad X$ is AM iff $S(X)$ is AM.
(2.8) Lemma. If $X$ satisfies the condition $M$, then so does $S(X)$.
(2.9) Corollary. (i) $X$ is an $\mathrm{AANR}_{C}$ for $\mathbf{C O M}$ iff so is $S(X)$.
(ii) If $X$ is an $\operatorname{AANR}_{N}$ for COM, then so is $S(X)$.

In a way similar to the one used in (2.4) and (2.5) we can show (2.6), (2.7) and (i) of (2.9). By a straightforward argument as used in (2.2) we can show (2.8). (ii) of (2.9) follows from (II. 5.11) and (i) of (2.9).

Let $X^{c}$ be a connected component of $X$ and $X_{a}^{c}$ a connected component of $X_{a}$ with $p_{a}\left(X^{c}\right) \subset X_{a}^{c}$ for $a \in A$. Put $\mathcal{U}_{a}^{c}=\left\{U \cap X_{a}^{c}: U \in \mathcal{U}_{a}\right\} \in \operatorname{Cov}\left(X_{a}^{c}\right)$. Let $p_{a}^{c}: X^{c} \rightarrow X_{a}^{c}$ and $p_{a^{\prime}, a}^{c}: X_{a^{\prime} \rightarrow X_{a}^{c}}^{c}$ be induced maps by $p_{a}$ and $p_{a^{\prime}, a}$ for $a^{\prime}>a$. Then it is easy to show that $p^{c}=\left\{p_{a}^{c}: a \in A\right\}: X^{c} \rightarrow(\mathscr{X}, \mathcal{U})^{c}=\left\{\left(X_{a}^{c}, \mathcal{U}_{a}^{c}\right), p_{a^{\prime} a}^{c}, A\right\}$ forms an approximative finite polyhedral resolution.
$f: X \rightarrow Y$ induces a map $f^{c}=f \mid X^{c}: X^{c} \rightarrow Y$. For each $b \in B \quad f_{b}: X_{f(b)} \rightarrow Y_{b}$ induces a map $f_{b}^{c}=f_{b} \mid X_{f(b)}^{c}: X_{f(b)}^{c} \rightarrow Y_{b}$. Since $\boldsymbol{f}:(\mathcal{X}, \mathcal{U}) \rightarrow(q, \mathcal{Q})$ is an appoximative resolution of $f$ with $\boldsymbol{p}$ and $\boldsymbol{q}, \boldsymbol{f}^{c}=\left\{f, f_{\dot{\varepsilon}}^{\ell}: b \in B\right\}:(\mathscr{X}, \mathcal{Q})^{c} \rightarrow(q, \mathcal{Q})$ is an approximative resolution of $f^{c}$ with respect to $\boldsymbol{p}^{c}$ and $\boldsymbol{q}$.
(2.10) Theorem. (i) $f: X \rightarrow Y$ is an AE-map iff $f^{c}: X^{c} \rightarrow Y$ is an AE-map for each connected component $X^{c}$ of $X$.
(ii) $f$ is an NE-map iff all $f^{c}$ are NE-maps.

Proof. We show (ii). In a similar way we can show (i). First we assume that $f$ is an NE-map. Take any connected component $X^{c}$ of $X$ and let $j^{c}: X^{c} \rightarrow X$ be the inclusion map. Since $f^{c}=f j^{c}$, by (1.8) $f^{c}$ is an NE-map.

Next we assume that all $f^{c}$ are NE-maps and show that $f$ is an NE-map. Take any $b \in B$ and any connected component $X^{c}$ of $X$. Since $\boldsymbol{f}^{c}:(\mathscr{X}, \mathscr{U})^{c} \rightarrow$ $\left(q_{g}, C\right)$ ) satisfies (NE), there exists $a(c)>f(b)$ satisfying (NE) for $\boldsymbol{f}^{c}$ and $b$. Since all $X_{a}$ are finite polyhedra, all connected components are open and closed. Then $X_{a(c)}^{c}$ is open and closed. Put $U^{\prime}\left(X^{c}\right)=p_{a}^{-1}(c)\left(X_{a(c)}^{c}\right)$ and then $U^{\prime}\left(X^{c}\right)$ is an open and closed neighborhood of $X^{c}$ in $X$. Put $U^{\prime}=\left\{U^{\prime}\left(X^{c}\right): X^{c}\right.$ is a connected component of $X\} \in \operatorname{Cov}(X)$. Since $X$ is compact, there exist finitely many connected components $X^{c 1}, X^{c 2}, \cdots, X^{c n}$ such that $X=\cup\left\{U^{\prime}\left(X^{c i}\right): i=1,2, \cdots, n\right\}$. Put $U_{i}=U^{\prime}\left(X^{c i}\right)-\cup\left\{U^{\prime}\left(X^{c j}\right): j=1,2, \cdots, i-1\right\}$ for each $i$ and then
all $U_{i}$ are open and closed, $U_{i} \cap U_{j}=\varnothing$ for $i \neq j$, and

$$
\begin{equation*}
U=\left\{U_{i}: i=1,2, \cdots, n\right\} \in \mathcal{C} \operatorname{Ov}(X) . \tag{1}
\end{equation*}
$$

By (1) there exists a canonical map $\boldsymbol{p}: X \rightarrow N(\mathcal{U})$ such that

$$
\begin{equation*}
p^{-1}(U)=U \text { for } U \in \mathcal{U} \text { and } N(\mathcal{U}) \text { is 0-dimensional. } \tag{2}
\end{equation*}
$$

Here $N(\mathscr{U})$ denotes the nerve of $\mathcal{U}$. Since $N(U)$ is 0 -dimensional by (1), then by (R1) there exist $a>a(c 1), \cdots, a(c n)$ and a map $h: X_{a} \rightarrow N(\mathcal{U})$ such that

$$
\begin{equation*}
p=h p_{a} . \tag{3}
\end{equation*}
$$

We define $K_{i}=\cup\left\{T: T\right.$ is a connected component of $X_{a}$ and $\left.T \cap p_{a}\left(U_{i}\right) \neq \varnothing\right\}$ for each $i$. Then all $K_{i}$ are open and closed in $X_{a}$ such that

$$
\begin{equation*}
p_{a}(X) \subset \cup\left\{K_{i}: i=1,2, \cdots, n\right\} \text { and } p_{a}(X) \cap K_{i} \neq \varnothing \text { for each } i . \tag{4}
\end{equation*}
$$

Claim 1. $K_{i} \cap K_{j}=\varnothing$ for $i \neq j$.
We assume $K_{i} \cap K_{j} \neq \varnothing$ for some $i \neq j$. Then there exists a connected component $T$ of $X_{a}$ satisfying $T \cap p_{a}\left(U_{i}\right) \neq \varnothing$ and $T \cap p_{a}\left(U_{j}\right) \neq \varnothing$. Since $N(\mathscr{U})$ is 0 -dimensional, $h(T) \in h p_{a}\left(U_{i}\right)$ and $h(T) \in h p_{a}\left(U_{j}\right)$. Since $h p_{a}\left(U_{i}\right)=p_{a}\left(U_{i}\right)=\left\{U_{i}\right\}$ and $h p_{a}\left(U_{j}\right)=\left\{U_{j}\right\}$ by $(3), h(T)=\left\{U_{i}\right\}=\left\{U_{j}\right\}$ and hence $i=j$. This is a contradiction. Hence we have Claim 1.

CLAIM 2. $\quad p_{a, a(c i)}\left(K_{i}\right) \subset X_{a(c i)}^{i{ }_{i}}$ for $1 \leqq i \leqq n$.
Take any $y \in K_{i}$ and then there exists a connected component $T$ such that $y \in T$ and $T \cap p_{a}\left(U_{i}\right) \neq \varnothing$. Thus there exists $x \in U_{i}$ with $p_{a}(x) \in T$. Since $U_{i} \subset U^{\prime}\left(X^{c i}\right)=p_{a(c i)}^{-1}\left(X_{a(c i)}^{c i}\right), p_{a(c i)}(x) \in X_{a(c i)}^{c i}$. Since $T$ is connected, $p_{a, a(c i)}(y)$, $p_{a(c i)}(x) \in p_{a, a(c i)}(T) \subset X_{a(c i)}^{c i}$. Thus $p_{a, a(c i)}(y) \in X_{a(c i)}^{c i}$ and hence we have Claim 2.

Put $\left.\left.K_{0}=X_{a}-\cup\right\} K_{i}: 0 \leqq i \leqq n\right\}$ and then $K_{0}$ is open and closed. Let $\mathcal{K}=$ $\left\{K_{i}: 0 \leqq i \leqq n\right\} \in \mathcal{C} o o\left(X_{a}\right)$ and then $\operatorname{st}\left(p_{a}(X), \mathcal{K}\right)=\cup\left\{K_{i}: 1 \leqq i \leqq n\right\}$. By (B4) there exists $a_{1}>a$ such that $p_{a_{1}, a}\left(X_{a_{1}}\right) \subset s t\left(p_{a}(X), \mathcal{K}\right)$. Put $L_{i}=p_{a_{1}, a}^{-1}\left(K_{i}\right)$ for $1 \leqq i \leqq n$ and then by Claim 1
(5) All $L_{i}$ are open and closed in $X_{a_{1}}$ and $X_{a_{1}}=\cup\left\{L_{i}: i=1,2, \cdots, n\right\}$ and $L_{i} \cap L_{j}=\varnothing$ for $i \neq j$.
We show that $a_{1}$ is the required index. Take any $b^{\prime}>b$. By the choice of $a(c i)$ there exists a map $g_{c i}: X_{a}^{c i} i(c i) \rightarrow Y_{b^{\prime}}$ such that $\left(q_{b^{\prime}, 0} g_{c i}, f_{b}^{c i} p_{a}^{c i}(c i), f(b)\right)<s t \subset V_{b}$, i.e.,

$$
\begin{equation*}
\left(q_{b^{\prime}, b} g_{c i}, f_{b} p_{a(c i), f(b)} \mid X_{a(c i)}^{c i}\right)<s t V_{b} . \tag{6}
\end{equation*}
$$

By Claim 2

$$
\begin{equation*}
p_{a_{1}, a(c i)}\left(L_{i}\right) \subset X_{a(c i)}^{c i} \quad \text { for } \quad 1 \leqq i \leqq n \tag{7}
\end{equation*}
$$

Now we define a map $g: X_{a_{1} \rightarrow} \rightarrow Y_{b^{\prime}}$ as follows: For each $y \in L_{i} g(y)=g_{c i} p_{a_{1}, a(c i)}(y)$. By (5) and (7) $g$ is well defined and continuous. By (6) $\left(q_{b^{\prime}, b} g, f_{b} p_{a_{1}, f(b)}\right)<s t \nabla_{b}$. This means that $\boldsymbol{f}$ satisfies (NE) and hence $f$ is an NE-map.

For any connected component $X^{c}$ of $X$ there exists a connected component $Y^{d}$ of $Y$ such that $f\left(X^{c}\right) \subset Y^{d} . f$ induces a map $f^{c, d}: X^{c} \rightarrow Y^{d}$.
(2.11) Corollary. (i) If all $f^{c . d}: X^{c} \rightarrow Y^{d}$ are AE-maps, then $f$ is an AEmap.
(ii) If all $f^{c, d}: X^{c} \rightarrow Y^{d}$ are NE-maps, then $f$ is an NE-map.

Proof. We show (ii). In the same way we can show (i). Since $f^{c, d}: X^{c}$ $\rightarrow Y^{d}$ are NE-maps, $f^{c}=j^{d} f^{c, d}: X^{c} \rightarrow Y$ are NE-maps by (1.8). Here $j^{d}: Y^{d} \rightarrow Y$ is the inclusion map. By (2.10) $f$ is an NE-map.
(2.12) Corollary. (i) If all connected components of $X$ are APs, then so is $X$.
(ii) If all connected components of $X$ are AM, then so is $X$.

In general the converse assertions of (2.11) and (2.12) do not hold, because we have the following example.
(2.13) Example. Let $X$ be a non-movable compact connected metric space. For example we can choose for $X$ the 2 -adic solenoid. Let $\mathfrak{X}=\left\{X_{i}, p_{j, i}, N\right\}$ be an inverse sequence of finite complexes such that $\lim \mathfrak{X}=X$. Put $Y_{i}=v\left\{X_{k}: k\right.$ $=1,2, \cdots, i-1\}$, that is, disjoint sum of $X_{1}, \cdots, X_{i-1}$ for each $i \in N$. We define $r_{i+1, i}: Y_{i+1} \rightarrow Y_{i}$ for each $i \in N$ as follows: $r_{i+1, i}(y)=y$ for $y \in Y_{i}$ and $r_{i+1, i}(y)=$ $p_{i+1, i}(y)$ for $y \in X_{i+1}$. Put $r_{j, i}=r_{j, j-1} \cdots r_{i+1, i}$ for $j \geqq i$. Thus $a j=\left\{Y_{i}, r_{j, i}, N\right\}$ forms an inverse sequence of finite polyhedra. Put $Y=\min \mathscr{Y}$ and then $Y$ is a compact metric space. It is easy to show that $Y$ is an approximative polyhedron and approximatively movable. Then $1_{Y}: Y \rightarrow Y$ is an AE-map and an NE-map. $X$ is a connected component of $Y$. We assume that $1_{X}: X \rightarrow X$ is an NE-map. Then $X$ is AM and hence $X$ is movable. This is a contradiction. Hence $1_{X}$ is not an NE-map and $X$ is not approximatively movable. We see in a similar way that $1_{X}$ is not an AE-map and $X$ is not an AP.

## § 3. Hyperspaces.

In this section we discuss approximative properties of hyperspaces.
In this section all spaces are compact spaces. Let $X$ be a space. We denote by $2^{X}$ the set of all non-empty closed subsets of $X$, by $C(X)$ the set of
all non-empty connected closed subsets of $X$, and by $X(n), n$ is a positive integer, the set of all non-empty subsets of $X$ consisting of at most $n$ points. $C(X)$ and $X(n)$ are subsets of $2^{x}$.

For open subsets $U_{1}, U_{2}, \cdots, U_{k}$ of $X$ we put $\left\langle U_{1}, U_{2}, \cdots, U_{k}\right\rangle=\left\{K \in 2^{X}\right.$ : $K \subset \cup_{i=1}^{k} U_{i}$ and $K \cap U_{i} \neq \varnothing$ for each $\left.0 \leqq i \leqq k\right\}$. Then $\left\{\left\langle U_{1}, U_{2}, \cdots, U_{k}\right\rangle: U_{1}, U_{2}\right.$, $\cdots, U_{k}$ are open subsets of $X$ and $\left.k=1,2, \cdots\right\}$ forms a base of a topology of $2^{X}$. This topology of $2^{x}$ is called the finite topology or the Vietoris topology. $2^{x}$ denotes the topological space with the Vietoris topology. We consider $C(X)$ and $X(n)$ as subspaces of $2^{x}$. These spaces are called hyperspaces of $X . \quad X(n)$ is the $n$-th symmetric product of $X$ (see Borsuk-Ulam [7] and Jaworowski [24]). Concerning hyperspaces see Kuratowski [32], Michael [37] and Nadler [39].

Let $\mathcal{U} \in \mathcal{C}_{o v}(X)$ and put $\langle Q\rangle=\left\{\left\langle U_{1}, U_{2}, \cdots, U_{k}\right\rangle: U_{1}, \cdots, U_{k} \in \mathcal{U}\right.$ and $k=$ $1,2, \cdots\}$. Then $\langle Q\rangle$ forms an open covering of $2^{x}$ and $\{\langle\vartheta\rangle: U \in \operatorname{Cov}(X)\}$ forms a uniformity of $2^{x}$ by Morita [38]. By the uniqueness of uniformities on compact spaces we have the following:
(3.1) Lemma. The uniformities $\{\langle\mathcal{U}\rangle: \mathcal{U} \in \operatorname{Cov}(X)\}$ and $\operatorname{Cov}\left(2^{x}\right)$ are equivalent, that is, for each $\mathscr{W} \in \operatorname{Cov}\left(2^{X}\right)$ there exists $\mathcal{U} \in \operatorname{Cov}(X)$ such that $\left.\mathscr{W}\right\rangle\langle\mathcal{U}\rangle$.

Let $Y$ be a space and $f: X \rightarrow Y$ a map. Then $f$ induces a map $f^{*}: 2^{X} \rightarrow 2^{Y}$ as follows: $f^{*}(K)=f(K)$ for each $K \in 2^{X}$. Clearly $f^{*}$ induces maps $f^{*}: C(X) \rightarrow$ $C(Y)$ and $f^{*}: X(n) \rightarrow Y(n)$ for each positive integer $n$. The following is an easy consequence of the definitions:
(3.2) Lemma. Let $\mathcal{U} \in \operatorname{Cov}(X)$ and $\mathcal{C} \in \mathcal{C} \operatorname{Cov}(Y)$. If $\left.f^{-1} \subset \cup\right\rangle \mathcal{U}$ then $f^{*-1}\langle\mathcal{V}\rangle$ $>\langle q\rangle$, where $f^{*}: 2^{X} \rightarrow 2^{Y}$. Similarly this holds for $f^{*}: C(X) \rightarrow C(Y)$ and $f^{*}: X(n)$ $\rightarrow Y(n)$, respectively.

Let $p=\left\{p_{a}: a \in A\right\}: X \rightarrow(\mathscr{X}, \mathcal{Y})=\left\{\left(X_{a}, \mathcal{U}_{a}\right), p_{a^{\prime}, a}, A\right\}$ be an approximative resolution of $X$.
(3.3) Lemma. $\boldsymbol{p}^{*}=\left\{p_{a}^{*}: a \in A\right\}: 2^{x} \rightarrow 2^{(x, q)}=\left\{\left(2^{x_{a}},\left\langle\mathcal{U}_{a}\right\rangle\right), p_{a^{\prime}, a}^{*}, A\right\}, p^{*}: C(X)$ $\rightarrow C(\mathscr{X}, \mathcal{U})=\left\{\left(C\left(X_{a}\right),\left\langle\mathcal{U}_{a}\right\rangle \mid C\left(X_{a}\right)\right), p_{a^{\prime}, a}^{*}, A\right\}$ and $p^{*}: X(n) \rightarrow(\mathscr{X}, \mathcal{U})(n)=\left\{\left(X_{a}(n)\right.\right.$, $\left.\left.\left\langle\mathcal{U}_{a}\right\rangle \mid X_{a}(n)\right), p_{a^{\prime}, a}^{*}, A\right\}$ are approximative resolution of $2^{x}, C(X)$ and $X(n)$, respectively.

Proof. We show the first case. In the same way we can show the others.

$$
\begin{equation*}
2^{(x, q)} \text { is an approximative inverse system. } \tag{1}
\end{equation*}
$$

We need to show (AI1)-(AI3). Clearly (AI1) holds and (Al2) follows from
(3.2) and (AI2) for ( $\mathscr{X}, \mathscr{U}$ ). Take any $a \in A$ and any $\mathscr{W} \in \mathcal{C o v}\left(2^{X_{a}}\right)$. By (3.1) there exists $\mathcal{U} \in \mathcal{C o v}\left(X_{a}\right)$ such that $\left.\mathscr{W}\right\rangle\langle\mathcal{U}\rangle$. By (AI3) for $(\mathfrak{X}, \mathcal{U})$ there exists $a^{\prime}>a$ such that $\left.p_{a^{\prime}, a}^{-1} \mathcal{U}\right\rangle \mathcal{U}_{a^{\prime}}$. Thus by (3.2) $\left.\left.p_{a^{\prime}, a}^{*-1} \mathscr{W}\right\rangle p_{a^{\prime}, a}^{*-1}(\langle\mathcal{U}\rangle)\right\rangle\left\langle\mathcal{U}_{a^{\prime}}\right\rangle$. Then we have (AI3) and hence (1).

$$
\begin{equation*}
p^{*}: 2^{x} \rightarrow 2^{x} \text { is a resolution. } \tag{2}
\end{equation*}
$$

By (I. 3.3) $\boldsymbol{p}: X \rightarrow \mathfrak{X}$ is a resolution. Since all spaces are compact, $\boldsymbol{p}: X \rightarrow X$ is an inverse limit by (I.7.1). By Lemma 2 of Kodama-Spiez-Watanabe [31] $p^{*}: 2^{x} \rightarrow 2^{x}$ is an inverse limit. Hence by (I. 3.13) we have (2).

By (1), (2) and (I. 3.3) $\boldsymbol{p}^{*}: 2^{x} \rightarrow 2^{(x, q)}$ forms an approximative resolution.
(3.4) Lemma. Let $f, g: X \rightarrow Y$ be maps and $\mathbb{V} \in \mathcal{C o v}(Y)$. If $(f, g)<\mathcal{V}$, then $\left(f^{*}, g^{*}\right)<\langle\subset\rangle$ for $f^{*}, g^{*}: 2^{X} \rightarrow 2^{Y}$. Similarly this holds for $f^{*}, g^{*}: C(X) \rightarrow C(Y)$ and $f^{*}, g^{*}: X(n) \rightarrow Y(n)$, respectively.

Proof. Take any $K \in 2^{x}$. Since $(f, g)<\varnothing$, for each $x \in K$ there exists $V_{x} \in \mathscr{C}$ such that $f(x), g(x) \in V_{x}$. Thus $f(K) \cup g(K) \subset \cup\left\{V_{x}: x \in X\right\}$. Since $K$ is compact, there exist finitely many points $x_{1}, x_{2}, \cdots, x_{k} \in X$ such that $f(K) \cup$ $g(K) \subset V_{x_{1}} \cup V_{x_{2}} \cup \cdots \cup V_{x_{k}}$. Since $f\left(x_{i}\right), g\left(x_{i}\right) \in V_{x_{i}}$ for $1 \leqq i \leqq k, f(K), g(K) \in$ $\left\langle V_{x_{1}}, V_{x_{2}}, \cdots, V_{x_{k}}\right\rangle$ and hence $\left(f^{*}, g^{*}\right)\langle\langle\mathcal{V}\rangle$. Trivially this implies the other cases.

Let $\boldsymbol{q}=\left\{q_{b}: b \in B\right\}: Y \rightarrow(q, \mathcal{V})=\left\{\left(Y_{b}, \mathcal{V}_{b}\right), q_{b^{\prime}, b}, B\right\}$ be an approximative resolution. Let $\boldsymbol{f}=\left\{f, f_{b}: b \in B\right\}:(\mathcal{X}, \mathcal{U}) \rightarrow(q, \mathcal{V})$ be an approximative resolution of a map $f: X \rightarrow Y$ with respect to $\boldsymbol{p}$ and $\boldsymbol{q}$. Let $\boldsymbol{f}^{*}=\left\{f, f_{b}^{*}: b \in B\right\}: 2^{(x, q)} \rightarrow$ $2^{(q,(v)}, \boldsymbol{f}^{*}=\left\{f, f_{b}^{*} \mid C\left(X_{f(b)}\right): b \in B\right\}: C(X, q) \rightarrow C(q, \mathcal{V})$ and $\boldsymbol{f}^{*}=\left\{f, f_{b}^{*} \mid X_{f(b)}(n):\right.$ $b \in B\}:(\mathscr{X}, \mathcal{U})(n) \rightarrow(q, \mathcal{Q})(n)$. Using (3.4) we can easily show the following:
(3.5) Lemma. $f^{*}: 2^{(x, q)} \rightarrow 2^{(q, q)}$ is an approximative resolution of $f^{*}: 2^{X} \rightarrow 2^{Y}$ with respect to $\boldsymbol{p}^{*}$ and $\boldsymbol{q}^{*}$. This holds for $\boldsymbol{f}^{*}: C(\mathscr{X}, \mathcal{U}) \rightarrow C(q, \mathcal{Q})$ and $\boldsymbol{f}^{*}:(\mathfrak{X}, \mathcal{Q})(n) \rightarrow(q, \mathcal{V})(n)$.
(3.6) Lemma (Wojdyslawski [47]). Let $X$ be a compact metric connected space. Then the following statements are equivalent:
(i) $X$ is locally connected.
(ii) $2^{x}$ is an AR.
(iii) $C(X)$ is an AR.
(3.7) Lemma (Ganea [18]). Let $X$ be a finite dimensional compact metric space. If $X$ is an ANR, then so is $X(n)$ for each positive integer $n$.
(3.8) Theorem. (i) If $f: X \rightarrow Y$ is an AE-map, then $f^{*}: 2^{x} \rightarrow 2^{Y}, f^{*}: C(X)$
$\rightarrow C(Y)$ and $f^{*}: X(n) \rightarrow Y(n)$ are AE-maps for each positive integer $n$.
(ii) If $f$ is an NE-map, then $f^{*}: 2^{X} \rightarrow 2^{Y}, f^{*}: C(X) \rightarrow C(Y)$ and $f^{*}: X(n) \rightarrow Y(n)$ are NE-maps for each positive integer $n$.

Proof. We show (ii). In the same way we can show (i). By (I. 3.15) there exist approximative finite polyhedral resolutions $\boldsymbol{p}: X \rightarrow(\mathscr{X}, \mathcal{U})$ and $\boldsymbol{q}: Y \rightarrow(q, \mathcal{Q})$. By (I.2.1) and (I. 3.3) st $(\boldsymbol{q})=\left\{q_{b}: b \in B\right\}: Y \rightarrow s t(q, q)$ is an approximative resolution. Then by (3.3) and (3.6) $\boldsymbol{p}^{*}: 2^{X} \rightarrow 2^{(x, q)}$ and $s t(\boldsymbol{q})^{*}: 2^{Y} \rightarrow 2^{s t(q)}(\mathscr{y})$ are approximative ANR-resolutions. Let $\boldsymbol{f}:(\mathscr{X}, \mathcal{U}) \rightarrow(\mathcal{q}, \mathcal{V})$ be an approximative resolution of $f$ with respect to $\boldsymbol{p}$ and $\boldsymbol{q}$, and then so is $\boldsymbol{f}$ with respect to $\boldsymbol{p}$ and $s t(\boldsymbol{q})$. By (3.5) $\boldsymbol{f}^{*}: 2^{(x, q)} \rightarrow 2^{s t(q,(q)}$ is an approximative resolution of $f^{*}: 2^{X} \rightarrow 2^{Y}$ with respect to $\boldsymbol{p}^{*}$ and $s t(\boldsymbol{q})^{*}$.

We show that $\boldsymbol{f}^{*}: 2^{(x, q)} \rightarrow 2^{s t(x, q)}$ satisfies (NE). Take any $b \in B$. Since $\boldsymbol{f}:(\mathcal{X}, \mathcal{U}) \rightarrow(q, \mathcal{C})$ satisfies (NE), there exists $a>f(b)$ satisfying (NE) for $\boldsymbol{f}$ and $b$. Then for each $b^{\prime}>b$ there exists a map $r: X_{a} \rightarrow Y_{b^{\prime}}$ such that ( $f_{b} p_{a, f(b)}, q_{b^{\prime}, b r}$ ) $<s t \mathcal{V}_{b}$. Since $\left(f_{b}^{*} p_{a, f(b)}^{*}, q_{b}^{*}, b r^{*}\right)<\left\langle s t \subset \mathcal{V}_{b}\right\rangle$ by (3.4), we have the required condition. Hence $f^{*}$ is an NE-map.
(3.9) Proposition. If $X$ satisfies the condition $M$, then so do $2^{x}, C(X)$ and $X(n)$.

In a way similar to the one used in Theorem 3 of Kodama-Spiez-Watanabe [31] we can easily show (3.9).
(3.10) Corollary. Let $n$ be a positive integer.
(i) If $X$ is an AP, then so are $2^{x}, C(X)$ and $X(n)$.
(ii) If $X$ is an $\mathrm{AANR}_{C}$, then so are $2^{x}, C(X)$ and $X(n)$. If, in addition, $X$ is connected, then $2^{x}, C(X)$ and $X(n)$ are AARs.
(iii) If $X$ is an $\mathrm{AANR}_{N}$, then so are $2^{X}, C(X)$ and $X(n)$.
(iv) If $X$ is AM , then so are $2^{X}, C(X)$ and $X(n)$.
(i) follows from (1.21) and (3.8). (ii) follows from (II. 5.10), (i) and Corollary 1 of Kodama-Spiez-Watanabe [31]. (iii) follows from (i) and (II. 5.11). (iv) follows from (1.12) and (3.8).

A continuum which is hereditarily unicoherent and arcwise connected is a dendroid. A dendroid which satisfies the smoothness condition is a smooth dendroid (see Charatonik-Eberhart [8]). A locally connected dendroid is a dendrite. A finite tree is a finite 1 -dimensional simplicial complex which is connected and does not contain any circle.
(3.11) Proposition. (i) Any dendroid is an AAR.
(ii) Any fan is an AAR.
(iii) Any smooth dendroid is an AAR.

Proof. We show (ii). Take an AR $M$ which contains $X$. Take any $q \in$ $\operatorname{Cov}(X)$. By Theorem 1 of Fugate [16] there exist a finite tree $T$ in $X$ and a retraction $r: X \rightarrow T$ such that $\left(j r, 1_{X}\right)<q$ and $r \mid T=1_{r}$. Here $j: T \rightarrow X$ is the inclusion map. Since $T$ is an AR, there exists a map $r^{\prime}: M \rightarrow T$ such that $r^{\prime} \mid X=r$. Thus ( $j r^{\prime} \mid X, 1_{X}$ )<q and hence $X$ is an AAR by (II. 5.3).

Using Theorem 2 of Fugate [17], in the same way as in (ii) we can easily show (iii). (i) follows from (iii) and Charatonik-Eberhart [8].
(3.12) Corollary. If $X$ is a dendrite, fan or smooth dendroid, then $2^{x}, C(X)$ are AARs.
(3.13) Problem. If $X$ is SAM, are $2^{x}, C(X)$ and $X(n)$ SAM?

## §4. $G$-products of spaces.

In this section we discuss approximative properties of $G$-products of spaces.
In this section all spaces are compact. Let $n$ be a positive integer. $S_{n}$ denotes the symmetric group on $n$ letters, i.e., it consists of all permutations of $\{1,2, \cdots, n\}$. Let $G$ be a subgroup of $S_{n}$. Let $X$ be a space and $X^{n}$ the $n$-th cartesian product with the product topology. Then $G$ can be considered as a subgroup of homeomorphisms of $X^{n}$ defined as follows: $g\left(x_{1}, x_{2}, \cdots, x_{n}\right)=$ $\left(x_{g(1)}, x_{g(2)}, \cdots, x_{g(n)}\right)$ for $g \in G$ and $x=\left(x_{1}, x_{2}, \cdots, x_{n}\right) \in X^{n} . X^{n} / G$ denotes the orbit space under this action with identification topology. We say that $X^{n} / G$ is the $n$-th $G$-product of $X . \quad \eta=\eta_{X}: X^{n} \rightarrow X^{n} / G$ denotes the quotient map. $\eta$ is open and closed, because $\eta^{-1} \eta(K)=\cup\{g(K): g \in G\}$ for $K \subset X^{n}$, all $g$ are homeomorphisms and $G$ is a finite set.

Let $f, f^{\prime}: X \rightarrow Y$ be maps. Then $f$ induces a map $f^{n}: X^{n} \rightarrow Y^{n}$ defined by $f^{n}\left(x_{1}, x_{2}, \cdots, x_{n}\right)=\left(f\left(x_{1}\right), f\left(x_{2}\right), \cdots, f\left(x_{n}\right)\right)$. Since $f^{n}$ commutes with the actions of $G$ on $X^{n}$ and $Y^{n}$, it induces a unique map $\underline{f}: X^{n} / G \rightarrow Y^{n} / G$ satisfying $\eta_{Y} f^{n}$ $=f \eta_{X}$. It is easy to show that $\underline{g} \circ \underline{f}=\underline{g} f$ and $\underline{1}_{X}=1_{X^{n / G}}$ for any map $g: Y \rightarrow Z$.
(4.1) Lemma. If $f, f^{\prime}$, then $\underline{f} \simeq \underline{f}^{\prime}$.

Proof. Take a homotopy $h: X \times I \rightarrow Y$ such that $h_{0}=f$ and $h_{1}=f^{\prime}$. We define a map $h^{n}: X^{n} \times I \rightarrow Y^{n}$ by $h^{n}\left(x_{1}, x_{2}, \cdots, x_{n}, t\right)=\left(h\left(x_{1}, t\right), h\left(x_{2}, t\right), \cdots, h\left(x_{n}, t\right)\right)$. It induces a function $H: X^{n} / G \times I \rightarrow Y^{n} / G$ satisfying $H\left(\eta_{X} \times 1_{I}\right)=\eta_{Y} h^{n}$. Since $\eta_{X}$ is a quotient map, by Theorem 3.3.17 of Engelking [14, p. 200] $\eta_{X} \times 1_{I}$ is
also a quotient map. Thus $H$ is continuous and $H_{0}=\underline{f}, H_{1}=\underline{f}^{\prime}$. Hence $\underline{f} \simeq \underline{f^{\prime}}$.
(4.2) Theorem. If $X$ is a compact metric ANR or AR, then $X^{n} / G$ is an ANR or an AR, respectively.

Proof. Maxwell [36] proved that
(1) If $K$ is a finite simplicial complex, then so is $K^{n} / G$.

First we assume that $X$ is a compact metric ANR and show that $X^{n} / G$ is an ANR. Since $G$ is a finite set, $\eta$ is a proper (perfect) map and then by Theorem 4.4.15 of Engelking [14, p. 355] $X^{n} / G$ is compact metric.

Take any $\mathcal{V} \in \operatorname{Cov}\left(X^{n} / G\right)$. There exists $\mathcal{U} \in \operatorname{Coo}(X)$ such that $\mathcal{U}^{n}=\mathcal{U} \times \mathcal{U}$ $\times \cdots \times \mathscr{U}<\eta^{-1} \mathbb{C} V$. Since $X$ is an ANR, by Corollary 6.2 of Hu [23, p. 139] there exist a finite simplicial complex $K$ and maps $f: X \rightarrow K, g: K \rightarrow X$ such that $g f$ is $\mathcal{U}$-homotopic to $1_{X}$. Take a $\mathcal{U}$-homotopy $h: X \times I \rightarrow X$ such that $h_{0}=g f$ and $h_{1}=1_{X}$. By (4.1) $h$ induces a homotopy $H: X^{n} / G \times I \rightarrow X^{n} / G$ such that $H_{0}=\underline{h}_{0}=$ $g f$ and $H_{1}=\underline{h}_{1}=1_{X^{n / G}}$.

## $H$ is a $C V$-homotopy.

Take any $x=\left(x_{1}, x_{2}, \cdots, x_{n}\right) \in X^{n}$. Since $h$ is a $\mathcal{U}$-homotopy, there exist $U_{i} \in \mathcal{U}$ such that $h\left(x_{i} \times I\right) \subset U_{i}$ for all $i$. By the choice of $\mathcal{U}$ there exists $V \in \mathbb{V}$ such that $U_{1} \times \cdots \times U_{n} \subset \eta^{-1} V$. Then $H(\eta(x) \times I)=H \circ \eta \times 1_{I}(x \times I)=\eta h^{n}(x \times I) \subset$ $\eta\left(U_{1} \times \cdots \times U_{n}\right) \subset V$. Hence we have (2).

By (1), (2) and Theorem 3.6 of Hu [23, p. 139], $X^{n} / G$ is a compact metric ANR.

Next we assume that $X$ is an AR and show that $X^{n} / G$ is an AR. By the assumption $X$ is a contractible ANR, that is, $X$ is homotopy equivalent to a one point space *. By (4.1) $X^{n} / G$ is homotopy equivalent to $*^{n} / G=*$. Thus $X^{n} / G$ is a contractible ANR and hence an AR.
(4.3) Remark. (4.2) was formulated by Jaworowski [25]. However Fedorchuk [15] pointed out a gap in his proof, and gave another proof. This proof depends on deep results in the theory of $Q$-manifolds and Fedorchuk used Schepin's theory. Our proof, which depends on (1) in (4.2), is elementary and simple.

Let $\mathscr{X}=\left\{X_{a}, p_{a^{\prime}, a}, A\right\}$ be an inverse system of compact spaces and let $\boldsymbol{p}=$ $\left\{p_{a}: a \in A\right\}: X \rightarrow \mathfrak{X}$ be an inverse limit. Then $\boldsymbol{p}^{n}=\left\{p_{a}^{n}: a \in A\right\}: X^{n} \rightarrow \mathfrak{X}^{n}=$ $\left\{X_{a,}^{n}, p_{a^{\prime}, a}^{n}, A\right\}$ is an inverse limit. Moreover $\underline{p}=\left\{\underline{p}_{a}: a \in A\right\}: X^{n} / G \rightarrow \mathfrak{X}^{n} / G=$ $\left\{X_{a}^{n} / G, \underline{p}_{a^{\prime}, a}, A\right\}$ forms a system map.
(4.4) Lemma. $\boldsymbol{p}: X^{n} / G \rightarrow \mathfrak{X}^{n} / G$ is an inverse limit

Proof. Let $\boldsymbol{q}=\left\{q_{a}: a \in A\right\}: Y \rightarrow \mathfrak{X}^{n} / G$ be a system map. We need to show that there exists a unique map $q: Y \rightarrow X^{n} / G$ such that $\boldsymbol{q}=\boldsymbol{p} q$, that is,

$$
\begin{equation*}
q_{a}=\underline{p}_{a} q \quad \text { for } \quad a \in A . \tag{1}
\end{equation*}
$$

Since $\boldsymbol{p}^{n}: X^{n} \rightarrow \mathfrak{X}^{n}$ is an inverse limit, by Lemma 2 of Kodama-Spiez-Watanabe [31]
(2) $\boldsymbol{p}^{n *}=\left\{\left(p_{a}^{n}\right)^{*}: a \in A\right\}: 2^{X^{n}} \rightarrow 2^{x n}==\left\{2^{x_{a}^{n}},\left(p_{a^{\prime}, a}^{n}\right)^{*}, A\right\}$ is an inverse limit.

Since $\eta_{a}=\eta_{x_{a}}: X_{a}^{n} \rightarrow X_{a}^{n} / G$ is open and closed, by Theorem 2 of Kuratowski [32, I. p. 165] $\eta_{a}^{-1}: 2^{X_{a}^{n / G}} \rightarrow 2^{X_{a}^{n}}$ is continuous. Let $j_{a}: X_{a}^{n} / G \rightarrow 2^{X_{a}^{n / G}}$ and $j: X^{n} / G \rightarrow 2^{X^{n / G}}$ be natural inclusion maps. From the definitions it is easy to show that

$$
\begin{array}{ll}
\left(p_{a^{\prime}, a}^{n}\right)^{*} \eta_{a^{-1}}^{-1} j_{a^{\prime}}=\eta_{a}^{-1} j_{a} \underline{p}_{a^{\prime}, a} & \text { for } \quad a^{\prime}>a \quad \text { and } \\
\left(\underline{p}_{a}^{n}\right)^{*} \eta_{X}^{-1} j=\eta_{a}^{-1} j_{a} \underline{p}_{a} & \text { for } \quad a \in A . \tag{4}
\end{array}
$$

By (3) $\left\{\eta_{a}^{-1} j_{a} q_{a}: a \in A\right\}: Y \rightarrow 2^{x n}$ forms a system map. By (2) there exists a unique map $s: Y \rightarrow 2^{X^{n}}$ such that

$$
\begin{equation*}
\left(p_{a}^{n}\right)^{*} s=\eta_{a}^{-1} j_{a} q_{a} \quad \text { for } \quad a \in A \tag{5}
\end{equation*}
$$

We show that

$$
\begin{equation*}
\eta_{X}^{\frac{*}{*}} s(Y) \subset j\left(X^{n} / G\right) . \tag{6}
\end{equation*}
$$

To prove (6) take any $y \in Y$. Then $s(y)$ is a subset of $X^{n}$. We need to show that $\eta_{X}(s(y))$ is a singleton set, i.e., for $x, x^{\prime} \in s(y)$, there exists $g \in G$ such that $x^{\prime}=g(x)$. Since $\eta_{a} p_{a}^{n}(s(y))=\left\{q_{a}(y)\right\}$ for each $a \in A$ by (5), $\eta_{a} p_{a}^{n}(x)=$ $\eta_{a} p_{a}^{n}\left(x^{\prime}\right)$. Thus there exists $g_{a} \in G$ such that

$$
\begin{equation*}
g_{a}\left(p_{a}^{n}(x)\right)=p_{a}^{n}\left(x^{\prime}\right) \tag{7}
\end{equation*}
$$

For each $a \in A$ we put $G_{a}=\left\{g \in G: g\left(p_{a}^{n}(x)\right)=p_{a}^{n}\left(x^{\prime}\right)\right\}$. We consider $G_{a}$ as a space with discrete topology. Since $G$ is a finite set, all $G_{a}$ are compact spaces. Since $G_{a^{\prime}} \subset G_{a}$ for $a^{\prime}>a, G=\left\{G_{a}, i_{a^{\prime}, a}, A\right\}$ forms an inverse system of compact spaces, where $i_{a^{\prime}, a}: G_{a} \rightarrow G_{a}$ are inclusion maps for $a^{\prime}>a$. Since $G_{a} \neq \varnothing$ for all $a \in A$ by (7), $\lim \mathcal{G}=\cap\left\{G_{a}: a \in A\right\} \neq \varnothing$. For each $g \in \lim \mathcal{G}, g \in G_{a}$ and then $p_{a}^{n}\left(x^{\prime}\right)=g\left(p_{a}^{n}(x)\right)=p_{a}^{n}(g(x))$ for all $a \in A$. By (2) $x^{\prime}=g(x)$. Hence we have (6).

Since $j$ is an embedding, by (6) we obtain a continuous map $q=j^{-1} \eta_{X}^{\frac{1}{x}} s: Y$ $\rightarrow X^{n} / G$. We show that $q$ satisfies (1). Take any $a \in A$ and any $y \in Y$. By (5) $j_{a} \underline{p}_{a} q(y)=\underline{p}_{a}^{*} j q(y)=\underline{p}_{a}^{*} j j^{-1} \eta_{x}^{*} s(y)=\underline{p}_{a}^{*} \eta_{a}^{*} s(y)=\eta_{a}^{*} p_{a}^{n *} s(y)=\eta_{a}^{*} \eta_{a}^{-1} j_{a} q_{a}(y)=$ $\eta_{a}\left(\eta_{a}^{-1}\left\{q_{a}(y)\right\}\right)=\left\{q_{a}(y)\right\}=j_{a} q_{a}(y)$. Since $j_{a}$ is $1-1$, we have (1).

We show the uniqueness of $q$. We assume that $q^{\prime}: Y \rightarrow X^{n} / G$ is a map such that $\underline{p}_{a} q^{\prime}=q_{a}$ for all $a \in A$, and show that $q=q^{\prime}$. For any $a \in A$ and $y \in Y$ by
(1) and (4) $p_{a}^{n *} \eta_{X}^{-1} j q^{\prime}(y)=\eta_{a}^{-1} j_{a} \underline{p}_{a} q^{\prime}(y)=\eta_{a}^{-1} j_{a} q_{a}(y)=\eta_{a}^{-1} j_{a} \underline{p}_{a} q(y)=p_{a}^{n *} \eta_{x}^{-1} j q(y)$. By
(2) $\eta_{x}^{-1} j q^{\prime}(y)=\eta_{x}^{-1} j q(y)$ and then $\left\{q^{\prime}(y)\right\}=\eta_{X} \eta_{x}^{-1}\left\{q^{\prime}(y)\right\}=\eta_{X} \eta_{x}^{-1} j q^{\prime}(y)=\eta_{X} \eta_{x}^{-1} j q(y)$ $=\{q(y)\}$. Thus $q^{\prime}(y)=q(y)$ and hence $q^{\prime}=q$.

For $\mathcal{U} \in \mathcal{C}_{o v}(X)$ we put $\mathcal{U}^{n}=\mathscr{U} \times \cdots \times \mathcal{U}(n$-times $) \in \mathcal{C}_{o v}\left(X^{n}\right)$. Since $\eta_{X}$ is an open map, $\eta_{X}\left(\mathscr{U}^{n}\right)=\left\{\eta_{X}\left(U_{2} \times \cdots \times U_{n}\right): U_{i} \in \mathscr{U}\right.$ for $\left.1 \leqq i \leqq n\right\}$ forms a covering of $X^{n} / G$.
(4.5) Lemma. Let $f, g: X \rightarrow Y$ be maps and $\mathcal{U} \in \operatorname{Cov}(X), \mathcal{V} \in \operatorname{Cov}(Y)$.
(i) If $(f, g)<\subset)$, then $(\underline{f}, \underline{g})<\eta_{Y}\left(\mathcal{V}^{n}\right)$.
(ii) If $(f, g)<s t \subset V$, then $(\underline{f}, \underline{g})<\operatorname{st}\left(\eta_{Y}\left(\subset V^{n}\right)\right)$,
(iii) If $f^{-1} \mathcal{V}>\mathcal{U}$, then $\underline{f}^{-1} \eta_{Y}\left(C V^{n}\right)>\eta_{X}\left(\mathcal{U}^{n}\right)$.

Proof. We show (ii). In a similar way we can easily show (i) and (iii). Take any $x=\left(x_{1}, x_{2}, \cdots, x_{n}\right) \in X^{n}$. By the assumption for each $i$ there exists $V_{i} \in \mathcal{V}$ such that $f\left(x_{i}\right), g\left(x_{i}\right) \in s t\left(V_{i}, \mathcal{V}\right)$. Then there exist $V_{i}^{\prime}, V_{i}^{\prime \prime} \in \mathcal{V}$ such that $f\left(x_{i}\right) \in V_{i}^{\prime}, g\left(x_{i}\right) \in V_{i}^{\prime \prime}, V_{i}^{\prime} \cap V_{i} \neq \varnothing$ and $V_{i}^{\prime \prime} \cap V_{i} \neq \varnothing$. Thus $f^{n}(x) \in V^{\prime}=V_{i}^{\prime}$ $\times \cdots \times V_{n}^{\prime}, g^{n}(x) \in V^{\prime \prime}=V_{1}^{\prime \prime} \times \cdots \times V_{n}^{\prime \prime}, V \cap V^{\prime} \neq \varnothing$ and $V \cap V^{\prime \prime} \neq \varnothing$, where $V=V_{1}$ $\times \cdots \times V_{n}$. This implies that $f \eta_{X}(x)=\eta_{Y} f^{n}(x) \in \eta_{Z}\left(V^{\prime}\right), \underline{g} \eta_{X}(x) \in \eta_{Y}\left(V^{\prime \prime}\right), \eta_{Y}\left(V^{\prime}\right)$ $\cap \eta_{Y}(V) \neq \varnothing$ and $\eta_{Y}\left(V^{\prime \prime}\right) \cap \eta_{Y}(V) \neq \varnothing$. This means that $\underline{f} \eta_{X}(x), g \eta_{X}(x) \in s t\left(\eta_{Y}(V)\right.$, $\left.\eta_{Y}\left(C V^{n}\right)\right)$, i.e., $\left(f \eta_{X}, g \eta_{X}\right)<s t\left(\eta_{Y}\left(V^{n}\right)\right)$. Since $\eta_{Y}$ is onto, we have the required conclusion.
(4.6) THEOREM. If $\boldsymbol{p}=\left\{p_{a}: a \in A\right\}: X \rightarrow(\mathscr{X}, \mathcal{U})=\left\{\left(X_{a}, \mathcal{U}_{a}\right), p_{a^{\prime}, a}, A\right\}$ is an approximative resolution, then $\boldsymbol{p}=\left\{\underline{p}_{a}: a \in A\right\}: X^{n} / G \rightarrow(\mathscr{X}, \mathcal{U})^{n} / G=\left\{\left(X_{a}^{n} / G, \eta_{a}\left(\mathcal{U}_{a}^{n}\right)\right)\right.$, $\left.\underline{p}_{a^{\prime}, a}, A\right\}$ is an approximative resolution.

Proof. We show (AI1)-(AI3) for $(\mathscr{X}, \mathcal{U})^{n} / G$. (Al1) is obvious. (AI2) and (AI3) follow from (iii) of (4.5) and (AI2), (Al3) for ( $\mathfrak{X}, \mathcal{U}$ ). Thus ( $\mathfrak{X}, \mathcal{U})^{n} / G$ forms an approximative inverse system.

By (I. 3.3) $\boldsymbol{p}: X \rightarrow X$ is a resolution and then by (I.7.1) it is an inverse limit, By (4.4) $p: X^{n} / G \rightarrow \mathfrak{X}^{n} / G$ is an inverse limit and then by (I. 3.13) it is a resolution. Hence by (I. 3.3) $\boldsymbol{p}: X^{n} / G \rightarrow(\mathscr{X}, \mathcal{U})^{n} / G$ is an approximative resolution.
(4.7) Corollary. If $\boldsymbol{p}: X \rightarrow(\mathcal{X}, \mathcal{U})$ is an approximative $\mathbf{A N R}(\mathbf{C M})$-resolution and an approximative $\mathbf{P O L}_{f}$-resolution, then so is $\boldsymbol{p}: X^{n} / G \rightarrow(\mathfrak{X}, \mathcal{U})^{n} / G$, respectively.
(4.7) follows from (4.2) and (4.6).
(4.8) Theorem. (i) If $f: X \rightarrow Y$ is an AE-map, then so is $\underline{f}: X^{n} / G \rightarrow Y^{n} / G$.
(ii) If $f$ is an NE-map, then so is $\underline{f}$.

Proof. We show (ii). In a similar way we can show (i). There exist approximative finite polyhedral resolutions $\boldsymbol{p}: X \rightarrow(\mathcal{X}, \mathcal{q}), \boldsymbol{q}=\left\{q_{b}: b \in B\right\}: Y \rightarrow(q, q)$ $=\left\{\left(Y_{b}, \mathcal{C}_{b}\right), q_{b^{\prime}, b}, B\right\}$ and an approximative resolution $\boldsymbol{f}=\left\{f, f_{b}: q \in B\right\}:(\mathscr{X}, \mathcal{U})$ $\rightarrow(q, \mathcal{Q})$ of $f$ with respect to $\boldsymbol{p}$ and $\boldsymbol{q}$ by (I.3.15) and (I.4.3). By (4.7) $\underline{p}: X^{n} / G$ $\rightarrow(X, Q)^{n} / G$ and $\underline{q}: Y^{n} / G \rightarrow(q, \mathcal{Q})^{n} / G$ are approximative finite polyhedral resolutions. It is easy by (4.5) to show that $\underline{f}=\left\{f, f_{b}: b \in B\right\}:(\mathfrak{X}, \mathcal{U})^{n} / G \rightarrow(\mathcal{q}, \mathcal{Q})^{n} / G$ forms an approximative resolution of $\underline{f}: X^{n} / G \rightarrow Y^{n} / G$ with respect to $\underline{p}$ and $\underline{q}$.

We show that $\underline{f}$ satisfies (NE). Take any $b \in B$. By the assumption $\boldsymbol{f}$ satisfies (NE) and then there exists $a>f(b)$ satisfying (NE) for $f$ and $b$. Take any $b^{\prime}>b$. Then there exists a map $r: X_{a} \rightarrow Y_{b^{\prime}}$ such that $\left(f_{b} p_{a, f(b)}, q_{b^{\prime}, b} r\right)<s t \mathcal{V}_{b}$. By (4.5) ( $\left.f_{0} \underline{p}_{a}, f(b), \underline{q}_{b^{\prime}, o r}\right)<s t\left(\eta_{b}\left(\mathcal{V}_{b}^{n}\right)\right)$ and then $\underline{f}$ satisfies (NE). Hence $\underline{f}$ is an NE-map.
(4.9) Corollary. If $X$ is UAM, AM or IAM, then so is $X^{n} / G$, respectively.
(4.9) follows from (II. 5.10), (1.12), (1.21) and (4.8).

We use the same notations $\boldsymbol{p}, \boldsymbol{q}, \underline{\boldsymbol{p}}$ and $\underline{\boldsymbol{q}}$ as in the proof of (4.8). By (I.5.7) $H(\boldsymbol{p})=\left\{H\left(p_{a}\right): a \in A\right\}: X \rightarrow H(\mathfrak{X})=\left\{X_{a}, H\left(p_{a^{\prime}, a}\right), A\right\}, H(\boldsymbol{q}): Y \rightarrow H(q), \quad H(\underline{p})=$ $\left\{H\left(\underline{p}_{a}\right): a \in A\right\}: X^{n} / G \rightarrow H\left(\mathscr{X}^{n} / G\right)=\left\{X_{a}^{n} / G, H\left(\underline{p}_{a^{\prime}, a}\right), A\right\} \quad$ and $H(\underline{q}): Y^{n} / G \rightarrow$ $H\left(q^{n} / G\right)$ are HPOL-expansions.

Let $f: X \rightarrow Y$ be a shaping. Let $H(f)=\left\{f, H\left(f_{b}\right): b \in B\right\}: H(\mathfrak{X}) \rightarrow H\left(q_{y}\right)$ be a system map in pro-HPOL which represents $f$. For each $b^{\prime}>b$ there exists $a>$ $f(b), f\left(b^{\prime}\right)$ such that $f_{b} p_{a, f(b)} \simeq q_{b^{\prime}, b} f_{b^{\prime}} p_{a, f\left(b^{\prime}\right)}$. By (4.1) $\underline{f}_{b} \underline{p}_{a, f(b)} \simeq q_{b^{\prime}, b} \underline{f}_{b^{\prime}} \underline{p}_{a, f\left(b^{\prime}\right)}$ and then $H(\underline{f})=\left\{f, H\left(\underline{f}_{b}\right): b \in B\right\}: H\left(X^{n} / G\right) \rightarrow H\left(q^{n} / G\right)$ forms a system map in pro-HPOL. We take another representation $H\left(\boldsymbol{f}^{\prime}\right)=\left\{f^{\prime}, H\left(f_{b}^{\prime}\right): b \in B\right\}: H(\mathfrak{X}) \rightarrow$ $H(q)$ of $f$. Then for each $b \in B$ there exists $a>f(b), f^{\prime}(b)$ such that $f_{b} p_{a, f(b)}$ $\simeq f_{b}^{\prime} p_{a, f^{\prime}(b)}$. Then by (4.1) $\underline{f}_{b} \underline{p}_{a, f(b)} \simeq \underline{f}_{b}^{\prime} \underline{p}_{a, f(b)}$. Thus $H(\underline{f})$ and $H\left(\underline{f}^{\prime}\right)$ are equivalent i.e., they represent the same shaping $f: X^{n} / G \rightarrow Y^{n} / G$. It is easy from the above definition to show that $\underline{g} f=\underline{g} \circ \underline{f}$ for shapings $f: X \rightarrow Y, g: Y \rightarrow Z$ and $1_{X}$ induces the identity shaping of $X^{n} / G$. Hence we may define a functor $G P^{n}: \mathbf{S h}(\mathbf{C O M}) \rightarrow \mathbf{S h}(\mathbf{C O M})$ as follows : $G P^{n}(X)=X^{n} / G$ for a space $X$ and $G P^{n}(f)$ $=\underline{f}$ for a shaping $f$. We summarize as follows:
(4.10) Theorem. The $n$-th $G$-product induces a functor $G P^{n}: \mathbf{S h}(\mathbf{C O M}) \rightarrow$ Sh(COM).
(4.11) Corollary. (i) If $X$ and $Y$ have the same shape type, then $X^{n} / G$ and $Y^{n} / G$ have the same shape type.
(ii) If $X$ is shape dominated by $Y$, then $X^{n} / G$ is shape dominated by $Y^{n} / G$.
(iii) If $X$ has trivial shape, then so does $X^{n} / G$.
(iv) If $X$ is an ANSR, then so is $X^{n} / G$.
(v) If $X$ is an ASR, then so $X^{n} / G$.
(i)-(ii) follow from (4.10). (iv)-(v) follow from (II.6.1), (4.2) and (ii).
(4.12) THEOREM. (i) If $X$ is internally movable, uniformly movable, strongly movable or movable, then so is $X^{n} / G$, respectively.
(ii) If $X$ satisfies the condition $M$, then so does $X^{n} / G$.

Proof. We assume that $X$ is movable and show that $X^{n} / G$ is movable. We use the same notations as in the proof of (4.10). By the assumption for each $a \in A$ there exists $a_{0}>a$ satisfying (MV) for $a$. Take any $a^{\prime}>a$ and then there exists a map $r: X_{a_{0}} \rightarrow X_{a^{\prime}}$ such that $p_{a^{\prime}, a} r \simeq p_{a_{0}, a}$. By (4.1) $\underline{p}_{a^{\prime}, a} \underline{r} \simeq \underline{p}_{a_{0}, a}$. Then $\mathscr{X}^{n} / G$ satisfies (MV) and hence $X^{n} / G$ is movable.

In a way similar to the one above we can show the other assertions.
(4.13) Corollary. If $X$ is an $\mathrm{AANR}_{C}$, an $\mathrm{AANR}_{N}$ or an AAR for COM, then so is $X^{n} / G$, respectively.

This follows from (II. 5.10), (II. 5.11), (4.9) and (4.11).

## § 5. Maxwell homomorphisms.

In this section we prove a stability theorem on pro-vector spaces and using it we extend Maxwell homomorphisms to compact spaces.

In this section all spaces are compact spaces. Let $F$ be a field. $\operatorname{Vec}(F)$ denotes the category consisting of all vector spaces over $F$ and all linear maps. $\operatorname{dim} G$ denotes the dimension of a vector space $G$ over $F$. $\operatorname{Vec}_{f}(F)$ denotes the full subcategory of $\operatorname{Vec}(F)$ consisting of all finite dimensional vector spaces over $F$. The following is an elementary fact:
(5.1) Lemma. Let $G$ and $H$ be objects of $\operatorname{Vec}_{f}(F)$ and $f: G \rightarrow H$ a linear map. If $f$ is onto and $\operatorname{dim} G=\operatorname{dim} H$, then $f$ is an isomorphism in $\operatorname{Vec}_{f}(F)$.

Let $\mathcal{G}=\left\{G_{a}, p_{a^{\prime}, a}, A\right\}$ be an object of $\operatorname{pro-} \operatorname{Vec}_{f}(F)$. That is, $\mathcal{G}$ is an inverse system on $\operatorname{Vec}_{f}(F)$. Let $p=\left\{p_{a}: a \in A\right\}: G=\lim G \rightarrow G$ be an inverse limit of $\mathcal{G}$. In general $G$ is contained in $\operatorname{Vec}(F)$. Using the method in the proof of Theorem 5.7 of Eilenberg-Steenrod [13, p. 226] and Kelly [26] it is not difficult to show that
(5.2) Lemma. If all bonding maps $p_{a^{\prime}, a}: G_{a^{\prime}} \rightarrow G_{a}$ are onto, then all $p_{a}: G$ $\rightarrow G_{a}$ are onto.
 a vector space $G$ in pro- $\operatorname{Vec}(F)$. In [43] the author discussed a stability theorem in pro-groups.
(5.3) Theorem. Let $\mathcal{G}$ be an object of pro $-\operatorname{Vec}_{f}(F)$. Then $G$ is stable in pro- $\operatorname{Vec}(F)$ iff the dimension of $\lim G$ is finite.

Proof. Let $G=\lim \mathcal{G}$ and $\operatorname{dim} G=n$. First we assume that $n$ is finite. Take any $a \in A$ and put $H_{a^{\prime}}^{a}=p_{a^{\prime}, a}\left(G_{a^{\prime}}\right)$ for each $a^{\prime} \in A$ with $a^{\prime}>a$. Since $\operatorname{dim} G_{a}$ is finite, $\operatorname{dim} H_{a^{\prime}}^{a}=n_{a^{\prime}}$ is also finite for $a^{\prime}>a$. Since $H_{a^{a}}^{a} \supset H_{a^{\prime}}^{a}$ for $a^{\prime \prime}>a^{\prime}>a$, $n_{a^{\prime}} \leqq n_{a^{\prime}}$. Since all $n_{a^{\prime}}$ are integers, there exists $k(a)>a$ such that $n_{k(a)}=n_{a^{\prime}}$ for each $a^{\prime}>k(a)$. Hence

$$
\begin{equation*}
H_{k(a)}^{a}=H_{a}^{a}, \text { for each } a^{\prime} \in A \text { with } a^{\prime}>k(a) \tag{1}
\end{equation*}
$$

(1) means that $G$ satisfies the Mittag-Leffler condition (see MS [34]).

Let $H_{a}=H_{k(a)}^{a}$ for $a \in A$. Then by (1) it is easy to show that

$$
\begin{equation*}
p_{a^{\prime \prime}, a^{\prime}}\left(H_{a^{\prime}}\right)=H_{a^{\prime}} \quad \text { for } \quad a^{\prime \prime}>a^{\prime} . \tag{2}
\end{equation*}
$$

By (2) $p_{a^{\prime}, a}: G_{a^{\prime}} \rightarrow G_{a}$ induces a linear map $p_{a^{\prime}, a}^{\prime}: H_{a^{\prime}} \rightarrow H_{a}$ for $a^{\prime}>a$. Then $\mathscr{H}=\left\{H_{a}, p_{a^{\prime}, a}^{\prime}, A\right\}$ forms an inverse system on $\operatorname{Vec}_{f}(F)$. Let $j_{a}: H_{a} \rightarrow G_{a}$ be the inclusion map for $a \in A$. Then $\boldsymbol{j}=\left\{1_{A}, j_{a}: a \in A\right\}: \mathscr{A} \rightarrow \mathcal{G}$ forms a system map. Since $j_{a} p_{k(a), a}=p_{k(a), a}$ and $p_{k(a), a} j_{k(a)}=p_{k(a), a}^{\prime}$, by Morita's diagonal theorem (see MS [34, p. 112])

$$
\begin{equation*}
\boldsymbol{j}: \mathscr{H} \rightarrow \mathcal{G} \text { is an isomorphism in } \operatorname{pro-\operatorname {Vec}(F).} \tag{3}
\end{equation*}
$$

Let $\boldsymbol{p}^{\prime}=\left\{\boldsymbol{p}_{a}^{\prime}: a \in A\right\}: H=\lim \mathscr{G} \rightarrow \mathscr{H}$ be an inverse limit. Then $\boldsymbol{j}$ induces a unique homomorphism $j: H \rightarrow G$ satisfying

$$
\begin{equation*}
\boldsymbol{j} \boldsymbol{p}^{\prime}=\boldsymbol{p} j \tag{4}
\end{equation*}
$$

Since $p_{a^{\prime}, a} p_{a^{\prime}}=p_{a}$ for $a^{\prime}>a, p_{a}(G) \subset H_{a}$ for $a \in A$. Then $p_{a}: G \rightarrow G_{a}$ induce maps $p_{a}^{\prime \prime}: G \rightarrow H_{a}$ such that $j_{a} p_{a}^{\prime \prime}=p_{a}$ and $p_{a^{\prime}, a}^{\prime} p_{a^{\prime}}^{\prime \prime}=p_{a}^{\prime \prime}$ for $a^{\prime}>a$. Thus $\boldsymbol{p}^{\prime \prime}=$ $\left\{p_{a}^{\prime \prime}: a \in A\right\}: G \rightarrow \mathscr{H}$ forms a system map satisfying

$$
\begin{equation*}
p=j \boldsymbol{p}^{\prime \prime} \tag{5}
\end{equation*}
$$

Then there exists a unique homomorphism $h: G \rightarrow H$ such that

$$
\begin{equation*}
\boldsymbol{p}^{\prime} \boldsymbol{h}=\boldsymbol{p}^{\prime \prime} \tag{6}
\end{equation*}
$$

Since $\boldsymbol{j}\left(\boldsymbol{p}^{\prime \prime} j\right)=\left(\boldsymbol{j} \boldsymbol{p}^{\prime \prime}\right) j=\boldsymbol{p} \boldsymbol{j}=\boldsymbol{j} \boldsymbol{p}^{\prime}$ by (4) and (5), by (3)

$$
\begin{equation*}
\boldsymbol{p}^{\prime \prime}{ }_{j=\boldsymbol{p}^{\prime}} \tag{7}
\end{equation*}
$$

Since $\boldsymbol{p}^{\prime}(h j)=\left(\boldsymbol{p}^{\prime} h\right) j=\boldsymbol{p}^{\prime \prime} j=\boldsymbol{p}^{\prime} 1_{H}$ by (6) and (7), then by the uniqueness of inverse limits $h j=1_{H}$. Since $\boldsymbol{p}(j h)=(\boldsymbol{p} j) h=\boldsymbol{j}\left(\boldsymbol{p}^{\prime} h\right)=\boldsymbol{j} \boldsymbol{p}^{\prime \prime}=\boldsymbol{p} 1_{G}$ by (4)-(6), then by the uniqueness $j h=1_{G}$ and hence

$$
\begin{equation*}
j: H \rightarrow G \text { is an isomorphism and then } \operatorname{dim} H=\operatorname{dim} G=n . \tag{8}
\end{equation*}
$$

Since all bonding maps $p_{a^{\prime}, a}^{\prime}$ are onto by (2), by (5.2) all $p_{a}^{\prime}: H \rightarrow H_{a}$ are onto and then $m_{a}=\operatorname{dim} H_{a} \leqq \operatorname{dim} H=n$ for all $a \in A$. By (2) $m_{a^{\prime}} \geqq m_{a}$ for $a^{\prime}>a$. Then there exists $a_{0} \in A$ such that $m_{a_{0}}=m_{a}$ for each $a>a_{0}$. Thus by (2) $p_{a}^{\prime}, a^{\prime}: H_{a^{\prime}} \rightarrow H_{a^{\prime}}$ is onto and $\operatorname{dim} H_{a^{\prime}}=\operatorname{dim} H_{a^{\prime}}$ for $a^{\prime \prime}>a^{\prime}>a_{0}$, and then by (5.1) $p_{a}^{\prime}, a^{\prime}: H_{a} \rightarrow H_{a^{\prime}}$ is an isomorphism for $a^{\prime \prime}>a^{\prime}>a_{0}$. It follows that $p_{a}^{\prime}: H \rightarrow H_{a}$ is an isomorphism for $a>a_{0}$. By this and Morita's diagonal theorem

$$
\begin{equation*}
\boldsymbol{p}^{\prime}: H \rightarrow \mathscr{A} \text { is an isomorphism in pro-Vec }(F) \tag{9}
\end{equation*}
$$

By (3), (4), (8) and (9) $\boldsymbol{p}: G \rightarrow \underline{Q}$ forms an isomorphism in pro-Vec $(F)$. Hence $G$ is stable in pro-Vec $(F)$.

Next we assume that $G$ is stable in pro-Vec $(F)$. By Lemma 2.13 of Dydak [12] an inverse limit $\boldsymbol{p}: G=\lim G \rightarrow G$ is an isomorphism in $\operatorname{pro-Vec}(F)$. Then there exists a system map $\boldsymbol{q}=\left\{q_{0}\right\}: \mathcal{G} \rightarrow G$ satisfying $\boldsymbol{p} \boldsymbol{q} \simeq 1_{\mathcal{G}}$ and $\boldsymbol{q} \boldsymbol{p} \simeq 1_{G}$. Put $q_{0}: G_{a_{0}} \rightarrow G$. Since $\boldsymbol{q} \boldsymbol{p} \simeq 1_{G}, q_{0} p_{a_{0}}=1_{G}$ and then $p_{a_{0}}: G \rightarrow G_{a_{0}}$ is 1-1. Thus $\operatorname{dim} G$ $=\operatorname{dim} p_{a_{0}}(G) \leqq \operatorname{dim} G_{a_{0}}<\infty$. Hence $\operatorname{dim} G$ is finite.

To show (1) in the proof of (5.3) we do not use the condition, $\operatorname{dim} G=n<\infty$. Thus we have the following:
(5.4) Corollary. Any inverse system on $\operatorname{Vec}_{f}(F)$ satisfies the Mittag-Leffler condition.
(5.5) Corollary. Let $\mathcal{G}$ be an inverse system on $\operatorname{Vec}_{f}(F)$. If dimension of $\lim \mathcal{G}$ is finite, then there exists $a_{0} \in A$ with the following properties:
(i) $p_{a}: \lim G \rightarrow G_{a}$ is 1-1 for each $a>a_{0}$, and
(ii) for each $a>a_{0}$ there exists $k(a)>a$ such that $p_{a}(\lim \mathcal{G})=p_{a^{\prime}, a}\left(G_{a^{\prime}}\right)$ for each $a^{\prime}>k(a)$.
$H_{j}(X ; F)$ denotes the $j$-th Čech homology of a space $X$ with coefficient $F$. A map $f: X \rightarrow Y$ induces a homomorphism $f_{* j}: H_{j}(X ; F) \rightarrow H_{j}(Y ; F)$. We say that $X$ is of finite type with respect to $F$ provided that there exists an interger $n$ such that $H_{j}(X ; F)=0$ for $j>n$ and $H_{j}(X ; F)$ is a finite dimensional vector space over $F$ for $j \leqq n$.
(5.6) Lemma. If a space $X$ is of finite type with respect to $F$, then there
exists $\mathscr{W} \in \operatorname{Cov}(X)$ with the following property:
(*) For any space $Y$ and any maps $f, g: Y \rightarrow X$ if $(f, g)<\mathscr{W}$, then $f_{* j}=$ $g_{*_{j}}: H_{j}(Y ; F) \rightarrow H_{j}(X ; F)$ for each $j$.

Proof. We recall the definition of Čech homology. Let $q, \mathcal{U}^{\prime} \in \operatorname{Cod}(X)$ with $\mathcal{U}^{\prime}<\mathcal{Q}$. Let $p_{U}: X \rightarrow N(\mathcal{U})$ be a canonical map into the nerve of $\mathscr{U}$ and $p_{U^{\prime}, \vartheta}: N\left(\mathscr{U}^{\prime}\right) \rightarrow N(\mathscr{U})$ a projection. $p_{\vartheta^{\prime}, \vartheta}$ is a simplicial map satisfying $p_{\vartheta^{\prime}, \vartheta\left(U^{\prime}\right)}$ $\supset U^{\prime}$ for each vertex $U^{\prime} \in N\left(\mathcal{U}^{\prime}\right)$. It is well known that if $p q^{\prime}, q^{\prime}, p_{q^{\prime}, q}^{\prime}: N\left(U^{\prime}\right)$ $\rightarrow N(\mathscr{U})$ are projections, then $p_{\mathcal{U}^{\prime}, \vartheta} \simeq p_{\mathcal{U}^{\prime}, \mathcal{Q} .}^{\prime} \quad \boldsymbol{p}_{* j}=\left\{p_{\mathcal{U}_{* j}}: \mathscr{U} \in \mathcal{C}_{o v}(X)\right\}: H_{j}(X ; F)$ $\rightarrow \operatorname{pro}-H_{j}(X ; F)=\left\{H_{j}(N(\mathcal{U}) ; F), p_{q^{\prime}, q * j}, \mathcal{C}_{o v}(X)\right\}$ forms an inverse limit.

Since $X$ is of finite type, there exists an integer $n$ such that $H_{j}(X ; F)=0$ for $j>n$ and $H_{j}(X ; F)$ is a finite dimensional vector space for $j \leqq n$. For any $j, 0 \leqq j \leqq n$ we show the following:
(1) There exists $\mathscr{W}_{j} \in \mathcal{C o v}(X)$ such that for any space $Y$ and any maps

$$
f, g: Y \rightarrow X \text { if }(f, g)<\mathscr{W}_{j}, \text { then } f_{* j}=g_{* j}: H_{j}(Y ; F) \rightarrow H_{j}(X ; F) .
$$

Since $X$ is compact, we may assume that all coverings $U$ are finite coverings and then $H_{j}(N(U) ; F)$ are finite dimensional vector spaces. Since $H_{j}(X ; F)$ is a finite dimensional vector space, by (5.5) there exists $U_{0} \in \mathcal{C}$ $o v(X)$ such that

$$
\begin{equation*}
p_{\mathcal{U}^{*} j}: H_{j}(X ; F) \rightarrow H_{j}(N(Q) ; F) \text { is } 1-1 \text { for } U<\mathcal{U}_{0} . \tag{2}
\end{equation*}
$$

Take any $\mathcal{U}=\left\{U_{1}, U_{2}, \cdots, U_{s}\right\} \in \mathcal{C}_{o v}(X)$ with $\mathscr{U}<\mathcal{U}_{0}$. Since $X$ is normal, $\mathscr{U}$ is shrinkable. Then there exists $\mathcal{U}^{\prime}=\left\{U_{1}^{\prime}, U_{2}^{\prime}, \cdots, U_{s}^{\prime}\right\} \in \operatorname{Cov}(X)$ such that $\bar{U}_{i}^{\prime} \subset U_{i}$ for $1 \leqq i \leqq s$. Since $\bar{U}_{i}^{\prime} \cap\left(X-U_{i}\right)=\varnothing$, there exists $\mathscr{K}_{i} \in \operatorname{Cov}(X)$ such that $s t\left(\bar{U}_{i}^{\prime}, \mathscr{K}_{i}\right)$ $\cap s t\left(X-U_{i}, \mathscr{K}_{i}\right)=\varnothing$ for each $i=1,2, \cdots$, s. Put $\mathscr{W}_{j}=\mathscr{K}_{1} \wedge \mathscr{K}_{2} \wedge \cdots \wedge \mathscr{K}_{s} \in \operatorname{Cov}(X)$ and then

$$
\begin{equation*}
s t\left(\bar{U}_{i}^{\prime}, \mathscr{W}_{j}\right) \cap s t\left(X-U_{i}, \mathscr{W}_{j}\right)=\varnothing \quad \text { for } \quad i=1,2, \cdots, s \tag{3}
\end{equation*}
$$

We show that $\mathscr{W}_{j}$ is the required covering. Take any space $Y$ and any maps $f, g: Y \rightarrow X$ such that $(f, g)<\mathscr{W}_{j}$.

$$
\begin{equation*}
g^{-1}\left(U_{i}^{\prime}\right) \subset f^{-1}\left(U_{i}\right) \quad \text { for } \quad i=1,2, \cdots, s \tag{4}
\end{equation*}
$$

For any $y \in g^{-1}\left(U_{i}^{\prime}\right)$ there exists $W_{1} \in W_{j}$ such that $f(y), g(y) \in W_{1}$. Since $g(y) \in$ $U_{i}^{\prime} \cap W_{1}, f(y) \in s t\left(\bar{U}_{i}^{\prime}, \mathscr{W}_{j}\right)$. By (3) $f(y) \notin s t\left(X-U_{i}, W_{j}\right)$ and then $f(y) \in U_{i}$. Thus we have (4).

Let $q_{C V}: Y \rightarrow N(\widetilde{V})$ and $q_{Q^{\prime}, \widetilde{ }}: N\left(V^{\prime}\right) \rightarrow N(\subset)$ be a canonical map and a projection for $\mathcal{V}^{\prime}<\mathbb{Q}$. Then $\boldsymbol{q}_{* j}=\left\{q_{\mathcal{O} *_{j}}: \mathcal{Q} \in \mathcal{C}_{o v}(Y)\right\}: H_{j}(Y ; F) \rightarrow \operatorname{pro}-H_{j}(Y ; F)=$ $\left\{H_{j}(N(\mathcal{Q}) ; F), p_{\mathcal{V}^{\prime}, \mathcal{O} * j}, \mathcal{C}_{o v}(Y)\right\}$ forms an inverse limit. By (4) we define a simplicial map $v: N\left(g^{-1} q^{\prime}\right) \rightarrow N\left(f^{-1} q\right)$ by $v\left(g^{-1} U_{i}^{\prime}\right)=f^{-1} U_{i}$ for each $i$. Then $v$ is a projection and thus $v \simeq q_{g^{-1} v^{\prime}, f^{-1}}$. Hence

$$
\begin{equation*}
v_{* j}=q_{g^{-1}-1 q^{\prime}, f^{-1} V_{* j}}: H_{j}\left(N\left(g^{-1} U^{\prime}\right) ; F\right) \rightarrow H_{j}\left(N\left(f^{-1} U\right) ; F\right) . \tag{5}
\end{equation*}
$$

$f$ and $g$ induce simplicial maps $f_{\#}: N\left(f^{-1} U\right) \rightarrow N(U)$ and $g_{\#}: N\left(g^{-1} \mho^{\prime}\right) \rightarrow N\left(\vartheta^{\prime}\right)$ by $f_{\#}\left(f^{-1} U_{i}\right)=U_{i}$ and $g_{\#}\left(g^{-1} U_{i}^{\prime}\right)=U_{i}^{\prime}$ for each $i$. Since $U_{i}^{\prime} \subset \bar{U}_{i}^{\prime} \subset U_{i}$ for each $i$, we define a simplicial map $u: N\left(\vartheta^{\prime}\right) \rightarrow N(\mathscr{U})$ by $u\left(U_{i}^{\prime}\right)=U_{i}$ for each $i$. Since $u$ and $p_{q^{\prime}, q}$ are projections, $u \simeq p_{q^{\prime}, q}$ and hence

$$
\begin{equation*}
u_{* j}=p_{q^{\prime}, q^{*} j}: H_{j}\left(N\left(q^{\prime}\right)\right) \rightarrow H_{j}\left(N\left(q^{\prime}\right)\right) . \tag{6}
\end{equation*}
$$

By the definitions of $f_{\#}, g_{\#}, u$ and $v$ clearly $u g_{\#}=f_{\#} u$ and hence

$$
\begin{equation*}
u_{* j} g_{\# * j}=f_{\# * j} v_{* j} . \tag{7}
\end{equation*}
$$

By (5)-(7)

$$
\begin{equation*}
p_{q^{\prime}, q * j} g_{\# j}=f_{\# * j} q_{g^{-1}-1 U^{\prime}, f^{-1}-1 q_{j}} . \tag{8}
\end{equation*}
$$

Take any $z \in H_{j}(Y ; F)$. By (8) $\quad p_{q_{* j} j} f_{* j}(z)=f_{\# * j} q_{f-1 q_{* *}}(z)=f_{\# * j} q_{g^{-1}} q^{\prime}, f^{-1 q_{* j}}$ $q_{g^{-1} q^{\prime} * j}(z)=p, q, q * j g_{\# * j} q_{g^{-1} q^{\prime} * j}(z)=p_{\vartheta^{\prime}, q * j} p_{q^{\prime} * j} g_{* j}(z)=p_{q_{* j} j} g_{* j}(z)$, that is, $p_{q * j}$ $f_{* j}(z)=p_{q^{*} j} g_{*_{j}}(z)$. By (2) $f_{* j}(z)=g_{* j}(z)$ and then $f_{* j}=g_{* j}$. Hence we have (1),

Finally we put $\mathscr{W}=\mathscr{W}_{0} \wedge \mathscr{W}_{1} \wedge \cdots \wedge \mathscr{W}_{n} \in \mathcal{C}_{o v}(X)$. By the choice of $n$ and (1) it is easy to show that $\mathscr{W}$ satisfies (*).

For compact metric spaces (5.6) was proved by Dugundji [11].
$Q$ denotes the field consisting of all rational numbers and put $H_{j}(X)=$ $H_{j}(X ; Q)$. We say that $X$ is of finite type provided that $X$ is of finite type with respect to $Q$.

Maxwell [36] defined homomorphisms $\mu_{j}^{K}: H_{j}\left(K^{n} / G\right) \rightarrow H_{j}(K)$ for finite polyhodra $K$ and integers $j$ satisfy the following conditions:
(M1) $f_{* j} \mu_{j}^{K}=\mu_{j}^{L} f_{*_{j}}$ for any map $f: K \rightarrow L$ between finite polyhedra;

(M2) $\sum_{i=1}^{n} \pi_{i * j}^{K}=\pi_{j}^{K} \eta_{K * j}$ for any finite polyhedron $K$;


Here $\pi_{i}=\pi_{i}^{K}: K^{n} \rightarrow K$ is the $i$-th projection.
We shall define homomorphisms $\mu_{j}^{X}: H_{j}\left(X^{n} / G\right) \rightarrow H_{j}(X)$ satisyng (M1) and (M2) for all (compact) spaces.

Let $X$ and $Y$ be compact spaces. Take any finite polyhedral resolution $\boldsymbol{p}=$ $\left\{p_{a}: a \in A\right\}: X \rightarrow \mathscr{X}=\left\{X_{a}, p_{a^{\prime}, a}, A\right\}$ and $\left.\boldsymbol{q}=\left\{q_{b}: b \in B\right\}: Y \rightarrow a\right\}=\left\{Y_{b}, q_{b^{\prime}, b}, B\right\}$. Then $\boldsymbol{p}^{n}=\left\{p^{n}: a \in A\right\}: X^{n} \rightarrow \mathscr{X}^{n}=\left\{X_{a}^{n}, p_{a^{n}, a}^{n}, A\right\}$ and $\underline{p}=\left\{\underline{p}_{a}: a \in A\right\}: X^{n} / G \rightarrow$ $\mathfrak{X}^{n} / G=\left\{X_{a}^{n} / G, \underline{p}_{a^{\prime}, a}, A\right\}$ are finite polyhedral resolutions (see $\S 4$ ). By (M1) for finite polyhedra the Maxwell homomorphisms $\mu_{j}^{a}=\mu_{j}^{X} a: H_{j}\left(X_{a}^{n} / G\right) \rightarrow H_{j}\left(X_{a}\right)$ satisfy $p_{a^{\prime}, a * j} \mu_{j}^{\alpha^{\prime}}=\mu_{j}^{a} \underline{a}_{a^{\prime}, a * j} \quad$ for $\quad a^{\prime}>a$. Then $\quad \mu_{j}^{p}=\left\{1_{A}, \mu_{j}^{a}: a \in A\right\}: H_{j}\left(\mathfrak{X}^{n} / G\right)=$ $\left\{H_{j}\left(X_{a}^{n} / G\right), \underline{p}_{a^{\prime}, a * j}, A\right\} \rightarrow H_{j}(\mathfrak{X})=\left\{H_{j}\left(X_{a}\right), p_{a^{\prime}, a * j}, A\right\}$ forms a system map. By taking inverse limits we have a homomorphism $\mu_{j}^{p}=\lim \mu_{j}^{p}: H_{j}\left(X^{n} / G\right)=\lim H_{j}\left(\mathfrak{X}^{n} / G\right)$ $\rightarrow \lim H_{j}(X)=H_{j}(X)$.
(5.7) Lemma. $f_{* j} \mu_{j}^{p}=\mu_{j}^{q} \underline{f}_{* j}$ for any shaping $f: X \rightarrow Y$. Here $\underline{f}=G P^{n}(f)$.

Proof. Take any representation $\boldsymbol{f}=\left\{f, H\left(f_{b}\right): b \in B\right\}: H(\mathscr{X})=\left\{X_{a}, H\left(p_{a^{\prime}, a}\right), A\right\}$ $\rightarrow H(q)=\left\{Y_{b}, H\left(q_{b^{\prime}, b}\right), B\right\}$ of a shaping $f$. Then $\underline{f}=\left\{f, H\left(\underline{f}_{b}\right): b \in B\right\}: H\left(\mathfrak{X}^{n} / G\right)$ $\rightarrow H\left(q^{n} / G\right)$ represents a shaping $\underset{f}{f}=G P^{n}(f)$ by (4.10). Thus $\boldsymbol{f}_{* j}=\left\{f, f_{b * j}: b \subseteq B\right\}$ : $H_{j}(\mathscr{X}) \rightarrow H_{j}(q)$ and $\underline{\boldsymbol{f}}_{*_{j}}=\left\{f, \underline{f}_{b_{* j}}: b \in B\right\} \quad H_{j}\left(\mathscr{X}^{n} / G\right) \rightarrow H_{j}\left(q q^{n} / G\right)$ form system maps on $\operatorname{Vec}(Q)$ by (4.1). Then $f_{*_{j}}=\lim \boldsymbol{f}_{*_{j}}: H_{j}(X) \rightarrow H_{j}(Y)$ and $\underline{f}_{* j}=\lim \underline{f}_{*_{j}}: H_{j}\left(X^{n} / G\right)$ $\rightarrow H_{j}\left(Y^{n} / G\right)$. For any $b \in B q_{b * j} f_{* j} \mu_{j}^{p}=f_{b * j} p_{f(b) * j} \mu_{j}^{p}=f_{b * j} \mu_{j}^{f(b)} \underline{p}_{f(b) * j}=\mu_{j}^{b} \underline{f}_{b * j} \underline{p}_{f(b) * j}$ $=\mu_{j \underline{b}}^{b} \underline{b}_{b j} \underline{f}_{* j}=q_{b * j} \mu_{j \underline{g}}^{q} \underline{f}_{* j}$. By the uniqueness of inverse limits we have the required one.

Let $X$ be a finite polyhedron. Let $\boldsymbol{p}(X): X \rightarrow\{X\}$ be the rudimental resolution of $X$. From the definition we have that
(5.8) Lemma. $\mu_{j}^{K}=\mu_{j}^{p(K)}$ for any finite polyhedron $K$.

When we take $f$ as the identity shaping, from (5.7) it follows
(5.9) Lemma. If $\boldsymbol{p}: X \rightarrow \mathfrak{X}$ and $\boldsymbol{p}^{\prime}: X \rightarrow \mathfrak{X}^{\prime}$ are finite polyhedral resolutions, then $\mu_{j}^{p}=\mu_{j}^{p^{\prime}}$.

By (5.9) $\mu_{j}^{p}$ does not depend on the choice of finite polyhedral resolutions of $X$ and then we denote it by $\mu_{j}^{X}$. By (5.8) our homomorphism coincides with the original Maxwell homomorphisms for finite polyhedra. By (5.7) (M1) holds for any shaping. By (M2) for finite polyhera and each $a \in A \quad p_{a * j} \mu_{j}^{p} \eta_{X * j}$ $=\mu_{j}^{a} \underline{p}_{a * j} \eta_{X *{ }_{j}}=\mu_{j}^{a} \eta_{a * j} p_{a * j}^{n}=\left(\sum_{i=1}^{n} \pi_{i \neq j}^{X}\right) p_{a * j}^{n}=\sum_{i=1}^{n}\left(\pi_{i}^{X} p_{a}^{n}\right)_{* j}=\sum_{i=1}^{n} p_{a * j} \pi_{i * j}^{X}=$ $p_{a * j}\left(\sum_{i=1}^{n} \pi_{i * j}^{X}\right)$. By the uniqueness of inverse limits $\mu_{j}^{X} \eta_{X * j}=\mu_{j}^{p} \eta_{X * j}=\sum_{i=1}^{n} \pi_{i * j}^{X}$. This means (M2) for compact spaces. We summarize as follows:
(5.10) Theorem. Maxwell homomorphisms can be extended to compact spaces satisfying (M1) for shapings and (M2).

Let $X$ be an ANSR. Then there exist a finite polyhedron $P$ and shapings $f: X \rightarrow P, g: P \rightarrow X$ such that $g f=S H\left(1_{X}\right)$ by (II.6.1). By (5.10) $f g=S H\left(1_{X^{n / G}}\right)$. Put $W \mu_{j}^{X}=g_{* j} \mu_{j}^{P} \underline{\underline{f}_{* j}}: H_{j}\left(X^{n} / G\right) \rightarrow H_{j}(X)$. By (5.7) $W \mu_{j}^{X}=g_{* j} \mu_{j}^{P} \underline{f}_{* j}=\mu_{j}^{X} g_{*_{j}} \underline{f}_{* j}=$ $\mu_{j}^{X} S H\left(1_{X n / G}\right)_{*_{j}}=\mu_{j}^{X}$. We summarize as follows:
(5.11) Lemma. $\quad W \mu_{j}^{X}=\mu_{j}^{X}$ for any ANSR $X$.

Masih [35] introduced the Maxwell homomorphisms $M \mu_{j}^{X}: H_{j}\left(X^{n} / G\right) \rightarrow H_{j}(X)$ for any compact metric ANR $X$ as follows: Since $X$ is an ANR, there exist a finite polyhedron $P$ and maps $f: X \rightarrow P, g: P \rightarrow X$ such that $g f \simeq 1_{X}$. He defines $M \mu_{j}^{X}=g_{* j} \mu_{j}^{P} \underline{f}_{* j}$. From the definitions $M \mu_{j}^{X}=W \mu_{j}^{X}$. Hence by (5.5) we have that
(5.12) Corollary. $M \mu_{j}^{X}=\mu_{j}^{X}$ for any compact metric ANR $X$.

Vora [42] introduced the Maxwell homomorphisms $V \mu_{j}^{X}: H_{j}\left(X^{n} / G\right) \rightarrow H_{j}(X)$ for any compact metric $\operatorname{AANR}_{N} X$. We define a homomorphism $V \mu_{j}^{X}$ by her method.

Let $X$ be a compact $\operatorname{AANR}_{N}$. By (4.13) $X^{n} / G$ is an $\operatorname{AANR}_{N}$. By (II. 6.1) and (II. 6.6) $X$ and $X^{n} / G$ are shape dominated by finite polyhedra, and then they are of finite type. By (5.6) there exist $\mathcal{U} \in \operatorname{Cov}(X)$ and $\mathcal{V} \in \mathcal{C}_{o v}\left(X^{n} / G\right)$ with the property in (5.6) for $X$ and $X^{n} / G$, respectively. Since $X$ is compact, there exists $U_{0} \in \mathcal{C} O o(X)$ such that $\mathcal{U}_{0}<\mathcal{U}$ and $\mathcal{U}_{0}^{n}<\mathcal{U}^{n} \wedge \eta_{X}^{-1} \subset V$. Since $X$ is an $A P$ by (II.5.10)-(II.5.11), there exist a finite polyhedron $P$ and maps $f: X \rightarrow P, g: P \rightarrow X$ such that $\left(g f, 1_{X}\right)<\mathcal{U}_{0}$. Then $(g f, 1)<\widetilde{V}$. By the choices of $\mathcal{U}$ and $\mathbb{V}, g_{* j} f_{* j}$ $=1_{X * j}$ and $\underline{g}_{* j} \underline{f}_{* j}=1_{X n / G * j}$. Vora defines homomorphisms $V \mu_{j}^{X}=g_{* j} \mu_{j}^{P} \underline{f}_{* j}$ : $H_{j}\left(X^{n} / G\right) \rightarrow H_{j}(X)$. By (5.7) $V \mu_{j}^{X}=g_{* j} \mu_{j}^{P} \underline{f_{* j}}=\mu_{j}^{X} g_{* j} \underline{f}_{* j}=\mu_{j}^{X} 1_{X^{n / G * j}}=\mu_{j}^{X}$. We summarize as follows:
(5.13) Lemma. $\quad V \mu_{j}^{X}=\mu_{j}^{X}$ for any compact $\operatorname{AANR}_{N} X$.
(5.12) and (5.13) mean that our extension of the Maxwell homomorphisms are natural.

## §6. Fixed point theorems.

In this section we discuss the Maxwell fixed point theorem for NE-maps. It implies the Lefschetz-Hopf fixed point theorem for NE-maps and fixed point theorems for hyperspaces and for cone spaces.

In this section all spaces are compact. Let $X$ be a space of finite type and $f: X \rightarrow X^{n} / G$ a map. We say that a point $x \in X$ is a fixed point of $f$ provided
that for each $\left(x_{1}, x_{2}, \cdots, x_{n}\right) \in X^{n}$ with $f(x)=\eta_{X}\left(x_{1}, x_{2}, \cdots, x_{n}\right)$, there exists $i$, $1 \leqq i \leqq n$, such that $x=x_{i}$. We define a Lefschetz number $L(f)=\sum_{j=0}^{\infty}(-1)^{j} \operatorname{tr}\left(\mu_{j}^{x} f_{* j}\right)$ of $f$. Here $\operatorname{tr}\left(\mu_{j}^{X} f_{*_{j}}\right)$ denotes the trace of the homomorphism $\mu_{j}^{X} f_{* j}: H_{j}(X) \rightarrow$ $H_{j}(X)$. Here $H_{j}(X)$ is the $j$-th Čech homology with rational coefficient $Q$.
(6.1) Lemma (Maxwell [36]). Let $P$ be a finite polyhedron and $f: P \rightarrow P^{n} / G$ a map. If $L(f) \neq 0$, then $f$ has a fixed point.
(6.2) Theorem. Let $X$ be a compact space of finite type and let $f: X \rightarrow$ $X^{n} / G$ be a map. If $f$ is an NE-map and $L(f) \neq 0$, then $f$ has a fixed point.

Using only (6.1) we shall show (6.2). To do so we need some lemmas. For each $i, 1 \leqq i \leqq n$ we put $F_{i}(f)=\left\{x \in X: x \in \pi_{i} \eta^{-1} f(x)\right\}$ and $F(f)=\cup\left\{F_{i}(f)\right.$ : $i=1,2, \cdots, n\}$.
(6.3) Lemma. $F(f)$ is the set of all fixed points of $f$.

Proof. Take any fixed poont $x$ of $f$. For each $\left(x_{1}, x_{2}, \cdots, x_{n}\right) \in X^{n}$ with $f(x)=\eta\left(x_{1}, x_{2}, \cdots, x_{n}\right)$, there exists $i$ such that $x=x_{i}$. Thus $x=x_{i} \in \pi_{i} \eta^{-1} f(x)$, that is, $x \in F_{i}(f) \subset F(f)$.

Take any $x \in F(f)$ and then $x \in F_{i}(f)$ for some $i$. Thus $x \in \pi_{i} \eta^{-1} f(x)$ and then there exists $\left(y_{1}, y_{2}, \cdots, y_{n}\right) \in \eta^{-1} f(x)$ such that $x=y_{i}$. Take any $\left(x_{1}, x_{2}, \cdots x_{n}\right)$ $\in X^{n}$ such that $\eta\left(x_{1}, x_{2}, \cdots, x_{n}\right)=f(x)$. Since $\eta\left(x_{1}, x_{2}, \cdots, x_{n}\right)=f(x)=\eta\left(y_{1}, y_{2}, \cdots, y_{n}\right)$, there exists $g \in G$ such that $g\left(x_{1}, x_{2}, \cdots, x_{n}\right)=\left(y_{1}, y_{2}, \cdots, y_{n}\right)$. Thus $x=y_{i}=$ $x_{g(i)}$ and hence $x$ is a fixed point of $f$.

Let $\mathcal{U} \in \operatorname{Cov}(X)$. We put $F_{i}(f, \mathcal{U})=\left\{x \in X: \operatorname{st}(x, \mathcal{Q}) \cap \pi_{i} \eta^{-1} f(x) \neq \varnothing\right\}$ for $i$ and $F(f, \mathcal{U})=\cup\left\{F_{i}(f, \mathscr{U}): i=1,2, \cdots, n\right\}$. We say that a point of $F(f, \mathcal{U})$ is a $\Psi$-fixed point of $f$. Trivially $F_{i}\left(f, \Psi^{\prime}\right) \subset F_{i}(f, \Psi)$ and $F\left(f, \Psi^{\prime}\right) \subset F(f, \mathscr{U})$ for $U^{\prime}<\mathcal{U}$. Let $j_{\vartheta^{\prime}, q}^{i}: \overline{F_{i}\left(f, U^{\prime}\right)} \rightarrow \overline{F_{i}(f, Q)}$ and $j_{q^{\prime} q}: \overline{F\left(f, U^{\prime}\right)} \rightarrow \overline{F(f, U)}$ be inclusion maps. Thus we may define inverse systems $\mathscr{T}_{i}(f)=\left\{\overline{F_{i}(f, Q)}, j j_{Q^{\prime}}^{i}, q\right.$, $\left.\left(\mathcal{C}_{o v}(X), \gg\right)\right\}$ and $\mathscr{F}(f)=\left\{\overline{F\left(f, \mathcal{U}^{\prime}\right)}, j_{\mathcal{V}^{\prime}, q},(\operatorname{Cov}(X), \gg)\right\}$. Here $\mathcal{U}^{\prime} \gg \mathcal{U}$ neans that $\mathcal{U}^{\prime}<\mathcal{Q}$, and then $(\operatorname{Cov}(X), \gg)$ forms a directed set.
(6.4) LEMMA. $\quad F_{i}(f)=\lim \mathscr{F}_{i}(f)$ and $F(f)=\lim \mathscr{T}(f)$ for each $i$.

Proof. Take any i. Since all bonding maps in $\mathscr{F}_{i}(f)$ and $\mathscr{F}(f)$ are inclusions, $\lim \mathscr{F}_{i}(f)=\cap\left\{\overline{F_{i}(f, \mathscr{U})}: \mathscr{U} \in \mathcal{C} o v(X)\right\}$ and $\lim \mathscr{G}(f)=\cap\left\{\overline{F(f, \widetilde{U})}: \mathscr{U} \in \mathcal{C}_{o v}(X)\right\}$. Then we need to show that $F_{i}(f)=\cap\left\{\overline{F_{i}(f, \mathscr{Q})}: \mathscr{U} \in \operatorname{Cov}(X)\right\}$ and $F(f)=\cap\{\overline{F(f, \mathscr{U})}$ : $\mathcal{U} \in \mathcal{C o v}(X)\}$. From the definitions $F_{i}(f) \subset F_{i}(f, \mathcal{U})$ and $F(f) \subset F(f, \mathcal{U})$ for $U \in \operatorname{Cov}(X)$. Thus it is sufficient to show that

$$
\begin{align*}
& \cap\left\{F_{i}(f, \mathscr{U}): \mathscr{U} \in \mathcal{C}_{o v}(X)\right\} \subset F_{i}(f) \text { and }  \tag{1}\\
& \cap\left\{F(f, \mathscr{U}): \mathcal{U} \in \mathcal{C}_{o v}(X)\right\} \subset F(f) . \tag{2}
\end{align*}
$$

Claim. For each $\mathcal{U} \in \mathcal{C}_{o v}(X)$ there exists $\mathscr{W}<\mathcal{U}$ such that $\overline{F_{i}(f, \mathscr{W}) \subset F_{i}(f, \mathcal{Q}) \text {. } . . . . . ~}$
We put $k_{i}=\pi_{i}^{*} \eta_{X}^{-1} j f: X \rightarrow X^{n} / G \xrightarrow{j} 2^{X n / G} \rightarrow 2^{X^{n}} \rightarrow 2^{X}$. Here $j$ is an inclusion map. Since $\eta_{X^{-1}}: 2^{X^{n / G}} \rightarrow 2^{X^{n}}$ is continuous by the proof of (4.4), $k_{i}$ is continuous. Take any $\mathcal{U} \in \mathcal{C}_{\operatorname{Ov}}(X)$. Since $X$ is compact, there exists a finite covering $\mathcal{V} \in$ $\mathcal{C o v}(X)$ such that $s t \mathcal{V}<\mathcal{U}$. For each $x \in X$ we put $m(x)=\left\{V \in \mathcal{V}: V \cap \pi_{i} \eta^{-1} f(x)\right.$ $\neq \varnothing\}$ and $m(x)=\left\{V_{1}^{x}, V_{2}^{x}, \cdots, V_{n(x)}^{x}\right\}$. Since $\left\langle V_{1}^{x}, V_{2}^{x}, \cdots, V_{n(x)}^{x}\right\rangle$ is an open neighborhood of $\pi_{i} \eta^{-1} f(x)$ in $2^{x}$, there exists an open neighborhood $W_{x}^{\prime}$ of $x$ in $X$ such that

$$
\begin{equation*}
k_{i}\left(W_{x}^{\prime}\right) \subset\left\langle V_{1}^{x}, V_{2}^{x}, \cdots, V_{n(x)}^{x}\right\rangle \quad \text { for each } \quad x \in X . \tag{3}
\end{equation*}
$$

We put $\mathscr{W}^{\prime}=\left\{W_{x}^{\prime}: x \in X\right\}$ and $\mathscr{W}=\mathscr{W}^{\prime} \wedge \subset \cup \in \operatorname{Cov}(X)$.
We show that $\mathscr{W}$ has the required property. Take any $x \in \overline{F_{i}(f, \mathscr{W})}$. There exists $V_{1} \in \mathscr{V}$ with $x \in V_{1}$. Since $V_{1} \cap W_{x}^{\prime}$ is a neighborhood of $x$ in $X, V_{1} \cap$ $W_{x}^{\prime} \cap F_{i}(f, \mathscr{W}) \neq \varnothing$. Take any $x_{1} \in V_{1} \cap W_{x}^{\prime} \cap F_{i}(f, \mathscr{W})$ and then $s t\left(x_{1}, \mathscr{W}\right) \cap$ $\pi_{i} \eta^{-1} f\left(x_{1}\right) \neq \varnothing$. There exists $W=V_{2} \cap W_{x^{\prime}}^{\prime}$ such that $V_{2} \in \mathcal{V}, W_{x^{\prime}}^{\prime} \in \mathscr{W}^{\prime}, x_{1} \in W$ and $W \cap \pi_{i} \eta^{-1} f\left(x_{1}\right) \neq \varnothing$. Then there exists $x_{2} \in W \cap \pi_{i} \eta^{-1} f\left(x_{1}\right)$ and thus

$$
\begin{equation*}
x_{1}, x_{2} \in V_{2} \quad \text { and } \quad x_{2} \in \pi_{i} \eta^{-1} f\left(x_{1}\right) \tag{4}
\end{equation*}
$$

Since $x, x_{1} \in V_{1} \cap W_{x}^{\prime}$, then $k_{i}(x), k_{i}\left(x_{1}\right) \in\left\langle V_{1}^{x}, V_{2}^{x}, \cdots, V_{n(x)}^{x}\right\rangle$ i.e.,

$$
\begin{align*}
& \pi_{i} \eta^{-1} f\left(x_{1}\right) \subset V_{1}^{x} \cup V_{2}^{x} \cup \cdots \cup V_{n(x)}^{x} \quad \text { and }  \tag{5}\\
& \pi_{i} \eta^{-1} f(x) \cap V_{t}^{x} \neq \varnothing \quad \text { for each } \quad t, 1 \leqq t \leqq n(x) .
\end{align*}
$$

By (4)-(5) $x_{2} \in V_{i_{0}}^{x}$ for some $t_{0}, 1 \leqq t_{0} \leqq n(x)$ and then by (6)

$$
\begin{equation*}
x_{2} \in V_{t_{0}}^{x} \quad \text { and } \quad \pi_{i} \eta^{-1} f(x) \cap V_{t_{0}}^{x} \neq \varnothing . \tag{7}
\end{equation*}
$$

Since $x, x_{1} \in V_{1} \cap W_{x}^{\prime}$, by (4) and (7)

$$
\begin{equation*}
x \in s t\left(V_{2}, Q\right) \text { and } s t\left(V_{2}, Q\right) \cap \pi_{i} \eta^{-1} f(x) \neq \varnothing \tag{8}
\end{equation*}
$$

Since $s t \subset \cup<\mathcal{Q}$, by (8) $s t\left(V_{2}, \mathcal{V}\right) \subset s t(x, \mathcal{U})$ and $s t(x, \mathcal{U}) \cap \pi_{i} \eta^{-1} f(x) \neq \varnothing$. Then $x \in F_{i}(f, U)$ and hence we have the Claim.

To prove (1) take any $x \notin F_{i}(f)$. Since $x \notin \pi_{i} \eta^{-1} f(x),\{x\}$ and $\pi_{i} \eta^{-1} f(x)$ are disjoint closed subsets of $X$. Then there exists $\mathcal{U} \in \operatorname{Cov}(X)$ such that $\operatorname{st}(x, \mathcal{U}) \cap$ $s t\left(\pi_{i} \eta^{-1} f(x), \mathcal{Q}\right)=\varnothing$. Thus $x \notin F_{i}(f, \mathcal{Q})$. By the Claim there exists $\mathscr{W} \in \mathcal{C}_{o v}(X)$ such that $\overline{F_{i}(f, \mathscr{W})} \subset F_{i}(f, \mathscr{Q})$. Then $x \notin \overline{F_{i}(f, \mathscr{W})}$ and hence $x \notin \cap\left\{\overline{F_{i}(f, \mathscr{Q})}: \mathcal{U}\right.$ $\left.\in \mathcal{C}_{o v}(X)\right\}$. This means (1) and hence the first assertion.

To prove (2) take any $x \notin F(f)$ and then $x \notin F_{i}(f)$ for each $i, 1 \leqq i \leqq n$. Since
$F_{i}(f)=\cap\left\{\overline{F_{i}(f, \mathcal{U})}: \mathcal{U} \in \operatorname{Cov}(X)\right\}$ by the first assertion, then there exists $\mathcal{U}_{i} \in$ $\mathcal{C}_{\text {oo }}(X)$ such that $x \notin \overline{F_{i}\left(f, \mathcal{U}_{i}\right)}$ for each $i$. We put $U=\mathcal{U}_{1} \wedge \mathcal{U}_{2} \wedge \cdots \wedge \mathcal{U}_{n} \in \mathcal{C}_{\text {ov }}(X)$ and then $x \notin \overline{F_{i}(f, \mathcal{U})}$ for all $i, 1 \leqq i \leqq n$. Since $\overline{F(f, V)}=\cup\left\{\overline{F_{i}(f, V)}: i=1,2, \cdots, n\right\}$, $x \notin \overline{F(f, \bar{Q})}$ and hence $x \notin \cap\{\overline{F(f, \bar{Q})}: U \in \mathcal{C}$ ov $(X)\}$. This means (2) and hence the second assertion.

Since $\mathscr{G}(f)$ is an inverse system of compact spaces, the following follows from (6.3) and (6.4).
(6.5) Lemma. If $f$ has a $\mathcal{U}$-fixed point for each $\mathcal{U} \in \operatorname{Cov}(X)$, then $f$ has a fixed point.
(6.6) Lemma. Let $x=\left(x_{1}, x_{2}, \cdots, x_{n}\right), \quad y=\left(y_{1}, y_{2}, \cdots, y_{n}\right) \in X^{n}$. Let $\mathcal{U} \in$ $\mathcal{C}_{\text {ov }}(X)$ and $U=U_{1} \times U_{2} \times \cdots \times U_{n} \in \mathcal{U}^{n}$. If $\eta(x), \eta(y) \in \operatorname{st}\left(\eta(U), \eta\left(\mathcal{U}^{n}\right)\right)$, then for each $i, 1 \leqq i \leqq n$, there exist $j, 1 \leqq j \leqq n$, and $U^{*} \in \mathcal{U}$ such that $x_{i}, y_{j} \in \operatorname{st}\left(U^{*}, \mathcal{U}\right)$.

Proof. Since $\eta(x), \eta(y) \in s t\left(\eta(U), \eta\left(U^{n}\right)\right)$, there exist $U^{\prime}=U_{1}^{\prime} \times \cdots \times U_{n}^{\prime}$, $U^{\prime \prime}=U_{1}^{\prime \prime} \times \cdots \times U_{n}^{\prime \prime} \in \mathcal{U}^{n}$ such that

$$
\begin{align*}
& \eta(x) \in \eta\left(U^{\prime}\right) \text { and } \quad \eta(y) \in \eta\left(U^{\prime \prime}\right),  \tag{1}\\
& \eta\left(U^{\prime}\right) \cap \eta(U) \neq \varnothing \quad \text { and } \quad \eta\left(U^{\prime \prime}\right) \cap \eta(U) \neq \varnothing . \tag{2}
\end{align*}
$$

By (2) there exist $s^{\prime}=\left(s_{1}^{\prime}, s_{2}^{\prime}, \cdots, s_{n}^{\prime}\right) \in U^{\prime}, s=\left(s_{1}, s_{2}, \cdots, s_{n}\right) \in U, t^{\prime \prime}=\left(t_{1}^{\prime \prime}, t_{2}^{\prime \prime}, \cdots, t_{n}^{\prime \prime}\right)$ $\in U^{\prime \prime}$ and $t=\left(t_{1}, t_{2}, \cdots, t_{n}\right) \in U$ such that

$$
\begin{align*}
& \eta\left(s^{\prime}\right)=\eta(s) \in \eta\left(U^{\prime}\right) \cap \eta(U) \text { and }  \tag{3}\\
& \eta\left(t^{\prime \prime}\right)=\eta(t) \in \eta\left(U^{\prime \prime}\right) \cap \eta(U) .
\end{align*}
$$

By (1) there exist $x^{\prime}=\left(x_{1}^{\prime}, x_{2}^{\prime}, \cdots, x_{n}^{\prime}\right) \in U^{\prime}$ and $y^{\prime \prime}=\left(y_{1}^{\prime \prime}, y_{2}^{\prime \prime}, \cdots, y_{n}^{\prime \prime}\right) \in U^{\prime \prime}$ such that

$$
\begin{equation*}
\eta(x)=\eta\left(x^{\prime}\right) \quad \text { and } \quad \eta(y)=\eta\left(y^{\prime \prime}\right) \tag{5}
\end{equation*}
$$

By (3)-(5) there exist $g_{1}, g_{2}, g_{3}, g_{4} \in G$ such that $x=g_{1} x^{\prime}, s^{\prime}=g_{2} s, t=g_{3} t^{\prime \prime}$ and $y^{\prime \prime}=g_{4} y$. Take any $i, 1 \leqq i \leqq n$, and then
(6) $x_{i}=x_{g_{1}(i)}^{\prime}, \quad s_{g_{1}(i)}^{\prime}=s_{g_{2} g_{1}(i)}, \quad t_{g_{2} g_{1}(i)}=t_{g_{3} g_{2} g_{1}(i)}^{\prime \prime}$ and $y_{g_{3} g_{2} g_{1}(i)}^{\prime \prime}=y_{g_{4} g_{3} g_{2} g_{1}(i)}$.

Since $x^{\prime}, s^{\prime} \in U^{\prime}, s, t \in U$ and $t^{\prime \prime}, y^{\prime \prime} \in U^{\prime \prime}$, we have that

$$
\begin{align*}
& x_{g_{1}(i)}^{\prime}, s_{g_{1}(i)}^{\prime} \in U_{g_{1}(i)}^{\prime}, \quad s_{g_{2} g_{1}(i)}, t_{g_{2} g_{1}(i)} \in U_{g_{2} g_{1}(i)} \quad \text { and }  \tag{7}\\
& t_{g_{3} g_{2} g_{1}(i)}^{\prime \prime}, y_{g_{3} g_{2} g_{1}(i)}^{\prime \prime} \in U_{B_{3} g_{2} g_{1}(i)}^{\prime \prime} .
\end{align*}
$$

$\operatorname{By}(6)$ and (7) $x_{i}, y_{g_{4} g_{3} g_{2} g_{1}(i)} \in s t\left(U_{g_{2} g_{1}(i)}, U\right)$. This means that $j=g_{4} g_{3} g_{2} g_{1}(i)$ and $U^{*}=U_{g_{2} g_{1}(i)} \in \mathcal{U}$ are the required index and covering.
(6.7) Lemma. Under the same conditions as in (6.2) $f$ has a U-fixed point for
each $\mathcal{U} \in \operatorname{Cov}(X)$.
Proof. By (I.3.15) there exists an approximative finite polyhedral resolution $p=\left\{p_{a}: a \in A\right\}: X \rightarrow\left(\mathscr{X}, \mathcal{U}^{\prime}\right)=\left\{\left(X_{a}, \mathcal{V}_{a}^{\prime}\right), p_{a^{\prime}, a}, A\right\}$. By (1) in the proof of (4.2) and (4.6) $\underline{p}=\left\{\underline{p}_{a}: a \in A\right\}: X^{n} / G \rightarrow\left(\mathcal{X}, \mathcal{U}^{\prime}\right)^{n} / G=\left\{\left(X_{a}^{n} / G, \eta_{a}\left(\mathcal{U}_{a}^{\prime n}\right)\right), \underline{p}_{a^{\prime}, a}, A\right\}$ forms an approximative finite polyhedral resolution. Since all $X_{a}$ and $X_{a}^{n} / G$ are finite polyhedra, there exist $\vartheta_{a}^{\prime \prime} \in \mathcal{C} \operatorname{Cov}\left(X_{a}\right)$ and $\mathcal{V}_{a}^{\prime \prime} \in \operatorname{Cov}\left(X_{a}^{n} / G\right)$ such that $s t^{2} \vartheta_{a}^{\prime \prime}$ and $s t^{2} \mathcal{C}_{a}^{\prime \prime}$ satisfy (**) in (I.5.6). By (I.4.4) there exist $\mathcal{U}_{a} \in \mathcal{C}_{o v}\left(X_{a}\right)$ for all $a \in A$ such that $\mathcal{U}_{a}<\mathcal{Y}_{a}^{\prime \prime}, \mathcal{V}_{a}^{n}<\eta_{X}^{-1} \mathcal{V}_{a}^{\prime \prime}$ for $a \in A$ and $(\mathscr{X}, \mathcal{U})=\left\{\left(X_{a}, \mathcal{U}_{a}\right), p_{a^{\prime}, a}, A\right\}$ forms an approximative inverse system. By the choice of $U_{a}$ and (I. 3.3) $\boldsymbol{p}: X$ $\rightarrow(\mathscr{X}, \mathcal{U})$ is an approximative $\mathrm{POL}_{f}$-resolution. By (4.6) $\underline{p}: X^{n} / G \rightarrow(\mathscr{X}, \mathcal{U})^{n} / G$ is also an approximative $\mathbf{P O L}_{f}$-resolution. By the choice of $\mathcal{U}_{a}$ for each $a \in A$ and for any space $Y$

> if $g, h: Y \rightarrow X_{a}$ are $s t^{2} U_{a}$-near, then $g \simeq h$ and
> if $g, h: Y \rightarrow X_{a}^{n} / G$ are $s t^{2} \eta_{a}\left(\vartheta_{a}^{n}\right)$-near, then $g \simeq h$.

By the continuity of Čech homology $H_{m}(X)=\lim \left\{H_{m}\left(X_{a}\right), p_{a^{\prime}, a * m}, A\right\}$. Since $X$ is of finite type and all $X_{a}$ are finite polyhedra, by (5.5) there exists $a_{0} \in A$ satisfying

$$
\begin{align*}
& p_{a * m}: H_{m}(X) \rightarrow H_{m}\left(X_{a}\right) \text { are } 1-1 \text { for all } m \text { and all } a>a_{0} \text { and }  \tag{3}\\
& \text { for each } a^{\prime}>a_{0} \text { there exists } k\left(a^{\prime}\right)>a^{\prime} \text { such that }  \tag{4}\\
& \operatorname{Im}\left(p_{a^{\prime} * m}\right)=\operatorname{Im}\left(p_{a, a^{\prime} * m}\right) \text { for all } m \text { and all } a>k\left(a^{\prime}\right) .
\end{align*}
$$

Here $\operatorname{Im}\left(p_{a^{\prime} * m}\right)$ denotes the image of $p_{a^{\prime} * m}: H_{m}(X) \rightarrow H_{m}\left(X_{a^{\prime}}\right)$.
Let $\boldsymbol{f}=\left\{f, f_{a}: a \in A\right\}:(\mathcal{X}, \mathcal{U}) \rightarrow(\mathscr{X}, \mathcal{U})^{n} / G$ be an approximative resolution of $f$ with respect to $\boldsymbol{p}$ and $\underline{p}$. Since $f$ is an NE-map, $\boldsymbol{f}$ satisfies (NE).

Take any $q \in \mathcal{C}_{o v}(X)$. Then by (AR1) there exists $a_{1}>a_{0}$ such that $p_{a_{1}}^{-1} t^{2} U_{a_{1}}$ $<\mathcal{U}$. By (NE) for $\boldsymbol{f}$ there exists $a_{2}>f\left(a_{1}\right)$ satisfying (NE) for $\boldsymbol{f}$ and $a_{1}$. Take any $a_{3}>a_{1}, a_{2}$. We put $A\left(a_{3}\right)=\left\{a \in A: a>a_{3}\right\}, F_{a}^{i}=\left\{x \in X_{a}: \operatorname{st}\left(p_{a, a_{1}}(x)\right.\right.$, st $\left.q_{a 1}\right)$ $\left.\cap \pi_{i} \eta_{a_{1}}^{-1} f_{a_{1}} p_{a, f\left(a_{1}\right)}(x) \neq \varnothing\right\}$ for each $a \in A\left(a_{3}\right)$ and $i=1,2, \cdots, n$, and $F_{a}=\cup$ $\left\{F_{a}^{i}: i=1,2, \cdots, n\right\}$. It is easy to show that $p_{a^{\prime}, a}\left(F_{a^{\prime}}^{i}\right) \subset F_{a}^{i}$ and then $p_{a^{\prime}, a}\left(F_{a^{\prime}}\right)$ $\subset F_{a}$ for $a^{\prime}>a$ and all $i$. Thus $p_{a^{\prime}, a}\left(\bar{F}_{a^{\prime}}\right) \subset \bar{F}_{a}$ for $a^{\prime} \geqq a$. This means that $\mathcal{F}=$ $\left\{\bar{F}_{a}, p_{a^{\prime}, a}, A\left(a_{3}\right)\right\}$ forms an inverse system consisting of compact spaces.

Claim 1. $F_{a} \neq \varnothing$ for all $a \in A\left(a_{3}\right)$.
Take any $a \in A\left(a_{3}\right)$. By the choice of $a_{2}$, there exists a map $r: X_{a_{2}} \rightarrow X_{k(a)}^{n} / G$ such that

$$
\begin{equation*}
\left(f_{a_{1}} p_{a_{2}, f\left(a_{1}\right)}, \underline{p}_{k(a), a_{1}} r\right)<\operatorname{st} \eta_{a_{1}}\left(\vartheta_{a_{1}}^{n}\right) . \tag{5}
\end{equation*}
$$

By (5) $\left(f_{a_{1}} p_{f\left(a_{1}\right)}, \underline{p}_{k(a), a_{1}} r p_{a_{2}}\right)<\operatorname{st} \eta_{a_{1}}\left(\mathcal{U}_{a_{1}}^{n}\right)$. Since $\boldsymbol{f}$ is an approximative resolu-
tion of $f$,

$$
\begin{equation*}
\left(\underline{p}_{a_{1}} f, f_{a_{1}} p_{f\left(a_{1}\right)}<\eta_{a_{1}}\left(q_{a_{1}}^{n}\right) .\right. \tag{6}
\end{equation*}
$$

Since $\left(\underline{p}_{a_{1}} f, \underline{p}_{k(a), a_{1}} r p_{a_{2}}\right)<s t^{2} \eta_{a_{1}}\left(\vartheta_{a_{1}}^{n}\right)$ by (6), by (2)

$$
\begin{equation*}
\underline{p}_{a_{1}} f \simeq \underline{p}_{k(a), a_{1}} r p_{a_{2}} . \tag{7}
\end{equation*}
$$

Take any integer $m$. By (7) $\underline{p}_{a_{1} * m} f_{* m}=\underline{p}_{k(a), a_{1} * m} r_{* m} p_{a_{2} * m}$ and by (M1)

$$
\begin{equation*}
p_{a, a_{1} * m} p_{a * m} \mu_{m} f_{* m}=p_{a, a_{1} * m} p_{k(a), a * m} \mu_{m}^{k(a)} r_{* m} p_{a_{2} * m} \tag{8}
\end{equation*}
$$

By (3) and (4)
(9) $p_{a, a_{1} * m} \mid \operatorname{Im}\left(p_{a * m}\right): \operatorname{Im}\left(p_{a * m}\right) \rightarrow H_{m}\left(X_{a_{1}}\right)$ is 1-1 and $\operatorname{Im}\left(p_{a * m}\right)=\operatorname{Im}\left(p_{k(a), a * m}\right)$.

Then by (8) and (9)

$$
\begin{equation*}
p_{a * m} \mu_{m} f_{* m}=p_{k(a), a * m} \mu_{m}^{k(a)} r_{* m} p_{a_{2} * m} . \tag{10}
\end{equation*}
$$

Let $g=\underline{p}_{k(a), a} r p_{a, a_{2}}: X_{a} \rightarrow X_{a}^{n} / G$ and then by (10) and (M1)

$$
\begin{equation*}
p_{a * m} \mu_{m} f_{* m}=\mu_{m}^{a} g_{* m} p_{a * m} \tag{11}
\end{equation*}
$$

Let $h_{m}=\left(p_{a * m}\right)^{-1} p_{k(a), a * m} \mu_{m}^{k(a)} r_{* m} p_{a, a_{2} * m}: H_{m}\left(X_{a}\right) \rightarrow H_{m}(X)$. By (9) $h_{m}$ is well defined and by (M1)

$$
\begin{equation*}
p_{a * m} h_{m}=\mu_{m}^{a} g_{* m} \tag{12}
\end{equation*}
$$

By (11) and (12) $p_{a * m} h_{m} p_{a * m}=p_{a * m} \mu_{m} f_{* m}$ and then by (3)

$$
\begin{equation*}
h_{m} p_{a * m}=\mu_{m} f_{* m} \tag{13}
\end{equation*}
$$

By (12) and (13) $\operatorname{tr}\left(\mu_{m} f_{* m}\right)=\operatorname{tr}\left(h_{m} p_{a * m}\right)=\operatorname{tr}\left(p_{a * m} h_{m}\right)=\operatorname{tr}\left(\mu_{m}^{a} g_{* m}\right)$. Then $L(f)=$ $\sum_{m=0}^{\infty}(-1)^{m} \operatorname{tr}\left(\mu_{m} f_{* m}\right)=\sum_{m=0}^{\infty}(-1)^{m} \operatorname{tr}\left(\mu_{m}^{a} g_{* m}\right)=L(g)$, that is,

$$
\begin{equation*}
L(f)=L(g) \tag{14}
\end{equation*}
$$

By the assumption $L(f) \neq 0$, then by (14) $L(g) \neq 0$. By (6.1) there exists a fixed point $x_{0}$ of $g$. Take any $x=\left(x_{1}, x_{2}, \cdots, x_{n}\right) \in X_{a}^{n}$ such that $\eta_{a}(x)=g\left(x_{0}\right)$. Since $x_{0}$ is a fixed point of $g$, there exists $i_{0}, 1 \leqq i_{0} \leqq n$ such that $x_{0}=x_{i_{0}}$. By the definition of $g$ and (5) $\left(f_{a_{1}} \beta_{a . f\left(a_{1}\right)}, \underline{p}_{a, a_{1}} g\right)<s t \eta_{a_{1}}\left(q_{a_{1}}^{n}\right)$ and then there exists $U=U_{1} \times \cdots \times U_{n} \in \mathcal{U}_{a_{1}}^{n}$ such that

$$
\begin{equation*}
f_{a_{1}} p_{a, f\left(a_{1}\right)}\left(x_{0}\right), \underline{p}_{a, a_{1}} g\left(x_{0}\right) \in s t\left(\eta_{a_{1}}(U), \eta_{a_{1}}\left(\vartheta_{a_{1}}^{n}\right)\right) \tag{15}
\end{equation*}
$$

Then $f_{a_{1}} p_{a, f\left(a_{1}\right)}\left(x_{0}\right)=\eta_{a_{1}}(y)$ for some $y=\left(y_{1}, y_{2}, \cdots, y_{n}\right) \in X_{a_{1}}^{n}$. Since $\underline{p}_{a, a_{1}} g\left(x_{0}\right)$ $=\underline{p}_{a, a_{1}} \eta_{a}(x)=\eta_{a_{1}} p_{a, a_{1}}^{n}\left(x_{1}, x_{2}, \cdots, x_{n}\right)=\eta_{a_{1}}\left(p_{a, a_{1}}\left(x_{1}\right), p_{a, a_{1}}\left(x_{2}\right), \cdots, p_{a, a_{1}}\left(x_{n}\right)\right)$, means that $\eta_{a_{1}}\left(y_{1}, y_{2}, \cdots, y_{n}\right), \eta_{a_{1}}\left(p_{a, a_{1}}\left(x_{1}\right), \cdots, p_{a, a_{1}}\left(x_{n}\right)\right) \in s t\left(\eta_{a_{1}}(U), \eta_{a_{1}}\left(\mho_{a_{1}}^{n}\right)\right)$. Thus by (6.6) there exists $j, 1 \leqq j \leqq n$ and $U^{*} \in \mathcal{G}_{a_{1}}$ such that

$$
\begin{equation*}
p_{a, a_{1}}\left(x_{i_{0}}\right), y_{j} \in s t\left(U^{*}, q_{a_{1}}\right) . \tag{16}
\end{equation*}
$$

Since $x_{0}=x_{i_{0}}$ and $y_{j} \in \pi_{j} \eta_{a_{1}}^{-1} f_{a_{1}} p_{a, f\left(a_{1}\right)}\left(x_{0}\right)$, (16) means that $s t\left(p_{a, a_{1}}\left(x_{0}\right), s t U_{a_{1}}\right) \cap$ $\pi_{j} \eta_{a_{1}}^{-1} f_{a_{1}} p_{a, f\left(a_{1}\right)}\left(x_{0}\right) \neq \varnothing$, that is, $x_{0} \in F_{a}^{j} \subset F_{a}$. Hence $F_{a}$ is not empty. We have Claim 1.

Claim 2. All points of $\lim \mathscr{F}$ are $U$-fixed points of $f$.
Take any $z \in F=\lim \mathcal{F}$, any $a \in A\left(a_{3}\right)$ and put $z_{a}=p_{a}(z) \in \bar{F}_{a}$. There exists $U_{1}^{*} \in \mathcal{G}_{a_{1}}$ such that $p_{a, a_{1}}\left(z_{a}\right)=p_{a_{1}}(z) \in U_{1}^{*} . \quad B y(6)$ there exists $U^{\prime}=U_{1}^{\prime} \times \cdots \times U_{n}^{\prime}$ $\in \mathcal{U}_{a_{1}}^{n}$ such that

$$
\begin{equation*}
\underline{p}_{a, a_{1}} f(z), f_{a_{1}} p_{a, f\left(a_{1}\right)}\left(z_{a}\right) \in \eta_{a_{1}}\left(U^{\prime}\right) . \tag{17}
\end{equation*}
$$

Put $W=p_{a, a_{1}}^{-1}\left(U_{1}^{*}\right) \cap\left(f_{a_{1}} p_{a, f\left(a_{1}\right)}\right)^{-1}\left(\eta_{a_{1}}\left(U^{\prime}\right)\right)$ and then $W$ is an open neighborhood of $z_{a}$ in $X_{a}$. Since $z_{a} \in \bar{F}_{a}$, then $W \cap F_{a} \neq \varnothing$. Take any $w \in W \cap F_{a}$. Since $w \in W$, then

$$
\begin{equation*}
p_{a, a_{1}}(w) \in U_{1}^{*} \quad \text { and } \quad f_{a_{1}} p_{a, f\left(a_{1}\right)}(w) \in \eta_{a_{1}}\left(U^{\prime}\right) \tag{18}
\end{equation*}
$$

Since $w \in F_{a}$, there exists $i_{1}, 1 \leqq i_{1} \leqq n$, with $w \in F_{a}^{i_{1}}$ and then there exists $U_{2}^{*} \in$ $\mathcal{U}_{a_{1}}$ such that

$$
\begin{align*}
& p_{a, a_{1}}(w) \in s t\left(U_{2}^{*}, U_{a_{1}}\right) \text { and }  \tag{19}\\
& \operatorname{st}\left(U_{2}^{*}, U_{a_{1}}\right) \cap \pi_{i_{1}} \eta_{a_{1}}^{-1} f_{a_{1}} p_{a, f\left(a_{1}\right)}(w) \neq \varnothing . \tag{20}
\end{align*}
$$

By (18) there exist $z_{f}=\left(z_{1}^{f}, z_{2}^{f}, \cdots, z_{n}^{f}\right) \in X^{n}$ and $w^{\prime}=\left(w_{1}^{\prime}, w_{2}^{\prime}, \cdots, w_{n}^{\prime}\right) \in U^{\prime}$ such that $f(z)=\eta\left(z_{f}\right)$ and $f_{a_{1}} p_{a, f\left(a_{1}\right)}(w)=\eta_{a_{1}}\left(w^{\prime}\right)$. By (20) there exists $w^{\prime \prime}=$ $\left(w_{1}^{\prime \prime}, w_{2}^{\prime \prime}, \cdots, w_{n}^{\prime \prime}\right) \in X_{a_{1}}^{n}$ such that $f_{a_{1}} p_{a, f\left(a_{1}\right)}(w)=\eta_{a_{1}}\left(w^{\prime \prime}\right)$ and

$$
\begin{equation*}
w_{i_{1}}^{\prime \prime} \in s t\left(U_{2}^{*}, U_{a_{1}}\right) \tag{21}
\end{equation*}
$$

Since $\eta_{a_{1}}\left(w^{\prime \prime}\right)=\eta_{a_{1}}\left(w^{\prime}\right)$, there exists $g_{1} \in G$ such that $g_{1}\left(w^{\prime}\right)=w^{\prime \prime}$, and then

$$
\begin{equation*}
w_{i_{1}}^{\prime \prime}=w_{g_{1}\left(i_{1}\right)}^{\prime} . \tag{22}
\end{equation*}
$$

By (17) there exists $z^{\prime}=\left(z_{1}^{\prime}, z_{2}^{\prime}, \cdots, z_{n}^{\prime}\right) \in U^{\prime}$ such that $\underline{p}_{a_{1}} f(z)=\eta_{a_{1}}\left(z^{\prime}\right)$. Since $\underline{p}_{a_{1}} f(z)=\underline{p}_{a_{1}} \eta\left(z_{f}\right)=\eta_{a_{1}} p_{a_{1}}^{n}\left(z_{f}\right)=\eta_{a_{1}}\left(p_{a_{1}}\left(z_{1}^{f}\right), \cdots, p_{a_{1}}\left(z_{n}^{f}\right)\right)$, there exists $g_{2} \in G$ such that $z^{\prime}=g_{2}\left(p_{a_{1}}\left(z_{1}^{f}\right), \cdots, p_{a_{1}}\left(z_{n}^{f}\right)\right)$ and then

$$
\begin{equation*}
z_{g_{1}\left(i_{1}\right)}^{\prime}=p_{a_{1}}\left(z_{k_{2} g_{1}\left(i_{1}\right)}^{f}\right) . \tag{23}
\end{equation*}
$$

Since $w^{\prime}, z^{\prime} \in U^{\prime}$, then $w_{g_{1}\left(i_{1}\right)}^{\prime}, z_{g_{1}\left(i_{1}\right)}^{\prime} \in U_{g_{1}\left(i_{1}\right)}^{\prime}$. By (21)-(23)

$$
\begin{equation*}
p_{a_{1}}\left(z_{g_{2} g_{1}\left(i_{1}\right)}^{f}\right) \in U_{g_{1}\left(i_{1}\right)}^{\prime} \quad \text { and } \quad U_{g_{1}\left(i_{1}\right)}^{\prime} \cap s t\left(U_{2}^{*}, U_{a_{1}}\right) \neq \varnothing . \tag{24}
\end{equation*}
$$

Since $p_{a_{1}}(z) \in U_{1}^{*}$, by (18) and (19)

$$
\begin{equation*}
p_{a_{1}}(z) \in U_{1}^{*} \quad \text { and } \quad U_{1}^{*} \cap s t\left(U_{2}^{*}, \mathcal{U}_{a_{1}}\right) \neq \varnothing . \tag{25}
\end{equation*}
$$

By (24) and (25) $p_{a_{1}}(z), p_{a_{1}}\left(z_{8_{2} g_{1}\left(i_{1}\right)}\right) \in s t\left(s t\left(U_{2}^{*}, \mathscr{U}_{a_{1}}\right)\right.$,st $\left.U_{a_{1}}\right)$. Since $p_{a_{1}}^{-1} s t^{2} U_{a_{1}}<\mathcal{Q}$, there exists $U^{* *} \in \mathcal{U}$ such that $z, z_{g_{2} g_{1}\left(i_{1}\right)}^{f} \in p_{a_{1}}^{-1} s t\left(s t\left(U_{2}^{*}, \mathcal{U}_{a_{1}}\right), s t \mathcal{U}_{a_{1}}\right) \subset U^{* *}$. Since
$z_{g_{2} g_{1}\left(i_{1}\right)} \in \pi_{g_{2} g_{1}\left(i_{1}\right)} \eta^{-1} f(z)$, we have that $s t(z, \mathcal{Q}) \cap \pi_{g_{2} g_{1}(i)} \eta^{-1} f(z) \neq \varnothing$ and then $z \in F_{g_{2} g_{1}\left(i_{1}\right)}(f, \mathcal{U}) \subset F(f, \mathcal{U})$. Hence $z$ is a $\mathcal{U}$-fixed point of $f$. We have Claim 2.

Since all $F_{a}$ are non-empty compact spaces by Claim $1, F=\lim \mathcal{F}$ is not empty and hence by Claim $2 f$ has a $U$-fixed point. Since $\mathcal{U} \in \mathcal{C o v}(X)$ is arbitrary we have the required assertion.

Theorem (6.2) follows from (6.5) and (6.7).
(6.8) Corollary. Let $X$ be a compact space of finite type, and let $f: X \rightarrow$ $X^{n} / G$ be a map. If $X$ is approximatively movable and $L(f) \neq 0$, then $f$ has a fixed point.
(6.9) Corollary. Let $X$ be a compact $\mathrm{AANR}_{C}$ of finite type, and let $f: X \rightarrow$ $X^{n} / G$ be a map. If $L(f) \neq 0$, then $f$ has a fixed point.
(6.10) Corollary. Let $X$ be a compact $\mathrm{AANR}_{N}$ and let $f: X \rightarrow X^{n} / G$ be $a$ map. If $L(f) \neq 0$, then $f$ has a fixed point.
(6.11) Corollary. Let $X$ be a compact ANR and let $f: X \rightarrow X^{n} / G$ be a map. If $L(f) \neq 0$, then $f$ has a fixed point.
(6.8) follows from (1.9), (1.12) and (6.2). (6.9) follows from (I.9.3) and (6.8). (6.10) follows from (II. 5.11) and (6.9). (6.11) follows from (II. 4.6) and (6.8).

We assume that $n=1$. Since $S_{n}$ consists of only the identity element, $G$ is the trivial group. Thus $X^{n} / G=X$ and $\eta: X^{n} / G \rightarrow X$ is the identity map. Then by (M2) $\mu_{j}: H_{j}\left(X^{n} / G\right)=H_{j}(X) \rightarrow H_{j}(X)$ must be the identity homomorphism. Hence $L(f)=\sum_{j=0}^{\infty}(-1)^{j} \operatorname{tr}\left(\mu_{j} f_{* j}\right)=\sum_{j=0}^{\infty}(-1)^{j} \operatorname{tr}\left(f_{*_{j}}\right)$, that is, $L(f)$ is the usual Lefschetz number $\Lambda(f)$ of $f$. Thus we have the following from (6.2).
(6.12) Theorem. Let $X$ be a compact space of finite type and and let $f: X$ $\rightarrow X$ be a map. If $f$ is an NE-map and $\Lambda(f) \neq 0$, then $f$ has a fixed point.

When $n=1$, (6.1) means the Lefschetz-Hopf fixed point theorem for finite polyhedra. Hence the proof of (6.2) asserts that (6.12) follows from the usual Lefschetz-Hopf fixed point theorem for finite polyhedra.
(6.13) Corollary. Let $X$ be a compact space of finite type and let $f: X \rightarrow X$ be a map. If $X$ is approximatively movable and $\Lambda(f) \neq 0$, then $f$ has a fixed point.
(6.14) Corollary. Let $X$ be a compact $\mathrm{AANR}_{C}$ of finite type and let $f: X$ $X$ be a map. If $\Lambda(f) \neq 0$, then $f$ has a fixed point.
(6.15) Corollary. Let $X$ be a compact $\mathrm{AANR}_{N}$ and let $f: X \rightarrow X$ be a map.

If $\Lambda(f) \neq 0$, then $f$ has a fixed point.
(6.16) Corollary. Let $X$ be a compact ANR and let $f: X \rightarrow X$ be a map. If $\Lambda(f) \neq 0$, then $f$ has a fixed point.

In the same way as for (6.8)-(6.11) we have (6.13)-(6.16) from (6.12).
(6.17) Corollary. Let $X$ be a compact space.
(i) If $X$ is approximatively movable, then $\operatorname{Cone}(X)$ has the fixed point property.
(ii) If $\operatorname{dim} X=n<\infty$ and $X$ is $L C^{n-1}$, then $\operatorname{Cone}(X)$ has the fixed point property.
(6.18) Corollary. If a compact connected space $X$ is approximatively movable, then $2^{x}$ and $C(X)$ have the fixed point property.
(6.19) Corollary. If $X$ is a dendrite, fan or smooth dendroid, then $2^{x}$ and $C(X)$ have the fixed point property.
(6.17) follows from (I. 3.1), (2.5) and (6.15). (6.18) follows from (3.10) and (6.15). (6.19) follows from (3.11) and (6.15).
(6.20) Remark. Kinoshita [27] constructed a contractible continnum $X$ without the fixed point property. Also he showed that Cone $(X)$ does not have the fixed point property. Knill [28] studied the fixed point property for cones. (6.17) is better than Theorem 2.7 of Knill [28]. Rogers [41] constructed a continuum $X$ such that $C(X)$ does not have the fixed point property. (6.18) gives a partial answer to problems in Rogers [41] and Nadler [39]. (6.19) was proved by Fugate [16, 17].
(6.21) Remark. Masih [35] proved (6.11) and Vora [42] proved (9.10) for compact metric spaces. Note that their Maxwell homomorphisms are equivalent to ours by (5.6) and (5.7). Knill [28] proved the Lefschetz-Hopf fixed point theorem for $Q$-simplicial spaces. Using his results Clapp [9] proved (6.14) for compact metric spaces. Granas [22] proved (6.15) for compact metric spaces. (6.12) was proved by Borsuk [4] for compact metric spaces and by Gauthier [19] for compact spaces. Their proofs depend on (6.16). Our proof depends only on the Lefschetz-Hopf fixed point theorem for finite polyhedra and then (6.16) is our corollary.

## References

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