

Heterogeneity of link weight and the evolution of cooperation

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Abstract

In this paper, we investigate the effect of *heterogeneity of link weight*, heterogeneity of the frequency or amount of interactions among individuals, on the evolution of cooperation. Based on an analysis of the evolutionary prisoner's dilemma game on a weighted one-dimensional lattice network with *intra-individual heterogeneity*, we confirm that moderate level of link-weight heterogeneity can facilitate cooperation. Furthermore, we identify two key mechanisms by which link-weight heterogeneity promotes the evolution of cooperation: mechanisms for spread and maintenance of cooperation. We also derive the corresponding conditions under which the mechanisms can work through evolutionary dynamics.

Keywords: Evolution of cooperation, Prisoner's dilemma, Heterogeneity of link weight, One-dimensional lattice network, Game theory

1. Introduction

The evolution of cooperation, which plays a key role in natural and social systems, has attracted much interest in diverse academic fields, including biology, sociology, and economics [1, 2]. The prisoner's dilemma (PD) is often
5 used to study the evolution of cooperation in a population consisting of selfish

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individuals [3, 4]. In the PD game, two individuals simultaneously decide to cooperate or defect. A payoff matrix of the PD game is given in Table 1.

	Cooperation	Defection
Cooperation	R, R	S, T
Defection	T, S	P, P

Table 1: Payoff matrix for the prisoner’s dilemma (PD) game. In this game, two individuals decide simultaneously to cooperate or defect. Mutual cooperation provides them both with a payoff R , whereas mutual defection results in a payoff P . If one individual cooperates and the other defects, the former obtains a payoff T , and the latter a payoff S . These values are assumed to satisfy the conditions $T > R > P > S$ and $2R > S + T$.

If either individual wishes to maximize his/her personal profit in this game, he/she will choose to defect regardless of the opponent’s decision, despite mutual cooperation being better than mutual defection for both individuals. According to the evolutionary dynamics of the PD game where an individual is paired with a randomly chosen opponent in a well-mixed population, cooperators become extinct whereas defectors eventually dominate in the population [5].

However, in a dilemma situation in the real world, we often see that altruistic behaviors exist among unrelated individuals. Nowak [6] proposed *five rules* as the mechanisms enabling the evolution of altruism: kin selection [7], direct reciprocity [4, 8], indirect reciprocity [9, 10], network reciprocity [11, 12, 13, 14, 15, 16, 17, 18, 19], and group selection [20].

In this study, we focus on *network reciprocity*, which is a mechanism pioneered by Nowak and May [11, 12] that enables the evolution of cooperation when each individual is likely to interact repeatedly with a fixed subset of the population only. In Nowak and May’s model, individuals are placed on nodes in a two-dimensional lattice and play the PD game repeatedly with their directly connected neighbors only. The authors show that the spatial constraint of interactions among individuals in the lattice network can facilitate the evolution of cooperation. Although Nowak and May’s model assumes that the population has a simple network structure, that is, a two-dimensional lattice, it has

recently been shown that many real-world networks are identified as *complex networks*. Well-known examples of complex networks are the small-world network [21] and the scale-free network [22], in which *the number of links* (degree) that each individual has differs. Recently, it has been confirmed by Santos and Pacheco [13] that *heterogeneity of the number of links* in complex networks can enhance the evolution of cooperation. There have been following studies that investigate the evolution of cooperation on networks with heterogeneous number of links [14, 15]. This heterogeneity is also known to contribute to the efficiency of collective action [23, 24]. Additionally, it has been shown that the mixing pattern of link degree can affect the emergence of cooperation [16]. See [17, 18] for detailed reviews of evolutionary and coevolutionary games on graphs. Also see [19] for a thorough survey of the evolutionary dynamics of group interactions on various types of structured populations.

The aforementioned studies, however, assume that individuals interact with one another with the same frequency or amount; that is, all the link weights between individuals in the society are identical. On the contrary, individuals in real-world networks, such as scientific collaboration networks, phone call networks, email networks, and airport transportation networks, have heterogeneous intentions in their relationships [25, 26, 27]. There is substantial interest among researchers in knowing how heterogeneity of the strength of relationships (that is, link weight) among individuals influences human behavioral traits (e.g. sociological studies such as [28, 29, 30]).

In particular, researchers have recently investigated whether the heterogeneity of link weight between individuals promotes the evolution of cooperation. For example, Du et al. [31] constructed a simulation model in which individuals are placed on a node in a scale-free network and connected to other individuals with heterogeneous link weights. In their model, individuals interact more frequently with neighbors connected by links with large weights and less frequently with those connected by links with small weights. Du et al. found that cooperative behavior can be more facilitated when the link weights shared by individuals are heterogeneous rather than homogeneous. Note that, in their

model, interaction networks have two kinds of heterogeneity: heterogeneity of
60 the *number of links* and that of *link weight*. Note also that each link weight is
determined according to the number of links of individuals; that is, link weight
is a function of the degrees of the two individuals at either side of the focal
link. Therefore, in the Du et al. model it is difficult to ascertain which factor
enhances cooperation: *heterogeneity of the number of links* or *heterogeneity of*
65 *link weight*.

Additionally, Ma et al. [32] employed a two-dimensional square lattice with
individuals placed on its nodes. In their model, individuals play the PD game
with their immediate neighbors connected by links with heterogeneous link
weights. Ma et al. arranged three populations, where the link weights in
70 the population follow either power-law, exponential, or uniform distribution
patterns. They confirmed that a network with a power-law distribution of link
weights better facilitates the evolution of cooperation than one with link weights
conforming to one of the other two probability distributions.

Because a two-dimensional square lattice is used in their model, each indi-
75 vidual has the same number of links (i.e., four). Thus, their result clearly shows
that *heterogeneity of link weight* can bring about a cooperative state even with-
out *heterogeneity of the number of links*. However, in their model, the sum
of link weights of an individual, which we call the *link-weight amount* of the
individual, differs from those of others. That is, not only each of the links pos-
80 sessed by an individual can have a different weight, but the individual can also
have a different link-weight amount from other individuals. We call the former
intra-individual heterogeneity and the latter *inter-individual heterogeneity*.

When *inter-individual heterogeneity* exists, some individuals play the PD
game more frequently than others (link-weight amount is heterogeneous among
85 individuals). That is, there is *heterogeneity of the interactions among individ-*
uals. It has already been shown [13, 14, 15] that heterogeneity of interactions
among individuals due to *heterogeneity of the number of links among individ-*
uals and not to *inter-individual heterogeneity* can facilitate the evolution of
cooperation.

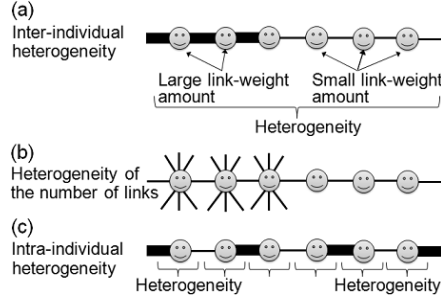


Fig. 1: Examples of a one-dimensional lattice with three kinds of heterogeneity: (a) *inter-individual heterogeneity*, (b) *heterogeneity of the number of links*, and (c) *intra-individual heterogeneity*. Thick and thin lines between individuals denote links with large and small weights, respectively.

Fig. 1 shows three examples of a one-dimensional lattice having, respectively, *intra-individual heterogeneity*, *inter-individual heterogeneity*, and *heterogeneity of the number of links*. Fig. 1(a) shows an example of *inter-individual heterogeneity*, where individuals on the left-hand side have large link-weight amounts and those on the right-hand side have small link-weight amounts. In this case, individuals on the left-hand side interact more frequently with others than those on the right-hand side; that is, there is heterogeneity of interactions between individuals. *Heterogeneity of the number of links* is shown in Fig. 1(b), where individuals on the left-hand side have a large number of links and thus more opportunity to interact than those on the right-hand side. Both *inter-individual heterogeneity* and *heterogeneity of the number of links* bring about a similar type of heterogeneity of interactions among individuals in the sense that either can cause link-weight amount heterogeneity. Finally, Fig. 1(c) shows an example of *intra-individual heterogeneity*, where each individual has both a large-weight link and a small-weight link, but all individuals have an equivalent link-weight amount. That is, *intra-individual heterogeneity* does not involve the heterogeneity of the link-weight amount among individuals but involves the heterogeneity of the weight of links of each individual. Thus, it should be noted that *intra-individual heterogeneity* and *inter-individual heterogeneity* are essentially

different types of heterogeneity.

110 The literature [31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48] has investigated the effect of heterogeneity on the evolution of cooperation from variety of viewpoints ¹. Especially, Du et al. [31] and Ma et al. [32] have clearly shown, as mentioned in the above, that the existence of link-weight heterogeneity facilitates the evolution of cooperation. However, we cannot reject
115 the possibility that the evolution of cooperation in the models of Du et al. and Ma et al. might be facilitated by the effect of link-weight amount heterogeneity, whose effect on the evolution of cooperation has already been confirmed by Santos and Pacheco [13]. This is because the link-weight heterogeneity in their models involves not only *intra-individual heterogeneity* but also *inter-individual*
120 *heterogeneity*. Whether heterogeneity of link weight without *heterogeneity of link-weight amount*, *intra-individual heterogeneity* alone, can promote the evolution of cooperation or not is the remaining question to be solved. Detailed investigation of this question would enable us to understand the underlying mechanism of the evolution of cooperation caused by the heterogeneity of inter-
125 actions among individuals.

To answer this question, we introduce the simplest possible model of a weighted network, with *intra-individual heterogeneity* and without *inter-individual heterogeneity*. First, we employ a weighted one-dimensional lattice as the simplest network model and investigate the effect of link-weight heterogeneity on
130 the enhancement of cooperation. Second, we examine when and how such heterogeneous link weight gives rise to the evolution of cooperation; that is, we investigate the mechanism by which heterogeneity enables cooperation to evolve.

¹For example, Cao et al. [35] focused on the dynamics (change over time) of the magnitude of the link-weight heterogeneity. Chen and Perc [38] examined the effect of the heterogeneity in incentives for rewarding individuals in the public goods game on promoting cooperation. Szolnoki et al. [41], Perc and Szolnoki [42], and Santos et al. [43] examined diversity of individuals. Perc [44] introduced the random variations to the payoff of individuals and investigated the effect of it on the evolution of cooperation. Brede [47] and Tanimoto [48] analyzed the bias in game partner selection.

Specifically, we identify the conditions under which link-weight heterogeneity enables society to become cooperative, through analytical calculation and computer simulation.

2. The model

In this study, we develop a model of a spatial evolutionary game with link-weight heterogeneity based both on the PD cellular automaton model proposed by Nowak and May [11, 12] and the weighted network model employed by Du et al. [31, 33], Ma et al. [32], Buesser [34], and so on. We construct a lattice network model in which each individual occupies one node and is connected to his/her neighbors by links with heterogeneous weights. Each individual has two links, one shared by the individual to his/her left and one to his/her right. We assume periodic boundary conditions for the network we employ.

There are two types of heterogeneity of link weight in a network: (i) *intra-individual heterogeneity*: the heterogeneity of link weight between the links of an individual; that is, an individual can have a large-weight link with one neighbor and a small-weight link with another; and (ii) *inter-individual heterogeneity*: the heterogeneity of link weight between individuals; that is, an individual can have many large-weight links whereas another can have many small-weight links. In this research, we focus on the former type of heterogeneity to begin our investigation on the effect of link-weight heterogeneity on the evolution of cooperation using the simplest form of heterogeneity.

Because we consider a network with *intra-individual heterogeneity* only (i.e., without *inter-individual heterogeneity*), the sums of the link weights of all the individuals are roughly equivalent. Let the weight of a link (large-weight link) of an individual be w_1 and the weight of the other link (small-weight link) be w_2 ($w_1 > w_2 > 0$). Because we assume that there is no *inter-individual heterogeneity* (the sum of w_1 and w_2 is the same for all individuals) and that an individual's right (left) link is shared by the right (left) neighbor, all individuals have a link with weight w_1 and one with weight w_2 .

Hereafter, we assume a large link weight to be $w_1 = 1.0 + w$ and a small weight to be $w_2 = 1.0 - w$ to express w_1 and w_2 using only one parameter, $w \in [0, 1]$. The larger the value of w , the more heterogeneous the link weight becomes. When $w = 0$, link weight in the lattice network is completely homogeneous.

To investigate the evolution of cooperation in weighted networks, we consider the situation where each individual i plays the PD game with his/her immediate neighbors in a weighted lattice network as described above. We assume an individual i has a strategy $s_i = \{C, D\}$ that determines whether to cooperate with or defect from all of his/her neighbors. That is, each individual can either be a cooperator who always cooperates with all his/her opponents or a defector who always defects. According to the literature [11, 12, 13, 14, 15, 16, 17, 18, 31, 32, 33, 35, 41, 42, 47], we rescale the game to be drawn using a single parameter. For the PD game, we let $T = b$, $R = 1$, and $P = S = 0$ ² to rescale the payoff matrix using one parameter b . This parameter represents the payoff of a defector when exploiting a cooperator, and is constrained by the interval $1.0 < b < 2.0$. In each generation, all pairs of connected individuals play the PD game. After playing the game, each individual obtains the payoff *multiplied by the value of the weight of the link with his/her opponent*. The weight of the link between individuals i and j is defined as w_{ij} , and the payoff of an individual i with strategy s_i , when playing with an individual j with strategy s_j , is represented as $\pi_{s_i s_j}$. The total payoff an individual i receives is expressed as $\Pi_i = \sum_{j \in V_i} \pi_{s_i s_j} w_{ij}$, where V_i is the set of neighbors of individual i . In the first generation, each individual's strategy, which is either to cooperate or to defect, is randomly determined with a 50 percent probability. We define the score of each individual in a generation as the sum of the payoffs received from

²As Nowak and May [11] noted, simulation results are typically not affected by whether the payoff matrix involves $P = S$ or $P > S$, thus, we assume $P = S$ in our study. This assumption enables the payoff matrix to be expressed and controlled only by one parameter b .

all the games with his/her neighbors.

After all individuals have played the PD game with all their neighbors, each
190 individual imitates the strategy of the individual with the maximum score
among all his/her neighbors including him/herself. An individual does not
change his/her strategy if he/she is one of those with the maximum score. If an
individual has more than one neighbor, excluding him/herself, with the max-
imum score, he/she chooses one of them randomly. Individuals update their
195 strategies simultaneously, after which one generation is completed.

For the evolutionary simulation, we set the network size $N=10,000$ and set
 b (the temptation to defect from a cooperator) such that $b \in (1.0, 2.0)$ in steps
of 0.01. We assume that $w \in [0, 1.0]$ in steps of 0.01, and therefore, $1.0 + w$
denotes a large weight (strong link) and $1.0 - w$ corresponds to a small weight
200 (weak link).

3. Simulation results and discussion

To examine how heterogeneity of link weight affects the evolution of coopera-
tion, we analyzed how the degree of link-weight heterogeneity, w , affected the
resulting *frequency of cooperation* in the population. The frequency of coopera-
205 tion in each generation was calculated as the ratio of the number of cooperators
to the total population size. We defined the frequency for a simulation run
as the average of the frequency of cooperation over 100 generations after the
2,000th generation. We adopted this definition because, although we wished to
estimate the frequency at the convergent state, we found that this state some-
times did not converge to a fixed state but went to a periodic state. (We checked
210 that the frequency of cooperation could reach a steady or periodic state within
2,000 generations.) We performed 100 runs of the computer simulation for each
parameter setting and calculated the average of the frequency of cooperation
for all the runs ³, which hereafter, we refer to as *the frequency of cooperation*.

³For each parameter setting, all individuals followed the payoff matrix in which parameter b had an identical value and the value of link-weight parameter w was the same for all links.

215 *3.1. Overview of the effect of link-weight heterogeneity on the evolution of co-
operation*

Figs. 2(a) and (b) illustrate the simulation results for the PD game on a weighted one-dimensional lattice and show the frequency of cooperation for different values of link-weight heterogeneity, w . As shown in these figures, changes in the frequency of cooperation with an increase in w differ in the case of a small $b = 1.2$ (Fig. 2(a)) and that of a large $b = 1.8$ (Fig. 2(b)).

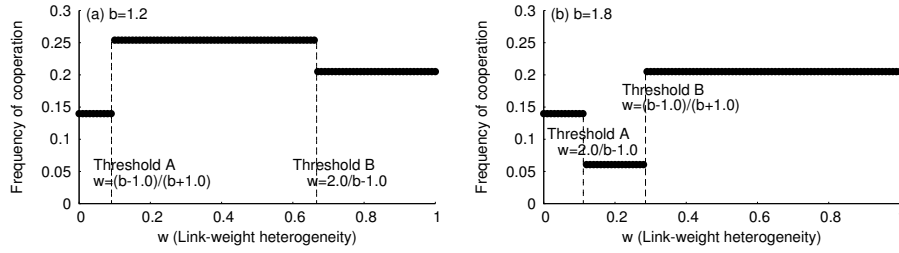


Fig. 2: Frequency of cooperation for different values of link-weight heterogeneity, w , in a weighted one-dimensional lattice: (a) case with a small b ($b=1.2$) and (b) case with a large b ($b=1.8$). The horizontal and vertical axes represent the degree of w , which reflects the magnitude of the heterogeneity of link weight and frequency of cooperation, respectively.

As shown in Fig. 2(a), the frequency of cooperation when the link weight is heterogeneous ($w > 0$) is always greater than that in the case of homogeneous weight ($w = 0$). Fig. 2(b) shows that the frequency of cooperation when the link weight is heterogeneous is smaller than that in the case of homogeneous weight. If the value of w increases further, however, the magnitude of cooperative behavior in the case of heterogeneous weight is greatly enhanced and exceeds that in the case of homogeneous weight. In both cases (a) and (b), the cooperation frequency reaches the maximum at some value of $w(> 0)$ (when there is some degree of link-weight heterogeneity). Both of these figures show that the frequency of cooperation does not change with an increase in w until w reaches a certain threshold; that is, the change in the frequency is not gradual, but *stepwise* with an increase in w . As shown in Figs. 2(a) and (b), there are two thresholds for w , *Threshold A* and *Threshold B*, at which the value of coopera-

tion frequency jumps up or down. These thresholds are $w = (b - 1.0)/(b + 1.0)$ and $w = 2.0/b - 1.0$, the derivations of which are provided later.

We have shown that moderate level of link-weight heterogeneity (intra-individual heterogeneity) can enhance cooperation and that there are some thresholds in w (a parameter that represents the degree of heterogeneity) at which the cooperation frequency changes in a stepwise manner. We checked that these results are robust against both the difference of the network size and the existence of the decision error. (See *Appendix A* of Iwata and Akiyama (2015) [49] for detail.)

3.2. Analysis of small population case — When and how does the heterogeneity of link weight facilitate cooperation?

In the following, we explore why the heterogeneity of link weight brings about the evolution of cooperation and why the frequency of cooperation changes in a stepwise manner with an increase in link-weight heterogeneity w . To answer these questions, we consider a much simpler model composed of six individuals only, and investigate in detail how the heterogeneity of link weight affects evolutionary dynamics.

In the case of a lattice network with six individuals, possible configurations of the strategies chosen by the six individuals are: “ $-C \equiv C - C \equiv C - C -$,” “ $-C \equiv C - C \equiv C - C \equiv D -$,” “ $-C \equiv C - C \equiv C - D \equiv C -$,” ..., “ $-D \equiv D - D \equiv D - D \equiv D -$,” where “C” and “D” denote cooperator and defector, respectively, “ \equiv ” represents a link with a large weight $1.0 + w$, and “ $-$ ” indicates a link with a small weight $1.0 - w$. The total number of possible configurations is $2^6=64$.

Starting with each of the 64 initial configurations, we investigated how the configuration changed over time resulting from updates of the six individuals’ strategies and identified the attractors of the evolutionary dynamics of the strategy configurations over generations, which were either steady states or periodic cycles. Next, we estimated the cooperation frequency in the attractor of evolutionary dynamics by taking an average of the data derived from the last 100 generations. In each of the 64 case studies, we focused on initial strategy

265 configurations that reached different cooperative states depending on the value
of link-weight heterogeneity w . Next, we classified these configurations into
three types: Type (i): configurations that lead to a higher cooperation level
when $w > 0$ than that with a homogeneous link weight ($w = 0$). Type (ii):
configurations that lead to a lower cooperation level when $w > 0$. Type (iii):
270 configurations leading to the same level of cooperation. (See *Appendix A* for
the classification of the initial strategy configurations into these three types.)
Because we are interested in cases where the heterogeneity of link weight has
an effect on the evolution of cooperation, in the following, we focus on strategy
configurations of the first and second types.

275 There are six strategy configurations that belong to Type (i) (see *Appendix*
A), which shows that higher heterogeneity (large w) causes an increase in coop-
eration frequency. These six configurations have a common pattern, as shown
in Figs. 3(a) and (b). Similarly, there are three strategy configurations that be-
long to Type (ii), where the magnitude of cooperation frequency decreases with
280 higher heterogeneity. These three configurations have a common configuration
pattern as shown in Fig. 4.

First, we consider the evolutionary dynamics, starting from the strategy con-
figuration pattern in Figs. 3(a) and (b). Here, we focus on the third individual
from the left in each of both figures, who we simply call the *focal individual*.
285 When starting from the strategy configuration pattern shown in these figures,
the focal individual chooses cooperation in the next step for a large w . For
a small w , however, the focal individual does not change his/her strategy and
keeps the strategy of defection. In short, this configuration pattern enables the
spread of cooperation if heterogeneity of link weight exists. We now investigate
290 in detail why this spread of cooperation occurs.

Figs. 3(a) and (b) show the strategy configuration patterns for Type (i),
where the heterogeneous link weight ($w > 0$) achieves a higher cooperation fre-
quency than the homogeneous one ($w = 0$). Of the 64 strategy configurations,
there are six configurations where greater link-weight heterogeneity enables a
295 higher cooperation level: “ $-C \equiv C - D \equiv D - C \equiv C -$,” “ $-D \equiv D - C \equiv C - C \equiv C -$,”

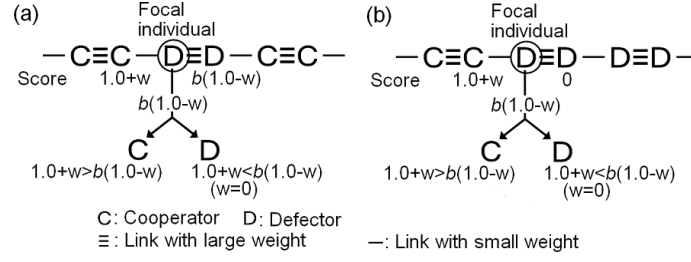


Fig. 3: Strategy configuration patterns for type (i), where heterogeneous link weight ($w > 0$) achieves higher cooperation frequency than the homogeneous one ($w = 0$). “C” and “D” denote cooperator and defector, respectively, “≡” represents a large-weight link, and “—” indicates a small-weight link. Whether the strategy of the *focal individual* changes from defection to cooperation depends on the value of link-weight heterogeneity w . The change in strategy of the *focal individual* after one generation (interactions and strategy updates) is indicated by the arrow in the lower part of each figure.

“—C≡C—C≡C—D≡D—,” “—C≡C—D≡D—D≡D—,” “—D≡D—D≡D—C≡C—,”
 and “—D≡D—C≡C—D≡D—.” Considering the periodic boundary condition,
 the first three configurations are equivalent to “—C≡C—D≡D—C≡C—,” which
 is shown at the top of Fig. 3(a). Similarly, the latter three configurations are
 equivalent to “—C≡C—D≡D—D≡D—,” which is shown at the top of Fig. 3(b).
 We define two cooperators connected by a large-weight link as “C≡C cluster,”
 two defectors connected by a large-weight link as “D≡D cluster,” and one coop-
 erator and one defector connected strongly as “C≡D cluster” or “D≡C cluster.”
 When “C≡C cluster,” “D≡D cluster,” and “C≡C or D≡D cluster” are adjacent
 as shown in Figs. 3(a) and (b), there is the possibility that the focal individual
 (the third individual) updates his/her strategy from defection to cooperation
 depending on the value of w (link-weight heterogeneity). We call this configu-
 ration pattern the *spread pattern strategy configuration*.

Given that there exists a *spread pattern strategy configuration*, we investigate
 the actual conditions under which the focal individual (the third individual)
 updates his/her strategy from defection to cooperation. Because each individual
 obtains the payoff of the PD game *multiplied by the value of the weight of the link*
with his/her opponent and each individual’s score is the sum of all the payoffs

obtained by playing PD games with his/her neighbors, the score of the third
 315 individual is $b(1.0 - w)$. The fourth individual obtains a score of $b(1.0 - w)$ if
 the fifth individual is a cooperator (see Fig. 3(a)), else 0 if the fifth is a defector
 (see Fig. 3(b)). Thus, in either case, the score of the focal individual (the third
 individual) is greater than or equal to that of the fourth individual. Because
 the focal individual is assumed to imitate the strategy of the individual with the
 320 maximum score, it is sufficient for the focal individual to compare his/her score
 with that of the second individual to ascertain whose strategy to imitate. The
 focal individual imitates the second individual's strategy and changes his/her
 strategy from defection to cooperation only if the second individual's score is
 higher than the focal individual's own score. Because the score of the focal
 325 individual is $b(1.0 - w)$ and that of the second individual is $1.0 + w$, the condition
 under which the focal individual imitates the strategy of the second individual
 is $1.0 + w > b(1.0 - w)$; that is, $w > (b - 1.0)/(b + 1.0)$ for a given b .

Thus, if the population involves the *spread pattern strategy configuration*
 composed of three adjoining clusters, namely, "C \equiv C cluster," "D \equiv D cluster,"
 330 and "C \equiv C or D \equiv D cluster," whether the focal individual changes his/her strat-
 egy from defection to cooperation depends on the link-weight heterogeneity;
 that is, he/she becomes a cooperator if the link weight satisfies the condition
 $w > (b - 1.0)/(b + 1.0)$. We refer to the inequality of w mentioned above as the
condition for the spread of cooperation. To summarize, if this condition is sat-
 335 isfied in the *spread pattern strategy configuration*, cooperative behavior spreads
 from the second to the third individual.

Next, we look at the evolutionary dynamics starting from the strategy con-
 figuration pattern in Fig. 4. As in the case of Figs. 3(a) and (b), we focus on
 the third individual from the left in this figure and call him/her the *focal indi-*
 340 *vidual*. When starting from the strategy configuration pattern shown in Fig. 4,
 the focal individual chooses defection in the next step for sufficiently large val-
 ues of w . For a small w , however, the focal individual does not change his/her
 strategy and retains a cooperative state. In short, this configuration pattern en-
 ables maintenance of cooperation when the heterogeneity is not so large. In the

345 following, we investigate in detail why this maintenance of cooperation occurs.

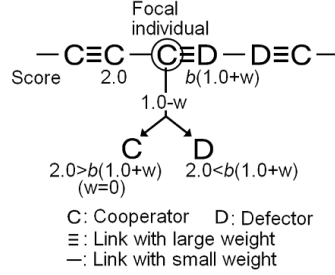


Fig. 4: Strategy configuration pattern for type (ii), where heterogeneous link weight ($w > 0$) reduces cooperation frequency more than homogeneous link weight ($w = 0$). Here, “C” and “D” denote cooperator and defector, respectively, “≡” represents a large-weight link, and “—” indicates a small-weight link. Whether the *focal individual* changes his/her strategy from cooperation to defection is dependent on the value of link-weight heterogeneity w . A change in the strategy of the *focal individual* after one generation (including interactions and strategy updates) is depicted by the arrow in the lower part of the figure.

Fig. 4 shows the strategy configuration pattern in the case of Type (ii), where homogeneous link weight ($w = 0$) achieves higher cooperation frequency than heterogeneous weight ($w > 0$). Of the 64 strategy configurations, there are three configurations where a small heterogeneity promotes further cooperation:

350 “—C≡C—C≡D—D≡C—,” “—C≡D—D≡C—C≡C—,” and “—D≡C—C≡C—C≡D—.”

Considering the periodic boundary condition, these configurations are equivalent to “—C≡C—C≡D—D≡C—,” as shown at the top of Fig. 4. When “C≡C cluster,” “C≡D cluster,” and “D≡C cluster” are adjacent, as shown in this figure, there is a possibility that the focal individual (third individual) updates

355 his/her strategy from cooperation to defection depending on the value of w (link-weight heterogeneity). We call this configuration pattern the *maintenance pattern strategy configuration*.

Given that there exists a *maintenance pattern strategy configuration*, we investigate the condition under which the focal individual (third individual)

360 does not update his/her strategy from cooperation to defection and retains the strategy of cooperation. In this case, the focal individual (third individual) has a score of $1.0 - w$, the second has a score of 2.0, and the fourth has a score

of $b(1.0 + w)$. So the focal individual does not imitate the fourth individual's strategy (defection) but imitates the second individual's strategy (cooperation),
 365 only if $2.0 > b(1.0 + w)$; that is, $w < 2.0/b - 1.0$ for a given b .

Therefore, if the population is subject to a *maintenance pattern strategy configuration* composed of three adjoining clusters, namely, "C≡C cluster," "C≡D cluster," and "D≡C cluster," whether the focal individual can refrain from changing his/her strategy from cooperation to defection depends on link-weight
 370 heterogeneity; that is, he/she remains a cooperator if the heterogeneity w satisfies the condition $w < 2.0/b - 1.0$. We call the inequality of w given above the *condition for maintenance of cooperation*. If this condition is satisfied in the *maintenance pattern strategy configuration*, defective behavior does not spread from the fourth to the third individual. Otherwise, defection spreads.

375 Thus far, we have derived the condition for the spread of cooperation $w > (b-1.0)/(b+1.0)^4$ and that for the maintenance of cooperation $w < 2.0/b - 1.0$ for one individual in a small population. These obtained conditions are illustrated in Fig. 5.

The parameter space for the temptation payoff, b , and link-weight heterogeneity, w , is divided into four regions, namely, region I, where both conditions
 380 are satisfied, region II, where only the spread condition is satisfied, region III where only the maintenance condition is satisfied, and region IV where neither condition is satisfied.

⁴In fact, the condition $w > (b - 1.0)/(b + 1.0)$ is not only the spread condition of cooperation but also is the maintenance condition, under which cooperator avoids from changing his/her strategy to defection; that is, cooperation can be maintained. However, this fact does not change our results in which the intermediate level of the magnitude of heterogeneity can enhance cooperation and that heterogeneity has several thresholds at which cooperation frequency changes in a stepwise manner. Thus, we omit the fact that $w > (b - 1.0)/(b + 1.0)$ involves both spread and maintenance conditions in this paper.

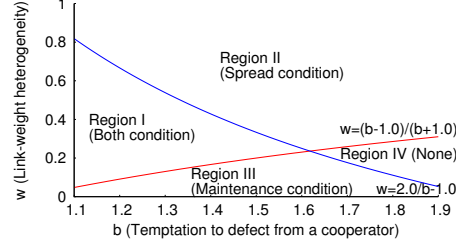


Fig. 5: Two conditions under which link-weight heterogeneity enables the spread/maintenance of cooperation in a small population. These conditions are determined and illustrated here using a combination of link-weight heterogeneity w and payoff b . The horizontal and vertical axes represent the payoff b and the value of w .

3.3. Simulation analysis on a large population

385 The two conditions identified in the previous subsection are based on the analysis of a small population (six nodes); nevertheless, whether these two conditions can control the spread/maintenance of the frequency of cooperation in a large population as well, remains to be seen. As mentioned, Figs. 2(a) and (b) depict the simulation results for a large (10,000 node) one-dimensional lattice
 390 showing how link-weight heterogeneity w affects the frequency of cooperation. By comparing Figs. 2(a) and (b) with Fig. 5, we can see whether the condition for the spread of cooperation $w > (b - 1.0)/(b + 1.0)$ and that for the maintenance of cooperation $w < 2.0/b - 1.0$ identified in the small population, also hold in a large population.

395 For example, when $b = 1.2$, the phase shifts in Fig. 5 through regions III (maintenance condition holds), I (both conditions hold), and II (spread condition holds), as parameter w increases. After an increase in w , it will be on the boundary between regions III and I where $w = (b - 1.0)/(b + 1.0)$ holds. As mentioned, in Fig. 2(a), if w has a value satisfying $w = (b - 1.0)/(b + 1.0)$, w is at
 400 *Threshold A*, at which point the cooperation frequency increases in a stepwise manner. If the value of w satisfies $(b - 1.0)/(b + 1.0) < w < 2.0/b - 1.0$, cooperation frequency is at its highest value in Fig. 2(a), and when $b = 1.2$, (w, b) is in region I in Fig. 5. Thereafter, if the value of w is equal to $w = 2.0/b - 1.0$, w is

at *Threshold B* at which point the cooperation frequency starts to decrease in
405 a stepwise manner in Fig. 2(a), and (w, b) is located at the boundary between
regions I and II in Fig. 5. Similarly, also in the case where $b = 1.8$, the phase
shifts in Fig. 5 through regions as an increase in the value of w correspond to
the changes in the cooperation frequency seen in Fig. 2(b).

We have found that the two conditions identified in the small group can
410 explain the effect of link-weight heterogeneity on the level of cooperation fre-
quency in a large population. However, so far we have confirmed this only in
the cases with $b = 1.2$ and $b = 1.8$. Next, we examine the possibility of an
application of the two obtained conditions for w to an increase or decrease in
the cooperation frequency in a stepwise manner for several thresholds of w over
415 the whole parameter range of $b \in (1.0, 2.0)$ (in steps of 0.01).

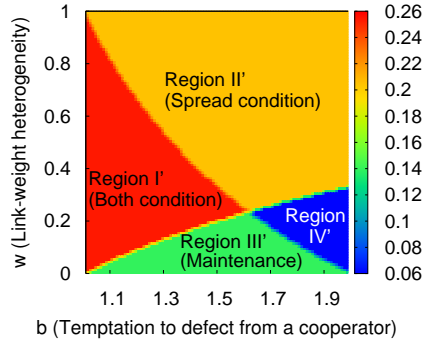


Fig. 6: Simulation results for the PD game showing the relationship between the frequency of cooperation and $b - w$ parameter combination. The horizontal and vertical axes denote temptation payoff b and link-weight heterogeneity w . Here, color coding represents the magnitude of the frequency of cooperation, as shown on the sidebar. We denote the region with the highest cooperation frequency (red) as region I', that with the second highest frequency (orange) as region II', that with the third highest (green) as region III', and the lowest frequency region (blue) as region IV'.

Fig. 6 illustrates the frequency of cooperation for different values of the combination of b and w . If the combination of b and w denotes a point that is

located in region I (both conditions hold) in Fig. 5, the same point is placed in region I' in Fig. 6, at which point the cooperation frequency has its highest value.

420 In addition, if the combination of b and w denotes a point that is located in region II (spread condition holds) in Fig. 5, the same point is placed in region II' in Fig. 6 and the magnitude of the cooperation frequency is the second highest. It is observed that the two lines $w = (b - 1.0)/(b + 1.0)$ and $w = 2.0/b - 1.0$ in Fig. 5 coincide with the lines dividing the parameter space into four regions
 425 (region I', II', III'', and IV') in Fig. 6. This coincidence implies that the two conditions for link-weight heterogeneity w identified in the small population also hold for the spread/maintenance of cooperation in the large population across the entire parameter range of b .

4. Conclusion

430 Much research has been conducted to analyze the factors that promote the evolution of cooperation in natural and social systems. Recently, several researchers [31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48] have examined the effect of heterogeneity on the evolution of cooperation. Especially, Du et al. [31] and Ma et al. [32] have clarified that link-weight heterogeneity can
 435 facilitate cooperation. However, they investigated heterogeneity of interactions among individuals, which includes both *intra-individual heterogeneity* and *inter-individual heterogeneity*, to the best of our knowledge. *Inter-individual heterogeneity* leads to heterogeneity of the *link-weight amount*, which causes heterogeneous interactions similar to those caused by the *heterogeneity of the number*
 440 *of links*, and the effect of the heterogeneity of the number of links on the promotion of cooperation has already been established in the literature [13, 14, 15]. Therefore, the effect of link-weight heterogeneity on the evolution of cooperation may be given only by *inter-individual heterogeneity* whose effect is similar to that of the *heterogeneity of the number of links*. To investigate whether link-
 445 weight heterogeneity within each individual alone can promote cooperation, it is necessary to use a model with *intra-individual heterogeneity* and without *inter-*

individual heterogeneity. Additionally, it has not been fully resolved *when and how* promotion of cooperation based on the heterogeneity of link weight takes place.

450 To address these issues, we constructed a simple model of one-dimensional lattice with heterogeneous link weight, on which individuals play the evolutionary PD game. We assumed that the sum of the link weights of each individual was equal, to remove the effect of *inter-individual heterogeneity* on the promotion of cooperation, thereby focusing only on *intra-individual heterogeneity*.

455 By performing calculations and analyses, we obtained the following two results. First, we clarified that the moderate magnitude of *intra-individual heterogeneity* of link weight can facilitate cooperation and that there are some thresholds in the range of the heterogeneity level, at which the change in the cooperation frequency occurs in a stepwise manner. This result suggests that, 460 even when there is no heterogeneity of link-weight amount that causes a similar effect to that of heterogeneity of the number of links as in Santos and Pacheco [13], heterogeneous link weight within each individual alone can promote cooperation. Second, we found the key mechanisms whereby link-weight heterogeneity facilitates the evolution of cooperation, the mechanisms for the 465 spread and maintenance of cooperation. We also derived corresponding conditions for the both mechanisms to work through evolutionary dynamics, which have not been clarified before.

Because the simulation model used is very simple, it may appear to be somewhat unrealistic. However, this simplicity enabled us to examine the effect of 470 heterogeneous link weight (*intra-individual heterogeneity*) and the aforementioned mechanisms. We believe that our discovery of these mechanisms can form the basis of future researches on link-weight heterogeneity. It would be interesting to investigate the effect of heterogeneity of link weight on the evolution of cooperation and its mechanism using a mathematical model with a 475 more realistic assumption. For example, to extend the network structure from

a one-dimensional lattice to a two-dimensional one ⁵, or so-called complex networks such as small-world and scale-free networks, would be attractive matter to be worked on as a future work. Another interesting avenue for future research would be to identify the mechanisms by which link-weight heterogeneity that
480 includes both *intra-individual heterogeneity* and *inter-individual heterogeneity*, such as link-weight heterogeneity in the real world, promotes cooperation. Although we found in this paper the mechanism by which *intra-individual heterogeneity* alone can facilitate cooperation, there may be a specific mechanism for the evolution of cooperation caused by the interplay between *intra-* and
485 *inter-individual heterogeneities*.

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cooperation, *arXiv:1507.06746* (2015).

Appendix A. Classification of strategy configurations

In this appendix, we show the classification of the initial strategy configurations for a convergent state of cooperation frequency in a small one-dimensional lattice consisting of six individuals. Of the $2^6=64$ initial strategy configurations, we focus on those configurations that, through evolution, reach different cooperative states depending on whether the link weight is heterogeneous ($w > 0$) or homogeneous ($w = 0$) as a result of the evolution of strategies. As mentioned in Section 3.2, the initial strategy configurations are classified into the following three types: Type (i) in which heterogeneous link weight ($w > 0$) leads to higher cooperation frequency than the homogeneous one ($w = 0$); Type (ii) in which heterogeneous weight suppresses cooperation; and Type (iii) where both heterogeneous and homogeneous link weights lead to the same magnitude of cooperation. The initial strategy configuration types are listed in Table A.1⁶.

⁶Six strategy configurations are classified as both Type (i) and (ii), where, whether the heterogeneous link weight ($w > 0$) achieves a higher cooperation frequency through evolution than the homogeneous weight ($w = 0$) depends on the value of b . Our purpose was to identify the mechanisms whereby link-weight heterogeneity enhances cooperation and to derive the conditions for the mechanisms to work. Therefore, we investigated the strategy configurations classified only as Type (i) or (ii).

Initial strategy configuration	Classification type
$-C \equiv C - D \equiv D - C \equiv C -$, $-D \equiv D - C \equiv C - C \equiv C -$, $-C \equiv C - C \equiv C - D \equiv D -$, $-C \equiv C - D \equiv D - D \equiv D -$, $-D \equiv D - D \equiv D - C \equiv C -$, $-D \equiv D - C \equiv C - D \equiv D -$	Type (i): Heterogeneous link weight ($w > 0$) promotes further cooperation
$-C \equiv C - C \equiv D - D \equiv C -$, $-C \equiv D - D \equiv C - C \equiv C -$, $-D \equiv C - C \equiv C - C \equiv D -$	Type (ii): Homogeneous link weight ($w = 0$) promotes further cooperation
$-C \equiv C - C \equiv C - C \equiv C -$, $-C \equiv C - C \equiv D - C \equiv D -$, $-C \equiv C - D \equiv C - D \equiv C -$, $-C \equiv C - D \equiv C - C \equiv D -$, $-C \equiv D - C \equiv C - D \equiv C -$, $-C \equiv D - C \equiv D - C \equiv C -$, $-C \equiv D - C \equiv D - D \equiv C -$, $-C \equiv D - C \equiv C - C \equiv D -$, $-C \equiv D - C \equiv D - C \equiv D -$, $-C \equiv D - C \equiv D - D \equiv D -$, $-C \equiv D - D \equiv C - D \equiv C -$, $-C \equiv D - D \equiv D - D \equiv C -$, $-C \equiv D - D \equiv C - C \equiv D -$, $-C \equiv D - D \equiv C - D \equiv D -$, $-C \equiv D - D \equiv D - C \equiv D -$, $-C \equiv D - D \equiv D - D \equiv D -$, $-D \equiv C - C \equiv C - D \equiv C -$, $-D \equiv C - C \equiv D - C \equiv C -$, $-D \equiv C - C \equiv D - C \equiv D -$, $-D \equiv C - C \equiv D - D \equiv C -$, $-D \equiv C - C \equiv D - D \equiv D -$, $-D \equiv C - D \equiv C - C \equiv C -$, $-D \equiv C - D \equiv C - D \equiv C -$, $-D \equiv C - D \equiv C - C \equiv D -$, $-D \equiv C - D \equiv C - D \equiv D -$, $-D \equiv C - D \equiv D - C \equiv D -$, $-D \equiv C - D \equiv D - D \equiv C -$, $-D \equiv C - D \equiv D - D \equiv D -$, $-D \equiv D - C \equiv D - C \equiv D -$, $-D \equiv D - C \equiv D - D \equiv C -$, $-D \equiv D - C \equiv D - D \equiv D -$, $-D \equiv D - D \equiv C - D \equiv C -$, $-D \equiv D - D \equiv D - D \equiv C -$, $-D \equiv D - D \equiv C - C \equiv D -$, $-D \equiv D - D \equiv C - D \equiv D -$, $-D \equiv D - D \equiv D - C \equiv D -$, $-D \equiv D - D \equiv D - D \equiv D -$	Type (iii): Heterogeneous weight ($w > 0$) and homogeneous weight ($w = 0$) achieve the same level of cooperation

Table A.1: List of initial strategy configurations and classification thereof into three types. The first row represents the initial strategy configurations; the second row shows the three classifications of the configurations in which greater link-weight heterogeneity w promotes more cooperation, higher w reduces cooperation frequency, and different values of w do not have any effect on the magnitude of the cooperation level, respectively. In the table, “C” and “D” denote cooperator and defector, respectively, while “ \equiv ” indicates a link with a large weight, and “ $-$ ” means a link with a small weight.